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High-order DG-SE approximations of elsatodynamic wave problems with stable Perfectly Matched Layers †

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Mathias 2019







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[†] This work is dedicated to the memory of Dimitri Komatitsch.







- Useful when the use of unstructured grid is non-sense (e.g. medium with a layer of water).
- Well suited for the coupling of numerical methods in order to reduce the computational cost and improve the accuracy.





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$$x \in \Omega \subset \mathbb{R}^d$$
, $t \in [0, T], T > 0$:

$$\begin{cases} \rho(x)\frac{\partial \mathbf{v}}{\partial t}(x,t) &= \nabla \cdot \underline{\underline{\sigma}}(x,t), \\ \frac{\partial \underline{\underline{\sigma}}}{\partial t}(x,t) &= \underline{\underline{C}}(x)\underline{\underline{\epsilon}}(\mathbf{v}(x,t)). \end{cases}$$

With:

- $\rho(x)$ the density,
- $\underline{C}(x)$ the elasticity tensor,
- $\underline{\epsilon}(x, t)$ the deformation tensor,
- v(x, t), the wavespeed,
- $\underline{\sigma}(x, t)$ the strain tensor.

Software written in Fortran for wave propagation simulation in the time domain

Features

Simulation:

- on various types of meshes (unstructured triangles and tetrahedra),
- on heterogeneous media (acoustic, elastic and elasto-acoustic).
- Discontinuous Galerkin (DG) based on unstructured triangles and unstructured tetrahedra,
- with various time-schemes : Runge-Kutta (2 or 4), Leap-Frog,
- with multi-order computation(p-adaptivity)...

DGm and SEm

- OG/SEM coupling
- Perfectly Matched Layer(PML)

Use discontinuous functions :



Degrees of freedom necessary on each cell :



h adaptivity :

General principle

- Finite Element Method (FEM) discretization + Gauss-Lobatto quadrature,
- Gauss-Lobatto points as degrees of freedom (gives us exponential convergence on L^2 -norm).



•
$$\int f(x)dx \approx \sum_{j=1}^{N+1} \omega_j f(\xi_j),$$

• $\varphi_i(\xi_j) = \delta_{ij}.$

DG

- Element per element computation (hp-adaptivity).
- Time discretization quasi explicit (block diagonal mass matrix).
- Simple to parallelize.
- Robust to brutal changes of physics and geometry

SEM

- Couples the flexibility of FEM with the accuracy of the pseudo-spectral method.
- Simplifies the mass and stiffness matrices (mass matrix diagonal).

- Aim at coupling P_k and Q_k structures.
- Need to extend or split some structures (e.g. neighbour indices).
- Define new face matrices:

$$M_{ij}^{K,L} = \int_{K \cap L} \phi_i^K \phi_j^L, \quad M_{ij}^{K,L} = \int_{K \cap L} \psi_i^K \psi_j^L, \quad M_{ij}^{K,L} = \int_{K \cap L} \phi_i^K \psi_j^L.$$

Global context

• Domain in two parts : $\Omega_{h,1}$ (structured quadrangles + SEM), $\Omega_{h,2}$ (unstructured triangles + DG).





Definitions

• Jump and average.

$$[[u]] = (u_{K_1} \mathbf{n}_{K_1} + u_{K_2} \mathbf{n}_{K_2})$$

$$\{\{u\}\} = \frac{1}{2}(u_{K_2} + u_{K_1})$$

SEM variational formulation :

$$\begin{cases} \int_{\Omega_{h,1}} \rho \partial_t \mathbf{v}_1 \cdot \mathbf{w}_1 = -\int_{\Omega_{h,1}} \sigma_1 : \nabla \mathbf{w}_1 + \int_{\Gamma_{out,1}} (\sigma_1 \mathbf{n}_1) \cdot \mathbf{w}_1, \\ \\ \int_{\Omega_{h,1}} \partial_t \sigma_1 : \xi_1 = \int_{\Omega_{h,1}} (C\xi_1) : \nabla \mathbf{v}_1. \end{cases}$$

DG variational formulation :

$$\begin{cases} \int_{\Omega_{h,2}} \rho \partial_t \mathbf{v}_2 \cdot \mathbf{w}_2 = -\int_{\Omega_{h,2}} \sigma_2 : \nabla \mathbf{w}_2 + \int_{\Gamma_{out,2}} (\sigma_2 \mathbf{n}_2) \cdot \mathbf{w}_2 + \int_{\Gamma_{int}} \{\{\sigma_2\}\} : [[\mathbf{w}_2]], \\ \\ \int_{\Omega_{h,2}} \partial_t \sigma_2 : \xi_2 = -\int_{\Omega_{h,2}} (\boldsymbol{\nabla} \cdot (\boldsymbol{C}\xi_2)) \cdot \mathbf{v}_2 + \int_{\Gamma_{out,2}} (\boldsymbol{C}\xi_2 \mathbf{n}_2) \cdot \mathbf{v}_2 + \int_{\Gamma_{int}} \{\{\mathbf{v}_2\}\} \cdot [[\boldsymbol{C}\xi_2]]. \end{cases}$$

$$\begin{cases} \int_{\Omega_{h,1}} \rho \partial_t \mathbf{v}_1 \cdot \mathbf{w}_1 + \int_{\Omega_{h,2}} \rho \partial_t \mathbf{v}_2 \cdot \mathbf{w}_2 = -\int_{\Omega_{h,1}} \sigma_1 : \nabla \mathbf{w}_1 - \int_{\Omega_{h,2}} \sigma_2 : \nabla \mathbf{w}_2 \\ + \int_{\Gamma_{out,1}} (\sigma_1 \mathbf{n}_1) \cdot \mathbf{w}_1 + \int_{\Gamma_{out,2}} (\sigma_2 \mathbf{n}_2) \cdot \mathbf{w}_2 + \int_{\Gamma_{int}} \{\{\sigma_2\}\} : [[\mathbf{w}_2]] \\ + \int_{\Gamma_{1/2}} [[\sigma \mathbf{w}]], \\ \int_{\Omega_{h,1}} \partial_t \sigma_1 : \xi_1 + \int_{\Omega_{h,2}} \partial_t \sigma_2 : \xi_2 = \int_{\Omega_{h,1}} (C\xi_1) : \nabla \mathbf{v}_1 - \int_{\Omega_{h,2}} (\nabla \cdot (C\xi_2)) \cdot \mathbf{v}_2 \\ + \int_{\Gamma_{out,2}} (C\xi_2 \mathbf{n}_2) \cdot \mathbf{v}_2 + \int_{\Gamma_{int}} \{\{\mathbf{v}_2\}\} \cdot [[C\xi_2]] \\ + \int_{\Gamma_{1/2}} [[(C\xi)\mathbf{v}]]. \end{cases}$$

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• Easy to implement



- Easy to implement
- Not really adapted to the simulation of "infinite" domain









• Possibility to simulate an infinite domain



- Possibility to simulate an infinite domain
- Complicated to implement when the order of the condition increase



- Possibility to simulate an infinite domain
- Complicated to implement when the order of the condition increase
- Apparition of reflection when it comes to waves with grazing incidence







• Possibility to simulate an infinite domain



• Possibility to simulate an infinite domain



- Possibility to simulate an infinite domain
- Some stability problems on elastic case using DGM

Step 1: Rewrite the system in the frequency domain

$$\begin{cases} i\omega\rho\mathbf{v} = \boldsymbol{\nabla}\cdot\underline{\boldsymbol{\sigma}}\\ i\omega\underline{\boldsymbol{\sigma}} = \underline{\boldsymbol{c}}:\nabla\mathbf{v} \end{cases}$$

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Step 2: Introduce a new system of complex coordinates

Define d_z the damping :

$$\left\{ egin{array}{ll} d_z > 0 & ext{if} & z \in \Omega_{PML} \ d_z = 0 & ext{if} & z
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$$ilde{z}(z) = z - rac{i}{\omega} \int_0^z d_z(s) ds$$

Define the associate differential operator :

$$\partial_{\tilde{z}} = rac{i\omega}{i\omega + d_z} \partial_z = 1 - rac{d_z}{i\omega + d_z} \partial_z$$

Step 3: Rewrite the system

$i\omega\rho v_x$	=	$\partial_x \sigma_{xx} + \partial_{\tilde{z}} \sigma_{xz},$
iωρvz	=	$\partial_x \sigma_{xz} + \partial_{\tilde{z}} \sigma_{zz},$
$i\omega\sigma_{xx}$	=	$(\lambda + 2\mu)\partial_x v_x + \lambda\partial_{\tilde{z}} v_z,$
$i\omega\sigma_{zz}$	=	$\lambda \partial_x v_x + (\lambda + 2\mu) \partial_{\tilde{z}} v_z,$
$i\omega\sigma_{xz}$	=	$\mu(\partial_x v_z + \partial_{\tilde{z}} v_x).$

A high-order time and space formulation of the unsplit perfectly matched layer for the seismic wave equation using Auxiliary Differential Equations (ADE-PML) Computer Modeling in Engineering and Sciences (CMES),2010

Introduction of $2^d + 1$ new variables $\psi_\star \in H^1 \to$ Simplify the implementation BUT add new equation to the linear system

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 \downarrow Back to original coordinates

 \downarrow

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$$i\omega\rho v_z = \partial_x \sigma_{xz} + \frac{\partial_{\tilde{z}}}{\sigma_{zz}}$$

Back to original coordinates

$$i\omega\rho v_z = \partial_x \sigma_{xz} + \partial_z \sigma_{zz} - \frac{d_z}{d_z + i\omega} \partial_z \sigma_{zz}$$

 \downarrow

↓

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Back to original coordinates

$$i\omega\rho v_z = \partial_x \sigma_{xz} + \partial_z \sigma_{zz} - \frac{d_z}{d_z + i\omega} \partial_z \sigma_{zz}$$

Back to time domain

 \downarrow

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$$i\omega\rho v_z = \partial_x \sigma_{xz} + \partial_{\tilde{z}} \sigma_{zz}$$

Back to original coordinates

$$i\omega\rho v_{z} = \partial_{x}\sigma_{xz} + \partial_{z}\sigma_{zz} - \frac{d_{z}}{d_{z} + i\omega}\partial_{z}\sigma_{zz}$$

$$\rho \partial_{t}v_{x} = \partial_{x}\sigma_{xz} + \partial_{z}\sigma_{zz} - \frac{d_{z}}{d_{z} + \partial_{t}}\partial_{z}\sigma_{zz}$$

Back to time domain

ADE-PML (Auxiliary Differential Equation)

Definition of the memory variable $\psi_{\sigma_{zz}}$:

$$\psi_{\sigma_{zz}} = -\frac{d_z}{d_z + \partial_t} \partial_z \sigma_{zz}$$

$$\psi_{\sigma_{zz}} = -\frac{d_z}{d_z + \partial_t} \partial_z \sigma_{zz}$$

$$\rho \partial_t \mathbf{v}_z = \partial_x \sigma_{xz} + \partial_z \sigma_{zz} + \psi_{\sigma_{zz}}$$

$$\psi_{\sigma_{ZZ}} = -\frac{d_z}{d_z + \partial_t} \partial_z \sigma_{ZZ}$$

$$\rho \partial_t \mathbf{v}_z = \partial_x \sigma_{xz} + \partial_z \sigma_{zz} + \psi_{\sigma_{zz}}$$

$$\partial_t \psi_{\sigma_{zz}} = -\mathbf{d}_z \partial_z \sigma_{zz} - \mathbf{d}_z \psi_{\sigma_{zz}}$$

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$$\rho \partial_t \mathbf{v}_z = \partial_x \sigma_{xz} + \partial_z \sigma_{zz} + \psi_{\sigma_{zz}}$$

$$\partial_t \psi_{\sigma_{zz}} = -\mathbf{d}_z \partial_z \sigma_{zz} - \mathbf{d}_z \psi_{\sigma_{zz}}$$

ADE with C-PML (Convolutional PML)

$$\partial_{\tilde{z}} = \left(1 - \frac{d_z}{\alpha_z + i\omega + d_z}\right)\partial_z$$

$$\psi_{\sigma_{zz}} = -\frac{d_z}{d_z + \partial_t} \partial_z \sigma_{zz}$$

$$\rho \partial_t \mathbf{v}_z = \partial_x \sigma_{xz} + \partial_z \sigma_{zz} + \psi_{\sigma_{zz}}$$

$$\partial_t \psi_{\sigma_{zz}} = -\mathbf{d}_z \partial_z \sigma_{zz} - \mathbf{d}_z \psi_{\sigma_{zz}}$$

ADE with C-PML (Convolutional PML)

$$\partial_{\tilde{z}} = \left(1 - \frac{d_z}{\alpha_z + i\omega + d_z}\right) \partial_z$$

$$\partial_t \psi_{\sigma_{zz}} = -d_z \partial_z \sigma_{zz} - (d_z + \alpha_z) \psi_{\sigma_{zz}}$$

DG and DGSEM comparison



(a) t=1.5s

(b) t=1.5s

DG and DGSEM comparison



















Conclusion

- SEM is more efficient on structured quadrangle mesh than DG
- Build a variational formulation for DG/SEM coupling and find a CFL condition that ensures stability
- Show the utility of using hybrid meshes and method coupling (reduce computational cost,...)

Achievements

- Implement DG/SEM coupling on the code (2D) \checkmark
- Develop DG/SEM coupling in 3D \checkmark
- Develop PML in the hexahedral part \checkmark

Thank you for your attention !

Questions?