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Domingo Alberto Tarzia

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UNITÉ DE RECHERCHE INRIA-ROCQUENCOURT

Institut National de Recherche en Informatique et en Automatique

Domaine de Voluceau Rocquencourt B.P.105 78153 Le Chesnay Cedex France Tél.:(1) 39 63 5511

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NUMERICAL ANALYSIS FOR THE
HEAT FLUX IN A MIXED
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A DISCRETE STEADY-STATE
TWO-PHASE STEFAN PROBLEM

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NUMERICAL ANALYSIS FOR THE HEAT FLUX IN A MIXED ELLIPTIC PROBLEM TO OBTAIN A DISCRETE STEADY-STATE TWO-PHASE STEFAN PROBLEM

ANALYSE NUMERIQUE DU FLUX DE CHALEUR DANS UN PROBLEME ELLIPTIQUE MIXTE POUR OBTENIR UN CAS STATIONNAIRE DISCRET DU PROBLEME DE STEFAN A DEUX PHASES

Domingo Alberto TARZIA (*)

Abstract

We consider a material $\Omega\subset\mathbb{R}^n$ which occupies a convex polygonal bounded domain, with regular boundary $\Gamma=\Gamma_1\cup\Gamma_2$ with meas $(\Gamma_1)=|\Gamma_1|>0$ and $|\Gamma_2|>0$. We assume, without loss of generality, that the melting temperature is 0°C. We apply a temperature b=Const. >0 on Γ_1 and a heat flux q=Const.>0 on Γ_2 . We consider a steady-state heat conduction problem in Ω .

We consider a regular triangulation of the domain Ω with Lagrange triangles of type 1. We study sufficient (and/or necessary) conditions for the heat flux q on Γ_2 to obtain a change of phase (steady-state two-phase discretized Stefan problem) into the corresponding discretized domain, that is a discrete temperature of non-constant sign in Ω .

Résumé

On considère un matériel $\Omega\subset\mathbb{R}^n$, un domaine polygonal borné et convexe avec une frontière réguliere $\Gamma=\Gamma_1\cup\Gamma_2$ avec $\operatorname{mes}(\Gamma_1)=|\Gamma_1|>0$ et $|\Gamma_2|>0$. On suppose, sans perte de généralité, que la température de changement de phase est 0°C. On considère une température b=Const. >0 sur Γ_1 et un flux de chaleur q=Const. >0 sur Γ_2 . On considère le cas stationnaire du problème de conduction de la chaleur dans Ω .

On considère une triangulation régulier de Ω avec des triangles de Lagrange de type 1. On étudie des conditions suffisantes (et/ou nécessaires) pour le flux de chaleur q sur Γ_2 pour obtenir un changement de phase (cas stationnaire discret d'un problème de Stefan à deux phases) dans le domaine discrète correspondante, c'est-à-dire une température discrète de signe non-constante dans Ω .

<u>Kev</u> <u>words</u>: Steady-state Stefan problem, finite element method, mixed elliptic problem, numerical analysis, variational inequalities, error bounds.

Mots Clés: Problème de Stefan stationnaire, méthode d'éléments finis, problème elliptique mixte, analyse numérique, inéquations variationnelles, estimation de l'erreur.

AMS Subject Classification: 35R35, 35J85, 65N15, 65N30.

(*) Departamento de Matemática, FCE, Universidad Austral, Moreno 1056, (2000) Rosario, Argentina and PROMAR (CONICET-UNR), Instituto de Matemática "Beppo Levi", Av. Pellegrini 250, (2000) Rosario, Argentina.

I.- INTRODUCTION.

We consider a material $\Omega\subset\mathbb{R}^n$ which occupies a convex polygonal bounded domain, with a regular boundary $\Gamma=\Gamma_1\cup\Gamma_2$ with meas $(\Gamma_1)=|\Gamma_1|>0$ and $|\Gamma_2|>0$. We assume, without loss of generality, that the melting temperature is 0°C. We apply a temperature b=Const. > 0 on Γ_1 and a heat flux $q=\mathrm{Const.}>0$ on Γ_2 . We consider a steady-state heat conduction problem in Ω . Following [7], we study the temperature $\theta=\theta(x)$ for $x\in\Omega$. The set Ω can be written by

$$\Omega = \Omega_1 \cup \Omega_2 \cup \mathcal{L} .$$

where

$$\Omega_1 = \left\{ \begin{array}{l} x \in \Omega \ / \ \theta(x) < 0 \end{array} \right\} \ (\text{liquid phase}) \,,$$

$$\Omega_2 = \left\{ \begin{array}{l} x \in \Omega \ / \ \theta(x) > 0 \end{array} \right\} \ (\text{solid phase}) \,,$$

$$\mathcal{L} = \left\{ \begin{array}{l} x \in \Omega \ / \ \theta(x) = 0 \end{array} \right\} \ (\text{free boundary}) \,,$$

are the liquid phase, the solid phase and the free boundary which separates them respectively. The temperature θ can be represented in Ω in the following way

(3)
$$\theta_1(x) < 0, \quad x \in \Omega_1,$$
$$\theta(x) = 0, \quad x \in \mathcal{L},$$
$$\theta_2(x) > 0, \quad x \in \Omega_2,$$

and satisfies the following conditions:

$$\Delta\theta_{1} = 0 \quad \text{in } \Omega_{1} \quad (i = 1, 2) \quad ,$$

$$\theta_{1} = \theta_{2} = 0 \quad , \quad k_{1} \quad \frac{\partial\theta_{1}}{\partial n} = k_{2} \quad \frac{\partial\theta_{2}}{\partial n} \quad \text{on } \mathcal{L} \quad ,$$

$$\theta_{2} \mid_{\Gamma_{1}} = b > 0 \quad ,$$

$$-k_{2} \quad \frac{\partial\theta_{2}}{\partial n} \mid_{\Gamma_{2}} = q \quad \text{if} \quad \theta \mid_{\Gamma_{2}} > 0 \quad ,$$

$$-k_{1} \quad \frac{\partial\theta_{1}}{\partial n} \mid_{\Gamma_{2}} = q \quad \text{if} \quad \theta \mid_{\Gamma_{2}} < 0 \quad ,$$

where $k_i > 0$ is the thermal conductivity in Ω_i (i=1: solid phase, i=2: liquid phase). If we introduce the new unknown function [2, 7]

(5)
$$u = k_2 \theta^+ - k_1 \theta^- (\theta = \frac{1}{k_2} u^+ - \frac{1}{k_1} u^-) \quad \text{in } \Omega$$
,

where θ^+ and θ^- represent the positive part and the negative part of the function θ respectively, then problem (4) is transformed into the following mixed elliptic problem

$$\Delta u = 0$$
 dans Ω ,

(6)
$$u \mid_{\Gamma_{1}} = B ,$$

$$-\frac{\partial u}{\partial n} \mid_{\Gamma_{2}} = q ,$$

whose variational formulation is given by

$$a(u,\,v\!-\!u)\,=\,L(v\!-\!u)\quad \, ,\qquad \forall\,\,v\,\in\,K\quad ,$$
 (7)
$$u\,\in\,K\quad ,$$

where

$$V \,=\, H^1(\Omega) \hspace{0.5cm}, \hspace{0.5cm} B \,=\, k_2 \ b \,>\, 0 \ \ on \ \Gamma_1 \ \ , \label{eq:V}$$

$$(8) \qquad K = \left\{ v \in V / v \mid_{\Gamma_{1}} = B \right\}, \quad V_{0} = \left\{ v \in V / v \mid_{\Gamma_{1}} = 0 \right\},$$

$$a(u, v) = \int_{\Omega} \nabla u \cdot \nabla u \ dx , \quad L(v) = L_{q}(v) = -\int_{\Gamma_{2}} q \ v \ d\gamma .$$

Moreover, the solution of (7) is characterized by the following minimum problem [4]

$$J(u) \leq J(v) \quad , \qquad \forall \ v \in K \quad ,$$
 (9)
$$u \in K \quad ,$$

where

(10)
$$J(v) = J_{q}(v) = \frac{1}{2} a(v,v) - L_{q}(v) = \frac{1}{2} a(v,v) + \int_{\Gamma_{2}} q v d\gamma .$$

We can define the real fonction $f: \mathbb{R}^+ \to \mathbb{R}$ in the following way

(11)
$$f(q) = J_{\mathbf{q}}(u(q)) = \frac{1}{2} a(u(q), u(q)) + q \int_{\Gamma_{\mathbf{q}}} u_{\mathbf{q}} d\gamma ,$$

where u = u(q) is the unique solution of the variational equality (7) for each heat flux q > 0 (for a given B > 0).

For the continuous problem (6) or (7), a sufficient condition to have a steady-state twophase Stefan problem (i.e. the solution u(q) of (7) is a function of non-constant sign in Ω) was obtained in [8, 9].

Theorem 1 .— (i) Function f is derivable. Moreover, f' is a continuous and strictly decreasing function, and it is given by the following expression

(12)
$$f'(q) = \int_{\Gamma_2} u(q) d\gamma .$$

(ii) There exists a geometrical constant $C = C(\Omega, \Gamma_1, \Gamma_2) > 0$ such that

$$a(u(q),\,u(q))\,=\,C\,\,q^2\ ,\quad f(q)\,=\,-\,\frac{C}{2}\,\,q^2\,+\,B\mid\Gamma_2\mid q\ ,\ \ \forall\,\,q\,>\,0\,\,.$$

Moreover, the constant C > 0 is given by

(14)
$$C = a(u_3,u_3) = \int_{\Gamma_2} u_3 d\gamma > 0,$$

where $u_3 \in V_0$ (u(q) = B - q u_3 in Ω) is the unique solution of the following mixed elliptic problem

$$\Delta u_3 = 0 \text{ in } \Omega ,$$
 (15)
$$u_3 \mid_{\Gamma_1} = 0 , \frac{\partial u_3}{\partial n} \mid_{\Gamma_2} = 1 ,$$

whose variational formulation is given by

$$a(u_3,v) = \int\limits_{\tilde{\Gamma}_2} v \; \mathrm{d}\gamma \;\;,\; \forall v \in V_o \;,$$
 (16)
$$u_3 \in V_o \;\;.$$

(iii) If
$$q > q_0$$
 (B)

then (6) or (7) represents a steady-state two-phase Stefan problem (i.e. the solution u(q) of problem (7) is a function of non-constant sign in Ω), where $q_0 = q_0(B)$ is given by

(18)
$$q_0(B) = \frac{B | \Gamma_2 |}{C}, \forall B > 0.$$

(iv) If the function u(q) is constant over Γ_2 , then the sufficient condition (given by (17)) is also necessary.

 $\underline{\text{Proof}}$. - See [8, 9].

Now, we consider τ_h , a regular triangulation of the polygonal domain Ω with Lagrange triangles of type 1, constituted by affine-equivalent finite element of class C^0 , where h>0 is a parameter which goes to zero. We can take h equals to the longest side of the triangles $T \in \tau_h$ and we can approximated V_0 by [1]:

$$(19) \quad V_{h} = \left\{ \left. v_{h} \in C^{0}(\overline{\Omega}) \middle/ v_{h} \right|_{T} \in P_{1}(T), \, \forall T \in \tau_{h}, \, v_{h} \right|_{\Gamma_{1}} = 0 \right\},$$

where P_1 is the set of the polynomials of degree less or equals than 1. Let π_h be the corresponding linear interpolatation operator. Then, we can consider that there exists a constant $C_0 > 0$ (independent of the parameter h) such that

$$(20) \qquad \qquad || \ \mathbf{v} - \pi_{\mathbf{h}} \ \mathbf{v} \ ||_{\mathbf{V}} \leq \mathbf{C_0} \ \mathbf{h^{r-1}} \quad || \ \mathbf{v} \ ||_{\mathbf{r},\Omega} \ , \ \forall \mathbf{v} \in \mathbf{H^r}(\Omega) \ , \ \text{with} \ 1 < \mathbf{r} \leq 2 \ .$$

We consider the following finite dimensional approximate variational problem, corresponding to the continuous variational problem (7), given by:

$$\begin{aligned} \mathbf{a}(\mathbf{u}_h,\,\mathbf{v}_h) &= \mathbf{L}(\mathbf{v}_h)\;,\;\;\forall \mathbf{v}_h \in \mathbf{V}_h\;\;,\\ \mathbf{u}_h \in \mathbf{K}_h &= \mathbf{B} + \mathbf{V}_h\;, \end{aligned}$$

and we can obtain the following results.

Lema 2 .- We have

$$\lim_{h \to 0^+} \| u_h - u \|_{V} = 0,$$

where u is the unique solution of the variational equality (7).

<u>Proof</u>. – Owing to meas(Γ_1) > 0, we have that the bilinear form a is coercitivity over V_0 , that is [4]:

$$\exists \ \alpha > 0 \ / \ a(v, \, v) = ||\ v\ ||_{V_{\Omega}}^2 \geq \alpha \ ||\ v\ ||_{V}^2 \ , \ \forall v \in V_{O} \ ,$$

and therefore $|| \ . \ ||_{V_0}$ and $|| \ . \ ||_V$ are two equivalents norms in V_0 . We follow a similar method

developped in [1].

Corollary 3 .- If we define

(24)
$$\theta_{h} = \frac{1}{k_{2}} u_{h}^{+} - \frac{1}{k_{1}} u_{h}^{-} \in V , \quad \theta = \frac{1}{k_{2}} u^{+} - \frac{1}{k_{1}} u^{-} \in V$$

then we have

(25)
$$\lim_{h \to 0^+} \|\theta_h - \theta\|_{H} = 0 ,$$

where $H = L^2(\Omega)$.

<u>Proof</u>. - If we consider the scalar product in H, defined by

(26)
$$(u, v) = \int_{\Omega} u v dx,$$

then, we deduce

$$\begin{aligned} \|u_{h} - u\|_{H}^{2} &= \|u_{h}^{+} - u^{+}\|_{H}^{2} + \|u_{h}^{-} - u^{-}\|_{H}^{2} + 2(u_{h}^{+}, u^{-}) + \\ &+ 2(u_{h}^{+}, u^{+}) \geq \|u_{h}^{+} - u^{+}\|_{H}^{2} + \|u_{h}^{-} - u^{-}\|_{H}^{2} , \end{aligned}$$

that is

(28)
$$\operatorname{Max} (|| u_{h}^{+} - u^{+} || , || u_{h}^{-} - u^{-} ||) \leq || u_{h}^{-} - u ||_{H}.$$

From (24) we obtain:

$$\begin{aligned} || \theta_{h} - \theta ||_{H} &\leq \frac{1}{k_{2}} || u_{h}^{+} - u^{+} ||_{H} + \frac{1}{k_{1}} || u_{h}^{-} - u^{-} ||_{H} \leq \\ &\leq (\frac{1}{k_{1}} + \frac{1}{k_{2}}) || u_{h} - u ||_{H} ,\end{aligned}$$
(29)

i.e. (25).

The goal of this paper is to consider the numerical analysis of the inequality (17). We study sufficient (and/or necessary) conditions for the constant heat flux q on Γ_2 to obtain a change of phase (steady-state two-phase discretized Stefan problem) into the corresponding discretized domain, that is a discrete temperature of non-constant sign in Ω . We obtain that:

i) there exists a constant $C_h>0$ (which depends only of the geometry of the domain Ω for each h>0 and it is characterized by a variational problem) such that if $q>q_{0h}(B)=B|\Gamma_2|/C_h$ then the steady-state discretized problem presents two phases.

- ii) we have the estimations $C_h < C$ and $q_0(B) < q_{0h}(B)$ where C and $q_0(B)$ have been obtained for the continuous problem by (14) and (18) respectively [9].
- iii) we deduce an error bounds for $C-C_h$ and $q_{0h}(B)-q_0(B)$ as a function of the parameter h.

In other words, we obtain for the mixed elliptic discretized problem, defined by uh, analogous conditions to the ones obtained for the corresponding continuous problem [9], defined by u.

II.— INEQUALITY FOR THE HEAT FLUX IN THE DISCRETIZED PROBLEM.

For each q>0 we consider the functions $u(q)\in K$ and $u_h(q)\in K_h$, as the unique solution of the variational equalities (7) (continuous problem) and (21) (discrete problem) respectively. We define the real function $f_h:\mathbb{R}^+\to\mathbb{R}$, for each h>0, in the following way

$$\mathrm{f}_h(q) \, = \, \mathrm{J}_q(\mathrm{u}_h(q)) \, = \, \tfrac{1}{2} \, \, \mathrm{a}(\mathrm{u}_h(q),\!\mathrm{u}_h(q)) \, + \, q \int\limits_{\Gamma_2} \mathrm{u}_h(q) \, \, \mathrm{d}\gamma \ \, , \ \, q \, > \, 0 \, \, .$$

Therefore, we obtain the following properties:

Theorem $\underline{4}$.— (i) If $u_i = u_h(q_i)$ is the solution of (21) for $q_i > 0$ (i = 1, 2), then we have the following equalities:

(31)
$$a(u_2 - u_1, u_2 - u_1) = (q_1 - q_2) \int_{\Gamma_2} (u_2 - u_1) d\gamma,$$

(32)
$$a(u_2, u_2) - a(u_1, u_1) = a(u_2 + u_1, u_2 - u_1) = (q_1 + q_2) \int_{\Gamma_2} (u_1 - u_2) d\gamma .$$

(ii) For all real numbers q > 0 and Δ such that $(q + \Delta) > 0$, we obtain the following estimations:

$$\left| \frac{1}{\Delta} [\mathbf{u}_{h}(\mathbf{q}) - \mathbf{u}_{h}(\mathbf{q} + \Delta)] \right|_{V} \leq D_{1} = \frac{\left\| \gamma_{0} \right\|}{\alpha} \left| \Gamma_{2} \right|^{1/2},$$

$$\| \frac{1}{\Delta} [u_h(q) - u_h(q + \Delta)] \|_{L^2(\Gamma_2)} \le D_2 = D_1 \| \gamma_0 \|,$$

where γ_0 is the linear and continuous trace operator, defined over V. Moreover, the function

$$\label{eq:q_sigma} \mathsf{q} > 0 \quad \to \quad \int\limits_{\Gamma_2} \mathsf{u}_{h}(\mathsf{q}) \; \mathsf{d}\gamma \, \in \, \mathbf{R} \; ,$$

is a continuous and strictly decreasing function.

(iii) Function $f_h = f_h(q)$ is derivable. Moreover, f_h' is a continuous and strictly decreasing function and given by the following expression

(36)
$$f_h'(q) = \int_{\Gamma_2} u_h(q) d\gamma ,$$

<u>Proof</u>.— (i) If we take $v = u_2 - u_1 \in V_h$ in the variational equality corresponding to u_1 and $v = u_1 - u_2 \in V_h$ in the one corresponding to u_2 , and we add up and subtract both equalities, then we obtain (31) and (32) respectively.

(ii) Taking into account (23), the Cauchy-Schwarz inequality and the continuity of the operator γ_0 we deduce (33). From (33) and the continuity of γ_0 we have (34). Therefore we have (35) because

(37)
$$\left| \int_{\Gamma_2} \left[u_h(q) - u_h(q + \Delta) \right] d\gamma \right| \leq D_2 \left| \Gamma_2 \right|^{1/2} \Delta.$$

Moreover, the monotony property is a consequence of (31).

(iii) From (30) and elementary computations, we deduce

(38)
$$\frac{1}{\Delta} [f_h (q + \Delta) - f_h(q)] = \frac{1}{2} \int_{\Gamma_2} [u_h(q) + u_h(q + \Delta)] d\gamma,$$

that is (36), by using (35).

Lema 5. - We have the following expressions:

$$a(u_{\mbox{h}}(q)\;,\,u_{\mbox{h}}(q)) \,=\, q\; B\; \mid \Gamma_2 \mid -\; q \int\limits_{\Gamma_2} u_{\mbox{h}}(q)\; d\gamma\;, \label{eq:aupprox}$$

$${\rm f}_{h}({\rm q}) \, = \, {\rm q} \, \, {\rm B} \, \, | \, \, \Gamma_{2} \, \, | \, - \, \frac{1}{2} \, \, \, {\rm a}({\rm u}_{h}({\rm q}) \, \, , \, {\rm u}_{h}({\rm q})) \, \, , \label{eq:fh}$$

(41)
$$f_h(q) = \frac{q B | \Gamma_2|}{2} + \frac{q}{2} \int_{\Gamma_2} [u_h(q) d\gamma,$$

(42)
$$q f_h''(q) = f_h'(q) - B | \Gamma_2 |,$$

(43)
$$\frac{d}{dq} [a(u_h(q), u_h(q))] = \frac{2}{q} a(u_h(q), u_h(q)) = 2 B | \Gamma_2| - 2 f_h'(q).$$

<u>Proof</u>. – Taking $v_h = B - u_h(q) \in V_h$ in (21) we obtain (31). We deduce (40) and (41) by using (30) and (39). From (36), (39)-(41) we obtain (42) and (43) by derivating with respect to variable q.

Theorem 6 .- (i) There exists a constant $C_h > 0$ such that

(44)
$$f_{h}(q) = q B | \Gamma_{2} | -\frac{1}{2} C_{h} q^{2} , \forall q > 0 ,$$

$${\rm a}(u_h^{}(q)\;,\,u_h^{}(q)) \,=\, C_h^{}\;q^2\;,\;\;\forall\;q\,>\,0\;. \label{eq:a_h_p}$$

(ii) If $q > q_{o_h}(B)$, then problem (21) represents a discretized steady-state two-phase Stefan problem (i.e. $u_h(q)$ is a funtion of non-constant sign in Ω), where

(46)
$$q_{0_{h}}(B) = \frac{B | \Gamma_{2}|}{C_{h}}.$$

(iii) The constant $C_h > 0$ can be computed by the expression

(47)
$$C_{h} = \frac{1}{q} \int_{\Gamma_{2}} \left[B - u_{h}(q)\right] d\gamma ,$$

for any q>0. Moreover, $C_{\mbox{\scriptsize h}}$ is given by

(48)
$$C_h = a(u_{3_h}, u_{3_h}) = \int_{\Gamma_2} u_{3_h} d\gamma$$
,

where u_{3h} is the unique solution of the variational equality

 $\underline{\text{Proof}}$.- (i) Function $f_h = f_h(q)$ satisfies $f_h'''(q) = 0$, $\forall q > 0$ because (42). Owing to

(50)
$$u_h(0^+) = B$$
, $f_h(0^+) = B | \Gamma_2 | q$, $f_h'(0^+) = B | \Gamma_2 |$,

there exists some constant $C_h > 0$ such that (44) and (45) are holds.

(ii) It follows taking into account

(51)
$$f_h'(q_{0_h}(B) = 0,$$

and the monotony property of function f_h^{\prime}.

(iii) From (39) and (45) we obtain (47) for any q>0. Moreover, if we define $w_h=w_h(q)\in V_h$ by the expression

$$\mathbf{w}_{h}(\mathbf{q}) = \frac{\mathbf{B} - \mathbf{u}_{h}(\mathbf{q})}{\mathbf{q}},$$

then, we have:

$$(53) \quad a(w_h(q), \, v_h) = \frac{1}{\bar{q}} \, a(B - u_h(q), \, v_h) = - \, \frac{1}{\bar{q}} \, a(u_h(q), \, v_h) = \int\limits_{\Gamma_2} v_h \, \, d\gamma \, \, , \quad \forall \, \, v_h \, \in V_h,$$

that is $w_h(q) = u_{3h}$ by uniqueness of the solution of the variational equality (49), then, we deduce (48).

Theorem 7. - (i) We have the following equality:

(54)
$$a(u(q), u_h(q)) = C_h q^2, \forall q > 0.$$

(ii) We have the following inequalities:

$${\rm (55)} \qquad \qquad {\rm (a)\ C_h\, < C\ ,} \qquad {\rm (b)\ q_0(B)\, <\ q_0}_h {\rm (B)\ .}$$

<u>Proof</u>. – (i) If we take $v = u_h(q) \in K_h = B + V_h \subset B + V_o = K$ in the variational equality (7), and we take into account the expressions (13) and (44), then we obtain (54).

(ii) On the other hand, from (23) and (54) we have

(56)
$$\alpha \| u(q) - u_h(q) \|_{V}^{2} \le a(u(q) - u_h(q), u(q) - u_h(q)) = (C - C_h) q^{2},$$

that is (55a). Moreover, (55b) follows from (18), (46) and (55).

Now, we shall use the interpolation result (20) for the funtion $u_3 \in H^r(\Omega)$, as a hipotesis of regularity of the continuous problem (7) (in general, $1 < r < \frac{3}{2}[3, 5, 6]$). In [8], we present three examples with explicit solution. In these cases, we have u(q), $u_3 \in C^{\infty}(\Omega)$.

Theorem 8. - We have the following relations and estimations:

(57)
$$a(u(q) - u_h(q), v_h) = 0 , \forall v_h \in V_h,$$

(58)
$$(C - C_h) q^2 = a(u(q) - u_h(q), u(q) - u_h(q)) \le$$

$$\le \inf_{v_h \in V_h} a(u(q) - v_h, u(q) - v_h),$$

(59)
$$0 < C - C_h \le C_0^2 h^{2(r-1)} |u_3|_{r,\Omega}^2,$$

(60)
$$0 < q_{0_{h}}(B) - q_{0}(B) \le \frac{C_{0}^{2} h^{2(r-1)}}{C} |u_{3}|_{r,\Omega}^{2} q_{0_{h}}(B).$$

<u>Proof</u>. – If we take $v = v_h \in V_h \subset V_o$ in the variational equality (7) and we subtract it with the variational equality (21), we obtain (57). By using (54), (56) and (57) we deduce

because a(.,.) is a scalar product in Vo, then we obtain (58).

By using (58), the facts that

(62)
$$\Pi_{h}(u(q)) \in B + V_{h}$$
, $u(q) - \Pi_{h}(u(q)) \in V_{h}$

and the interpolation result (20), we deduce (59). The relation (60) is obtained by using the definition of $q_{0_h}(B)$ and $q_0(B)$, and (59).

Remark 1. – If we only have $u(q) \in V$ (i.e. $u_3 \in V$) we can obtain

$$0 < C - C_h \le \frac{1}{q^2} || u(q) - \Pi_h(u(q)) ||_V^2 = || u_3 - \Pi_h(u_3) ||_V^2,$$

where the second term converges to zero when $h\rightarrow 0^+$ [1], but we cannot give an order of convergence.

Remark 2.— If the constant heat flux on Γ_2 verifies the inequality $q > q_{0h}(B)$, then both discrete and continuous problem represent a steady-state two-phase Stefan problem, that is, their temperatures are of non-constant sign in Ω .

Remark 3.— When the function $u_h(q)$ is constant on Γ_2 (as a funtion of $x \in \Gamma_2$), then the sufficient condition, given by the Theorem 6—part (ii), is also a necessary condition to have a

two-phase discrete problem, because

$$\int\limits_{\Gamma_2} u_{\rm h}(q) \; d\gamma \, < \, 0 \; \Leftrightarrow \; u_{\rm h}(q) \, < \, 0 \; \text{ on } \; \Gamma_2 \; . \label{eq:condition}$$

Theorem 9.— If we consider h, B > 0, and $0 < \epsilon_0 < 1$ (ϵ_0 is a parameter to be chosen arbitrarily), then we have the following estimations:

(65)
$$q_o(B) < q_{o_h}(B) \le \frac{q_o(B)}{\epsilon_o} \text{ and } C_h \ge C \epsilon_o , \forall h \le h_r(\epsilon_o),$$

(66)
$$0 < q_{o_h}(B) - q_{o}(B) \le \frac{C_o^2 |u_3|^2}{C \epsilon_o} q_{o}(B) h^{2(r-1)}, \quad \forall h \le h_r(\epsilon_o),$$

where

(67)
$$h_{\mathbf{r}}(\epsilon_{\mathbf{o}}) = \left(\frac{C\left(1 - \epsilon_{\mathbf{o}}\right)}{C_{\mathbf{o}}^{2} \mid u_{3} \mid^{2}}\right)^{\frac{1}{2(\mathbf{r} - 1)}}.$$

Proof .- From (60) we deduce

(68)
$$A(h) q_{0_h}(B) \le q_0(B)$$
,

where

(69)
$$A(h) = 1 - \frac{C_0^2 |u_3|^2}{C} h^{2(r-1)} < 1.$$

If we consider, for each parameter 0 < ϵ_{0} < 1, the following equivalence :

(70)
$$0 < \epsilon_{O} < A(h) < 1 \quad \Leftrightarrow \quad 0 < h < h_{\Gamma}(\epsilon_{O}),$$

we can deduce the inequalities (65) and (66).

Corollary 10. — If B > 0, then we have the following limit

(71)
$$\lim_{h \to 0^+} q_{o_h}(B) = q_o(B).$$

Remark $\underline{4}$. — If r=2 then the convergence in Corollary 10 is of the order of h.

- Remark 5.— Every thing we proved in this paper is still valid if the boundary Γ of the bounded domain Ω is represented by the union of the portions ($\Gamma = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3$) such that they have the following characteristics:
- (i) Γ_1 and Γ_2 have the same conditions as the ones previously described in (4).
- (ii) Γ_3 is a wall impermeable to heat, i.e. we have $\frac{\partial \theta}{\partial n} \mid_{\Gamma_3} = 0$ in (4) and therefore $\frac{\partial u}{\partial n} \mid_{\Gamma_3} = 0$ in (6).

Moreover, the first example considered in [8] verifies this condition.

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