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Claudio Baiocchi, Michel Crouzeix. On the equivalence of a-stability and g-stability. [Research Report] RR-0609, INRIA. 1987. inria-00075945

HAL Id: inria-00075945 https://inria.hal.science/inria-00075945

Submitted on 24 May 2006

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Rapports de Recherche

Nº 609

ON THE EQUIVALENCE OF A-STABILITY AND G-STABILITY

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Février 1987

IRISA

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On the equivalence of A-stability and G-stability

Equivalence entre A-stabilité et G-stabilité

Publication Interne n°330 - Décembre 1986 5 pages

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Abstract: We prove an algebraic result which gives a new characterization of the A-stability property for linear multistep methods. This enables us to obtain a new simple proof of the equivalence between A-stability and G-stability for one-leg methods. Using the algebraic result, we also give an alternative proof of the second Dahlquist barrier.

Résumé : On montre un résultat algébrique qui fournit une nouvelle caractérisation de la A-stabilité pour les méthodes linéaires à pas multiples. Nous en déduisons une démonstration simple de l'équivalence entre A- et G-stabilité ainsi que la seconde barrière de Dahlquist.

"On the equivalence of A-stability and G-stability."

by Claudio Baiocchi and Michel Crouzeix.

Abstract: We prove an algebraic result which gives a new characterization of the A-stability property for linear multistep methods. This enables us to obtain a new simple proof of the equivalence between A-stability and G-stability for one-leg methods. Using the algebraic result, we also give an alternative proof of the second Dahlquist barrier.

1- The algebraic result.

Given two polynomials ρ and σ , of degree $r \geq 1$, with real coefficients, we consider the properties

(A)
$$|z| \ge 1 \Rightarrow \text{Re } \rho(z) \ \sigma(\overline{z}) \ge 0$$

and

there exist (r+1) real polynomials $p_1,...,p_r$ and q with

(B) $\deg (p_k) \le r-1$ and $\deg (q) \le r$, such that, for arbitrary $z, w \in C$,

$$\rho(z) \ \sigma(w) + \rho(w) \ \sigma(z) + (1 - zw) \sum_{k=1}^{r} p_k(z) \ p_k(w) = q(z) \ q(w).$$

Theorem 1. The properties (A) and (B) are equivalent; furthermore, if the polynomials ρ and σ are relatively prime, then the polynomials ρ_k are linearly independent.

Proof. Implication (B) \Rightarrow (A) is obtained by taking $w = \overline{z}$. For the converse, we can assume that the polynomials ρ and σ are relatively prime, otherwise we may divide them by their common factor.

As a first step, we show that there exists a polynomial q , with real coefficients and $deg(q) \le r$, such that

$$E(z) = \rho(z) \sigma(1/z) + \rho(1/z) \sigma(z) = q(z) q(1/z)$$
. (1)

Indeed, if we exclude the trivial case $E\equiv 0$, the roots of E are different from zero and their number (counted with their multiplicities) cannot exceed 2r; since E(z)=E(1/z), if z_j is a root of E with multiplicity n_j , $1/z_j$ is also a root of E with multiplicity n_j ; when |z|=1,

property (A) yields E(z)=2 Re $\rho(z)$ $\sigma(\overline{z})\geq0$, therefore the multiplicities of the unimodular roots of E are even. Then E can be written as follows:



$$\mathsf{E}(z) \ = \ a_0 \prod_{j: \ |z_j| \ge 1} \ (\ z - z_j)^m j \ (1/z - z_j)^m j \ ,$$

where $m_j = n_j$ if $|z_j| > 1$ and $m_j = n_j/2$ if $|z_j| = 1$. We have $a_0 > 0$ since $E(z) \ge 0$ for |z| = 1. Then we can choose $q(z) = \sqrt{a_0} \ \Pi \ (z - z_j)^m j$; the coefficients of the polynomial q are real, since each complex root is associated with its conjugate.

Now the relation (1) is satisfied; this means that the polynomial $q(z)\ q(w)\ -\ \rho(z)\ \sigma(w)\ -\ \rho(w)\ \sigma(z) \quad \text{is equal to zero when}\quad zw=1\ .$ It can then be written as follows

$$q(z) \ q(w) - \rho(z) \ \sigma(w) - \rho(w) \ \sigma(z) = (1 - zw) \sum_{k,\ell=1}^{r} g_{k\ell} \ z^{\ell-1} \ w^{k-1} \ . \tag{2}$$

By lemma 2 below, there exists a real matrix $A = (a_{ij})$, such that $G = A^T A$; the theorem follows by taking

$$p_k(z) = \sum_{i=1}^r a_{ki} z^{i-1}$$
.

Since the matrix A is regular, the polynomials $p_{\boldsymbol{k}}$ are linearly independent.

Lemma 2. The symmetric matrix $G = (g_{k\ell})$ is positive definite.

Proof. For a multiple root z of $\rho + \lambda \sigma$, we have $\rho(z) + \lambda \sigma(z) = \rho'(z) + \lambda \sigma'(z) = 0$, whence $\rho(z) \sigma'(z) - \rho'(z) \sigma(z) = 0$; so that the multiple roots have a finite number of possible values. Since the polynomials ρ and σ are supposed relatively prime, the number of values of λ such that the polynomial $\rho(z) + \lambda \sigma(z)$ has multiple roots is finite. It follows that there exist a real number λ and r distinct complex numbers z_i satisfying,

$$\lambda > 0$$
, $\rho(z_i) + \lambda \sigma(z_i) = 0$ and $\sigma(z_i) \neq 0$, for $i = 1, ..., r$. (3)

Furthermore, property (A) yields

$$|z_i| < 1$$
, for $i = 1,...,r$. (4)

Now we consider the Vandermonde, r x r, matrix

$$V = (v_{ij})$$
 where $v_{ij} = z_i^{i-1}$;

from (1) we deduce $V^*GV==(b_{ij})$, where

$$\begin{split} b_{ij} &= \left[\ q(\overline{z_i}) \ q(z_j) - \rho(\overline{z_i}) \ \sigma(z_j) - \rho(z_j) \ \sigma(\overline{z_i}) \ \right] \ / \ (1 - \overline{z_i} \ z_j) \\ &= \left[\ q(\overline{z_i}) \ q(z_j) + 2 \ \lambda \ \sigma(\overline{z_i}) \ \sigma(z_j) \ \right] \ / \ (1 - \overline{z_i} z_j) \ . \end{split}$$

The bound (4) allows the expansion

$$b_{ij} = \sum_{m=0}^{\infty} \left[\overline{z}_i^m \ q(\overline{z}_i) \ q(z_j) \ z_j^m + 2 \lambda \overline{z}_i^m \ \sigma(\overline{z}_i) \ \sigma(z_j) \ z_j^m \right].$$

Since $\sigma(z_i) \neq 0$, for i=1,...,r, we deduce that the matrix B, and consequently the matrix G, is positive definite.

2. Application 1. The equivalence of A- and G-stability.

In order to approximate the solution of differential equations, we consider the linear multistep method associated with the pair of polynomials (ρ , σ). For a sequence y_0 , y_1 ,..., y_n ,... of complex numbers, we denote by E the unitary shift operator: E $y_n = y_{n+1}$. According to G. Dahlquist, the (ρ , σ) method is A-stable if, for all complex numbers λ such that Re λ < 0 and all sequences y_n satisfying $\rho(E)$ $y_n = \lambda \, \sigma(E)$ y_n , we have $\lim_{n \to \infty} y_n = 0$; or equivalently

$$\forall \lambda \in \mathbf{C}$$
, Re $\lambda < 0$ and $\rho(z) - \lambda \sigma(z) = 0 \implies |z| < 1$.

Therefore, A-stability implies property (A), (and is equivalent to it, when the polynomials ρ and σ are relatively prime).

Consider the column vector $Y_n = (y_n, y_{n+1}, ..., y_{n+r-1})^T$ in \mathbf{C}^r ; according to G. Dahlquist, the (ρ, σ) method is G-stable if there exists a symmetric, positive definite matrix G such that

Re
$$\rho(E) y_n \cdot \overline{\sigma(E) y_n} \le 0 \implies Y_{n+1}^* G Y_{n+1} \le Y_n^* G Y_n$$
 (5)

We have seen that the property (B) implies (2), therefore

q(E) $y_n . \overline{q(E)} y_n - 2 \operatorname{Re} \rho(E) y_n . \overline{\sigma(E)} y_n = Y_n^* G Y_n - Y_{n+1}^* G Y_{n+1}$, which gives (5) . Conversely, using the sequence $y_n = z^n$, we obtain the property (A) from (5) . We get in another way, the following result of G. Dahlquist.

Theorem 3. If the polynomials ρ and σ are relatively prime, A-stability and G-stability are equivalent.

We remark also that the proof of theorem 1 provides a way to construct the matrix G.

3. Application 2. The second barrier of Dahlquist.

Theorem 4. The order of accuracy of a linear multistep A-stable method is limited to two. For the method of order two, the best possible error constant is 1/12.

Proof. The order of a (ρ , σ) method is 2 if

$$\rho(e^{z}) / \sigma(e^{z}) = z - c z^{3} + O(z^{4}), \quad (as z \to 0) ;$$
 (6)

it is greater than 2 when the error constant $\,c\,$ is zero. Furthermore A-stability and (6) imply property (B) and $\,\sigma(1)\neq 0$. Setting

$$\pi_k(z) = \rho_k(e^z) / \sigma(e^z)$$
, $\varphi(z) = q(e^z) / \sigma(e^z)$,

we obtain

$$z + w - c (z^3 + w^3) + (1 - e^{z+w}) \sum_{k=1}^{r} \pi_k(z) \pi_k(w) = \phi(z) \phi(w) + O(z^4 + w^4).$$

If we identify the coefficients in the Taylor expansion, we deduce that

$$\varphi(0) = \varphi'(0) = 0$$
,

$$\sum_{k=1}^{r} \pi_{k}(0)^{2} = 1 , \sum_{k=1}^{r} \pi_{k}(0) \pi_{k}'(0) = -1/2 , \sum_{k=1}^{r} \pi_{k}'(0)^{2} = c + 1/6 .$$

From the Cauchy-Schwarz inequality $1/4 \le c + 1/6$, whence $c \ge 1/12$.

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Imprimé en France
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