

Execution Trace Management to Support Dynamic V&V for Executable DSMLs

Ph.D defense

December 3, 2015

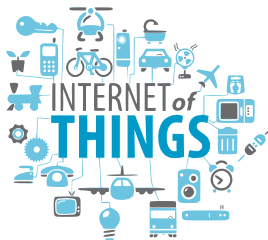
Jury

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Prof. Franck Barbier, UPPA / *rapporteur*
Dr. Julien DeAntoni, UNS / *examineur*
Prof. François Taïani, UR1 / *examineur*
Dr. Benoit Baudry, Inria / *directeur de thèse*
Dr. Benoit Combemale, Inria – UR1 / *co-encadrant*

Erwan Bousse
University of Rennes 1

A photograph of the cockpit of a Boeing 737-400. The view is from the front of the cabin looking back into the cockpit. Two pilots' seats with blue upholstery are visible on either side of the center console. The instrument panel features multiple large digital displays and analog gauges. The center console has various controls and a small display. The overall lighting is bright, and the cockpit appears clean and modern.

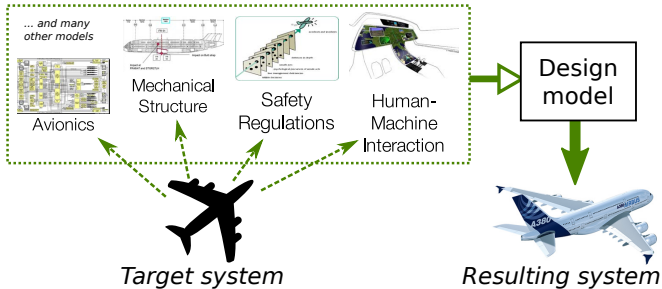
AIRBUS A380



- **Systems are more and more complex:** cyber physical systems, internet of things, massively multiplayer games, ...
- One system = **diverse and heterogeneous domains**

⇒ Many threats to their proper development and functioning

Model driven engineering (MDE)



- **Separation of concerns** through the use of **models**
- Using **domain specific modeling languages** (DSMLs)
- Enables **early verification and validation** (early V&V)

Dynamic V&V of behavioral models

- **Behavioral models** are essential in various domains and in various forms of engineering
- **Dynamic V&V** required to check their behavioral properties
 - requires models to be **executable**
 - requires defining the **execution semantics** of the DSMLs
- **Execution semantics** are composed of
 - definition of the **execution state** of conforming models
 - definition of the **execution function** that changes this state

DSML + execution semantics = **executable DSML** (xDSML)

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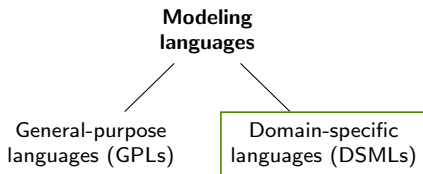
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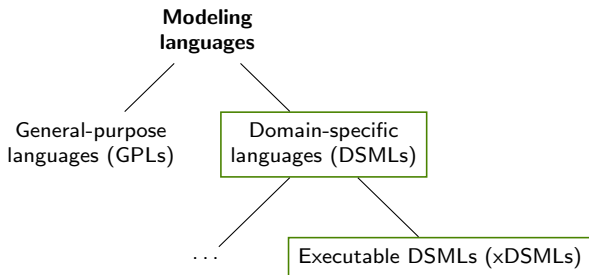
Scope and hypotheses

**Modeling
languages**

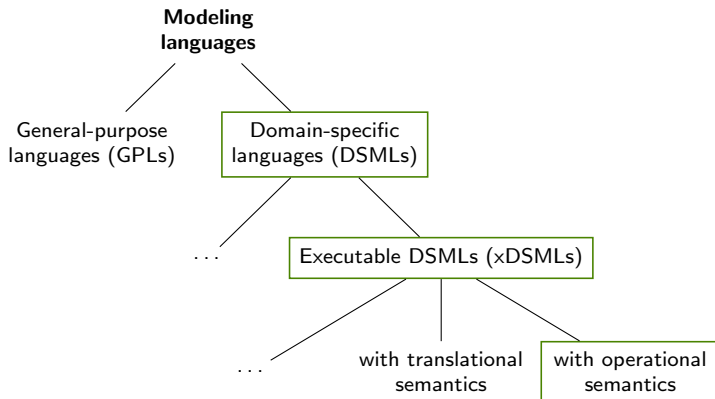
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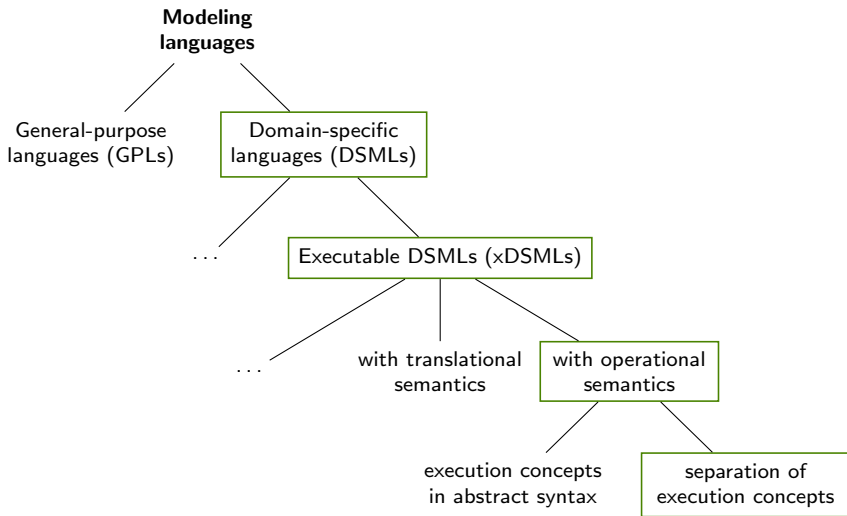
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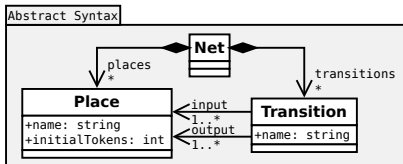
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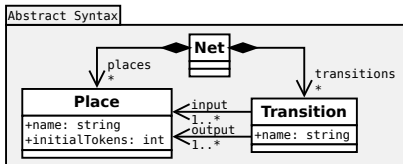
Scope and hypotheses



Example of Petri net xDSML and model

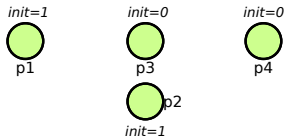
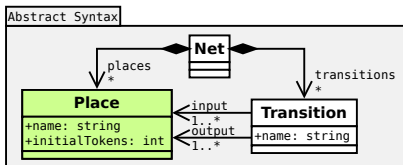


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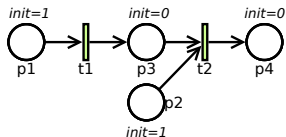
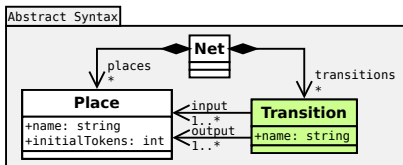
Petri net model

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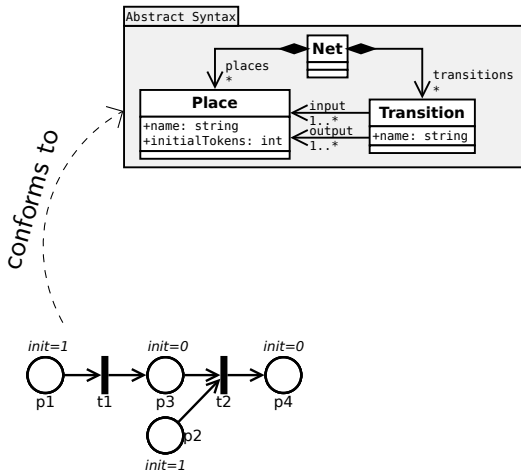
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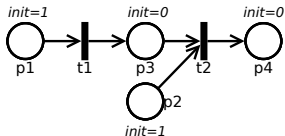
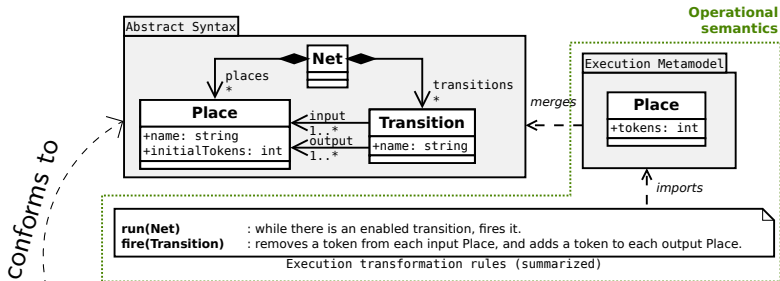
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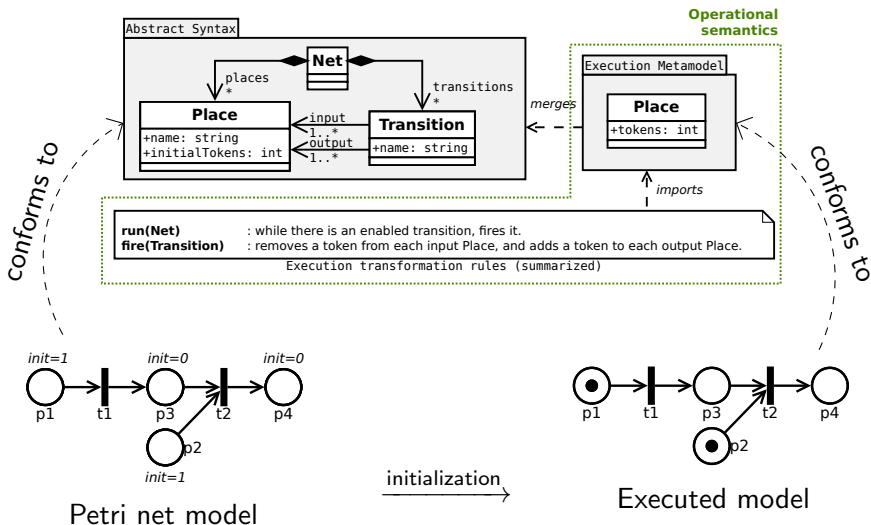
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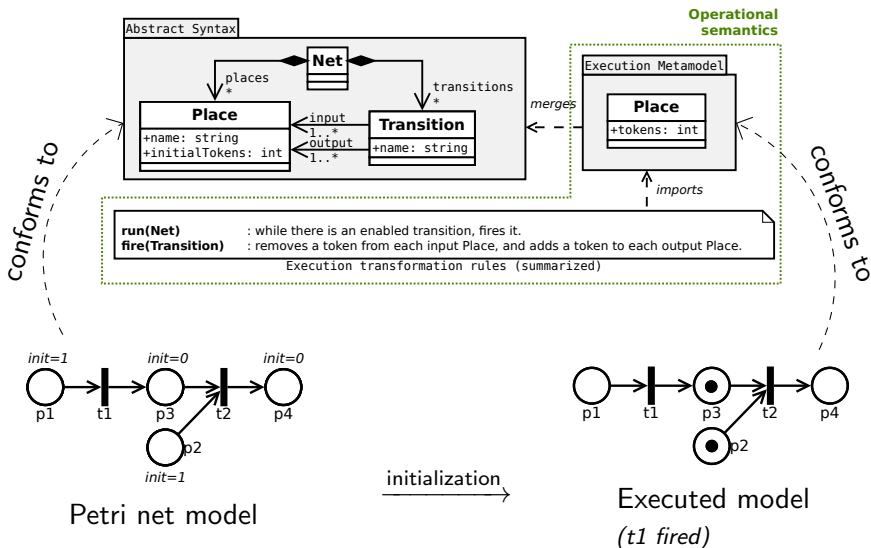


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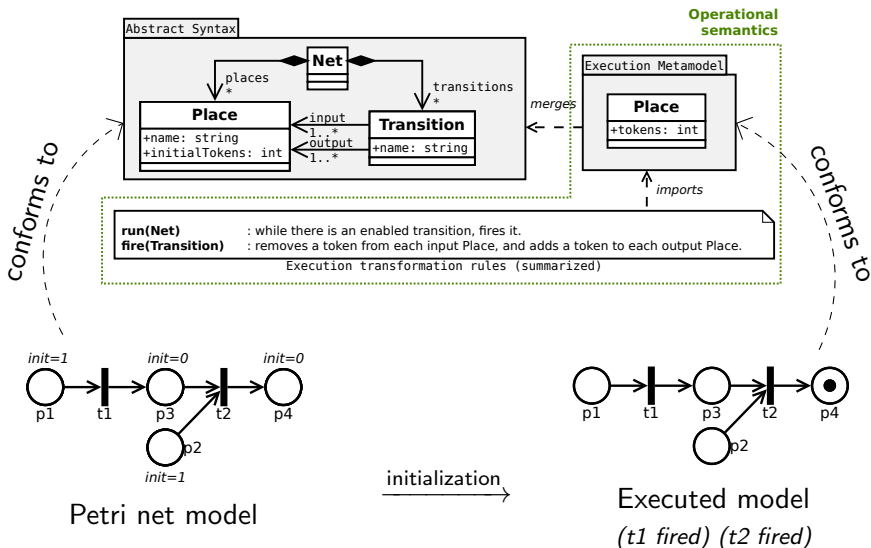
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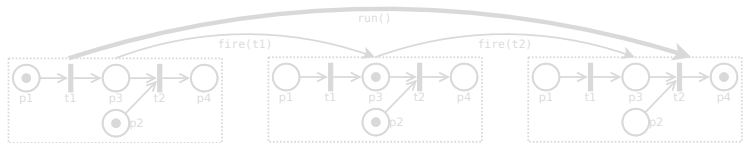
Example of Petri net xDSML and model



Representing executions as traces

How to **represent executions** in order to **analyze** them?

Example of a Petri net **execution trace**:

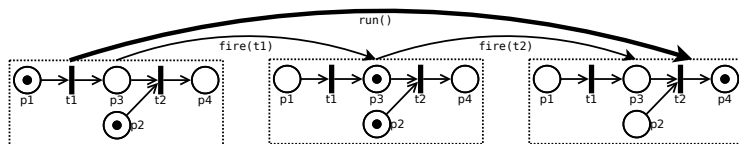


- **Execution states**, each storing the values of the mutable parts of the model (e.g. tokens)
- **Execution steps**, each being the application of a *transformation rule* of the operational semantics, with:
 - *small steps* in between execution states (e.g. fire)
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Difficulties in trace management

■ Execution traces can be large

- Requires **large amounts of memory** to construct a trace
- Impacts processing time during analyses
- *example*: looping small petri net (4 places and 3 transitions),
150 000 states = 130 MB

■ Many kinds of trace manipulations

- Generic (e.g. amount of steps)
- Domain-specific (e.g. number of tokens that traversed a place)

■ Many possible xDSMLs

- Existing ones (e.g. Petri net, Activity diagrams)
- Future ones (cf. language engineering)

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Problem statement

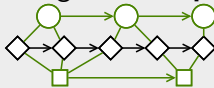
How to provide efficient execution trace management facilities for any xDSML?

Three main inter-related challenges:

- 1 **Scalability in memory** to construct large traces
- 2 **Scalability in time** to process large traces
- 3 **Usability** of the execution trace data structure, to cope with the complexity of data of arbitrarily complex xDSMLs

Contributions and applications

Multidimensionnal domain-specific trace
metamodel generation [ECMFA'15]

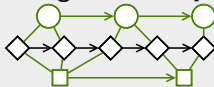


Scalable armies of model clones
[MODELS'14]



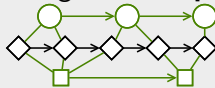
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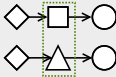
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Multidimensionnal domain-specific trace
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applied to

Enhanced semantic
differencing



applied to

Advanced and efficient
omniscient debugging [SLE'15]



Outline

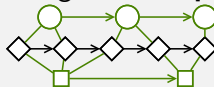
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2 Contribution

3 Evaluation

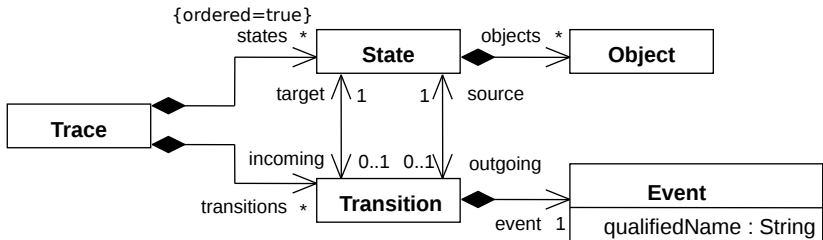
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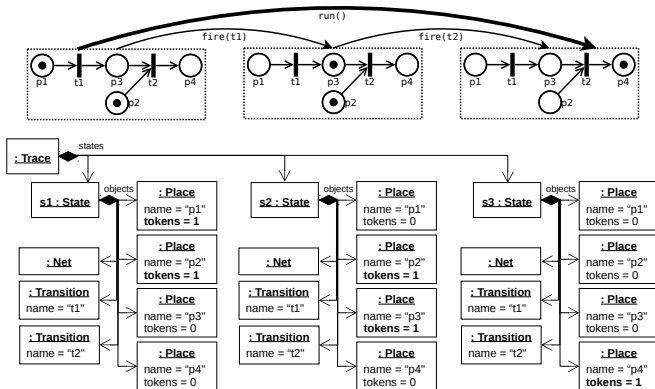
Generic trace management

State of the art: generic trace metamodel [Langer et al.'14]



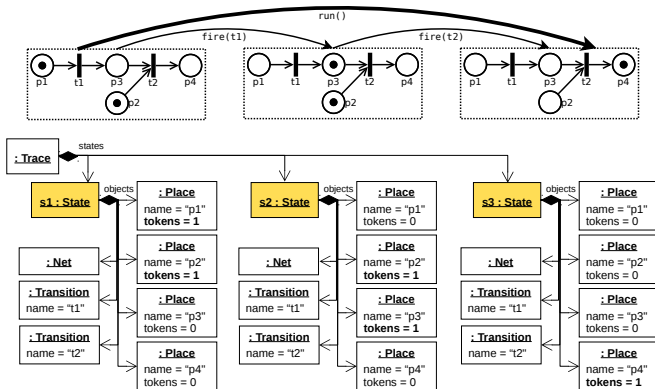
- States are stored in a unique **sequence**
- Each state is a **snapshot** (or clone) of the executed model

Example of Petri net generic trace



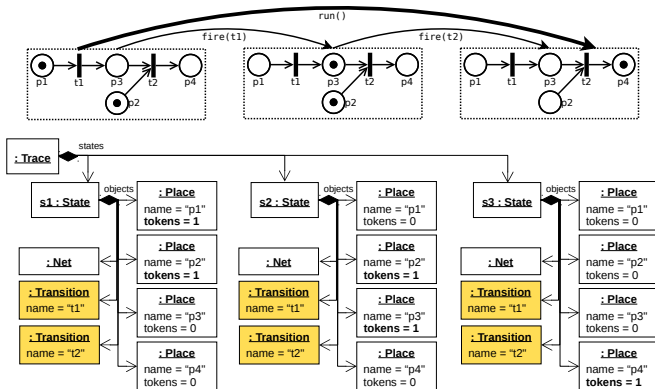
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- Usability problem: type checks and casting

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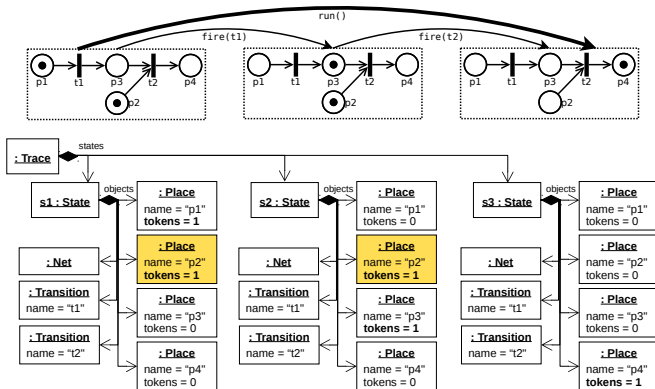
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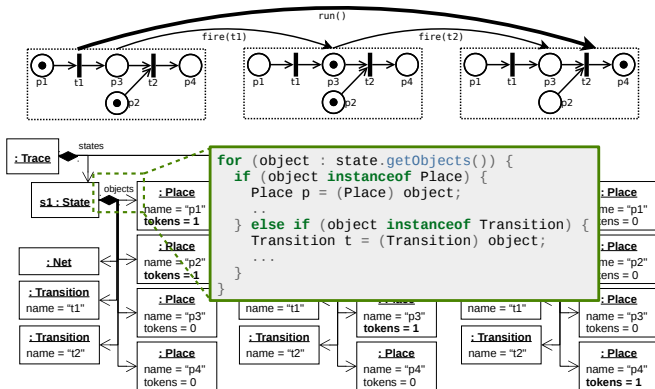
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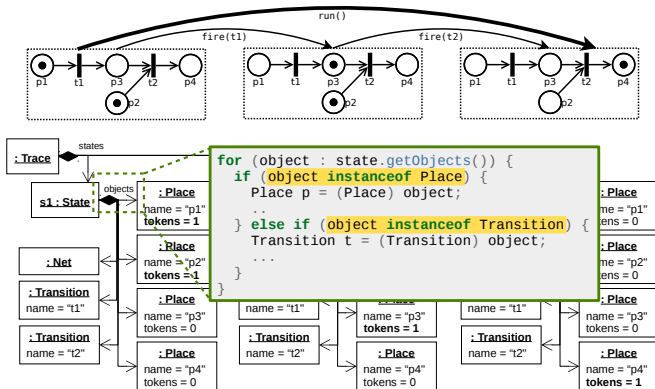
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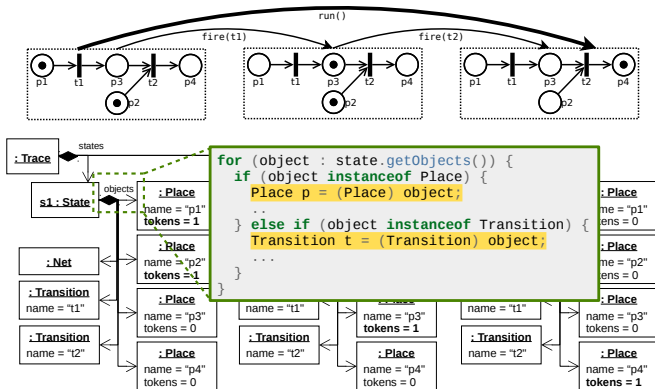
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Approach: generating a domain-specific trace metamodel

To provide usability and scalability in memory

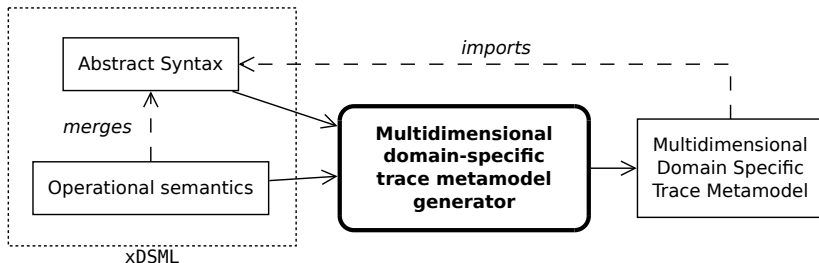
Generative approach to automatically derive a **domain-specific trace metamodel** for a given xDSML

- *Domain-specific*: domain concepts are directly accessible
- *Precise*: only concepts related to execution are kept
- *Automated*: save language engineers the design of a complex metamodel, which is time-consuming and error-prone

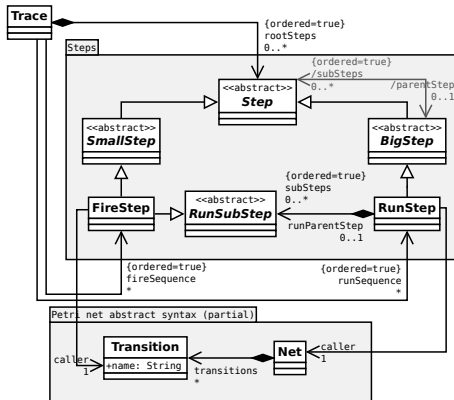
To provide scalability in time

Multidimensional navigation facilities, e.g. browsing a trace according to the values reached by a specific mutable element

Overview

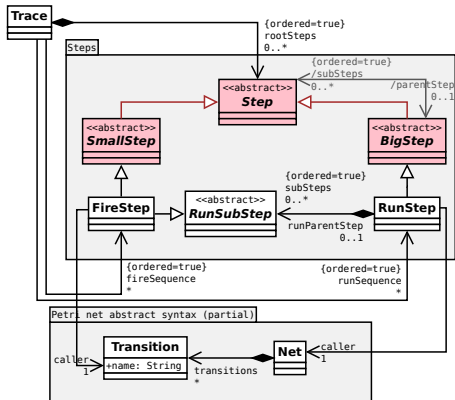


Trace metamodel generation – Steps concepts



- 1 Base classes
 - **small step** = standalone transformation rule
 - **big step** = rule relying on other rules
- 2 Reification of rules into step classes
- 3 Steps made accessible as sequences or as a containment tree

Trace metamamodel generation – Steps concepts



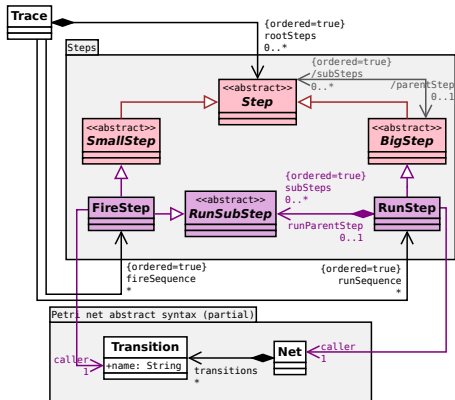
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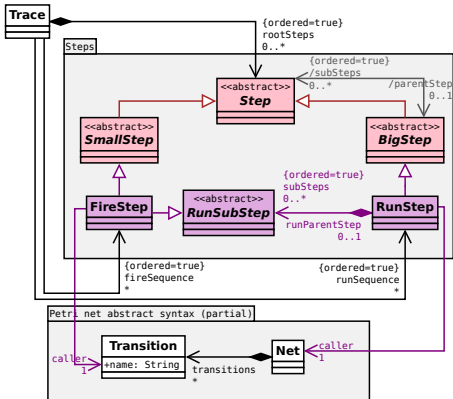
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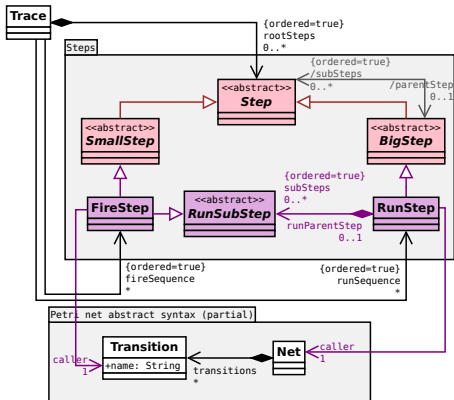
Step classes are inferred by **static analysis** of the model transformation.

- ## 1 Analysis of the code

```
def void fire() {
    ...
}

def void run() {
    while (_self.getNext() != null) {
        _self.getNext().fire()
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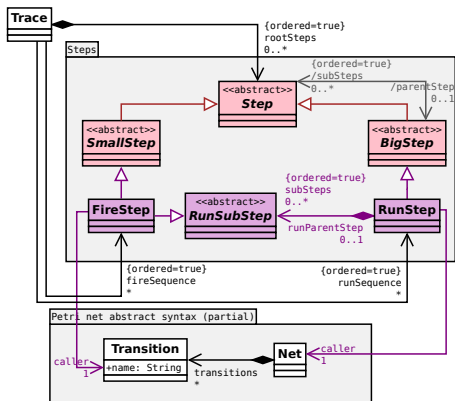
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2 Creation of a call graph

3 Pre-processing of the call graph (e.g. methods overriding)

4 Discovery of big/small steps

Trace metamodel generation – Steps concepts

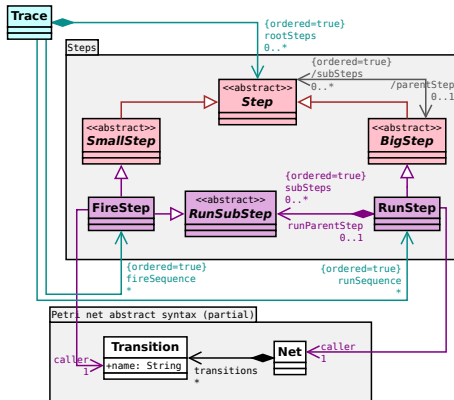


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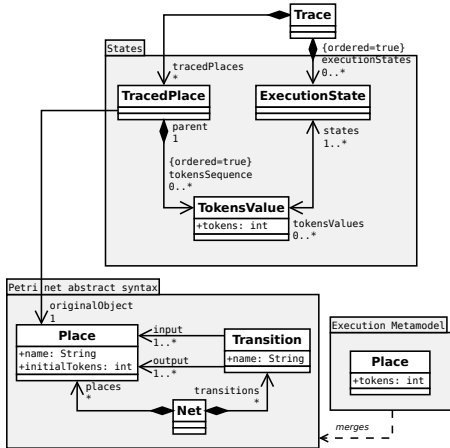
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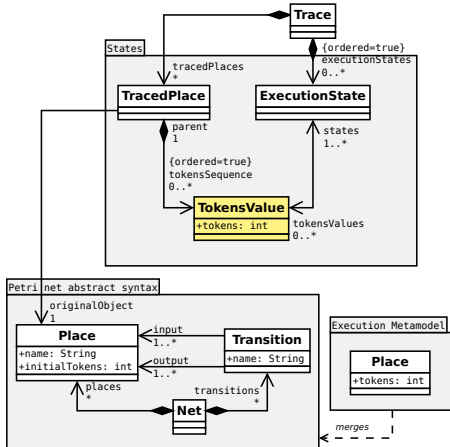
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Trace metamodel generation – States concepts



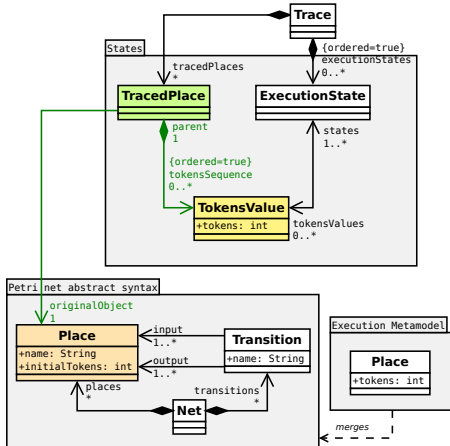
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Trace metamodel generation – States concepts



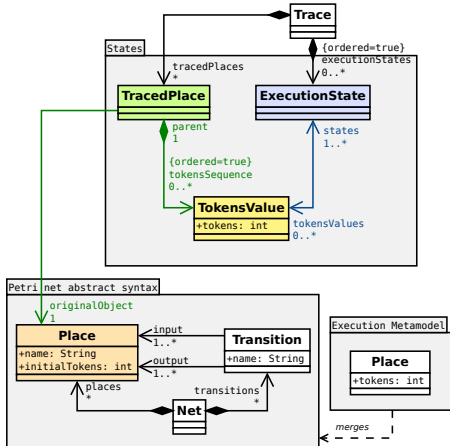
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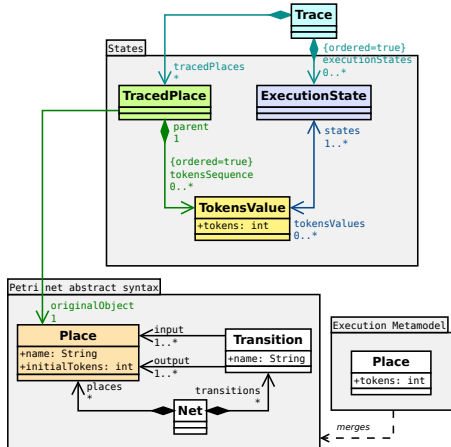
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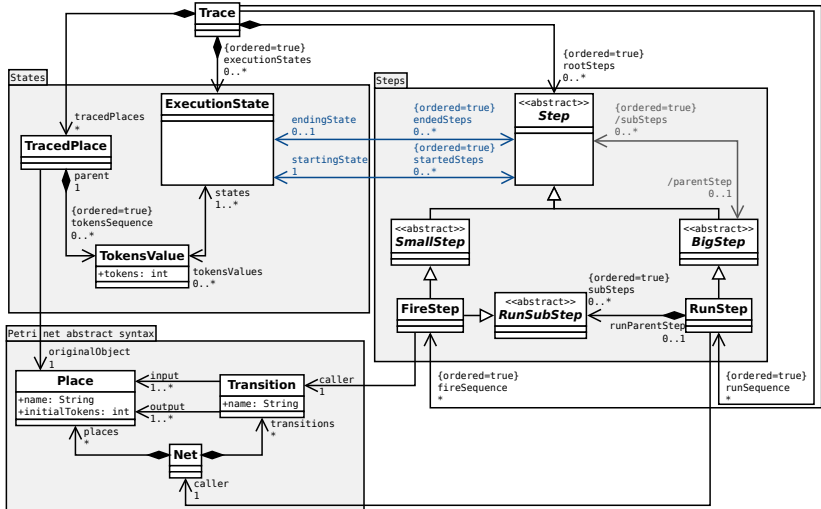
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Resulting Petri net trace metamodel



Conclusion

Summary

- **Precise capture** of the domain of the traces of an xDSML
- **Multidimensional navigation facilities** to ease queries

Questions

- **Usability** and **memory consumption** improved with domain-specificness?
- **Processing time** reduced thanks to multidimensional navigation?

⇒ Application to two different V&V techniques + measurements

Outline

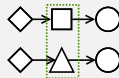
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Enhanced semantic
differencing



Advanced and efficient
omniscient debugging [SLE'15]



Evaluation

Research questions (summarized)

As compared to a generic clone-based trace metamodel:

- **RQ1: Usability** of generated trace metamodels
- **RQ2: Scalability in time** of trace manipulations
- **RQ3: Scalability in memory** of traces

Considered V&V techniques

1 Semantic differencing

- Manually defined trace manipulations
- Evaluation of RQ1 and RQ2

2 Omniscient debugging

- Generated trace manipulations
- Evaluation of RQ2 and RQ3

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Semantic model differencing

Context

- **Model differencing**: analyzing and understanding the changes made to a model during its development
- Mostly done syntactically (e.g. version control systems)

The case of xDSMLs

- A change in an executable model \equiv a change in its behavior
- Hence, model differencing must be done **semantically**
- One approach: **traces comparison** before and after a change.

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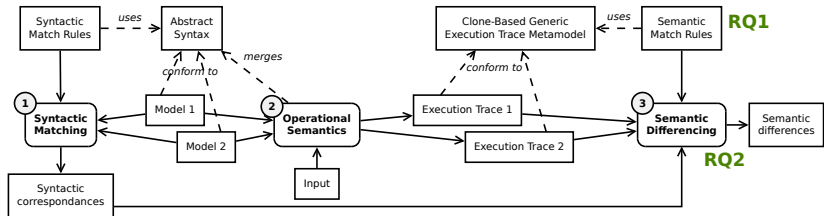
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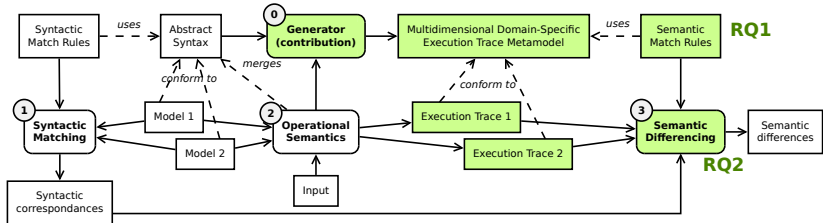
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Existing base approach [Langer et al.'14]



- Requires the **manual definition of semantic match rules** specific to the xDSML
- Relies on a **generic trace metamodel**
 - *usability (RQ1)*: match rules are hard to write
 - *scalability in time (RQ2)*: match rules are long to execute

Enhanced approach



Enhancement

- **Additional prior step:** generation of a *domain-specific trace metamodel* with our contribution
- **New semantic match rules** relying on multiple dimensions
- What we measure:
 - *usability (RQ1): complexity of the match rules*
 - *scalability in time (RQ2): execution time of the match rules*

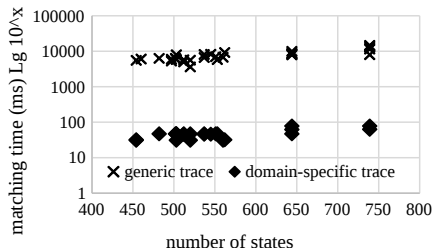
Evaluation results

Case study: fUML xDSML and models from [Maoz et al.'11]

*Complexity of
rules (RQ1)*

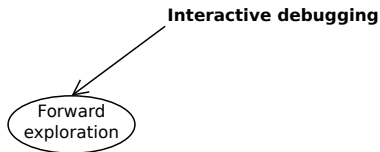
| Elements | Generic | Domain-specific |
|-----------------|---------|-----------------|
| Lines of code | 90 | 44 |
| Statements | 35 | 16 |
| Operations | 8 | 3 |
| Operation calls | 35 | 24 |
| Loops | 5 | 4 |
| Type checks | 4 | 1 |
| Conditionals | 11 | 3 |

*Rules execution
time (RQ2)*



Model omniscient debugging: terminology and scope

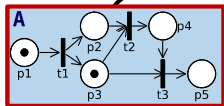
Model omniscient debugging: terminology and scope



Model omniscient debugging: terminology and scope

Interactive debugging

Forward
exploration

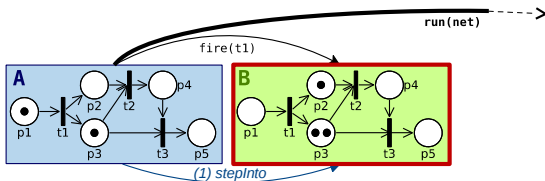


run(net)

Model omniscient debugging: terminology and scope

Interactive debugging

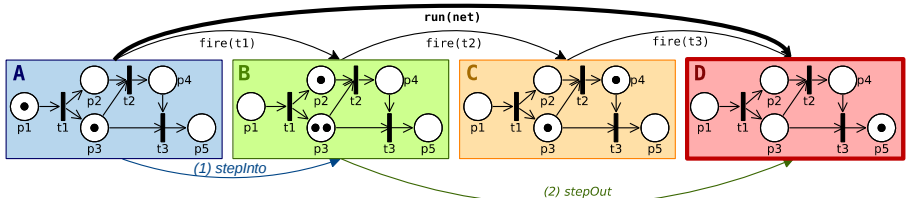
Forward
exploration



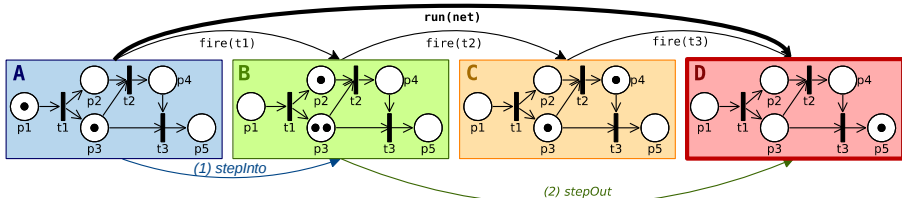
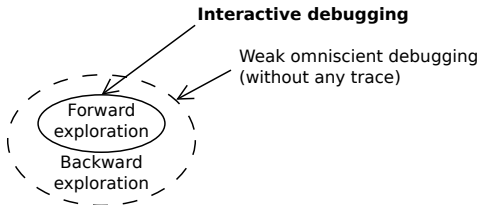
Model omniscient debugging: terminology and scope

Interactive debugging

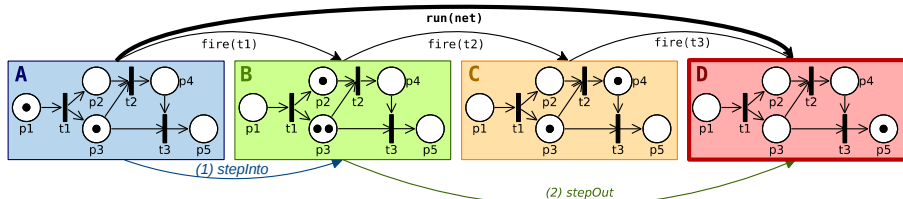
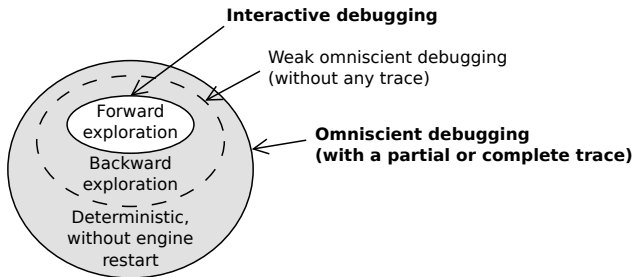
Forward
exploration



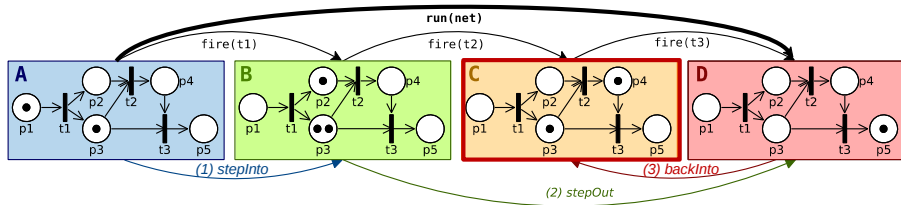
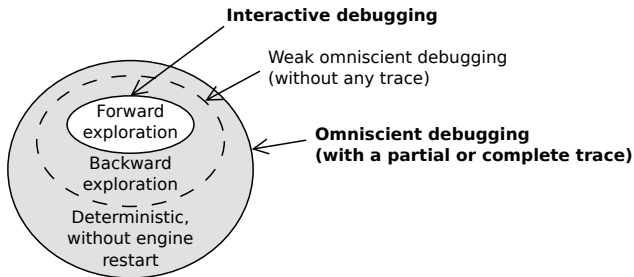
Model omniscient debugging: terminology and scope



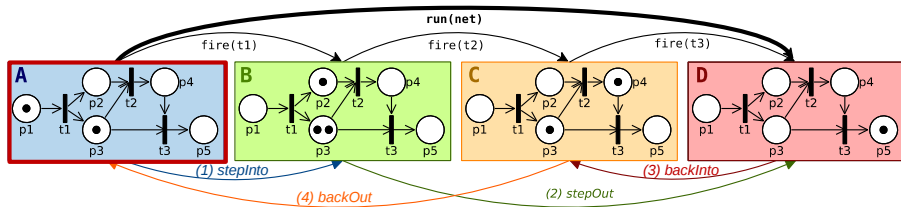
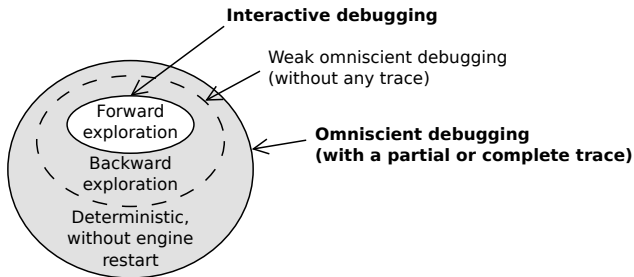
Model omniscient debugging: terminology and scope



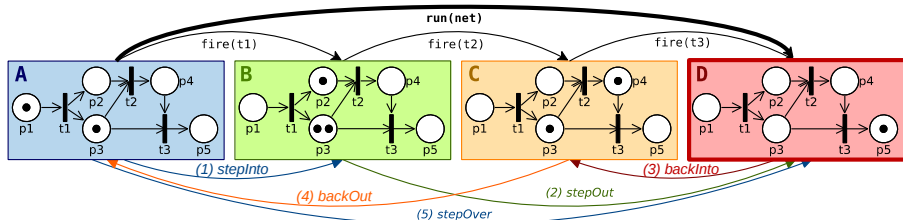
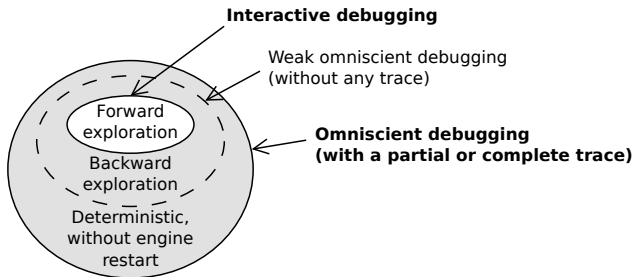
Model omniscient debugging: terminology and scope



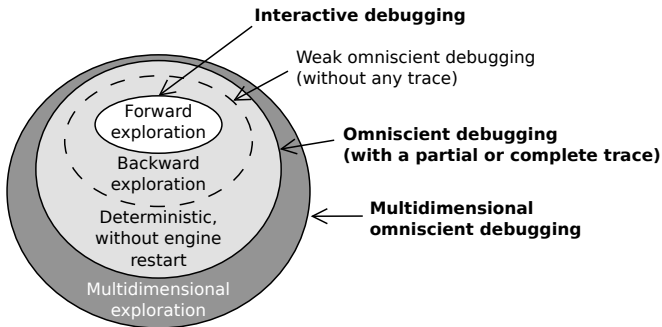
Model omniscient debugging: terminology and scope



Model omniscient debugging: terminology and scope



Model omniscient debugging: terminology and scope



Omniscient debugging for any xDSML?

- Generic omniscient debugging possible, based on steps
- Two key problems: **responsiveness** and **understandability** when debugging models from arbitrarily complex xDSML

Approach

- 1 Efficient generated domain-specific trace management facilities for *responsiveness*
 - generated trace metamodel (using our contribution)
 - generated trace manipulations (e.g. “jump back”)
 - *RQ2 and RQ3 can be evaluated*
- 2 Advanced generic multidimensional omniscient debugging services for *understandability*

Omniscient debugging for any xDSML?

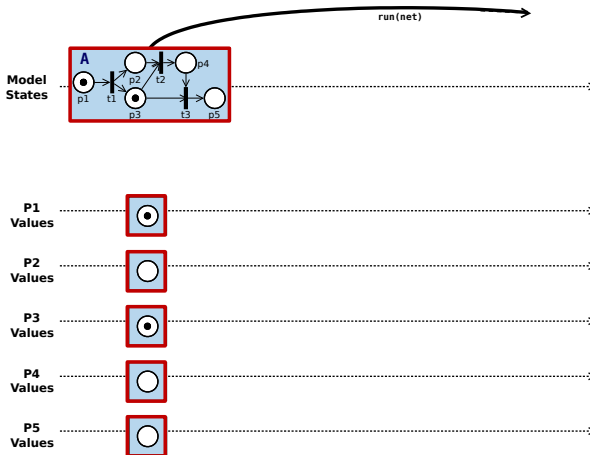
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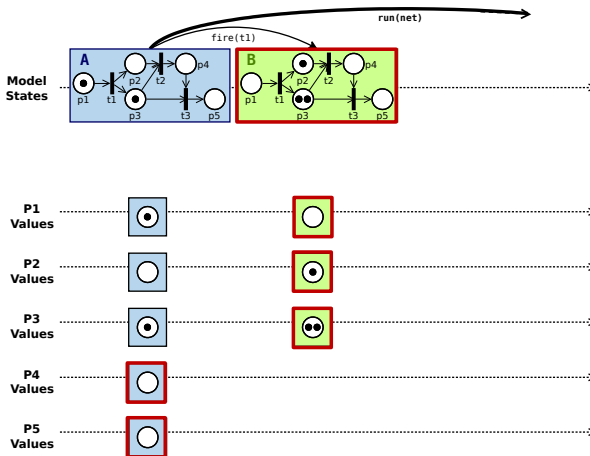
Advanced omniscient debugging

- **New advanced debugging services** to navigate according to the different **dimensions** of the model



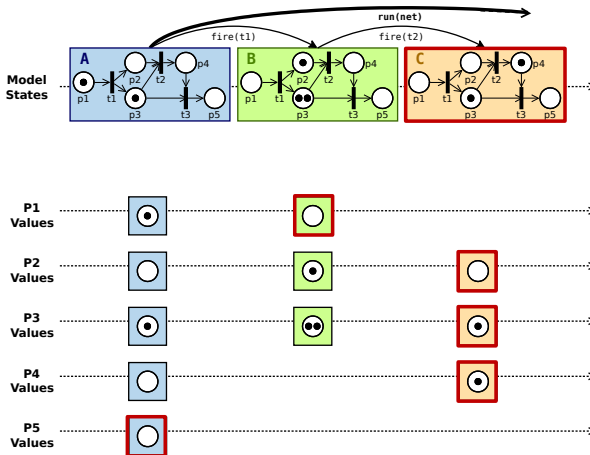
Advanced omniscient debugging

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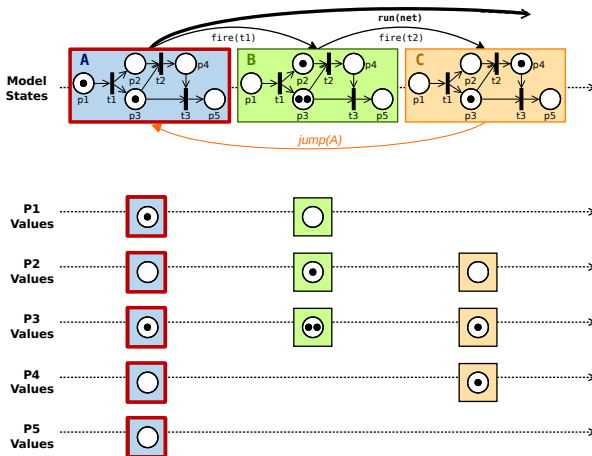
Advanced omniscient debugging

- **New advanced debugging services** to navigate according to the different **dimensions** of the model



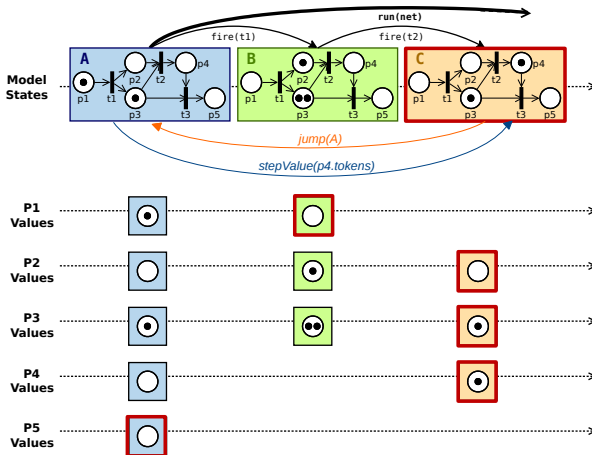
Advanced omniscient debugging

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Advanced omniscient debugging

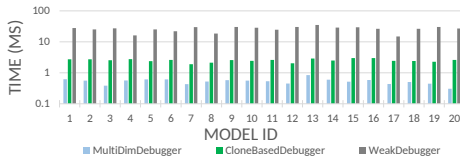
- **New advanced debugging services** to navigate according to the different **dimensions** of the model



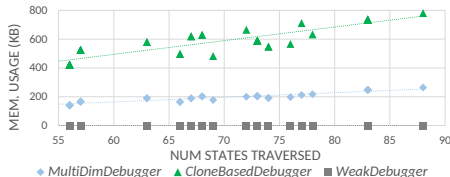
Evaluation of responsiveness

- **Same case study:** fUML models from [Maoz et al.'11]
- Comparison of our **advanced debugger** with two others:
weak (no trace) and **clone-based** (generic trace)

*“Jump back”
execution
time (RQ2)*



*Memory
consumption
(RQ3)*



Note regarding evaluation of time

RQ2 (time) was evaluated in two different ways:

- *Semantic differencing*: the **whole trace** is read and compared
- *Omniscient debugging*: a **single state** is read to jump back

Results are improved in both cases:

- Thanks to the **dimensions** when reading the whole trace
- Thanks to the **precise capture of the execution concepts**, when reading a single state

Outline

1 Introduction

2 Contribution

3 Evaluation

4 Conclusion

Conclusion

How to provide efficient execution trace management facilities for any xDSML?

- Contribution: **new generative approach** to manage execution traces of any xDSML
- Validation in a **realistic context** with applications to two existing V&V techniques using a real-world xDSML
- Results show that:
 - RQ1: **Reduces complexity** of domain-specific manipulations
 - RQ2: **Reduces processing time** by 75%
 - RQ3: **Reduces memory consumption** by 75%

Short-term perspectives

- **Customization of generated trace metamodels** to better fit expected trace manipulations, e.g. ignore unused parts of the metamodel
- **Represent execution branches** sharing a common prefix, within a single execution trace
- **Domain-specific property language** to define temporal properties over traces (cf. [Maoz et al.'14])
- **Domain-specific debugging services** using the underlying domain-specific trace metamodel (cf. [Chiş et al.'15])

Long-term perspectives

Execution traces as core modeling artifacts

- **“Live modeling”**: instant visualization of the impact of a change in a model regarding its behavior
- Versioning of the behavior of models: “trace of traces”

Generating *everything* for an xDSML

- Generating domain-specific mutation operators
- Generating a DSML to define test suites for an xDSML
- ...

Publications

International conferences:

■ **Model omniscient debugging:**

E. Bousse, J. Corley, B. Combemale, J. Gray, and B. Baudry. “Supporting Efficient and Advanced Omniscient Debugging for xDSMLs”. **SLE 2015**.

■ **Trace metamodel generation:**

E. Bousse, T. Mayerhofer, B. Combemale, and B. Baudry. “A Generative Approach to Define Rich Domain-Specific Trace Metamodels”. **ECMFA 2015**.

■ **Model cloning:**

E. Bousse, B. Combemale, and B. Baudry. “Scalable Armies of Model Clones through Data Sharing”. **MODELS 2014**.

+ 4 international workshops papers

Appendix

Outline

5 Appendix

■ Evaluation

Types of semantics (I)

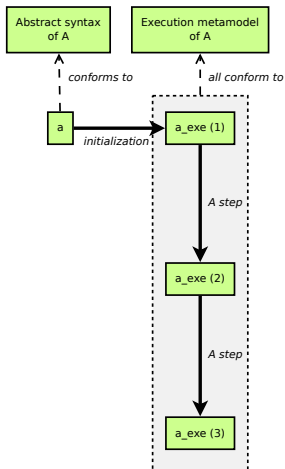


Figure: Operational semantics

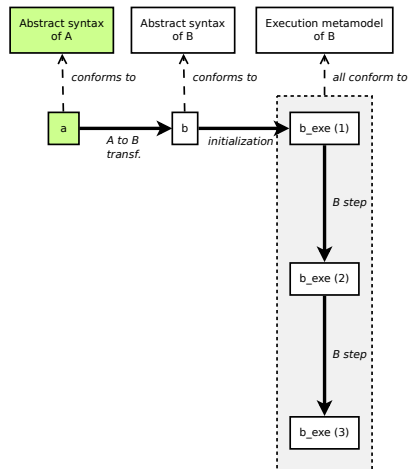


Figure: Translational semantics

Types of semantics (II)

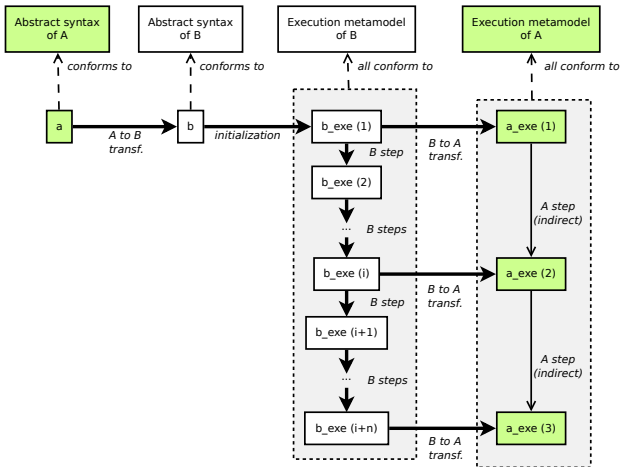


Figure: Translational semantics with back-annotation

Implicit steps

```
1  def void run() {
2    ... // code with model change (1)
3    someTransition.fire()
4    ... // code with model change (2)
5  }
```

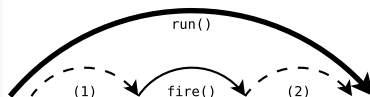


Figure: Implicit step illustration

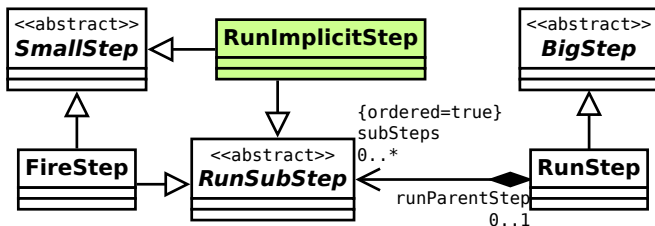
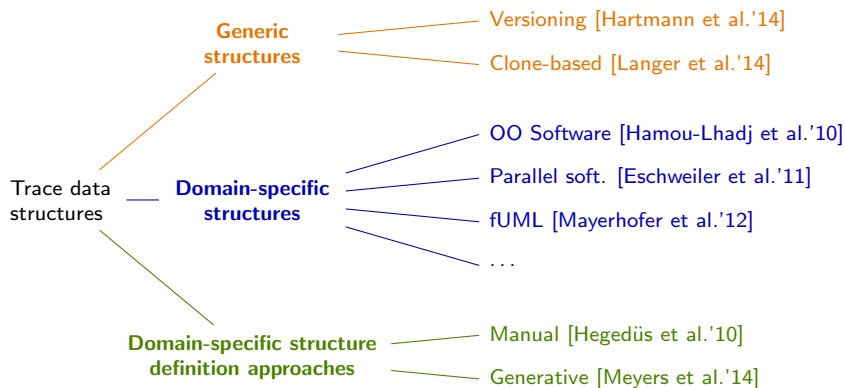


Figure: Petri net implicit step class

State of the art (summary)



State of the art (table)

| Name | Type | Ev./St. | Concerns |
|-----------------------------|-----------------|-------------------|----------------------|
| Open Trace Format 2 [56] | ASCII format | Both ^a | Parallel software |
| MPI Trace Format [3] | Metamodel | Events | HPC ^b |
| Compact Trace Format [77] | Metamodel | Events | Software |
| KPTrace [146] | ASCII format | Events | Operating systems |
| CUBE4 [67] | Binary format | Both ^c | Distributed software |
| UML Testing Profile [75] | Metamodel | Events | Software (UML) |
| fUML [113] | Metamodel | Events | fUML |
| Scenario-Based Traces [111] | ASCII format | Events | Sequence charts |
| Timesquare [46] | Metamodel | Events | Time, Timesquare |
| Gen. Sem. Diff. [99] | Metamodel | Both | Generic |
| KMF Versioning [81] | Other | States | Generic |
| Pablo SDDF [4] | ASCII/Binary | Both | Self-defining |
| Pajé [139] | ASCII format | Both | Self-defining |
| SOC-Trace project [124] | Metamodel | Events | Self-defining |
| Common Trace Format [47] | ASCII/Binary | Events | Self-defining |
| TOPCASED [32, 41] | Approach | Events | Domain-specific |
| Hegedüs et al. [83] | Approach | Both | Domain-specific |
| Promobox [116] | Generative App. | Both | Domain-specific |
| Filmstrip models [69, 85] | Generative App. | Both | Domain-specific |

Figure: Execution trace data structures

Screenshot GEMOC debugger (during execution)

The screenshot displays the GEMOC debugger interface with the following components:

- Debug Console:** Shows the execution stack with the following entries:
 - Run SEQUENTIAL [Gemoc Sequential Executable Model]
 - Gemoc debug target
 - Model debugging
 - OpaqueAction (MSE_OpaqueActionImpl_sendOffers) [activitydiagram]
 - OpaqueAction (MSE_OpaqueActionImpl_execute) [activitydiagram]
 - Activity (MSE_ActivityImpl_execute) [activitydiagram.impl.Activity]
 - Activity
- Variables Panel:**

| Name | Value |
|--|-------|
| InitialNode_O_heldTokens | [] |
| JoinNode_O_heldTokens | [] |
| MergeNode_O_heldTokens | [] |
| OpaqueAction_add_to_website_heldTokens | [] |
| OpaqueAction_assign_to_project_external_heldTokens | [] |
| OpaqueAction_assign_to_project_internal_heldTokens | [] |
| OpaqueAction_authorize_payment_heldTokens | [] |
- Multidimensional Timeline:** A vertical timeline showing the execution of various actions over time, with colored dots representing different states or events.
- Activity Diagram:** A UML Activity Diagram showing the flow of execution. The diagram includes nodes for "assign to project internal heldTokens", "add to website heldTokens", "get website pack heldTokens", and "register heldTokens". The diagram is currently in a state where the "assign to project internal heldTokens" node is active.
- Gemoc Engines Status:** A table showing the status of the engines:

| Engine | Status |
|---------------|---------|
| h(rev).xml 14 | Running |
| h(rev).xml 1 | Stopped |

Screenshot GEMOC debugger (after jump back)

The screenshot displays the GEMOC debugger interface with the following components:

- Debug Console:** Shows the execution flow of the 'Run SEQUENTIAL' target. The current step is 'Activity (MSE_ActivityImpl.execute) [activitydiagram.impl.Activity]'.
- Variables:** A table listing variables and their values:

| Name | Value |
|--|-------|
| InitialNode_O_heldTokens | [] |
| JoinNode_O_heldTokens | [] |
| MergeNode_O_heldTokens | [] |
| OpaqueAction_add_to_website_heldTokens | [] |
| OpaqueAction_assign_to_project_external_heldTokens | [] |
| OpaqueAction_assign_to_project_internal_heldTokens | [] |
| OpaqueAction_authorize_payment_heldTokens | [] |
- Multidimensional Timeline:** A visualization of the execution timeline with colored dots representing different states or events across 21 time steps (0 to 20).
- Activity Diagram:** A flowchart showing the execution of the 'hireV1' activity. The flow starts with 'tokenOfferCount=0', goes through 'assign to project internal heldTokens =0', 'add to website heldTokens =0', 'get welcome pack heldTokens =0', and ends with 'register heldTokens =1'.
- Gemc Engines Status:** A list of engines with their status:
 - hireV1.amd 14
 - hireV1.amx 1

Session saving

fUML case study

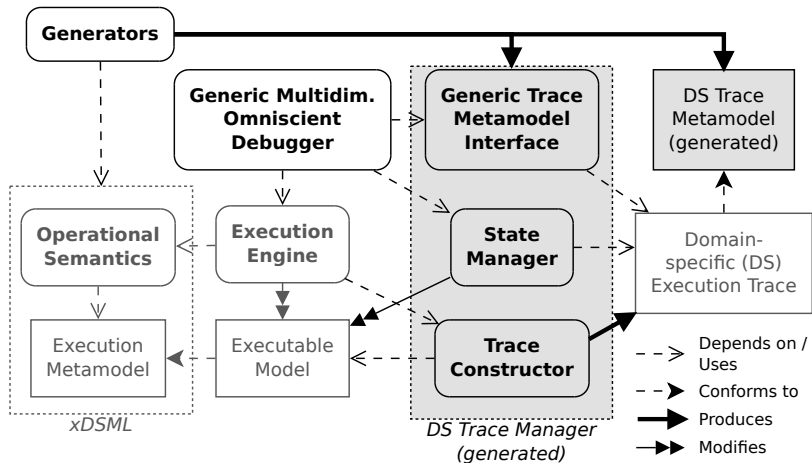
fUML xDSML

- subset of UML
- 57 classes

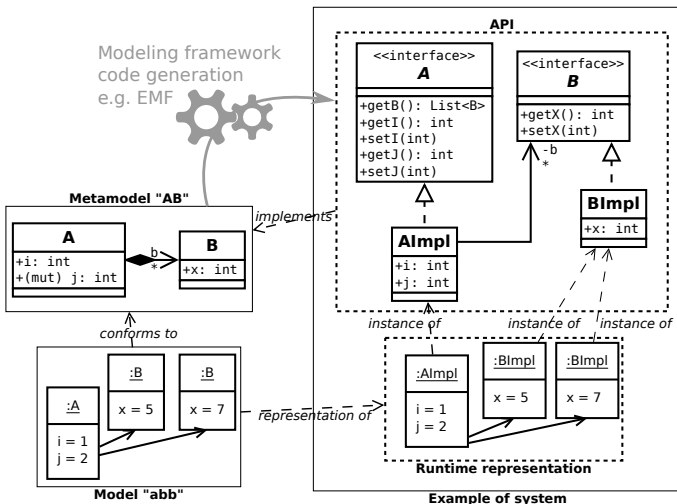
fUML Models

- Case study of Maoz et al. to evaluate a semantic differencing operator
- Models drawn from industrial sources
- Multiple sequences of models, each sequence with a change
- 40 models considered, sizes range from 36 to 51 objects
- Source: <http://www.se-rwth.de/materials/semdiff/>

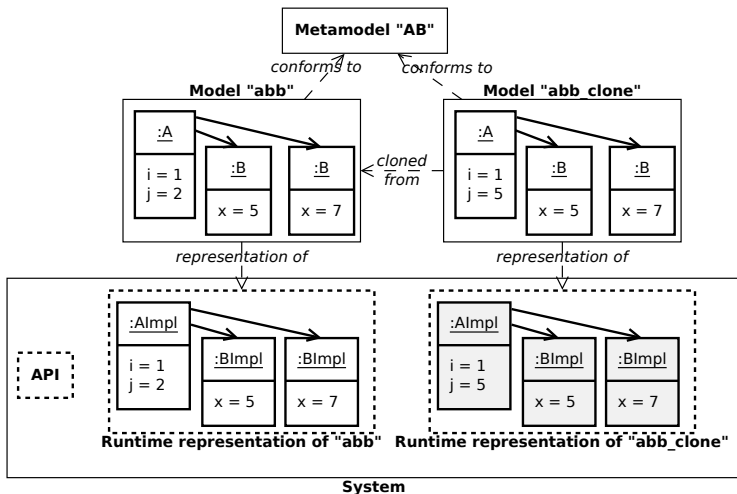
Omniscient debugger architecture



Example: a metamodel, a model, and runtime counterparts



Example: a model clone obtained using *deep cloning*



Data sharing: existing approaches

Idea for Req #1: considering that only a subset of a model changes during its lifecycle, **avoid data redundancy among clones**

Dynamically: copy-on-write (aka lazy copy)

Create virtual copies, and create real copies on write accesses.

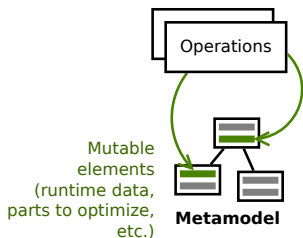
- either using a specific API/entry-point, **breaks Req#3**
- or in a transparent way, but managing consistency depends on the implementation language (e.g. Java is pass-by-value)
- Copies are done during manipulations, **may break Req#2**

Statically: flyweight design pattern

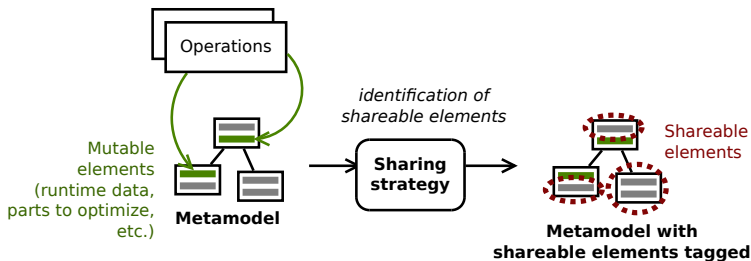
Objects are designed to be used in multiple contexts.

- Requires the passing the extrinsic state (ie the mutable part) of the object as a parameter, for all its operations, **breaks Req #3**

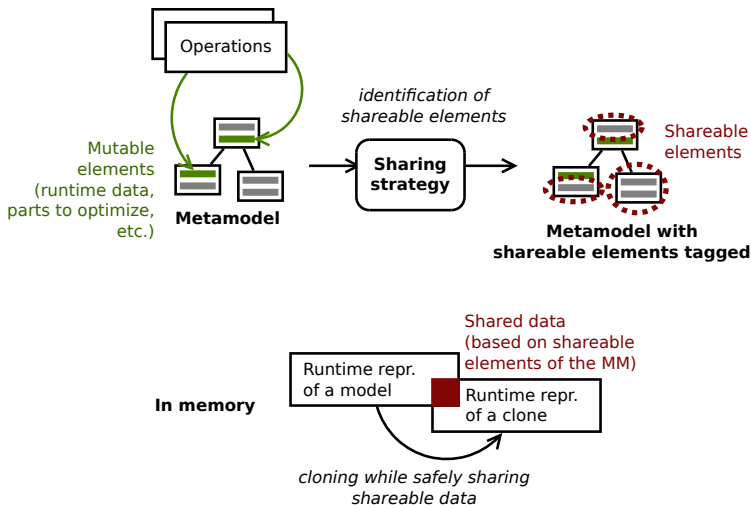
Approach: *static* identification of safely shareable parts



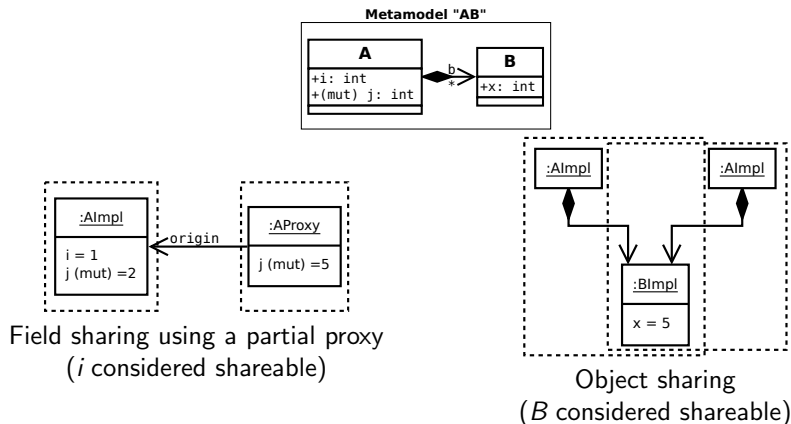
Approach: *static* identification of safely shareable parts



Approach: *static* identification of safely shareable parts



Shareable elements and sharing mechanisms



- Req #2 (efficiency) is not satisfied when sharing fields
- Req #4 (reflective layer) is not satisfied when sharing objects, since it breaks MOF container() operation

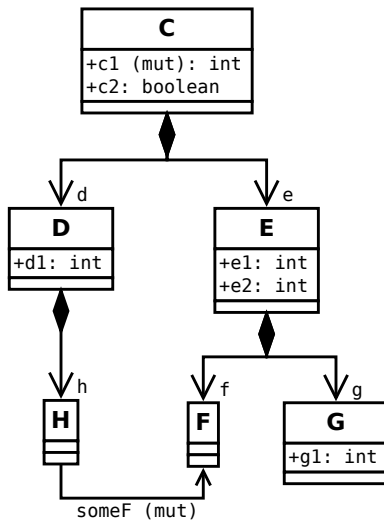
Data sharing strategies

For design-time, **3 sharing strategies with trade-offs** between memory use and satisfaction of Req #2 and Req #4

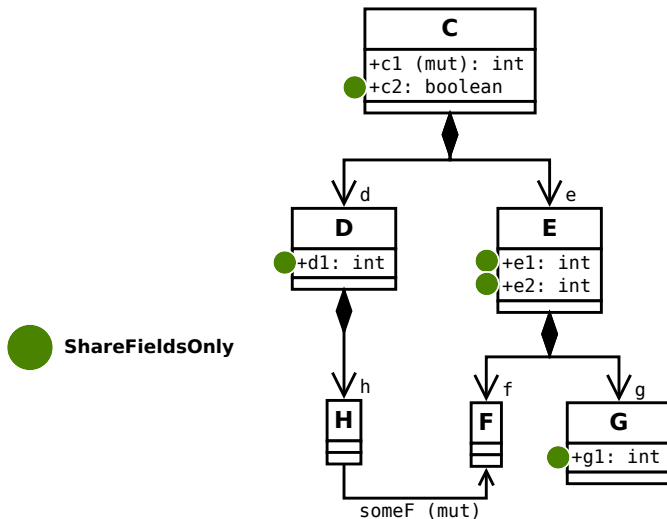
| | |
|------------------------|--|
| DeepCloning | Nothing is shareable. |
| ShareFieldsOnly | Only immutable attributes are shareable. |
| ShareObjOnly | Classes that can't (transitively) access mutable parts are shareable. |
| ShareAll | Shareable elements are immutable attributes, classes whose properties are all shareable, and immutable references pointing to shareable classes. |

For runtime, **1 generic algorithm** parameterized by a sharing strategy → *3 data sharing cloning operators*.

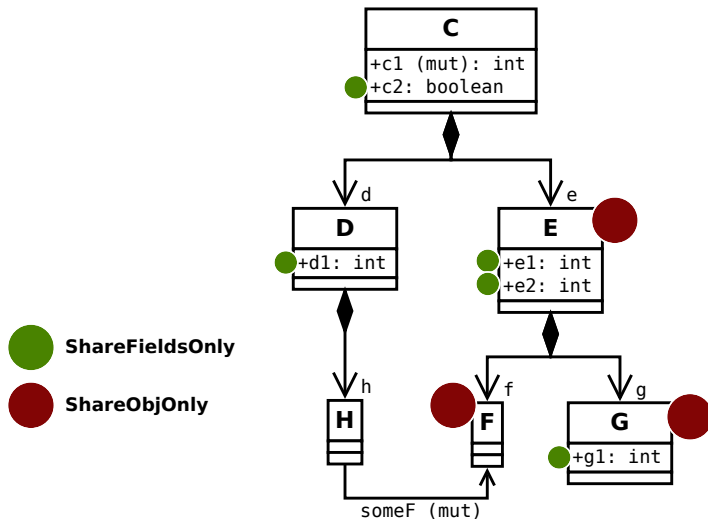
Data sharing strategies: example



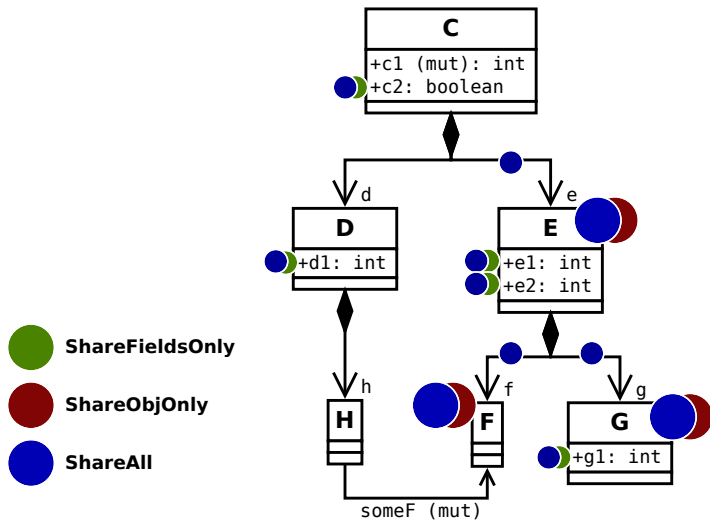
Data sharing strategies: example



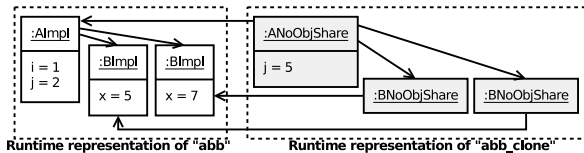
Data sharing strategies: example



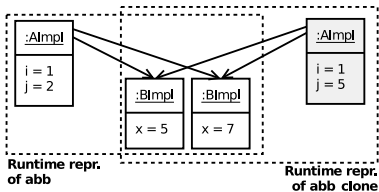
Data sharing strategies: example



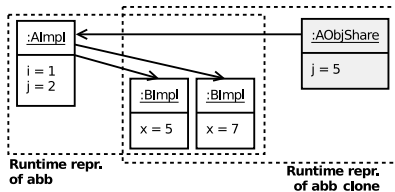
Resulting cloning operators



(a) *ShareFieldsOnly*



(b) *ShareObjOnly*



(c) *ShareAll*

Research questions

RQ#1

Do the new operators reduce the memory footprint of clones, compared to deep cloning?

RQ#2

Can a clone be manip. with the same efficiency as the original ?

RQ#3

Can a clone be manip. using the same generated API ?

RQ#4

Can a clone be manip. using the reflective layer (e.g. as stated in the MOF Reflection package)?

Evaluation – RQ#1 and RQ#2

Experiment

- **data set:** 100 randomly generated metamodels
- **memory measures:** gain as compared to *deep cloning*, after cloning the model 1000 times
- **performance measures:** loss of time as compared to the original model, when navigating 10 000 times through each object of the model while accessing all properties

Results

- **memory:** the more shareable parts, the more memory gain
- **performance:** worst median overhead is 9,5% when manipulating clones with fields sharing

Evaluation – results overview

RQ1: memory

RQ2: efficiency

RQ3: same API

RQ4: reflective layer

| | RQ1 | RQ2 | RQ3 | RQ4 |
|-----------------|-----|-----|-----|-----|
| DeepCloning | ✗ | ✓ | ✓ | ✓ |
| ShareFieldsOnly | + | -- | ✓ | ✓ |
| ShareObjOnly | ++ | ✓ | ✓ | ✗ |
| ShareAll | +++ | - | ✓ | ✗ |