

# Zubov's method for interconnected systems

Fabian Wirth, Fabio Camilli, Lars Grüne

### ▶ To cite this version:

Fabian Wirth, Fabio Camilli, Lars Grüne. Zubov's method for interconnected systems. SADCO Kick off, Mar 2011, Paris, France. inria-00585701

# HAL Id: inria-00585701 https://inria.hal.science/inria-00585701

Submitted on 14 Apr 2011

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# Zubov's method for interconnected systems

#### Fabian Wirth

Institute of Mathematics University of Würzburg

SADCO - Kick off meeting Paris, March, 1–2 2011.

joint work with:

Fabio Camilli (L'Aquila) and Lars Grüne (Bayreuth)







#### Zubov's Method

The domain of attraction Zubov's equation

#### Robust domains of attraction

Problem statement A robust version of Zubov's theorem Examples

Interconnected Systems
ISS and Lyapunov functions

Zubov's Method and Interconnected Systems







### The domain of attraction

### Consider a nonlinear system

$$\dot{x} = f(x) \qquad (1)$$

$$x(0) = x_0 \in \mathbb{R}^n,$$

$$f$$
 Lipschitz continuous,  $f(0) = 0$ .  
Assume  $x^* = 0$  is asymptotically stable.





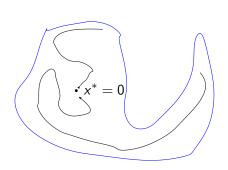
(1)

### The domain of attraction

### Consider a nonlinear system

$$\dot{x} = f(x) 
x(0) = x_0 \in \mathbb{R}^n,$$

f Lipschitz continuous, f(0) = 0. Assume  $x^* = 0$  is asymptotically stable.







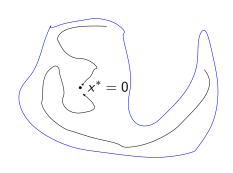
### The domain of attraction

### Consider a nonlinear system

$$\dot{x} = f(x) \tag{1}$$

$$x(0) = x_0 \in \mathbb{R}^n,$$

f Lipschitz continuous, f(0) = 0. Assume  $x^* = 0$  is asymptotically stable.



The domain of attraction of 0 is defined by

$$\mathcal{A}(0) := \{x \in \mathbb{R}^n \mid \varphi(t;x) \to 0, \text{ as } t \to \infty\}$$
.

Here  $\varphi(\cdot; x)$  denotes the solution of (1).







Zubov's equation

# Zubov's result (1956)

$$\dot{x} = f(x) \tag{1}$$

$$f(0) = 0, \quad x^* = 0$$
 is asymptotically stable. (2)

#### **Theorem**

A set A containing 0 in its interior is the domain of attraction of (1) if and only if





Zubov's equation

# Zubov's result (1956)

$$\dot{x} = f(x) \tag{1}$$

$$f(0) = 0, \quad x^* = 0$$
 is asymptotically stable. (2)

#### **Theorem**







# Zubov's result (1956)

$$\dot{x} = f(x) \tag{1}$$

$$f(0) = 0$$
,  $x^* = 0$  is asymptotically stable. (2)

### **Theorem**

► 
$$V(0) = h(0) = 0$$
,  
  $0 < V(x) < 1$  for  $x \in A \setminus \{0\}$ ,  $h > 0$  on  $\mathbb{R}^n \setminus \{0\}$ 





# Zubov's result (1956)

$$\dot{x} = f(x) \tag{1}$$

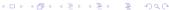
$$f(0) = 0$$
,  $x^* = 0$  is asymptotically stable. (2)

### **Theorem**

- ▶ V(0) = h(0) = 0, 0 < V(x) < 1 for  $x \in A \setminus \{0\}$ , h > 0 on  $\mathbb{R}^n \setminus \{0\}$
- ▶  $V(x_n) \to 1$  for  $x_n \to \partial A$  or  $||x_n|| \to \infty$ ,







# Zubov's result (1956)

$$\dot{x} = f(x) \tag{1}$$

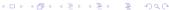
$$f(0) = 0, \quad x^* = 0$$
 is asymptotically stable. (2)

### **Theorem**

- ▶ V(0) = h(0) = 0, 0 < V(x) < 1 for  $x \in A \setminus \{0\}$ , h > 0 on  $\mathbb{R}^n \setminus \{0\}$
- ▶  $V(x_n) \to 1$  for  $x_n \to \partial A$  or  $||x_n|| \to \infty$ ,
- $DV(x) \cdot f(x) = -h(x)(1 V(x))\sqrt{1 + \|f(x)\|^2}$







Consider systems

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

with a perturbation term d. We are interested in robust stability properties. In particular, the robust domain of attraction.

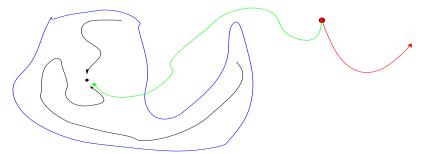




### Consider systems

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

with a perturbation term d. We are interested in robust stability properties. In particular, the robust domain of attraction.









$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

### Assumptions:

- $f: \mathbb{R}^n \times D \to \mathbb{R}^n$  continuous, locally Lipschitz continuous in x, uniformly in d
- $D \subset \mathbb{R}^m$  compact, convex,  $d(t) \in D$  a.e.







$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

### Assumptions:

- $f: \mathbb{R}^n \times D \to \mathbb{R}^n$  continuous, locally Lipschitz continuous in x, uniformly in d
- $D \subset \mathbb{R}^m$  compact, convex,  $d(t) \in D$  a.e.
- f(0, d) = 0 for all  $d \in D$
- 0 is locally uniformly asymptotically stable

Notation:  $\mathcal{D} := \{d : \mathbb{R} \to D ; d \text{ Lebesgue measurable} \}$ 







$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

### Assumptions:

- $f: \mathbb{R}^n \times D \to \mathbb{R}^n$  continuous, locally Lipschitz continuous in x, uniformly in d
- $D \subset \mathbb{R}^m$  compact, convex,  $d(t) \in D$  a.e.
- f(0, d) = 0 for all  $d \in D$
- 0 is locally uniformly asymptotically stable

Notation:  $\mathcal{D} := \{d : \mathbb{R} \to D ; d \text{ Lebesgue measurable}\}$ 

$$\mathcal{A}_D(0) := \{ x \in \mathbb{R}^n \mid \phi(t; x.d) \to 0 \, \forall d \in \mathcal{D} \}$$







### A robust version of Zubov's theorem

**Theorem:** [Zubov's theorem for perturbed systems, SICON 2001] Under suitable growth conditions on g there is a unique viscosity solution of

$$\begin{cases} \inf_{d \in D} \{-Dv(x)f(x,d) - (1-v(x))g(x,d)\} = 0 \\ v(0) = 0 \end{cases}$$

The robust domain of attraction satisfies

$$A_D(0) = v^{-1}([0,1)).$$







# Example

$$\dot{x}_1 = -x_1 + x_2 
\dot{x}_2 = 0.1x_1 - 2x_2 - x_1^2 - 0.1x_1^3$$

Fixed points:

[0,0], unstable

[-2.5505, -2.5505], asymptotically stable

[-7.4495, -7.4495], asymptotically stable.

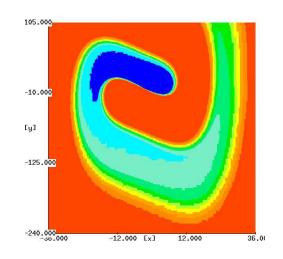






# Example

$$\dot{x}_1 = -x_1 + x_2 
\dot{x}_2 = 0.1x_1 - 2x_2 - x_1^2 
- (0.1 + d(t))x_1^3 
D = \{0\}$$



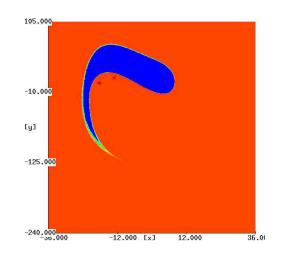




# Example

$$\dot{x}_1 = -x_1 + x_2 
\dot{x}_2 = 0.1x_1 - 2x_2 - x_1^2 
- (0.1 + d(t))x_1^3$$

D = [-0.02, 0.02]









### **Drawbacks**

- ► Solution of the PDE is obtained by discretisation of the state space.
- Curse of dimensionality: For systems of dimension greater than 4 the method is not really applicable.







### Drawbacks

Examples

- Solution of the PDE is obtained by discretisation of the state space.
- Curse of dimensionality: For systems of dimension greater than 4 the method is not really applicable.

#### Idea:

View systems in larger dimension as interconnection of low-dimensional systems.







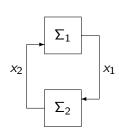
## Interconnection of two systems

### Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i: \mathbb{R}^{N_1+N_2+N_u} \to \mathbb{R}^{N_i}$$







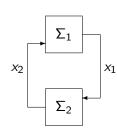
### Interconnection of two systems

### Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i: \mathbb{R}^{N_1+N_2+N_u} \to \mathbb{R}^{N_i}$$



with two Lyapunov functions such that

$$V_1(x_1) > \gamma_{12}(V_2(x_2)) \quad \Rightarrow \dot{V}_1 < -\alpha_1(||x_1||)$$

$$V_2(x_2) > \gamma_{21}(V_1(x_1)) \quad \Rightarrow \dot{V}_2 < -\alpha_2(||x_2||)$$







ISS and Lyapunov functions



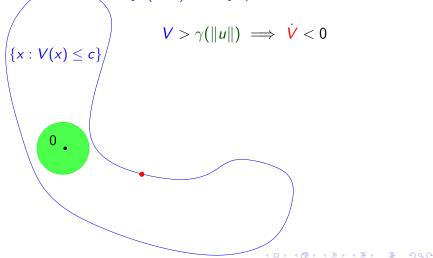


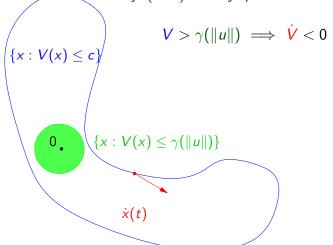


$$V > \gamma(\|u\|) \implies \dot{V} < 0$$



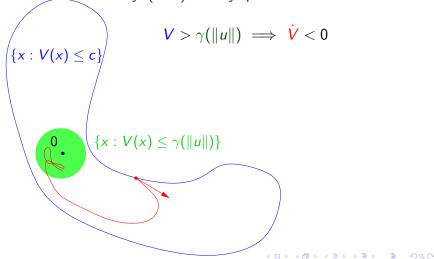
ISS and Lyapunov functions











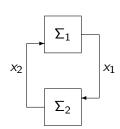
## Interconnection of two systems

### Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i: \mathbb{R}^{N_1+N_2+N_u} \to \mathbb{R}^{N_i}$$







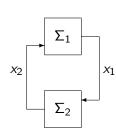
# Interconnection of two systems

### Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i: \mathbb{R}^{N_1+N_2+N_u} \to \mathbb{R}^{N_i}$$



with two Lyapunov functions such that

$$V_1(x_1) > \gamma_{12}(V_2(x_2)) \Rightarrow \dot{V}_1 < -\alpha_1(||x_1||)$$

$$V_2(x_2) > \gamma_{21}(V_1(x_1)) \Rightarrow \dot{V}_2 < -\alpha_2(||x_2||)$$







# The ISS small gain theorem

### Theorem (Jiang, Mareels, Wang 1996)

If there exist  $\mathcal{K}_{\infty}$ -functions  $\rho_1, \rho_2$  such that

$$(\mathrm{i}d + \rho_1) \circ \gamma_{12} \circ (\mathrm{i}d + \rho_2) \circ \gamma_{21} < \mathrm{id},$$

then

$$\dot{x} = f(x) = \begin{pmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{pmatrix}$$

with  $x = (x_1, x_2)^{\top}$  is asymptotically stable in  $(x_1^*, x_2^*) = (0, 0)$ .

See also [Jiang, Teel, Praly 1994] [Grüne 2002] and [Dashkovskiy, Rüffer, W. 2007, 2009].







ISS and Lyapunov functions

### Goal

Can we compute ISS Lyapunov functions using a Zubov approach?







## Zubov and ISS Lyapunov functions

Choose a gain  $\gamma \in \mathcal{K}_{\infty}$  and define

$$\tilde{f}_{\gamma} : \mathbb{R}^{n} \times B(0,1) \to \mathbb{R}^{n}$$
 $(x,d) \mapsto f(x,\gamma(\|x\|)d)$ 

$$\dot{x} = f(x, \gamma(\|x\|)d) := \tilde{f}_{\gamma}(x, d), \qquad (3)$$

### **Proposition**

Let  $\gamma \in \mathcal{K}_{\infty}$  be locally Lipschitz on  $(0, \infty)$ .

If V is a robust Lyapunov function for (3) it is an ISS Lyapunov function for

$$\dot{x} = f(x, d)$$

with Lyapunov gain  $\gamma^{-1}$ .







(i) For each of the subsystems i=1,2 choose  $\gamma_i\in\mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .





- (i) For each of the subsystems i=1,2 choose  $\gamma_i\in\mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,j}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$





- (i) For each of the subsystems i=1,2 choose  $\gamma_i\in\mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,j}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

(iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$







- (i) For each of the subsystems i=1,2 choose  $\gamma_i\in\mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,j}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

(iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$

(iv) Do the two gains  $\tilde{\gamma}_{12}, \tilde{\gamma}_{21}$  satisfy the small gain condition ?





- (i) For each of the subsystems i=1,2 choose  $\gamma_i\in\mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,j}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

(iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}$$
.

- (iv) Do the two gains  $\tilde{\gamma}_{12}, \tilde{\gamma}_{21}$  satisfy the small gain condition ?
- (v) If this is the case there is a constructive procedure to get a Lyapunov function for the interconnected system, (see Dashkovskiy, Rüffer, W. 2009).







- (i) For each of the subsystems i=1,2 choose  $\gamma_i\in\mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,j}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

(iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}$$
.

- (iv) Do the two gains  $\tilde{\gamma}_{12}, \tilde{\gamma}_{21}$  satisfy the small gain condition ?
- (v) If this is the case there is a constructive procedure to get a Lyapunov function for the interconnected system, (see Dashkovskiy, Rüffer, W. 2009).
- (vi) Use this function to estimate the domain of attraction.







### Conclusions

- ► An approach for the computation of lower estimates for the domain of attraction of interconnected systems has been presented.
- The idea still needs a lot of tuning:
  - ightharpoonup which  $\gamma$  do you choose
  - is  $\gamma \in \mathcal{K}_{\infty}$  really necessary ? (Angeli and Astolfi, 2007) says clearly that this is not the case
  - ▶ Do state transformations help?





