

A Top-down attentional system scanning multiple targets with saccades

Jérémy Fix, Nicolas P. Rougier, Frédéric Alexandre

▶ To cite this version:

Jérémy Fix, Nicolas P. Rougier, Frédéric Alexandre. A Top-down attentional system scanning multiple targets with saccades. From Computational Cognitive Neuroscience to Computer Vision: CCNCV 2007, Mar 2007, Bielefeld, Germany. inria-00166538

HAL Id: inria-00166538 https://inria.hal.science/inria-00166538v1

Submitted on 7 Aug 2007

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

A Top-down attentional system scanning multiple targets with saccades

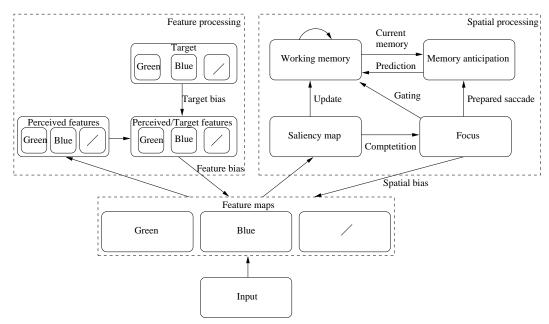
Jérémy Fix, Nicolas P. Rougier and Frederic Alexandre

Loria Laboratory Campus Scientifique, B.P. 239 54506 Vandoeuvre-lès-Nancy Cedex, France

We would like to introduce recent developments in the computational cognitive neuroscience domain, applied to computer vision. Our objective in this paper is to propose a biologicially inspired algorithm to solve a computer vision problem that is to focus (by the mean of eye movements or camera movements) on several targets that share given properties. This algorithm relies on the paradigm of distributed, asynchronous and numerical computations that we think could lead to efficient algorithms in the long run.

From the cognitive neuroscience point of view, it relies on several physiological principles: the feature integration theory proposed in [1] and the separation of feature and spatial processing proposed in [2]. Our approach is also based on two previous works. In [3], the author proposed a neural network architecture which aims at simulating the visual attentional phenoma (for details about that phenoma, please refer to [4]). In [5], we proposed a mechanism that allows a robot to successively focus on several stimuli. By focus on we mean performing an eye movement centering a target on the camera's retina. In the figure below, the combination of these two previous models leads to a computational model that is able to focus on several targets, that share given properties (defined in the **target** maps), memorizing the previously scanned objects in a **working memory**. An interesting property of this model is that the decision of which target to focus on next is completely distributed; it depends both on the properties of the target and on the previously focused ones.

We are conscious that, for the moment, it is quite difficult to make such a model work in real world applications for several reasons (the parameters of the equations must be adjusted, the proposed architecture is quite simple); It is designed for simplified world but it must be emphasized that the architecture is quite simple too and adding, step by step, the features it lacks, should make it more efficient.



References

- [1] Treisman, A., Gelade, G.: A feature-integration theory of attention. Cognitive Psychology 12(1) (1980) 97–136
- [2] Ungerleider, L., Mishkin, M.: Two cortical visual systems. In: Analysis of Visual Behavior. MIT Press (1982) 549–586
- [3] Hamker, F.: A dynamic model of how feature cues guide spatial attention. Vision Research 44 (2004) 501–521
- [4] Posner, M., Petersen, S.: The attentional system of the human brain. Annual Review of Neurosciences 13 (1990) 25–42
- [5] Fix, J., Vitay, J., Rougier, N.: A computational model of spatial memory anticipation during visual search. In Butz, M., Sigaud, O., Pezzulo, G., Baldassarre, G., eds.: Proceeding of the Third Workshop on Anticipatory Behavior in Adaptive Learning System (ABIALS 2006). (2006)