



HAL
open science

Pseudo-conforming polynomial finite elements on quadrilaterals

Eric Dubach, Robert Luce, Jean-Marie Thomas

► **To cite this version:**

Eric Dubach, Robert Luce, Jean-Marie Thomas. Pseudo-conforming polynomial finite elements on quadrilaterals. *International Journal of Computer Mathematics*, 2009, 86 (10-11), pp.1798-1816. 10.1080/00207160902759342 . inria-00342656

HAL Id: inria-00342656

<https://inria.hal.science/inria-00342656>

Submitted on 27 Nov 2008

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

RESEARCH ARTICLE

Pseudo-conforming polynomial finite elements on quadrilaterals

Eric DUBACH*, Robert LUCE^{*,†}, Jean-Marie THOMAS*

(Received 00 Month 200x; in final form 00 Month 200x)

The aim of this paper is to present a new class of finite elements on quadrilaterals where the approximation is polynomial on each element K . In the case of Lagrange finite elements, the degrees of freedom are the values at the vertices and in the case of mixed finite elements the degrees of freedom are the mean values of the fluxes on each side. The degrees of freedom are the same as those of classical finite elements. However, in general, with this kind of finite elements, the resolution of second order elliptic problems leads to non conforming approximations. In the particular case when the finite elements are parallelograms, we can notice that our method is conform and coincides with the classical finite elements on structured meshes.

First, a motivation for the study of the Pseudo-conforming polynomial finite elements method is given, and the convergence of the method established. Then, numerical results that confirm the error estimates, predicted by the theory, are presented.

Keywords: Lagrange and mixed finite elements, polynomial approximation, non conforming approximation, quadrilateral meshes

AMS Subject Classification: 65N15, 65N15, 65N30

1. Introduction

Quadrilaterals and hexahedra are often used in meshers particularly in geophysical applications and in fluids mechanics. When the geometry and the medium are structured, regular rectangular meshes are used. Otherwise general convex quadrilaterals or hexahedra (or bricks) are used. Then, with isoparametric Lagrange finite elements ([1],[2],[6]) or mixed finite elements ([3],[5]), we must construct finite elements on the mesh by using multilinear mappings noted F to a reference rectangle or rectangular solid.

For Lagrange isoparametric finite elements the jacobian of these mappings leads to non polynomial basis functions on the elements of the mesh and introduces non polynomial matrices in the partial differential operators. For mixed finite elements, consequences are even worse since the use of the Piola transform to work on the reference element is effective only when the mapping is linear otherwise a loss of order of convergence is observed ([7]).

In this paper, we are interested in quadrilateral meshes. To build our finite elements, we consider a quadrilateral as a distortion of a parallelogram and the Lagrange basis functions are built under conditions of weak-continuity of the unknowns across the elements. The obtained finite elements are not conform but the conditions of weak-continuity are sufficient to ensure the expected order of convergence. Finite elements of lower degree are presented. We focus on the process to obtain the finite elements and we present some theoretical and technical results.

We use the following notations:

*Laboratoire de Mathématiques Appliquées, UMR 5142, Université de Pau et des Pays de l'Adour, BP 1155, 64013 Pau Cedex, France.

† INRIA Sud-Ouest

For a vector $\mathbf{v} \in \mathbb{R}^n$, $v = (v_1, \dots, v_n)$ and $|\mathbf{v}| = \left\{ \sum_{j=1}^n |v_j|^2 \right\}^{1/2}$. For a square matrix B , $\|B\|$ is the spectral norm.

For a triangle or a quadrilateral K , $|K|$ denotes the area of K , and $|\gamma|$ the length of an edge γ of K .

For a polyhedral domain K , we define

$$H^m(K) = \{v \in L^2(K); \partial^\alpha v \in L^2(K), \text{ for all } \alpha \text{ with } |\alpha| \leq m\}$$

equipped with the norm and the semi-norm

$$\|v\|_{m,K} = \left(\sum_{|\alpha| \leq m} \int_K |\partial^\alpha v|^2 dx \right)^{1/2}, \quad |v|_{m,K} = \left(\sum_{|\alpha|=m} \int_K |\partial^\alpha v|^2 dx \right)^{1/2}.$$

We consider also the following norm and semi-norm

$$\|v\|_{m,\infty,K} = \max_{|\alpha| \leq m} \left\{ \text{ess sup}_{x \in K} |\partial^\alpha v| \right\}, \quad |v|_{m,\infty,K} = \max_{|\alpha|=m} \left\{ \text{ess sup}_{x \in K} |\partial^\alpha v| \right\}.$$

Equally, we define

$$H(\text{div}, K) = \{\mathbf{q} \in L^2(K) \times L^2(K); \text{div}(\mathbf{q}) \in L^2(K)\}$$

equipped with the norm

$$\|\mathbf{q}\|_{H\text{div}(0,K)} = \left(\int_K |\mathbf{q}|^2 dx + \int_K |\text{div}(\mathbf{q})|^2 dx \right)^{1/2}.$$

$\mathbf{q} \in H^m(K)$ means that all the component of \mathbf{q} are in $H^m(K)$. Let $P(K)$ be the vectorial space $\{\mathbf{x} \in K \mapsto p(\mathbf{x}); p \in P\}$, where P is a N variables polynomial space and K is a domain in \mathbb{R}^N . For any integer k , P_k denotes the space of polynomial functions of degree $\leq k$, while Q_k is the space of polyomial functions of degree $\leq k$ in each variable.

For each polyhedral K , h_K denotes the diameter of K and ρ_K denotes the diameter of the largest ball contained in K .

2. The finite element geometry.

2.1 The geometry; vertex and face numbering.

Let K be a convex nondegenerated quadrilateral. Let $\{\mathbf{a}_i \in \mathbb{R}^2, 1 \leq i \leq 4\}$ be the vertices of K .

Two vertices which do not belong to the same edge of K are said to be opposite vertices. The center of a polyhedral is the isobarycenter of its vertices; we denote by \mathbf{a}_0 the center of K :

$$\mathbf{a}_0 = \frac{1}{4} \sum_{1 \leq i \leq 4} \mathbf{a}_i.$$

Let now $\{\gamma_m, 1 \leq m \leq 4\}$ be the set of the edges of K . Two edges without common vertex are said opposite edges. The vertex and face numbering is shown on Figure

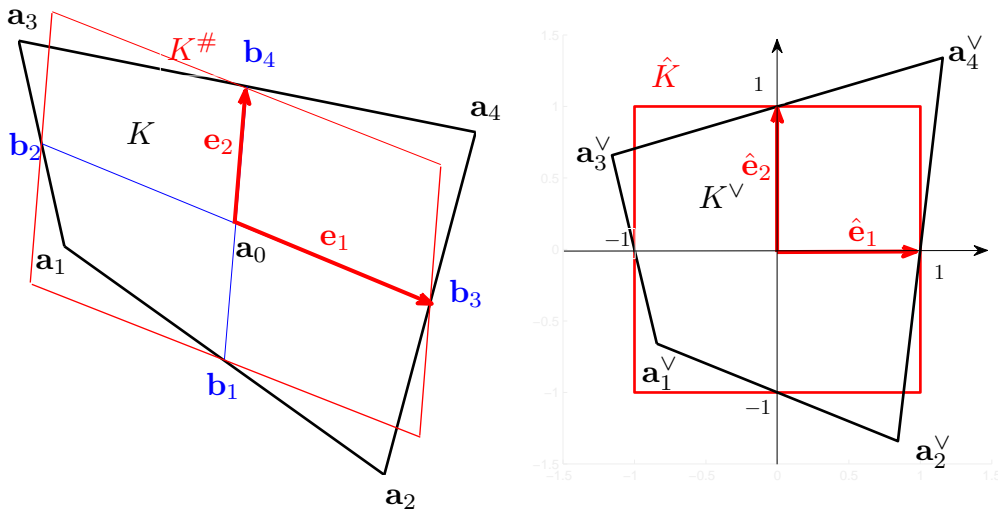


Figure 1. Numerotation

1. This numbering is such that:

$$\gamma_1 = (\mathbf{a}_1, \mathbf{a}_2), \gamma_2 = (\mathbf{a}_1, \mathbf{a}_3),$$

a_{5-m} opposite a_m , and

$$\gamma_{5-m} \text{ opposite } \gamma_m; \text{ for } m = 1, 2.$$

Last, let \mathbf{b}_m be the center of the face γ_m , for $m = 1, \dots, 4$, and let us introduce the vectors $\mathbf{e}_1, \mathbf{e}_2 \in \mathbb{R}^2$ defined by

$$\mathbf{e}_1 = \mathbf{a}_0 - \mathbf{b}_2 = \mathbf{b}_3 - \mathbf{a}_0, \quad \mathbf{e}_2 = \mathbf{a}_0 - \mathbf{b}_1 = \mathbf{b}_4 - \mathbf{a}_0.$$

Since K is assumed to be a nondegenerated quadrilateral, $(\mathbf{e}_1, \mathbf{e}_2)$ is a basis of \mathbb{R}^2 .

2.2 Affine-equivalent elements.

Let $\widehat{K} = [-1, +1]^2$ be the reference square. The vertices of \widehat{K} are denoted by $\widehat{\mathbf{a}}_i$, $1 \leq i \leq 4$ and the faces are denoted by $\widehat{\gamma}_m$, $1 \leq m \leq 4$.

We choose

$$\widehat{\mathbf{a}}_1 = \begin{pmatrix} -1 \\ -1 \end{pmatrix}, \quad \widehat{\mathbf{a}}_2 = \begin{pmatrix} +1 \\ -1 \end{pmatrix}$$

and the vertex and face numbering is made as previously. Let $\widehat{\mathbf{b}}_m$ be the center of the edge $\widehat{\gamma}_m$, for $m = 1, \dots, 4$. The canonical basis $(\widehat{\mathbf{e}}_1, \widehat{\mathbf{e}}_2)$ of \mathbb{R}^2 can be simply expressed with the vectors $\widehat{\mathbf{b}}_m$

$$\widehat{\mathbf{e}}_1 = -\widehat{\mathbf{b}}_2 \quad (= \widehat{\mathbf{b}}_3), \quad \widehat{\mathbf{e}}_2 = -\widehat{\mathbf{b}}_1 \quad (= \widehat{\mathbf{b}}_4).$$

Let B_K be the change of basis matrix given by

$$B_K \widehat{\mathbf{e}}_1 = \mathbf{e}_1, \quad B_K \widehat{\mathbf{e}}_2 = \mathbf{e}_2.$$

and F_K^\sharp be the invertible affine mapping

$$F_K^\sharp : \widehat{\mathbf{x}} \in \mathbb{R}^2 \rightarrow F_K^\sharp(\widehat{\mathbf{x}}) = \mathbf{a}_0 + B_K \widehat{\mathbf{x}}.$$

This mapping F_K^\sharp is the unique affine mapping such that

$$F_K^\sharp(\widehat{\mathbf{b}}_1) = \mathbf{b}_1, \quad F_K^\sharp(\widehat{\mathbf{b}}_2) = \mathbf{b}_2.$$

It is a bijection between \widehat{K} and its image

$$K^\sharp = F_K^\sharp(\widehat{K}).$$

As image of the reference square by an invertible affine mapping, K^\sharp is a parallelogram. The associated parallelogram of K being by definition the parallelogram which has the same face centers than K . We see that K^\sharp is the associated parallelogram of K and we have $K^\sharp = K$ if and only if K is a parallelogram. Let

$$K^\vee = (F_K^\sharp)^{-1}(K).$$

The parallelogram associated to the quadrilateral K^\vee is the reference square \widehat{K} . To be able to make the analysis of quadrangular finite element ([1]), we must precise the shape of the quadrangles that can be considered. In this purpose, we define in the next section the distortion of any element K with respect to K^\sharp .

2.3 Distortion parameters

Let \mathbf{d} be the vector of \mathbb{R}^2 given by

$$\mathbf{d} = \frac{1}{4}(\mathbf{a}_1 - \mathbf{a}_2 - \mathbf{a}_3 + \mathbf{a}_4). \quad (1)$$

We can interpret $2\mathbf{d}$ as a vector whose endpoints are the midpoints of the diagonals of the quadrilateral K . This means that the quadrilateral K is a parallelogram if and only if $\mathbf{d} = 0$. It is easy to see that the vertices of K^\sharp (the parallelogram associated to the quadrilateral K), are given by (see Figure 2)

$$\mathbf{a}_i^\sharp = \mathbf{a}_i - s_i \mathbf{d}, \quad 1 \leq i \leq 4$$

where

$$s_1 = s_4 = +1, \quad s_2 = s_3 = -1. \quad (2)$$

We have $K = K^\sharp$ if and only if $\mathbf{d} = 0$ in \mathbb{R}^{2*} .

DEFINITION 2.1 *The vector \mathbf{d} is named the distortion vector of K .*

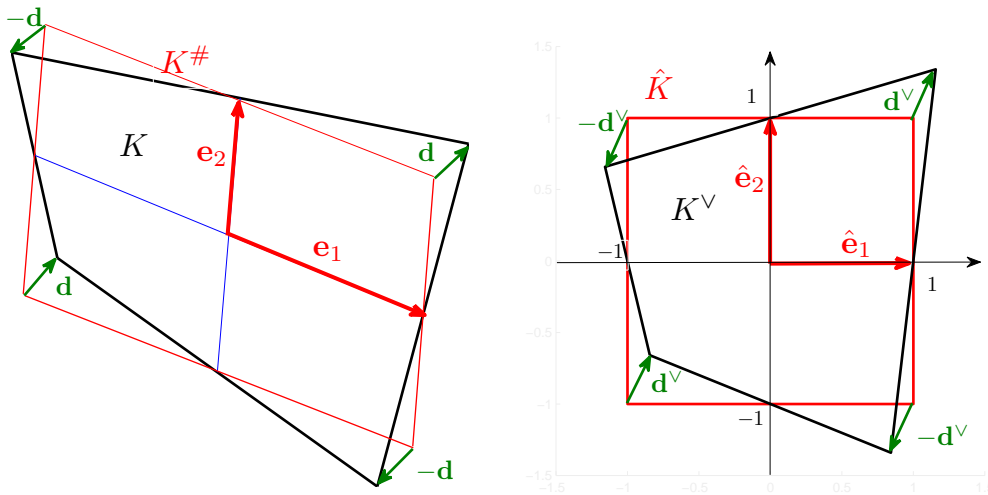


Figure 2. Distorsion vector

Let the distortion parameters, of K , δ_1 and δ_2 be such that

$$\mathbf{d} = \delta_1 \mathbf{e}_1 + \delta_2 \mathbf{e}_2 \tag{3}$$

where we recall that \mathbf{e}_m is given by $\mathbf{e}_m = \mathbf{a}_0 - \mathbf{b}_m$, $1 \leq m \leq 2$. These parameters are invariant by affine mapping; in particular for the distortion vector \mathbf{d}^\vee of K^\vee we have

$$\mathbf{d}^\vee = \delta_1 \hat{\mathbf{e}}_1 + \delta_2 \hat{\mathbf{e}}_2.$$

Since the mapping F_K^\sharp is invertible affine, K is a convex quadrilateral if and only if K^\vee is a convex quadrilateral. It is easy to show that K is a convex quadrilateral if and only if we have

$$|\delta_1| + |\delta_2| < 1. \tag{4}$$

Then K^\vee contains $B(\mathbf{0}, 1/\sqrt{2})$ the ball centered at the origin and of radius $1/\sqrt{2}$ and K^\vee is contained in the square $[-2, +2]^2$. The quadrilateral K is contained in the parallelogram

$$K^{2\sharp} = F_K^\sharp([-2, +2]^2).$$

This element $K^{2\sharp}$ is homothetic to K^\sharp with a ratio equal to 2. Then, we have the inequality

$$h_K \leq 2h_{K^\sharp}.$$

Last, we note that the Euclidean norm of the distortion vector of K satisfies

$$\frac{1}{4} \left(\sum_{1 \leq m \leq 2} |\delta_m| \right) \rho_{K^\sharp} \leq |\mathbf{d}| \leq \frac{1}{2} \left(\sum_{1 \leq m \leq 2} |\delta_m| \right) h_{K^\sharp}.$$

Now, we give the definition of a family of regular meshes.

DEFINITION 2.2 *Regular Mesh*

A family of quadrangular meshes is regular if and only if for each K the distortion parameters satisfy (4), and

$$\exists \sigma > 0; \quad \frac{h_{K^\sharp}}{\rho_{K^\sharp}} \leq \sigma.$$

We can notice that this definition corresponds to the classical definition given by P.G. Ciarlet ([2]) when the K 's are parallelogram.

3. Local error estimates

In this section we give some local error estimates without demonstration. The demonstration concerning the Lagrange finite elements can be found in ([10]) and with the same technics the results can be easily extended to the mixed finite elements.

3.1 Interpolation error estimates

3.1.1 Lagrange interpolation error estimates

Let P_K be a finite dimensional vectorial space of polynomial functions defined over the quadrilateral K . We assume that the set $S_K = \{\mathbf{a}_i, 1 \leq i \leq 4\}$ is P_K -unisolvent. Then necessarily, $\dim(P_K) = 4$. The basis functions of the Lagrange finite element (K, P_K, S_K) are noted $p_{i,K}$ and the P_K -Lagrange interpolation operator is noted Π_K : for every function u defined on the vertices of K ,

$$\Pi_K u = \sum_{1 \leq i \leq 4} u(\mathbf{a}_i) p_{i,K}.$$

The basis functions $p_{i,K}$ are functions defined by definition on K ; in fact, since they are polynomial, we consider them as functions defined on $K^{2\sharp}$.

PROPOSITION 3.1 *Let us assume that the distortion parameters of K satisfy (4), that the set S_K is P_K -unisolvent and that the inclusion $P_1(K) \subset P_K$ holds. Moreover, let r be an integer sufficiently large for the the inclusion $P_K \subseteq P_r(K)$ to hold. Then there exists a constant c_r , which depends only on r , such that for every $u \in H^2(K)$,*

$$\|u - \Pi_K u\|_{1,K} \leq c_r \frac{h_{K^\sharp}^2}{\rho_{K^\sharp}} \left(\sum_{1 \leq i \leq 4} \|p_{i,K}\|_{0,\infty,K^{2\sharp}} \right) |u|_{2,K}. \quad (5)$$

3.1.2 *Hdiv interpolation error estimates*

Let $\Psi_K = P_K \times P_K$ be a finite dimensional vectorial space of polynomial functions defined over the quadrilateral K . We assume that the set $\Sigma_K = \left\{ \mathbf{w} \rightarrow \frac{1}{|\gamma_m|} \int_{\gamma_m} \mathbf{w} \cdot \mathbf{n} \, d\sigma; 1 \leq m \leq 4 \right\}$ is Ψ_K -unisolvent. The basis functions of the mixed finite element (K, Ψ_K, Σ_K) are noted $\psi_{m,K}$ and the Ψ_K -Withney interpolation operator is noted Π_K^W : for every function \mathbf{p} such that $\int_{\gamma_m} \mathbf{p} \cdot \mathbf{n} \, d\sigma; 1 \leq m \leq 4$ exist

$$\Pi_K^W \mathbf{p} = \sum_{1 \leq m \leq 4} \frac{1}{|\gamma_m|} \int_{\gamma_m} \mathbf{p} \cdot \mathbf{n} \, d\sigma \, \psi_{m,K}.$$

The basis functions $\psi_{m,K}$ are considered as functions defined on $K^{2\sharp}$.

PROPOSITION 3.2 *Let us assume that the distortion parameters of K satisfy (4), that the set Σ_K is $P_K \times P_K$ -unisolvent and that the inclusion $P_0(K)^2 \oplus \mathbf{x}P_0(K) \subset P_K \times P_K$ holds. Moreover, let r be an integer sufficiently large for the the inclusion $P_K \times P_K \subseteq P_r(K) \times P_r(K)$ to hold. Then there exists a constant c_r , which depends only on r , such that for every $\mathbf{p} \in H^1(K)$,*

$$\|\mathbf{p} - \Pi_K^W \mathbf{p}\|_{H(\text{div},K)} \leq c_r \frac{h_{K^\sharp}^2}{\rho_{K^\sharp}} \left(\sum_{1 \leq m \leq 4} \|\psi_{m,K}\|_{0,\infty,K^{2\sharp}} \right) |\mathbf{p}|_{1,K}. \quad (6)$$

PROPOSITION 3.3 *We suppose that there exists an integer r sufficiently large such that $P_K \times P_K \subseteq P_r(K) \times P_r(K)$. Then, for every $\mathbf{q}_h \in P_K \times P_K$ there exists a constant c_r depending only on r such that*

$$\|\mathbf{q}_h\|_{1,K^{2\sharp}} \leq c_r \frac{1}{\rho_{K^\sharp}} \|\mathbf{q}_h\|_{0,K^{2\sharp}}. \quad (7)$$

3.2 *error face estimates*

For $u \in H^1(K)$ we note $\pi_{\gamma_m}^k u$ the best approximation of the trace of u in $L^2(\gamma_m)$ by a polynomial P_k .

LEMMA 3.4 *Assume (4); then there exists a constant C , independent of the distortion parameters, such that for every $u \in H^1(K^\vee)$ and every m with $1 \leq m \leq 4$*

$$\|u\|_{0,\gamma_m^\vee} \leq C \|u\|_{1,K^\vee}.$$

PROPOSITION 3.5 *Assume that the distortion parameters of K satisfy (4). Then there exists a constant C , independent of the geometry of K , such that: $\forall u \in H^1(K)$ and $\forall m$ with $1 \leq m \leq 4$, we have*

$$\|u - \pi_{\gamma_m}^0 u\|_{0,\gamma_m} \leq C h_{K^\sharp}^{1/2} \left(\frac{h_{K^\sharp}}{\rho_{K^\sharp}} \right)^{1/2} |u|_{1,K}. \quad (8)$$

We can notice that $\pi_{\gamma_m}^0 u$ corresponds to the mean value of u on the face γ_m of K .

PROPOSITION 3.6 *Assume that the distortion parameters of K satisfy (4). Then there exists a constant C , independent of the geometry of K , such that: $\forall u \in$*

$H^2(K)$ and $\forall m$ with $1 \leq m \leq 4$, we have

$$\|u - \pi_{\gamma_m}^1 u\|_{0,\gamma_m} \leq C h_{K^\sharp}^{3/2} \left(\frac{h_{K^\sharp}}{\rho_{K^\sharp}}\right)^{1/2} |u|_{2,K}. \tag{9}$$

4. The model problem and the patch tests

We consider the second order elliptic model problem:

$$\begin{cases} -div(A \mathbf{grad} u) = f & \text{in } \Omega, \\ u = 0 & \text{on } \Gamma. \end{cases} \tag{10}$$

where $A = (a_{i,j})$ is a symmetric matrix satisfying

$$\forall x \in \bar{\Omega}, \forall \xi \in \mathbb{R}^2, \quad c \sum_{i=1}^2 \xi_i^2 \leq \sum_{i,j=1}^2 a_{i,j}(x) \xi_i \xi_j \leq c^{-1} \sum_{i=1}^2 \xi_i^2,$$

and $\Gamma := \partial\Omega$ is the boundary of a polyhedral domain $\Omega \subset \mathbb{R}^2$. Let \mathcal{T}_h be a triangulation of Ω into quadrilaterals. Let $\partial\mathcal{T}_h$ denotes the set of the edges of the elements of \mathcal{T}_h and $\partial\mathcal{T}_h \setminus \partial\Omega$ denotes the set of interior edges. For each element γ of $\partial\mathcal{T}_h \setminus \partial\Omega$, there exist K^+ and K^- in \mathcal{T}_h such that $\bar{K}^+ \cap \bar{K}^- = \gamma$. The unitary outward normal of K^+ is noted \mathbf{n}^+ and the normal of a face is defined by $\mathbf{n} = \mathbf{n}^+$. For each subset γ of $\partial\Omega$, \mathbf{n} denotes the unitary outward normal of Ω .

4.1 Variational formulation and error estimate

The variational problem associated to (10) is: find $u \in H_0^1(\Omega)$ such that

$$\forall v \in H_0^1(\Omega) \quad \int_{\Omega} A \mathbf{grad} u \cdot \mathbf{grad} v dx = \int_{\Omega} f v dx. \tag{11}$$

We consider

$$V_{\mathcal{T}_h} = \{v \in L^2(\Omega); v|_K \in H^1(K) \text{ for each } K \in \mathcal{T}_h\}$$

and

$$V_h = \{v_h \in L^2(\Omega); v_h|_K \in P_K \text{ for each } K \in \mathcal{T}_h\}.$$

Where P_K is a polynomial space. A non conforming finite element method for problem (11) is: find $u_h \in V_h$ such that

$$\forall v_h \in V_h, \quad \sum_{K \in \mathcal{T}_h} \int_K A \mathbf{grad} u_h \cdot \mathbf{grad} v_h dx = \int_{\Omega} f v_h dx. \tag{12}$$

For $v, w \in H_0^1(\Omega) + V_{\mathcal{T}_h}$ we define

$$a_h(v, w) = \sum_{K \in \mathcal{T}_h} \int_K A \mathbf{grad} \cdot v \mathbf{grad} w dx$$

and

$$\|v\|_{1,h} = \left(\sum_{K \in \mathcal{T}_h} \|v\|_{1,K}^2 \right)^{1/2}, \quad |v|_{1,h} = \left(\sum_{K \in \mathcal{T}_h} |v|_{1,K}^2 \right)^{1/2}.$$

Let us define the jump of $w_h \in V_h$ on γ . If γ is in $\partial\mathcal{T}_h \setminus \partial\Omega$ then $[w_h] = w_h^+ - w_h^-$ where w_h^\pm is the trace on γ of $w_h^\pm \in H^1(K^\pm)$ else $[w_h]$ represents the trace on γ of $w_h \in H^1(K)$.

Since $a_h(\cdot, \cdot)$ is uniformly $V_{\mathcal{T}_h}$ elliptic, the following basic error estimate (approximation and consistency error) hold (see [1], [6], [8]).

$$\|u - u_h\|_{1,h} \leq c \left(\inf_{w_h \in V_h} \|u - w_h\|_{1,h} + \sup_{0 \neq w_h \in V_h} \frac{|a_h(u, w_h) - (f, w_h)|}{\|w_h\|_{1,h}} \right) \quad (13)$$

with

$$a_h(u, w_h) - (f, w_h) = \sum_{\gamma \in \mathcal{T}_h} \int_{\gamma} \frac{\partial u}{\partial n} [w_h] ds.$$

We suppose that the solution u of (10) is in $H^2(\Omega)$ and the mesh is regular.

PROPOSITION 4.1 *Approximation error*

First of all we assume that for any K , the set $\{a_i, 1 \leq i \leq 4\}$ is P_K -unisolvent. Secondly we suppose that $\exists r > 0 \forall K P_1(K) \subset P_K \subset P_r(K)$. Moreover we assume that the basis functions $p_{i,K}$ of P_K satisfy $\exists C > 0 \|p_{i,K}\|_{0,\infty,K^{2\#}} < C$.

Under these three assumptions, we have

$$\inf_{w_h \in V_h} \|u - w_h\|_{1,h} \leq Ch|u|_{2,\Omega}.$$

Proof Using Proposition 3.1, we have immediatly

$$\left(\sum_{K \in \mathcal{T}_h} \|u - \Pi_K u\|_{1,h} \right)^{1/2} \leq Ch|u|_{2,\Omega}$$

where C is a constant independent of the mesh. ■

PROPOSITION 4.2 *Consistency error*

We suppose that the Patch Test is satisfied, namely

$$\forall w_h \in V_h, \quad \forall \gamma \in \partial\mathcal{T}_h \quad \int_{\gamma} [w_h] ds = 0,$$

then

$$|a_h(u, w_h) - (f, w_h)| \leq Ch|u|_{2,\Omega} \|w_h\|_{1,h}.$$

Proof Let γ be in $\partial\mathcal{T}_h \setminus \partial\Omega$, we have $\int_{\gamma} \frac{\partial u}{\partial \mathbf{n}} [w_h] d\sigma = \int_{\gamma} \frac{\partial u}{\partial \mathbf{n}^+} (w_h^+ - w_h^-) d\sigma$ where w_h satisfies $\int_{\gamma} w_h^+ d\sigma = \int_{\gamma} w_h^- d\sigma$. Therefore, dividing by $|\gamma|$, we have $\overline{w_h^+}^{\gamma} = \overline{w_h^-}^{\gamma}$.

Thus, we obtain

$$\int_{\gamma} \frac{\partial u}{\partial \mathbf{n}} [w_h] d\sigma = \int_{\gamma} \frac{\partial u}{\partial \mathbf{n}^+} (w_h^+ - \overline{w_h^+}^{\gamma}) d\sigma - \int_{\gamma} \frac{\partial u}{\partial \mathbf{n}^-} (w_h^- - \overline{w_h^-}^{\gamma}) d\sigma.$$

Obviously, for each constant c we have

$$\int_{\gamma} \frac{\partial u}{\partial \mathbf{n}^+} (w_{h^+} - \overline{w_{h^+}^{\gamma}}) d\sigma = \int_{\gamma} (\mathbf{grad} u \cdot \mathbf{n}^+ - c) (w_{h^+} - \overline{w_{h^+}^{\gamma}}) d\sigma.$$

As γ is flat face, \mathbf{n}^+ is a constant vector on γ and it can be extended to K^+ . Since $u \in H^2(\Omega)$, $\mathbf{grad} u \cdot \mathbf{n}^+ \in H^1(K^+)$. From (9) we have

$$\begin{aligned} \left| \int_{\gamma} (\mathbf{grad} u \cdot \mathbf{n}^+ - \pi_{\gamma}^0(\mathbf{grad} u \cdot \mathbf{n}^+)) (w_{h^+} - \overline{w_{h^+}^{\gamma}}) d\sigma \right| \\ \leq C h \|\mathbf{grad} u \cdot \mathbf{n}^+\|_{1,K^+} |w_h|_{1,K^+} \leq C h \|u\|_{2,K^+} |w_h|_{1,K^+} \end{aligned}$$

and finally

$$\left| \int_{\gamma} \frac{\partial u}{\partial \mathbf{n}} [w_h] d\sigma \right| \leq C h \left(\|u\|_{2,K^+} |w_h|_{1,K^+} + \|u\|_{2,K^-} |w_h|_{1,K^-} \right).$$

The result, for each $\gamma \subset \partial\Omega$, is similar

$$\left| \int_{\gamma} \frac{\partial u}{\partial \mathbf{n}} [w_h] d\sigma \right| \leq C h \|u\|_{2,K} |w_h|_{1,K}.$$

Summing on all faces γ_m , the right hand side of the inequality on each element K appears at most 4 times. Thus, the expected results hold. ■

Consequently, the pseudo-conforming Lagrange finite element method converges with the order 1.

4.2 Mixed formulation and error estimate

In the classical mixed formulation ([3], [5]) we introduce the new variable $\mathbf{p} = A \mathbf{grad} u$ and the mixed variational formulation for (10) is: find $u \in L^2(\Omega)$ and $\mathbf{p} \in H(\text{div}, \Omega)$ such that

$$\int_{\Omega} \text{div} \mathbf{p} v dx - \int_{\Omega} f v dx = 0 \quad \forall v \in L^2(\Omega), \quad (14)$$

$$\int_{\Omega} A^{-1} \mathbf{p} \cdot \mathbf{q} - \int_{\Omega} u \text{div} \mathbf{q} dx = 0 \quad \forall \mathbf{q} \in H(\text{div}, \Omega). \quad (15)$$

We consider

$$M_h = \{v_h \in L^2(\Omega); v_h|_K \in P_0 \text{ for each } K \in \mathcal{T}_h\},$$

$$L_{\mathcal{T}_h} = \{\mathbf{q} \in L^2(\Omega) \times L^2(\Omega); \mathbf{q}|_K \in H(\text{div}, K) \text{ for each } K \in \mathcal{T}_h\}$$

and

$$L_h = \{ \mathbf{q}_h \in L^2(\Omega) \times L^2(\Omega); \mathbf{q}_h|_K \in P_K \times P_K \text{ for each } K \in \mathcal{T}_h \},$$

where P_K is a polynomial space.

For $\mathbf{p} \in H(\text{div}, \Omega) + \mathcal{T}_h$, we define

$$\|\mathbf{p}\|_{H\text{div}(0,h)}^2 = \sum_{K \in \mathcal{T}_h} \|\mathbf{p}\|_{H(\text{div},K)}^2.$$

Let us notice that the space M_h is defined as usually, and $L_{\mathcal{T}_h} \not\subseteq H(\text{div}, \Omega)$. Therefore the non-conformity to study concerns the approximation of \mathbf{q} .

For any $(u, \mathbf{p}, \mathbf{q}) \in L^2(\Omega) \times H(\text{div}, \Omega) \times H(\text{div}, \Omega) + L^2(\Omega) \times L_{\mathcal{T}_h} \times L_{\mathcal{T}_h}$ we define

$$c_h(u, \mathbf{p}, \mathbf{q}) = \sum_{K \in \mathcal{T}_h} \int_K A^{-1} \mathbf{p} \cdot \mathbf{q} - \sum_{K \in \mathcal{T}_h} \int_K u \text{div } \mathbf{q} \, dx.$$

A non conforming mixed finite element method for problem (11) is: find $u_h \in M_h$ and $\mathbf{q}_h \in L_h$ such that

$$\sum_{K \in \mathcal{T}_h} \int_K v_h \text{div } \mathbf{p}_h \, dx - \sum_{K \in \mathcal{T}_h} \int_K f v_h \, dx = 0 \quad \forall v_h \in M_h, \quad (16)$$

$$\sum_{K \in \mathcal{T}_h} \int_K A^{-1} \mathbf{p}_h \cdot \mathbf{q}_h - \sum_{K \in \mathcal{T}_h} \int_K u_h \text{div } \mathbf{q}_h \, dx = 0 \quad \forall \mathbf{q}_h \in L_h. \quad (17)$$

If the following *inf – sup* condition is satisfied:

$$\inf_{\{v_h \in M_h; \|u_h\|_{0,\Omega}=1\}} \sup_{\{\mathbf{q}_h \in L_h, \|\mathbf{q}_h\|_{H\text{div}(0,h)}=1\}} b(u_h, \mathbf{q}_h) \geq \beta > 0, \quad (18)$$

where $b(u_h, \mathbf{q}_h) = \sum_{K \in \mathcal{T}_h} \int_K u_h \text{div } \mathbf{q}_h \, dx$, then the problem (16),(17) admits a unique solution and we have the *a priori* error estimate

$$\|\mathbf{p} - \mathbf{p}_h\|_{H\text{div}(0,h)} + \|u - u_h\|_{0,h} \leq c \left(\inf_{v_h \in M_h} \|u - v_h\|_{0,h} + \inf_{\mathbf{q}_h \in L_h} \|\mathbf{p} - \mathbf{q}_h\|_{H\text{div}(0,h)} + \sup_{0 \neq \mathbf{q}_h \in L_h} \frac{|c_h(u, \mathbf{p}, \mathbf{q}_h)|}{\|\mathbf{q}_h\|_{0,h}} \right).$$

Using the Green formula : $\int_K u \text{div}(\mathbf{q}_h) dx = - \int_K \mathbf{grad} u \cdot \mathbf{q}_h dx + \int_{\partial K} u \mathbf{q}_h \cdot \mathbf{n} d\sigma$ we prove that

$$c_h(u, \mathbf{p}, \mathbf{q}_h) = \sum_{\gamma \in \partial \mathcal{T}_h} \int_{\gamma} u [\mathbf{q}_h \cdot \mathbf{n}] d\sigma.$$

Now we suppose that the solution u of (10) is in $H^2(\Omega)$ and the mesh is regular.

PROPOSITION 4.3 *inf – sup condition*

We assume first that for all K , Σ_K is Ψ_K -unisolvent. Secondly we suppose that for each $\mathbf{q}_h \in L_h$, $\text{div}(\mathbf{q}_h) \in M_h$. Moreover we assume that the basis functions $\psi_{m,K}$

of Ψ_K satisfy $\exists C > 0 \|\psi_{m,K}\|_{0,\infty,K^{2\#}} < C$.

Under these three assumptions the inf – sup condition (18) holds.

Proof Since the domain Ω is regular, the inf – sup condition on the continuous problem (cf [3], [5]) gives :

For each $u \in L^2(\Omega)$, there exists $\mathbf{p} \in H^1(\Omega)$ such that $div(\mathbf{p}) = u$ and the estimate $\|\mathbf{p}\|_{1,\Omega} \leq C\|u\|_{0,\Omega}$ holds with a constant C independant of the mesh.

Therefore, this property is true for each $u_h \in M_h$. Let $\mathbf{p}_h = \Pi_h^W \mathbf{p}$ be the Withney-interpolant of \mathbf{p} in L_h and we want to prove that $\|\mathbf{p}_h\|_{Hdiv(0,h)} \leq C\|u_h\|_{0,\Omega}$. Using the assumption 3, we have $div(\mathbf{p}_h) = div(\mathbf{p})$ on each K . Furthermore, for each \mathbf{x} in K , we have

$$|\mathbf{p}_h(\mathbf{x})| \leq \sum_{1 \leq m \leq 4} \frac{1}{|\gamma_m|} \left| \int_{\gamma_m} \mathbf{p} \cdot \mathbf{n} \, d\sigma \right| |\psi_{m,K}(\mathbf{x})|$$

then

$$\|\mathbf{p}_h\|_{0,K} \leq \sum_{1 \leq m \leq 4} \|\mathbf{p} \cdot \mathbf{n}\|_{0,\gamma_m} \sum_{1 \leq m \leq 4} \|\psi_{m,K}\|_{0,\infty,K}$$

and using lemma 3.4 and the assumption 2 we obtain

$$\|\mathbf{p}_h\|_{0,K} \leq C\|\mathbf{p}\|_{1,K}.$$

Equally, for each \mathbf{x} in K , we have

$$|div(\mathbf{p}_h(\mathbf{x}))| \leq \sum_{1 \leq m \leq 4} \frac{1}{|\gamma_m|} \left| \int_{\gamma_m} \mathbf{p} \cdot \mathbf{n} \, d\sigma \right| |div(\psi_{m,K}(\mathbf{x}))|,$$

since $div(\psi_{m,K}(\mathbf{x}))$ is constant on K , we deduce

$$\|div \mathbf{p}_h\|_{0,K} \leq C\|\mathbf{p}\|_{1,K}.$$

Finally we have

$$\|\mathbf{p}_h\|_{Hdiv(0,h)} \leq C\|\mathbf{p}\|_{1,\Omega} \leq C\|u_h\|_{0,\Omega}.$$

We notice that $b(u_h, \mathbf{p}_h) = \|u_h\|_{0,\Omega}^2$ and conclude that

$$\begin{aligned} \inf_{\{v_h \in M_h; \|u_h\|_{0,\Omega}=1\}} \sup_{\{\mathbf{q}_h \in L_h, \mathbf{q}_h \neq 0\}} \frac{b(u_h, \mathbf{q}_h)}{\|\mathbf{q}_h\|_{Hdiv(0,h)}} &\geq \inf_{\{v_h \in M_h; \|u_h\|_{0,\Omega}=1\}} \frac{b(u_h, \mathbf{p}_h)}{\|\mathbf{p}_h\|_{Hdiv(0,h)}} \\ &\geq \frac{1}{C} > 0. \end{aligned}$$

■

PROPOSITION 4.4 *Approximation error*

We assume first that for any K , Σ_K is Ψ_K -unisolvent. Secondly we suppose that $\exists r > 0 \forall K P_0(K)^2 \oplus \mathbf{x}P_0(K) \subset \Psi_K \subset P_r(K) \times P_r(K)$. Moreover we assume that the basis functions $\psi_{m,K}$ of Ψ_K satisfy $\exists C > 0 \|\psi_{m,K}\|_{0,\infty,K^{2\#}} < C$.

Under these three assumptions we have

$$\inf_{\mathbf{q}_h \in L_h} \|\mathbf{p} - \mathbf{q}_h\|_{Hdiv(0,h)} \leq Ch|u|_{2,\Omega}.$$

Proof Since $\mathbf{p} = \mathbf{Agrad}u$ and using Proposition 3.2 , we have immediatly

$$\left(\sum_{K \in \mathcal{T}_h} \|\mathbf{p} - \Pi_K^W \mathbf{p}\|_{H(div,K)} \right)^{1/2} \leq Ch|\mathbf{Agrad}u|_{1,\Omega} \leq Ch|u|_{2,\Omega}$$

where C is a constant independent of the mesh. ■

Remark: The approximation error on u_h does not raise problem and is bounded by $Ch|u|_{1,\Omega}$.

PROPOSITION 4.5 *Consistency error*

If the Patch Test conditions are satisfied, namely

$$\forall \mathbf{q}_h \in V_h, \quad \forall \gamma \in \partial \mathcal{T}_h \quad \int_{\gamma} [\mathbf{q}_h \cdot \mathbf{n}] d\sigma = 0,$$

and

$$\forall \mathbf{q}_h \in V_h, \quad \forall \gamma \in \partial \mathcal{T}_h \quad \int_{\gamma} \sigma[\mathbf{q}_h \cdot \mathbf{n}] d\sigma = 0,$$

then

$$|c_h(u, \mathbf{p}, \mathbf{q}_h)| \leq Ch|u|_{2,\Omega} \|w_h\|_{1,h}.$$

Proof Let γ be in $\partial \mathcal{T}_h \setminus \partial \Omega$, we have $\int_{\gamma} u[\mathbf{q}_h \cdot \mathbf{n}] d\sigma = \int_{\gamma} u(\mathbf{q}_h^+ \cdot \mathbf{n}^+ - \mathbf{q}_h^- \cdot \mathbf{n}^-) d\sigma$.

Since $\int_{\gamma} \mathbf{q}_h^+ \cdot \mathbf{n}^+ d\sigma = \int_{\gamma} \mathbf{q}_h^- \cdot \mathbf{n}^- d\sigma$ we have $\pi_{\gamma}^0(\mathbf{q}_h^+ \cdot \mathbf{n}^+) = \pi_{\gamma}^0(\mathbf{q}_h^- \cdot \mathbf{n}^-)$.

Consequently,

$$\int_{\gamma} u(\mathbf{q}_h^+ \cdot \mathbf{n}^+ - \mathbf{q}_h^- \cdot \mathbf{n}^-) d\sigma = \int_{\gamma} u - (\mathbf{q}_h^+ \cdot \mathbf{n}^+ - \pi_{\gamma}^0(\mathbf{q}_h^+ \cdot \mathbf{n}^+)) d\sigma - \int_{\gamma} u - (\mathbf{q}_h^- \cdot \mathbf{n}^- - \pi_{\gamma}^0(\mathbf{q}_h^- \cdot \mathbf{n}^-)) d\sigma.$$

So, for each constant c_0 and c_1 we have

$$\int_{\gamma} u(\mathbf{q}_h^+ \cdot \mathbf{n}^+ - \pi_{\gamma}^0(\mathbf{q}_h^+ \cdot \mathbf{n}^+)) d\sigma = \int_{\gamma} (u - c_0 + c_1 \sigma)(\mathbf{q}_h^+ \cdot \mathbf{n}^+ - \pi_{\gamma}^0(\mathbf{q}_h^+ \cdot \mathbf{n}^+)) d\sigma$$

and

$$\left| \int_{\gamma} (u - \pi_{\gamma}^1 u)(\mathbf{q}_h^+ \cdot \mathbf{n}^+ - \pi_{\gamma}^0(\mathbf{q}_h^+ \cdot \mathbf{n}^+)) d\sigma \right| \leq \|u - \pi_{\gamma}^1 u\|_{0,\gamma} \|\mathbf{q}_h^+ - \pi_{\gamma}^0(\mathbf{q}_h^+ \cdot \mathbf{n}^+)\|_{0,\gamma}.$$

From Propositions 3.5, 3.6 and 3.3 we deduce that

$$\begin{aligned} \left| \int_{\gamma} u \mathbf{q}_h^+ \cdot \mathbf{n}^+ d\sigma \right| &\leq ch^2 \|\mathbf{q}_h^+\|_{1,K^+} |u|_{2,K^+} \\ &\leq ch \|\mathbf{q}_h^+\|_{0,K^{+2\#}} |u|_{2,K^+} \end{aligned}$$

and finally

$$\left| \int_{\gamma} u[\mathbf{q}_h \cdot \mathbf{n}] d\sigma \right| \leq ch \left(\|\mathbf{q}_h^+\|_{0,K^{+2\sharp}} |u|_{2,K^+} + \|\mathbf{q}_h^-\|_{0,K^{-2\sharp}} |u|_{2,K^-} \right).$$

We sum on all the faces γ . In the right hand side of the inequality an element K appears at most 4 times, so we have

$$\begin{aligned} \left| \sum_{\gamma \in \partial \mathcal{T}_h} \int_{\gamma} u[\mathbf{q}_h \cdot \mathbf{n}] d\sigma \right| &\leq ch \left(\sum_{K \in \mathcal{T}_h} \|\mathbf{q}_h\|_{0,K^{2\sharp}} \right) |u|_{2,\Omega} \\ &\leq ch \|\mathbf{q}_h\|_{0,\Omega} |u|_{2,\Omega}. \end{aligned}$$

■

Consequently, the pseudo-conforming mixed finite element converges with order 1.

5. Polynomial finite elements

This section is devoted to the construction of polynomial finite elements on quadrilaterals satisfying the assumptions used in 4. In the first subsection we study the case of Lagrange finite elements and in the second the case of Raviart-Thomas finite elements. For each finite element we give explicitly the basic functions.

5.1 Lagrange finite elements

Note that $P_k = \left\{ q = q^\vee \circ \left(F_K^\sharp \right)^{-1}; q^\vee \in P_k \right\}$. The same property is not true for the space Q_k . Therefore we introduce the space:

$$Q_k^K = \left\{ q^\vee \circ \left(F_K^\sharp \right)^{-1}; q^\vee \in Q_k \right\}$$

which is a subspace of P_{2k} .

If we choose $P_K = Q_1^K$ then (K, P_K, S_K) is a finite element, but the approximation u_h of the solution of (10) obtained with this element does not converge without additional assumptions (see the numerical results in the next section). Indeed the basic functions of the space $V_{\mathcal{T}_h}$ are discontinuous on the faces of the elements, and we loose the order of convergence on the consistency error term.

Therefore our goal is to build polynomial finite elements on quadrilaterals satisfying the assumptions of Propositions 4.1 and 4.2.

Since the trapezoidal formula is exact for each polynomial of order 1, we have

$$\forall q \in P_1, \int_{\gamma_m} q d\sigma = \frac{1}{2} |\gamma_m| \sum_{a_i \in \gamma_m} q(a_i), \text{ for all } m = 1, \dots, 4 \quad (19)$$

where $|\gamma_m|$ is the length of the edge γ_m .

Let P_K be the following polynomial space:

$$P_K = \left\{ q \in Q_2^K \cap P_3; \int_{\gamma_m} q d\sigma = \frac{1}{2} |\gamma_m| \sum_{a_i \in \gamma_m} q(a_i), \text{ for all } m = 1, \dots, 4 \right\}. \quad (20)$$

The Simpson formula integrates exactly the cubic functions on each edge and consequently the space P_K can be defined as well as

$$P_K = \left\{ q \in Q_2^K \cap P_3; q(b_m) = \frac{1}{2} \sum_{a_i \in \gamma_m} q(a_i), \text{ for all } m = 1, \dots, 4 \right\}.$$

PROPOSITION 5.1 *For any convex quadrilateral K , the triad (K, P_K, S_K) is a Lagrange finite element.*

Proof Let us introduce $a_i^\vee = b_{i-4}^\vee$ and $\hat{a}_i = \hat{b}_{i-4}$ for $i = 5, \dots, 8$. Using the invertible affine mapping F_K^\sharp , we only need to prove that:

For each distortion parameters $\delta = (\delta_1, \delta_2)$ such that $|\delta_1| + |\delta_2| < 1$ the unique function $q \in Q_2^K \cap P_3$ satisfying $(q^\vee(a_i^\vee) = 0; 1 \leq i \leq 8)$ is $q \equiv 0$.

Let us introduce the polynomials $r_j \in Q_2 \cap P_3$ satisfying

$$r_j(\hat{a}_i) = \delta_{i,j},$$

and the square matrix R of order 8 defined by $R_{i,j} = r_j(a_i^\vee)$. Both symbolic calculus and an explicit calculus give

$$\det R = (1 - \delta_1^2) (1 - \delta_2^2) \left(1 - (\delta_1 + \delta_2)^2\right) \left(1 - (\delta_1 - \delta_2)^2\right).$$

Since $|\delta_1| + |\delta_2| < 1$ then $\det R > 0$. Therefore R is invertible and $q \equiv 0$. Note that if $\delta = 0$ the r_j 's correspond to the basis of the serendipity finite element and in this case $P_K \equiv Q_1^K$. ■

Using the matrix R , we can calculate explicitly the image by F_K^\sharp of the 4 basis functions of P_K

$$\begin{aligned} p_{1,K}^\vee(x_1^\vee, x_2^\vee) &= \frac{1}{4} (1 + x_1^\vee - x_2^\vee - (1 + \delta_1 - \delta_2) \omega(x_1^\vee, x_2^\vee)) \\ p_{2,K}^\vee(x_1^\vee, x_2^\vee) &= \frac{1}{4} (1 + x_1^\vee + x_2^\vee + (1 - \delta_1 - \delta_2) \omega(x_1^\vee, x_2^\vee)) \\ p_{3,K}^\vee(x_1^\vee, x_2^\vee) &= \frac{1}{4} (1 - x_1^\vee + x_2^\vee - (1 - \delta_1 + \delta_2) \omega(x_1^\vee, x_2^\vee)) \\ p_{4,K}^\vee(x_1^\vee, x_2^\vee) &= \frac{1}{4} (1 - x_1^\vee - x_2^\vee + (1 + \delta_1 + \delta_2) \omega(x_1^\vee, x_2^\vee)) \end{aligned}$$

where

$$\begin{aligned} \omega(x_1^\vee, x_2^\vee) = & \frac{3\delta_1\delta_2}{(1 - (\delta_1 + \delta_2)^2)(1 - (\delta_1 - \delta_2)^2)} (1 - (x_1^\vee)^2 - (x_2^\vee)^2) \\ & - \frac{(1 - 2\delta_1^2 - 2\delta_2^2 + \delta_1^4 + 7\delta_1^2\delta_2^2 + \delta_2^4 - 3\delta_1^2\delta_2^4 - 3\delta_1^4\delta_2^2)}{(1 - \delta_1^2)(1 - \delta_2^2)(1 - (\delta_1 + \delta_2)^2)(1 - (\delta_1 - \delta_2)^2)} x_1^\vee x_2^\vee \\ & + \frac{\delta_2(1 + \delta_1^2 - 2\delta_2^2 - 2\delta_1^4 + \delta_1^2\delta_2^2 + \delta_2^4)}{(1 - \delta_1^2)(1 - \delta_2^2)(1 - (\delta_1 + \delta_2)^2)(1 - (\delta_1 - \delta_2)^2)} (x_1^\vee)^2 x_2^\vee \\ & + \frac{\delta_1(1 - 2\delta_1^2 + \delta_2^2 + \delta_1^4 + \delta_1^2\delta_2^2 - 2\delta_2^4)}{(1 - \delta_1^2)(1 - \delta_2^2)(1 - (\delta_1 + \delta_2)^2)(1 - (\delta_1 - \delta_2)^2)} x_1^\vee (x_2^\vee)^2. \end{aligned}$$

Remarks

- The finite element basis depends on δ .
- if $\delta = 0$ (i.e. K is a parallelogram) then (K, P_K, S_K) coincides with the classical bilinear finite element.
- $P_K = span(1, x_1, x_2, F_K^\sharp(\omega))$.
- Numerically, it is more efficient to calculate the finite element basis by solving a linear system of order eight than to obtain the explicit basis of P_K .

PROPOSITION 5.2 *We assume that there exists $\alpha > 0$ such that for each $K \in \mathcal{T}_h$, $|\delta_1| + |\delta_2| \leq 1 - \alpha$. Then the assumptions of Propositions 4.1 and 4.2 are satisfied.*

Proof The inclusions $P_1 \subseteq P_K \subseteq P_3$ are obvious.

Since $|\delta_1| + |\delta_2| \leq 1 - \alpha$, $\frac{1}{|\det R|}$ is bounded, and consequently the $P_{i,K}$'s are bounded on $K^{2\#}$. Finally, by construction, the patch test is satisfied. ■

5.2 Mixed finite elements

Let us recall the definition of $BDM_{[k]}$ for $k \geq 1$

$$\begin{aligned} BDM_{[k]} = \left\{ \mathbf{w}^\vee \mid \mathbf{w}^\vee = \mathbf{v}(x_1^\vee, x_2^\vee) + r \operatorname{curl}(x_1^{\vee k+1} x_2^{\vee k}) \right. \\ \left. + s \operatorname{curl}(x_1^{\vee k} x_2^{\vee k+1}), \mathbf{v}(x_1^\vee, x_2^\vee) \in (P_k)^2 \right\} \end{aligned}$$

We denote by $BDM_{[1]}^K$ the following space:

$$BDM_{[1]}^K = \left\{ \mathcal{P}_{K^\vee} \circ \mathbf{w}^\vee \circ (F_K^\sharp)^{-1}; \mathbf{w}^\vee \in BDM_{[1]} \right\}$$

where \mathcal{P}_{K^\vee} is the piola's transform defined by

$$\mathbf{w}^\vee \longrightarrow \frac{1}{\det B_K} B_K \mathbf{w}^\vee.$$

We have for any function \mathbf{w} in $P_0^2 \oplus \mathbf{x}P_0$

$$\forall p \in P_1, \int_{\gamma_m} p \mathbf{w} \cdot \mathbf{n} \, d\sigma = \frac{1}{|\gamma_m|} \int_{\gamma_m} p \, d\sigma \int_{\gamma_m} \mathbf{w} \cdot \mathbf{n} \, d\sigma.$$

The result is clear for \mathbf{w} in P_0^2 . Moreover it is true for $\mathbf{w} = \mathbf{x}$ since $\mathbf{x} \cdot \mathbf{n}$ remains constant for geometrical reasons.

Let us consider now the following vectorial polynomial space:

$$\Psi_K = \left\{ \mathbf{w} \in BDM_{[1]}^K; \text{ for } 1 \leq m \leq 4, \forall p \in P_1, \int_{\gamma_m} p \mathbf{w} \cdot \mathbf{n} \, d\sigma = \frac{1}{|\gamma_m|} \int_{\gamma_m} p \, d\sigma \int_{\gamma_m} \mathbf{w} \cdot \mathbf{n} \, d\sigma \right\}.$$

Clearly we have $P_0^2 \oplus \mathbf{x}P_0 \subseteq \Psi_K$. Thus, we have the following result:

PROPOSITION 5.3 *For any convex quadrilateral K , the triad (K, Ψ_K, Σ_K) is a Raviart-Thomas finite element.*

Proof We proceed in the same way than for Proposition 5.1. For any polynomial \mathbf{w} we set :

$$\widehat{I}_m(\mathbf{w}) = \int_{\widehat{\gamma}_m} \widehat{\mathbf{w}} \cdot \mathbf{n} \, d\sigma \quad 1 \leq m \leq 4, \quad \widehat{I}_m(\mathbf{w}) = \int_{\widehat{\gamma}_{m-4}} \sigma \widehat{\mathbf{w}} \cdot \mathbf{n} \, d\sigma \quad 5 \leq m \leq 8,$$

and

$$I_m^\vee(\mathbf{w}) = \int_{\gamma_m^\vee} \mathbf{w}^\vee \cdot \mathbf{n} \, d\sigma \quad 1 \leq m \leq 4, \quad I_m^\vee(\mathbf{w}) = \int_{\gamma_{m-4}^\vee} \sigma \mathbf{w}^\vee \cdot \mathbf{n} \, d\sigma \quad 5 \leq m \leq 8.$$

Next we introduce the polynomials $r_j \in BDM_{[1]}$ satisfying

$$\widehat{I}_m(r_j) = \delta_{m,j}, \quad 1 \leq m, j \leq 8.$$

The r_j 's exist since they correspond to the basis of the $BDM_{[1]}$ finite element. Then we consider the square matrix T of order 8 such that $T_{m,j} = I_m^\vee(r_j)$. The symbolic calculus gives $\det T = \det R$ (where R is the matrix defined in Proposition 5.1. So the proof is achieved. \blacksquare

Remarks

- if $d = 0$ (i.e. K is a parallelogram) then $(F_K^\sharp)^{-1}(\Psi_K) = RT_{[0]}^K = \left\{ \mathbf{q}^\vee \circ (F_K^\sharp)^{-1}; \mathbf{q}^\vee \in RT_{[0]} \right\}$.
- The finite element (K, Ψ_K, Σ_K) can be built by using the De Rham diagram $H^1 \xrightarrow{curl} H(div)$ and

$$(F_K^\sharp)^{-1}(\Psi_K) = span \left(\phi_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \phi_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \phi_3 = \begin{pmatrix} x_1^\vee \\ x_2^\vee \end{pmatrix}, \phi_4 = curl(\omega_K) \right),$$

with these notations the image by F_K^\sharp of the basis functions of Ψ_K are

$$\begin{aligned} \psi_{1,K}^\vee(x_1^\vee, x_2^\vee) &= \frac{1}{8}(2 - \delta_2)\phi_1 - \frac{1}{8}\delta_1\phi_2 + \frac{1}{8}\phi_3 + \frac{1}{8}(\delta_1^2 - (1 - \delta_2))^2\phi_4 \\ \psi_{2,K}^\vee(x_1^\vee, x_2^\vee) &= -\frac{1}{8}\delta_2\phi_1 + \frac{1}{8}(2 - \delta_1)\phi_2 + \frac{1}{8}\phi_3 - \frac{1}{8}(\delta_2^2 - (1 - \delta_1))^2\phi_4 \\ \psi_{3,K}^\vee(x_1^\vee, x_2^\vee) &= \frac{1}{8}(2 + \delta_2)\phi_1 - \frac{1}{8}\delta_1\phi_2 + \frac{1}{8}\phi_3 + \frac{1}{8}(\delta_1^2 - (1 + \delta_2))^2\phi_4 \\ \psi_{4,K}^\vee(x_1^\vee, x_2^\vee) &= -\frac{1}{8}\delta_2\phi_1 - \frac{1}{8}(2 + \delta_1)\phi_2 + \frac{1}{8}\phi_3 - \frac{1}{8}(\delta_2^2 - (1 + \delta_1))^2\phi_4 \end{aligned}$$

PROPOSITION 5.4 *We assume that there exists $\alpha > 0$ such that for each $K \in \mathcal{T}_h$, $|\delta_1| + |\delta_2| \leq 1 - \alpha$. Then the assumptions of Propositions 4.4 and 4.5 are satisfied.*

Proof The inclusions $P_0(K)^2 \oplus \mathbf{x}P_0(K) \subset \Psi_K \subset P_2(K) \times P_2(K)$ are obvious. Since $|\delta_1| + |\delta_2| \leq 1 - \alpha$, $\frac{1}{|\det T|}$ is bounded, and consequently the $\psi_{i,K}$'s are bounded on $K^{2\sharp}$. Finally, by construction, the patch test is satisfied. ■

6. Numerical tests

We take $\Omega =]0, 1[\times]0, 1[$ and the exact solution is $u(x_1, x_2) = \sin(\pi x_1)\sin(\pi x_2)$. We consider two types of mesh. They are composed of two patterns and their shapes are the same for each mesh used, see Figure 3. The first mesh is a mesh in chevron given in [9] and the second is a mesh in honeycomb.

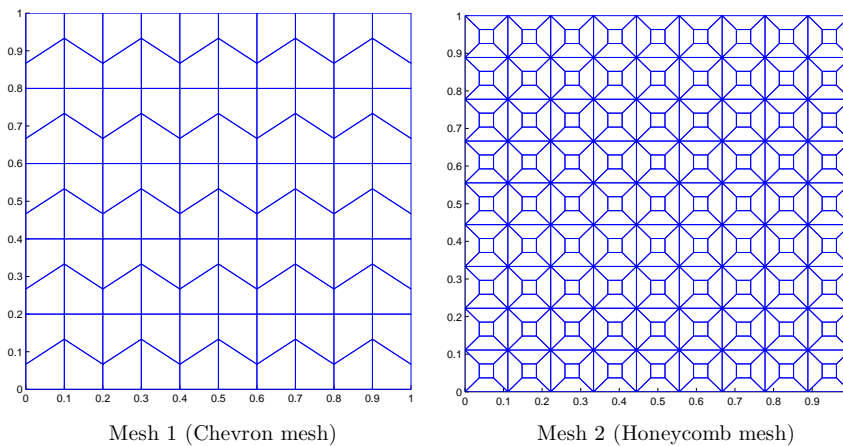


Figure 3. meshes 1 and 2

6.1 Lagrange finite element

In the first test, we take $P_K = Q_1^K$ and as expected the method does not converge on (deformed) quadrilateral meshes but converges on meshes based on squares or parallelograms, see Figure 4. In the second test, P_K is given by (20). For the two meshes proposed, we obtain the expected order of convergence, see Figure 5.

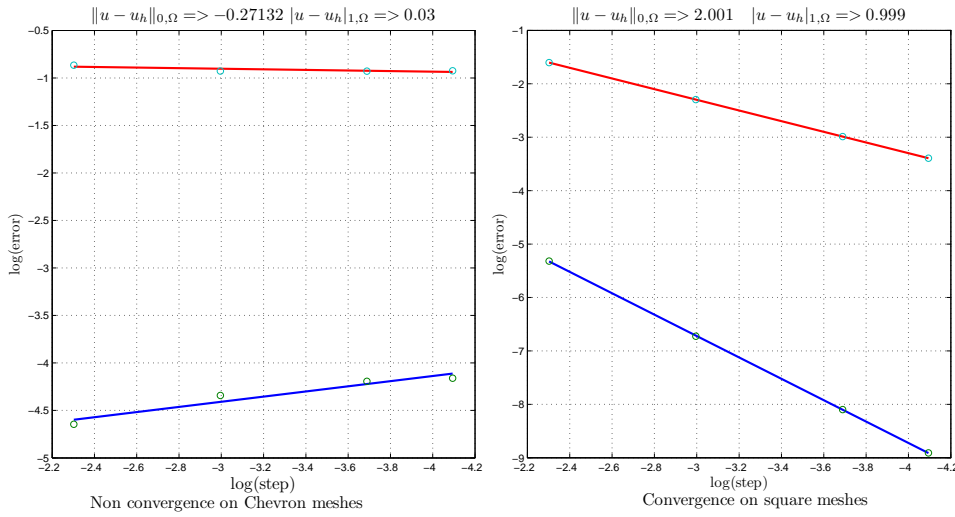


Figure 4. Convergence curves when $P_K = Q_1^K$

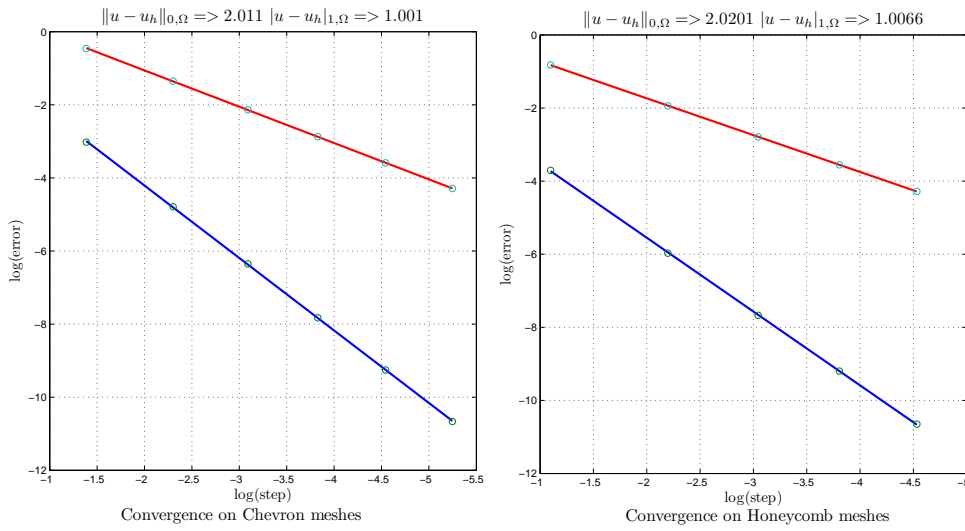


Figure 5. Convergence curves when P_K is given by (20)

6.2 Mixed finite element

The classical mixed finite element method (2D or 3D case) ([5],[3]) corresponds to the problem (16),(17) by substituting L_h for a conform subspace of $H(div, \Omega)$ i.e.

$$\left\{ \mathbf{q}_h \in H(div, \Omega); \widehat{\mathbf{q}}_h|_{\widehat{K}} \in RT_{[0]}(\widehat{K}) \text{ for each } K \in \mathcal{T}_h \right\},$$

where $\widehat{\mathbf{q}}_h$ is defined by the non linear Piola transform :

$$\mathbf{q}_h = \frac{1}{\det J_F} J_F \widehat{\mathbf{q}}_h$$

(J_F being the jacobian of the transformation of K into \widehat{K}).

As mentioned in the introduction, the obtained approximation (u_h, \mathbf{q}_h) does not converge in $L^2(\Omega) \times H(div, \Omega)$ ([9]). On general quadrilaterals, u_h and \mathbf{p}_h converge

in $L^2(\Omega)$ but \mathbf{p}_h does not converge in $H(\text{div}, \Omega)$. In the 3D case on general hexahedra, the situation is worse since u_h and \mathbf{p}_h do not converge (see Figure 6).

The rates of convergence on Figure 7 correspond to Ψ_K given by (21) and as

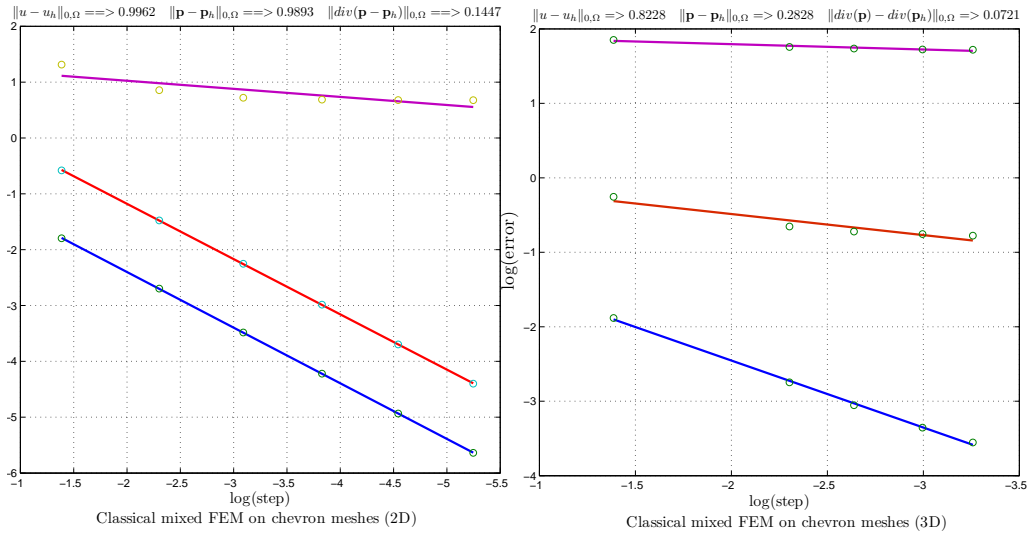


Figure 6. Rates of convergence of classical mixed finite element

expected u_h (resp. \mathbf{p}_h) converges in L^2 (resp. $H\text{div}$) with the order 1.

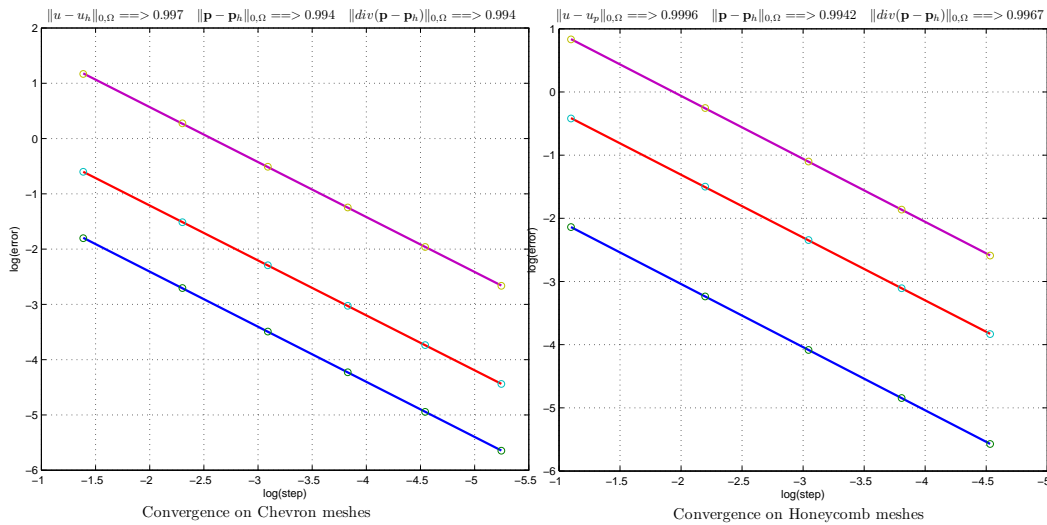


Figure 7. Rates of convergence when Ψ_K is given by (21)

7. Conclusion

One of the motivations of this work refers to the loss of convergence problem when using classical mixed finite elements on quadrilaterals and hexahedra (see for instance [9], [4]). The pseudo-conforming finite elements are a good answer to this problem. The process described can be extended to the 3D case, pseudo-conforming

Lagrange finite elements on hexaedra are presented in ([10]), and the case of mixed finite elements will be treated in a paper to come. Note that another way for obtaining polynomial basis functions is to cut the quadrilaterals into triangles (or hexahedra into tetrahedra) and work with macro-elements ([11], [12], [4]).

References

- [1] P.-G. CIARLET, *The Finite Element Method for Elliptic Problems* Classics in Applied Mathematics, Vol.40, SIAM, Philadelphia, 2002. First edition published by North-Holland, Amsterdam, 1978.
- [2] P.-G. CIARLET, *Basic error estimates for elliptic problems*, in "Handbook of Numerical Analysis, Vol.II" (eds. P.G. Ciarlet and J.L. Lions), Elsevier, (1991), 17-351.
- [3] J. E. ROBERTS, J.-M. THOMAS *Mixed and hybrid methods*. In Handbook of Numerical Analysis, VOL.II, Finite Element Methods (Part 1), Elsevier Science Publishers B.V. (North-Holland), Amsterdam (1991) (1977) 523-639,.
- [4] A. SBOUI, J. E. ROBERTS AND J. JAFFRÉ, *A Composite Mixed Finite element for general hexahedral grids for Darcy flow calculations*, Preprint INRIA, submitted to SIAM
- [5] F. BREZZI, M. FORTIN, *Mixed and Hybrid Finite Element Methods*, Springer-Verlag, Berlin, 1991.
- [6] G. STRANG AND G. J. FIX, *An Analysis of the Finite Element Method*, Prentice-Hall, Englewood Cliffs, NJ, 1973
- [7] D. N. ARNOLD, D. BOFFI, R. S. FALK, *Approximation by quadrilateral finite elements*, Maths of Comp., **239** (2002), 909 - 922.
- [8] S. C. BRENNER L. R. SCOTT, *The Mathematical Theory of Finite Element Methods* Series: Texts in Applied Mathematics , Vol. 15 2nd ed., 2002
- [9] D. N. ARNOLD, D. BOFFI, R. S. FALK, *Quadrilateral $H(\text{div})$ finite elements*, SIAM J. Numerical Analysis, 42 (2005) 2529-2451.
- [10] E. DUBACH, R. LUCE, J.M. THOMAS, *Peuso-conform Lagrange Finite Elements on quadrilaterals and Hexahedra* Rapport de recherche RR-6572 (2008) [inria-00293546 version 1]
- [11] Y. KUZNETSOV, S. REPIN, *New mixed finite element method on polygonal and polyhedral meshes*, Russ. J. Numer. Anal. Math. Model. 18 (3) (2003) 261-278.
- [12] Y. KUZNETSOV, S. REPIN, *Convergence analysis and error estimates for mixed finite element method on distorted meshes*, J. Numer. Math. 13 (1) (2005) 33-51.