

Impact of missing data on mixtures and clustering with illustrations in Biology and Medicine

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Impact of missing data on mixtures and clustering with illustrations in Biology and Medicine

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Université de Lille



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Take home message

Missing data may change preconceptions

- Mixtures: EM has unexpected behaviour concerning degeneracy dynamic
- Clustering: the missing data pattern may convey some information on partition

These topics are in the research agenda of Statisticians since:

The larger the datasets, the more missing data may appear...

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- Gaussian mixture degeneracy without missing data
- Gaussian mixture degeneracy with missing data

- A model-based MAR approach
- Biology study illustration

- A model-based MNAR clustering approach
- Medical study illustration

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Missing data: notations

- $y = \{y_1 | \dots | y_n\}^T$: full dataset with *n* individuals
- $y_i = (y_{i1}, \dots, y_{id}) \in \mathcal{Y} = \mathbb{R}^d$ with individual $i \in \{1, \dots, n\}$
- $c = \{c_1 | \dots | c_n\}^T \in \{0, 1\}^{n \times d}$: pattern of missing data for the full dataset
- $c_i = (c_{i1}, \ldots, c_{id}) \in \{0, 1\}^d$: pattern of missing data for individual $i \in \{1, \ldots, n\}$

$$c_{ij} = 1 \Leftrightarrow y_{ij}$$
 is missing

• y_i^{obs} : the observed variables values for indiv. *i* (and $y^{\text{obs}} = \{y_1^{\text{obs}}| \dots |y_n^{\text{obs}}\}^T$) • y_i^{mis} : the missing variables values for individual *i* (and $y^{\text{mis}} = \{y_1^{\text{mis}}| \dots |y_n^{\text{mis}}\}^T$)

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Typology of the missingness mechanisms

Missing completely at random (MCAR):

$$p(c|y;\psi) = p(c;\psi) \quad \forall y$$

Missing at random (MAR):

$$\mathsf{p}(c|y;\psi) = \mathsf{p}(c|y^{\mathrm{obs}};\psi) \quad \forall y^{\mathrm{mis}}$$

Missing not at random (MNAR): the mechanism is not MCAR nor MAR



Ignorable vs. non ignorable model

A missing mechanism is ignorable if likelihoods can be decomposed as

$$L(\theta, \psi; \underbrace{y^{\text{obs}}, c}_{\text{observed data}}) = L(\psi; c | y^{\text{obs}}) \times L(\theta; y^{\text{obs}})$$

Some simple algebra show that this occurs when missing mechanism is not MNAR

Inference of θ

"If the missing mechanism is ignorable then likelihood-based inferences for θ from $L(\theta; y^{\text{obs}})$ will be the same as likelihood based inference for θ from $L(\theta, \psi; y^{\text{obs}}, c)$." [Little and Rubin, 2002 Section 6.2]

- M(C)AR is ignorable
- MNAR is not ignorable

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Mixture model and clustering (Gaussian case)

- Partition (K clusters): $z = (z_1 | \dots | z_n)^T \in \{0, 1\}^{n \times K}$ where
 - $z_i = (z_{i1}, \ldots, z_{iK}) \in \{0, 1\}^K$
 - $z_{ik} = 1$ if y_i belongs to cluster k, $z_{ik} = 0$ otherwise
- **•** Mixture model: y_1, \ldots, y_n are i.i.d. from the *d*-variate Gaussian mixture

$$f(y_i;\theta) = \sum_{k=1}^{K} \pi_k f_k(y_i;\alpha_k)$$

- $\pi_k = p(z_{ik} = 1)$ $f_k(.: \alpha_k) = \phi(.: \mu_k, \Sigma_k) \text{ is the } d$
- $f_k(.; \alpha_k) = \phi(.; \mu_k, \Sigma_k)$ is the d-variate Gaussian distribution with mean vector μ_k and covariance matrix Σ_k
- $\theta = (\pi_1, \ldots, \pi_K, \alpha_1, \ldots, \alpha_K)$ is the whole mixture parameter
- Clustering: MAP principle from the mixture output to estimate the partition

And also: algorithm estimation (EM, SEM...) and model selection (BIC, ICL...)

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Degeneracy genesis: unbounded likelihood

■ *d*-variate Gaussian mixture

$$f(y_{i};\theta) = \sum_{k=1}^{K} \pi_{k} \underbrace{\frac{1}{(2\pi)^{d/2} |\Sigma_{k}|^{1/2}} \exp\left(-\frac{1}{2}(y_{i}-\mu_{k})^{T} \Sigma_{k}^{-1}(y_{i}-\mu_{k})\right)}_{\phi(y_{i};\mu_{k},\Sigma_{k})}$$

Sampling:
$$y_1, \ldots, y_n \stackrel{i.i.d.}{\sim} p(.; \theta)$$
 without any missing data $(y^{obs} = y)$
Likelihood: $\ell(\theta; y) = \ln L(\theta; y) = \sum_{i=1}^n \ln f(y_i; \theta)$

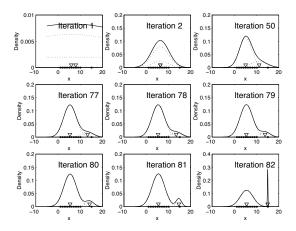
$$\text{particular center } \mu_2 = y_i \quad \Rightarrow \quad \lim_{|\Sigma_2| \to 0} \ell(\theta; y) = +\infty$$

[Kiefer and Wolfowitz, 1956] [Day, 1969]

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EM behaviour: illustration



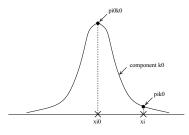
degeneracy may occur even when starting from large variances

- convergence can be slow when far from the degenerate limit
- convergence extremely fast near degeneracy

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EM behaviour: results



$$u_0 = \left[\frac{1}{p_{i_0k_0}}, \{p_{ik_0}\}_{i \neq i_0}\right]$$

degeneracy of component k_0 at y_{i_0}

 \Leftrightarrow $||u_0|| \rightarrow 0$ [Biernacki and Chrétien, 2003] [Ingrassia and Rocci, 2009]

Proposition 1: Existence of a bassin of attraction

 $\exists \epsilon > 0 \text{ s.t. if } \|u_0\| \leq \epsilon \text{ then } \|u_0^+\| = o\|u_0\| \text{ with probability 1.}$

Proposition 2: Speed towards degeneracy is exponential

 $\exists \epsilon > 0, \alpha > 0$ and $\beta > 0$ s.t. if $||u_0|| \le \epsilon$ then, with probability 1, $|\Sigma_{k_0}^+| \le \alpha / |\Sigma_{k_0}| \cdot \exp\left(-\beta / |\Sigma_{k_0}|\right).$

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Gaussian mixture degeneracy without missing data

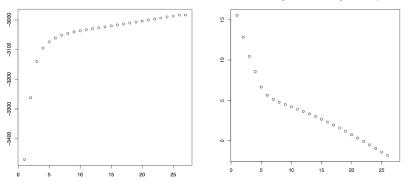
Gaussian mixture degeneracy with missing data

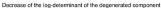
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EM behaviour illustration

- Breast cancer tissue of the UCI database repository: 106 units, 9 variables.
- 10% of missing data randomly generated
- K = 4 clusters

Log-likelihood according to the number of iterations





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Detail from the illustration

	1	2	3	4	5	6	7	8	9
1	211.00		0.09	30.75	151.98	4.94	14.27	27.24	217.13
2	196.86	0.02	0.09	28.59	82.06	2.87	7.97	27.66	200.75
3	144.00	0.12	0.05	19.65	70.43	3.58		7.57	160.37
4	172.52	0.13	0.04		192.22	5.12	19.32	32.19	174.93
5	121.00	0.17	0.09	24.44	144.47	5.91	22.02	10.59	141.77
6	223.00	0.12	0.08	33.10	197.01	5.95	30.45	12.96	252.48
7		0.17	0.23	34.22	94.35	2.76	31.28	13.88	180.61
8	303.00	0.06	0.04	22.57		4.54	21.83	5.72	321.65
9	250.00	0.09	0.09	29.64	180.76	6.10	26.14	13.96	280.12
10	391.00	0.06	0.01	35.78		7.41	22.13	28.11	400.99
11	176.00	0.09	0.08	20.59	79.71		18.23	9.58	191.99
12	145.00		0.11	21.22	82.46	3.89	20.30	6.17	162.51
13	124.13	0.13	0.11	20.59			18.46	9.12	134.89
14	103.00	0.16	0.29	23.75	78.26	3.29	22.32	8.12	124.98

Table : Data belonging to the degenerated component.

- Cvg. towards a degenerated component (no plateau of the log-likelihood)
- Degeneracy relatively slow: log-likelihood linear according to the nb of it.
- Number of points of the degenerated solution greater than the space dimension d (but the number of complete points lower than d)

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Intermediate conclusion on missing data

<u>Like</u> the complete data y case

- Likelihood is unbounded
- EM can be attracted by degenerate solutions

<u>Unlike</u> the complete data y case

- Risk to consider a degenerated solution as valid
- Risk of losing a lot of time in useless iterations

Statisticians should be aware of such dangerous EM behaviour...

... since missing data are more and more frequent

Understanding degeneracy speed on a toy example

- Univariate framework, no mixture, only one observed data: y
- Maximum likelihood estimator (Unbounded likelihood!): $\mu = y$, $\sigma^2 = 0$
- Suppose equivalently that n-1 data are unobserved (unchanged likelihood)
- Here is one iteration of a (useless) EM algorithm (it. q)

$$\mu^{(q+1)} = \frac{(n-1)\mu^{(q)} + y}{n} \text{ and } \sigma^{2(q+1)} = \frac{(n-1)\sigma^{2(q)} + (y-\mu^{(q+1)})^2}{n}$$

Linear grow of the log-likelihood (have a look also when *n* increases!) $\ell(\theta^{(q)};x) \sim -0.5q \log \frac{n-1}{n}$

Geometrical convergence rate towards 0 for the variance

$$\sigma^{2(q)} \sim \sigma^{2(0)} \left(\frac{n-1}{n}\right)^q$$

Influence of the missing data rate

% missing data	0	5	10	15	20	25	30
% deg.	16	4	12	11	46	51	100
Average nb of iterations before deg.	2	13	13	82	304	138	215

Table : Frequency and speed of degeneracy (deg.) according to the rate of missing data on the breast cancer data set.

When the rate of missing data increases:

- The rate of degeneracy increases
- The number of iterations before degeneracy seems to (globally) increase

Again, statisticians should be aware of such dangerous EM behaviour...

... since missing data are more and more frequent

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Full mixed data: conditional independence everywhere¹

The aim is to combine continuous, categorical, integer data, ordinal, ranking and functional data

$$y_1 = (y_1^{cont}, y_1^{cat}, y_1^{int}, \ldots)$$

The proposed solution is to mixed all types by inter-type conditional independence

$$\mathsf{p}(y_1;\alpha_k) = \mathsf{p}(y_1^{cont};\alpha_k^{cont}) \times \mathsf{p}(y_1^{cat};\alpha_k^{cat}) \times \mathsf{p}(y_1^{int};\alpha_k^{int}) \times \dots$$

In addition, for symmetry between types, intra-type conditional independence

Only need to define the univariate pdf for each variable type!

- Continuous: Gaussian
- Categorical: multinomial
- Integer: Poisson

...

¹MixtComp package: https://cran.r-project.org/web/packages/RMixtComp/index.html

Missing data: MAR assumption and estimation

Assumption on the missingness mecanism

Missing At Randon (MAR): the probability that a variable is missing does not depend on its own value given the observed variables.

Observed log-likelihood...

$$\ell(\theta; y^{\text{obs}}) = \sum_{i=1}^{n} \log \left(\sum_{k=1}^{K} \pi_k \mathsf{p}(y_i^{\text{obs}}; \alpha_k) \right) = \sum_{i=1}^{n} \ln \left[\sum_{k=1}^{K} \pi_k \underbrace{\int_{y_i^{\text{mis}}} \mathsf{p}(y_i^{\text{obs}}, y_i^{\text{mis}}; \alpha_k) dy_i^{\text{mis}}}_{\text{MAR assumption}} \right]$$

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SEM algorithm

(implemented in the MixtComp package, available on the CRAN repository)

A SEM algorithm to estimate θ by maximizing the observed-data log-likelihood

- Initialisation $\theta^{(0)}$
- Iteration nb q:
 - **E**-step: compute conditional probabilities $p(y^{\min}, z | y^{obs}; \theta^{(q)})$
 - **S-step:** draw $(y^{\min(q)}, z^{(q)})$ from $p(y^{\min}, z|y^{obs}; \theta^{(q)})$
 - M-step: maximize $\theta^{(q+1)} = \arg \max_{\theta} \ln p(y^{\text{obs}}, y^{\min(q)}, z^{(q)}; \theta)$
- Stopping rule: iteration number

Properties: simpler than EM and interesting properties!

- Avoid possibly difficult E-step in an EM
- Classical M steps
- Avoids local maxima
- The mean of the sequence $(\theta^{(q)})$ approximates $\hat{\theta}$
- The variance of the sequence $(\theta^{(q)})$ gives confidence intervals

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A model-based MAR approach

Biology study illustration

Prostate cancer data (with missing data)³

- Individuals: 506 patients with prostatic cancer grouped on clinical criteria into two Stages 3 and 4 of the disease
- Variables: d = 12 pre-trial variates were measured on each patient, composed by eight continuous variables (age, weight, systolic blood pressure, diastolic blood pressure, serum haemoglobin, size of primary tumour, index of tumour stage and histolic grade, serum prostatic acid phosphatase) and four categorical variables with various numbers of levels (performance rating, cardiovascular disease history, electrocardiogram code, bone metastases)
- Some missing data: 62 missing values ($\approx 1\%$)

We forget the classes (Stages of the desease) for performing clustering

Questions

- How many clusters?
- Which partition?

³Byar DP, Green SB (1980): Bulletin Cancer, Paris 67:477-488

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Two strategies in competition

Strategy "mice⁴ + MixtComp": MixtComp on the dataset completed by mice

> data.imp=mice(data)

> data.comp.mice=complete(data.imp)

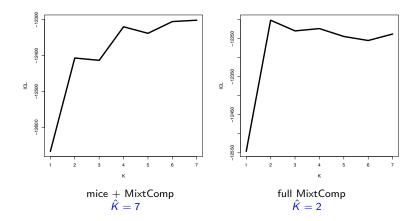
Strategy "full MixtComp": MixtComp on the observed (no completed) dataset

Partition q	uality with $K =$	2		
Strategy		mice + MixtComp	full MixtComp	
	% misclassified	12.8	8.1	

 $^{4} http://cran.r-project.org/web/packages/mice/mice.pdf$

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Choosing K with the ICL criterion



... may lose some cluster information when imputation before clustering

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Proposed MNAR models in clustering

Question we address now

Since MNAR is not ignorable, which distribution $p(c|y, z; \psi)$ to propose?

Hypothesis 1: conditional independence

$$p(c_i|y_i, z_{ik} = 1; \psi) = \prod_{j=1}^d p(c_{ij}|y_i, z_{ik} = 1; \psi)$$

Hypothesis 2: linear function within canonical link functions ρ

$$\mathsf{p}(c_{ij} = 1 \mid y_i, z_{ik} = 1; \psi) = \rho(\alpha_{kj} + \beta_{kj} y_{ij})$$

• $\psi = (\alpha, \beta)$ where $\alpha = (\alpha_{11}, \dots, \alpha_{1d}, \dots, \alpha_{K1}, \dots, \alpha_{Kd})^T \in \mathbb{R}^{Kd}$ and $\beta = (\beta_{11}, \dots, \beta_{1d}, \dots, \beta_{K1}, \dots, \beta_{Kd})^T \in \mathbb{R}^{Kd}$

 \bullet ρ is the cdf of any continuous distribution (logit, probit)

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A by-product zoology of MNAR models

	Effect on the variable <i>j</i>		Effect on the class membership <i>k</i>		Nb parameters
	Depends on <i>j</i>	Depends on <i>k</i>	Depends on <i>j</i>	Depends on <i>k</i>	Continuous
$MNARz^{j}y^{k}$	\checkmark	✓	✓	\checkmark	2Kd
MNAR <i>yzⁱ</i>	\checkmark	×	\checkmark	\checkmark	(K+1)d
MNARy ^k z	\checkmark	\checkmark	×	\checkmark	K(d+1)
MNAR <i>yz</i>	\checkmark	×	×	\checkmark	(K+d)
MNARy	\checkmark	×	×	×	d
MNARy ^k	\checkmark	\checkmark	×	×	Kd
MNAR <i>z</i>	×	×	×	\checkmark	K
MNAR <i>z^j</i>	×	X	\checkmark	\checkmark	Kd

Remarks:

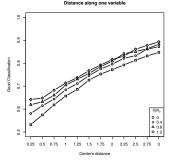
- $MNARz^j y^k$ is the most complex model
- MNARz, MNARz^{*j*}: the only effect of missingness is on the class membership, $\psi = (\alpha_{11}, ..., \alpha_{1d}, ..., \alpha_{K1}, ..., \alpha_{Kd})^T$, $p(c_{ij} = 1 | y_i, z_{ik} = 1; \psi) = \rho(\alpha_{kj})$
- MCAR is a specific and simple case



MNARz analysis: pattern c gives information on partition z!

Draw Bayes error of a MNARz model with two components and 20% of missing data

 $\pi_k = 0.5, \; \|\mu_2 - \mu_1\|$ varies, $\Sigma_1 = \Sigma_2 = \mathsf{I}, |lpha_2 - lpha_1|$ varies



Both μ_k and α_k act on the Bayes error

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Reinterpretation of the MNARz and MNARz^j models as MAR

Commonly used in Machine Learning [Jones, 1996], [Little and Rubin, 2002], [Josse et al., 2019]

Mixture model for y^{obs} and Bernoulli distribution for C \Leftrightarrow MAR mixture model for $\tilde{y}^{obs} = (y^{obs}|c)$

For example,

$$y^{\rm obs} = \left(\begin{array}{ccc} ? & 2.6 & 5\\ {\rm blue} & 1.9 & 4\\ {\rm red} & 2.3 & ? \end{array}\right), \quad c = \left(\begin{array}{ccc} 1 & 0 & 0\\ 0 & 0 & 0\\ 0 & 0 & 1 \end{array}\right)$$

then \tilde{y}^{obs} is expressed as

$$\tilde{y}^{\rm obs} = \left(\begin{array}{ccccccc} ? & 2.6 & 5 & 1 & 0 & 0 \\ {\rm blue} & 1.9 & 4 & 0 & 0 & 0 \\ {\rm red} & 2.3 & ? & 0 & 0 & 1 \end{array} \right)$$

Proposition 3: in terms of maximum likelihood

The maximum likelihood estimate associated to the dataset $\tilde{y}^{\rm obs}$ under MAR model is the one associated to the dataset $y^{\rm obs}$ under MNARz or MNARz^j models.

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Identifiability

Previous works: [Teicher, 1963] (without NA), [Miao et al., 2016] (for MNAR data)

Proposition 4

Assume that

- **I** The marginal mixture $\sum_{k=1}^{K} \pi_k f_k(y_i; \theta_k)$ is identifiable
- **2** There exists a total ordering \leq of $\mathcal{F}_j \times \mathcal{R}$, for $j \in \{1, \ldots, d\}$ fixed, where $\mathcal{F}_j = \{f_{1j}, \ldots, f_{Kj}\}$ and $\mathcal{R} = \{\rho_1, \ldots, \rho_K\} = \{\rho(.; \psi_1), \ldots, \rho(.; \psi_K)\}$. The total ordering is s.t. $\forall k < \ell$, $F_k = \rho_k f_{kj} \leq F_\ell = \rho_\ell f_{\ell j}$ implies

$$\lim_{u\to+\infty}\frac{\rho_\ell(u)f_{\ell j}(u)}{\rho_k(u)f_{k j}(u)}=0$$

Then the mixture model with one of the $\mathsf{MNAR}*$ mechanisms is identifiable up to label swapping

All MNAR models are identifiable (or at least generically identifiable) for probit/logit

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Estimation procedure overview

- Use EM or Stochastic EM (SEM) algorithms
- MNARz and MNARz^j: EM and SEM are very simple
- MNARy*: the SE step requires a within Gibbs loop, sometimes involving itself a Sampling Importance Resampling (SIR)

	E	Μ	SEM	
MNAR <i>z</i> MNAR <i>z^j</i>	✓		✓	
	Probit	Logit	Probit	Logit
MNARy*	no closed form	no closed form, optim. pb	✓	require algorithms as SIR (costly)

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Model selection

Can select between MCAR and MNAR* with any information criterion (BIC, ICL)

Even if the missing mechanism is ignorable for MCAR...

... need to model c to compare a MCAR and a MNAR model

CAUTION

- It is just a selection between several proposed MNAR models
- It is not deciding if missingness procedure is "genererically" MNAR or not

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4 Impact of MNAR data on clustering

A model-based MNAR clustering approach

Medical study illustration

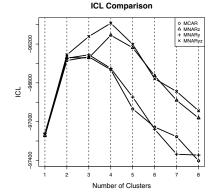
Introduction	Impact of MAR data on the EM algorithm	Impact of MAR data on clustering	Impact of MNAR data on clustering	Concluding
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Hospital data description

- Number of patients: $n = 5 \ 146$
- Number of features: d = 7
 - Age
 - Size
 - Weight
 - Cardiac frequency
 - Hemoglobin concentration
 - Temperature
 - Minimum Diastolic and Systolic Blood Pressure
- Percentage of missing data: 6.4%

Doctors are convinced that their missing data are MNAR

ICL comparison



• MCAR, MNARy and MNARz are equivalent until K = 3

• MNARz and MNARyz clearly indicate presence of an additional cluster (K = 4)

It seems to be an illustation of the effect of c through MNARz and MNARyz

Introduction Impact of MAR data on the EM algorithm Impact of MAR data on clustering Impact of MNAR data on clustering Concluding remarks

Outline

- Gaussian mixture degeneracy without missing data
- Gaussian mixture degeneracy with missing data

- A model-based MAR approach
- Biology study illustration

- A model-based MNAR clustering approach
- Medical study illustration

5 Concluding remarks

Introduction	Impact of MAR data on the EM algorithm	Impact of MAR data on clustering	Impact of MNAR data on clustering	Concluding remarks
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To conclude

Summary

- Statisticians should properly consider the potential missing data impact both from an algorithmic and from a modeling point of view
- EM: be careful about degeneracy which seems to exacerbated/masqued
- MAR: the minimal approach to be used by statisticians...
- MNAR: interest of the simple but meaningful model MNARz, link with usual methods

Ongoing works

- EM: propose mechanism to identify/discard degenerate runs
- MNAR: extend to categorical, count and mixed data