



**HAL**  
open science

# Parallel and interacting Markov chains Monte Carlo method

Fabien Campillo, Vivien Rossi

► **To cite this version:**

Fabien Campillo, Vivien Rossi. Parallel and interacting Markov chains Monte Carlo method. [Research Report] 2006. inria-00103871v1

**HAL Id: inria-00103871**

**<https://inria.hal.science/inria-00103871v1>**

Submitted on 5 Oct 2006 (v1), last revised 2 Nov 2006 (v2)

**HAL** is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.



INSTITUT NATIONAL DE RECHERCHE EN INFORMATIQUE ET EN AUTOMATIQUE

*Parallel and interacting  
Markov chains Monte Carlo method*

Fabien Campillo and Vivien Rossi

N°????

October 2006

————— Systèmes numériques —————



*R*apport  
de recherche





## Parallel and interacting Markov chains Monte Carlo method

Fabien Campillo \* and Vivien Rossi † ‡

Systèmes numériques  
Projets Aspi

Rapport de recherche n° 700 — October 2006 — 27 pages  
algorithmsection\*.12 pages

**Abstract:** In many situations it is important to be able to propose  $N$  independent realizations of a given distribution law. We propose a strategy for making  $N$  parallel Monte Carlo Markov Chains (MCMC) interact in order to get an approximation of an independent  $N$ -sample of a given target law. In this method each individual chain proposes candidates for all other chains. We prove that the set of interacting chains is itself a MCMC method for the product of  $N$  target measures. Compared to independent parallel chains this method is more time consuming, but we show through concrete examples that it possesses many advantages: it can speed up convergence toward the target law as well as handle the multi-modal case.

**Key-words:** Markov chain Monte Carlo method, Metropolis-Hastings, interacting chains, particle approximation

*(Résumé : tsvp)*

\* INRIA/IRISA, Rennes, [Fabien.Campillo@inria.fr](mailto:Fabien.Campillo@inria.fr)

† IURC, University of Montpellier I – [Vivien.Rossi@iurc.montp.inserm.fr](mailto:Vivien.Rossi@iurc.montp.inserm.fr)

‡ The research of the second author was done during a postdoctoral stay at the INRIA/IRISA, Rennes.

## Méthode de Monte Carlo par chaînes de Markov en parallèle et en interaction

**Résumé :** Dans de nombreuses situations il est important de pouvoir disposer de  $N$  réalisations indépendantes d'une loi donnée. Notre but est de développer une stratégie d'interaction de  $N$  méthodes de Monte Carlo par Chaîne de Markov (MCCM) dans le but de proposer une approximation d'un échantillon indépendant de taille  $N$  d'une loi cible donnée. L'idée est que chaque chaîne propose un candidat pour elle-même mais également pour toutes les autres chaînes. On montre que l'ensemble de ces  $N$  chaînes en interaction est lui-même une méthode MCCM pour le produit de  $N$  mesures cibles. Cette approche est naturellement plus coûteuse que  $N$  chaînes indépendantes, on montre toutefois au travers d'exemples concrets qu'elle possède plusieurs avantages : elle peut sensiblement accélérer la convergence vers la loi cible, elle permet également d'appréhender le cas multimodal.

**Mots-clé :** méthode de Monte Carlo par chaîne de Markov, Metropolis-Hastings, chaînes en interaction, approximation particulière

## Contents

<b>1</b>	<b>Introduction</b>	<b>5</b>
<b>2</b>	<b>Parallel/interacting MH algorithm</b>	<b>5</b>
2.1	The algorithm . . . . .	6
2.2	Description of the MH kernel . . . . .	7
2.3	Invariance property . . . . .	10
<b>3</b>	<b>Parallel/interacting MwG algorithm</b>	<b>12</b>
3.1	The algorithm . . . . .	12
3.2	Description of the MH kernel . . . . .	13
3.3	Invariance property . . . . .	16
<b>4</b>	<b>Numerical tests</b>	<b>19</b>
4.1	A multi-modal example . . . . .	19
4.2	An hidden Markov model . . . . .	21
<b>5</b>	<b>Conclusion</b>	<b>23</b>



## 1 Introduction

Markov chain Monte Carlo (MCMC) algorithms [19, 12, 18] allows us to draw samples from a probability distribution  $\pi(x) dx$  known up to a multiplicative constant. They consist in sequentially simulating a single Markov chain whose limit distribution is  $\pi(x) dx$ . There exist many techniques to speed up the convergence toward the target distribution by improving the mixing properties of the chain [13]. Moreover, special attention should be given to the convergence diagnosis of this method [1, 6, 15].

An alternative is to run many Markov chains in parallel. The simplest multiple chain algorithm is to make use of parallel independent chains [9]. The recommendations concerning this idea seem contradictory in the literature (cf. the “many short runs” *vs* “one long run” debate described in [10]). We can note with [11] and [18, §6.5] that independent parallel chains could be a poor idea: among these chains some may not converge, so one long chain could be preferable to many short ones. Moreover, many parallel independent chains can artificially exhibit a more robust behavior which does not correspond to a real convergence of the algorithm.

In practice one however make use of several chains in parallel. It is then tempting to exchange information between these chains to improve mixing properties of the MCMC samplers [4, 5, 16, 3, 7, 8]. A general framework of “Population Monte Carlo” has been proposed in this context [14, 17, 2]. In this paper we propose an interacting method between parallel chains which provides an independent sample from the target distribution. Contrary to papers previously cited, the proposal law in our work is given and does not adapt itself to the previous simulations. Hence, the problem of the choice of this law still remains.

The Metropolis-Hastings (MH) algorithm and its theoretical properties are presented in section 2. The corresponding Metropolis within Gibbs (MwG) algorithm and its theoretical properties are presented in section 3. In Section 4, two simple numerical examples illustrate how the introduction of interactions can speed up the convergence and handle multi-modal cases.

## 2 Parallel/interacting Metropolis Hastings (MH) algorithm

Consider a target density law  $\pi(x)$  defined on  $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$  and a proposal kernel density  $\pi^{\text{prop}}(y|x)$ . We propose a method for sampling  $N$  independent values  $X^1, \dots, X^N \in \mathbb{R}^n$  of the law  $\pi(x) dx$ .

**Notations:** *Let*

$$X = X^{1:N} = X_{1:n} \in \mathbb{R}^{n \times N},$$

*so that  $X_\ell \in \mathbb{R}^n$  and  $X^i \in \mathbb{R}^n$  (the same for  $Y$  and  $Z$ );  $x \in \mathbb{R}^n$  so that  $x_\ell \in \mathbb{R}$  (the same for  $y$  and  $z$ );  $\xi, \xi' \in \mathbb{R}$ . Here  $X^{1:N} = (X^1, \dots, X^N)$  and  $X_{1:n} = (X_1, \dots, X_n)$ . We also define*



$\neg\ell = \{1, \dots, n\} \setminus \{\ell\}$ . Note that the structure of the matrix  $X$  is:

$$X = \begin{array}{c} X^i \\ \uparrow \\ \begin{bmatrix} X_1^1 & \cdots & X_1^i & \cdots & X_1^N \\ \vdots & & \vdots & & \vdots \\ X_\ell^1 & \cdots & X_\ell^i & \cdots & X_\ell^N \\ \vdots & & \vdots & & \vdots \\ X_n^1 & \cdots & X_n^i & \cdots & X_n^N \end{bmatrix} \end{array} \rightarrow X_\ell \quad .$$

## 2.1 The algorithm

We describe the Markov chain  $\{\mathbf{X}^{(k)}\}_{k \geq 0}$  over  $\mathbb{R}^{n \times N}$  corresponding the MH algorithm. It consists in  $N$  *mutually dependent* realizations  $\mathbf{X}^{i,(k)}$  ( $i = 1, \dots, N$ ) of the state variable and its limit distribution will be

$$\Pi(dX) \stackrel{\text{def}}{=} \pi(X^1) dX^1 \cdots \pi(X^N) dX^N .$$

We detail an iteration  $\mathbf{X}^{(k)} = X \rightarrow \mathbf{X}^{(k+1)} = Z$  of the MH algorithm. The  $N$  vectors are updated sequentially:

$$[X^{1:N}] \rightarrow [Z^1 X^{2:N}] \rightarrow [Z^{1:2} X^{3:N}] \cdots [Z^{1:N-1} X^N] \rightarrow [Z^{1:N}] .$$

At sub-iteration “ $i$ ”, that is  $[Z^{1:i-1} X^{i:N}] \rightarrow [Z^{1:i} X^{i+1:N}]$ , we simulate  $Z^i$  in two steps:

*Proposal step:* independently one from the other, each chain  $j = 1 \cdots N$  proposes a candidate  $Y^j \in \mathbb{R}^n$  according to the proposal kernel starting from its current position, i.e.

$$Y^j \sim \pi_{i,j}^{\text{prop}}(y | Z^{1:i-1}, X^i, X^{i+1:N}) dy .$$

Note that the candidates  $Y^j$  depend also on  $i$ . We will use a lighter notation:

$$\pi_{i,j}^{\text{prop}}(y | X^i) = \pi_{i,j}^{\text{prop}}(y | Z^{1:i-1}, X^i, X^{i+1:N}) . \quad (1)$$

*Selection step:* We can chose among these  $N$  candidates  $Y^{1:N}$  or stay at  $X^i$  according to the multinomial law:

$$Z^i \leftarrow \begin{cases} Y^1 & \text{with probability } \frac{1}{N} \alpha^{i,1}(X^i, Y^1), \\ \vdots \\ Y^N & \text{with probability } \frac{1}{N} \alpha^{i,N}(X^i, Y^N), \\ X^i & \text{with probability } \tilde{\rho}^i(X^i, Y) \end{cases}$$

where the acceptance probabilities are

$$\alpha^{i,j}(x, y) \stackrel{\text{def}}{=} \frac{\pi(y)}{\pi(x)} \frac{\pi_{i,j}^{\text{prop}}(x|y)}{\pi_{i,j}^{\text{prop}}(y|x)} \wedge 1,$$

$$\tilde{\rho}^i(X^i, Y) \stackrel{\text{def}}{=} 1 - \frac{1}{N} \sum_{j=1}^N \alpha^{i,j}(X^i, Y^j).$$

The final algorithm is depicted in Algorithm 1.

---

```

choose  $X \in \mathbb{R}^{n \times N}$ 
for  $k = 1, 2, \dots$  do
  for  $i = 1 : N$  do
    for  $j = 1 : N$  do
       $Y^j \sim \pi_{i,j}^{\text{prop}}(y|X^i) dy$ 
       $\alpha^j \leftarrow [\pi(Y^j) \pi_{i,j}^{\text{prop}}(X^i|Y^j)] / [\pi(X^i) \pi_{i,j}^{\text{prop}}(Y^j|X^i)] \wedge 1$ 
    end for
     $\tilde{\rho} \leftarrow 1 - \frac{1}{N} \sum_{j=1}^N \alpha^j$ 
     $X^i \leftarrow \begin{cases} Y^1 & \text{with probability } \alpha^1/N \\ \vdots \\ Y^N & \text{with probability } \alpha^N/N \\ X^i & \text{with probability } \tilde{\rho} \end{cases}$ 
  end for
end for

```

---

Algorithm 1: *Parallel/interacting MH algorithm.*

## 2.2 Description of the MH kernel

**Lemma 2.1** *The Markov kernel associated with the MH procedure described in Section 2.1 is*

$$P(X; dZ) \stackrel{\text{def}}{=} P^1(X^{1:N}; dZ^1) P^2(Z^1, X^{2:N}; dZ^2) \dots P^N(Z^{1:N-1}, X^N; dZ^N) \quad (2)$$

where

$$P^i(Z^{1:i-1}, X^{i:N}; dz) \stackrel{\text{def}}{=} \frac{1}{N} \sum_{j=1}^N \alpha^{i,j}(X^i, z) \pi_{i,j}^{\text{prop}}(z|X^i) dz + \rho^i(X^i) \delta_{X^i}(dz). \quad (3)$$

Acceptation probability is

$$\alpha^{i,j}(x, z) \stackrel{\text{def}}{=} \begin{cases} r^{i,j}(x, z) \wedge 1 & \text{if } (x, z) \in R^{i,j}, \\ 0 & \text{otherwise,} \end{cases} \quad (4)$$

$$r^{i,j}(x, z) \stackrel{\text{def}}{=} \frac{\pi(z)}{\pi(x)} \frac{\pi_{i,j}^{\text{prop}}(x|z)}{\pi_{i,j}^{\text{prop}}(z|x)}, \quad (5)$$

$$\rho^i(x) \stackrel{\text{def}}{=} 1 - \frac{1}{N} \sum_{j=1}^N \int_{\mathbb{R}} \alpha^{i,j}(x, z) \pi_{i,j}^{\text{prop}}(z|x) dz. \quad (6)$$

The set  $R^{i,j}$  is defined by:

$$R^{i,j} \stackrel{\text{def}}{=} \{(x, z) \in \mathbb{R}^n \times \mathbb{R}^n; \pi(z) \pi_{i,j}^{\text{prop}}(x|z) > 0 \text{ and } \pi(x) \pi_{i,j}^{\text{prop}}(z|x) > 0\}.$$

Note that the functions  $\alpha^{i,j}(x, z)$ ,  $\rho^i(x)$ ,  $r^{i,j}(x, z)$  and the set  $R^{i,j}$  depend on  $Z^{1:i-1}$  and  $X^{i:N}$ .

The measures

$$\nu(dx \times dz) = \pi(z) \pi_{i,j}^{\text{prop}}(x|z) dz dx, \quad \nu^T(dx \times dz) = \pi(x) \pi_{i,j}^{\text{prop}}(z|x) dz dx$$

are mutually absolutely continuous over  $R^{i,j}$  and mutually singular on the complementary set  $[R^{i,j}]^c$ . The set  $R^{i,j}$  is unique, up to the  $\nu$  and  $\nu^T$  negligible sets, and symmetric, i.e.  $(x, z) \in R^{i,j} \Rightarrow (z, x) \in R^{i,j}$ .

**Proof** This construction follows the general setup proposed by Luke Tierney in [20]. We now derive the probability kernel associated with the iteration described in the previous subsection 2.1. The kernel  $P^i(Z^{1:i-1}, X^{i:N}; dz)$  is the composition of a proposition kernel and of a selection kernel:

$$P^i(Z^{1:i-1}, X^{i:N}; dz) = \int_{Y^{1:N}} S^i(Z^{1:i-1}, X^{i:N}, Y^{1:N}; dz) Q^i(Z^{1:i-1}, X^{i:N}; dY^{1:N})$$

which consists in proposing independently  $N$  candidates  $Y^{1:N}$  sampled from the density proposition, i.e.

$$Q^i(Z^{1:i-1}, X^{i:N}; dY^{1:N}) \stackrel{\text{def}}{=} \prod_{k=1}^N \pi_{i,k}^{\text{prop}}(Y^k|X^i) dY^k$$

then to select among these candidates or to stay at  $X^i$  with the MH acceptance probability, i.e.

$$S^i(Z^{1:i-1}, X^{i:N}, Y^{1:N}; dz) \stackrel{\text{def}}{=} \frac{1}{N} \sum_{j=1}^N \alpha^{i,j}(X^i, Y^j) \delta_{Y^j}(dz) + \tilde{\rho}^i(X^i, Y) \delta_{X^i}(dz).$$

Hence:

$$\begin{aligned} P^i(Z^{1:i-1}, X^{i:N}; dz) &= \\ &= \frac{1}{N} \sum_{j=1}^N \int_{Y^{1:N}} \alpha^{i,j}(X^i, Y^j) \delta_{Y^j}(dz) \left\{ \prod_{k=1}^N \pi_{i,k}^{\text{prop}}(Y^k | X^i) dY^k \right\} \\ &\quad + \int_{Y^{1:N}} \tilde{\rho}^i(X^i, Y) \delta_{X^i}(dz) \left\{ \prod_{k=1}^N \pi_{i,k}^{\text{prop}}(Y^k | X^i) dY^k \right\} = A_1 + A_2 \end{aligned}$$

and

$$\begin{aligned} A_1 &= \frac{1}{N} \sum_{j=1}^N \int_{Y^j} \alpha^{i,j}(X^i, Y^j) \delta_{Y^j}(dz) \pi_{i,j}^{\text{prop}}(Y^j | X^i) \\ &\quad \underbrace{\int_{Y^{-j}} \left\{ \prod_{k \neq j}^N \pi_{i,k}^{\text{prop}}(Y^k | X^i) dY^k \right\}}_{=1} dY^j \\ &= \frac{1}{N} \sum_{j=1}^N \alpha^{i,j}(X^i, z) \pi_{i,j}^{\text{prop}}(z | X^i) dz \end{aligned}$$

because  $\int_{Y^j} \delta_{Y^j}(dz) dY^j = dz$ . The second term  $A_2$  reads:

$$\begin{aligned} A_2 &= \int_{Y^{1:N}} \tilde{\rho}^i(X^i, Y) \delta_{X^i}(dz) \left\{ \prod_{k=1}^N \pi_{i,k}^{\text{prop}}(Y^k | X^i) dY^k \right\} \\ &= \delta_{X^i}(dz) \int_{Y^{1:N}} \left\{ 1 - \frac{1}{N} \sum_{j=1}^N \alpha^{i,j}(X^i, Y^j) \right\} \left\{ \prod_{k=1}^N \pi_{i,k}^{\text{prop}}(Y^k | X^i) dY^k \right\} \\ &= \delta_{X^i}(dz) \left\{ 1 - \frac{1}{N} \sum_{j=1}^N \int_{Y^{1:N}} \alpha^{i,j}(X^i, Y^j) \prod_{k=1}^N \pi_{i,k}^{\text{prop}}(Y^k | X^i) dY^k \right\} \\ &= \delta_{X^i}(dz) \left\{ 1 - \frac{1}{N} \sum_{j=1}^N \int_{Y^j} \alpha^{i,j}(X^i, Y^j) \pi_{i,j}^{\text{prop}}(Y^j | X^i) dY^j \right\}. \end{aligned}$$

Summing up  $A_1$  and  $A_2$  proves the Lemma.  $\square$

### 2.3 Invariance property

**Lemma 2.2** For all  $(x, z) \in \mathbb{R}^n \times \mathbb{R}^n$  a.e. we have:

$$\alpha^{i,j}(x, z) \pi(x) \pi_{i,j}^{\text{prop}}(z|x) = \alpha^{i,j}(z, x) \pi(z) \pi_{i,j}^{\text{prop}}(x|z).$$

**Proof** For  $(x, z) \notin R^{i,j}$  the result is obvious. For  $(x, z) \in R^{i,j}$  we have:

$$\begin{aligned} & (r^{i,j}(x, z) \wedge 1) \pi(x) \pi_{i,j}^{\text{prop}}(z|x) \\ &= \min \left\{ \pi(z) \pi_{i,j}^{\text{prop}}(x|z), \pi(x) \pi_{i,j}^{\text{prop}}(z|x) \right\} \\ &= (r^{i,j}(z, x) \wedge 1) \pi(z) \pi_{i,j}^{\text{prop}}(x|z). \end{aligned}$$

□

**Lemma 2.3 (conditional detailed balance)** The following equality of measures defined on  $\mathbb{R}^n \times \mathbb{R}^n$

$$P^i(Z^{1:i-1}, X^{i:N}; dZ^i) \pi(X^i) dX^i = P^i(Z^{1:i}, X^{i+1:N}; dX^i) \pi(Z^i) dZ^i \quad (7)$$

holds true for any  $i = 1, \dots, N$ ,  $Z^{1:i-1} \in \mathbb{R}^{(i-1) \times N}$ , and  $X^{i+1:N} \in \mathbb{R}^{(N-i) \times N}$ .

**Proof** Left hand side of (7) is a measure, say  $\nu(dZ^i \times dX^i)$  on  $(\mathbb{R}^n \times \mathbb{R}^n, \mathcal{B}(\mathbb{R}^n \times \mathbb{R}^n))$ . For all  $A_1, A_2 \in \mathcal{B}(\mathbb{R}^n)$ , we want to prove that  $\nu(A_1 \times A_2) = \nu(A_2 \times A_1)$ . We have:

$$\nu(A_1 \times A_2) = \int P^i(Z^{1:i-1}, X^{i:N}; A_1) \mathbf{1}_{A_2}(X^i) \pi(X^i) dX^i$$

and

$$\begin{aligned} P^i(Z^{1:i-1}, X^{i:N}; A_1) &= \frac{1}{N} \sum_{j=1}^N \int \mathbf{1}_{A_1}(Z^i) \alpha^{i,j}(X^i, Z^i) \pi_{i,j}^{\text{prop}}(Z^i|X^i) dZ^i \\ &\quad + \rho^i(X^i) \mathbf{1}_{A_1}(X^i) \end{aligned}$$

so that

$$\begin{aligned} & \nu(A_1 \times A_2) \\ &= \frac{1}{N} \sum_{j=1}^N \iint \mathbf{1}_{A_1}(Z^i) \mathbf{1}_{A_2}(X^i) \alpha^{i,j}(X^i, Z^i) \pi(X^i) \pi_{i,j}^{\text{prop}}(Z^i|X^i) dX^i dZ^i \\ &\quad + \int \rho^i(X^i) \mathbf{1}_{A_1}(X^i) \mathbf{1}_{A_2}(X^i) \pi(X^i) dX^i. \end{aligned} \quad (8)$$

And from Lemma 2.2, we get:

$$\begin{aligned} \nu(A_1 \times A_2) &= \frac{1}{N} \sum_{j=1}^N \iint \mathbf{1}_{A_1}(Z^i) \mathbf{1}_{A_2}(X^i) \alpha^{i,j}(Z^i, X^i) \pi(Z^i) \pi_{i,j}^{\text{prop}}(X^i|Z^i) dZ^i dX^i \\ &\quad + \int \rho^i(X^i) \mathbf{1}_{A_1}(X^i) \mathbf{1}_{A_2}(X^i) \pi(X^i) dX^i \end{aligned}$$

Exchanging the name of variables  $X^i \leftrightarrow Z^i$  in the first term of the right hand side of the previous equality, leads to the same expression as (8) where  $A_1$  and  $A_2$  were interchanged, in other words  $\nu(A_1 \times A_2) = \nu(A_2 \times A_1)$ .  $\square$

**Proposition 2.4 (invariance)** *The probability measure*

$$\Pi(dX) = \pi(X^1) dX^1 \dots \pi(X^N) dX^N$$

*is an invariant distribution of the Markov kernel  $P$ , i.e.  $\Pi P = \Pi$  that is:*

$$\int_X P(X, dZ) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} = \prod_{i=1}^N \pi(Z^i) dZ^i. \quad (9)$$

**Proof**

$$\begin{aligned} &\int_X P(X, dZ) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} \\ &= \int_X P^1(X^{1:N}; dZ^1) P^2(Z^1, X^{2:N}; dZ^2) \dots \\ &\quad \dots P^N(Z^{1:N-1}, X^N; dZ^N) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} \\ &= \int_X P^1(X^{1:N}; dZ^1) \pi(X^1) dX^1 P^2(Z^1, X^{2:N}; dZ^2) \dots \\ &\quad \dots P^N(Z^{1:N-1}, X^N; dZ^N) \left\{ \prod_{i=2}^N \pi(X^i) dX^i \right\}. \end{aligned}$$

Using (7) with  $i = 1$  gives:

$$\begin{aligned} &\int_X P(X, dZ) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} = \\ &= \int_X P^1(Z^1, X^{2:N}; dX^1) \pi(Z^1) dZ^1 P^2(Z^1, X^{2:N}; dZ^2) \dots \\ &\quad \dots P^N(Z^{1:N-1}, X^N; dZ^N) \left\{ \prod_{i=2}^N \pi(X^i) dX^i \right\}. \end{aligned}$$

In this last expression the kernel  $P^1(Z^1, X^{2:N}; dX^1)$  is a measure on the variable  $X^1$  which no longer appears in the integrand. Therefore its integral with respect to this variable is 1, hence:

$$\begin{aligned} \int_X P(X, dZ) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} &= \\ &= \pi(Z^1) dZ^1 \int_{X^{2:N}} P^2(Z^1, X^{2:N}; dZ^2) \dots \\ &\quad \dots P^n(Z^{1:N-1}, X^N; dZ^N) \left\{ \prod_{i=2}^N \pi(X^i) dX^i \right\}. \end{aligned}$$

Repeating this procedure successively for  $X^2$  to  $X^N$  leads to (9).  $\square$

### 3 Parallel/interacting Metropolis within Gibbs (MwG) algorithm

Let  $\pi(x)$  be the probability density function of a target distribution defined on  $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$ . For  $\ell = 1, \dots, n$ , we define the conditional laws:

$$\pi_\ell(x_\ell | x_{-\ell}) \stackrel{\text{def}}{=} \frac{\pi(x_{1:n})}{\int \pi(x_{1:n}) dx_{-\ell}}. \quad (10)$$

When we know to sample from (10), we are able to use the Gibbs sampler. It is possible to adapt our interacting method to parallel Gibbs sampler. But very often we do not know how to sample from (10) and therefore we consider proposal conditional densities  $\pi_\ell^{\text{prop}}(x_\ell)$  defined for all  $\ell$ . In this case, we use Metropolis within Gibbs algorithm (see appendix). We present in the following how to make interactions between parallel MwG algorithms. The MwG algorithm is more general than Gibbs algorithm, so a parallel/interacted Gibbs algorithm can easily be deduced from the parallel/interacted MwG algorithm.

#### 3.1 The algorithm

One iteration  $X \rightarrow Z$  of the parallel/interacting Metropolis within Gibbs method consists in updating the components  $X_\ell$  successively for  $\ell = 1, \dots, n$ , i.e.

$$[X_{1:n}] \rightarrow [Z_1 X_{2:n}] \rightarrow [Z_{1:2} X_{3:n}] \cdots [Z_{1:n-1} X_n] \rightarrow [Z_{1:n}].$$

For each  $\ell$  fixed, the subcomponents  $X_\ell^i$  are updated sequentially for  $i = 1, \dots, N$  in two steps:

- (i) *Proposal step*: We sample independently  $N$  candidates  $Y_\ell^j \in \mathbb{R}$  for  $j = 1 : N$  according to:

$$Y_\ell^j \sim \pi_{i,j}^{\ell, \text{prop}}(\xi | [Z, X_\ell^i, X]_\ell^i) d\xi, \quad 1 \leq j \leq n$$

where

$$\llbracket Z, \xi, X \rrbracket_\ell^i \stackrel{\text{def}}{=} \left[ \begin{array}{c|c} Z_{1:\ell-1} & \begin{array}{c} Z_\ell^1 \\ \vdots \\ Z_\ell^{i-1} \\ \xi \\ X_\ell^{i+1} \\ \vdots \\ X_\ell^N \end{array} \\ \hline & X_{\ell+1:n} \end{array} \right].$$

We also use the following lighter notation:

$$\pi_{i,j}^{\ell, \text{prop}}(\xi | \xi') = \pi_{i,j}^{\ell, \text{prop}}(\xi | \llbracket Z, \xi', X \rrbracket_\ell^i).$$

- (ii) *Selection step:* The subcomponent  $X_\ell^i$  could be replaced by one of the  $N$  candidates  $Y_\ell^{1:N}$  or stay unchanged according to a multinomial sampling, the resulting value is called  $Z_\ell^i$ , i.e.:

$$Z_\ell^i \leftarrow \begin{cases} Y_\ell^1 & \text{with probability } \frac{1}{N} \alpha_\ell^{i,1}(X_\ell^i, Y_\ell^1), \\ \vdots \\ Y_\ell^N & \text{with probability } \frac{1}{N} \alpha_\ell^{i,N}(X_\ell^i, Y_\ell^N), \\ X_\ell^i & \text{with probability } \tilde{\rho}_\ell^i(X_\ell^i, Y_\ell^{1:N}) \end{cases}$$

where:

$$\alpha_\ell^{i,j}(\xi, \xi') \stackrel{\text{def}}{=} \frac{\pi_\ell(\xi' | X_{-\ell}^i)}{\pi_\ell(\xi | X_{-\ell}^i)} \frac{\pi_{i,j}^{\ell, \text{prop}}(\xi | \xi')}{\pi_{i,j}^{\ell, \text{prop}}(\xi' | \xi)} \wedge 1,$$

$$\tilde{\rho}_\ell^i(X_\ell^i, Y_\ell^{1:N}) \stackrel{\text{def}}{=} 1 - \frac{1}{N} \sum_{j=1}^N \alpha_\ell^{i,j}(X_\ell^i, Y_\ell^j).$$

The resulting algorithm is depicted in Algorithm 2.

### 3.2 Description of the MH kernel

**Lemma 3.1** *The Markov kernel on  $\mathbb{R}^{n \times N}$  associated with the MH algorithm described in Section 3.1, is*

$$P(X, dZ) \stackrel{\text{def}}{=} P_1(X_{1:n}; dZ_1) P_2(Z_1, X_{2:n}; dZ_2) \cdots P_n(Z_{1:n-1}, X_n; dZ_n). \quad (11)$$

At iteration  $\ell$ , the kernel  $P_\ell(Z_{1:\ell-1}, X_{\ell:n}; dZ_\ell)$  generates  $Z_\ell^{1:N}$  from the already updated components  $Z_{1:\ell-1}^{1:N}$  and the remaining components  $X_{\ell:n}^{1:N}$ .

Each component  $Z_{1,\ell}^i$ , for  $i = 1 \cdots N$ , is updated independently one from each other:

$$P_\ell(Z_{1:\ell-1}, X_{\ell:n}; dZ_\ell) \stackrel{\text{def}}{=} \prod_{i=1}^N P_\ell^i(\llbracket Z, X_\ell^i, X \rrbracket_\ell^i; dZ_\ell^i). \quad (12)$$



---

```

choose  $X \in \mathbb{R}^{n \times N}$ 
for  $k = 1, 2, \dots$  do
  for  $\ell = 1 : n$  do
    for  $i = 1 : N$  do
      for  $j = 1 : N$  do
         $Y_\ell^j \sim \pi_{i,j}^{\ell, \text{prop}}(\xi) d\xi$ 
         $\alpha^j \leftarrow \frac{\pi_\ell(Y_\ell^j | X_\ell^i)}{\pi_\ell(X_\ell^i | X_{-\ell}^i)} \frac{\pi_{i,j}^{\ell, \text{prop}}(X_\ell^i | Y_\ell^j)}{\pi_{i,j}^{\ell, \text{prop}}(Y_\ell^j | X_\ell^i)} \wedge 1$ 
      end for
       $\tilde{\rho} \leftarrow 1 - \frac{1}{N} \sum_{j=1}^N \alpha^j$ 
       $X_\ell^i \leftarrow \begin{cases} Y_\ell^1 & \text{with probability } \alpha^1/N \\ \vdots \\ Y_\ell^N & \text{with probability } \alpha^N/N \\ X_\ell^i & \text{with probability } \tilde{\rho} \end{cases}$ 
    end for
  end for
end for

```

---

Algorithm 2: *Parallel/interacting MwG.*

Here  $Z_\ell^i$  is generated from  $\llbracket Z, X_\ell^i, X \rrbracket_\ell^i$  according to:

$$P_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; d\xi') \stackrel{\text{def}}{=} \frac{1}{N} \sum_{j=1}^N \alpha_\ell^{i,j}(\xi, \xi') \pi_{i,j}^{\ell, \text{prop}}(\xi' | \xi) d\xi' + \rho_\ell^i(\xi) \delta_\xi(d\xi') \quad (13)$$

Acceptation probabilities are:

$$\alpha_\ell^{i,j}(\xi, \xi') \stackrel{\text{def}}{=} \begin{cases} r_\ell^{i,j}(\xi, \xi') \wedge 1 & \text{if } (\xi, \xi') \in R_\ell^{i,j}, \\ 0 & \text{otherwise,} \end{cases} \quad (14)$$

$$r_\ell^{i,j}(\xi, \xi') \stackrel{\text{def}}{=} \frac{\pi_\ell(\xi' | Z_{1:\ell-1}^i, X_{\ell+1:n}^i)}{\pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i)} \frac{\pi_{i,j}^{\ell, \text{prop}}(\xi | \xi')}{\pi_{i,j}^{\ell, \text{prop}}(\xi' | \xi)}, \quad (15)$$

$$\rho_\ell^i(\xi) \stackrel{\text{def}}{=} 1 - \frac{1}{N} \sum_{j=1}^N \int_{\mathbb{R}} \alpha_\ell^{i,j}(\xi, \xi') \pi_{i,j}^{\ell, \text{prop}}(\xi' | \xi) d\xi'. \quad (16)$$

Finally,  $R_\ell^{i,j}$  is the set of ordered pairs  $(\xi, \xi') \in \mathbb{R}^2$  such that

$$\begin{aligned}\pi_\ell(\xi'|Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_{i,j}^{\ell, \text{prop}}(\xi|\xi') &> 0, \\ \pi_\ell(\xi|Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_{i,j}^{\ell, \text{prop}}(\xi'|\xi) &> 0.\end{aligned}$$

Note that the functions  $\alpha_\ell^{i,j}(\xi, \xi')$ ,  $\rho_\ell^i(\xi)$ ,  $r_\ell^{i,j}(\xi, \xi')$  and the set  $R_\ell^{i,j}$  depend on  $Z_{1:\ell-1}$  and  $X_{\ell+1:n}$ .

**Proof** This construction follows the general setup proposed by Luke Tierney in [20]. The kernel is defined by:

$$P_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; d\xi') \stackrel{\text{def}}{=} \int_{\mathbb{R}^N} \underbrace{S_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i, \zeta^{1:N}; d\xi')}_{\text{selection kernel}} \times \underbrace{Q_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; d\zeta^{1:N})}_{\text{proposal kernel}}.$$

This kernel consists firstly in proposing a population of  $N$  candidates  $\zeta^{1:N} \in \mathbb{R}^N$  sampled from:

$$Q_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; d\zeta^{1:N}) \stackrel{\text{def}}{=} \prod_{j=1}^N \pi_{i,j}^{\ell, \text{prop}}(\zeta^j|\xi) d\zeta^j, \quad (17)$$

then secondly in selecting among these candidates or rejecting them according to a MH technique, i.e.

$$S_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i, \zeta^{1:N}; d\xi') \stackrel{\text{def}}{=} \frac{1}{N} \sum_{j=1}^N \alpha_\ell^{i,j}(\xi, \zeta^j) \delta_{\zeta^j}(d\xi') + \tilde{\rho}_\ell^i(\xi, \zeta^{1:N}) \delta_\xi(d\xi') \quad (18)$$

where  $\alpha_\ell^{i,j}$  is given by (14) and  $\tilde{\rho}_\ell^i(\xi, \zeta^{1:N}) \stackrel{\text{def}}{=} 1 - \frac{1}{N} \sum_{j=1}^N \alpha_\ell^{i,j}(\xi, \zeta^j)$ .

Hence:

$$\begin{aligned}
P_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; d\xi') &\stackrel{\text{def}}{=} \int_{\zeta^{1:N}} S_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i, \zeta^{1:N}; d\xi') Q_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; d\zeta^{1:N}) \\
&= \frac{1}{N} \sum_{j=1}^N \int_{\zeta^{1:N}} \alpha_\ell^{i,j}(\xi, \zeta^j) \delta_{\zeta^j}(d\xi') \prod_{k=1}^N \pi_{i,j}^{\ell, \text{prop}}(\zeta^k | \xi) d\zeta^k \\
&\quad + \left\{ 1 - \frac{1}{N} \sum_{j=1}^N \int_{\zeta^{1:N}} \alpha_\ell^{i,j}(\xi, \zeta^j) \prod_{k=1}^N \pi_{i,j}^{\ell, \text{prop}}(\zeta^k | \xi) d\zeta^k \right\} \delta_\xi(d\xi') \\
&= \frac{1}{N} \sum_{j=1}^N \int_{\zeta^j} \alpha_\ell^{i,j}(\xi, \zeta^j) \delta_{\zeta^j}(d\xi') \pi_\ell^{\text{prop}}(\zeta^j | \xi) d\zeta^j \\
&\quad + \left\{ 1 - \frac{1}{N} \sum_{j=1}^N \int_{\zeta^j} \alpha_\ell^{i,j}(\xi, \zeta^j) \pi_\ell^{\text{prop}}(\zeta^j | \xi) d\zeta^j \right\} \delta_\xi(d\xi') \\
&= \frac{1}{N} \sum_{j=1}^N \alpha_\ell^{i,j}(\xi, \xi') \pi_\ell^{\text{prop}}(\xi' | \xi) d\xi' \\
&\quad + \left\{ 1 - \frac{1}{N} \sum_{j=1}^N \int_{\xi''} \alpha_\ell^{i,j}(\xi, \xi'') \pi_\ell^{\text{prop}}(\xi'' | \xi) d\xi'' \right\} \delta_\xi(d\xi')
\end{aligned}$$

which correspond to Equations (13) to (16).  $\square$

### 3.3 Invariance property

**Lemma 3.2** For almost all  $(\xi, \xi') \in \mathbb{R}^2$ :

$$\begin{aligned}
\alpha_\ell^{i,j}(\xi, \xi') \pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_{i,j}^{\ell, \text{prop}}(\xi' | \xi) \\
= \alpha_\ell^{i,j}(\xi', \xi) \pi_\ell(\xi' | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_{i,j}^{\ell, \text{prop}}(\xi | \xi')
\end{aligned}$$

for any  $\ell, i, j$ ,  $(Z_{1:\ell-1}^i, X_{\ell+1:n}^i)$ , and  $(Z_{1:\ell-1}^j, X_{\ell+1:n}^j)$ .

**Proof** For  $(\xi, \xi') \notin R_\ell^{i,j}$ , the result is obvious. For  $(\xi, \xi') \in R_\ell^{i,j}$  a.e.:

$$\begin{aligned}
&(r_\ell^{i,j}(\xi, \xi') \wedge 1) \pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_\ell^{\text{prop}}(\xi' | \xi) \\
&= \min \left\{ \pi_\ell(\xi' | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_\ell^{\text{prop}}(\xi | \xi'), \pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_\ell^{\text{prop}}(\xi' | \xi) \right\} \\
&= (r_\ell^{i,j}(\xi', \xi) \wedge 1) \pi_\ell(\xi' | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_\ell^{\text{prop}}(\xi | \xi').
\end{aligned}$$

$\square$

**Lemma 3.3 (conditional detailed balance)** *The following equality of measures defined on  $\mathbb{R} \times \mathbb{R}$*

$$\begin{aligned} P_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; d\xi') \times \pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) d\xi \\ = P_\ell^i(\llbracket Z, \xi', X \rrbracket_\ell^i; d\xi) \times \pi_\ell(\xi' | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) d\xi' \end{aligned} \quad (19)$$

holds true for any  $\ell = 1 \cdots n$ ,  $i = 1 \cdots N$  and  $Z_{1:\ell-1} \in \mathbb{R}^{N \times (\ell-1)}$ ,  $X_{\ell+1:n} \in \mathbb{R}^{N \times (n-\ell)}$ .

**Proof** The left hand side of equality (19) is a measure  $\nu(d\xi' \times d\xi)$  defined on  $(\mathbb{R}^2, \mathcal{B}(\mathbb{R}^2))$ . For all  $A_1, A_2 \in \mathcal{B}(\mathbb{R})$ , we want to prove that  $\nu(A_1 \times A_2) = \nu(A_2 \times A_1)$ .

We have:

$$\nu(A_1 \times A_2) = \int P_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; A_1) \mathbf{1}_{A_2}(\xi) \pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) d\xi$$

and

$$P_\ell^i(\llbracket Z, \xi, X \rrbracket_\ell^i; A_1) = \frac{1}{N} \sum_{j=1}^N \int \mathbf{1}_{A_1}(\xi') \alpha_\ell^{i,j}(\xi, \xi') \pi_\ell^{\text{prop}}(\xi' | \xi) d\xi' + \rho_\ell^i(\xi) \mathbf{1}_{A_1}(\xi)$$

so that

$$\begin{aligned} \nu(A_1 \times A_2) &= \frac{1}{N} \sum_{j=1}^N \iint \mathbf{1}_{A_1}(\xi') \mathbf{1}_{A_2}(\xi) \alpha_\ell^{i,j}(\xi, \xi') \\ &\quad \pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_\ell^{\text{prop}}(\xi' | \xi) d\xi d\xi' \\ &\quad + \int \rho_\ell^i(\xi) \mathbf{1}_{A_1}(\xi) \mathbf{1}_{A_2}(\xi) \pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) d\xi \end{aligned} \quad (20)$$

Using Lemma 3.2 we get:

$$\begin{aligned} \nu(A_1 \times A_2) &= \frac{1}{N} \sum_{j=1}^N \iint \mathbf{1}_{A_1}(\xi') \mathbf{1}_{A_2}(\xi) \alpha_\ell^{i,j}(\xi', \xi) \\ &\quad \pi_\ell(\xi' | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) \pi_\ell^{\text{prop}}(\xi | \xi') d\xi' d\xi \\ &\quad + \int \rho_\ell^i(\xi) \mathbf{1}_{A_1}(\xi) \mathbf{1}_{A_2}(\xi) \pi_\ell(\xi | Z_{1:\ell-1}^i, X_{\ell+1:n}^i) d\xi \end{aligned}$$

Exchanging the name of variables  $\xi \leftrightarrow \xi'$  in the first term of the right hand side of the previous equality leads to the same expression as (20) where  $A_1$  and  $A_2$  were interchanged, in other words  $\nu(A_1 \times A_2) = \nu(A_2 \times A_1)$ .  $\square$

**Proposition 3.4 (invariance)** *The measure*

$$\Pi(dX) = \pi(X^1) dX^1 \cdots \pi(X^N) dX^N$$

is invariant for the kernel  $P$ , that is  $\Pi P = \Pi$  i.e.:

$$\int_X P(X, dZ) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} = \prod_{i=1}^N \pi(Z^i) dZ^i. \quad (21)$$

**Proof**

$$\begin{aligned}
& \int_X P(X, dZ) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} \\
&= \int_X P_1(X_{1:n}; dZ_1) P_2(Z_1, X_{2:n}; dZ_2) \cdots P_n(Z_{1:n-1}, X_n; dZ_n) \\
&\quad \prod_{i=1}^N \left\{ \pi_1(X_1^i | X_{2:n}^i) dX_1^i \pi_{-1}(X_{2:n}^i) dX_{2:n}^i \right\} \\
&= \int_X P_1(X_{1:n}; dZ_1) \left\{ \prod_{i=1}^N \pi_1(X_1^i | X_{2:n}^i) dX_1^i \right\} \\
&\quad P_2(Z_1, X_{2:n}; dZ_2) \cdots P_n(Z_{1:n-1}, X_n; dZ_n) \left\{ \prod_{i=1}^N \pi_{-1}(X_{2:n}^i) dX_{2:n}^i \right\} \\
&= \int_X \left\{ \prod_{i=1}^N P_1^i(\llbracket Z, X_1^i, X_{1:n}^i \rrbracket; dZ_1^i) \right\} \left\{ \prod_{i=1}^N \pi_1(X_1^i | X_{2:n}^i) dX_1^i \right\} \\
&\quad P_2(Z_1, X_{2:n}; dZ_2) \cdots P_n(Z_{1:n-1}, X_n; dZ_n) \left\{ \prod_{i=1}^N \pi_{-1}(X_{2:n}^i) dX_{2:n}^i \right\}
\end{aligned}$$

Moreover

$$\begin{aligned}
& P_1(X_{1:n}; dZ_1) \left\{ \prod_{i=1}^N \pi_1(X_1^i | X_{2:n}^i) dX_1^i \right\} = \\
&= \left\{ \prod_{i=1}^N P_1^i(\llbracket Z, X_1^i, X_{1:n}^i \rrbracket; dZ_1^i) \right\} \left\{ \prod_{i=1}^N \pi_1(X_1^i | X_{2:n}^i) dX_1^i \right\} \\
&= \prod_{i=1}^N P_1^i(\llbracket Z, X_1^i, X_{1:n}^i \rrbracket; dZ_1^i) \pi_1(X_1^i | X_{2:n}^i) dX_1^i \\
&= \prod_{i=1}^N P_1^i(\llbracket Z, Z_1^i, X_{1:n}^i \rrbracket; dZ_1^i) \pi_1(Z_1^i | X_{2:n}^i) dZ_1^i
\end{aligned}$$

this last equality follows from Equation (19). Hence,

$$\begin{aligned}
& \int_X P(X, dZ) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} \\
&= \int_X \prod_{i=1}^N \left\{ P_1^i(\llbracket Z, Z_1^i, X_{1:n}^i \rrbracket; dZ_1^i) \pi_1(Z_1^i | X_{2:n}^i) dZ_1^i \right\} P_2(Z_1, X_{2:n}; dZ_2) \cdots \\
&\quad \cdots P_n(Z_{1:n-1}, X_n; dZ_n) \left\{ \prod_{i=1}^N \pi_{-1}(X_{2:n}^i) dX_{2:n}^i \right\}
\end{aligned}$$

In this last expression, for  $i = 1, \dots, N$ , the kernel  $P_1^i(\llbracket Z, Z_1^i, X \rrbracket_1^i; dX_1^i)$  is a measure for the variable  $X_1^i$  which no longer appears in the integrand. Using the fact that the integral of the kernel w.r.t.  $X_1^i$  is 1 we get:

$$\begin{aligned} & \int_X P(X, dZ) \left\{ \prod_{i=1}^N \pi(X^i) dX^i \right\} \\ &= \int_{X_{2:N}} \prod_{i=1}^N \left\{ \pi_1(Z_1^i | X_{2:n}^i) dZ_1^i \right\} P_2(Z_1, X_{2:n}; dZ_2) \cdots \\ & \quad \cdots P_n(Z_{1:n-1}, X_n; dZ_n) \left\{ \prod_{i=1}^N \pi_{-1}(X_{2:n}^i) dX_{2:n}^i \right\} \\ &= \int_{X_{2:N}} \prod_{i=1}^N P_2(Z_1, X_{2:n}; dZ_2) \cdots \\ & \quad \cdots P_n(Z_{1:n-1}, X_n; dZ_n) \left\{ \prod_{i=1}^N \pi(Z_1^i X_{2:n}^i) dZ_1^i dX_{2:n}^i \right\} \end{aligned}$$

Repeating this process successively for  $X_2$  to  $X_n$  leads to (21).  $\square$

## 4 Numerical tests

### 4.1 A multi-modal example

We apply now the parallel/interacting Metropolis-Hastings sampler, see Section 2, to a case where the target distribution is multimodal:

$$\pi = p_1 \mathcal{N}(C_1, I) + p_2 \mathcal{N}(C_2, I) + p_3 \mathcal{N}(C_3, I)$$

with  $p_1 = 0.1$ ,  $p_2 = 0.3$ ,  $p_3 = 0.6$ , and  $C_1 = (-10, -10)$ ,  $C_2 = (5, 0)$ ,  $C_3 = (-5, 5)$ . It is a mixture of 3 two-dimensional Gaussian densities.

We describe the proposal kernel (1), for updating the component  $X^i$ , each chain  $j$  propose a new candidate according to the following distribution law:

$$\pi_{i,j}^{\text{prop}}(y | X^i) = \pi_{i,j}^{\text{prop}}(y | Z^{1:i-1}, X^i, X^{i+1:N}) = \begin{cases} \mathcal{N}(X^i, \frac{1}{d} I), & \text{if } i \neq j, \\ \mathcal{N}(X^j, I), & \text{if } i = j \end{cases}$$

where  $d \stackrel{\text{def}}{=} |X^i - X^j|$ .

The idea here is to explore the space with a Gaussian random walk ( $i = j$ ) but also to allow ‘‘jumps’’ toward already explored interesting areas ( $i \neq j$ ). If  $X^i$  and  $X^j$  are close one the other, then ‘‘the chain  $j$  will propose a candidate far from  $X^j$  and  $X^i$ ’’. If  $X^i$  and  $X^j$  are far one to the other, then the ‘‘chain  $j$  will propose a candidate close to  $X^j$ ’’.

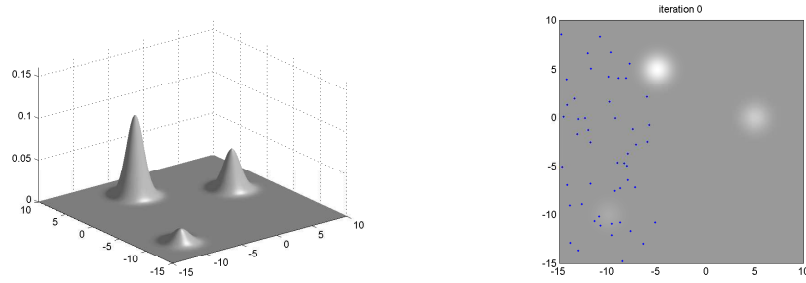


Figure 1: Target distribution  $\pi(x)$  (left) and initial positions of the chains  $X^{(0),i}$ , for  $i = 1 \dots N$  (right).

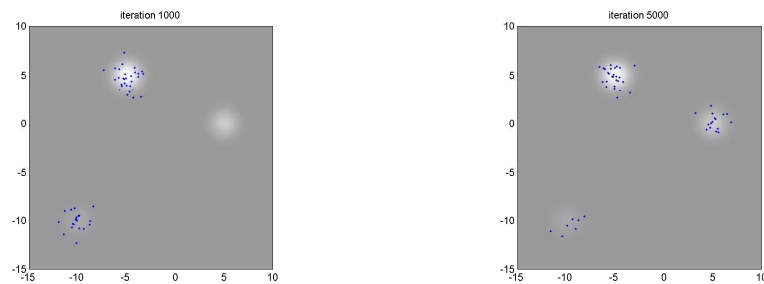
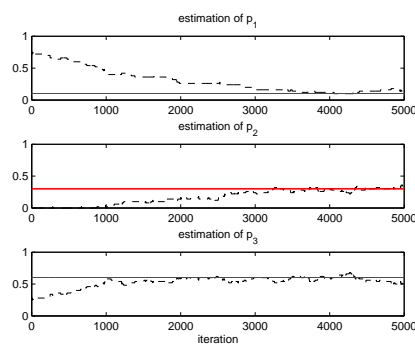


Figure 2: Positions of the chains  $X^{(k),i}$ , for  $i = 1 \dots N$ , at iterations  $k = 1000$  (left) and  $k = 5000$  (right).



INRIA

Figure 3: Evolution of the proportion of particles located in the three different modes.

Here  $N = 50$ , and the initial points  $\mathbf{X}^{(0),i}$ , for  $i = 1 \dots N$ , are sampled according to the uniform law on the square  $[-15, 10] \times [0, 10]$ , see Figure 1 (right). Figures 2 clearly demonstrate the convergence of the method. In Figure 3 we present the evolution of the proportion of particles located in the neighbor of the three different modes: this also demonstrates the good behavior of the method. Note that the initial particles do not cover the mode number 2, so the algorithm is able to reach the isolated mode and to balances the particles among the modes according to the parameters  $p_i$ .

## 4.2 An hidden Markov model

We apply the parallel/interacting Metropolis within Gibbs sampler, see Section 3, to a toy problem where a good estimate  $\hat{\pi}$  of the target distribution  $\pi$  is available. Consider the linear Gaussian state space model:

$$\mathbf{s}_{\ell+1} = \mathbf{a} \mathbf{s}_{\ell} + \mathbf{w}_{\ell}, \quad \mathbf{s}_1 \sim \mathcal{N}(\bar{\mathbf{s}}_1, Q_1), \quad (22a)$$

$$\mathbf{y}_{\ell} = \mathbf{b} \mathbf{s}_{\ell} + \mathbf{v}_{\ell} \quad (22b)$$

for  $\ell = 1 \dots n$ , where  $\mathbf{w}_{1:n}$  and  $\mathbf{v}_{1:n}$  are centered white Gaussian noises with variances  $\sigma_w^2$  and  $\sigma_v^2$ . Suppose that  $\mathbf{b}$  is known and  $\mathbf{a} = \theta$  is unknown with a priori law  $\mathcal{N}(\mu_{\theta}, \sigma_{\theta}^2)$ . We also suppose that  $\mathbf{w}_{1:n}$ ,  $\mathbf{v}_{1:n}$ ,  $\mathbf{s}_1$  and  $\theta$  are mutually independent.

The state variable is

$$\mathbf{x}_{1:n+1} \stackrel{\text{def}}{=} (\mathbf{s}_{1:n}, \theta)$$

and the target conditional density is

$$\pi(\mathbf{x}_{1:n+1}) d\mathbf{x}_{1:n+1} = \pi(\mathbf{s}_{1:n}, \vartheta) d\mathbf{s}_{1:n} d\vartheta \stackrel{\text{def}}{=} \text{law}(\mathbf{s}_{1:n}, \theta | \mathbf{y}_{1:n} = \mathbf{y}_{1:n}).$$

This target law is not Gaussian, but we can perform a Gibbs sampler. Indeed the marginal conditional laws are available:

$$\begin{aligned} \pi_{\mathbf{s}_{\ell}}(s_{\ell} | s_{-\ell}, \vartheta) d\mathbf{s}_{\ell} &\stackrel{\text{def}}{=} \text{law}(\mathbf{s}_{\ell} | \mathbf{s}_{-\ell} = s_{-\ell}, \theta = \vartheta, \mathbf{y}_{1:n} = \mathbf{y}_{1:n}) = \mathcal{N}(\mathbf{m}_{\ell}, \mathbf{r}^2), \\ \pi_{\theta}(\vartheta | \mathbf{s}_{1:n}) d\vartheta &\stackrel{\text{def}}{=} \text{law}(\theta | \mathbf{s}_{1:n} = \mathbf{s}_{1:n}, \mathbf{y}_{1:n} = \mathbf{y}_{1:n}) = \mathcal{N}(\tilde{\mathbf{m}}, \tilde{\mathbf{r}}^2) \end{aligned}$$

with

$$\begin{aligned} \mathbf{r}^2 &\stackrel{\text{def}}{=} \left( \frac{\mathbf{b}^2}{\sigma_v^2} + \frac{1}{\sigma_w^2} + \frac{\vartheta^2}{\sigma_w^2} \right)^{-1}, & \mathbf{m}_{\ell} &\stackrel{\text{def}}{=} \mathbf{r}^2 \left( \frac{\mathbf{b} \mathbf{y}_{\ell}}{\sigma_v^2} + \frac{\vartheta \mathbf{s}_{\ell+1}}{\sigma_w^2} + \frac{\vartheta \mathbf{s}_{\ell-1}}{\sigma_w^2} \right), \\ \tilde{\mathbf{r}}^2 &\stackrel{\text{def}}{=} \left( \frac{1}{\sigma_{\theta}^2} + \frac{\sum_{\ell=2}^n \mathbf{s}_{\ell-1}^2}{\sigma_w^2} \right)^{-1}, & \tilde{\mathbf{m}} &\stackrel{\text{def}}{=} \tilde{\mathbf{r}}^2 \left( \frac{\mu_{\theta}}{\sigma_{\theta}^2} + \frac{\sum_{\ell=2}^n \mathbf{s}_{\ell-1} \mathbf{s}_{\ell}}{\sigma_w^2} \right). \end{aligned}$$

We will perform three algorithms:

- (i)  $N$  parallel/interacting Metropolis within Gibbs samplers (Alg. 2),
- (ii)  $N$  parallel/independent Metropolis within Gibbs samplers (Alg. 3),



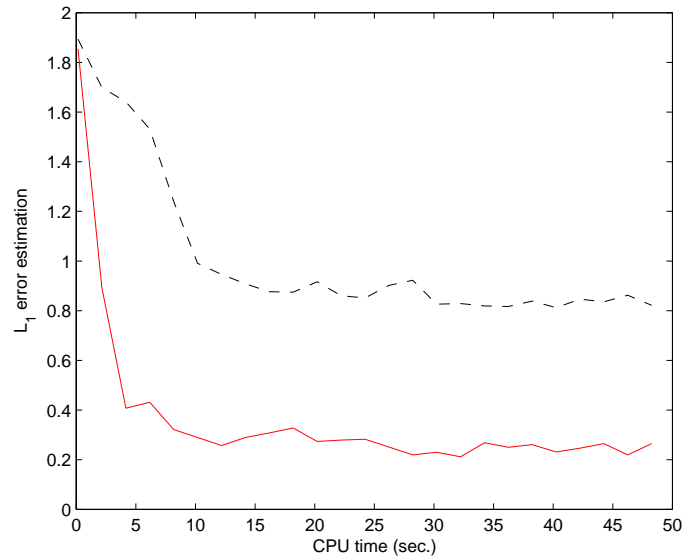


Figure 4: Evolution of the indicator  $\varepsilon^k$ , see (23), for the parallel/independent MwG sampler (- -), and for the parallel/interacting MH sampler (-). This evolution is depicted as a function of the CPU time and not as a function of the iteration number  $k$ . The residual error of about 0.22 for the second method is due to the limited size of the sample.

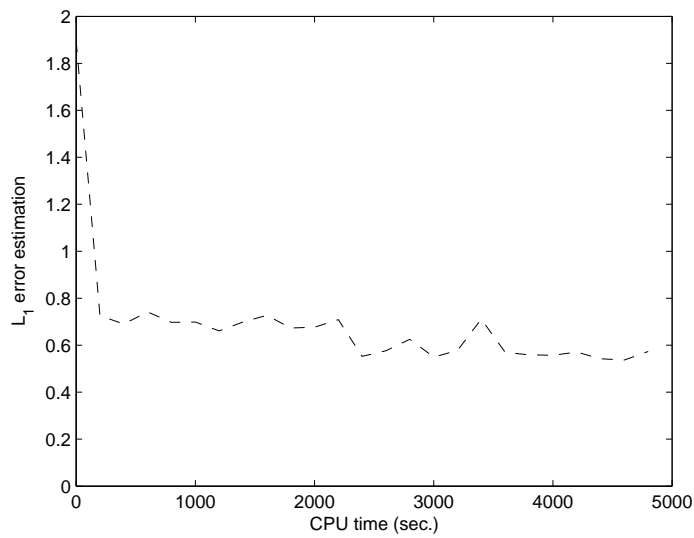


Figure 5: Evolution of the indicator  $\varepsilon^k$ , see (23), for the parallel/independent MwG sampler (- -). After 5000 sec. CPU time, the convergence of this method is still unsatisfactory.

(iii)  $N_{\text{Gibbs}}$  parallel/independent Gibbs samplers.

Our aim is to show that making parallel samplers interact could speed up the convergence toward the stationary distribution.

Because of its good convergence property, method (iii) is considered as a reference method. Here we perform  $k = 10000$  iterations of  $N_{\text{Gibbs}} = 5000$  independent Gibbs samplers. We obtain a kernel density estimate  $\hat{\pi}$  of the target density based on the  $N_{\text{Gibbs}} = 5000$  final values. Let  $\hat{\pi}_{x_\ell}$  be the corresponding  $\ell$ -th marginal density.

For methods (i) and (ii) we perform  $N = 50$  parallel samplers. Let  $\pi^{\text{int},k}$  and  $\pi^{\text{ind},k}$  be the kernel density estimates of the target density based on the final values of methods (i) and (ii) respectively. Let  $\pi_{x_\ell}^{\text{int},k}$  and  $\pi_{x_\ell}^{\text{ind},k}$  be the corresponding  $\ell$ -th marginal densities.

The parameter values for the simulations are  $\mathbf{a} = 2$ ,  $\mathbf{b} = 2$ ,  $\sigma_w^2 = 9$ ,  $\sigma_v^2 = 25$ ,  $s_1 \sim \mathcal{N}(4, 9)$ ,  $\theta \sim \mathcal{N}(1, 4)$  and  $n = 10$ .

For each algorithm (i) and (ii), that is for  $\pi_{x_\ell}^k = \pi_{x_\ell}^{\text{ind},k}$  and  $\pi_{x_\ell}^{\text{int},k}$ , we compute

$$\varepsilon_\ell^k \stackrel{\text{def}}{=} \int |\pi_{x_\ell}^k(\xi) - \hat{\pi}_{x_\ell}(\xi)| d\xi, \quad \ell = 1 \cdots n + 1.$$

Hence  $\varepsilon_\ell^k$  is an estimation of the  $L^1$  error between the target probability distribution and its estimation provided by the algorithm used. To sum up the information of the  $n = 10$  indicators we consider their mean:

$$\varepsilon^k = \frac{1}{n+1} \sum_{\ell=1}^{n+1} \varepsilon_\ell^k. \quad (23)$$

These estimations are based on a sample of size  $N = 50$  only, so they suffer from variability. This is not problematical, indeed we do not want to estimate  $L^1$  errors but to diagnose the convergence toward the stationary distribution. So we use  $\varepsilon_\ell^k$  as an indicator which must decrease and remain close to a small value when convergence occurs.

To compare fairly the parallel/independent MwG algorithm and the parallel/interacted MwG algorithm, we represent on Figures 4 and 5 the indicator  $\varepsilon^k$  for each algorithm not as a function of  $k$  but as a function of the CPU time.

In Figure 4 we see that even if one iteration of algorithm (i) needs more CPU than one of (ii), still the first algorithm converges more rapidly than the second one. The residual error of 0.22 is due to the limited size of the sample. This error decreases to 0 as  $N \uparrow \infty$ . Figure 5 shows the inefficiency of parallel/independent MwG on this simple model.

## 5 Conclusion

This work showed that making parallel MCMC chains interact could improve their convergence properties. We proved the basic properties of the MCMC method, we did not prove that the proposed strategy speeds up the convergence. This difficult point is related to the problem of the rate of the convergence of the MCMC algorithms.

Through a simple example we saw that the Metropolis within Gibbs strategy could be a poor strategy. However this method is widely used in practice on more complex non linear models. In this situation our strategy improved the convergence properties. We also demonstrated that this approach can handle multimodal cases.

## Appendix: MwG algorithm

One iteration  $X \rightarrow Z$  of the Metropolis within Gibbs method consists in updating the components  $X_\ell$  successively for  $\ell = 1, \dots, n$ , i.e.

$$[X_{1:n}] \rightarrow [Z_1 X_{2:n}] \rightarrow [Z_{1:2} X_{3:n}] \cdots [Z_{1:n-1} X_n] \rightarrow [Z_{1:n}].$$

Each components  $X_\ell$  is updated in two steps:

- (i) *Proposal step*: We sample a candidate  $Y_\ell$  according to:

$$Y_\ell \sim \pi_\ell^{\text{prop}}(\xi) d\xi$$

- (ii) *Selection step*: The component  $X_\ell$  could be replaced by the candidate  $Y_\ell$  or stay unchanged according to a binomial sampling, the resulting value is called  $Z_\ell$ , i.e.:

$$Z_\ell \leftarrow \begin{cases} Y_\ell & \text{with probability } \alpha_\ell(X_\ell, Y_\ell), \\ X_\ell & \text{with probability } 1 - \alpha_\ell(X_\ell, Y_\ell) \end{cases}$$

where:

$$\alpha_\ell(\xi, \xi') \stackrel{\text{def}}{=} \frac{\pi_\ell(\xi')}{\pi_\ell(\xi)} \frac{\pi_\ell^{\text{prop}}(\xi)}{\pi_\ell^{\text{prop}}(\xi')} \wedge 1$$

The resulting algorithm is depicted in Algorithm 3.

---

```

choose  $X_{1:n} \in \mathbb{R}^n$ 
for  $k = 1, 2, \dots$  do
  for  $\ell = 1 : n$  do
     $Y_\ell \sim \pi_\ell^{\text{prop}}(\xi) d\xi$  {proposed candidate}
     $u \sim \mathcal{U}[0, 1]$ 
    if  $u \leq \alpha_\ell(X_\ell, Y_\ell)$  then
       $X_\ell \leftarrow Y_\ell$ 
    end if
  end for
end for

```

---

Algorithm 3: *Metropolis within Gibbs sampler. We can go through the component indices in a random way.*

## References

- [1] Stephen P. Brooks and Gareth O. Roberts. Convergence assessment techniques for Markov chain Monte Carlo. *Statistics and Computing*, 8(4):319–335, 1998.
- [2] Olivier Cappé, Arnaud Guillin, Jean-Michel Marin, and Christian P. Robert. Population Monte Carlo. *Journal of Computational and Graphical Statistics*, 13(4):907–929, 2004.
- [3] Chang-Tai Chao. Markov Chain Monte Carlo on optimal adaptive sampling selection. *Environmental and Ecological Statistics*, 10(1):129 – 151, 2003.
- [4] Didier Chauveau and Pierre Vandekerkhove. Algorithmes de Hastings-Metropolis en interaction. *Comptes Rendus de l'Académie des Sciences, Série I, Mathématique*, 333(9):881–884, 2001.
- [5] Didier Chauveau and Pierre Vandekerkhove. Improving convergence of Hastings–Metropolis algorithm with an adaptive proposal. *Scandinavian Journal of Statistics*, 29(1):13–29, March 2002.
- [6] Mary Kathryn Cowles and Bradley P. Carlin. Markov chain Monte Carlo convergence diagnostics: a comparative review. *Journal of the American Statistical Association*, 91(434):883–904, 1996.
- [7] Madalina M. Drugan and Dirk Thierens. Evolutionary Markov Chain Monte Carlo. *Lecture Notes in Computer Science*, 2936:63–76, 2004.
- [8] Madalina M. Drugan and Dirk Thierens. Recombinative EMCMC algorithms. In *IEEE Congress on Evolutionary Computation*, pages 2024– 2031, 2005.
- [9] Andrew Gelman and Donald B. Rubin. Inference from iterative simulation using multiple sequences (with discussion). *Statistical Science*, 7:457–511, 1992.
- [10] Charles J. Geyer. Markov chain monte carlo maximum likelihood. In E.M. Keramidas, editor, *Computing Science and Statistics: Proceedings of the 23rd Symposium on the Interface*, 1991.
- [11] Charles J. Geyer. Practical Markov chain Monte Carlo (with discussion). *Statistical Science*, 4:473–482, 1992.
- [12] Walter R. Gilks, Sylvia Richardson, and David J. Spiegelhalter, editors. *Markov Chain Monte Carlo in practice*. Chapman & Hall, London, 1995.
- [13] Walter R. Gilks and Gareth O. Roberts. Strategies for improving MCMC. In W.R. Gilks, S. Richardson, and D.J. Spiegelhalter, editors, *Markov Chain Monte Carlo in practice*. Chapman & Hall, 1995.
- [14] Yukito Iba. Population Monte Carlo algorithms. *Transactions of the Japanese Society for Artificial Intelligence*, 16(2):279–286, 2001.

- 
- [15] Robert E. Kass, Bradley P. Carlin, Andrew Gelman, and Radford M. Neal. Markov Chain Monte Carlo in practice: A roundtable discussion. *The American Statistician*, 52:93–100, 1998.
- [16] Kathryn B. Laskey and James W. Myers. Population Markov Chain Monte Carlo. *Machine Learning*, 50(1-2):175–196, 2003.
- [17] Kerrie L. Mengersen and Christian P. Robert. Population Markov Chain Monte Carlo: the pinball sampler. In J.O. Berger, A.P. Dawid, and A.F.M. Smith, editors, *Bayesian Statistics 7*. Oxford University Press, 2003.
- [18] Christian P. Robert. *Méthodes de Monte Carlo par Chaînes de Markov*. Economica, Paris, 1996.
- [19] Luke Tierney. Markov chains for exploring posterior distributions (with discussion). *The Annals of Statistics*, 22(4):1701–1728, December 1994.
- [20] Luke Tierney. A note on Metropolis-Hastings kernels for general state spaces. *The Annals of Applied Probability*, 8(1):1–9, 1998.



---

Unité de recherche INRIA Lorraine, Technopôle de Nancy-Brabois, Campus scientifique,  
615 rue du Jardin Botanique, BP 101, 54600 VILLERS LÈS NANCY  
Unité de recherche INRIA Rennes, Irisa, Campus universitaire de Beaulieu, 35042 RENNES Cedex  
Unité de recherche INRIA Rhône-Alpes, 655, avenue de l'Europe, 38330 MONTBONNOT ST MARTIN  
Unité de recherche INRIA Rocquencourt, Domaine de Voluceau, Rocquencourt, BP 105, 78153 LE CHESNAY Cedex  
Unité de recherche INRIA Sophia-Antipolis, 2004 route des Lucioles, BP 93, 06902 SOPHIA-ANTIPOLIS Cedex

---

Éditeur  
INRIA, Domaine de Voluceau, Rocquencourt, BP 105, 78153 LE CHESNAY Cedex (France)  
<http://www.inria.fr>  
ISSN 0249-6399