Graphics Gems Revisited
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Abstract

We present an algorithm for rendering faceted colored gemstones in real time, using graphics hardware. Beyond the technical challenge of handling the complex behavior of light in such objects, a real time high quality rendering of gemstones has direct applications in the field of jewelry prototyping, which has now become a standard practice for replacing tedious (and less interactive) wax carving methods. Our solution is based on a number of controlled approximations of the physical phenomena involved when light enters a stone, which permit an implementation based on the most recent – yet commonly available – hardware features such as fragment programs, cube-mapping.

Keywords: Crystal optics, Hardware-based rendering, real time

1 Introduction

Gemstones are fascinating because they display many visually appealing phenomena thanks to their ability to alter light in a number of very specific ways. Examples include brilliance from internal reflections, fire due to dispersion of light, dichroism and doubling due to birefringence, color-shifting because of a camel-shaped absorbance spectrum, and darkening due to polarization. Unfortunately, the complexity of light interaction inside gemstones, due to their particular crystal structure, makes correct renderings of such objects very difficult to obtain.

Furthermore, our investigations among jewelry design packages show that computer aided prototyping has now become a standard [Doyle 2000]. Applications need a fast algorithm for rendering gemstones to allow the user to move and appreciate the variations in color and brightness over several views of the stone. The quality of the rendering is most important during the design of a piece hand-in-hand with a client who may want to see a high quality view of the expected result.

Up to now, the academic solutions which have been proposed for rendering gemstones have all been based on more or less complex ray tracing implementations, and therefore do not offer the possibility of real time display. To our knowledge, no commercial jewelry design software has such a capability. In the specifications of the two software packages JewelSpace™ (see www.jewelspace.net) and JewelCAD™ (see www.jacadcam.com), for instance, one learns that the first combines radiosity and ray tracing while the second uses OpenGL and ray tracing, which gives nice, but not instant, results.

We show in this paper that the convexity and polyhedral nature of faceted gemstones raises the possibility of an efficient hardware implementation, which we achieve by using the most recent hardware capabilities such as high level fragment programming [Mark et al. 2003], as well as more classical techniques such as cube mapping [Greene 1986]. It is indeed possible to rely on these tools for implementing pixel-based computation of Fresnel terms, directional light sampling and tone reproduction.

Our system introduces new possibilities of observing virtual gemstones: not only can the viewing conditions be changed in real time but also the physical properties (e.g., color, refractive index) and even the geometry of the stone. Indeed, our management of rendering complexity offers the possibility to trade accuracy for speed, so as to maintain interactive rendering speed. Among applications, our algorithm could be a plugin for rendering faceted objects in a more complex scene as our results show. In terms of jewelry design, our contribution should be seen as a potential solution for real time examination of created objects with high rendering quality. For educational purposes it also permits to study interactively the visual properties of gemstone cuts in measured light conditions.

In section 3 we present a physical model for the behavior of light in colored gemstones. The importance of each phenomenon is then examined with a correct order of priority in terms of visual impact in Section 4, in order to derive a model suitable for hardware implementation. This implementation is presented in section 5. We finally give a number of results prior to concluding.

2 Related work

Yokoi et al. propose an algorithm [Yokoi et al. 1986] aimed particularly at the reproduction of asterism (i.e., the effect seen on star sapphires) and chatoyancy effects. For this, a model for the dispersion of light rays into a distribution of micro facets is elaborated, which produces the expected result.

Yuan uses an adaptive ray tracing for adequately sampling the light spectrum for various wavelengths [Yuan et al. 1988], while keeping the overall complexity much lower than traditional dispersive ray tracing [Thomas 1986] and obtains fine images of diamonds. Dispersion is further investigated in [Sun et al. 2000b] and [Wilkie et al. 2000] for the rendering of glass-made objects.

Sun [Sun et al. 2000a] obtains images of colored diamonds using Fresnel reflection, volume absorption and light dispersion in a ray tracer. He also proposes a method to handle the non-linearity of absorption and the poor regularity of absorbance spectra using a composite spectral model.

These three papers constitute the few contributions in the field of computer graphics which aiming at rendering gemstones specifically. All these methods share a ray tracing basis with high computation time. None of them implements polarization which however incurs several visually important phenomena in gemstones.

Wolff proposes one of the first attempts to incorporate polarization effects in ray tracing [Wolff and Kurlander 1990], in the context
of generalizing the Torrance-Sparrow reflectance model. For this,
he uses the formalism of coherency matrices, introduced by Wolf
in 1959 [Wolf 1959]. Another formalism (Stokes light vectors) was
used by Wilkie in 2001 to get rid of complex numbers [Wilkie et al.
2001] and to incorporate polarization along with fluorescence ef-
fcts in a ray tracer, with convincing results on semi-transparent
objects. In 1994, Tannenbaum gave some details about the im-
plementation of the birefringency phenomenon [Tannenbaum et al.
1994] for computing images of highly birefringent media such as
calcite. As we explain below, birefringency is responsible for color
variations in many stones.

3 Light propagation in gemstones

We start by presenting a physical model for light propagation
in gemstones. This model will be used as a starting point for the
approximations which lead to our simplified model (in Section 4),
which is suitable for hardware implementation. It will also serve in
a ray tracer (see Section 6) for validating these approximations.

Although the polarization state of light is for, most rendering
applications, an expensive and unnecessary feature, it does play a
critical role in the interaction of light with gemstones, and there-
fore must be incorporated into any rendering model that wants to
 reproduce these effects. Indeed, while the naked eye is not trained
for detecting light polarization, the path of light through a faceted
transparent object involves a number of selective changes in the po-
larization. This succession of changes is responsible for the darken-
ing of some regions and, in the case of anisotropic crystal structures,
a color change depending on the direction of propagation (Figure 3,
left) combines a combination of these two effects.

Let $\mathbf{E}$ be the electric field of a monochromatic planar wave
propagating along vector $\mathbf{s}$ at speed $v$ and angular frequency $\omega$. $\mathbf{E}$ is
expressed in the plane orthogonal to $\mathbf{s}$ as space and time dependent
2D vector:

$$
\mathbf{E}(r,t) = \begin{bmatrix} E_\perp \cos(\omega(t-r/s/v)) \\ E_\parallel \cos(\omega(t-r/s/v)+\delta) \end{bmatrix} = R \begin{bmatrix} e^{i\omega(t-r/s/v)} \\ e^{i\omega(t-r/s/v)+\delta} \end{bmatrix}
$$

(1)

$E_\perp$ and $E_\parallel$ are the amplitudes of each component and $\delta$ is the phase
shift between the two components of $\mathbf{E}$. As shown, $\mathbf{E}$ may alterna-
tively be represented as the real part of a complex-valued field. For
rendering, we are interested in the intensity of $\mathbf{E}$, which is

$$
I = E_\perp^2 + E_\parallel^2
$$

3.1 Fresnel laws

Most crystal-structured materials are optically anisotropic (e.g.,
tourmaline, sapphire, but not diamond). This comes from the
geometric asymmetry of the atoms arranged in the structure,
which favors different charge transfers – i.e., different wavelength
absorptions–, and different propagation speeds, depending on
the direction of propagation. In the case of uniaxial crystals the
medium is characterized by two indices of refraction $n_0$ and $n_1$, and
its optical axis $\mathbf{a}$. For a given wave propagation vector $\mathbf{s}$, we define the
crystal coordinate system by its orthonormal basis $X_a$, $Y_a$, $Z_a$

$$
\mathbf{X}_a(s) = \frac{\mathbf{a} \times \mathbf{s}}{||\mathbf{a} \times \mathbf{s}||}, \quad \mathbf{Y}_a(s) = \frac{\mathbf{s} \times (\mathbf{a} \times \mathbf{s})}{||\mathbf{s} \times (\mathbf{a} \times \mathbf{s})||}, \quad \mathbf{Z}_a(s) = \mathbf{a}
$$

(2)

Let $\epsilon$ be the dielectric tensor of the medium, defined by:

$$
\epsilon = \epsilon_0 \begin{bmatrix} n_1^2 & 0 & 0 \\ 0 & n_0^2 & 0 \\ 0 & 0 & n_1^2 \end{bmatrix}
$$

(3)

The dielectric displacement vector $D$ of the wave is related to the
electric field $E$ by:

$$
D = \epsilon E
$$

A light ray entering an anisotropic gemstone separates into two
sub-rays linearly polarized along orthogonal directions (see Figure
1), called ordinary ray, or $o$-ray, and extraordinary ray, or $e$-ray [Born and Wolf 1999]. These rays belong to the only two
categories of waves which are allowed to propagate in uniaxial crys-
tals, and have their own characteristics:

![Diagram of light ray propagation in a gemstone](image)

Figure 1: Formation of an ordinary and extraordinary ray when an
incident light ray encounters an anisotropic medium.

The two waves have respective directions of propagation $\mathbf{s}_o$ and
$\mathbf{s}_e$. The directions of polarization are such that for the $o$-ray, $\mathbf{D}_o$
vibrates perpendicular to the principal plane (i.e., along $\mathbf{X}_a(s_0)$), and
for the $e$-ray, $\mathbf{D}_e$ vibrates parallel to the principal plane (i.e., along
$\mathbf{Y}_a(s_e)$). The electric field of the $o$-ray is orthogonal to the direc-
tion of propagation $\mathbf{s}_o$ of its wave, whereas that of the $e$-ray is not, be-
cause $\epsilon \mathbf{E}_e$ is not collinear to $\mathbf{D}_e$. The energy propagation vectors of the two waves (i.e., the directions used for ray tracing) are thus
t $\mathbf{t}_o = \mathbf{s}_o$ and $\mathbf{t}_e \neq \mathbf{s}_e$.

The speed $v$ of the two rays can be computed from the speed $c$ of
light in vacuum, using [Born and Wolf 1999]:

$$
\frac{v^o}{c} = \frac{\gamma}{\gamma-1}, \quad \frac{v^e}{c} = \left(\frac{\gamma^2}{\gamma^2-1}\right)^{1/2}
$$

with $\cos \theta = \mathbf{a} \cdot \mathbf{e}$.

While the $o$-ray lies in the plane of incidence and obeys Snell’s
law, the transmitted $e$-ray does not. Its ray direction $\mathbf{t}_e$ can be computed
using the following formula [Beyerle and McDermid 1998] in which $\mathbf{n}$ is the interface normal and $n_1$ the refractive index of the
incident medium:

$$
\mathbf{t}_e = \frac{\gamma^2(n^2_s + (R-n^2_s)n^2_e)}{||\gamma^2(n^2_s + (R-n^2_s)n^2_e)||}
$$

(3)

Similar to refractions, internal reflections inside an anisotropic
crystal splits light waves into ordinary and extraordinary rays.
While the direction of the former obeys the classical rule of reflec-
tion, the direction of the $e$-ray obtained by internal reflection must
be computed using [Beyerle and McDermid 1998]:

$$
\mathbf{t}_e = \frac{\gamma^2(n^2_s + 2(s \cdot n^2)a^2)}{||\gamma^2(n^2_s + 2(s \cdot n^2)a^2)||}
$$

(4)

Finally, for a given wave refracting and reflecting at the interface
between the air and an anisotropic medium, we need to express the
Fresnel coefficients which permit us to compute the refracted and
reflected fields. This happens when light enters or exits a gemstone,
and depending on the case, reflected or refracted waves may either
be the sum of an ordinary and extraordinary rays, or a unpolarized
wave. We treat both cases at once by considering the interface between two anisotropic media. If one medium is isotropic, the waves in this medium are still the sum of two orthogonally polarized wave components and can thus be represented as a ‘o—ray’ and a ‘e—ray’ with the same direction of propagation with arbitrary choice of the ‘optical axis’ of the medium. We take the convention that subscripts t and r stand for transmitted and reflected fields, while o and e stand for ordinary and extraordinary.

Let $E_i$ be an incident linearly polarized wave of amplitude $E_i$, vibrating direction $e_i$, and speed $v_i = \frac{1}{\mu_i}$. We want to find the coefficients $\alpha_{oe}, \alpha_{eo}, \alpha_{ee}, \alpha_{oo}$ by which to multiply $E_i$ to obtain the amplitudes of the four reflected and refracted fields.

Maxwell theory requires that the tangential components of the total electric field and the magnetic field $\mathbf{H} = \frac{1}{\mu} \mathbf{E} \times \mathbf{E}$ be continuous across the surface (where $\mu$ is the magnetic permeability, supposed identical in both media):

$$n \times (E_i + E_r + E'_r + E'_o) = n \times (E_o + E'_o)
$$

$$n \times (H_i + H_r + H'_r + H'_o) = n \times (H_o + H'_o)$$

Let $e_o, e'_o, e_e, e'_e$ and $h_o, h'_o, h_e, h'_e$ be the respective vibrating directions of the electrical and magnetic fields. By expressing each component $E_i$ (resp. $H_i$) as $\alpha_{oe}E_o$ (resp. $\alpha_{ee}E_e$), with $h'_o = s_k \times e_o / (s_k \times e_o)$, and computing the dot product of these equations with two independent vectors $v_1$ and $v_2$ in the interface plane, one obtains [C.McClain et al. 1993]:

$$\begin{bmatrix}
-v_1 e_o - v_1 e'_e - v_1 e'_o - v_1 e_e \\
-v_2 e_o - v_2 e'_e - v_2 e'_o - v_2 e_e \\
-n_1 v_1 h_e - n_1 v_1 h'_e - n_1 v_1 h'_e - n_1 v_1 h_e \\
-n_2 v_2 h_e - n_2 v_2 h'_e - n_2 v_2 h'_e - n_2 v_2 h_e
\end{bmatrix}
\begin{bmatrix}
\alpha_{oe} \\
\alpha_{ee} \\
\alpha_{oo} \\
\alpha_{eo}
\end{bmatrix}
= \begin{bmatrix}
\alpha_{oe} \\
\alpha_{ee} \\
\alpha_{oo} \\
\alpha_{eo}
\end{bmatrix}$$

(5)

This linear system can be solved numerically. In the case of total reflection it should first be simplified into a 2x2 system by suppressing the $\alpha_{ee}$ and $\alpha_{oo}$ unknowns. Up to now $E_i$ has been supposed linearly polarized, which applies for e—rays and o—rays inside an anisotropic medium. If the incident medium is isotropic, the two solutions corresponding to setting $e_i$ orthogonal and then parallel to the incident plane gives the 8 needed coefficients. If both media are chosen isotropic, and if the ‘optical axis’ is set to be the normal of the interface, we have checked that the obtained solution corresponds to the well known Fresnel formulas given in Figure 2.

$$F'_r = \alpha_{oo} = -\sin (\theta_i - \theta_i) \sin (\theta_i + \theta_i)^{-1}
$$

$$F'_t = \alpha_{ee} = \tan (\theta_i - \theta_i) \tan (\theta_i + \theta_i)^{-1}
$$

$$F'_r = \alpha_{oo} = 1 + F'_r
$$

$$F'_t = \alpha_{ee} = (1 - F'_r) \cos \theta_i \cos \theta_i^{-1}
$$

Figure 2: Geometric configuration and Fresnel coefficients for a light ray refracting and reflecting at the interface between two isotropic media. The crossed coefficients $\alpha_{ee}, \alpha_{eo}, \alpha_{ee}, \alpha_{oo}$ are null in this particular case.

### 3.2 Absorption

As a general rule, a fraction of the light traveling inside a transparent material is absorbed. The absorption along a path $(x_0, x)$ is ruled by the Bouguer-Lambertian law [Wyszecki and Stiles 1982], giving the resulting intensity after a distance $d$:

$$I(x) = I_0(x_0) e^{-\kappa(x) d}
$$

$k$ is called the absorbance of the medium and depends on the wavelength. Absorption is responsible for the color of gemstones, and the absorbance spectrum acts as a tracer for the chemical nature, geographic source and applied treatments of a stone.

### 4 Adopted model

At this point of the paper, we discuss the importance and priorities that should be given to the phenomena previously described, keeping in mind a possible hardware implementation. In section 4.1 we justify our choices for representing color as three separate wavelengths, and examine in section 4.2 how light will be represented for each wavelength.

#### 4.1 Representation of color

Choosing a good representation of color is usually a compromise between visual accuracy of the result and a bulky set of coefficients.
Because the constraints of the hardware, we have chosen to work with 3 color components. Richer spectral rendering [Peercy 1993] could still be achieved by adding more passes and a final reconstruction, at the expense of rendering time [Sun et al. 1999].

We thus limit ourselves to spectral sampling, although the non linear relationship between absorbance and transmittance tends to saturate colors when darkening them [Sun et al. 1999]. Such an approximation on the facility to approach the attenuation by its linear counterpart is justified below.

One other important aspect of spectral sampling is to correctly choose the absorbance coefficients $\kappa_r$, $\kappa_g$, and $\kappa_b$ for the $R,G$ and $B$ channels. Directly reading spectral absorption coefficients from the spectral absorbance curve at the exact wavelengths of red (700.0nm), green (546.1nm) and blue (435.8nm) introduces significant errors due to peaks in the absorbance curve [Sun et al. 1999].

We thus need a way to extract significant enough absorbance values from the stone’s spectral absorbance curves. Inspired by existing approximations for reflectance [Borges 1991], we propose the following:

The $R,G,B$ color components perceived by human eye for a given spectrum $S$ are computed using the color matching functions $\tau$, $\varphi$ and $\beta$ of $\lambda$ [Wyszecki and Stiles 1982] by:

$$
\begin{bmatrix}
R \\
G \\
B
\end{bmatrix} = \int_{\lambda} \begin{bmatrix}
\tau(\lambda) \\
\varphi(\lambda) \\
\beta(\lambda)
\end{bmatrix} S(\lambda) d\lambda.
$$

Following Equation 6, a spectrum $S_0$ corresponding to white light will transform, after a path of length $x$, into:

$$
S(x,\lambda) = S_0(\lambda) e^{-\kappa(\lambda) x}
\quad \text{e.g., } R(x) = \int_{\lambda} \tau(\lambda) S_0(\lambda) e^{-\kappa(\lambda) x} d\lambda
$$

We are looking for an absorbance value $\kappa_r$ such that $R(x) = R(0) e^{-\kappa_r x}$ approximates equation 8 for small values of $x$. We thus take:

$$
\kappa_r = \frac{1}{R(0)} \int_{\lambda} \kappa(\lambda) \tau(\lambda) S_0(\lambda) d\lambda
\quad \text{using } R_0 = \int_{\lambda} \tau(\lambda) S_0(\lambda) d\lambda.
$$

Proceeding identically for the green and blue components we obtain suitable absorbance coefficients from the absorbance spectra, while avoiding artifacts of direct sampling of absorbance functions with peaks.

The error of the above approximation for $\kappa_r$, $\kappa_g$, $\kappa_b$ depends on the extent to which absorption differs from its linear approximation in Equation 9. The error is thus small because the diameter $L$ of the stone, times the absorbance $\kappa$ is small (the absorbance is computed piecewise between successive internal reflections of light). For typical values of $L = 1cm$ and $\kappa = 0.4$ for instance, we get an error of $\frac{e^{-\kappa L} - (1 - \kappa L)}{e^{-\kappa L}} = 0.00125\%$

### 4.2 Representation of monochromatic light

We adopt the formalism of coherency matrices [Glassner 1995; Wolf 1959] for representing the intensity and the polarization state of the electric field along a ray of light. The coherency matrix of a field $E = (e^{i} (t), e^{i*} (t))$ is defined as

$$
J = \begin{bmatrix}
< e^{i} e^{i*} & < e^{i} e^{i*} > \\
< e^{i} e^{i*} & < e^{i} e^{i*} >
\end{bmatrix} =< E E^* > = \begin{bmatrix}
J_{xx} & J_{xy} \\
J_{yx} & J_{yy}
\end{bmatrix}
$$

where $E$ is the complex representation of $E$, $E^*$ is the conjugate transpose of $E$, and $< u >$ denotes the mean value of $u$ over time. The intensity of the field is given by $I = J_{xx} + J_{yy}$. From this, the coherency matrix of an incoherent (non polarized) light ray of intensity $I_0$ is [Wolf 1959]:

$$
J_{\text{incoherent}} = \frac{1}{2} I_0 \begin{bmatrix}
1 & 0 \\
0 & 1
\end{bmatrix}
$$

For any linear transformation $M$ (also called a modifier matrix) applied to $E$, the corresponding coherency matrix becomes, from the definition of $J$, $J' = MJM^*$. It is thus possible to compute the matrix $J$ along a ray by applying successive modifier matrices corresponding to refraction and internal reflections on the faces of the gemstone, and rotations to account for the change in coordinate systems between two successive media interfaces. The matrices involved for refraction, reflection and rotation with an angle of $\theta$, are respectively:

$$
M' = \begin{bmatrix}
\alpha^R & \beta^R \\
\beta^R & \alpha^R
\end{bmatrix} \quad M'' = \begin{bmatrix}
\alpha^G & \beta^G \\
\beta^G & \alpha^G
\end{bmatrix} \quad R_0 = \begin{bmatrix}
\cos \theta & \sin \theta \\
-\sin \theta & \cos \theta
\end{bmatrix}
$$

In birefringent gemstones, the direction of the ordinary ray is easily computed using Snell’s law, but the intervention of a different direction for the extraordinary refracted and reflected rays make the computation cost grow exponentially with the depth of paths inside the stone. We computed the maximum angle between the $o$—ray and $e$—ray for all incidence angles in $[0, \pi/2]$ and any orientation of the optical axis, for common gemstones (zircon being an extreme case):

<table>
<thead>
<tr>
<th>Material</th>
<th>Zircon</th>
<th>Tourmaline</th>
<th>Sapphire</th>
<th>Emerald</th>
</tr>
</thead>
<tbody>
<tr>
<td>Angle (deg.)</td>
<td>2.328</td>
<td>0.767</td>
<td>0.45</td>
<td>0.324</td>
</tr>
<tr>
<td>Error</td>
<td>4.06 %</td>
<td>1.34 %</td>
<td>0.785 %</td>
<td>0.565 %</td>
</tr>
</tbody>
</table>

The “error” field gives the distance between the two images of an edge on the far side of the stone, as a fraction of the total size of the stone. For a 1cm Zircon, for instance, the two images would be 0.5mm apart: on a 1000-pixel image, this would 50 pixels, but this is the extreme case (by far). The validity of this approximation is confirmed by the photos of the tourmaline gemstones on Figures 3 and 11: no doubling of the edges seen by refraction is perceptible whereas in the orientation of the optical axis corresponds to a case of maximum deviation in Figure 3.

Computing Fresnel coefficients using Equation 5 can not conveniently be implemented in graphics hardware. Contrariwise, Fresnel coefficients at the interface of two isotropic media (given in Figure 2) can be tabulated very efficiently. Because $o$—rays and $e$—rays propagate along close directions and have orthogonal polarization, the generalized Fresnel coefficients are very close to the isotropic ones when the difference $n_e - n_o$ is small, if expressed into the same coordinate systems. Let $R_0$, $R_1$, $R_2$ be the rotation matrices which align the coordinate systems for the isotropic Fresnel coefficients of Figure 2 to the corresponding implicit coordinate systems of the general Fresnel coefficients of equation 5 in the coordinate system on the principal planes (Equation 2). We have:

$$
M' \approx R_{0} \begin{bmatrix}
F_{1} & 0 \\
0 & F_{1}
\end{bmatrix} R_{0} \quad \text{and} \quad M'' \approx R_{0} \begin{bmatrix}
F_{1} & 0 \\
0 & F_{2}
\end{bmatrix} R_{0}.
$$

Equality holds when $n^e = n^o$. For instance let’s consider the case of a ray entering an anisotropic medium of optical axis $a$ from an isotropic medium. $n$ is the interface normal and $s_i$ the propagation vector of the transmitted wave. Generalized Fresnel coefficients already relate the reflected field to the incident field in the same co-ordinate system than in the isotropic case, but the transmitted field is expressed in the coordinate system with the orthogonal vibrating direction given by $a \times s$, so one should take:

$$
\theta_i = 0, \quad \theta_r = 0, \quad \theta = n \times s_i \cdot a \times s_i, \quad \sin \theta_i = n \times s_i \times (a \times s_i)
$$

The proposed approximation works very well, even on zircon, as illustrated on figure 4.
The facet tree at depth $n_i$ corresponds to the intersection of a beam traced from the viewpoint through a front face of the gemstone, the linear approximation proposed by Heckbert for beam tracing [Heckbert and Hanrahan 1984]. To each facet is thus associated an active contribution representing refraction through a front face of the gemstone, the linear approximation proposed by Heckbert for beam tracing [Heckbert and Hanrahan 1984].

Conversely, the change in absorption due to the polarization of rays with respect to the optical axis of the stone dramatically affects the rendering color and should not be neglected (see Figure 3).

Because the waves along the $o$–ray and the $e$–ray are polarized orthogonally to each other, we can represent them using a single coherency matrix in the coordinate system based on the ordinary and extraordinary vibration directions and their suppositions on the direction of propagation $s$. In this coordinate system, the matrix of a wave propagating inside the crystal is therefore diagonal, and is attenuated by a diagonal modifier matrix depending on the direction of propagation, using the attenuation coefficients of Equation 7:

$$A(s) = \begin{bmatrix} e^{-\kappa_s/2} & 0 \\ 0 & e^{-\kappa_t/2} \end{bmatrix}$$

(11)

In the case of isotropic crystals (e.g., diamonds, garnets) the matrix $A(s)$ becomes identity times the attenuation given by Equation 6.

5 Rendering algorithm

Figure 5 shows the path of the light obtained by tracing a ray from the eye to a point on the stone. To compute the resulting intensity $I_0$ along such a path, we need to add the contributions of light at each interface $P_k$ between the stone and the air, and accounting for attenuation $A_{k,k+1}$ along segments $[P_k,P_{k+1}]$ inside the stone. Denoting by $J_k$ the coherency matrix of the light from point $P_k$ in the path, we have:

$$J_0 = M_0^e M_0^i A_{0,0} I_0$$

$$J_k = M_k^e J_{k-1}^e M_k^i + M_k^i A_{k,k+1} J_{k+1}^e A_{k+1,k+2}^e$$

For rendering a gemstone using classical ray tracing, one would collect these contributions from back to front (i.e., at $P_0, P_{n-1}$ and finally $P_1$), transforming rays at each successive interface to account for refraction, external reflection, or internal reflections encountered along the path.

Our hardware-based algorithm relies on the fact that, for a given depth $k$, the set of points $P_k$ that contribute to the image through the same succession of transformations, can be rendered at the same time using a fragment program. Such a set is called a facet. We regroup facets in a tree structure called the facet tree. Each node of the facet tree at depth $k$ contains a product of $k$ transformations and a region of points included in one face of the gemstone.

Rendering a gemstone from a given viewpoint thus requires for each frame to (1) build the facet tree corresponding to current viewpoint and (2) accumulate contributions of all facets of the facet tree, from back to front, using a fragment program. The lighting environment used for rendering gemstones is stored in a cube-map [NVIDIA Corporation 2000]. As illustrated in the result section, rendering gemstones needs to deal with high dynamic range lighting and rendering. All computations are thus performed with floating point values and a final tone reproduction pass (3) turns the result of pass (2) into a 8–bits rbg image. Pass (1), (2) and (3) are detailed in Sections 5.1, 5.2 and 5.3.

When changing the viewpoint the facet tree changes and must therefore be updated. This means that not only the viewpoint, but also the geometry of the gemstone as well as its physical parameters (refractive indices, orientation of optical axis, attenuation) can arbitrarily be changed during rendering, at the same cost.

5.1 Pass 1: construction of the facet tree

Because refraction is not in general a linear transform, the facets as defined above are not polygons. However the nonlinearity does not noticeably affect the refracted images of short segments such as the edges of a gemstone, as shown on figure 6, and we adopt, for representing refraction through a front face of the gemstone, the linear approximation proposed by Heckbert for beam tracing [Heckbert and Hanrahan 1984]. To each facet is thus associated a fictive viewpoint. Note however, that when we render the facet tree, the refraction direction of incoming light $I_0$ at point $P_{k=0}$ will be computed exactly by the fragment shader. Approximations of refraction only affect the point $P_0$.

Figure 6: Left: image computed using exact refraction with our ray tracer. Center: image computed with graphics hardware algorithm and linearized refraction. Right: difference image.

Thanks to this approximation and to the linearity of internal reflections on the gemstone faces, each facet is an actual polygon and a subset of a single face of the gemstone. We compute facets with the OpenGL feedback buffer using the following algorithm:

At level 0 of the tree the facets are the faces of the gemstone polyhedron directly seen from the viewpoint. At level 1 the child facets of level 0 facet $f_0^0$ correspond to the intersection of a beam traced from the viewpoint through $f_0^0$ with the gemstone transformed by refraction. At subsequent levels the gemstone is further transformed
by reflection through the support face of the parent facet and clipped with this facet.

The window coordinates of each facet are computed by rendering the initial geometry of the gemstone (stored in a display list) into the OpenGL feedback buffer [Neider et al. 1993], using the appropriate viewpoint and transformation, while inserting clipping planes corresponding to the edges of the parent facet as shown on Figure 7.

Figure 7: Construction of the facet tree, using a fictive viewpoint for linearized refraction and successive symmetries for internal reflections. For level \( k \) the gemstone model is transformed through reflection/refraction around the support plane of the parent facet, then drawn in the OpenGL feedback buffer, and clipped by the edges of the parent facet. The resulting mesh is displayed on the right, using the same color for facets of the same level.

To minimize costly access to the feedback buffer, the facet tree is constructed breadth-first. The depth of the tree is limited by three conditions: (1) the total path length to a facet attenuates light strongly enough to reduce the resulting intensity under a fixed value; (2) the area of the facet is smaller than a user defined threshold; (3) the computation time down to the current level exceeds the frame-rate limit.

Because refraction indices depend on wavelengths, the facet tree should not be the same for the red, green and blue components. Depending on the intensity of dispersion, we compute either one single facet tree corresponding to an average refractive index, or three distinct facet trees, at the expense of frame rate. However, the fragment shader which computes the refraction of light at points \( P_{1-n} \) still uses the correct indices of refraction. We thus still achieve in the worst case an approximation of dispersion effects, as shown on Figure 8.

Figure 8: Image of a highly dispersive stone, computed using exact refraction with our ray trace(top left) and with our hardware algorithm with one facet tree (top right). Left: a difference image shows that some –but not all, as explained in the text– rainbow effects are missed by our algorithm in this case.

For a given maximum depth, fully building the facet tree is not in fact necessary: during this operation, we estimate the cumulative effect of attenuation and Fresnel coefficients for a single point on each facet down to the next level. We locally prune the construction if the contribution of next facet will be less than a threshold in percentage to the accumulated energy before the current facet. Section 6.2 shows a practical example of this.

5.2 Pass 2: rendering the facet tree

We implemented and tested the rendering algorithm of the facet tree on a NVidia GeForce FX 5900 using Cg programming [Lindholm et al. 2001].

Figure 9 summarizes our implementation: the facet tree is traversed breadth-first, by decreasing order of level. At a given level \( k > 0 \), a \( P \)-buffer is filled with the result of the internal reflection fragment program, which computes the exact refraction of light entering the gemstone from the cube-map, as well as the internal refraction of the contribution of level \( k+1 \) stored in the accumulation buffer. The combined result is copied to the accumulation buffer for level \( k-1 \). At level 0 the external reflection fragment program is used instead, for adding the result of the previous calls seen by refraction, with the light reflecting on the faces directly visible. Both fragment programs compute the attenuation using Equations 7 and 11. The path length is obtained by subtracting the distance from the fictive viewpoint to the current pixel (c.f. Figure 7) to that of the pixels in the previous result. The Fresnel coefficients are computed using equation 10, from the formulas of Figure 2, tabulated in 1D float textures.

5.3 Pass 3: tone reproduction

Tone reproduction is achieved entirely in hardware using a publicly available shader of Industrial Light+Magic [Bogart et al. 2003], to display floating point images stored in the OpenEXR format. Such an approach makes comparisons between ray-traced images, pictures of gemstones, and images rendered using the hardware method very convenient, since the first two are produced in OpenEXR format and displayed using the same shader as the one used in the hardware implementation. We also tested hardware based glare effect [Spencer et al. 1995;Debevec 1998] on our HDR images with success, as in the teaser on page 1, and the diamond on Figure 11. Glare effect was not used anywhere else in the paper, to prevent masking important artifacts and details of the method.
6 Results

6.1 Modus operandi

The work presented may seem hard to reproduce without a clear road map, which we give here.

Using the reference ray tracing algorithm requires working with coherency matrices. Directions of the ordinary reflected and transmitted \( o \)-rays can be computed using Snell’s law, while those of the \( e \)-rays are given by Equations 3 and 4. Absorption is computed by Equations 7 and 11. General Fresnel coefficients at each interface are obtained by solving the 4x4 linear system in Equation 5.

Our hardware based algorithm differs from a standard ray tracer in that ray directions always follow Snell’s law; Fresnel coefficients are obtained using Equation 10, and refraction is linearized as explained in Section 5.1.

Both methods use equation 12 for composing coherency matrices at media interfaces, and use the same set of parameters, as described in the following three paragraphs:

**System parameters** We detail in the table below the parameters we used for our experiments. One needs the nature of the medium (‘I’=isotropic, ‘U’=birefringent uniaxial, ‘B’=biaxial) and the refractive indices \( n_o \) and \( n_e \) when applicable. Values are indicated for the green channel whereas red and blue are obtained after adding or subtracting the value after \( \pm \) (half the dispersion value found in usual tables). Tricolored absorbance values are computed using Equation 9 from the absorbance spectra of each stone\(^1\).

<table>
<thead>
<tr>
<th>Gemstone</th>
<th>Type</th>
<th>(( K_r, K_g, K_b ))</th>
<th>Colors</th>
<th>( a_{pe} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>Garnet</td>
<td>I</td>
<td>(0.136, 0.153, 0.175)</td>
<td>orange-red</td>
<td>1.730 ± 0.14</td>
</tr>
<tr>
<td>Tourmaline (Dravite)</td>
<td>U</td>
<td>(0.033, 0.034, 0.082), (0.010, 0.076, 0.015),</td>
<td>yellow green, blue green</td>
<td>1.642 ± 0.01</td>
</tr>
<tr>
<td>Peridot</td>
<td>B</td>
<td>(0.023, 0.015, 0.051), (0.011, 0.003, 0.028),</td>
<td>green, yellow green</td>
<td>1.680 ± 0.01</td>
</tr>
<tr>
<td>Diamond</td>
<td>I</td>
<td>(0.001, 0.001, 0.001), (0.032, 0.270, 0.156), (0.016, 0.147, 0.185),</td>
<td>white, light blue, violetish blue</td>
<td>2.410 ± 0.022</td>
</tr>
<tr>
<td>Sapphire</td>
<td>U</td>
<td>(0.0056, 0.006, 0.0183), (0.170, 0.175, 0.257),</td>
<td>greenish red, yellowish green</td>
<td>1.635 ± 0.005</td>
</tr>
</tbody>
</table>

**Geometric models** Models of standard gemstone cuts are readily available on the internet\(^2\). However, problems arise when a particular gemstone needs to be simulated, as in our comparisons with photographs. While expensive gemstones (e.g., very clear and fine quality stones) tend to be cut using very precise standards, more affordable pieces often display an constraint such as avoiding inclusions. Laser-scanning gemstones is not applicable due to both their size and specularity. We also tried X-ray tomography with very poor results.

The solution we used is based on manually designing the mesh and applying an iterative relaxation algorithm on vertex positions so as to fit symmetries, distance and planarity constraints measured on the stones. This works well provided that the hand-designed mesh is not too far from the real object. The model at right was designed that way and corresponds to the tourmaline of Figure 11.

**Acquisition of light** We used traditional methods for acquiring cube-maps. Photographs of a mirrored ball were taken along two orthogonal directions and using a set of 10 different exposures. Each set is first converted into a HDR image in Radiance format. The two HDR images are combined using HDRShop\(^{TM} \) (www.debevec.com/HDRShop), and the result saved as a cube-map. We proceed identically to obtain HDR images of sample gemstones in the same lighting environment.

6.2 Additional validation tests

**Computation times** In Figure 10 we present the computation times (in ms) and the numbers of facets in the resulting facet trees for two different models. This experiment shows that cleverly pruning the facet tree makes the computation more efficient. Typical framersates for less complex models (40 to 80 facets), in a 800 × 600 window, range from 12 to 30 fps at depths 2 and 3.

**Comparison to real images** On the top-right of Figure 11 one can see a comparison between a simulated tourmaline and a picture of a real one. The simulation was performed using the absorbance values and the geometric model displayed in Section 6.1, and captured lighting conditions.

Because it was impossible to precisely duplicate the geometry of the gems and the lighting conditions, and because the appearance of gems is very sensitive to both, one cannot expect a pixel-by-pixel correspondence between the images; one can, on the other hand, evaluate the phenomenological similarities and differences quite well. Both images display a change in color along the axis (oriented at approximately 60° in the image plane) hence the bluish tint on the bottom of each image (this effect, also seen on stones (e),(f) and (g) proves the need to account for birefringency in the simulation). Color ranges are quite similar, as well as flash effects (from a qualitative point of view) thanks to the HDR rendering.

However one can complain that the luster of the stone (responsible for the iridescent colors on the top faces in the photography)
is not simulated, which would be a challenging problem to solve using graphics hardware.

7 Conclusion

We have presented a solution for rendering faceted colored gemstones based on the analysis of optical phenomena, their simplification and their adaptation to a hardware-based implementation. We have shown – we think for the first time – that it is possible to obtain some very visually pleasant and mostly physically correct approximations of the real phenomena.

Our implementation benefits from the high level programming of today’s graphic cards [Mark et al. 2003], which allows a comprehensive and portable implementation. Moreover, the rendering speed of our system offers new possibility for observing gemstones: not only the viewpoint can be changed in real time, but also the stone physical properties and geometry.

Our model can easily be extended to biaxial media. Other important features of gemstones, such as inclusions, color zoning and luster would be interesting to incorporate as well.

Acknowledgments

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References


