

Impact of missing data on mixtures and clustering with illustrations in Biology and Medicine

Christophe Biernacki, Claire Boyer, Gilles Celeux, Julie Josse, Fabien Laporte, M Marbac, Aude Sportisse, Vincent Vandewalle

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C. Biernacki

with C. Boyer, G. Celeux, J. Josse, F. Laporte, M. Marbac, A. Sportisse, V. Vandewalle

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Take home message

Missing data may change preconceptions

- Mixtures: EM has unexpected behaviour concerning degeneracy dynamic
- Clustering: the missing data pattern may convey some information on partition

These topics are in the research agenda of Statisticians since:

The larger the datasets, the more missing data may appear...

- 1 Introduction
- 2 Impact of MAR data on the EM algorithm
 - Gaussian mixture degeneracy without missing data
 - Gaussian mixture degeneracy with missing data
- 3 Impact of MAR data on clustering
 - A model-based MAR approach
 - Biology study illustration
- 4 Impact of MNAR data on clustering
 - A model-based MNAR clustering approach
 - Medical study illustration
- 5 Concluding remarks

Missing data: notations

- $y = \{y_1 | \dots | y_n\}^T$: full dataset with *n* individuals
- $\mathbf{v}_i = (y_{i1}, \dots, y_{id}) \in \mathcal{Y} = \mathbb{R}^d$ with individual $i \in \{1, \dots, n\}$
- $\mathbf{c} = \{c_1 | \dots | c_n\}^T \in \{0,1\}^{n \times d}$: pattern of missing data for the full dataset
- $c_i = (c_{i1}, \dots, c_{id}) \in \{0, 1\}^d$: pattern of missing data for individual $i \in \{1, \dots, n\}$

$$c_{ii} = 1 \Leftrightarrow y_{ii}$$
 is missing

- y_i^{obs} : the observed variables values for indiv. i (and $y^{\text{obs}} = \{y_1^{\text{obs}} | \dots | y_n^{\text{obs}} \}^T$)
- y_i^{mis} : the missing variables values for individual i (and $y^{\text{mis}} = \{y_1^{\text{mis}} | \dots | y_n^{\text{mis}} \}^T$)

Missing completely at random (MCAR):

$$p(c|y;\psi) = p(c;\psi) \quad \forall y$$

Missing at random (MAR):

$$p(c|y; \psi) = p(c|y^{obs}; \psi) \quad \forall y^{mis}$$

■ Missing not at random (MNAR): the mechanism is not MCAR nor MAR

Ignorable vs. non ignorable model

A missing mechanism is ignorable if likelihoods can be decomposed as

$$L(\theta, \psi; \underbrace{y^{\text{obs}}, c}) = L(\psi; c|y^{\text{obs}}) \times L(\theta; y^{\text{obs}})$$

Some simple algebra show that this occurs when missing mechanism is not MNAR

Inference of θ

"If the missing mechanism is ignorable then likelihood-based inferences for θ from $L(\theta; y^{\text{obs}})$ will be the same as likelihood based inference for θ from $L(\theta, \psi; y^{\text{obs}}, c)$." [Little and Rubin, 2002 Section 6.2]

- M(C)AR is ignorable
- MNAR is not ignorable

Mixture model and clustering (Gaussian case)

- Partition (*K* clusters): $z = (z_1 | \dots | z_n)^T \in \{0, 1\}^{n \times K}$ where
 - $z_i = (z_{i1}, \ldots, z_{iK}) \in \{0, 1\}^K$
 - $z_{ik} = 1$ if y_i belongs to cluster k, $z_{ik} = 0$ otherwise
- Mixture model: $y_1, ..., y_n$ are i.i.d. from the d-variate Gaussian mixture

$$f(y_i;\theta) = \sum_{k=1}^K \pi_k f_k(y_i;\alpha_k)$$

- $\pi_{\nu} = p(z_{i\nu} = 1)$
- $f_k(.; \alpha_k) = \phi(.; \mu_k, \Sigma_k)$ is the d-variate **Gaussian distribution** with mean vector μ_k and covariance matrix Σ_{ν}
- $m{\theta} = (\pi_1, \dots, \pi_K, \alpha_1, \dots, \alpha_K)$ is the whole mixture parameter
- Clustering: MAP principle from the mixture output to estimate the partition

And also: algorithm estimation (EM, SEM...) and model selection (BIC, ICL...)

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d-variate Gaussian mixture

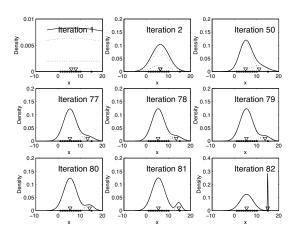
$$f(y_i; \theta) = \sum_{k=1}^{K} \pi_k \underbrace{\frac{1}{(2\pi)^{d/2} |\Sigma_k|^{1/2}} \exp\left(-\frac{1}{2} (y_i - \mu_k)^T \Sigma_k^{-1} (y_i - \mu_k)\right)}_{\phi(y_i; \mu_k, \Sigma_k)}$$

- Sampling: $v_1, \ldots, v_n \overset{i.i.d.}{\sim} p(:;\theta)$ without any missing data $(v^{\text{obs}} = v)$
- Likelihood: $\ell(\theta; y) = \ln L(\theta; y) = \sum_{i=1}^{n} \ln f(y_i; \theta)$

particular center
$$\mu_2 = y_i \quad \Rightarrow \quad \lim_{|\Sigma_2| \to 0} \ell(\theta; y) = +\infty$$

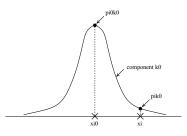
[Kiefer and Wolfowitz, 1956] [Dav. 1969]

EM behaviour: illustration



- degeneracy may occur even when starting from large variances
- convergence can be slow when far from the degenerate limit
- convergence extremely fast near degeneracy

EM behaviour: results



$$u_0 = \left[\frac{1}{p_{i_0k_0}}, \{p_{ik_0}\}_{i \neq i_0}\right]$$

degeneracy of component k_0 at y_{i_0}

$$||u_0|| \to 0$$

[Biernacki and Chrétien, 2003] [Ingrassia and Rocci, 2009]

Proposition 1: Existence of a bassin of attraction

 $\exists \epsilon > 0 \text{ s.t. if } \|u_0\| \le \epsilon \text{ then } \|u_0^+\| = o\|u_0\| \text{ with probability } 1.$

Proposition 2: Speed towards degeneracy is exponential

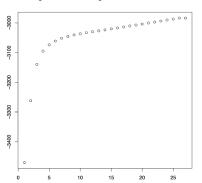
$$\exists \epsilon > 0, \, \alpha > 0 \text{ and } \beta > 0 \text{ s.t. if } \|u_0\| \leq \epsilon \text{ then, with probability } 1, \\ |\Sigma_{k_0}^+| \leq \alpha/|\Sigma_{k_0}| \cdot \exp\Big(-\beta/|\Sigma_{k_0}|\Big).$$

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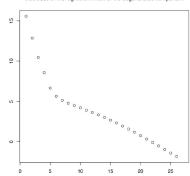
EM behaviour illustration

- Breast cancer tissue of the UCI database repository: 106 units, 9 variables.
- 10% of missing data randomly generated
- K = 4 clusters

Log-likelihood according to the number of iterations



Decrease of the log-determinant of the degenerated component



	1	2	3	4	5	6	7	8	9
1	211.00		0.09	30.75	151.98	4.94	14.27	27.24	217.13
2	196.86	0.02	0.09	28.59	82.06	2.87	7.97	27.66	200.75
3	144.00	0.12	0.05	19.65	70.43	3.58		7.57	160.37
4	172.52	0.13	0.04		192.22	5.12	19.32	32.19	174.93
5	121.00	0.17	0.09	24.44	144.47	5.91	22.02	10.59	141.77
6	223.00	0.12	0.08	33.10	197.01	5.95	30.45	12.96	252.48
7		0.17	0.23	34.22	94.35	2.76	31.28	13.88	180.61
8	303.00	0.06	0.04	22.57		4.54	21.83	5.72	321.65
9	250.00	0.09	0.09	29.64	180.76	6.10	26.14	13.96	280.12
10	391.00	0.06	0.01	35.78		7.41	22.13	28.11	400.99
11	176.00	0.09	0.08	20.59	79.71		18.23	9.58	191.99
12	145.00		0.11	21.22	82.46	3.89	20.30	6.17	162.51
13	124.13	0.13	0.11	20.59			18.46	9.12	134.89
14	103.00	0.16	0.29	23.75	78.26	3.29	22.32	8.12	124.98

Table: Data belonging to the degenerated component.

- Cvg. towards a degenerated component (no plateau of the log-likelihood)
- Degeneracy relatively slow: log-likelihood linear according to the nb of it.
- Number of points of the degenerated solution greater than the space dimension d (but the number of complete points lower than d)

Intermediate conclusion on missing data

Like the complete data y case

- Likelihood is unbounded
- EM can be attracted by degenerate solutions

Unlike the complete data y case

- Risk to consider a degenerated solution as valid
- Risk of losing a lot of time in useless iterations

Statisticians should be aware of such dangerous EM behaviour. . .

... since missing data are more and more frequent

Understanding degeneracy speed on a toy example

- Univariate framework, no mixture, only one observed data: y
- Maximum likelihood estimator (Unbounded likelihood!): $\mu = y$, $\sigma^2 = 0$
- Suppose equivalently that n-1 data are unobserved (unchanged likelihood)
- Here is one iteration of a (useless) EM algorithm (it. q)

$$\mu^{(q+1)} = \frac{(n-1)\mu^{(q)} + y}{n} \text{ and } \sigma^{2(q+1)} = \frac{(n-1)\sigma^{2(q)} + (y - \mu^{(q+1)})^2}{n}$$

Linear grow of the log-likelihood (have a look also when n increases!)

$$\ell(\theta^{(q)}; x) \sim -0.5q \log \frac{n-1}{n}$$

Geometrical convergence rate towards 0 for the variance

$$\sigma^{2(q)} \sim \sigma^{2(0)} \left(\frac{n-1}{n}\right)^q$$

Influence of the missing data rate

% missing data	0	5	10	15	20	25	30
% deg.	16	4	12	11	46	51	100
Average nb of iterations before deg.	2	13	13	82	304	138	215

Table : Frequency and speed of degeneracy (deg.) according to the rate of missing data on the breast cancer data set.

When the rate of missing data increases:

- The rate of degeneracy increases
- The number of iterations before degeneracy seems to (globally) increase

Again, statisticians should be aware of such dangerous EM behaviour. . .

... since missing data are more and more frequent

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The aim is to combine continuous, categorical, integer data, ordinal, ranking and functional data

$$y_1 = (y_1^{cont}, y_1^{cat}, y_1^{int}, \ldots)$$

The proposed solution is to mixed all types by inter-type conditional independence

$$p(y_1; \alpha_k) = p(y_1^{cont}; \alpha_k^{cont}) \times p(y_1^{cat}; \alpha_k^{cat}) \times p(y_1^{int}; \alpha_k^{int}) \times \dots$$

In addition, for symmetry between types, intra-type conditional independence

Only need to define the univariate pdf for each variable type!

- Continuous: Gaussian
- Categorical: multinomial
- Integer: Poisson

¹MixtComp package: https://cran.r-project.org/web/packages/RMixtComp/index.html

Missing data: MAR assumption and estimation

Assumption on the missingness mecanism

Missing At Randon (MAR): the probability that a variable is missing does not depend on its own value given the observed variables.

Observed log-likelihood...

$$\ell(\theta; y^{\text{obs}}) = \sum_{i=1}^{n} \log \left(\sum_{k=1}^{K} \pi_k \mathsf{p}(y_i^{\text{obs}}; \alpha_k) \right) = \sum_{i=1}^{n} \ln \left[\sum_{k=1}^{K} \pi_k \underbrace{\int_{y_i^{\text{mis}}} \mathsf{p}(y_i^{\text{obs}}, y_i^{\text{mis}}; \alpha_k) dy_i^{\text{mis}}}_{\text{MAR assumption}} \right]$$

SEM algorithm

(implemented in the MixtComp package, available on the CRAN repository)

A SEM algorithm to estimate θ by maximizing the observed-data log-likelihood

- Initialisation: $\theta^{(0)}$
- Iteration nb q:
 - **E**-step: compute conditional probabilities $p(y^{mis}, z|y^{obs}; \theta^{(q)})$
 - **S-step**: draw $(y^{\min(q)}, z^{(q)})$ from $p(y^{\min}, z|y^{\text{obs}}; \theta^{(q)})$
 - M-step: maximize $\theta^{(q+1)} = \arg \max_{\theta} \ln p(y^{\text{obs}}, y^{\text{mis}(q)}, z^{(q)}; \theta)$
- Stopping rule: iteration number

Properties: simpler than EM and interesting properties!

- Avoid possibly difficult E-step in an EM
- Classical M steps
- Avoids local maxima
- The mean of the sequence $(\theta^{(q)})$ approximates $\hat{\theta}$
- The variance of the sequence $(\theta^{(q)})$ gives confidence intervals

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Prostate cancer data (with missing data)³

- Individuals: 506 patients with prostatic cancer grouped on clinical criteria into two Stages 3 and 4 of the disease
- \blacksquare Variables: d=12 pre-trial variates were measured on each patient, composed by eight continuous variables (age, weight, systolic blood pressure, diastolic blood pressure, serum haemoglobin, size of primary tumour, index of tumour stage and histolic grade, serum prostatic acid phosphatase) and four categorical variables with various numbers of levels (performance rating, cardiovascular disease history, electrocardiogram code, bone metastases)
- Some missing data: 62 missing values ($\approx 1\%$)

We forget the classes (Stages of the desease) for performing clustering

Questions

- How many clusters?
- Which partition?

³Byar DP, Green SB (1980): Bulletin Cancer, Paris 67:477-488

Two strategies in competition

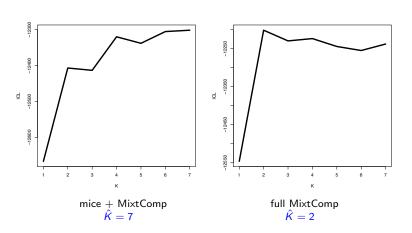
- Strategy "mice⁴ + MixtComp": MixtComp on the dataset completed by mice
- > data.imp=mice(data)
- > data.comp.mice=complete(data.imp)
- Strategy "full MixtComp": MixtComp on the observed (no completed) dataset

Partition quality with K=2

Strategy	mice + MixtComp	full MixtComp
% misclassified	12.8	8.1

⁴http://cran.r-project.org/web/packages/mice/mice.pdf

Choosing *K* with the ICL criterion



... may lose some cluster information when imputation before clustering

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Question we address now

Since MNAR is not ignorable, which distribution $p(c|y, z; \psi)$ to propose?

Hypothesis 1: conditional independence

$$p(c_i|y_i, z_{ik} = 1; \psi) = \prod_{j=1}^d p(c_{ij}|y_i, z_{ik} = 1; \psi)$$

Hypothesis 2: linear function within canonical link functions ρ

$$p(c_{ij} = 1 \mid y_i, z_{ik} = 1; \psi) = \rho(\alpha_{kj} + \beta_{kj}y_{ij})$$

- \bullet ρ is the cdf of any continuous distribution (logit, probit)

A by-product zoology of MNAR models

	Effect variabl		Effect on members	the class hip k	Nb parameters
	Depends on j	Depends on k	Depends on j	Depends on k	Continuous
$MNAR z^j y^k$	✓	√	✓	✓	2Kd
MNAR <i>yz^j</i>	✓	×	✓	✓	(K+1)d
MNARy ^k z	✓	✓	Х	✓	K(d+1)
MNARyz	✓	×	×	✓	(K+d)
MNARy	✓	×	×	×	d
$MNARy^k$	✓	✓	Х	X	Kd
MNARz	X	×	Х	✓	K
$MNARz^j$	Х	X	✓	✓	Kd

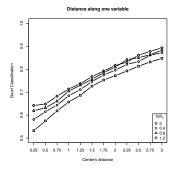
Remarks:

- MNAR $z^j y^k$ is the most complex model
- MNARz, MNARz^j: the only effect of missingness is on the class membership, $\psi = (\alpha_{11}, \dots, \alpha_{1d}, \dots, \alpha_{K1}, \dots, \alpha_{Kd})^T$, $\mathsf{p}(c_{ij} = 1 \mid y_i, z_{ik} = 1; \psi) = \rho(\alpha_{ki})$
- MCAR is a specific and simple case

MNARz analysis: pattern c gives information on partition z!

Draw Bayes error of a MNARz model with two components and 20% of missing data

$$\pi_k = 0.5$$
, $\|\mu_2 - \mu_1\|$ varies, $\Sigma_1 = \Sigma_2 = I$, $|\alpha_2 - \alpha_1|$ varies



Both μ_k and α_k act on the Bayes error

Reinterpretation of the MNARz and MNARz^j models as MAR

Commonly used in Machine Learning [Jones, 1996], [Little and Rubin, 2002], [Josse et al., 2019]

Mixture model for y^{obs} and Bernoulli distribution for C \Leftrightarrow MAR mixture model for $\tilde{y}^{\text{obs}} = (y^{\text{obs}}|c)$

For example,

$$y^{\text{obs}} = \begin{pmatrix} ? & 2.6 & 5 \\ \text{blue} & 1.9 & 4 \\ \text{red} & 2.3 & ? \end{pmatrix}, \quad c = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

then \tilde{y}^{obs} is expressed as

$$\tilde{y}^{\mathrm{obs}} = \left(\begin{array}{ccccc} ? & 2.6 & 5 & 1 & 0 & 0 \\ \mathrm{blue} & 1.9 & 4 & 0 & 0 & 0 \\ \mathrm{red} & 2.3 & ? & 0 & 0 & 1 \end{array} \right).$$

Proposition 3: in terms of maximum likelihood

The maximum likelihood estimate associated to the dataset $\tilde{\gamma}^{\mathrm{obs}}$ under MAR model is the one associated to the dataset y^{obs} under MNARz or MNARz^j models.

Previous works: [Teicher, 1963] (without NA), [Miao et al., 2016] (for MNAR data)

Proposition 4

Assume that

- **The marginal mixture** $\sum_{k=1}^{K} \pi_k f_k(y_i; \theta_k)$ is identifiable
- **2** There exists a total ordering \leq of $\mathcal{F}_i \times \mathcal{R}$, for $j \in \{1, \dots, d\}$ fixed, where $\mathcal{F}_{i} = \{f_{1i}, \dots, f_{Ki}\}\$ and $\mathcal{R} = \{\rho_{1}, \dots, \rho_{K}\} = \{\rho(.; \psi_{1}), \dots, \rho(.; \psi_{K})\}.$ The total ordering is s.t. $\forall k < \ell$, $F_k = \rho_k f_{ki} \leq F_\ell = \rho_\ell f_{\ell i}$ implies

$$\lim_{u\to+\infty}\frac{\rho_{\ell}(u)f_{\ell j}(u)}{\rho_{k}(u)f_{k j}(u)}=0$$

Then the mixture model with one of the MNAR* mechanisms is identifiable up to label swapping

All MNAR models are identifiable (or at least generically identifiable) for probit/logit

Estimation procedure overview

- Use EM or Stochastic EM (SEM) algorithms
- MNARz and MNAR z^j : EM and SEM are very simple
- MNARy*: the SE step requires a within Gibbs loop, sometimes involving itself a Sampling Importance Resampling (SIR)

	E	.M	SEM		
MNAR <i>z</i> MNAR <i>z^j</i>	,	/	✓		
	Probit	Logit	Probit	Logit	
MNARy*	no closed form	no closed form, optim. pb	√	require algorithms as SIR (costly)	

Model selection

Can select between MCAR and MNAR* with any information criterion (BIC, ICL)

Even if the missing mechanism is ignorable for MCAR...

 \dots need to model c to compare a MCAR and a MNAR model

CAUTION

- It is just a selection between several proposed MNAR models
- It is not deciding if missingness procedure is "genererically" MNAR or not

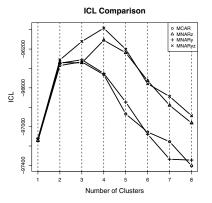
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Hospital data description

- Number of patients: n = 5 146
- Number of features: d = 7
 - Age
 - Size
 - WeightCardiac frequency
 - Hemoglobin concentration
 - Temperature
 - Minimum Diastolic and Systolic Blood Pressure
- Percentage of missing data: 6.4%

Doctors are convinced that their missing data are MNAR





- MCAR, MNARy and MNARz are equivalent until K = 3
- MNARz and MNARyz clearly indicate presence of an additional cluster (K = 4)

It seems to be an illustation of the effect of c through MNARz and MNARyz

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To conclude

Summary

- Statisticians should properly consider the potential missing data impact both from an algorithmic and from a modeling point of view
- EM: be careful about degeneracy which seems to exacerbated/masqued
- MAR: the minimal approach to be used by statisticians. . .
- MNAR: interest of the simple but meaningful model MNARz, link with usual methods

Ongoing works

- EM: propose mechanism to identify/discard degenerate runs
- MNAR: extend to categorical, count and mixed data

Thanks!