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Hierarchical Probabilistic Graphical Models and Deep Convolutional Neural Networks for Semantic Segmentation of Remote Sensing Images

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INTRODUCTION

Innía

This work deals with the challenge of semantic segmentation based on deep learning methods in the case of realistic scarce ground truth maps. Exhaustive ground truths usually found in benchmark datasets can be used to train deep learning architectures successfully. On the contrary, real-world ground truths are almost never exhaustive, they are spatially sparse and typically they don't represent the spatial borders among the classes, affecting the accuracy of the resulting segmentation maps significantly.

Here, the proposed approach addresses precisely this challenge with a novel combination of hierarchical probabilistic graphical models (PGMs) and deep neural networks. The rationale is to exploit the spatial modeling capabilities of hierarchical PGMs to mitigate the impact of incomplete ground truth and obtain accurate classification results in scenarios where exhaustive ground truth does not exist.

RESULTS









PROPOSED METHOD



The idea is to integrate the multiscale data representation extracted by a fully convolutional network (FCN) with a hierarchical PGM through a quadtree topology:

- 1. An FCN is trained with a dataset of very high-resolution images. Activations at *L* different blocks are associated with a quadtree topology.
- 2. An ensemble approach (Random Forest, RF) links the representation extracted by the FCN and the Bayesian inference structure of the PGM.
- 3. A hierarchical PGM is defined on the quadtree to model multiscale and longrange spatial dependencies over the pixel lattice.

A neighborhood relation \leq is introduced to ensure causality over the pixel lattice. The proposed PGM is causal and the joint distribution of all labels and feature vectors in the quadtree is entirely defined by (a) (b) (c) (d) Figure 1. Ground truth and classification maps: (a) IRRG image, (b) ground truth; classification maps obtained by (c) the FCN (U-Net) and (d) the proposed method. Classes: building, road, vegetation, tree, car, clutter.

The ISPRS semantic labeling challenge Potsdam and Vaihingen datasets were used for the experiments. To approach realistic ground truths, several training conditions were considered, e.g., the removal of a percentage of labeled pixels and morphological erosion. The estimation of the posterior probabilities used to link the FCN and the PGM was also performed in different ways, resulting in different formulations of the proposed method.

	Architecture	building	road	vegetation	tree	car	OA	recall	precision	К	F1 score
Full dataset	Standard U-Net	0.92	0.83	0.71	0.92	0.74	0.85	0.83	0.84	0.79	0.83
	Standard SegNet	0.90	0.73	0.73	0.92	0.67	0.83	0.79	0.81	0.76	0.80
	DeepLabV3+	0.91	0.87	0.66	0.90	0.80	0.84	0.83	0.82	0.78	0.82
	Proposed	0.87	0.84	0.71	0.92	0.89	0.82	0.83	0.78	0.75	0.80
Erosion	Standard U-Net	0.91	0.92	0.15	0.62	0.27	0.87	0.57	0.77	0.75	0.66
	Proposed	0.88	0.87	0.51	0.60	0.70	0.86	0.71	0.68	0.72	0.69
70% unlab.	Standard U-Net	0.83	0.92	0.55	0.87	0.80	0.80	0.79	0.74	0.72	0.76
	Proposed	0.82	0.85	0.76	0.86	0.96	0.82	0.85	0.72	0.76	0.78
Connected components	Standard U-Net	0.96	0.65	0.47	0.89	0.48	0.76	0.69	0.81	0.66	0.75
	Multiscale feature fusion	0.91	0.75	0.44	0.87	0.51	0.76	0.70	0.64	0.67	0.72
	Proposed	0.94	0.68	0.49	0.86	0.74	0.76	0.74	0.76	0.67	0.75

CONCLUSIONS

• Novel technique that combines FCNs and hierarchical probabilistic graphical models to overcome the critical problem of the impact of spatially sparse ground truth on semantic segmentation maps obtained by deep learning methods.

- the transition probabilities across the scales $P(x_s|x_{s^-})$
- the past neighbor transition probabilities within each layer $P(x_s | x_r, r \preceq s)$
- the pixelwise class-conditional likelihoods $P(y_s|x_s)$

and the inference is addressed through the marginal posterior mode criterion:



- Very effective in the discrimination of minority classes.
- Advantageous in terms of recall and computational burden.
- These advantages are more remarkable the more the training set approaches the real case scenario of spatially sparse ground truth.

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