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#### ▶ To cite this version:

Benoit Caillaud, Mathias Malandain, Joan Thibault. Demo: IsamDAE, an Implicit Structural Analysis Tool for Multimode DAE Systems. HSCC 2020 - 23rd ACM International Conference on Hybrid Systems: Computation and Control, Apr 2020, Sydney, Australia. pp.1. hal-02545380

## HAL Id: hal-02545380 https://inria.hal.science/hal-02545380

Submitted on 17 Apr 2020

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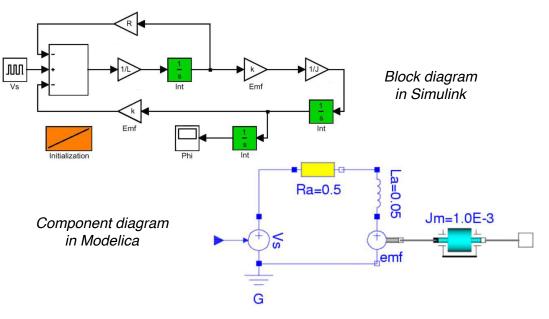
# Demo: IsamDAE, an Implicit Structural Analysis Tool for Multimode DAE Systems

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## DAE FOR THE MODELING OF (LARGE) CYBER-PHYSICAL SYSTEMS

#### **Large physical systems** → *Differential-Algebraic Equations* (DAE)

- Components modeled with a few differential and/or algebraic equations
- Connections: algebraic equations (balance equations, Kirchhoff laws)
- Pros: compositional modeling, high reusability of physical components



## Non-smooth, or hybrid, systems → *Multimode DAE* (mDAE)

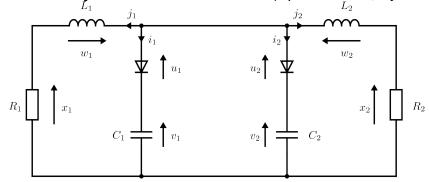
In general, mDAE are poorly handled by existing tools
 No proper structural analysis of mDAE at compile time

## Variable dimension systems $\rightarrow$ *Variable dimension* models

- (Dis)appearance of components in a CPS would be easily handled
- Such models are not handled by existing tools

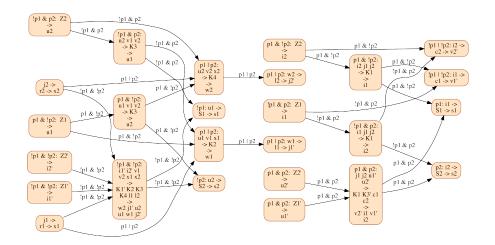
## THE RLDC2 EXAMPLE

- Two RLC circuits with ideal diodes, in parallel
- Mode-dependent structure: differentiation orders for the equations, as well as the resulting equation blocks, depend on the mode
- Not handled by current DAE-based tools (OpenModelica, Dymola)



## Mode-dependent structural analysis by IsamDAE

- · Checks that the model is determined in all modes
- · Generates the mode-dependent scheduling graph shown below
- In each mode: description of the (ODE-like) blocks to be compiled into simulation code + dependencies (for their scheduling)
  - ✓ Same results, in each mode, as those of standard structural analysis



## STRUCTURAL ANALYSIS OF DAE

#### Handling DAE systems is harder than ODE

- · No direct criterion to determine whether a DAE is determined
- · Simulation code cannot be generated from the original model
- Compilation relies on Structural Analysis (SA)

#### Structural analysis

- Graph-based (Pantelides method) or linear programming (Pryce's Sigma-method) algorithms
- · Provides diagnosis about the model at compile time ('typechecking')
- Enables the generation of efficient simulation code:
  - > equations are carefully differentiated, and grouped into the smallest possible *equation blocks*;
  - ➤ blocks are ordered (`scheduled') for the simulation of a time step

## THE ISAMDAE TOOL

## Structural analysis for mDAE, in an `all-modes-at-once' fashion

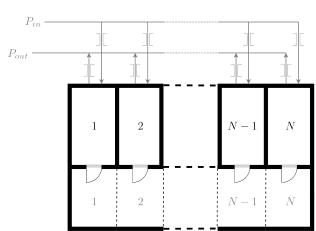
- Input: Ad hoc equation language used for declaring mDAE models
  - ➤ Implicit representation with BDD (preserves sparsity)
  - > Structural analysis (from the Sigma-method) and block scheduling: adaptation of existing methods and novel algorithms
- *Output:* Detailed (but condensed) description of the simulation blocks and their dependencies, in all modes

## Implementation

- About 16,000 lines of OCam1 code
- Libraries: menhir, mlbdd, OCaml-Tools, pprint, xml-light
- Software package: GraphViz

## THE BUILDING EXAMPLE

- Scalable model: single-story building with N rooms and doors
- Instantaneous mode transitions when a door is opened or closed
- Variables taken into account: pressures, temperatures →, air masses, enthalpies, heat and mass flows (compressible air)
- For *N* rooms : 16N+5 equations and variables, 6<sup>N</sup>/2 modes



## Scaling-up of the structural analysis by IsamDAE

- The total number of blocks is an affine function of N
- Experimental computation times: about O(N³)

