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The Nullstellensatz and Positivstellensatz for Sparse Tropical Polynomial Systems

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Abstract

Grigoriev and Podolskii (2018) have established a tropical analogue of the effective Nullstellensatz, showing that a system of tropical polynomial equations is solvable if and only if a linearized system obtained from a truncated Macaulay matrix is solvable. They provided an upper bound of the minimal admissible truncation degree, as a function of the degrees of the tropical polynomials. We establish a tropical Nullstellensatz adapted to *sparse* tropical polynomial systems. Our approach is inspired by a construction of Canny-Emiris (1993), refined by Sturmfels (1994). This leads to an improved bound of the truncation degree, which coincides with the classical Macaulay degree in the case of $n + 1$ equations in n unknowns. We also establish a tropical Positivstellensatz, allowing one to decide the inclusion of tropical basic semialgebraic sets. This allows one to reduce decision problems for tropical semi-algebraic sets to the solution of systems of tropical linear equalities and inequalities.

1 Introduction

Motivation

A basic problem in computational tropical geometry consists in solving systems of equations or of inequalities involving multivariate tropical polynomials.

Such systems arise in the study of *non-archimedean amoebas*, which are images by a non-archimedean valuation of an algebraic set [EKL06]. A super-approximation of a non-archimedean amoeba can be obtained by translating the defining equations of the algebraic set in the tropical semifield. This leads to a system of tropical polynomial equations, the solution set of which is called a *tropical prevariety*. Moreover, when working over an algebraically closed non-archimedean field, this approximation is exact under appropriate genericity conditions, or if the defining set is sufficiently rich, see in particular the ‘fundamental theorem of tropical geometry’ in [MS15], in which case the non-archimedean amoeba is called a *tropical variety*.

Similarly, the solution sets of systems of tropical polynomial inequalities provide upper approximations of images by a non-archimedean valuation of semi-algebraic sets over real closed non-archimedean fields, and these approximations are exact under genericity conditions [IV96, AGS20, JSY20]. Moreover, owing to their combinatorial nature, tropical polynomial systems are often easier to grasp than their classical analogues. These ideas, which can be traced back to works of Viro (see [Vir89]), Gelfand, Kapranov, Zelevinsky [GKZ94], Sturmfels (see [HS95]), or Mikhalkin [Mik05], are at the heart of tropical geometry, see [IMS09, MS15] for background.

Systems of tropical polynomial equations and inequations are also interesting in their own right, since they arise in specific applications, independently of the nonarchimedean interpretation. In particular, they arise in the computation of stationary behaviors of discrete event systems [CGQ98], see e.g. [ABG15] for an application to performance evaluation of emergency call centers. Other motivations arise from auction theory [BK19], or chemical reaction networks, see e.g. [DSR22].

Grigoriev and Podolskii established in [GP18] a *tropical Nullstellensatz*, which states that a system of tropical polynomial equations is solvable if and only if its linearization, obtained by truncating the Macaulay matrix up to an appropriate degree, is solvable. Their results also apply to polynomial inequations. Since systems of tropical linear equations and inequations reduce to mean payoff games [AGG12], this provides both theoretical tools (strong duality theorems) and algorithms. The proof of [GP18], confirming a conjecture made by Grigoriev [Gri12], is based on very ingenious geometric arguments. However, Grigoriev and Podolskii observed that their proof leads to an estimate of the truncation degree which may not be optimal.

Contribution

We provide here a *tropical Nullstellensatz* (Theorem 3.5) for systems of tropical equations and inequations, taking into account the *sparse* structure. When specialized to full polynomials with given degrees, we recover the statement of Grigoriev and Podolskii, with an improved degree bound, matching the classical Macaulay degree bound for systems of $n + 1$ equations in n unknowns, see [Laz81, Laz83, Giu84], and also [BCC⁺05, CLO15] for background. Our approach also leads to a *tropical Positivstellensatz* (Theorem 4.1), allowing one to check the inclusion between two tropical basic semialgebraic sets, by reduction to a system with both strict and weak tropical linear inequalities. These two results are ultimately combined in the most general form in an *hybrid tropical Positivstellensatz* (Theorem 4.13).

To do so, we connect the tropical Nullstellensatz with a fundamental notion in classical polynomial system solving, the *Canny-Emiris sets*. In [CE93] and [Emi05], Canny and Emiris developed an algorithm to compute sparse resultants, for systems of $n + 1$ polynomial equations in n variables. This involves the construction of a submatrix of the Macaulay matrix, in which rows and columns are determined by considering the integer points of a generic perturbation of the Minkowski sum of the Newton polytopes of the polynomials. Their construction was generalized by Sturmfels in [Stu94, §3], by considering a generic collection of polyhedral concave functions. Here, we apply this tool to a different problem, showing that any Canny-Emiris set leads to a tropically valid linearization. In a nutshell, we show that if a tropical system is unfeasible, then, the ‘row contents’ arising in the Canny-Emiris construction provide a submatrix of the Macaulay matrix which is tropically nonsingular, and which therefore serves as an unfeasibility certificate. The case of systems combining polynomial equalities as well as weak and strict inequalities is more delicate: it relies on additional ingredients, including the Shapley-Folkman theorem, and it leads to a degree bound which may not be optimal. In this case, the reduction involves tropical linear systems combining equalities with weak and strict inequalities. The latter still reduce to mean-payoff games [AFG⁺14].

An advantage of the linearization approach lies in the *scalability* of mean-payoff games algorithms. Whereas the existence of a polytime algorithm to solve a mean-payoff game is a long standing open problem, in practice, typical large sparse instances of mean-payoff games can be solved efficiently by value-iteration type algorithms [ZP96, AGG12] or by policy iteration algorithms, see in particular [DG06, Cha09]. The application of game algorithms to solve instances arising from tropical polynomial systems is further discussed in the final section of [ABG23].

For simplicity, we state and prove the present tropical Nullstellensatz and Positivstellensatz by working over the ordinary tropical semifield \mathbb{R}_∞ . More generally, a tropical semifield can be constructed over any divisible (totally) ordered group, and this is helpful to study ‘higher rank’ tropicalizations [Aro10a, Aro10b, AGT16, AI22, JS23]. Then, using the completeness of the first order theory of divisible ordered groups [Rob56, §4.3], it is immediate to see that the present results carry over to this case.

Related work

As discussed above, the present work is inspired by [GP18]. The main contribution here is the handling of sparsity, with a new proof, leading to an improved truncation bound in the dense case. We also handle strict inequalities, which allows us to interpret the results in terms of ‘Positivstellensätze’. However, contrarily to what is done in [GP18], we limit our attention to the ‘toric case’, looking only for solutions in \mathbb{R}^n , see Remark 3.9 for more information.

The standard approach to the computation of tropical prevarieties is to exploit the duality between arrangements of tropical hypersurfaces and mixed-polyhedral subdivisions. In that way, decision problems concerning tropical prevarieties can be reduced to the enumeration of mixed cells, see [Jen16, Mal16]. A number of current works deal with the efficient computation of tropical varieties and prevarieties, see [MR19, GRZ22] and the references therein.

In these approaches, *all* solutions are typically constructed. In contrast, when applying the tropical Nullstellensatz or Positivstellensatz, we do not need to enumerate all the cells of a polyhedral complex (which amounts to testing all candidate solutions). Instead, we directly decide the feasibility or unfeasibility by reduction to a mean payoff game. In the special case of linear inequalities, the advantage of the second approach can be quantified: there are exponentially many tropically extreme solutions [AGK11], hence exponentially many cells, making the enumeration unfeasible unless the dimension is only of a few dozens, whereas checking the feasibility reduces to solving a mean payoff game with a size linearly bounded in input size, which can be done for large systems with pseudo-polynomial complexity bounds. This advantage subsists for a significant class of higher degree instances, although the size of the game now becomes exponential in the input size. We expect the present approach to be especially useful in the ‘Positivstellensatz’ case, in which the exhaustive cell enumeration is especially heavy, whereas only a single feasible cell, or an unfeasibility certificate, is looked for.

A different approach relies on the application of general-purpose SMT solving algorithms [Lü20].

A tropical Nullstellensatz for tropical ideals, building on [GP18], is established in [MR18]. Other tropical Nullstellensätze of different natures have also been established in [SI07, BE17, GP20].

The initial account of the present results appeared in the ISSAC conference paper [ABG23], which also discusses algorithmic aspects. The present paper contains the proofs of the theoretical results of [ABG23]. An implementation of algorithms to decide the feasibility of tropical polynomial systems, using the present sparse Nullstellensatz and Positivstellensatz, is available from [Bé23].

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2 Generalities on valued fields, polynomials and varieties

Throughout this paper, we will use the typographic convention to denote tropical objects with normal weight fonts, and reserve bold fonts to denote their classical analogues in a valued field \mathcal{K} (most of the time objects in the field of univariate complex generalized Puiseux series).

First, we recall the definition of the different notions we will be working with throughout this paper. Let $(\Gamma, +, \leq)$ be a totally ordered abelian group. Then the group law and ordering on Γ can be extended to the set $\Gamma \cup \{\perp\}$, where \perp denotes the *bottom* element, by setting $\perp \leq v$ and $\perp + v = v + \perp = \perp$ for all $v \in \Gamma$. In $\Gamma \cup \{\perp\}$, the maximum function is defined as usual.

Definition 2.1. Let \mathcal{K} be a field and Γ a totally ordered abelian group. A map val from \mathcal{K} to $\Gamma \cup \{\perp\}$ is called a *valuation* if it satisfies the following properties for all $\mathbf{x}, \mathbf{y} \in \mathcal{K}$:

- (i) $\text{val}(\mathbf{x}) = \perp$ if and only if $\mathbf{x} = 0$;
- (ii) $\text{val}(\mathbf{x}\mathbf{y}) = \text{val}(\mathbf{x}) + \text{val}(\mathbf{y})$;
- (iii) $\text{val}(\mathbf{x} + \mathbf{y}) \leq \max(\text{val}(\mathbf{x}), \text{val}(\mathbf{y}))$.

A field endowed with a valuation is called a *valued field*.

Note that in valuation theory, it is more common to call valuation the opposite of the map val . This would lead us to work which min-plus type, rather than max-plus type, tropical semifields,

Note that from items (i) and (ii) of the previous definition, we obtain in particular that val induces a group morphism from (\mathcal{K}^*, \times) to $(\Gamma, +)$, where $\mathcal{K}^* := \mathcal{K} \setminus \{0\}$ is the set of invertible elements. This motivates the following definition.

Definition 2.2. The *value group* of a valued field \mathcal{K} is the group $\Gamma_{\text{val}} := \text{val}(\mathcal{K}^*)$.

Remark 2.3. The value group Γ_{val} is thus a subgroup of Γ . However, in a lot of cases, we will be working with $\Gamma = \mathbb{R}$. In this case, we say that \mathcal{K} is a field with *real valuation* and that val is a *real valuation*.

Example 2.4. A basic example of valued field is the field $\mathbb{C}\{\{t\}\}$ of complex *Puiseux series* over one indeterminate. This field is endowed with the valuation given by

$$\text{val}(\mathbf{x}) := -\min\{q \in \mathbb{Q} : a_q \neq 0\} \quad \text{if} \quad \mathbf{x} = \sum_{q \in \mathbb{Q}} \mathbf{x}_q t^q$$

and in this case we have $\Gamma_{\text{val}} = \mathbb{Q}$.

We will also consider the field $\mathbb{C}[[t^{\mathbb{R}}]]$ of univariate complex *Hahn series*¹, that is the set of formal sums

$$\mathbf{x} = \sum_{r \in \mathbb{R}} \mathbf{x}_r t^r \quad \text{such that} \quad \{r \in \mathbb{R} : \mathbf{x}_r \neq 0\} \text{ is a well ordered subset of } \mathbb{R},$$

in which case the quantity

$$\text{val}(\mathbf{x}) := -\min\{r \in \mathbb{R} : \mathbf{x}_r \neq 0\}$$

is well-defined and yields a valuation of $\mathbb{C}[[t^{\mathbb{R}}]]$, which is surjective in this case, *i.e.* $\Gamma_{\text{val}} = \mathbb{R}$.

In the context of tropical algebra, the algebraic structure we typically use for calculations is not a ring, as we are used to, but a semiring. The definition of a semiring is the following.

¹Sometimes the notation $\mathbb{C}((\mathbb{R}))$ is also encountered, notably in [MS15].

Definition 2.5. A *semiring* $(R, +, \cdot, 0, 1)$ is a set R equipped with addition $+$ and multiplication \cdot such that

- (i) $(R, +)$ is a commutative monoid with identity element 0 called the *zero element*;
- (ii) (R, \cdot) is a monoid with identity element 1 called the *unit element*;
- (iii) the multiplication is distributive over the addition;
- (iv) 0 is the absorbing element for the multiplication.

If moreover, the multiplication is commutative, then R is called a *commutative semiring*, and if every nonzero element has an inverse for the multiplication, then R is called a *semifield*.

Note that a semiring R satisfy all the properties of a ring except one: the existence of an opposite element for the addition is not guaranteed. In particular, a ring is a semiring. There are many interesting examples of semirings besides rings, such as the set \mathbb{N} of nonnegative integers, endowed with the usual arithmetic operations, the sets of ideals of a ring, with ideal addition and multiplication, or any Boolean algebra, with \vee as addition and \wedge as multiplication. However, in this paper, we will be focusing on the following semiring.

Definition 2.6. The *tropical* (or *max-plus*) *semiring* is the semiring $(\mathbb{R} \cup \{-\infty\}, \oplus, \odot, 0, \mathbb{1})$ with addition $\oplus = \max$, multiplication $\odot = +$, zero element $0 = -\infty$ and unit element $\mathbb{1} = 0$. The operations \oplus and \odot are respectively referred to as the *tropical addition* and the *tropical multiplication*, and the tropical semiring is denoted by \mathbb{R}_∞ .

Remark 2.7. In fact, we can similarly define a semiring structure for any totally ordered abelian group with bottom element $\Gamma \cup \{\perp\}$, but in the context of this paper, we will focus on the case where $\Gamma = \mathbb{R}$ once again. Moreover, note that \mathbb{R}_∞ is not only a semiring but actually a semifield.

The definition of a formal polynomial over a semiring is identical to the usual definition of a formal polynomial over a ring.

Definition 2.8. A *formal Laurent polynomial* f over a semiring — and *a fortiori* over a ring — $(R, +, \cdot, 0, 1)$ in n variables is a map

$$\begin{aligned} \mathbb{Z}^n &\longrightarrow R \\ \alpha &\longmapsto \mathbf{f}_\alpha \end{aligned}$$

such that $\mathbf{f}_\alpha = 0$ for all $\alpha \in \mathbb{Z}^n$ but a finite number. If $\alpha = (\alpha_1, \dots, \alpha_n)$, then we use the following notation:

$$\mathbf{f} = \sum_{\alpha \in \mathbb{Z}^n} \mathbf{f}_\alpha X^\alpha = \sum_{\alpha \in \mathbb{Z}^n} \mathbf{f}_\alpha X_1^{\alpha_1} \cdots X_n^{\alpha_n}$$

and we denote by $R[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$ the set of formal Laurent polynomials in n variables over the semiring R .

The *support* $\text{supp}(\mathbf{f})$ of a formal Laurent polynomial $\mathbf{f} \in R[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$ is the set

$$\{\alpha \in \mathbb{Z}^n : \mathbf{f}_\alpha \neq 0\} .$$

Finally, the *polynomial function* associated to a formal Laurent polynomial $\mathbf{f} \in R[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$ is the function

$$\begin{aligned} (R^\times)^n &\longrightarrow R \\ \mathbf{x} &\longmapsto \sum_{\alpha \in \mathbb{Z}^n} \mathbf{f}_\alpha \mathbf{x}^\alpha , \end{aligned}$$

where R^\times denotes the multiplicative group of invertible elements of R and $\mathbf{x}^\alpha = \mathbf{x}_1^{\alpha_1} \times \cdots \times \mathbf{x}_n^{\alpha_n}$ if $\mathbf{x} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$ and $\alpha = (\alpha_1, \dots, \alpha_n)$. More generally, we call polynomial function any function of the previous form.

In particular, in the case where the semiring R corresponds to the tropical semiring, then a formal Laurent polynomial over R will be called a *formal tropical Laurent polynomial*, and its associated polynomial function a *tropical polynomial function*.

In the remainder of this paper, we will refer to formal Laurent polynomials as *formal polynomials*, or even simply as *polynomials* if the context is unambiguous, and a (formal Laurent) polynomial f with support included in \mathbb{N}^n will be referred to as an *ordinary polynomial* whenever we need to highlight the fact that all the exponents belong in the positive orthant, and we denote by $R[X_1, \dots, X_n]$ the set of formal ordinary polynomials in n variables over a semiring R .

Remark 2.9. If f is a tropical polynomial in n variables, then the tropical polynomial function associated to f is the function

$$\begin{aligned} \mathbb{R}^n &\longrightarrow \mathbb{R}_\infty \\ x &\longmapsto \bigoplus_{\alpha \in \mathbb{Z}^n} f_\alpha \odot x^{\odot \alpha} = \max_{\alpha \in \mathbb{Z}^n} (f_\alpha + \langle x, \alpha \rangle) \quad , \end{aligned}$$

where $x^{\odot \alpha} := x_1^{\odot \alpha_1} \odot \cdots \odot x_n^{\odot \alpha_n} = \langle x, \alpha \rangle$ denotes the usual scalar product of $x = (x_1, \dots, x_n)$ and $\alpha = (\alpha_1, \dots, \alpha_n)$ in \mathbb{R}^n .

Note that while in the case of an infinite field, there is a one-to-one correspondance between polynomial functions and formal polynomials, this is not the case in the tropical setting, where two distinct formal tropical polynomial can have the same tropical polynomial function. Therefore, we will always be explicit about the nature of the tropical objects we manipulate.

Now we can discuss the notion of root. A *root* of a polynomial f over a ring R is an element x of R such that evaluating the polynomial function of f at x gives the zero element. This definition, however, is not suited for polynomials over semirings, and in particular for tropical polynomials, for which we need to give another definition of a root.

Definition 2.10. Let $f = \bigoplus_{\alpha \in \mathbb{Z}^n} f_\alpha X^\alpha \in \mathbb{R}_\infty[X_1^\pm, \dots, X_n^\pm]$ be a tropical polynomial. An element $x = (x_1, \dots, x_n)$ of \mathbb{R}^n is called a (*tropical*) *root* of f whenever the maximum in the expression

$$\max_{\alpha \in \mathbb{Z}^n} (f_\alpha + \langle x, \alpha \rangle)$$

is attained for at least two distinct values of $\alpha \in \mathbb{Z}^n$. This is denoted² as $f(x) \nabla 0$.

In particular, if f is an ordinary tropical polynomial, then a root x of f is an element \mathbb{R}_∞^n (instead of \mathbb{R}^n) satisfying the same property, and in this case the *support* of the root is the set of indices whose associated coefficient is not equal to 0 .

Finally, note that for a finite collection $\mathbf{f} = (f_1, \dots, f_k)$ of Laurent polynomials, you can always find a monomial X^α such that for all $1 \leq i \leq k$, the polynomial $X^\alpha f_i$ is an ordinary polynomial. Therefore, we could in most cases only consider systems of ordinary polynomials.

Now, we recall a few definitions from [MS15] regarding the notion of tropicalization.

Definition 2.11. Let $(\mathcal{K}, \text{val})$ be a valued field and consider a Laurent polynomial $\mathbf{f} = \sum_{\alpha \in \mathbb{Z}^n} f_\alpha X^\alpha$ in $\mathcal{K}[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$. Then the *hypersurface* (or *variety*) associated to \mathbf{f} is the set

$$\mathcal{V}_{\mathcal{K}}(\mathbf{f}) := \{x \in (\mathcal{K}^*)^n : \mathbf{f}(x) = 0\} \quad .$$

Similarly, consider a tropical Laurent polynomial $f \in \mathbb{R}_\infty[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$. Then the *tropical hypersurface* (or *tropical variety*) associated to the tropical polynomial f is the set

$$\mathcal{V}_{\text{trop}}(f) := \{x \in \mathbb{R}^n, f(x) \nabla 0\} \quad ,$$

Definition 2.12. Let $(\mathcal{K}, \text{val})$ be a valued field and consider a Laurent polynomial $\mathbf{f} = \sum_{\alpha \in \mathbb{Z}^n} f_\alpha X^\alpha$ in $\mathcal{K}[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$. Then:

- the *tropicalization* of \mathbf{f} is the tropical polynomial function $\text{trop}(\mathbf{f})$ defined by

$$\text{trop}(\mathbf{f}) : \begin{cases} \mathbb{R}^n &\longrightarrow \mathbb{R}_\infty \\ x &\longmapsto \bigoplus_{\alpha \in \mathbb{Z}^n} \text{val}(f_\alpha) \odot x^{\odot \alpha} = \max_{\alpha \in \mathbb{Z}^n} (\text{val}(f_\alpha) + \langle x, \alpha \rangle) \quad ; \end{cases}$$

- the *tropicalization* of $\mathcal{V}_{\mathcal{K}}(\mathbf{f})$ or the *tropical hypersurface* associated to the (ordinary) polynomial \mathbf{f} is the set $\mathcal{T}_{\mathcal{K}}(\mathbf{f})$ defined by

$$\mathcal{T}_{\mathcal{K}}(\mathbf{f}) = \mathcal{V}_{\text{trop}}(\text{trop}(\mathbf{f})) \quad .$$

i.e. it corresponds to the set of points x in \mathbb{R}^n such that the maximum in the expression $\text{trop}(\mathbf{f})(x)$ is achieved at least twice.

Now let assume that there is a *splitting*³ of the surjection $\mathcal{K}^* \rightarrow \Gamma_{\text{val}}$, that is a group morphism

$$\begin{aligned} \Gamma_{\text{val}} &\longrightarrow \mathcal{K}^* \\ v &\longrightarrow t^v \quad . \end{aligned}$$

²This notation is not only used to convey the fact that $f(x) \nabla 0$ is the tropical analogue of the equation $\mathbf{f}(x) = 0$ in a ring, but it also has a deeper meaning as it comes from a natural binary relation that arises in extensions of the tropical semifield. For more details, see for instance Section 4. of [AGG09].

³Some authors also talk about *cross-sections*, which is the more standard terminology in the language of Denef-Pas, see [Pas89].

such that $\text{val}(t^v) = v$ for all $v \in \Gamma_{\text{val}}$. The existence of such a splitting is guaranteed whenever \mathcal{K} is algebraically closed, see Lemma 2.1.15 of [MS15]. Finally, let \mathcal{O} be the *valuation ring* of \mathcal{K} which is defined by

$$\mathcal{O} = \{x \in \mathcal{K} : \text{val}(x) \leq 0\} .$$

It is a local ring, with group of units

$$\mathcal{O}^\times = \{x \in \mathcal{K} : \text{val}(x) = 0\} ,$$

and we denote by \mathcal{M} its unique maximal ideal, which satisfies the equality

$$\mathcal{M} = \{x \in \mathcal{K} : \text{val}(x) < 0\} ,$$

and let $\mathcal{k} := \mathcal{O}/\mathcal{M}$ be the residue field of \mathcal{K} . We denote the projection from \mathcal{O} onto \mathcal{k} by

$$\begin{aligned} \mathcal{O} &\longrightarrow \mathcal{k} \\ x &\longmapsto \bar{x} . \end{aligned}$$

This projection induces a group morphism from \mathcal{O}^\times to \mathcal{k}^* which we extend into a group morphism π from \mathcal{K}^* to \mathcal{k}^* defined as follows

$$\pi : \begin{cases} \mathcal{K}^* &\longrightarrow \mathcal{k}^* \\ x &\longmapsto \frac{\bar{x}}{x t^{-\text{val}(x)}} . \end{cases}$$

In this context, we can define initial forms and initial ideal, which will allow us to give another description of tropical hypersurfaces and varieties.

Definition 2.13. Let $\mathbf{f} = \sum_{\alpha \in \mathbb{Z}^n} \mathbf{f}_\alpha X^\alpha$ be a formal polynomial in $\mathcal{K}[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$ and let $x \in \mathbb{R}^n$. Then the *initial form* of \mathbf{f} with respect to x is the formal polynomial $\text{in}_x(\mathbf{f}) \in \mathcal{k}[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$ given by

$$\text{in}_x(\mathbf{f}) = \sum_{\substack{\beta \in \arg \max_{\alpha \in \mathbb{Z}^n} \\ (\text{val}(\mathbf{f}_\alpha) + \langle x, \alpha \rangle)}} \pi(\mathbf{f}_\beta) X^\beta .$$

Moreover, if I is an ideal of $\mathcal{K}[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$, then the *initial ideal* of I with respect to x is the ideal $\text{in}_x(I)$ generated by the initial forms $\text{in}_x(\mathbf{f})$ where \mathbf{f} runs over I .

Remark 2.14. With the previous definition, the tropical variety $\mathcal{T}_{\mathcal{K}}(\mathbf{f})$ also corresponds to the set of points $x \in \mathbb{R}^n$ such that the initial form $\text{in}_x(\mathbf{f})$ is not a monomial.

We can then define the tropicalization of any variety of $(\mathcal{K}^*)^n$ as follows.

Definition 2.15. Let I be an ideal of $\mathcal{K}[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$, and $\mathcal{V}_{\mathcal{K}}(I)$ the variety it defines in $(\mathcal{K}^*)^n$. Then the *tropicalization* of the variety $\mathcal{V}_{\mathcal{K}}(I)$, or the *tropical variety* associated to the ideal I is the subset $\mathcal{T}_{\mathcal{K}}(I)$ of \mathbb{R}^n defined by

$$\mathcal{T}_{\mathcal{K}}(I) = \bigcap_{\mathbf{f} \in I} \mathcal{T}_{\mathcal{K}}(\mathbf{f}) . \quad (1)$$

More generally, we call *tropical variety* in \mathbb{R}^n any subset of the previous form.

In the case where \mathcal{K} has a nontrivial valuation, then there is an equivalent way to express $\mathcal{T}_{\mathcal{K}}(I)$.

Theorem 2.16 (Fundamental theorem of Tropical Algebraic Geometry). *Let \mathcal{K} be an algebraically closed field endowed with a nontrivial valuation val and let I be an ideal in $\mathcal{K}[X_1^{\pm 1}, \dots, X_n^{\pm 1}]$. Then the following three subsets of \mathbb{R}^n coincide:*

- (i) the tropical variety $\mathcal{T}_{\mathcal{K}}(I)$;
- (ii) the set of all vectors $x \in \mathbb{R}^n$ such that $\text{in}_x(I) \neq \langle 1 \rangle$;
- (iii) the closure of the set of coordinatewise valuations of points of $\mathcal{V}_{\mathcal{K}}(I)$, i.e. of the set

$$\text{val}(\mathcal{V}_{\mathcal{K}}(I)) = \{(\text{val}(\mathbf{x}_1), \dots, \text{val}(\mathbf{x}_n)) \in \mathbb{R}^n : (\mathbf{x}_1, \dots, \mathbf{x}_n) \in \mathcal{V}_{\mathcal{K}}(I)\} .$$

Proof. This is Theorem 3.2.3 of [MS15]. □

Remark 2.17. Note that in item (ii) of the previous theorem, the condition $\text{in}_x(I) \neq \langle 1 \rangle$ can be replaced with the equivalent condition that the ideal $\text{in}_x(I)$ contains no monomial, since monomials are exactly the invertible elements of the ring of Laurent polynomials in n variables.

Theorem 2.16 motivates the present work. Indeed, for any finite family of polynomials $\mathbf{f}_1, \dots, \mathbf{f}_k$ in the ideal I , checking that $\bigcap_{j \in [k]} \mathcal{T}_{\mathcal{K}}(\mathbf{f}_j) = \emptyset$, which can be done by applying the present tropical Nullstellensatz, entails that $\text{val}(\mathcal{V}_{\mathcal{K}}(I)) = \emptyset$. Hence, the tropical Nullstellensatz provides a certificate of emptiness for an algebraic variety over a valued field. Moreover, it is shown in [MS15] that the intersection (1) is achieved by considering only a finite subintersection, which entails that the collection of certificates obtained in this way is complete.

3 The Sparse Tropical Nullstellensatz

3.1 Statement of the theorem

The idea of the main theorem in this section is to reduce the problem of the existence of a solution to a system of polynomial equations to the existence of a solution to a system of tropical linear equations arising from a certain matrix called the Macaulay matrix, which can be constructed using the coefficients of the polynomials f_1, \dots, f_k . From now on, we denote by f the collection (f_1, \dots, f_k) of polynomials, and by $f \nabla \emptyset$ the system

$$\bigoplus_{\alpha \in \mathcal{A}_i} f_{i,\alpha} \odot x^{\odot \alpha} \nabla \emptyset \quad \text{for all } 1 \leq i \leq k$$

of tropical polynomial equations with unknown $x \in \mathbb{R}^n$.

We start by giving a proper setting to talk about tropical linear equations. We call *tropical matrix* a matrix with coefficients in \mathbb{R}_∞ . The set of $p \times m$ tropical matrices is denoted by $\mathcal{M}_{p,m}(\mathbb{R}_\infty)$, or simply $\mathcal{M}_m(\mathbb{R}_\infty)$ whenever $p = m$. We can define tropical addition \oplus and multiplication \odot on tropical matrices by replacing the usual operations by their tropical version in the definition of the usual matrix operations. This notably gives a semiring structure to the set $\mathcal{M}_m(\mathbb{R}_\infty)$.

Particularly, if $A = (a_{ij})_{\substack{1 \leq i \leq p \\ 1 \leq j \leq m}} \in \mathcal{M}_{p,m}(\mathbb{R}_\infty)$ and $y = (y_j)_{1 \leq j \leq m} \in \mathbb{R}_\infty^m$, then we have

$$A \odot y = \left(\max_{\substack{1 \leq j \leq m \\ 1 \leq i \leq p}} a_{ij} + y_j \right)_{1 \leq i \leq p} . \quad (2)$$

Definition 3.1. Let A be a $p \times m$ tropical matrix and let $y \in \mathbb{R}_\infty^m$. Then we write that $A \odot y \nabla \emptyset$ whenever the maximum is attained twice for every coefficient in the righthandside of (2). The set of vectors $y \in \mathbb{R}_\infty^m$ such that $A \odot y \nabla \emptyset$ is called the *tropical right null space* or *kernel* of the matrix A . Moreover, we set by convention that all vectors $y \in \mathbb{R}_\infty^m$ are in the tropical kernel of a $0 \times m$ matrix.

Remark 3.2. Note that as in the usual case, the matrix equation $A \odot y \nabla \emptyset$ is equivalent to the system $g \nabla \emptyset$ where $g = (g_1, \dots, g_p)$ is the collection of tropical (linear) m -variate polynomials given by

$$g_i(y) = \bigoplus_{j=1}^m a_{ij} \odot y_j .$$

Now, we define the Macaulay matrix associated to the system f , which plays a crucial role in the determination of the solvability of a polynomial system, with no restriction on the number of equations, nor on the dimension of the resultant variety, as we will see in the next theorem.

Definition 3.3. Given a collection of tropical polynomials $f = (f_1, \dots, f_k)$, we define the *Macaulay matrix* \mathcal{M} of the system as such: the rows of \mathcal{M} are indexed by pairs (i, α) where $1 \leq i \leq k$ and $\alpha \in \mathbb{Z}^n$, the columns of \mathcal{M} are indexed by integer vectors $\beta \in \mathbb{Z}^n$, and for given (i, α) and β , we set the entry $\mathcal{M}_{(i,\alpha),\beta}$ of \mathcal{M} equal to the coefficient of the monomial X^β in the polynomial $X^\alpha f_i(X)$, or $-\infty$ if no such monomial exists.

Given a Macaulay matrix \mathcal{M} as above, a *nonempty* finite subset \mathcal{E} of \mathbb{Z}^n , and a collection $\mathcal{A} = (\mathcal{A}_1, \dots, \mathcal{A}_k)$ of subsets of \mathbb{Z}^n , we denote by $\mathcal{M}_{\mathcal{E}}^{\mathcal{A}}$ the submatrix of \mathcal{M} consisting only of the columns with indices $\beta \in \mathcal{E}$, and the rows indexed by pairs (i, α) where $1 \leq i \leq k$ and $\alpha \in \mathbb{Z}^n$ such that $\alpha + \mathcal{A}_i \subseteq \mathcal{E}$. When the polynomials f_i have their support equal to \mathcal{A}_i , and \mathcal{M} is associated to $f = (f_1, \dots, f_k)$, we simply write $\mathcal{M}_{\mathcal{E}}$ instead of $\mathcal{M}_{\mathcal{E}}^{\mathcal{A}}$.

Remark 3.4. Note that, equivalently, $\mathcal{M}_{\mathcal{E}}$ is the submatrix of \mathcal{M} consisting of the columns with indices $\beta \in \mathcal{E}$, and the rows that have all their finite entries in these columns. Moreover, if \mathcal{E} is nonempty but too small, it might be possible that there are no such row of \mathcal{M} , and thus the set of rows of $\mathcal{M}_{\mathcal{E}}^{\mathcal{A}}$ might be empty, in which case by the convention of the previous definition, all vectors are considered to be in the tropical kernel of $\mathcal{M}_{\mathcal{E}}^{\mathcal{A}}$.

Now, let us denote as previously by $\mathcal{A} = (\mathcal{A}_1, \dots, \mathcal{A}_k)$ a collection of subsets of \mathbb{Z}^n , and for all $1 \leq i \leq k$, let Q_i be the convex hull of \mathcal{A}_i and set $Q := Q_1 + \dots + Q_k$. Take a generic vector $\delta \in V + \mathbb{Z}^n$ where $V \subseteq \mathbb{R}^n$ is the vector space directing the affine hull of Q , and consider the set

$$\mathcal{E} := (Q + \delta) \cap \mathbb{Z}^n .$$

We will refer to sets of this form as *Canny-Emiris subsets* of \mathbb{Z}^n associated to the collection \mathcal{A} . Note that for δ small enough, we always have the inclusion

$$\text{relint}(Q) \cap \mathbb{Z}^n \subseteq \mathcal{E} \subseteq Q \cap \mathbb{Z}^n ,$$

where relint denotes the relative interior.

Now, for a collection $f = (f_1, \dots, f_k)$ of tropical polynomials, we shall consider in particular the collection $\mathcal{A} = (\mathcal{A}_1, \dots, \mathcal{A}_k)$ where for $1 \leq i \leq k$, \mathcal{A}_i is the support of f_i . In that case, the set Q_i is referred to as the *Newton polytope* of f_i , and we shall also refer to Q as the *Newton polytope* of f . Also the Canny-Emiris subsets \mathcal{E} associated to the collection \mathcal{A} are referred to as the *Canny-Emiris sets associated to f* .

The tropical linear system $\mathcal{M}_{\mathcal{E}} \odot y \nabla \mathbb{0}$ will be of interest to us in the resolution of the previous problem. More precisely, we have the following result, which will be proven in Section 3.3.2.

Theorem 3.5 (Sparse tropical Nullstellensatz). *There exists a common root $x \in \mathbb{R}^n$ to the system $f(x) \nabla \mathbb{0}$ if and only if there exists a vector $y \in \mathbb{R}^{\mathcal{E}'}$ in the tropical kernel of the submatrix $\mathcal{M}_{\mathcal{E}'}$ of the Macaulay matrix \mathcal{M} associated to the collection f — i.e. $\mathcal{M}_{\mathcal{E}'} \odot y \nabla \mathbb{0}$ — where \mathcal{E}' is any subset of \mathbb{Z}^n containing a nonempty Canny-Emiris subset \mathcal{E} of \mathbb{Z}^n associated to f .*

Moreover, if $\mathcal{E}' = \mathcal{E}$, these conditions are equivalent to the existence of a vector $y \in \mathbb{R}_{\infty}^{\mathcal{E}} \setminus \{\mathbb{0}\}$ such that $\mathcal{M}_{\mathcal{E}} \odot y \nabla \mathbb{0}$.

When we have no particular information on the supports of the polynomials f_i besides that they are ordinary tropical polynomials with respective degrees d_i , we denote by \mathcal{M}_N the submatrix $\mathcal{M}_{\bar{\mathcal{E}}}$ of \mathcal{M} with $\bar{\mathcal{E}} = N\Delta \cap \mathbb{N}^n$, and $\mathcal{A}_i = d_i\Delta \cap \mathbb{N}^n$, where

$$\Delta := \{\alpha \in \mathbb{R}_{\geq 0}^n : |\alpha| = \alpha_1 + \dots + \alpha_n \leq 1\}$$

denotes the unit simplex. In this case, the integer N is called the *truncation degree* of the Macaulay submatrix \mathcal{M}_N .

More generally, if it is only known, for all $i = 1, \dots, k$, that the support of f_i is included in \mathcal{A}_i (which plays now the role of an *a priori* support), then one shall consider a bigger set

$$\bar{\mathcal{E}} := Q \cap \mathbb{Z}^n ,$$

where Q is defined using the collection $\mathcal{A} = (\mathcal{A}_1, \dots, \mathcal{A}_k)$. Recall that for δ small enough $\mathcal{E} \subseteq \bar{\mathcal{E}}$. In that case, one has the following theorem, in which we consider the matrices $\mathcal{M}_{\bar{\mathcal{E}}}$ with $\mathcal{E}' \supseteq \bar{\mathcal{E}}$.

Theorem 3.6 (Nullstellensatz for sparse Tropical Polynomial Systems with *a priori* supports). *There exists a common root $x \in \mathbb{R}^n$ to the system $f(x) \nabla \mathbb{0}$ if and only if there exists a vector $y \in \mathbb{R}^{\mathcal{E}'}$ in the tropical kernel of the submatrix $\mathcal{M}_{\bar{\mathcal{E}}}$ of the Macaulay matrix \mathcal{M} associated to the collection f , where \mathcal{E}' is any subset of \mathbb{Z}^n containing $\bar{\mathcal{E}}$ and \mathcal{A} is a collection of *a priori* supports of the f_i .*

Moreover, when the Newton polytope of f has same dimension as Q , one can replace $\bar{\mathcal{E}}$ by any nonempty Canny-Emiris set \mathcal{E} associated to \mathcal{A} .

Proof. The inclusions $\mathcal{E} \subseteq \mathcal{E}'$ and $\text{supp}(f_i) \subseteq \mathcal{A}_i$ for all $1 \leq i \leq k$ imply that the matrix $\mathcal{M}_{\mathcal{E}}$ is a submatrix of the matrix $\mathcal{M}_{\mathcal{E}'}$. More precisely, if (i, α) is the index of a row of $\mathcal{M}_{\mathcal{E}}$, then this indicates that the support of polynomial $x^\alpha f_i$ is included in \mathcal{E} , and therefore

$$\alpha \in \text{conv} \left(\sum_{1 \leq j \neq i \leq n} \text{supp}(f_j) \right) \subseteq \text{conv} \left(\sum_{1 \leq j \neq i \leq n} \mathcal{A}_j \right) ,$$

which shows that (i, α) is also the index of a row of the matrix $\mathcal{M}_{\bar{\mathcal{E}}}$. The theorem then follows directly from Theorem 3.5 and from the latter remark. \square

When $f = (f_1, \dots, f_k)$ is a collection of ordinary tropical polynomials f_i with respective degree d_i and the matrix \mathcal{M}_N is defined as above, applying Theorem 3.6 with $\mathcal{A}_i = d_i\Delta \cap \mathbb{N}^n$, we deduce the following result.

Corollary 3.7. *There exists a common root $x \in \mathbb{R}^n$ to the system $f(x) \nabla \mathbb{0}$ if and only if there exists a vector $y \in \mathbb{R}^{\mathcal{E}'}$ such that $\mathcal{M}_N \odot y \nabla \mathbb{0}$, where $\mathcal{E}' = N\Delta \cap \mathbb{N}^n$ and $N \geq d_1 + \dots + d_k$. Moreover, when the Newton polytope of f has full dimension, one can replace the above lower bound on N by $N \geq d_1 + \dots + d_k - n$.*

Proof. This result is obtained by applying Theorem 3.6 with $\mathcal{A}_i = d_i\Delta \cap \mathbb{N}^n$, and $\mathcal{E}' = N\Delta \cap \mathbb{N}^n$, since $\bar{\mathcal{E}} = (d_1 + \dots + d_k)\Delta \cap \mathbb{N}^n \subseteq \mathcal{E}'$. \square

Remark 3.8. This improves on Grigoriev and Podolskii's Tropical Dual Nullstellensatz from [GP18, Theorem 3.3 (i)], which requires $N \geq (n+2)(d_1 + \dots + d_k)$. Moreover, under the condition that the Newton polytope of f is full-dimensional, and when $k = n+1$, we obtain the classical Macaulay bound $N \geq d_1 + \dots + d_{n+1} - n$.

In [GP18, §4.6], the authors provide for all degree $d \geq 2$ and all number $n \geq 2$ of variables the following family of $n + 1$ polynomials of degree at most d

$$\begin{aligned} f_1 &= 0 \oplus 0x_1 \\ f_i &= 0x_{i-1}^d \oplus 0x_i, \quad 2 \leq i \leq n \\ f_{n+1} &= 0 \oplus 1x_n \end{aligned}$$

and show that the linearized system with truncation degree $N = (n - 1)(d - 1)$

$$\mathcal{M}_{(n-1)(d-1)} \odot y \nabla 0$$

has a solution in $\mathbb{R}^{\binom{N+n}{n}}$ while the polynomial system does not have a solution in \mathbb{R}^n , showing that our improved bound is tight, as in this example, our bound yields

$$d_1 + \cdots + d_{n+1} - n = 1 + (n - 1)d + 1 - n = (n - 1)(d - 1) + 1 .$$

The previous system is inspired by an example by Masser and Philippon (see [Bro87, §1] and also [GV01]) of a system of n degree d polynomials in n variables for which the minimal truncation degree needed in Hilbert's Nullstellensatz is bounded below by $(d - 1)d^{n-1}$. Hence, in the classical case, the truncation degree appearing in the Nullstellensatz may be exponential in n , whereas in the tropical case, it is bounded in terms of the *sum* of degrees of the polynomials.

However, in non-square cases, the lower bound in Corollary 3.7 is not necessarily optimal.

For instance, in the case of $k > n + 1$ degree one polynomials, for all $1 \leq i \leq k$, the tropical polynomial function associated to f_i is simply a tropical affine function

$$(x_1, \dots, x_n) \mapsto f_{i0} \oplus f_{i1}x_1 \oplus \cdots \oplus f_{in}x_n ,$$

and thus $x = (x_1, \dots, x_n) \in \mathbb{R}^n$ is a common root of f_1, \dots, f_k if and only if

$$\begin{pmatrix} f_{10} & f_{11} & \cdots & f_{1n} \\ \vdots & \vdots & & \vdots \\ f_{k0} & f_{k1} & \cdots & f_{kn} \end{pmatrix} \odot \begin{pmatrix} 1 \\ x_1 \\ \vdots \\ x_n \end{pmatrix} \nabla 0 ,$$

and thus the collection of polynomials f has a common root if and only if the matrix

$$(f_{ij})_{\substack{1 \leq i \leq k \\ 0 \leq j \leq n}}$$

has an element $(y_0, \dots, y_n) \in \mathbb{R}^{n+1}$ in its right null space, in which case $(y_1 - y_0, \dots, y_n - y_0) \in \mathbb{R}^n$ is a common root of f . But this matrix corresponds to the submatrix of the Macaulay matrix \mathcal{M} obtained by taking $N = 1$ as the truncation degree for the Macaulay matrix, while the previous bound gives $N = d_1 + \cdots + d_k - n = k - n$.

Remark 3.9. Although Theorem 3.5 only deals with the toric case, *i.e.* only accounts for solutions in $x \in \mathbb{R}^n$, one can still use it to deal with the non-toric case and find solutions in $x \in \mathbb{R}_\infty^n$: for all subset I of $\{1, \dots, n\}$, if $x \in \mathbb{R}_\infty^n$ is a solution of a tropical polynomial system such that

$$\begin{cases} x_i \neq 0 & \text{for all } i \in I \\ x_i = 0 & \text{for all } i \in J := \{1, \dots, n\} \setminus I , \end{cases}$$

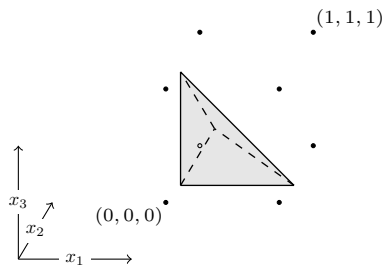
then $x_I := (x_i)_{i \in I} \in \mathbb{R}^I$ is a root of the tropical polynomial system obtained by removing all the monomials in which the variables X_j for $j \in J$ appear.

Note however that in [GP18, Theorems 3.3 (ii) and 4.20], it is shown that the linearization remains valid with $-\infty$ but at the price of an exponential blow up of the truncation degree, which becomes $N = 2(n + 2)^2 k (4d)^{\min(n, k) + 2}$, and thus for practical applications, enumerating the 2^n possible supports of a solution leads to a faster method.

Remark 3.10. The assumption that the considered Canny-Emiris set \mathcal{E} is nonempty is needed because it is possible to find systems both with and without a common root for which the empty set is a Canny-Emiris subset associated to the system. For instance for $n = 3$ and $k = 2$, consider the system

$$(S_1) : \begin{cases} f_1 &= 0 \oplus 0x_1 \oplus 0x_2 \oplus 0x_3 \\ f_2 &= 0 . \end{cases}$$

Figure 1: The polytope $Q + \delta$ with $\varepsilon = 0.1$ for the system (S_1) .



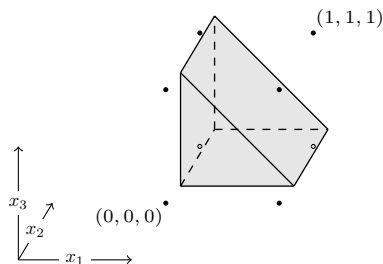
In this case, Q is simply the tetrahedron with vertices $(0, 0, 0)$, $(0, 0, 1)$, $(0, 1, 0)$ and $(1, 0, 0)$. Now if we take $\delta = (\varepsilon, \varepsilon, \varepsilon)$ for ε small enough, we obtain a Canny-Emiris set $\mathcal{E} := (Q + \delta) \cap \mathbb{Z}^n$ which is empty, as illustrated in Figure 1. Of course, the system (S_1) does not have a common root since f_2 is a constant.

Now, still for $n = 3$ and $k = 2$, consider the system

$$(S_2) : \begin{cases} f_1 &= 0 \oplus 0x_1 \oplus 0x_3 \\ f_2 &= 0 \oplus 0x_2 \end{cases} .$$

Now, Q is the triangular prism with vertices $(0, 0, 0)$, $(1, 0, 0)$, $(0, 0, 1)$, $(0, 1, 0)$, $(1, 1, 0)$ and $(0, 1, 1)$. Once again, if we take $\delta = (\varepsilon, \varepsilon, \varepsilon)$ for ε small enough, we obtain a Canny-Emiris set which is empty, as illustrated in Figure 2. This time however, the system (S_2) has a common root, namely $(0, 0, 0)$.

Figure 2: The polytope $Q + \delta$ with $\varepsilon = 0.1$ for the system (S_2) .



Therefore, it is *a priori* not possible to conclude if the considered Canny-Emiris set is taken empty, although excluding the case where some of the polynomials of the system are monomials is rather degenerate. Excluding this particular case, one can wonder if it is then possible to reach a conclusion in the case of systems where there exists a empty associated Canny-Emiris set.

3.2 Preliminary results

In this section, we state and prove a number of lemmas which will be used in order to prove Theorem 3.5.

3.2.1 Nonsingular and diagonally dominant tropical matrices

We first recall the definition of nonsingularity and diagonal dominance for tropical matrices.

Definition 3.11. Let $A = (a_{ij})_{(i,j) \in [p] \times [m]}$ be a $p \times m$ tropical matrix. Then the matrix A is said to be *tropically nonsingular* whenever the only solution to the equation $A \odot y \nabla \mathbb{0}$ of unknown $y \in \mathbb{R}_\infty^m$ is $y = \mathbb{0}$.

Remark 3.12. In the case where $A \in \mathcal{M}_d(\mathbb{R}_\infty)$ is a square matrix, one can consider its *tropical determinant* $\text{tdet}(A)$ which is given by

$$\text{tdet}(A) = \max_{\sigma \in \mathfrak{S}_d} a_{1\sigma(1)} + \cdots + a_{d\sigma(d)} .$$

If the maximum in the previous expression is attained exactly once, hence if $\text{tdet}(A) \not\propto \mathbb{0}$, then as a direct consequence of Corollary 6.12 of [AGG09], the only possible solution to the equation $A \odot y \nabla \mathbb{0}$ is $y = \mathbb{0}$, *i.e.* the matrix A is tropically nonsingular.

Definition 3.13. A matrix $A = (a_{ij})_{(i,j) \in [d] \times [d]} \in \mathcal{M}_d(\mathbb{R}_\infty)$ is said to be *weakly diagonally dominant* in the tropical sense whenever we have the inequalities

$$a_{ii} \geq a_{ij} \quad \text{for all } 1 \leq i, j \leq d \text{ such that } i \neq j ,$$

and we say that it is *diagonally dominant* if these inequalities are strict.

A notable fact about diagonally dominant tropical matrices, which will play a crucial role in the proof of Theorem 3.5, is the fact that similarly to classical diagonally dominant matrices, these matrices are non-singular. More precisely, we have the following result.

Lemma 3.14. *Let $A \in \mathcal{M}_d(\mathbb{R}_\infty) = (a_{ij})_{(i,j) \in [d] \times [d]}$ be a diagonally dominant tropical matrix. Then A is tropically nonsingular.*

Proof. Let $y = (y_1, \dots, y_d) \in \mathbb{R}_\infty^d$ be such that $A \odot y \nabla \mathbb{0}$, and consider $1 \leq i \leq d$ such that $y_i = \max_{1 \leq j \leq d} y_j$. Then from the relation $A \odot y \nabla \mathbb{0}$, it follows in particular that the maximum in the expression

$$\max_{1 \leq j \leq d} (a_{ij} + y_j)$$

is attained twice, but since for all $1 \leq j \leq d$, we have

$$a_{ii} > a_{ij} \quad \text{and} \quad y_i \geq y_j \quad ,$$

the only possible way such that the maximum in the previous expression is attained twice is that

$$y_i = -\infty$$

and thus

$$y = \mathbb{0} \quad .$$

□

Remark 3.15. Since A is diagonally dominant, it means that the maximum in the expression

$$\text{tdet}(A) = \max_{\sigma \in \mathfrak{S}_d} a_{1\sigma(1)} + \dots + a_{d\sigma(d)}$$

is attained exactly once, hence $\text{tdet}(A) \not\propto \mathbb{0}$, and thus by the previous remark, A is tropically nonsingular.

Finally we will also make use of the following two lemmas.

Lemma 3.16. *Let $A = (a_{ij})_{(i,j) \in [p] \times [m]}$ be a $p \times m$ tropical matrix. Fix for $1 \leq j \leq m$, $\varepsilon_j \in \mathbb{R}$, and set $\tilde{A} = (\tilde{a}_{ij})_{(i,j) \in [p] \times [m]} \in \mathcal{M}_{p,m}(\mathbb{R}_\infty)$ with $\tilde{a}_{ij} = a_{ij} + \varepsilon_j$ for all $1 \leq i \leq p$ and $1 \leq j \leq m$. Then A is tropically nonsingular if and only if \tilde{A} is tropically nonsingular.*

Proof. Assume that A is nonsingular, and let $\tilde{y} = (\tilde{y}_j)_{1 \leq j \leq m} \in \mathbb{R}_\infty^m$ be such that $\tilde{A} \odot \tilde{y} \nabla \mathbb{0}$. Then, this means that for all $1 \leq i \leq p$, the maximum in the expression

$$\max_{1 \leq j \leq m} (\tilde{a}_{ij} + \tilde{y}_j) = \max_{1 \leq j \leq m} (a_{ij} + (\tilde{y}_j + \varepsilon_j))$$

is attained twice. In other words, setting $y = (\tilde{y}_j + \varepsilon_j)_{1 \leq j \leq m}$, we obtain that $A \odot y \nabla \mathbb{0}$. Therefore, by nonsingularity of A , we must have $y = \mathbb{0}$, and since ε_j is finite for all $1 \leq j \leq m$, this implies that $\tilde{y} = \mathbb{0}$, hence \tilde{A} is tropically nonsingular.

The converse implication is obtained by swapping A and \tilde{A} and changing $(\varepsilon_j)_{1 \leq j \leq m}$ to $(-\varepsilon_j)_{1 \leq j \leq m}$. □

Lemma 3.17. *Let A be a $p \times m$ tropical matrix, and assume that A can be written by block as a lower-triangular matrix*

$$A = \begin{pmatrix} A^{(d)} & \mathbb{0} \\ * & * \end{pmatrix}$$

with $A^{(d)}$ a $d \times d$ square submatrix. Moreover, assume that $A^{(d)}$ is tropically nonsingular. Then the equation $A \odot y \nabla \mathbb{0}$ of unknown y has no solution in \mathbb{R}^m .

Proof. Let $y = (y_j)_{1 \leq j \leq m} \in \mathbb{R}_\infty^m$ be such that $A \odot y \nabla \mathbb{0}$. Then by setting $y^{(d)} = (y_j)_{1 \leq j \leq d} \in \mathbb{R}_\infty^d$, we obtain in particular, by looking at the first d rows of the product $A \odot y$, that $A^{(d)} \odot y^{(d)} \nabla \mathbb{0}$, which implies by nonsingularity of $A^{(d)}$ that $y^{(d)} = \mathbb{0}$ and thus y does not belong to \mathbb{R}^m . □

3.2.2 Generalities on sup-convolution and Minkowski sums

In order to write the proof of Theorem 3.5, we also need to introduce the following definition, which simply corresponds to the tropical equivalent of the convolution product. The *support* of a function $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\pm\infty\}$ is defined by $\text{supp}(f) = \overline{\{x \in \mathbb{R}^n : f(x) > -\infty\}}$. The *hypograph* of h is the set $\text{hypo}(h) = \{(x, t) \in \mathbb{R}^n \times \mathbb{R} : t \leq h(x)\}$.

Definition 3.18. The *Minkowski sum* of two subsets $E, F \subset \mathbb{R}^n$ is defined as $E + F = \{x + y : x \in E, y \in F\}$. The *sup-convolution* is the binary operator \square defined on the set of functions from \mathbb{R}^n to $\mathbb{R} \cup \{\pm\infty\}$ by

$$f \square g(x) = \sup_{y+z=x} f(y) + g(z) ,$$

with the convention $(-\infty) + (+\infty) = -\infty$.

In particular, if f and g are upper semicontinuous, take values in \mathbb{R}_∞ , and have compact support, then, the supremum in the expression of $f \square g(x)$ is achieved and $f \square g$ also has compact support. Recall that the operations of sup-convolution and Minkowski sum are commutative and associative, and that we have the following immediate properties:

Property 3.19. Let E_1, \dots, E_ℓ be a collection of subsets of \mathbb{R}^n and let h_1, \dots, h_ℓ be a family of upper semi-continuous functions with compact support from \mathbb{R}^n to $\mathbb{R} \cup \{\pm\infty\}$. Let $E = E_1 + \dots + E_\ell$ and $h = h_1 \square \dots \square h_\ell$. Then,

- (a) $E = \{x_1 + \dots + x_\ell : x_i \in E_i \text{ for all } 1 \leq i \leq \ell\}$;
- (b) For all $q \in \mathbb{R}^n$, $h(q) = \max_{q_1 + \dots + q_\ell = q} h_1(q_1) + \dots + h_\ell(q_\ell)$;
- (c) $\text{hypo}(h) = \text{hypo}(h_1) + \dots + \text{hypo}(h_\ell)$ and $\text{supp}(h) = \text{supp}(h_1) + \dots + \text{supp}(h_\ell)$;
- (d) For $1 \leq i \leq \ell$, let $\widehat{h}_i := h_1 \square \dots \square h_{i-1} \square h_{i+1} \square \dots \square h_\ell$. Then we have $h_i \square \widehat{h}_i = h$.

Definition 3.20. The *normal cone* $N_x(P)$ to a polyhedron $P \subset \mathbb{R}^n$ at a point $x \in P$ is defined by

$$N_x(P) = \{y \in \mathbb{R}^n : \langle y, z - x \rangle \leq 0, \forall z \in P\} .$$

The *normal cone* $N_F(P)$ to P at a face F of P is defined as $N_x(P)$ where x is an arbitrary point in the relative interior of F — this object is well-defined because you can easily check that two points in the relative interior of the same face of P yield the same normal fan. Moreover, the collection

$$\mathcal{N}(P) = \{N_F(P) : F \text{ face of } P\}$$

of normal cones at every face of P is called the *normal fan* of P .

Remark 3.21. Note that the normal fan of a polyhedron $P \subseteq \mathbb{R}^n$ is the same as the normal fan of any translation $P + b$ of P . More precisely, if $b \in \mathbb{R}^n$, then the map $F \mapsto F + b$ gives us a correspondance between the faces of P and the faces of $P + b$, and moreover we can easily show that $N_{F+b}(P+b) = N_F(P)$

We recall the correspondance between the set $\mathcal{F}(P)$ of faces of a polyhedron P and its normal fan $\mathcal{N}(P)$.

Proposition 3.22. *Let P be a polyhedron in \mathbb{R}^n . Then the map*

$$\begin{array}{ccc} \mathcal{F}(P) & \longrightarrow & \mathcal{N}(P) \\ F & \longmapsto & N_F(P) \end{array}$$

is a poset anti-isomorphism from the lattice of faces of P to the lattice of normal cones of P . In particular, we have $\dim(F) + \dim(N_F(P)) = n$.

Proof. This is a quite standard result which is stated, amongst others, in Section 7 of [Tho06]. □

We deduce the following corollary from the previous proposition, which will help us deal with the case where the polyhedron we are working with is not full-dimensional.

Corollary 3.23. *Let P be a polyhedron in \mathbb{R}^n and let W be the vector subspace of \mathbb{R}^n directing the affine hull of P . Then*

$$\dim(N_F(P) \cap W) = \dim(P) - \dim(F) .$$

Proof. Since translating a polyhedron does not affect its normal fan, we can assume without loss of generality that P is included in W . Then we notice that for any $x \in P$,

$$N_x(P) \cap W = \{y \in W : \langle y, z - x \rangle \leq 0, \forall z \in P\} ,$$

This means that $N_x(P) \cap W$ corresponds to the normal cone at point x of the polyhedron P seen as a full dimensional polyhedron of W . We can then apply the previous proposition and we obtain that

$$\dim(F) + \dim(N_F(P) \cap W) = \dim(W) = \dim(P) .$$

□

Definition 3.24. A concave function $\mathbb{R}^n \rightarrow \mathbb{R}_\infty$ is said to be *polyhedral* if its hypograph is a (closed) polyhedron. We say that a convex subset F of $\mathbb{R}^n \times \mathbb{R}$ is *vertical* if the orthogonal of the vector space directing the affine hull of F set is included in $\mathbb{R}^n \times \{0\}$.

Example 3.25. The main example of concave polyhedral function that will be of interest in this paper are the function obtained by taking the concavification of the coefficient map $\omega : \mathbb{R}^n \rightarrow \mathbb{R}_\infty$, defined by

$$\omega(\alpha) = \begin{cases} f_\alpha & \text{if } \alpha \in \text{supp}(f), \\ 0 & \text{otherwise.} \end{cases}$$

of a tropical polynomial f . These functions satisfy in particular the property that the projection of the singularities of their graph onto $\mathbb{R}^n \times \{0\}$ is a rational polyhedral complex. Moreover, the projection of vertices of their hypograph are elements of $\text{supp}(f)$.

For all functions $h : \mathbb{R}^n \rightarrow \mathbb{R}_\infty$, and for all $x \in \mathbb{R}^n$, we set

$$\mathcal{C}(x, h) := \arg \max_{q \in \mathbb{R}^n} (\langle q, x \rangle + h(q)) \quad \text{and} \quad \mathcal{F}(x, h) := \{(q, h(q)) : q \in \mathcal{C}(x, h)\} .$$

We make the following crucial observations.

Observation 3.26.

- (a) If h is a concave polyhedral function nonidentically $-\infty$, then $\mathcal{F}(x, h)$ is the face of the hypograph of h , which is obtained as the intersection of this hypograph with a supporting hyperplane of outer normal vector $(x, 1)$. In particular, this face is non-vertical, and hence it is a proper face of $\text{hypo}(h)$, i.e. $\mathcal{F}(x, h) \subsetneq \text{hypo}(h)$.
- (b) If h is the concavification of the coefficient map ω as in Example 3.25, then $\mathcal{C}(x, h)$ is the convex hull of

$$\mathcal{C}(x, \omega) = \arg \max_{\alpha \in \mathbb{Z}^n} (f_\alpha + \langle x, \alpha \rangle) ,$$

which coincides with the intersection of $\mathcal{C}(x, h)$ with the elements $\alpha \in \text{supp}(f)$ such that $h(\alpha) = f_\alpha$. Then, $\mathcal{F}(x, h)$ is the convex hull of $\mathcal{F}(x, \omega)$. We also have that $\mathcal{F}(x, h)$ is the convex hull of its intersection with the set of vertices of $\text{hypo}(h)$.

- (c) For such a function h , if F is a non-vertical face of $\text{hypo}(h)$, then $F = \mathcal{F}(x, h)$ if and only if $(x, 1)$ is in the relative interior of $N_F(\text{hypo}(h))$. In particular, if F is a facet of $\text{hypo}(h)$, then there exists a unique vector $x \in \mathbb{R}^n$ such that $F = \mathcal{F}(x, h)$ and x is in the vector space directing the affine hull of $Q := \text{supp}(h)$. Indeed, from Corollary 3.23, we have $\dim(N_F(\text{hypo}(h)) \cap W) = (n + 1) - n = 1$ where $W = V \times \mathbb{R}$ is the vector space directing the affine hull of $\text{hypo}(h)$, and thus if $(x, 1)$ and $(x', 1)$ are both in the half-line $N_F(\text{hypo}(h)) \cap W$, then it follows that $x' = x$.

We now state a useful lemma on convex polyhedra.

Lemma 3.27. *Let P_1, \dots, P_ℓ be a finite collection of convex polyhedra, and denote by P their Minkowski sum $P_1 + \dots + P_\ell$. Let F be a face of P and let y be in the relative interior of $N_F(P)$. If $p = p_1 + \dots + p_\ell \in F$ with $p_i \in P_i$ for all $1 \leq i \leq \ell$, then for all $1 \leq i \leq \ell$, $y \in N_{p_i}(P_i)$, i.e. $p_i \in \arg \max_{p'_i \in P_i} \langle p'_i, y \rangle$.*

Proof. As y being in the relative interior of $N_F(P)$ is equivalent to the equality $F = \arg \max_{p' \in P} \langle p', y \rangle$, then one has

$$\begin{aligned} \langle p_1, y \rangle + \dots + \langle p_\ell, y \rangle &= \langle p, y \rangle \\ &= \max_{p' \in P} \langle p', y \rangle \\ &= \max_{p'_1 \in P_1, \dots, p'_\ell \in P_\ell} (\langle p'_1, y \rangle + \dots + \langle p'_\ell, y \rangle) \\ &= \max_{p'_1 \in P_1} \langle p'_1, y \rangle + \dots + \max_{p'_\ell \in P_\ell} \langle p'_\ell, y \rangle , \end{aligned}$$

therefore $\langle p_i, y \rangle = \max_{p'_i \in P_i} \langle p'_i, y \rangle$ for all $1 \leq i \leq \ell$, i.e. $y \in N_{p_i}(P_i)$ for all $1 \leq i \leq \ell$. □

Remark 3.28. In particular, from the previous lemma, by setting $F_i := \arg \max_{p'_i \in P_i} \langle p'_i, y \rangle$, we obtain that the decomposition of F as a sum of faces of the P_i is precisely $F = F_1 + \dots + F_\ell$.

The following result is a direct corollary of the previous lemma.

Corollary 3.29. *Let h_1, \dots, h_ℓ denote concave non-identically $-\infty$ polyhedral functions from \mathbb{R}^n to \mathbb{R}_∞ . Consider the sup-convolution*

$$h = h_1 \square \dots \square h_\ell .$$

Let F be a non-vertical face of $\text{hypo}(h)$, and let $x \in \mathbb{R}^n$ be such that $(x, 1)$ is in the relative interior of the normal cone of $\text{hypo}(h)$ at this face. Consider a point $(q, \lambda) \in F$ such that

$$(q, \lambda) = (q_1, \lambda_1) + \dots + (q_\ell, \lambda_\ell) \quad \text{with} \quad (q_i, \lambda_i) \in \text{hypo}(h_i) \text{ for all } 1 \leq i \leq \ell .$$

Then for all $1 \leq i \leq \ell$, $(q_i, \lambda_i) \in \mathcal{F}(x, h_i)$.

In particular,

$$F = \mathcal{F}(x, h) = \mathcal{F}(x, h_1) + \dots + \mathcal{F}(x, h_\ell)$$

and moreover, for all $1 \leq i \leq \ell$, $(x, 1)$ is in the normal cone of $\text{hypo}(h_i)$ at point (q_i, λ_i) .

Proof. We apply the previous lemma for $P_i = \text{hypo}(h_i)$ for all $1 \leq i \leq \ell$ and $P = \text{hypo}(h)$. Since $(x, 1)$ is in the relative interior of $N_F(P)$, then we have $F = \mathcal{F}(x, h)$ by definition, and moreover from the previous lemma, we have $(x, 1) \in N_{(q_i, \lambda_i)}(P_i)$, or equivalently $(q_i, \lambda_i) \in \mathcal{F}(x, h_i)$ for all $1 \leq i \leq \ell$. The remainder follows immediately. \square

3.3 Proving the Tropical Nullstellensatz

3.3.1 The Canny-Emiris construction

Here, we assume given the polynomials f_1, \dots, f_k , a nonempty Canny-Emiris subset \mathcal{E} associated to the system f , and a subset \mathcal{E}' of \mathbb{Z}^n containing \mathcal{E} . We can now describe the construction of Canny and Emiris from [CE93] and [Emi05], which was generalized by Sturmfels in part 3 of [Stu94], which we will apply to the system $f = (f_1, \dots, f_k)$ in the particular case where the polynomials f_i do not share a common root. In particular, contrary to the previous constructions, we do not assume that the coefficients satisfy any genericity condition.

First of all, let us settle some notations for the rest of this section. For all $1 \leq i \leq k$, let \mathcal{A}_i denote the support of f_i , Q_i the convex hull of \mathcal{A}_i , $Q := Q_1 + \dots + Q_k$. The Canny-Emiris subset \mathcal{E} of \mathbb{Z}^n is such that $\mathcal{E} := \mathbb{Z}^n \cap (Q + \delta)$, for some generic vector $\delta \in V + \mathbb{Z}^n$, where $V \subseteq \mathbb{R}^n$ is the vector space directing the affine hull of Q . Let $\omega = (\omega_i)_{1 \leq i \leq k}$ be the collection of coefficient maps of the f_i , that is defined by

$$\omega_i(\alpha) = \begin{cases} f_{i,\alpha} & \text{if } \alpha \in \mathcal{A}_i \\ 0 & \text{else,} \end{cases}$$

and let $h_i : \mathbb{R}^n \rightarrow \mathbb{R}_\infty$ denote the concave hull of ω_i . Let $Q_{i,\omega} := \text{hypo}(h_i)$ (this is referred to by Grigoriev and Podolskii in [GP18] as the *extended Newton polytope* of f_i) and $Q_\omega := Q_{1,\omega} + \dots + Q_{k,\omega} = \text{hypo}(h)$ with $h := h_1 \square \dots \square h_k$.

Observation 3.30. Note that for all $1 \leq i \leq k$, by construction of the maps h_i , we have

$$h_i(\alpha) \geq f_{i,\alpha} \quad \forall \alpha \in \mathcal{A}_i ,$$

with equality whenever the monomial $f_{i,\alpha} X^\alpha$ is *essential* in f_i , that is whenever there exists a point $x \in \mathbb{R}^n$ at which the monomial of exponent α is the only one achieving the maximum over all the monomials of f_i . Equivalently, the monomial $f_{i,\alpha} X^\alpha$ of f_i is essential if, and only if, the point $(\alpha, f_{i,\alpha})$ is a vertex of $\text{hypo}(h_i)$. Note also that if $(q, h(q))$ is an extreme point of Q_ω , then $h(q)$ corresponds to the coefficient of X^q in the product $f_1 \dots f_k$. \diamond

Now let us apply the Canny-Emiris construction, to the collection ω of maps — note that as opposed to what is done in [Stu94], ω is given and might not be generic. The projection of Q_ω onto Q induces a mixed coherent subdivision Δ_ω of Q , given by the points of non-differentiability of h . The following observation follows readily from the genericity of δ .

Observation 3.31. Given $p \in \mathcal{E}$, the couple $(p - \delta, h(p - \delta))$ lies in the relative interior of a unique non-vertical facet F of Q_ω , or equivalently, $p - \delta$ lies in the relative interior of the associated cell C of Q , obtained as the image of F by the projection mapping. Moreover, there is a unique $x \in V$ such that $F = \mathcal{F}(x, h)$ and $C = \mathcal{C}(x, h)$. \diamond

We construct a matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$, whose rows are indexed by \mathcal{E} and whose columns are indexed by \mathcal{E}' . We proceed as follows. First, for $p \in \mathcal{E}$, consider the associated $x \in V \subseteq \mathbb{R}^n$, and for all $1 \leq i \leq k$, let F_i denote the face $\mathcal{F}(x, h_i)$ of $Q_{i,\omega}$, and C_i the cell $\mathcal{C}(x, h_i)$ of the associated subdivision of Q_i . Then by Corollary 3.29, we have

$$F = F_1 + \cdots + F_k \quad \text{and} \quad C = C_1 + \cdots + C_k .$$

Moreover, under the assumption that the tropical polynomials f_1, \dots, f_k do not share a common root, we know that at least one of the C_i is a singleton, and we let j be the maximal index such that $C_j = \{a_j\}$ is a singleton. We call the couple (j, a_j) the *row content* of p . Note that this row content only depends on the cell C containing $p - \delta$ in its interior. Then since $p - \delta \in C$, thus it can be written as

$$p - \delta = q_1 + \cdots + q_j + \cdots + q_k \quad \text{with} \quad \begin{cases} q_i \in C_i & \text{for all } 1 \leq i \neq j \leq k \\ q_j = a_j . \end{cases} \quad (3)$$

We then construct the matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$ as follows : for every $p \in \mathcal{E}$, we associate to p its row content (j, a_j) , and then we put the row $(j, p - a_j)$ of the Canny-Emiris submatrix $\mathcal{M}_{\mathcal{E}'}$ in $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$, whose coefficients are given by the coefficients of the polynomial $X^{p-a_j} f_j(X)$. Note that all exponents appearing in the support of $X^{p-a_j} f_j(X)$ belong to \mathcal{E} and thus to \mathcal{E}' . Indeed, if $a'_j \in \mathcal{A}_j$, then

$$\begin{aligned} p - a_j + a'_j &= \delta + q_1 + \cdots + q_j + \cdots + q_k - a_j + a'_j \\ &= \delta + q_1 + \cdots + a'_j + \cdots + q_k \in (Q + \delta) \cap \mathbb{Z}^n = \mathcal{E} \subseteq \mathcal{E}' . \end{aligned}$$

Thus, we end up with a matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}'} = (m_{pp'})_{(p,p') \in \mathcal{E} \times \mathcal{E}'}$ indexed by $\mathcal{E} \times \mathcal{E}'$. We shall show in the proof of Theorem 3.5 that this matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$ is actually a submatrix of $\mathcal{M}_{\mathcal{E}'}$. Also notice that by grouping together the columns of $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$ indexed by \mathcal{E} and by $\mathcal{E}' \setminus \mathcal{E}$, the matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$ can be written as a block matrix

$$\mathcal{M}_{\mathcal{E}\mathcal{E}'} = (\mathcal{M}_{\mathcal{E}\mathcal{E}} \quad \mathbb{0})$$

where $\mathcal{M}_{\mathcal{E}\mathcal{E}} = (m_{pp'})_{(p,p') \in \mathcal{E} \times \mathcal{E}}$ is a square matrix indexed by $\mathcal{E} \times \mathcal{E}$, which we shall show is a submatrix of $\mathcal{M}_{\mathcal{E}}$.

3.3.2 The proof of Theorem 3.5

In order to prove Theorem 3.5, we will make use of the following lemma.

Lemma 3.32. *Consider h and h_1, \dots, h_k as defined as in Section 3.3.1, and moreover for all $1 \leq j \leq k$, set $\widehat{h}_j = h_1 \square \cdots \square h_{j-1} \square h_{j+1} \square \cdots \square h_k$. Let $p \in \mathcal{E}$ and let (j, a_j) be its row content. Then for all $p' \in \mathcal{E}$ and $a'_j \in \mathbb{Z}^n$ such that $p' = p - a_j + a'_j$, we have*

$$h(p' - \delta) \geq h_j(a'_j) + \widehat{h}_j(p - \delta - a_j), \quad (4)$$

with equality if and only if $p' = p$ and $a'_j = a_j$.

Proof. Since $p' - \delta = a'_j + (p - \delta - a_j)$, the inequality (4) follows from the definition of sup-convolution, noting that $h = h_j \square \widehat{h}_j$.

We next show that the equality holds if $p' = p$, which entails that $a'_j = a_j$. Indeed, since

$$(p - \delta, h(p - \delta)) \in Q_\omega = \text{hypo}(h_j) + \text{hypo}(\widehat{h}_j) ,$$

we can write

$$(p - \delta, h(p - \delta)) = (q_j, \lambda_j) + (\widehat{q}_j, \widehat{\lambda}_j) \quad (5)$$

with $(q_j, \lambda_j) \in \text{hypo}(h_j)$ and $(\widehat{q}_j, \widehat{\lambda}_j) \in \text{hypo}(\widehat{h}_j)$. Then by Corollary 3.29, defining x as in Observation 3.31, it follows that $(q_j, \lambda_j) \in \mathcal{F}(x, h_j)$ and $(\widehat{q}_j, \widehat{\lambda}_j) \in \mathcal{F}(x, \widehat{h}_j)$. In particular, since (j, a_j) is the row content of p , we have $\mathcal{F}(x, h_j) = \{(a_j, h_j(a_j))\}$. Hence,

$$(q_j, \lambda_j) = (a_j, h_j(a_j)) ,$$

and therefore we deduce from (5) that

$$(\widehat{q}_j, \widehat{\lambda}_j) = (p - \delta - a_j, \widehat{h}_j(p - \delta - a_j)) ,$$

hence the equality

$$h(p - \delta) = h_j(a_j) + \widehat{h}_j(p - \delta - a_j) . \quad (6)$$

We now show that (4) is strict whenever $p \neq p'$. Indeed, assume that the equality is achieved. Then this implies that

$$(p' - \delta, h(p' - \delta)) = (a'_j, h_j(a'_j)) + (p - \delta - a_j, \widehat{h}_j(p - \delta - a_j)) .$$

Now consider $x' \in \mathbb{R}^n$ such that $F' = \mathcal{F}(x', h)$ is the facet in the interior of which $(p' - \delta, h(p' - \delta))$ lies. Then from Corollary 3.29, we have

$$(a'_j, h_j(a'_j)) \in \mathcal{F}(x', h_j) \quad \text{and} \quad (p - \delta - a_j, \widehat{h}_j(p - \delta - a_j)) \in \mathcal{F}(x', \widehat{h}_j) .$$

However, we also know from equality (6) and Corollary 3.29 that

$$(p - \delta - a_j, \widehat{h}_j(p - \delta - a_j)) \in \mathcal{F}(x, \widehat{h}_j) ,$$

and since $\mathcal{F}(x, h_j) = \{(a_j, h_j(a_j))\}$ is a singleton, then $\mathcal{F}(x, \widehat{h}_j)$ is simply a translation of $\mathcal{F}(x, h)$, and moreover since $(p - \delta, h(p - \delta))$ is in the relative interior of $\mathcal{F}(x, h)$, then it means that $(p - \delta - a_j, \widehat{h}_j(p - \delta - a_j))$ is in the relative interior of $\mathcal{F}(x, \widehat{h}_j)$, and that $\mathcal{F}(x, \widehat{h}_j)$ is a facet of $\widehat{Q}_{j,\omega} := \text{hypo}(\widehat{h}_j)$. Therefore, since $(p - \delta - a_j, \widehat{h}_j(p - \delta - a_j))$ is in both $\mathcal{F}(x, \widehat{h}_j)$ and $\mathcal{F}(x', \widehat{h}_j)$ and since it is in particular in the relative interior of the first face, we deduce that

$$\mathcal{F}(x, \widehat{h}_j) \subseteq \mathcal{F}(x', \widehat{h}_j) .$$

Since by Observation 3.26 (a), $\mathcal{F}(x', \widehat{h}_j)$ is a proper face of $\widehat{Q}_{j,\omega}$, then it implies that it is also a facet of $\widehat{Q}_{j,\omega}$, and thus that

$$\mathcal{F}(x, \widehat{h}_j) = \mathcal{F}(x', \widehat{h}_j) .$$

Hence, it follows from Observation 3.26 (b) that $x = x'$, and therefore $(a'_j, h_j(a'_j)) \in \mathcal{F}(x, h_j) = \{(a_j, h_j(a_j))\}$, hence $a'_j = a_j$ and thus $p' = p$. \square

Using Lemma 3.32, we are now all set to give a proof of Theorem 3.5.

Proof of Theorem 3.5. The ‘only if’ implication is straightforward, for if x is a common root of the system f , then its image by the Veronese embedding

$$\text{ver} : \begin{cases} \mathbb{R}^n & \longrightarrow & \mathbb{R}^{\mathcal{E}'} \\ x & \longmapsto & \text{ver}(x) = (x^\nu)_{\nu \in \mathcal{E}'} \end{cases}$$

yields a finite vector in the right null space of the matrix $\mathcal{M}_{\mathcal{E}'}$. Note that by convention, this also holds when $\mathcal{M}_{\mathcal{E}'}$ is empty.

For the converse implication, we rather show the contrapositive. Assume that the tropical polynomial system f does not have a solution, and consider the matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}'} = (m_{pp'})_{(p,p') \in \mathcal{E} \times \mathcal{E}'}$ obtained from the Canny-Emiris construction described in Section 3.3.1. Note that this construction implies that the matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}}$ and *a fortiori* the matrix $\mathcal{M}_{\mathcal{E}}$ are nonempty, leading to a contradiction when $\mathcal{M}_{\mathcal{E}}$ is empty, thus proving the ‘if’ implication in that case. We now assume that $\mathcal{M}_{\mathcal{E}}$ and thus $\mathcal{M}_{\mathcal{E}'}$ are nonempty.

Let

$$\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}'} = (\widetilde{m}_{pp'})_{(p,p') \in \mathcal{E} \times \mathcal{E}'} \quad \text{with} \quad \widetilde{m}_{pp'} = m_{pp'} - h(p' - \delta) .$$

Similarly to $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$, this matrix can also be written as a block matrix in the following way:

$$\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}'} = \begin{pmatrix} \widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}} & \mathbb{0} \end{pmatrix}$$

where $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}} = (\widetilde{m}_{pp'})_{(p,p') \in \mathcal{E} \times \mathcal{E}}$ is a square matrix indexed by $\mathcal{E} \times \mathcal{E}$. We show that the tropical matrix $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}$ is diagonally dominant. Indeed, for all $p, p' \in \mathcal{E}$, and let (j, a_j) be the row content of p . Then, we have for $a'_j \in \mathbb{Z}^n$ such that $p' = p - a_j + a'_j$

$$m_{pp'} = \begin{cases} f_{j,a'_j} & \text{if } a'_j \in \mathcal{A}_j \\ 0 & \text{otherwise,} \end{cases}$$

or in other words, $m_{pp'} = \omega_j(a'_j)$. In particular, for $p' = p$, we have

$$\widetilde{m}_{pp} = f_{j,a_j} - h(p - \delta) .$$

Moreover, by assumption, the monomial $f_{j,a_j} X^{a_j}$ of f_j is essential. By Observation 3.30, we have therefore $h_j(a_j) = f_{j,a_j}$, hence we obtain from the equality case of Lemma 3.32 that

$$\widetilde{m}_{pp} = -\widehat{h}_j(p - \delta - a_j) .$$

Now for the case of $p' \neq p$, again since $h_j(a'_j) = f_{j,a'_j}$, then by rearranging the inequality of Lemma 3.32, we obtain that

$$\tilde{m}_{pp'} = -\widehat{h}_j(p - \delta - a_j) \geq f_{j,a'_j} - h(p' - \delta) = \tilde{m}_{pp'} ,$$

with equality if and only if $p' = p$. Thus, the matrix $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}$ is tropically diagonally dominant. In particular, it follows that any two rows of $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}'}$ are distinct, and thus it is also true for $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$ because $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}'}$ was obtained from $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$ by adding the same vector to all of its rows. Therefore, it means that the matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}'}$ is indeed a submatrix of $\mathcal{M}_{\mathcal{E}'}$ — and likewise the rows of $\mathcal{M}_{\mathcal{E}\mathcal{E}}$ are pairwise distinct, thus $\mathcal{M}_{\mathcal{E}\mathcal{E}}$ is a (square) submatrix of $\mathcal{M}_{\mathcal{E}}$.

Finally, since $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}$ is tropically diagonally dominant, by Lemma 3.14, it also is nonsingular, and thus applying Lemma 3.16 to $\mathcal{M}_{\mathcal{E}\mathcal{E}}$, we obtain that $\mathcal{M}_{\mathcal{E}\mathcal{E}}$ is also nonsingular. Therefore, the matrix $\mathcal{M}_{\mathcal{E}'}$ has the following form

$$\mathcal{M}_{\mathcal{E}'} = \begin{pmatrix} \mathcal{M}_{\mathcal{E}\mathcal{E}} & \mathbb{0} \\ * & * \end{pmatrix}$$

and thus Lemma 3.17 entails that the equation $\mathcal{M}_{\mathcal{E}'} \odot y \nabla \mathbb{0}$ has no solution y in $\mathbb{R}^{\mathcal{E}'}$, i.e. there cannot exist a finite vector in the tropical right null space of $\mathcal{M}_{\mathcal{E}'}$. \square

Remark 3.33. Notice that in the case where $\mathcal{E}' = \mathcal{E}$, following the same proof, you obtain a weaker condition on the right null space of $\mathcal{M}_{\mathcal{E}}$ in order to find a finite solution of the system f . More precisely, you can show that there exists a solution $x \in \mathbb{R}^n$ to the system f if and only if there exists a vector $y \in \mathbb{R}_{\infty}^{\mathcal{E}} \setminus \{\mathbb{0}\}$ such that $\mathcal{M}_{\mathcal{E}} \odot y \nabla \mathbb{0}$. In other words, in the case where $\mathcal{E}' = \mathcal{E}$, the existence of a nonzero vector in the right null space of $\mathcal{M}_{\mathcal{E}}$, even possibly with some coordinates equal to $\mathbb{0}$, is enough to guarantee the existence of a finite solution of the system f .

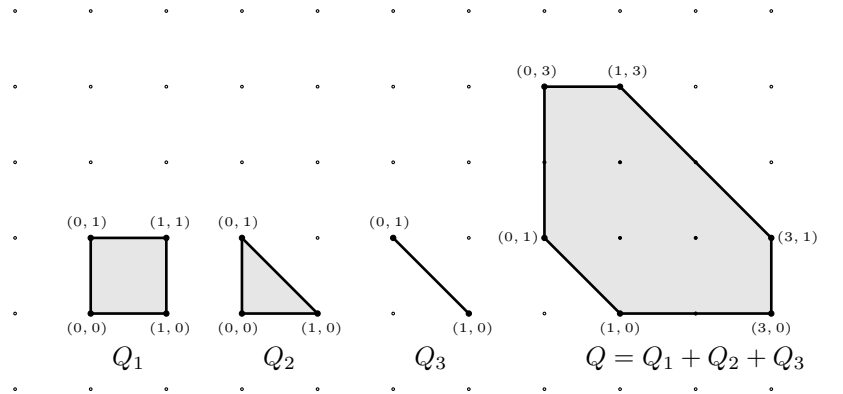
3.4 Some examples

Let us illustrate Theorem 3.5 with some explicit examples. Consider the following two systems:

$$(\mathcal{S}_1) : \begin{cases} f_1 = 1 \oplus 2x_1 \oplus 1x_2 \oplus 1x_1x_2 \\ f_2 = 0 \oplus 0x_1 \oplus 1x_2 \\ f_3 = 2x_1 \oplus 0x_2 \end{cases} \quad \text{and} \quad (\mathcal{S}_2) : \begin{cases} f_1 = 1 \oplus 4x_1 \oplus 1x_2 \oplus 3x_1x_2 \\ f_2 = 0 \oplus 0x_1 \oplus 1x_2 \\ f_3 = 2x_1 \oplus 0x_2 \end{cases}$$

Both systems have the same supports, and thus yield the same polytope Q .

Figure 3: The Newton polytopes associated f_1, f_2, f_3 and their Minkowski sum.



For this collection of supports, one can take $\delta = (-1 + \varepsilon, -1 + \varepsilon)$ with $\varepsilon > 0$ sufficiently small, for instance $\varepsilon = 0.1$, which gives us the Canny-Emiris set

$$\mathcal{E} := (Q + \delta) \cap \mathbb{Z}^n = \{(0, 0), (1, 0), (0, 1), (2, 0), (1, 1), (0, 2)\} ,$$

corresponding to the set of monomials

$$\{1, x_1, x_2, x_1^2, x_1x_2, x_2^2\} .$$

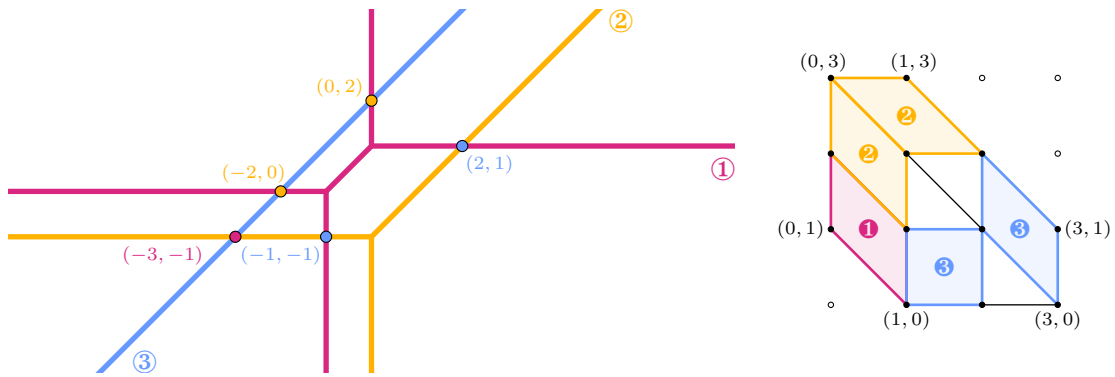
Note that we could simply have chosen δ to be $(\varepsilon, \varepsilon)$ instead, but we chose to also translate Q by $(-1, -1)$ so that $Q + \delta$ contains the origin, thus ensuring that \mathcal{E} contains smaller degree monomials. We can therefore

write the respective submatrices $\mathcal{M}_{\mathcal{E}}^{(1)}$ and $\mathcal{M}_{\mathcal{E}}^{(2)}$ of the Macaulay matrix associated to the set \mathcal{E} and we obtain the following 7×6 matrices

$$\mathcal{M}_{\mathcal{E}}^{(1)} = \begin{matrix} f_1 \\ f_2 \\ x_1 f_2 \\ x_2 f_2 \\ f_3 \\ x_1 f_3 \\ x_2 f_3 \end{matrix} \begin{pmatrix} 1 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 \\ 1 & 2 & 1 & & 1 & \\ 0 & 0 & 1 & & & \\ 0 & 0 & & 0 & 1 & \\ & & 0 & 0 & 0 & 1 \\ & 2 & 0 & & & \\ & & & 2 & 0 & \\ & & & & 2 & 0 \end{pmatrix} \text{ and } \mathcal{M}_{\mathcal{E}}^{(2)} = \begin{matrix} f_1 \\ f_2 \\ x_1 f_2 \\ x_2 f_2 \\ f_3 \\ x_1 f_3 \\ x_2 f_3 \end{matrix} \begin{pmatrix} 1 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 \\ 1 & 4 & 1 & & 3 & \\ 0 & 0 & 1 & & & \\ 0 & 0 & & 0 & 1 & \\ & & 0 & 0 & 0 & 1 \\ & 2 & 0 & & & \\ & & & 2 & 0 & \\ & & & & 2 & 0 \end{pmatrix}.$$

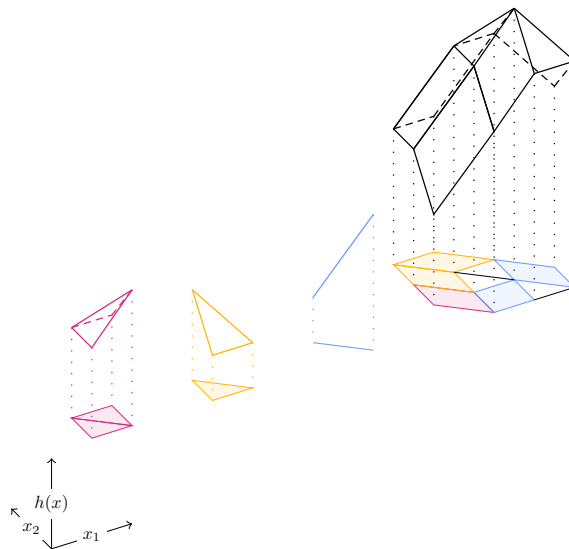
One can check that the system (S_1) does not have a common root, as the different intersection points of the tropical hypersurfaces associated to f_1 , f_2 and f_3 are listed on Figure 4 (and we know that two tropical lines only have at most one intersection point, and a line and a quadric have at most two intersection points).

Figure 4: The arrangement of tropical varieties of the polynomials from the system (S_1) and the associated subdivision of Q .



We can therefore apply the Canny-Emiris construction to it. First, we obtain a subdivision of Q by projecting the non-vertical faces of the Minkowski sum of the hypographs of h_1 , h_2 and h_3 onto the horizontal hyperplane $\mathbb{R}^n \times \{0\}$ as shown on Figure 5.

Figure 5: The subdivision of Q arises from the projection of the Minkowski sum of the hypographs of the h_i .



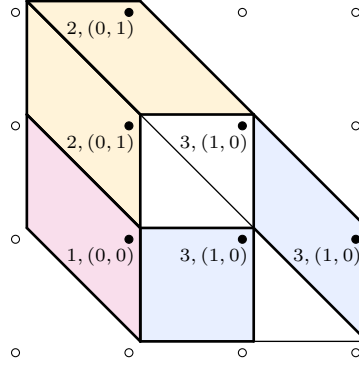
With this subdivision, we associate to every point $p \in \mathcal{E}$ its row content i, a_i , which is univocally determined by the maximal-dimensional cell of the decomposition of Q to which $p - \delta$ belongs. This process is illustrated in Figure 6.

More precisely, in the following table, for each point p of \mathcal{E} in the first row:

- the second row displays the monomial x^p which corresponds to a column of the Macaulay matrix,
- the third row displays the row content i, a_i of p ,
- the fourth row displays the polynomial $x^{p-a_i} f_i$ which corresponds to a row of the Macaulay matrix,
- and finally the last row displays the tropical scaling factor $h(p - \delta)$ which must be subtracted (in the usual sense) to the column p of the matrix $\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(1)}$ in order to obtain the matrix $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^{(1)}$.

$p \in \mathcal{E}$	(0, 0)	(1, 0)	(0, 1)	(2, 0)	(1, 1)	(0, 2)
x^p	1	x_1	x_2	x_1^2	x_1x_2	x_2^2
i, a_i	1, (0, 0)	3, (1, 0)	2, (0, 1)	3, (1, 0)	3, (1, 0)	2, (0, 1)
$x^{p-a_i} f_i$	f_1	f_3	f_2	$x_1 f_3$	$x_2 f_3$	$x_2 f_2$
$h(p - \delta)$	3.6	4.8	3.8	3.3	4.1	2.2

Figure 6: The polytope $Q + \delta$, with the integer points inside the maximal dimensional cells of the decomposition of $Q + \delta$ labelled by the row content the cell they belong to.



With the information from the previous table, we obtain the following 6×6 square submatrix $\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(1)}$ of

$$\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(1)} = \begin{matrix} & 1 & x_1 & x_2 & x_1^2 & x_1x_2 & x_2^2 \\ \begin{matrix} f_1 \\ f_3 \\ f_2 \\ x_1f_3 \\ x_2f_3 \\ x_2f_2 \end{matrix} & \begin{pmatrix} 1 & 2 & 1 & & & 1 \\ & 2 & 0 & & & \\ 0 & 0 & 1 & & & \\ & & & 2 & 0 & \\ & & & & 2 & 0 \\ & & 0 & & 0 & 1 \end{pmatrix} & , \end{matrix}$$

and after applying the tropical scaling of factor $h(p - \delta)$ to the column p of the previous matrix for all $p \in \mathcal{E}$, we obtain the following matrix, in which we highlighted the diagonal coefficients by writing them in bold

$$\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^{(1)} = \begin{matrix} & 1 & x_1 & x_2 & x_1^2 & x_1x_2 & x_2^2 \\ \begin{matrix} f_1 \\ f_3 \\ f_2 \\ x_1f_3 \\ x_2f_3 \\ x_2f_2 \end{matrix} & \begin{pmatrix} -\mathbf{2.6} & -2.8 & -2.8 & & & -3.1 \\ & -\mathbf{2.8} & -3.8 & & & \\ -3.6 & -4.8 & -\mathbf{2.8} & & & \\ & & & -\mathbf{1.3} & -4.1 & \\ & & & & -\mathbf{2.1} & -2.2 \\ & & -3.8 & & -3.1 & -\mathbf{1.2} \end{pmatrix} & . \end{matrix}$$

We finally observe that the matrix $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^{(1)}$ is tropically diagonally dominant, and therefore it follows from Lemmas 3.14 and 3.16 that $\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(1)}$ is also nonsingular⁴, thus there is no solution $y \in \mathbb{R}^{\mathcal{E}}$ to the equation $\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(1)} \odot y \nabla 0$.

Besides, note that by choosing a different ordering of the polynomials, in which f_3 comes before f_2 , then the row content of (1, 1) would be 2, (1, 0) and thus the fifth row of $\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(1)}$ would change to be

$$x_1 f_2 \quad \begin{pmatrix} 1 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 \\ & 0 & & 0 & 1 & \end{pmatrix}$$

and we can still check likewise that the right null space of this matrix is simply equal to $\{0\}$. With a similar argument to the first system, one can check that $(-3, -1)$ is the only common root of the system (\mathcal{S}_2) (see Figure 7), and indeed by choosing

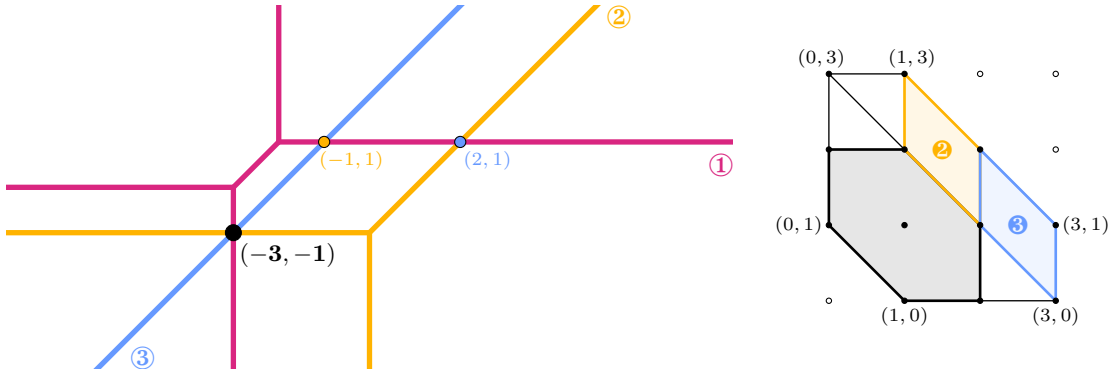
$$y = \text{ver}(-3, -1) = \begin{pmatrix} 0 \\ -3 \\ -1 \\ -6 \\ -4 \\ -2 \end{pmatrix},$$

we observe that

$$\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(2)} \odot y \nabla 0.$$

Moreover, note that the set of solutions $y \in \mathbb{R}^6$ to the tropical linear system $\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(2)} \odot y \nabla 0$ consists precisely in the set $\{\lambda + \text{ver}(-3, -1) : \lambda \in \mathbb{R}\}$ of tropical multiples of the Veronese embedding of the point $(-3, -1)$, which indeed attests to the uniqueness of the solution $(-3, -1)$, as two distinct solutions would have two non-collinear Veronese embeddings, in the tropical sense.

Figure 7: The arrangement of tropical varieties of the polynomials from the system (\mathcal{S}_2) and the associated subdivision of Q .



4 The Tropical Positivstellensatz for two-sided systems

4.1 Statement of the theorem

Now we formulate a result similar to Theorem 3.5, for systems mixing equalities and weak and strict inequalities between tropical polynomial functions (also called ‘two sided’ systems). More precisely, consider $f^+ = (f_1^+, \dots, f_k^+)$ and $f^- = (f_1^-, \dots, f_k^-)$ two collections of k tropical polynomials. For $1 \leq i \leq k$, we denote by \mathcal{A}_i^+ and \mathcal{A}_i^- respectively the supports of f_i^+ and f_i^- , and set $\mathcal{A}_i = \mathcal{A}_i^+ \cup \mathcal{A}_i^-$, and $\mathcal{A} = (\mathcal{A}_1, \dots, \mathcal{A}_k)$. Equivalently, \mathcal{A} is the collection of supports of the polynomials $f_i := f_i^+ \oplus f_i^-$.

Consider also a collection $\triangleright = (\triangleright_1, \dots, \triangleright_k)$ of relations $\triangleright_i \in \{\geq, =, >\}$, for $1 \leq i \leq k$. We denote by $f^+(x) \triangleright f^-(x)$ the system

$$\max_{\alpha \in \mathcal{A}_i^+} (f_{i,\alpha}^+ + \langle \alpha, x \rangle) \triangleright_i \max_{\alpha \in \mathcal{A}_i^-} (f_{i,\alpha}^- + \langle \alpha, x \rangle) \text{ for all } 1 \leq i \leq k, \quad (7)$$

⁴Alternatively, one can verify that $\text{tdet}(\mathcal{M}_{\mathcal{E}\mathcal{E}}^{(1)}) \not\propto 0$ if tdet denotes the tropical determinant defined in Remark 3.12.

of unknown $x \in \mathbb{R}_\infty^n$. Note that this is equivalent to the expressions $\hat{f}_i^+(x) \triangleright_i \hat{f}_i^-(x)$, $i = 1, \dots, k$. Finally, we denote by \mathcal{M}^+ and \mathcal{M}^- the Macaulay matrices associated to f^+ and f^- respectively, so with entries $\mathcal{M}_{(i,\alpha),\beta}^\pm = f_{i,\beta-\alpha}^\pm$. Then, for any subset \mathcal{E} of \mathbb{Z}^n , we denote by $\mathcal{M}_{\mathcal{E}}^+$ and $\mathcal{M}_{\mathcal{E}}^-$ the submatrices associated to \mathcal{E} and the collection \mathcal{A} defined above, that is $\mathcal{M}_{\mathcal{E}}^+ = (\mathcal{M}^+)^{\mathcal{A}}$ and $\mathcal{M}_{\mathcal{E}}^- = (\mathcal{M}^-)^{\mathcal{A}}$, and we likewise set for $N \in \mathbb{N}$, $\mathcal{M}_N^+ = (\mathcal{M}^+)_N^{\mathcal{A}}$ and $\mathcal{M}_N^- = (\mathcal{M}^-)_N^{\mathcal{A}}$.

Finally, we set for $1 \leq i \leq k$:

$$r_i = \begin{cases} \dim(\text{aff}(\mathcal{A}_i^-)) + 1 & \text{if } \triangleright_i \in \{\geq, >\} \\ \max(\dim(\text{aff}(\mathcal{A}_i^-)), \dim(\text{aff}(\mathcal{A}_i^+))) + 1 & \text{if } \triangleright_i \in \{=\} \end{cases} .$$

Notice that in particular, this definition implies the following inequality

$$r_i \leq \begin{cases} \min(|\mathcal{A}_i^-|, n+1) & \text{if } \triangleright_i \in \{\geq, >\} \\ \min(\max(|\mathcal{A}_i^-|, |\mathcal{A}_i^+|), n+1) & \text{if } \triangleright_i \in \{=\} \end{cases} .$$

We now call *Canny-Emiris subsets* of \mathbb{Z}^n associated to the system $f^+ \triangleright f^-$ any set \mathcal{E} of the form

$$\mathcal{E} := (\tilde{Q} + \delta) \cap \mathbb{Z}^n \quad \text{with} \quad \tilde{Q} = r_1 Q_1 + \dots + r_k Q_k ,$$

where $Q_i = \text{conv}(\mathcal{A}_i)$ for $1 \leq i \leq k$, and δ is a generic vector in $V + \mathbb{Z}^n$, with V the direction of the affine hull of \tilde{Q} (note that this is the same as for $Q_1 + \dots + Q_k$). Finally, for any subset \mathcal{E}' of \mathbb{Z}^n containing a Canny-Emiris subset \mathcal{E} associated to $f^+ \triangleright f^-$ and $y \in \mathbb{R}^{\mathcal{E}'}$, we denote by $\mathcal{M}_{\mathcal{E}'}^+ \odot y \triangleright \mathcal{M}_{\mathcal{E}'}^- \odot y$ the following system of tropical linear equalities:

$$\max_{\beta \in \mathcal{E}'} (m_{(i,\alpha),\beta}^+ + y_\beta) \triangleright_i \max_{\beta \in \mathcal{E}'} (m_{(i,\alpha),\beta}^- + y_\beta) \quad \text{for all } 1 \leq i \leq k \quad \text{and} \quad \alpha \in \mathcal{A}_i .$$

We now state a Positivstellensatz for the case of tropical polynomial systems allowing both weak and strict inequalities, and equalities.

Theorem 4.1 (Sparse tropical Positivstellensatz). *There exists a solution $x \in \mathbb{R}^n$ to the system $f^+ \triangleright f^-$ if and only if there exists a vector $y \in \mathbb{R}^{\mathcal{E}'}$ satisfying $\mathcal{M}_{\mathcal{E}'}^+ \odot y \triangleright \mathcal{M}_{\mathcal{E}'}^- \odot y$, where \mathcal{E}' is any subset of \mathbb{Z}^n containing a nonempty Canny-Emiris subset \mathcal{E} of \mathbb{Z}^n associated to the system $f^+ \triangleright f^-$.*

The following observation justifies the name of *tropical Positivstellensatz* given to the previous theorem.

Remark 4.2. Let $f_1^\pm, \dots, f_{k+1}^\pm$ be a collection of pairs of tropical polynomials. We consider the following problem:

$$\begin{cases} f_1^+(x) \geq f_1^-(x) \\ \vdots \\ f_k^+(x) \geq f_k^-(x) \end{cases} \stackrel{?}{\implies} f_{k+1}^+(x) \geq f_{k+1}^-(x) \quad \forall x \in \mathbb{R}^n . \quad (\mathcal{P})$$

Solving (\mathcal{P}) is equivalent to showing that the following system

$$(\mathcal{S}) : \begin{cases} f_1^+(x) \geq f_1^-(x) \\ \vdots \\ f_k^+(x) \geq f_k^-(x) \\ f_{k+1}^+(x) < f_{k+1}^-(x) \end{cases}$$

has no solution $x \in \mathbb{R}^n$.

In other words, (\mathcal{P}) is the problem of the inclusion of a given closed tropical basic semialgebraic set — defined to be a set of vectors $x \in \mathbb{R}^n$ satisfying a system of tropical polynomial inequations in the form of the left member of the implication in (\mathcal{P}) — into another one, and Theorem 4.1 shows that this problem can be reduced to the problem of the unsolvability a system of linear tropical (in)equations.

Remark 4.3. Once again, the proof of the implication that if there is a solution $x \in \mathbb{R}^n$ to the system $f^+ \triangleright f^-$, then there exists a vector $y \in \mathbb{R}^{\mathcal{E}'}$ such that $\mathcal{M}^+ \odot y \triangleright \mathcal{M}^- \odot y$ is immediate by choosing y to be the Veronese embedding $\text{ver}(x)$ of x , which we recall is equal to the vector $(x^\nu)_{\nu \in \mathcal{E}'}$. Therefore, we will only focus on the converse implication in what follows, or rather on its contrapositive.

4.2 Further preliminary results

In this section, we adapt the results from Section 3.2 to the two-sided case in order to prove Theorem 4.1.

4.2.1 Diagonal dominance for a pair of matrices

In order to prove this theorem, we introduce a notion of diagonal dominance adapted to systems of inequalities and equalities.

Definition 4.4. Let $A = (a_{ij})_{1 \leq i, j \leq d}$ and $B = (b_{ij})_{1 \leq i, j \leq d}$ be a pair of matrices in $\mathcal{M}_d(\mathbb{R}_\infty)$. One says that B diagonally dominates A , or that A is diagonally dominated by B whenever

$$b_{ii} > a_{ij} \quad \text{for all } 1 \leq i, j \leq d .$$

Lemma 4.5. Let A and B be a pair of matrices in $\mathcal{M}_d(\mathbb{R}_\infty)$ such that A is diagonally dominated by B . Then the only solution to the inequation $A \odot y \geq B \odot y$ of unknown $y \in \mathbb{R}_\infty^d$ is $y = 0$.

Proof. Let $y = (y_1, \dots, y_d) \in \mathbb{R}_\infty^d$ be such that $A \odot y \geq B \odot y$ and consider $1 \leq i \leq d$ such that $y_i = \max_{1 \leq j \leq d} y_j$. Assume that $y \neq 0$, and thus that $y_i > -\infty$. Then from the relation $A \odot y \geq B \odot y$, it follows in particular that

$$\max_{1 \leq j \leq d} (a_{ij} + y_j) \geq \max_{1 \leq j \leq d} (b_{ij} + y_j) \geq b_{ii} + y_i ,$$

but by choice of i and since A is diagonally dominated by B , we have

$$b_{ii} + y_i > a_{ij} + y_j \quad \text{for all } 1 \leq j \leq d ,$$

hence we get a contradiction. \square

Corollary 4.6. Let A and B be a pair of matrices in $\mathcal{M}_d(\mathbb{R}_\infty)$ such that for all $1 \leq i \leq d$, we have either

$$b_{ii} > \max_{1 \leq j \leq d} a_{ij} \quad \text{or} \quad a_{ii} > \max_{1 \leq j \leq d} b_{ij} . \quad (8)$$

Then the only solution to the inequation $A \odot y = B \odot y$ of unknown $y \in \mathbb{R}_\infty^d$ is $y = 0$.

Proof. The idea of the proof is simply that by swapping some of the rows of A and B , we can obtain a pair of matrices \tilde{A} and \tilde{B} such that \tilde{A} is diagonally dominated by \tilde{B} . More precisely, set

$$I = \{1 \leq i \leq n : b_{ii} > a_{ij} \text{ for all } 1 \leq j \leq n\} \quad \text{and} \quad J = \{1, \dots, n\} \setminus I ,$$

and let

$$\tilde{A} = (\tilde{a}_{ij})_{1 \leq i, j \leq n} \quad \text{with} \quad \tilde{a}_{ij} = \begin{cases} a_{ij} & \text{if } i \in I \\ b_{ij} & \text{if } i \in J \end{cases}$$

and

$$\tilde{B} = (\tilde{b}_{ij})_{1 \leq i, j \leq n} \quad \text{with} \quad \tilde{b}_{ij} = \begin{cases} b_{ij} & \text{if } i \in I \\ a_{ij} & \text{if } i \in J . \end{cases}$$

By construction, notice that for $y \in \mathbb{R}^n$, we have

$$\tilde{A} \odot y = \tilde{B} \odot y \iff A \odot y = B \odot y ,$$

and moreover \tilde{A} is diagonally dominated by \tilde{B} , thus by the previous lemma, the only solution to the equality $\tilde{A} \odot y = \tilde{B} \odot y$ is $y = 0$, and thus 0 is also the only solution to the equality $A \odot y = B \odot y$. \square

Finally we will also make use of the following two lemmas, which are immediate adaptations of Lemma 3.16 and Lemma 3.17 to the two-sided case.

Lemma 4.7. Let $\triangleright \in \{\geq, =\}$. Let $A = (a_{ij})_{(i,j) \in [p] \times [m]}$ and $B = (b_{ij})_{(i,j) \in [p] \times [m]} \in \mathcal{M}_{p,m}(\mathbb{R}_\infty)$ be two $p \times m$ tropical matrices. Fix for $1 \leq j \leq m$, $\varepsilon_j \in \mathbb{R}$, and set $\tilde{A} = (\tilde{a}_{ij})_{(i,j) \in [p] \times [m]} \in \mathcal{M}_{p,m}(\mathbb{R}_\infty)$ and $\tilde{B} = (\tilde{b}_{ij})_{(i,j) \in [p] \times [m]} \in \mathcal{M}_{p,m}(\mathbb{R}_\infty)$ with $\tilde{a}_{ij} = a_{ij} + \varepsilon_j$ and $\tilde{b}_{ij} = b_{ij} + \varepsilon_j$ for all $1 \leq i \leq p$ and $1 \leq j \leq m$. Then the (in)equality $A \odot y \triangleright B \odot y$ of unknown $y \in \mathbb{R}_\infty^m$ has no nonzero solution if and only if the (in)equality $\tilde{A} \odot \tilde{y} \triangleright \tilde{B} \odot \tilde{y}$ of unknown $\tilde{y} \in \mathbb{R}_\infty^m$ has no nonzero solution.

Lemma 4.8. Let $\triangleright \in \{\geq, =\}$. Let A and B be two $p \times m$ tropical matrices, and assume that A and B can both be written by block as lower-triangular matrices

$$A = \begin{pmatrix} A^{(d)} & 0 \\ * & * \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} B^{(d)} & 0 \\ * & * \end{pmatrix}$$

with $A^{(d)}$ and $B^{(d)}$ two $d \times d$ square submatrix. Moreover, assume that the only solution to the equation $A^{(d)} \odot y^{(d)} \triangleright B^{(d)} \odot y^{(d)}$ of unknown $y^{(d)} \in \mathbb{R}_\infty^d$ is $y^{(d)} = 0$. Then the equation $A \odot y \triangleright B \odot y$ of unknown y has no solution in \mathbb{R}^m .

4.2.2 The Shapley-Folkman lemma

In this brief subsection, we recall the following lemma which will allow us to define a notion of row content adapted to the two-sided case.

Lemma 4.9 (Shapley-Folkman, see [Sch13, Theorem 3.1.2]). *Let $A_1, \dots, A_k \subseteq \mathbb{R}^n$, and let*

$$x \in \sum_{i=1}^k \text{conv}(A_i) .$$

Then there is an index set $I \subseteq \{1, \dots, k\}$ with $|I| \leq n$ such that

$$x \in \sum_{i \in I} \text{conv}(A_i) + \sum_{i \in \{1, \dots, k\} \setminus I} A_i .$$

In the case where the Minkowski sum of the A_i is not full-dimensional, one has the following direct corollary of the previous result.

Corollary 4.10. *If in Lemma 4.9 $\sum_{i=1}^k \text{conv}(A_i)$ has (affine) dimension $d < n$, then the index set I can be chosen such that $|I| \leq d$.*

4.3 Proving the Tropical Positivstellensatz

Before detailing the proof of Theorem 4.1, notice that we can simply consider the case where all relations in system (7) are of the form $\triangleright_i \in \{\geq, =\}$. Indeed, suppose the system $f^+(x) \triangleright f^-(x)$ comprises relations of the form $f_i^+(x) > f_i^-(x)$ for $i \in I \subseteq \{1, \dots, k\}$. Let $\lambda > \mathbb{1} = 0$, and let us consider the transformed system $\mathcal{S}(\lambda)$, in which every relation

$$f_i^+(x) > f_i^-(x)$$

is replaced by

$$f_i^+(x) \geq \lambda \odot f_i^-(x) .$$

Let $\mathcal{M}_{\mathcal{E}'}^-(\lambda)$ denote the negative Macaulay matrix associated to $\mathcal{S}(\lambda)$, and let us take \triangleright'_j to be equal to \geq for $j \in I$, and to \triangleright_j otherwise.

Then, the relation $\mathcal{M}_{\mathcal{E}'}^+ \odot y \triangleright \mathcal{M}_{\mathcal{E}'}^- \odot y$ holds iff $\mathcal{M}_{\mathcal{E}'}^+ \odot y \triangleright' \mathcal{M}_{\mathcal{E}'}^-(\lambda) \odot y$ holds for some $\lambda > \mathbb{1}$. Thus, if the theorem is proven for systems without strict inequalities, it follows that the latter relation is equivalent to the solvability of $\mathcal{S}(\lambda)$, for the same value of λ , which proves the result for systems which include strict inequalities.

In the following, we will therefore simply focus on systems such that $\triangleright_i \in \{\geq, =\}$ for all $1 \leq i \leq k$.

4.3.1 A row content adapted to two-sided relations

We consider the collection $f = (f_1, \dots, f_k)$ of tropical polynomials, their associated Newton polytopes Q_i as in Section 4.1 and the constants r_i defined in Section 4.1. We also consider the maps h_1, \dots, h_k defined as in Section 3.3.1. Moreover, we set

$$\tilde{h} = h_1^{\square r_1} \square \dots \square h_k^{\square r_k} ,$$

and note that $\tilde{Q} = \text{supp}(\tilde{h})$.

Recall that now \mathcal{E} is a Canny-Emiris set associated to the system $f^+ \triangleright f^-$, that is $\mathcal{E} = (\tilde{Q} + \delta) \cap \mathbb{Z}^n$, where δ is a generic vector in $V + \mathbb{Z}^n$ and V is the direction of the affine hull of \tilde{Q} . Assume that there is no solution $x \in \mathbb{R}^n$ to the system $f^+(x) \triangleright f^-(x)$, i.e. that for all $x \in \mathbb{R}^n$, there exists $1 \leq j \leq k$ such that

$$f_j^+(x) \not\triangleright_j f_j^-(x) . \tag{9}$$

More precisely, (9) implies that either

$$f_j^-(x) > f_j^+(x) , \tag{10a}$$

or

$$\triangleright_j \text{ is an equality and } f_j^-(x) < f_j^+(x) . \tag{10b}$$

Then for $p \in \mathcal{E}$, $(p - \delta, \tilde{h}(p - \delta))$ is in the relative interior of a facet \tilde{F} of $\text{hypo}(\tilde{h}) = \sum_{i=1}^k r_i \text{hypo}(h_i)$. This facet satisfies $\tilde{F} = \mathcal{F}(x, \tilde{h})$ for some $x \in V$, and then

$$\tilde{F} = r_1 F_1 + \dots + r_k F_k ,$$

with $F_i = \mathcal{F}(x, h_i)$. This means that we can write $p - \delta = r_1 q_1 + \dots + r_k q_k$ with $(q_i, h_i(q_i)) \in F_i$ for all $1 \leq i \leq k$. Set j to be the maximal index such that (9) is satisfied. We have

$$r_j(q_j, h_j(q_j)) \in r_j F_j = F_j + \dots + F_j$$

where the sum has r_j terms. Moreover, F_j is isomorphic to its projection $C_j := \mathcal{C}(x, h_j)$ on \mathbb{R}^n , and the set of extremal points of C_j is included in the finite set $\mathcal{C}(x, \omega_j)$, where ω_j is the coefficient map of the tropical polynomial f_j (see Section 3.3.1 and Observation 3.26(b)). Moreover, by assumption j and x satisfy (9), hence, in case (10a), one must have $\mathcal{C}(x, \omega_j) \subset \mathcal{A}_j^-$, because the maximum in the expression

$$\max_{\alpha \in \mathcal{A}_j} f_{j,\alpha} + \langle x, \alpha \rangle$$

cannot be attained by a monomial of f_j^+ , and likewise in case (10b), one must have $\mathcal{C}(x, \omega_j) \subset \mathcal{A}_j^+$. Therefore, this means by definition of r_j that the cell C_j , as well as the facet F_j have dimension at most $r_j - 1$, and so does the facet $r_j F_j = F_j + \dots + F_j$. Thus, applying Corollary 4.10 (of the Shapley-Folkman lemma), there exists $(q'_j, h_j(q'_j)) \in F_j$ and a_j an extremal point of C_j such that $r_j(q_j, h_j(q_j)) = (r_j - 1)(q'_j, h_j(q'_j)) + (a_j, h_j(a_j))$. Moreover, since a_j is an extremal point of C_j , we know that in case (10a), one has $a_j \in \mathcal{A}_j^-$, while in case (10b), one has $a_j \in \mathcal{A}_j^+$.

We then define the *row content* of p in this context to be equal to a couple (j, a_j) satisfying the above properties. Note that the element $a_j \in \mathcal{A}_j$ satisfying the above condition need not be unique, but we will see in the proof that this does not matter. Since a_j is an extremal point of $\mathcal{C}(x, h_j)$, we have that $(a_j, h_j(a_j))$ is a vertex of $\text{hypo}(h_j)$, which implies that $h_j(a_j) = f_{j,a_j}$, by Observation 3.30.

Now for any subset \mathcal{E}' of \mathbb{Z}^n containing \mathcal{E} , we can construct the matrices $\mathcal{M}_{\mathcal{E}\mathcal{E}'}^\pm = (m_{pp'}^\pm)_{(p,p') \in \mathcal{E} \times \mathcal{E}'}$ similarly to Section 3.3.1, by setting the row p of $\mathcal{M}_{\mathcal{E}\mathcal{E}'}^\pm$ to be the row $(j, p - a_j)$ of $\mathcal{M}_{\mathcal{E}\mathcal{E}'}^\pm$, if (j, a_j) is the row content of p .

4.3.2 The proof of Theorem 4.1

In order to prove Theorem 4.1, we will make use of the following lemma.

Lemma 4.11. *Consider h_1, \dots, h_k and \tilde{h} as defined in Section 3.3.1, and let $p \in \mathcal{E}$ and let (j, a_j) be its row content. Then for all $p' \in \mathcal{E}$ and $a'_j \in \mathbb{Z}^n$ such that $p' = p - a_j + a'_j$, we have*

$$\begin{aligned} (\dagger) \qquad \qquad \qquad (\ddagger) \\ \tilde{h}(p' - \delta) \geq \tilde{h}(p - \delta) - h_j(a_j) + h_j(a'_j) \geq \tilde{h}(p - \delta) - f_{j,a_j}^- + f_{j,a'_j}^+ , \end{aligned} \quad (11)$$

and moreover at least one of the two inequalities is strict.

Proof. By setting

$$\hat{h}_j = \underbrace{h_1 \square \dots \square h_1}_{r_1 \text{ terms}} \square \dots \square \underbrace{h_j \square \dots \square h_j}_{r_j - 1 \text{ terms}} \square \dots \square \underbrace{h_k \square \dots \square h_k}_{r_k \text{ terms}} ,$$

so that $\tilde{h} = h_j \square \hat{h}_j$, the exact same reasoning as in the proof of Lemma 3.32 shows that

$$\tilde{h}(p' - \delta) \geq h_j(a'_j) + \hat{h}_j(p - \delta - a_j) ,$$

and that if $p' = p$, which entails that $a'_j = a_j$, then this inequality is an equality. This implies inequality (\dagger).

Inequality (\ddagger) simply follows from the fact that $f_{j,a_j}^- = h_j(a_j)$ and $f_{j,a'_j}^+ \leq h_j(a'_j)$.

We now show that either (\dagger) or (\ddagger) is strict. If $p' = p$, then inequality (\ddagger) reduces to $f_{j,a_j}^- \geq f_{j,a_j}^+$ which is known to be strict. Now assume that $p' \neq p$, and suppose that the equality is achieved in (\dagger). Then this implies that

$$(p' - \delta, \tilde{h}(p' - \delta)) = (a'_j, h_j(a'_j)) + (p - \delta - a_j, \hat{h}_j(p - \delta - a_j)) . \quad (12)$$

Now consider $x, x' \in \mathbb{R}^n$ such that $F = \mathcal{F}(x, \tilde{h})$ and $F' = \mathcal{F}(x', \tilde{h})$ are the facet in the interior of which $(p - \delta, \tilde{h}(p - \delta))$ and $(p' - \delta, \tilde{h}(p' - \delta))$ respectively lie. Then from Corollary 3.29, we have

$$(a'_j, h_j(a'_j)) \in \mathcal{F}(x', h_j) \quad \text{and} \quad (p - \delta - a_j, \hat{h}_j(p - \delta - a_j)) \in \mathcal{F}(x', \hat{h}_j) .$$

However, we also know from equality (12) and Corollary 3.29 that

$$(p - \delta - a_j, \hat{h}_j(p - \delta - a_j)) \in \mathcal{F}(x, \hat{h}_j) .$$

Moreover, by the Shapley-Folkman lemma (Lemma 4.9), we have that

$$r_j \mathcal{F}(x, h_j) = \mathcal{S} + (r_j - 1) \mathcal{F}(x, h_j)$$

with $\mathcal{S} := \{(\alpha, h_j(\alpha)) \in \mathbb{Z}^n \times \mathbb{R} : (\alpha, h_j(\alpha)) \text{ is a vertex of } \mathcal{F}(x, h_j)\}$ which is in particular a finite set, and thus

$$\mathcal{F}(x, \tilde{h}) = \mathcal{S} + \mathcal{F}(x, \hat{h}_j) .$$

Since $(p - \delta, h(p - \delta))$ is in the relative interior of $\mathcal{F}(x, \tilde{h})$, and since δ was taken generic, then it follows that $(p - \delta - a_j, \hat{h}_j(p - \delta - a_j))$ is in the relative interior of $\mathcal{F}(x, \hat{h}_j)$, and that $\mathcal{F}(x, \hat{h}_j)$ is a facet of $\text{hypo}(\hat{h}_j)$. Therefore, since $(p - \delta - a_j, \hat{h}_j(p - \delta - a_j))$ is in both $\mathcal{F}(x, \hat{h}_j)$ and $\mathcal{F}(x', \hat{h}_j)$ and since it is in particular in the relative interior of the first face, we deduce that

$$\mathcal{F}(x, \hat{h}_j) \subseteq \mathcal{F}(x', \hat{h}_j) .$$

Since by Observation 3.26 (a), $\mathcal{F}(x', \hat{h}_j)$ is a proper face of $\text{hypo}(\hat{h}_j)$, then it implies that it is also a facet of $\text{hypo}(\hat{h}_j)$, and thus that

$$\mathcal{F}(x, \hat{h}_j) = \mathcal{F}(x', \hat{h}_j) .$$

Hence, it follows from Observation 3.26 (b) that $x = x'$, and therefore $(a'_j, h_j(a'_j)) \in \mathcal{F}(x, h_j)$. Therefore, we have

$$h_j(a'_j) + \langle x, a'_j \rangle = \max_{q_j \in Q_j} h_j(q_j) + \langle x, q_j \rangle = \max_{\alpha \in \mathcal{A}_j} f_{j, \alpha} + \langle x, \alpha \rangle = f(x) ,$$

and since $f^-(x) > f^+(x)$, this implies that $a'_j \in A_j^-$, and thus

$$f_{j, a'_j}^- + \langle x, a'_j \rangle = f^-(x) > f^+(x) \geq f_{j, a'_j}^+ + \langle x, a'_j \rangle ,$$

hence $f_{j, a'_j}^+ < f_{j, a'_j}^- = h_j(a'_j)$, thus inequality (\ddagger) is strict. \square

Proof of Theorem 4.1. We keep the notation of Section 4.3.1. We first look at the case of systems in the form $f^+(x) \geq f^-(x)$, as the result for the general case will follow from this case. For any subset \mathcal{E}' from \mathbb{Z}^n containing \mathcal{E} , we can construct the submatrices $\mathcal{M}_{\mathcal{E}\mathcal{E}'}^+ = (m_{pp'}^+)_{(p, p') \in \mathcal{E} \times \mathcal{E}'}$ and $\mathcal{M}_{\mathcal{E}\mathcal{E}'}^- = (m_{pp'}^-)_{(p, p') \in \mathcal{E} \times \mathcal{E}'}$ of respectively $\mathcal{M}_{\mathcal{E}}^+$ and $\mathcal{M}_{\mathcal{E}}^-$, similarly to Section 3.3.1, by setting $m_{pp'}^+$ to be the coefficient in p' of $X^{p-a_j} f_j^+$ where (j, a_j) is the row content of p , i.e.

$$m_{pp'}^\pm = \begin{cases} f_{j, a'_j}^\pm & \text{if } a'_j \in \mathcal{A}_j^\pm \\ 0 & \text{otherwise,} \end{cases}$$

where $a'_j \in \mathbb{Z}^n$ is such that $p' = p - a_j + a'_j$, as well as the matrices $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^\pm = (\widetilde{m}_{pp'}^\pm)_{(p, p') \in \mathcal{E} \times \mathcal{E}}$ defined by

$$\widetilde{m}_{pp'}^\pm = m_{pp'}^\pm - \tilde{h}(p' - \delta)$$

for all $p, p' \in \mathcal{E}$. We now show that the matrix $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^+$ is diagonally dominated by $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^-$, which will lead to the desired result. Let $p, p' \in \mathcal{E}$. Then:

- if $p' \neq p$, then $a'_j \neq a_j$ and thus the inequality $\widetilde{m}_{pp'}^- > \widetilde{m}_{pp'}^+$ is equivalent to the inequality

$$\tilde{h}(p' - \delta) > \tilde{h}(p - \delta) - f_{j, a_j}^- + f_{j, a'_j}^+ , \quad (13)$$

which follows directly from Lemma 4.11;

- if $p' = p$, then $a'_j = a_j$ and the inequality $\widetilde{m}_{pp}^- > \widetilde{m}_{pp}^+$ is equivalent to the inequality

$$f_{j, a_j}^- > f_{j, a_j}^+ ,$$

which is satisfied since $f_{j, a_j}^- + \langle x, a_j \rangle = f^-(x) > f^+(x) \geq f_{j, a_j}^+ + \langle x, a_j \rangle$.

Thus, the matrix $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^+$ is diagonally dominated by $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^-$, and therefore thanks to Lemma 4.5, this shows that the only solution to the inequation

$$\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^+ \odot \tilde{z} \geq \widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^- \odot \tilde{z}$$

of unknown $\tilde{z} \in \mathbb{R}_\infty^\mathcal{E}$ is $\tilde{z} = \mathbb{0}$.

Finally, using Lemma 4.7 and Lemma 4.8, we find that this implies that there cannot exist a vector $y \in \mathbb{R}^{\mathcal{E}'}$ such that $\mathcal{M}_{\mathcal{E}'}^+ \odot y \geq \mathcal{M}_{\mathcal{E}'}^- \odot y$.

Now for the general case, assume that there is no solution in \mathbb{R}^n to the system $f^+(x) \triangleright f^-(x)$. Then, for all $x \in \mathbb{R}^n$, there exists $1 \leq j \leq k$ such that

$$f_j^+(x) \not\triangleright_j f_j^-(x) .$$

We reiterate the construction of the matrices $\mathcal{M}_{\mathcal{E}\mathcal{E}}^\pm$ as above, as well as the renormalized matrices $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^\pm$, with the only difference that for $p \in \mathcal{E}$ with row content (j, a_j) , one might have either $a_j \in \mathcal{A}_j^+$ or $a_j \in \mathcal{A}_j^-$. In fact, applying (13) gives us this time that

$$\widetilde{m}_{pp}^- > \max_{p' \in \mathcal{E}} \widetilde{m}_{pp'}^+ \iff a_j \in \mathcal{A}_j^- \quad \text{and} \quad \widetilde{m}_{pp}^+ > \max_{p' \in \mathcal{E}} \widetilde{m}_{pp'}^- \iff a_j \in \mathcal{A}_j^+ .$$

In particular, this shows that the matrices $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^+$ and $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^-$ satisfy the condition (8) of Corollary 4.6. It thus follows from Lemma 4.11 that the matrices $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^+$ and $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^-$ satisfy the condition (8) of Corollary 4.6, hence the only solution to the system $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^+ \odot \tilde{z} \triangleright \widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^- \odot \tilde{z}$ of unknown $\tilde{z} \in \mathbb{R}_\infty^\mathcal{E}$ is $\tilde{z} = \mathbb{0}$, and using Lemma 4.7 and Lemma 4.8, we obtain there is no solution $y \in \mathbb{R}^{\mathcal{E}'}$ to the equation $\mathcal{M}_{\mathcal{E}'}^+ \odot y \triangleright \mathcal{M}_{\mathcal{E}'}^- \odot y$. \square

Remark 4.12. Note that in the previous construction, the matrices $\mathcal{M}_{\mathcal{E}\mathcal{E}}^\pm$ need not necessarily be submatrices of the matrices $\mathcal{M}_{\mathcal{E}}^\pm$, as the construction of the row content in this case could allow for one row of the Macaulay matrix to appear multiple times in $\mathcal{M}_{\mathcal{E}\mathcal{E}}^\pm$. This however does not have any impact on the outcome of the proof.

4.4 The case of hybrid systems

In fact, Theorem 4.1 can be generalized even further so as to also include relations of the form $f_i(x) \nabla \mathbb{0}$. More precisely, let f_1^\pm, \dots, f_k^\pm be a collection of pairs of tropical polynomials and let f_{k+1}, \dots, f_ℓ be a second collection of tropical polynomials. Keeping the notation of Section 4.1, the system we consider is the following

$$\begin{cases} f_i^+(x) \triangleright_i f_i^-(x) & \text{for } 1 \leq i \leq k \\ f_i(x) \nabla \mathbb{0} & \text{for } k+1 \leq i \leq \ell \end{cases} , \quad (\mathcal{S}_{\text{pol}})$$

with $\triangleright_i \in \{\geq, =, >\}$ for all $1 \leq i \leq k$. Recall also that

$$r_i = \begin{cases} \dim(\text{aff}(\mathcal{A}_i^-)) + 1 & \text{if } \triangleright_i \in \{\geq, >\} \\ \max(\dim(\text{aff}(\mathcal{A}_i^-)), \dim(\text{aff}(\mathcal{A}_i^+))) + 1 & \text{if } \triangleright_i \in \{=\} \end{cases} .$$

We define Canny-Emiris subsets \mathcal{E} of \mathbb{Z}^n associated to system $(\mathcal{S}_{\text{pol}})$ to be sets of the form

$$\mathcal{E} := (\widetilde{Q} + \delta) \cap \mathbb{Z}^n \quad \text{with} \quad \widetilde{Q} = r_1 Q_1 + \dots + r_k Q_k + Q_{k+1} + \dots + Q_\ell ,$$

where δ is a generic vector in $V + \mathbb{Z}^n$, with V the direction of the affine hull of \widetilde{Q} . Then we have the following result.

Theorem 4.13 (Sparse tropical Positivstellensatz for hybrid systems). *The system $(\mathcal{S}_{\text{pol}})$ has a solution $x \in \mathbb{R}^n$ if and only if the linear tropical system*

$$\begin{cases} \mathcal{M}_{\mathcal{E}'}^+ \odot y \triangleright \mathcal{M}_{\mathcal{E}'}^- \odot y \\ \mathcal{M}_{\mathcal{E}'} \odot y \nabla \mathbb{0} \end{cases} \quad (\mathcal{S}_{\text{lin}})$$

has a solution $y \in \mathbb{R}^{\mathcal{E}'}$, where $\mathcal{M}^+, \mathcal{M}^-$ is the pair of Macaulay matrices associated to system $f_i^+(x) \triangleright_i f_i^-(x)$ for $1 \leq i \leq k$, \mathcal{M} is the Macaulay matrix associated to system $f_i(x) \nabla \mathbb{0}$ for $k+1 \leq i \leq \ell$, and \mathcal{E}' is any subset of \mathbb{Z}^n containing a nonempty Canny-Emiris subset \mathcal{E} of \mathbb{Z}^n associated to the system $(\mathcal{S}_{\text{pol}})$.

Proof. This proof is mainly combination of the proofs of Theorem 3.5 and Theorem 4.1, so we will just give the outline of the proof and skip the details to avoid repetition. Moreover, as previously, the existence of a root $x \in \mathbb{R}^n$ to the polynomial easily implies the existence of an element $y \in \mathbb{R}^{\mathcal{E}'}$ solution of the system $(\mathcal{S}_{\text{lin}})$, given by the Veronese embedding.

Assume that system $(\mathcal{S}_{\text{pol}})$ does not have a root in \mathbb{R}^n . Then this means that for all $x \in \mathbb{R}^n$, either $f_j(x) \not\triangleright \mathbb{0}$ for some $k+1 \leq j \leq \ell$, or $f_j^+(x) \not\triangleright_j f_j^-(x)$ for some $1 \leq i \leq k$ (or possibly both cases can

happen at the same time). This allows us to construct a notion of row content for this case in the following way.

First, we define the maps h_1, \dots, h_ℓ as in the proofs of Theorem 3.5 and Theorem 4.1, and set

$$\tilde{h} := h_1^{\square r_1} \square \dots \square h_k^{\square r_k} \square h_{k+1} \square \dots \square h_\ell .$$

Then for all $p \in (\tilde{Q} + \delta) \cap \mathbb{Z}^n$, the point $(p - \delta, \tilde{h}(p - \delta))$ lies in the relative interior of a facet \tilde{F} of $\text{hypo}(\tilde{h})$, and this facet can be written as

$$\tilde{F} = r_1 F_1 + \dots + r_k F_k + F_{k+1} + \dots + F_\ell ,$$

where for all $1 \leq j \leq \ell$, F_j is a facet of $\text{hypo}(h_j)$, and there exists an element x of V such that $\tilde{F} = \mathcal{F}(\tilde{h}, x)$ and for all $1 \leq j \leq \ell$, $F_j = \mathcal{F}(h_j, x)$. Then:

- if there exists $k + 1 \leq j \leq \ell$ such that $f_j(x) \not\propto 0$, then F_j is a singleton $\{a_j\}$, and we set the row content of p to be the pair (j, a_j) , where such an index j is taken to be maximal;
- if $f_j(x) \nabla 0$ for all $k + 1 \leq j \leq \ell$, then since x is not a root of $(\mathcal{S}_{\text{pol}})$, this implies that there exists $1 \leq j \leq k$ such that $f_j^+(x) \not\propto_j f_j^-(x)$, and this time we can construct the row content of x using the Shapley-Folkman lemma as in the proof of Theorem 4.1.

Now for $p \in \mathcal{E}$ with row content (j, a_j) , if $1 \leq j \leq k$, then we apply Lemma 4.11 to obtain that for all $p' \in \mathcal{E}$ and $a'_j \in \mathbb{Z}^n$ such that $p' = p - a_j + a'_j$,

$$\tilde{h}(p' - \delta) > \tilde{h}(p - \delta) - f_{j,a_j}^- + f_{j,a'_j}^+ ,$$

and if $k + 1 \leq j \leq \ell$, then we apply Lemma 3.32 to obtain that for all $p' \in \mathcal{E}$ and $a'_j \in \mathbb{Z}^n$ such that $p' = p - a_j + a'_j$,

$$\tilde{h}(p' - \delta) > \tilde{h}(p - \delta) - f_{j,a_j} + f_{j,a'_j} ,$$

with equality if and only if $p' = p$. We denote \mathcal{E}_1 the set of $p \in \mathcal{E}$ satisfying the first condition, and \mathcal{E}_2 the set of $p \in \mathcal{E}$ satisfying the second condition, such that $\mathcal{E} = \mathcal{E}_1 \sqcup \mathcal{E}_2$.

Thus, we can construct as previously matrices $\mathcal{M}_{\mathcal{E}_1 \mathcal{E}}^+$, $\mathcal{M}_{\mathcal{E}_1 \mathcal{E}}^-$ and $\mathcal{M}_{\mathcal{E}_2 \mathcal{E}}$ such that $\mathcal{M}_{\mathcal{E}_1 \mathcal{E}}^-$ and $\mathcal{M}_{\mathcal{E}_1 \mathcal{E}}^+$ satisfy the condition (8) of Corollary 4.6, and $\mathcal{M}_{\mathcal{E}_2 \mathcal{E}}$ is diagonally dominant in the tropical sense.

From this point, it can easily be shown using a combination of Lemma 3.14 and 4.5 that the only solution $z \in \mathbb{R}_{\infty}^{\mathcal{E}}$ to the system

$$\begin{cases} \mathcal{M}_{\mathcal{E}_1 \mathcal{E}}^+ \odot z \triangleright \mathcal{M}_{\mathcal{E}_1 \mathcal{E}}^- \odot z \\ \mathcal{M}_{\mathcal{E}_2 \mathcal{E}} \odot z \nabla 0 , \end{cases}$$

is $z = 0$, and thus it follows that there is no solution $y \in \mathbb{R}^{\mathcal{E}'}$ to system $(\mathcal{S}_{\text{lin}})$. \square

4.5 More examples

Now let us illustrate Theorem 3.5 with an example. Consider the following problem

$$\begin{cases} 0x_1 \oplus 0x_1x_2 & \geq & 0x_2 \\ 2 \oplus 0x_1 & \geq & 1x_2 \\ 3 & \geq & 0x_1 \end{cases} \implies 1x_1 \geq 0x_2 \oplus (-3)x_1^2 . \quad (\mathcal{P})$$

We want to show that the implication in (\mathcal{P}) holds. This is the case if and only if the system

$$\begin{cases} 0x_1 \oplus 0x_1x_2 & \geq & 0x_2 \\ 2 \oplus 0x_1 & \geq & 1x_2 \\ 3 & \geq & 0x_1 \\ 0x_2 \oplus (-3)x_1^2 & > & 1x_1 \end{cases} \quad (\mathcal{S})$$

does not have a solution $x \in \mathbb{R}^2$. We can turn the strict inequality into a weak inequality by noticing that the latter system does not have a solution on \mathbb{R}^2 if and only if for all $\lambda > 1 = 0$, the system

$$\begin{cases} 0x_1 \oplus 0x_1x_2 & \geq & 0x_2 \\ 2 \oplus 0x_1 & \geq & 1x_2 \\ 3 & \geq & 0x_1 \\ 0x_2 \oplus (-3)x_1^2 & \geq & \lambda \odot 1x_1 \end{cases} \quad (\mathcal{S}'_\lambda)$$

does not have a solution $x \in \mathbb{R}^2$.

We thus set

$$\begin{array}{lll}
 f_1^+ = 0x_1 \oplus 0x_1x_2 & f_1^- = 0x_2 & f_1 = 0x_1 \oplus 0x_2 \oplus 0x_1x_2 \\
 f_2^+ = 2 \oplus 0x_1 & f_2^- = 1x_2 & f_2 = 2 \oplus 0x_1 \oplus 1x_2 \\
 f_3^+ = 3 & f_3^- = 0x_1 & f_3 = 3 \oplus 0x_1 \\
 f_4^+ = 1x_1 & f_4^- = 0x_2 \oplus (-3)x_1^2 & f_4 = 1x_1 \oplus 0x_2 \oplus (-3)x_1^2
 \end{array}$$

On Figure 8, we show the Newton polytopes associated to the polynomials f_1, f_2, f_3 and f_4 as well as their Minkowski sum. Moreover, on Figures 9 and 10, we show on the left the configuration of hypersurfaces associated respectively to (\mathcal{P}) and (\mathcal{S}'_λ) . In this configuration, we colored every intersection point by the colors of the curves that do not take part in the intersection, and we reported the coloring on the matching cell of the decomposition of Q on the right, as to illustrate the duality between the hypersurface configuration and the subdivision of Q .

Figure 8: The Newton polytopes associated f_1, f_2, f_3, f_4 and their Minkowski sum.

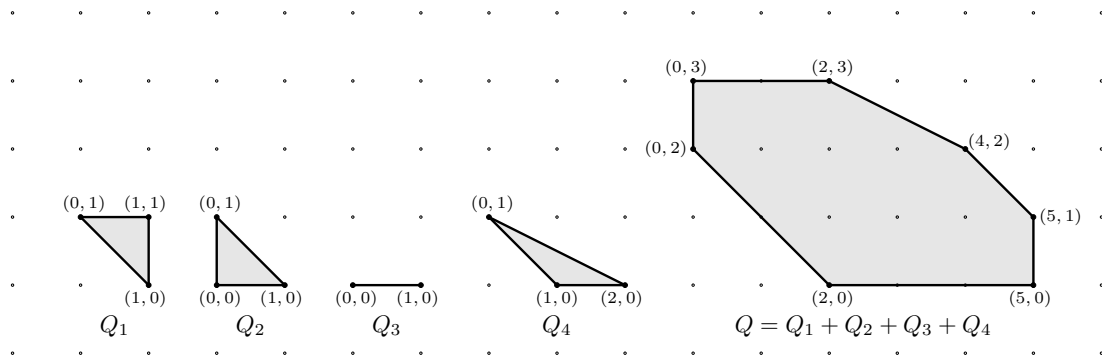


Figure 9: Problem (\mathcal{P}) is illustrated here as the tropical basic semialgebraic set $\{f_1^+ \geq f_1^-\} \cap \{f_2^+ \geq f_2^-\} \cap \{f_3^+ \geq f_3^-\}$ is indeed included in the set $\{f_4^+ \geq f_4^-\}$. The subdivision of Q associated to this system is displayed on the right.

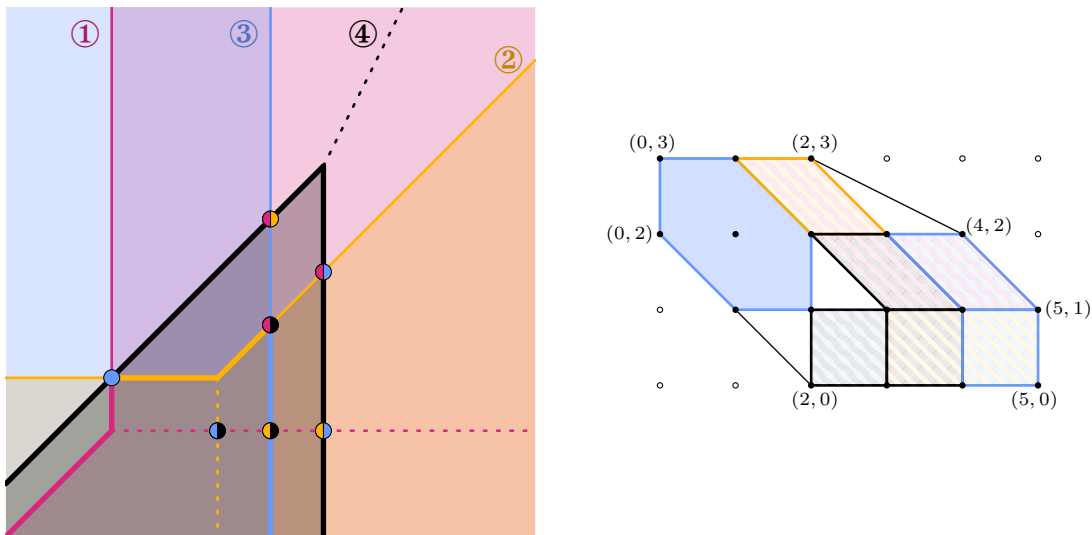
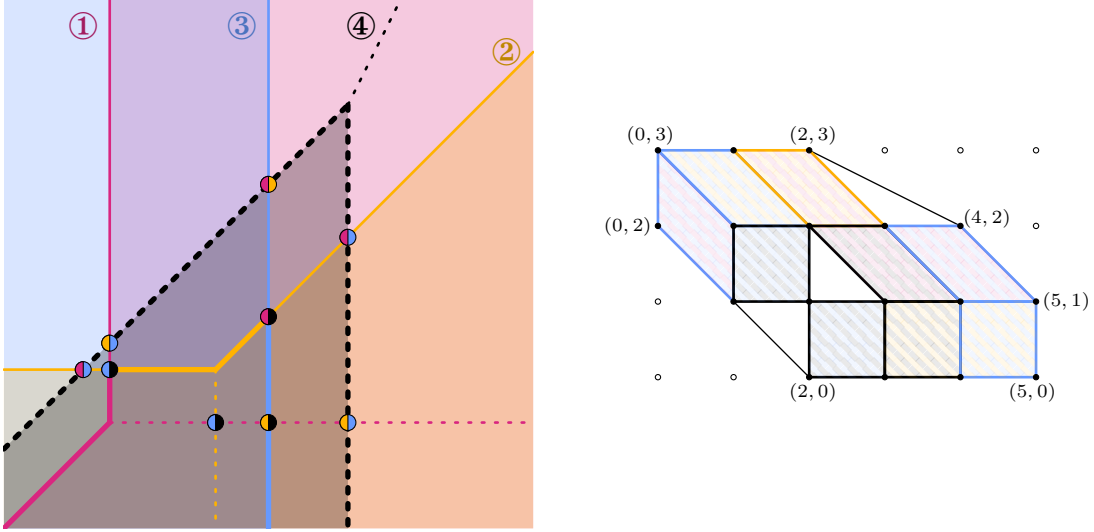


Figure 10: For all $\lambda > 0$, the tropical basic semialgebraic set $\{f_1^+ \geq f_1^-\} \cap \{f_2^+ \geq f_2^-\} \cap \{f_3^+ \geq f_3^-\}$ is indeed included in the set $\{\lambda \odot f_4^+ > f_4^-\}$, showing that system (S'_λ) does not have a solution in \mathbb{R}^2 . The subdivision of Q associated to this system is displayed on the right.



For this collection of supports, one can once take $\delta = (-1 + \varepsilon, -1 + \varepsilon)$ with $\varepsilon = \frac{1}{10}$, which gives us the Canny-Emiris set

$$\mathcal{E} = \{(1, 0), (0, 1), (2, 0), (1, 1), (0, 2), (3, 0), (2, 1), (1, 2), (4, 0), (3, 1)\}$$

corresponding to the set of monomials

$$\{x_1, x_2, x_1^2, x_1x_2, x_2^2, x_1^3, x_1^2x_2, x_1x_2^2, x_1^4, x_1^3x_2\}.$$

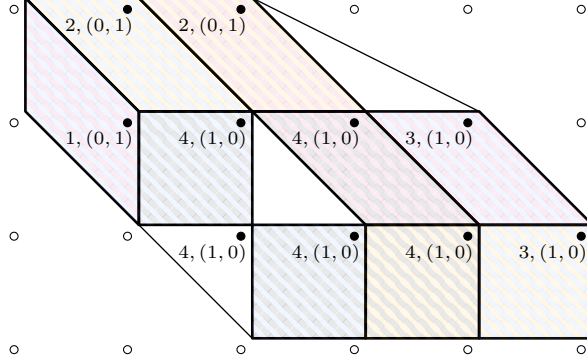
We thus obtain the 21×10 submatrices $\mathcal{M}_\mathcal{E}^+$ and $\mathcal{M}_\mathcal{E}^-$ of the Macaulay matrix associated to the set \mathcal{E} , which we combined in the single following matrix for the sake of readability and to save some space, with the normal font weight coefficients corresponding to the coefficients of $\mathcal{M}_\mathcal{E}^+$, and the bold ones corresponding to $\mathcal{M}_\mathcal{E}^-$

$$\mathcal{M}_\mathcal{E}^\pm = \begin{pmatrix} f_1 & x_1 & x_2 & x_1^2 & x_1x_2 & x_2^2 & x_1^3 & x_1^2x_2 & x_1x_2^2 & x_1^4 & x_1^3x_2 \\ x_1f_1 & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ x_2f_1 & & & & & & & & & & & \mathbf{0} \\ x_1^2f_1 & & & & & & & & & & & \mathbf{0} \\ x_1f_2 & 2 & & 0 & \mathbf{1} & & & & & & & \mathbf{0} \\ x_2f_2 & & 2 & & 0 & \mathbf{1} & & & & & & \mathbf{0} \\ x_1^2f_2 & & & 2 & & & 0 & \mathbf{1} & & & & \mathbf{0} \\ x_1x_2f_2 & & & & 2 & & & 0 & \mathbf{1} & & & \mathbf{0} \\ x_1^3f_2 & & & & & & 2 & & & 0 & \mathbf{1} & \mathbf{0} \\ x_1f_3 & 3 & & \mathbf{0} & & & & & & & & \mathbf{0} \\ x_2f_3 & & 3 & & \mathbf{0} & & & & & & & \mathbf{0} \\ x_1^2f_3 & & & 3 & & & \mathbf{0} & & & & & \mathbf{0} \\ x_1x_2f_3 & & & & 3 & & & \mathbf{0} & & & & \mathbf{0} \\ x_2^2f_3 & & & & & 3 & & & \mathbf{0} & & & \mathbf{0} \\ x_1^3f_3 & & & & & & 3 & & & \mathbf{0} & & \mathbf{0} \\ x_1^2x_2f_3 & & & & & & & 3 & & & & \mathbf{0} \\ f_4 & \mathbf{1 + \lambda} & \mathbf{0} & \mathbf{-3} & & & & & & & & \mathbf{0} \\ x_1f_4 & & & \mathbf{1 + \lambda} & \mathbf{0} & & \mathbf{-3} & & & & & \mathbf{0} \\ x_2f_4 & & & & \mathbf{1 + \lambda} & \mathbf{0} & & \mathbf{-3} & & & & \mathbf{0} \\ x_1^2f_4 & & & & & \mathbf{1 + \lambda} & & \mathbf{0} & & \mathbf{-3} & & \mathbf{0} \\ x_1x_2f_4 & & & & & & \mathbf{1 + \lambda} & \mathbf{0} & & \mathbf{-3} & & \mathbf{-3} \end{pmatrix}.$$

Applying the Canny-Emiris construction to the collection of polynomials in the system (S'_λ) , we obtain the subdivision of Q which allows us to associate to every point $p \in \mathcal{E}$ its row content i, a_i , which we

recall is univocally determined by the maximal-dimensional cell of the decomposition of Q to which $p - \delta$ belongs, as illustrated in Figure 11.

Figure 11: The polytope $Q + \delta$, with the integer points inside the maximal dimensional cells of the decomposition of $Q + \delta$ labelled by the row content the cell they belong to.



More precisely, in the following table, for each point p of \mathcal{E} in the first row:

- the second row displays the monomial x^p which corresponds to a column of the Macaulay matrix,
- the third row displays the row content i, a_i of p ,
- the fourth row displays the polynomial $x^{p-a_i} f_i$ which corresponds to a row of the Macaulay matrix,
- and finally the last row displays the tropical scaling factor $h(p - \delta)$ which must be subtracted (in the usual sense) to the column p of the matrices $\mathcal{M}_{\mathcal{E}\mathcal{E}}^{\pm}$ in order to obtain the matrix $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^{\pm}$.

$p \in \mathcal{E}$	(1, 0)	(0, 1)	(2, 0)	(1, 1)	(0, 2)	(3, 0)	(2, 1)	(1, 2)	(4, 0)	(3, 1)
x^p	x_1	x_2	x_1^2	$x_1 x_2$	x_2^2	x_1^3	$x_1^2 x_2$	$x_1 x_2^2$	x_1^4	$x_1^3 x_2$
i, a_i	4, (1, 0)	1, (0, 1)	4, (1, 0)	4, (1, 0)	2, (0, 1)	4, (1, 0)	4, (1, 0)	2, (0, 1)	3, (1, 0)	3, (1, 0)
$x^{p-a_i} f_i$	f_4	f_1	$x_1 f_4$	$x_2 f_4$	$x_2^2 f_2$	$x_1^2 f_4$	$x_1 x_2 f_4$	$x_1 x_2^2 f_2$	$x_1^3 f_3$	$x_1^2 x_2 f_3$
$h(p - \delta)$	$6 + \lambda$	$\frac{51+9\lambda}{10}$	$\frac{42}{10} + \lambda$	$\frac{51}{10} + \lambda$	$\frac{41+\lambda}{10}$	$\frac{13}{10} + \lambda$	$\frac{25}{10} + \lambda$	$\frac{17+\lambda}{10}$	$\frac{-26+\lambda}{10}$	$\frac{-13+2\lambda}{10}$

With the information from the previous table, we obtain the following 10×10 pair of square submatrices $\mathcal{M}_{\mathcal{E}\mathcal{E}}^{\pm}$ of $\mathcal{M}_{\mathcal{E}}^{\pm}$

$$\mathcal{M}_{\mathcal{E}\mathcal{E}}^{\pm} = \begin{pmatrix} f_4 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 & x_1^3 & x_1^2 x_2 & x_1 x_2^2 & x_1^4 & x_1^3 x_2 \\ f_1 & 1 + \lambda & 0 & -3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ x_1 f_4 & 0 & 0 & 1 + \lambda & 0 & 0 & -3 & 0 & 0 & 0 & 0 \\ x_2 f_4 & 0 & 0 & 0 & 1 + \lambda & 0 & 0 & -3 & 0 & 0 & 0 \\ x_2 f_2 & 0 & 2 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ x_1^2 f_4 & 0 & 0 & 0 & 0 & 0 & 1 + \lambda & 0 & 0 & -3 & 0 \\ x_1 x_2 f_4 & 0 & 0 & 0 & 0 & 0 & 0 & 1 + \lambda & 0 & 0 & -3 \\ x_1 x_2 f_2 & 0 & 0 & 2 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ x_1^3 f_3 & 0 & 0 & 0 & 0 & 0 & 3 & 0 & 0 & 0 & 0 \\ x_1^2 x_2 f_3 & 0 & 0 & 0 & 0 & 0 & 0 & 3 & 0 & 0 & 0 \end{pmatrix}.$$

Finally, after applying the tropical scaling of factor $h(p - \delta)$ to the column p of the previous matrices for all $p \in \mathcal{E}$, we obtain the following pair of matrices

$$\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}}^{\pm} = -\frac{1}{10} \begin{pmatrix} 50 & 51 + 9\lambda & 72 + 10\lambda & 51 + 10\lambda & 51 + 10\lambda & 43 + 10\lambda & 55 + 10\lambda & 17 + \lambda & 4 + \lambda & 17 + 2\lambda \\ 60 + 10\lambda & 51 + 9\lambda & 32 & 51 + 10\lambda & 41 & 41 + \lambda & 25 + 10\lambda & 15 & 7 + \lambda & 17 + 2\lambda \\ 31 + 9\lambda & 51 + 10\lambda & 31 + \lambda & 51 + 10\lambda & 31 + 10\lambda & 3 & 25 + 10\lambda & 7 + \lambda & -26 + \lambda & 17 + 2\lambda \\ 31 + 10\lambda & 31 + 10\lambda & -17 + 10\lambda & 31 + 10\lambda & -17 + 10\lambda & -5 + 10\lambda & -26 + \lambda & -13 + 2\lambda & -13 + 2\lambda & -13 + 2\lambda \end{pmatrix}$$

and we indeed observe for every $\lambda > 0$ that for each row, the diagonal coefficient of $\widetilde{\mathcal{M}}_{\varepsilon\varepsilon}^-$ is strictly greater than all the coefficients of $\widetilde{\mathcal{M}}_{\varepsilon\varepsilon}^+$ in the same row, or in other words that $\widetilde{\mathcal{M}}_{\varepsilon\varepsilon}^+$ is diagonally dominated by $\widetilde{\mathcal{M}}_{\varepsilon\varepsilon}^-$, and thus from Lemmas 4.5 and 4.7, the only solution to the equation $\mathcal{M}_{\varepsilon\varepsilon}^+ \odot y \geq \mathcal{M}_{\varepsilon\varepsilon}^- \odot y$ in \mathbb{R}^{10} is $y = \mathbb{0}$.

5 Concluding remarks

We have developed a new approach to the tropical Nullstellensatz, initially established by Grigoriev and Podolskii [GP18]. Our proof relies on a fundamental tool of sparse elimination theory, the Canny-Emiris set [CE93, Emi05, Stu94]. This leads to improved bounds on the truncation degree. We also obtained tropical Positivstellensätze, allowing one to deal both with strict and weak inequalities. For the simplest systems of tropical relations — requiring maxima to be achieved twice — this approach leads to a tight truncation degree, as discussed in Remark 3.8. For more general systems, our proof method is based on a new definition of the row content, exploiting a discrete geometry result (the Shapley-Folkman lemma), and it leads to a ‘dilation’ of the Canny-Emiris set by a factor up to $n + 1$. Whether this dilation could be avoided is left as an open problem.

We provided in [Bé23], following [ABG23], a first implementation of the present method. So far, we only considered the feasibility problem. We note however that by a dichotomy approach, one can find an explicit (exact) solution of a feasible system with rational coefficients, using the present tools. We also observe that in some special cases, unfeasibility certificates may be obtained by considering smaller linearizations. This suggests the possibility to develop accelerated algorithms, for instance, constructing dynamically linearizations with increased rows and columns sets. Such refinements will be developed elsewhere.

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