



HAL
open science

On the complexity of computing real radicals of polynomial systems

Mohab Safey El Din, Zhi-Hong Yang, Lihong Zhi

► **To cite this version:**

Mohab Safey El Din, Zhi-Hong Yang, Lihong Zhi. On the complexity of computing real radicals of polynomial systems. ISSAC '18 - The 2018 ACM on International Symposium on Symbolic and Algebraic Computation, Jul 2018, New-York, United States. pp.351-358, 10.1145/3208976.3209002 . hal-01956596

HAL Id: hal-01956596

<https://inria.hal.science/hal-01956596v1>

Submitted on 16 Dec 2018

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

On the complexity of computing real radicals of polynomial systems

Mohab Safey El Din* Zhi-Hong Yang† Lihong Zhi‡

December 16, 2018

Abstract

Let $\mathbf{f} = (f_1, \dots, f_s)$ be a sequence of polynomials in $\mathbb{Q}[X_1, \dots, X_n]$ of maximal degree D and $V \subset \mathbb{C}^n$ be the algebraic set defined by \mathbf{f} and r be its dimension. The real radical $\sqrt[r]{\langle \mathbf{f} \rangle}$ associated to \mathbf{f} is the largest ideal which defines the real trace of V . When V is smooth, we show that $\sqrt[r]{\langle \mathbf{f} \rangle}$, has a finite set of generators with degrees bounded by $\deg V$. Moreover, we present a probabilistic algorithm of complexity $(snD^n)^{O(1)}$ to compute the minimal primes of $\sqrt[r]{\langle \mathbf{f} \rangle}$.

When V is not smooth, we give a probabilistic algorithm of complexity $s^{O(1)}(nD)^{O(nr2^r)}$ to compute rational parametrizations for all irreducible components of the real algebraic set $V \cap \mathbb{R}^n$. Experiments are given to show the efficiency of our approaches.

1 Introduction

Let \mathbb{Q} , \mathbb{R} and \mathbb{C} be the fields of rational, real and complex numbers and $X = (X_1, \dots, X_n)$ be a sequence of variables.

For $\mathbf{f} = (f_1, \dots, f_s)$ in $\mathbb{Q}[X] := \mathbb{Q}[X_1, \dots, X_n]$, we denote by $\langle \mathbf{f} \rangle$ the ideal generated by \mathbf{f} in $\mathbb{Q}[X]$. For $\mathbb{K} = \mathbb{C}$ or \mathbb{R} , we let $V_{\mathbb{K}}(\mathbf{f}) := \{x \in \mathbb{K}^n \mid f_1(x) = 0 \dots, f_s(x) = 0\}$. The radical ideal of $\langle \mathbf{f} \rangle$ is the vanishing ideal of the algebraic set $V_{\mathbb{C}}(\mathbf{f}) \subset \mathbb{C}^n$.

The real radical $\sqrt[r]{\langle \mathbf{f} \rangle}$ of $\langle \mathbf{f} \rangle$ in $\mathbb{Q}[X]$ is defined as the set of polynomials $g \in \mathbb{Q}[X]$ such that $g^{2m} + \sum_{i=1}^l a_i^2 \in \langle \mathbf{f} \rangle$ for $m, l \in \mathbb{N}$, $a_i \in \mathbb{Q}[X]$. An ideal $I \subset \mathbb{Q}[X]$ is said to be real if it equals its real radical, that is, $I = \sqrt[r]{I}$. The Real Nullstellensatz (see e.g. (Neuhaus, 1998)) states that $\sqrt[r]{\langle \mathbf{f} \rangle}$ is equal to the vanishing ideal of $V_{\mathbb{R}}(\mathbf{f})$. Hence, representing the real radical associated to \mathbf{f} provides some insight on the geometry of $V_{\mathbb{R}}(\mathbf{f})$.

Computing real radicals has attracted much attention both on the symbolic and numerical side. Symbolic algorithms were developed at first in Becker and Neuhaus (1993).

*Sorbonne Université, CNRS, INRIA, Laboratoire d'Informatique de Paris 6, LIP6, Équipe POLSYS, 4 place Jussieu, F-75252, Paris Cedex 05, France

†KLMM, Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing 100190, China, University of Chinese Academy of Sciences, Beijing 100049, China

‡KLMM, Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing 100190, China, University of Chinese Academy of Sciences, Beijing 100049, China

Later Neuhaus (1998) proposed a revised form of this algorithm and gave an upper bound $D^{2^{O(n^2)}}$ for the degree of the generators of $\sqrt[\mathbb{R}]{\langle \mathbf{f} \rangle}$, where $D = \max\{\deg f_1, \dots, \deg f_s\}$. Spang (2007, 2008) implemented this algorithm and improved its efficiency by avoiding some linear changes of coordinates. This algorithm is based on properties of isolated points of real algebraic sets and computation of real radicals of zero-dimensional ideals. Instead of computing real radicals, Chen et al. (2010, 2013, 2011) give a method to decompose semi-algebraic systems into regular semi-algebraic systems.

On the numerical side, Lasserre et al. (2008, 2013) presented an algorithm based on moment relaxations to compute zero-dimensional real radicals in $\mathbb{R}[X]$. Subsequently, Ma et al. (2016) generalized this algorithm to positive dimensional cases. Brake et al. (2016) gave a method based on numerical algebraic geometry and sums of squares programming to certify that a set of polynomials generates the real radical. We emphasize that these algorithms compute real radicals in $\mathbb{R}[X]$ and hence return approximate encodings of those radicals. To see this, consider a univariate polynomial $f \in \mathbb{Q}[X_1]$ with a single irrational real root ρ . The real radical of $\langle f \rangle$ is generated by $X_1 - \rho$. The aforementioned algorithms based on numerical computations use an approximation of ρ to encode the output. By contrast, symbolic algorithms return real radicals with base field \mathbb{Q} and in the example we just considered would simply return f .

In this paper, we focus on symbolic algorithms for computing generators or *lazy representations* (see Definition 2) for real radicals in $\mathbb{Q}[X]$ with a focus on complexity issues.

Main results. All in all, we improve the complexity bound $D^{2^{O(n^2)}}$ for computing real radicals. When $V_{\mathbb{C}}(\mathbf{f})$ is smooth, we use polynomial system solving techniques in (Jeronimo et al., 2004; Blanco et al., 2004; Safey El Din, 2005) to obtain an algorithm running in time polynomial in snD^n .

Theorem 1. *Let $\mathbf{f} = (f_1, \dots, f_s) \subset \mathbb{Q}[X_1, \dots, X_n]$ with $D = \max(\deg(f_i), i = 1, \dots, s)$ encoded by a straight-line program Γ . Assume that $V_{\mathbb{C}}(\mathbf{f})$ is smooth, of dimension r and of degree δ . There exists a probabilistic algorithm which takes as input Γ and returns generators of each minimal associated prime of $\sqrt[\mathbb{R}]{\langle \mathbf{f} \rangle}$ with maximum degree δ . In case of success, the algorithm uses $(snD^n)^{O(1)}$ arithmetic operations in \mathbb{Q} .*

When $V = V_{\mathbb{C}}(\mathbf{f})$ is not smooth and has dimension r , we obtain an algorithm using $s^{O(1)}(nD)^{O(nr2^r)}$ arithmetic operations in \mathbb{Q} to represent the irreducible components of $\sqrt[\mathbb{R}]{\langle \mathbf{f} \rangle}$. Hence for fixed r , it is singly exponential in n by contrast to previous results.

The difficulty in the non-smooth case is that the real algebraic set $V_{\mathbb{R}}(\mathbf{f})$ might be embedded in the singular locus of V , or even worse, in the singular locus of the singular locus of V , etc. Using the Jacobian criterion and Gröbner bases to compute the vanishing ideal of the singular locus of V , would result in the complexity $D^{2^{O(n^2)}}$ as in (Neuhaus, 1998). To bypass complexity issues, we use techniques developed in the last decades to represent algebraic sets. Such techniques, which are now standard in computer algebra, consist in representing an equidimensional algebraic set $V \subset \mathbb{C}^n$ outside a Zariski closed set, hence often restricting to a subset of V which is a complete intersection. There are two main such representations, either triangular sets Wu (1984); Wang (1998) (also known as regular chains Kalkbrener (1991), tower of simple extensions Lazard (1991), regular set Moreno Maza (1997)) or rational parametrizations (also known as geometric resolutions) (see e.g. Giusti et al. (2001); Lecerf (2003); Schost (2003); Safey El Din and Schost (2017)). The following definition is folklore.

Definition 2. An r -dimensional rational parametrization $\mathcal{Q} = ((w, v_1, \dots, v_n), \ell)$ in $\mathbb{Q}[T_1, \dots, T_{r+1}]$ of degree δ consists of the following:

- a sequence of polynomials (w, v_1, \dots, v_n) in $\mathbb{Q}[T_1, \dots, T_{r+1}]$ such that the following holds: the variables T_1, \dots, T_{r+1} are new and w is square-free and monic and of degree δ in each variable T_1, \dots, T_{r+1} and, for $1 \leq i \leq n$, $\deg(v_i, T_{r+1}) < \deg(w, T_{r+1})$.
- $\ell = (\lambda_1, \dots, \lambda_{r+1})$ is a sequence of linear forms in variables X_1, \dots, X_n such that $\lambda_i(v_1, \dots, v_n) = T_i \frac{\partial w}{\partial T_{r+1}} \pmod{w}$.

The corresponding algebraic set $Z(\mathcal{Q}) \subset \mathbb{C}^n$ is the Zariski closure of the locally closed set of points $(x_1, \dots, x_n) \in \mathbb{C}^n$ such that $\exists \vartheta \in \mathbb{C}^{r+1}, w(\vartheta) = 0, \frac{\partial w}{\partial T_{r+1}}(\vartheta) \neq 0, x_i = \frac{v_i}{\partial w / \partial T_{r+1}}(\vartheta)$. Observe that $Z(\mathcal{Q})$ is equidimensional (using the Jacobian criterion) and that the Zariski closure of the image of $Z(\mathcal{Q})$ by the map $x \rightarrow (\lambda_1(x), \dots, \lambda_{r+1}(x))$ is defined by $w = 0$. Furthermore, the polynomial w is called the eliminating polynomial of the parametrization. Besides, the degree of w coincides with the degree of $Z(\mathcal{Q})$ (see Giusti et al. (2001); Lecerf (2003)). Finally, observe also that the parametrization ((1)) encodes the empty set. Equidimensional decompositions of algebraic sets whose components are represented by such parametrizations can be efficiently computed using (Lecerf, 2000). This is a key ingredient for the proof of the result below.

Theorem 3. Let $\mathbf{f} = (f_1, \dots, f_s) \subset \mathbb{Q}[X_1, \dots, X_n]$ of degrees bounded by D . Let r be the maximum of 1 and the dimension of the algebraic set $V_{\mathbb{C}}(\mathbf{f})$. Then, there exists a probabilistic algorithm **LazyRealRadical** which takes as input \mathbf{f} and returns rational parametrizations of the minimal associated primes of $\sqrt{\langle \mathbf{f} \rangle}$ using $s^{O(1)}(nD)^{O(nr2^r)}$ arithmetic operations in \mathbb{Q} .

Plan of the paper. In Section 2, we introduce some basic notions that will be used throughout the paper. In Section 3, we present an algorithm for computing generators of real radicals under the smoothness assumption and show the correctness and the complexity of the algorithm. In Section 4, we give a probabilistic algorithm to compute rational parametrizations for all irreducible components of an arbitrarily given real algebraic set. The last section is devoted to practical experiments.

2 Preliminaries

2.1 Ideals and varieties

For basic notions related to affine and projective spaces, ideals and algebraic sets (and their irreducible components), as well as equidimensionality we refer to Cox et al. (1992). For basic definitions on real algebraic sets and semi-algebraic sets, we refer to Bochnak et al. (1998). In the sequel, we use the following notations.

We denote by $\mathbb{P}^n(\mathbb{C})$ the n -dimensional *projective space* over \mathbb{C} . A subset of $\mathbb{P}^n(\mathbb{C})$ is called a *projective algebraic set* if it is the set of common zeros of some homogeneous polynomials in $\mathbb{Q}[X_0, X_1, \dots, X_n]$.

Let $S \subset \mathbb{C}^n$, we denote by \overline{S} the Zariski closure of S which is the smallest algebraic set containing S ; we denote by $I(S)$ the *vanishing ideal* of S which is the set of all polynomials in $\mathbb{Q}[X_1, \dots, X_n]$ vanishing identically over S .

Let $V \subset \mathbb{C}^n$ be an algebraic set. Let $I(V) = \langle f_1, \dots, f_s \rangle \subset \mathbb{Q}[X]$ and p be a point of V . The *tangent space* of V at p , denoted by $T_p(V)$, is given by $T_p(V) := \bigcap_{j=1}^s \left\{ x \in \mathbb{C}^n \mid \sum_{i=1}^n \frac{\partial f_j}{\partial X_i}(p) x_i = 0 \right\}$. The dimension of V at p , denoted by $\dim_p V$, is the maximum dimension of an irreducible component of V containing p . The point p is said to be *non-singular* (or *regular*) at V if $\dim T_p(V) = \dim_p V$. Otherwise, p is called a *singular point* of V . The *singular locus* of V is the set $\text{Sing}(V) := \{p \in V \mid p \text{ is a singular point of } V\}$. We say that V is *smooth* if V has no singular point, that is, $\text{Sing}(V) = \emptyset$.

All the notions above can be similarly defined for real algebraic sets in \mathbb{R}^n and projective algebraic sets in $\mathbb{P}^n(\mathbb{C})$.

Let $W \subset \mathbb{C}^n$ be an irreducible algebraic set and $r := \dim W$. The *degree* $\deg W$ of W is $\sup\{\#(H_1 \cap \dots \cap H_r \cap W)\}$ where H_1, \dots, H_r are hyperplanes in \mathbb{C}^n meeting W at finitely many points. If W is not irreducible, then its *degree* is defined to be the sum of the degrees of all its irreducible components.

2.2 Chow forms

We recall the definition of Chow forms (Gelfand et al., 1994, Chapter 3). Let $V \subset \mathbb{P}^n(\mathbb{C})$ be an irreducible projective set, where $\dim V = r$. For $i = 0, \dots, r$, we denote by $U_i = (U_{i0}, \dots, U_{in})$ a group of $n + 1$ variables and $U := (U_0, \dots, U_r)$. Let $L_i = U_{i0}X_0 + \dots + U_{in}X_n$, $i = 0, \dots, r$. The *Chow form* of the projective set V is the unique (up to a scalar factor) irreducible polynomial $\mathcal{F}_V \in \mathbb{Q}[U]$ such that for any $u_0, \dots, u_r \in \mathbb{C}^{n+1}$,

$$\mathcal{F}_V(u_0, \dots, u_r) = 0 \Leftrightarrow V \cap \{L_0(u_0, X) = 0, \dots, L_r(u_r, X) = 0\} \neq \emptyset$$

where $L_i(u_i, X) = u_{i0}X_0 + \dots + u_{in}X_n$, $i = 0, \dots, r$.

Let $W \subset \mathbb{P}^n(\mathbb{C})$ be an equidimensional projective set and W_i be its irreducible components ($1 \leq i \leq \ell$). The Chow form of W is defined as $\mathcal{F}_W = \prod_{i=1}^{\ell} \mathcal{F}_{W_i}$, where \mathcal{F}_{W_i} is the Chow form of W_i .

This definition can be extended to equidimensional affine algebraic sets in \mathbb{C}^n . Assume that we are given a finite sequence of polynomials $\mathbf{f} = (f_1, \dots, f_s)$ in $\mathbb{Q}[X_1, \dots, X_n]$ and let f_i^h be the homogenization of f_i using the new variable X_0 . Denote $\mathbf{f}^h = (f_1^h, \dots, f_s^h)$. Then the affine algebraic set $V := V_{\mathbb{C}}(\mathbf{f})$ can be identified with a subset of $\mathbb{P}^n(\mathbb{C})$ which is $V_{\mathbb{C}}(\mathbf{f}^h) \setminus V_{\mathbb{C}}(X_0)$, and the *projective closure* of V is the smallest projective algebraic set containing $V_{\mathbb{C}}(\mathbf{f}^h) \setminus V_{\mathbb{C}}(X_0)$ (see Cox et al., 1992, Chapter 8). The Chow form of V is defined to be the Chow form of its projective closure in $\mathbb{P}^n(\mathbb{C})$ (see Jeronimo et al., 2004, Section 1.1).

3 Algorithm for the smooth case

3.1 Preliminary results

Let V be a smooth and equidimensional algebraic set in \mathbb{C}^n defined by polynomials in $\mathbb{Q}[X]$ and let $m := (n - \dim V)(1 + \dim V)$. It has been shown in (Blanco et al., 2004, Theorem 10 and Corollary 17) that there exist polynomials g_1, \dots, g_m with $\deg g_i \leq \deg V$ such that g_1, \dots, g_m generate the ideal $I(V)$. Moreover, the polynomials g_1, \dots, g_m

can be obtained by specializing the Chow form of V at some generic linear forms with rational coefficients (see (Blanco et al., 2004, Section 4) for details). We slightly generalize this result.

Theorem 4. *Let V be a smooth algebraic set in \mathbb{C}^n of degree δ . There exists a finite set of polynomials $G = (g_1, \dots, g_s) \subset \mathbb{Q}[X]$ with $\max(\deg(g_i), i = 1, \dots, s) \leq \delta$ such that $\langle G \rangle = I(V)$.*

Proof. Set $r = \dim(V)$ and $V = \bigcup_{i=0}^r V_i$ be the minimal equidimensional decomposition of V , where V_i is either empty or i -equidimensional. Let $m_i := (n - i)(i + 1)$, for $i = 0, \dots, r$. By (Blanco et al., 2004, Theorem 10 and Corollary 17), there exist polynomials $g_1^{(i)}, \dots, g_{m_i}^{(i)}$ with degrees bounded by $\deg V_i$ such that $I(V_i) = \langle g_1^{(i)}, \dots, g_{m_i}^{(i)} \rangle$, for $i = 0, \dots, r$. Since V is smooth, according to (Cox et al., 1992, §9.6, Theorem 8), we have $V_i \cap V_j = \emptyset$ for any $0 \leq i < j \leq r$. Then $I(V_i) + I(V_j) = \langle 1 \rangle$ for all $0 \leq i < j \leq r$ and therefore $I(V) = \bigcap_{i=0}^r I(V_i)$ which equals $\left\langle \left\{ g_{j_0}^{(0)} \cdots g_{j_r}^{(r)} \mid 1 \leq j_0 \leq m_0, \dots, 1 \leq j_r \leq m_r \right\} \right\rangle$.

Moreover, $\deg \left(g_{j_0}^{(0)} \cdots g_{j_r}^{(r)} \right) \leq \deg V_0 + \dots + \deg V_r = \delta$. Let $G := \left\{ g_{j_0}^{(0)} \cdots g_{j_r}^{(r)} \mid 1 \leq j_0 \leq m_0, \dots, 1 \leq j_r \leq m_r \right\}$ we have $\langle G \rangle = I(V) = \sqrt{I}$ and $\deg(g) \leq \delta$ for all $g \in G$. \square

We recall now a well-known criterion for testing whether a given prime ideal is real.

Proposition 5. (Marshall, 2008, Theorem 12.6.1) *Let I be a prime ideal in $\mathbb{Q}[X]$, then I is real if and only if I has a non-singular real zero.*

Theorem 6. *Let \mathbf{f} be a finite polynomial sequence of $\mathbb{Q}[X]$ and $V := V_{\mathbb{C}}(\mathbf{f})$ of degree δ . If V is smooth, then $\sqrt[r]{\langle \mathbf{f} \rangle}$ has a finite set of generators $G \subset \mathbb{Q}[X]$ with $\deg(g) \leq \delta$ for $g \in G$.*

Proof. Let $V = \bigcup_{i=1}^s V_i$ be the minimal irreducible decomposition of V . Note that for $i = 1, \dots, s$, V_i is smooth (because V is) and $I(V_i)$ is prime. W.l.o.g. we assume that $V \cap \mathbb{R}^n \neq \emptyset$ since otherwise the conclusion is trivial. Let $\Omega := \{V_j \mid V_j \cap \mathbb{R}^n \neq \emptyset, 1 \leq j \leq s\}$. If $V_j \in \Omega$, then the prime ideal $I(V_j)$ has at least one non-singular real zero because V_j is smooth and $V_j \cap \mathbb{R}^n \neq \emptyset$. Therefore, according to Proposition 5, $I(V_j)$ is real for every $V_j \in \Omega$. Now we have $I(\overline{V \cap \mathbb{R}^n}) = I(V \cap \mathbb{R}^n) = I\left(\bigcup_{V_j \in \Omega} (V_j \cap \mathbb{R}^n)\right)$ which equals $\bigcap_{V_j \in \Omega} I(V_j \cap \mathbb{R}^n) = \bigcap_{V_j \in \Omega} I(V_j)$, where $\overline{V \cap \mathbb{R}^n}$ is the Zariski closure of $V \cap \mathbb{R}^n$ in \mathbb{C}^n , and the last equality follows from the fact that $I(V_j)$ is real. Note that the first equality holds because for any subset S of \mathbb{C}^n , S and its Zariski closure \overline{S} have the same vanishing ideal (see Cox et al., 1992, §4.4). It follows that $I(\overline{V \cap \mathbb{R}^n})$ and $\bigcap_{V_j \in \Omega} I(V_j)$ define the same algebraic set, that is, $\overline{V \cap \mathbb{R}^n} = \bigcup_{V_j \in \Omega} V_j$. Then,

$$\deg(\overline{V \cap \mathbb{R}^n}) = \sum_{V_j \in \Omega} \deg V_j \leq \sum_{i=1}^s \deg V_i = \deg V. \quad (1)$$

By the Real Nullstellensatz, $\sqrt[r]{\langle \mathbf{f} \rangle} = I(V \cap \mathbb{R}^n)$. We already observed that $I(\overline{V \cap \mathbb{R}^n}) = I(V \cap \mathbb{R}^n)$. Hence, we have $\sqrt[r]{\langle \mathbf{f} \rangle} = I(\overline{V \cap \mathbb{R}^n})$. Moreover, $\overline{V \cap \mathbb{R}^n}$ is smooth because V is smooth. The conclusion follows from Theorem 4 and the inequality (1). \square

3.2 Algorithm description

Let $\mathbf{f} = (f_1, \dots, f_s) \in \mathbb{Q}[X]$, and assume that $V = V_{\mathbb{C}}(\mathbf{f})$ is smooth of dimension r . Write the minimal equidimensional decomposition of V as $V = \bigcup_{i=1}^r V_i$, where V_i is either empty or is i -equidimensional. Denote by f_1^h, \dots, f_s^h the homogenizations of f_1, \dots, f_s using the new variable X_0 . Our algorithm uses several subroutines for computing generators of real radicals when $V = V_{\mathbb{C}}(\mathbf{f})$ is smooth.

- **PointsPerComponents.** It takes as input polynomials $f_1 = 0, \dots, f_s = 0$ and returns a set of real points meeting every connected component of $V_{\mathbb{R}}(f_1, \dots, f_s)$ (see Safey El Din, 2005).
- **Equidim.** It takes as input homogeneous polynomials $f_1^h, \dots, f_s^h, g \in \mathbb{Q}[X_0, \dots, X_n]$ and returns the Chow forms of all equidimensional components of $V_{\mathbb{C}}(f_1^h, \dots, f_s^h) \setminus V_{\mathbb{C}}(g)$ (see Jeronimo et al., 2004).
- **Generators.** It takes as input a Chow form \mathcal{F}_{V_i} of some equidimensional algebraic set V_i and returns a set of generators of the radical ideal $I(V_i)$ (see Blanco et al., 2004).

Let $V_i \subset \mathbb{C}^n$ be an equidimensional component of V and $V_i^h \subset \mathbb{P}^n$ denote the projective closure of V_i . Let $V_i = \bigcup_{j=1}^{m_i} V_{ij}$ be the minimal irreducible decomposition of V_i . Then $V_i^h = \bigcup_{j=1}^{m_i} V_{ij}^h$, where V_{ij}^h is the projective closure of V_{ij} . We can compute the Chow form \mathcal{F}_{V_i} of V_i by the subroutine **Equidim**. According to the definition of the Chow form, $\mathcal{F}_{V_i} = \prod_{j=1}^{m_i} \mathcal{F}_{V_{ij}}$. Therefore we can compute the Chow forms of all the irreducible components of V_i by factorizing \mathcal{F}_{V_i} over \mathbb{Q} . The following is the algorithm mentioned in Theorem 1.

RealRadicalSmooth(\mathbf{f})

1. $S = \text{PointsPerComponents}(\mathbf{f} = 0)$;
2. if $S = \emptyset$, then return $\{1\}$;
3. $\{\mathcal{F}_{V_0}, \dots, \mathcal{F}_{V_r}\} = \text{Equidim}(\mathbf{f}^h, X_0)$;
4. for $0 \leq i \leq r$ do
 - $\{\mathcal{F}_{V_{i1}}, \dots, \mathcal{F}_{V_{im_i}}\} \leftarrow$ irreducible factors of \mathcal{F}_{V_i} ;
5. $\Omega = \{\}$;
6. for $0 \leq i \leq r$ and $1 \leq j \leq m_i$ do
 - $G_{ij} = \text{Generators}(\mathcal{F}_{V_{ij}})$;
 - if $V_{\mathbb{C}}(G_{ij}) \cap S \neq \emptyset$ then $\Omega = \Omega \cup \{G_{ij}\}$;
7. return Ω .

3.3 Proof of Theorem 1

Probabilistic aspects. The algorithms used in Step 1,3,4,6 are probabilistic. The probability of success of these algorithms depends on choices of points in $\mathbb{Q}^{n^{O(1)}}$, and there exist a Zariski open set in $\mathbb{Q}^{n^{O(1)}}$ such that for all choices in this set yield correct answers for these algorithms in `RealRadicalSmooth`. In the following, we assume that all the probabilistic calls mentioned above perform correctly.

Correctness of algorithm `RealRadicalSmooth`. Let $V_{ij} := V_{\mathbb{C}}(G_{ij})$. Since V is smooth, by (Cox et al., 1992, §9.6, Theorem 8), its irreducible components V_{ij} do not intersect each other. Hence for each nonempty real algebraic set $V_{ij} \cap \mathbb{R}^n$, it contains at least one connected component of $V_{\mathbb{R}}(\mathbf{f})$, which implies that $V_{ij} \cap \mathbb{R}^n \neq \emptyset$ if and only if $V_{ij} \cap S \neq \emptyset$. On the other hand, the prime ideal $I(V_{ij})$ is real if and only if $V_{ij} \cap \mathbb{R}^n \neq \emptyset$ (see the proof of Theorem 6). Thus, $I(V_{ij})$ is real if and only if $V_{ij} \cap S \neq \emptyset$. Then we have $\sqrt[\text{re}]{\langle \mathbf{f} \rangle} = \bigcap_{V_{ij} \cap S \neq \emptyset} I(V_{ij})$ (Neuhaus, 1998, Lemma 2.2(a)). Finally, the ideals $I(V_{ij})$ are exactly the prime components of $\sqrt[\text{re}]{\langle \mathbf{f} \rangle}$ since V_{ij} are irreducible components of $V_{\mathbb{C}}(\mathbf{f})$. The correctness of the algorithm is proved.

Complexity analysis. The first step of `RealRadicalSmooth` computes a finite set S of real points meeting every connected component of the real algebraic set $V_{\mathbb{R}}(\mathbf{f})$. Many algorithms can be used (see Safey El Din and Schost (2003, 2004); Safey El Din (2005, 2007b,a)). Using Safey El Din (2007a) and by the complexity analysis in Safey El Din (2005), Step 1 uses $sL(nD^n)^{O(1)}$ arithmetic operations in \mathbb{Q} where L is the length of the straight-line program Γ .

Next, by (Jeronimo et al., 2004, Theorem 1), computing the Chow forms of all equidimensional components of $V_{\mathbb{C}}(f_1^h, \dots, f_s^h) \setminus V_{\mathbb{C}}(X_0)$ requires at most $sL(nD^n)^{O(1)}$ arithmetic operations in \mathbb{Q} . The Chow forms $\{\mathcal{F}_{V_0}, \dots, \mathcal{F}_{V_r}\}$ computed in Step 3 are encoded by straight-line programs of length bounded by $sL(nD^n)^{O(1)}$ (Jeronimo et al., 2004, Section 3.5).

Suppose that the straight-line program encoding \mathcal{F}_{V_i} has length L_i , then the cost of factorizing \mathcal{F}_{V_i} over \mathbb{Q} is polynomial in L_i and the total degree of \mathcal{F}_{V_i} (Kaltofen, 1989; Kaltofen and Trager, 1990). Note that the total degree of \mathcal{F}_{V_i} is bounded by $(i+1)D^n$, so Step 4 can be done using at most $(sLn(r+1)D^n)^{O(1)}$ arithmetic operations in \mathbb{Q} . Observe that $r \leq n-1$, we can bound $(sLn(r+1)D^n)^{O(1)}$ by $(sLnD^n)^{O(1)}$.

The cost of computing generators G_{ij} of $I(V_{ij})$ from the Chow form $\mathcal{F}_{V_{ij}}$ does not increase the order of the complexity of Step 4 (Blanco et al., 2004, Section 5.5). Deciding the emptiness of $V_{\mathbb{C}}(G_{ij}) \cap S$ is done by evaluating the polynomials of G_{ij} at all points of S , and its cost is negligible. Observe that L is bounded by $O(s(nD)^n)$ (see e.g. Krick (2002)). Therefore, in case of success, the algorithm `RealRadicalSmooth` uses $(snD^n)^{O(1)}$ arithmetic operations in \mathbb{Q} .

4 Lazy representations and non-smooth case

4.1 Preliminary results

The following result is folklore and extracted from Durvy and Lecerf (2008); Lecerf (2003).

Lemma 7. *Let $V \subset \mathbb{C}^n$ be an equi-dimensional algebraic set defined over \mathbb{Q} of dimension r . There exists a non-empty Zariski open set $\mathcal{G}(V) \subset \mathbb{C}^{n \times (r+1)}$ such that for $\ell \in \mathcal{G}(V) \cap \mathbb{Q}^{n \times (r+1)}$ the following holds. There exists a sequence of polynomials (w, v_1, \dots, v_n) in $\mathbb{Q}[T_1, \dots, T_{r+1}]$ such that $Z(\mathcal{Q}) = V$ with $\mathcal{Q} = ((w, v_1, \dots, v_n), \ell)$.*

Let $\mathcal{Q} = ((w, v_1, \dots, v_n), \ell = (\lambda_1, \dots, \lambda_{r+1}))$ be a rational parametrization. We define the polynomial $\sigma_{\mathcal{Q}}$ as the one obtained by substituting the variables T_1, \dots, T_{r+1} with the $\lambda_1, \dots, \lambda_{r+1}$ in $\frac{\partial w}{\partial T_{r+1}}$. We denote by $\mathcal{S}(\mathcal{Q})$ the intersection of $Z(\mathcal{Q})$ with $V_{\mathbb{C}}(\sigma_{\mathcal{Q}})$. The following lemma is pointed out as a remark in the conclusion of Lecerf (2000).

Lemma 8. *Under the above notations, the ideal associated to $Z(\mathcal{Q})$ in $\mathbb{Q}[X_1, \dots, X_n]$ is prime if and only if w is irreducible over \mathbb{Q} .*

Lemma 9. *Assume that the vanishing ideal of $Z(\mathcal{Q})$ in $\mathbb{Q}[X]$ is prime. Then, it is real if and only if one of the following equivalent conditions are satisfied:*

- (i) $Z(\mathcal{Q})$ contains a real regular point;
- (ii) the semi-algebraic set defined by $w = 0, \frac{\partial w}{\partial T_{r+1}} \neq 0$ is non-empty.

In particular, if the vanishing ideal of $Z(\mathcal{Q})$ is not real, then $Z(\mathcal{Q}) \cap \mathbb{R}^n$ coincides with $\mathcal{S}(\mathcal{Q}) \cap \mathbb{R}^n$.

Proof. We denote $h = \frac{\partial w}{\partial T_{r+1}}$ and I the vanishing ideal of $Z(\mathcal{Q})$. By (Marshall, 2008, Theorem 12.6.1) I is real if and only if it has a regular real zero which is equivalent to the assertion that $Z(\mathcal{Q})$ contains a regular real point.

Now we prove that the condition (ii) holds if and only if I is real. Without loss of generality, we assume that the linear forms $\lambda_i = X_i$ for $i = 1, \dots, r+1$. Then $T_i = X_i$ for $i = 1, \dots, r+1$.

If the semi-algebraic set defined by $w = 0, h \neq 0$ is not empty, that is, there exists $\vartheta \in \mathbb{R}^{r+1}$ such that $w(\vartheta) = 0$ and $h(\vartheta) \neq 0$, then we have a real point $x = (\frac{v_1}{h}(\vartheta), \dots, \frac{v_n}{h}(\vartheta)) \in Z(\mathcal{Q})$. It follows from the definition of $Z(\mathcal{Q})$ and the Hilbert Nullstellensatz that the polynomials $w, hX_{r+2} - v_{r+2}, \dots, hX_n - v_n$ belong to I . Then x is a regular real zero of I because the Jacobian matrix of $w, hX_{r+2} - v_{r+2}, \dots, hX_n - v_n$ has rank $n - r$ at the point x . Thus the ideal I is real.

Conversely, if the set $\{\vartheta \in \mathbb{R}^{r+1} \mid w(\vartheta) = 0, h(\vartheta) \neq 0\}$ is empty, then we have $Z(\mathcal{Q}) \cap \mathbb{R}^n \subset Z(\mathcal{Q}) \cap V_{\mathbb{C}}(\sigma_{\mathcal{Q}})$. On the other hand, $Z(\mathcal{Q}) \cap V_{\mathbb{C}}(\sigma_{\mathcal{Q}})$ has dimension less than $\dim(Z(\mathcal{Q}))$ (since $Z(\mathcal{Q})$ is irreducible and $Z(\mathcal{Q}) \cap V_{\mathbb{C}}(\sigma_{\mathcal{Q}})$ is strictly contained in $Z(\mathcal{Q})$). Hence $Z(\mathcal{Q}) \cap \mathbb{R}^n$ has dimension less than $\dim(Z(\mathcal{Q}))$, which implies that the vanishing ideal of $Z(\mathcal{Q})$ is not real. \square

From the proof of Lemma 9, we immediately have the following corollary:

Corollary 10. *Under the above notations, assume that $Z(\mathcal{Q})$ is irreducible, then $\mathcal{S}(\mathcal{Q})$ has dimension strictly less than $\dim(Z(\mathcal{Q}))$.*

4.2 Subroutines

In this paragraph, we describe the subroutines used in the main algorithm.

Subroutine IrreducibleDecomposition This subroutine aims at performing the following. Given a straight-line program of length L which evaluates a sequence of polynomials $\mathbf{f} = (f_1, \dots, f_s)$ in $\mathbb{Q}[X]$, it outputs a list of rational parametrizations encoding the irreducible components of $V_{\mathbb{C}}(\mathbf{f})$. This computation simply consists of calling the equidimensional decomposition algorithm in Lecerf (2000) which uses $(sLnD^n)^{O(1)}$ operations in \mathbb{Q} to return zero-dimensional parametrizations of generic points in $V_{\mathbb{C}}(\mathbf{f})$. Combined with the Hensel lifting technique in Giusti et al. (2001) (which are actually used in Lecerf (2000)), that algorithm allows to recover r -equidimensional parametrizations for the components of dimension r . The total cost becomes $(snD^{n \max(1,r)})^{O(1)}$. Deducing from this the irreducible components is then easily done by factoring the eliminating polynomials of the parametrizations (the one which vanishes in the representation); the cost of this latter step is negligible Kaltofen (1989); Kaltofen and Trager (1990).)

Lemma 11. *Let $\mathbf{f} = (f_1, \dots, f_s)$ be a sequence of polynomials in $\mathbb{Q}[X]$ of degree bounded by D and V be the algebraic set defined by \mathbf{f} with $r = \dim(V)$. There exists a probabilistic algorithm which computes a list of rational parametrizations encoding the irreducible components of V using $(snD^{n \max(1,r)})^{O(1)}$ operations in \mathbb{Q} .*

Subroutine IsReal Let \mathcal{Q} be a rational parametrization in $\mathbb{Q}[T_1, \dots, T_{r+1}]$ of degree δ with $Z(\mathcal{Q})$ irreducible, the subroutine **IsReal** decides if $Z(\mathcal{Q})$ contains a real regular point in time $\delta^{O(r)}$.

Lemma 12. *Let $\mathcal{Q} = (w, v_1, \dots, v_n, \ell)$ be a rational parametrization in $\mathbb{Q}[T_1, \dots, T_{r+1}]$ of degree δ such that $Z(\mathcal{Q})$ is irreducible. There exists an algorithm **IsReal** which returns true if $Z(\mathcal{Q})$ contains real regular points or false otherwise. It uses $\delta^{O(\max(1,r))}$ arithmetic operations in \mathbb{Q} .*

Proof. By Lemma 9, it suffices to decide if the semi-algebraic system $w = 0, \frac{\partial w}{\partial T_{r+1}} \neq 0$ has a real solution. Using (Basu et al., 2006, Chapter 14), this can be done using $\delta^{O(\max(1,r))}$ arithmetic operations in \mathbb{Q} . \square

Subroutine ChangeSeparatingElement We describe now a subroutine which takes as input a rational parametrization encoding an equidimensional algebraic set Z using linear forms ℓ and returns a new sequence of linear forms ℓ' and which computes a new rational parametrization still encoding Z but using ℓ' .

Lemma 13. *Let $\mathcal{Q} = ((w, v_1, \dots, v_n), \ell)$ be a rational parametrization of degree δ encoding a r -equidimensional algebraic set Z and ℓ in the non-empty Zariski open set $\mathcal{G}(Z)$ defined in Lemma 7.*

*Then, there exists a routine **ChangeSeparatingElement** which computes a rational parametrization $\mathcal{Q}' = ((w', v'_1, \dots, v'_n), \ell')$ using $(r+1)(n\delta)^{O(\max(1,r))}$ arithmetic operations in \mathbb{Q} .*

Proof. The algorithm for changing one linear form works as in the proof of (Safey El Din and Schost, 2017, Lemma J.8 of the electronic Appendix). It simply consists in using the algorithm underlying (Poteaux and Schost, 2013, Lemma 2) which performs this operation in the zero-dimensional case in time $(n\delta)^{O(1)}$.

Here, we deal with positive dimensional situations. In (Safey El Din and Schost, 2017, Lemma J.8 of the Appendix), the one dimensional situation is tackled by performing

operations in a univariate power series ring $\mathbb{Q}[[T_1 - y_1]]$ (where y_1 is chosen randomly) by applying (Poteaux and Schost, 2013, Lemma 2). Doing this allows us to use the algorithm designed for the zero-dimensional case but performing operations in $\mathbb{Q}[[T_1 - y_1]]$ and truncate computations up to $\deg(\mathcal{Q}) + 1$. The extra cost of such a strategy is just the extra cost induced by the arithmetics in $\mathbb{Q}[[T_1 - y_1]]$.

To tackle the r -dimensional case, we do the same but using power series ring $\mathbb{Q}[[T_1 - y_1, \dots, T_r - y_r]]$ where y_1, \dots, y_r are chosen randomly and truncating computations again up to the degree of \mathcal{Q} . Again the extra cost comes from arithmetic operations in $\mathbb{Q}[[T_1 - y_1, \dots, T_r - y_r]]$ which is dominated by $(n\delta)^{O(r)}$ since computations are truncated up to $\deg(\mathcal{Q}) + 1$.

Now, changing $r + 1$ linear forms requires to perform the above operations $r + 1$ times. \square

Subroutine Intersect Let $\mathcal{Q} = ((w, v_1, \dots, v_n), \ell)$ with $\ell = (\lambda_1, \dots, \lambda_{r+1})$ be a rational parametrization in $\mathbb{Q}[T_1, \dots, T_{r+1}]$ and $g \in \mathbb{Q}[T_1, \dots, T_{r+1}]$. We denote by $g_{\mathcal{Q}}$ the polynomial $g(\lambda_1, \dots, \lambda_{r+1}) \in \mathbb{Q}[X]$. A key step for our algorithm is to compute $Z(\mathcal{Q}) \cap V_{\mathbb{C}}(g_{\mathcal{Q}})$

Lemma 14. *Let $\mathcal{Q} = ((w, v_1, \dots, v_n), \ell)$ be a rational parametrization in $\mathbb{Q}[T_1, \dots, T_{r+1}]$ encoding an equidimensional algebraic set $Z = Z(\mathcal{Q}) \subset \mathbb{C}^n$ of dimension $r \geq 1$ and degree δ and let g be a polynomial in $\mathbb{Q}[T_1, \dots, T_{r+1}]$ of degree δ' . Assume that the intersection of Z with $V_{\mathbb{C}}(g_{\mathcal{Q}})$ has dimension $r - 1$. There exists an algorithm **Intersect** which on input (\mathcal{Q}, g) outputs a list of rational parametrizations encoding the irreducible components of $Z \cap V_{\mathbb{C}}(g_{\mathcal{Q}})$ in time $(n \max(\delta, \delta'))^{O(r)}$.*

Proof. The algorithm starts by choosing randomly a sequence of $r + 1$ linear forms $\ell' = (\lambda'_1, \dots, \lambda'_{r+1})$ in X_1, \dots, X_n assuming that ℓ' lies in the non-empty Zariski open set $\mathcal{G}(Z)$ (defined in Lemma 7).

Recall that Z is r -equidimensional. Observe that by Krull's theorem Eisenbud (1995), $Z \cap V_{\mathbb{C}}(g_{\mathcal{Q}})$ is either empty or has dimension greater than or equal to $r - 1$ and hence none of its irreducible components has dimension less than $r - 1$. Since, by assumption, $\dim(Z \cap V_{\mathbb{C}}(g_{\mathcal{Q}})) = r - 1$, we deduce that it is equidimensional (of dimension $r - 1$).

Hence, it makes sense to assume additionally that the first r linear forms of ℓ' lie in the non-empty Zariski open set $\mathcal{G}(Z \cap V_{\mathbb{C}}(g_{\mathcal{Q}}))$ (see again Lemma 7). Another assumption of the same nature will be done and stated precisely below.

Next, one computes a rational parametrization $\mathcal{Q}' = ((w', v'_1, \dots, v'_n), \ell')$ defining Z . For clarity, we denote by T'_1, \dots, T'_{r+1} the variables involved in \mathcal{Q}' . Lemma 13 establishes that this step can be performed using $(r + 1)(n\delta)^{O(r)}$ arithmetic operations in \mathbb{Q} .

Now, we want to compute a rational parametrization of the intersection of $Z = Z(\mathcal{Q}')$ with $V_{\mathbb{C}}(g_{\mathcal{Q}})$. The process we would like to mimic is as follows:

1. substitute in g the variables T_1, \dots, T_{r+1} by the linear forms $\lambda_1, \dots, \lambda_{r+1}$ used in \mathcal{Q} (hence yielding an explicit representation of $g_{\mathcal{Q}}$);
2. substitute the X_i 's by their parametrizations in \mathcal{Q}' , hence obtaining a rational fraction g' (it lies in $\mathbb{Q}(T'_1, \dots, T'_{r+1})$);

3. compute a representation of the intersection of the vanishing sets of the numerator of g' and w' (through subresultant computations as in Giusti et al. (2001)) and deduce from that a rational representation of $Z \cap V_{\mathbb{C}}(g_{\mathcal{Q}})$.

Carrying out directly these steps without taking care of denominators does not allow us to obtain the announced complexity statement.

To achieve the announced complexity bound, we use a classical evaluation interpolation technique: that will allow us to obtain a better control on the monomial combinatorics and handle the presence of denominators.

Instead of computing an explicit representation of $g_{\mathcal{Q}}$, we will actually build a straight-line program Γ evaluating it. Since g is a polynomial of degree δ' involving $r+1$ variables and since ℓ is composed of $r+1$ linear forms in X_1, \dots, X_n which are equal to T_1, \dots, T_{r+1} , the length of such a straight-line program is bounded by $(r\delta')^{O(r)} + O(nr)$.

Evaluating the rational fraction g' defined above is then obtained by stacking to Γ the parametrizations $X_i = \frac{v'_i}{\partial w' / \partial T_{r+1}}$. Evaluating all parametrizations can be done using $(n\delta)^{O(r)}$ operations in \mathbb{Q} (because the polynomials in \mathcal{Q}' have degree $\leq \delta$ and involve $r+1$ variables). In the end, one can evaluate g' using $(r\delta')^{O(r)} + O(nr) + (n\delta)^{O(r)}$ arithmetic operations in \mathbb{Q} .

Now take $y = (y_1, \dots, y_{r-1})$ in \mathbb{Q}^{r-1} . Substituting the variables T'_1, \dots, T'_{r-1} by y_1, \dots, y_{r-1} in g' is done thanks to the procedure described above in time $(r\delta')^{O(r)} + O(nr) + (n\delta)^{O(r)}$.

For y as above, we denote by g'_y the obtained rational fraction. Similarly, \mathcal{Q}'_y denotes the rational parametrization obtained by substituting the variables T'_1, \dots, T'_{r-1} with y_1, \dots, y_{r-1} in \mathcal{Q}' .

Using the intersection algorithm of Giusti et al. (2001) with input \mathcal{Q}'_y and the numerator of g'_y , one computes a zero-dimensional rational parametrization encoding $Z \cap V_{\mathbb{C}}(g_{\mathcal{Q}}) \cap V_{\mathbb{C}}(\ell'_y)$.

Since, by Bézout's theorem, the intersection of Z with $V_{\mathbb{C}}(g_{\mathcal{Q}})$ has degree bounded by $\delta'\delta$, it is sufficient to repeat this process $(\delta'\delta)^{O(r)}$ times to interpolate a rational parametrization for $Z \cap V_{\mathbb{C}}(g_{\mathcal{Q}})$. The last step consists in extracting from that parametrization the irreducible components of $Z \cap V_{\mathbb{C}}(g_{\mathcal{Q}})$ by factoring the eliminating polynomial of \mathcal{Q} . The complexity statement follows easily. \square

Subroutine RemoveRedundantComponents Let $\mathcal{L} = (\mathcal{Q}_1, \dots, \mathcal{Q}_t)$ be a list of rational parametrizations such that, for $1 \leq i \leq t$, $Z(\mathcal{Q}_i)$ is irreducible. The routine **RemoveRedundantComponents** returns a subset of \mathcal{L} say, $\mathcal{Q}_{i_1}, \dots, \mathcal{Q}_{i_k}$ such that, $Z(\mathcal{Q}_{i_1} \cup \dots \cup \mathcal{Q}_{i_k}) = Z(\mathcal{Q}_1) \cup \dots \cup Z(\mathcal{Q}_t)$ and, for $u \neq v$, $Z(\mathcal{Q}_{i_u}) \not\subset Z(\mathcal{Q}_{i_v})$.

Lemma 15. Let $\mathcal{L} = (\mathcal{Q}_1, \dots, \mathcal{Q}_t)$ be a list of rational parametrizations with δ_i being the degree of \mathcal{Q}_i and δ be the maximum of $\delta_1, \dots, \delta_t$. Assume that for $1 \leq i \leq t$, $Z(\mathcal{Q}_i)$ is irreducible of dimension r_i ; let r be the maximum of 1 and r_1, \dots, r_t .

There exists an algorithm **RemoveRedundantComponents** which on input \mathcal{L} returns a subset $\mathcal{Q}_{i_1}, \dots, \mathcal{Q}_{i_k}$ of \mathcal{L} such that, the following holds:

- $Z(\mathcal{Q}_{i_1}) \cup \dots \cup Z(\mathcal{Q}_{i_k}) = Z(\mathcal{Q}_1) \cup \dots \cup Z(\mathcal{Q}_t)$;
- for $u \neq v$, $Z(\mathcal{Q}_{i_u}) \not\subset Z(\mathcal{Q}_{i_v})$.

It uses $t(r+1)(n\delta)^{O(r)}$ operations in \mathbb{Q} .

Proof. The algorithm starts by sorting (in ascending order) the rational parametrizations according to their dimension. Up to renumbering, one may assume that $\mathcal{Q}_1, \dots, \mathcal{Q}_t$ are already sorted by nondecreasing dimension (i.e. $r_i \leq r_{i+1}$). The algorithm starts by choosing randomly $r+1$ linear forms $\ell = (\lambda_1, \dots, \lambda_{r+1})$ and call the routine **ChangeSeparatingElement** with input \mathcal{Q}_i and $(\lambda_1, \dots, \lambda_{r+1})$. According to Lemma 13, this step uses $t(r+1)(n\delta)^{O(r)}$ operations in \mathbb{Q} . To keep notations simple, we keep on naming $\mathcal{Q}_1, \dots, \mathcal{Q}_t$ for the obtained rational parametrizations. Since, by assumption, the rational parametrizations define irreducible algebraic sets, one only needs to decide if $Z(\mathcal{Q}_i) \subset Z(\mathcal{Q}_j)$ for $i < j$ and $r_i < r_j$. Thanks to the change of separating element, it then suffices to pick a random rational point in \mathbb{Q}^{r_i-1} and specialize both in \mathcal{Q}_i and \mathcal{Q}_j the parameters corresponding to $\lambda_1, \dots, \lambda_{r_i}$. Hence, we are led to decide the inclusion of a finite set of points in an algebraic set ; both are given by a rational parametrization. This boils down to standard Euclidean remainder computations (see Lecerf (2003)). \square

4.3 Description of main algorithm

The algorithm takes as input a sequence $\mathbf{f} = (f_1, \dots, f_s)$ of polynomials in $\mathbb{Q}[X_1, \dots, X_n]$ of degree bounded by D .

It returns a list of rational parametrizations, each of which defining a prime component of the real radical ideal generated by \mathbf{f} .

The algorithm starts by calling **IrreducibleDecomposition** to compute a finite sequence of rational parametrizations $\mathcal{R}_1, \dots, \mathcal{R}_t$ encoding the irreducible components of $V_{\mathbb{C}}(\mathbf{f})$. Next, for $1 \leq i \leq t$, one computes a list of rational parametrizations encoding the irreducible components of the real radical associated to $Z(\mathcal{R}_i)$. This is done by calling a routine called **LazyRealRadicalRec** which is described further. Finally, the routine **RemoveRedundantComponents** is called with input the list of all previously computed rational parametrizations to remove redundancies.

LazyRealRadical(\mathbf{f})

1. $(\mathcal{R}_1, \dots, \mathcal{R}_t) = \text{IrreducibleDecomposition}(\mathbf{f});$
2. if $t = 1$ and $\mathcal{R}_1 = (1)$ then return $((1));$
3. $\text{res} = \{\};$
4. for $1 \leq j \leq t$ do
 - $\text{res} = \text{res} \cup \text{LazyRealRadicalRec}(\mathcal{R}_j);$
5. return **RemoveRedundantComponents**(res).

We describe now the routine **LazyRealRadicalRec**. It takes as input a rational parametrization \mathcal{Q} and outputs a list of rational parametrizations encoding the irreducible algebraic sets defined by the prime components of the real radical associated to $Z(\mathcal{Q})$.

It works as follows. First, it decides if $Z(\mathcal{Q})$ contains real regular points using the routine **IsReal**. If this is the case, then it returns \mathcal{Q} , else it computes rational parametrizations encoding the prime components of the set $\mathcal{S}(\mathcal{Q})$ and performs a recursive call with input these parametrizations.

LazyRealRadicalRec(\mathcal{Q})

1. if $\mathcal{Q} = (1)$ then return (1);
2. if $\text{IsReal}(\mathcal{Q})$ then return (\mathcal{Q});
3. let w be the eliminating polynomial of \mathcal{Q} in $\mathbb{Q}[T_1, \dots, T_{r+1}]$;
4. $(\mathcal{Q}'_1, \dots, \mathcal{Q}'_k) = \text{Intersect}(\mathcal{Q}, \frac{\partial w}{\partial T_{r+1}})$;
5. for $1 \leq \ell \leq k$ do
 - $\text{res} = \text{res} \cup \text{LazyRealRadicalRec}(\mathcal{Q}'_\ell)$;
6. return $\text{RemoveRedundantComponents}(\text{res})$.

4.4 Proof of Theorem 3

We start by proving correctness and termination.

Proof. On input \mathbf{f} , LazyRealRadical starts by computing an irreducible decomposition of the algebraic set defined by \mathbf{f} by means of rational parametrizations $\mathcal{R}_1, \dots, \mathcal{R}_t$. The next step consists in computing rational parametrizations encoding the prime components of the real radical associated to $Z(\mathcal{R}_i)$ for $1 \leq i \leq t$.

This is done through the call to the routine LazyRealRadicalRec. Hence, the main step for proving correctness of LazyRealRadical consists in proving the correctness of LazyRealRadicalRec. Recall that it takes as input a rational parametrization \mathcal{Q} encoding an irreducible algebraic set. We prove its correctness by decreasing induction on the dimension of $Z(\mathcal{Q})$. The case where the $Z(\mathcal{Q})$ is finite is immediate; hence we assume below that $Z(\mathcal{Q})$ has positive dimension, say r , and terminates and is correct on inputs encoding algebraic sets of dimension less than r .

The routine LazyRealRadicalRec decides if the prime ideal associated to $Z(\mathcal{Q})$ is real by calling the routine IsReal. If this is the case, \mathcal{Q} is returned as expected. Else, it computes a decomposition of $\mathcal{S}(\mathcal{Q})$ following Lemma 9. Besides, Corollary 10 establishes that $\mathcal{S}(\mathcal{Q})$ has dimension strictly less than $\dim(Z(\mathcal{Q}))$. Termination and correctness follow by the induction assumption. □

We can now prove the complexity statement.

Proof. The first step of LazyRealRadical consists in calling the routing IrreducibleDecomposition which uses $(snD^{nr})^{O(1)}$ arithmetic operations in \mathbb{Q} (Lemma 11) where r is the maximum of 1 and the dimension of the algebraic set defined by the input \mathbf{f} . By Bézout's theorem, the sum of the degrees of the irreducible components encoded by the output is bounded by D^n . Hence, we have $t \leq D^n$ and for $1 \leq i \leq t$, the degree of \mathcal{R}_i is bounded by D^n .

Next, one enters in the loop and call t times LazyRealRadicalRec with \mathcal{R}_i as input (for $1 \leq i \leq t$). Below, we prove that running LazyRealRadicalRec with input a rational parametrization, say \mathcal{Q} , of degree δ encoding an irreducible algebraic set of dimension ρ takes $(n\delta)^{O(2^\rho)}$ arithmetic operations in \mathbb{Q} and the sum of the degrees of the rational

parametrizations it outputs lies in $(n\delta)^{O(2^\rho)}$. Hence, the whole cost of the “for loop” is $(nD)^{O(n2^r)}$.

The last step consists in calling the routine `RemoveRedundantComponents`. Lemma 15 allows to estimate the complexity of this step. All in all, the total cost is bounded by $s^{O(1)}(nD)^{O(nr2^r)}$.

We prove now the claim on the complexity of `LazyRealRadicalRec`. The first step consists in calling subroutine `IsReal` on input \mathcal{Q} . This call takes $\delta^{O(\rho)}$ arithmetic operations in \mathbb{Q} (Lemma 12). When it returns true, \mathcal{Q} is returned else a call to `Intersect` is performed with input \mathcal{Q} and $\frac{\partial w}{\partial T_{\rho+1}}$ where w is the eliminating polynomial of \mathcal{Q} . By Lemma 14, this uses $(n\delta)^{O(\rho)}$ arithmetic operations in \mathbb{Q} .

The sum of the degrees of the output is bounded by δ^2 but the dimension of these output rational parametrizations is $\rho-1$. Hence, denoting by $T(\delta, \rho)$ the cost of `LazyRealRadicalRec` on input a rational parametrization of degree δ encoding an irreducible algebraic set of dimension ρ , the following recursive formula holds:

$$T(\delta, \rho) \leq (n\delta)^{O(\rho)} + T(\delta^2, \rho - 1).$$

Solving this recurrence formula yields a complexity $(n\delta)^{O(2^\rho)}$. The same formula occurs for the degree bounds on the output. Hence, we are done. \square

As for algorithm `RealRadicalSmooth`, most of subroutines which are used in `LazyRealRadical` are probabilistic: they rely on either generic specialization points or generic choices of linear changes of variables (or linear forms).

5 Experiments

We give several examples to show the efficiency of our approach. All the examples given below are beyond the reach of the Singular library `realrad` implemented by Spang (Spang, 2007) which is, up to our knowledge, the single available implementation of the algorithm given by Becker and Neuhaus (1993); Neuhaus (1998). That implementation is based on Gröbner bases.

Observe that one can use Singular functionalities to compute equidimensional/prime decompositions and intersections of ideals as well as elimination ideals, by means of Gröbner bases. Hence, one can “simulate” `LazyRealRadical` using those functionalities combined with the `HasRealSolutions` function in the Maple library `RAGlib` Safey El Din (2007a).

In a word, taking a polynomial sequence \mathbf{f} as input, we will obtain generators of the minimal associated primes of $\sqrt[\mathbb{R}]{\langle \mathbf{f} \rangle}$.

The computations were performed on an Intel(R) Xeon(R) CPU E7-4809 v2 @ 1.90GHz and 756GB of RAM.

Example 16 (Vor1). *The following polynomial comes from (Everett et al., 2009):*

$$\begin{aligned} \text{Vor1} = & (\alpha^2 + \beta^2 + 1)a^2\lambda^4 - 2a(2a\beta^2 + ay\beta + a\alpha x - \beta\alpha + 2a + 2a\alpha^2 - \beta\alpha a^2)\lambda^3 \\ & + (\beta^2 + 6a^2\beta^2 - 2\beta xa^3 - 6\beta\alpha a^3 + 6y\beta a^2 - 6a\beta\alpha - 2a\beta x + 6\alpha xa^2 + y^2 a^2 \\ & - 2a\alpha y + x^2 a^2 - 2y\alpha a^3 + 6a^2\alpha^2 + a^4\alpha^2 + 4a^2)\lambda^2 \\ & - 2(xa - ya^2 - 2\beta a^2 - \beta + 2a\alpha + \alpha a^3)(xa - y - \beta + a\alpha)\lambda + (1 + a^2)(xa - y - \beta + a\alpha)^2. \end{aligned}$$

This polynomial is a sum of squares (Kaltofen et al., 2008), thus the ideal $\langle \text{Vor1} \rangle$ is not real. Take Vor1 as input and we obtain in 9 sec. the minimal primes of the real radical $\sqrt[\text{re}]{\langle \text{Vor1} \rangle}$:

$$P_1 = \langle a\alpha - ax + \beta - y, \lambda + 1 \rangle, P_2 = \langle a\alpha + ax - \beta - y, \lambda \rangle, P_3 = \langle 2\beta\lambda + \beta + y, a \rangle.$$

Example 17. Consider the discriminant \mathcal{D} of the characteristic polynomial of the following linear symmetric matrix:

$$\begin{pmatrix} x & 1 & 1 \\ 1 & y & 1 \\ 1 & 1 & z \end{pmatrix}.$$

It has been proved that \mathcal{D} is a sum of squares (Lax, 2005). On input \mathcal{D} , our algorithm computed in 4 sec. the real radical $\sqrt[\text{re}]{\langle \mathcal{D} \rangle}$. It has only one minimal prime which is $\langle y - z, g \rangle$ where

$$\begin{aligned} g = & -19y^{12} + 228y^{11}z - 1254y^{10}z^2 + 4180y^9z^3 - 9405y^8z^4 + 15048y^7z^5 - 17556y^6z^6 + 15048y^5z^7 \\ & - 9405y^4z^8 + 4180y^3z^9 - 1254y^2z^{10} + 228yz^{11} - 19z^{12} - 606y^{10} + 6060y^9z - 27270y^8z^2 \\ & + 72720y^7z^3 - 127260y^6z^4 + 152712y^5z^5 - 127260y^4z^6 + 72720y^3z^7 - 27270y^2z^8 + 6060yz^9 \\ & - 606z^{10} - 6732y^8 + 53856y^7z - 188496y^6z^2 + 376992y^5z^3 - 471240y^4z^4 + 376992y^3z^5 \\ & - 188496y^2z^6 + 53856yz^7 - 6732z^8 - 35370y^6 + 212220y^5z - 530550y^4z^2 + 707400y^3z^3 \\ & - 530550y^2z^4 + 212220yz^5 - 35370z^6 - 116073y^4 + 464292y^3z - 696438y^2z^2 + 464292yz^3 \\ & - 116073z^4 - 77760y^2 + 155520yz - 77760z^2 + 139968x - 69984y - 69984z. \end{aligned}$$

Example 18 (Homotopy-1). This example is taken from Chen et al. (2013):

$$f_1 = x^3y^2 + c_1x^3y + y^2 + c_2x + c_3, f_2 = c_4x^4y^2 - x^2y + y + c_5, f_3 = c_4 - 1.$$

Take the sequence $\mathbf{f} = (f_1, f_2, f_3)$ as input and we obtain in a single second that $\sqrt[\text{re}]{\langle \mathbf{f} \rangle}$ has only one minimal prime which is the ideal $\langle \mathbf{f} \rangle$. This shows that the ideal $\langle \mathbf{f} \rangle$ is prime and real.

Example 19 (Cinquin-3-4). This is also an example taken from Chen et al. (2013):

$$f_1 = s - x_1(1 + x_2^4 + x_3^4), f_2 = s - x_2(1 + x_1^4 + x_3^4), f_3 = s - x_3(1 + x_1^4 + x_2^4).$$

We obtain in 47 sec. the minimal primes of $\sqrt[\text{re}]{\langle \mathbf{f} \rangle}$ for $\mathbf{f} = (f_1, f_2, f_3)$:

$$\begin{aligned} P_1 &= \langle x_3 - x_1, x_2 - x_1, -x_3^4x_1 - x_2^4x_1 - x_1 + s \rangle, \\ P_2 &= \langle x_3 - x_1, x_2^3x_1 + x_2^2x_1^2 + x_2x_1^3 - x_1^4 - 1, -x_3^4x_1 - x_2^4x_1 - x_1 + s \rangle, \\ P_3 &= \langle x_2 - x_1, x_3^3x_1 + x_3^2x_1^2 + x_3x_1^3 - x_1^4 - 1, -x_3^4x_1 - x_2^4x_1 - x_1 + s \rangle, \\ P_4 &= \langle x_3 - x_2, x_2^4 - x_2^3x_1 - x_2^2x_1^2 - x_2x_1^3 + 1, -x_3^4x_1 - x_2^4x_1 - x_1 + s \rangle. \end{aligned}$$

Example 20 (Essential Variety). This is an example taken from Fløystad et al. (2017). Let \mathcal{E} be the essential variety defined as:

$$\mathcal{E} = \{M \in \mathbb{R}^{3 \times 3} \mid \det(M) = 0, 2(MM^T)M - \text{tr}(MM^T)M = 0\},$$

where $\det(M)$ is the determinant of M and $\text{tr}(MM^T)$ is the trace of MM^T .

If we write the matrix M as

$$\begin{pmatrix} a & b & c \\ u & v & w \\ x & y & z \end{pmatrix},$$

then the 10 cubics defining \mathcal{E} are:

$$\begin{aligned} & avz - awy - buz + bwx + cuy - cvx, \\ & (2a^2 + 2b^2 + 2c^2)a + (2au + 2bv + 2cw)u + (2ax + 2by + 2cz)x - ga, \\ & (2a^2 + 2b^2 + 2c^2)b + (2au + 2bv + 2cw)v + (2ax + 2by + 2cz)y - gb, \\ & (2a^2 + 2b^2 + 2c^2)c + (2au + 2bv + 2cw)w + (2ax + 2by + 2cz)z - gc, \\ & (2au + 2bv + 2cw)a + (2u^2 + 2v^2 + 2w^2)u + (2ux + 2vy + 2wz)x - gu, \\ & (2au + 2bv + 2cw)b + (2u^2 + 2v^2 + 2w^2)v + (2ux + 2vy + 2wz)y - gv, \\ & (2au + 2bv + 2cw)c + (2u^2 + 2v^2 + 2w^2)w + (2ux + 2vy + 2wz)z - gw, \\ & (2ax + 2by + 2cz)a + (2ux + 2vy + 2wz)u + (2x^2 + 2y^2 + 2z^2)x - gx, \\ & (2ax + 2by + 2cz)b + (2ux + 2vy + 2wz)v + (2x^2 + 2y^2 + 2z^2)y - gy, \\ & (2ax + 2by + 2cz)c + (2ux + 2vy + 2wz)w + (2x^2 + 2y^2 + 2z^2)z - gz, \end{aligned}$$

where $g = (a^2 + b^2 + c^2 + u^2 + v^2 + w^2 + x^2 + y^2 + z^2)$. Let I denote the ideal generated by these 10 cubics. Take these 10 cubics as input and we obtain in 800 sec. only one minimal prime of \sqrt{I} , which is the ideal I itself. Thus I is a real ideal.

Acknowledgment

We thank Yue Ren for his help with the implementation of our algorithms. We also thank Erich L. Kaltofen for his valuable suggestions on the complexity of factorizing multivariate polynomials.

Mohab Safey El Din is supported by the ANR grant ANR-17-CE40-0009 GALOP and the PGMO grant GAMMA. Zhi-Hong Yang and Lihong Zhi are supported in part by the National Key Research Project of China 2016YFB0200504 and the National Natural Science Foundation of China under Grants 11571350.

References

- Basu, S., Pollack, R., Roy, M.-F., 2006. Algorithms in Real Algebraic Geometry. Springer Berlin Heidelberg, Berlin, Heidelberg.
- Becker, E., Neuhaus, R., 1993. Computation of real radicals of polynomial ideals. In: Eyssette, F., Galligo, A. (Eds.), Computational Algebraic Geometry. Vol. 109. Birkhäuser, Boston, MA, pp. 1–20.
- Blanco, C., Jeronimo, G., Solernó, P., 2004. Computing generators of the ideal of a smooth affine algebraic variety. Journal of Symbolic Computation 38 (1), 843–872.
- Bochnak, J., Coste, M., Roy, M.-F., 1998. Real algebraic geometry. Vol. 36. Springer, Berlin, Heidelberg.
- Brake, D. A., Hauenstein, J. D., Liddell, Jr., A. C., 2016. Validating the completeness of the real solution set of a system of polynomial equations. In: Proceedings of the 2016 International Symposium on Symbolic and Algebraic Computation. ISSAC’16. ACM, New York, NY, USA, pp. 143–150.

- Chen, C., Davenport, J. H., May, J. P., Maza, M. M., Xia, B., Xiao, R., 2010. Triangular decomposition of semi-algebraic systems. In: Proceedings of the 2010 International Symposium on Symbolic and Algebraic Computation. ISSAC'10. ACM, New York, NY, USA, pp. 187–194.
- Chen, C., Davenport, J. H., May, J. P., Maza, M. M., Xia, B., Xiao, R., 2013. Triangular decomposition of semi-algebraic systems. *Journal of Symbolic Computation* 49, 3–26.
- Chen, C., Davenport, J. H., Moreno Maza, M., Xia, B., Xiao, R., 2011. Computing with semi-algebraic sets represented by triangular decomposition. In: Proceedings of the 36th International Symposium on Symbolic and Algebraic Computation. ISSAC'11. ACM, New York, NY, USA, pp. 75–82.
- Cox, D., Little, J., O’shea, D., 1992. Ideals, varieties, and algorithms. Vol. 3. Springer.
- Durvy, C., Lecerf, G., 2008. A concise proof of the Kronecker polynomial system solver from scratch. *Expositiones Mathematicae* 26 (2), 101–139.
- Eisenbud, D., 1995. Commutative Algebra: with a View Toward Algebraic Geometry. Vol. 150. Springer New York, New York, NY.
- Everett, H., Lazard, D., Lazard, S., Safey El Din, M., 2009. The Voronoi diagram of three lines. *Discrete & Computational Geometry* 42 (1), 94–130.
- Fløystad, G., Kileel, J., Ottaviani, G., 2017. The Chow form of the essential variety in computer vision. *Journal of Symbolic Computation*.
- Gelfand, I. M., Kapranov, M. M., Zelevinsky, A. V., 1994. Discriminants, Resultants, and Multidimensional Determinants. Birkhäuser Boston, Boston, MA.
- Giusti, M., Lecerf, G., Salvy, B., 2001. A Gröbner free alternative for polynomial system solving. *Journal of complexity* 17 (1), 154–211.
- Jeronimo, G., Krick, T., Sabia, J., Sombra, M., 2004. The computational complexity of the Chow form. *Foundations of Computational Mathematics* 4 (1), 41–117.
- Kalkbrener, M., 1991. Three contributions to elimination theory. Ph.D. thesis, Johannes Kepler University, Linz.
- Kaltofen, E., 1989. Factorization of polynomials given by straight-line programs. *Randomness and Computation* 5, 375–412.
- Kaltofen, E., Li, B., Yang, Z., Zhi, L., 2008. Exact certification of global optimality of approximate factorizations via rationalizing sums-of-squares with floating point scalars. In: Proceedings of the Twenty-first International Symposium on Symbolic and Algebraic Computation. ISSAC'08. ACM, New York, NY, USA, pp. 155–164.
- Kaltofen, E., Trager, B. M., 1990. Computing with polynomials given by black boxes for their evaluations: greatest common divisors, factorization, separation of numerators and denominators. *Journal of Symbolic Computation* 9 (3), 301–320.

- Krick, T., 2002. Straight-line programs in polynomial equation solving. *Foundations of computational mathematics: Minneapolis 312*, 96–136.
- Lasserre, J.-B., Laurent, M., Mourrain, B., Rostalski, P., Trébuchet, P., 2013. Moment matrices, border bases and real radical computation. *Journal of Symbolic Computation* 51, 63–85.
- Lasserre, J. B., Laurent, M., Rostalski, P., 2008. Semidefinite characterization and computation of zero-dimensional real radical ideals. *Foundations of Computational Mathematics* 8 (5), 607–647.
- Lax, P., 2005. On the discriminant of real symmetric matrices. *Selected Papers Volume II*, 577–586.
- Lazard, D., 1991. A new method for solving algebraic systems of positive dimension. *Discrete Applied Mathematics* 33 (1-3), 147–160.
- Lecerf, G., 2000. Computing an equidimensional decomposition of an algebraic variety by means of geometric resolutions. In: *Proceedings of the 2000 International Symposium on Symbolic and Algebraic Computation. ISSAC'00*. ACM, New York, NY, USA, pp. 209–216.
- Lecerf, G., 2003. Computing the equidimensional decomposition of an algebraic closed set by means of lifting fibers. *Journal of Complexity* 19 (4), 564–596.
- Ma, Y., Wang, C., Zhi, L., 2016. A certificate for semidefinite relaxations in computing positive-dimensional real radical ideals. *Journal of Symbolic Computation* 72, 1–20.
- Marshall, M., 2008. Positive polynomials and sums of squares. No. 146. American Mathematical Soc.
- Moreno Maza, M., 1997. Calculs de pgcd au-dessus des tours d'extensions simples et résolution des systèmes d'équations algébriques. Ph.D. thesis, Université Paris 6.
- Neuhaus, R., 1998. Computation of real radicals of polynomial ideals – II. *Journal of Pure and Applied Algebra* 124 (1), 261–280.
- Poteaux, A., Schost, É., 2013. On the complexity of computing with zero-dimensional triangular sets. *Journal of Symbolic Computation* 50 (Supplement C), 110 – 138.
- Safey El Din, M., 2005. Finding sampling points on real hypersurfaces is easier in singular situations. *MEGA (Effective Methods in Algebraic Geometry) Electronic proceedings*.
- Safey El Din, M., 2007a. RAGLib (Real Algebraic Geometry Library), Maple package.
- Safey El Din, M., 2007b. Testing sign conditions on a multivariate polynomial and applications. *Mathematics in Computer Science* 1 (1), 177–207.
- Safey El Din, M., Schost, É., 2003. Polar varieties and computation of one point in each connected component of a smooth real algebraic set. In: *Proceedings of the 2003 International Symposium on Symbolic and Algebraic Computation. ISSAC'03*. ACM, New York, NY, USA, pp. 224–231.

- Safey El Din, M., Schost, É., 2004. Properness defects of projections and computation of at least one point in each connected component of a real algebraic set. *Discrete & Computational Geometry* 32 (3), 417–430.
- Safey El Din, M., Schost, É., 2017. A nearly optimal algorithm for deciding connectivity queries in smooth and bounded real algebraic sets. *Journal of the ACM* 63 (6), 48:1–48:37.
URL <http://doi.acm.org/10.1145/2996450>
- Schost, É., 2003. Computing parametric geometric resolutions. *Applicable Algebra in Engineering, Communication and Computing* 13 (5), 349–393.
- Spang, S. J., 2007. On the computation of the real radical. Ph.D. thesis, Technische Universität Kaiserslautern.
- Spang, S. J., 2008. A zero-dimensional approach to compute real radicals. *The Computer Science Journal of Moldova* 16 (1), 64–92.
- Wang, D., 1998. Decomposing polynomial systems into simple systems. *Journal of Symbolic Computation* 25 (3), 295–314.
- Wu, W.-T., 1984. Basic principles of mechanical theorem proving in elementary geometries. *Journal of Systems Science and Mathematical Sciences* 4, 207–235.