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Tableau Method and NEXPTIME-Completeness of DEL-Sequents

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Abstract

Dynamic Epistemic Logic (DEL) deals with the representation of situations in a multi-agent and dynamic setting. It can express in a uniform way statements about:

- (i) what is true about an initial situation
- (ii) what is true about an event occurring in this situation
- (iii) what is true about the resulting situation after the event has occurred.

After proving that what we can infer about (ii) given (i) and (iii) and what we can infer about (i) given (ii) and (iii) are both reducible to what we can infer about (iii) given (i) and (ii), we provide a tableau method deciding whether such an inference is valid. We implement it in LOTREC scheme and show that this decision problem is NEXPTIME-complete. This contributes to the proof theory and the study of the computational complexity of DEL which have rather been neglected so far.

Keywords: Dynamic epistemic logic, tableau method, computational complexity

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1 Introduction

Dynamic Epistemic Logic (DEL) deals with the logical study in a multi-agent setting of knowledge and belief change, and more generally of information change [van Ditmarsch et al., 2007]. To account for these logical dynamics, the core idea of DEL is to split the task of representing the agents' beliefs into three parts: first, one represents their beliefs about an initial situation; second, one represents their beliefs about an event taking place in this situation; third, one represents the way the agents update their beliefs about the situation after (or during) the occurrence of the event. Consequently, one can express uniformly within the logical framework of DEL statements about:

- (i) what is true about an initial situation,
- (ii) what is true about an event occurring in this situation,
- (iii) what is true about the resulting situation after the event has occurred.

From a logical point of view, this trichotomy begs the following three questions. Given (i) and (ii), what can we infer about (ii)? Given (i) and (iii), what can we infer about (ii)? Providing formal tools that can be used to answer these questions is certainly of interest for human or artificial agents. Indeed, they could not only use them to plan their actions to achieve a given epistemic goal (the first and second questions actually correspond respectively to the problems of *deductive* and *abductive* planning in the situation calculus), but they could also use them to explain and determine a posteriori the causes that lead to a given situation. Nevertheless, to be applicable, these formal tools should lead to implementable decision procedures. To this aim, we provide a tableau method giving an answer to the first question. This is sufficient since we prove that the two other questions are in fact both reducible formally to the first one.

The paper is organized as follows. In Section 2, we define our three DELsequents corresponding to our three questions above, and we show that these DEL-sequents are interdefinable. In Section 3, we provide two terminating, sound and complete tableau methods. This leads us to define in Section 4 an algorithm in NEXPTIME, which we prove to be optimal by reducing a tiling problem known to be NEXPTIME-complete to our decision problem. A link to an implementation of our tableau method in LOTREC scheme is provided in Section 5. Finally, we conclude in Section 6 by a discussion of related works.

2 Dynamic Epistemic Logic: DEL-sequents

2.1 Representation of the initial situation: \mathcal{L} -model

In the rest of this paper, Φ is a countable set of propositional letters (possibly infinite) called *atomic facts* which describe static situations, and *Agt* is a finite

set of agents. A \mathcal{L} -model is a tuple $\mathcal{M} = (W, R, V)$ where:

- W is a non-empty set of possible worlds,
- $R: Agt \to 2^{W \times W}$ is a function assigning to each agent $j \in Agt$ an accessibility relation on W,
- $V: \Phi \to 2^W$ is a function assigning to each propositional letter of Φ a subset of W. The function V is called a valuation.

We write $w \in \mathcal{M}$ for $w \in W$, and (\mathcal{M}, w) is called a pointed \mathcal{L} -model (w often represents the actual world). If $w, v \in W$, we write wR_jv for R(j)(w, v) and $R_j(w) = \{v \in W \mid wR_jv\}$. Intuitively, wR_jv means that in world w agent j considers that world v might correspond to the actual world. Then, we define the following epistemic language \mathcal{L} that can be used to describe and state properties of \mathcal{L} -models:

$$\mathcal{L}:\phi ::= p \mid \neg\phi \mid \phi \land \phi \mid B_j\phi$$

where p ranges over Φ and j over Agt. We define $\phi \lor \psi =^{\text{def}} \neg (\neg \phi \land \neg \psi)$ and $\langle B_j \rangle \phi =^{\text{def}} \neg B_j \neg \phi$. The symbol \top is an abbreviation for $p \lor \neg p$ for a chosen $p \in \Phi$. Let \mathcal{M} be a \mathcal{L} -model, $w \in \mathcal{M}$ and $\phi \in \mathcal{L}$. $\mathcal{M}, w \models \phi$ is defined inductively as follows:

$$\mathcal{M}, w \models p \quad \text{iff } w \in V(p) \qquad \mathcal{M}, w \models \phi \land \psi \text{ iff } \mathcal{M}, w \models \phi \text{ and } \mathcal{M}, w \models \psi \\ \mathcal{M}, w \models \neg \phi \text{ iff not } \mathcal{M}, w \models \phi \quad \mathcal{M}, w \models B_j \phi \quad \text{iff for all } v \in R_j(w), \, \mathcal{M}, v \models \phi$$

The formula $B_j \phi$ reads as "agent j believes ϕ ". Its truth conditions are defined in such a way that agent j believes ϕ holds in a possible world when ϕ holds in all the worlds agent j considers possible.

2.2 Representation of the event: \mathcal{L}' -model

The propositional letters p'_{ψ} describing events are called *atomic events* and range over $\Phi' = \{p'_{\psi} \mid \psi \text{ ranges over } \mathcal{L}\}$. The reading of p'_{ψ} is "an event of precondition ψ is occurring". A \mathcal{L}' -model is a tuple $\mathcal{M}' = (W', R', V')$ where:

- W' is a non-empty set of possible events,
- $R': Agt \to 2^{W' \times W'}$ is a function assigning to each agent $j \in Agt$ an accessibility relation on W',
- $V': \Phi' \to 2^{W'}$ is a function assigning to each propositionnal letter of Φ' a subset of W' such that for all $w' \in W'$, there is at most one p'_{ψ} such that $w' \in V(p'_{\psi})$ (Exclusivity).

We write $w' \in \mathcal{M}'$ for $w' \in W'$, and (\mathcal{M}', w') is called a *pointed* \mathcal{L}' -model (w' often represents the actual event). If $w', v' \in W'$, we write $w'R'_jv'$ for R'(j)(w', v') and $R'_j(w') = \{v' \in W' \mid w'R'_jv'\}$. Intuitively, $v' \in R_j(w')$ means that while the possible event represented by w' is occurring, agent j considers possible that the possible event represented by v' is actually occurring. Our

definition of a \mathcal{L}' -model is equivalent to the definition of an action signature in the logical framework of [Baltag and Moss, 2004].⁵ Just as we defined a language \mathcal{L} for \mathcal{L} -models, we also define a language \mathcal{L}' for \mathcal{L}' -models:

$$\mathcal{L}':\phi' \quad ::= \quad p'_{\psi} \quad | \quad \neg \phi' \quad | \quad \phi' \land \phi' \quad | \quad B_j \phi'$$

where p'_{ψ} ranges over $\Phi' = \{p'_{\psi} \mid \psi \in \mathcal{L}\}$ and j over Agt. In fact, \mathcal{L}' was already introduced in [Baltag et al., 1999]. In the sequel, formulas of \mathcal{L}' are always indexed by the quotation mark ', unlike formulas of \mathcal{L} . The truth conditions of the language \mathcal{L}' are identical to the ones of the language \mathcal{L} . Let \mathcal{M}' be a \mathcal{L}' -model, $w' \in \mathcal{M}'$ and $\phi' \in \mathcal{L}'$. $\mathcal{M}', w' \models \phi'$ is defined inductively as follows:

$$\begin{aligned} \mathcal{M}', w' &\models p'_{\psi} & \text{iff } w' \in V'(p'_{\psi}) \\ \mathcal{M}', w' &\models \neg \phi' & \text{iff } \text{not } \mathcal{M}', w' \models \phi' \\ \mathcal{M}', w' &\models \phi' \land \psi' & \text{iff } \mathcal{M}', w' \models \phi' \text{ and } \mathcal{M}', w' \models \psi' \\ \mathcal{M}', w' &\models B_{j} \phi' & \text{iff } \text{ for all } v' \in R_{j}(w'), \ \mathcal{M}', v' \models \phi' \end{aligned}$$

2.3 Update of the initial situation by the event: product update

A \mathcal{L}' -model induces the definition of a precondition function. The precondition $\operatorname{Pre}(w')$ of a possible event w' corresponds to the property that should be true at a world w of a \mathcal{L} -model so that the possible event w' can 'physically' occur in this world w. The precondition function Pre : $W' \to \mathcal{L}$ induced by the \mathcal{L}' -model $\mathcal{M}' = (W', R', V')$ is defined as follows: $\operatorname{Pre}(w') = \psi$ if there is p'_{ψ} such that $\mathcal{M}', w' \models p'_{\psi}$; $\operatorname{Pre}(w') = \top$ otherwise.

We then redefine equivalently in our setting the BMS product update of [Baltag et al., 1998] as follows. Let $(\mathcal{M}, w) = (W, R, V, w)$ be a pointed \mathcal{L} model and let $(\mathcal{M}', w') = (W', R', V', w')$ be a pointed \mathcal{L}' -model such that $\mathcal{M}, w \models \operatorname{Pre}(w')$. The product update of (\mathcal{M}, w) and (\mathcal{M}', w') is the pointed \mathcal{L} -model $(\mathcal{M} \otimes \mathcal{M}', (w, w')) = (W^{\otimes}, R^{\otimes}, V^{\otimes}, (w, w'))$ defined as follows:

- $W^{\otimes} = \{(v, v') \in W \times W' \mid \mathcal{M}, v \models \operatorname{Pre}(v')\},\$
- $R_i^{\otimes}(v, v') = \{(u, u') \in W^{\otimes} \mid u \in R_j(v) \text{ and } u' \in R'_i(v')\},\$
- $V^{\otimes}(p) = \{(v, v') \in W^{\otimes} \mid \mathcal{M}, v \models p\}.$

This product update yields a new \mathcal{L} -model $(\mathcal{M}, w) \otimes (\mathcal{M}', w')$ representing how the new situation which was previously represented by (\mathcal{M}, w) is perceived by the agents after the occurrence of the event represented by (\mathcal{M}', w') .

2.4 Definitions of our DEL-sequents

Let $\phi, \phi'' \in \mathcal{L}$ and $\phi' \in \mathcal{L}'$. We define the logical consequence relations $\phi, \phi' \models \phi'', \phi, \phi'' \models \phi'$ and $\phi', \phi'' \models \phi$ as follows. The second and third re-

⁵ If $\Sigma = (W', R', (w'_1, \dots, w'_n))$ is an action signature and $\phi_1, \dots, \phi_n \in \mathcal{L}$, then the \mathcal{L}' model associated to $(\Sigma, \phi_1, \dots, \phi_n)$ is the tuple $\mathcal{M}' = (W', R', V')$ where $V'(p'_{\psi}) = \{w'_i\}$ if $\psi = \phi_i, V'(p'_{\psi}) = \{w'_1, \dots, w'_n\}$ if $\psi = \top$, and $V'(p'_{\psi}) = \emptyset$ otherwise.

lations can be used for epistemic planning and goal regression respectively.

 $\phi, \phi' \models \phi''$ iff for all pointed \mathcal{L} -model (\mathcal{M}, w) , and \mathcal{L}' -model (\mathcal{M}', w') such that $\mathcal{M}, w \models \operatorname{Pre}(w'), \mathcal{M}, w \models \phi$ and $\mathcal{M}', w' \models \phi'$, it holds that $(\mathcal{M}, w) \otimes (\mathcal{M}', w') \models \phi''$

 $\phi, \phi'' \models \phi'$ iff for all pointed \mathcal{L} -models (\mathcal{M}, w) , and (\mathcal{M}'', w'') such that $\mathcal{M}, w \models \phi$ and $\mathcal{M}'', w'' \models \phi''$, if (\mathcal{M}', w') is a pointed \mathcal{L}' -model such that $\mathcal{M}, w \models \operatorname{Pre}(w')$ and $(\mathcal{M}, w) \otimes (\mathcal{M}', w')$ is bisimilar to (\mathcal{M}'', w'') , then $\mathcal{M}', w' \models \phi'$ $\phi', \phi'' \models \phi$ iff for all pointed \mathcal{L}' -model (\mathcal{M}', w') , and \mathcal{L} -model (\mathcal{M}'', w'') such that $\mathcal{M}', w' \models \phi'$ and $\mathcal{M}'', w'' \models \phi''$,

if (\mathcal{M}, w) is a pointed \mathcal{L} -model such that $\mathcal{M}, w \models \operatorname{Pre}(w')$ and $(\mathcal{M}, w) \otimes (\mathcal{M}', w')$ is bisimilar to (\mathcal{M}'', w'') , then $\mathcal{M}, w \models \phi$

In fact, as the following proposition shows, our three DEL-sequent are interdefinable. Therefore, in the rest of this paper, we will focus only on providing a tableau method for the DEL-sequent $\phi, \phi' \models \phi''$. Tableau methods and complexity results for the other DEL-sequents can easily be adapted from the ones provided for this DEL-sequent.

3 Tableau method

We consider three formulae, $\phi \in \mathcal{L}$, $\phi' \in \mathcal{L}'$ and $\phi'' \in \mathcal{L}$, and we want to address the problem of deciding whether $\phi, \phi' \models \phi''$ holds. To do so we equivalently decide whether there exist a pointed \mathcal{L} -model (\mathcal{M}, w) and a pointed \mathcal{L}' -model (\mathcal{M}', w') such that $\mathcal{M}, w \models \operatorname{Pre}(w'), \mathcal{M}, w \models \phi, \mathcal{M}', w' \models \phi'$ and $\mathcal{M} \otimes \mathcal{M}', (w, w') \models \neg \phi''$. We call this dual problem the *satisfiability problem*.

3.1 Tableau method description

The formulas that appear in our tableau method and that we call *tableau* formulas are of the following kind:

- $(l \ \phi)$: l is a label l_w (resp. $l_{w'}$) that represents a world of the model \mathcal{M} (resp. \mathcal{M}') being constructed, and ϕ is a formula of \mathcal{L} (resp. \mathcal{L}') that should be true at \mathcal{M}, w (resp. \mathcal{M}', w').
- $(l_w \ l_{w'} \ \phi'')$: l_w represents a world w of \mathcal{M} , $l_{w'}$ a world w' of \mathcal{M}' , and ϕ'' is a formula of \mathcal{L} that should be true at $\mathcal{M} \otimes \mathcal{M}', (w, w')$. Moreover, $(l_w \ l_{w'} \ 0)$ means that (w, w') is not in $\mathcal{M} \otimes \mathcal{M}'$.
- $(R \ l \ l')$ (resp. $(R' \ l \ l')$): R (resp. R') is some R_j (resp. R'_j), l and l' represent two worlds w and u (resp. w' and u') such that wR_ju (resp.

 $w'R_ju').$

• \perp : Denotes an inconsistency.

A tableau rule is represented by a numerator \mathcal{N} above a line and a finite list of denominators $\mathcal{D}_1, \ldots, \mathcal{D}_k$ below this line, separated by vertical bars:

$$rac{\mathcal{N}}{\mathcal{D}_1 \mid \ldots \mid \mathcal{D}_k}$$

The numerator and the denominators are finite sets of tableau formulas.

A tableau for a triple (ϕ, ϕ', ϕ'') of formulas is a finite tree with a set of tableau formulas at each node, and whose root is:

$$\Gamma_0 = \{ (l_w \phi), (l_{w'} \phi'), (l_w l_{w'} \phi'') \}$$

A rule with numerator \mathcal{N} is *applicable* to a node carrying a set Γ if Γ contains an instance of \mathcal{N} . If no rule is applicable, Γ is said to be *saturated*. We call a node *n* an *end node* if the set of formulas Γ it carries is saturated, or if $\bot \in \Gamma$. The tableau is extended the following way:

- (i) Choose a leaf node n carrying Γ where n is not an end node, and choose a rule ρ applicable to n.
- (ii) (a) If ρ has only one denominator, add the appropriate instanciation to Γ .
 - (b) If ρ has k denominators with k > 1, create k successor nodes for n, where each successor i carries the union of Γ with an appropriate instanciation of denominator \mathcal{D}_i .

A branch in a tableau is a path from the root to an end node. A branch is *closed* if its end node contains \perp , otherwise it is *open*. A tableau is *closed* if all its branches are closed, otherwise it is *open*. A triple (ϕ, ϕ', ϕ'') is said to be *consistent* if no tableau for (ϕ, ϕ', ϕ'') is closed, and a triple (ϕ, ϕ', ϕ'') is a *theorem*, which we write $\phi, \phi' \models \phi''$, if there is a closed tableau for $(\phi, \phi', \neg \phi'')$.

3.2 Tableau rules

Common rules for \mathcal{M} , \mathcal{M}' and \mathcal{M}'' (*l* is either l_w , $l_{w'}$ or l_w $l_{w'}$):

$$\frac{(l \phi \land \psi)}{(l \phi) (l \psi)} \land \qquad \frac{(l \neg (\phi \land \psi))}{(l \neg \phi) \mid (l \neg \psi)} \neg \land \qquad \frac{(l \neg \neg \phi)}{(l \phi)} \neg \qquad \frac{(l p)(l \neg p)}{\bot} \bot$$

where $p \in \Phi$

Specific rules for \mathcal{M} and \mathcal{M}' (*l* is either l_w or $l_{w'}$):

$$\frac{(l \langle B_j \rangle \phi)}{(R \ l \ l')(l' \ \phi)} \langle B_j \rangle \qquad \frac{(l \ B_j \phi)(R \ l \ l')}{(l' \ \phi)} \ B_j \qquad \frac{(l_{w'} \ p'_{\phi})(l_{w'} \ p'_{\psi})}{\perp} \text{ Excl}$$

where $\phi \neq \psi$

Specific rules for
$$\mathcal{M}''$$
:

$$\frac{(l_w \ l_{w'} \ \langle B_j \rangle \phi)}{(R \ l_w \ l_u)(R' \ l_{w'} \ l_{u'})(l_u \ l_{u'} \ \phi)} \ \langle B_j \rangle_{\otimes} \quad \frac{(l_w \ l_{w'} \ B_j \phi)(R \ l_w \ l_u)(R' \ l_{w'} \ l_{u'})}{(l_u \ l_{u'} \ \phi)|(l_u \ l_{u'} \ 0)} \ B_{j_{\otimes}}$$

$$\frac{(l_w \ l_{w'} \ p)}{(l_w \ p)} \leftarrow_1 \qquad \frac{(l_w \ l_{w'} \ \neg p)}{(l_w \ \neg p)} \leftarrow_2$$

$$\frac{(l_w \ l_{w'} \ 0)(l_{w'} \ p'_{\psi})}{(l_w \ \neg \psi)} \ \operatorname{Pre}_1 \qquad \frac{(l_w \ l_{w'} \ \phi)(l_{w'} \ p'_{\psi})}{(l_w \ \psi)} \ \operatorname{Pre}_2$$
where $\phi \neq 0$

Remark 3.1 Another sound and complete tableau method can be obtained by replacing the rule Pre_1 above by the following rule:

$$\frac{(l_w \ l_{w'} \ 0)}{(l_{w'} \ p'_{\psi_1}) \ (l_w \ \neg \psi_1) \ | \ \dots \ | \ (l_{w'} \ p'_{\psi_n}) \ (l_w \ \neg \psi_n)} \ \operatorname{Pre}'_1$$

where $p'_{\psi_1}, \ldots, p'_{\psi_n}$ is the set of propositional letters appearing in ϕ' at the root of the tableau. This second tableau method is more modular, in the sense that if we remove Rule (Excl), then the resulting tableau method is still sound and complete with respect to the semantics where we do not impose the (Exclusivity) condition on \mathcal{L}' -models. Note also that the \mathcal{L} -model and \mathcal{L}' -model obtained from an open branch with this tableau method do not need to be adapted to fulfill the satisfiability problem, as in the proof of Proposition 3.3 with the first tableau method.

3.3 Tableau method soundness and completeness

Proposition 3.2 (Tableau method soundness) For all $\phi, \phi'' \in \mathcal{L}$, for all $\phi' \in \mathcal{L}', \phi, \phi' \models \phi''$ implies $\phi, \phi' \models \phi''$

Proof. Instead of proving that $\phi, \phi' \vdash \phi''$ implies $\phi, \phi' \models \phi''$, we equivalently prove that $\phi, \phi' \nvDash \phi''$ implies $\phi, \phi' \nvDash \phi''$. Suppose there exist a pointed \mathcal{L} -model (\mathcal{M}, w) , a \mathcal{L}' -model (\mathcal{M}', w') such that $\mathcal{M}, w \models \phi, \mathcal{M}', w' \models \phi', \mathcal{M}, w \models$ Pre(w') and $\mathcal{M} \otimes \mathcal{M}', (w, w') \nvDash \phi''$. We must prove that every tableau for $(\phi, \phi', \neg \phi'')$ has an open branch (the proof of termination is postponed to Section 4).

We say that a set Σ of tableau formulae is *interpretable* if there exist a \mathcal{L} -model \mathcal{M} , a \mathcal{L}' -model \mathcal{M}' , $f : \text{LABEL} \to W$ and $f' : \text{LABEL}' \to W'$ (where LABEL and LABEL' are the sets of labels for worlds appearing in Σ) such that $(\mathcal{M}, \mathcal{M}', f, f')$ makes all the tableau formulae in Σ true for the following semantics \models_T :

 $\begin{array}{ll} (\mathcal{M}, \mathcal{M}', f, f') \models_T (l_w \phi) & \text{iff } \mathcal{M}, f(l_w) \models \phi \\ (\mathcal{M}, \mathcal{M}', f, f') \models_T (l_{w'} \phi') & \text{iff } \mathcal{M}', f'(l_{w'}) \models \phi' \\ (\mathcal{M}, \mathcal{M}', f, f') \models_T (R \, l_w \, l_u) & \text{iff } f(l_w) R f(l_u) \end{array}$

$$\begin{aligned} (\mathcal{M}, \mathcal{M}', f, f') &\models_T (R' l_{w'} l_{u'}) & \text{iff} \quad f'(l_{w'}) R'f'(l_{u'}) \\ (\mathcal{M}, \mathcal{M}', f, f') &\models_T (l_w l_{w'} 0) & \text{iff} \quad \mathcal{M}, f(l_w) \nvDash \operatorname{Pre}(f'(l_{w'})) \\ (\mathcal{M}, \mathcal{M}', f, f') &\models_T (l_w l_{w'} \phi'') & \text{iff} \quad \mathcal{M}, f(l_w) \models \operatorname{Pre}(f'(l_{w'})) \text{ and} \\ & \mathcal{M} \otimes \mathcal{M}', (f(l_w), f'(l_{w'})) \models \phi'' \\ (\mathcal{M}, \mathcal{M}', f, f') &\models_T \bot & \text{iff} \quad \text{false} \end{aligned}$$

Notice that since $\phi, \phi' \not\models \phi''$, the set $\Gamma_0 = \{(l_w \ \phi)(l_{w'} \ \phi')(l_w \ l_{w'} \ \neg \phi'')\}$ is interpretable. Furthermore, if a set of formulas is interpretable, it does not contain \perp . So if we prove that when the numerator of a rule is interpretable, one of the denominators also is, then we have that every tableau for $(\phi, \phi', \neg \phi'')$ has an open branch. We only prove it for the specific rules of \mathcal{M}'' , the proof for the other rules being standard. In the following, when f is a function, we let $f(x \mapsto a)$ be the function that maps x to a and y to f(y) if $y \neq x$.

Rule $\langle B_j \rangle_{\otimes}$: If $\mathcal{M}, \mathcal{M}', f, f' \models_T (l_w \ l_{w'} \ \langle B_j \rangle \phi)$ then $\mathcal{M} \otimes \mathcal{M}', (f(l_w), f'(l_{w'})) \models \langle B_j \rangle \phi$. So there exists $(u, u') \in W''$ such that $(f(l_w), f'(l_{w'}))R''(u, u')$ and $\mathcal{M} \otimes \mathcal{M}', (u, u') \models \phi$. Since $(f(l_w), f'(l_{w'}))R''(u, u')$ we have that $f(l_w)Ru, f'(l_{w'})R'u'$ and $\mathcal{M}, u \models \operatorname{Pre}(u')$. So by letting $g := f(l_u \mapsto u)$ and $g' := f'(l_{u'} \mapsto u')$ we have that $\mathcal{M}, \mathcal{M}', g, g' \models_T \{(R \ l_w \ l_u)(R' \ l_{w'} \ l_{u'})(l_u \ l_{u'} \ \phi)\}.$

Rule $B_{j\otimes}$: If $\mathcal{M}, \mathcal{M}', f, f' \models_T \{(l_w \ l_{w'} \ B_j \phi)(R \ l_w \ l_u)(R' \ l_{w'} \ l_{u'})\}$ then $\mathcal{M}, f(l_w) \models \operatorname{Pre}(f(l_{w'})), \ \mathcal{M} \otimes \mathcal{M}', (f(l_w), f'(l_{w'})) \models B_j \phi, \ f(l_w)Rf(l_u) \text{ and} f'(l_{w'})R'f'(l_{u'}).$ So, either $\mathcal{M}, f(l_u) \nvDash \operatorname{Pre}(l_{u'})$ or $\mathcal{M}, f(l_u) \models \operatorname{Pre}(l_{u'})$. In the first case, $\mathcal{M}, \mathcal{M}', f, f' \models_T (l_u \ l_{u'} \ 0)$. In the second case, $(f(l_u), f'(l_{u'}))$ is a world of \mathcal{M}'' , and $(f(l_w), f'(l_{w'}))R''(f(l_u), f'(l_{u'}))$. Therefore we have $\mathcal{M} \otimes \mathcal{M}', (f(l_u), f'(l_{u'})) \models \phi$, hence $\mathcal{M}, \mathcal{M}', f, f' \models_T (l_u \ l_{u'} \phi)$

Rules \leftarrow_1 and \leftarrow_2 : If $\mathcal{M}, \mathcal{M}', f, f' \models_T \{l_w \ l_{w'} \ p\}$ then $\mathcal{M}, f(l_w) \models$ Pre $(f(l_{w'})$ and $\mathcal{M} \otimes \mathcal{M}', (f(l_w), f'(l_{w'})) \models p$. Since $V''(f(l_w), f'(l_{w'})) =$ $V(f(l_w))$, we have that $\mathcal{M}, f(l_w) \models p$, hence $\mathcal{M}, \mathcal{M}', f, f' \models_T \{(l_w \ p)\}$. Rule \leftarrow_2 is proved similarly.

Rules Pre₁ and Pre₂: If $\mathcal{M}, \mathcal{M}', f, f' \models_T \{(l_w \ l_{w'} \ \phi)(l_{w'} \ p'_{\psi})\}$ for some $\phi \neq 0$, then $\mathcal{M}, f(l_w) \models \operatorname{Pre}(f'(l_{w'}))$, and $f'(l_{w'}) \in V'(p'_{\psi})$. So $\mathcal{M}, f(l_w) \models \operatorname{Pre}(p'_{\psi})$, and $\mathcal{M}, \mathcal{M}', f, f' \models_T (l_w \ \psi)$. As for Rule Pre₁, if $\mathcal{M}, \mathcal{M}', f, f' \models_T \{(l_w \ l_{w'} \ 0)(l_{w'} \ p'_{\psi})\}$, then, by definition of $\models_T, \mathcal{M}, f(l_w) \models \neg \operatorname{Pre}(f(l_{w'}))$ and $\mathcal{M}', f(l_{w'}) \models p'_{\psi}$. Therefore, by the (Exclusivity) condition, $\operatorname{Pre}(f(l_{w'})) = \psi$, and so $\mathcal{M}, f(l_w) \models \neg \psi$, i.e. $(l_w \ \neg \psi)$.

Proposition 3.3 (Tableau method completeness) For all $\phi, \phi'' \in \mathcal{L}$, for all $\phi' \in \mathcal{L}', \phi, \phi' \models \phi''$ implies $\phi, \phi' \models \phi''$.

Proof. We prove that $\phi, \phi' \nvDash \phi''$ implies $\phi, \phi' \nvDash \phi''$. Suppose there is a tableau for $(\phi, \phi', \neg \phi'')$ that has an open branch, we prove that there exist a pointed \mathcal{L} -model (\mathcal{M}, w) and a pointed \mathcal{L}' -model (\mathcal{M}', w') such that $\mathcal{M}, w \models \operatorname{Pre}(w')$,

 $\mathcal{M}, w \models \phi, \mathcal{M}', w' \models \phi' \text{ and } \mathcal{M} \otimes \mathcal{M}', (w, w') \models \neg \phi''.$

Let Γ_f be the set of tableau formulas carried by the end node of the open branch. We define \mathcal{M} and \mathcal{M}' as follows. Each of them is built in two steps.

- Let $\mathcal{M}_0 = (W_0, R_0, V_0)$ with $W_0 = \{w \mid (l_w \ \psi) \in \Gamma_f\}, V_0(p) = \{w \mid (l_w \ p) \in \Gamma_f\}$ and $R_0 = \{(w, u) \mid (R \ l_w \ l_u) \in \Gamma_f\}$. We then define the pointed \mathcal{L} -model (\mathcal{M}, w) as the bisimulation contraction of (\mathcal{M}_0, w_0) .⁶
- Let $\mathcal{M}' = (W', R', V')$ with $W' = \{w' \mid (l_{w'} \ \psi) \in \Gamma_f\}, V(p'_{\psi}) = \{w' \mid (l_{w'} \ p'_{\psi}) \in \Gamma_f\}, \text{ and } R' = \{(w', u') \mid (R' \ l_{w'} \ l_{u'}) \in \Gamma_f\}.$ Moreover, for all $w' \in \mathcal{M}'$ such that there is no $(l_{w'} \ p'_{\psi}) \in \Gamma_f$, we set $w' \in V'(p'_{\delta_{S_{w'}}})$ if $S_{w'} \neq \emptyset$, where $S_{w'}$ and $\delta_{S_{w'}}$ are defined as follows. Let $S_{w'} = \{w \in \mathcal{M} \mid (l_{w_0} l_{w'} \phi) \in \Gamma_f \text{ for some } \phi \neq 0 \text{ and } w_0 \in w\}.$ Then $\delta_{S_{w'}} = \bigvee_{w \in S_{w'}} \delta(\mathcal{M}, w)$ where $\delta(\mathcal{M}, w)$ is a characteristic formula of (\mathcal{M}, w)

in \mathcal{M} . Note that by soundness of Rule (Excl), \mathcal{M}' satisfies the exclusivity condition.

Finally, we define \mathcal{M}'' as $\mathcal{M} \otimes \mathcal{M}'$ (we will prove later that $\mathcal{M}, w \models \operatorname{Pre}(w')$). Lemmas 3.4 and 3.5 below establish the completeness of our tableau method. \Box

Lemma 3.4 If $(l_{w_0} \phi) \in \Gamma_f$ then $\mathcal{M}, w \models \phi$, and if $(l_{w'} \phi') \in \Gamma_f$ then $\mathcal{M}', w' \models \phi'$.

Proof. We only prove it for \mathcal{M} , it is similar for \mathcal{M}' . We first prove it for \mathcal{M}_0 . The result is then transferred for \mathcal{M} because \mathcal{M}_0 and \mathcal{M} are bisimilar. The proof is done by induction on ϕ .

- $p, \neg p$: by definition of V. As for the case $\phi \land \psi$, by saturation of rule \land , Γ_f also contains $(l_{w_0} \phi)$ and $(l_{w_0} \psi)$. By induction hypothesis we have that $\mathcal{M}_0, w_0 \models \phi$ and $\mathcal{M}_0, w_0 \models \psi$, so $\mathcal{M}_0, w_0 \models \phi \land \psi$. The cases $\neg(\phi \land \psi)$ and $\neg \neg \phi$ are proved similarly.
- $\langle B_j \rangle \phi$: By saturation of rule $\langle B_j \rangle$ there exists l_{u_0} such that $(R \ l_{w_0} \ l_{u_0}) \in \Gamma_f$ and $(l_{u_0} \ \phi) \in \Gamma_f$. By induction hypothesis $\mathcal{M}, u_0 \models \phi$, and $w_0 R u_0$ holds by construction of \mathcal{M}_0 , so $\mathcal{M}_0, w_0 \models \langle B_j \rangle \phi$.
- $B_j\phi$: Take some u_0 in W_0 such that w_0Ru_0 holds, we prove that $\mathcal{M}_0, u_0 \models \phi$ and conclude that $\mathcal{M}_0, w_0 \models B_j\phi$. Since w_0Ru_0 holds we know by construction of \mathcal{M}_0 that $(R \ l_{w_0} \ l_{u_0})$ is in Γ_f . So by saturation of rule B_j , $(l_{u_0} \ \phi)$ also belongs to Γ_f , and by induction hypothesis $\mathcal{M}_0, u_0 \models \phi$.

⁶ Formally, M = (W, R, V) where $W = \{\{v \mid v \text{ is bisimilar to } w_0\} \mid w_0 \in W_0\}, R = \{(w, v) \in W \times W \mid \text{ there is } w_0 \in w \text{ and } v_0 \in v \text{ such that } v_0 \in R(w_0)\} \text{ and } V(p) = \{w \in W \mid \text{ there is } w_0 \in w \text{ such that } w_0 \in V_0(p)\}.$ We write w for the set of worlds of W_0 which are bisimilar to w_0 .

Lemma 3.5 If $(l_{w_0} \ l_{w'} \ \phi'') \in \Gamma_f$ with $\phi'' \neq 0$, then $\mathcal{M}, w \models Pre(w')$ and $\mathcal{M} \otimes \mathcal{M}', (w, w') \models \phi''.$

Proof. We first prove the following Fact:

Fact 3.6 If $(l_{w_0} \ l_{w'} \ \phi) \in \Gamma_f$ with $\phi \neq 0$, then $\mathcal{M}, w \models Pre(w')$.

Assume towards a contradiction that $\mathcal{M}, w \nvDash \operatorname{Pre}(w')$. There are then two cases: either there is $(l_{w'} p'_{\psi}) \in \Gamma_f$ or there is no $(l_{w'} p'_{\psi}) \in \Gamma_f$. In the first case, $\mathcal{M}_0, w_0 \nvDash \psi$ because $\psi = \operatorname{Pre}(w')$ by the (Exclusivity) condition, and so $\mathcal{M}, w \nvDash \psi$. However, by the rule $\operatorname{Pre}_2, (l_{w_0} \psi) \in \Gamma_f$. Then, by Lemma 3.4, $\mathcal{M}, w \models \psi$. This is impossible. In the second case, because $(l_{w_0} l_{w'} \phi) \in \Gamma_f$ for some $\phi \neq 0$, we have that $\mathcal{M}, w \models \delta_{S_{w'}}$. Besides, $\mathcal{M}', w' \models p'_{\delta_{S_{w'}}}$ by definition of V'. Therefore, $\mathcal{M}, w \models \operatorname{Pre}(w')$. This is also impossible.

We can now prove Lemma 3.5. We prove it by induction on ϕ .

- $p, \neg p$: By Rule \leftarrow_1 , $(l_{w_0} p) \in \Gamma_f$, and so $\mathcal{M}, w \models p$ by Lemma 3.4. Moreover, by Fact 3.6, $\mathcal{M}, w \models \operatorname{Pre}(w')$. Therefore, $\mathcal{M} \otimes \mathcal{M}', (w, w') \models p$ by definition of the product update. The proof for $\neg p$ is similar to the case of p. The proof of the other boolean cases $\phi \wedge \psi$, $\neg(\phi \wedge \psi)$ and $\neg \neg \phi$ is obtained by applying straightforwardly the Induction Hypothesis.
- $\langle B_j \rangle \phi$: If $(l_{w_0} \ l_{w'} \ \langle B_j \rangle \phi) \in \Gamma_f$, then by saturation of Rule $\langle B_j \rangle_{\otimes}$, $(R \ l_{w_0} \ l_u)$, $(R' \ l_{w'} \ l_{u'})$ and $(l_{u_0} \ l_{u'} \ \phi)$ belong to Γ_f . Now, by application of Fact 3.6, $\mathcal{M}, w \models \operatorname{Pre}(w')$. Besides, by definition of \mathcal{M} and $\mathcal{M}', \ u \in R(w)$ and $u' \in R'(w')$. Hence, $(u, u') \in R(w, w')$. Moreover, $(l_{u_0} \ l_{u'} \ \phi) \in \Gamma_f$ and $\phi \neq 0$, so by application of the induction hypothesis, $\mathcal{M}, u \models \operatorname{Pre}(u')$ and $\mathcal{M} \otimes \mathcal{M}', (u, u') \models \phi$. Therefore, $\mathcal{M}, w \models \operatorname{Pre}(w')$ and $\mathcal{M} \otimes \mathcal{M}' \models \langle B_j \rangle \phi$.
- $B_j\phi$: If $(l_{w_0} \ l_{w'} \ B_j\phi) \in \Gamma_f$, then by application of Fact 3.6, $\mathcal{M}, w \models \operatorname{Pre}(w')$. Let $(u, u') \in R(w, w')$. Then $u \in R(w)$ and $u' \in R'(w')$ by definition of the product update. Then there is $u_0 \in u$ such that $u_0 \in R(w_0)$ by definition of \mathcal{M} . Therefore, by definition of \mathcal{M} and $\mathcal{M}', (R \ l_{w_0} \ l_{u_0}) \in \Gamma_f$ and $(R' \ l_{w'} \ l_{u'}) \in \Gamma_f$. Then, by saturation of Rule $B_{j\otimes}$, either (i) $(l_{u_0} \ l_{u'} \ 0) \in \Gamma_f$ or (ii) $(l_{u_0} \ l_{u'} \ \phi) \in \Gamma_f$.
 - (i) In the first case, assume that there is (l_{u'} p'_ψ) ∈ Γ_f. Then, by saturation of Rule Pre₁, (l_{u0} ¬ψ) ∈ Γ_f. Therefore, M, u ⊨ ¬ψ by Lemma 3.4. This is impossible because M', u' ⊨ p'_ψ, and so M, u ⊨ ψ should also hold because (u, u') ∈ M ⊗ M'. Therefore, there is no (l_{u'} p'_ψ) ∈ Γ_f.
 (a) If there is u* ⊂ u such that (l + l + φ) for some φ ≠ 0, then by

(a) If there is $u_0^* \in u$ such that $(l_{u_0^*} \ l_{u'} \ \phi)$ for some $\phi \neq 0$, then by Induction Hypothesis, $\mathcal{M}, u \models \operatorname{Pre}(u')$ and $\mathcal{M} \otimes \mathcal{M}', (u, u') \models \psi$.

(b) If there is no $u_0^* \in u$ such that $(l_{u_0^*} \ l_{u'} \ \phi)$ for some $\phi \neq 0$, then by definition of $S_{u'}$, $u \notin S_{u'}$. Therefore, $\mathcal{M}, u \nvDash \delta_{S_{u'}}$, because the formula $\delta_{S_{u'}}$ characterizes exactly the worlds of $S_{u'}$. Hence, $\mathcal{M}, u \nvDash$ $\operatorname{Pre}(u')$ by definition of V', because $\mathcal{M}', u' \models p'_{\delta_{S_{u'}}}$. However, $(u, u') \in$ R(w, w'), and so $\mathcal{M}, u \models \operatorname{Pre}(u')$. There is a contradiction, so this case is impossible.

- (ii) In the second case, by Induction Hypothesis, $\mathcal{M}, u \models \operatorname{Pre}(u')$ and $\mathcal{M} \otimes \mathcal{M}', (u, u') \models \phi$
- So, in any case, $\mathcal{M} \otimes \mathcal{M}, (u, u') \models \phi$. Therefore, $\mathcal{M} \otimes \mathcal{M}', (w, w') \models B_j \phi$.

4 Complexity of the satisfiability problem

Proposition 4.1 The satisfiability problem is in NEXPTIME.

Proof. The tableau rules presented in Section 3.2 give rise to a nondeterministic algorithm running in exponential time. We say that a label l_u is of depth k if there is a sequence $w = u_1, \ldots, u_k = u$ such that $(R \ l_{w_i} \ l_{w_{i+1}})$ for all i < k. Let $p'_{\psi_1}, \ldots, p'_{\psi_n}$ be the set of atomic propositions appearing in ϕ' . Let $\delta(.)$ be the function that gives the modal depth of a given formula. The algorithm starts with the following set of tableau formulas $\Gamma_0 = \{(l_w \ \phi), (l_{w'} \ \phi'), (l_w \ l_{w'} \ \phi'')\}$. Let $N = max\{\delta(\phi), \delta(\phi'), \delta(\phi'') + max_{k \in \{1, \ldots, n\}}\delta(\psi_k)\}$.

The algorithm runs as follows. For i = 0 to N, we execute:

- (i) $\Gamma'_i :=$ the saturation of Γ_i by rules $\land, \neg \land, \neg, \bot, Excl, \leftarrow_1, \leftarrow_2, Pre_1, Pre_2;$
- (ii) If $\perp \in \Gamma'_i$, we stop the current execution;
- (iii) $\Gamma_{i+1} :=$ the set of tableau formulas obtained by applying $\langle B_j \rangle, B_j, \langle B_j \rangle_{\otimes}, B_{j_{\otimes}}$ on Γ'_i .

Step 1 is non-deterministic and corresponds to a Boolean saturation of labels of depth *i*. It non-deterministically runs in linear size of Γ_i . Step 2 consists in checking if rule \perp has been executed. In this case, the current execution halts. Step 3 produces tableau formulas where labels are of depth i + 1.

Note that the maximal depth of formulas ψ'' in tableau formulas of the form $(l_u \ l_{u'} \ \psi'')$ in Γ_i is strictly decreasing with i (see rule $\langle B_j \rangle_{\otimes}$ and $B_{j_{\otimes}}$). So when $i > \delta(\phi'')$, there is no more tableau formula of the form $(l_u \ l_{u'} \ \psi'')$ in Γ_i with $\psi'' \neq 0$. So when $i > \delta(\phi'')$, the rules Pre_2 , $\langle B_j \rangle_{\otimes}$ and $B_{j_{\otimes}}$ will no more be applied.

Likewise, the maximal depth of formulas ψ (resp. ψ') in tableau formulas of the form $(l_u \psi)$ (resp. $(l_{u'} \psi')$ in Γ_i is strictly decreasing with *i*. Moreover the depth of the formulas ψ appearing in a tableau formula of the form $(l_u \psi)$ is less than $max\{\delta(\phi), max_{k \in \{1,...,n\}}\delta(\psi_k)\}$, and the depth of the formulas ψ' appearing in a tableau formula of the form $(l_{u'} \psi')$ is less than $\delta(\phi')$.

At the end, $\Gamma_{N+1} = \emptyset$ and the algorithm has applied rules until saturation, that is, the set of tableau formulas $\bigcup_{i=0}^{N} \Gamma_i$ is saturated. Now let us have a look at the time required to execute the algorithm. Let x be the size of the input, that is the sum of the sizes of ϕ , ϕ' , ϕ'' and $\operatorname{Pre}(p_k)$. Step 1 saturates the worlds u, u' and (u, u') appearing in the tableau formulas in Γ_i . For each of those worlds, the saturation is linear in x. Step 3 creates new tableau formulas for each $\langle B_j \rangle$ -formula appearing in Γ'_i . So for each world in Γ_i it produces at most 2x new worlds. If we note y_i the maximal number of worlds in Γ_i , we have that $y_{i+1} = 2xy_i$. So $y_i = (2x)^i$. The numbers of created worlds is bounded by $(2x)^{x+1}$ and this construction takes an exponential amount of time.

To prove NEXPTIME-hardness of the satisfiability problem, we will reduce a NEXPTIME-complete tiling problem to it [Boas, 1997]. Let k be a natural number. A tile type t is a 4-tuple of colors t = (left(t), right(t), up(t), down(t)). The tiling problem we consider is defined as follows.

- Input: a finite set T of tile types, a $t_0 \in T$ and a natural number k written in its binary form.
- Output: yes iff we can tile a $k \times k$ grid with the tile types of T and t_0 being placed onto (0,0).

In other worlds, the problem is to decide whether there exists a function τ from $\{1, \ldots k\}^2$ to T satisfying the following constraints:

(i)
$$\tau(0,0) = t_0;$$

- (ii) $up(\tau(x,y)) = down(\tau(x,y+1))$ for all $x \in \{1,\ldots,k\}, y \in \{1,\ldots,k-1\};$
- (iii) $right(\tau(x,y)) = left(\tau(x+1,y))$ for all $x \in \{1, \dots, k-1\}, y \in \{1, \dots, k\}$.

Proposition 4.2 The satisfiability problem is NEXPTIME-hard.

Proof. Without loss of generality we may assume that $k = 2^n$. Let us consider an instance (T, t_0, k) of the tiling problem. We now define three formulas ϕ, ϕ', ϕ'' that are computable in polynomial time in |T| and n such that it is possible to tile a $k \times k$ grid with the tile types of T and t_0 being placed onto (0, 0) iff (ϕ, ϕ', ϕ'') is satisfiable.

There is a modal formula χ of length $O(n^2)$ which is satisfied in a frame iff the model contains as a submodel a binary tree of depth 2n, for instance:

$$\chi = \bigwedge_{l < 2n} B_j^{\ l} \left((\langle B_j \rangle p_l \land \langle B_j \rangle \neg p_l) \land \bigwedge_{i < l} ((p_i \to B_j p_i) \land (\neg p_i \to B_j \neg p_i)) \right).$$

The 2^{2n} leaves of the tree are labeled by 2n-tuples containing either p_i or $\neg p_i$ for i < 2n. The 2^{2n} leaves correspond to the 2^{2n} tile locations (x, y) in the following sense: the values of the propositions p_i , where i < n, correspond to the binary representation of the abscissa x and the values of the propositions p_i , where $n \leq i < 2n$, correspond to the binary representation of the ordinate y. For instance, for n = 4 the location where x = 4 and y = 3 is represented by the following valuation:

$$\underbrace{\neg p_0, p_1, \neg p_2, \neg p_3}_{4} \underbrace{\neg p_4, \neg p_5, p_6, p_7}_{3}$$

The idea of encoding the existence of a $k \times k$ tiling is as follows:

- ϕ encodes a tiling τ_1 with such a binary tree such that $\tau_1(0,0) = t_0$;
- ϕ' also encodes a tiling τ_2 wich such a binary tree;
- ϕ'' encodes that $\tau_1 = \tau_2 = \tau$, and constraints (ii) and (iii) of the tiling τ .

Defining ϕ

We define the following formula: $path = \langle B_j \rangle^{2n+|T|} \top \wedge \bigwedge_{i < 2n+|T|} B_j^{\ i} \langle B_j \rangle \top$. The formula *path* says that there is a path whose length is greater that 2n+|T| but no shorter path in the model.

In order to define ϕ , each tiling type t is used as a proposition in the language, and means : 'for the current location (x, y), we have $\tau_1(x, y) = t$ '.

We define ϕ by:

$$\phi = \chi \wedge B_j^{2n} \left(path \wedge \bigvee_{t \in T} t \wedge \bigwedge_{t \in T} (t \to \bigwedge_{u \in T, u \neq t} \neg u) \wedge \left(\left(\bigwedge_{i < 2n} \neg p_i \right) \to t_0 \right) \right)$$

Defining ϕ'

For all *i*, we define $l'_i = \langle B_j \rangle^{i+1} B_j \bot$. Let $\chi' = \bigwedge_{i < 2n} B_j^{i} (\langle B_j \rangle B_j^{2n-i-1} l'_i \wedge \langle B_j \rangle B_j^{2n-i-1} \neg l'_i)$. The formula χ' has the same aim as χ and enables to enforce the existence of a binary tree where leaves correspond to the locations (x, y) of the tiling τ_2 . Formulas l'_i for i < 2n represent the binary representation of (x, y).

Let $t_1, \ldots, t_{|T|}$ be an enumeration of elements of T. In order to define ϕ' , for each tiling type t_i we use the formula $t'_i = l'_{i+2n}$ in the language whose intuitive meaning is 'for the current location (x, y), we have $\tau_2(x, y) = t_i$.

We define ϕ' by

$$\phi' = \chi' \wedge goodProduct \wedge B_j^{2n} (\bigvee_{i \in \{1, \dots, |T|\}} t'_i \wedge \bigwedge_{i \in \{1, \dots, |T|\}} (t'_i \to \bigwedge_{k \in \{1, \dots, |T|\}, k \neq i} \neg t'_k)).$$

where $goodProduct = \bigwedge_{i \leq 2n+2n+|T|+1} B_j{}^i p'_{\top}$ ensures that all worlds (w, w') appear in the product model.

Defining ϕ''

The formula ϕ'' will consider all the leaves (w, w') of the product model where w is a leaf of the model M and w' is a leaf of the model M' in order to encode the fact that $\tau_1 = \tau_2$ and the constraints (ii) and (iii).

We define ϕ'' by:

$$\phi'' = B_j^{2n} [(\alpha \land \beta \to \bigwedge_{j \in \{1, \dots, |T|\}} (t_j \leftrightarrow t'_j)) \land \\ (\alpha \land \beta_1 \to \bigwedge_{j \in \{1, \dots, |T|\}} (t_j \to \bigvee_{k \in \{1, \dots, |T|\} | down(t_k) = up(t_j)} t'_k)) \land \\ (\alpha_1 \land \beta \to \bigwedge_{j \in \{1, \dots, |T|\}} (t_j \to \bigvee_{k \in \{1, \dots, |T|\} | left(t_k) = right(t_j)} t'_k))]$$

where:

- $\alpha = \bigwedge_{i < n} (p_i \leftrightarrow l'_i)$ means 'the abscissa x of the tile location of w is equal to the absissa x' of the tile location of w'';
- $\beta = \bigwedge_{n \le i < 2n} (p_i \leftrightarrow l'_i)$ means 'the ordinate y of the tile location of w is equal to the ordinate y' of the tile location of w'';
- $\alpha_1 = \bigvee_{i < n} \left(\bigwedge_{j < i} (p_j \leftrightarrow l'_j) \land \neg p_i \land l'_i \land \bigwedge_{i < j < n} (p_j \land \neg l'_j) \right)$ means "the abscissa x of the tile location of w and the abscissa x' of the tile location of w'" are such that x' = x + 1;
- $\beta_1 = \bigvee_{n \le i < 2n} \left(\bigwedge_{n \le j < i} (p_j \leftrightarrow l'_j) \land \neg p_i \land l'_i \land \bigwedge_{i < j < 2n} (p_j \land \neg l'_j) \right)$ means "the ordinate y of the tile location of w and the ordinate y' of the tile location of w' are such that y' = y + 1.

We leave the reader prove that we can tile a $k \times k$ grid with the tile types of T and t_0 being placed onto (0,0) iff (ϕ, ϕ', ϕ'') is satisfiable.

5 Implementation

The tableau method described in Remark 3.1 of Section 3.2 is implemented in LoTRECScheme (a variant of LoTREC [Gasquet et al., 2005] written in Scheme). Contrary to LoTREC, the system of LoTRECScheme allows the name of a node to be a couple (w, w') and this functionnality is suitable for our tableau rules. You can find the implementation at the following web page:

http://www.irisa.fr/prive/fschwarz/publications/m4m2011/.

6 Concluding remarks and related work

This paper contributes to the proof theory and the study of the computational complexity of DEL, which has been rather neglected so far. Indeed, most work in this field has often been inspired or applied to logico-philosophical puzzles such as for example the muddy children riddle, Fitch paradox, or Moorean sentences. Up to our knowledge, the only known results of computational complexity are the PSPACE-completeness of the satisfiability problem for public announcement logic [Lutz, 2006] and the polynomial time upper bound of the model-checking problem for public announcement logic. As for proof theory, a sound and complete sequent calculus for DEL has been developped in [Baltag et al., 2004], yet in an algebraic setting. Because of this different setting, the comparison cannot be systematic, but, unlike our DEL-sequents, their sequents $m_1, \ldots, q_1, \ldots, A_1, \ldots, m_k, \ldots, q_l, \ldots, A_n \vdash \delta$ are arbitrarily long and consist of different types of formulas which can contain propositions m_1, \ldots, m_k , events q_1, \ldots, q_l and agents A_1, \ldots, A_n , and which resolve into a single proposition or event δ . Some tableau methods have been proposed for DEL, but only for public announcement logic [Balbiani et al., 2010, de Boer, 2007] and hybrid public anouncement logic [Hansen, 2010]. A terminating tableau method has also been proposed for the full BMS framework in [Hansen, 2010] by encoding the reduction axioms as tableau rules. However, none of these tableau methods can somehow address the three questions raised in the introduction, because the BMS language of [Baltag and Moss, 2004] does not allow for partial and incomplete descriptions of events: an event model or a formula announced publicly specifies *completely* how all the agents perceive the occurrence of the corresponding event.

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