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# Orthogonalization schemes in tensor train format 

Martina Iannacito, Olivier Coulaud, Luc Giraud

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## Orthogonalization schemes in tensor train format

29th Biennial Numerical Analysis Conference, June 28th 2023, Glasgow

Martina lannacito* joint work with Olivier Coulaud ${ }^{\dagger}$ and Luc Giraud ${ }^{\dagger}$

* KU Leuven
$\dagger$ Centre Inria at the University of Bordeaux
- Stochastic equations
- Uncertainty quantification problems
- Quantum and vibration chemistry
- Optimization
- Machine learning
reduce their problems to

$$
\begin{aligned}
& \text { Least-squares } \\
& \min _{x \in \mathcal{S}}| | b-A x \|
\end{aligned}
$$

Eigenpairs
$A x=\lambda x$

Linear systems
$A x=b$

## From theory to coding: an example I

## Gram-Schmidt process [Leon et al. 2013]

Given $\left\{a_{h}\right\}_{h}$ linearly independent vectors, we construct an orthogonal basis $\left\{q_{h}\right\}$ such that

$$
q_{1}=a_{1},
$$

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How to make an algorithm out of it?

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How to make an algorithm out of it? let $Q_{k}=\left[q_{1}, \ldots, q_{k}\right]$ be a $n \times k$ matrix

## All projections, then subtractions

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All projections, then subtractions

$$
q_{k+1} \leftarrow\left(\mathbb{I}_{n}-Q_{k} Q_{k}^{\top}\right) a_{k+1}
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Projections alternate subtractions

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q_{k+1} \leftarrow\left(\mathbb{I}_{n}-Q_{k} Q_{k}^{\top}\right) a_{k+1}
$$

Projections alternate subtractions
$q_{k+1} \leftarrow\left(\mathbb{I}_{n}-q_{k} \otimes q_{k}\right) \ldots\left(\mathbb{I}_{n}-q_{1} \otimes q_{1}\right) a_{k+1}$

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\text { let } Q_{k}=\left[q_{1}, \ldots, q_{k}\right] \text { be a } n \times k \text { matrix }
$$

All projections, then subtractions

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q_{k+1} \leftarrow\left(\mathbb{I}_{n}-Q_{k} Q_{k}^{\top}\right) a_{k+1}
$$

$$
\begin{gathered}
\text { Projections alternate subtractions } \\
q_{k+1} \leftarrow\left(\mathbb{I}_{n}-q_{k} \otimes q_{k}\right) \ldots\left(\mathbb{I}_{n}-q_{1} \otimes q_{1}\right) a_{k+1}
\end{gathered}
$$

Are these versions equivalent in finite precision arithmetic?

## From theory to coding: an example II

Not equivalent in general

## Classical Gram-Schmidt

All projections, then subtractions

$$
q_{k+1} \leftarrow\left(\mathbb{I}_{n}-Q_{k} Q_{k}^{\top}\right) a_{k+1}
$$

## Modified Gram-Schmidt

Projections alternate subtractions

$$
q_{k+1} \leftarrow\left(\mathbb{I}_{n}-q_{k} \otimes q_{k}\right) \ldots\left(\mathbb{I}_{n}-q_{1} \otimes q_{1}\right) a_{k+1}
$$

## From theory to coding: an example II

Not equivalent in general

## Classical Gram-Schmidt

All projections, then subtractions

$$
q_{k+1} \leftarrow\left(\mathbb{I}_{n}-Q_{k} Q_{k}^{\top}\right) a_{k+1}
$$

$$
A=\left[\begin{array}{lll}
1 & 1 & 1 \\
\varepsilon & 0 & 0 \\
0 & \varepsilon & 0 \\
0 & 0 & \varepsilon
\end{array}\right] \quad \text { with } \quad \varepsilon=1 e-10 \quad \text { in } \mathrm{fp} 64
$$

## From theory to coding: an example II

Not equivalent in general

## Classical Gram-Schmidt

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$$

$$
Q_{\mathrm{Ccs}}=\left[\begin{array}{ccc}
1 & 0 & 0 \\
\varepsilon & -\varepsilon & -\varepsilon \\
0 & \varepsilon & 0 \\
0 & 0 & \varepsilon
\end{array}\right],
$$

## From theory to coding: an example II

Not equivalent in general

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$$

$$
Q_{\mathrm{CGS}}=\left[\begin{array}{ccc}
1 & 0 & 0 \\
\varepsilon & -\varepsilon & -\varepsilon \\
0 & \varepsilon & 0 \\
0 & 0 & \varepsilon
\end{array}\right],\left\langle q_{2}, q_{3}\right\rangle=\frac{1}{2}
$$

## From theory to coding: an example II

Not equivalent in general

## Classical Gram-Schmidt

All projections, then subtractions

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q_{k+1} \leftarrow\left(\mathbb{I}_{n}-Q_{k} Q_{k}^{\top}\right) a_{k+1}
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\varepsilon & -\varepsilon & -\varepsilon \\
0 & \varepsilon & 0 \\
0 & 0 & \varepsilon
\end{array}\right],\left\langle q_{2}, q_{3}\right\rangle=\frac{1}{2}
$$

$$
Q_{\text {MGS }}=\left[\begin{array}{ccc}
1 & 0 & 0 \\
\varepsilon & -\varepsilon & -\varepsilon / 2 \\
0 & \varepsilon & -\varepsilon / 2 \\
0 & 0 & \varepsilon
\end{array}\right],
$$

## From theory to coding: an example II

Not equivalent in general

## Classical Gram-Schmidt

All projections, then subtractions

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q_{k+1} \leftarrow\left(\mathbb{I}_{n}-Q_{k} Q_{k}^{\top}\right) a_{k+1}
$$

$$
\begin{gathered}
A=\left[\begin{array}{lll}
1 & 1 & 1 \\
\varepsilon & 0 & 0 \\
0 & \varepsilon & 0 \\
0 & 0 & \varepsilon
\end{array}\right] \quad \text { with } \quad \varepsilon=1 e-10 \quad \text { in fp64 } \\
Q_{\mathrm{CGS}}=\left[\begin{array}{ccc}
1 & 0 & 0 \\
\varepsilon & -\varepsilon & -\varepsilon \\
0 & \varepsilon & 0 \\
0 & 0 & \varepsilon
\end{array}\right],\left\langle q_{2}, q_{3}\right\rangle=\frac{1}{2}
\end{gathered} Q_{\text {MGS }}=\left[\begin{array}{ccc}
1 & 0 & 0 \\
\varepsilon & -\varepsilon & -\varepsilon / 2 \\
0 & \varepsilon & -\varepsilon / 2 \\
0 & 0 & \varepsilon
\end{array}\right]
$$

## Modified Gram-Schmidt

## Projections alternate subtractions

$$
q_{k+1} \leftarrow\left(\mathbb{I}_{n}-q_{k} \otimes q_{k}\right) \ldots\left(\mathbb{I}_{n}-q_{1} \otimes q_{1}\right) a_{k+1}
$$

This example was taken from [Björck 1996].

## Loss of orthogonality

Let $Q_{k}=\left[q_{1}, \ldots, q_{k}\right]$ be the computed orthogonal basis, then its loss of orthogonality is

$$
\left\|\mathbb{I}_{k}-Q_{k}^{\top} Q_{k}\right\|
$$

It measures the quality in terms of orthogonality of the computed basis. It is linked with the computational precision $u$ and the linearly dependency of the input vectors $A_{k}=\left[a_{1}, \ldots, a_{k}\right]$, estimated through $\kappa\left(A_{k}\right)$.

| Matrix |  |  |
| :--- | :--- | :---: |
|  | Algorithm | $\left\\|\mathbb{I}_{k}-Q_{k}^{\top} Q_{k}\right\\|$ |
| Source | (Stathopoulos et al. 2002] | Gram |$c \mathcal{O}\left(u \kappa^{2}\left(A_{k}\right)\right)$

## The advent of tensors

 matrix$\left[\begin{array}{lll}1 & 8 & 4 \\ 9 & 2 & 2 \\ 7 & 1 & 6\end{array}\right]$ since the last century

$$
\left[\begin{array}{ccccc}
\ddots & 8 & 4 & \text { tensor } \\
9 \\
7 \\
7 & 5 & - & 3 & 1 \\
1 & 2 & 4 & 9 \\
6 & 8 & 7
\end{array}\right]
$$

## The advent of tensors

$\left[\begin{array}{lll}1 & 8 & 4 \\ 9 & 2 & 2 \\ 7 & 1 & 6\end{array}\right]$ since the last century $\left[\begin{array}{llll}\cdots & 8 & 4 & \text { tens } \\ 9 \\ 7 \\ 7 & - & 5 & 3 \\ 2 & 1 \\ 1 & 2 & 4 & 4 \\ 6 & 8 & 7\end{array}\right]$

+ Better representation
- Curse of dimensionality


## The advent of tensors

## matrix

$\left[\begin{array}{lll}1 & 8 & 4 \\ 9 & 2 & 2 \\ 7 & 1 & 6\end{array}\right]$
since the last century $\left[\begin{array}{llll}\ddots & 8 & 4 & \text { ten } \\ 9 \\ 7 \\ 7 & - & 5 & \ddots \\ 2 & 2 & 3 & 1 \\ 1 & 4 & 9 \\ 6 & 8 & 7\end{array}\right]$

+ Better representation
- Curse of dimensionality

Approximation techniques were proposed

- Canonical Polyadic
- Tucker
- Hierarchical Tucker
- Tensor-Train


Figure: from [Bi et al. 2022]

## The advent of tensors

## matrix

$\left[\begin{array}{lll}1 & 8 & 4 \\ 9 & 2 & 2 \\ 7 & 1 & 6\end{array}\right]$
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Approximation techniques were proposed

- Canonical Polyadic
- Tucker
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- Tensor-Train


Figure: from [Bi et al. 2022]
Approximation techniques introduce norm-wise compression errors
Íría

## Tensor Train formalism

$-$

scalar
vector

matrix

order-3 tensor

## Tensor Train formalism



## Tensor Train formalism



+ The storage cost is $\mathcal{O}\left(d n r^{2}\right)$ with $r=\max \left\{r_{i}\right\}$, said TT-ranks


## Tensor Train formalism



+ The storage cost is $\mathcal{O}\left(d n r^{2}\right)$ with $r=\max \left\{r_{i}\right\}$, said TT-ranks
- Linear combinations increase the TT-ranks


## Tensor Train formalism

scalar
vector

matrix

order-3 tensor

Let $\mathbf{x} \in \mathbb{R}^{n_{1} \times \cdots \times n_{d}}$ be order- $d$ tensor, its TT-representation is


+ The storage cost is $\mathcal{O}\left(d n r^{2}\right)$ with $r=\max \left\{r_{i}\right\}$, said TT-ranks
- Linear combinations increase the TT-ranks


## TT-rounding [Oseledets 2011]

If $\mathbf{z}$ is an order- $\boldsymbol{d}$ tensor in TT-format and $\delta \in(0,1)$, then $\overline{\mathbf{z}}=\mathrm{TT}-$ rounding $(\mathbf{z}, \delta)$ such that

$$
\|\mathbf{z}-\overline{\mathbf{z}}\| \leq \delta\|\mathbf{z}\|
$$

## The questions

In the Tensor-Train framework
compression precision $\delta$

- norm-wise perturbation
- TT-model [Oseledets 2011]
computational precision $u$
- component-wise perturbation
- IEEE model [Higham 2002]


## The questions

In the Tensor-Train framework
compression precision $\delta$

- norm-wise perturbation
- TT-model [Oseledets 2011]


## computational precision $u$

- component-wise perturbation
- IEEE model [Higham 2002]
- How to design orthogonalization kernels for tensor subspace?
- Does compression affect the loss of orthogonality?
- Are tensor results related with the known linear algebra ones?


## Classical and Modified Gram-Schmidt

| $\mathcal{Q}, R=\operatorname{CGS}(\mathcal{A}, \delta)$ |  |
| :---: | :---: |
| Input: $\mathcal{A}=\left\{\mathbf{a}_{1}, \ldots, \mathbf{a}_{m}\right\}, \delta \in \mathbb{R}_{+}$ |  |
|  |  |
| 2 | $\mathbf{p}=\mathbf{a}_{i}$ |
| 3 | for $j=1, \ldots, i-1$ do |
| 4 | $R(i, j)=\left\langle\mathbf{a}_{i}, \mathbf{q}_{j}\right\rangle$ |
| 5 | $\underline{p}=\mathbf{p}-R(i, j) \mathbf{q}_{j}$ |
| 6 | end |
| 7 | $\mathbf{p}=\mathrm{TT}$-rounding $(\mathbf{p}, \delta)$ |
| 8 | $R(i, i)=\\|\mathbf{p}\\|$ |
| 9 | $\mathbf{q}_{i}=1 / R(i, i) \mathbf{p}$ |
| 10 end |  |
|  | utput: $\mathcal{Q}=\left\{\mathbf{q}_{1}, \ldots, \mathbf{q}_{m}\right\}, R$ |

```
\(\mathcal{Q}, R=\operatorname{MGS}(\mathcal{A}, \delta)\)
    Input: \(\mathcal{A}=\left\{\mathbf{a}_{1}, \ldots, \mathbf{a}_{m}\right\}, \delta \in \mathbb{R}_{+}\)
1 for \(i=1, \ldots, m\) do
\(2 \quad \mathbf{p}=\mathbf{a}_{i}\)
3 for \(j=1, \ldots, i-1\) do
                \(R(i, j)=\left\langle\mathbf{p}, \mathbf{q}_{j}\right\rangle\)
                \(\mathbf{p}=\mathbf{p}-R(i, j) \mathbf{q}_{j}\)
end
    \(\mathbf{p}=\mathrm{TT}-\) rounding \((\mathbf{p}, \delta)\)
    \(R(i, i)=\|\mathbf{p}\|\)
    \(\mathbf{q}_{i}=1 / R(i, i) \mathbf{p}\)
end
Output: \(\mathcal{Q}=\left\{\mathbf{q}_{1}, \ldots, \mathbf{q}_{m}\right\}, R\)
```

They readily write in TT-format.

## CGS and MGS with reorthogonalization

| $\mathcal{Q}, R=\operatorname{CGS2}(\mathcal{A}, \delta)$ | $\mathcal{Q}, R=\operatorname{MGS2}(\mathcal{A}, \delta)$ |
| :---: | :---: |
| Input: $\mathcal{A}=\left\{\mathbf{a}_{1}, \ldots, \mathbf{a}_{m}\right\}, \delta \in \mathbb{R}_{+}$ 1 for $i=1, \ldots, m$ do | Input: $\mathcal{A}=\left\{\mathbf{a}_{1}, \ldots, \mathbf{a}_{m}\right\}, \delta \in \mathbb{R}_{+}$ for $i=1, \ldots, m$ do |
| $2 \quad \mathbf{p}_{k}=\mathbf{a}_{i}$ | $2 \mathbf{p}_{k}=\mathbf{a}_{i}$ |
| 3 for $k=1,2$ do | 3 for $k=1,2$ do |
| $4 \quad \mid \quad \mathbf{p}_{k}=\mathbf{p}_{k-1}$ | $4 \quad \mid \quad \mathbf{p}_{k}=\mathbf{p}_{k-1}$ |
| $5 \quad$ for $j=1, \ldots, i-1$ do | $5 \quad$ for $j=1, \ldots, i-1$ do |
| $6 \quad \quad \mid \quad R(i, j)=\left\langle\mathbf{p}_{k-1}, \mathbf{q}_{j}\right\rangle$ | $6 \quad \quad \quad R(i, j)=\left\langle\mathbf{p}_{k}, \mathbf{q}_{j}\right\rangle$ |
| $7 \quad \mid \quad \mathbf{p}_{k}=\mathbf{p}_{k}-R(i, j) \mathbf{q}_{j}$ | $7 \quad \quad \mathbf{p}_{k}=\mathbf{p}_{k}-R(i, j) \mathbf{q}_{j}$ |
| 8 end | 8 end |
| $9 \quad \mathbf{p}_{k}=$ TT-rounding $\left(\mathbf{p}_{k}, \delta\right)$ | $9 \quad \mathbf{p}_{k}=$ TT-rounding $\left(\mathbf{p}_{k}, \delta\right)$ |
| 10 end | 10 end |
| $11 \quad R(i, i)=\left\\|\mathbf{p}_{2}\right\\|$ | $11 \quad R(i, i)=\left\\|\mathbf{p}_{2}\right\\|$ |
| $12 \quad \mathbf{q}_{i}=1 / R(i, i) \mathbf{p}_{2}$ | $12 \quad \mathbf{q}_{i}=1 / R(i, i) \mathbf{p}_{2}$ |
| 13 end | 13 end |
| Output: $\mathcal{Q}=\left\{\mathbf{q}_{1}, \ldots, \mathbf{q}_{m}\right\}, R$ | Output: $\mathcal{Q}=\left\{\mathbf{q}_{1}, \ldots, \mathbf{q}_{m}\right\}, R$ |

## Gram approach - matrix format

Let $A=\left[a_{1}, \ldots, a_{m}\right]$, then we look for $A=Q R$ with $Q^{\top} Q=\mathbb{I}_{m}$ compute the Gram matrix

$$
A^{\top} A=\left(R^{\top} Q^{\top}\right) Q R=R^{\top} R
$$

this is (almost) the Cholesky factorization of $A^{\top} A$ that can be written as

$$
A^{\top} A=R^{\top} R=L L^{\top}
$$

with the Cholesky factor $L=R^{\top}$. Thus, it follows

$$
A=Q R=Q L^{\top}
$$

from which we obtain $Q$ by solving a linear system.

## Gram approach - TT-format

```
        \(\mathcal{Q}, R=\operatorname{Gram}(\mathcal{A}, \delta)\)
Input: \(\mathcal{A}=\left\{\mathbf{a}_{1}, \ldots, \mathbf{a}_{m}\right\}, \delta \in \mathbb{R}_{+}\)
\(1 G\) is \((m \times m)\) Gram matrix from \(\mathcal{A}\)
\(2 L=\operatorname{cholesky}(G)\)
\(3\left\{\mathbf{p}_{1}, \ldots, \mathbf{p}_{m}\right\}\) from \(\mathcal{A}\) and \(\left(L^{\top}\right)^{-1}\)
4 for \(i=1, \ldots, m\) do
\(5 \mid \quad \mathbf{q}_{i}=\) TT-rounding \(\left(\mathbf{p}_{i}, \delta\right)\)
6 end
    Output: \(\mathcal{Q}=\left\{\mathbf{q}_{1}, \ldots, \mathbf{q}_{m}\right\}, R\)
```

In TT-format the following modifications occur

- $G(i, j)$ is the scalar product of $\mathbf{a}_{i}$ and $\mathbf{a}_{j}$
- The inverse of $L^{\top}$ is explicitly computed
- $\mathbf{p}_{i}$ is constructed as a linear combination of $\mathcal{A}$ elements


## Householder transformation

Given a vector $x \in \mathbb{R}^{n}$ and a direction $y \in \mathbb{R}^{n}$, the Householder reflector $H$ reflects $x$ along $y$, i.e.,

$$
H x=\|x\| y \quad \text { with } \quad\|y\|=1
$$

Thanks to its properties, $H$ writes as

$$
H=\mathbb{I}_{n}-\frac{2}{\|z\|^{2}} z \otimes z \quad \text { with } \quad z=(x-\|x\| y)
$$

The practical implementation of the Householder transformation kernel uses the components of the input vectors.

## Remark

The Householder algorithm does not readily apply to tensor in TT-formats, because of the compressed nature of this format. It is described in [lannacito 2022]

## Numerical experiments in TT-format

Let $\boldsymbol{\Delta}_{d}$ is be the TT-Laplacian, then $\left\{\mathbf{a}_{k}\right\}$ are 'Krylov tensors', i.e., $\mathbf{a}_{k+1}=$ TT-rounding $\left(\boldsymbol{\Delta}_{d} \mathbf{x}_{k}\right.$, max_rank $\left.=1\right) \quad$ with $\quad \mathbf{x}_{k+1}=\frac{1}{\left\|\mathbf{a}_{k+1}\right\|} \mathbf{a}_{k+1}$

## Numerical experiments in TT-format

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- Gram approach
- CGS
- MGS
- CGS2
- MGS2
- Householder transformation

Figure: 20 tensors of order $d=3$ and mode size $n=15$, compression precision $\delta=10^{-5}$, computational precision $u=\mathcal{O}\left(10^{-16}\right)$

## Numerical experiments in TT-format

Loss of orthogonality for $\left\{\mathbf{a}_{k}\right\}$ 'Krylov tensors'


Figure: 20 tensors of order $d=3$ and mode size $n=15$, compression precision $\delta=10^{-5}$, computational precision $u=\mathcal{O}\left(10^{-16}\right)$

- Gram approach
- CGS
- $\delta \kappa^{2}\left(A_{k}\right)$ with

$$
A_{k}=\left[\operatorname{vec}\left(\mathbf{a}_{1}\right), \ldots \operatorname{vec}\left(\mathbf{a}_{k}\right)\right]
$$

then we conjecture

$$
\mathcal{O}\left(\delta \kappa^{2}\left(A_{k}\right)\right)
$$

## Numerical experiments in TT-format

Loss of orthogonality for $\left\{\mathbf{a}_{k}\right\}$ 'Krylov tensors'


Figure: 20 tensors of order $d=3$ and mode size $n=15$, compression precision $\delta=10^{-5}$, computational precision $u=\mathcal{O}\left(10^{-16}\right)$

- MGS
- $\delta k\left(A_{k}\right)$ with

$$
A_{k}=\left[\operatorname{vec}\left(\mathbf{a}_{1}\right), \ldots \operatorname{vec}\left(\mathbf{a}_{k}\right)\right]
$$

then we conjecture

$$
\mathcal{O}\left(\delta \kappa\left(A_{k}\right)\right)
$$

## Numerical experiments in TT-format

Loss of orthogonality for $\left\{\mathbf{a}_{k}\right\}$ 'Krylov tensors'


Figure: 20 tensors of order $d=3$ and mode size $n=15$, compression precision $\delta=10^{-5}$, computational precision $u=\mathcal{O}\left(10^{-16}\right)$

- CGS2
- MGS2
- Householder transformation then we conjecture $\mathcal{O}(\delta)$

Matrix, theoretical
TT-format, conjecture

| Algorithm | $\left\\|\mathbb{I}_{k}-Q_{k}^{\top} Q_{k}\right\\|$ | $\left\\|\mathbb{I}_{k}-\mathcal{Q}_{k}^{\top} \mathcal{Q}_{k}\right\\|$ |
| :--- | :---: | :---: |
| Gram | $\mathcal{O}\left(u \kappa^{2}\left(A_{k}\right)\right)$ | $\mathcal{O}\left(\delta \kappa^{2}\left(\mathcal{A}_{k}\right)\right)$ |
| CGS | $\mathcal{O}\left(u \kappa^{2}\left(A_{k}\right)\right)$ | $\mathcal{O}\left(\delta \kappa^{2}\left(\mathcal{A}_{k}\right)\right)$ |
| MGS | $\mathcal{O}\left(u \kappa\left(A_{k}\right)\right)$ | $\mathcal{O}\left(\delta \kappa\left(\mathcal{A}_{k}\right)\right)$ |
| CGS2 | $\mathcal{O}(u)$ | $\mathcal{O}(\delta)$ |
| MGS2 | $\mathcal{O}(u)$ | $\mathcal{O}(\delta)$ |
| Householder | $\mathcal{O}(u)$ | $\mathcal{O}(\delta)$ |

with $u$ the computational precision, $\delta$ the compression precision

## Conclusions and perspectives

- All the 6 kernels can be generalized to the TT-framework
- Loss of orthogonality bounds appears to hold true with
$>$ the compression precision $\delta$ independent from the machine architecture
$>$ the compression precision $\delta$ replacing the computational one $u$
$>$ the compression acting norm-wise rather than component-wise
More detailed results can be found at [Coulaud et al. 2022]


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## What is left out?

- Theoretical proof of the loss of orthogonality bounds
- Investigating the quality of the tensor subspace spanned by the orthogonal basis


## Computational costs: matrix vs tensor

## cost in fp operations

| Gram | $\mathcal{O}\left(2 n m^{2}\right)$ | $m$ |
| :--- | :---: | :---: |
| CGS | $\mathcal{O}\left(2 n m^{2}\right)$ | $m$ |
| MGS | $\mathcal{O}\left(2 n m^{2}\right)$ | $m$ |
| CGS2 | $\mathcal{O}\left(4 n m^{2}\right)$ | $2 m$ |
| MGS2 | $\mathcal{O}\left(4 n m^{2}\right)$ | $2 m$ |
| Householder | $\mathcal{O}\left(2 n m^{2}-2 m^{3} / 3\right)$ | $4 m$ |

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# Thanks for the attention. 

Questions?

Cinvía

