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► **To cite this version:**

Tomer Libal, Dale Miller. Functions-as-constructors Higher-order Unification. 1st International Conference on Formal Structures for Computation and Deduction (FSCD 2016), Delia Kesner and Brigitte Pientka, Jun 2016, Porto, Portugal. pp.1 - 17, 10.4230/LIPIcs.FSCD.2016.26 . hal-01379683

HAL Id: hal-01379683

<https://inria.hal.science/hal-01379683>

Submitted on 11 Oct 2016

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Functions-as-constructors Higher-order Unification

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Abstract

Unification is a central operation in the construction of a range of computational logic systems based on first-order and higher-order logics. First-order unification has a number of properties that dominates the way it is incorporated within such systems. In particular, first-order unification is decidable, unary, and can be performed on untyped term structures. None of these three properties hold for full higher-order unification: unification is undecidable, unifiers can be incomparable, and term-level typing can dominate the search for unifiers. The so-called *pattern* subset of higher-order unification was designed to be a small extension to first-order unification that respected the basic laws governing λ -binding (the equalities of α , β , and η -conversion) but which also satisfied those three properties. While the pattern fragment of higher-order unification has been popular in various implemented systems and in various theoretical considerations, it is too weak for a number of applications. In this paper, we define an extension of pattern unification that is motivated by some existing applications and which satisfies these three properties. The main idea behind this extension is that the arguments to a higher-order, free variable can be more than just distinct bound variables: they can also be terms constructed from (sufficient numbers of) such variables using term constructors and where no argument is a subterm of any other argument. We show that this extension to pattern unification satisfies the three properties mentioned above.

1998 ACM Subject Classification F.4.1 Mathematical Logic: Mechanical theorem proving

Keywords and phrases higher-order unification; pattern unification

Digital Object Identifier 10.4230/LIPIcs.FSCD.2016.<article-no>

1 Introduction

Unification is the process of solving equality constraints by the computation of substitutions. This process is used in computational logic systems ranging from automated theorem provers, proof assistants, type inference systems, and logic programming. The first-order unification—that is, unification restricted to first-order terms—enjoys at least three important computational properties, namely, (1) decidability, (2) determinacy, and (3) type-freeness. These properties of unification shaped the way it can be used within computational logic systems. The first two of these properties ensures that unification—as a process—will either fail to find a unifier for a given set of disagreement pairs or will succeed and return the *most general unifier* that solves all those disagreement pairs. The notion of type-freeness simply means that unification can be done independently of the possible typing discipline that might be employed with terms. Thus, first-order unification can be performed on untyped first-order terms (as terms are usually considered in, say, Prolog). This property is important since it means that unification can be used with any typing discipline that might be adopted. Since typing is usually an open-ended design issue in many languages (consider, for example, higher-order types, subtypes, dependent types, parametric types, linear types, etc.), the type-freeness of unification makes it possible for it to be applied to a range of typing disciplines.



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1st International Conference on Formal Structures for Computation and Deduction (FSCD 2016).

Editor: D. Kesner and B. Pientka; Article No. <article-no>; pp. <article-no>:1–<article-no>:17

Leibniz International Proceedings in Informatics



LIPICs Schloss Dagstuhl – Leibniz-Zentrum für Informatik, Dagstuhl Publishing, Germany

Of course, many syntactic objects are not most naturally considered as purely first-order terms: this is the case when that syntax contains bindings. Instead, many systems have adopted the approach used by Church in his Simple Theory of Types [11] where terms and term equality comes directly from the λ -calculus. All binding operations—quantification in first-order formulas, function arguments in functional programs, local variables, etc.—can be represented using the sole binder of the λ -calculus. Early papers showed that second-order pattern matching could be used to support interesting program analysis and program transformation [18] and that a higher-order version of Prolog could be used to do more general manipulations of programs and formulas [21]. Today, there is a rich collection of computational logic systems that have moved beyond first-order term unification and rely on some form of higher-order unification. These include the theorem provers TPS [3], Leo [7] and Satallax [10]; the proof assistants Isabelle [26], Coq [36], Matita [4], Minlog [31], Agda [9], Abella [5], and Beluga [29]; the logic programming languages λ Prolog [23] and Twelf [28]; and various application domains such as natural language processing [12].

The integration of full higher-order unification into computational logic systems is not as simple as it is in first-order systems since the three properties mentioned above do not hold. The unification of simply typed λ -terms is undecidable [15, 16] and there can be incomparable unifiers, implying that no most general unifiers exist in the general situation. Also, types matter a great deal in determining the search space of unifiers. For example, let i and j be primitive types, let a be a constant of type i , and let F and X be variables of type $\alpha \rightarrow i$ and α , respectively, where α is a type variable. Consider the unification problem $(F X) = a$. If we set α to j , then there is an mgu for this problem, namely $[F \mapsto \lambda w.a]$. If we set α to i , then there are two incomparable solutions, namely $[F \mapsto \lambda w.a]$ and $[F \mapsto \lambda w.w, X \mapsto a]$. If we set α to $i \rightarrow i$, then there is an infinite number of incomparable solutions: $[F \mapsto \lambda f.a]$ and, for each natural number n , $[F \mapsto \lambda f.f^n a, X \mapsto \lambda w.w]$. If higher order values for α are considered, the possibility of unifiers becomes dizzying.

For these reasons, the integration of unification for simply typed λ -terms into computational logic systems is complex: most such integration efforts attempt to accommodate the (pre-)unification search procedure of Huet [17].

Instead of moving from first-order unification to full higher-order unification, it is possible to move to an intermediate space of unification problems. Given that higher-order unification is undecidable, there is an infinite number of decidable classes that one could consider. The setting of *higher-order pattern unification* (proposed in [20] and called L_λ -unification there) could be seen as the weakest extension of first-order unification in which the equations of α , β , and η conversion hold. In this fragment, a free variable cannot be applied to general terms but only to bound variables that cannot appear free in eventual instantiations for the free variable. This restriction means that all forms of β -reduction encountered during unification are actually (α -equivalent) to the rule $(\lambda x.B)x = B$ (a conversion rule called β_0). Notice that in this setting, β -reduction reduces the size of terms: hence, unification takes on a much simpler nature. The unification problems that result retain all three properties we listed for first-order unification [20]. As a result, the integration of pattern unification into a prover is usually much simpler than incorporating all the search behavior implied by Huet's (pre-)unification procedure.

A somewhat surprising fact about pattern unification is that many computational logic systems actually need only this subset of higher-order unification in order to be “practically complete”: that is, restricting unification to just this subset did not stop the bulk of specifications from being properly executed. For example, while both early implementations of λ Prolog and LF [24, 28] implemented full higher-order unification, the most recent versions

of those languages implement only pattern unification [1, 30]. A design feature of both of those systems is to treat any unification problem that is not in the pattern fragment as a suspended constraint: usually, subsequent substitutions will cause such delayed problems to convert into the pattern fragment. Processing of constraints may also be possible: the application of *pruning* to flexible-flexible constraints in [22] is such an example. Also since pattern unification does not require typing information, it has been possible to describe variants of such unification in settings where types can play a role during unification: see for example, generalizations of pattern unification for dependent and polymorphic types [27], product types [13, 14], and sum types [2].

Since pattern unification is a weak fragment of higher-order unification, it is natural to ask if it can be extended and still keep the same high-level properties. There have been extensions of pattern unification considered in the literature. The generalization (mentioned above) of pattern unification to patterns by Fettig and Löchner [14] and Duggan [13] allows for constructors denoting projections to be admitted in the scope of free functional variables. These projections are specific unary functions which are closed under a number of properties, such as associativity. When attempting to encode the meta-theory of sequent calculus in which eigenvariables are seen as abstractions over sequents [19], a single bound variable was intended to be used as a list of bound (eigen)variables. Thus, in order to encode the sequent judgment $x_0, \dots, x_n \vdash Cx_0 \dots x_n$ (for $n \geq 0$ and all variables being of the same primitive type) one would instead use the simply typed term $\lambda l.C(\text{fst } l) \dots (\text{fst } \text{snd}^n l)$, where the environment abstraction l has type, say, evs , and fst and snd are constructors of type $\text{evs} \rightarrow i$ and $\text{evs} \rightarrow \text{evs}$, respectively. Tiu showed how to lift pattern unification to this setting [33]. The Coq proof assistant allows for some limited forms of unification and many simple unification problems can appear that should be automatically solved. A typical such example is of the form $\lambda x.Y(gx) \doteq \lambda x.f(gx)$, where Y is a free variable of type $i \rightarrow i$ and f and g are constructors of the type $i \rightarrow i$. Clearly, this problem has the mgu $Y \mapsto \lambda z.fz$ but it falls outside the pattern restriction. There are certain uses of Coq (for example, with the `bigop` library of `SSReflect`) which produce a number of non-pattern unification problems.¹

Let us return to the definition of pattern unification problems. The restriction on occurrences of the free variable, say, M is that (1) it can be applied only to variables that cannot appear free in terms that are used to instantiate M and (2) that those arguments are distinct. Condition (1) essentially says that the arguments of M form a primitive pattern that allows one to form an abstraction to solve a unification problem. Thus, $M \ x \ y$ can equal, say, $(s \ x) + y$ simply by forming the abstraction $\lambda x \lambda y.(s \ x) + y$. Condition (2) implies that such abstractions are unique.

The examples of needing richer unification problems above illustrate that it is also natural to consider arguments built using variables *and* term constructors: that is, we should consider generalizing condition (1) above by allowing the application $\lambda l.(M \ (\text{fst } l) \ (\text{fst } \text{snd } l))$. If this application is required to unify with a term of the form $\lambda l.t$ then all occurrence of l in t must occur in subterms of the form $(\text{fst } l)$ or $(\text{fst } \text{snd } l)$. In that case, forming an abstraction of t by replacing all occurrences of $(\text{fst } l)$ and $(\text{fst } \text{snd } l)$ with separate bound variables gives a solution to this unification problem. To guarantee uniqueness of such solutions, we shall also generalize condition (2) so that the arguments of M cannot be subterms of each other. This additional constraint is required here (but not in the papers by Duggan [13] and Tiu [33]) since we wish to handle richer signatures than just those with monadic constraints.

Many of the examples leading to this generalization of pattern unification arise in situations

¹ Personal communication with Enrico Tassi.

where operators (such as `fst` and `snd`) are really functions and *not* constructors: the intended meaning of those two operators are as functions that map lists to either their first element or to their tail. When they arise in unification problems, however, we can only expect to treat them as constructors. Thus, we shall name this extended pattern unification as *function-as-constructor* (pattern) unification, or just FCU for short.

The rest of this paper is structured as follows. We cover the basic concepts related to higher-order unification in Section 2. The class of unification problems addressed in this paper, the *functions-as-constructor* class, is defined in Section 3 as is a unification algorithm for that class. We prove the correctness of that algorithm in Section 4. We conclude in Section 5.

2 Preliminaries

2.1 The Lambda-Calculus

In this section we will present the logical language that will be used throughout the paper. The language is a version of Church’s simple theory of types [11] with an η -conversion rule as presented in [6] and [32] and with implicit α -conversions. Unless stated otherwise, all terms are implicitly converted into β -normal and η -expanded form. Most of the definitions in this section are adapted from [32].

Let \mathfrak{T}_0 be a set of basic types, then the set of types \mathfrak{T} is generated by $\mathfrak{T} := \mathfrak{T}_0 \mid \mathfrak{T} \rightarrow \mathfrak{T}$. Let \mathfrak{C} be a signature of function symbols and let \mathfrak{V} be a countably infinite set of variable symbols. *Variables* are normally denoted by the letters $l, x, y, w, z, X, Y, W, Z$ and *function symbols* by the letters f, g, h, k, a or typed names like `cons`. We sometimes use subscripts and superscripts as well. We sometimes add a superscript to symbols in order to specify their type. The set \mathbf{Term}^α of terms of type α is generated by $\mathbf{Term}^\alpha := f^\alpha \mid x^\alpha \mid (\lambda x^\beta. \mathbf{Term}^\gamma) \mid (\mathbf{Term}^{\beta \rightarrow \alpha} \mathbf{Term}^\beta)$ where $f \in \mathfrak{C}, x \in \mathfrak{V}$ and $\alpha \in \mathfrak{T}$ (in the abstraction, $\alpha = \beta \rightarrow \gamma$). Applications throughout the paper will be associated to the left. We will sometimes omit brackets when the meaning is clear. We will also normally omit typing information when it is not crucial for the correctness of the results. $\tau(t^\alpha) = \alpha$ refers to the type of a term. The set \mathbf{Term} denotes the set of all terms. *Subterms* and *positions* are defined as usual. We denote the fact that t is a (strict) subterm of s using the infix binary symbol $(\sqsubset) \sqsubseteq$. *Sizes of positions* denote the length of the path to the position. We denote the subterm of t at position p by $t|_p$. *Bound* and *free variables* are defined as usual. We will use the convention of denoting bound and universally quantified variables by lower letters while existentially quantified variables will be denoted by capital letters. Given a term t , we denote by $\mathbf{hd}(t)$ its *head symbol* and distinguish between *flex* terms, whose head is a free variable and *rigid* terms, whose head is a function symbol or a bound variable.

We will use both *set union* (\cup) and *disjoint set union* (\uplus) in the text.

Substitutions and their *composition* (\circ) are defined as usual. Namely, $(\sigma \circ \theta)X = \theta(\sigma X)$. \mathbf{id} denotes the trivial substitution mapping each variable to itself. We denote by $\sigma|_W$ the substitution obtained from substitution σ by restricting its domain to variables in W . We denote by $\sigma[X \mapsto t]$ the substitution obtained from σ by mapping X to t , where X might already exist in the domain of σ . We extend the application of substitutions to terms in the usual way and denote it by postfix notation. Variable capture is avoided by implicitly renaming variables to fresh names upon binding. A substitution σ is *more general* than a substitution θ , denoted $\sigma \leq \theta$, if there is a substitution δ such that $\sigma \circ \delta = \theta$. The *domain* of a substitution σ is denoted by $\mathbf{dom}(\sigma)$.

We introduce also a vector notation $\overline{t_n}$ for the sequence of terms t_1, \dots, t_n . This notation

also holds for nesting of sequences. For example, the term $f (X_1 z_1 z_2) (X_2 z_1 z_2) (X_3 z_1 z_2)$ will be denoted by $f \overline{X_3 z_2}$. The meaning of the notation $\lambda \overline{z_n}$ is $\lambda z_1, \dots, \lambda z_n$. When the order of the sequence is not important, we will use this notation also for multisets.

2.2 Higher-order Pre-unification

In this section we present Huet's pre-unification procedure [17] as defined in [32]. The procedure will be proven, in Section 3.2, to be deterministic for the class of FCU problems. This result, together with the completeness of the procedure, implies the existence of most-general unifiers for unifiable problems of this class.

The presentation in this paper of both the pattern and FCU unification algorithms is much simplified if the following non-standard normal form is being used. All terms, including functional existential variables but excluding the arguments of these variables, are considered to be in η -expanded form. The arguments of these variables are expected to be in η -normal forms. In a similar manner to the one in [32], one can prove that all substitutions used in this paper preserve this normal form.

► **Definition 1 (Unification Problem).** An equation is a formula $t \doteq s$ where t and s are $\beta\eta$ -normalized (see remark above) terms. A unification problem is a formula of the form $\exists \overline{X_m}. e_1 \wedge \dots \wedge e_n$ where e_i for $0 < i \leq n$ is an equation. Sets of equations are always closed under symmetry, i.e. if $t \doteq s$ is in the set, then also $s \doteq t$.

► **Definition 2 (Unification System).** A unification system over a signature \mathfrak{C} is the following quadruple $\langle Q_\exists, Q_\forall, S, \sigma \rangle$ where Q_\exists and Q_\forall are disjoint sets of variables, S is a set of equations and σ a substitution. Given a unification problem $\exists \overline{X_m}. e_1 \wedge \dots \wedge e_n$ we consider the unification system over signature \mathfrak{C} by setting $Q_\exists = \overline{X_m}$, $Q_\forall = \{\}$, $S = \{e_1, \dots, e_n\}$ and $\sigma = \text{id}$. Let $\text{bvars}(e_i) = \overline{z_n}$ for $e_i = (\lambda \overline{z_n}. t_i \doteq \lambda \overline{z_n}. s_i)$.

An important property of terms in which we will be interested later is the subterm property between terms of different equations. Such a property is not closed under α -renaming of bound variables for our current definition of unification systems. Since we implicitly assume such renaming in order to avoid variables capture, we have to add the following additional requirement.

► **Definition 3 (Regular Unification Systems).** A regular unification system is a unification system in which each bound variable which is bound in a different context has a different name.

► **Example 4.** The system $\langle \emptyset, \emptyset, \{\lambda x.f x \doteq \lambda x.g x, \lambda y.h y \doteq \lambda y.k y\}, \text{id} \rangle$ is regular while the system $\langle \emptyset, \emptyset, \{\lambda x.f x \doteq \lambda x.g x, \lambda x.h x \doteq \lambda x.k x\}, \text{id} \rangle$ is not.

The next lemma is easily proven.

► **Lemma 5.** *The subterm property is closed under α -renaming of bound variables for regular unification systems.*

Regular unification systems will also be called systems.

Before presenting Huet's procedure for pre-unification, we will repeat the definition of partial bindings as given in [32].

► **Definition 6 (Partial bindings).** A partial binding of type $\alpha_1 \rightarrow \dots \rightarrow \alpha_n \rightarrow \beta$ where $\beta \in \mathfrak{T}_\circ$ is a term of the form $\lambda \overline{y_n}. a(\lambda \overline{z_{p_1}^1}. X_1(\overline{y_n}, \overline{z_{p_1}^1}), \dots, \lambda \overline{z_{p_m}^m}. X_m(\overline{y_n}, \overline{z_{p_m}^m}))$ for some atom a where

- $\tau(y_i) = \alpha_i$ for $0 < i \leq n$.
 - $\tau(a) = \gamma_1 \rightarrow \dots \rightarrow \gamma_m \rightarrow \beta$ where $\gamma_i = \delta_1^i \rightarrow \dots \rightarrow \delta_{p_i}^i \rightarrow \gamma'_i$ for $0 < i \leq m$.
 - $\gamma'_1, \dots, \gamma'_m \in \mathfrak{T}_o$.
 - $\tau(z_j^i) = \delta_j^i$ for $0 < i \leq m$ and $0 < j \leq p_i$.
 - X_i is a fresh variable and $\tau(X_i) = \alpha_1 \rightarrow \dots \rightarrow \alpha_n \rightarrow \delta_1^i \rightarrow \dots \rightarrow \delta_{p_i}^i \rightarrow \gamma'_i$ for $0 < i \leq m$.
- Partial bindings fall into two categories, imitation bindings, which for a given atom a and type α , are denoted by $\text{PB}(a, \alpha)$ and projection bindings, which for a given index $0 < i \leq n$ and a type α , are denoted by $\text{PB}(i, \alpha)$ and in which the atom a is equal to the bound variable y_i . Since partial bindings are uniquely determined by an index, a type and an atom (up to renaming of the fresh variables $\overline{X_m}$), this defines a particular term.

► **Definition 7** (Huet's Pre-unification Procedure). Huet's pre-unification procedure is given in Table 1. Note that the sets Q_\exists and Q_\forall are fixed during the execution and are mentioned explicitly just for compatibility with the algorithms given later in the paper.

$\langle Q_\exists, Q_\forall, S \uplus \{t \doteq t\}, \sigma \rangle \rightarrow \langle Q_\exists, Q_\forall, S, \sigma \rangle$	(Delete)
$\langle Q_\exists, Q_\forall, S \uplus \{\lambda \overline{z}_k. f \overline{t}_n \doteq \lambda \overline{z}_k. f \overline{s}_n\}, \sigma \rangle \rightarrow \langle Q_\exists, Q_\forall, S \uplus \{\lambda \overline{z}_k. t_1 \doteq \lambda \overline{z}_k. s_1, \dots, \lambda \overline{z}_k. t_n \doteq \lambda \overline{z}_k. s_n\}, \sigma \rangle$	(Decomp)
$\langle Q_\exists, Q_\forall, S \uplus \{\lambda \overline{z}_k. X \overline{z}_k \doteq \lambda \overline{z}_k. t\}, \sigma \rangle \rightarrow \langle Q_\exists, Q_\forall, S \uplus \theta \uplus \{X \doteq \lambda \overline{z}_k. t\}, \sigma \circ \theta \rangle$	(Bind)
where $X \notin \text{fvars}(t)$ and $\theta = [X \mapsto \lambda \overline{z}_k. t]$	
$\langle Q_\exists, Q_\forall, S \uplus \{\lambda \overline{z}_k. X^\alpha(\overline{s}_n) \doteq \lambda \overline{z}_k. f(\overline{t}_m)\}, \sigma \rangle \rightarrow \langle Q_\exists, Q_\forall, S \uplus \{X \doteq u, \lambda \overline{z}_k. X^\alpha(\overline{s}_n) \doteq \lambda \overline{z}_k. f(\overline{t}_m)\}, \sigma \rangle$	(Imitate)
where $u = \text{PB}(f, \alpha)$ and $f \in \mathfrak{C}$	
$\langle Q_\exists, Q_\forall, S \uplus \{\lambda \overline{z}_k. X^\alpha(\overline{s}_n) \doteq \lambda \overline{z}_k. a(\overline{t}_m)\}, \sigma \rangle \rightarrow \langle Q_\exists, Q_\forall, S \uplus \{X \doteq u, \lambda \overline{z}_k. X^\alpha(\overline{s}_n) \doteq \lambda \overline{z}_k. a(\overline{t}_m)\}, \sigma \rangle$	(Project)
where $0 < i \leq k, u = \text{PB}(i, \alpha)$ and either $a \in \mathfrak{C}$ or $a = z_i$ for some $0 < i \leq k$	

■ **Table 1** PUA- Huet's pre-unification procedure

The next theorem states the completeness of this procedure.

► **Theorem 8** ([32]). *Given a system $\langle Q_\exists, Q_\forall, S, \text{id} \rangle$ and assuming it is unifiable by σ , then there is a sequence of rule applications in Def. 7 resulting in $\langle Q'_\exists, Q'_\forall, \emptyset, \theta \rangle$ such that $\theta \leq \sigma$.*

2.3 Pattern Unification

In this section we describe the higher-order pattern unification algorithm in [20]. The notation used is similar to the one in [25]. This algorithm forms the basis for our algorithm.

► **Definition 9** (Pattern Systems). A system $\langle Q_\exists, Q_\forall, S, \sigma \rangle$ is called a pattern system if for all equations $e_i \in S$ and for all subterms $X \overline{z}_n$ in these equations such that $X \in Q_\exists$ we have that $\overline{z}_n \subseteq Q_\forall \cup \text{bvars}(e_i)$ and $z_i \neq z_j$ for all $0 < i < j \leq n$.

The following simplification will be called during the execution of the algorithm given in Def. 11.

- **Definition 10** (Pruning). Given a pattern system $\langle Q_\exists, Q_\forall, S, \sigma \rangle$ such that $\lambda \overline{z}_n. X \overline{z}_n^1 \doteq \lambda \overline{z}_n. r \in S$, r contains an occurrence y such that $y \in Q_\forall \cup \overline{z}_n$ and $y \notin \overline{z}_n^1$:
- if there is a subterm $W \overline{z}_m^2$ of r such that $y = z_i^2$ for some $0 < i \leq m$, then return $\langle Q_\exists \uplus \{W'\} \setminus \{W\}, Q_\forall, S \uplus \theta, \sigma \circ \theta \rangle$ where $\theta = [W \mapsto \lambda \overline{z}_m^2. W' \overline{z}_{m-1}^3]$ and $\overline{z}_{m-1}^3 = \overline{z}_m^2 \setminus \{z_i^2\}$.
 - otherwise, return $\langle Q_\exists, Q_\forall, \perp, \text{id} \rangle$.

► **Definition 11** (Pattern Unification Algorithm). The pattern unification algorithm is the application of the rules from Table 2 such that before the application of rules (3) and (5) we apply exhaustively pruning.

Paper [20] contains a proof that the algorithm from Def. 11 is terminating, sound and complete.

$$\langle Q_{\exists}, Q_{\forall}, S \uplus \{t \doteq t\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall}, S \rangle, \sigma \quad (0)$$

$$\langle Q_{\exists}, Q_{\forall}, S \uplus \{\lambda x.s \doteq \lambda x.t\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall} \uplus \{x\}, S \uplus \{s \doteq t\}, \sigma \rangle \quad (1)$$

$$\langle Q_{\exists}, Q_{\forall}, S \uplus \{f\overline{t}_n \doteq f\overline{s}_n\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall}, S \uplus \{t_1 \doteq s_1, \dots, t_n \doteq s_n\}, \sigma \rangle \quad (2)$$

where $f \in \mathcal{C} \cup Q_{\forall}$

$$\langle Q_{\exists} \uplus \{X\}, Q_{\forall}, S \uplus \{X\overline{z}_n \doteq f\overline{s}_m\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall}, S\theta, \sigma \circ \theta \rangle \quad (3)$$

where $f \in \mathcal{C}$, $X \notin \mathbf{fvars}(f\overline{s}_m)$ and $\theta = [X \mapsto \lambda \overline{z}_n.f\overline{s}_m]$

$$\langle Q_{\exists} \uplus \{X\}, Q_{\forall}, S \uplus \{X\overline{z}_n^1 \doteq X\overline{z}_n^2\}, \sigma \rangle \rightarrow \langle Q_{\exists} \uplus \{W\}, Q_{\forall}, S\theta, \sigma \circ \theta \rangle \quad (4)$$

$\theta = [X \mapsto \lambda \overline{z}_n^1.W\overline{z}_n^2]$ and $\overline{z}_k^3 = \{z_i^1 \mid z_i^1 = z_i^2\}$

$$\langle Q_{\exists} \uplus \{Y\}, Q_{\forall}, S \uplus \{X\overline{z}_n^1 \doteq Y\overline{z}_m^2\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall}, S\theta, \sigma \circ \theta \rangle \quad (5)$$

where $X \neq Y$, $\theta = [Y \mapsto \lambda \overline{z}_m^2.X\overline{z}_{\phi(m)}^1]$ and ϕ is a permutation

such that $\phi(j) = i$ if $z_i^1 = z_j^2$ for $0 < i \leq n$ and $0 < j \leq m$

■ **Table 2** Pattern Unification Algorithm

3 A Unification Algorithm for FC Higher-order Unification Problems

3.1 FC Higher-order Unification (FCU) Problems

The main difference between pattern and FCU problems is in the form of arguments of existentially quantified variables. While in pattern unification problems, these arguments must be a list of distinct universally quantified variables which occur in the scope of the existentially quantified one, we relax this requirement for FCU problems. This relaxation still ensures the existence of mgus if the problems are unifiable.

► **Definition 12** (Restricted Terms). Given \mathcal{C} , Q_{\forall} and an equation e , a restricted term in e is defined inductively as follows:

- $a \in Q_{\forall} \cup \mathbf{bvars}(e)$ is a restricted term.
- $f\overline{t}_n$ is a restricted term if $n > 0$, $f \in \mathcal{C} \cup Q_{\forall} \cup \mathbf{bvars}(e)$ and t_i is a restricted term for all $0 < i \leq n$.

When e is clear from the context, we will refer to these terms just as restricted terms.

We will use examples over $\mathcal{C} = \{\mathbf{cons}, \mathbf{fst}, \mathbf{snd}, \mathbf{nil}\}$ and $Q_{\forall} = \{l, z\}$ to explain the definition and algorithms presented in the paper.

► **Example 13.** The terms l , $(\mathbf{cons} \ z, l)$, $(\mathbf{cons} \ (\mathbf{fst} \ l) \ l)$ and $(\mathbf{snd} \ (\mathbf{cons} \ z \ l))$ are restricted terms over the above \mathcal{C} and Q_{\forall} , while \mathbf{nil} and $(\mathbf{cons} \ z \ \mathbf{nil})$ are not.

► **Definition 14** (FCU Systems). A system $\langle Q_{\exists}, Q_{\forall}, S, \sigma \rangle$ is an FCU system if the following three conditions are satisfied:

- **argument restriction** - for all occurrences $X\overline{t}_n$ in S where $X \in Q_{\exists}$, t_i for all $0 < i \leq n$ is a restricted term.
- **local restriction** - for all occurrences $X\overline{t}_n$ in S where $X \in Q_{\exists}$ and for each t_i and t_j such that $0 < i, j \leq n$ and $i \neq j$, $t_i \not\sqsubseteq t_j$.
- **global restriction** - for each two different occurrences $X\overline{t}_n$ and $Y\overline{s}_m$ in S where $X, Y \in Q_{\exists}$ and for each $0 < i \leq n$ and $0 < j \leq m$, $t_i \not\sqsubseteq s_j$.

► **Example 15.** Some examples of the equations of FCU systems are $\{X \ l \ z \doteq \mathbf{fst} \ (\mathbf{snd} \ l)\}$ and $\{\mathbf{cons} \ (X \ (\mathbf{fst} \ l)) \ (\mathbf{snd} \ l) \doteq \mathbf{snd} \ (Y \ (\mathbf{fst} \ l) \ (\mathbf{fst} \ (\mathbf{snd} \ l)))\}$. Note that only the first example is a pattern unification problem. Examples of non-FCU problems are $\{X \ (\mathbf{cons} \ z \ \mathbf{nil}) \doteq \mathbf{snd} \ l\}$ which violates the **argument restriction**, $\{X \ (\mathbf{fst} \ l) \ l \doteq \mathbf{cons} \ z \ l\}$ which violates the

local restriction and $\{X (\text{fst } l) \doteq \text{snd } (Y (\text{cons } (\text{fst } l) (\text{snd } l)))\}$ which violates (only) the global restriction.

It is important to note that when dealing with *restricted* unification problems, the **global restriction** from above cannot be violated by occurrences within different equations. The name **global** only refers, therefore, to the context of one equation.

The next proposition is easy to verify.

► **Proposition 16.** *Pattern systems are FCU systems.*

Before going on to show the properties of these problems, we would like to present a short discussion about the motivation behind the restrictions above. The three restrictions are required in order to maintain uniqueness of the result and will be used in the next section in order to prove the determinacy of Huet's procedure over FCU problems. Nevertheless, we do not prove that this result does not hold when weakening the above restrictions. The **local restriction** and **global restriction** can easily be shown to be required even for very simple examples. This is not the case for the **argument restriction**. One alternative is to weaken the restricted term definition from above to require only one subterm in the second condition to be restricted. I.e. to allow terms such as $(\text{cons } z \text{ nil})$ as arguments of existential variables. In the following, we will give a counter-example to this weaker restriction. Still, it should be noted that the counter-example depends on allowing inductive definitions containing more than one base case (in particular, we allow for different empty list constructors nil_1 and nil_2). When such definitions are not allowed, it may be possible to prove the results given in this paper for a stronger class of problems.

► **Example 17.** $\langle \{X, Y\}, \{z, z_2\}, \{X (\text{cons } z \text{ nil}_1) (\text{cons } z \text{ nil}_2) \doteq \text{cons } z (Y z_2)\}, \text{id} \rangle$ is unifiable by the following two incompatible substitutions:

1. $[Y \mapsto \lambda z_1. \text{nil}_1, X \mapsto \lambda z_1, z_2. z_1]$.
2. $[Y \mapsto \lambda z_1. \text{nil}_2, X \mapsto \lambda z_1, z_2. z_2]$.

3.2 The Existence of Most-general Unifiers

From this section on, an FCU problem will be referred to simply as system, unless indicated otherwise.

In [32] it is claimed that the only "don't-know" non-determinism in the general higher-order procedure stems from the choice between the different applications of (**Imitate**) and (**Project**). We prove that fulfilling the three restrictions in Def. 14 makes these choices deterministic.

We first prove a couple of auxiliary lemmas.

► **Lemma 18.** *let t be a restricted term, s a term containing the subterm $X\bar{r}_n$ and σ a substitution such that $t = s\sigma$, then there is a restricted term t' such that $t' = X\bar{r}_n\sigma$.*

Proof. Let k be the length of the position of $X\bar{r}_n$ in s , we prove by induction on k .

- $k = 0$, then $t' = t$.
- $k > 0$, then $s = f\bar{s}_m$ and $f\bar{s}_m\sigma = f\bar{t}_m = t$. Since t is restricted, by definition so are t_1, \dots, t_m . Assume $X\bar{r}_n$ occurs in s_i , then, according to the inductive hypothesis, there is a restricted term t' such that $t' = X\bar{r}_n\sigma$.

◀

► **Lemma 19.** *Given a unifiable equation $X\bar{t}_n \doteq r$, where r is a restricted term. Then, there is $0 < i \leq n$ such that t_i is a subterm of r .*

Proof. Assume the contrary and let σ be the unifier. Then, $X\overline{t_n}\sigma = r$. By definition, r contains a symbol $a \in Q_V$ and we get a contradiction. \blacktriangleleft

► **Lemma 20.** *Let $t = t'\overline{t_k}$ and $s = f\overline{s_n}$ such that t' is a restricted term and $f \in \mathfrak{C} \cup Q_V$. If $t \doteq s$ is unifiable, then $t = f\overline{v_{n-k}t_k}$ for restricted terms $\overline{v_{n-k}}$.*

Proof. Since t' is restricted, it does not contain abstractions and variables and as t is unifiable with s , it can be written as $f\overline{v_{n-k}t_k}$. Since t' is restricted, all its subterms are restricted as well. \blacktriangleleft

The next two lemmas prove the determinism claim on applications of (Project) and (Imitate).

► **Lemma 21.** *Given the equation $X\overline{t_n} \doteq f\overline{s_m}$ where X does not occur in $f\overline{s_m}$ and assuming we can obtain the following two equations by applying the substitutions $\sigma_0 = X \mapsto \lambda\overline{z_n}.z_i\overline{X_m\overline{z_n}}$ and $\theta_0 = X \mapsto \lambda\overline{z_n}.z_j\overline{Y_k\overline{z_n}}$ for some $0 < i < j \leq n$:*

$$t_i\overline{X_l t_n} \doteq f\overline{s_m} \quad (1)$$

and

$$t_j\overline{Y_k t_n} \doteq f\overline{s_m} \quad (2)$$

Then, there are no substitutions σ and θ such that σ unifies equation 1 and θ unifies equation 2.

Proof. Assume the existence of the two unifiers and obtain a contradiction. According to Lemma 20, we can rewrite the two equations as

$$f\overline{v_{m-l}X_l t_n} \doteq f\overline{s_m} \quad (3)$$

and

$$f\overline{u_{m-k}Y_k t_n} \doteq f\overline{s_m} \quad (4)$$

for restricted terms $\overline{v_{m-l}}$ and $\overline{u_{m-k}}$. Assume, wlog, that $l \geq k$. Note also, that since $t_i \neq t_j$ and t_i, t_j have f as head symbol, $m \geq m - k > 0$. We consider two cases:

- s_1, \dots, s_{m-k} are all ground terms. In this case and since both equations are unifiable, we get the equation

$$f\overline{v_{m-l}X_{l-k}t_n}\sigma = f\overline{s_{m-k}} = f\overline{u_{m-k}} \quad (5)$$

Clearly, $k \neq l$ since otherwise $t_i = t_j$ which violates the **local restriction** from Def. 14. We can now conclude that

$$X_l\overline{t_n}\sigma = u_{m-l+1} \quad (6)$$

Since u_{m-l+1} is a restricted term then, according to Lemma 19, there is $0 < k_1 \leq n$ such that t_{k_1} is a subterm of u_{m-l+1} . Since u_{m-l+1} is a subterm of t_j , we get that t_{k_1} is a subterm of t_j which contradicts the **local restriction**.

- There is s_{k_1} for $0 < k_1 \leq m - k$ which contains an occurrence of $Z\overline{r_{k_2}}$. This must occur as a subterm of s_{k_1} as otherwise the subterm $Z\overline{r_{k_2}}r'$ where r' is not a restricted term, violates the **argument restriction**. Since $s_{k_1}\theta = u_{k_1}$ and u_{k_1} is a restricted term, we have, according to Lemma 18, that there exist a restricted term u' such that $Z\overline{r_{k_2}}\theta = u'$. Using Lemma 19, we can conclude that there is $0 < k_3 \leq k_2$ such that r_{k_3} is a subterm of u' , which is a subterm of u_{k_1} which is a strict subterm of t_j , which violates the **global restriction**.



► **Lemma 22.** *Given the equation $X\bar{t}_n \doteq f\bar{s}_m$ where X does not occur in $f\bar{s}_m$ and assuming we can obtain the following two equations by applying the substitutions $\sigma_0 = X \mapsto \lambda\bar{z}_n.f\bar{X}_m\bar{z}_n$ and $\theta_0 = X \mapsto \lambda\bar{z}_n.z_j\bar{Y}_k\bar{z}_n$ for some $0 < j \leq n$:*

$$f\bar{X}_m\bar{t}_n \doteq f\bar{s}_m \quad (7)$$

and

$$t_j\bar{Y}_k\bar{t}_n \doteq f\bar{s}_m \quad (8)$$

Then, there are no substitutions σ and θ such that σ unifies equation 7 and θ unifies equation 8.

Proof. Assume the existence of the two unifiers and obtain a contradiction. Using Lemma 20, we can rewrite Eq. 8 as:

$$f\bar{v}_{m-k}\bar{Y}_k\bar{t}_n \doteq f\bar{s}_m \quad (9)$$

where v_1, \dots, v_{m-k} are restricted terms and strict subterms of t_j . Since f is imitated, it is not a restricted term and $f \neq t_j$ which implies that $m - k > 0$. Eq. 9 tells us that $v_1 = s_1\theta$ which implies that $s_1\theta$ is a strict subterm of t_j and a restricted term. On the other hand, we have that $X_1\bar{t}_n = s_1\sigma$ from Eq. 7. We consider two cases:

- s_1 is ground. In this case we can use Lemma 19 and the fact that s_1 is a restricted term to conclude that there is $0 < k_1 \leq n$ such that t_{k_1} is a subterm of s_1 . On the other hand, we know that s_1 is a strict subterm of t_j and therefore we get that t_{k_1} is a strict subterm of t_j , which contradicts the **local restriction**.
- If s_1 is not ground, it must contain an occurrence $Z\bar{r}_l$. This occurrence cannot occur as the subterm $Z\bar{r}_l r'$ where r' is not a restricted term as it violates the **argument restriction**. Therefore, $Z\bar{r}_l$ is a subterm of s_1 . Since $s_1\theta = v_1$ and since v_1 is a restricted term, we can use Lemma 18 to get that there is a restricted term v' such that $Z\bar{r}_l = v'$. Now we use Lemma 19 and get that there is $0 < k_1 \leq l$ such that r_{k_1} is a subterm of v' , which is a strict subterm of t_j . We get again a contradiction to the **global restriction**.



► **Theorem 23** (The existence of most-general unifiers). *Given a unifiable FCU system S , then applying the procedure in Def. 7 to S terminates and returns a most-general unifier for S .*

Proof. The procedure in Def. 7 computes complete sets of unifiers and terminates with an element in this set [32]. Using the lemmas 21 and 22 we obtain that all transformations are deterministic. Therefore, the complete set contains only one element, which is the most-general unifier of S .



3.3 The Unification Algorithm

For defining the unification algorithm, we need to slightly extend the definition of pruning.

► **Definition 24** (Covers). A cover for $X\bar{t}_n$ and a restricted term q is a substitution σ such that $X\bar{t}_n\sigma = q$.

Note, uniqueness of covers follows from Theorem 23

► **Example 25.** The following substitution $[X \mapsto \lambda z_1 \lambda z_2. \text{cons}(\text{fst } z_1) z_2]$ is a cover for $(X l z)$ and $(\text{cons}(\text{fst } l) z)$.

► **Definition 26** (Pruning). Given an FCU system $\langle Q_{\exists}, Q_{\forall}, S, \sigma \rangle$ such that $(X \bar{t}_n \doteq r) \in S$ and r contains an occurrence of a maximal restricted term q such that $q \notin \bar{t}_n$:

- if there is a subterm $W \bar{s}_m$ of r such that $q = s_i$ for some $0 < i \leq m$, then return $\langle Q_{\exists} \uplus \{W'\} \setminus \{W\}, Q_{\forall}, S\theta, \sigma \circ \theta \rangle$ where $\theta = [W \mapsto \lambda \bar{z}_m. W' \bar{z}'_{m-1}]$ and $\bar{z}'_{m-1} = \bar{z}_m \setminus \{z_i\}$.
- else if there is no cover ρ for $X \bar{t}_n$ and q , then return $\langle Q_{\exists}, Q_{\forall}, \perp, \text{id} \rangle$.
- else, do nothing.

► **Example 27.** Given the system $\langle \{X, Y, W, Z\}, \{l, w, z\}, \{X(\text{snd } l) z \doteq Y z(\text{fst } l), W(\text{fst } l) z \doteq \text{snd}(Z w(\text{fst } l))\}, \text{id} \rangle$, we can apply the following three prunings, $\sigma_1 = [Z \mapsto \lambda z_1, z_2. Z' z_1]$, $\sigma_2 = [Y \mapsto \lambda z_1, z_2. Y' z_1]$ and $\sigma_3 = [x \mapsto \lambda z_1, z_2. X' z_2]$ and obtain the system $\langle \{X', Y', W, Z'\}, \{l, w, z\}, \{X' z \doteq Y' z, W(\text{fst } l) z \doteq \text{snd}(Z' z)\}, \sigma_1 \circ \sigma_2 \circ \sigma_3 \rangle$.

For the next definition, we will use the following replacement operator $r \stackrel{\bar{t}_n}{\bar{z}_n}$ to denote the replacement of each occurrence t_i in r with z_i for $0 < i \leq n$.

► **Definition 28** (Algorithm for FCU Systems). The rules of an algorithm for the unification of FCU systems is given in Table 3 where before the application of rules (3) and (5) we apply exhaustively pruning.

$$\langle Q_{\exists}, Q_{\forall}, S \uplus \{t \doteq t\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall}, S, \sigma \rangle \quad (0)$$

$$\langle Q_{\exists}, Q_{\forall}, S \uplus \{\lambda x. s \doteq \lambda x. t\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall} \uplus \{x\}, S \uplus \{s \doteq t\}, \sigma \rangle \quad (1)$$

$$\langle Q_{\exists}, Q_{\forall}, S \uplus \{f \bar{t}_n \doteq f \bar{s}_n\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall}, S \uplus \{t_1 \doteq s_1, \dots, t_n \doteq s_n\}, \sigma \rangle \quad (2)$$

where $f \in \mathcal{C} \uplus Q_{\forall}$

$$\langle Q_{\exists} \uplus \{X\}, Q_{\forall}, S \uplus \{X \bar{t}_n \doteq f \bar{s}_m\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall}, S\theta, \sigma \circ \theta \rangle \quad (3)$$

where $f \in \mathcal{C}$, $X \notin \text{fvars}(f \bar{s}_m)$ and $\theta = [X \mapsto \lambda \bar{z}_n. f \bar{s}_m \stackrel{\bar{t}_n}{\bar{z}_n}]$

$$\langle Q_{\exists} \uplus \{X\}, Q_{\forall}, S \uplus \{X \bar{t}_n \doteq X \bar{s}_n\}, \sigma \rangle \rightarrow \langle Q_{\exists} \uplus \{W\}, Q_{\forall}, S\theta, \sigma \circ \theta \rangle \quad (4)$$

where $W \notin Q_{\exists}$, $\bar{t}_n \neq \bar{s}_n$, $\theta = [X \mapsto \lambda \bar{z}_n. W \bar{z}_{r_k}]$ and $\bar{r}_k = \{i \mid 0 < i \leq n \wedge t_i \doteq s_i\}$

$$\langle Q_{\exists} \uplus \{Y\}, Q_{\forall}, S \uplus \{X \bar{t}_n \doteq Y \bar{s}_m\}, \sigma \rangle \rightarrow \langle Q_{\exists}, Q_{\forall}, S\theta, \sigma \circ \theta \rangle \quad (5)$$

where $X \neq Y$, $\theta = [Y \mapsto \lambda \bar{z}_m. X \bar{z}_{\phi(m)}]$ and ϕ is a permutation (see Lemma 36)

such that $\phi(j) = i$ if $t_i = s_j$ for $0 < i \leq n$ and $0 < j \leq m$

■ **Table 3** An algorithm for FCU problems

► **Example 29.** The following problem is contained in one of the classes of problems discussed in the introduction: $\exists X \exists Y \lambda l_1 \lambda l_2. X(\text{fst } l_1)(\text{fst}(\text{snd } l_1)) \doteq \lambda l_1 \lambda l_2. \text{snd}(Y(\text{fst } l_2)(\text{fst } l_1))$ Table 4 gives a full execution of the algorithm on it.

$$\begin{aligned} & \langle \{X, Y\}, \emptyset, \{\lambda l_1 \lambda l_2. X(\text{fst } l_1)(\text{fst}(\text{snd } l_1)) \doteq \lambda l_1 \lambda l_2. \text{snd}(Y(\text{fst } l_2)(\text{fst } l_1))\}, \text{id} \rangle && \rightarrow^{(1) \times 2} \\ & \langle \{X, Y\}, \{l_1, l_2\}, \{X(\text{fst } l_1)(\text{fst}(\text{snd } l_1)) \doteq \text{snd}(Y(\text{fst } l_2)(\text{fst } l_1))\}, \text{id} \rangle && \rightarrow^{\text{prun}} \\ & \langle \{X, Y'\}, \{l_1, l_2\}, \{X(\text{fst } l_1)(\text{fst}(\text{snd } l_1)) \doteq \text{snd}(Y'(\text{fst } l_1))\}, [Y \mapsto \lambda z_1 \lambda z_2. Y' z_2] \rangle && \rightarrow^{(3)} \\ & \langle \{Y'\}, \{l_1, l_2\}, \{\text{snd}(Y'(\text{fst } l_1)) \doteq \text{snd}(Y'(\text{fst } l_1))\}, [Y \mapsto \lambda z_1 \lambda z_2. Y' z_2, X \mapsto \lambda z_1 \lambda z_2. \text{snd}(Y' z_1)] \rangle && \rightarrow^{(0)} \\ & \langle \{Y'\}, \{l_1, l_2\}, \emptyset, [Y \mapsto \lambda z_1 \lambda z_2. Y' z_2, X \mapsto \lambda z_1 \lambda z_2. \text{snd}(Y' z_1)] \rangle && \end{aligned}$$

■ **Table 4** An example of a reduction on an FCU

Notice that this algorithm can also work with terms that are essentially untyped: it is the presence or absence of constructors and bound variables that matters in this algorithm and not the types of those constructors and variables. Rich typing can, of course, be used to disallow unifiers that are created by considering terms to be type-less.

4 Correctness of the Algorithm

The unification algorithm transforms systems by the application of substitutions and by the elimination of equations. We prove next that the application of rules of the algorithm in Def. 28 on FCU problems results in FCU problems as well.

► **Lemma 30.** *Given an FCU problem, then the application of rules from Def. 28 results in an FCU problem.*

Proof. Removing equations from the system clearly preserves the restrictions of FCU problems. This result is also immediate when applying substitutions as the only change to the arguments of the variables in the problem is to eliminate them and we have already claimed that the subterm property is closed under α -renaming for these problems in Lemma 5. ◀

The following lemma states that projected arguments of variables on one side of the equation must always match arguments on the other side.

► **Lemma 31.** *Let $X\bar{t}_n \doteq r$ be an equation such that r contains an occurrence of $Y\bar{s}_m$ where $r \neq Y\bar{s}_m$ and let σ be a unifier of this equation such that $\sigma Y = \lambda\bar{z}_m.s$. Then, for each occurrence z_i in s for $0 < i \leq m$, there is $0 < j \leq n$ such that $s_i = t_j$.*

Proof. We prove by induction on the number of occurrences. If s does not contain such occurrence, then the lemma clearly holds. Assume s contains an occurrence z_i for $0 < i \leq m$ and that there is no $0 < j \leq n$ such that $s_i = t_j$. In case there is more than one such occurrence in s , choose this occurrence to be in a minimal such subterm, i.e. z_i occurs in a subterm $z_i\bar{v}_k$ such that all occurrences of $z \in \bar{z}_m$ in \bar{v}_k fulfill the requirement that there is $t_j = z$ for some $0 < j \leq n$. Let $\lambda\bar{z}_m.z_i\bar{v}_k(\bar{s}_m) = s_i\bar{v}'_k$. Since $r \neq Y\bar{s}_m$ and the **argument restriction**, we have that $Y\bar{s}_m \sqsubset r$. Since $X\bar{t}_n\sigma = r\sigma$, we get that $s_i\bar{v}'_k \sqsubset X\bar{t}_n\sigma$. Since s_i is a restricted term, we get that there is $0 < j \leq n$ such that either

- $s_i\bar{v}'_k \sqsubset t_j$. By the minimality assumption, if \bar{v}'_k contains a restricted term, then it must be equal to some t_l $0 < l \leq n$ and therefore, that $t_l \sqsubset t_j$, which contradicts the **local restriction**. Therefore, since t_j is a restricted term, $k = 0$. We obtain that $s_i \sqsubset t_j$ and since $s_i \neq t_j$ by assumption, we get, again, a contradiction to the **global restriction**.
- $t_j \sqsubset s_i$. Again, since $s_i \neq t_j$, we get a contraction to the **global restriction**.

◀

We now prove, for each rule in the FCU algorithm, a relative completeness result. We start by the non-unifiability of problems with a positive occur check.

► **Lemma 32.** *Let $\langle Q_\exists, Q_\forall, S \cup \{X\bar{t}_n \doteq f\bar{s}_m\}, \sigma \rangle$ be a system such that X occurs in \bar{s}_m , then the system is not unifiable.*

Proof. Assume it is unifiable by θ and $\theta X = \lambda\bar{z}_n.s$. Consider two cases:

- s does not contain any occurrence of a variable z_i for $0 < i \leq n$. Let $\#t$ be the number of occurrences of symbols from \mathfrak{C} in t . Then, $\#(X\bar{t}_n\theta) = \#(\theta X) \leq \#(\bar{s}_m\theta) < \#(f\bar{s}_m\theta)$ and we get a contradiction to $X\bar{t}_n\theta = f\bar{s}_m\theta$.
- In case s contains such an occurrence and let $X\bar{q}_n$ be the occurrence in \bar{s}_m . According to Lemma 31, we know that for all occurrences of z_i in s for $0 < i \leq n$, there is an index $0 < j \leq n$ such that $t_j = q_i$. Let ρ be the mapping between indices defined as above such that $\rho(i) = j$. Let \bar{r}_k be the set of indices $0 < i \leq n$ which occur in s for some $k \leq n$. Let p' be the non-trivial position of $X\bar{q}_n$ in $f\bar{s}_m$ and let p be the maximal position of a z_i in s for $i \in \bar{r}_k$. This means we have q_i at position $p' \circ p$ in $f\bar{s}_m\theta$ and since $t_{\rho(i)} = q_i$

and $X\bar{t}_n\theta = f\bar{s}_m\theta$, we get that $t_{\rho(i)}$ occurs at position $p' \circ p$ in $X\bar{t}_n\theta$. Since $t_{\rho(i)}$ is a restricted term, there is an occurrence of $z_{\rho(i)}$ in s at position $p' \circ p$, in contradiction to the maximality of p . ◀

► **Lemma 33.** *Given a system $\langle Q_{\exists}, Q_{\forall}, S, \rho \rangle$ where $X\bar{t}_n \doteq r \in S$ and assuming we apply pruning in order to obtain system $\langle Q_{\exists}, Q_{\forall}, S', \rho' \rangle$ as defined in Def. 26, then, if S is unifiable by substitution σ , then there is a substitution σ' , such that $\sigma = \theta \circ \sigma'$. If S is not unifiable, then S' is not unifiable.*

Proof. The rule is applicable only if there is such an occurrence q . Otherwise, $S = S'$ and $\theta = \text{id}$. We consider the two cases in the lemma:

- there is a subterm $Y\bar{s}_m$ of r such that $q = s_i$ for $0 < i \leq m$. If S is not unifiable, then assume S' is unifiable by σ' and since $S' = S\theta$, we get that S is unifiable by $\theta \circ \sigma'$, a contradiction. Assume the system is unifiable and let $\sigma Y = \lambda\bar{z}_m.s$. Then, according to Lemma 31, either there is $0 < j \leq n$, such that $t_j = s_i$, which contradicts the assumption, or s does not contain an occurrence of s_i . In the second case, by taking $\sigma' = \sigma|_{\mathfrak{D}(S) \setminus \{Y\}}[W \mapsto \lambda\bar{z}_{r_{m-1}}.Y\bar{z}_m\sigma]$ where $\bar{z}_m \setminus \bar{z}'_{m-1} \not\subseteq Q_{\forall}$, we get that $Y\bar{s}_m\sigma = W\bar{s}_{r_{m-1}}\sigma' = Y\bar{s}_m\theta \circ \sigma'$.
- If there is no such cover, then there is no substitution which unifies this equation. ◀

► **Lemma 34.** *Given a system $\langle Q_{\exists}, Q_{\forall}, S, \rho \rangle$ where $X\bar{t}_n \doteq s \in S$ and X does not occur in s and assuming we apply the substitution θ as defined in rule (3) in Table 3. Then, if σ a unifier of S , then there is σ' such that $\sigma = \theta \circ \sigma'$.*

Proof. We prove by induction on the structure of s . Note that two base cases are also defined in the last two cases below for $m = 0$.

- $s = Y\bar{s}_m$ for $0 \leq m$. Note, that in this case, since $t_i \not\sqsubseteq s_j$ for $0 < i \leq n$ and $0 < j \leq m$ and that since $m \leq n$ due to pruning, we get that $X\bar{t}_n\theta = Y\bar{t}_{\phi(m)}$ for ϕ defined as in rule (5) in Table 3. The rest of the proof is similar to the proof of Lemma 36.
- $s = t_i\bar{s}_m$ for some $0 < i \leq n$ and $0 \leq m$ and therefore $\theta X = \lambda\bar{z}_n.z_i\bar{s}'_m$ for some \bar{s}'_m . Assume applying (Project) with the substitution $\theta' = \lambda\bar{z}_n.z_i\bar{X}_m\bar{z}_n$ as defined in Def. 7. After applying (Bind) and possibly also several (Decomp), we get the problem, since X cannot occur in s ,

$$S'\theta' \cup \{X_1\bar{t}_n \doteq s_1, \dots, X_m\bar{t}_n \doteq s_m\} \quad (10)$$

Since, by assumption, $X\bar{t}_n \doteq t_i\bar{s}_m$ is unifiable and t_i is a restricted term, it follows, using an argument similar to the one in the proof of Lemma 21, that also each of the $X_j\bar{t}_n \doteq s_j$ is unifiable by some σ_j^o for $0 < j \leq m$. By following lemmas 21 and 22, we have that applying any other projection or imitation to $X\bar{t}_n \doteq t_i\bar{s}_m$ will render it non-unifiable. By using Theorem 8, we have that σ_j^o can be extended into a unifier σ_j of $S'\theta' \cup \{X_j\bar{t}_n \doteq s_j\}$ for all $0 < j \leq m$ and $\sigma = \theta' \circ \sigma_1 \circ \dots \circ \sigma_m$. By applying the induction hypothesis, we get that there are substitutions σ'_j unifying $S'\theta' \cup \{X_j\bar{t}_n \doteq s_j\}$ for all $0 < j \leq m$ such that $\sigma_j = \theta_j \circ \sigma'_j$ for $\theta_j X_j = \lambda\bar{z}_n.s'_j$. I.e. that $\sigma = \theta' \circ \theta_1 \circ \sigma'_1 \circ \dots \circ \theta_m \circ \sigma'_m$. Since each σ_j is a unifier of the above equations and σ is a unifier of S , we get that for each $m \geq j' > j$, $\sigma'_{j'} \leq \sigma'_j|_{\text{dom}(\sigma'_{j'})}$. From this, together with the fact that the domain and range of each σ'_j do not contain variables from the domain of each $\theta_{j'}$ for $0 < j < j' \leq m$, we get that $\sigma = \theta' \circ \theta_1 \circ \dots \circ \theta_m \circ \sigma'_1 \circ \dots \circ \sigma'_m$. On the other hand, by applying θ , we get the problem

$$S'\theta \cup \{s'_1 \doteq s_1, \dots, s'_m \doteq s_m\} \quad (11)$$

But, since $\theta = \theta' \circ \theta_1 \circ \dots \circ \theta_m$, we just need to choose $\sigma' = \sigma'_1 \circ \dots \circ \sigma'_m$ and we have $\sigma = \theta \circ \sigma'$.

- $s = f\overline{s_m}$ for $0 \leq m$ and therefore $\theta X = \lambda\overline{z_n}.f\overline{s'_m}$. Assume applying (Imitate) with the substitution $\theta' = \lambda\overline{z_n}.f\overline{X_m\overline{z_n}}$. After applying (Bind) and a (Decomp), we get the problem, since x cannot occur in s ,

$$S'\theta' \cup \{X_1\overline{t_n} \doteq s_1, \dots, X_m\overline{t_n} \doteq s_m\} \quad (12)$$

From here we follow as before and use again Theorem 8 and Lemma 22. ◀

- **Lemma 35.** *Given a system $\langle Q_\exists, Q_\forall, S' \cup \{X\overline{t_n} \doteq X\overline{s_n}\}, \rho \rangle$ and assuming we apply the substitution θ as defined in rule (4) in Table 3. Then, if the system is unifiable by a substitution σ , then there is σ' such that $\sigma = \theta \circ \sigma'$.*

Proof. Assume that $\sigma X = \lambda\overline{z_n}.s$, we first prove that there is no occurrence z_i in s such that there is $0 < j \leq k$ where $i = r_j$ and $t_i \neq s_i$. Assume on the contrary, then $X\overline{t_n}\sigma = X\overline{s_n}\sigma$ which implies that $t_i = s_i$. Now we can define $\sigma' = \sigma|_{\mathfrak{V}(S) \setminus \{X\}}[W \mapsto \lambda\overline{z_{r_k}}.X\overline{z_n}\sigma]$ where $\overline{z_n} \setminus \overline{z_{r_k}} \not\subseteq Q_\forall$ are new variables. ◀

- **Lemma 36.** *Given a system $\langle Q_\exists, Q_\forall, S' \cup \{X\overline{t_n} \doteq Y\overline{s_m}\}, \rho \rangle$ where $X \neq Y$ and assuming we apply the substitution θ as defined in rule (5) in Table 3. Then, if the system is unifiable by a substitution σ , then there is σ' such that $\sigma = \theta \circ \sigma'$.*

Proof. First note that since we apply pruning beforehand (in a symmetric way), $n = m$ and ϕ is indeed a permutation. Assume, wlog, that $\sigma X = \lambda\overline{z_n}.s$. We know that for each occurrence z_i in s for $0 < i \leq n$, $s_i = t_{\phi(i)}$. By choosing $\sigma' = \sigma|_{\mathfrak{V}(S) \setminus \{Y\}}$, we get that $Y\overline{s_m}\sigma = X\overline{s_{\phi(m)}}\sigma = X\overline{s_{\phi(m)}}\sigma' = Y\overline{s_m}\theta \circ \sigma'$. Therefore, $\sigma = \theta \circ \sigma'$. ◀

- **Theorem 37 (Termination).** *Given a system $\langle Q_\exists, Q_\forall, S, \sigma \rangle$, the algorithm in Def. 28 always terminates.*

Proof. Let the tuple $m = \langle m_1, m_2 \rangle$ where m_1 is the size of the set Q_\exists and m_2 is the number of all symbols except \doteq in S . Consider its lexicographical order, it is clear that m is well founded. We show that it decreases with every rule application of the algorithm:

- rules (0), (1) and (2) decrease m_2 and do not increase m_1 .
- rule (3) decreases m_1 .
- rule (4) decreases m_2 and does not increase m_1 .
- rule (5) decreases m_1 .
- pruning decreases m_2 and does not increase m_1 . ◀

- **Theorem 38 (Completeness).** *Given a system $\langle Q_\exists, Q_\forall, S, \mathfrak{d} \rangle$ and assuming it is unifiable by σ , there there is a sequence of rule applications in Def. 28 resulting in $\langle Q'_\exists, Q'_\forall, \emptyset, \theta \rangle$ such that $\theta \leq \sigma$.*

Proof. Since the algorithm terminates and since it has a rule application for each unifiable equation, we obtain at the end the above system. Lemmas 32, 33, 34, 35 and 36 then give us that for any unifier σ of S , there is a substitution σ' such that $\sigma = \theta \circ \sigma'$. Therefore, $\theta \leq \sigma$. ◀

The next theorem is an easy corollary of the completeness theorem.

► **Theorem 39** (Most-general unifier). *Given a system $\langle Q_{\exists}, Q_{\forall}, S, \mathbf{id} \rangle$, if the algorithm defined in Def. 28 terminates with system $\langle Q'_{\exists}, Q'_{\forall}, \emptyset, \sigma \rangle$, then σ is an mgu of S .*

Proof. Since the algorithm in Def. 28 is deterministic, then we can use Theorem 38 in order to prove that σ is an mgu. ◀

The next theorem is proved by simulating the algorithm in Def. 28 using the procedure in Def. 7.

► **Theorem 40** (Soundness). *Given a system $\langle Q_{\exists}, Q_{\forall}, S, \mathbf{id} \rangle$ and assuming there is a sequence of rule applications in Def. 28 resulting in $\langle Q'_{\exists}, Q'_{\forall}, \emptyset, \theta \rangle$, then θ is a unifier of S .*

Proof. It is obvious we can simulate each of the rules (0), (1), (2) and (3) using the procedure in Def. 7. We get the required result by using Theorem 23. For rules (4), (5) and the first case of pruning, assume there is another substitution ρ such that ρ unifies the problem and $\rho \not\prec \theta$. This can only happen if $\rho X = \lambda \bar{z}_n. \overline{W' r_{k'}}$ such that $\bar{r}_k \subset \bar{r}'_{k'}$. Lemma 35 states that there is no unifier ω and a substitution γ such that $\omega = \rho \circ \gamma$. Since the second case of pruning results in failure, we are done. ◀

5 Conclusion

We have described an extension of pattern unification called *function-as-constructor* unification. Such unification problems typically show up in situations where functions are applied to bound variables and where such functions are treated as term constructors (at least during the process of unification). We have shown that the properties that make first-order and pattern unification desirable for implementation—decidability and the existence of mgus for unifiable pairs—also hold for this class of unification problems. We are planning an implementation within the Leo-III theorem prover [35] and we then plan to compare this approach to unification with the implementation of Huet’s pre-unification algorithm available in Leo-III when exercised against the THF set of problems within TPTP [8].

Another possible extension of the work is to improve its complexity class. The current algorithm, like the one in [20] and first-order unification algorithms which are used in practice, is of an exponential complexity. We would like to follow the work of Qian [34] and prove that FCU is of linear complexity.

Acknowledgments. We thank Enrico Tassi for discussions related to this paper. We benefited greatly from the many comments of the anonymous reviewers of an earlier draft of this paper. This work has been funded by the ERC Advanced Grant ProofCert.

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