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Top-down definition of design spaces based on skeleton modelling

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Abstract. This paper introduces a novel modelling approach based on the analogy to the incubator concept so as to provide a suitable support for designers through product design process. The main objective is to define a knowledge-intensive design context in the early product design stages. The main goal of the proposed approach is to provide a knowledge-based design context for designers by considering engineering knowledge in an appropriate and seamless manner. As such, the proposed design incubator will assist designers to make better-informed decisions by delivering knowledge and engineering information at the right time. A case study has been introduced to illustrate the relevance of the proposed approach.

Keywords: Assembly modelling, Skeleton-based modelling, Top-down assembly design, Proactive engineering, Design context definition, Knowledge-intensive design

1 Introduction

The current globalised competitive context requires industry to reduce development lead times at optimised costs and improve the quality and the efficiency of their products in order to fulfil customers' requirements. To reach these goals, a phase of architectural design is required. The role of product architects will be to consider the numerous number of constraints (i.e. reliability, sustainability, ...) in the product design process. Product architects also have a global view on the system to be developed especially on functional, structural, behavioural, geometric and physical aspects which are associated to different viewpoints [6].

The fact of working collaboratively and remotely on the same product is part of a recurrent issue in large-scaled companies. As such, it is important to define a design context to assist designers through their activities. This paper is based on previous research works on proactive design for assembly and skeleton based

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modelling approaches ([7] [8] [9]). Built on this, the whole is to propose a proactive top-down modelling approach of layout elements based on an analogical reasoning approach with incubator in the early product design stage. The incubator is composed of several layers of engineering information and knowledge (i.e. skeleton entities, functional surfaces, design spaces, parameters, knowledge and requirements to name a few). Compared to previous research efforts in this field [8], this approach will introduce the generation of design spaces from skeleton interface entities and functional surfaces.

Built on this, section 2 reviews some previous research works in the field of top-down and layout modelling design. In Section 3, a presentation of the design incubator concept is proposed and the overall approach is also presented. Then section 4 discusses about the deployment of the approach through a mechanical assembly. Finally, conclusions and future work are given.

2 Related works

This section aims to give a brief overview of published research works on top-down and layout modelling design issues, so as to provide the foundation of the proposed approach based on current status and challenges.

2.1 Top-down design

Top-down approach starts with the formalisation of requirements and the establishment of general layout models, specifying but not detailing any first-level components. Then, components are refined in greater details until the overall definition of the product. Support for top-down design and multiple viewpoints is a key point of top-down design which should be take into account when developing computer environments for mechanical assembly design [15]. An overview in this research domain [22] highlights some issues such as assembly model representation for top-down product design and the reasoning method from conceptual model top parametric model which must be tackled. In addition, Mäntylä [16]state that the design process could be decomposed into several stages (i.e. functional, conceptual and detailed design) while a top-down design process should support multiple abstraction models.

2.2 Layout Modelling

The product design process is composed of several stages from the identification of customer needs to the detailed definition of product [18]. Layout design has a crucial role to play [3] in the embodiment design stage which is the focus of this paper. By using layout elements (featured by geometric entities and engineering information), it is possible to support designers activities and exchange design data with other teams. In literature, many attempts have been made to carry out various aspects of the layout design. [12] uses layout elements to define kinematics constraints between functional components. Li et al.

[14] capture all the feasible designs to find an optimal geometry by integrating user-defined constraints. Theodosiou et al. [20] developed full comprehensive models for spatial constraints, and in particular, for free space requirements. Ballu et al. [2] proposed a functional design method that early aides to identify and analyse functional geometrical entities and tolerance (Technologically and Topologically Related Surfaces). Mun et al. [17] proposed a solution to share skeleton model among companies working collaboratively in order to protect their intellectual property. Delgado et al. [5] uses spatial design to generate a structural solution inside it. Moreover, Gelston et al. [11] proposed a method for reconstructing boundary surfaces corresponding to skeletal curves, and then extend the method for reconstruction of boundary surfaces corresponding to skeletal surfaces. Kovacs et al. [13] describes the incremental development of a knowledge-based system for supporting floor plan design. Bai et al. [1] deployed tools based on Product Layout Feature concept to carry out collaborative design activities among multi-disciplinary teams. Skander et al. [21] proposed a skeleton-based method and models that tackle the issue of manufacturing processes selection and constraints integration , as soon as possible, into the product modelling stage. Csabai et al. [4] uses design spaces to analyse interferences between product components. Gane et al. [10] defined a methodology for building and managing requirements driven design spaces with parametric Computer Aided Design tools.

3 Proposed approach

This section presents the proposed approach which introduces the design incubator concept (Fig. 1). Design incubator provides a knowledge-intensive and living support to designers by defining layout product geometry at the beginning of the embodiment design phase. Such analogical reasoning will enable the introduction of a novel paradigm in CAD modelling stage.

The incubator improve coordination and information flows between three systems, such as Product Data Management (PDM) system, knowledge base and CAD system. Its role is first to generate a design context to designers. Then, when designers start their activities, it will identify and analyse their intents. Once design intents are captured, a request to the knowledge base is process in order to get appropriate engineering information or knowledge for designers at the right time. Finally, when designers store their component, the incubator will generate design intents history. Such procedures will ensure understanding and traceability in design with new technical objects.

3.1 Overall methodology description

Based on the SKL-ACD approach[7] [19], an enriched flow chart is introduced to describe the proposed approach in a more detailed view (Fig. 2). An explanation of the different steps of the method is visible below:

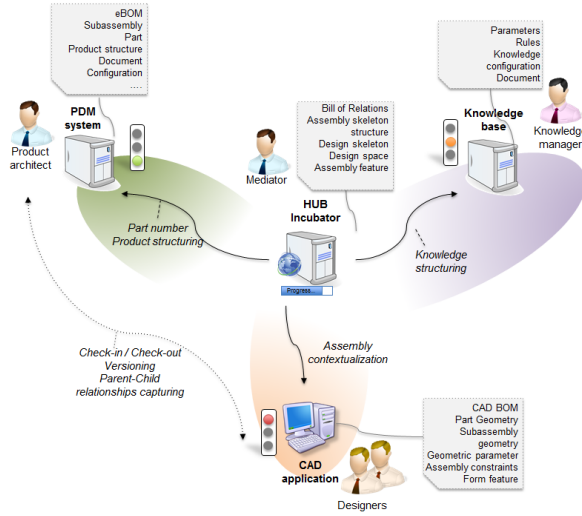


Fig. 1. Incubator concept.

- Start: Starting from the early defined assembly sequence and product relational information embedded in graphs and matrices, the product architect defines kinematics/technological pairs in the directed graph;
- Steps 1 and 2. The product structure is automatically generated and assembly skeleton places are assigned inside (Steps 1 and 2 of Fig. 2);
- Steps 3 and 4. Based on these relationships, assembly constraints are automatically defined and geometric skeleton entities are generated in order to provide interface control elements for assembly modelling (Steps 3 and 4 of Fig. 2);
- Step 5. The product architect introduces new assembly constraints between the generated geometric skeleton entities (Step 5 of Fig. 2); A new graph, called skeleton graph, built upon these constraints, is defined by skeleton entities and their related assembly constraints;
- Step 6. This graph is simplified later on by the generalization and the concatenation of skeleton elements into a minimal skeleton graph (Step 6 of Fig. 2);
- Step 7. Based on this minimal skeleton graph and the early-defined assembly sequence, this step allows the structuring and regrouping of skeleton elements in assembly skeletons (Step 7 of Fig. 2);
- Step 8. An assembly coordinate system is defined for each assembly layer and associated to each identified base part. Therefore new constraints are introduced to link the defined assembly coordinate systems with the interface control elements from the minimal skeleton graph (Step 8 of Fig. 2);
- Step 2. The resulting assembly skeletons can be allocated to the initial product structure. At this stage, it is possible to assign rights to a skeleton entity which is at the interface of different assembly skeletons (Step 2 of Fig. 2);

- Step 9. Based on the kinematic pairs between components and product architect choice, the skeleton interfaces entities are defined (Step 9 of Fig. 2);
- Step 10. Supported by skeleton interfaces entities, functional surfaces are defined (Step 10 of Fig. 2);
- Step 11. From functional surfaces and skeleton interface entities, design spaces are generated (Step 11 of Fig. 2);
- End: As a result, the assembly skeleton CAD model, functional surfaces and design spaces are semi-automatically generated.

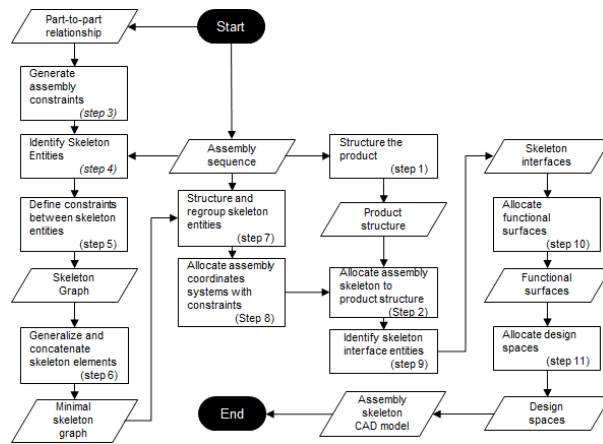


Fig. 2. Enriched flowchart of the proposed approach.

4 Case Study

In this section, the proposed approach is illustrated with a mechanical system (Fig. 3). Each step of the method are described for a better understanding (Fig. 4 and Fig. 5).

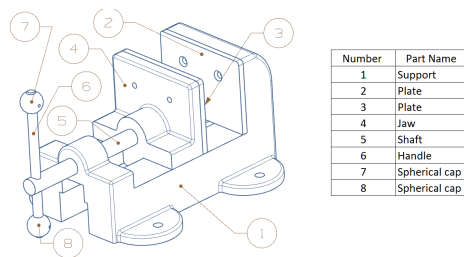


Fig. 3. Case study : vice and parts list of the case study.

4.1 Determination of the skeleton minimal graph (Step 3 to 6 of Fig. 2) and Introduction of an assembly coordinate system (Step 7 to 8 of Fig. 2)

The product architect starts by defining the kinematic pairs between each parts. Based on the kinematic pairs, the skeleton entities and position constraints between each parts are deduced. At this point, to facilitate the management of the skeleton entities, it is possible to simplify the proposed skeleton graph by generalize and concatenate skeleton entities. Based on the minimal skeleton graph of the previous step, an assembly coordinate system is introduced. Each skeleton entities are linked to this new assembly coordinate system by the intermediate of geometrical constraints. Then, the geometrical constraints are concatenated.

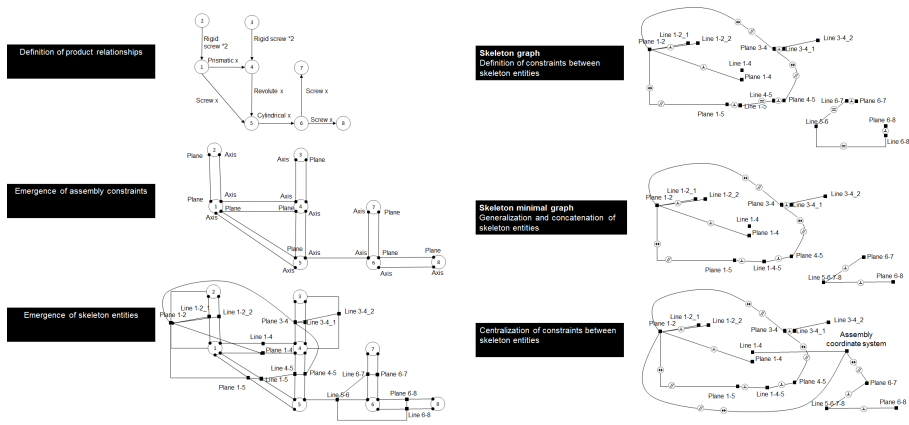


Fig. 4. Definition process of a minimal skeleton model.

4.2 Allocation of skeleton interface entities and functional surfaces (step 9 to 10 of Fig. 2) and generation of design spaces (step 11 of Fig. 2)

Based on previous steps, the skeleton interface entities are defined and associated to skeleton entities.

Then, it is possible to concatenate skeleton interface entities in order to simplify the design environment. Finally, after this simplification, the functional surface are deduced from the skeleton interface entities.

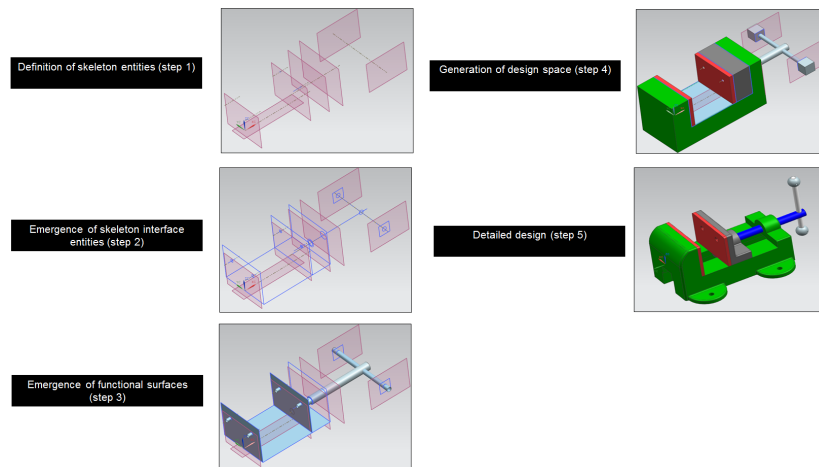


Fig. 5. Definition process of design spaces models.

5 Conclusions and future work

In this paper, a novel approach to define a design context in the early phases of the design development has been proposed and described in detail. The current issue of the paper is to allocate design spaces to the assembly skeleton model. Defining design spaces based on skeleton modelling will permit a better understanding of “what to design“ by designers. To illustrate the feasibility and the relevance of the proposed approach, a use case has been carried out. Finally, three main issues demand further research: the incorporation of knowledge; adding requirements; and create a link between the method and PDM system.

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