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A time domain analysis of PML models in acoustics.

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Abstract

We present in this paper a time-domain analysis of PML's for non-advective and advective acoustics. We focus our attention on time-stability and error estimates (with respect to the parameters of the layers). The main new technical tool is the Cagniard-de Hoop method. Our theoretical results are validated and illustrated by various numerical results.

Key words: Perfectly Matched Layers; Acoustics; Stability; Error Estimates; Cagniard-de Hoop.

PACS:

The PML technique for the numerical absorption of waves, initially introduced about ten years ago by Bérenger [1] in electromagnetism, is now widely used for simulating the propagation of waves in unbounded domains, in particular in time domain acoustics [2–8].

From the mathematical point of view, much work has been devoted to the stability analysis of the PML model [9,10]. The question of the accuracy of PML's in time domain is much less discussed. Existing results mainly concern the plane wave analysis [4,11] (reflection of plane waves at the artificial boundary) or convergence results in the time harmonic regime [12–14].

The object of the present paper is to regroup some results obtained by the two authors concerning the time domain analysis for acoustic wave propagation models.

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In section 1, we first derive an error analysis for the PML for non advective acoustics. This work is a continuation of [15] that concerned absorbing boundary conditions. The main point is the derivation of an explicit solution using the Cagniard-De Hoop technique [16–18]. Our results show the exponential accuracy of PML’s with respect to the damping factor σ and the width L of the layer.

Section 2 is devoted to classical PML’s for advective acoustics: the propagation of waves in the presence of a uniform mean flow is modeled by linearized Euler equations. We revisit the well-known instability of standard PML’s by the Cagniard-De Hoop technique.

In section 3, we are concerned by the question of the stabilization of PML’s for advective acoustics when the flow is orthogonal to the artificial boundary. We proposed a stable PML (already introduced in [19]) which consists, in a first step, of sticking to the physical domain a non advective propagation model designed in such a way that no reflection is produced at the interface between the physical domain and the artificial one (this is the "PML property"), and in a second step, of using standard PML’s for the artificial domain. We derive the stability and accuracy analysis for this new PML.

Our theoretical results are illustrated by various numerical results. Of course the present work has to be compared with some recent ones in the literature, in particular by Hagström and Nazarov [20], Abarbanel, Gottlieb and Hesthaven [21] and more specially by Hu [22] whose work on stabilized PML for advective acoustics appears to be close to what we are doing in this paper as it will be briefly discussed in the last section of this paper.

An appendix is devoted to a partial solution to the problem of constructing stable PML’s in the case of an oblique (with respect to the boundaries of the rectangular computational domain) mean flow.

1 PML for acoustics

Let us consider the two dimensional wave equation

$$\frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} - \Delta u = f(\mathbf{x}, t), \quad \mathbf{x} = (x_1, x_2) \in \mathbb{R}^2, \quad t > 0. \quad (1)$$

If the initial data of the problem and the domain of interest are supported in the left half-space

$$\mathbb{R}_-^2 = \mathbb{R}_- \times \mathbb{R}$$

it is natural to try to reduce the computation to this half-space. There are two main classes of method to do so. The first ones are the so-called absorbing

boundary condition, whose principle consists in imposing a specific condition on the boundary designed so that the waves leave the computational domain without being (too much) reflected. Another way to bound the computational domain consists in adding a vertical layer where (1) is modified by an absorption term (see figure 1). In [1,6], Bérenger proposed to introduce a very special

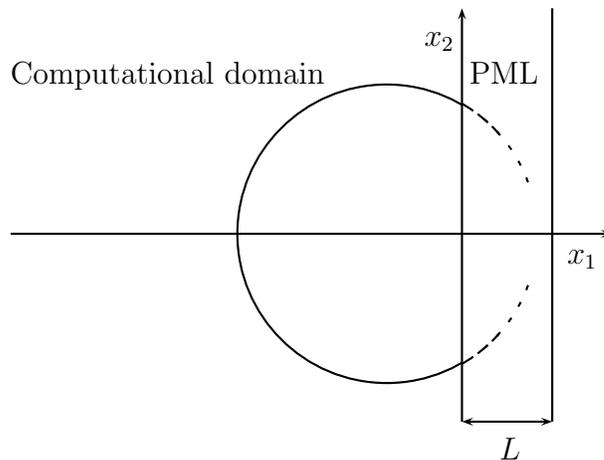


Fig. 1. Computational domain and Perfectly Matched Layer

anisotropic damping term acting only in the direction which is orthogonal to the interface. An alternative to the original split form of its model (see section 2) consists in replacing the derivation with respect to x_1 by the operator $D_{x_1}^\sigma$ formally defined by :

$$D_{x_1}^\sigma = \left(\frac{\partial}{\partial t} + \sigma(x_1) \right)^{-1} \frac{\partial}{\partial t} \frac{\partial}{\partial x_1},$$

where σ is a non-negative function of x_1 .

More rigorously $\psi = D_{x_1}^\sigma \phi$ means :

$$\left(\frac{\partial}{\partial t} + \sigma(x_1) \right) \psi = \frac{\partial}{\partial t} \frac{\partial}{\partial x_1} \phi \quad \text{and} \quad \psi(t = 0) = 0.$$

The equation in the PML then becomes :

$$\frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} - (D_{x_1}^\sigma)^2 u - \frac{\partial^2 u}{\partial x_2^2} = 0, \quad \mathbf{x} = (x_1, x_2) \in [0 ; L] \times \mathbb{R}, \quad t > 0. \quad (2)$$

The most interesting property of the PML is that a wave propagating in the computational domain is transmitted to the absorbing layer without being reflected. As this method is moreover really easy to implement (even in the corners of the domain), it has rapidly attracted a lot of people in different fields of application.

The case of an infinite PML. We are first interested in the explicit expression of the fundamental solution $u^{\sigma, \infty}$ of the wave equation in the left half space \mathbb{R}_-^2 with an infinite PML in the right half-space. $u^{\sigma, \infty}$ satisfies :

$$\left\{ \begin{array}{l} \text{Find } u : \mathbb{R}^2 \times \mathbb{R}_+ \mapsto \mathbb{R}, \text{ null for } t < 0 \quad \text{such that} \\ \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} - (D_{x_1}^\sigma)^2 u - \frac{\partial^2 u}{\partial x_2^2} = \delta(\mathbf{x} - \mathbf{x}_S) \times \delta(t), \quad \text{in } \mathbb{R}^2 \times \mathbb{R}_+. \end{array} \right. \quad (3)$$

where $\mathbf{x}_S = (-h, 0)$, $\sigma(x_1) = 0$ if $x_1 \leq 0$ and $\sigma(x_1) > 0$ if $x_1 > 0$.

Let us define $r(\mathbf{x}) = |\mathbf{x} - \mathbf{x}_S|$ and the function $\theta(\mathbf{x})$ by :

$$\theta(\mathbf{x}) \in]0, 2\pi], \quad \mathbf{x} - \mathbf{x}_S = (r(\mathbf{x}) \cos \theta(\mathbf{x}), r(\mathbf{x}) \sin \theta(\mathbf{x}))^t,$$

and the function $\Sigma(x_1)$ by : $\Sigma(x_1) = \int_0^{x_1} \sigma(x) dx$. The functions $A(\mathbf{x}, t)$ and $B(\mathbf{x}, t)$ are defined by ($r = r(\mathbf{x})$ and $\theta = \theta(\mathbf{x})$) :

$$A(\mathbf{x}, t) = |\cos \theta| \frac{\Sigma(x_1) t}{r} > 0 \quad \text{and} \quad B(\mathbf{x}, t) = |\sin \theta| \Sigma(x_1) \sqrt{\frac{t^2}{r^2} - \frac{1}{c^2}}.$$

Theorem 1 *The expression of the solution $u^{\sigma, \infty}(\mathbf{x}, t) = G_i^{\sigma, \infty}(\mathbf{x}, t)$ of problem (3) is given by :*

$$\left\{ \begin{array}{l} G_i^{\sigma, \infty}(\mathbf{x}, t) = \frac{H(ct - r(\mathbf{x}))}{2\pi \sqrt{t^2 - \frac{r(\mathbf{x})^2}{c^2}}}, \quad x_1 \leq 0 \\ G_i^{\sigma, \infty}(\mathbf{x}, t) = \frac{H(ct - r(\mathbf{x}))}{2\pi \sqrt{t^2 - \frac{r(\mathbf{x})^2}{c^2}}} e^{-A(\mathbf{x}, t)} \cos[B(\mathbf{x}, t)], \quad x_1 > 0. \end{array} \right. \quad (4)$$

where H denotes the Heaviside function

Remark 2 *The restriction of $G_i^{\sigma, \infty}(\mathbf{x}, t)$ to the left half-space \mathbb{R}_-^2 does not depend on σ and is nothing more than the restriction to the left half-space of the fundamental solution of the wave equation in the whole plane : the infinite PML does not produce any parasitical reflection.*

The case of a finite PML. We now consider a PML of finite width L with

a Neumann condition at its bottom end. Problem (3) then becomes :

$$\left\{ \begin{array}{l} \text{Find } u : \mathbb{R}^2 \times \mathbb{R}_+ \mapsto \mathbb{R}, \text{ null for } t < 0 \quad \text{such that} \\ \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} - (D_{x_1}^\sigma)^2 u - \frac{\partial^2 u}{\partial x_2^2} = \delta(\mathbf{x} - \mathbf{x}_S) \times \delta(t), \quad \text{in } [-\infty ; L] \times \mathbb{R} \times \mathbb{R}_+, \\ \frac{\partial u}{\partial x_1}(L, x_2, t) = 0. \end{array} \right. \quad (5)$$

We define the image point source, symmetrical to the point source with respect to the line $x_1 = L$ by :

$$\mathbf{x}_S^* = (h + 2L, 0),$$

we denote $r^*(\mathbf{x}) = |\mathbf{x} - \mathbf{x}_S^*|$ and we define the function $\theta^*(\mathbf{x})$ by :

$$\theta^*(\mathbf{x}) \in \left] \frac{\pi}{2}, \frac{3\pi}{2} \right], \quad \mathbf{x} - \mathbf{x}_S^* = (r^*(\mathbf{x}) \cos \theta^*(\mathbf{x}), r^*(\mathbf{x}) \sin \theta^*(\mathbf{x}))^t.$$

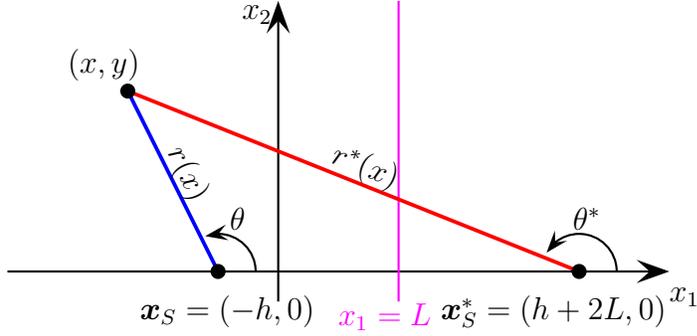


Fig. 2. Illustration of the notation

We also define the function $\Sigma^*(x_1)$ by :

$$\Sigma^*(x_1) = \int_0^L \sigma(x) dx + \int_{x_1}^L \sigma(x) dx \quad (= 2\Sigma(L) \text{ for } x_1 < 0),$$

and the functions $A^*(\mathbf{x}, t)$ and $B^*(\mathbf{x}, t)$ by ($r^* = r^*(\mathbf{x})$ and $\theta^* = \theta^*(\mathbf{x})$) :

$$A^*(\mathbf{x}, t) = |\cos \theta^*| \Sigma^*(x_1) \frac{t}{r^*} > 0 \quad \text{and} \quad B^*(\mathbf{x}, t) = |\sin \theta^*| \Sigma^*(x_1) \sqrt{\frac{t^2}{r^{*2}} - \frac{1}{c^2}}.$$

Theorem 3 *The expression of the solution $u^{\sigma,L}(\mathbf{x}, t) = G^{\sigma,L}(\mathbf{x}, t)$ of problem (5) is given by :*

$$G^{\sigma,L}(\mathbf{x}, t) = G_i^{\sigma,\infty}(\mathbf{x}, t) + G_r^{\sigma,L}(\mathbf{x}, t)$$

with

$$G_r^{\sigma,L}(\mathbf{x}, t) = \frac{H(ct - r^*(\mathbf{x}))}{2\pi \sqrt{t^2 - \frac{r^{*2}(\mathbf{x})}{c^2}}} e^{-A^*(\mathbf{x}, t)} \cos [B^*(\mathbf{x}, t)]. \quad (6)$$

This theorem can easily be deduced from theorem 1 thanks to the image principle. Therefore, only theorem 1 will be proved in this paper.

Error Estimates. Let us consider the approximation, in the upper half-space, of the solution u of problem (1) (the wave equation with a “regular” point source), by the function $u^{\sigma,L}$, solution of problem :

$$\left\{ \begin{array}{l} \text{Find } u^{\sigma,L} : \mathbb{R}^2 \times \mathbb{R}_+ \mapsto \mathbb{R}, \text{ null for } t < 0 \quad \text{such that} \\ \frac{1}{c^2} \frac{\partial^2 u^{\sigma,L}}{\partial t^2} - (D_{x_1}^\sigma)^2 u^{\sigma,L} - \frac{\partial^2 u^{\sigma,L}}{\partial x_2^2} = \delta(\mathbf{x} - \mathbf{x}_S) \times f(t), \text{ in } [-\infty; L] \times \mathbb{R} \times \mathbb{R}_+, \\ \frac{\partial u^{\sigma,L}}{\partial x_1}(L, x_2, t) = 0. \end{array} \right. \quad (7)$$

After having defined the function $\Phi(t)$, null for $t < (h + 2L)/c$, by :

$$\left\{ \begin{array}{l} \Phi(t) = \text{Log} \left(\frac{t + \sqrt{t^2 - ((2L + h)/c)^2}}{((2L + h)/c)} \right), \text{ if } \frac{h + 2L}{c} \leq t \leq \frac{h + 2L}{c} + T, \\ \Phi(t) = \text{Log} \left(\frac{t + \sqrt{t^2 - (t - T)^2}}{t - T} \right), \text{ if } t > \frac{h + 2L}{c} + T. \end{array} \right.$$

we can state the

Theorem 4 *One has the uniform estimates :*

$$\|(u - u^{\sigma,L})(\cdot, t)\|_{L^\infty(\mathbb{R}_-^2)} \leq \frac{e^{-2\frac{2L+h}{c^2 t} L \bar{\sigma}}}{2\pi} \Phi(t) \|f\|_{L^\infty}. \quad (8)$$

where $\bar{\sigma} = \frac{1}{L} \int_0^L \sigma(x) dx$ is the mean value of σ in the PML.

This result appeals the following comments :

- The error converges spectrally to 0 (in the uniform norm) when $\bar{\sigma}$ (or L) goes to infinity.
- For given t , the upper bound in the estimate diminishes when the distance h from the source to the absorbing layer increases. This is coherent with the physical intuition and numerical observations.
- Concerning the behavior of the error for large t , if we assume that $T < +\infty$, we observe that the right hand side in the estimate behaves for large t as

$$\frac{1}{2\pi} \sqrt{\frac{2T}{t}},$$

which shows that, for all $\bar{\sigma}$, L and h , the error converges uniformly to 0 when t tends to $+\infty$.

- As the plane wave analysis might suggest, the shape of the function $\sigma(x_1)$ does not influence the estimates, only its mean value between 0 and L has an importance.
- We could have imagined, once again from the plane wave analysis, that $\bar{\sigma}$ and L did play the same role (i.e. increasing L is equivalent to increasing $\bar{\sigma}$), but the uniform estimates show that increasing L allows us, not only to increase the absorption thanks to the term $L \bar{\sigma}$, but also to move away the point source from the absorbing layer thanks to the term $2L + h$.

The case of a rectangular domain surrounded by PML. One of the advantages of PML when compared to absorbing boundary conditions (ABC's) is the simplicity of their implementation in the corner. By the principle of images and Cagniard-de Hoop method, it is also easy to compute the analytical solution in the case of a rectangular domain surrounded by PML's (whereas it is not possible with ABC's).

We now suppose that the computational domain Ω is the square $[-h; h]^2$ and is surrounded by PML's of width L . We impose a Neumann condition at the end of the layers. We then consider the problem :

$$\left\{ \begin{array}{ll} \text{Find } u : \mathbb{R}^2 \times \mathbb{R}_+ \mapsto \mathbb{R} & \text{such that} \\ \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} - (D_{x_1}^\sigma)^2 u - (D_{x_2}^\sigma)^2 u = \delta(\mathbf{x}) \times \delta(t), \text{ in } [-L; L]^2 \times \mathbb{R}_+, & \\ \frac{\partial u}{\partial x_1}(\mathbf{x}, t) = 0, & \text{for } x_1 = \pm L \\ \frac{\partial u}{\partial x_2}(\mathbf{x}, t) = 0, & \text{for } x_2 = \pm L, \\ u(\mathbf{x}, t) = 0, & \text{for } t < 0. \end{array} \right. \quad (9)$$

Let us define the image points source $(\mathbf{x}_{ij})_{(i,j) \in \mathbb{Z}^2}$ as

$$\mathbf{x}_{ij} = (2i(h + L), 2j(h + L)).$$

We set $r_{ij}(\mathbf{x}) = |\mathbf{x} - \mathbf{x}_{ij}|$ and we define the functions $\theta_{ij}(\mathbf{x})$ by :

$$\theta_{ij}(\mathbf{x}) \in] - \pi, \pi], \quad \mathbf{x} = (r_{ij}(\mathbf{x}) \sin \theta_{ij}(\mathbf{x}), r_{ij}(\mathbf{x}) \cos \theta_{ij}(\mathbf{x}))^t,$$

and the non-negative functions $(\Sigma_i(x))_{i \in \mathbb{Z}}$ by :

$$\begin{cases} \Sigma_i(x) = (2i - 1) \int_0^L \sigma(x) dx + \int_{-L}^x \sigma(x) dx & \text{if } i < 0, \\ \Sigma_i(x) = (2i - 1) \int_0^L \sigma(x) dx + \int_x^L \sigma(x) dx & \text{if } i > 0, \\ \Sigma_0(x) = \left| \int_0^x \sigma(x) dx \right|. \end{cases}$$

Finally we define the functions $A_{ij}(\mathbf{x}, t)$ and $B_{ij}(\mathbf{x}, t)$ by :

$$A_{ij}(\mathbf{x}, t) = (|\cos \theta_{ij}(\mathbf{x})| \Sigma_j(x_2) + |\sin \theta_{ij}(\mathbf{x})| \Sigma_i(x_1)) \frac{t}{r_{ij}(\mathbf{x})} > 0$$

and

$$B_{ij}(\mathbf{x}, t) = (|\cos \theta_{ij}(\mathbf{x})| \Sigma_i(x_1) + |\sin \theta_{ij}(\mathbf{x})| \Sigma_j(x_2)) \sqrt{\frac{t^2}{r_{ij}(\mathbf{x})^2} - \frac{1}{c^2}}.$$

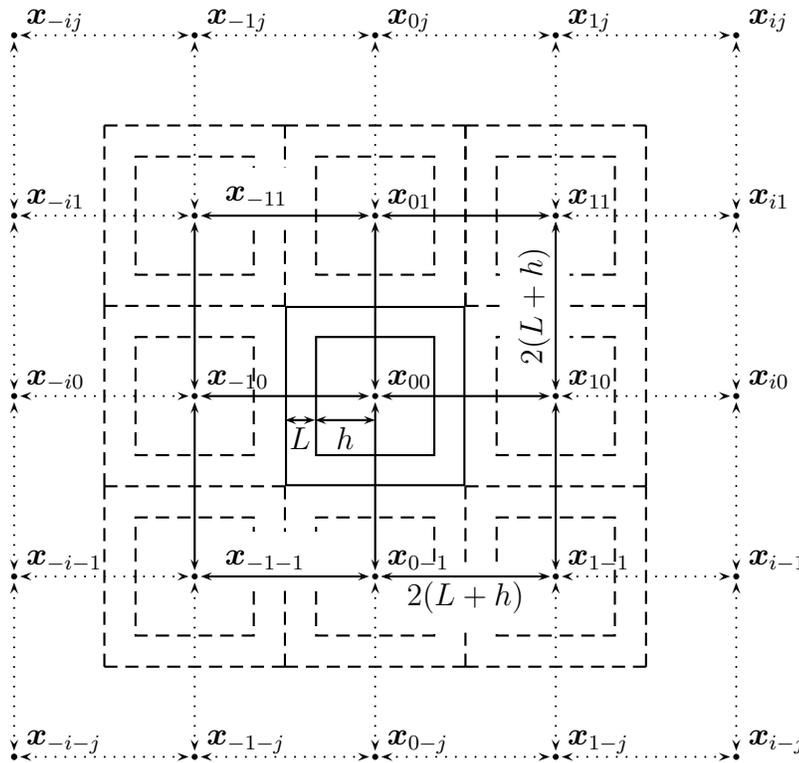


Fig. 3. The image points source

Theorem 1.1 *The solution $u^{\sigma, h, L}(x, t) = G^{\sigma, h, L}(\mathbf{x}, t)$ of problem (9) is given by :*

$$G^{\sigma, h, L}(\mathbf{x}, t) = \sum_{(i, j) \in \mathbb{Z}^2} G_{i, j}^{\sigma, h, L}(\mathbf{x}, t)$$

where

$$G_{ij}^{\sigma,h,L}(\mathbf{x}, t) = \frac{H(ct - r_{ij}(\mathbf{x}))}{2\pi\sqrt{t^2 - \frac{r_{ij}(\mathbf{x})^2}{c^2}}} e^{-A_{ij}(\mathbf{x},t)} \cos[B_{ij}(\mathbf{x}, t)]. \quad (10)$$

Remark 5 For given t and \mathbf{x} , $G^{\sigma,h,L}(\mathbf{x}, t)$ is a finite sum. Indeed if i and j are such that $r_{ij}(\mathbf{x}) < ct$, then $G_{ij}^{\sigma,h,L}(\mathbf{x}, t)$ is null.

We do not present here the details of the proof which is very similar to the half-plane case, we refer the reader to [23] for details.

1.2 Proof of the theorems

Expression of the Green's function. Let $G_i^{\sigma,\infty}(\mathbf{x}, t)$ be the solution of problem (3). The first step of the Cagniard-de Hoop's method consists in applying successively to $G_i^{\sigma,\infty}(\mathbf{x}, t)$ the Laplace transform in time and the Fourier transform in the space variable x_2 (we denote by s (resp. k) the dual variable of t (resp. x_2)). The resulting function $x_1 \mapsto \widehat{G}_i^{\sigma,\infty}(x_1, k, s)$ satisfies the ordinary differential equation :

$$-\frac{s}{s + \sigma(x_1)} \frac{d}{dx_1} \left(\frac{s}{s + \sigma(x_1)} \frac{d\widehat{G}_i^{\sigma,\infty}}{dx_1} \right) + \left(k^2 + \frac{s^2}{c^2} \right) \widehat{G}_i^{\sigma,\infty} = \delta(x_1 + h),$$

Introducing $\widehat{\mathcal{G}} \left(X_1(x_1, s) = x_1 + \frac{1}{s} \int_0^{x_1} \sigma(x) dx, k, s \right) = \widehat{G}_i^{\sigma,\infty}(x_1, k, s)$ we get :

$$-\frac{d^2 \widehat{\mathcal{G}}}{dX_1^2} + \left(k^2 + \frac{s^2}{c^2} \right) \widehat{\mathcal{G}} = \delta(X_1 + h).$$

which leads to the expressions :

$$\widehat{\mathcal{G}}(X_1, k, s) = \frac{e^{-(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}} |X_1 + h|}}{2(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}}} \implies \widehat{G}_i^{\sigma,\infty}(x_1, k, s) = \frac{e^{-(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}} |x_1 + h + \frac{\Sigma(x_1)}{s}|}}{2(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}}}.$$

Let us remark that, if x_1 is negative, $\Sigma(x_1) = 0$ and

$$\widehat{G}_i^{\sigma,\infty}(x_1, k, s) = \frac{e^{-(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}} |x_1 + h|}}{2(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}}},$$

which is nothing but the Fourier-Laplace transform of the fundamental solution of the wave equation :

$$\widehat{G}_i^{\sigma,\infty}(x_1, x_2, t) = \frac{H(ct - r(\mathbf{x}))}{2\pi\sqrt{t^2 - \frac{r(\mathbf{x})^2}{c^2}}}, \quad x_1 < 0.$$

Let us now consider $x_1 > 0$ so that $x_1 + h + \frac{\Sigma(x_1)}{s} > 0$ and

$$\widehat{G}_i^{\sigma, \infty}(x_1, k, s) = \frac{e^{-(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}} \left(x_1 + h + \frac{\Sigma(x_1)}{s}\right)}}{2(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}}}.$$

Applying the x_2 inverse Fourier transform to $\widehat{G}_i^{\sigma, \infty}$ we get :

$$\widetilde{G}_i^{\sigma, \infty}(x_1, x_2, s) = \frac{1}{4\pi} \int_{-\infty}^{+\infty} \frac{e^{-(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}} \left(x_1 + h + \frac{\Sigma(x_1)}{s}\right) - ikx_2}}{(k^2 + \frac{s^2}{c^2})^{\frac{1}{2}}} dk.$$

Contrary to what a reader familiar with the Cagniard-de Hoop could expect, the term in the exponential is not an homogeneous function in (k, s) . Applying the usual change of variable $k = ps/c$ allows us however to obtain :

$$\widetilde{G}_i^{\sigma, \infty}(x_1, x_2, s) = \int \frac{e^{-\frac{\Sigma(x_1)}{c}(1+p^2)^{\frac{1}{2}}} e^{-\frac{s}{c}[(1+p^2)^{\frac{1}{2}}(x_1+h) + ipx_2]}}{4\pi(1+p^2)^{\frac{1}{2}}} dp, \left(\equiv \int_{-\infty}^{+\infty} \Psi(p) dp \right).$$

We then have to deal with the product of two exponential functions. The first one does not depend on s and the other one is the one that usually appears in most applications of the Cagniard-de Hoop method.

Let us introduce the so-called Cagniard-de Hoop contour Γ defined as :

$$\Gamma = \Gamma^+ \cup \Gamma^- \text{ with } \Gamma^\pm = \left\{ p = \gamma^\pm(t) \equiv -i \frac{ct}{r} \sin \theta \pm \cos \theta \sqrt{\frac{c^2 t^2}{r^2} - 1}, t \geq \frac{r}{c} \right\}.$$

so that $(1+p^2)^{\frac{1}{2}}(x_1+h) + ipx_2 = ct \in \mathbb{R}_+$ for all $p \in \Gamma$.

It is clear that the two curves Γ^\pm are symmetric the one from the other with respect to the imaginary axis and meet at point $-i \sin \theta$ (for $t = r/c$). Actually Γ is nothing but the branch of the hyperbola of equation:

$$\frac{Y^2}{\sin^2 \theta} - \frac{X^2}{\cos^2 \theta} = 1, \quad (p = X + iY, (X, Y) \in \mathbb{R}^2),$$

which is located in the upper half-space $Y = \Im m p > 0$ if $\sin \theta < 0$. Note that this hyperbola does not intersect the two branch cuts of Ψ . All this information is summarized in figure 4.

Let us denote by D the real line and by Ω the connected part of the complex plane delimited by D and Γ . Let $\rho > 0$ a parameter devoted to tend to $+\infty$. We set:

$$D_\rho = \{p \in D / |p| \leq \rho\}, \Gamma_\rho = \{p \in \Gamma / |p| \leq \rho\} \text{ and } C_\rho = \{p \in \Omega / |p| = \rho\}.$$

Note that $D_\rho \cup C_\rho \cup \Gamma_\rho$ is a closed curve (see figure 5). Since $\Psi(p)$ is analytic

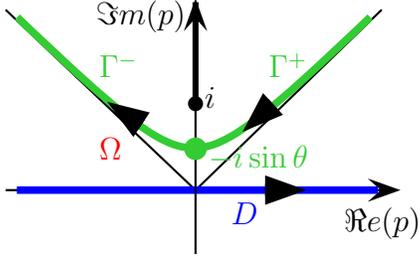


Fig. 4. The contours Γ and D

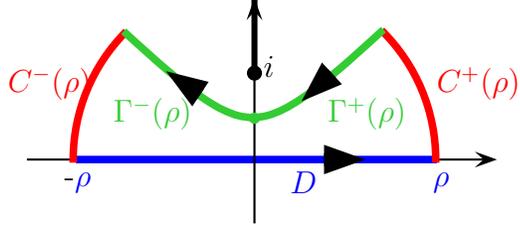


Fig. 5. The closed contour $D_\rho \cup C_\rho \cup \Gamma_\rho$

in Ω , the integral of Ψ along $D_\rho \cup C_\rho \cup \Gamma_\rho$, that we orient according to figure 5, is identically 0 :

$$\int_{D_\rho} \Psi(p) dp + \int_{C_\rho} \Psi(p) dp + \int_{\Gamma_\rho} \Psi(p) dp = 0.$$

Thanks to the choice of the square root and since $x_1 + h > 0$, the function $\Psi(p)$ decays exponentially to 0 when $\Im m p$ goes to $+\infty$. As a consequence, it is easy to show that (Jordan's lemma) :

$$\lim_{\rho \rightarrow +\infty} \int_{C_\rho} \Psi(p) dp = 0, \text{ which implies } \int_{-\infty}^{+\infty} \Psi(p) dp = - \int_{\Gamma} \Psi(p) dp \quad \text{and}$$

$$\tilde{G}_i^{\sigma, \infty}(x_1, x_2, s) = -\frac{1}{4\pi} \int_{\Gamma} \frac{e^{-\frac{\Sigma(x_1)}{c}(1+p^2)^{\frac{1}{2}}} e^{-s \left[(1+p^2)^{\frac{1}{2}} \frac{x_1+h}{c} + ip \frac{x_2}{c} \right]}}{(1+p^2)^{\frac{1}{2}}} dp.$$

We use the parametrisations $p = \gamma^+(t)$ and $p = \gamma^-(t)$, for $t \geq r/c$, respectively along Γ^+ and Γ^- and remark that :

$$\left\{ \begin{array}{l} \bullet (1+p^2)^{\frac{1}{2}} \left(\frac{x_1+h}{c} \right) + ip \frac{x_2}{c} = t, \quad \text{(by construction),} \\ \bullet \frac{dp}{(1+p^2)^{\frac{1}{2}}} = \pm \frac{dt}{(t^2 - \frac{r^2}{c^2})^{\frac{1}{2}}}, \quad \text{on } \Gamma^\pm, \\ \bullet \frac{(1+p^2)^{\frac{1}{2}}}{c} = \frac{t}{r^2}(x_1+h) \mp i \frac{x_2}{r^2} (t^2 - \frac{r^2}{c^2})^{\frac{1}{2}}, \quad \text{on } \Gamma^\pm. \end{array} \right.$$

Therefore, since t goes from $+\infty$ to $\frac{r}{c}$ on Γ^+ and from $\frac{r}{c}$ to $+\infty$ on Γ^- :

$$\tilde{G}_i^{\sigma, \infty}(x_1, x_2, s) = \frac{1}{2\pi} \int_{\frac{r}{c}}^{+\infty} \frac{e^{-(x_1+h)\Sigma(x_1)\frac{t}{r^2}}}{(t^2 - \frac{r^2}{c^2})^{\frac{1}{2}}} \cos \left[\frac{x_2}{r^2} \Sigma(x_1) (t^2 - \frac{r^2}{c^2})^{\frac{1}{2}} \right] e^{-st} dt.$$

We can now conclude, using the injectivity of the Laplace-Fourier transform.

Error Estimates Let u and $u^{\sigma, L}$ be the respective solutions of (1) and (7). We introduce the error (or reflected field) defined as $e^{\sigma, L} = u^{\sigma, L} - u$. Using the fact that f is supported in $[0, T]$ and $G_r^{\sigma, L}$ in $[r^*/c, \infty]$, we obviously have

$e^{\sigma,L}(\mathbf{x}, t) = 0$ if $t \leq r^*/c$ and :

$$e^{\sigma,L}(\mathbf{x}, t) = \int_{\max(r^*/c, t-T)}^{+\infty} G_r^{\sigma,L}(\mathbf{x}, \tau) f(t - \tau) d\tau \quad \text{if } t > \frac{r^*}{c}. \quad (11)$$

We deduce that :

$$\begin{cases} |e^{\sigma,L}(\mathbf{x}, t)| \leq \|f\|_{L^\infty(0,t)} \cdot \|G_r^{\sigma,L}(\mathbf{x}, \cdot)\|_{L^1(\frac{r^*}{c}, t)} & \text{if } \frac{r^*}{c} \leq t \leq \frac{r^*}{c} + T, \\ |e^{\sigma,L}(\mathbf{x}, t)| \leq \|f\|_{L^\infty(0,T)} \cdot \|G_r^{\sigma,L}(\mathbf{x}, \cdot)\|_{L^1(t-T, t)} & \text{if } t > \frac{r^*}{c} + T. \end{cases} \quad (12)$$

Let us now introduce the two disjoint sets $\Omega_1(t)$ and $\Omega_2(t)$:

$$\begin{cases} \Omega_1(t) = \{ \mathbf{x} \in R_+^2 / c(t-T) < r^*(\mathbf{x}) \leq ct \} \\ \Omega_2(t) = \{ \mathbf{x} \in R_+^2 / r^*(\mathbf{x}) \leq c(t-T) \} \end{cases} \quad (13)$$

These two sets are represented on figures 6 and 7 for two values of t . Note that $\Omega_1(t)$ is not empty as soon as $t > (h+2L)/c$ while $\Omega_2(t)$ is not empty as soon as $t > (h+2L)/c + T$.

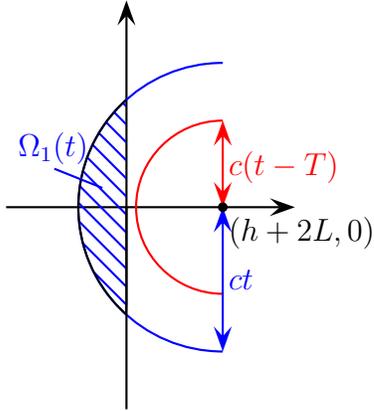


Fig. 6. The sets $\Omega_1(t)$ and $\Omega_2(t)$, if $(h+2L)/c \leq t < T + (h+2L)/c$.

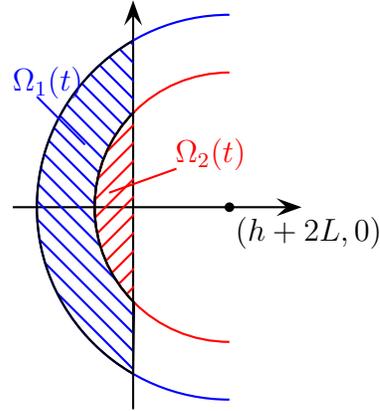


Fig. 7. The sets $\Omega_1(t)$ and $\Omega_2(t)$, if $t \geq T + (h+2L)/c$.

According to (12), in order to derive an L^∞ estimate of $e^{\sigma,L}(\cdot, t)$, we need an upper bound for the quantity:

$$\sup_{x \in \Omega_1(t)} \|G_r^N(x, \cdot)\|_{L^1(\frac{r^*}{c}, t)} \quad \text{when } t > \frac{h+2L}{c},$$

and for the quantity:

$$\sup_{x \in \Omega_2(t)} \|G_r^N(x, \cdot)\|_{L^1(t-T, t)} \quad \text{when } t > \frac{h+2L}{c} + T.$$

We thus first have to estimate L^1 -norms in time of $G_r^{\sigma,L}(\mathbf{x}, \cdot)$. Estimating the cosine function by 1, we get :

$$|G_r^{\sigma,L}(\mathbf{x}, t)| < \frac{e^{-A^*(\mathbf{x},t)}}{2\pi\sqrt{t^2 - \frac{r^*(\mathbf{x})^2}{c^2}}}.$$

Let us remark that the function $t \mapsto e^{-A^*(\mathbf{x},t)}$ is decreasing for $t > 0$, thus, recalling that, for $x_1 < 0$, $\Sigma^*(x_1) = 2\Sigma(L) = 2L\bar{\sigma}$:

$$\left| \begin{aligned} \|G_r^{\sigma,L}(\mathbf{x}, \cdot)\|_{L^1(\frac{r^*}{c}, t)} &\leq \frac{1}{2\pi} e^{-A^*(\mathbf{x}, \frac{r^*}{c})} \int_{\frac{r^*}{c}}^t \frac{d\tau}{\sqrt{t^2 - \frac{r^{*2}}{c^2}}}, \\ &= \frac{1}{2\pi} e^{-\frac{2L}{c}\bar{\sigma}|\cos\theta^*|} \text{Log} \left(\frac{ct + \sqrt{c^2t^2 - r^{*2}}}{r^*} \right) \end{aligned} \right. \quad (14)$$

in the same way :

$$\|G_r^{\sigma,L}(\mathbf{x}, \cdot)\|_{L^1(t-T, t)} \leq \frac{e^{-2L\bar{\sigma}|\cos\theta^*|\frac{t-T}{r^*}}}{2\pi} \text{Log} \left(\frac{ct + \sqrt{c^2t^2 - r^{*2}}}{c(t-T) + \sqrt{c^2(t-T)^2 - r^{*2}}} \right). \quad (15)$$

Since $\cos\theta^*(\mathbf{x}) = (x_1 - 2L - h)/r^*(\mathbf{x})$ we easily verify that

$$\inf_{\mathbf{x} \in \Omega_1(t)} |\cos\theta^*(\mathbf{x})| = \frac{2L+h}{ct} \quad \text{and} \quad \inf_{\mathbf{x} \in \Omega_2(t)} \frac{|\cos\theta^*(\mathbf{x})|}{r^*(\mathbf{x})} = \frac{2L+h}{c^2(t-T)^2},$$

hence

$$\sup_{\mathbf{x} \in \Omega_1(t)} e^{-\frac{2L}{c}\bar{\sigma}|\cos\theta^*(\mathbf{x})|} = e^{-\frac{2L(2L+h)\bar{\sigma}}{c^2t}} \quad \text{and} \quad \sup_{\mathbf{x} \in \Omega_2(t)} e^{-2L\bar{\sigma}\sin\theta^*\frac{t-T}{r^*}} = e^{-\frac{2L(2L+h)\bar{\sigma}}{c^2t}}.$$

On the other hand, using the fact that the two functions:

$$\left| \begin{aligned} r &\mapsto \frac{ct}{r} + \sqrt{\frac{c^2t^2}{r^2} - 1}, & r &\in [0, ct], \\ r &\mapsto \frac{ct + \sqrt{c^2t^2 - r^2}}{c(t-T) + \sqrt{c^2(t-T)^2 - r^2}}, & r &\in [0, c(t-T)], \quad (t > T) \end{aligned} \right.$$

are respectively decreasing and increasing, we deduce that:

$$\begin{aligned} &\sup_{x \in \Omega_1(t)} \text{Log} \left| \frac{ct}{r^*} + \sqrt{\frac{c^2t^2}{r^{*2}} - 1} \right| = \Phi(t) \\ \text{and} \quad &\sup_{x \in \Omega_2(t)} \text{Log} \left| \frac{ct + \sqrt{c^2t^2 - r^{*2}}}{c(t-T) + \sqrt{c^2(t-T)^2 - r^{*2}}} \right| = \Phi(t). \end{aligned}$$

It is now obvious to obtain :

$$\begin{cases} \sup_{x \in \Omega_1(t)} \|G_r^{\sigma,L}(x, \cdot)\|_{L^1(r^*, t)} \leq \frac{1}{2\pi} e^{-\frac{2L(2L+h)\bar{\sigma}}{c^2 t}} \Phi(t) \\ \sup_{x \in \Omega_2(t)} \|G_r^{\sigma,L}(x, \cdot)\|_{L^1(t-T, t)} \leq \frac{1}{2\pi} e^{-\frac{2L(2L+h)\bar{\sigma}}{c^2 (t-T)}} \Phi(t) \end{cases} \quad (16)$$

Since, for $t > \frac{2L+h}{c} + T$, $\exp(-1/t) > \exp(-1/(t-T))$, it is easy to obtain the uniform estimates from the first inequality.

1.3 Numerical Results

The Green's function. The main difficulty, if one wants to represent numerically the function $G_r^{\sigma,L}(x, \cdot)$ is the singularity on the circle $r^*(\mathbf{x}) = ct$. To overcome this problem we introduce the relative error defined by :

$$\gamma_r^{\sigma,L}(\mathbf{x}, t) = \frac{G_r^{\sigma,L}(\mathbf{x}, \cdot)}{G_r^{0,L}(\mathbf{x}, \cdot)} = e^{-A(\mathbf{x}, t)} \cos [B(\mathbf{x}, t)]. \quad (17)$$

Note that $G_r^{0,L}(x, \cdot)$ represents the field we would have obtained by imposing a Neumann condition on the line $x_1 = L$ without adding a damping term. That is why $\gamma^{\sigma,L}$ is called a relative error. We choose $h = 1$ and $c = 1$. The figure 8 represents the level curves of $\gamma^{\sigma,L}$ for three different values of $\bar{\sigma}$ ($\bar{\sigma}=10, 20$ and 50 from the left to the right). We remark that the amplitude of the error decrease strongly with $\bar{\sigma}$: the error level is 0.6 for $\bar{\sigma} = 10$, 0.3 for $\bar{\sigma} = 20$ and 0.06 for $\bar{\sigma} = 50$. When $\bar{\sigma}$ increases, the amplitude of the error concentrates more and more at the neighborhood of the layer. Moreover, its dependence with respect to the space variable is much more complicated because of the influence of the cosine function.

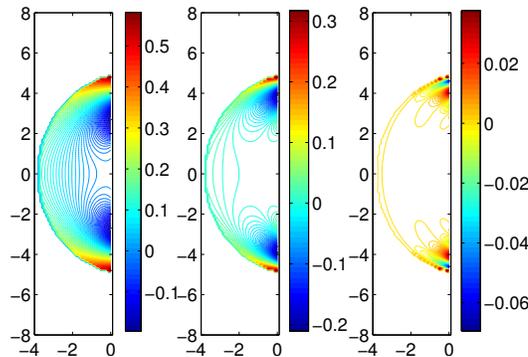


Fig. 8. $\mathbf{x} \rightarrow \gamma_r^{\sigma,0.1}(\mathbf{x})$, $\bar{\sigma} = 10, 20, 50$.

The case of a source term. We have implemented a Matlab code to com-

pute the convolution integral (11). To validate our solution we have compared it to the one obtained by a finite difference code (based on a standard central finite difference scheme of leap-frog type, second order accurate in space and time).

In our experiment, the source function is a truncated first derivative of a Gaussian:

$$f(t) = \frac{d}{dt} \left\{ e^{-2\pi f_0(t-t_0)^2} \right\} H(2t_0 - t), \quad f_0 = 10, \quad t_0 = 1/f_0 \quad (18)$$

On figures 9 and 10 we have compared the “analytical” solution (top picture in each figure) to the numerical one (bottom picture in each figure) for two values of $\bar{\sigma}$: $\bar{\sigma} = 1.5$ and 3. In each picture we represent the level lines of the solution at time $t = 0.4$. The left pictures represent the total field while the right pictures represent the reflected field (the error). For the representation, the reflected field has been amplified by a factor which depends on $\bar{\sigma}$: 4 for $\bar{\sigma} = 1.5$ and 10 for $\bar{\sigma} = 3$. In each case, the results reveal a very good agreement between the two solutions.

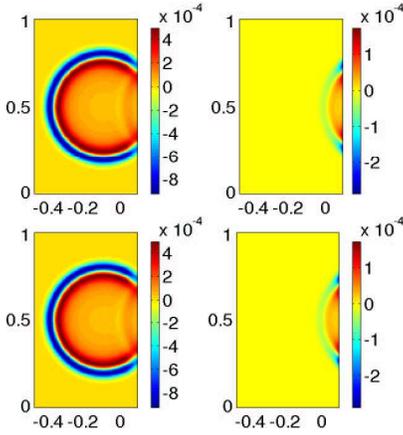


Fig. 9. Comparison between analytical (top picture) and numerical (bottom picture) solution $\bar{\sigma} = 1.5$.

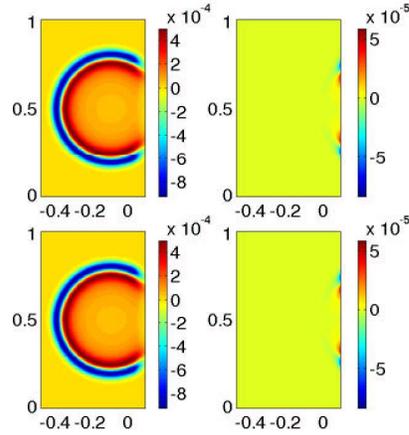


Fig. 10. Comparison between analytical (top picture) and numerical (bottom picture) solution $\bar{\sigma} = 3$.

On figures 11 and 12 we have compared both solutions at point $(0.9, 0.1)$ as functions of time. The solid curves represent the “analytical” solution and the dashed curves the numerical one for two values of $\bar{\sigma}$: $\bar{\sigma} = 1.5$ and 3. As before the left pictures represent the total field while the right pictures represent the reflected field.

L^∞ error estimates. On figure 13 we have compared the L^∞ norm of the reflected field (the solid curves) to the uniform estimates (8) given by Theorem 4 (the dashed curves) for $\bar{\sigma} = 1, 10, 100$. The source is a step function in time : $f(t) = 1$ if $0 \leq t \leq 2$ and $f(t) = 0$ otherwise. Our estimate appears to be

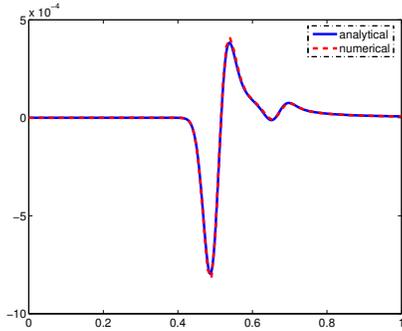


Fig. 11.a. The total field.

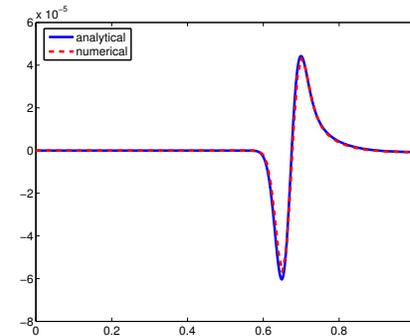


Fig. 11.b. The reflected field.

Fig. 11. Comparison between analytical (top picture) and numerical (bottom picture) solution, $\sigma = 1.5$

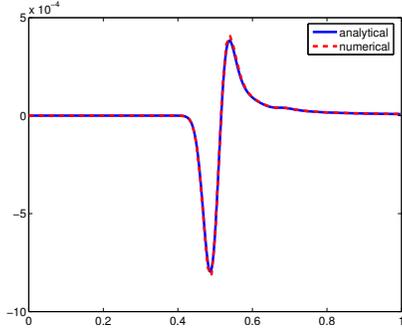


Fig. 12.a. The total field.

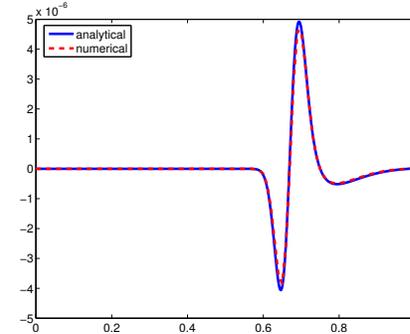


Fig. 12.b. The reflected field.

Fig. 12. Comparison between analytical (top picture) and numerical (bottom picture) solution, $\sigma = 3$

very sharp for $\bar{\sigma} = 1$ and becomes less accurate (although quite acceptable) when $\bar{\sigma}$ increases.

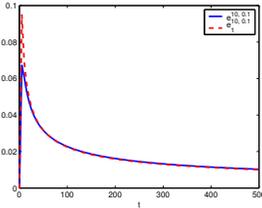


Fig. 13.a. $\bar{\sigma} = 1$.

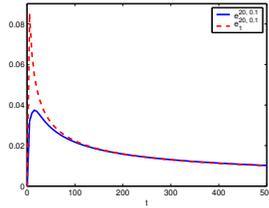


Fig. 13.b. $\bar{\sigma} = 10$.

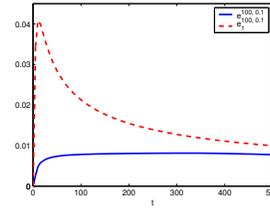


Fig. 13.c. $\bar{\sigma} = 100$.

Fig. 13. Error estimates (dashed curve) and effective error (solid curve)

The case of a rectangular domain surrounded by PML. We consider a domain $[0 ; 1]^2$ surrounded by a PML of width $L = 0.1$. We use a point source in space located at the center of the domain, the expression of the source in time is given by (18). As for the case of the half-plane, we have compared our results to a numerical solution obtained by the same code as for the previous paragraph. These results are represented in figures 14, 15 and 16, respectively at time 7, 12 and 17 (take care to the fact that the color

scale differs from one picture to another). Here again the results show a very good agreement between the analytical and numerical solution, even for long time, after several reflections.

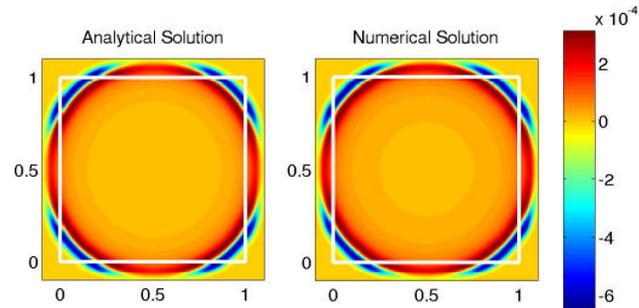


Fig. 14. The analytical (left picture) and numerical (right picture) solutions at time 7

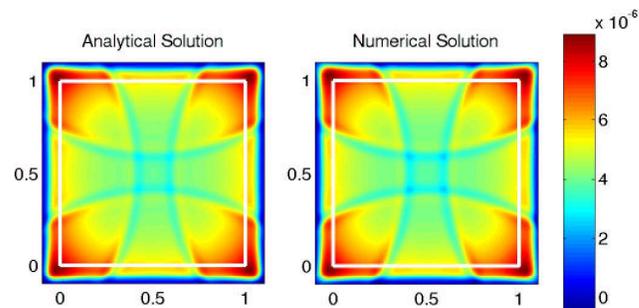


Fig. 15. The analytical (left picture) and numerical (right picture) solutions at time 12

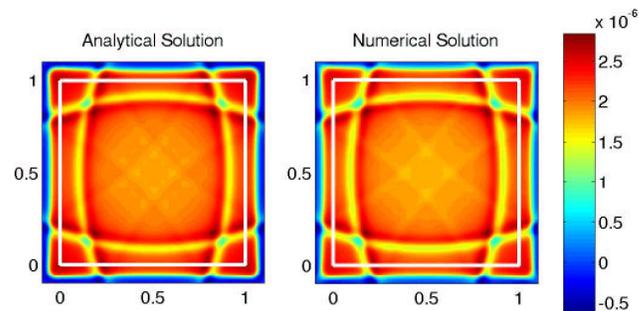


Fig. 16. The analytical (left picture) and numerical (right picture) solutions at time 17

2 Classical PML for advective acoustics

The Bérenger's PML were adapted to the aeroacoustics equations for instance by Hu [22] in 1996. Let us first recall his model, considering an horizontal

uniform mean flow M . We have to rewrite the aeroacoustics equations whose unknowns are the pressure and the velocity ($p, \mathbf{U} = (u, v)$),

$$\begin{cases} \frac{\partial p}{\partial t} + M \frac{\partial p}{\partial x_1} + \frac{\partial u}{\partial x_1} + \frac{\partial v}{\partial x_2} = 0, \\ \frac{\partial u}{\partial t} + M \frac{\partial u}{\partial x_1} + \frac{\partial p}{\partial x_1} = 0, \\ \frac{\partial v}{\partial t} + M \frac{\partial v}{\partial x_1} + \frac{\partial p}{\partial x_2} = 0, \end{cases} \quad (19)$$

in a so-called “split form” with the unknowns (p_1, p_2, u, v_1, v_2) where p_1 and p_2 (resp. v_1 and v_2) are non physical variables, whose sum is equal to the pressure (resp. the second component of the velocity). One then obtains the PML model by adding a zero-order absorption term, for instance in the equations containing the derivatives with respect to x_1 for a vertical layer :

$$\begin{cases} \frac{\partial p_1}{\partial t} + \sigma(x_1)p_1 + M \frac{\partial p}{\partial x_1} + \frac{\partial u}{\partial x_1} = 0, \\ \frac{\partial p_2}{\partial t} + \frac{\partial v}{\partial x_2} = 0, \\ \frac{\partial u}{\partial t} + \sigma(x_1)u + M \frac{\partial u}{\partial x_1} + \frac{\partial p}{\partial x_1} = 0, \\ \frac{\partial v_1}{\partial t} + \sigma(x_1)v_1 + M \frac{\partial v}{\partial x_1} = 0, \\ \frac{\partial v_2}{\partial t} + \frac{\partial p}{\partial x_2} = 0. \end{cases} \quad (20)$$

Though this problem is (weakly) well-posed (see [24]), it is unstable as soon as $|M| > 0$: it may admit solution growing exponentially with the time variable.

2.1 Analysis of the instabilities via the slowness curve

The instabilities can be analyzed thanks to a plane wave analysis and to the slowness curves : we search for (ω, k_1, k_2) such that

$$[p_1, p_2, u, v_1, v_2]^t(x_1, x_2, t) = [p_1^0, p_2^0, u^0, v_1^0, v_2^0]^t e^{i(\omega t + k_1 x_1 + k_2 x_2)}.$$

It is well-known that, if $\sigma = 0$ (i.e for the aeroacoustics equations), (ω, k_1, k_2) is solution of one of the two following dispersion equations :

- the dispersion equation of the advective waves :

$$(\omega + M k_1)^2 - k_1^2 - k_2^2 = 0; \quad (21)$$

- the dispersion equation of the vorticity waves :

$$\omega + Mk_1 = 0. \quad (22)$$

The slowness curves are the representation in the so-called slowness plane $(k_1/\omega, k_2/\omega)$ of the solutions of these equations. One can easily show that the slowness curve associated to the advective waves is an ellipse whose center is $(M/(1 - M^2), 0)$ and that the slowness curve associated to the vorticity is a line of equation $k_1/\omega = -1/M$. Let us also define the slowness vector and the group velocity respectively by : $\boldsymbol{l} = [k_1/\omega, k_2/\omega]^t$ and $\boldsymbol{v}_g = \nabla_k \omega$. It is immediate to deduce the slowness vector from the slowness curve. Moreover the group velocity vector is orthogonal to the slowness curves (see figure 17). It is well-known that, as soon as $|M| > 0$, it exists waves whose first component of slowness and of group velocity vector have opposite signs (in red in figure 17).

It has been shown [25,2,10] that the high-frequency instabilities are due to these so-called back-propagating modes. It is thus easy to deduce the set of unstable waves : the advective waves such that $0 < k_1/\omega < M/(1 - M^2)$ (see figure 18). An illustration of this instabilities is given in figure 19 for $M = 0.5$.

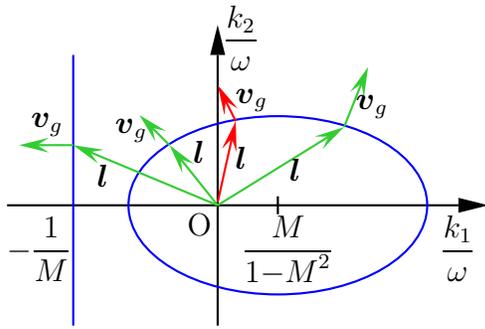


Fig. 17. The slowness and group velocity vectors

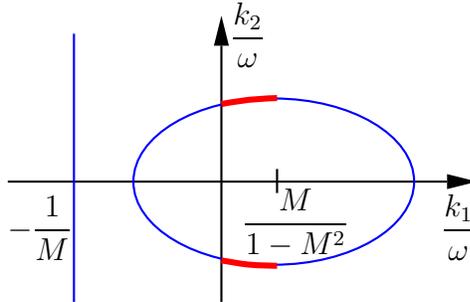


Fig. 18. The set of unstable points

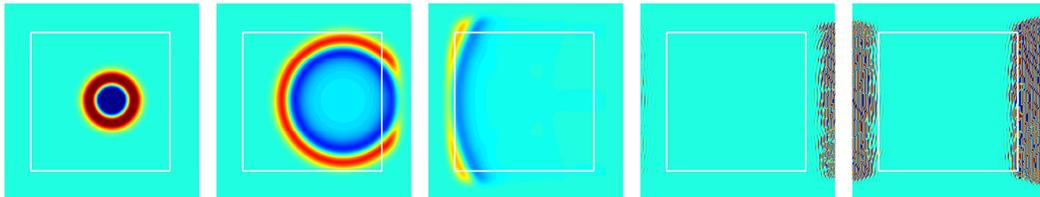


Fig. 19. The instabilities in the PML, $t=1, 3, 8, 30$ and 50

2.2 The main results

As for the acoustics equation, it is possible to obtain an analytic expression of the fundamental solution of problem 20. Let us first remark that this problem can be formally rewritten as (the calculations are left to the reader) :

$$\begin{cases} \frac{\partial p}{\partial t} + MD_{x_1}^\sigma p + D_{x_1}^\sigma u + \frac{\partial v}{\partial x_2} = 0, \\ \frac{\partial u}{\partial t} + MD_{x_1}^\sigma u + D_{x_1}^\sigma p = 0, \\ \frac{\partial v}{\partial t} + MD_{x_1}^\sigma v + \frac{\partial p}{\partial x_2} = 0. \end{cases} \quad (23)$$

Then, straightforward calculations lead us to the following decoupled system :

$$\begin{cases} \frac{\partial^2 p}{\partial t^2} + 2MD_{x_1}^\sigma \frac{\partial p}{\partial t} - (1 - M^2)(D_{x_1}^\sigma)^2 p - \frac{\partial^2 p}{\partial x_2^2} = 0, \\ \frac{\partial u}{\partial t} + MD_{x_1}^\sigma u + D_{x_1}^\sigma p = 0, \\ \frac{\partial v}{\partial t} + MD_{x_1}^\sigma v + \frac{\partial p}{\partial x_2} = 0. \end{cases} \quad (24)$$

The first equation is nothing but the advective wave equation where the derivation with respect to x_1 has been replaced by the operator $D_{x_1}^\sigma$. This equation, which we choose to study here, is the cause of the instabilities.

As for the acoustics case we consider the problem

$$\begin{cases} \text{Find } u : \mathbb{R}^2 \times \mathbb{R}_+ \mapsto \mathbb{R}, \text{ null for } t < 0 & \text{such that} \\ \left[\frac{\partial^2 p}{\partial t^2} + 2M \frac{\partial}{\partial t} D_{x_1}^\sigma p - \left[(1 - M^2)(D_{x_1}^\sigma)^2 p + \frac{\partial^2 p}{\partial x_2^2} \right] \right] = \delta(\mathbf{x} - \mathbf{x}_S) \delta(t) & \text{in } \mathbb{R}^2 \times \mathbb{R}_+. \end{cases} \quad (25)$$

where $\mathbf{x}_S = (-h, 0)$, $\sigma(x_1) = 0$ if $x_1 \leq 0$ and $\sigma(x_1) = 1$ if $x_1 > 0$.

We define the functions $r(\mathbf{x})$ and $\theta(\mathbf{x})$ (“generalized polar coordinates”) as :

$$r^2(\mathbf{x}) = \frac{(x_1 + h)^2}{(1 - M^2)^2} + \frac{x_2^2}{1 - M^2}, \quad \cos \theta(\mathbf{x}) = \frac{x_1 + h}{r(1 - M^2)} \quad \text{and} \quad \sin \theta(\mathbf{x}) = \frac{x_2}{r\sqrt{1 - M^2}}.$$

Note that the level lines of $r(\mathbf{x})$ and $\theta(\mathbf{x})$ are ellipses and half-lines (see Fig.20).

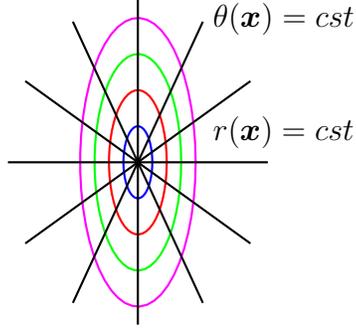


Fig. 20. The level lines of $r(\mathbf{x})$ and $\theta(\mathbf{x})$

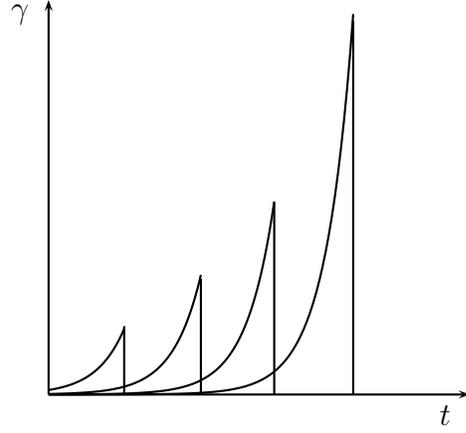


Fig. 21. $r \mapsto \gamma(r, \theta_0, t)$

We also introduce the two functions $A(\mathbf{x}, t)$ and $B(\mathbf{x}, t)$ defined by

$$A(\mathbf{x}, t) = \Sigma(x_1) \left(\frac{t}{r} \cos \theta - M \sin^2 \theta \right)$$

$$\text{and } B(\mathbf{x}, t) = \Sigma(x_1) \sin \theta \sqrt{\left(\frac{t}{r} + M \cos \theta \right)^2 - 1}.$$

Theorem 6 *The expression of the solution $p(\mathbf{x}, t) = G_i^\sigma(\mathbf{x}, t)$ of problem (25) is given by :*

$$\left\{ \begin{array}{l} G_i^\sigma(\mathbf{x}, t) = \frac{H(t - r(1 - M \cos \theta))}{2\pi\sqrt{1 - M^2}\sqrt{(t + Mr \cos \theta)^2 - r^2}}, \quad x_1 \leq 0 \\ G_i^\sigma(\mathbf{x}, t) = \frac{H(t - r(1 - M \cos \theta))}{2\pi\sqrt{1 - M^2}\sqrt{(t + Mr \cos \theta)^2 - r^2}} e^{-A(\mathbf{x}, t)} \cos [B(\mathbf{x}, t)], \quad x_1 > 0. \end{array} \right. \quad (26)$$

For $x_1 > 0$ and $t > t_0 = r(1 - M \cos \theta)$ we define the function

$$\gamma(\mathbf{x}, t) = \frac{G_i^\sigma(\mathbf{x}, t)}{G_i^0(\mathbf{x}, t)} = e^{-A(\mathbf{x}, t)} \cos [B(\mathbf{x}, t)].$$

Theorem 7 *For fixed \mathbf{x} , the function $t \rightarrow \gamma(\mathbf{x}, t)$ is bounded : $\gamma(\mathbf{x}, t) \leq C(\mathbf{x})$. However, given a direction θ_0 , let us denote*

$$r^{\max}(t) = \frac{t}{(1 - M \cos \theta_0)},$$

then, $\gamma(r^{\max}(t), \theta_0, t) > e^{\alpha(\theta_0)t}$ with $\alpha(\theta_0) > 0$ if $\cos \theta_0 < M$ and $\alpha(\theta_0) \leq 0$ if $\cos \theta_0 \geq M$. Consequently the $L^\infty(\mathbb{R}^+)$ -norm of $\gamma(\mathbf{x}, t)$ grows exponentially

with t :

$$\|\gamma(\cdot, t)\|_{L^\infty} \geq C e^{\alpha t}, \quad \alpha > 0.$$

The kind of instability expressed by this theorem is often called “convective instability” because the instability is “moving with the wave front”. To illustrate this point we have represented the variations of γ with respect to r for a given unstable direction θ_0 and for four values of t in figure 21.

We have also implemented a Matlab code to compute the solution of problem (25) where the source function is once again a truncated first derivated of a Gaussian. In the following experiment the frequency of the source is 1 and the source is located at point $(0, -2)$. Figures (22) and (23) represents the propagation of an advective wave, respectively with $M = 0.5$ and $M = 0.9$. We have represented in red the half lines $\theta(\mathbf{x}) = \arccos(M)$ and $\theta(\mathbf{x}) = -\arccos(M)$ that define the set of unstable points.

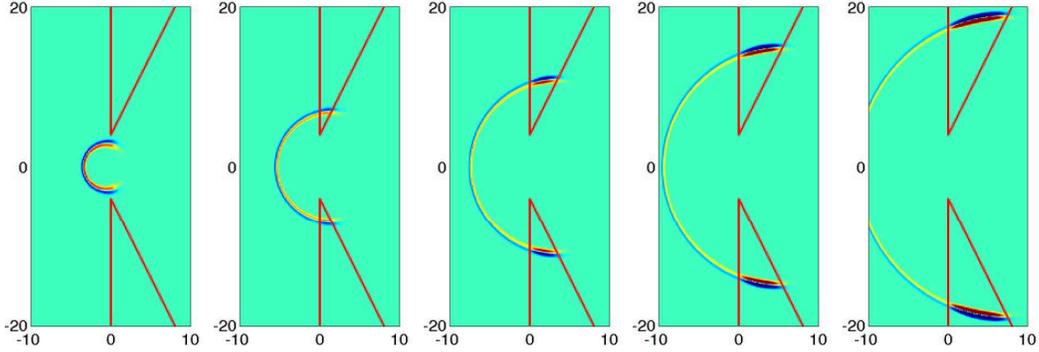


Fig. 22. Instabilities in the PML with $M = 0.5$

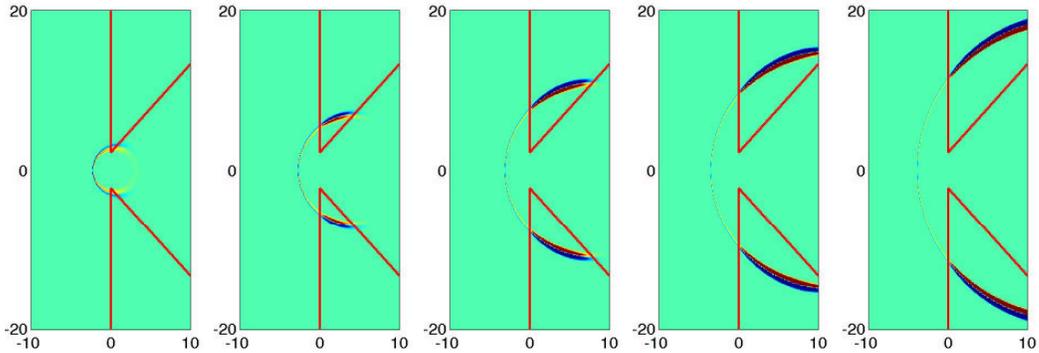


Fig. 23. Instabilities in the PML with $M = 0.9$

2.3 Proof of the theorems

Expression of the analytic solution. Let us first apply to G_i^σ the Laplace transform in t and the Fourier transform in x_2 . The resulting function $x_1 \mapsto$

$\widehat{G}_i^\sigma(x_1, k, s)$ satisfies the ordinary differential equation :

$$-(1-M^2)\frac{s}{s+\sigma}\frac{d}{dx_1}\left(\frac{s}{s+\sigma}\frac{d\widehat{G}_i^\sigma}{dx_1}\right)+2Ms\frac{s}{s+\sigma}\frac{\partial\widehat{G}_i^\sigma}{\partial x_1}+(k^2+s^2)\widehat{G}_i^\sigma=\delta(x_1+h) \quad (27)$$

We denote

$$\lambda(x_1)=\begin{cases} M+\sqrt{1+(1-M^2)\frac{k^2}{s^2}}, & \text{if } x_1 < -h, \\ M-\sqrt{1+(1-M^2)\frac{k^2}{s^2}}, & \text{if } x_1 > -h, \end{cases}$$

$\widehat{G}_i^\sigma(x_1, k, s)$ has the following form

$$\widehat{G}_i^\sigma(x_1, k, s)=\mathcal{A}(k, s)e^{\frac{s(x_1+h)+\Sigma(x_1)}{1-M^2}\lambda(x_1)}$$

Taking into account the jump condition

$$\left[-(1-M^2)\left(\frac{s}{s+\sigma}\right)^2\frac{\partial\widehat{G}_i^\sigma}{\partial x_1}+2M\frac{s}{s+\sigma}\widehat{G}_i^\sigma\right]_{x_1=-h}=1, \quad (28)$$

one obtains, if $\sigma(-h)=0$, $\mathcal{A}(k, s)=\frac{1}{2\sqrt{s^2+(1-M^2)k^2}}$.

If x_1 is negative, $\Sigma(x_1)=0$ and $\widehat{G}_i^\sigma(x_1, k, s)=\frac{e^{\frac{s(x_1+h)}{1-M^2}\lambda(x_1)}}{2\sqrt{1+(1-M^2)\frac{k^2}{s^2}}}$.

This is nothing but the Fourier-Laplace transform of the fundamental solution of the advective wave equation :

$$G_i^\sigma(\mathbf{x}, t)=\frac{H(ct-r(1-M\cos\theta))}{2\pi\sqrt{(t+Mr\cos\theta)^2-r^2}}, \quad x_1 \leq 0.$$

Let us now consider $x_1 > 0$ so that $\lambda(x_1)=M-\sqrt{1+(1-M^2)\frac{k^2}{s^2}}$ and

$$\widehat{G}_i^\sigma(x_1, k, s)=\frac{e^{\frac{s(x_1+h)+\Sigma(x_1)}{1-M^2}\left(M-\sqrt{1+(1-M^2)\frac{k^2}{s^2}}\right)}}{2\sqrt{s^2+(1-M^2)k^2}}$$

Applying the x_2 inverse Fourier transform to $\widehat{G}_i^\sigma(x_1, k, s)$, we get

$$\widetilde{G}_i^\sigma(x_1, x_2, s)=\frac{1}{4\pi}\int_{-\infty}^{+\infty}e^{\frac{s(x_1+h)+\Sigma(x_1)}{1-M^2}\left(M-\sqrt{1+(1-M^2)\frac{k^2}{s^2}}\right)}\frac{e^{-ikx_2}}{\sqrt{s^2+(1-M^2)k^2}}dk, \quad (29)$$

We apply the change of variable $k = \frac{ps}{\sqrt{1-M^2}}$ and obtain:

$$\tilde{G}_i^\sigma(x_1, x_2, s) = \frac{1}{4\pi} \int_{-\infty}^{+\infty} \frac{e^{\Sigma(x_1) \frac{M-\sqrt{1+p^2}}{1-M^2}} e^{s \left[\frac{(M-\sqrt{1+p^2})}{1-M^2} (x_1+h) - ip \frac{x_2}{\sqrt{1-M^2}} \right]}}{\sqrt{(1-M^2)(1+p^2)}} dp. \quad (30)$$

We now have to search a path in the complex plane such that

$$\frac{M - \sqrt{1+p^2}}{1-M^2} (x_1+h) - ip \frac{x_2}{\sqrt{1-M^2}} = -t, \quad \text{for } t > 0, \quad (31)$$

For $t \geq t_0 = r(1 - M \cos \theta)$ we define the functions $\gamma^\pm(t)$ by

$$\gamma^\pm(t) \equiv -i \left(\frac{t}{r} + M \cos \theta \right) \sin \theta \pm \cos \theta \sqrt{\left(\frac{t}{r} + M \cos \theta \right)^2 - 1},$$

and we introduce the Cagniard-de Hoop contour Γ defined as:

$$\Gamma = \Gamma^+ \cup \Gamma^-, \quad \Gamma^\pm = \left\{ p = \gamma^\pm(t) \right\}. \quad (32)$$

The contour Γ is very similar to the one exposed at the previous section (consider denoting $T = t + Mr \cos \theta$): in particular it does not intercept the branch cut of the function $(1+p^2)^{-\frac{1}{2}}$. Then, as for the acoustics case, we easily deduce :

$$\tilde{G}_i^\sigma(x_1, x_2, s) = -\frac{1}{4\pi} \int_{\Gamma} \frac{e^{\Sigma(x_1) \frac{M-\sqrt{1+p^2}}{1-M^2}} e^{s \left[\frac{(M-\sqrt{1+p^2})}{1-M^2} (x_1+h) - ip \frac{x_2}{\sqrt{1-M^2}} \right]}}{\sqrt{1+p^2}} dp.$$

We use the parameterizations $p = \gamma^+(t)$ and $p = \gamma^-(t)$, for $t \geq t_0$, respectively along Γ^+ and Γ^- and remark that:

$$\left| \begin{array}{l} \bullet \frac{(M - \sqrt{1+p^2})}{1-M^2} (x_1+h) - ip \frac{x_2}{\sqrt{1-M^2}} = -t, \quad (\text{by construction}), \\ \bullet \frac{dp}{(1+p^2)^{\frac{1}{2}}} = \pm \frac{dt}{\left[(t + Mr \cos \theta)^2 - r^2 \right]^{\frac{1}{2}}}, \quad \text{on } \Gamma^\pm, \\ \bullet \Sigma(x_1) \frac{M - \sqrt{1+p^2}}{1-M^2} = -A(\mathbf{x}, t) \mp iB(\mathbf{x}, t), \quad \text{on } \Gamma^\pm \end{array} \right.$$

Therefore, since t goes from $+\infty$ to t_0 on Γ^+ and from t_0 to $+\infty$ on Γ^- :

$$\tilde{G}_i^\sigma(x_1, x_2, s) = \frac{1}{4\pi} \int_{t_0}^{+\infty} \frac{e^{-A(\mathbf{x}, t)} \cos(B(\mathbf{x}, t))}{\sqrt{1-M^2} \sqrt{(t + Mr \sin \theta)^2 - r^2}} e^{-st} dt.$$

It is then easy to conclude.

Properties of the function γ . For fixed \mathbf{x} , the function $B(\mathbf{x}, t)$ is bounded by 1 in time. Moreover the function $t \rightarrow A(\mathbf{x}, t)$ is obviously increasing with t on $[t_0 ; +\infty]$ and its minimum is then $A(\mathbf{x}, t_0) = \Sigma(x_1)(\cos \theta - M)$. Then

$$\max_{t \geq t_0} \gamma(\mathbf{x}, t) \leq e^{-\Sigma(x_1)(\cos \theta - M)}.$$

For given t we denote by $\Omega(t)$ the support of $\gamma(\cdot, t)$, it is a disk of center $(Mt - h, 0)$ and of radius t . Let us remark that the point of generalized polar coordinates $(r^{\max}(t), \theta_0)$ belongs to $\partial\Omega_t$. Denoting

$$x_1^{\max}(t) = (1 - M^2)r^{\max}(t) \cos \theta_0 - h = \max_{\Delta(\theta_0, t)} x_1,$$

it is easy to check that

$$\gamma(r^{\max}(t), \theta_0, t) = e^{-\Sigma(x_1^{\max}(t))(\cos \theta_0 - M)},$$

since $B(r^{\max}(t), \theta_0, t) = 0$, then, since $x_1^{\max}(t)$ grows linearly with t and Σ grows with x_1 it is easy to conclude the proof

3 Stabilized PML for advective acoustics

Various solutions have been proposed in the literature to prevent instabilities in the PML. Hu [5] used a low-pass filter inside the absorbing layer. Tam, Auriault and Cambuli [2] proposed to use selective damping coefficients. Hesthaven [25] decelerated progressively the flow in the layer. Lions, Metral and Vacus [26] defined a new layer by regularizing the damping terms.

However all these methods may be not perfectly matched and, although these problems are well-posed, their stability has not been proven. Recently a significant advance has been achieved by Abarbanel, Gottlieb and Hesthaven [21] and by Hu [22] who has presented a stable and perfectly matched model, close to the one we are going to present (though the two models have been obtained independently). Hagström [20], using a different method, has also constructed a similar layer.

3.1 The advective wave equation

We are first concerned by stabilizing the PML for the advective equation whose associated slowness curve is the ellipse represented in the figure 18. As we said before, the instabilities produced by the PML can be explained by the

fact that the center of this ellipse is not the origin of the axes. Therefore an idea for stabilizing the PML consists in using a change of variable to translate the ellipse by the vector $(-M/(1 - M^2), 0)$ for its center to be located at the origin (see figure 24). Therefore we introduce the new unknowns k_1^* and ω^*

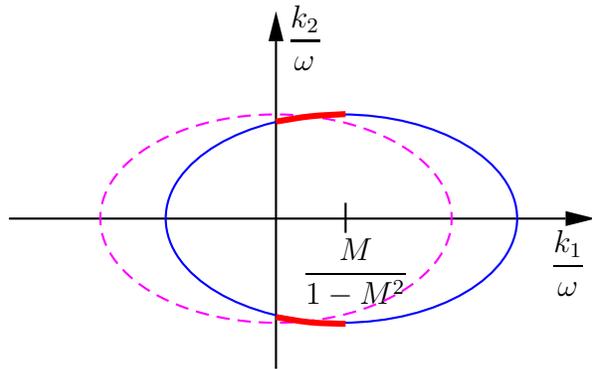


Fig. 24. The slowness curve before the change of variable (in blue/solid) and after (in magenta/dashed)

such that

$$\frac{k_1^*}{\omega^*} = \frac{k_1}{\omega} - \frac{M}{1 - M^2}.$$

If we set $\omega^* = \omega$ this relation becomes

$$k_1^* = k_1 - \frac{M}{1 - M^2}\omega.$$

This change of variable can also be expressed through the time-space variables :

$$\frac{\partial}{\partial x_1} - \frac{M}{1 - M^2} \frac{\partial}{\partial t} \implies \frac{\partial}{\partial x_1^*},$$

which is obtained by using the new variables :

$$x_1^* = x_1, \quad x_2^* = x_2, \quad \text{and} \quad t^* = t - \frac{M}{1 - M^2}x_1. \quad (33)$$

Note that this change of variable does not affect the spatial coordinates and consequently the interface between the computational domain and the layer. The choice $\omega^* = \omega$ has been made to obtain this property.

Construction of the stabilized PML model. Let us first show how to obtain an infinite PML in \mathbb{R}_+^2 ($x_1 > 0$). The steps of the methods are :

- (1) Rewrite the problem as a transmission problem between \mathbb{R}_-^2 and \mathbb{R}_+^2 :

$$\left\{ \begin{array}{l} \frac{\partial^2 p}{\partial t^2} + 2M \frac{\partial p}{\partial t \partial x_1} - (1 - M^2) \frac{\partial^2 p}{\partial x_1^2} - \frac{\partial^2 p}{\partial x_2^2} = \delta(\mathbf{x} - \mathbf{x}_s) \delta(t), \quad x_1 < 0, \quad (34a) \\ \frac{\partial^2 p}{\partial t^2} + 2M \frac{\partial p}{\partial t \partial x_1} - (1 - M^2) \frac{\partial^2 p}{\partial x_1^2} - \frac{\partial^2 p}{\partial x_2^2} = 0, \quad x_1 > 0, \quad (34b) \\ p(0^-, x_2, t) = p(0^+, x_2, t), \quad (34c) \\ \frac{\partial p}{\partial x_1}(0^-, x_2, t) = \frac{\partial p}{\partial x_1}(0^+, x_2, t). \quad (34d) \end{array} \right.$$

(2) Apply the change of variable

$$p^*(x_1, x_2, t) = p(x_1, x_2, t - \frac{M}{1 - M^2} x_1),$$

in the PML to obtain the new transmission problem :

$$\left\{ \begin{array}{l} \frac{\partial^2 p}{\partial t^2} + 2M \frac{\partial p}{\partial t \partial x_1} - (1 - M^2) \frac{\partial^2 p}{\partial x_1^2} - \frac{\partial^2 p}{\partial x_2^2} = \delta(\mathbf{x} - \mathbf{x}_s) \delta(t), \quad x_1 < 0, \quad (35a) \\ \frac{1}{1 - M^2} \frac{\partial^2 p^*}{\partial t^2} - (1 - M^2) \frac{\partial^2 p^*}{\partial x_1^2} - \frac{\partial^2 p^*}{\partial x_2^2} = 0 \quad x_1 > 0, \quad (35b) \\ p(0, x_2, t) = p^*(0, x_2, t), \quad (35c) \\ \frac{\partial p}{\partial x_1}(0, x_2, t) = \frac{\partial p^*}{\partial x_1}(0, x_2, t) + \frac{M}{1 - M^2} \frac{\partial p^*}{\partial t}(0, x_2, t). \quad (35d) \end{array} \right.$$

Note that the advective wave equation has been turned into an equation very close to the classical wave equation by this change of variable.

Let us now define the function $\rho(\mathbf{x})$ by $\rho(\mathbf{x}) = 1$ if $x_1 < 0$ and $\rho(\mathbf{x}) = 1/(1 - M^2)$ otherwise.

Theorem 8 *The following energy is conserved :*

$$E(t) = \frac{1}{2} \int_{\mathbb{R}^2} \left[\rho(\mathbf{x}) \left| \frac{\partial p}{\partial t} \right|^2 + (1 - M^2) \left| \frac{\partial p}{\partial x_1} \right|^2 + \left| \frac{\partial p}{\partial x_2} \right|^2 \right].$$

Proof. Let us respectively multiply (35a) and (35b) by $\partial p / \partial t$ and $\partial p^* / \partial t$. After having integrated both this equations over their respective defini-

tion domain (\mathbb{R}_-^2 and \mathbb{R}_+^2) and added them, we check that :

$$\begin{aligned} \frac{dE}{dt}(t) + \int_{\mathbb{R}_-^2} 2M \frac{\partial p}{\partial t} \frac{\partial p}{\partial x_1} \frac{\partial p}{\partial t} + \int_{\Gamma} (1 - M^2) \left(\frac{\partial p^*}{\partial x_1} \frac{\partial p^*}{\partial t} - \frac{\partial p}{\partial x_1} \frac{\partial p}{\partial t} \right) \\ + \int_{\Gamma} \left(\frac{\partial p^*}{\partial x_2} \frac{\partial p^*}{\partial t} - \frac{\partial p}{\partial x_2} \frac{\partial p}{\partial t} \right) = 0 \end{aligned}$$

where Γ is the line of equation $x_1 = 0$. Using the continuity of p (and consequently of its derivatives with respect to x_2 and t) it is obvious that the last integral in this equation is zero. Furthermore

$$\int_{\mathbb{R}_-^2} M \frac{\partial p}{\partial t} \frac{\partial p}{\partial x_1} \frac{\partial p}{\partial t} = \int_{\Gamma} M \frac{\partial p}{\partial t} \frac{\partial p}{\partial t} - \int_{\mathbb{R}_-^2} M \frac{\partial p}{\partial t} \frac{\partial p}{\partial t \partial x_1}.$$

Then

$$\begin{aligned} \int_{\mathbb{R}_-^2} 2M \frac{\partial p}{\partial t} \frac{\partial p}{\partial x_1} \frac{\partial p}{\partial t} + \int_{\Gamma} (1 - M^2) \left(\frac{\partial p^*}{\partial x_1} \frac{\partial p^*}{\partial t} - \frac{\partial p}{\partial x_1} \frac{\partial p}{\partial t} \right) \\ = \int_{\Gamma} \frac{\partial p}{\partial t} \left[M \frac{\partial p}{\partial t} + (1 - M^2) \left(\frac{\partial p^*}{\partial x_1} - \frac{\partial p}{\partial x_1} \right) \right] \end{aligned}$$

We deduce from (35d) that this expression is zero :

$$\frac{dE}{dt}(t) = 0.$$

- (3) It only remains to replace formally the derivatives with respect to x_1 by the operator $D_{x_1}^\sigma$:

$$\left\{ \begin{array}{l} \frac{\partial^2 p}{\partial t^2} + 2M \frac{\partial p}{\partial t \partial x_1} - (1 - M^2) \frac{\partial^2 p}{\partial x_1^2} - \frac{\partial^2 p}{\partial x_2^2} = \delta(\mathbf{x} - \mathbf{x}_s), \quad x_1 < 0, \quad (36a) \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{1}{1 - M^2} \frac{\partial^2 p^*}{\partial t^2} - (1 - M^2) (D_{x_1}^\sigma)^2 p^* - \frac{\partial^2 p^*}{\partial x_2^2} = 0 \quad x_1 > 0, \quad (36b) \end{array} \right.$$

$$\left\{ \begin{array}{l} p(0, x_2, t) = p^*(0, x_2, t), \quad (36c) \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{\partial p}{\partial x_1} = D_{x_1}^\sigma p^*(0, x_2, t) + \frac{M}{1 - M^2} \frac{\partial p^*}{\partial t}. \quad (36d) \end{array} \right.$$

Analysis of the new model. Let us define the functions $r(\mathbf{x})$ and $\theta(\mathbf{x})$ by

$$r^2(\mathbf{x}) = \frac{(x_1 + h)^2}{(1 - M^2)^2} + \frac{x_2^2}{1 - M^2}, \quad \cos \theta(\mathbf{x}) = \frac{x_1 + h}{r(1 - M^2)} \quad \text{and} \quad \sin \theta(\mathbf{x}) = \frac{x_2}{r\sqrt{1 - M^2}}.$$

Let $A(\mathbf{x}, t)$ and $B(\mathbf{x}, t)$ be defined by

$$A(\mathbf{x}, t) = \Sigma(x_1) \left(t + \frac{Mh}{1-M^2} \right) \frac{\cos \theta}{r} > 0$$

$$\text{and } B(\mathbf{x}, t) = \Sigma(x_1) \frac{\sin \theta}{r} \sqrt{\left(t + \frac{Mh}{1-M^2} \right)^2 - 1}.$$

Theorem 9 *The expression of the solution $(p, p^*)(\mathbf{x}, t) = (G_i, G_i^*)(\mathbf{x}, t)$ of problem (36) is given by :*

$$\left\{ \begin{array}{l} G_i(\mathbf{x}, t) = \frac{H(t - r(1 - M \cos \theta))}{2\pi\sqrt{1 - M^2}\sqrt{(t + Mr \cos \theta)^2 - r^2}}, \quad x_1 \leq 0 \\ G_i^*(\mathbf{x}, t) = \frac{H(t + \frac{Mh}{1-M^2} - r)}{2\pi\sqrt{1 - M^2}\sqrt{\left(t + \frac{Mh}{1-M^2}\right)^2 - r^2}} e^{-A(\mathbf{x}, t)} \cos [B(\mathbf{x}, t)], \quad x_1 > 0. \end{array} \right. \quad (37)$$

This expression is similar to one exposed at the previous section. The difference lies in the fact that the function A is always positive which guarantee the stability of the layer.

Proof via the Cagniard-de Hoop technique. After applying a Laplace transform in t and a Fourier transform in x_2 we obtain the following differential system :

$$\left\{ \begin{array}{l} (s^2 + k^2)\widehat{G}_i + 2sM \frac{d\widehat{G}_i}{dx_1} - (1 - M^2) \frac{d^2\widehat{G}_i}{dx_1^2} = \delta(x_1 + h), \quad x_1 < 0, (38a) \\ \left(\frac{s^2}{1 - M^2} + k^2 \right) \widehat{G}_i^* - (1 - M^2) \frac{s}{s + \sigma} \frac{d}{dx_1} \left(\frac{s}{s + \sigma} \frac{d\widehat{G}_i^*}{dx_1} \right) = 0 \quad x_1 > 0, (38b) \\ \widehat{G}_i(0) = \widehat{G}_i^*(0), \quad (38c) \\ \frac{d\widehat{G}_i}{dx_1}(0) = \frac{s}{s + \sigma} \frac{d\widehat{G}_i^*}{dx_1}(0) + \frac{Ms}{1 - M^2} \widehat{G}_i^*(0). \quad (38d) \end{array} \right.$$

After calculations (similar to the ones of section 2) we obtain :

$$\widehat{G}_i(x_1, k, s) = \frac{e^{\frac{s(x_1+h)}{1-M^2}\lambda(x_1)}}{2\sqrt{s^2 + (1 - M^2)k^2}},$$

$$\widehat{G}_i^*(x_1, k, s) = \frac{e^{\frac{1}{1-M^2} \left(shM - \left(x_1 + h + \frac{\Sigma(x_1)}{s} \right) \sqrt{s^2 + (1-M^2)k^2} \right)}}{2\sqrt{s^2 + (1-M^2)k^2}},$$

where λ has been defined at the section 2. As \widehat{G}_i is once again the Fourier-Laplace transform of the classical advective wave equation it is obvious that the new PML does not produce parasitical reflection. Applying the x_2 inverse Fourier transform to $\widehat{G}_i^*(x_1, k, s)$, we get

$$\widetilde{G}_i^*(x_1, x_2, s) = \frac{1}{4\pi} \int_{-\infty}^{+\infty} \frac{e^{\frac{1}{1-M^2} \left(shM - \left(x_1 + h + \frac{\Sigma(x_1)}{s} \right) \sqrt{s^2 + (1-M^2)k^2} \right)}}{2\sqrt{s^2 + (1-M^2)k^2}} e^{-ikx_2} dk, \quad (39)$$

We apply the change of variable $k = \frac{ps}{\sqrt{1-M^2}}$ and obtain:

$$\widetilde{G}_i^*(x_1, x_2, s) = \frac{1}{4\pi} \int_{-\infty}^{+\infty} \frac{e^{-\Sigma(x_1) \frac{\sqrt{1+p^2}}{1-M^2}} e^{s \left[\frac{(Mh - (x_1+h)\sqrt{1+p^2})}{1-M^2} - ip \frac{x_2}{\sqrt{1-M^2}} \right]}}{\sqrt{(1-M^2)(1+p^2)}} dp. \quad (40)$$

We now have to search a path in the complex plane such that

$$\frac{Mh - (x_1 + h)\sqrt{1+p^2}}{1-M^2} - ip \frac{x_2}{\sqrt{1-M^2}} = -t, \quad \text{for } t > 0, \quad (41)$$

For $t \geq t_0 = r - \frac{Mh}{1-M^2} > 0$ we define the functions $\gamma^\pm(t)$ by

$$\gamma^\pm(t) \equiv -i \left(\frac{t}{r} + \frac{Mh}{r(1-M^2)} \right) \sin \theta \pm \cos \theta \sqrt{\left(\frac{t}{r} + \frac{Mh}{r(1-M^2)} \right)^2 - 1},$$

and we introduce the Cagniard-de Hoop contour Γ defined as:

$$\Gamma = \Gamma^+ \cup \Gamma^-, \quad \Gamma^\pm = \left\{ p = \gamma^\pm(t) \right\}. \quad (42)$$

As for the acoustics case we easily deduce :

$$\widetilde{G}_i^*(x_1, x_2, s) = -\frac{1}{4\pi} \int_{\Gamma} \frac{e^{-\Sigma(x_1) \frac{\sqrt{1+p^2}}{1-M^2}} e^{s \left[\frac{(Mh - (x_1+h)\sqrt{1+p^2})}{1-M^2} - ip \frac{x_2}{\sqrt{1-M^2}} \right]}}{\sqrt{(1-M^2)(1+p^2)}} dp.$$

We use the parameterizations $p = \gamma^+(t)$ and $p = \gamma^-(t)$, for $t \geq t_0$, respectively along Γ^+ and Γ^- and remark that:

$$\left\{ \begin{array}{l} \bullet \frac{Mh - (x_1 + h)\sqrt{1 + p^2}}{1 - M^2} - ip \frac{x_2}{\sqrt{1 - M^2}} = -t, \quad (\text{by construction}), \\ \bullet \frac{dp}{(1 + p^2)^{\frac{1}{2}}} = \pm \frac{dt}{\left[\left(t + \frac{Mh}{1 - M^2} \right)^2 - r^2 \right]^{\frac{1}{2}}}, \quad \text{on } \Gamma^\pm, \\ \bullet -\Sigma(x_1) \frac{\sqrt{1 + p^2}}{1 - M^2} = -A(\mathbf{x}, t) \mp iB(\mathbf{x}, t), \quad \text{on } \Gamma^\pm \end{array} \right.$$

Therefore, since t goes from $+\infty$ to t_0 on Γ^+ and from t_0 to $+\infty$ on Γ^- :

$$\widetilde{G}_i(x_1, x_2, s) = \frac{1}{4\pi} \int_{t_0}^{+\infty} \frac{e^{-A(\mathbf{x}, t)} \cos(B(\mathbf{x}, t))}{\sqrt{1 - M^2} \sqrt{\left(t + \frac{Mh}{1 - M^2} \right)^2 - r^2}} e^{-st} dt.$$

It is then easy to conclude.

Numerical illustration. In figure 25 we compare three numerical experiments :

- (1) (top picture) the propagation of an advective wave in a large computational domain :
- (2) (middle picture) the same experiment but the change of variable (33) has been applied in the left and right hand layers ;
- (3) (bottom picture) in the last one a damping term has been added in the layers.

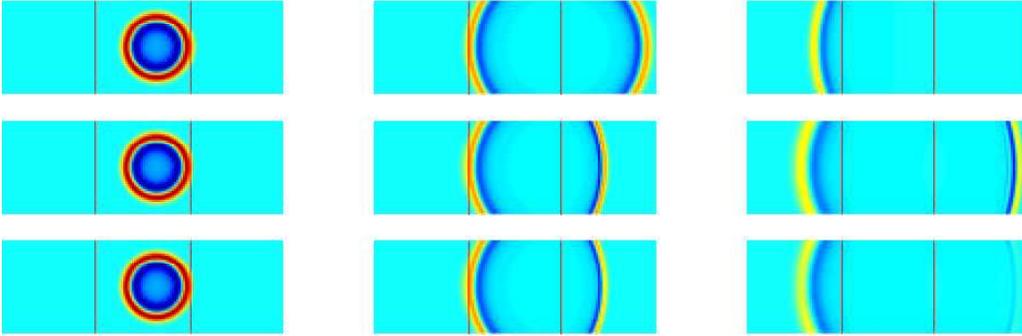


Fig. 25. Comparison between three experiments

If we compare the two first experiments we remark that the change of variable (33) slows down the wave in the right hand layer whereas it accelerate it in the left hand one (actually, this change of variable “makes the flow vanish”). The last experiment shows that the waves are properly damped in the PML.

3.2 Extension to the linearized Euler equations

Looking at the shape of slowness curve associated to the vorticity waves (a line orthogonal to the axis k_1/ω), we can reasonably assume that the change of variable (33), which translate the slowness curves of $M/(1 - M^2)$ to the right (see figure 26), does not generate instabilities.

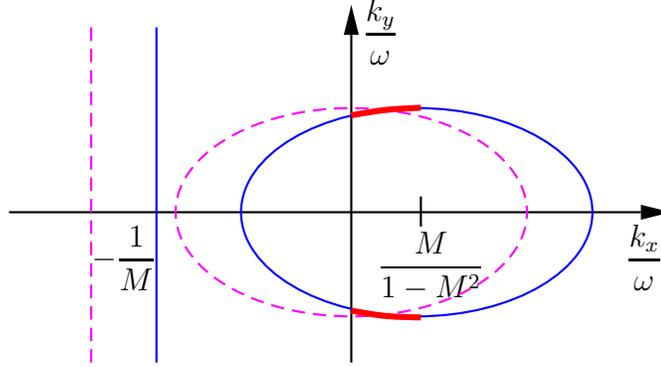


Fig. 26. The slowness curve before (in blue/solid) and after (in magenta/dashed) the change of variable

It is useful to introduce the new unknowns $s = p + u$ and $d = p - u$, and to rewrite the aeroacoustics equation as :

$$\left\{ \begin{array}{l} \frac{\partial s}{\partial t} + (1 + M) \frac{\partial s}{\partial x_1} + \frac{\partial v}{\partial x_2} = 0, \end{array} \right. \quad (43a)$$

$$\left\{ \begin{array}{l} \frac{\partial d}{\partial t} - (1 - M) \frac{\partial d}{\partial x_1} + \frac{\partial v}{\partial x_2} = 0, \end{array} \right. \quad (43b)$$

$$\left\{ \begin{array}{l} \frac{\partial v}{\partial t} + M \frac{\partial v}{\partial x_1} + \frac{1}{2} \left(\frac{\partial s}{\partial x_2} + \frac{\partial d}{\partial x_2} \right) = 0. \end{array} \right. \quad (43c)$$

Then the three steps of the construction of a stable PML are :

- (1) Write a transmission problem between $x_1 < 0$ and $x_1 > 0$.
- (2) Apply the change of variable (33) to obtain the following new equations in the domain $x_1 > 0$:

$$\left\{ \begin{array}{l} \frac{1}{1 - M} \frac{\partial s^*}{\partial t} + (1 + M) \frac{\partial s^*}{\partial x_1} + \frac{\partial v^*}{\partial x_2} = 0, \end{array} \right. \quad (44a)$$

$$\left\{ \begin{array}{l} \frac{1}{1 + M} \frac{\partial d^*}{\partial t} - (1 - M) \frac{\partial d^*}{\partial x_1} + \frac{\partial v^*}{\partial x_2} = 0, \end{array} \right. \quad (44b)$$

$$\left\{ \begin{array}{l} \frac{1}{1 - M^2} \frac{\partial v^*}{\partial t} + M \frac{\partial v^*}{\partial x_1} + \frac{1}{2} \left(\frac{\partial s^*}{\partial x_2} + \frac{\partial d^*}{\partial x_2} \right) = 0, \end{array} \right. \quad (44c)$$

that are coupled to (43) by the continuity conditions :

$$s^*(0, x_2, t) = s(0, x_2, t), \quad d^*(0, x_2, t) = d(0, x_2, t), \quad v^*(0, x_2, t) = v(0, x_2, t).$$

(3) Apply to (44) the usual PML model.

Remark 10 *The well-posedness of the transmission problem obtained after step 2 is guaranteed by the following theorem, whose proof, omitted here, is similar to the one of theorem (8).*

Theorem 11 *The following energy is conserved :*

$$E_2(t) = \frac{1}{2} \int_{\mathbb{R}^-} [s^2 + d^2 + 2v^2] + \frac{1}{2} \int_{\mathbb{R}^+} \left[\frac{s^{*2}}{1-M} + \frac{d^{*2}}{1+M} + 2\frac{v^{*2}}{1-M^2} \right]. \quad (45)$$

Comparison with the Hu's model. The PML recently proposed by Hu are close to the one we have presented here. Both are based on the same change of variable, the difference lies in the fact that Hu applies this change of variable in the whole domain whereas we only apply it for $x_1 > 0$. Therefore he does not need to impose transmission condition at the interface. Then he replace formally the derivatives with respect to x_1 by the operator $D_{x_1}^\sigma$. Finally he use the inverse change of variable in the whole domain to come back to the original variables. This inverse change of variable makes the operator $D_{x_1}^\sigma$ slightly more complicated.

3.3 Numerical Results

In figure (27) we represent the propagation of an advective wave in an uniform mean flow with $M = 0.5$ in open domain. The domain of interest is $[-5 ; 5]^2$ and we impose an initial condition $p = \exp(-4(x_1^2 + x_2^2) \ln(2))$. The width of the PML is $L = 1$ and the profile of the damping coefficient is $\sigma(x) = \sigma_0 x^2 / D$. We have represented the level lines of the pressure at time $t = 1, 3, 8, 30$ and 50. We have repeated the same experiment but with an initial condition

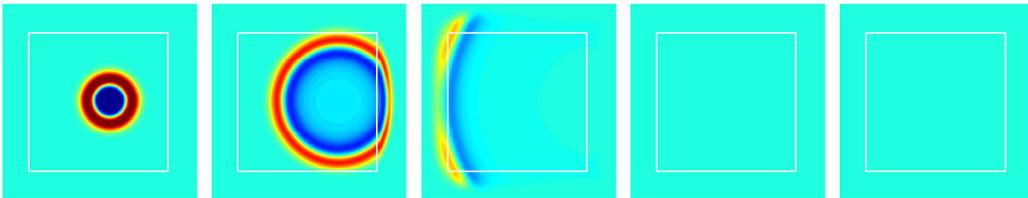


Fig. 27. Propagation of an advective wave $t = 1, 3, 8, 30$ and 50

$u = x_1 \exp(-(x_1^2 + x_2^2) \ln(2))$ and $v = -x_2 \exp(-(x_1^2 + x_2^2) \ln(2))$ designed to simulate the propagation of a vorticity wave. Figure 28 represent the level lines of the modulus of the velocity at time $t = 1, 3, 7, 11$ and 50.

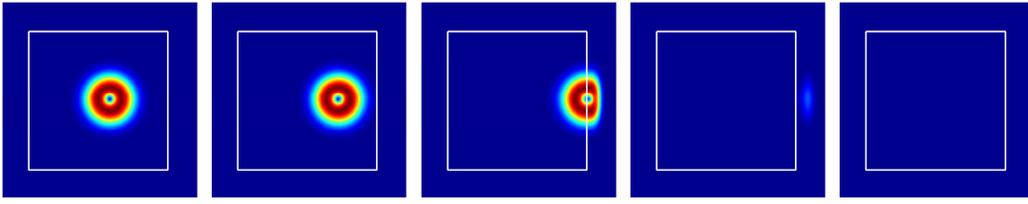


Fig. 28. Propagation of a vorticity wave $t= 1, 3, 7, 11$ and 50

A The case of a non-parallel mean-flow

The case of a non-parallel mean flow (with respect to the boundaries) is of interest for practical applications. Here we restrict ourselves to the case of the advective wave equation. Surprisingly, linearized Euler equations still arised open questions that are under study.

A.1 Construction of a vertical PML for the advective equation

A non-parallel mean flow is characterized by the Mach vector $\mathbf{M} = [M_1 ; M_2]^t$ and we set $M = \|\mathbf{M}\|$. The advective wave equation is then :

$$\frac{\partial^2 p}{\partial t^2} + 2M_1 \frac{\partial^2 p}{\partial t \partial x_1} + 2M_2 \frac{\partial^2 p}{\partial t \partial x_2} + 2M_1 M_2 \frac{\partial^2 p}{\partial x_1 \partial x_2} - (1-M_1^2) \frac{\partial^2 p}{\partial x_1^2} - (1-M_2^2) \frac{\partial^2 p}{\partial x_2^2} = 0.$$

The slowness curve associated to this equation is represented in figure A.1 (the set of unstable points for a vertical layer has been highlighted in red), it is an ellipse of center $C = (M_1/(1 - M^2), M_2/(1 - M^2))$. The construction of stabilized PML's is inspired by what has been done in the case of an horizontal mean flow. The novelty lies in the apparition of a new step (step (2.2))

- (1) Write a transmission problem between $x_1 < 0$ and $x_1 > 0$.
- (2.1) In the region $x_1 > 0$, get rid of the convective term by applying a change of variable :

$$p^*(x_1, x_2, t) = p\left(x_1, x_2, t - \frac{M_1}{1 - M^2}x_1 - \frac{M_2}{1 - M^2}x_2\right).$$

The new slowness curve (see figure A.2) still gives rise to instability if one applies classical PML. This is due to the presence of the cross-derivative with respect to x_1 and x_2 .

- (2.2) In the region $x_1 > 0$ we apply the second change of variable (which let invariant the axis $x_1 = 0$)

$$\tilde{x}_1 = \alpha x_1 \text{ and } \tilde{x}_2 = x_2 + \beta x_1.$$

Writing the equations in the new variables, one observes that the cross derivatives disappear if α and β are related by :

$$\beta = -\frac{M_1 M_2}{1 - M_1^2} \alpha.$$

Choosing $\alpha = 1$, we see that the new function

$$\tilde{p}(x_1, x_2, t) = p^* \left(x_1, x_2 - \frac{M_1 M_2}{1 - M_1^2} x_1, t \right)$$

satisfies the following equation, whose slowness curve is shown in Fig. A.3:

$$\frac{1}{1 - M^2} \frac{\partial^2 \tilde{p}}{\partial t^2} - (1 - M_1^2) \frac{\partial^2 \tilde{p}}{\partial x_1^2} - \left(1 - \frac{M_2^2}{1 - M_1^2}\right) \frac{\partial^2 \tilde{p}}{\partial x_2^2} = 0. \quad (\text{A.1})$$

(3) Apply the standard PML technique to (A.1).

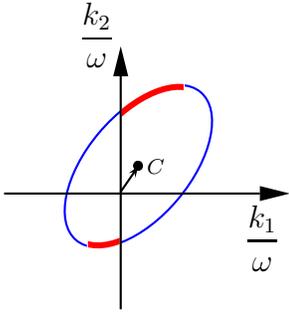


Fig. A.1. The slowness curve associated to the advective waves

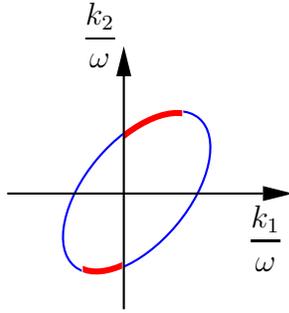


Fig. A.2. The slowness curve after the first change of variable

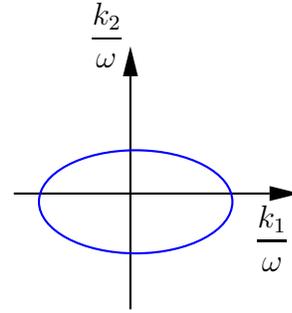


Fig. A.3. The slowness curve after the second change of variable

A.2 The corner problem

The solution we have adopted for corners is much less justified from a numerical point of view but appears to give satisfactory results (see Fig. A.4). Let us for instance suppose that the computational domain is the quarter-plane $\mathbb{R}^- \times \mathbb{R}^-$. In the horizontal and vertical layers, according to the previous section, we use the following models

$$\left\{ \begin{array}{l} \frac{1}{1 - M^2} \frac{\partial^2 \tilde{p}}{\partial t^2} - (1 - M_1^2) (D_{x_1}^\sigma)^2 \tilde{p} - \left(1 - \frac{M_2^2}{1 - M_1^2}\right) \frac{\partial^2 \tilde{p}}{\partial x_2^2} = 0 \quad (\text{vertical}) \\ \frac{1}{1 - M^2} \frac{\partial^2 \tilde{p}}{\partial t^2} - \left(1 - \frac{M_1^2}{1 - M_2^2}\right) \frac{\partial^2 \tilde{p}}{\partial x_1^2} - (1 - M_2^2) (D_{x_2}^\sigma)^2 \tilde{p} = 0 \quad (\text{horizontal}). \end{array} \right.$$

In the corner we have chosen to use the following equation in which variables x_1 and x_2 are not treated in a symmetric way!

$$\frac{1}{1 - M^2} \frac{\partial^2 \tilde{p}}{\partial t^2} - (1 - M_1^2)(D_{x_1}^\sigma)^2 \tilde{p} - (1 - \frac{M_2^2}{1 - M_1^2})(D_{x_2}^\sigma)^2 \tilde{p} = 0$$

We refer to [23] and present in figure A.4 a numerical result obtained with this method.

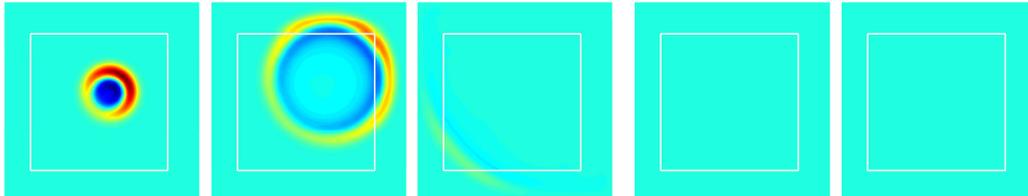


Fig. A.4. The case of a non-parallel mean flow, $t= 1\ 3\ 7\ 15$ and 50

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