# CryptoVerif: a Computationally-Sound Security Protocol Verifier <br> Bruno Blanchet, Charlie Jacomme 

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## inréa

# CryptoVerif: a Computationally-Sound Security Protocol Verifier 

Bruno Blanchet, Charlie Jacomme

## RESEARCH

# CryptoVerif: a Computationally-Sound Security Protocol Verifier 

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#### Abstract

This document presents the security protocol verifier CryptoVerif. CryptoVerif does not rely on the symbolic, Dolev-Yao model, but on the computational model. It can verify secrecy, correspondence properties (which include authentication), and indistinguishability properties. It produces proofs presented as sequences of games, like those manually written by cryptographers; these games are formalized in a probabilistic process calculus. CryptoVerif provides a generic method for specifying security properties of the cryptographic primitives. It produces proofs valid for any number of sessions of the protocol, and provides an upper bound on the probability of success of an attack against the protocol as a function of the probability of breaking each primitive and of the number of sessions. CryptoVerif is post-quantum sound: when the used cryptographic assumptions are valid for quantum adversaries, the proofs hold for quantum adversaries. It can work automatically, or the user can guide it with manual proof indications.


Key-words: security protocols, verification, computational model

[^0]
## CryptoVerif: un vérificateur de protocoles cryptographiques sûr dans le modèle calculatoire

Résumé : Ce document présente le vérificateur de protocoles cryptographiques CryptoVerif. CryptoVerif ne s'appuie pas sur le modèle symbolique de Dolev-Yao, mais sur le modèle calculatoire. Il peut vérifier le secret, les correspondances (qui comprennent l'authentification) et les propriétés d'indistinguabilité. Il produit des preuves par suites de jeux, comme celles écrites manuellement par les cryptographes ; ces jeux sont formalisés dans un calcul de processus probabiliste. CryptoVerif fournit une méthode générique pour spécifier les propriétés de sécurité des primitives cryptographiques. Il produit des preuves valables pour un nombre quelconque de sessions du protocole, et fournit une borne supérieure sur la probabilité de succès d'une attaque contre le protocole en fonction de la probabilité de casser chaque primitive et du nombre de sessions. CryptoVerif est sûr contre des attaquants quantiques : quand les hypothèses cryptographiques utilisées sont valides pour des attaquants quantiques, les preuves produites sont valides pour des attaquants quantiques. Il peut fonctionner automatiquement, ou l'utilisateur peut guider la preuve manuellement.

Mots-clés : protocoles cryptographiques, vérification, modèle calculatoire

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## 1 Introduction

There exist two main approaches for analyzing security protocols. In the computational model, messages are bitstrings, and the adversary is a probabilistic polynomial-time Turing machine. This model is close to the real execution of protocols, but the proofs are usually manual and informal. In contrast, in the symbolic, Dolev-Yao model, cryptographic primitives are considered as perfect blackboxes, modeled by function symbols in an algebra of terms, possibly with equations. The adversary can compute using only these blackboxes. This abstract model makes it easier to build automatic verification tools, but the security proofs are in general not sound with respect to the computational model.

In contrast to most previous protocol verifiers, CryptoVerif works directly in the computational model, without considering the Dolev-Yao model. It produces proofs valid for any number of sessions of the protocol, in the presence of an active adversary. These proofs are presented as sequences of games, as used by cryptographers $22,66,67$ : the initial game represents the protocol to prove; the goal is to bound the probability of breaking a certain security property in this game; intermediate games are obtained each from the previous one by transformations such that the difference of probability between consecutive games can easily be bounded; the final game is such that the desired probability is obviously bounded from the form of the game. (In general, it is simply 0 in that game.) The desired probability can then be easily bounded in the initial game. We represent games in a process calculus defining oracles interacting with an adversary. This calculus tries to mimick how classical cryptographic games are defined.

In this calculus, messages are bitstrings, and cryptographic primitives are functions from bitstrings to bitstrings. The calculus has a probabilistic semantics. The main tool for specifying security properties is indistinguishability: $Q$ is indistinguishable from $Q^{\prime}$ up to probability $p$, $Q \approx_{p} Q^{\prime}$, when the adversary has probability at most $p$ of distinguishing $Q$ from $Q^{\prime}$. With respect to previous calculi used for representing cryptographic games, our calculus introduces an important novelty which is key for the automatic proof of security protocols: the values of all variables during the execution of a process are stored in arrays. For instance, $x[i]$ is the value of $x$ in the $i$-th copy of the process that defines $x$. Arrays represent global variables that are shared between all processes, and each cell can be given a value by a process for instance through an assignment or a random sampling. After being given a value, cells cannot be updated anymore. Arrays replace lists often used by cryptographers in their manual proofs of protocols. For example, consider the standard security assumption on a message authentication code (MAC). Informally, this definition says that the adversary has a negligible probability of forging a MAC, that is, that all correct MACs have been computed by calling the MAC oracle (i.e., function). So, in cryptographic proofs, one defines a list containing the arguments of calls to the MAC oracle, and when checking a MAC of a message $m$, one can additionally check that $m$ is in this list, with a negligible change in probability. In our calculus, the arguments of the MAC oracle are stored in arrays, and we perform a lookup in these arrays in order to find the message $m$. Arrays make it easier to automate proofs since they are always present in the calculus: one does not need to add explicit instructions to insert values in them, in contrast to the lists used in manual proofs. Therefore, many trivially sound but difficult to automate syntactic transformations disappear. Furthermore, relations between elements of arrays can easily be expressed by equalities, possibly involving computations on array indices.

CryptoVerif relies on a collection of game transformations, in order to transform the initial protocol into a game on which the desired security property is obvious. The most important kind of transformations exploits the security assumptions on cryptographic primitives in order to obtain a simpler game. As described in Section 5.2, these transformations can be specified in a generic way: we represent the security assumption of each cryptographic primitive by an
observational equivalence $L \approx_{p} R$, where the processes $L$ and $R$ encode oracles: they receive the arguments of the oracle and return its result. Then, the prover can automatically transform a process $Q$ that calls the oracles of $L$ (more precisely, contains as subterms terms that perform the same computations as oracles of $L$ ) into a process $Q^{\prime}$ that calls the oracles of $R$ instead. We have used this technique to specify several variants of shared-key and public-key encryption, signature, message authentication codes, hash functions, Diffie-Hellman key agreement, simply by giving the appropriate equivalence $L \approx_{p} R$ to the prover. Other game transformations are syntactic transformations, used in order to be able to apply an assumption on a cryptographic primitive, or to simplify the game obtained after applying such an assumption.

In order to prove protocols, these game transformations are organized using a proof strategy based on advice: when a transformation fails, it suggests other transformations that should be applied before, in order to enable the desired transformation. Thanks to this strategy, simple protocols can often be proved in a fully automatic way. For delicate cases, CryptoVerif has an interactive mode, in which the user can manually specify the transformations to apply. It is often sufficient to specify a few well-chosen case distinctions and transformations coming from the security assumptions of primitives, by indicating the concerned cryptographic primitive and the concerned secret key if any; the prover infers the intermediate syntactic transformations by the advice strategy. This mode is helpful for instance for proving some public-key protocols, in which several security assumptions on primitives can be applied, but only one leads to a proof of the protocol. Importantly, CryptoVerif is always sound: whatever indications the user gives, when the prover shows a security property of the protocol, the property indeed holds assuming the given assumptions on the cryptographic primitives.

Finally, as we demonstrate in the rest of the this document, CryptoVerif is post-quantum sound: when the used cryptographic assumptions are valid for quantum adversaries, the proofs hold for quantum adversaries. The game transformations performed by CryptoVerif are valid not only against a classical probabilistic Turing-machine adversary, but also against a quantum adversary. More generally, they are valid against any kind of interactive black-box adversary that can simulate bounded time probabilistic Turing machines, limited by the cryptographic assumptions.

In addition to the oracle-based process calculus, CryptoVerif also allows to define games in a channel-based process calculus inspired by the applied pi calculus [1,2] and by the calculi of [59] and of 55. The channel-based calculus is presented in Section 2.6 with a translation to the oracle-based calculus. The channel-based calculus was the initial version of the calculus used by CryptoVerif, as detailed in a previous report 29]. Future developments will use the oracle-based calculus with the semantics presented in this document. This language allowed us to prove the post-quantum soundness of CryptoVerif. It is closer to classical computational proofs and paves the way for important extensions, such as sharing parts of the code in calls to internal oracles, composition results, and loops implemented by recursive oracle calls, as it is easier to inline oracle calls than channel communications.

CryptoVerif has been implemented in OCaml (more than 60000 lines of code) and is available at http://cryptoverif.inria.fr/.

Related Work Various methods have been proposed for verifying security protocols in the computational model. Following the seminal paper by Abadi and Rogaway [3], many results show the soundness of the Dolev-Yao model with respect to the computational model, which makes it possible to use Dolev-Yao provers in order to prove protocols in the computational model (see, e.g., 7, 37, 41, 42,50 and the survey [40). However, these results have limitations, in particular in terms of allowed cryptographic primitives (they must satisfy strong security properties so that they correspond to Dolev-Yao style primitives), and they require some restrictions on
protocols (such as the absence of key cycles). A tool [39] was developed based on 41] to obtain computational proofs using the formal verifier AVISPA, for protocols that rely on public-key encryption and signatures.

Several frameworks exist for formalizing proofs of protocols in the computational model. Backes, Pfitzmann, and Waidner [9,10 designed an abstract cryptographic library and showed its soundness with respect to computational primitives, under arbitrary active attacks. This framework has been used for a computationally-sound machine-checked proof of the Needham-Schroeder-Lowe protocol 70,71$]$. Canetti [34] introduced the notion of universal composability. With Herzog [36], they show how a Dolev-Yao-style symbolic analysis can be used to prove security properties of protocols within the framework of universal composability, for a restricted class of protocols using public-key encryption as only cryptographic primitive. Then, they use the automatic Dolev-Yao verification tool ProVerif 24 for verifying protocols in this framework. Process calculi have been designed for representing cryptographic games, such as the probabilistic polynomial-time calculus of $[59]$ and the cryptographic lambda-calculus of 62] Logics have also been designed for proving security protocols in the computational model, such as the computational variant of PCL (Protocol Composition Logic) 46, 47 and CIL (Computational Indistinguishability Logic) [13]. Canetti et al. 35] use the framework of time-bounded taskPIOAs (Probabilistic Input/Output Automata) to prove security protocols in the computational model. This framework makes it possible to combine probabilistic and non-deterministic behaviors. These frameworks can be used to prove security properties of protocols in the computational sense, but except for [36] which relies on a Dolev-Yao prover, they have not been automated up to now, as far as we know.

Several techniques have been used for directly mechanizing proofs in the computational model. Type systems 45,55 57 69 provide computational security guarantees. For instance, 55] handles shared-key and public-key encryption, with an unbounded number of sessions, by relying on the Backes-Pfitzmann-Waidner library. A type inference algorithm is given in 8. The recent tool OWL [48] also relies on a type system that provides computational security guarantees. It supports MACs, public-key signatures, authenticated symmetric and public key encryption, random oracles, and the gap Diffie-Hellman assumption 63. It can prove secrecy and integrity properties. In another line of research, a specialized Hoare logic was designed for proving asymmetric encryption schemes in the random oracle model 43,44 .

The tool CertiCrypt $[14,15,17,19,20$ enables the machine-checked construction and verification of cryptographic proofs by sequences of games 22,68 . It relies on the general-purpose proof assistant Coq, which is widely believed to be correct. Nowak et al. [5, 60, 61 follow a similar idea by providing Coq proofs for several cryptographic primitives. More recently, frameworks for cryptographic proofs in Coq, FCF [64], and in Isabelle, CryptHOL 18], have been designed and used for proving cryptographic schemes. EasyCrypt [16] , the successor of CertiCrypt, no longer generates Coq proofs, but provides a higher automation level by relying on SMT solvers, which makes the tool easier to use. Even if it focuses more on cryptographic primitives and schemes than on protocols, it has been used for proving some protocols such as one-round key exchange [12], e-voting [38, AWS key management [6], and distance bounding [31]. These frameworks and tools can perform more subtle reasoning than CryptoVerif, at the cost of more user effort: the user has to give all games and guide the proof that the games are indistinguishable. That becomes tedious for large protocols, which require many large games.

The tool Squirrel [11] relies on a computationaly sound logic that allows to write interactive proofs of, e.g., stateful protocols. Still, it currently proves a security notion weaker than the standard one: the number of sessions of the protocol must be bounded independently of the security parameter (instead of being polynomial in the security parameter).

Independently, we have built the tool CryptoVerif 26 to help cryptographers, not only for
the verification, but also by generating the proofs by sequences of games 22,68 , automatically or with little user interaction. In particular, CryptoVerif generates the games, possibly using the indications of which transformations to perform. This tool extends considerably early work by Laud [53 54 which was limited either to passive adversaries or to a single session of the protocol. More recently, Tšahhirov and Laud [56, 72] developed a tool similar to CryptoVerif but that represents games by dependency graphs. It handles public-key and shared-key encryption and proves secrecy properties; it does not provide bounds on the probability of success of an attack.

Outline The next section presents our process calculus for representing games, with its syntax, type system, formal semantics, as well as the definition of security properties. Section 3 collects information about games and reasons using it. Section 4 gives criteria for proving security properties of protocols. Section 5 describes the game transformations that we use for proving protocols. Section 6 explains how the prover chooses which transformation to apply at each point.

Notations We recall the following notations. We denote by $\left\{M_{1} / x_{1}, \ldots, M_{m} / x_{m}\right\}$ the substitution that replaces $x_{j}$ with $M_{j}$ for each $j \in\{1, \ldots, m\}$. The cardinal of a set or multiset $S$ is denoted by $|S|$. Multisets $S$ are represented by functions that map each element $x$ of $S$ to the number of occurrences of $x$ in $S$, that is, when $S$ is a multiset, $S(x)$ is the number of elements of $S$ equal to $x$. We use $\uplus$ for multiset union, defined by $\left(S_{1} \uplus S_{2}\right)(x)=S_{1}(x)+S_{2}(x)$. When $S$ and $S^{\prime}$ are multisets, $\max \left(S, S^{\prime}\right)$ is the multiset such that $\max \left(S, S^{\prime}\right)(x)=\max \left(S(x), S^{\prime}(x)\right)$. The notation $\left\{x_{1} \mapsto a_{1}, \ldots, x_{m} \mapsto a_{m}\right\}$ designates the function that maps $x_{j}$ for $a_{j}$ for each $j \in\{1, \ldots, m\}$ and is undefined for other inputs. When $f$ is a function, $f[x \mapsto a]$ is the function that maps $x$ to $a$ and all other elements as $f$. If $S$ is a finite set, $x \stackrel{R}{\leftarrow} S$ chooses a random element uniformly in $S$ and assigns it to $x$. If $\mathcal{A}$ is a probabilistic algorithm, $x \leftarrow \mathcal{A}\left(x_{1}, \ldots, x_{m}\right)$ denotes the experiment of choosing random coins $r$ and assigning to $x$ the result of running $\mathcal{A}\left(x_{1}, \ldots, x_{m}\right)$ with coins $r$. Otherwise, $x \leftarrow M$ is a simple assignment statement. If $D$ is a discrete probability distribution, we denote by $D(a)$ the probability that $X=a, \operatorname{Pr}[X=a]$, where $X$ is a random variable with probability distribution $D$, and we denote by $a \stackrel{R}{\leftarrow} D$ the random sampling of a value following the distribution $D$. We denote by $\operatorname{Distr}(S)$ the set of discrete probability distributions over a set $S$. We denote by $\emptyset$ the empty stack, and a non empty stack $\mathcal{S} t$ can be denoted by $a:: \mathcal{S} t_{l}$, where $a$ is then the head of $\mathcal{S} t$ and $\mathcal{S} t_{l}$ its tail stack.

## 2 A Calculus for Cryptographic Games

### 2.1 Syntax and Informal Semantics

CryptoVerif represents games in the syntax of Figure 1. This syntax assumes a countable set of oracles names, denoted by $O$. It uses parameters, denoted by $n$, which are integers that bound the number of executions of oracles.

It also uses types, denoted by $T$, which are sets of values. So that types can be meaningfully interpreted by an attacker, we assume that there exists an efficient bijection from the disjoint union of all types to bitstrings. That implies in particular that all types are countable.

A type is fixed when it is the set of all bitstrings of a certain length; a type is bounded when it is a finite set. Particular types are predefined: bool $=\{$ true, false $\}$, where false is 0 and true is 1 ; bitstring is the set of all bitstrings; bitstring $\perp_{\perp}=$ bitstring $\cup\{\perp\}$ where $\perp$ is a special symbol; $[1, n]$ is the set of integers $\{1, \ldots, n\}$, where $n$ is a parameter. (We consider integers as bitstrings without leading zeroes.) We denote by any the specific type corresponding to the empty set of

```
\(M, N::=\)
    \(x\left[M_{1}, \ldots, M_{m}\right]\)
    \(f\left(M_{1}, \ldots, M_{m}\right)\)
    \(x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; N\)
    let \(p=M\) in \(N\) else \(N^{\prime}\)
    let \(x \widetilde{i}]: T=M\) in \(N\)
    if \(M\) then \(N\) else \(N^{\prime}\)
    find [unique?] \(\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}\) suchthat
        defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}^{\prime}\) then \(\left.N_{j}\right)\) else \(N^{\prime} \quad\) array lookup
    insert \(\operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; N \quad\) insert in table
    get[unique?] \(\operatorname{Tbl}\left(p_{1}, \ldots, p_{l}\right)\) suchthat \(M\) in \(N\) else \(N^{\prime}\)
    event \(e\left(M_{1}, \ldots, M_{l}\right) ; N\)
    event_abort \(e\)
\(p::=\)
    \(x[\widetilde{i}]: T\)
    \(f\left(p_{1}, \ldots, p_{m}\right)\)
    \(=M\)
\(Q::=\)
    0
    \(Q \mid Q^{\prime}\)
    foreach \(i \leq n\) do \(Q\)
    newOracle \(O ; Q\)
    \(O \widetilde{[i}](p):=P\)
\(P::=\quad\) oracle body
    return \((N) ; Q \quad\) return
    let \(p=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i]} \leq n_{1}, \ldots, ? u_{m} \widetilde{[i]} \leq n_{m}\right](N)\) in \(P\) else \(P^{\prime}\)
        oracle call
    \(x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P \quad\) random number
    let \(p=M\) in \(P\) else \(P^{\prime} \quad\) assignment
    if \(M\) then \(P\) else \(P^{\prime}\) conditional
    find \([\) unique? \(]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}\) suchthat
        defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}\) then \(\left.P_{j}\right)\) else \(P \quad\) array lookup
    insert \(\operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; P \quad\) insert in table
    get[unique?] \(T b l\left(p_{1}, \ldots, p_{l}\right)\) suchthat \(M\) in \(P\) else \(P^{\prime}\)
    event \(e\left(M_{1}, \ldots, M_{l}\right) ; P\)
    event_abort \(e\)
    yield end
```

Figure 1: Syntax for games
values, which is thus contained in any other type. No other type can be empty, and any cannot be used within the syntax of the games.

The syntax also uses function symbols $f$. Each function symbol comes with a type declaration $f: T_{1} \times \ldots \times T_{m} \rightarrow T$, and represents an efficiently computable, deterministic function that maps each tuple in $T_{1} \times \ldots \times T_{m}$ to an element of $T$. Particular functions are predefined, and some of them use the infix notation: $M=N$ for the equality test, $M \neq N$ for the inequality test (both taking two values of the same type $T$ and returning a value of type bool), $M \vee N$ for the boolean or, $M \wedge N$ for the boolean and, $\neg M$ for the boolean negation (taking and returning values of type bool), tuples $\left(M_{1}, \ldots, M_{m}\right)$ (taking values of any types and returning values of type bitstring; tuples are assumed to provide unambiguous concatenation, with tags for the types of $M_{1}, \ldots, M_{m}$ so that tuples of different types are always different); test if fun $\left(M_{1}, M_{2}, M_{3}\right)$ (with a first argument of type bool and the last two arguments of the same type $T$; it returns a value of type $T: M_{2}$ when $M_{1}$ is true and $M_{3}$ when $M_{1}$ is false).

In this syntax, terms represent computations on bitstrings. The replication index $i$ is an integer which serves in distinguishing different copies of a replicated oracle foreach $i \leq n$ do. (Replication indices are typically used as array indices.) The variable access $x\left[M_{1}, \ldots, M_{m}\right]$ returns the content of the cell of indices $M_{1}, \ldots, M_{m}$ of the $m$-dimensional array variable $x$. We use $x, y, z, u$ as variable names. The function application $f\left(M_{1}, \ldots, M_{m}\right)$ returns the result of applying function $f$ to $M_{1}, \ldots, M_{m}$ Terms contain additional constructs which are very similar to those also included in oracle bodies and explained below. These constructs conclude by evaluating a term, instead of executing an oracle body. The construct event_abort $e$ executes event $e$ (without argument) and aborts the game.

The calculus distinguishes two kinds of processes, oracle definitions and oracle bodies.
An oracle definition $Q$ defines a set of parallel oracles ready to be called, each oracle being defined with a body $P$ that may end with a return value, followed by a potential new oracle definition $Q^{\prime}$.

The oracle definition 0 defines no oracle; $Q \mid Q^{\prime}$ is the parallel composition of $Q$ and $Q^{\prime}$, it defines both oracles in $Q$ and in $Q^{\prime}$; foreach $i \leq n$ do $Q$ represents $n$ copies of $Q$ in parallel, each with a different value of $i \in[1, n]$; newOracle $O ; Q$ creates a new private oracle $O$ and executes $Q$; this construct is useful in proofs, but does not occur in games manipulated by CryptoVerif. The oracle declaration $O \widetilde{i}](p):=P$ defines the oracles $O[\widetilde{i}]$, where the indices $\widetilde{i}$ are bound by the replications above the oracle declaration $O \widetilde{[ }](p):=P$. The oracle $O \widetilde{i}]$ executes the oracle body $P$ when it is called with an argument that matches the pattern $p$. It will be explained in more detail below together with the semantics of the oracle call let $p=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i}\right] \leq$ $\left.n_{1}, \ldots, ? u_{m} \widetilde{[i]} \leq n_{m}\right](N)$ in $P$ else $P^{\prime}$.

The oracle body construct $x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P$ chooses a new random value in $T$, stores it in $x[\widetilde{i}]$, and executes $P$. The abbreviation $\widetilde{i}$ stands for a sequence of replication indices $i_{1}, \ldots, i_{m}$. The random value is chosen according to the default distribution $D_{T}$ for type $T$, which is determined as follows:

- When the type $T$ is declared with option nonuniform, the default probability distribution $D_{T}$ for type $T$ may be non-uniform. It is left unspecified.
- Otherwise, if $T$ is fixed, $T$ consists of all bitstrings of a certain length, and the default distribution is the uniform distribution. The probability of each element of $T$ is $1 /|T|$.
- If $T$ is bounded but not fixed, $T$ is finite, and the default distribution is an approximately uniform distribution, such that its distance to the uniform distribution is at most $\epsilon_{T}$. The
distance between two probability distributions $D_{1}$ and $D_{2}$ for type $T$ is

$$
d\left(D_{1}, D_{2}\right)=\frac{1}{2} \sum_{a \in T}\left|D_{1}(a)-D_{2}(a)\right|
$$

Indeed, probabilistic Turing machines that run in bounded time cannot choose random elements exactly uniformly in sets whose cardinal is not a power of 2 .

For example, a possible algorithm to obtain a random integer in $[0, m-1]$ is to choose a random integer $x^{\prime}$ uniformly among $\left[0,2^{k}-1\right]$ for a certain $k$ large enough and return $x^{\prime} \bmod m$. By euclidean division, we have $2^{k}=q m+r$ with $r \in[0, m-1]$. With this algorithm

$$
D(a)= \begin{cases}\frac{q+1}{2^{k}} & \text { if } a \in[0, r-1] \\ \frac{q}{2^{k}} & \text { if } a \in[r, m-1]\end{cases}
$$

so

$$
\left|D(a)-\frac{1}{m}\right|= \begin{cases}\frac{q+1}{2^{k}}-\frac{1}{m} & \text { if } a \in[0, r-1] \\ \frac{1}{m}-\frac{q}{2^{k}} & \text { if } a \in[r, m-1]\end{cases}
$$

Therefore

$$
\begin{aligned}
d\left(D_{T}, \text { uniform }\right) & =\frac{1}{2} \sum_{a \in T}\left|D(a)-\frac{1}{m}\right|=\frac{1}{2} r\left(\frac{q+1}{2^{k}}-\frac{1}{m}\right)-\frac{1}{2}(m-r)\left(\frac{1}{m}-\frac{q}{2^{k}}\right) \\
& =\frac{r(m-r)}{m \cdot 2^{k}} \leq \frac{m}{2^{k+1}}
\end{aligned}
$$

so we can take $\epsilon_{T}=\frac{m}{2^{k+1}}$. A given precision of $\epsilon_{T}=\frac{1}{2^{k^{\prime}}}$ can be obtained by choosing $k=\left(k^{\prime}+\right.$ number of bits of $\left.m\right)$ random bits.
By default, CryptoVerif does not display $\epsilon_{T}$ in probability formulas, to make them more readable.

When $T$ is not declared with any of the options nonuniform, fixed, or bounded, CryptoVerif rejects the construct $x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P$. Function symbols represent deterministic functions, so all random numbers must be chosen by $x[\widetilde{i}] \stackrel{R}{\leftarrow} T$. Deterministic functions make automatic syntactic manipulations easier: we can duplicate a term without changing its value.

The construct let $x \widetilde{i}]: T=M$ in $P$ stores the value of $M$ (which must be in $T$ ) in $x \widetilde{i}]$ and executes $P$. Furthermore, we say that a function $f: T_{1} \times \ldots \times T_{m} \rightarrow T$ is efficiently injective when it is injective and its inverses are efficiently computable, that is, there exist functions $f_{j}^{-1}: T \rightarrow T_{j}(1 \leq j \leq m)$ such that $f_{j}^{-1}\left(f\left(x_{1}, \ldots, x_{m}\right)\right)=x_{j}$ and $f_{j}^{-1}$ is efficiently computable. When $f$ is efficiently injective, we define a pattern matching construct let $f\left(x_{1}, \ldots, x_{m}\right)=$ $M$ in $P$ else $P^{\prime}$ as an abbreviation for let $y: T=M$ in let $x_{1}^{\prime}: T_{1}=f_{1}^{-1}(y)$ in $\ldots$ let $x_{m}^{\prime}$ : $T_{m}=f_{m}^{-1}(y)$ in if $f\left(x_{1}^{\prime}, \ldots, x_{m}^{\prime}\right)=y$ then (let $x_{1}: T_{1}=x_{1}^{\prime}$ in $\ldots$ let $x_{m}: T_{m}=x_{m}^{\prime}$ in $P$ ) else $P^{\prime}$ where $y, x_{1}^{\prime}, \ldots, x_{m}^{\prime}$ are fresh variables. (The variables $x_{1}^{\prime}, \ldots, x_{m}^{\prime}$ are introduced to make sure that none of the variables $x_{1}, \ldots, x_{m}$ is defined when the pattern-matching fails.) We naturally generalize this construct to let $p=M$ in $P$ else $P^{\prime}$ where $p$ is built from variables, efficiently injective functions, and equality tests. When $p$ is simply a variable, the pattern-matching always succeeds, so the else branch of the assignment is never executed and can be omitted. In this case, the alternative syntax $x \leftarrow M ; P$ is a synonym for let $x=M$ in $P$.

The construct event $e\left(M_{1}, \ldots, M_{l}\right) ; P$ executes the event $e\left(M_{1}, \ldots, M_{l}\right)$, then runs $P$. This event records that a certain program point has been reached with certain values of $M_{1}, \ldots, M_{l}$,
but otherwise does not affect the execution of the oracle. Events are used in particular for specifying security properties.

The construct event_abort $e$ executes event $e$ (without argument) and aborts the game.
Next, we explain the construct find[unique? $\left.]\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{i}\right]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq$ $n_{j m_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $P$. The order and array indices on tuples are taken component-wise, so for instance, $u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i]}=i_{j m_{j}} \leq n_{j m_{j}}$ can be further abbreviated $\left.\widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$. A simple example is the following: find $u=i \leq n$ suchthat defined $(x[i]) \wedge x[i]=a$ then $P^{\prime}$ else $P$ tries to find an index $i$ such that $x[i]$ is defined and $x[i]=a$, and when such an $i$ is found, it stores it in $u$ and executes $P^{\prime}$ with that value of $u$; otherwise, it executes $P$. In other words, this find construct looks for the value $a$ in the array $x$, and when $a$ is found, it stores in $u$ an index such that $x[u]=a$. Therefore, the find construct allows us to access arrays, which is key for our purpose. More generally, find $u_{1}[\widetilde{i}]=$ $\left.i_{1} \leq n_{1}, \ldots, u_{m} \widetilde{[i}\right]=i_{m} \leq n_{m}$ suchthat defined $\left(M_{1}, \ldots, M_{l}\right) \wedge M$ then $P^{\prime}$ else $P$ tries to find values of $i_{1}, \ldots, i_{m}$ for which $M_{1}, \ldots, M_{l}$ are defined and $M$ is true. In case of success, it stores the obtained values in $u_{1} \widetilde{[i]}, \ldots, u_{m} \widetilde{[i]}$ and executes $P^{\prime}$. In case of failure, it executes $P$. This is further generalized to $m$ branches: find $\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $P$ tries to find a branch $j$ in $[1, m]$ such that there are values of $i_{j 1}, \ldots, i_{j m_{j}}$ for which $M_{j 1}, \ldots, M_{j l_{j}}$ are defined and $M_{j}$ is true. In case of success, it stores them in $u_{j 1} \widetilde{[i]}, \ldots, u_{j m} \widetilde{[i]}$ and executes $P_{j}$. In case of failure for all branches, it executes $P$. More formally, it evaluates the conditions defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ for each $j$ and each value of $i_{j 1}, \ldots, i_{j m_{j}}$ in $\left[1, n_{j 1}\right] \times \ldots \times\left[1, n_{j m_{j}}\right]$. If none of these conditions is true, it executes $P$. Otherwise, it chooses randomly one $j$ and one value of $i_{j 1}, \ldots, i_{j m_{j}}$ such that the corresponding condition is true, according to the distribution $D_{\text {find }}(S)$ where $S$ is the set of possible solutions $j, i_{j 1}, \ldots, i_{j m_{j}}$, stores it in $\left.u_{j 1} \widetilde{[ }\right], \ldots, u_{j m_{j}} \widetilde{[i]}$, and executes $P_{j}$. The distribution $D_{\text {find }}(S)$ is almost uniform: formally, the distance between $D_{\text {find }}(S)$ and the uniform distribution is at most $\epsilon_{\text {find }} / 2$, that is, $d\left(D_{\text {find }}(S)\right.$, uniform $) \leq \epsilon_{\text {find }} / 2$, that is, $\frac{1}{2} \sum_{v \in S}\left|D_{\text {find }}(S)(v)-\frac{1}{|S|}\right| \leq \frac{\epsilon_{\text {find }}}{2}$, so that, when $|S|=\left|S^{\prime}\right|$, for any bijection $\phi: S \rightarrow S^{\prime}, \frac{1}{2} \sum_{v \in S}\left|D_{\text {find }}(S)(v)-D_{\text {find }}\left(S^{\prime}\right)(\phi(v))\right| \leq \epsilon_{\text {find }}$. Moreover $D_{\text {find }}(S)\left(v_{i}\right)=D_{|S|}(i)$ where $S=\left\{v_{1}, \ldots, v_{|S|}\right\}$ with the values $v_{i}$ ordered in increasing order lexicographically, for some distribution $D_{|S|}$ that depends only on the cardinal of $S$. In other words, the probability of a value $v_{i}$ in the distribution $D_{\text {find }}(S)$ does not depend on the values in the set $S$ but only on the number $|S|$ of elements of $S$ and on the position $i$ of the value $v_{i}$ in $S$ ordered in increasing order lexicographically. Therefore, transformations that do not modify the number of successful values nor their order, that is, transformations that map elements $v$ of $S$ to elements $\phi(v)$ of $S^{\prime}$ at the same position $i$, preserve the probabilities exactly and we do not need to add $\epsilon_{\text {find }}$ to the probability when we apply such a transformation. This is true for instance when we remove a branch of find that is never taken. By default, CryptoVerif does not display $\epsilon_{\text {find }}$ in probability formulas, to make them more readable. We cannot take the first element found because the game transformations made by CryptoVerif may reorder the elements. For these transformations to preserve the behavior of the game, the distribution of the chosen element must be invariant by reordering, up to a small probability $\epsilon_{\text {find }}$. In this definition, the variables $i_{j 1}, \ldots, i_{j m_{j}}$ are considered as replication indices, while $\left.\left.u_{j 1} \widetilde{[i}\right], \ldots, u_{j m_{j}} \widetilde{[i}\right]$ are considered as array variables. The indication [unique?] stands for either [unique ${ }_{e}$ ] or empty. The empty case has just been explained. When the find is marked [unique ${ }_{e}$ ] and there are several solutions that make the condition of the find evaluate to true, we execute the event $e$ and abort the game. When there is zero or one solution, the find is executed as when [unique?] is empty. This semantics allows us to perform game transformations that require the find to have a single solution.

The conditional if $M$ then $P$ else $P^{\prime}$ executes $P$ if $M$ evaluates to true. Otherwise, it executes
$P^{\prime}$. CryptoVerif also supports the conditional if defined $\left(M_{1}, \ldots, M_{l}\right) \wedge M$ then $P$ else $P^{\prime}$, which executes $P$ if $M_{1}, \ldots, M_{l}$ are defined and $M$ evaluates to true. Otherwise, it executes $P^{\prime}$. This conditional is internally encoded as find suchthat defined $\left(M_{1}, \ldots, M_{l}\right) \wedge M$ then $P$ else $P^{\prime}$. The conjunct $M$ can be omitted when it is true, writing if defined $\left(M_{1}, \ldots, M_{l}\right)$ then $P$ else $P^{\prime}$.

The constructs insert and get handle tables, used for instance to store the keys of the protocol participants. A table can be represented as a list of tuples; insert $\operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; P$ inserts the element $M_{1}, \ldots, M_{l}$ in the table $T b l$; get $\operatorname{Tbl}\left(x_{1}: T_{1}, \ldots, x_{l}: T_{l}\right)$ suchthat $M$ in $P$ else $P^{\prime}$ tries to retrieve an element $\left(x_{1}, \ldots, x_{l}\right)$ in the table $T b l$ such that $M$ is true. When such an element is found, it executes $P$ with $x_{1}, \ldots, x_{l}$ bound to that element. (When several such elements are found, one of them is chosen randomly according to distribution $D_{\text {get }}(S)$ where $S$ is the set of indices of suitable elements, with $d\left(D_{\text {get }}(S)\right.$, uniform $) \leq \epsilon_{\text {find }} / 2$.) When no such element is found, $P^{\prime}$ is executed. We can generalize this construct to patterns instead of variables similarly to the let case. As in the case of find, the indication [unique?] stands for either [unique ${ }_{e}$ ] or empty. The empty case has just been explained. When the get is marked [unique ${ }_{e}$ ] and there are several solutions, we execute the event $e$ and abort the game. When there is zero or one solution, the get is executed as when [unique?] is empty. CryptoVerif internally translates the insert and get constructs into find.

Let us explain the return $(N)$, yield, and oracle call commands. A semantic configuration always contains an oracles execution stack, the head oracle being the one currently executed and the stack corresponding to the nested calls. It also contains a set of callable oracles.

Whenever we encounter an oracle declaration $O \widetilde{i}](p):=P$, this oracle is added to the set of callable oracles. Intuitively, it is then possible to call this oracle for the given indices and with an argument that matches the pattern $p$. In the following, we will consider that all oracle declarations are of the form $O[\widetilde{i}](x[\widetilde{i}]: T):=P$, where we encode the input pattern for $O \widetilde{i}](p):=$ $P$ as $O \widetilde{i}](x \widetilde{i}]: T):=$ let $p=x$ in $P$ else yield.

Whenever the head oracle executes an oracle call let $x[\widetilde{i}]: T=O\left[M_{1}, \ldots, M_{l}\right](N)$ in $P$ else $P^{\prime}$, one looks for an available oracle $O\left[a_{1}, \ldots, a_{l}\right]$ where $M_{1}, \ldots, M_{l}$ evaluate to $a_{1}, \ldots, a_{l}$. (Terms $M_{1}, \ldots, M_{l}$ are intuitively analogous to IP addresses and ports, which are numbers that the adversary may guess.) If no such callable oracle is found, the execution blocks. Otherwise, by the invariants given below, there is at most one such oracle $O\left[a_{1}, \ldots, a_{l}\right]\left(x^{\prime}\left[\widetilde{i^{\prime}}\right]: T^{\prime}\right):=P^{\prime \prime}$. This oracle is then executed: the argument $N$ is evaluated and stored in $x^{\prime}\left[\widetilde{i^{\prime}}\right]$ if it is in $T^{\prime}$ (otherwise the execution blocks). The well-typed condition is not a restriction for the attacker, as it can always use type conversion functions.

Finally, the oracle $O\left[a_{1}, \ldots, a_{l}\right]\left(x^{\prime}\left[\widetilde{i^{\prime}}\right]: T^{\prime}\right):=P^{\prime \prime}$ is removed from the set of callable oracles, the body $P^{\prime \prime}$ of the called oracle is pushed on top of the stack, and executed. In this situation, we then have a new oracle body currently being executed, and the second one in the stack is the latest oracle call let $x[\widetilde{i}]: T=O\left[M_{1}, \ldots, M_{l}\right](N)$ in $P$ else $P^{\prime}$ waiting for a return value.

When an oracle performs a return command return $\left(N^{\prime}\right) ; Q$, it returns normally, and the in branch of the caller is executed. In more details, we pop the return command from the execution stack. The head of the execution stack is then the latest oracle call, of the form let $x \widetilde{[i]}: T=O\left[M_{1}, \ldots, M_{l}\right](N)$ in $P$ else $P^{\prime}$. We evaluate $N^{\prime}$, store it in $\left.x \widetilde{i}\right]$ if it is in $T$ and continue the execution with $P$, in a similar fashion to an assignment. The oracles in $Q$, which follow the executed return command, are added to the set of callable oracles.

When an oracle performs a yield command, it returns abnormally, and the else branch of the caller is executed. In more detail, we also pop the yield command from the execution stack. The head of the execution stack is then the latest oracle call, of the form let $x \widetilde{i}]$ : $T=O\left[M_{1}, \ldots, M_{l}\right](N)$ in $P$ else $P^{\prime}$, and we execute $P^{\prime}$.

In the case of an oracle call with pattern matching let $p=O\left[M_{1}, \ldots, M_{l}\right](N)$ in $P$ else $P^{\prime}$, the pattern-matching is encoded as in assignments. The oracle body $P^{\prime}$ is executed in case the
pattern-matching fails. We note that in contrast to the assignment encoding, we still need an else branch for the specific failure case of yield that cannot be encoded with a conditional. Oracles that take several arguments or return several results are encoded using tuples and pattern-matching on tuples.

Oracle calls can be made with some unspecified indices, following the syntax

$$
\text { let } \left.x[\widetilde{i}]: T=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i]} \leq n_{1}, \ldots, ? u_{m} \widetilde{[i}\right] \leq n_{m}\right](N) \text { in } P \text { else } P^{\prime}
$$

In this case, we evaluate $M_{1}, \ldots, M_{l}$ to $a_{1}, \ldots, a_{l}$, and consider the set $S$ of oracles $O\left[a_{1}, \ldots, a_{l}\right.$, $\left.b_{1}, \ldots, b_{m}\right]$ among the set of callable oracles. We choose one of these oracles randomly following the probability distribution $D_{\text {call }}(S)$, which is approximately uniform like $D_{\text {find }}(S)$. Then we perform the call as explained above. In the remainder of the execution, ? $\left.u_{1}[\widetilde{i}], \ldots, ? u_{m} \widetilde{i}\right]$ are bound to $b_{1}, \ldots, b_{m}$. In a call to oracle $O$, only indices corresponding to replications that are directly above the oracle declaration of $O$ can be unspecified. Indices that are used inside a previous oracle definition must then be explicitly specified. For instance, if oracle $O_{2}$ is defined by

$$
\text { foreach } i_{1} \leq n_{1} \text { do } O_{1}\left[i_{1}\right]\left(p_{1}\right):=\ldots \text { return }(N) ; \text { foreach } i_{2} \leq n_{2} \text { do } O_{2}\left[i_{1}, i_{2}\right]\left(p_{2}\right):=\ldots
$$

in call to $O_{2}$, the first index $i_{1}$ must always be explicitly specified by a term $M_{1}$; the second index may either be specified by a term $M_{2}$ or left unspecified by ? $\left.u_{2} \widetilde{i}\right] \leq n_{2}$.

The execution depends on a parametric attacker $\mathcal{A}$. Whenever the execution stack is empty, the attacker can perform an oracle call, and the attacker receives the return of the last oracle in the stack. Oracle $O$ can be declared private with newOracle $O$, in which case only oracles under the scope of newOracle $O$ can call $O$, and in particular the attacker cannot. (This is useful in the proofs, although all oracles of protocols are often public.) In effect, the attacker can then be seen as controlling the network between communicating oracles.

An else branch of find, if, get, or let may be omitted when it is else yield. (Note that "else 0" would not be syntactically correct.) Similarly, ; yield may be omitted after event, $\stackrel{R}{\leftarrow}$, or insert and in yield may be omitted after let. A trailing 0 after a return may be omitted. We also omit oracle parameters and replication indices if there are none.

The current replication indices at a certain program point in a process are the replication indices $i_{1}, \ldots, i_{m}$ bound by replications and find above that program point. The replication foreach $i \leq n$ do $Q$ binds the replication index $i$ in $Q$. The find construct

$$
\begin{gathered}
\text { find }[\text { unique } ?]\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{i}\right]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i]}=i_{j m_{j}} \leq n_{j m_{j}} \text { suchthat } \\
\left.\quad \text { } \quad \text { defined }\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j} \text { then } \ldots\right) \\
\text { else } \ldots
\end{gathered}
$$

binds the replication indices $i_{j 1}, \ldots, i_{j m_{j}}$ in defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$. We often abbreviate $x\left[i_{1}, \ldots, i_{m}\right]$ by $x$ when $i_{1}, \ldots, i_{m}$ are the current replication indices at the definition of $x$, but it should be kept in mind that this is only an abbreviation. Variables defined under a replication must be arrays: for example foreach $i_{1} \leq n_{1}$ do $\ldots$ foreach $i_{m} \leq n_{m}$ do let $x\left[i_{1}, \ldots, i_{m}\right]: T=$ $M$ in ... More formally, we require the following invariant:

Invariant 1 (Single definition) The oracle definition $Q_{0}$ satisfies Invariant 1 if and only if

1. in every definition of $x\left[i_{1}, \ldots, i_{m}\right]$ in $Q_{0}$, the indices $i_{1}, \ldots, i_{m}$ of $x$ are the current replication indices at that definition, and
2. two different definitions of the same variable $x$ in $Q_{0}$ are in different branches of a find, if (or let), oracle call, or get.

In a let with pattern-matching, let $p=M$ in $P$ else $P^{\prime}$, the variables bound by $p$ are considered to be defined in the in branch; however, the variables defined in $M$ and in terms included in the pattern $p$ are defined before the branching.
Similarly, in an oracle call, let $\left.\left.p=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{i}\right] \leq n_{1}, \ldots, ? u_{m} \widetilde{i}\right] \leq n_{m}\right](N)$ in $P$ else $P^{\prime}$, the variables bound by $p$ are considered to be defined in the in branch; however, the variables defined in $N, M_{1}, \ldots, M_{l}$ and in terms included in the pattern $p$ as well as the variables $u_{1}, \ldots, u_{m}$ are defined before the branching.

In get[unique?] $\operatorname{Tbl}\left(p_{1}, \ldots, p_{l}\right)$ suchthat $M$ in $P$ else $P^{\prime}$, the variables bound by $p_{j}$ for $j \leq l$ and the variables defined in $M$ and in terms included in the patterns $p_{j}$ are (temporarily) defined before the branching.

Invariant 1 guarantees that each variable is assigned at most once for each value of its indices. (Indeed, item 2 shows that only one definition of each variable can be executed for given indices in each trace.) A definition of $x \widetilde{[i]}$ can be $x \widetilde{i}] \stackrel{R}{\leftarrow} T$, a let, get, or oracle declaration that
 $\left.O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i]} \leq n_{1}, \ldots, ? u_{m} \widetilde{[i}\right] \leq n_{m}\right](N)$ in $P$ else $P^{\prime}$ where $p$ contains the pattern $x \widetilde{[i]}: T$ or when $x[\widetilde{i}]$ is $u_{j}[\widetilde{i}]$ for some $j \leq m$.

Invariant 2 (Defined variables) The oracle definition $Q_{0}$ satisfies Invariant 2 if and only if every occurrence of a variable access $x\left[M_{1}, \ldots, M_{m}\right]$ in $Q_{0}$ is either

- syntactically under the definition of $x\left[M_{1}, \ldots, M_{m}\right]$ (in which case $M_{1}, \ldots, M_{m}$ are in fact the current replication indices at the definition of $x$ );
- or in a defined condition in a find command or term;
- or in $M_{j}^{\prime}$ in a process or term of the form find $\left(\bigoplus_{j=1}^{m^{\prime \prime}} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}} \operatorname{suchthat} \operatorname{defined}\left(M_{j 1}^{\prime}\right.$, $\left.\ldots, M_{j l_{j}}^{\prime}\right) \wedge M_{j}^{\prime}$ then $\left.P_{j}\right)$ else $P$ where for some $k \leq l_{j}, x\left[M_{1}, \ldots, M_{m}\right]$ is a subterm of $M_{j k}^{\prime}$.
- or in $P_{j}$ in a process or term of the form find $\left(\bigoplus_{j=1}^{m^{\prime \prime}} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$ suchthat defined $\left(M_{j 1}^{\prime}\right.$, $\left.\ldots, M_{j l_{j}}^{\prime}\right) \wedge M_{j}^{\prime}$ then $P_{j}$ ) else $P$ where for some $k \leq l_{j}$, there is a subterm $N$ of $M_{j k}^{\prime}$ such that $N\left\{\widetilde{u_{j}}[\widetilde{i}] / \widetilde{i_{j}}\right\}=x\left[M_{1}, \ldots, M_{m}\right]$.

Invariant 2 guarantees that variables can be accessed only when they have been initialized. It checks that the definition of the variable access is either in scope (first item) or checked by a find (last two items). The scope of variable definitions is defined as follows: $x[\widetilde{i}]$ is syntactically under its definition when it is

- inside $P$ in $x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P ;$
- inside $N$ in $x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; N$;
- inside $P$ in let $p=M$ in $P$ else $P^{\prime}$ when $x[\widetilde{i}]: T$ is bound in the pattern $p$;
- inside $N$ in let $p=M$ in $N$ else $N^{\prime}$ when $x \widetilde{[i]}: T$ is bound in the pattern $p$;
- inside $N$ in let $x[\widetilde{i}]: T=M$ in $N$;
- inside $P_{j}$ in find[unique?] $\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i}\right]=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $P$ when $x$ is $u_{j k}$ for some $k \leq m_{j}$;
- inside $N_{j}$ in find[unique? $\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i]}=i_{j m_{j}} \leq n_{j m_{j}}\right.$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.N_{j}\right)$ else $N$ when $x$ is $u_{j k}$ for some $k \leq m_{j}$;
- inside $M$ or $P$ in get[unique?] $T b l\left(p_{1}, \ldots, p_{l}\right)$ suchthat $M$ in $P$ else $P^{\prime}$ when $x[\widetilde{i}]: T$ is bound in one of the patterns $p_{1}, \ldots, p_{l}$;
- inside $M$ or $N$ in get[unique?] $\operatorname{Tbl}\left(p_{1}, \ldots, p_{l}\right)$ suchthat $M$ in $N$ else $N^{\prime}$ when $x \widetilde{[i]}: T$ is bound in one of the patterns $p_{1}, \ldots, p_{l}$;
- inside $P$ in $O \widetilde{[ }](p):=P$ when $x \widetilde{[ }]: T$ is bound in the pattern $p$.
- inside $P$ in let $\left.p=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i]} \leq n_{1}, \ldots, ? u_{m} \widetilde{[i}\right] \leq n_{m}\right](N)$ in $P$ else $P^{\prime}$ when $x \widetilde{i}]: T$ is bound in the pattern $p$, or when $x$ is $u_{m}$ for some $j \leq m$.

A variable access that does not correspond to the first item of Invariant 2 is called an array access. We furthermore require the following invariant. In this invariant, we consider a finite set of public variables $V$ : these variables are defined in the considered oracle definition $Q_{0}$ (though it may sometimes happen that they are never defined) and can be accessed by the adversary via the find construct.

Invariant 3 (Variables defined in find and get conditions) The oracle definition $Q_{0}$ satisfies Invariant 3 with public variables $V$ if and only if the variables defined in conditions of find and the variables defined in patterns and in conditions of get have no array accesses and are not in the set of variables $V$.

These conditions are needed for variables of get, because they will be transformed into variables defined in conditions of find by the transformation of get into find.

Invariant 4 (Terms in find and get conditions) The oracle definition $Q_{0}$ satisfies Invariant 4 if and only if event and insert do not occur in conditions of find and get.

Invariant 4 guarantees that evaluating the condition of a find or get does not change the state of the system.

Definition 1 A term is simple when it contains only replication indices, variables, and function applications.

Invariant 5 (Terms in defined conditions) The oracle definition $Q_{0}$ satisfies Invariant 5 if and only if the terms $M_{1}, \ldots, M_{l}$ in conditions defined $\left(M_{1}, \ldots, M_{l}\right)$ in find are simple.

Terms that are not simple are handled by expanding them into their corresponding oracle body commands. Invariant 5 is needed because terms in defined conditions cannot be expanded (see the transformation expand in Section 5.1.3). By combining this invariant with Invariant 2, we see that the terms of all variable accesses $x\left[M_{1}, \ldots, M_{m}\right]$ are simple.

Invariant 6 (Events) We distinguish three disjoint sets of events $e$, Shoup events, non-unique events, and other events. The oracle definition $Q_{0}$ satisfies Invariant 6 if and only if

- Shoup events occur only in processes or terms of the form event_abort $e$ in $Q_{0}$,
- non-unique events occur only in find[unique ${ }_{e}$ ] or get[unique $e_{e}$ ] in $Q_{0}$, and
- other events occur in event $e\left(M_{1}, \ldots, M_{l}\right)$ or in event_abort $e$ in $Q_{0}$.

The name "Shoup events" is used because these events are introduced when applying Shoup's lemma (68 (see Section 5.1.12). The non-unique events are those triggered when a find[unique ${ }_{e}$ ] or get $\left[u^{\prime}\right.$ nique $_{e}$ ] actually has several solutions.

To provide an invariant expressing that oracles for a given name are defined only once, we define the following multiset by induction on oracle definitions and bodies:

$$
\begin{aligned}
& \text { Defined }^{O}(0)=\emptyset \\
& \text { Defined }^{O}\left(Q_{1} \mid Q_{2}\right)=\text { Defined }^{O}\left(Q_{1}\right) \uplus \text { Defined }^{O}\left(Q_{2}\right) \\
& \text { Defined }^{O}(\text { foreach } i \leq n \text { do } Q)=\text { Defined }^{O}(Q) \\
& \text { Defined }^{O}(O \widetilde{[i]}(x[\widetilde{i}]: T):=P)=\{O\} \uplus \text { Defined }^{O}(P) \\
& \text { Defined }^{O}(\text { newOracle } O ; Q)=\text { Defined }^{O}(Q) \backslash\{O\} \\
& \text { Defined }^{O}\left(C\left[Q_{1}, \ldots, Q_{k}\right]\right)=\max _{j=1}^{k} \text { Defined }^{O}\left(Q_{j}\right)
\end{aligned}
$$

Here, we denote by $C$ an oracle body context, that is, a context with only oracle body constructs and several holes for oracle definitions as possible continuations, and $C\left[Q_{1}, \ldots, Q_{k}\right]$ corresponds to instantiating the continuations with the given processes. We use $C\left[Q_{1}, \ldots, Q_{k}\right]$ to define by induction the function at once for all oracle body constructs.

Invariant 7 (Single Oracle definition) The oracle definitions $Q_{0}$ satisfies Invariant 7 if and only if

1. in every oracle declaration of $O \widetilde{[i}](p)$ in $Q_{0}$, the indices $\widetilde{i}$ of $O$ are the current replication indices at that declaration, and
2. Defined ${ }^{O}\left(Q_{0}\right)$ does not contain duplicate elements.

Similar to the invariant 1 for variables, we guarantee that each oracle is correctly defined at most once. Thanks to this invariant, we can omit the indices of oracles in oracle declarations, writing $O(p):=P$ for $O \widetilde{i}](p):=P$ where $\widetilde{i}$ are the current replication indices at that declaration.

All these invariants are checked by the prover for the initial game and preserved by all game transformations.

We denote by $\operatorname{var}(P)$ the set of variables that occur in $P$, vardef $(P)$ the set of variables defined in $P(\operatorname{var}(P)$ may contain more variables than vardef $(P)$ in case some variables are read using find but never defined), and by fo $(P)$ the set of free oracles of $P$. (We use similar notations for oracle definitions.)

### 2.2 Example

Let us introduce two cryptographic primitives that we use below.

Definition 2 Let $T_{m k}$ and $T_{m s}$ be types that correspond intuitively to keys and message authentication codes, respectively; $T_{m k}$ is a fixed-length type. A message authentication code scheme MAC 21 consists of two function symbols:

- mac : bitstring $\times T_{m k} \rightarrow T_{m s}$ is the MAC algorithm taking as arguments a message and a key, and returning the corresponding tag. (We assume here that mac is deterministic; we could easily encode a randomized mac by adding random coins as an additional argument.)
- verify : bitstring $\times T_{m k} \times T_{m s} \rightarrow$ bool is a verification algorithm such that verify $(m, k, t)=$ true if and only if $t$ is a valid MAC of message $m$ under key $k$. (Since mac is deterministic, $\operatorname{verify}(m, k, t)$ is typically $\operatorname{mac}(m, k)=t$.

We have $\forall m \in$ bitstring, $\forall k \in T_{m k}$, verify $(m, k, \operatorname{mac}(m, k))=$ true.
The advantage of an adversary against unforgeability under chosen message attacks (UFCMA) is

$$
\operatorname{Succ}_{\mathrm{MAC}}^{\mathrm{uf}-\mathrm{cma}}\left(t, q_{m}, q_{v}, l\right)=\max _{\mathcal{A}} \operatorname{Pr}\left[\begin{array}{c}
k \stackrel{R}{\leftarrow} T_{m k} ;(m, s) \leftarrow \mathcal{A}^{\operatorname{mac}(., k), \text { verify }(., k, .)}: \operatorname{verify}(m, k, s) \\
\wedge m \text { was never queried to the oracle } \operatorname{mac}(., k)
\end{array}\right]
$$

where the adversary $\mathcal{A}$ is any probabilistic Turing machine that runs in time at most $t$, calls $\operatorname{mac}(., k)$ at most $q_{m}$ times with messages of length at most $l$, and calls verify (., $\left.k,.\right)$ at most $q_{v}$ times with messages of length at most $l$.
$\operatorname{Succ}_{\text {MAC }}^{\text {uf }-c m a ~}\left(t, q_{m}, q_{v}, l\right)$ is the probability that an adversary forges a MAC, that is, returns a pair $(m, s)$ where $s$ is a correct MAC for $m$, without having queried the MAC oracle $\operatorname{mac}(., k)$ on $m$. Intuitively, when the MAC is secure, this probability is small: the adversary has little chance of forging a MAC. Hence, the MAC guarantees the integrity of the MACed message because one cannot compute the MAC without the secret key.

Two frameworks exist for expressing security properties. In the asymptotic framework, used in [25, 26], the length of keys is determined by a security parameter $\eta$, and a MAC is UF-CMA when $\operatorname{Succ}_{\text {MAC }}^{\text {uf-cma }}\left(t, q_{m}, q_{v}, l\right)$ is a negligible function of $\eta$ when $t$ is polynomial in $\eta$. $(f(\eta)$ is negligible when for all polynomials $q$, there exists $\eta_{o} \in \mathbb{N}$ such that for all $\eta>\eta_{0}, f(\eta) \leq$ $\frac{1}{q(\eta)}$.) The assumption that functions are efficiently computable means that they are computable in time polynomial in $\eta$ and in the length of their arguments. The goal is to show that the probability of success of an attack against the protocol is negligible, assuming the parameters $n$ are polynomial in $\eta$ and the network messages are of length polynomial in $\eta$. In contrast, in the exact security framework, on which we focus in this report, one computes the probability of success of an attack against the protocol as a function of the probability of breaking the primitives such as $\operatorname{Succ}_{\mathrm{MAC}}^{\mathrm{uf}-\mathrm{cma}}\left(t, q_{m}, q_{v}, l\right)$, of the runtime of functions, of the parameters $n$, and of the length of messages, thus providing a more precise security result. Intuitively, the probability $\operatorname{Succ}_{\mathrm{MAC}}^{\text {uf-cma }}\left(t, q_{m}, q_{v}, l\right)$ is assumed to be small (otherwise, the computed probability of attack will be large), but no formal assumption on this probability is needed to establish the security theorem.

Definition 3 Let $T_{k}, T_{r}$, and $T_{e}$ be types for random coins, keys, and ciphertexts respectively. $T_{k}$ and $T_{r}$ are fixed-length types. A symmetric encryption scheme SE 21] consists of two function symbols:

- enc : bitstring $\times T_{k} \times T_{r} \rightarrow T_{e}$ is the encryption algorithm taking as arguments the cleartext, the key, and random coins, and returning the ciphertext,
- dec : $T_{e} \times T_{k} \rightarrow$ bitstring $_{\perp}$ is the decryption algorithm taking as arguments the ciphertext and the key, and returning either the cleartext when decryption succeeds or $\perp$ when decryption fails,
such that $\forall k \in T_{k}, \forall m \in$ bitstring, $\forall r \in T_{r}, \operatorname{dec}(\operatorname{enc}(m, k, r), k)=m$.
Let $L R(x, y, b)=x$ if $b=0$ and $L R(x, y, b)=y$ if $b=1$, defined only when $x$ and $y$ are bitstrings of the same length. The advantage of an adversary against indistinguishability under chosen plaintext attacks (IND-CPA) is

$$
\operatorname{Succ}_{\mathrm{SE}}^{\text {ind }-\mathrm{cpa}}\left(t, q_{e}, l\right)=\max _{\mathcal{A}} 2 \operatorname{Pr}\left[\begin{array}{l}
b \stackrel{R}{\leftarrow}\{0,1\} ; k \stackrel{R}{\leftarrow} T_{k} ; \\
b^{\prime} \leftarrow \mathcal{A}^{r}{ }^{r} T_{r} ; \operatorname{enc}(L R(.,, b), k, r)
\end{array} b^{\prime}=b\right]-1
$$

where $\mathcal{A}$ is any probabilistic Turing machine that runs in time at most $t$ and calls $r \stackrel{R}{\leftarrow} T_{r}$; $\operatorname{enc}(L R(., ., b), k, r)$ at most $q_{e}$ times on messages of length at most $l$.

Given two bitstrings $a_{0}$ and $a_{1}$ of the same length, the left-right encryption oracle $r \stackrel{R}{\leftarrow} T_{r}$; $\operatorname{enc}(L R(., ., b), k, r)$ returns $r \stackrel{R}{\leftarrow} T_{r} ; \operatorname{enc}\left(L R\left(a_{0}, a_{1}, b\right), k, r\right)$, that is, encrypts $a_{0}$ when $b=0$ and $a_{1}$ when $b=1$. $\operatorname{Succ}_{\mathrm{SE}}^{\text {ind }-\mathrm{cpa}}\left(t, q_{e}, l\right)$ is the probability that the adversary distinguishes the encryption of the messages $a_{0}$ given as first arguments to the left-right encryption oracle from the encryption of the messages $a_{1}$ given as second arguments. Intuitively, when the encryption scheme is IND-CPA secure, this probability is small: the ciphertext gives almost no information on what the cleartext is (one cannot determine whether it is $a_{0}$ or $a_{1}$ without having the secret key).

Example 1 Let us consider the following trivial protocol:

$$
\begin{array}{r}
A \rightarrow B: e, \operatorname{mac}\left(e, x_{m k}\right) \quad \text { where } e=\operatorname{enc}\left(x_{k}^{\prime}, x_{k}, x_{r}\right) \\
\text { and } x_{r}, x_{k}^{\prime} \text { are fresh random numbers }
\end{array}
$$

$A$ and $B$ are assumed to share a key $x_{k}$ for a symmetric encryption scheme and a key $x_{m k}$ for a message authentication code. $A$ creates a fresh key $x_{k}^{\prime}$ and sends it encrypted under $x_{k}$ to $B$. A MAC is appended to the message, in order to guarantee integrity. In other words, the protocol sends the key $x_{k}^{\prime}$ encrypted using an encrypt-then-MAC scheme [21]. The goal of the protocol is that $x_{k}^{\prime}$ should be a secret key shared between $A$ and $B$. This protocol can be modeled in our calculus by the following oracle definition $Q_{0}$ :

$$
\begin{aligned}
Q_{0}= & O_{0}():=x_{k} \stackrel{R}{\leftarrow} T_{k} ; x_{m k} \stackrel{R}{\leftarrow} T_{m k} ; \text { return }() ;\left(Q_{A} \mid Q_{B}\right) \\
Q_{A}= & \text { foreach } i \leq n \text { do } O_{A}():=x_{k}^{\prime} \stackrel{R}{\leftarrow} T_{k} ; x_{r} \stackrel{R}{\leftarrow} T_{r} ; \\
& \text { let } x_{m}: \text { bitstring }=\operatorname{enc}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime}\right), x_{k}, x_{r}\right) \text { in return }\left(x_{m}, \operatorname{mac}\left(x_{m}, x_{m k}\right)\right) \\
Q_{B}= & \text { foreach } i^{\prime} \leq n^{\prime} \text { do } O_{B}\left(x_{m}^{\prime}, x_{m a}\right):=\text { if verify }\left(x_{m}^{\prime}, x_{m k}, x_{m a}\right) \text { then } \\
& \text { let } \mathrm{i}_{\perp}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime \prime}\right)\right)=\operatorname{dec}\left(x_{m}^{\prime}, x_{k}\right) \text { in return }()
\end{aligned}
$$

When the oracle $O_{0}$ is called, it begins execution: it generates the keys $x_{k}$ and $x_{m k}$ randomly. Then it returns control to the adversary, and provides $n$ copies of oracles $O_{A}$ and $n^{\prime}$ copies of $O_{B}$ for $A$ and $B$ respectively. The adversary can call them by calling $O_{A}[i]$ and $O_{B}\left[i^{\prime}\right]$ respectively. In a session that runs as expected, the adversary first calls $O_{A}[i]$. Then $O_{A}$ creates a fresh key $x_{k}^{\prime}$ ( $T_{k}$ is assumed to be a fixed-length type), encrypts it under $x_{k}$ with random coins $x_{r}$, computes the MAC under $x_{m k}$ of the ciphertext, and returns the ciphertext and the MAC. The function $\mathrm{k} 2 \mathrm{~b}: T_{k} \rightarrow$ bitstring is the natural injection $\mathrm{k} 2 \mathrm{~b}(x)=x$; it is needed only for type conversion. The adversary is then expected to forward this returned message to $O_{B}[i]$. When $O_{B}$ receives this message, it verifies the MAC, decrypts, and stores the obtained key in $x_{k}^{\prime \prime}$. (The function $\mathrm{i}_{\perp}:$ bitstring $\rightarrow$ bitstring $_{\perp}$ is the natural injection; it is useful to check that decryption succeeded.) This key $x_{k}^{\prime \prime}$ should be secret.

The adversary is responsible for forwarding messages from $A$ to $B$. It can call the oracles in unexpected ways in order to mount an attack.

This very small example is sufficient to illustrate the main features of CryptoVerif.

### 2.3 Type System

We use a type system to check that bitstrings of the proper type are passed to each function and oracle, and that array indices are used correctly.

To be able to type variable accesses used not under their definition (such accesses are guarded by a find construct) and oracle calls, the type-checking builds a type environment $\mathcal{E}$, which maps:

- variable names $x$ to types $\left[1, n_{1}\right] \times \ldots \times\left[1, n_{m}\right] \rightarrow T$, where the definition of $x\left[i_{1}, \ldots, i_{m}\right]$ of type $T$ occurs under replications or find that bind $i_{1}, \ldots, i_{m}$ with declaration $i_{j} \leq n_{j}$;
- oracle names $O$ to types $\left[1, n_{1}\right] \times \ldots \times\left[1, n_{m}\right] \rightarrow T \rightarrow T^{\prime}$, where the definition of $O\left[i_{1}\right.$, $\left.\ldots, i_{m}\right](p):=P$ of type $T \rightarrow T^{\prime}$ occurs under replications or find that bind $i_{1}, \ldots, i_{m}$ with declaration $i_{j} \leq n_{j}$.

For instance, the definition of $x\left[i_{1}, \ldots, i_{m}\right]$ occurs under foreach $i_{1} \leq n_{1}$ do,$\ldots$, foreach $i_{m} \leq$ $n_{m}$ do or it occurs in the condition of find $u_{1}=i_{1} \leq n_{1}, \ldots, u_{m}=i_{m} \leq n_{m}$ under no replication. The type $T$ is the one given in the definition of $x$ in $x \widetilde{i}] \stackrel{R}{\leftarrow} T$ or in a pattern $x \widetilde{i}]: T$ in an assignment, an oracle call, an oracle declaration, or a get. In the find construct, find $\ldots x[\widetilde{i}]=i \leq n$, the type $T$ of $x$ is $T=[1, n]$. In the oracle call let $p=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i}\right] \leq$ $\left.n_{1}, \ldots, ? u_{m} \widetilde{[i]} \leq n_{m}\right](N)$ in $P$ else $P^{\prime}$, the type $T_{j}$ of $u_{j}$ is $\left[1, n_{j}\right]$ for $j \leq m$. The tool checks that all definitions of the same variable $x$ yield the same value of $\mathcal{E}(x)$, so that $\mathcal{E}$ is properly defined. Similarly, all definitions of the same oracle $O$ must yield the same value of $\mathcal{E}(O)$. While the type of variables can be determined by a preliminary pass on their definitions, provided their type is explicit at their definition, determining the type of oracles requires typing the oracle bodies. The type environment for oracles would then not be fully known at the beginning, but determined during typing by collecting constraints on the type of each oracle, provided the pattern in which the result of an oracle call is stored is explicitly typed. However, as we explain below, CryptoVerif currently does not accept oracle calls in its input language, which simplifies the typing algorithm. We sketch this algorithm below.

Oracles are typechecked in the type environment $\mathcal{E}$ using the rules of Figures 2, 3, and 4. These figures defines four judgments:

- $\mathcal{E} \vdash M: T$ means that the term $M$ has type $T$ in environment $\mathcal{E}$.
- $\mathcal{E} \vdash p: T$ means that the pattern $p$ has type $T$ in environment $\mathcal{E}$.
- $\mathcal{E} \vdash P: T$ means that the oracle body $P$ will return a value of type $T$ in environment $\mathcal{E}$.
- $\mathcal{E} \vdash Q$ means that the oracle definition $Q$ is well-typed in environment $\mathcal{E}$.

When a term $M$ never evaluates to a value (it always ends with event_abort $e$ ), it has the special type any, which can be converted to any other type by subtyping. Similarly, when an oracle body $P$ never returns (it always ends with yield or event_abort $e$ ), it has type any. The type any is not allowed in declarations of function symbols, tables, and events. Variables can have type any only when they are actually never defined (their definition is a term that always aborts). Patterns can have type any only when the pattern-matching will always fail (because it is an equality with a term that always aborts). The result type of oracles can be any, when they never return.

Typing rules for terms:

$$
\begin{gather*}
\frac{\mathcal{E}(i)=T}{\mathcal{E} \vdash i: T}  \tag{TIndex}\\
\frac{\mathcal{E}(x)=T_{1} \times \ldots \times T_{m} \rightarrow T \quad \forall j \leq m, \mathcal{E} \vdash M_{j}: T_{j}}{\mathcal{E} \vdash x\left[M_{1}, \ldots, M_{m}\right]: T}  \tag{TVar}\\
\frac{f: T_{1} \times \ldots \times T_{m} \rightarrow T \quad \forall j \leq m, \mathcal{E} \vdash M_{j}: T_{j}}{\mathcal{E} \vdash f\left(M_{1}, \ldots, M_{m}\right): T} \tag{TFun}
\end{gather*}
$$

$\underline{T \text { fixed, bounded, or nonuniform } \quad \mathcal{E} \vdash x[\widetilde{i}]: T \quad \mathcal{E} \vdash N: T^{\prime}}$

$$
\begin{equation*}
\mathcal{E} \vdash x \widetilde{[\bar{i}]} \stackrel{R}{\leftarrow} T ; N: T^{\prime} \tag{TNewT}
\end{equation*}
$$

$$
\begin{equation*}
\frac{\mathcal{E} \vdash M: T \quad \mathcal{E} \vdash p: T \quad \mathcal{E} \vdash N: T^{\prime} \quad \mathcal{E} \vdash N^{\prime}: T^{\prime}}{\mathcal{E} \vdash \text { let } p=M \text { in } N \text { else } N^{\prime}: T^{\prime}} \tag{TLetT}
\end{equation*}
$$

$$
\begin{equation*}
\frac{\mathcal{E} \vdash M: T \quad \mathcal{E} \vdash x \widetilde{i}]: T \quad \mathcal{E} \vdash N: T^{\prime}}{\mathcal{E} \vdash \text { let } x[\widetilde{i}]: T=M \text { in } N: T^{\prime}} \tag{TLetT2}
\end{equation*}
$$

$$
\begin{equation*}
\frac{\mathcal{E} \vdash M: \text { bool } \quad \mathcal{E} \vdash N: T \quad \mathcal{E} \vdash N^{\prime}: T}{\mathcal{E} \vdash \text { if } M \text { then } N \text { else } N^{\prime}: T} \tag{TIfT}
\end{equation*}
$$

$$
\forall j \leq m, \forall k \leq m_{j}, \mathcal{E} \vdash u_{j k}[\widetilde{i}]:\left[1, n_{j k}\right]
$$

$\forall j \leq m, \forall k \leq l_{j}, \mathcal{E}\left[i_{j 1} \mapsto\left[1, n_{j 1}\right], \ldots, i_{j m_{j}} \mapsto\left[1, n_{j m_{j}}\right]\right] \vdash M_{j k}: T_{j k}$ $\forall j \leq m, \mathcal{E}\left[i_{j 1} \mapsto\left[1, n_{j 1}\right], \ldots, i_{j m_{j}} \mapsto\left[1, n_{j m_{j}}\right]\right] \vdash M_{j}$ : bool
$\forall j \leq m, \mathcal{E} \vdash N_{j}: T \quad \mathcal{E} \vdash N: T$
$\overline{\mathcal{E}} \vdash$ find $[$ unique $?]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}}[\widetilde{i}]=i_{j m_{j}} \leq n_{j m_{j}}\right.$ suchthat

$$
\begin{equation*}
\left.\operatorname{defined}\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j} \text { then } N_{j}\right) \text { else } N: T \tag{TFindT}
\end{equation*}
$$

$$
\begin{equation*}
\frac{T b l: T_{1} \times \ldots \times T_{l} \quad \forall j \leq l, \mathcal{E} \vdash M_{j}: T_{j} \quad \mathcal{E} \vdash N: T}{\mathcal{E} \vdash \text { insert } T b l\left(M_{1}, \ldots, M_{l}\right) ; N: T} \tag{TInsertT}
\end{equation*}
$$

$\frac{T b l: T_{1} \times \ldots \times T_{l} \quad \forall j \leq l, \mathcal{E} \vdash p_{j}: T_{j} \quad \mathcal{E} \vdash M: \text { bool } \quad \mathcal{E} \vdash N: T}{\operatorname{get}[\text { unique } ?] \operatorname{Tbl}\left(p_{1}, \ldots, p_{l}\right) \text { suchthat } M \text { in } N \text { else } N^{\prime}: T}$

$$
\begin{equation*}
\frac{e: T_{1} \times \ldots \times T_{l} \quad \forall j \leq l, \mathcal{E} \vdash M_{j}: T_{j} \quad \mathcal{E} \vdash N: T}{\mathcal{E} \vdash \text { event } e\left(M_{1}, \ldots, M_{l}\right) ; N: T} \tag{TGetT}
\end{equation*}
$$

$$
\begin{equation*}
\frac{e:()}{\mathcal{E} \vdash \text { event_abort } e: a n y} \tag{TEventT}
\end{equation*}
$$

$$
\begin{equation*}
\frac{\mathcal{E} \vdash M: a n y}{\mathcal{E} \vdash M: T} \tag{SubtypingT}
\end{equation*}
$$

Typing rules for patterns:

Figure 2: Typing rules (1)
RR n ${ }^{\circ} 9526$

$$
\begin{align*}
& \frac{\mathcal{E} \vdash x[\widetilde{i}]: T}{\mathcal{E} \vdash(x[\widetilde{i}]: T): T}  \tag{TVarP}\\
& \frac{f: T_{1} \times \ldots \times T_{m} \rightarrow T \quad \forall j \leq m, \mathcal{E} \vdash p_{j}: T_{j}}{\mathcal{E} \vdash f\left(p_{1}, \ldots, p_{m}\right): T}  \tag{TFunP}\\
& \frac{\mathcal{E} \vdash M: T}{\mathcal{E} \vdash=M: T} \tag{TEqP}
\end{align*}
$$

Typing rules for oracle definitions:

$$
\begin{gather*}
\mathcal{E} \vdash 0  \tag{TNil}\\
\frac{\mathcal{E} \vdash Q \quad \mathcal{E} \vdash Q^{\prime}}{\mathcal{E} \vdash Q \mid Q^{\prime}}  \tag{TPar}\\
\frac{\mathcal{E}[i \mapsto[1, n]] \vdash Q}{\mathcal{E} \vdash \text { foreach } i \leq n \text { do } Q}  \tag{TRepl}\\
\frac{\mathcal{E}\left[O \mapsto T_{1} \times \ldots \times T_{m} \rightarrow T \rightarrow T^{\prime}\right] \vdash Q}{\mathcal{E} \vdash \text { newOracle } O ; Q} \\
\hline \mathcal{E} \vdash p: T \quad \mathcal{E} \vdash P: T^{\prime} \quad \forall j \leq m, \mathcal{E} \vdash i_{j}: T_{j} \quad \text { (TNil) } \\
\mathcal{E} \vdash O\left[i_{1}, \ldots, i_{m}\right](p):=P
\end{gather*}
$$

(TODecl)

Figure 3: Typing rules (2)

In $x\left[M_{1}, \ldots, M_{m}\right], M_{1}, \ldots, M_{m}$ must be of the suitable interval type. When $f\left(M_{1}, \ldots, M_{m}\right)$ is called and $f: T_{1} \times \ldots \times T_{m} \rightarrow T, M_{j}$ must be of type $T_{j}$, and $f\left(M_{1}, \ldots, M_{m}\right)$ is then of type $T$.

The term $x \widetilde{\sim} \widetilde{i}]^{R} T ; N$ is accepted only when $T$ is declared fixed, bounded, or nonuniform. We check that $x \widetilde{i}]$ is of type $T$ (which is in fact always true when the construction of $\mathcal{E}$ succeeds). $N$ must well-typed, and its type is also the type of $x \widetilde{[i]} \stackrel{R}{\leftarrow} T ; N$.

In let $p=M$ in $N$ else $N^{\prime}, p$ must have the same type as $M$, and $N$ and $N^{\prime}$ must have the same type, which is also the type of let $p=M$ in $N$ else $N^{\prime}$. The typing rules for patterns $p$ are found at the bottom of Figure 2 . The pattern $x \widetilde{[ }]: T$ has type $T$, provided $x \widetilde{\sim}]$ has type $T$ (which is in fact always true when the construction of $\mathcal{E}$ succeeds). The other typing rules for patterns are straightforward. The particular case let $x \widetilde{i}]: T=M$ in $N$ is typed similarly, except that the else branch is omitted.

In if $M$ then $N$ else $N^{\prime}, M$ must be of type bool and $N$ and $N^{\prime}$ must have the same type, which is also the type of if $M$ then $N$ else $N^{\prime}$.

In

$$
\begin{aligned}
& \text { find }[\text { unique? }]\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}} \text { suchthat } \\
& \left.\quad \text { defined }\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j} \text { then } N_{j}\right) \text { else } N
\end{aligned}
$$

the replication indices $i_{j 1}, \ldots, i_{j m_{j}}$ are bound in $M_{j 1}, \ldots, M_{j l_{j}}, M_{j}$, of types $\left[1, n_{j 1}\right], \ldots,\left[1, n_{j m_{j}}\right]$ respectively; $M_{j}$ is of type bool for all $j \leq m ; N_{j}$ for all $j \leq m$ and $N$ all have the same type, which is also the type of the find term.

In insert $\operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; N, M_{1}, \ldots, M_{l}$ must be of the type declared for the elements of the table $T b l$, and the type of $N$ is the type of the insert term.

In get[unique?] $\operatorname{Tbl}\left(p_{1}, \ldots, p_{l}\right)$ suchthat $M$ in $N$ else $N^{\prime}, p_{1}, \ldots, p_{l}$ must be of the type declared for the elements of the table $T b l$ and $M$ must be of type bool. The terms $N$ and $N^{\prime}$ must have the same type, which is also the type of the get term.

In event $e\left(M_{1}, \ldots, M_{l}\right) ; N, M_{1}, \ldots, M_{l}$ must be of the type declared for the arguments of event $e$, and the type of $N$ is the type of the event term.

The term event_abort $e$ is of type any, and can thus be of any type (because it aborts the game); the event $e$ must be declared without argument, which we denote by $e:()$. Terms of type

Typing rules for oracle bodies:

$$
\begin{equation*}
\frac{\mathcal{E} \vdash N: T \quad \mathcal{E} \vdash Q}{\mathcal{E} \vdash \operatorname{return}(N) ; Q: T} \tag{TRet}
\end{equation*}
$$

$$
\begin{equation*}
\frac{\mathcal{E} \vdash O: T_{1}^{\prime} \times \ldots \times T_{j}^{\prime} \times\left[1, n_{1}\right] \times \ldots \times\left[1, n_{m}\right] \rightarrow T \rightarrow T^{\prime}}{\left.\mathcal{E} \vdash \text { let } p=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i}\right] \leq n_{1}, \ldots, ? u_{m}[\widetilde{i}] \leq n_{m}\right](N) \text { in } P \text { else } P^{\prime}: T^{\prime \prime}} \tag{TCall}
\end{equation*}
$$

$$
\begin{equation*}
\underline{T \text { fixed, bounded, or nonuniform }} \quad \mathcal{E} \vdash x \widetilde{[\bar{i}]: T} \quad \mathcal{E} \vdash P: T^{\prime} \tag{TNew}
\end{equation*}
$$

$$
\mathcal{E} \vdash x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P: T^{\prime}
$$

$$
\begin{equation*}
\frac{\mathcal{E} \vdash M: T \quad \mathcal{E} \vdash p: T \quad \mathcal{E} \vdash P: T^{\prime} \quad \mathcal{E} \vdash P^{\prime}: T^{\prime}}{\mathcal{E} \vdash \text { let } p=M \text { in } P \text { else } P^{\prime}: T^{\prime}} \tag{TLet}
\end{equation*}
$$

$$
\begin{equation*}
\frac{\mathcal{E} \vdash M: \text { bool } \quad \mathcal{E} \vdash P: T \quad \mathcal{E} \vdash P^{\prime}: T}{\mathcal{E} \vdash \text { if } M \text { then } P \text { else } P^{\prime}: T} \tag{TIf}
\end{equation*}
$$

$$
\forall j \leq m, \forall k \leq m_{j}, \mathcal{E} \vdash u_{j k} \widetilde{[i]}:\left[1, n_{j k}\right]
$$

$$
\forall j \leq m, \forall k \leq l_{j}, \mathcal{E}\left[i_{j 1} \mapsto\left[1, n_{j 1}\right], \ldots, i_{j m_{j}} \mapsto\left[1, n_{j m_{j}}\right]\right] \vdash M_{j k}: T_{j k}
$$

$$
\forall j \leq m, \mathcal{E}\left[i_{j 1} \mapsto\left[1, n_{j 1}\right], \ldots, i_{j m_{j}} \mapsto\left[1, n_{j m_{j}}\right]\right] \vdash M_{j}: \text { bool }
$$

$$
\underset{\sim}{\forall j \leq m, \mathcal{E} \vdash P_{j}: T} \quad \mathcal{E} \vdash P: T
$$

$$
\begin{equation*}
\overline{\mathcal{E}} \vdash \text { find }[\text { unique } ?]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}}[\widetilde{i}]=i_{j m_{j}} \leq n_{j m_{j}}\right. \text { suchthat } \tag{TFind}
\end{equation*}
$$

$$
\left.\operatorname{defined}\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j} \text { then } P_{j}\right) \text { else } P: T
$$

$$
\begin{array}{rrr}
\frac{T b l: T_{1} \times \ldots \times T_{l} \quad \forall j \leq l, \mathcal{E} \vdash M_{j}: T_{j}}{} \quad \mathcal{E} \vdash P: T \\
\mathcal{E} \vdash \text { insert } \operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; P: T  \tag{TGet}\\
\frac{T b l}{}: T_{1} \times \ldots \times T_{l} \quad \forall j \leq l, \mathcal{E} \vdash p_{j}: T_{j} \quad \mathcal{E} \vdash M: \text { bool } & \mathcal{E} \vdash P: T & \mathcal{E} \vdash P^{\prime}: T \\
\hline \operatorname{get}[\text { unique } ?] \operatorname{Tbl}\left(p_{1}, \ldots, p_{l}\right) \text { suchthat } M \text { in } P \text { else } P^{\prime}: T
\end{array}
$$

$$
\begin{equation*}
\frac{e: T_{1} \times \ldots \times T_{l} \quad \forall j \leq l, \mathcal{E} \vdash M_{j}: T_{j} \quad \mathcal{E} \vdash P: T}{\mathcal{E} \vdash \text { event } e\left(M_{1}, \ldots, M_{l}\right) ; P: T} \tag{TEvent}
\end{equation*}
$$

$$
e:()
$$

$\overline{\mathcal{E}} \vdash$ event_abort $e: a n y$

$$
\begin{equation*}
\mathcal{E} \vdash \text { yield }: \text { any } \tag{TYield}
\end{equation*}
$$

$$
\frac{\mathcal{E} \vdash P: a n y}{\mathcal{E} \vdash P: T}
$$

(Subtyping)

$$
\begin{equation*}
\frac{\mathcal{E}(O)=T_{1} \times \ldots \times T_{m} \rightarrow T \rightarrow T^{\prime}}{\mathcal{E} \vdash O: T_{1} \times \ldots \times T_{m} \rightarrow T \rightarrow T^{\prime}} \tag{TO}
\end{equation*}
$$

$$
\frac{\mathcal{E} \vdash O: T_{1} \times \ldots \times T_{m} \rightarrow T \rightarrow \text { any }}{\mathcal{E} \vdash O: T_{1} \times \ldots \times T_{m} \rightarrow T \rightarrow T^{\prime}}
$$

(SubtypingO)

Figure 4: Typing rules (3)
any can then be given any type through the subtyping rule.
The type system for oracle definitions and bodies requires each subterm to be well-typed. In foreach $i \leq n$ do $Q, i$ is of type $[1, n]$ in $Q$. The oracle commands $\stackrel{R}{\leftarrow}$, let, if, find, insert, get, event, and event_abort are typed similarly to the corresponding terms. The command yield, which aborts the execution of an oracle without returning any value, is typed with any. A return $(N)$ is typed with the type of the term $N$. In an oracle call let $p=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i}\right] \leq$ $\left.\left.n_{1}, \ldots, ? u_{m} \widetilde{[i}\right] \leq n_{m}\right](N)$ in $P$ else $P^{\prime}$, the indices $\left.M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i}\right] \leq n_{1}, \ldots, ? u_{m} \widetilde{[i]} \leq n_{m}$ must have the same type as the indices at the definition of oracle $O$, the type of $N$ must correspond to the type expected by the oracle $O$, the type of the result of oracle $O$ must correspond to the type of the pattern $p$, and both branches $P$ and $P^{\prime}$ must have the same type, which is also the type of the whole oracle call construct. Subtyping is lifted from terms to oracles with dedicated rules, and can be used either on an oracle body or an oracle definition.

We say that an occurrence of a term $M$ in an oracle definition $Q$ is of type $T$ when $\mathcal{E} \vdash$ $M: T$ where $\mathcal{E}$ is the type environment of $Q$ extended with $i \mapsto[1, n]$ for each replication foreach $i \leq n$ do above $M$ in $Q$ and with $i_{j 1} \mapsto\left[1, n_{j 1}\right], \ldots, i_{j m_{j}} \mapsto\left[1, n_{j m_{j}}\right]$ for each find [unique?] $\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i}\right]=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $P_{j}$ ) else $P$ such that the considered occurrence of $M$ is in the condition defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge$ $M_{j}$.

Invariant 8 (Typing) The oracle definition $Q_{0}$ satisfies Invariant 8 if and only if there exists a type environment $\mathcal{E}$ for $Q_{0}$ such that $\mathcal{E} \vdash Q_{0}$.

On the implementation side, we only have to check that input processes following the subset for the initial game (see Figure 13) are well-typed, so we do not need to deal with oracle calls and newOracle. In practice, the type of oracles in the type environment is determined by maintaining a list of oracles when going through the process, storing for each oracle its name, the type of indices, the type of arguments, and the potential type of the returns. For distinct branches of execution, we merge the oracle lists allowing duplicated names but ensuring that the same oracle name always corresponds to the same number of indices, the same type of arguments, and that the return type either corresponds to none or the same. For parallel execution branches and for oracles defined syntactically one under the other, we forbid oracles with the same names, to guarantee Invariant 7 .

The type of variables in the type environment is determined by inspecting all variables definitions in a preliminary pass before the actual typing. Variables with several incompatible definitions (different indices, different types, or variables defined in the same branch of a test, which would contradict Invariant 11) are automatically renamed to distinct variable names. Such variables cannot be used queries and nor in defined conditions of find. For simplicity, variables defined without giving them an explicit type also cannot be used in queries and nor in defined conditions of find, even if their type is later inferred by the typing algorithm, and are also renamed to distinct variable names.

Looking forward, an adversary against a protocol will be made of two components:

- an attacker $\mathcal{A}$ that can be instantiated by any black-box interactive and stateful function;
- an adversary context $C$, inside our game syntax, that allows the adversary to, e.g., raise events.

We require the adversary context to be well-typed. This requirement does not restrict its computing power, because it can always define type-cast functions $f: T \rightarrow T^{\prime}$ to bypass the type system. Similarly, the type system does not restrict the class of protocols that we consider, since
the protocol may contain type-cast functions. The type system just makes explicit which set of values may appear at each point of the protocol.

The attacker calls to oracles will also be well-typed by the semantics, which once again does not restrict its computing power.

### 2.4 Formal Semantics

### 2.4.1 Definition of the Semantics

The formal semantics of our programming language is presented in Figures 5, 6, 8, 9, 10, and 11 ,
In this semantics, each term $M$ or process $P$ or $Q$ is labeled by a program point $\mu$, replacing $M$ with ${ }^{\mu} M$ and similarly for $P$ and $Q$. We still use the notations $M, P, Q$ for terms and processes tagged with program points. The program points are used in order to track from where each term or process comes from in the initial oracle definition. These program points are simply constant tags, and the initial oracle definition is tagged with a distinct program point at each subterm and subprocess.

The semantics depends on an attacker that may interact with the oracles. We consider attackers $\mathcal{A}$ from a recursively defined attacker space $\mathcal{B B}$, that are probabilistic functions of type $\mathcal{A}:$ Bitstring $\mapsto \operatorname{Distr}(\mathcal{B B} \times$ Bitstring $)$. To each input, the attacker $\mathcal{A}$ gives out a distribution yielding the corresponding output and next attacker step with some probability. It models an interactive black-box attacker, where given an input, it gives back with some probability both an output and the next attacker step. Here, Bitstring $=\{0,1\}^{*}$ is the set of concrete bitstrings, and we implicitly rely on the efficient bijections from types and oracle names to concrete bitstrings so that the attacker can interact with the oracles.

A semantic configuration is a sextuple $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$, where

- $E$ is an environment mapping array cells to values.
- $\mathcal{S} t$ is an execution stack of the form $\left(\sigma_{0}, P_{0}\right):: \ldots::\left(\sigma_{m}, P_{m}\right):: \mathcal{A}$ where $P_{j}$ are oracle bodies and $\sigma_{j}$ are the associated mapping sequences which give values of replication indices. The oracle body $P_{0}$ is the one currently being executed, and the oracle bodies $P_{1}, \ldots, P_{m}$ correspond to oracle calls that have not returned yet. The stack always contains at least one pair ( $\sigma_{j}, P_{j}$ ) and always contains as a last element an attacker $\mathcal{A}$.
The mapping sequence $\sigma=\left[i_{1} \mapsto a_{1}, \ldots, i_{m} \mapsto a_{m}\right]$ is a sequence of mappings $i_{j} \mapsto a_{j}$, which can also be interpreted as a function: $\sigma\left(i_{j}\right)=a_{j}$ for all $j \leq m$, and $\left.\sigma \widetilde{i}\right)$ is defined by the natural extension to sequences. However, using a sequence allows us to define $\operatorname{Dom}(\sigma)=$ $\left[i_{1}, \ldots, i_{m}\right]$ to be the sequence of current replication indices and $\operatorname{Im}(\sigma)=\left[a_{1}, \ldots, a_{m}\right]$ to be the sequence of their values. When $\sigma=\left[i_{1} \mapsto a_{1}, \ldots, i_{m} \mapsto a_{m}\right], \sigma\left[i_{m+1} \mapsto a_{m+1}, \ldots, i_{l} \mapsto\right.$ $\left.a_{l}\right]=\left[i_{1} \mapsto a_{1}, \ldots, i_{l} \mapsto a_{l}\right]$.
- $\mathcal{Q}$ is the multiset of oracle declarations running in parallel with $P$, with their associated mapping sequences giving values of replication indices. It is the set of callable oracles.
- $\mathcal{O} r=\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}\right)$ represents the oracles already created. $\mathcal{O} r_{\text {pub }}$ is the set of public oracles, which can be called by the adversary; $\mathcal{O} r_{\text {priv }}$ is the set of private oracles.
- $\mathcal{T}$ defines the contents of tables. It is a list of $\operatorname{Tbl}\left(a_{1}, \ldots, a_{m}\right)$ indicating that table $T b l$ contains the element $\left(a_{1}, \ldots, a_{m}\right)$.
- $\mu \mathcal{E} v$ is a sequence representing the events executed so far. Each element of the sequence is of the form $(\mu, \widetilde{a}): e\left(a_{1}, \ldots, a_{m}\right)$, meaning that the event $e\left(a_{1}, \ldots, a_{m}\right)$ has been executed at program point $\mu$ with replication indices evaluating to $\widetilde{a}$.

We define $\mathcal{E} v=\operatorname{removepp}(\mu \mathcal{E} v)=\left[e\left(a_{1}, \ldots, a_{m}\right) \mid(\mu, \widetilde{a}): e\left(a_{1}, \ldots, a_{m}\right) \in \mu \mathcal{E} v\right]$ to be the sequence of events $\mu \mathcal{E} v$ without their associated program points and replication indices.

In addition to the grammar given in Figure 1, the terms $M$ of the semantics can be values $a$ and abort event values event_abort $(\mu, \widetilde{a}): e$, and the oracle bodies $P$ can be abort, corresponding to the situation in which the game has been aborted. These additional terms and oracle bodies are not tagged with program points. (They do not occur in the initial oracle definition.)

The semantics is defined by reduction rules of the form $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v{ }_{\rightarrow_{t}} E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}$, $\mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ meaning that $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ reduces to $E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ with probability $p$. The index $t$ just serves in distinguishing reductions that yield the same configuration with the same probability in different ways, so that the probability of a certain reduction can be computed correctly:

$$
\operatorname{Pr}\left[E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \rightarrow E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}\right]=\sum_{E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{{ }_{t} E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}} p} p
$$

The probability of a trace $\operatorname{Tr}=E_{1}, \mathcal{S} t_{1}, \mathcal{Q}_{1}, \mathcal{O} r_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1} \xrightarrow{p_{1}} t_{1} \ldots \xrightarrow{p_{m-1}} t_{t_{m-1}} E_{m}, \mathcal{S} t_{m}, \mathcal{Q}_{m}$, $\mathcal{O} r_{m}, \mathcal{T}_{m}, \mu \mathcal{E} v_{m}$ is $\operatorname{Pr}[T r]=p_{1} \times \ldots \times p_{m-1}$. We define the semantics only for patterns $\left.x \widetilde{[ }\right]: T$, the other patterns can be encoded as outlined in Section 2.1

In Figures 5 and 6 , we define an auxiliary relation for evaluating terms: $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t}$ $E^{\prime}, \sigma, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ means that the term $M$ reduces to $M^{\prime}$ in environment $E$ with the replication indices defined by $\sigma$, the table contents $\mathcal{T}$, and the sequence of events $\mu \mathcal{E} v$, with probability $p$. Rule (ReplIndex) evaluates replication indices using the function $\sigma$. Rule (Var) looks for the value of the variable in the environment $E$. Rule Fun evaluates the function call. Rule (NewT) chooses a random $a \in T$ according to distribution $D_{T}$, and stores it in $x[\sigma(\widetilde{i})]$ by extending the environment $E$ accordingly. Similarly, Rule (LetT) extends the environment $E$ with the value of $x[\sigma(\widetilde{i})]$. Rule IITT1) evaluates the then branch of if when the condition is true, and Rule IIfT2) evaluates the else branch otherwise.

Rules FindTE to FindT3 define the semantics of find. First, they all evaluate the conditions for all branches $j$ and all values of the indices $i_{j 1}, \ldots, i_{j m_{j}}$. If one of these evaluations executes an event (which can happen in case the condition contains an event_abort $e$ or a find [unique $\left.e_{e}\right]$ ), the whole find executes the same event; in case the evaluations of the conditions execute several different events, one of them is chosen randomly, according to distribution $D_{\text {find }}(S)$, that is, almost uniformly over the choices of branches and indices (Rule FindTE). Otherwise, the branch and indices for which the condition is true are collected in a set $S$. If $S$ is empty, the else branch of the find is executed (Rule (FindT2p). When $S$ is not empty, two cases can happen. Either the find is not marked [unique ${ }_{e}$ ], and we choose an element $v_{0}=\left(j^{\prime}, a_{1}^{\prime}, \ldots, a_{m_{j^{\prime}}}^{\prime}\right)$ of $S$ randomly according to the distribution $D_{\text {find }}(S)$, store the corresponding indices $a_{1}^{\prime}, \ldots, a_{m_{j^{\prime}}}^{\prime}$ in $\left.u_{j^{\prime} 1}[\sigma(\widetilde{i})], \ldots, u_{j^{\prime} m_{j^{\prime}}}[\sigma \widetilde{i})\right]$ by extending the environment accordingly, and we continue with the selected branch $N_{j}^{\prime j}$. If the find is marked [unique ${ }_{e}$ ] and $S$ has a single element, we do the same. If the find is marked [unique ${ }_{e}$ ] and $S$ has several elements, we execute the event $e$ (Rule (FindT3)). We recall that $D_{\text {find }}(S)\left(v_{0}\right)$ denotes the probability of choosing $v_{0}$ in the distribution $D_{\text {find }}(S)$. The terms in conditions of find may define variables, included in the environment $E^{\prime \prime}$; we ignore these additional variables and compute the final environment from the initial environment $E$, because these variables have no array accesses by Invariant 3, so the values of these variables are not used after the evaluation of the condition. The conditions of find, $D \wedge M$, are evaluated using Rules (DefinedNo and DefinedYes). If an element of the defined condition $D$ is not defined, then the condition is false (Rule (DefinedNo); when all elements of the defined condition are defined, we evaluate $M$ (Rule DefinedYes). Since terms in conditions of find do not contain

$$
\begin{gather*}
E, \sigma,{ }^{\mu} i, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, \sigma(i), \mathcal{T}, \mu \mathcal{E} v \\
x\left[a_{1}, \ldots, a_{m}\right] \in \operatorname{Dom}(E)  \tag{Var}\\
\frac{f: T_{1} \times \ldots \times T_{m} \rightarrow T \quad \forall j \leq m, a_{j} \in T_{j} \quad f\left(a_{1}, \ldots, a_{m}\right)=a}{E, \sigma,{ }^{\mu} x\left[a_{1}, \ldots, a_{m}\right], \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, E\left(x\left[a_{1}, \ldots, a_{m}\right]\right), \mathcal{T}, \mu \mathcal{E} v}  \tag{Fun}\\
\frac{a \in T\left(a_{1}, \ldots, a_{m}\right), \mathcal{T}, \mu \mathcal{E} v \xrightarrow[\rightarrow]{1} E, \sigma, a, \mathcal{T}, \mu \mathcal{E} v}{E^{\prime}=E[x[\sigma(\widetilde{i})] \mapsto a]}  \tag{NewT}\\
\frac{a,{ }^{\mu},{ }^{\mu} x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{D_{T}(a)} N(a) E^{\prime}, \sigma, N, \mathcal{T}, \mu \mathcal{E} v}{a \in T \quad E^{\prime}=E[x[\sigma \widetilde{(\widetilde{i})] \mapsto a]}} \begin{array}{c}
\frac{a}{E, \sigma,{ }^{\mu} \text { let } x \widetilde{[i]}: T=a \text { in } N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E^{\prime}, \sigma, N, \mathcal{T}, \mu \mathcal{E} v} \\
E, \sigma,{ }^{{ }^{\text {if }}} \text { true then } N \text { else } N^{\prime}, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v
\end{array} \tag{Let}
\end{gather*}
$$

(ReplIndex)
$\left(v_{k}\right)_{1 \leq k \leq l}$ is the sequence of $\left(j, a_{1}, \ldots, a_{m_{j}}\right)$ for $a_{1} \in\left[1, n_{j 1}\right], \ldots, a_{m_{j}} \in\left[1, n_{j m_{j}}\right]$ ordered in increasing lexicographic order
$\forall k \in[1, l], E, \sigma\left[i_{j 1} \mapsto a_{1}, \ldots, i_{j m_{j}} \mapsto a_{m_{j}}\right], D_{j} \wedge M_{j}, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{k}}{ }_{t_{k}}^{*} E_{k}, \sigma_{k}, r_{k}, \mathcal{T}, \mu \mathcal{E} v$ where $v_{k}=\left(j, a_{1}, \ldots, a_{m_{j}}\right)$ and $r_{k}$ is a value or event_abort $\left(\mu^{\prime}, \widetilde{a}\right): e$

$$
S=\left\{k \mid \exists\left(\mu^{\prime}, \widetilde{a}, e\right), r_{k}=\text { event_abort }\left(\mu^{\prime}, \widetilde{a}\right): e\right\} \quad k_{0} \in S
$$

$E, \sigma,{ }^{\mu}$ find $[$ unique? $]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat
$D_{j} \wedge M_{j}$ then $\left.N_{j}\right)$ else $N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{1} \ldots p_{l} D_{\text {find }}(S)\left(k_{0}\right)}{ }_{t_{1} \ldots t_{l} F E\left(k_{0}\right)} E_{k_{0}}, \sigma_{k_{0}}, r_{k_{0}}, \mathcal{T}, \mu \mathcal{E} v$
(FindTE)
$\left(v_{k}\right)_{1 \leq k \leq l}$ is the sequence of $\left(j, a_{1}, \ldots, a_{m_{j}}\right)$ for $a_{1} \in\left[1, n_{j 1}\right], \ldots, a_{m_{j}} \in\left[1, n_{j m_{j}}\right]$ ordered in increasing lexicographic order
$\forall k \in[1, l], E, \sigma\left[i_{j 1} \mapsto a_{1}, \ldots, i_{j m_{j}} \mapsto a_{m_{j}}\right], D_{j} \wedge M_{j}, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{p_{k}}{ }_{t_{k}}} E^{\prime \prime}, \sigma^{\prime}, r_{k}, \mathcal{T}, \mu \mathcal{E} v$ where $v_{k}=\left(j, a_{1}, \ldots, a_{m_{j}}\right)$ and $r_{k}$ is a value

$$
S=\left\{v_{k} \mid r_{k}=\text { true }\right\} \quad|S|=1 \text { or }[\text { unique?] is empty }
$$

$v_{0}=\left(j^{\prime}, a_{1}^{\prime}, \ldots, a_{m_{j^{\prime}}}^{\prime}\right) \in S \quad E^{\prime}=E\left[u_{j^{\prime}}\left[\sigma \widetilde{\left.(\widetilde{i})] \mapsto a_{1}^{\prime}, \ldots, u_{j^{\prime} m_{j^{\prime}}}[\sigma(\widetilde{i})] \mapsto a_{m_{j^{\prime}}}^{\prime}\right]}\right.\right.$
$E, \sigma,{ }^{\mu}$ find $[$ unique? $]\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat
$D_{j} \wedge M_{j}$ then $N_{j}$ ) else $N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{1} \ldots p_{l} D_{\text {find }}(S)\left(v_{0}\right)} t_{1} \ldots t_{l} F 1\left(v_{0}\right) E^{\prime}, \sigma, N_{j^{\prime}}, \mathcal{T}, \mu \mathcal{E} v$
(FindT1)
First four lines as in FindT1 $\quad S=\left\{v_{k} \mid r_{k}=\right.$ true $\}=\emptyset$
$E, \sigma,{ }^{\mu}$ find $[$ unique? $]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}}[\widetilde{i}]=i_{j m_{j}} \leq n_{j m_{j}}\right.$ suchthat $D_{j} \wedge M_{j}$ then $N_{j}$ ) else $N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{1} \ldots p_{l}}{ }_{t_{1} \ldots t_{l} F 2} E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v$

First four lines as in FindT1 $\quad S=\left\{v_{k} \mid r_{k}=\right.$ true $\} \quad|S|>1$
$E, \sigma,{ }^{\mu}$ find [unique $\left.e\right]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}}[\widetilde{i}]=i_{j m_{j}} \leq n_{j m_{j}}\right.$ suchthat $D_{j} \wedge M_{j}$ then $\left.N_{j}\right)$ else $N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{1} \ldots p_{l}} t_{t_{1} \ldots t_{l} F 3} E, \sigma$, event_abort $(\mu, \operatorname{Im}(\sigma)): e, \mathcal{T}, \mu \mathcal{E} v$

Figure 5: Semantics (1): terms, first part

$$
\begin{align*}
& E, \sigma,{ }^{\mu_{\text {insert }}} \operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right) ; N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, N,\left(\mathcal{T}, \operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right)\right), \mu \mathcal{E} v \\
& {\left[v_{1}, \ldots, v_{m}\right]=\left[x \in \mathcal{T} \mid \exists a_{1}, \ldots, \exists a_{l}, x=\operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right)\right]} \\
& \forall k \in[1, m], E\left[x_{1}[\sigma(\widetilde{i})] \mapsto a_{1}, \ldots, x_{l}[\sigma(\widetilde{i})] \mapsto a_{l}\right], \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{t_{k}}}{ }^{*} E_{k}, \sigma_{k}, r_{k}, \mathcal{T}, \mu \mathcal{E} v \\
& \text { where } v_{k}=\operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right) \text { and } r_{k} \text { is a value or event_abort }\left(\mu^{\prime}, \widetilde{a}\right): e \\
& S=\left\{k \in[1, m] \mid \exists\left(\mu^{\prime}, \widetilde{a}, e\right), r_{k}=\text { event_abort }\left(\mu^{\prime}, \widetilde{a}\right): e\right\} \quad k_{0} \in S \\
& E, \sigma,{ }^{\mu} \operatorname{get}[u n i q u e ?] \operatorname{Tbl}\left(x_{1} \widetilde{[i]}: T_{1}, \ldots, x_{l} \widetilde{[i]}: T_{l}\right) \text { suchthat } M \text { in } N \text { else } N^{\prime}, \mathcal{T}, \mu \mathcal{E} v \\
& \xrightarrow{p_{1} \ldots p_{m} D_{\mathrm{get}}(S)\left(k_{0}\right)} t_{t_{1} \ldots t_{m} G E\left(k_{0}\right)} E_{k_{0}}, \sigma_{k_{0}}, r_{k_{0}}, \mathcal{T}, \mu \mathcal{E} v \\
& {\left[v_{1}, \ldots, v_{m}\right]=\left[x \in \mathcal{T} \mid \exists a_{1}, \ldots, \exists a_{l}, x=\operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right)\right]} \\
& \forall k \in[1, m], E\left[x_{1}[\sigma(\widetilde{i})] \mapsto a_{1}, \ldots, x_{l}[\sigma(\widetilde{i})] \mapsto a_{l}\right], \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{k_{k}}}{ }_{t_{k}}^{*} E^{\prime \prime}, \sigma, r_{k}, \mathcal{T}, \mu \mathcal{E} v \\
& \text { where } v_{k}=\operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right) \text { and } r_{k} \text { is a value } \\
& S=\left\{k \in[1, m] \mid r_{k}=\text { true }\right\} \\
& |S|=1 \text { or [unique?] is empty } \\
& \frac{k_{0} \in S \quad \operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right)=v_{k_{0}} \quad E^{\prime}=E\left[x_{1}[\sigma(\widetilde{i})] \mapsto a_{1}, \ldots, x_{l}[\sigma(\widetilde{i})] \mapsto a_{l}\right]}{\left.\left.E, \sigma,{ }^{\mu} \operatorname{get}[\text { unique } ?] \operatorname{Tbl}\left(x_{1} \widetilde{i}\right]: T_{1}, \ldots, x_{l} \widetilde{i}\right]: T_{l}\right) \text { suchthat } M \text { in } N \text { else } N^{\prime}, \mathcal{T}, \mu \mathcal{E} v}  \tag{GetT1}\\
& \xrightarrow{p_{1} \ldots p_{m} D_{\mathrm{get}}(S)\left(k_{0}\right)} t_{1} \ldots t_{m} G 1\left(k_{0}\right) E^{\prime}, \sigma, N, \mathcal{T}, \mu \mathcal{E} v \\
& \text { First four lines as in GetT1 } \quad S=\emptyset \\
& \left.E, \sigma,{ }^{\mu} \operatorname{get}[\text { unique } ?] \operatorname{Tbl}\left(x_{1}[\widetilde{i}]: T_{1}, \ldots, x_{l} \widetilde{i}\right]: T_{l}\right) \text { suchthat } M \text { in } N \text { else } N^{\prime}, \mathcal{T}, \mu \mathcal{E} v \\
& \xrightarrow{p_{1} \ldots p_{m}} t_{1} \ldots t_{m} G 2 E, \sigma, N^{\prime}, \mathcal{T}, \mu \mathcal{E} v \\
& \text { First four lines as in (GetT1 } \quad|S|>1 \\
& \xrightarrow{p_{1} \ldots p_{m}}{ }_{t_{1} \ldots t_{m} G 2} E, \sigma, N^{\prime}, \mathcal{T}, \mu \mathcal{E} v \\
& \begin{array}{c}
\overline{E, \sigma,{ }^{\mu} \operatorname{get}_{\left[\text {unique }_{e}\right]} \operatorname{Tbl}\left(x_{1}[\widetilde{i}]: T_{1}, \ldots, x_{l}[\widetilde{i}]: T_{l}\right) \text { suchthat } M \text { in } N \text { else } N^{\prime}, \mathcal{T}, \mu \mathcal{E} v} \\
\xrightarrow{p_{1} \ldots p_{m}}{ }_{t_{1} \ldots t_{m} G 3} E, \sigma, \text { event_abort }(\mu, \operatorname{Im}(\sigma)): e, \mathcal{T}, \mu \mathcal{E} v
\end{array} \\
& E, \sigma,{ }^{\mu} \text { event } e\left(a_{1}, \ldots, a_{l}\right) ; N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, N, \mathcal{T},\left(\mu \mathcal{E} v,(\mu, \operatorname{Im}(\sigma)): e\left(a_{1}, \ldots, a_{l}\right)\right) \quad \text { (EventT) } \\
& E, \sigma,{ }^{\mu} \text { event_abort } e, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, \text { event_abort }(\mu, \operatorname{Im}(\sigma)): e, \mathcal{T}, \mu \mathcal{E} v \quad \text { (EventAbortT) } \\
& \frac{E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, N^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}}{E, \sigma, C[N], \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, C\left[N^{\prime}\right], \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}}  \tag{CtxT}\\
& E, \sigma, C[\text { event_abort }(\mu, \widetilde{a}): e], \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, \text { event_abort }(\mu, \widetilde{a}): e, \mathcal{T}, \mu \mathcal{E} v \quad \text { (CtxEventT) } \\
& \frac{\neg \forall j \leq l, \exists a_{j}, E, \sigma, M_{j}, \mathcal{T}, \mu \mathcal{E} v{ }^{1^{*}} E, \sigma, a_{j}, \mathcal{T}, \mu \mathcal{E} v}{E, \sigma, \operatorname{defined}\left(M_{1}, \ldots, M_{l}\right) \wedge M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, \text { false }, \mathcal{T}, \mu \mathcal{E} v}  \tag{DefinedNo}\\
& \frac{\forall j \leq l, \exists a_{j}, E, \sigma, M_{j}, \mathcal{T}, \mu \mathcal{E} v{ }^{1}{ }^{*} E, \sigma, a_{j}, \mathcal{T}, \mu \mathcal{E} v}{E, \sigma, \operatorname{defined}\left(M_{1}, \ldots, M_{l}\right) \wedge M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v} \tag{DefinedYes}
\end{align*}
$$

Figure 6: Semantics (2): terms, second part, and defined conditions

$$
\begin{aligned}
C::= & { }^{\mu} x\left[a_{1}, \ldots, a_{k-1},[], M_{k+1}, \ldots, M_{m}\right] \\
& { }^{\mu} f\left(a_{1}, \ldots, a_{k-1},[], M_{k+1}, \ldots, M_{m}\right) \\
& { }^{\mu} \text { let } x \widetilde{[i]}: T=[] \text { in } N \\
& \mu_{\text {if }}[] \text { then } N \text { else } N^{\prime} \\
& { }^{\prime} \text { event } e\left(a_{1}, \ldots, a_{k-1},[], M_{k+1}, \ldots, M_{l}\right) ; N \\
& \mu_{\text {insert }} \operatorname{Tbl}\left(a_{1}, \ldots, a_{k-1},[], M_{k+1}, \ldots, M_{l}\right) ; N
\end{aligned}
$$

Figure 7: Term contexts
insert nor event (Invariant 4), the table contents and the sequence of events are left unchanged by the evaluation of the condition of find.

Rule InsertT inserts the new table element in $\mathcal{T}$. Rules GetTE to GetT3 define the semantics of get. We denote by $[x \in L \mid f(x)]$ the list of all elements $x$ of the list $L$ that satisfy $f(x)$, in the same order as in $L$. We denote by $|L|$ the length of list $L$. We denote by nth $(L, j)$ the $j$-th element of the list $L$. Rule GetTE executes event_abort $e$ when the evaluation of the condition $M$ executes event_abort $e$ for some element of the table $T b l$; when several events may be executed, one of them is chosen randomly according to distribution $D_{\text {get }}(S)$, that is, almost uniformly in the elements of the table Tbl. Rules (GetT1), GetT2), and (GetT3) compute the set $S$ of elements of indices of elements of table $T b l$ in $\mathcal{T}$ that satisfy condition $M$. If $S$ is empty, we execute $N^{\prime}$ (Rule GetT2). When $S$ is not empty, two cases can happen. If the get is not marked [unique ${ }_{e}$ ] or $S$ has a single element, then one of its elements is chosen randomly according to distribution $D_{\text {get }}(S)$, we store this element in $x_{1}[\sigma(\widetilde{i})], \ldots, x_{l}[\sigma(\widetilde{i})]$ by extending the environment $E$, and continue by executing $N$ (Rule GetT1). If the get is marked [unique ${ }_{e}$ ] and $S$ contains several elements, then we execute event $e$ and abort (Rule (GetT3). Since terms in conditions of get do not contain insert nor event (Invariant 4), the table contents and the sequence of events are left unchanged by the evaluation of $M$. The modified environment $E^{\prime \prime}$ obtained after evaluating a condition $M$ can be ignored because there are no array accesses to the variables defined in conditions of get, by Invariant 3, so the values of these variables are not used after the evaluation of the condition.

Remark 1 Another way of defining the semantics of tables would be to consider two distinct calculi, one with tables (used for the initial game), and one without tables (used for the other games). The semantics of the calculus without tables can be defined without the component $\mathcal{T}$. We then need to relate the two semantics.

Rule EventT adds the executed event to $\mu \mathcal{E} v$. Rule EventAbortT) executes event_abort $e$. The event $e$ is not immediately added to $\mu \mathcal{E} v$, because for terms that occur in conditions of find, in case several branches execute event_abort, we may need to choose randomly which event will be added to $\mu \mathcal{E} v$. Hence, we use the result event_abort $(\mu, \widetilde{a}): e$ instead.

Rules (CtxT) and (CtxEventT) allow evaluating terms under a context. In these rules, $C$ is an elementary context, of one of the forms defined in Figure 7. When the term $N$ reduces to some other term $N^{\prime}$, Rule CtxT allows one to reduce it in the same way under a context $C$. When the term $N$ is an event, $C[N]$ also executes the same event by Rule CtxEventT.

These rules define a small-step semantics for terms. We consider the reflexive and transitive closure $\stackrel{p}{\rightarrow}_{t}^{*}$ of the relation $\xrightarrow{p}_{t}$ to reach directly the normal form of the term, which can be either a

$$
\begin{align*}
& \left\{\left(\sigma,^{\mu}\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r \rightsquigarrow \mathcal{Q}, \mathcal{O} r  \tag{Nil}\\
& \left\{\left(\sigma,{ }^{\mu}\left(Q_{1} \mid Q_{2}\right)\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r \rightsquigarrow\left\{\left(\sigma, Q_{1}\right),\left(\sigma, Q_{2}\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r  \tag{Par}\\
& \left\{\left(\sigma,^{\mu} \text { foreach } i \leq n \text { do } Q\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r \rightsquigarrow\{(\sigma[i \mapsto a], Q) \mid a \in[1, n]\} \uplus \mathcal{Q}, \mathcal{O} r  \tag{Repl}\\
& \frac{\mathcal{O} r=\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}\right) \quad O^{\prime} \notin \mathcal{O} r_{\text {pub }} \cup \mathcal{O} r_{\text {priv }}}{\left\{\left(\sigma,^{\mu} \text { newOracle } O ; Q\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r \rightsquigarrow\left\{\left(\sigma, Q\left\{O^{\prime} / O\right\}\right)\right\} \uplus \mathcal{Q},\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }} \cup\left\{O^{\prime}\right\}\right)} \\
& \left.\left.\left\{\left(\sigma,{ }^{\mu} O \widetilde{i}\right](x[\widetilde{i}]: T):=P\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r \rightsquigarrow\left\{\left(\sigma,{ }^{\mu} O[\sigma \widetilde{i})\right](x[\widetilde{i}]: T):=P\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r \\
& \text { reduce }(\mathcal{Q}, \mathcal{O} r) \text { is the normal form of } \mathcal{Q}, \mathcal{O} r \text { by } \rightsquigarrow \\
& \text { reduce }(\mathcal{Q}, \mathcal{O} r) \text { is the normal form of } \mathcal{Q}, \mathcal{O} r \text { by } \rightsquigarrow
\end{align*}
$$

Figure 8: Semantics (3): oracle definitions
value $a$ or an abort event value event_abort $(\mu, \widetilde{a}): e$. We have $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v{ }^{1}{ }^{*} E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ and, if $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ and $E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime} \xrightarrow{p^{\prime}{ }^{\prime}} E^{\prime \prime}, \sigma^{\prime \prime}, M^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}$, then $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p \times p^{\prime}} t_{t} E^{\prime \prime}, \sigma^{\prime \prime}, M^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}:$ we take the product of the probabilities to have the probability of a sequence of reductions, and we specify which sequence was taken by a list of indices $t, t^{\prime}$.

Figure 8 defines the semantics of oracle definitions. We use an auxiliary reduction relation $\rightsquigarrow$, for reducing oracle definitions. This relation transforms configurations of the form $\mathcal{Q}, \mathcal{O} r$. Rule (Nil) removes nil definitions. Rules (Par and Repl expand parallel compositions and replications, respectively. Rule NewOracle creates a new oracle and adds it to $\mathcal{O} r_{\text {priv }}$. Semantic configurations are considered equivalent modulo renaming of oracles in $\mathcal{O} r_{\text {priv }}$, so that a single semantic configuration is obtained after applying (NewOracle). Rule DefOracle evaluates the replication indices in an oracle declaration. The oracle itself is not executed: the call is done by the OracleCall rule. The relation $\rightsquigarrow$ is convergent (confluent and terminating), so it has normal forms. Oracle definitions in $\mathcal{Q}$ in configurations $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ are always in normal form by $\rightsquigarrow$, so they always start with an oracle declaration.

Finally, Figures 9,10 and 11 define the semantics of oracles bodies. Most of these rules are very similar to those for terms: they just use oracles instead of terms as continuations, and include a whole semantic configuration. Rule EventAbort executes event $e$ and aborts the game, by reducing to the configuration with oracle body abort. Similarly to the case of terms, Rules (Ctx) and CtxEvent allow evaluating terms under a context inside an oracle body. In these rules, $C$ is an elementary context, of one of the forms defined in Figure 12

Rule OracleCall performs an oracle call: it selects an available oracle, and immediately executes it. (The oracle call blocks if no suitable oracle is available.) The head of the execution stack after this rule is the body of the called oracle. In this rule, $S$ is a multiset. When we take probabilities over multisets, we consider that $D_{\text {call }}(S)\left(\sigma^{\prime}, Q_{0}\right)$ is the probability of choosing one of the elements equal to $\sigma^{\prime}, Q_{0}$ in $S$ according to the distribution $D_{\text {call }}(S)$, so that the probability of choosing any element equal to $\left(\sigma^{\prime}, Q_{0}\right)$ is in fact $S\left(\sigma^{\prime}, Q_{0}\right) \times D_{\text {call }}(S)\left(\sigma^{\prime}, Q_{0}\right)$.

The rule Return corresponds to an oracle body finishing its execution and returning the result to the caller, which is the next oracle $P_{0}$ in the execution stack. The oracle definitions that follow the return are added to the set of available oracles, after reducing them by rules of Figure 8 . The in branch of the caller is then executed. The rule Yield corresponds to an oracle body finishing its execution by yield. The else branch of the caller is then executed.

Rule AttIO corresponds to the attacker receiving a return and then triggering a new oracle call. The probability is over all possible attacker choices, as well as the corresponding oracles.

(Find1)
First four lines as in FindT1 $\quad S=\left\{v_{k} \mid r_{k}=\right.$ true $\}=\emptyset$
$E,\left(\sigma,{ }^{\mu}\right.$ find [unique? $\left.]\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{i}\right]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat $D_{j} \wedge M_{j}$ then $\left.P_{j}\right)$ else $\left.P\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{1} \ldots p_{l}} t_{t_{1} \ldots t_{l} F 2} E,(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$

$$
\begin{align*}
& \text { First four lines as in FindT1 } \quad S=\left\{v_{k} \mid r_{k}=\text { true }\right\} \quad|S|>1  \tag{Find2}\\
& \overline{E,\left(\sigma,{ }^{\mu}{ }^{\text {find }\left[\text { unique }_{e}\right]}\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[ }\right]=i_{j m_{j}} \leq n_{j m_{j}} \text { suchthat } D_{j} \wedge\right.} \\
& \left.M_{j} \text { then } P_{j} \text { ) else } P\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \\
& \xrightarrow{p_{1} \ldots p_{l}} t_{t_{1} \ldots t_{l} F 3} E,(\sigma, \text { abort }):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T},(\mu \mathcal{E} v,(\mu, \operatorname{Im}(\sigma)): e) \tag{Find3}
\end{align*}
$$

$$
\begin{align*}
E,(\sigma, & \left.{ }^{\text {insert }} \operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right) ; P\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \\
& \xrightarrow{1} E,(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r,\left(\mathcal{T}, \operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right)\right), \mu \mathcal{E} v \tag{Insert}
\end{align*}
$$

Same assumption as in GetTE $\quad r_{k_{0}}=$ event_abort $\left(\mu^{\prime}, \widetilde{a}\right): e$
$E,\left(\sigma,{ }^{\mu} \operatorname{get}[u n i q u e ?] \operatorname{Tbl}\left(x_{1} \widetilde{[i]}: T_{1}, \ldots, x_{l} \widetilde{[i]}: T_{l}\right)\right.$ suchthat $M$ in $P$ else $\left.P^{\prime}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ $\xrightarrow{p_{1} \ldots p_{m} D_{\mathrm{get}}(S)\left(k_{0}\right)}{ }_{t_{1} \ldots t_{m} G E\left(k_{0}\right)} E_{k_{0}},\left(\sigma_{k_{0}}\right.$, abort $):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T},\left(\mu \mathcal{E} v,\left(\mu^{\prime}, \widetilde{a}\right): e\right)$

First four lines as in GetT1 $\quad|S|=1$ or [unique?] is empty
$\left.k_{0} \in S \quad \operatorname{Tbl}\left(a_{1}, \ldots, a_{l}\right)=v_{k_{0}} \quad E^{\prime}=E\left[x_{1}[\sigma \widetilde{i})\right] \mapsto a_{1}, \ldots, x_{l}[\sigma(\widetilde{i})] \mapsto a_{l}\right]$
$E,\left(\sigma,{ }^{\mu} \operatorname{get}[u n i q u e ?] \operatorname{Tbl}\left(x_{1} \widetilde{[i]}: T_{1}, \ldots, x_{l}[\widetilde{i}]: T_{l}\right)\right.$ suchthat $M$ in $P$ else $\left.P^{\prime}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$
$\xrightarrow{p_{1} \ldots p_{m} D_{\mathrm{get}}(S)\left(k_{0}\right)}{ }_{t_{1} \ldots t_{m} G 1\left(k_{0}\right)} E^{\prime},(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$
(Get1)
First four lines as in GetT1 $\quad S=\emptyset$
$\left.E,\left(\sigma,{ }^{\mu} \operatorname{get}[u n i q u e ?] \operatorname{Tbl}\left(x_{1} \widetilde{i}\right]: T_{1}, \ldots, x_{l} \widetilde{i}\right]: T_{l}\right)$ suchthat $M$ in $P$ else $\left.P^{\prime}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ $\xrightarrow{p_{1} \ldots p_{m}} t_{t_{1} \ldots t_{m} G 2} E,\left(\sigma, P^{\prime}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$
(Get2)
First four lines as in (GetT1) $\quad|S|>1$
$E,\left(\sigma,{ }^{\mu} \operatorname{get}\left[\right.\right.$ unique $\left.\left.\left._{e}\right] \operatorname{Tbl}\left(x_{1} \widetilde{[ }\right]: T_{1}, \ldots, x_{l} \widetilde{[ }\right]: T_{l}\right)$ suchthat $M$ in $P$ else $\left.P^{\prime}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$

$$
\begin{equation*}
\xrightarrow{p_{1} \ldots p_{m}} t_{t_{1} \ldots t_{m} G 3} E,(\sigma, \text { abort }):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T},(\mu \mathcal{E} v,(\mu, \operatorname{Im}(\sigma)): e) \tag{Get3}
\end{equation*}
$$

Figure 9: Semantics (4): oracle bodies, first part

$$
\begin{align*}
& \frac{a \in T \quad E^{\prime}=E[x[\sigma \widetilde{(i)}] \mapsto a]}{E,\left(\sigma,{ }^{\mu} x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v{\xrightarrow{D_{T}(a)}}_{N(a)} E^{\prime},(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v}  \tag{New}\\
& \frac{a \in T \quad E^{\prime}=E[x[\sigma(\widetilde{i})] \mapsto a]}{E,\left(\sigma,{ }^{\mu} \text { let } x[\widetilde{i}]: T=a \text { in } P\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E^{\prime},(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v}  \tag{Let}\\
& E,\left(\sigma,{ }^{\mu_{\text {if }}} \text { true then } P \text { else } P^{\prime}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E,(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v  \tag{If1}\\
& a \neq \text { true } \\
& E,\left(\sigma, \mu_{\text {if }} a \text { then } P \text { else } P^{\prime}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E,\left(\sigma, P^{\prime}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v  \tag{If2}\\
& E,\left(\sigma,{ }^{\mu} \text { event } e\left(a_{1}, \ldots, a_{l}\right) ; P\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} \\
& E,(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T},\left(\mu \mathcal{E} v,(\mu, \operatorname{Im}(\sigma)): e\left(a_{1}, \ldots, a_{l}\right)\right) \\
& E,\left(\sigma,{ }^{\mu} \text { event_abort } e\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E,(\sigma, \text { abort }):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T},(\mu \mathcal{E} v,(\mu, \operatorname{Im}(\sigma)): e) \\
& \text { (EventAbort) } \\
& \frac{E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, N^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}}{E,(\sigma, C[N]):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime},\left(\sigma^{\prime}, C\left[N^{\prime}\right]\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}}  \tag{Ctx}\\
& E,(\sigma, C[\text { event_abort }(\mu, \widetilde{a}): e]):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} \\
& E,(\sigma, \text { abort }):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T},(\mu \mathcal{E} v,(\mu, \widetilde{a}): e) \\
& \text { (CtxEvent) } \\
& \left.\left.P_{0}=\text { let } x[\widetilde{i}]: T=O\left[a_{1}, \ldots, a_{l}, ? u_{l+1} \widetilde{i}\right] \leq n_{l+1}, \ldots, ? u_{k} \widetilde{i}\right] \leq n_{k}\right](b) \text { in } P_{1} \text { else } P_{2} \\
& S=\left\{\left(\sigma^{\prime}, Q\right) \in \mathcal{Q} \mid Q=\mu^{\prime \prime} O\left[a_{1}, \ldots, a_{l}, c_{l+1}, \ldots, c_{k}\right]\left(x^{\prime}\left[\widetilde{i^{\prime}}\right]: T^{\prime}\right):=P^{\prime} \text { and } b \in T^{\prime}\right. \\
& \text { for some } \left.\mu^{\prime \prime}, \sigma^{\prime}, x^{\prime}, T^{\prime}, P^{\prime}, c_{l+1} \in\left[1, n_{l+1}\right], \ldots, c_{k} \in\left[1, n_{k}\right]\right\} \\
& \left(\sigma^{\prime}, Q_{0}\right) \in S \quad Q_{0}=\mu^{\prime} O\left[a_{1}, \ldots, a_{k}\right]\left(x^{\prime}\left[\widetilde{i^{\prime}}\right]: T^{\prime}\right):=P^{\prime} \\
& P_{0}^{\prime}=\text { let } x[\widetilde{i}]: T=O\left[a_{1}, \ldots, a_{k}\right](b) \text { in } P_{1} \text { else } P_{2} \\
& E,\left(\sigma,{ }^{\mu} P_{0}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{S\left(\sigma^{\prime}, Q_{0}\right) \times D_{\text {call }}(S)\left(\sigma^{\prime}, Q_{0}\right)} O\left(\sigma^{\prime}, Q_{0}\right) \\
& E\left[x^{\prime}\left[\sigma^{\prime}\left(\widetilde{i^{\prime}}\right)\right] \mapsto b, u_{l+1}[\sigma(\widetilde{i})] \mapsto c_{l+1}, \ldots, u_{k}[\sigma(\widetilde{i})] \mapsto c_{k}\right], \\
& \left(\sigma^{\prime}, P^{\prime}\right)::\left(\sigma,^{\mu} P_{0}^{\prime}\right):: \mathcal{S} t, \mathcal{Q} \uplus \backslash\left\{\left(\sigma^{\prime}, Q_{0}\right)\right\}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \\
& d \in T \quad \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}=\operatorname{reduce}(\{(\sigma, Q)\}, \mathcal{O} r) \\
& \frac{P_{0}=\text { let } x[\widetilde{i}]: T=O\left[a_{1}, \ldots, a_{k}\right](b) \text { in } P_{1} \text { else } P_{2}}{E,\left(\sigma,{ }^{\mu^{\prime}} \text { return }(d) ; Q\right)::\left(\sigma^{\prime},{ }^{\mu} P_{0}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1}} \\
& E\left[x\left[\sigma^{\prime}(\widetilde{i})\right] \mapsto d\right],\left(\sigma^{\prime}, P_{1}\right):: \mathcal{S} t, \mathcal{Q} \uplus \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}, \mu \mathcal{E} v \\
& \frac{P_{0}=\text { let } x[\widetilde{i}]: T=O\left[a_{1}, \ldots, a_{k}\right](b) \text { in } P_{1} \text { else } P_{2}}{E,\left(\sigma,{ }^{\mu^{\prime}} \text { yield }\right)::\left(\sigma^{\prime},{ }^{\mu} P_{0}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1} E,\left(\sigma^{\prime}, P_{2}\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v}
\end{align*}
$$

Figure 10: Semantics (5): oracle bodies, second part

$$
\begin{align*}
& \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}=\operatorname{reduce}(\{(\sigma, Q)\}, \mathcal{O} r) \\
& S=\left\{\left(\sigma^{\prime}, Q\right) \in \mathcal{Q} \uplus \mathcal{Q}^{\prime} \mid Q=\mu^{\prime \prime} O\left[a_{1}, \ldots, a_{k}\right]\left(x^{\prime} \widetilde{x^{\prime}} \widetilde{i}\right]: T^{\prime}\right):=P^{\prime} \text { and } b \in T^{\prime} \\
& \text { for some } \left.\mu^{\prime \prime}, \sigma^{\prime}, x^{\prime}, \widetilde{i}, T^{\prime}, P^{\prime}\right\} \\
& \left(\sigma^{\prime}, Q_{0}\right) \in S \quad Q_{0}=\mu^{\prime} O\left[a_{1}, \ldots, a_{k}\right](x \widetilde{[i]}: T):=P^{\prime} \\
& \begin{array}{rc}
\mathcal{A}(d)=D_{\mathcal{A}}^{d} & \mathcal{A}_{0}, m_{0} \stackrel{R}{\leftarrow} D_{\mathcal{A}}^{d} \\
\mathcal{O} r^{\prime}=\left(\mathcal{O} r_{\text {pub }}^{\prime}, \mathcal{O} r_{\text {priv }}^{\prime}\right) & m_{0}=\left(O, a_{1}, \ldots, a_{k}, b\right) \\
O \notin \mathcal{O} r_{\text {priv }}^{\prime}
\end{array} \\
& E,\left(\sigma,{ }^{\mu} \operatorname{return}(d) ; Q\right):: \mathcal{A}, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{S\left(\sigma^{\prime}, Q_{0}\right) \times D_{\text {call }}(S)\left(\sigma^{\prime}, Q_{0}\right) \times D_{\mathcal{A}}^{d}\left(\mathcal{A}_{0}, m_{0}\right)} O\left(\sigma^{\prime}, Q_{0}, \mathcal{A}_{0}, a_{1}, \ldots, a_{k}, b\right) \\
& E\left[x\left[\sigma^{\prime}(\widetilde{i})\right] \mapsto b\right],\left(\sigma^{\prime}, P^{\prime}\right):: \mathcal{A}, \mathcal{Q} \uplus \mathcal{Q}^{\prime} \uplus \backslash\left\{\left(\sigma^{\prime}, Q_{0}\right)\right\}, \mathcal{O} r^{\prime}, \mathcal{T}, \mu \mathcal{E} v  \tag{AttIO}\\
& S=\left\{\left(\sigma^{\prime}, Q\right) \in \mathcal{Q} \mid Q=\mu^{\prime \prime} O\left[a_{1}, \ldots, a_{k}\right]\left(x^{\prime} \widetilde{[i]}: T^{\prime}\right):=P^{\prime} \text { and } b \in T^{\prime} \text { for some } \mu^{\prime \prime}, \sigma^{\prime}, x^{\prime}, \widetilde{i}, T^{\prime}, P^{\prime}\right\} \\
& \left.\left(\sigma^{\prime}, Q_{0}\right) \in S \quad Q_{0}=\mu^{\prime} O\left[a_{1}, \ldots, a_{k}\right](x \widetilde{i}]: T\right):=P^{\prime} \\
& \mathcal{A}()=D_{\mathcal{A}}^{\emptyset} \quad \mathcal{A}_{0}, m_{0} \stackrel{R}{\leftarrow} D_{\mathcal{A}}^{\emptyset} \quad m_{0}=\left(O, a_{1}, \ldots, a_{k}, b\right) \\
& \mathcal{O} r=\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}\right) \quad O \notin \mathcal{O} r_{\text {priv }} \\
& \begin{array}{c}
E,\left(\sigma,{ }^{\mu} \text { yield }\right):: \mathcal{A}, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{S\left(\sigma^{\prime}, Q_{0}\right) \times D_{\text {call }}(S)\left(\sigma^{\prime}, Q_{0}\right) \times D_{\mathcal{A}}^{\emptyset}\left(\mathcal{A}_{0}, m_{0}\right)} O\left(\sigma^{\prime}, Q_{0}, \mathcal{A}_{0}, a_{1}, \ldots, a_{k}, b\right) \\
E\left[x\left[\sigma^{\prime}(\widetilde{\tilde{i}})\right] \mapsto b\right],\left(\sigma^{\prime}, P^{\prime}\right):: \mathcal{A}, \mathcal{Q} \uplus \backslash\left\{\left(\sigma^{\prime}, Q_{0}\right)\right\}, \mathcal{O} r \mathcal{T}, \mu \mathcal{E} v
\end{array} \tag{AttYield}
\end{align*}
$$

Figure 11: Semantics (6): oracle bodies, third part, attackers interactions

We later show in Section 2.4.4 that there is in fact always at most one such possible oracle, and that the probability only depends on attacker choices. Rule AttYield handles the case of a yield returned to the attacker, where we then call the attacker with an empty input. This call is disjoint from any other call to the attacker that could be performed through rule (AttIO): it is assumed that the efficient bijection from types to concrete bitstrings does not return the empty string.

After finishing execution of an oracle definition, the system produces as a result the sequence of executed events $\mu \mathcal{E} v$. Looking forward, recall that an adversary will always be made of an attacker $\mathcal{A}$ and an adversary context, this context thus allowing the adversary to raise arbitrary values in the sequence of events.

These events can be used to distinguish games, so we introduce an additional algorithm, a distinguisher $D$ that takes as input a sequence of events $\mathcal{E} v$ (without program points and replication indices) and returns true or false.

An example of distinguisher is $D_{e}$ defined by $D_{e}(\mathcal{E} v)=$ true if and only if $e \in \mathcal{E} v$ : this distinguisher detects the execution of event $e$. We will denote the distinguisher $D_{e}$ simply by $e$. More generally, distinguishers can detect various properties of the sequence of events $\mathcal{E} v$ executed by the game and of its result $a$. We denote by $D \vee D^{\prime}, D \wedge D^{\prime}$, and $\neg D$ the distinguishers such that $\left(D \vee D^{\prime}\right)(\mathcal{E} v)=D(\mathcal{E} v) \vee D^{\prime}(\mathcal{E} v),\left(D \wedge D^{\prime}\right)(\mathcal{E} v)=D(\mathcal{E} v) \wedge D^{\prime}(\mathcal{E} v)$, and $(\neg D)(\mathcal{E} v)=\neg D(\mathcal{E} v)$. We denote by $\operatorname{Pr}[Q: D]$ the probability that $Q$ executes a sequence of events $\mathcal{E} v$ such that $D(\mathcal{E} v)=$ true. This is formally defined as follows.

Definition 4 The initial configuration for running oracle definition $Q$ against attacker $\mathcal{A}$ is $\operatorname{initConfig}(Q, \mathcal{A})=\emptyset,\left(\sigma_{0}\right.$, return $($ start $\left.)\right):: \mathcal{A}, \mathcal{Q}, \mathcal{O} r, \emptyset, \emptyset$ where $\mathcal{Q}, \mathcal{O} r=\operatorname{reduce}\left(\left\{\left(\sigma_{0}, Q\right)\right\},(\operatorname{fo}(Q)\right.$, $\emptyset)$ ) and $\sigma_{0}$ is the empty mapping sequence. A trace of $Q$ for attacler $\mathcal{A}$ is a trace that starts from initConfig $(Q, \mathcal{A}): \operatorname{Tr}=\operatorname{initConfig}(Q, \mathcal{A}) \xrightarrow{p_{1}} t_{1} \ldots \xrightarrow{p_{m-1}} t_{t_{m-1}} \operatorname{Conf}{ }_{m}$. Let $\mathcal{T} r^{\mathcal{A}, Q}$ be the set of all traces of $Q$ for an attacker $\mathcal{A} \in \mathcal{B B}$.

```
\(C::={ }^{\mu}\) let \(x[\widetilde{i}]: T=[]\) in \(P\)
    \(\mu_{\text {if }}[]\) then \(P\) else \(P^{\prime}\)
    \({ }^{\mu}\) return ([]); \(Q\)
    \({ }^{\mu}\) let \(\left.x[\widetilde{i}]: T=O\left[a_{1}, \ldots, a_{k-1},[], M_{k+1}, \ldots, M_{l}, ? u_{1}[\widetilde{i}] \leq n_{1}, \ldots, ? u_{m} \widetilde{[i}\right] \leq n_{m}\right](N)\) in \(P\)
            else \(P^{\prime}\)
    \({ }^{\mu}\) let \(x \widetilde{[i]}: T=O\left[a_{1}, \ldots, a_{l}, ? u_{1}[\widetilde{i}] \leq n_{1}, \ldots, ? u_{m} \widetilde{[i]} \leq n_{m}\right]([])\) in \(P\) else \(P^{\prime}\)
    \(\mu_{\text {insert }} \operatorname{Tbl}\left(a_{1}, \ldots, a_{k-1},[], M_{k+1}, \ldots, M_{l}\right) ; P\)
    \({ }^{\mu}\) event \(e\left(a_{1}, \ldots, a_{k-1},[], M_{k+1}, \ldots, M_{l}\right) ; P\)
```

Figure 12: Oracle contexts

Let $\mathcal{T} r_{\text {full }}^{\mathcal{A}, Q}$ be the set of full traces of $Q$, that is, the set of traces of $\mathcal{T} r^{\mathcal{A}, Q}$ whose last configuration $\operatorname{Conf}_{m}$ cannot be reduced.

A trace $T r^{\prime}$ is an extension of $\operatorname{Tr}$ when $T r^{\prime}$ is obtained by continuing execution from the last configuration of $T r$. Equivalently, $\operatorname{Tr}$ is a prefix of $T r^{\prime}$.

Let $\varphi$ be a property of traces, that is, a function from traces to \{true, false\}. We say that $\operatorname{Tr}$ satisfies $\varphi$, and we write $\operatorname{Tr} \vdash \varphi$, when $\varphi(\operatorname{Tr})=$ true.

A property $\varphi$ is preserved by extension when for all traces $\operatorname{Tr}$ such that $\operatorname{Tr} \vdash \varphi$, for all extensions $T r^{\prime}$ of $T r, T r^{\prime} \vdash \varphi$.
 $\ldots \times p_{m-1}$. We define

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}[Q: \varphi]=\sum_{T r \in \mathcal{T}_{r_{\text {full }}^{\mathcal{A}, Q}, T r \vdash \varphi}} \operatorname{Pr}[\operatorname{Tr}], \\
& \operatorname{Pr}^{\mathcal{A}}[Q \preceq \varphi]=\sum_{\operatorname{Tr} \in \mathcal{T r}_{\text {full }}^{\mathcal{A}, Q}, \exists \nexists r^{\prime} \text { prefix of } \operatorname{Tr}, \operatorname{Tr}^{\prime} \vdash \varphi} \operatorname{Pr}[\operatorname{Tr}] \\
& =\sum_{T r \in \mathcal{T}^{A} \mathcal{A}, Q, T r \vdash \varphi, \text { for any strict prefix } T r^{\prime} \text { of } T r, T r^{\prime} \nvdash \varphi} \operatorname{Pr}[T r] .
\end{aligned}
$$

Given a distinguisher $D$, we can consider it as a property of traces by defining $\operatorname{Tr} \vdash D$ if and only if $D\left(\operatorname{removepp}\left(\mu \mathcal{E} v_{m}\right)\right)=$ true where the last configuration of $\operatorname{Tr}$ is $\operatorname{Conf}_{m}=E_{m}, \mathcal{S} t_{m}, \mathcal{Q}_{m}$, $\mathcal{O} r_{m}, \mathcal{T}_{m}, \mu \mathcal{E} v_{m}$. The function removepp guarantees that the pair (program point, replication indices) is not used in the evaluation of the distinguisher. Actually, this pair could be removed from the semantics. It is useful for the proof of injective correspondences (Section 4.2.4).

## Lemma 1 1. $\operatorname{Pr}^{\mathcal{A}}[Q: \varphi] \leq \operatorname{Pr}^{\mathcal{A}}[Q \preceq \varphi]$.

2. If $\varphi$ is preserved by extension, then $\operatorname{Pr}^{\mathcal{A}}[Q: \varphi]=\operatorname{Pr}^{\mathcal{A}}[Q \preceq \varphi]$.

Proof The first property holds because, when $\operatorname{Tr} \vdash \varphi$, there exists a prefix $\operatorname{Tr}^{\prime}$ of $\operatorname{Tr}$ (take $\left.T r^{\prime}=T r\right)$ such that $T r^{\prime} \vdash \varphi$.

The second property holds because, if $\varphi$ is preserved by extension and there exists a prefix $T r^{\prime}$ of $\operatorname{Tr}$ such that $\operatorname{Tr}^{\prime} \vdash \varphi$, then $\operatorname{Tr} \vdash \varphi$.

For simple terms $M$, the evaluation can be defined without tables and events. We define $E, \rho, M \Downarrow a$ if and only if $E, \rho, M, \emptyset, \emptyset \xrightarrow{*}^{*} E, \rho, a, \emptyset, \emptyset$, where the environment $E$ gives the values of process variables (in particular arrays), and the environment $\rho$ gives the values of replication indices and other variables (e.g., those used in correspondences, see Section 2.8.3). The evaluation relation $E, \rho, M \Downarrow a$ can also be defined by induction as follows:

$$
\begin{gathered}
E, \rho, i \Downarrow \rho(i) \\
\forall j \leq m, E, \rho, M_{j} \Downarrow a_{j} \\
E, \rho, x\left[M_{1}, \ldots, M_{m}\right] \Downarrow E\left(x\left[a_{1}, \ldots, a_{m}\right]\right) \\
\forall j \leq m, E, \rho, M_{j} \Downarrow a_{j} \\
E, \rho, f\left(M_{1}, \ldots, M_{m}\right) \Downarrow f\left(a_{1}, \ldots, a_{m}\right)
\end{gathered}
$$

For terms that do not contain process variables, the environment $E$ can be omitted, and we write $\rho, M \Downarrow a$. It can also be defined by induction as follows:

$$
\begin{gathered}
\rho, i \Downarrow \rho(i) \\
\frac{\forall j \leq m, \rho, M_{j} \Downarrow a_{j}}{\rho, f\left(M_{1}, \ldots, M_{m}\right) \Downarrow f\left(a_{1}, \ldots, a_{m}\right)}
\end{gathered}
$$

### 2.4.2 Properties

Given an oracle definition $Q_{0}$, we write $I_{\mu}$ for the current replication indices at $\mu$ in $Q_{0}$. For ${ }^{\mu}$ return (start) in the initial configuration, we let $I_{\mu}=\emptyset$ be the empty sequence.

Lemma 2 Let Tr be a trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$. In the derivation of Tr, for all configurations $E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E} v, \operatorname{Dom}(\sigma)=I_{\mu} ;$ for all configurations $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$, for all $\left(\sigma,{ }^{\mu} P\right) \in \mathcal{S} t$, $\operatorname{Dom}(\sigma)=I_{\mu} ;$ and for all configurations $\mathcal{Q}, \mathcal{O} r$ or $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$, for all $\left(\sigma,{ }^{\mu} Q\right) \in \mathcal{Q}$, $\operatorname{Dom}(\sigma)=I_{\mu}$.

Proof sketch We say that

- a configuration $E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E} v$ is ok when $\operatorname{Dom}(\sigma)=I_{\mu}$;
- a configuration $\mathcal{Q}, \mathcal{O} r$ is ok when for all $\left(\sigma,{ }^{\mu} Q\right) \in \mathcal{Q}, \operatorname{Dom}(\sigma)=I_{\mu}$;
- a configuration $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ is ok when for all $\left(\sigma,{ }^{\mu} P\right) \in \mathcal{S} t, \operatorname{Dom}(\sigma)=I_{\mu}$ and for all $\left(\sigma,{ }^{\mu} Q\right) \in \mathcal{Q}, \operatorname{Dom}(\sigma)=I_{\mu}$.

We show by induction on the derivations that

1. if $E_{1}, \sigma_{1}, M_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}$ is ok, then all configurations $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ in the derivation of $E_{1}$, $\sigma_{1}, M_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}{ }^{p}{ }_{t} E_{2}, \sigma_{2}, M_{2}, \mathcal{T}_{2}, \mu \mathcal{E} v_{2}$ are ok;
2. if $\mathcal{Q}_{1}, \mathcal{O} r_{1}$ is ok and $\mathcal{Q}_{1}, \mathcal{O} r_{1} \rightsquigarrow \mathcal{Q}_{2}, \mathcal{O} r_{2}$, then $\mathcal{Q}_{2}, \mathcal{O} r_{2}$ is ok;
3. if $\mathcal{Q}_{1}, \mathcal{O} r_{1}$ is ok, then reduce $\left(\mathcal{Q}_{1}, \mathcal{O} r_{1}\right)$ is ok and all configurations $\mathcal{Q}, \mathcal{O} r$ and in the derivation of $\mathcal{Q}_{1}, \mathcal{O} r_{1} \rightsquigarrow *$ reduce $\left(\mathcal{Q}_{1}, \mathcal{O} r_{1}\right)$ are ok;
4. if $E_{1}, \mathcal{S} t_{1}, \mathcal{Q}_{1}, \mathcal{O} r_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}$ is ok, then all configurations $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ or $\mathcal{Q}, \mathcal{O} r$ or $E, \mathcal{S} t$, $\mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ in the derivation of $E_{1}, \mathcal{S} t_{1}, \mathcal{Q}_{1}, \mathcal{O} r_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}{ }_{\rightarrow}^{p} E_{2}, \mathcal{S} t_{2}, \mathcal{Q}_{2}, \mathcal{O} r_{2}, \mathcal{T}_{2}, \mu \mathcal{E} v_{2}$ are ok.

Indeed, the changes in $\sigma$ match the definition of replication indices.
For Property 1, in rules for find, the indices of the find condition are added to the domain of $\sigma$ when evaluating the condition and in all other cases, $\sigma$ is unchanged.

In the proof of Property 2 in Repl), the replication index $i$ is added to $\sigma$ and in all other cases, $\sigma$ is unchanged.

Property 3 follows immediately from Property 2 by induction.
For Property 4 in rules for find, the indices of the find condition are added to the domain of $\sigma$ when evaluating the condition, as in Property 1 in Return, we use Property 3. In all other cases, $\sigma$ is unchanged and remains associated with the same program point or a program point with the same replication indices. We use Property 1 when evaluating terms, in conditions of find and get and in (Ctx).

Moreover, in the computation of initConfig $\left(Q_{0}, \mathcal{A}\right)$, the configuration $\left\{\left(\sigma_{0}, Q_{0}\right)\right\},(\mathrm{fo}(Q), \emptyset)$ is ok (the current replication indices at the root of $Q_{0}$ are empty), so by Property 3 , initConfig $\left(Q_{0}\right.$, $\mathcal{A}$ ) is ok.

Lemma 3 If $E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, N^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, then $E^{\prime}$ is an extension of $E$, $\mathcal{T}$ is a prefix of $\mathcal{T}^{\prime}, \mu \mathcal{E} v$ is a prefix of $\mu \mathcal{E} v^{\prime}, \sigma^{\prime}$ is an extension of $\sigma$, and if the term $N^{\prime}$ is not of the form $C_{1}\left[\ldots C_{k}\right.$ [event_abort $\left.\left.(\mu, \widetilde{a}): e\right] \ldots\right]$ for some $k \in \mathbb{N}$ and $C_{1}, \ldots, C_{k}$ contexts defined in Figure 7 , then $\sigma^{\prime}=\sigma$. For all configurations $E^{\prime \prime}, \sigma^{\prime \prime}, N^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}$ in the derivation of $E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t}$ $E^{\prime}, \sigma^{\prime}, N^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, we have that $E^{\prime \prime}$ is an extension of $E$ and, if $E^{\prime \prime}, \sigma^{\prime \prime}, N^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}$ is not in the derivation of an hypothesis of a rule for find or get, then $E^{\prime}$ is an extension of $E^{\prime \prime} ; \sigma^{\prime \prime}$ is an extension of $\sigma ; \mathcal{T}$ is a prefix of $\mathcal{T}^{\prime \prime}$, which is a prefix of $\mathcal{T}^{\prime}$; and $\mu \mathcal{E} v$ is a prefix of $\mu \mathcal{E} v^{\prime \prime}$, which is a prefix of $\mu \mathcal{E} v^{\prime}$.

If $\mathcal{Q},\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}\right) \rightsquigarrow \mathcal{Q}^{\prime},\left(\mathcal{O} r_{\text {pub }}^{\prime}, \mathcal{O} r_{\text {priv }}^{\prime}\right)$, then $\mathcal{O} r_{\text {pub }}^{\prime}=\mathcal{O} r_{\text {pub }}$ and $\mathcal{O} r_{\text {priv }} \subseteq \mathcal{O} r_{\text {priv }}^{\prime}$.
If $E,(\sigma, P):: \mathcal{S} t, \mathcal{Q},\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}\right), \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime},\left(\sigma^{\prime}, P^{\prime}\right):: \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime},\left(\mathcal{O} r_{\text {pub }}^{\prime}, \mathcal{O} r_{\text {priv }}^{\prime}\right), \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, then $E^{\prime}$ is an extension of $E, \mathcal{T}$ is a prefix of $\mathcal{T}^{\prime}, \mu \mathcal{E} v$ is a prefix of $\mu \mathcal{E} v^{\prime}, \mathcal{O} r_{\text {pub }}=\mathcal{O} r_{\text {pub }}^{\prime}$ and $\mathcal{O} r_{\text {priv }} \subseteq \mathcal{O} r_{\text {priv }}^{\prime}$.

- If $E,(\sigma, P):: \mathcal{S} t, \mathcal{Q},\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}\right), \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime},\left(\sigma^{\prime}, P^{\prime}\right):: \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime},\left(\mathcal{O} r_{\text {pub }}^{\prime}, \mathcal{O} r_{\text {priv }}^{\prime}\right), \mathcal{T}^{\prime}$, $\mu \mathcal{E} v^{\prime}$ is derived by Return or AttIO, then $\mathcal{T}^{\prime}=\mathcal{T}, \mu \mathcal{E} v^{\prime}=\mu \mathcal{E} v$, and for all configurations $\mathcal{Q}^{\prime \prime}, \mathcal{O} r^{\prime \prime}$ in that derivation, $\mathcal{O} r_{\text {priv }} \subseteq \mathcal{O} r_{\text {priv }}^{\prime \prime} \subseteq \mathcal{O} r_{\text {priv }}^{\prime}$ and $\mathcal{O} r_{\text {pub }}=\mathcal{O} r_{\text {pub }}^{\prime \prime}=\mathcal{O} r_{\text {pub }}^{\prime}$.
- If $E,(\sigma, P):: \mathcal{S} t, \mathcal{Q},\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}\right), \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime},\left(\sigma^{\prime}, P^{\prime}\right):: \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime},\left(\mathcal{O} r_{\text {pub }}^{\prime}, \mathcal{O} r_{\text {priv }}^{\prime}\right), \mathcal{T}^{\prime}$, $\mu \mathcal{E} v^{\prime}$ is derived by Yield, OracleCall, or AttYield, then $\mathcal{T}^{\prime}=\mathcal{T}, \mu \mathcal{E} v^{\prime}=\mu \mathcal{E} v, \mathcal{O} r_{\text {priv }}=$ $\mathcal{O} r_{\text {priv }}^{\prime}$, and $\mathcal{O} r_{\text {pub }}=\mathcal{O} r_{\text {pub }}^{\prime}$.
- In all other cases, $\mathcal{O} r_{\text {pub }}^{\prime}=\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}^{\prime}=\mathcal{O} r_{\text {priv }}, \mathcal{S} t=\mathcal{S} t^{\prime}, \sigma^{\prime}$ is an extension of $\sigma$, and if the oracle body $P^{\prime}$ is not abort or of the form $C_{0}\left[C_{1}\left[\ldots C_{k}\right.\right.$ [event_abort $\left.\left.\left.(\mu, \widetilde{a}): e\right] \ldots\right]\right]$ for some $C_{0}$ context defined in Figure $12, k \in \mathbb{N}$, and $C_{1}, \ldots, C_{k}$ contexts defined in Figure 7 , then $\sigma^{\prime}=\sigma$. For all configurations $E^{\prime \prime}, \sigma^{\prime \prime}, N^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}$ in the derivation of $E,(\sigma, P)::$ $\mathcal{S} t, \mathcal{Q},\left(\mathcal{O} r_{\text {pub }}, \mathcal{O} r_{\text {priv }}\right), \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime},\left(\sigma^{\prime}, P^{\prime}\right):: \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime},\left(\mathcal{O} r_{\text {pub }}^{\prime}, \mathcal{O} r_{\text {priv }}^{\prime}\right), \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, we have that $E^{\prime \prime}$ is an extension of $E$ and, if $E^{\prime \prime}, \sigma^{\prime \prime}, N^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}$ is not in the derivation of an hypothesis of a rule for find or get, then $E^{\prime}$ is an extension of $E^{\prime \prime} ; \sigma^{\prime \prime}$ is an extension of $\sigma$; $\mathcal{T}$ is a prefix of $\mathcal{T}^{\prime \prime}$, which is a prefix of $\mathcal{T}^{\prime}$; and $\mu \mathcal{E} v$ is a prefix of $\mu \mathcal{E} v^{\prime \prime}$, which is a prefix of $\mu \mathcal{E} v^{\prime}$.

Proof sketch By induction on the derivation of $E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, N^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ and by cases on the reductions $\mathcal{Q}, \mathcal{O} r \rightsquigarrow \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$ and $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$.

We say that a term $N$ is in evaluation position in a configuration $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ when $M=C_{1}\left[\ldots C_{k}[N] \ldots\right]$ for some $k \in \mathbb{N}$ and $C_{1}, \ldots, C_{k}$ contexts defined in Figure 7 ,

We say that a term $N$ is in evaluation position in a configuration $E,(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}$, $\mu \mathcal{E} v$ when $P=C_{0}\left[C_{1}\left[\ldots C_{k}[N] \ldots\right]\right]$ for some $C_{0}$ context defined in Figure $12 k \in \mathbb{N}$, and $C_{1}$, $\ldots, C_{k}$ contexts defined in Figure 7 or ( $\sigma^{\prime}$, let $x[\widetilde{i}]: T=O\left[a_{1}, \ldots, a_{k}\right](b)$ in $P_{1}$ else $\left.P_{2}\right) \in \mathcal{S} t$ and $N$ is $a_{1}, \ldots, a_{k}$, or $b$.

The oracle bodies $P$ such that $(\sigma, P) \in \mathcal{S} t$ for some $\sigma$ are in evaluation position in configuration $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$. The oracle definitions $Q$ such that $(\sigma, Q) \in \mathcal{Q}$ for some $\sigma$ are in evaluation position in configurations $\mathcal{Q}, \mathcal{O} r$ and $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$.

Lemma 4 Consider a trace $\operatorname{Tr}$ of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$.
All subterms of $M$ that occur in non-evaluation position in a configuration $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ in the derivation of $\operatorname{Tr}$ are subterms of $Q_{0}$.

All subterms and subprocesses of oracle definitions in $\mathcal{Q}$ that occur in non-evaluation position in a configuration $\mathcal{Q}, \mathcal{O} r$ in the derivation of $T r$ are subterms, resp. subprocesses, of $Q_{0}$ up to renaming of oracles. All subterms and subprocesses of $\mathcal{S}$ t and of $\mathcal{Q}$ that occur in non-evaluation position in a configuration $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ in the derivation of $\operatorname{Tr}$ are subterms, resp. subprocesses, of $Q_{0}$ up to renaming of oracles (except for the process 0 that follows return (start) in $\left.\operatorname{initConfig}\left(Q_{0}, \mathcal{A}\right)\right)$.

Proof We say that

- a configuration $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ is ok when all subterms of $M$ that are not in evaluation position are subterms of $Q_{0}$;
- a configuration $\mathcal{Q}, \mathcal{O} r$ is ok when all subterms and subprocesses of $\mathcal{Q}$ that are not in evaluation position are subterms, resp. subprocesses, of $Q_{0}$ up to renaming of oracles;
- a configuration $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ is ok when all subterms and subprocesses of $\mathcal{S} t$ and of $\mathcal{Q}$ that are not in evaluation position are subterms, resp. subprocesses, of $Q_{0}$ up to renaming of oracles.

We show by induction on the derivations that

1. if $E_{1}, \sigma_{1}, M_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}$ is ok, then all configurations $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ in the derivation of $E_{1}$, $\sigma_{1}, M_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}{ }_{\rightarrow}^{p} E_{2}, \sigma_{2}, M_{2}, \mathcal{T}_{2}, \mu \mathcal{E} v_{2}$ are ok;
2. if $\mathcal{Q}_{1}, \mathcal{O} r_{1}$ is ok and $\mathcal{Q}_{1}, \mathcal{O} r_{1} \rightsquigarrow \mathcal{Q}_{2}, \mathcal{O} r_{2}$, then $\mathcal{Q}_{2}, \mathcal{O} r_{2}$ is ok;
3. if $\mathcal{Q}_{1}, \mathcal{O} r_{1}$ is ok, then reduce $\left(\mathcal{Q}_{1}, \mathcal{O} r_{1}\right)$ is ok and all configurations $\mathcal{Q}, \mathcal{O} r$ in the derivation of $\mathcal{Q}_{1}, \mathcal{O} r_{1} \rightsquigarrow^{*}$ reduce $\left(\mathcal{Q}_{1}, \mathcal{O} r_{1}\right)$ are ok;
4. if $E_{1}, \mathcal{S} t_{1}, \mathcal{Q}_{1}, \mathcal{O} r_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}$ is ok, then all configurations $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ or $\mathcal{Q}, \mathcal{O} r$ or $E, \mathcal{S} t$, $\mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ in the derivation of $E_{1}, \mathcal{S} t_{1}, \mathcal{Q}_{1}, \mathcal{O} r_{1}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}{ }_{\rightarrow}^{p} E_{2}, \mathcal{S} t_{2}, \mathcal{Q}_{2}, \mathcal{O} r_{2}, \mathcal{T}_{2}, \mu \mathcal{E} v_{2}$ are ok.

Property 1 In ReplIndex, Var), Fun), and EventAbortT, all terms are in evaluation position, so all configurations are ok. In (NewT), LetT), (IfT1), IfT2), InsertT), and (EventT), $N$ (resp. $N^{\prime}$ ) is not in evaluation position, so by hypothesis it is a subterm of $Q_{0}$. Therefore, the target configuration is ok. In the rules for find, the recursive calls are on $D_{j} \wedge M_{j}$ which is not in evaluation position, so it is a subterm of $Q_{0}$. Therefore, the initial configurations of the recursive calls are ok, and we conclude for the configurations inside the recursive calls by induction hypothesis. The target configuration is ok because in FindTE) and FindT3), the resulting
term is in evaluation position (it has no subterm), and in (FindT1) and (FindT2), the resulting term is a term that is not evaluation position in the initial configuration, so it is a subterm of $Q_{0}$. In DefinedNo and DefinedYes, the terms $M_{1}, \ldots, M_{l}$ are not in evaluation position in the initial configuration, so they are subterms of $Q_{0}$. Hence the initial configurations of the recursive calls are ok, and we conclude for the configurations inside the recursive calls by induction hypothesis. The target configuration is ok because in DefinedNo, false is in evaluation position (it has no subterm) and in DefinedYes, the resulting term $M$ is a term that is not evaluation position in the initial configuration, so it is a subterm of $Q_{0}$. The case of get is similar to the one of find. In CtxT, the initial configuration of the recursive call is ok because terms that are not in evaluation position in $N$ are also not in evaluation position in $C[N]$, so they are subterms of $Q_{0}$. We conclude for the configurations inside the recursive call by induction hypothesis. The target configuration is ok because terms that are not in evaluation position in $C\left[N^{\prime}\right]$ are either not in evaluation position inside $C$, in which case they are subterms of $Q_{0}$ because the initial configuration is ok, or they are not in evaluation position in $N^{\prime}$, in which case they are also subterms of $Q_{0}$ because the target configuration of the recursive call is ok. In CtxEventT, the target configuration is ok because the term is in evaluation position (it has no subterm).

Property 2 The desired property is preserved for unmodified oracle definitions in $\mathcal{Q}$. This is enough to conclude for Nill . For Par and Repl , the resulting oracle definitions $Q_{1}, Q_{2}, Q$ are not in evaluation position in the initial configuration, so they are subprocesses of $Q_{0}$ up to renaming of oracles. For NewOracle, $Q$ is not in evaluation position in the initial configuration, so it is a subprocess of $Q_{0}$ up to renaming of oracles, and so is $Q\left\{O^{\prime} / O\right\}$. For DefOracle, the target configuration is ok because the subterms or subprocesses not in evaluation position are subterms or subprocesses of $P$, which are not in evaluation position in the initial configuration, so that are subterms or subprocesses of $Q_{0}$ up to renaming of oracles.

Property 3 follows immediately from Property 2 by induction.
Property 4. In Return, AttYield or AttIO, $Q$ is not in evaluation position in the initial configuration, so it is a subprocess of $Q_{0}$ up to renaming of oracles. Therefore, the configuration $\{(\sigma, Q)\}, \mathcal{O} r$ is ok. By Property 3 , all configurations in the computation of $\mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$ and $\mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$ itself are ok. Moreover, in Return, $P_{1}$ is not in evaluation position in the initial configuration, so it is a subprocess of $Q_{0}$ up to renaming of oracles. We can then conclude that the target configuration is ok. In AttIO or AttYield, $P^{\prime}$ is not in evaluation position in the initial configuration, so it is a subprocess of $Q_{0}$ up to renaming of oracles. We can then conclude that the target configuration is ok. Rule OracleCall is similar with $P^{\prime}, P_{1}, P_{2}$ also not in evaluation position in the initial configuration. In Yield), $P_{2}$ is not in evaluation position in the initial configuration. All other cases can be treated similarly to terms in Property 1 Moreover, in the computation of initConfig $\left(Q_{0}, \mathcal{A}\right)$, the configuration $\left\{\left(\sigma_{0}, Q_{0}\right)\right\},(f o(Q), \emptyset)$ is ok, so by Property 3 , initConfig $\left(Q_{0}, \mathcal{A}\right)$ is ok except for the process 0 that follows return (start) in initConfig $\left(Q_{0}, \mathcal{A}\right)$. That process disappears in the first reduction, which is by AttIO.

Corollary 1 Consider a trace $\operatorname{Tr}$ of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$.
In Tr , the target oracle body of rules (New), (Let), (If1), (If2), (Find1), (Find2), (Insert), (Get1), Get2, OracleCall, Return, Yield, AttIO, AttYield, (Event is a subprocess of $Q_{0}$ up to renaming of oracles.

In Tr , the target term of rules NewT, LetT, IfT1, IfT2, (FindT1, (FindT2, (InsertT), GetT1), GetT2), EventT), (DefinedYes) is a subterm $Q_{0}$.

Proof The target term or oracle body of these rules appears in non-evaluation position in the initial configuration of these rules, so by Lemma 4, it is a subterm of $Q_{0}$ or a subprocess of $Q_{0}$ up to renaming of oracles.

We say that a configuration Conf is at program point $\mu$ in a trace $\operatorname{Tr}$ of $Q_{0}$ when Conf occurs in the derivation of $T r$, and either Conf $=E, \sigma,{ }^{\mu} N, \mathcal{T}, \mu \mathcal{E} v$ for some subterm ${ }^{\mu} N$ of $Q_{0}$ or $\operatorname{Conf}=E,\left(\sigma,{ }^{\mu} P\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ for some subprocess ${ }^{\mu} P$ of $Q_{0}$ up to renaming of oracles.

Lemma 5 Let $\operatorname{Tr}$ be a trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$. Let Conf be a configuration at program point $\mu$ in Tr. If $\mu$ is not inside a condition of find or get, then Conf is not in the derivation of an hypothesis of a rule for find or get inside the derivation of Tr .

Proof The only rules that can conclude with a term find or get are (NewT), (LetT), (IfT1), (IfT2), (FindT1), FindT2), (InsertT), (GetT1), (GetT2), EventT), (DefinedYes) and, by Corollary 1, their target term is a subterm of $Q_{0}$. The situation is similar find and get processes. So the executed term or oracle in the initial configuration of rules for find and get is always a subterm or subprocess of $Q_{0}$ up to renaming of oracles. When a configuration Conf is in the derivation of an hypothesis of a rule for find or get, it therefore always deals with program points syntactically in conditions of find or get in $Q_{0}$. (The semantic rules do not create program points.) Since $\mu$ is not inside a condition of find or get, we conclude that Conf is not in the derivation of an hypothesis of a rule for find or get.

Given a trace $T r$, we define a partial ordering relation $\preceq_{T r}$ (reflexive, transitive, antisymmetric) on the occurrences of configurations in the derivation of $T r$ : if $\operatorname{Conf}_{1} \xrightarrow{p}{ }_{t}$ Conf $_{2}$ occurs in the derivation of $T r$, then $\operatorname{Conf}_{1} \preceq_{T r} \operatorname{Conf}_{2}$ and for all Conf that occur in the derivation of the assumptions of $\operatorname{Conf}_{1} \xrightarrow{p}_{t} \operatorname{Conf}_{2}, \operatorname{Conf}_{1} \preceq_{\operatorname{Tr}} \operatorname{Conf} \preceq_{\operatorname{Tr}} \operatorname{Conf}_{2}$, and similarly for $\rightsquigarrow$ instead of $\xrightarrow{p}_{t}$. If $\operatorname{Tr}$ is a trace of $Q_{0}$ for $\mathcal{A}$, then for all Conf that occur in the derivation of $\left\{\left(\sigma_{0}, Q_{0}\right)\right\}$, $\left(\mathrm{fo}\left(Q_{0}\right), \emptyset\right) \rightsquigarrow^{*} \mathcal{Q}, \mathcal{O} r$, we have $\operatorname{Conf} \preceq \operatorname{Tr}_{r} \operatorname{initConfig}\left(Q_{0}, \mathcal{A}\right)$. When Conf $_{1} \preceq_{T r} \operatorname{Conf}_{2}$, we say that Conf $_{1}$ occurs before $\operatorname{Conf}_{2}$ in $\operatorname{Tr}$, or equivalently, that Conf ${ }_{2}$ occurs after Conf $_{1}$ in Tr .

We say that a configuration Conf $=E, \sigma,{ }^{\mu} N, \mathcal{T}, \mu \mathcal{E} v, \operatorname{Conf}=E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ with $\left(\sigma^{\prime},{ }^{\mu} Q\right) \in \mathcal{Q}$, or $\left(\sigma^{\prime},{ }^{\mu} P\right) \in \mathcal{S} t$, or $\operatorname{Conf}=\mathcal{Q}, \mathcal{O} r$ with $\left(\sigma^{\prime},{ }^{\mu} Q\right) \in \mathcal{Q}$ is inside program point $\mu$. A configuration may be inside several program points: $\operatorname{Conf}=\mathcal{Q}, \mathcal{O} r$ is inside the program points of the oracle definitions in $\mathcal{Q}, \operatorname{Conf}=E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ is inside the program points of the oracle bodies in $\mathcal{S} t$ as well as the oracle definitions in $\mathcal{Q}$.

We say that the program point $\mu$ is immediately above the program points $\mu_{j}$ in a process $Q_{0}$ when $Q_{0}$ contains one of the following constructs:

$$
\begin{aligned}
& { }^{\mu} x\left[{ }^{\mu_{1}} M_{1}, \ldots,{ }^{\mu_{m}} M_{m}\right] \\
& { }^{\mu} f\left({ }^{\mu_{1}} M_{1}, \ldots,{ }^{\mu_{m}} M_{m}\right) \\
& { }^{\mu} x[\widetilde{i}] \stackrel{R}{\leftarrow} T ;{ }^{\mu_{1}} N \\
& { }^{\mu} \text { let } x[\widetilde{i}]: T={ }^{\mu_{1}} M \text { in }{ }^{\mu_{2}} N \\
& \mu_{\text {if }}{ }^{\mu_{1}} M \text { then }{ }^{\mu_{2}} N \text { else }{ }^{\mu_{3}} N^{\prime} \\
& { }^{\mu} \text { find }[\text { unique? }]\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{i}\right]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}}[\widetilde{i}]=i_{j m_{j}} \leq n_{j m_{j}} \text { suchthat } \\
& \text { defined } \left.\left({ }^{\mu_{j, 1}} M_{j 1}, \ldots,{ }^{\mu_{j, l_{j}}} M_{j l_{j}}\right) \wedge{ }^{\mu_{j, l_{j}+1}} M_{j}^{\prime} \text { then }{ }^{\mu_{j, l_{j}+2}} N_{j}\right) \text { else }{ }^{\mu_{0}} N^{\prime} \\
& { }^{\mu_{\text {insert }}} \operatorname{Tbl}\left({ }^{\mu_{1}} M_{1}, \ldots,{ }^{\mu_{l}} M_{l}\right) ;{ }^{\mu_{0}} N \\
& \left.{ }^{\mu} \operatorname{get}[\text { unique } ?] \operatorname{Tbl}\left(x_{1} \widetilde{[i]}: T_{1}, \ldots, x_{l} \widetilde{i}\right]: T_{l}\right) \text { suchthat }{ }^{\mu_{1}} M \text { in }{ }^{\mu_{2}} N \text { else }{ }^{\mu_{3}} N^{\prime} \\
& { }^{\mu} \text { event } e\left({ }^{\mu_{1}} M_{1}, \ldots,{ }^{\mu_{l}} M_{l}\right) ;{ }^{\mu_{0}} N \\
& { }^{\mu}\left({ }^{\mu_{1}} Q \mid{ }^{\mu_{2}} Q^{\prime}\right)
\end{aligned}
$$

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\({ }^{\mu}\) foreach \(i \leq n\) do \({ }^{\mu_{1}} Q\)
\({ }^{\mu}\) newOracle \(O ;{ }^{\mu_{1}} Q\)
\({ }^{\mu} O[\widetilde{i}](x[\widetilde{i}]: T):={ }^{\mu_{0}} P\)
\({ }^{\mu}\) return \(\left({ }^{\mu_{1}} M\right) ;{ }^{\mu_{2}} Q\)
\({ }^{\mu}\) let \(x[\widetilde{i}]: T=O\left[{ }^{\mu_{1}} M_{1}, \ldots,{ }^{\mu_{l}} M_{l}, ? u_{1} \widetilde{[i]} \leq n_{1}, \ldots, ? u_{m} \widetilde{[i]} \leq n_{m}\right]\left({ }^{\mu_{0}} M\right)\) in \({ }^{\mu_{1}^{\prime}} P_{1}\) else \({ }^{\mu_{2}^{\prime}} P_{2}\)
\({ }^{\mu} x[\widetilde{i}] \stackrel{R}{\leftarrow} T ;{ }^{\mu_{1}} P\)
\({ }^{\mu}\) let \(x[\widetilde{i}]={ }^{\mu_{1}} M\) in \({ }^{\mu_{2}} P\)
\(\mu_{\text {if }}{ }^{\mu_{1}} M\) then \({ }^{\mu_{2}} P\) else \({ }^{\mu_{3}} P^{\prime}\)
\(\mu_{\text {find }}[u n i q u e ?]\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i]}=i_{j m_{j}} \leq n_{j m_{j}}\right.\) suchthat
    defined \(\left({ }^{\mu_{j, 1}} M_{j 1}, \ldots,{ }^{\mu_{j, l_{j}}} M_{j l_{j}}\right) \wedge^{\mu_{j, l_{j}+1}} M_{j}\) then \(\left.{ }^{\mu_{j, l_{j}+2}} P_{j}\right)\) else \({ }^{\mu_{0}} P\)
\(\mu_{\text {insert }} \operatorname{Tbl}\left({ }^{\mu_{1}} M_{1}, \ldots,{ }^{\mu_{l}} M_{l}\right) ;{ }^{\mu_{0}} P\)
\({ }^{\mu} \operatorname{get}[\) unique \(?] \operatorname{Tbl}\left(x_{1}[\widetilde{i}]: T_{1}, \ldots, x_{l} \widetilde{[i]}: T_{l}\right)\) suchthat \({ }^{\mu_{1}} M\) in \({ }^{\mu_{2}} P\) else \({ }^{\mu_{3}} P^{\prime}\)
\({ }^{\mu}\) event \(e\left({ }^{\mu_{1}} M_{1}, \ldots,{ }^{\mu_{l}} M_{l}\right) ;{ }^{\mu_{0}} P\)
```

The relation " $\mu$ is above $\mu^{\prime \prime}$ " is the reflexive and transitive closure of " $\mu$ is immediately above $\mu^{\prime \prime}$.

Lemma 6 Let $\operatorname{Tr}$ be a trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$. If Conf is a configuration in $\operatorname{Tr}$ inside program point $\mu$ and $\mu$ is a program point in $Q_{0}$, then either Conf is at the program point $\mu$ at the top of $Q_{0}$, or there exists a configuration Conf ${ }^{\prime} \neq$ Conf such that Conf $\preceq_{T r}$ Conf and Conf ${ }^{\prime}$ is inside program point $\mu$ or inside the program point $\mu^{\prime}$ immediately above $\mu$ in $Q_{0}$.

As a consequence, if a configuration Conf inside program point $\mu$ in $Q_{0}$ is in $\operatorname{Tr}$, then there are configurations inside all program points above $\mu$ in $Q_{0}$ before Conf in Tr .

Proof First property. Since Conf is a configuration in $T r$, we are in one of the following cases:

- Conf $=\left\{\left(\sigma_{0}, Q_{0}\right)\right\},\left(f o\left(Q_{0}\right), \emptyset\right)$, the very first configuration of $\operatorname{Tr}$. The configuration Conf is at the program point $\mu$ at the top of $Q_{0}$.
- Conf $=\operatorname{initConfig}\left(Q_{0}, \mathcal{A}\right)=\emptyset,\left(\sigma_{0}, \mu^{\prime \prime}\right.$ return $($ start $\left.)\right):: \mathcal{A}, \mathcal{Q}, \mathcal{O} r, \emptyset, \emptyset$. Since $\mu^{\prime \prime}$ is not in $Q_{0}$, $\mu$ is the program point of an oracle declaration in $\mathcal{Q}$. Then $\operatorname{Conf}^{\prime}=\mathcal{Q}, \mathcal{O} r$ is also inside $\mu$ and Conf ${ }^{\prime} \preceq_{T r}$ Conf , by definition of $\preceq_{T r}$.
- Conf is the initial configuration of an assumption of a semantic rule. In rules for find, the initial configuration of the assumption is not inside a program point (because it evaluates the defined condition, not a term). In rules for get, CtxT, and Ctx), the initial configuration of the conclusion is inside the program point $\mu^{\prime}$ immediately above $\mu$. In rules DefinedNo and DefinedYes, these rules are used to conclude assumptions of find, and the initial configuration of the find rule is inside the program point $\mu^{\prime}$ immediately above $\mu$. In rules Return and AttIO, Conf $=\{(\sigma, Q)\}, \mathcal{O} r$, and the initial configuration of the conclusion of the rule is inside the program point $\mu^{\prime}$ immediately above $\mu$.
- Conf is the target configuration of a semantic rule. In rules (NewT), LetT), (IfT1), (IfT2), (FindT1), FindT2), InsertT, GetT1, GetT2, and EventT), the initial configuration of the rule is inside the program point $\mu^{\prime}$ immediately above $\mu$. In rule (CtxT), the initial
configuration of the rule is inside the same program point $\mu$. In rule DefinedYes), this rule is used to conclude assumptions of find, and the initial configuration of the find rule is inside the program point $\mu^{\prime}$ immediately above $\mu$. In the rules for oracle definitions, if $\mu$ is the program point of an unchanged element of $\mathcal{Q}$, the initial configuration of the rule is also inside $\mu$. This is sufficient for (Nil). If $\mu$ is the program point of a modified oracle, then for rules ( Par), Repl), and NewOracle, the initial configuration of the rule is inside the program point $\mu^{\prime}$ immediately above $\mu$, and for rule (DefOracle, the initial configuration of the rule is inside the same program point $\mu$. In the rules for oracle bodies other than AttIO, AttYield, OracleCall, and Return, $\mathcal{Q}$ is unchanged, so if $\mu$ is the program point of an oracle declaration in $\mathcal{Q}$, then the initial configuration of the rule is inside the same program point $\mu$. If $\mu$ is the program point of an oracle body not at the root of the stack, then the initial configuration of the rule is also inside the same program point $\mu$, because that part of the stack is unchanged. In rules (New), (Let), (If1), (If2), (Find1), (Find2), (Insert), Get1), Get2), Event), and (Yield), if $\mu$ is the program point of an oracle body at the root of the stack, then the initial configuration of the rule is inside the program point $\mu^{\prime}$ immediately above $\mu$. In rule Ctx, the initial configuration of the rule is inside the same program point $\mu$.
In rules OracleCall, AttYield, and AttIO, if $\mu$ is the program point of an oracle definition in $\mathcal{Q}$, then the initial configuration of the rule is inside the same program point $\mu$. In rules OracleCall and AttYield, if $\mu$ is the program point of $P^{\prime}$, then the initial configuration of the rule is inside the program point $\mu^{\prime}$ immediately above $\mu$, because $\left(\sigma^{\prime}, Q_{0}\right) \in S \subseteq \mathcal{Q}$ and $\mu^{\prime}$ is the program point of $Q_{0}$. Additionally, in rule OracleCall), if $\mu$ is the program point of an oracle body in $\left(\sigma, P_{0}^{\prime}\right):: \mathcal{S} t$, then the initial configuration of the rule is inside the same program point $\mu$. In rule AttIO, we have $\left(\sigma^{\prime}, Q_{0}\right) \in S \subseteq \mathcal{Q} \uplus \mathcal{Q}^{\prime}$. If $\left(\sigma^{\prime}, Q_{0}\right) \in \mathcal{Q}$ and $\mu$ is the program point of $P^{\prime}$, then the initial configuration of the rule is inside the program point $\mu^{\prime}$ immediately above $\mu$, as above because $\mu^{\prime}$ is the program point of $Q_{0}$. If $\left(\sigma^{\prime}, Q_{0}\right) \in \mathcal{Q}^{\prime}$ and $\mu$ is the program point of $P^{\prime}$, then $\mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$ is inside the program point $\mu^{\prime}$ immediately above $\mu$.

In rule Return), if $\mu$ is the program point of an oracle definition in $\mathcal{Q}$, then the initial configuration of the rule is inside the same program point $\mu$. If $\mu$ is the program point of an oracle definition in $\mathcal{Q}^{\prime}$, then the configuration $\mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$ in the assumption of the rule is inside the same program point $\mu$. If $\mu$ is the program point of $P_{1}$, then the initial configuration of the rule is inside the program point $\mu^{\prime}$ immediately above $\mu$ as $\left(\sigma^{\prime}, P_{0}\right)$ is in the stack and $\mu^{\prime}$ is the program point of $P_{0}$. If $\mu$ is the program point of an oracle body in $\mathcal{S} t$, then the initial configuration of the rule is inside the same program point $\mu$.

Second property. Suppose that Conf is inside $\mu$ and there is a program point $\mu^{\prime}$ immediately above $\mu$ in $Q_{0}$. Let us show that there exists $\operatorname{Conf}^{\prime} \preceq_{T r} \operatorname{Conf}$ such that Conf ${ }^{\prime}$ is inside $\mu^{\prime}$. The proof proceeds by well-founded induction on $\preceq_{T r}$. The program point $\mu$ is not at the top of $Q_{0}$, so by the first property, there exists Conf $\neq$ Conf such that Conf ${ }^{\prime} \preceq_{T r}$ Conf and Conf ${ }^{\prime}$ is inside $\mu$ or inside $\mu^{\prime}$. If $C o n f^{\prime}$ is inside $\mu$, we conclude by applying the induction hypothesis on Conf ${ }^{\prime}$. If Conf ${ }^{\prime}$ is inside $\mu^{\prime}$, we have the result. By applying this property repeatedly, we obtain the second property.

Lemma 7 Let $\operatorname{Tr}$ be a trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$.

1. If Conf $=E, \sigma, C_{m}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right], \mathcal{T}, \mu \mathcal{E} v$ is the target configuration of a semantic rule in $\operatorname{Tr}$, where $\mu$ is a program point in $Q_{0}, C_{1}, \ldots, C_{m}$ are term contexts defined in Figure 7, and ${ }^{\mu} M$ is not a subterm of $Q_{0}$, then the reduction that yields Conf is obtained by $m$
applications of $\left(\overline{\mathrm{CtxT}}\right.$ with contexts $C_{m}, \ldots, C_{1}$ from a reduction with target configuration $E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E} v$, itself proved by (CtxT).
2. If Conf $=E,\left(\sigma, C_{0}\left[C_{m}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]\right]\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ is the target configuration of a semantic rule in Tr , where $\mu$ is a program point in $Q_{0}, C_{0}$ is an oracle context defined in Figure 12, $C_{1}, \ldots, C_{m}$ are term contexts defined in Figure 7, and ${ }^{\mu} M$ is not a subterm of $Q_{0}$, then the reduction that yields Conf is obtained by one application of (Ctx) with context $C_{0}$ and $m$ applications of CtxT with contexts $C_{m}, \ldots, C_{1}$ from a reduction with target configuration $E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E v}$, itself proved by (CtxT).

Proof Property 1. This property is proved by induction of $m$. The reduction that yields Conf cannot be obtained by (NewT), (LetT), (IfT1), (IfT2), (FindT1), FindT2), (InsertT), GetT1), (GetT2), EventT], DefinedYes), because in this case, by Corollary $1 . C_{m}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]$ would be a subterm of $Q_{0}$, so ${ }^{\mu} M$ would be a subterm of $Q_{0}$. So it is obtained by (CtxT). For $m=0$, this is enough to conclude. For $m>0$, the rule CtxT) is applied with context $C_{m}$. Indeed, since ${ }^{\mu} M$ is not a value, the hole of the context cannot be after $C_{m-1}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]$ and, since ${ }^{\mu} M$ is not a subterm of $Q_{0}$, the hole of the context cannot be before $C_{m-1}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]$. (If it were before, $C_{m-1}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]$ would not be in evaluation position in the initial configuration of rule CtxT, so by Lemma 4, $C_{m-1}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]$ would be a subterm of $Q_{0}$.) Hence the reduction that yields Conf is obtained from a reduction that yields $E, \sigma, C_{m-1}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right], \mathcal{T}, \mu \mathcal{E} v$ by applying CtxT with context $C_{m}$. We conclude by applying the induction hypothesis.

Property 2 . The reduction that yields Conf cannot be obtained by (New), (Let), (If1), (If2), (Find1), Find2, (Insert), Get1), Get2, (Return), Yield, OracleCall), AttYield, (AttIO), or (Event), because in this case, by Corollary 1. the oracle body of Conf would be a subprocess of $Q_{0}$ up to renaming of oracles, so ${ }^{\mu} M$ would be a subterm of $Q_{0}$. Therefore, Conf is the target configuration of (Ctx). Furthermore, by the same reasoning as in Property 1, this rule is applied with context $C_{0}$. Hence the reduction that yields Conf is obtained from a reduction that yields $E, \sigma, C_{m}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right], \mathcal{T}, \mu \mathcal{E} v$ by applying (Ctx) with context $C_{0}$. We conclude by Property 1 .

Lemma 8 Let $\operatorname{Tr}$ be a trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$.

1. If Conf $=E,\left(\sigma,{ }^{\mu} P\right):: \mathcal{S}, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ is a configuration in $\operatorname{Tr}$ where $\mu$ is a program point in $Q_{0}$, then this configuration is derived in Tr from a configuration Conf ${ }^{\prime}=E^{\prime}$, $\left(\sigma,{ }^{\mu} P^{\prime}\right):: \mathcal{S} t^{\prime}, \mathcal{Q}, \mathcal{O} r, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ where ${ }^{\mu} P^{\prime}$ is a subprocess of $Q_{0}$ up to renaming of oracles, by (Ctx any number of times.
2. If Conf $=\left\{\left(\sigma,{ }^{\mu} Q\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r$ is a configuration in $\operatorname{Tr}$ where $\mu$ is a program point in $Q_{0}$, then, possibly after swapping reductions in $\operatorname{Tr}$, this configuration is derived from a configuration Conf ${ }^{\prime}=\left\{\left(\sigma,{ }^{\mu} Q^{\prime}\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r$ where ${ }^{\mu} Q^{\prime}$ is a subprocess of $Q_{0}$ up to renaming of oracles, by (DefOracle) any number of times.
3. If Conf $=E,\left(\sigma, C_{0}\left[C_{m}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]\right]\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ is a configuration in $\operatorname{Tr}$ where $\mu$ is a program point in $Q_{0}, C_{0}$ is an oracle context defined in Figure 12, and $C_{1}, \ldots, C_{m}$ are term contexts defined in Figure 7, then we have

$$
E^{\prime}, \sigma,{ }^{\mu} M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime} \xrightarrow{p}_{t} \ldots{\xrightarrow{p^{\prime}} t^{\prime}} E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E} v
$$

by CtxT any number of times, where ${ }^{\mu} M^{\prime}$ is a subterm of $Q_{0}$ and in Tr , these reductions are in fact performed starting from a configuration Conf ${ }^{\prime}=E^{\prime},\left(\sigma, C_{0}\left[C_{m}\left[\ldots C_{1}\left[{ }^{\mu} M^{\prime}\right] \ldots\right]\right]\right)$, $\mathcal{Q}, \mathcal{O} r, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ under one application of rule Ctx with context $C_{0}$ and $m$ applications of rule (CtxT with contexts $C_{m}, \ldots, C_{1}$.
4. If Conf $=E, \sigma, C_{l}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right], \mathcal{T}, \mu \mathcal{E} v$ is a configuration in $\operatorname{Tr}$ and $\mu$ is a program point in $Q_{0}$ where $C_{1}, \ldots, C_{l}$ are term contexts defined in Figure 7, then we have

$$
E^{\prime}, \sigma,{ }^{\mu} M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime} \xrightarrow{p}_{t} \ldots{\xrightarrow{p^{\prime}}}_{t^{\prime}} E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E} v
$$

by (CtxT) any number of times, where ${ }^{\mu} M^{\prime}$ is a subterm of $Q_{0}$ and in $T r$, these reductions are in fact performed starting

- from a configuration Conf ${ }^{\prime}=E^{\prime}, \sigma, C_{m}\left[\ldots C_{1}\left[{ }^{\mu} M^{\prime}\right] \ldots\right], \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ where $m \geq l, C_{1}$, $\ldots, C_{m}$ are term contexts defined in Figure 7, under $m$ applications of CtxT with contexts $C_{m}, \ldots, C_{1}$.
- or from a configuration Conf ${ }^{\prime}=E^{\prime},\left(\sigma, C_{0}\left[C_{m}\left[\ldots C_{1}\left[{ }^{\mu} M^{\prime}\right] \ldots\right]\right]\right):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ where $m \geq l, C_{0}$ is an oracle context defined in Figure 12, and $C_{1}, \ldots, C_{l}$ are term contexts defined in Figure 7, under one application of (Ctx) with context $C_{0}$ and $m$ applications of CtxT with contexts $C_{m}, \ldots, C_{1}$.

Proof Property 1 . The proof proceeds by well-founded induction on $\preceq_{T r}$. The configuration Conf cannot be initConfig $\left(Q_{0}, \mathcal{A}\right)$ because $\mu$ is a program point in $Q_{0}$. Then, Conf is the target configuration of some semantic rule. If Conf is the target configuration of (New), (Let), (If1), (If2), (Find1), (Find2), (Insert), Get1), (Get2), OracleCall), Return), AttYield), AttIO) or (Event), then by Corollary 1, ${ }^{\mu} P$ is a subprocess of $Q_{0}$ up to renaming of oracles, so the property holds with Conf ${ }^{\prime}=$ Conf. If it is the target configuration of Ctx, we conclude by applying the induction hypothesis to the initial configuration of this rule.

Property 2. The proof proceeds by well-founded induction on $\preceq T_{T r}$. If $\operatorname{Conf}=\left\{\left(\sigma_{0}, Q_{0}\right)\right\}$, (fo $\left.\left(Q_{0}\right), \emptyset\right)$, then the property holds with $\operatorname{Conf}^{\prime}=\operatorname{Conf}$, since $Q_{0}$ is a subprocess of $Q_{0}$. If Conf is the initial configuration of the assumption of Return or AttIO, then by Lemma 4 , $Q$ is a subprocess of $Q_{0}$ up to renaming of oracles, since $Q$ occurs in non-evaluation position in the initial configuration of Return or AttIO. So the property holds with Conf $=$ Conf. Otherwise, Conf is the target configuration of a semantic rule.

- If that rule does not affect $Q$, then it is of the form $\left\{\left(\sigma,{ }^{\mu} Q\right)\right\} \uplus \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime} \rightsquigarrow\left\{\left(\sigma,{ }^{\mu} Q\right)\right\} \uplus$ $\mathcal{Q}, \mathcal{O} r$. We apply the induction hypothesis to $\left\{\left(\sigma,^{\mu} Q\right)\right\} \uplus \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$, so possibly after swapping reductions in $\operatorname{Tr}$, we have $\left\{\left(\sigma,{ }^{\mu} Q^{\prime}\right)\right\} \uplus \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime} \rightsquigarrow{ }^{*}\left\{\left(\sigma,{ }^{\mu} Q\right)\right\} \uplus \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$ by DefOracle any number of times, where ${ }^{\mu} Q^{\prime}$ is a subprocess of $Q_{0}$ up to renaming of oracles. By swapping reductions, we have $\left\{\left(\sigma,{ }^{\mu} Q^{\prime}\right)\right\} \uplus \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime} \rightsquigarrow\left\{\left(\sigma,{ }^{\mu} Q^{\prime}\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r \rightsquigarrow{ }^{*}\left\{\left(\sigma,{ }^{\mu} Q\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r$, so we obtain the desired property with $\operatorname{Conf}^{\prime}=\left\{\left(\sigma,{ }^{\mu} Q^{\prime}\right)\right\} \uplus \mathcal{Q}, \mathcal{O} r$.
- Otherwise, that rule affects $Q$. If that rule is Par, Repl, or NewOracle, then by Lemma 4. $Q$ is a subprocess of $Q_{0}$ up to renaming of oracles, since $Q$ occurs in nonevaluation position in the initial configuration of the rule. So the property holds with Conf $^{\prime}=$ Conf. If that rule is DefOracle, then we obtain the result by induction hypothesis applied to the initial configuration of the rule.

Property 3 The proof proceeds by well-founded induction on $\preceq_{T r}$. The configuration Conf cannot be initConfig $\left(Q_{0}, \mathcal{A}\right)$ because $\mu$ is a program point in $Q_{0}$. Then, Conf is the target configuration of some semantic rule. If ${ }^{\mu} M$ is a subterm of $Q_{0}$, then the property holds with Conf ${ }^{\prime}=$ Conf. Otherwise, by Lemma 7, Property 2, the reduction that yields Conf is obtained by one application of (Ctx with context $C_{0}$ and $m$ applications of (CtxT with contexts $C_{m}$, $\ldots, C_{1}$ from a reduction with target configuration $E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E} v$, itself proved by (CtxT). We obtain the desired property by applying the induction hypothesis to the configuration before this reduction step by Ctx.

Property 4 The proof proceeds by well-founded induction on $\preceq_{T r}$. First case: Conf is the initial configuration of an assumption of a semantic rule. This rule cannot be a rule for find (in rules for find, the initial configuration of assumption is not inside a program point, because it evaluates the defined condition, not a term). In rules for get, (DefinedNo, and DefinedYes, by Lemma 4 , since the term in Conf occurs in non-evaluation position in the initial configuration of the rule, it is a subterm of $Q_{0}$, so ${ }^{\mu} M$ is a subterm of $Q_{0}$. The property holds with Conf ${ }^{\prime}=$ Conf. In (CtxT), we let $C_{l+1}$ be the context used in this rule, and we conclude by induction hypothesis applied to the initial configuration of this rule: $E, \sigma, C_{l+1}\left[C_{l}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]\right], \mathcal{T}, \mu \mathcal{E} v$. In (Ctx), we let $m=l$. The initial configuration of the rule is of the form $E,\left(\sigma, C_{0}\left[C_{l}\left[\ldots C_{1}\left[{ }^{\mu} M\right] \ldots\right]\right]\right), \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ for some process context $C_{0}$ defined in Figure 12 . We conclude by applying Property 3 to that configuration.

Second case: Conf is the target configuration of a semantic rule. If ${ }^{\mu} M$ is a subterm of $Q_{0}$, then the property holds with Conf $f^{\prime}=$ Conf. Otherwise, by Lemma 7 Property 1 the reduction that yields Conf is obtained by $l$ applications of (CtxT) with contexts $C_{l}, \ldots, C_{1}$ from a reduction with target configuration $E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E} v$, itself proved by (CtxT). We apply the induction hypothesis to the initial configuration of the reduction that yields Conf, and we continue the reduction one more step by applying possibly (Ctx) with context $C_{0}$, (CtxT) $m$ times with contexts $C_{m}, \ldots, C_{1}$ under the reduction with target configuration $E, \sigma,{ }^{\mu} M, \mathcal{T}, \mu \mathcal{E} v$. This is also what happens in Tr. (By inspection of the rules, only the rule (Ctx) with context $C_{0}$ can reduce an oracle body $C_{0}[N]$, where $C_{0}$ is a process context defined in Figure 12, only the rule $\left[\mathrm{CtxT}\right.$ with context $C_{j}$ can reduce a term $C_{j}[N]$, where $C_{j}$ is a term context defined in Figure 7)

### 2.4.3 Each Variable is Defined at Most Once

In this section, we show that Invariant 1 implies that each array cell is assigned at most once during the execution of a process.

We define the multiset of variable accesses that may be defined by a term or a process (given the replication indices fixed by a mapping sequence $\sigma$ ) as follows:

$$
\begin{aligned}
& \operatorname{Defined}\left(\sigma,{ }^{\mu} i\right)=\emptyset \\
& \operatorname{Defined}\left(\sigma,{ }^{\mu} x\left[M_{1}, \ldots, M_{m}\right]\right)=\biguplus_{j=1}^{m} \operatorname{Defined}\left(\sigma, M_{j}\right) \\
& \operatorname{Defined}\left(\sigma,{ }^{\mu} f\left(M_{1}, \ldots, M_{m}\right)\right)=\biguplus_{j=1}^{m} \operatorname{Defined}\left(\sigma, M_{j}\right) \\
& \operatorname{Defined}\left(\sigma,{ }^{\mu} x[\widetilde{i}] \stackrel{R}{\stackrel{R}{*}} T ; N\right)=\{x[\sigma(\widetilde{i})]\} \uplus \operatorname{Defined}(\sigma, N) \\
& \operatorname{Defined}\left(\sigma,{ }^{\mu} \text { let } x[\widetilde{i}]: T=M \text { in } N\right)=\{x[\sigma(\widetilde{i})]\} \uplus \operatorname{Defined}(\sigma, M) \uplus \operatorname{Defined}(\sigma, N) \\
& \operatorname{Defined}\left(\sigma,{ }^{\mu_{\text {if }}} M \text { then } N \text { else } N^{\prime}\right)=\operatorname{Defined}(M) \uplus \max \left(\operatorname{Defined}(N), \operatorname{Defined}\left(N^{\prime}\right)\right) \\
& \left.\operatorname{Defined}\left(\sigma,{ }^{\mu} \text { find }[\text { unique? }]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}} \text { suchthat defined }\left(\widetilde{M_{j}}\right) \wedge M_{j} \text { then } N_{j}\right) \text { else } N\right)= \\
& \left.\max \left(\max _{j=1}^{m} \max _{\widetilde{a} \leq \widetilde{n}_{j}} \operatorname{Defined}\left(\sigma\left[\widetilde{i_{j}} \mapsto \widetilde{a}\right], M_{j}\right), \max _{j=1}^{m}\left\{\widetilde{u_{j}}[\sigma \widetilde{( })\right]\right\} \uplus \operatorname{Defined}\left(\sigma, N_{j}\right) \text {, } \operatorname{Defined}(\sigma, N)\right) \\
& \operatorname{Defined}\left(\sigma,{ }_{\text {insert }} \operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; N\right)=\biguplus_{j=1}^{l} \operatorname{Defined}\left(\sigma, M_{j}\right) \uplus \operatorname{Defined}(\sigma, N)
\end{aligned}
$$

$\operatorname{Defined}\left(\sigma,{ }^{\mu} \operatorname{get}[\right.$ unique $?] \operatorname{Tbl}\left(x_{1} \widetilde{[i]}: T_{1}, \ldots, x_{l} \widetilde{[i]}: T_{l}\right)$ suchthat $M$ in $N$ else $\left.N^{\prime}\right)=$ $\left.\max \left(\left\{x_{j}[\sigma \widetilde{i})\right] \mid j \leq l\right\} \uplus \max (\operatorname{Defined}(\sigma, M), \operatorname{Defined}(\sigma, N)), \operatorname{Defined}\left(\sigma, N^{\prime}\right)\right)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ event $\left.e\left(M_{1}, \ldots, M_{l}\right) ; N\right)=\biguplus_{j=1}^{l} \operatorname{Defined}\left(\sigma, M_{j}\right) \uplus \operatorname{Defined}(\sigma, N)$
Defined $\left(\sigma,{ }^{\mu}\right.$ event_abort $\left.e\right)=\emptyset$
$\operatorname{Defined}(\sigma, a)=\operatorname{Defined}(\sigma$, event_abort $(\mu, \widetilde{a}): e)=\emptyset$
$\operatorname{Defined}\left(\sigma,{ }^{\mu} 0\right)=\emptyset$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\left(Q_{1} \mid Q_{2}\right)\right)=\operatorname{Defined}\left(\sigma, Q_{1}\right) \uplus \operatorname{Defined}\left(\sigma, Q_{2}\right)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ foreach $i \leq n$ do $\left.Q\right)=\biguplus_{a \in[1, n]} \operatorname{Defined}(\sigma[i \mapsto a], Q)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ newOracle $\left.O ; Q\right)=\operatorname{Defined}(\sigma, Q)$
$\left.\operatorname{Defined}\left(\sigma,{ }^{\mu} O \widetilde{i}\right](x[\widetilde{i}]: T):=P\right)=\{x[\sigma(\widetilde{i})]\} \uplus \operatorname{Defined}(\sigma, P)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ return $\left.(M) ; Q\right)=\operatorname{Defined}(\sigma, M) \uplus \operatorname{Defined}(\sigma, Q)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ let $\left.\left.x[\widetilde{i}]: T=O\left[M_{1}, \ldots, M_{l}, ? u_{1} \widetilde{[i}\right] \leq n_{1}, \ldots, ? u_{m} \widetilde{[i}\right] \leq n_{m}\right](N)$ in $P$ else $\left.P^{\prime}\right)=$

$$
\biguplus_{j=1}^{l} \operatorname{Defined}\left(M_{j}\right) \uplus\left\{u_{j}[\sigma(\widetilde{i})] \mid j \leq m\right\} \uplus \max \left(\{x[\sigma(\widetilde{i})]\} \uplus \operatorname{Defined}(\sigma, P), \text { Defined }\left(\sigma, P^{\prime}\right)\right)
$$

$\operatorname{Defined}\left(\sigma,{ }^{\mu} x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P\right)=\{x[\sigma(\widetilde{i})]\} \uplus \operatorname{Defined}(\sigma, P)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ let $x[\widetilde{i}]: T=M$ in $\left.P\right)=\{x[\sigma(\widetilde{i})]\} \uplus \operatorname{Defined}(\sigma, M) \uplus \operatorname{Defined}(\sigma, P)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ if $M$ then $P$ else $\left.P^{\prime}\right)=\operatorname{Defined}(M) \uplus \max \left(\operatorname{Defined}(P), \operatorname{Defined}\left(P^{\prime}\right)\right)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ find $[u n i q u e ?]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}}[\widetilde{i}]=\widetilde{i_{j}} \leq \widetilde{n_{j}} \operatorname{suchthat~defined}\left(\widetilde{M_{j}}\right) \wedge M_{j}\right.$ then $\left.P_{j}\right)$ else $\left.P\right)=$ $\left.\max \left(\max _{j=1}^{m} \max _{\widetilde{a} \leq \bar{n}_{j}} \operatorname{Defined}\left(\sigma\left[\widetilde{i_{j}} \mapsto \widetilde{a}\right], M_{j}\right), \max _{j=1}\left\{\widetilde{u_{j}}[\sigma \widetilde{( })\right]\right\} \uplus \operatorname{Defined}\left(\sigma, P_{j}\right), \operatorname{Defined}(\sigma, P)\right)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu_{\text {insert }}} \operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; P\right)=\biguplus_{j=1}^{l} \operatorname{Defined}\left(\sigma, M_{j}\right) \uplus \operatorname{Defined}(\sigma, P)$
$\left.\operatorname{Defined}\left(\sigma,{ }^{\mu} \operatorname{get}[u n i q u e ?] \operatorname{Tbl}\left(x_{1} \widetilde{i}\right]: T_{1}, \ldots, x_{l} \widetilde{i}\right]: T_{l}\right)$ suchthat $M$ in $P$ else $\left.P^{\prime}\right)=$ $\max \left(\left\{x_{j}[\sigma \widetilde{(i)}] \mid j \leq l\right\} \uplus \max (\operatorname{Defined}(\sigma, M), \operatorname{Defined}(\sigma, P)), \operatorname{Defined}\left(\sigma, P^{\prime}\right)\right)$
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ event $\left.e\left(M_{1}, \ldots, M_{l}\right) ; P\right)=\biguplus_{j=1}^{l} \operatorname{Defined}\left(\sigma, M_{j}\right) \uplus \operatorname{Defined}(\sigma, P)$
Defined $\left(\sigma,{ }^{\mu}\right.$ event_abort $\left.e\right)=\emptyset$
$\operatorname{Defined}(\sigma$, abort $)=\emptyset$
$\operatorname{Defined}(\sigma$, yield $)=\emptyset$
Notice that, by Invariant 5, the terms $\widetilde{M}_{j}$ in defined conditions of find do not define any variable. By Invariant 3, the variables defined in conditions of find and get can be considered as defined temporarily only during the evaluation of the considered condition. Given a configuration Conf $=E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v$ or Conf $=E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$, we denote by $E_{\text {Conf }}$ the environment $E$ in configuration Conf. For Conf $=\mathcal{Q}, \mathcal{O} r, E_{\text {Conf }}$ is empty. We define

$$
\text { Defined }^{\text {Fut }}(E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v)=\operatorname{Defined}(\sigma, M)
$$

$$
\begin{aligned}
& \text { Defined }^{\mathrm{Fut}}(\mathcal{Q}, \mathcal{O} r)=\biguplus_{(\sigma, Q) \in \mathcal{Q}} \operatorname{Defined}(\sigma, Q) \\
& \operatorname{Defined}^{\mathrm{Fut}}(E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v)=\biguplus_{(\sigma, P) \in \mathcal{S} t} \operatorname{Defined}(\sigma, P) \uplus \biguplus_{(\sigma, Q) \in \mathcal{Q}} \operatorname{Defined}(\sigma, Q) \\
& \operatorname{Defined}(\text { Conf })=\operatorname{Dom}\left(E_{\text {Conf }}\right) \uplus \operatorname{Defined}^{\mathrm{Fut}}(\text { Conf }) .
\end{aligned}
$$

Invariant 9 (Single definition, for executing games) The semantic configuration Conf (which can be $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ or $\mathcal{Q}, \mathcal{O} r$ or $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ ) satisfies Invariant 9 if and only if Defined (Conf) does not contain duplicate elements.

Lemma 9 Let $\operatorname{Tr}$ be trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$. If $Q_{0}$ satisfies Invariant 1, then all semantic configurations in the derivation of $\operatorname{Tr}$ satisfy Invariant 9 .

Proof sketch We first show that, for all program points $\mu$ in $Q_{0}$, if $\operatorname{Dom}(\sigma)=I_{\mu}$ are the current replication indices at $\mu$ and the process or term $Q$ at $\mu$ satisfies Invariant 1 then all elements of Defined $(\sigma, Q)$ are of the form $x[\widetilde{a}]$ where $x \in \operatorname{vardef}(Q)$ and $\operatorname{Im}(\sigma)$ is a prefix of $\widetilde{a}$. The proof proceeds by induction on $Q$. At the definition of a variable $x \widetilde{i}], x[\sigma(\widetilde{i})]$ is added to $\operatorname{Defined}(\sigma, Q)$ and we have $x \in \operatorname{vardef}(Q)$; by Invariant $1, \widetilde{i}$ are the current replication indices at that definition, so $\sigma(\widetilde{i})=\operatorname{Im}(\sigma)$. All recursive calls $D e f i n e d\left(\sigma^{\prime}, \mu^{\prime} Q^{\prime}\right)$ consider an extension $\sigma^{\prime}$ of $\sigma$ and a subprocess or subterm $Q^{\prime}$ of $Q\left(\operatorname{so} \operatorname{vardef}\left(Q^{\prime}\right) \subseteq \operatorname{vardef}(Q)\right)$ such that $\operatorname{Dom}\left(\sigma^{\prime}\right)=I_{\mu^{\prime}}$ are the current replication indices at $\mu^{\prime}$.

Next, we show that, for all program points $\mu$, if $\operatorname{Dom}(\sigma)=I_{\mu}$ are the current replication indices at $\mu$ and the process or term $Q$ at $\mu$ satisfies Invariant 1, then Defined $(\sigma, Q)$ does not contain duplicate elements. The proof proceeds by induction on $Q$. All multiset unions in the computation of $\operatorname{Defined}(\sigma, Q)$ are disjoint unions by the property above, because either they use different extensions of $\sigma$ (case of replication) or they use disjoint variable definitions or subprocesses or subterms in the same branch of find, if, get, or oracle call, which must define different variables by Invariant 1 .

We show by induction on the derivations that, if Conf $\xrightarrow{p}_{t}$ Conf ${ }^{\prime}$, then $\operatorname{Defined}(\operatorname{Conf}) \supseteq$ Defined (Conf ${ }^{\prime}$ ) and for all semantic configurations Conf ${ }^{\prime \prime}$ in the derivation of Conf ${ }^{p}{ }_{t}$ Conf ${ }^{\prime}$, $\operatorname{Defined}($ Conf $) \supseteq \operatorname{Defined}\left(\right.$ Conf $\left.f^{\prime \prime}\right)$, and similarly with $\rightsquigarrow$ instead of ${ }_{\rightarrow}^{p}$.

The result follows: since $Q_{0}$ satisfies Invariant 1, Defined $\left(\sigma_{0}, Q_{0}\right)$ does not contain duplicate elements, where $\sigma_{0}$ is the empty mapping sequence. Then $\left\{\left(\sigma_{0}, Q_{0}\right)\right\}$, $\left(\mathrm{fo}\left(Q_{0}\right), \emptyset\right)$ satisfies Invariant 9 and so do reduce $\left(\left\{\left(\sigma_{0}, Q_{0}\right)\right\},\left(f o\left(Q_{0}\right), \emptyset\right)\right)$, initConfig $\left(Q_{0}, \mathcal{A}\right)$, and the other configurations of Tr .

Corollary 2 If $Q_{0}$ satisfies Invariant 1, then each variable that is not defined in a condition of find or get is defined at most once for each value of its array indices in a trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$.

Proof Let $x$ be the considered variable and $\operatorname{Tr}$ be the considered trace of $Q_{0}$. The only semantic rules that can add $x[\widetilde{a}]$ to the environment $E$ are $(N e w T$, (LetT), (FindT1), GetT1), (New), Let, (Find1), Get1, AttYield, AttIO, OracleCall) and (Return). By Corollary 1. the target term or process of these rules is a subterm or subprocess of $Q_{0}$ up to renaming of oracles. Hence, the target configuration Conf ${ }^{\prime}$ of these rules is at some program point $\mu$ in Tr . By hypothesis, $x$ is not defined in conditions of find or get, so $\mu$ is not inside the condition of find or get in $Q_{0}$, so by Lemma 5, the configuration Conf ${ }^{\prime}$ is not in the derivation of an assumption of a rule for find or get.

In order to derive a contradiction, assume that two transitions $\operatorname{Conf}_{1} \xrightarrow{p_{1}}{ }_{t_{1}} \operatorname{Conf}_{1}^{\prime}$ and $\mathrm{Conf}_{2} \xrightarrow{p_{2}} t_{2}$ Conf $_{2}^{\prime}$ inside $\operatorname{Tr}$ define the same variable $x[\widetilde{a}]$.

- First case: one transition happens before the other, for instance $\operatorname{Conf}_{1}^{\prime} \preceq{ }_{T r} \operatorname{Conf}_{2}$. (The case $\operatorname{Conf}_{2}^{\prime} \preceq \operatorname{Tr} \operatorname{Conf}_{1}$ is symmetric.) Since $\operatorname{Conf}_{1} \xrightarrow{p_{1}} t_{1} C o n f_{1}^{\prime}$ defines $x[\widetilde{a}]$, we have $x[\widetilde{a}] \in \operatorname{Dom}\left(E_{\text {Conf }_{1}^{\prime}}\right)$. Since $\operatorname{Conf}_{1}^{\prime}$ is not in the derivation of an assumption of a rule for find or get, by Lemma 3, $E_{\text {Conf }_{2}}$ extends $E_{\text {Conf }_{1}^{\prime}}$, so $x[\widetilde{a}] \in \operatorname{Dom}\left(E_{\text {Conf }_{2}}\right)$. Moreover, since Conf $_{2} \xrightarrow{p_{2}} t_{2}$ Conf $_{2}^{\prime}$ defines $x[\widetilde{a}]$, we have $x[\widetilde{a}] \in$ Defined $^{\text {Fut }}\left(\right.$ Conf $\left._{2}\right)$, by inspecting all rules that add elements to the environment. Therefore $\operatorname{Defined}\left(\operatorname{Conf}_{2}\right)=\operatorname{Dom}\left(E_{\text {Conf }_{2}}\right) \uplus$ Defined ${ }^{\text {Fut }}\left(\right.$ Conf $\left._{2}\right)$ contains twice $x[\widetilde{a}]$. Contradiction with Invariant 9 .
- Second case: the transitions cannot be ordered. By definition of $\preceq_{T r}$, this can happen only when a semantic rule uses several derivations for its assumptions, which happens only in rules for find or get. Contradiction.
That concludes the proof.
Variables defined in conditions of get may be defined several times, once for each element of the table that is tested. Variables defined in conditions of find may be defined several times in case the same variable is used in several branches of the same find. (We use the indices of the find as indices of the variables defined in the condition, so when we evaluate several times the condition of a certain branch of a find, we use variables with different indices.) In Section 2.7, we define properties that exclude these situations (Properties 3 and 4 ), and we prove in Lemma 29 that every variable is defined at most once for each value of its indices when these properties are satisfied.


### 2.4.4 Each Oracle is defined at most once

Similarly to the variable definition case, we can show that Invariant 7 implies that each oracle is defined at most once during the execution of a process. This ensures that for every oracle call, a unique corresponding oracle is potentially available. We generalize the previous Defined ${ }^{O}$ definition of Invariant 7 to also take into account the replication indices fixed by a mapping sequence $\sigma$ as follows:

$$
\begin{aligned}
& \operatorname{Defined~}_{p}^{O}\left(\sigma,{ }^{\mu} 0\right)=\emptyset \\
& \operatorname{Defined}_{p}^{O}\left(\sigma,{ }^{\mu}\left(Q_{1} \mid Q_{2}\right)\right)=\operatorname{Defined}_{p}^{O}\left(\sigma, Q_{1}\right) \uplus \operatorname{Defined}_{p}^{O}\left(\sigma, Q_{2}\right) \\
& \operatorname{Defined}_{p}^{O}\left(\sigma,{ }^{\mu} \text { foreach } i \leq n \text { do } Q\right)=\biguplus_{a \in[1, n]} \operatorname{Defined}_{p}^{O}(\sigma[i \mapsto a], Q) \\
& \operatorname{Defined}_{p}^{O}\left(\sigma,{ }^{\mu} \text { newOracle } O ; Q\right)=\operatorname{Defined}_{p}^{O}(\sigma, Q) \backslash\left\{O \widetilde{[i]} \mid k \in \mathbb{N}, \widetilde{i} \in \mathbb{N}^{k}\right\} \\
& \operatorname{Defined}_{p}^{O}\left(\sigma,{ }^{\mu} O \widetilde{[i]}(x \widetilde{[i]}: T):=P\right)=\left\{O \left[\sigma \widetilde{(i)]\} \uplus \operatorname{Defined}_{p}^{O}(\sigma, P)}\right.\right. \\
& \operatorname{Defined}_{p}^{O}\left(\sigma,{ }^{\mu} C\left[Q_{1}, \ldots, Q_{k}\right]\right)=\max _{j=1}^{k} \operatorname{Defined}_{p}^{O}\left(\sigma, Q_{j}\right)
\end{aligned}
$$

Here, similarly to the definition of Invariant 7, $C$ is a context restricted to oracle body constructs only. We lift Defined $_{p}^{O}$ to configurations in a similar fashion to Defined, as:

$$
\begin{aligned}
& \operatorname{Defined}_{p}^{O}(\mathcal{Q}, \mathcal{O} r)=\biguplus_{(\sigma, Q) \in \mathcal{Q}} \operatorname{Defined}_{p}^{O}(\sigma, Q) \\
& \operatorname{Defined}_{p}^{O}(E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v)=\biguplus_{(\sigma, P) \in \mathcal{S} t} \operatorname{Defined}_{p}^{O}(\sigma, P) \uplus \biguplus_{(\sigma, Q) \in \mathcal{Q}} \operatorname{Defined}_{p}^{O}(\sigma, Q)
\end{aligned}
$$

Invariant 10 (Single definition, for executing games) The semantic configuration Conf (which can be $\mathcal{Q}, \mathcal{O} r$ or $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ ) satisfies Invariant 10 if and only if Defined $_{p}^{O}(\operatorname{Conf})$ does not contain duplicate elements.

Lemma 10 Let $\operatorname{Tr}$ be trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$. If $Q_{0}$ satisfies Invariant 7 , then all semantic configurations in the derivation of $\operatorname{Tr}$ satisfy Invariant 10 .

We omit the proof, which is similar to the one of Lemma 9 . The core difference is that Defined ${ }_{p}^{O}$ does not directly diminish over the evolution of configurations, as newOracle $O$ introduces new definitions. We remark that however, Defined $_{p}^{O} \cap \mathcal{O} r_{\text {pub }}$ diminishes for all rules, and by construction, a newOracle $O$ command introduces new oracle definitions that are distinct from all existing ones.

### 2.4.5 Variables are Defined Before Being Used

In this section, we show that Invariant 2 implies that all variables are defined before being used. In order to show this property, we use the following invariant:

Invariant 11 (Defined variables, for executing games) The semantic configuration $E, \mathcal{S} t$, $\mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ satisfies Invariant 11 if and only if every occurrence of a variable access $x\left[M_{1}, \ldots\right.$, $\left.M_{m}\right]$ in $\mathcal{S} t$ or $\mathcal{Q}$ is either

1. present in $\operatorname{Dom}(E)$ : if $x\left[M_{1}, \ldots, M_{m}\right]$ occurs in a process $P^{\prime}$ for $\left(\sigma^{\prime}, P^{\prime}\right) \in \mathcal{S} t \cup \mathcal{Q}$, then for all $j \leq m, E, \sigma^{\prime}, M_{j} \Downarrow a_{j}$ and $x\left[a_{1}, \ldots, a_{m}\right] \in \operatorname{Dom}(E)$;
2. or syntactically under the definition of $x\left[M_{1}, \ldots, M_{m}\right]$ (in which case for all $j \leq m, M_{j}$ is a constant or variable replication index);
3. or in a defined condition in a find process or term;
4. or in $M_{j}^{\prime}$ in a process or term of the form find $\left(\bigoplus_{j=1}^{m^{\prime \prime}} \widetilde{u_{j}} \widetilde{[i]}=\widetilde{i_{j}} \leq \widetilde{n_{j}}\right.$ suchthat defined $\left(M_{j 1}^{\prime}\right.$, $\left.\ldots, M_{j l_{j}}^{\prime}\right) \wedge M_{j}^{\prime}$ then $P_{j}$ ) else $P$ where for some $k \leq l_{j}, x\left[M_{1}, \ldots, M_{m}\right]$ is a subterm of $M_{j k}^{\prime}$.
5. or in $P_{j}$ in a process or term of the form find $\left(\bigoplus_{j=1}^{m^{\prime \prime}} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$ suchthat defined $\left(M_{j 1}^{\prime}\right.$, $\left.\ldots, M_{j l_{j}}^{\prime}\right) \wedge M_{j}^{\prime}$ then $P_{j}$ ) else $P$ where for some $k \leq l_{j}$, there is a subterm $N$ of $M_{j k}^{\prime}$ such that $N\left\{\widetilde{u_{j}} \widetilde{[i]} / \widetilde{i_{j}}\right\}=x\left[M_{1}, \ldots, M_{m}\right]$.

Similarly, $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ satisfies Invariant 11 if and only if every occurrence of a variable access $x\left[M_{1}, \ldots, M_{m}\right]$ in $M$ either is present in $\operatorname{Dom}(E)$ (for all $j \leq m, E, \sigma, M_{j} \Downarrow a_{j}$ and $\left.x\left[a_{1}, \ldots, a_{m}\right] \in \operatorname{Dom}(E)\right)$ or satisfies one of the last four conditions above.
$E, \sigma$, defined $\left(M_{1}^{\prime}, \ldots, M_{l}^{\prime}\right) \wedge M, \mathcal{T}, \mu \mathcal{E} v$ satisfies Invariant 11 if and only if every occurrence of a variable access $x\left[M_{1}, \ldots, M_{m}\right]$ in $M$ either is a subterm of $M_{1}^{\prime}, \ldots, M_{l}^{\prime}$, or is present in $\operatorname{Dom}(E)$ (for all $j \leq m, E, \sigma, M_{j} \Downarrow a_{j}$ and $x\left[a_{1}, \ldots, a_{m}\right] \in \operatorname{Dom}(E)$ ) or satisfies one of the last four conditions above.

Recall that, by Invariants 2 and 5, the terms of all variable accesses $x\left[M_{1}, \ldots, M_{m}\right]$ are simple. That is why we can evaluate them by $E, \sigma^{\prime}, M_{j} \Downarrow a_{j}$.

Lemma 11 If $Q_{0}$ satisfies Invariant 2, then $\operatorname{initConfig}\left(Q_{0}, \mathcal{A}\right)$ satisfies Invariant 11 .
Lemma 12 Let $M$ be a simple term. If $E, \sigma, M \Downarrow a$, then for all subterms $x\left[M_{1}, \ldots, M_{m}\right]$ of $M$, for all $j^{\prime} \leq m, E, \sigma, M_{j^{\prime}} \Downarrow a_{j^{\prime}}$ and $x\left[a_{1}, \ldots, a_{m}\right]$ is in $\operatorname{Dom}(E)$.

Proof sketch By induction on $M$.
Lemma 13 Let $N, M$ be simple terms. If $E, \sigma\left[i \mapsto a^{\prime}\right], N \Downarrow a$ and $E, \sigma, M \Downarrow a^{\prime}$, then we have $E, \sigma, N\{M / i\} \Downarrow a$.

Proof sketch By induction on $N$.
Lemma 14 If $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ and $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ satisfies Invariant 11 , then so does $E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$.

If $E, \sigma$, defined $\left(M_{1}, \ldots, M_{m}\right) \wedge M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ and $E, \sigma$, defined $\left(M_{1}, \ldots\right.$, $\left.M_{m}\right) \wedge M, \mathcal{T}, \mu \mathcal{E} v$ satisfies Invariant 11 , then so does $E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$.

If $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ and $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ satisfies Invariant 11, then so does $E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$.

Moreover, if the rules that define $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ (respectively $E, \sigma$, defined $\left(M_{1}, \ldots, M_{m}\right) \wedge M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ or $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}$, $\left.\mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}\right)$ require as assumption $E^{\prime \prime}, \sigma^{\prime \prime}, M^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime} \xrightarrow{p}_{t} \ldots$ or $E^{\prime \prime}, \sigma^{\prime \prime}$, defined $\left(M_{1}^{\prime \prime}, \ldots\right.$, $\left.M_{m}^{\prime \prime}\right) \wedge M^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime} \xrightarrow{p}_{t} \ldots$, and the initial configuration $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v$ (resp. $E, \sigma$, defined $\left(M_{1}\right.$, $\left.\ldots, M_{m}\right) \wedge M, \mathcal{T}, \mu \mathcal{E} v$ or $\left.E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v\right)$ satisfies Invariant 11 , then so does the initial configuration of the assumption, $E^{\prime \prime}, \sigma^{\prime \prime}, M^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}$ or $E^{\prime \prime}, \sigma^{\prime \prime}$, defined $\left(M_{1}^{\prime \prime}, \ldots, M_{m}^{\prime \prime}\right) \wedge M^{\prime \prime}$, $\mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}$.

Proof sketch The proof proceeds by induction following the definition of $\xrightarrow{p}_{t}$. We just sketch the main arguments.

If $x\left[M_{1}, \ldots, M_{m}\right]$ is in the second case of Invariant 11 , and we execute the definition of $x\left[M_{1}, \ldots, M_{m}\right]$, then for all $j \leq m, M_{j}$ is a variable replication index and $x\left[\sigma\left(M_{1}\right), \ldots, \sigma\left(M_{m}\right)\right]$ is added to $\operatorname{Dom}(E)$ by rules (NewT), LetT, (FindT1), GetT1, New, (Let), (Find1), AttYield), AttIO), OracleCall), (Return) or (Get1) so it moves to the first case of Invariant 11.

If $x\left[M_{1}, \ldots, M_{m}\right]$ is in the third case of Invariant 11 , and we execute the corresponding find, this access to $x$ simply disappears.

If $x\left[M_{1}, \ldots, M_{m}\right]$ is in the fourth case of Invariant 11 , and we execute the find, then $x\left[M_{1}, \ldots\right.$, $\left.M_{m}\right]$ is a subterm of $M_{j k}^{\prime}$ for some $j \leq m^{\prime \prime}$ and $k \leq l_{j}$. Therefore, the initial configuration of the assumption $E, \sigma\left[\widetilde{i_{j}} \mapsto \widetilde{a}\right], D_{j} \wedge M_{j}^{\prime}, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{k_{k^{\prime}}}} E^{\prime \prime}, \sigma^{\prime}, r_{k^{\prime}}, \mathcal{T}, \mu \mathcal{E} v$ with $D_{j} \wedge M_{j}^{\prime}=\operatorname{defined}\left(M_{j 1}^{\prime}\right.$, $\left.\ldots, M_{j l_{j}}^{\prime}\right) \wedge M_{j}^{\prime}$ and $\sigma^{\prime}=\sigma\left[\widetilde{i_{j}} \mapsto \widetilde{a}\right]$ also satisfies Invariant 11 . In case this assumption is reduced by DefinedYes), we have $E, \sigma^{\prime}, M_{j k}^{\prime}, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{{ }^{*}} E, \sigma^{\prime}, a_{j k}, \mathcal{T}, \mu \mathcal{E} v$, that is, $E, \sigma^{\prime}, M_{j k}^{\prime} \Downarrow a_{j k}$. Therefore, by Lemma 12 , for all $j^{\prime} \leq m, E, \sigma^{\prime}, M_{j^{\prime}} \Downarrow a_{j^{\prime}}$ and $x\left[a_{1}, \ldots, a_{m}\right]$ is in $\operatorname{Dom}(E)$. So $x\left[M_{1}, \ldots, M_{m}\right]$ moves to the first case of Invariant 11 in $E, \sigma^{\prime}, M_{j}^{\prime}, \mathcal{T}, \mu \mathcal{E} v$ after reduction by (DefinedYes).

If $x\left[M_{1}, \ldots, M_{m}\right]$ is in the last case of Invariant 11, and we execute the find selecting branch $j$ by (FindT1) or (Find1), then there is a subterm $N$ of $M_{j k}^{\prime}$ for some $k \leq l_{j}$ such that $\left.N\left\{\widetilde{u_{j}} \widetilde{i}\right] / \widetilde{i_{j}}\right\}=$ $x\left[M_{1}, \ldots, M_{m}\right]$. By hypothesis of FindT1 or Find1, we have $E, \sigma\left[\widetilde{i_{j}} \mapsto \widetilde{a^{\prime}}\right], D_{j} \wedge M_{j}^{\prime}, \mathcal{T}$, $\mu \mathcal{E} v \xrightarrow{p_{k_{k^{\prime}}}}{ }^{*} E, \sigma^{\prime}, r_{k^{\prime}}, \mathcal{T}, \mu \mathcal{E} v$ where $r_{k^{\prime}}=\operatorname{true}, v_{0}=\left(j, \widetilde{a^{\prime}}\right) \in S, D_{j} \wedge M_{j}^{\prime}=\operatorname{defined}\left(M_{j 1}^{\prime}, \ldots\right.$, $\left.M_{j l_{j}}^{\prime}\right) \wedge M_{j}^{\prime}$, and $\sigma^{\prime}=\sigma\left[\widetilde{i_{j}} \mapsto \widetilde{a^{\prime}}\right]$. This assumption cannot reduce by DefinedNo because the result is true, so it reduces by DefinedYes. Therefore, we have $E, \sigma^{\prime}, M_{j k}^{\prime}, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{1}{ }^{*} E$, $\sigma^{\prime}, a, \mathcal{T}, \mu \mathcal{E} v$ for some $a$, that is, $E, \sigma^{\prime}, M_{j k}^{\prime} \Downarrow a$. The term $N=x\left[N_{1}, \ldots, N_{m}\right]$ is a subterm of $M_{j k}^{\prime}$. Therefore, by Lemma 12 , for all $j^{\prime} \leq m, E, \sigma^{\prime}, N_{j^{\prime}} \Downarrow a_{j^{\prime}}$ and $x\left[a_{1}, \ldots, a_{m}\right]$ is in
$\operatorname{Dom}(E)$. Moreover, the resulting environment $E^{\prime}$ is an extension of $E$, so a fortiori for all $j^{\prime} \leq m$, $E^{\prime}, \sigma^{\prime}, N_{j^{\prime}} \Downarrow a_{j^{\prime}}$ and $x\left[a_{1}, \ldots, a_{m}\right]$ is in $\operatorname{Dom}\left(E^{\prime}\right)$. We have for all $j^{\prime} \leq m, M_{j^{\prime}}=N_{j^{\prime}}\left\{\widetilde{u_{j}} \widetilde{(\widetilde{i}]} / \widetilde{i_{j}}\right\}$, $E^{\prime}\left(\widetilde{u_{j}} \widetilde{[i]}\right)=\widetilde{a^{\prime}}$, and $\sigma^{\prime}\left(\widetilde{i_{j}}\right)=\widetilde{a^{\prime}}$, so by Lemma 13 , for all $j^{\prime} \leq m, E^{\prime}, \sigma, M_{j^{\prime}} \Downarrow a_{j^{\prime}}$ and $x\left[a_{1}, \ldots, a_{m}\right]$ is in $\operatorname{Dom}\left(E^{\prime}\right)$. So $x\left[M_{1}, \ldots, M_{m}\right]$ also moves to the first case of Invariant 11.

In all other cases, the situation remains unchanged. For context rules, this is because, in the allowed contexts, the hole is never under a defined condition.

Therefore, if $Q_{0}$ satisfies Invariant 2, then in traces of $Q_{0}$, the test $x\left[a_{1}, \ldots, a_{m}\right] \in \operatorname{Dom}(E)$ in rule $(\mathrm{Var})$ always succeeds, except when the considered term occurs in a defined condition of a find.

Indeed, consider an application of rule $\sqrt{\operatorname{Var}}$, where the array access $x\left[M_{1}, \ldots, M_{m}\right]$ is not in a defined condition of a find. Then, this array access is not under any variable definition or find, so it is present in $\operatorname{Dom}(E)$ : for all $j \leq m, E, \sigma, M_{j} \Downarrow a_{j}$ and $x\left[a_{1}, \ldots, a_{m}\right] \in \operatorname{Dom}(E)$. Hence, the test $x\left[a_{1}, \ldots, a_{m}\right] \in \operatorname{Dom}(E)$ succeeds.

### 2.4.6 Typing

In this section, we show that our type system is compatible with the semantics of the oracles, that is, we define a notion of typing for semantic configurations and show that typing is preserved by reduction (subject reduction). Finally, the property that semantic configurations are well-typed shows that certain conditions in the semantics always hold.

We use the following definitions:

- $\mathcal{E} \vdash E$ if and only if $E\left(x\left[a_{1}, \ldots, a_{m}\right]\right)=a$ implies $\mathcal{E}(x)=T_{1} \times \ldots \times T_{m} \rightarrow T$ with for all $j \leq m, a_{j} \in T_{j}$ and $a \in T$.
- We define $\mathcal{E} \vdash P: T, \mathcal{E} \vdash Q$, and $\mathcal{E} \vdash M: T$ as in Section 2.3, with the additional rules $\mathcal{E} \vdash a: T$ if and only if $a \in T, \mathcal{E} \vdash$ event_abort $(\mu, \widetilde{a}): e: T$ for all $T$, and $\mathcal{E} \vdash$ abort : $T$ for all $T$. (These rules are useful to type evaluated terms and processes.)
- $\mathcal{E} \vdash(\sigma, P): T$ if and only if $\mathcal{E}\left[i_{1} \mapsto\left[1, n_{1}\right], \ldots, i_{m} \mapsto\left[1, n_{m}\right]\right] \vdash P: T$ and for all $j \leq m$, $\sigma\left(i_{j}\right) \in\left[1, n_{j}\right]$ for some $n_{1}, \ldots, n_{m}$, where $\operatorname{Dom}(\sigma)=\left[i_{1}, \ldots, i_{m}\right]$. The judgments $\mathcal{E} \vdash$ $(\sigma, M): T$ and $\mathcal{E} \vdash(\sigma, Q)$ are defined in the same way.
- $\mathcal{E} \vdash(\sigma, P): T \mapsto T^{\prime}$ if and only if $\mathcal{E} \vdash(\sigma, P): T^{\prime}$ and $P$ is of the form let $x[\widetilde{i}]: T=$ $O\left[M_{1}, \ldots, M_{l}\right](N)$ in $P_{1}$ else $P_{2}$.
- $\mathcal{E} \vdash \mathcal{T}$ if and only if $\operatorname{Tbl}\left(a_{1}, \ldots, a_{m}\right) \in \mathcal{T}$ implies $T b l: T_{1} \times \ldots \times T_{m}$ with for all $j \leq m$, $a_{j} \in T_{j}$.
- $\mathcal{E} \vdash \mu \mathcal{E} v$ if and only if $(\mu, \widetilde{a}): e\left(a_{1}, \ldots, a_{m}\right) \in \mu \mathcal{E} v$ implies $e: T_{1} \times \ldots \times T_{m}$ with for all $j \leq m, a_{j} \in T_{j}$.
- $\mathcal{E} \vdash E,\left(\sigma_{0}, P_{0}\right):: \ldots::\left(\sigma_{m}, P_{m}\right):: \mathcal{A}, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ if and only if $\mathcal{E} \vdash E,\left(\sigma_{0}, P_{0}\right): T_{0}$, for all $1 \leq i \leq m, \mathcal{E} \vdash\left(\sigma_{i}, P_{i}\right): T_{i-1} \mapsto T_{i}, \mathcal{E} \vdash \mathcal{T}, \mathcal{E} \vdash \mu \mathcal{E} v$, and for all $\left(\sigma^{\prime}, Q\right) \in \mathcal{Q}, \mathcal{E} \vdash\left(\sigma^{\prime}, Q\right)$.
- $\mathcal{E} \vdash \mathcal{Q}, \mathcal{O} r$ if and only if for all $\left(\sigma^{\prime}, Q\right) \in \mathcal{Q}, \mathcal{E} \vdash\left(\sigma^{\prime}, Q\right)$.
- $\mathcal{E} \vdash E, \sigma, M: T, \mathcal{T}, \mu \mathcal{E} v$ if and only if $\mathcal{E} \vdash E, \mathcal{E} \vdash(\sigma, M): T, \mathcal{E} \vdash \mathcal{T}$, and $\mathcal{E} \vdash \mu \mathcal{E} v$.

Lemma 15 If $\mathcal{E} \vdash E, \sigma, M: T, \mathcal{T}, \mu \mathcal{E} v$ and $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, then $\mathcal{E} \vdash$ $E^{\prime}, \sigma^{\prime}, M^{\prime}: T, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$.

So, $\mathcal{E} \vdash E, \sigma, M: T, \mathcal{T}, \mu \mathcal{E} v$ and $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t}^{*} E^{\prime}, \sigma^{\prime}, a, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, then $\mathcal{E} \vdash E^{\prime}, \sigma^{\prime}, a:$ $T, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$.

Proof sketch By induction on the derivation of $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$.
Lemma 16 If $\mathcal{E} \vdash \mathcal{Q}, \mathcal{O} r$ and $\mathcal{Q}, \mathcal{O} r \rightsquigarrow \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$, then $\mathcal{E} \vdash \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$.
So, if $\mathcal{E} \vdash \mathcal{Q}, \mathcal{O} r$, then $\mathcal{E} \vdash \operatorname{reduce}(\mathcal{Q}, \mathcal{O} r)$.
Proof sketch By cases on the derivation of $\mathcal{Q}, \mathcal{O} r \rightsquigarrow \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$. In the case of the replication, we have $\mathcal{E} \vdash(\sigma$, foreach $i \leq n$ do $Q)$, so $\mathcal{E}\left[i_{1} \mapsto\left[1, n_{1}\right], \ldots, i_{m} \mapsto\left[1, n_{m}\right]\right] \vdash$ foreach $i \leq n$ do $Q$ and for all $j \leq m, \sigma\left(i_{j}\right) \in\left[1, n_{j}\right]$ for some $n_{1}, \ldots, n_{m}$, where $\operatorname{Dom}(\sigma)=\left[i_{1}, \ldots, i_{m}\right]$. By TRepl), $\mathcal{E}\left[i_{1} \mapsto\left[1, n_{1}\right], \ldots, i_{m} \mapsto\left[1, n_{m}\right], i \mapsto[1, n]\right] \vdash Q$, so $\mathcal{E} \vdash(\sigma[i \mapsto a], Q)$ for $a \in[1, n]$.

Lemma 17 If $\mathcal{E} \vdash Q_{0}$, then $\mathcal{E} \vdash \operatorname{initConfig}\left(Q_{0}, \mathcal{A}\right)$.
Proof sketch By Lemma 16 and the previous definitions.
 $\mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, then $\mathcal{E} \vdash E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$.

Proof sketch By cases on the derivation of $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, using Lemmas 15 and 16 .

Moreover, if the rules that define $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$ (resp. $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r$, $\left.\mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \mathcal{S} t^{\prime}, \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}\right)$ require as assumption $E^{\prime \prime}, \sigma^{\prime \prime}, M^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime} \xrightarrow{p}_{\rightarrow} \ldots$ and the initial configuration is well-typed $\mathcal{E} \vdash E, \sigma, M: T, \mathcal{T}, \mu \mathcal{E} v$ (resp. $\mathcal{E} \vdash E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ ) then so is the initial configuration of the assumption, that is, there exists $T^{\prime \prime}$ such that $\mathcal{E} \vdash E^{\prime \prime}, \sigma^{\prime \prime}, M^{\prime \prime}$ : $T^{\prime \prime}, \mathcal{T}^{\prime \prime}, \mu \mathcal{E} v^{\prime \prime}$.

As an immediate consequence of Lemmas 17, 18, and 15 and the observation above, we obtain: if $Q_{0}$ satisfies Invariant 8 , then in traces of $Q_{0}$, the tests $a \in T$ in rules (LetT) and (Let) and $\forall j \leq m, a_{j} \in T_{j}$ in rule Fun always succeed. Moreover, in rules NewT and New, we always have that $T$ is fixed, bounded, or nonuniform. In rules (IfT1), IIfT2), (If1), and (If2), the condition is in bool $=\{$ false, true $\}$ (when it is a value, not an abort event value), so the condition $a \neq$ true is equivalent to $a=$ false. In the rules for find, we have $r_{k} \in\{$ false, true $\}$ when $r_{k}$ is a value (not an abort event value). In the rules InsertT, GetTE, GetT1, GetT2), (Insert), (GetE), (Get1), and (Get2), we have $a_{j} \in T_{j}$ for $j \leq l$, where $T b l: T_{1} \times \ldots \times T_{l}$. In the rules (EventT) and (Event), we have $a_{j} \in T_{j}$ for $j \leq l$, where $e: T_{1} \times \ldots \times T_{l}$. In the rule (Return), we have $d \in T$. Finally, in the rule (OracleCall), the set $S$ of available oracles is equal to the one where we would not filter over the type of the oracle argument $b$.

### 2.5 Subset for the Initial Game

The variables are always defined with the current replication indices $\widetilde{i}$, so we omit them, writing $x$ for $x \widetilde{[i}]$; they are implicitly added by CryptoVerif. When a variable is used with the current replication indices at its definition, we can also omit the indices.

Along similar lines, the oracles $O$ in oracle declarations are used without indices, and the current replication indices are implicitly added by CryptoVerif. The construct newOracle and the oracle calls cannot occur in games manipulated by CryptoVerif. They are used only inside proofs. The grammar of the resulting syntax is summarized in Figure 13.

We recommend using the constructs get and insert to manage key tables, instead of find or if with defined conditions. When no find nor if with defined conditions occurs in the game, by Invariant 2, all accesses to variable $x$ are of the form $x[\widetilde{i}]$ where $\widetilde{i}$ are the current replication

```
\(M, N::=\)
    i
    \(x\left[M_{1}, \ldots, M_{m}\right]\)
    \(f\left(M_{1}, \ldots, M_{m}\right)\)
    \(x \stackrel{R}{\leftarrow} T ; N\)
    let \(p=M\) in \(N\) else \(N^{\prime}\)
    let \(x: T=M\) in \(N\)
    if \(M\) then \(N\) else \(N^{\prime}\)
    find \([\) unique \(?]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}\) suchthat
        defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}^{\prime}\) then \(\left.N_{j}\right)\) else \(N^{\prime} \quad\) array lookup
    insert \(\operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; N\)
    get[unique?] \(\operatorname{Tbl}\left(p_{1}, \ldots, p_{l}\right)\) suchthat \(M\) in \(N\) else \(N^{\prime}\)
    event \(e\left(M_{1}, \ldots, M_{l}\right) ; N\)
    event_abort \(e\)
\(p::=\)
    \(x: T\)
    \(f\left(p_{1}, \ldots, p_{m}\right)\)
    \(=M\)
\(Q::=\)
    0
    \(Q \mid Q^{\prime}\)
    foreach \(i \leq n\) do \(Q\)
    \(O(p):=P\)
\(P::=\)
    oracle body
    return \((N) ; Q\)
    \(x \stackrel{R}{\leftarrow} T ; P\)
    let \(p=M\) in \(P\) else \(P^{\prime}\)
    if \(M\) then \(P\) else \(P^{\prime} \quad\) conditional
    find \([\) unique? \(\left.]\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i}\right]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}\) suchthat
        defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}\) then \(\left.P_{j}\right)\) else \(P\)
    array lookup
    insert \(\operatorname{Tbl}\left(M_{1}, \ldots, M_{l}\right) ; P\)
    get[unique?] \(\operatorname{Tbl}\left(p_{1}, \ldots, p_{l}\right)\) suchthat \(M\) in \(P\) else \(P^{\prime}\)
    event \(e\left(M_{1}, \ldots, M_{l}\right) ; P\)
    event_abort \(e \quad\) event \(e\) and abort
    yield end
oracle definition
    nil
    parallel composition
    replication \(n\) times
    oracle definition
    return
    assignment
    insert in table
    get from table
    event
```

Figure 13: Subset of the calculus for the initial game
indices at the definition of $x$. Such accesses are simply abbreviated as $x$. Variables can then be considered as ordinary variables instead of arrays, since we only access the array cell at the current replication indices. This choice has several other advantages:

- Tables with get/insert are closer to lists usually used by cryptographers than find, they should be easier to understand for the user.
- Our compiler that translates CryptoVerif specifications into OCaml implementations 32] does not support find, because tables with get/insert are also much easier to implement than find.

We can define processes by macros: let $\operatorname{pid}\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right)=P$ or let $\operatorname{qid}\left(x_{1}: T_{1}, \ldots\right.$, $\left.x_{m}: T_{m}\right)=Q$. If a process $\operatorname{pid}\left(M_{1}, \ldots, M_{m}\right)$ occurs in the initial game, CryptoVerif verifies that $M_{1}, \ldots, M_{m}$ are of types $T_{1}, \ldots, T_{m}$ respectively, and replaces $\operatorname{pid}\left(M_{1}, \ldots, M_{m}\right)$ with the expansion $P\left\{M_{1} / x_{1}, \ldots, M_{m} / x_{m}\right\}$.

We can also define functions by macros: letfun $f\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right)=M$. If a term $f\left(M_{1}\right.$, $\ldots, M_{m}$ ) occurs in the initial game, CryptoVerif verifies that $M_{1}, \ldots, M_{m}$ are of types $T_{1}, \ldots$, $T_{m}$ respectively, and replaces $f\left(M_{1}, \ldots, M_{m}\right)$ with the expansion $M\left\{M_{1} / x_{1}, \ldots, M_{m} / x_{m}\right\}$.

In the initial game, all bound variables with several incompatible definitions (different indices, different types, or variables defined in the same branch of a test) as well as variables declared without an explicit type are not allowed to occur in $V$ nor in defined conditions of find or if and are renamed to distinct names, so that Invariant 1 is satisfied for these variables. CryptoVerif checks the rest of the invariants.

### 2.6 Input Language with Channels instead of Oracles

CryptoVerif also allows defining games in a channel-based process calculus inspired by the applied pi calculus [1, 2] and by the calculi of [59] and of [55]. This input language is mostly compatible with the symbolic protocol verifier ProVerif (28 (http://proverif.inria.fr), up to the following differences:

- ProVerif does not support find. Since ProVerif supports tables, one can encode most usages of find using tables instead for compatibility with ProVerif.
- ProVerif does not support channels with indices. As mentioned below, in CryptoVerif, the channels are indexed with the current replication indices. Since CryptoVerif automatically adds the current replication indices to channels without indices, one can easily use channels without indices.

So avoiding find and channels with indices allows us to have a language compatible with ProVerif for the definition of processes. (The assumptions on cryptographic primitives still need to be defined in a different way. In practice, these assumptions can be included in a library, using different libraries for ProVerif and for CryptoVerif.)

### 2.6.1 Input Language Description

Instead of defining oracles that the adversary can interact with, processes are now considered as communicating over a network with explicit input and output commands. The adversary has full control over the network: it receives any value output by a process and it is in charge of sending the input values to the processes. Inputs and outputs are made over channels, a set of constants often denoted by $c$.

Concretely, the following changes are made to the syntax previously defined in Figure 1

- oracle definitions are called input processes and oracle bodies are called output processes;
- oracle declarations $O \widetilde{i}](p):=P$ do not exist anymore and are replaced with inputs $c \widetilde{i}](p) ; P$, where $\widetilde{i}$ are the current replication indices;
- return commands return $(N) ; Q$ are now output commands $\overline{c[\widetilde{i}]}\langle N\rangle ; Q$, where $\widetilde{i}$ are the current replication indices;
- the yield command is now considered as syntactic sugar for $\overline{y i e l d}\rangle$, where yield is a specific channel not used elsewhere;
- oracle calls and oracle restrictions do no exist anymore. (Oracle calls can be encoded via channel inputs and outputs. We could introduce a channel restriction to match the oracle restriction, but it would be useful only in proofs, not in the input calculus of CryptoVerif.)


### 2.6.2 Translating from the Channel Calculus to the Oracle Calculus

Processes specified in the channel calculus are directly translated to the oracle calculus; this feature is only a form of syntactic sugar available for convenience. Notably, we do not define a formal semantics for the channel calculus, and all up to date theoretical developments of CryptoVerif are over the oracle calculus. For reference, the old semantics of the channel calculus variant can be found here 29]. We describe informally the translation here, which proceeds as follows:

- Any input of the form $c \widetilde{i}](p) ; P$ is translated as an oracle definition $O_{c} \widetilde{[i]}(p):=P$ where the oracle name $O_{c}$ is built from the input channel $c$.
- Any output of the form $\overline{c[\tilde{[i]}}\langle N\rangle ; Q$ is translated as return $(N) ; Q$.

All input processes cannot be translated. We provide a list of invariants needed so that the translation preserves the semantics and produces valid instances of the oracle calculus. A first invariant is needed so that the translated process satisfies Invariant 7. We define the following multiset by induction over input and output processes, in a similar fashion to the previously defined Defined ${ }^{O}$ :

$$
\begin{aligned}
& \text { Defined }^{c}(0)=\emptyset \\
& \text { Defined }^{c}\left(Q_{1} \mid Q_{2}\right)=\text { Defined }^{c}\left(Q_{1}\right) \uplus \text { Defined }^{c}\left(Q_{2}\right) \\
& \text { Defined }^{c}(\text { foreach } i \leq n \text { do } Q)=\text { Defined }^{c}(Q) \\
& \text { Defined }^{c}(c \widetilde{[i]}(p) ; P)=\{c\} \uplus \text { Defined }^{c}(P) \\
& \text { Defined }^{c}\left(C\left[Q_{1}, \ldots, Q_{k}\right]\right)=\max _{j=1}^{k} \operatorname{Defined~}^{c}\left(Q_{j}\right)
\end{aligned}
$$

where $C$ is any oracle body context.
Channel Calculus Invariant 1 The input process $Q_{0}$ satisfies the Channel Invariant 1 if and only if

1. in every input and output over channel $c$ in $Q_{0}$, the indices $\widetilde{i}$ of $c$ are the current replication indices at that declaration, and
2. Defined ${ }^{c}\left(Q_{0}\right)$ does not contain duplicate elements.

In other words, Item 2 of Channel Invariant 1 means that inputs on the same channel occur in different branches of a find, if (or let), oracle call, or get.

A more complex issue is that in the channel calculus semantics, whenever an output can be received on the same channel by an input of the process, the output is probabilistically either caught by the attacker or directly transmitted to the input process. There is no equivalent to this probabilistic choice in the oracle setting. We thus add a channel invariant that makes it so that no output of the defined process can be received by the process itself. To this end, we define the following functions:

- $C h_{o}(Q)$ is the set of pairs $(c, k)$ of channels $c$ that occur with $k$ indices as output inside $Q$, that is, in a subprocess of the form $\overline{c \widetilde{[i]}}\langle N\rangle ; Q^{\prime}$ inside $Q$, where the length of $\widetilde{i}$ is $k$;
- $C h_{i}(Q)$ is the set of pairs $(c, k)$ of channels $c$ that occur with $k$ indices as input inside $Q$, that is, in a subprocess of the form $c \widetilde{i}](p) ; P$ inside $Q$, where the length of $\widetilde{i}$ is $k$;
- $\operatorname{NoIntIO}(Q)$ is true when no direct communication on a channel can occur inside $Q$, without going through the attacker:

$$
\begin{aligned}
& \text { NoIntIO }(0)=\text { true } \\
& \text { NoIntIO }\left(Q_{1} \mid Q_{2}\right)=\operatorname{NoIntIO}\left(Q_{1}\right) \wedge \operatorname{NoIntIO}\left(Q_{2}\right) \wedge \\
& \quad\left(\operatorname{Ch}_{i}\left(Q_{1}\right) \cap C h_{o}\left(Q_{2}\right)=\emptyset\right) \wedge\left(\operatorname{Ch}_{i}\left(Q_{2}\right) \cap C h_{o}\left(Q_{1}\right)=\emptyset\right) \\
& \text { NoIntIO }(\text { foreach } i \leq n \text { do } Q)=\operatorname{NoIntIO}(Q) \\
& \text { NoIntIO } \left.(c \widetilde{i}](p) ; C\left[Q_{1}, \ldots, Q_{k}\right]\right)=\bigwedge_{j=1}^{k} \operatorname{NoIntIO}\left(Q_{j}\right)
\end{aligned}
$$

where $C$ is any oracle body context.
Channel Calculus Invariant 2 The input process $Q_{0}$ satisfies the Channel Invariant 2 if and only if $\operatorname{NoIntIO}\left(Q_{0}\right)=$ true.

This invariant guarantees that dynamically, there will be no input available in the process on a channel when the process performs an output on that channel. This is obtained by statically requiring that, when there is an output on channel $c$, the inputs on channel $c$ with the same number of indices are syntactically above or under that output, or in a different branch, but not in a process in parallel.

When translating an output to a return, notice that the channel is dropped. The attacker might lose some distinguishing power if several outputs in distinct branches were made on distinct channels. We thus forbid this in the channel calculus.

Channel Calculus Invariant 3 The input process $Q_{0}$ satisfies the Channel Invariant 3 if and only if for all inputs on a given channel, all outputs directly below these inputs are over the same channel.

Most other previously defined invariants must also hold and can be seen as independent from oracles or channels.

Channel Calculus Invariant 4 The input process $Q_{0}$ satisfies the Channel Invariant 4 if only if it satisfies the Invariants 1 (with the minor modification that there are no oracle calls), 2,3 4.5 and 6

We do not explicitly state the typing Channel Invariant, which would correspond to Invariant 8. The old typing invariant for the channel calculus can be found in 29. However, the translation to oracles strengthens this invariant: informally, inputs on the same channel must receive messages of same type (since they translate to oracle definitions of the same oracle) and outputs that follow inputs on the same channel must send messages of the same type (since they translate into returns of the same oracle).

### 2.7 Subsets used inside the Sequence of Games

During the computation of the sequence of games, several properties are used by CryptoVerif, either required by some game transformations or guaranteed by others. We summarize them in this section.

Property 1 No function returns values of interval types. The types of values chosen by $x \widetilde{i}] \stackrel{R}{\leftarrow} T$ are not interval types. The type $T$ of the returned message in the TRet rule and of the receiving pattern in the TODecl rule are not interval types.

This property is satisfied by all games manipulated by CryptoVerif, but not by contexts that model parts of the adversary. Combined with Invariants 8, 2, and 5, it implies that the terms of variable accesses $x\left[M_{1}, \ldots, M_{m}\right]$ contain only replication indices and variables. (Tuples, events, and tables can take interval types as arguments. The constraint on oracle declarations and returns could probably be relaxed.)

For oracles that model security assumptions on primitives, the receiving variable can be of an interval type. (This is used for instance to specify the computational Diffie-Hellman assumption; see Section 5.2.)

Property 2 The construct newOracle $O$ and the oracle calls do not appear in games.
These properties are also satisfied by all games manipulated by CryptoVerif, but not by processes that model the adversary.

Property 3 The constructs insert and get do not occur in the game.
This property is not valid in the initial game, but it is in all other games of the sequence produced by CryptoVerif. The very first game transformation applied by CryptoVerif, expand_tables, encodes insert and get using find (see Section 5.1.2). The constructs insert and get are never introduced by subsequent game transformations, so this property remains valid in the rest of the sequence.

Property 4 The variables defined in conditions of find have pairwise distinct names.
This property is enforced by the transformation auto_SArename (see Section 5.1.2) by renaming variables defined in conditions of find to distinct names. (This is easy since these variables do not have array accesses by Invariant 3) Property 4 is required as a precondition by many game transformations, and may be broken by game transformations that duplicate code. Therefore, we apply auto_SArename after these game transformations.

Property 5 The terms $M$ are simple except for conditions of find.

```
\(M, N::=\)
    \(i\)
    \(x\left[M_{1}, \ldots, M_{m}\right]\)
    \(f\left(M_{1}, \ldots, M_{m}\right)\)
\(F C:=\quad\) find condition
    M
    \(x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; F C\)
    let \(p=M\) in \(F C\) else \(F C^{\prime}\)
    let \(x \widetilde{\sim}]: T=M\) in \(N\)
    if \(M\) then \(F C\) else \(F C^{\prime}\)
    find \([\) unique? \(]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i]}=i_{j m_{j}} \leq n_{j m_{j}}\right.\) suchthat
        defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge F C_{j}^{\prime}\) then \(\left.F C_{j}\right)\) else \(F C^{\prime \prime} \quad\) array lookup
    event_abort \(e\)
        terms
    replication index
    variable access
    function application
    term
    random number
    assignment (pattern-matching)
    assignment
    conditional
    event \(e\) and abort
\(p::=\)
    pattern
    \(x[\widetilde{i}]: T\)
    variable
    \(f\left(p_{1}, \ldots, p_{m}\right)\)
    function application
    \(=M \quad\) comparison with a term
\(Q::=\quad\) oracle definition
    0
    \(Q \mid Q^{\prime}\)
    parallel composition
    foreach \(i \leq n\) do \(Q \quad\) replication \(n\) times
    \(O \widetilde{[i]}(p):=P\)
    oracle declaration
\(P::=\quad\) oracle body
    return \((N) ; Q\)
    \(x \widetilde{[i]} \stackrel{R}{\leftarrow} T ; P \quad\) random number
    let \(p=M\) in \(P\) else \(P^{\prime}\)
    assignment
    if \(M\) then \(P\) else \(P^{\prime}\)
    if \(M\) then \(P\) else \(P^{\prime}\)
find \([u n i q u e\) ? \(]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i}\right]=i_{j m_{j}} \leq n_{j m_{j}}\) suchthat
        defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge F C_{j}\) then \(\left.P_{j}\right)\) else \(P \quad\) array lookup
    event \(e\left(M_{1}, \ldots, M_{l}\right) ; P\) event
    event_abort \(e \quad\) event \(e\) and abort
    yield
    end
```

Figure 14: Subset after game expansion

The grammar of the language taking into account this property as well as Properties 2 and 3 is shown in Figure 14. By Invariant 4, event does not occur in conditions of find, so event never occurs as term. Property 5 is enforced by the transformation expand (see Section 5.1.3) by converting other terms into processes. This transformation is applied on the initial game after expand_tables. Property 5 is broken by the cryptographic transformation of Section 5.2 so by default expand is called again after this transformation. Many game transformations require Property 5 as a precondition.

### 2.8 Security Properties, Indistinguishability

A context is a process containing a hole []. An evaluation context $C$ is a context built from [], newOracle $O ; C, Q \mid C$, and $C \mid Q$.

We use an evaluation context to represent an adversary in addition to the attacker $\mathcal{A}$. Adversarial contexts are useful, e.g., to push code inside the adversary in reduction proofs, but are also needed so that the attacker $\mathcal{A}$ can raise events, access the public variables in $V$, and return its final result to a distinguisher by raising an event with that result as argument, by calling oracles of the context that execute these actions. We denote by $C[Q]$ the oracle definition obtained by replacing the hole [] in the context $C$ with the oracle definition $Q$.

We write event $(D)$ for the set of events that occur in the distinguisher $D$ (i.e. are used by the distinguisher $D$ ). We write $\operatorname{event}(Q)$ for the set of events that occur in the process $Q$. We use similar notations for oracle bodies, contexts, $\ldots$ We write $\operatorname{event}\left(Q, Q^{\prime}\right)$ for $\operatorname{event}(Q) \cup \operatorname{event}\left(Q^{\prime}\right)$.

From now on, we consider in this section a fixed attacker space $\mathcal{B B}$, and all security definitions are given for this $\mathcal{B B}$. There must exist a function allowing to extract a run-time from the execution of an attacker. Classically, $\mathcal{B B}$ would be the set of interactive probabilistic Turing machines, but the theory of CryptoVerif is sound for any kind of black-box interactive attacker, where the computational power is restricted by the cryptographic axioms. As cryptographic reductions sound for a black-box interactive attacker are also sound for quantum Turing Machines, this notably implies the post-quantum soundness of CryptoVerif, by considering as $\mathcal{B B}$ the set of interactive quantum Turing machines.

Definition 5 (Indistinguishability) Let $Q$ and $Q^{\prime}$ be two processes, $V$ a set of variables, and $\mathcal{E}$ a set of events. Assume that $Q$ and $Q^{\prime}$ satisfy Invariants 1 to 8 with public variables $V$, and the variables of $V$ are defined in $Q$ and $Q^{\prime}$, with the same types.

An evaluation context $C$ is said to be acceptable for $Q$ with public variables $V$ if and only if $\operatorname{var}(C) \cap \operatorname{var}(Q) \subseteq V, \operatorname{vardef}(C) \cap V=\emptyset, C$ and $Q$ do not use any common table, and $C[Q]$ satisfies Invariants 1 to 8 with public variables $V$.

We write $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$ when, for all attackers $\mathcal{A} \in \mathcal{B B}$, for all evaluation contexts $C$ acceptable for $Q$ and $Q^{\prime}$ with public variables $V$ and all distinguishers $D$ that run in time at most $t_{D}$ and such that $\operatorname{event}(D) \cap \operatorname{event}\left(Q, Q^{\prime}\right) \subseteq \mathcal{E},\left|\operatorname{Pr}^{\mathcal{A}}[C[Q]: D]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: D\right]\right| \leq p\left(\mathcal{A}, C, t_{D}\right)$.

This definition formalizes that the probability that algorithms $\mathcal{A}, C$, and $D$ distinguish the games $Q$ and $Q^{\prime}$ is at most $p\left(\mathcal{A}, C, t_{D}\right)$. The probability $p$ typically depends on the runtime of $\mathcal{A}, C$, and $D$, but may also depend on other parameters, such as the number of queries to each oracle made by $C$ or $\mathcal{A}$. That is why $p$ takes as arguments the whole algorithms $\mathcal{A}, C$ and the runtime of $D$. More specifically:

Property 6 All probabilities computed by CryptoVerif are built from the following components by mathematical operations:

- the runtime of the context plus the attacker;
- the maximum number of oracle calls made by the context or the attacker;
- the value of replication bounds, which is also determined from the number of calls performed by the context or attacker;
- the maximum length of the bitstring represented by a term, in particular a variable; this length may depend on messages computed by the context or the attacker; it is used only for unbounded types; for bounded types, we use the maximum length of the type instead;
- the maximum length of bitstring of a type $T$;
- the length of the result of a function, expressed as a function of the length of its arguments;
- the time of some action, expressed as a function of other elements of the formula;
- probability functions, used in particular to express the probability of breaking each primitive from other elements of the formula;
- the cardinal $|T|$ of a type $T$;
- the probability of collision between two random values of a type $T$, or between a random value and a value independent from that random value; these probabilities depend on the default distribution on the type $D_{T}$;
- $\epsilon_{T}$, the distance between the default distribution $D_{T}$ of type $T$ and the uniform distribution;
- $\epsilon_{\text {find }}$, where the distance between $D_{\text {find }}(S)$ and the uniform distribution is $\epsilon_{\text {find }} / 2$.

Among the elements above, the first four depend on the context and the attacker. In particular, probability formulas output by CryptoVerif do not depend on the variable, table, event names in the context. They also do not depend on the values of variables, but may depend on their length. For variables of bounded types, the probabilities do not depend at all on the values. We do not in practice distinguish between the calls of the context or the attacker.

The set of events $\mathcal{E}$ corresponds to events that the adversary is allowed to observe. When $\mathcal{E}=\operatorname{event}\left(Q, Q^{\prime}\right)$, we omit it and write $Q \approx_{p}^{V} Q^{\prime}$.

The unusual requirement on variables of $C$ comes from the presence of arrays and of the associated find construct which gives $C$ direct access to variables of $Q$ and $Q^{\prime}$ : the context $C$ is allowed to access variables of $Q$ and $Q^{\prime}$ only when they are in the finite set of public variables $V$. (In more standard settings, the calculus does not have constructs that allow the context to access variables of $Q$ and $Q^{\prime}$.) When $V$ is empty, we omit it and write $Q \approx_{p}^{\mathcal{E}} Q^{\prime}$.

When $C$ is acceptable for $Q$ with public variables $V$, and we transform $Q$ into $Q^{\prime}$, we can rename the fresh variables of $Q^{\prime}$ (introduced by the game transformation) so that they do not occur in $C$. Then $C$ is also acceptable for $Q^{\prime}$ with public variables $V$. (To establish this property, we use that the variables of $V$ are defined in $Q$ and $Q^{\prime}$, with the same types, so that, if $C[Q]$ is well-typed, then so is $C\left[Q^{\prime}\right]$.)

When $C$ is acceptable for $Q$ with public variables $V$, we have that $\operatorname{vardef}(C) \cap \operatorname{var}(Q)=\emptyset$, because vardef $(C) \cap \operatorname{var}(Q)=\operatorname{vardef}(C) \cap \operatorname{var}(C) \cap \operatorname{var}(Q) \subseteq \operatorname{vardef}(C) \cap V=\emptyset$.

The following lemma is a straightforward consequence of Definition 5
Lemma 19 1. Reflexivity: $Q \approx_{0}^{V, \mathcal{E}} Q$.
2. Symmetry: If $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$, then $Q^{\prime} \approx_{p}^{V, \mathcal{E}} Q$.
3. Transitivity: If $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$ and $Q^{\prime} \approx_{p^{\prime}}^{V, \mathcal{E}} Q^{\prime \prime}$, then $Q \approx_{p+p^{\prime}}^{V, \mathcal{E}} Q^{\prime \prime}$.
4. Application of a context: If $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$ and $C$ is an evaluation context acceptable for $Q$ and $Q^{\prime}$ with public variables $V$, then $C[Q] \approx_{p^{\prime}}^{V^{\prime} \mathcal{E}^{\prime}} C\left[Q^{\prime}\right]$, where $p^{\prime}\left(\mathcal{A}, C^{\prime}, t_{D}\right)=p\left(\mathcal{A}, C^{\prime}[C[]]\right)$, $V^{\prime} \subseteq V \cup \operatorname{var}(C)$, and $\mathcal{E}^{\prime}=\mathcal{E} \cup\left(\operatorname{event}(C) \backslash \operatorname{event}\left(Q, Q^{\prime}\right)\right)$.

Next, we introduce a notion related to indistinguishability that treats Shoup and non-unique events specially.

Definition 6 (Property preservation with introduction of events) Let $Q$ and $Q^{\prime}$ be two processes and $V$ a set of variables. Assume that $Q$ and $Q^{\prime}$ satisfy Invariants 1 to 8 with public variables $V$, and the variables of $V$ are defined in $Q$ and $Q^{\prime}$, with the same types.

Let $D_{\text {false }}(\mathcal{E} v)=$ false for all $\mathcal{E} v$. Let NonUnique $_{Q}=\bigvee\left\{e \mid\right.$ [unique $e_{e}$ ] occurs in $\left.Q\right\}$ and NonUnique $_{Q, D}=\bigvee\left\{e \mid\right.$ [unique $\left._{e}\right]$ occurs in $\left.Q, e \notin D\right\}$, where $D$ is a distinguisher consisting of a disjunction of Shoup and non-unique events, and we write $e \notin D$ to say that $e$ does not occur in this disjunction. We have NonUnique ${ }_{Q, D}=$ NonUnique $_{Q} \wedge \neg D$.

We write $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D, E v U s e d \xrightarrow{V}{ }_{p} Q^{\prime}, D^{\prime}, E v U s e d^{\prime}$ when $\mathcal{D}$ is a set of distinguishers, $\mathcal{D}_{\text {SNU }}$ is a set of Shoup and non-unique events in EvUsed, $D$ and $D^{\prime}$ are distinguishers consisting of a disjunction of Shoup and non-unique events, the events that occur in $Q$ or in $D$ are in EvUsed, EvUsed $\subseteq E v U s e d^{\prime}$, the events that occur in $Q^{\prime}$ but not in $Q$ are in EvUsed ${ }^{\prime}$ but not in EvUsed, the events that occur in $D^{\prime}$ but not in $D$ are in EvUsed ${ }^{\prime}$ but not in EvUsed, and, for all $\mathcal{A} \in \mathcal{B B}$, for all evaluation contexts $C$ acceptable for $Q$ and $Q^{\prime}$ with public variables $V$ that do not contain events in EvUsed', all distinguishers $D_{0} \in \mathcal{D} \cup\left\{D_{\text {false }}\right\}$ that run in time at most $t_{D_{0}}$, all distinguishers $D_{1}$ that are disjunctions of events in $\mathcal{D}_{\mathrm{SNU}}$,

$$
\begin{align*}
& \operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(D_{0} \vee D_{1} \vee D\right) \wedge \neg \text { NonUnique }_{Q, D_{1} \vee D}\right]  \tag{1}\\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]:\left(D_{0} \vee D_{1} \vee D^{\prime}\right) \wedge \neg \text { NonUnique }_{Q^{\prime}, D_{1} \vee D^{\prime}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{align*}
$$

Intuitively, the events EvUsed are those used by CryptoVerif in the sequence of games until the game $Q$ included, while the events EvUsed ${ }^{\prime}$ are those used until $Q^{\prime}$. Hence, EvUsed contains the events that occur in $Q ; E v U s e d^{\prime}$ contains EvUsed and the events that occur in $Q^{\prime}$. The formula $D_{0} \in \mathcal{D} \cup\left\{D_{\text {false }}\right\}$ corresponds to the initial query to prove: it is

- a correspondence distinguisher $\neg \varphi$ for a correspondence property (see Section 2.8.3;
- $S$ or $\neg \overline{\mathrm{S}}$ for (one-session) secrecy (see Section 2.8.1) and bit secrecy (see Section 2.8.2;
- any distinguisher for indistinguishability;
- $D_{\text {false }}$ when the initial query has already been proved, and only Shoup and non-unique events remain to be proved.

We need to specify precisely the distinguishers needed for the queries we want to prove, because some game transformations of CryptoVerif rely on that. For instance, simplify (Section 5.1.21) removes events that are not used by the queries.

The formula $D_{1}$ is a disjunction of Shoup and non-unique events that remain to be proved, both in $Q$ and in $Q^{\prime}$. These events are in $\mathcal{D}_{\text {SNU }}$ and in EvUsed. The formula $D$ is a disjunction of Shoup and non-unique events that remain to be proved in $Q$, while the formula $D^{\prime}$ is a disjunction of Shoup and non-unique events that remain to be proved in $Q^{\prime}$. Hence, the events that occur in $D$ and not in $D^{\prime}$ are events proved while transforming $Q$ into $Q^{\prime}$. ("Proving" an event means proving that this event has a negligible probability of occurring, and adding that probability to p.) In contrast, the events that occur in $D^{\prime}$ and not in $D$ are fresh Shoup and non-unique events introduced during the transformation of $Q$ into $Q^{\prime}$, and that will need to be proved later; hence
these events are in EvUsed ${ }^{\prime}$ but not in EvUsed. More generally, all events that occur in $Q^{\prime}$ but not in $Q$ are fresh events introduced in the transformation of $Q$ into $Q^{\prime}$, so they are in EvUsed ${ }^{\prime}$ but not in EvUsed.

When there are no Shoup nor non-unique events, we have $D_{1}=D=D^{\prime}=D_{\text {false }}$ and NonUnique $_{Q, D_{1} \vee D}=$ NonUnique $_{Q^{\prime}, D_{1} \vee D^{\prime}}=D_{\text {false }}$, so the inequality (1) reduces to

$$
\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{0}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: D_{0}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

Using $\neg D_{0}$ instead of $D_{0}$, we obtain

$$
1-\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{0}\right] \leq 1-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: D_{0}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

so by combining the two, $\left|\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{0}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: D_{0}\right]\right| \leq p\left(\mathcal{A}, C, t_{D_{0}}\right)$ as in the definition of indistinguishability. In the general case, the inequality (1) differs from this formula because (1) always counts the traces that execute Shoup and non-unique events that remain to be proved (these traces are always included in the probability by $D_{1} \vee D$, resp. $D_{1} \vee D^{\prime}$; the probability of these events needs to be bounded), and never counts the traces that execute proved nonunique events (these traces are excluded by $\neg$ NonUnique $_{Q, D_{1} \vee D}$, resp. $\neg$ NonUnique $_{Q^{\prime}, D_{1} \vee D^{\prime}}$; the probability of these events has already been bounded). We could also exclude traces that execute proved Shoup events, though it is less essential: Shoup events often simply disappear when they are proved, while non-unique events remain in the game. Excluding traces that execute proved non-unique events allows us to exploit that the corresponding find or get is unique in the transformation from $Q$ to $Q^{\prime}$ : intuitively, the traces in which the find or get is not unique are not counted, so they can be ignored. (Obviously, this point needs to be proved more precisely for each game transformation.)

We need to introduce a distinct event for each [unique $e_{e}$ ] because not all find[unique ${ }_{e}$ ] and get[unique ${ }_{e}$ ] may be proved unique in the current process and because we need to distinguish the non-unique events that occur in $Q$ from those that occur in the context $C$. (We note that the attacker $\mathcal{A}$ cannot raise events itself.) However, once a [unique ${ }_{e}$ ] is proved, its name does not matter: all such events are counted in NonUnique ${ }_{Q, D_{1} \vee D}$, and that remains true in future game transformations, since events are never re-added to $D_{1}$ or $D$. Therefore, we can rename all such events to the same name. So we simply abbreviate [unique ${ }_{e}$ ] by [unique] when event $e$ is proved. The context $C$ must not contain the events used in $Q$ or $Q^{\prime}$ and more generally events in EvUsed ${ }^{\prime}$.

The formula (1) could also be written

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(D_{0} \wedge \neg \text { NonUnique }_{Q}\right) \vee D_{1} \vee D\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]:\left(D_{0} \wedge \neg \text { NonUnique }_{Q^{\prime}}\right) \vee D_{1} \vee D^{\prime}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

since NonUnique ${ }_{Q, D_{1} \vee D}=$ NonUnique $_{Q} \wedge \neg\left(D_{1} \vee D\right)$. The advantage of the latter formulation is that the dependency in $D_{1}, D, D^{\prime}$ is simpler, which we sometimes exploit in the proofs. However, its drawback is that it is less clear for which events the traces are always counted and for which ones they are never counted, because some events appear both in NonUnique ${ }_{Q}$ and in $D_{1} \vee D$. That is why we chose formula (1), to make it clear that the traces that execute events in $D_{1} \vee D$ are always counted and the traces that execute events in NonUnique ${ }_{Q, D_{1} \vee D}$ are never counted.

When $f$ is a function from sequences of events to sequences of events and $D$ is a distinguisher, we define the distinguisher $D \circ f$ by $(D \circ f)(\mathcal{E} v)=D(f(\mathcal{E} v))$. In particular, when $\sigma$ is a renaming of events, the distinguisher $D \circ \sigma^{-1}$ is defined by $\left(D \circ \sigma^{-1}\right)(\mathcal{E} v)=D\left(\sigma^{-1} \mathcal{E} v\right)$. When $D$ is defined as a logical formula, that corresponds to renaming the events in $D$. For instance, if $D=e_{1} \vee \ldots \vee e_{m}$, then $D \circ \sigma^{-1}=\sigma e_{1} \vee \ldots \vee \sigma e_{m}$. When $\mathcal{D}$ is a set of distinguishers, $\sigma \mathcal{D}=\left\{D \circ \sigma^{-1} \mid D \in \mathcal{D}\right\}$.

We write $\mathcal{D}_{\neg \mathcal{E}}$ for the set of distinguishers that do not use events in $\mathcal{E}$.

Lemma 20 1. Link with indistinguishability:
(a) Suppose that $\mathcal{D}_{\mathrm{SNU}}$ is a set of Shoup events, $D$ is a distinguisher consisting of a disjunction of Shoup events, $Q, Q^{\prime}$ do not contain non-unique events, the events that occur in $Q, D, \mathcal{D}$, or $\mathcal{D}_{\mathrm{SNU}}$ are in EvUsed, and the events that occur in $Q^{\prime}$ also occur in $Q$. If $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}_{p} Q^{\prime}, D$, EvUsed, for all $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}, D$ such that $\operatorname{event}(\mathcal{D}) \cap E v U$ sed $\subseteq \mathcal{E}, \mathcal{D}_{\text {SNU }} \subseteq \mathcal{E}, \operatorname{event}(D) \subseteq \mathcal{E}$.
(b) Suppose that $Q$ and $Q^{\prime}$ do not contain non-unique events, the events that occur in $Q$ are in EvUsed, and the events that occur in $Q^{\prime}$ also occur in $Q$. Then $\mathcal{D}_{\neg(E v U s e d \backslash \mathcal{E})}, \emptyset$ : $Q, D_{\text {false }}$, EvUsed $\xrightarrow{V}{ }_{p}^{\prime}, D_{\text {false }}$, EvUsed if and only if $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$.
2. Reflexivity: If $\mathcal{D}_{\mathrm{SNU}}$ is a set of Shoup and non-unique events in EvUsed, $D$ is a distinguisher consisting of a disjunction of Shoup and non-unique events, and the events that occur in $Q$ or in $D$ are in EvUsed, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}: Q, D, E v U s e d ~{ }_{\rightarrow} Q, D$, EvUsed.
3. Transitivity: If $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}_{p} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$ and $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$ $\xrightarrow[p^{\prime}]{ } Q^{\prime \prime}, D^{\prime \prime}$, EvUsed ${ }^{\prime \prime}$, then we have $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow[p^{\prime \prime}]{ } Q^{\prime \prime}, D^{\prime \prime}$, EvUsed $^{\prime \prime}$, where $p^{\prime \prime}\left(\mathcal{A}, C, t_{D_{0}}\right)=p\left(\mathcal{A}, C, t_{D_{0}}\right)+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right)$.
4. Application of a context: If $\mathcal{D}_{\neg \text { EvUsed }}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}{ }_{p} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$, $\sigma$ is a renaming of the events in EvUsed ${ }^{\prime}$ to events not in EvUsed ${ }^{+}, C$ is a context acceptable for $\sigma Q$ and $\sigma Q^{\prime}$ with public variables $V$ such that $\operatorname{event}(C) \subseteq E v U s e d^{+}$, and $\mathcal{D}_{\text {SNU }}^{\prime}$ is a set of Shoup and non-unique events in EvUsed ${ }^{+}$, then we have $\mathcal{D}_{\neg \sigma E v U s e d^{\prime}}, \sigma \mathcal{D}_{\mathrm{SNU}} \cup \mathcal{D}_{\mathrm{SNU}}^{\prime}$ : $C[\sigma Q], D \circ \sigma^{-1}, \sigma E v U s e d \cup E v U s e d^{+}{\xrightarrow{V^{\prime}}}_{p^{\prime}} C\left[\sigma Q^{\prime}\right], D^{\prime} \circ \sigma^{-1}, \sigma E v U s e d^{\prime} \cup E v U s e d^{+}$, where $p^{\prime}\left(\mathcal{A}, C^{\prime}, t_{D_{0}}\right)=p\left(\mathcal{A}, \sigma^{-1}\left(C^{\prime}[C[]]\right), t_{D_{0}}\right)$, and $V^{\prime} \subseteq V \cup \operatorname{var}(C)$.
5. Adding distinguishers: If $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}{ }_{p} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$ and $e \in \mathcal{D}_{\mathrm{SNU}}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D \vee e$, EvUsed $\xrightarrow{V}_{p} Q^{\prime}, D^{\prime} \vee e$, EvUsed ${ }^{\prime}$.
6. Removing distinguishers: If $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{{ }^{V}}{ }_{p} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}, \mathcal{D}^{\prime} \subseteq \mathcal{D}$, and $\mathcal{D}_{\mathrm{SNU}}^{\prime} \subseteq \mathcal{D}_{\mathrm{SNU}}$, then $\mathcal{D}^{\prime}, \mathcal{D}_{\mathrm{SNU}}^{\prime}: Q, D$, EvUsed $\xrightarrow{V}{ }^{\prime} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$

Proof Property 1 a Given the hypothesis, $\mathcal{D}, \mathcal{D}_{\text {SNU }}: Q, D$, EvUsed $\xrightarrow{V}{ }_{p} Q^{\prime}, D$, EvUsed reduces to: for all attackers $\mathcal{A} \in \mathcal{B B}$, for all evaluation contexts $C$ acceptable for $Q$ and $Q^{\prime}$ with public variables $V$ that do not contain events in EvUsed, all distinguishers $D_{0} \in \mathcal{D} \cup\left\{D_{\text {false }}\right\}$ that run in time at most $t_{D_{0}}$, and all distinguishers $D_{1}$ that are disjunctions of events in $\mathcal{D}_{\text {SNU }}$,

$$
\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{0} \vee D_{1} \vee D\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: D_{0} \vee D_{1} \vee D\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

We have event $\left(D_{0} \vee D_{1} \vee D\right) \cap \operatorname{event}\left(Q, Q^{\prime}\right) \subseteq \operatorname{event}\left(D_{0} \vee D_{1} \vee D\right) \cap E v U s e d \subseteq \mathcal{E}$. Moreover, $D_{0} \vee D_{1} \vee D$ can be implemented in the same time as $D_{0}$ since evaluating $D_{0} \vee D_{1} \vee D$ can be done by setting the final result to true as soon as an event in $D_{1} \vee D$ is executed, and evaluating $D_{0}$ otherwise. This does not take more time than evaluating $D_{0}$. So this inequality is a consequence of $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$.

Property 1 b . Given the hypothesis, $\mathcal{D}_{\neg(\text { EvUsed } \backslash \mathcal{E})}, \emptyset: Q, D_{\text {false }}$, EvUsed ${ }^{V}{ }_{p} Q^{\prime}, D_{\text {false }}$, EvUsed reduces to: for all attackers $\mathcal{A} \in \mathcal{B B}$, for all evaluation contexts $C$ acceptable for $Q$ and $Q^{\prime}$ with public variables $V$ that do not contain events in EvUsed, and all distinguishers $D_{0} \in \mathcal{D}_{\neg(\text { EvUsed } \backslash \mathcal{E})}$ that run in time at most $t_{D_{0}}$,

$$
\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{0}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: D_{0}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

that is,

$$
\begin{equation*}
\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{0}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: D_{0}\right] \leq p\left(\mathcal{A}, C, t_{D_{0}}\right) \tag{2}
\end{equation*}
$$

We have event $\left(D_{0}\right) \cap \operatorname{event}\left(Q, Q^{\prime}\right) \subseteq \operatorname{event}\left(D_{0}\right) \cap$ EvUsed $\subseteq \mathcal{E}$. Therefore, $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$ implies $\mathcal{D}_{\neg(\text { EvUsed } \backslash \mathcal{E})}, \emptyset: Q, D_{\text {false }}$, EvUsed $\xrightarrow{V}_{p} Q^{\prime}, D_{\text {false }}$, EvUsed.

Conversely, assume $\mathcal{D}_{\neg(\text { EvUsed } \backslash \mathcal{E})}, \emptyset: Q, D_{\text {false }}, E v U s e d \xrightarrow{V}{ }_{p} Q^{\prime}, D_{\text {false }}$, EvUsed. Let $\mathcal{A} \in \mathcal{B B}$ be an attacker, Let $C$ be an evaluation context $C$ acceptable for $Q$ and $Q^{\prime}$ with public variables $V$ and $D$ be a distinguisher such that event $(D) \cap \operatorname{event}\left(Q, Q^{\prime}\right) \subseteq \mathcal{E}$. Let $\sigma$ be a renaming of events in EvUsed to fresh events. Then $\sigma C$ does not contain events in EvUsed. Given a sequence of events $\mathcal{E} v$, let $f(\mathcal{E} v)$ be obtained by removing all events in $E v U s e d \backslash \mathcal{E}$ from $\mathcal{E} v$ and, in the remaining sequence, renaming the events $e$ in $\sigma E v U s e d$ to $\sigma^{-1}(e)$. Let $D_{0}=D \circ f$. By construction, $D_{0} \in \mathcal{D}_{\neg(\text { EvUsed } \backslash \mathcal{E})}$. So by (2), we get

$$
\operatorname{Pr}^{\mathcal{A}}\left[(\sigma C)[Q]: D_{0}\right]-\operatorname{Pr}^{\mathcal{A}}\left[(\sigma C)\left[Q^{\prime}\right]: D_{0}\right] \leq p\left(\mathcal{A}, C, t_{D_{0}}\right) .
$$

Since $\neg D_{0} \in \mathcal{D}_{\neg(\text { EvUsed } \backslash \mathcal{E})}$ and runs in the same time as $D_{0}$,

$$
1-\operatorname{Pr}^{\mathcal{A}}\left[(\sigma C)[Q]: D_{0}\right]-1+\operatorname{Pr}^{\mathcal{A}}\left[(\sigma C)\left[Q^{\prime}\right]: D_{0}\right] \leq p\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

so

$$
\mid \operatorname{Pr}^{\mathcal{A}}\left[(\sigma C)[Q]: D_{0}\right]-\operatorname{Pr}^{\mathcal{A}}\left[(\sigma C)\left[Q^{\prime}\right]: D_{0} \mid\right] \leq p\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

Furthermore, each trace of $(\sigma C)[Q]$ with sequence of events $\mathcal{E} v$ corresponds to a trace of $C[Q]$ with the same probability and a sequence of events $\mathcal{E} v^{\prime}$ equal to $f(\mathcal{E} v)$ plus some events not used by $D$, so $D_{0}(\mathcal{E} v)=D(f(\mathcal{E} v))=D\left(\mathcal{E} v^{\prime}\right)$. Indeed, in a trace of $(\sigma C)[Q]$, if an event $e(\ldots)$ is executed in $Q$, then it is executed by $C[Q]$ as well. If it is in $\mathcal{E}$, then it is left unchanged by $f$. If it is not in $\mathcal{E}$, then it is in $\operatorname{event}(Q) \backslash \mathcal{E} \subseteq E v U s e d \backslash \mathcal{E}$, so it is removed by $f$; furthermore, this event is not used by $D$ since $\operatorname{event}(D) \cap \operatorname{event}(Q) \subseteq \mathcal{E}$. If an event $e(\ldots)$ is executed in $\sigma C$, then either $e \in \sigma E v U s e d, e^{\prime}(\ldots)$ is executed by $C[Q]$ with $e^{\prime}=\sigma^{-1}(e)$, and $f$ maps $e$ to $e^{\prime}$; or $e \notin \sigma E v U s e d, e \notin E v U s e d, e(\ldots)$ is executed by $C[Q]$, and $f$ leaves $e$ unchanged. Therefore, $\operatorname{Pr}^{\mathcal{A}}\left[(\sigma C)[Q]: D_{0}\right]=\operatorname{Pr}^{\mathcal{A}}[C[Q]: D]$. We have a similar situation for $Q^{\prime}$ instead of $Q$, and $D$ can be implemented in the same time as $D_{0}$, so

$$
\left|\operatorname{Pr}^{\mathcal{A}}[C[Q]: D]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: D\right]\right| \leq p\left(\mathcal{A}, C, t_{D}\right)
$$

so $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}$.
Property 2 Obvious.
Property 3. The events in $Q$ or $D$ are in EvUsed. We have EvUsed $\subseteq E v U s e d^{\prime} \subseteq E^{\prime} \subseteq$ Evsed $^{\prime \prime}$. The events that occur in $Q^{\prime \prime}$ but not in $Q$ occur either in $Q^{\prime \prime}$ but not in $Q^{\prime}$ or in $Q^{\prime}$ but not in $Q$; in the former case, they are in EvUsed ${ }^{\prime \prime} \backslash E v U s e d^{\prime}$; in the latter case, they are in EvUsed ${ }^{\prime} \backslash$ EvUsed; so in both cases they are in $E v U s e d^{\prime \prime} \backslash E v U s e d$. The same reasoning applies for the events that occur in $D^{\prime \prime}$ but not in $D$.

Let $\mathcal{A} \in \mathcal{B B}$ be an attacker, $C$ be any evaluation context acceptable for $Q$ and $Q^{\prime \prime}$ with public variables $V$ that does not contain events in $E v U s e d^{\prime \prime}$. After renaming the variables of $C$ that do not occur in $Q$ and $Q^{\prime \prime}$ and the tables of $C$ that do not occur in $Q$ and $Q^{\prime \prime}$ so that they do not occur in $Q^{\prime}, C$ is also acceptable for $Q^{\prime}$ with public variables $V$. Furthermore, by Property 6 . this renaming does not change the probabilities. Since EvUsed ${ }^{\prime} \subseteq E v U s e d^{\prime \prime}, C$ does not contain events in EvUsed ${ }^{\prime}$.

Let $D_{0} \in \mathcal{D} \cup\left\{D_{\text {false }}\right\}$ that runs in time at most $t_{D_{0}}$. Let $D_{1}$ be a disjunction of events of $\mathcal{D}_{\text {SNU }}$. Then we have:

$$
\begin{aligned}
& \left.\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(D_{0} \vee D_{1} \vee D\right)\right) \wedge \neg \text { NonUnique }_{Q, D_{1} \vee D}\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]:\left(D_{0} \vee D_{1} \vee D^{\prime}\right) \wedge \neg \text { NonUnique }_{Q^{\prime}, D_{1} \vee D^{\prime}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right) \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime \prime}\right]:\left(D_{0} \vee D_{1} \vee D^{\prime \prime}\right) \wedge \neg \text { NonUnique }_{Q^{\prime \prime}, D_{1} \vee D^{\prime \prime}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right) \\
& \left.\quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime \prime}\right]:\left(D_{0} \vee D_{1} \vee D^{\prime \prime}\right)\right) \wedge \neg \text { NonUnique }_{Q^{\prime \prime}, D_{1} \vee D^{\prime \prime}}\right]+p^{\prime \prime}\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

by definition of $p^{\prime \prime}$. Therefore, we have $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}{ }_{p^{\prime \prime}} Q^{\prime \prime}, D^{\prime \prime}$, EvUsed ${ }^{\prime \prime}$.
Property $4 \quad \sigma \mathcal{D}_{\mathrm{SNU}}$ is a set of Shoup and non-unique events in $\sigma$ EvUsed $\subseteq \sigma$ EvUsed $\cup$ $E v U s e d^{+}$, so $\sigma \mathcal{D}_{\text {SNU }} \cup \mathcal{D}_{\text {SNU }}^{\prime}$ is a set of Shoup and non-unique events in $\sigma E v U s e d \cup E v U s e d^{+}$. The events that occur in $C[\sigma Q]$ are either in $C$ or in $\sigma Q$; the former case, they are in EvUsed ${ }^{+}$ by hypothesis; in the latter case, they are also in $\sigma$ EvUsed, since the events of $Q$ are in EvUsed. So the events that occur in $C[\sigma Q]$ are in $\sigma E v U s e d \cup E v U s e d^{+}$. The events in $D \circ \sigma^{-1}$ are in $\sigma E v U s e d \subseteq \sigma E v U s e d \cup E v U s e d^{+}$. We have EvUsed $\subseteq E v U s e d^{\prime}$, so $\sigma E v U s e d \cup E v U s e d^{+} \subseteq$ $\sigma E v U s e d^{\prime} \cup E v U s e d^{+}$. The events that occur in $C\left[\sigma Q^{\prime}\right]$ but not in $C[\sigma Q]$ are in $\sigma Q^{\prime}$ but not in $\sigma Q$, so they are in $\sigma E v U s e d^{\prime} \backslash \sigma E v U s e d$, so in $\left(\sigma E v U s e d^{\prime} \cup E v U s e d^{+}\right) \backslash\left(\sigma\right.$ EvUsed $\left.\cup E v U s e d^{+}\right)$. Similarly, the events that occur in $D^{\prime} \circ \sigma^{-1}$ but not in $D \circ \sigma^{-1}$ are in $\sigma E v U s e d^{\prime} \backslash \sigma E v U s e d$, so they are in $\left(\sigma E v U s e d^{\prime} \cup E v U s e d^{+}\right) \backslash\left(\sigma E v U s e d \cup E v U s e d^{+}\right)$.

Let $C^{\prime}$ be any evaluation context acceptable for $C[\sigma Q]$ and $C\left[\sigma Q^{\prime}\right]$ with public variables $V^{\prime}$ that does not contain events in $\sigma E v U s e d^{\prime} \cup E v U s e d^{+}$. We rename the variables of $C^{\prime}$ not in $V^{\prime}$ so that they are not in $V$; by Property 6, this renaming does not change the probabilities. Then $\sigma^{-1}\left(C^{\prime}[C[]]\right)$ is an evaluation context acceptable for $Q$ and $Q^{\prime}$ with public variables $V$. Indeed,

$$
\begin{aligned}
\operatorname{var}\left(\sigma^{-1}\left(C^{\prime}[C[]]\right)\right) \cap \operatorname{var}(Q) & =\left(\operatorname{var}\left(C^{\prime}\right) \cup \operatorname{var}(C)\right) \cap \operatorname{var}(Q) \\
& \subseteq\left(V^{\prime} \cup \operatorname{var}(C)\right) \cap \operatorname{var}(Q) \\
& \quad \operatorname{since} \operatorname{var}\left(C^{\prime}\right) \cap \operatorname{var}(Q) \subseteq \operatorname{var}\left(C^{\prime}\right) \cap \operatorname{var}(C[Q]) \subseteq V^{\prime} \\
& \subseteq(V \cup \operatorname{var}(C)) \cap \operatorname{var}(Q) \quad \text { since } V^{\prime} \subseteq V \cup \operatorname{var}(C) \\
& \subseteq V \quad \text { since } \operatorname{var}(C) \cap \operatorname{var}(Q) \subseteq V
\end{aligned}
$$

We have similarly $\operatorname{var}\left(\sigma^{-1}\left(C^{\prime}[C[]]\right)\right) \cap \operatorname{var}\left(Q^{\prime}\right) \subseteq V$. We also have vardef $\left(\sigma^{-1}\left(C^{\prime}[C[]]\right)\right) \cap V=$ (vardef $\left.\left(C^{\prime}\right) \cap V\right) \cup(\operatorname{vardef}(C) \cap V)=\emptyset$ since $\operatorname{vardef}(C) \cap V=\emptyset$ because $C$ is an acceptable evaluation context for $\sigma Q$ with public variables $V$ and $\operatorname{vardef}\left(C^{\prime}\right) \cap V \subseteq \operatorname{vardef}\left(C^{\prime}\right) \cap V^{\prime}=\emptyset$ because we have renamed the variables of $C^{\prime}$ not in $V^{\prime}$ so that they are not in $V$ and $C^{\prime}$ is an acceptable evaluation context for $C[\sigma Q]$ and with public variables $V^{\prime}$. Moreover, $C$ and $\sigma Q$ do not use any common table, and $C^{\prime}$ and $C[\sigma Q]$ do not use any common table so a fortiori $C^{\prime}$ and $\sigma Q$ do not use any common table. Therefore, $C^{\prime}[C[]]$ and $\sigma Q$ do not use any common table, so $\sigma^{-1}\left(C^{\prime}[C[]]\right)$ and $Q$ do not use any common table. Similarly, $\sigma^{-1}\left(C^{\prime}[C[]]\right)$ and $Q^{\prime}$ do not use any common table. The context $\sigma^{-1}\left(C^{\prime}[C[]]\right)$ does not contain events in EvUsed ${ }^{\prime}$, since $C^{\prime}$ and $C$ do not contain events in $\sigma E v U s e d^{\prime}$, because $C^{\prime}$ does not contain events in $\sigma E v U s e d^{\prime} \cup E v U s e d^{+}$ and the events of $C$ are in $E v U s e d^{+}$which is disjoint from $\sigma E v U s e d^{\prime}$. (The renamings $\sigma$ and $\sigma^{-1}$ are bijections, so for instance $\sigma$ maps the fresh events introduced by $\sigma$ to $E v U s e d^{\prime}$ and $\sigma^{-1}$ maps EvUsed ${ }^{\prime}$ to the fresh events introduced by $\sigma$.)

By using the property $\mathcal{D}_{\neg \text { EvUsed }}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}{ }_{p} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$ with the context $\sigma^{-1}\left(C^{\prime}[C[]]\right)$, we get for all attackers $\mathcal{A} \in \mathcal{B B}$ and for any distinguishers $D_{0} \in \mathcal{D}_{\neg \text { EvUsed }} \cup\left\{D_{\text {false }}\right\}$
that runs in time $t_{D_{0}}$ and $D_{1}$ disjunction of events in $\mathcal{D}_{\text {SNU }}$ :

$$
\begin{align*}
& \left.\operatorname{Pr}^{\mathcal{A}}\left[\sigma^{-1} C^{\prime}\left[\sigma^{-1} C[Q]\right]:\left(D_{0} \vee D_{1} \vee D\right)\right) \wedge \neg \text { NonUnique }_{Q, D_{1} \vee D}\right] \\
& \left.\quad \leq \operatorname{Pr}^{\mathcal{A}}\left[\sigma^{-1} C^{\prime}\left[\sigma^{-1} C\left[Q^{\prime}\right]\right]:\left(D_{0} \vee D_{1} \vee D^{\prime}\right)\right) \wedge \neg \text { NonUnique }_{Q^{\prime}, D_{1} \vee D^{\prime}}\right]+p\left(\mathcal{A}, \sigma^{-1}\left(C^{\prime}[C[]]\right), t_{D_{0}}\right) \tag{3}
\end{align*}
$$

Let $D_{0}^{\prime} \in \mathcal{D}_{\neg \sigma \text { EvUsed }} \cup\left\{D_{\text {false }}\right\}$ that runs in time at most $t_{D_{0}}$, Let $D_{1}^{\prime}$ be a disjunction of events in $\sigma \mathcal{D}_{\mathrm{SNU}} \cup \mathcal{D}_{\mathrm{SNU}}^{\prime}$. We can write $D_{1}^{\prime}$ under the form $D_{1}^{\prime}=D_{2}^{\prime} \vee D_{3}^{\prime}$ where $D_{2}^{\prime}$ is a disjunction of events in $\sigma \mathcal{D}_{\text {SNU }}$ and $D_{3}^{\prime}$ is a disjunction of events in $\mathcal{D}_{\text {SNU }}^{\prime}$.

By applying (3) to $D_{0}=\left(D_{0}^{\prime} \circ \sigma \vee D_{3}^{\prime} \circ \sigma\right) \wedge \neg$ NonUnique $_{\sigma^{-1} C, D_{3}^{\prime} \circ \sigma}$, which uses events not in EvUsed' , and to $D_{1}=D_{2}^{\prime} \circ \sigma$, we get for all $\mathcal{A} \in \mathcal{B B}$

$$
\begin{aligned}
\operatorname{Pr}^{\mathcal{A}} & {\left[\sigma^{-1} C^{\prime}\left[\sigma^{-1} C[Q]\right]:\left(\left(\left(D_{0}^{\prime} \circ \sigma \vee D_{3}^{\prime} \circ \sigma\right) \wedge \neg \text { NonUnique }_{\sigma^{-1} C, D_{3}^{\prime} \circ \sigma}\right) \vee D_{2}^{\prime} \circ \sigma \vee D\right)\right) } \\
& \left.\wedge \neg \text { NonUnique }_{Q, D_{2}^{\prime} \circ \sigma \vee D}\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[\sigma^{-1} C^{\prime}\left[\sigma^{-1} C\left[Q^{\prime}\right]\right]:\left(\left(\left(D_{0}^{\prime} \circ \sigma \vee D_{3}^{\prime} \circ \sigma\right) \wedge \neg \text { NonUnique }_{\sigma^{-1} C, D_{3}^{\prime} \circ \sigma}\right) \vee D_{2}^{\prime} \circ \sigma \vee D^{\prime}\right)\right) \\
& \left.\wedge \neg \text { NonUnique }_{Q^{\prime}, D_{2}^{\prime} \circ \sigma \vee D^{\prime}}\right]+p\left(\mathcal{A}, \sigma^{-1}\left(C^{\prime}[C[]]\right), t_{D_{0}^{\prime}}\right)
\end{aligned}
$$

since $D_{0}$ can be implemented to run in the same time as $D_{0}^{\prime}$. By applying $\sigma$, we have for all $\mathcal{A} \in \mathcal{B B}$

$$
\begin{aligned}
&\left.\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}[C[\sigma Q]]:\left(\left(\left(D_{0}^{\prime} \vee D_{3}^{\prime}\right) \wedge \neg \text { NonUnique }_{C, D_{3}^{\prime}}\right) \vee D_{2}^{\prime} \vee D \circ \sigma^{-1}\right)\right) \wedge \neg \text { NonUnique }_{\sigma Q, D_{2}^{\prime} \vee D \circ \sigma^{-1}}\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C\left[\sigma Q^{\prime}\right]\right]:\left(\left(\left(D_{0}^{\prime} \vee D_{3}^{\prime}\right) \wedge \neg \text { NonUnique }_{C, D_{3}^{\prime}}\right) \vee D_{2}^{\prime} \vee D^{\prime} \circ \sigma^{-1}\right)\right) \\
&\left.\wedge \neg \text { NonUnique }_{\sigma Q^{\prime}, D_{2}^{\prime} \vee D^{\prime} \circ \sigma^{-1}}\right]+p\left(\mathcal{A}, \sigma^{-1}\left(C^{\prime}[C[]]\right), t_{D_{0}^{\prime}}\right)
\end{aligned}
$$

Since the events of $C$ are in $E v U s e d^{+}$, the events of NonUnique ${ }_{C, D_{3}^{\prime}}$ are disjoint from those in $\left(D_{2}^{\prime} \vee D \circ \sigma^{-1}\right)$, so $\left(\neg\right.$ NonUnique $\left._{C, D_{3}^{\prime}}\right) \vee\left(D_{2}^{\prime} \vee D \circ \sigma^{-1}\right)=\neg$ NonUnique $_{C, D_{3}^{\prime}}$ and similarly $\left(\neg\right.$ NonUnique $\left._{C, D_{3}^{\prime}}\right) \vee\left(D_{2}^{\prime} \vee D^{\prime} \circ \sigma^{-1}\right)=\neg$ NonUnique $_{C, D_{3}^{\prime}}$. So we have for all $\mathcal{A} \in \mathcal{B B}$

$$
\begin{aligned}
\operatorname{Pr}^{\mathcal{A}} & {\left.\left[C^{\prime}[C[\sigma Q]]:\left(D_{0}^{\prime} \vee D_{3}^{\prime} \vee D_{2}^{\prime} \vee D \circ \sigma^{-1}\right)\right) \wedge \neg \text { NonUnique }_{C, D_{3}^{\prime}} \wedge \neg \text { NonUnique }_{\sigma Q, D_{2}^{\prime} \vee D \circ \sigma^{-1}}\right] } \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C\left[\sigma Q^{\prime}\right]\right]:\left(D_{0}^{\prime} \vee D_{3}^{\prime} \vee D_{2}^{\prime} \vee D^{\prime} \circ \sigma^{-1}\right)\right) \wedge \neg \text { NonUnique }_{C, D_{3}^{\prime}} \\
& \left.\wedge \neg \text { NonUnique }_{\sigma Q^{\prime}, D_{2}^{\prime} \vee D^{\prime} \circ \sigma^{-1}}\right]+p\left(\mathcal{A}, \sigma^{-1}\left(C^{\prime}[C[]]\right), t_{D_{0}^{\prime}}\right)
\end{aligned}
$$

that is

$$
\begin{aligned}
\operatorname{Pr}^{\mathcal{A}} & {\left.\left[C^{\prime}[C[\sigma Q]]:\left(D_{0}^{\prime} \vee D_{1}^{\prime} \vee D \circ \sigma^{-1}\right)\right) \wedge \neg \text { NonUnique }_{C[\sigma Q], D_{1}^{\prime} \vee D \circ \sigma^{-1}}\right] } \\
\leq & \left.\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C\left[\sigma Q^{\prime}\right]\right]:\left(D_{0}^{\prime} \vee D_{1}^{\prime} \vee D^{\prime} \circ \sigma^{-1}\right)\right) \wedge \neg \text { NonUnique }_{C\left[\sigma Q^{\prime}\right], D_{1}^{\prime} \vee D^{\prime} \circ \sigma^{-1}}\right] \\
& +p\left(\mathcal{A}, \sigma^{-1}\left(C^{\prime}[C[]]\right), t_{D_{0}^{\prime}}\right)
\end{aligned}
$$

Properties 5 and 6 Obvious.
When CryptoVerif transforms a game $G$ into a game $G^{\prime}$, in most cases, we have $G \approx_{p}^{V, \mathcal{E}}$ $G^{\prime}$, where $p$ is the probability difference coming from the transformation, and computed by CryptoVerif, which implies $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, D$, EvUsed $\xrightarrow{V}_{p} G^{\prime}, D$, EvUsed, for all $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}, D$ such that $\operatorname{event}(\mathcal{D}) \cap E v U s e d \subseteq \mathcal{E}, \mathcal{D}_{\mathrm{SNU}} \subseteq \mathcal{E}, \operatorname{event}(D) \subseteq \mathcal{E}$ by Lemma 20. Property 1a. However, there are exceptions to this situation:

- transformations that exploit the uniqueness of find $\left[\right.$ unique $\left._{e}\right]$ or get [unique $\left.{ }_{e}\right]$, which are valid only when event $e$ is not executed. These events are taken into account by NonUnique ${ }_{Q, D}$.
- transformations that insert events using Shoup's lemma. This is the case of the transformations insert_event (see Section 5.1.12) and insert (see Section 5.1.13). In this case, we have $\mathcal{D}, \mathcal{D}_{\text {SNU }}: G, D_{\text {false }}$, EvUsed $\xrightarrow{V} G^{\prime}, e$, EvUsed $\cup\{e\}$ where $e$ is the introduced event.
The addition of Shoup events may also be combined with the cryptographic transformation of Section 5.2, for example for specifying the decisional Diffie-Hellman assumption. In general, the cryptographic axioms are of the form

$$
\mathcal{D}_{\neg \text { EvUsed }_{R}}, \emptyset: L, D_{\mathrm{false}}, \emptyset \rightarrow_{p} R, D_{R}, \text { EvUsed }_{R}
$$

where $L$ does not contain events, $D_{R}=\bigvee\{e \mid$ event_abort $e$ occurs in $R\}$ and EvUsed ${ }_{R}=$ $\{e$ that occur in $R\}$ (both event_abort $e$ and [unique $\left.{ }_{e}\right]$ ). By Lemma 20, Property 4 , we infer

$$
\mathcal{D}_{\neg \sigma E v U s e d_{R}}, \mathcal{D}_{\mathrm{SNU}}: C[L], D_{\mathrm{false}}, \text { EvUsed }{\xrightarrow{p^{\prime}}} C[\sigma R], D_{R} \circ \sigma^{-1}, \text { EvUsed } \cup \sigma \text { EvUsed }_{R}
$$

where $\sigma$ is a renaming of the events in EvUsed ${ }_{R}$ to events not in EvUsed, $C$ is a context acceptable for $L$ and $R$ such that the events that occur in $C$ are in EvUsed, $\mathcal{D}_{\text {SNU }}$ is a set of Shoup and non-unique events in EvUsed, $p^{\prime}\left(\mathcal{A}, C^{\prime}, t_{D_{0}}\right)=p\left(\mathcal{A}, \sigma^{-1}\left(C^{\prime}[C[]]\right), t_{D_{0}}\right)$, and $V \subseteq \operatorname{var}(C)$.
Distinguishers in $\mathcal{D}_{\neg \sigma \text { EvUsed }}^{R}$ include distinguishers that use events in EvUsed, in particular distinguishers for correspondences in $G$, as well as distinguishers in $\mathcal{D}_{\neg\left(\text { EvUsed } \cup \sigma \text { EvUsed }_{R}\right)}$ used for secrecy and indistinguishability.

- transformations that prove the absence of some events (up to some probability). For such transformations, we have $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, e, E v U s e d \xrightarrow{V}_{p} G, D_{\text {false }}, E v U s e d$ where $p$ is an upper bound of the probability of event $e$ in $G$. For Shoup events, this generally happens when $G$ does not contain $e$ and $p\left(\mathcal{A}, C, t_{D_{0}}\right)=0$. For non-unique events, $p$ is the probability that the find[unique ${ }_{e}$ ] or get[unique ${ }_{e}$ ] yields several possible choices; after this step, the event $e$ is in NonUnique ${ }_{G, D}$, so we can exploit uniqueness of find[unique ${ }_{e}$ ] or get[unique ${ }_{e}$ ].

That is why, in general, when CryptoVerif transforms a game $G$ into a game $G^{\prime}$, we have $\mathcal{D}, \mathcal{D}_{\text {SNU }}$ : $G, D, E v U s e d \xrightarrow{V} G^{\prime}, D^{\prime}, E v U s e d^{\prime}$.

There are still transformations that do not fit in this framework (guess and guess_branch, because they multiply probabilities, as shown in Sections 5.1.17, 5.1.18, and 5.1.19, success simplify because it needs to compensate probabilities of traces that execute $S$ with those that execute $\overline{\mathrm{S}}$ to show soundness for secrecy, as shown in Section 5.1.23.

### 2.8.1 Secrecy

Let us now define the secrecy properties that are proved by CryptoVerif.
Definition 7 ((One-session) secrecy) Let $Q$ be an oracle definition, $x$ a variable, and $V$ a set of variables. Let

$$
\begin{aligned}
Q_{1 \text {-ses.secr. }(x)}= & O_{s 0}():=b \stackrel{R}{\leftarrow} \text { bool } ; \text { return }() ; \\
& \left(O_{s}\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):=\text { if defined }\left(x\left[u_{1}, \ldots, u_{m}\right]\right)\right. \text { then } \\
& \text { if } b \text { then return }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \text { else } y \stackrel{R}{\leftarrow} T ; \text { return }(y)
\end{aligned}
$$

$$
\begin{aligned}
& \left.\mid O_{s}^{\prime}\left(b^{\prime}: \text { bool }\right):=\text { if } b=b^{\prime} \text { then event_abort } \mathrm{S} \text { else event_abort } \overline{\mathrm{S}}\right) \\
Q_{\text {Secrecy }(x)}= & O_{s 0}():=b \stackrel{R}{\leftarrow} \text { bool; return }() ; \\
& \left(\text { foreach } i_{s} \leq n_{s} \text { do } O_{s}\left[i_{s}\right]\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):=\right. \\
& \text { if defined }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \text { then } \\
& \text { if } b \text { then return }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \text { else } \\
& \text { find } u_{s}^{\prime}=i_{s}^{\prime} \leq n_{s} \text { suchthat defined }\left(y\left[i_{s}^{\prime}\right], u_{1}\left[i_{s}^{\prime}\right], \ldots, u_{m}\left[i_{s}^{\prime}\right]\right) \wedge \\
& u_{1}\left[i_{s}^{\prime}\right]=u_{1} \wedge \ldots \wedge u_{m}\left[i_{s}^{\prime}\right]=u_{m} \\
& \text { then return }\left(y\left[u_{s}^{\prime}\right]\right) \\
& \text { else } y \stackrel{R}{\leftarrow} T ; \text { return }(y) \\
& \left.\mid O_{s}^{\prime}\left(b^{\prime}: \text { bool }\right):=\text { if } b=b^{\prime} \text { then event_abort } \mathrm{S} \text { else event_abort } \overline{\mathrm{S}}\right)
\end{aligned}
$$

where $O_{s 0}, O_{s}, O_{s}^{\prime} \notin \mathrm{fo}(Q), u_{1}, \ldots, u_{m}, u_{s}^{\prime}, y, b, b^{\prime} \notin \operatorname{var}(Q) \cup V, \mathrm{~S}, \overline{\mathrm{~S}}$ do not occur in $Q$, and $\mathcal{E}(x)=\left[1, n_{1}\right] \times \ldots \times\left[1, n_{m}\right] \rightarrow T$.

Let $s p$ be 1-ses.secr. $(x)$ (one-session secrecy of $x$ ) or Secrecy $(x)$ (secrecy of $x)$. The events used by $s p$ are S and $\overline{\mathrm{S}}$. Let $C_{s p}=[] \mid Q_{s p}$.

Let $C$ be an evaluation context acceptable for $C_{s p}[Q]$ with public variables $V(x \notin V)$ that does not contain the events used by $s p$, and $\mathcal{A} \in \mathcal{B B}$ be an attacker. The advantage of the adversary $\mathcal{A}, C$ against $s p$ in process $Q$ is

$$
\operatorname{Adv}_{Q}^{s p}(\mathcal{A}, C)=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \overline{\mathrm{S}}\right]
$$

The process $Q$ satisfies $s p$ with public variables $V(x \notin V)$ up to probability $p$ when, for all attackers $\mathcal{A} \in \mathcal{B B}$, for all evaluation contexts $C$ acceptable for $C_{s p}[Q]$ with public variables $V$ that do not contain the events used by $s p, \operatorname{Adv}_{Q}^{s p}(\mathcal{A}, C) \leq p(\mathcal{A}, C)$.

Intuitively, when $Q$ satisfies $s p$, the adversary cannot guess the random bit $b$, that is, it cannot distinguish whether the test oracle $Q_{s p}$ returns the value of the secret ( $b=$ true) or a random number ( $b=$ false).

For one-session secrecy, the adversary performs a single test query, modeled by $Q_{1 \text {-ses.secr. }(x)}$. In more detail, in $Q_{1 \text {-ses.secr. (x) }}$, we choose a random bit $b$; the adversary queries oracle $O_{s}$ with the indices $\left(u_{1}, \ldots, u_{m}\right)$ to perform a test query on $x\left[u_{1}, \ldots, u_{m}\right]$ : if $b=$ true, the test query returns $x\left[u_{1}, \ldots, u_{m}\right]$; if $b=$ false, it returns a random value $y$. Finally, the adversary should guess the bit $b$ : it calls oracle $O_{s}^{\prime}$ with its guess $b^{\prime}$ and, if the guess is correct, then event S is executed, and otherwise, event $\overline{\mathrm{S}}$ is executed. The probability of getting some information on the secret is the difference between the probability of S and the probability of $\overline{\mathrm{S}}$. (When the adversary always calls oracle $O_{s}^{\prime}$, we have $\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \overline{\mathrm{S}}\right]=1-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \mathrm{S}\right]$, so the advantage of the adversary is $\operatorname{Adv}_{Q}^{s p}(\mathcal{A}, C)=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \overline{\mathrm{S}}\right]=2 \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \mathrm{S}\right]-1$, which is a more standard formula. By flipping a coin, the adversary can execute events $S$ and $\bar{S}$ with the same probability, that is why the probability that the adversary really guesses $b$ is the difference between the probability of these two events. We need not take the absolute value of $\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \overline{\mathrm{S}}\right]$ because, when it is negative, we can obtain the opposite, positive value by considering an adversary that calls $O_{s}^{\prime}$ with the guess $\neg b^{\prime}$ instead of $b^{\prime}$.)

For secrecy, the adversary can perform several test queries, modeled by $Q_{\text {Secrecy }(x)}$. This corresponds to the "real-or-random" definition of security [4]. (As shown in 4], this notion is stronger than the more standard approach in which the adversary can perform a single test query and some reveal queries, which always reveal $x\left[u_{1}, \ldots, u_{m}\right]$.) The replication bound $n_{s}$ in $Q_{\text {Secrecy (x) }}$ is chosen large enough so that it does not prevent oracle calls that would otherwise
occur, so $n_{s}$ does not actually limit the number of test queries. When we return a random value ( $b=$ false) and several tests queries are performed on the same indices $u_{1}, \ldots, u_{m}$, we must return the same random value. That is why, in this case, we look for previous test queries (find $u_{s}^{\prime} \ldots$ ) and return the previous value of $y$ in case a previous test query was performed with the same indices. For different indices $u_{1}, \ldots, u_{m}$, the returned random values are independent of each other, so the secrecy of $x$ requires that the cells of array $x$ are indistinguishable from independent random values. In contrast, the one-session secrecy of $x$ only requires that all array cells of $x$ are indistinguishable from random values, not that they are independent of each other.

By Invariant 3, the variables defined in conditions of find and in patterns and in conditions of get have no array accesses. Therefore, the definition above applies only to variables $x$ that are not defined in conditions of find nor in patterns nor in conditions of get.

Lemma 21 Let sp be 1-ses.secr. $(x)$ or $\operatorname{Secrecy}(x)$.
If $Q$ satisfies sp with public variables $V$ up to probability $p$ and $C$ is an acceptable evaluation context for $Q$ with public variables $V$, then for all $V^{\prime} \subseteq V \cup \operatorname{var}(C), C[Q]$ satisfies sp with public variables $V^{\prime}$ up to probability $p^{\prime}$ such that $p^{\prime}\left(\mathcal{A}, C^{\prime}\right)=p\left(\mathcal{A}, C^{\prime}[C]\right)$.

If $Q \approx_{p}^{V \cup\{x\}, \mathcal{E}} Q^{\prime}$ and $Q$ satisfies sp with public variables $V$ up to probability $p^{\prime}$, then $Q^{\prime}$ satisfies sp with public variables $V$ up to probability $p^{\prime \prime}$ such that $p^{\prime \prime}(\mathcal{A}, C)=p^{\prime}(\mathcal{A}, C)+2 \times$ $p\left(\mathcal{A}, C\left[C_{s p}[]\right], t_{\mathrm{S}}\right)$.

Proof Suppose that $Q$ satisfies $s p$ with public variables $V(x \notin V), \mathcal{A} \in \mathcal{B B}$ is an attacker and $C$ is an acceptable evaluation context for $Q$ with public variables $V$. Let $V^{\prime} \subseteq V \cup \operatorname{var}(C)$. Choose oracles $O_{s 0}, O_{s}, O_{s}^{\prime}$, variables $u_{1}, \ldots, u_{m}, u_{s}^{\prime}, y, b, b^{\prime}$, and events $\mathrm{S}, \overline{\mathrm{S}}$ such that they do not occur in $C[Q]$. Let $C^{\prime}$ be an acceptable evaluation context for $C_{s p}[C[Q]]$ with public variables $V^{\prime}$ that does not contain S nor $\overline{\mathrm{S}}$. Then we have

$$
\begin{aligned}
\operatorname{Adv}_{C[Q]}^{s p}\left(\mathcal{A}, C^{\prime}\right) & =\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C_{s p}[C[Q]]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C_{s p}[C[Q]]\right]: \overline{\mathrm{S}}\right] \\
& =\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C\left[C_{s p}[Q]\right]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C\left[C_{s p}[Q]\right]\right]: \overline{\mathrm{S}}\right] \\
& \leq p\left(\mathcal{A}, C^{\prime}[C]\right)
\end{aligned}
$$

We can commute the contexts $C$ and $C_{s p}$ because the context $C$ does not bind the oracles of $Q_{s p}$. The context $C^{\prime}[C]$ is an acceptable evaluation context for $C_{s p}[Q]$ with public variables $V$ that does not contain S nor $\overline{\mathrm{S}}$ : there is no common table between $C$ and $Q$, and between $C^{\prime}$ and $C_{s p}[C[Q]]$, so a fortiori between $C^{\prime}$ and $Q$ and $Q_{s p}$ does not use tables, so there is no common table between $C^{\prime}[C]$ and $C_{s p}[Q]$; moreover

$$
\begin{aligned}
& \operatorname{var}\left(C^{\prime}[C]\right) \cap \operatorname{var}\left(C_{s p}[Q]\right) \\
& \quad=\left(\left(\operatorname{var}\left(C^{\prime}\right) \cap \operatorname{var}\left(C_{s p}[Q]\right)\right) \cup \operatorname{var}(C)\right) \cap \operatorname{var}\left(C_{s p}[Q]\right) \\
& \quad \subseteq\left(V^{\prime} \cup \operatorname{var}(C)\right) \cap \operatorname{var}\left(C_{s p}[Q]\right) \quad \text { since } \operatorname{var}\left(C^{\prime}\right) \cap \operatorname{var}\left(C_{s p}[C[Q]]\right) \subseteq V^{\prime} \\
& \quad \subseteq(V \cup \operatorname{var}(C)) \cap \operatorname{var}\left(C_{s p}[Q]\right) \\
& \quad \subseteq V \quad \text { since } V^{\prime} \subseteq V \cup \operatorname{var}(C) \\
& \\
& \quad \text { since } \operatorname{var}(C) \cap \operatorname{var}(Q) \subseteq V \text { and } \operatorname{var}(C) \cap \operatorname{var}\left(Q_{s p}\right)=\emptyset
\end{aligned}
$$

Suppose that $Q \approx_{p}^{V \cup\{x\}, \mathcal{E}} Q^{\prime}$ and $Q$ satisfies $s p$ with public variables $V$ up to probability $p^{\prime}$. Let $\mathcal{A} \in \mathcal{B B}$ be an attacker. Let $C$ be an acceptable evaluation context for $C_{s p}\left[Q^{\prime}\right]$ with public
variables $V$ that does not contain S nor $\overline{\mathrm{S}}$.

$$
\begin{aligned}
\operatorname{Adv}_{Q^{\prime}}^{s p}(\mathcal{A}, C)= & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q^{\prime}\right]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q^{\prime}\right]\right]: \overline{\mathrm{S}}\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \overline{\mathrm{S}}\right]+ \\
& \left|\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q^{\prime}\right]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \mathrm{S}\right]\right|+ \\
& \left|\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[Q]\right]: \overline{\mathrm{S}}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q^{\prime}\right]\right]: \overline{\mathrm{S}}\right]\right| \\
\leq & p^{\prime}(\mathcal{A}, C)+2 \times p\left(\mathcal{A}, C\left[C_{s p}[]\right], t_{\mathrm{S}}\right)
\end{aligned}
$$

since $t_{\mathrm{S}}=t_{\overline{\mathrm{S}}}$. Indeed, by renaming the variables and tables of $C$ that do not appear in $Q^{\prime}$ to variables and tables that also do not occur in $Q, C$ is also an acceptable evaluation context for $C_{s p}[Q]$ with public variables $V$. Furthermore, by Property 6 , this renaming does not change the probabilities.

### 2.8.2 Secrecy for a Bit

Definition 8 (Bit secrecy) Let $Q$ be a process, $x$ a boolean variable defined under no replication, and $V$ a set of variables. Let

$$
Q_{\text {bit secr. }(x)}=O_{s}^{\prime \prime}\left(b^{\prime}: b o o l\right):=\text { if defined }(x) \text { then if } x=b^{\prime} \text { then event_abort } \mathrm{S} \text { else event_abort } \overline{\mathrm{S}}
$$

where $O_{s}^{\prime \prime} \notin$ fo $(Q), b^{\prime} \notin \operatorname{var}(Q) \cup V, \mathrm{~S}, \overline{\mathrm{~S}}$ do not occur in $Q$, and $\mathcal{E}(x)=$ bool.
Let $s p$ be bit secr. $(x)$ (bit secrecy of $x$ ). The events used by $s p$ are S and $\overline{\mathrm{S}}$. Let $C_{s p}=[] \mid Q_{s p}$. The definitions of $\operatorname{Adv}_{Q}^{s p}(\mathcal{A}, C)$ and " $Q$ satisfies $s p$ " are as in Definition 7
Intuitively, when $Q$ satisfies $s p$, the adversary cannot guess the boolean $x$, that is, it cannot distinguish whether $x=$ true or $x=$ false. The adversary performs a single test query, modeled by $Q_{\text {bit secr. }(x)}$. This definition is simpler than the definition of (one-session) secrecy for $x$, because we do not introduce an additional random bit $b$.

By Invariant 3, the variables defined in conditions of find and in patterns and in conditions of get have no array accesses. Therefore, the definition above applies only to variables $x$ that are not defined in conditions of find nor in patterns nor in conditions of get.

Lemma 21 is also valid when $s p=$ bit secr. $(x)$, with the same statement and proof.
Lemma 22 If $b_{0}$ is a boolean variable defined under no replication and $Q$ preserves the onesession secrecy of $b_{0}$ with public variables $V$ up to probability $p$, then $Q$ preserves the bit secrecy of $b_{0}$ with public variables $V$ up to probability $2 p$.

Proof Let $\mathcal{A} \in \mathcal{B B}$ be an attacker. Let $C$ be any acceptable evaluation context for $Q \mid$ $Q_{\text {bit secr. }\left(b_{0}\right)}$ with public variables $V$. Let

$$
C^{\prime}=C\left[-\mid O_{s}^{\prime \prime}\left(b_{0}^{\prime}: \text { bool }\right):=\text { let }()=O_{s 0}() \text { in let } b_{0}^{\prime \prime}: \text { bool }=O_{s}() \text { in let }()=O_{s}^{\prime}\left(b_{0}^{\prime}=b_{0}^{\prime \prime}\right) \text { in yield }\right] .
$$

We execute $C^{\prime}\left[Q \mid Q_{\left.1 \text {-ses.secr.( } b_{0}\right)}\right]$ with attacker $\mathcal{A}$.
When $b_{0}^{\prime}=b_{0}\left(C\left[Q \mid Q_{\text {bit secr. }\left(b_{0}\right)}\right]\right.$ executes S$)$,

- if $b=$ true (probability $1 / 2$ ), then $b_{0}^{\prime \prime}=b_{0}$, so $b^{\prime}=\left(b_{0}^{\prime}=b_{0}^{\prime \prime}\right)=$ true and S is executed with probability $1 / 2$
- if $b=$ false (probability $1 / 2$ ), then $b_{0}^{\prime \prime}$ is random, so

$$
-b_{0}^{\prime \prime}=b_{0}^{\prime} \text { with probability } 1 / 4 \text {, so } b^{\prime}=\left(b_{0}^{\prime}=b_{0}^{\prime \prime}\right)=\text { true and } \overline{\mathrm{S}} \text { is executed; }
$$

$-b_{0}^{\prime \prime}=\neg b_{0}^{\prime}$ with probability $1 / 4$, so $b^{\prime}=\left(b_{0}^{\prime}=b_{0}^{\prime \prime}\right)=$ false and S is executed.
When $b_{0}^{\prime}=\neg b_{0}\left(C\left[Q \mid Q_{\text {bit secr. }\left(b_{0}\right)}\right]\right.$ executes $\left.\overline{\mathrm{S}}\right)$,

- if $b=$ true (probability $1 / 2$ ), then $b_{0}^{\prime \prime}=b_{0}$, so $b^{\prime}$ is false and $\overline{\mathrm{S}}$ is executed with probability $1 / 2$;
- if $b=$ false (probability $1 / 2$ ), then $b_{0}^{\prime \prime}$ is random, so
$-b_{0}^{\prime \prime}=b_{0}^{\prime}$ with probability $1 / 4$, so $b^{\prime}=$ true and $\overline{\mathrm{S}}$ is executed;
$-b_{0}^{\prime \prime}=\neg b_{0}^{\prime}$ with probability $1 / 4$, so $b^{\prime}=$ false and $S$ is executed.
So

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[Q \mid Q_{\left.1 \text {-ses.secr.( } b_{0}\right)}\right]: \mathrm{S}\right]=\frac{3}{4} \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q \mid Q_{\text {bit secr.( } \left.b_{0}\right)}\right]: \mathrm{S}\right]+\frac{1}{4} \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q \mid Q_{\text {bit secr.( } \left.b_{0}\right)}\right]: \overline{\mathrm{S}}\right] \\
& \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[Q \mid Q_{\left.1 \text {-ses.secr.( } b_{0}\right)}\right]: \overline{\mathrm{S}}\right]=\frac{1}{4} \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q \mid Q_{\text {bit secr.( } \left.b_{0}\right)}\right]: \mathrm{S}\right]+\frac{3}{4} \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q \mid Q_{\text {bit secr.( } \left.b_{0}\right)}\right]: \overline{\mathrm{S}}\right]
\end{aligned}
$$

Finally, we obtain

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[Q \mid Q_{\left.1 \text {-ses.secr.( } b_{0}\right)}\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[Q \mid Q_{1 \text {-ses.secr.(boc) }}\right]: \overline{\mathrm{S}}\right] \\
& \quad=\frac{1}{2}\left(\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q \mid Q_{\text {bit secr.( } \left.b_{0}\right)}\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q \mid Q_{\text {bit secr.( } \left.b_{0}\right)}\right]: \overline{\mathrm{S}}\right]\right)
\end{aligned}
$$

so $\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q \mid Q_{\left.\text {bit secr.( } b_{0}\right)}\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q \mid Q_{\left.\text {bit secr.( } b_{0}\right)}\right]: \overline{\mathrm{S}}\right]=2\left(\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[Q \mid Q_{\left.1 \text {-ses.secr.( } b_{0}\right)}\right]:\right.\right.$ $\left.\mathrm{S}]-\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[Q \mid Q_{1 \text {-ses.secr. }\left(b_{0}\right)}\right]: \overline{\mathrm{S}}\right]\right) \leq 2 p\left(\mathcal{A}, C^{\prime}\right)=2 p(\mathcal{A}, C)$, neglecting the additional runtime of $C^{\prime}$.

Intuitively, the factor 2 is necessary, because in the definition of one-session secrecy, even if the adversary knows the secret bit $b_{0}$ perfectly, it will not be able to distinguish $b_{0}$ from the random bit $y$ in half of the cases, because $b_{0}$ and $y$ have the same value.

In the rest of Section 2.8.2, we consider a process

$$
Q=O():=b_{0} \stackrel{R}{\leftarrow} \text { bool } ; \text { return }() ; Q^{\prime}
$$

and let $Q_{L}=Q^{\prime}\left\{\right.$ true $\left./ b_{0}\right\}$ and $Q_{R}=Q^{\prime}\left\{\right.$ false $\left./ b_{0}\right\}$, so that $Q$ chooses a random bit $b_{0}$ and runs as $Q_{L}$ when $b_{0}$ is true and as $Q_{R}$ when $b_{0}$ is false. We assume that $Q_{L}$ and $Q_{R}$ never abort, that is, they contain neither event_abort nor find $\left[\right.$ unique $\left._{e}\right]$. Moreover, they do not use the variable $b_{0}$. We have the following lemmas.

Lemma 23 We assume that attackers in $\mathcal{B B}$ can at least represent probabilistic Turing machines. If $Q$ preserves the bit secrecy of $b_{0}$ with public variables $V$ up to probability $p$, then $Q_{L} \approx_{p^{\prime}}^{V, \emptyset} Q_{R}$ where $p^{\prime}\left(\mathcal{A}, C, t_{D}\right)=p\left(\mathcal{A}+C+t_{D}, C_{V}\right)$ for some attacker $\mathcal{A}+C+t_{D}$ and context $C_{V}$ such that the attacker $\mathcal{A}+C+t_{D}$ with context $C_{V}$ runs in time $t_{\mathcal{A}}+t_{C}+t_{D}$ and its other parameters (replication bounds, lengths of bitstrings) are the same as for $\mathcal{A}$ plus $C$.

The processes $Q_{L}$ and $Q_{R}$ can execute different events without breaking the bit secrecy of $b_{0}$, because the adversary for the bit secrecy of $b_{0}$ does not have access to the events executed by $Q$. Hence, $Q_{L} \approx_{p^{\prime}}^{V} Q_{R}$ would not hold in general.

Proof Let $\mathcal{A} \in \mathcal{B B}$ be an attacker. Let $C$ be any acceptable evaluation context for $Q_{L}$ and $Q_{R}$ with public variables $V$, and $D$ a distinguisher such that event $(D) \cap \operatorname{event}\left(Q_{L}, Q_{R}\right)=\emptyset$. Let $O$ and $O_{s}^{\prime \prime}$ be oracles that $C$ does not use.

Let $\mathcal{A}^{\prime}$ be an attacker that calls oracle $O$, runs $\mathcal{A}$ and $C$ but stores events executed by $C$ in its internal state instead of actually executing events, computes $D$ on the stored sequence of events executed by $C$, stores the result in $b_{0}^{\prime}$, and calls $O_{s}^{\prime \prime}\left(b_{0}^{\prime}\right)$. Such an attacker $\mathcal{A}^{\prime}$ exists because attackers in $\mathcal{B B}$ can at least represent probabilistic Turing machines. However, this attacker needs to be able to access the public variables in $V$. To this end, given a variable $x \in V$ with type $x:\left[1, n_{1}\right] \times \cdots \times\left[1, n_{m}\right] \rightarrow T$, we define the oracle definition $Q_{x}=$ foreach $i \leq$ $n$ do $O_{x}\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):=$ if defined $\left(x\left[u_{1}, \ldots, u_{m}\right]\right)$ then return $\left(x\left[u_{1}, \ldots, u_{m}\right]\right)$, with $n$ large enough so that it does not limit the number of queries that the attacker makes. Given a set of public variables $V=\left\{v_{1}, \ldots, v_{m}\right\}$, we then define the context $C_{V}=Q_{v_{1}}|\ldots| Q_{v_{m}} \mid[]$. Whenever $\mathcal{A}^{\prime}$ executes a part of $C$ that depends on some public variable, it uses the corresponding oracle to obtain the values inside the array. With such a construction, and without going into any formal details, the runtime of $t_{\mathcal{A}}+t_{C}+t_{D}$ is roughly equal to the runtime of $t_{\mathcal{A}^{\prime}}+t_{C_{V}}$. To formalize this statement, some care would need to be taken on how $\mathcal{A}^{\prime}$ can simulate the find constructs of $C$ by going through the full array by making many queries to oracles in $C_{V}$.

When $b_{0}$ is true, $Q \mid Q_{\text {bit secr. (x) }}$ run with attacker $\mathcal{A}^{\prime}$ and context $C_{V}$ stores in $b_{0}^{\prime}$ the result of $C\left[Q_{L}\right]: D$ run with attacker $\mathcal{A}$. When $b_{0}^{\prime}=$ true, S is executed. When $b_{0}^{\prime}=$ false, $\overline{\mathrm{S}}$ is executed. So

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}^{\prime}}\left[C_{V}\left[Q \mid Q_{\text {bit secr.(x) }}\right]: \mathrm{S} / b_{0}=\operatorname{true}\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{L}\right]: D\right] \\
& \operatorname{Pr}^{\mathcal{A}^{\prime}}\left[C_{V}\left[Q \mid Q_{\text {bit secr.(x) }}\right]: \overline{\mathrm{S}} / b_{0}=\text { true }\right]=1-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{L}\right]: D\right]
\end{aligned}
$$

When $b_{0}$ is false, $Q \mid Q_{\text {bit secr.(x) }}$ run with attacker $\mathcal{A}^{\prime}$ and context $C_{V}$ stores in $b_{0}^{\prime}$ the result of $C\left[Q_{R}\right]: D$ run with attacker $\mathcal{A}$. When $b_{0}^{\prime}=$ true, $\overline{\mathrm{S}}$ is executed. When $b_{0}^{\prime}=$ false, S is executed. So

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}^{\prime}}\left[C_{V}\left[Q \mid Q_{\text {bit secr. }(x)}\right]: \mathrm{S} / b_{0}=\text { false }\right]=1-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{R}\right]: D\right] \\
& \operatorname{Pr}^{\mathcal{A}^{\prime}}\left[C_{V}\left[Q \mid Q_{\text {bit secr. }(x)}\right]: \overline{\mathrm{S}} / b_{0}=\text { false }\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{R}\right]: D\right]
\end{aligned}
$$

Finally, we obtain

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}^{\prime}}\left[C_{V}\left[Q \mid Q_{\text {bit secr. }(x)}\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}^{\prime}}\left[C_{V}\left[Q \mid Q_{\text {bit secr. }(x)}\right]: \overline{\mathrm{S}}\right] \\
& \quad=\frac{1}{2}\left(\operatorname{Pr}\left[C\left[Q_{L}\right]: D\right]+1-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{R}\right]: D\right]-\left(1-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{L}\right]: D\right]\right)-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{R}\right]: D\right]\right) \\
& \quad=\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{L}\right]: D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{R}\right]: D\right]
\end{aligned}
$$

so $\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{L}\right]: D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{R}\right]: D\right] \leq p^{\prime}\left(\mathcal{A}, C, t_{D}\right)$. By negating the bit $b_{0}^{\prime}$, we swap the events S and $\overline{\mathrm{S}}$ without changing the probability, so $\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{R}\right]: D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{L}\right]: D\right] \leq p^{\prime}\left(\mathcal{A}, C, t_{D}\right)$. Therefore, $\left|\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{L}\right]: D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{R}\right]: D\right]\right| \leq p^{\prime}\left(\mathcal{A}, C, t_{D}\right)$. So $Q_{L} \approx_{p^{\prime}}^{V, \emptyset} Q_{R}$.

Lemma 23 is the main motivation for the notion of secrecy for a bit: it allows proving indistinguishability between two processes by showing secrecy of bit $b_{0}$. Using this notion instead of one-session secrecy of $b_{0}$ avoids losing a factor 2 , as shown by Lemma 22 ,

We use this idea to encode the diff construct originally introduced in ProVerif [30]: given a process $Q_{1}$ that contains terms diff $\left[M, M^{\prime}\right]$ and processes diff $\left[P, P^{\prime}\right]$, we define $\mathrm{fst}\left(\overline{Q_{1}}\right)$ as $Q_{1}$ with $\operatorname{diff}\left[M, M^{\prime}\right]$ replaced with $M$ and $\operatorname{snd}\left(Q_{1}\right)$ as $Q_{1}$ with $\operatorname{diff}\left[M, M^{\prime}\right]$ replaced with $M^{\prime}$, and similarly for diff $\left[P, P^{\prime}\right]$; the goal is to show that $\operatorname{fst}\left(Q_{1}\right) \approx_{p}^{V, \emptyset} \operatorname{snd}\left(Q_{1}\right)$ for some $p$ and determine
$p$. In order to do that, we define $Q^{\prime}$ as $Q_{1}$ with diff $\left[M, M^{\prime}\right]$ replaced with if fun $\left(b_{0}, M, M^{\prime}\right)$ when $M$ and $M^{\prime}$ are simple and with if $b_{0}$ then $M$ else $M^{\prime}$ otherwis $\left.{ }^{1}\right]$ diff $\left[P, P^{\prime}\right]$ replaced with if $b_{0}$ then $P$ else $P^{\prime}$, and $Q=O():=b_{0} \stackrel{R}{\leftarrow}$ bool; return ( $) ; Q^{\prime}$. We have $Q_{L}=Q^{\prime}\left\{\right.$ true $\left./ b_{0}\right\} \approx_{0}^{V, \emptyset}$ $\operatorname{fst}\left(Q_{1}\right)$ and $Q_{R}=Q^{\prime}\left\{\right.$ false $\left./ b_{0}\right\} \approx_{0}^{V, \emptyset} \operatorname{snd}\left(Q_{1}\right)$, so by Lemma 23 if $Q$ preserves the bit secrecy of $b_{0}$ with public variables $V$ up to probability $p$, then $\operatorname{fst}\left(Q_{1}\right) \approx_{p^{\prime}}^{, \emptyset} \operatorname{snd}\left(Q_{1}\right)$ where $p^{\prime}\left(\mathcal{A}, C, t_{D}\right)=$ $p\left(\mathcal{A}+C+t_{D}, C_{V}\right)$.

Lemma 24 If $Q_{L} \approx_{p}^{V, \emptyset} Q_{R}$ then $Q \approx_{p / 2}^{V \cup\left\{b_{0}\right\}, \emptyset} O():=b_{0} \stackrel{R}{\leftarrow}$ bool; return (); $Q_{R}$.
Proof Let $\mathcal{A} \in \mathcal{B B}$ be an attacker. Let $C$ be an evaluation context acceptable for $Q$ and $O():=b_{0} \stackrel{R}{\leftarrow}$ bool; return (); $Q_{R}$ with public variables $V \cup\left\{b_{0}\right\}$ and $D$ be a distinguisher. We have

$$
\begin{aligned}
& \mid \operatorname{Pr}^{\mathcal{A}} {[C[Q]: D]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=b_{0} \stackrel{R}{\leftarrow} \text { bool } ; \text { return }() ; Q_{R}\right]: D \mid\right.} \\
& \leq \left.\left.\frac{1}{2} \right\rvert\, \operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D / b_{0}=\text { true }\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=b_{0} \stackrel{R}{\leftarrow} \text { bool } ; \text { return }() ; Q_{R}\right]: D / b_{0}=\text { true }\right] \right\rvert\, \\
& \left.\left.+\frac{1}{2} \right\rvert\, \operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D / b_{0}=\text { false }\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=b_{0} \stackrel{R}{\leftarrow} \text { bool } ; \text { return }() ; Q_{R}\right]: D / b_{0}=\text { false }\right] \right\rvert\, \\
& \leq \left.\frac{1}{2} \right\rvert\, \operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=\text { let } b_{0}=\text { true in return }() ; Q_{L}\right]: D\right] \\
& \quad-\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=\text { let } b_{0}=\text { true in return }() ; Q_{R}\right]: D\right] \mid \\
& \leq \frac{1}{2} p\left(\mathcal{A}, C, t_{D}\right)
\end{aligned}
$$

Indeed, $\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=\right.\right.$ let $b_{0}=$ true in return ()$\left.\left.; Q_{L}\right]: D\right]=\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}\left[Q_{L}\right]: D\right]$ (and similarly for $\left.Q_{R}\right)$, where $C^{\prime \prime}=C\left[\right.$ newOracle $\widetilde{O}^{\prime} ;\left(F_{\widetilde{O}, \widetilde{O}^{\prime}} \mid\right.$ newOracle $\widetilde{O} ;\left(O():=\right.$ let $b_{0}=\operatorname{true}$ in return ()$\left.; F_{\widetilde{O^{\prime}}, \widetilde{O}}\right) \mid$ [])], $\widetilde{O}$ are the oracles at the root of $Q_{L}$ and $Q_{R}$ (they are not used elsewhere by Invariant 7 ), $\widetilde{O^{\prime}}$ are fresh oracles corresponding to oracles in $\widetilde{O}$, and $F_{\widetilde{O^{\prime}}, \widetilde{O}}$ forwards all oracle calls on an oracle in $\widetilde{O^{\prime}}$ to the corresponding oracle in $\widetilde{O}$, with the same replication bounds as in $Q_{\mathcal{O}_{L}}$ and $Q_{R}$. (All calls to oracles in $\widetilde{O}$ are forwarded to oracles in $\widetilde{O}^{\prime}$ and then back to oracles in $\widetilde{O}$ provided the code $O():=$ let $b_{0}=$ true in return () has already been executed. That prevents executing $Q_{L}$ or $Q_{R}$ before $O():=$ let $b_{0}=$ true in return ().) By Property 6 , replacing $C^{\prime \prime}$ with $C$ as argument of $p\left(C, t_{D}\right)$ does not affect the probability. (We neglect the additional runtime of $C^{\prime \prime}$.)

Lemma 25 is the converse of Lemma 23.
Lemma 25 If $Q_{L} \approx_{p}^{V, \emptyset} Q_{R}$, then $Q$ preserves the bit secrecy of $b_{0}$ with public variables $V$ up to probability $p^{\prime}$ where $p^{\prime}(\mathcal{A}, C)=p\left(\mathcal{A}, C\left[C_{\text {bit secr. }}\left(b_{0}\right)\right]\right.$, $\left.t_{\mathrm{S}}\right)$.

Proof If $Q_{L} \approx_{p}^{V, \emptyset} Q_{R}$, then by Lemma $24, Q \approx_{p / 2}^{V \cup\left\{b_{0}\right\}, \emptyset} O():=b_{0} \stackrel{R}{\leftarrow}$ bool; return (); $Q_{R}$. Moreover, $O():=b_{0} \stackrel{R}{\leftarrow}$ bool; return (); $Q_{R}$ preserves the bit secrecy of $b_{0}$ with public variables $V$ up to probability 0. (Since $Q_{R}$ does not use $b_{0}$, the variable $b^{\prime}$ in $Q_{\text {bit secr. ( } b_{0} \text { ) }}$ is independent of $b_{0}$, so a trace that executes S corresponds to a trace of the same probability and that executes $\overline{\mathrm{S}}$ by changing the value of $b_{0}$, so $\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=b_{0} \stackrel{R}{\leftarrow}\right.\right.$ bool; return ()$\left.\left.; Q_{R} \mid Q_{\text {bit secr. }\left(b_{0}\right)}\right]: \mathrm{S}\right]=$

[^1]$\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=b_{0} \stackrel{R}{\leftarrow}\right.\right.$ bool; return (); $\left.\left.Q_{R} \mid Q_{\text {bit secr. }\left(b_{0}\right)}\right]: \overline{\mathrm{S}}\right]$.) So by Lemma 21 (version for bit secrecy), $Q$ preserves the bit secrecy of $b_{0}$ with public variables $V$ up to probability $p^{\prime}$.

Lemma 26 provides a converse of Lemma 22 when $Q$ has the particular form given above. There is no probability loss in this case.

Lemma 26 We assume that attackers in $\mathcal{B B}$ can at least represent probabilistic Turing machines. If $Q$ preserves the bit secrecy of $b_{0}$ with public variables $V$ up to probability $p$, then $Q$ preserves the one-session secrecy of $b_{0}$ with public variables $V$ up to probability $p$.

Proof If $Q$ preserves the bit secrecy of $b_{0}$ with public variables $V$ up to probability $p$, then by Lemma 23. $Q_{L} \approx_{p^{\prime}}^{V, \emptyset} Q_{R}$ where $p^{\prime}\left(\mathcal{A}, C, t_{D}\right)=p\left(\mathcal{A}+C+t_{D}, C_{V}\right)$. By Lemma 24, $Q \approx_{p^{\prime} / 2}^{V \cup\left\{b_{0}\right\}, \emptyset}$ $O():=b_{0} \stackrel{R}{\leftarrow}$ bool; return ()$; Q_{R}$.

Moreover, $O():=b_{0} \stackrel{R}{\leftarrow}$ bool; return (); $Q_{R}$ preserves the one-session secrecy of $b_{0}$ with public variables $V$ up to probability 0 . Indeed, since $Q_{R}$ does not use $b_{0}, b_{0}$ can in fact be chosen in the test query in $Q_{\left.1 \text {-ses.secr.( } b_{0}\right)}$, so that test query always returns a random boolean, independently of the value of the variable $b$ of $Q_{1 \text {-ses.secr. }\left(b_{0}\right)}$. Therefore, the variable $b^{\prime}$ is independent of $b$, so a trace that executes $S$ corresponds to a trace of the same probability and that executes $\overline{\mathrm{S}}$ by changing the value of $b$, so $\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=b_{0} \stackrel{R}{\leftarrow}\right.\right.$ bool; return ()$\left.\left.; Q_{R} \mid Q_{\left.1 \text {-ses.secr.( } b_{0}\right)}\right]: \mathrm{S}\right]=$ $\operatorname{Pr}^{\mathcal{A}}\left[C\left[O():=b_{0} \stackrel{R}{\leftarrow}\right.\right.$ bool $;$ return ()$\left.\left.; Q_{R} \mid Q_{1 \text {-ses.secr. }\left(b_{0}\right)}\right]: \overline{\mathrm{S}}\right]$.

So by Lemma 21 (version for one-session secrecy), $Q$ preserves the one-session secrecy of $b_{0}$ with public variables $V$ up to probability $p^{\prime \prime}$ such that $p^{\prime \prime}(\mathcal{A}, C)=p^{\prime}\left(\mathcal{A}, C\left[C_{1 \text {-ses.secr. }\left(b_{0}\right)}\right], t_{\mathrm{S}}\right)=$ $p\left(\mathcal{A}+C\left[C_{1 \text {-ses.secr. }\left(b_{0}\right)}\right]+t_{\mathrm{s}}, C_{V}\right)$ which is about $p(\mathcal{A}, C)$ by Property 6 , neglecting the additional runtime of the context.

### 2.8.3 Correspondences

In this section, we define non-injective and injective correspondences.

Non-injective Correspondences A non-injective correspondence is a property of the form "if some events have been executed, then some other events have been executed at least once". Here, we generalize these correspondences to implications between logical formulas $\psi \Rightarrow \phi$, which may contain events. We use the following logical formulas:

```
\phi ::=
    M
    event(e(M}\mp@subsup{M}{1}{},\ldots,\mp@subsup{M}{m}{})
    \phi
    \phi
```

        formula
    term
    event
    conjunction
    disjunction
    Terms $M, M_{1}, \ldots, M_{m}$ in formulas must contain only variables $x$ without array indices and function applications, and their variables are assumed to be distinct from variables of processes. Formulas denoted by $\psi$ are conjunctions of events. In a correspondence $\psi \Rightarrow \phi$, the variables of $\psi$ are universally quantified; those of $\phi$ that do not occur in $\psi$ are existentially quantified. Formally:

Definition 9 The semantics of the correspondence $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$, also written $\widetilde{x}: \widetilde{T}, \widetilde{y}$ : $\widetilde{T}^{\prime} ; \psi \Rightarrow \phi$ in a less explicit syntax, is $\llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi \rrbracket=\llbracket \widetilde{x}: \widetilde{T}, \widetilde{y}: \widetilde{T}^{\prime} ; \psi \Rightarrow \phi \rrbracket=\forall \widetilde{x} \in$ $\widetilde{T},\left(\psi \Rightarrow \exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi\right)$, where $\widetilde{x}=\operatorname{var}(\psi)$ and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$.

The formula $M$ holds when $M$ evaluates to true. The formula event $\left(e\left(M_{1}, \ldots, M_{n}\right)\right)$ holds when the event $e\left(M_{1}, \ldots, M_{n}\right)$ has been executed. Conjunction, disjunction, implication, existential and universal quantifications are defined as usual. More formally, we write $\rho, \mathcal{E} v \vdash \varphi$ when the sequence of events $\mathcal{E} v$ satisfies the formula $\varphi$, in the environment $\rho$ that maps variables to their values. We define $\rho, \mathcal{E} v \vdash \varphi$ as follows:
$\rho, \mathcal{E} v \vdash M$ if and only if $\rho, M \Downarrow$ true
$\rho, \mathcal{E} v \vdash \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right)$ if and only if
for all $j \leq m, \rho, M_{j} \Downarrow a_{j}$ and $e\left(a_{1}, \ldots, a_{m}\right) \in \mathcal{E} v$
$\rho, \mathcal{E} v \vdash \varphi_{1} \wedge \varphi_{2}$ if and only if $\rho, \mathcal{E} v \vdash \varphi_{1}$ and $\rho, \mathcal{E} v \vdash \varphi_{2}$
$\rho, \mathcal{E} v \vdash \varphi_{1} \vee \varphi_{2}$ if and only if $\rho, \mathcal{E} v \vdash \varphi_{1}$ or $\rho, \mathcal{E} v \vdash \varphi_{2}$
$\rho, \mathcal{E} v \vdash \varphi_{1} \Rightarrow \varphi_{2}$ if and only if $\rho, \mathcal{E} v \vdash \varphi_{1}$ implies $\rho, \mathcal{E} v \vdash \varphi_{2}$
$\rho, \mathcal{E} v \vdash \exists x \in T, \varphi$ if and only if there exists $a \in T$ such that $\rho[x \mapsto a], \mathcal{E} v \vdash \varphi$
$\rho, \mathcal{E} v \vdash \forall x \in T, \varphi$ if and only if for every $a \in T$, we have $\rho[x \mapsto a], \mathcal{E} v \vdash \varphi$
When $\varphi$ is a closed formula, we write $\mathcal{E} v \vdash \varphi$ for $\rho, \mathcal{E} v \vdash \varphi$ where $\rho$ is the empty function.
Definition 10 The sequence of events $\mathcal{E} v$ satisfies the correspondence $\varphi$ if and only if $\mathcal{E} v \vdash \varphi$.
Definition 11 We define a distinguisher $D(\mathcal{E} v)=$ true if and only if $\mathcal{E} v \vdash \varphi$, and we denote this distinguisher $D$ simply by $\varphi$.

The advantage of the adversary $\mathcal{A}, C$ against the correspondence $\varphi$ in process $Q$ is $\operatorname{Adv}_{Q}^{\varphi}(\mathcal{A}$, $C)=\operatorname{Pr}^{\mathcal{A}}[C[Q]: \neg \varphi]$, where $C$ is an evaluation context acceptable for $Q$ with any public variables that does not contain events used by $\varphi$.

The process $Q$ satisfies the correspondence $\varphi$ with public variables $V$ up to probability $p$ if and only if for all evaluation contexts $C$ acceptable for $Q$ with public variables $V$ that do not contain events used by $\varphi$ and all $\mathcal{A} \in \mathcal{B B}, \operatorname{Adv}_{Q}^{\varphi}(\mathcal{A}, C) \leq p(\mathcal{A}, C)$.

When $s p$ is a correspondence $\varphi$, we define $C_{s p}=[]$ and the events used by $s p$ are the events that occur in the formula $\varphi$. Therefore, the definition of " $Q$ satisfies the correspondence $\varphi$ " matches the definition of " $Q$ satisfies $s p$ " given in Definition 7 .

A process satisfies $\varphi$ up to probability $p$ when the probability that it generates a sequence of events $\mathcal{E} v$ that does not satisfy $\varphi$ is at most $p(\mathcal{A}, C)$, in the presence of an adversary represented by the attacker $\mathcal{A}$ and the context $C$.

Example 2 The semantics of the correspondence

$$
\begin{equation*}
\forall x: p k e y, y: h o s t, z: n o n c e ; \operatorname{event}\left(e_{B}(x, y, z)\right) \Rightarrow \operatorname{event}\left(e_{A}(x, y, z)\right) \tag{4}
\end{equation*}
$$

is

$$
\begin{equation*}
\forall x \in \text { pkey, } \forall y \in h o s t, \forall z \in \text { nonce, }, \operatorname{event}\left(e_{B}(x, y, z)\right) \Rightarrow \operatorname{event}\left(e_{A}(x, y, z)\right) \tag{5}
\end{equation*}
$$

It means that, with overwhelming probability, for all $x, y, z$, if $e_{B}(x, y, z)$ has been executed, then $e_{A}(x, y, z)$ has been executed.

The semantics of the correspondence

$$
\begin{aligned}
& \forall x: T ; \text { event }\left(e_{1}(x)\right) \wedge \operatorname{event}\left(e_{2}(x)\right) \Rightarrow \\
& \quad \exists y: T^{\prime} ; \operatorname{event}\left(e_{3}(x)\right) \vee\left(\operatorname{event}\left(e_{4}(x, y)\right) \wedge \operatorname{event}\left(e_{5}(x, y)\right)\right)
\end{aligned}
$$

is

$$
\begin{aligned}
& \forall x \in T, \text { event }\left(e_{1}(x)\right) \wedge \operatorname{event}\left(e_{2}(x)\right) \Rightarrow \\
& \quad \exists y \in T^{\prime}, \operatorname{event}\left(e_{3}(x)\right) \vee\left(\operatorname{event}\left(e_{4}(x, y)\right) \wedge \operatorname{event}\left(e_{5}(x, y)\right)\right)
\end{aligned}
$$

It means that, with overwhelming probability, for all $x$, if $e_{1}(x)$ and $e_{2}(x)$ have been executed, then $e_{3}(x)$ has been executed or there exists $y$ such that both $e_{4}(x, y)$ and $e_{5}(x, y)$ have been executed.

Injective Correspondences Injective correspondences are properties of the form "if some event has been executed $n$ times, then some other events have been executed at least $n$ times". In order to model them in our logical formulas, we extend the grammar of formulas $\phi$ with injective events $\operatorname{inj}$-event $\left(e\left(M_{1}, \ldots, M_{m}\right)\right)$. The formula $\psi$ is a conjunction of (injective or noninjective) events. The conditions on the number of executions of events apply only to injective events.

The definition of formula satisfaction is also extended, to be able to indicate at which step an event has been executed (that is, at which index it appears in $\mathcal{E} v$ ): event $(e(\widetilde{M})) @ \tau$ means that event $e(\widetilde{M})$ has been executed at step $\tau$. Formally:
$\rho, \mathcal{E} v \vdash \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ M_{0}$ if and only if
for all $j \leq m, \rho, M_{j} \Downarrow a_{j}, a_{0} \neq \perp$, and $e\left(a_{1}, \ldots, a_{m}\right)=\mathcal{E} v\left(a_{0}\right)$
With this definition, we have:
Definition 12 The semantics of the correspondence $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$, also written $\widetilde{x}$ : $\widetilde{T}, \widetilde{y}: \widetilde{T}^{\prime} ; \psi \Rightarrow \phi$ in a less explicit syntax, is

$$
\begin{aligned}
& \llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi \rrbracket=\llbracket \widetilde{x}: \widetilde{T}, \widetilde{y}: \widetilde{T}^{\prime} ; \psi \Rightarrow \phi \rrbracket=\exists f_{1}, \ldots, f_{k} \in \mathbb{N}^{m} \times \prod \widetilde{T} \rightarrow \mathbb{N} \cup\{\perp\}, \\
& \quad \operatorname{Inj}\left(I, f_{1}\right) \wedge \cdots \wedge \operatorname{Inj}\left(I, f_{k}\right) \wedge \forall \tau_{1}, \ldots, \tau_{m} \in \mathbb{N}, \forall \widetilde{x} \in \widetilde{T},\left(\psi^{\tau} \Rightarrow \exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi^{\tau}\right),
\end{aligned}
$$

where $\widetilde{x}=\operatorname{var}(\psi), \widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi), \psi=F_{1} \wedge \cdots \wedge F_{m}, \psi^{\tau}=F_{1}^{\tau} \wedge \cdots \wedge F_{m}^{\tau}, F_{j}^{\tau}=$ $\operatorname{event}(e(\widetilde{M})) @ \tau_{j}$ if $F_{j}=\operatorname{event}(e(\widetilde{M}))$ or $F_{j}=\operatorname{inj}$-event $(e(\widetilde{M})), I=\left\{j \mid F_{j}=\operatorname{inj}\right.$-event $\left.(\ldots)\right\}, \phi^{\tau}$ is obtained from $\phi$ by replacing each injective event inj-event $(e(\widetilde{M}))$ with event $(e(\widetilde{M})) @ f_{j}\left(\tau_{1}\right.$, $\left.\ldots, \tau_{m}, \widetilde{x}\right)$ using a distinct function $f_{j}$ for each injective event in $\phi^{\tau}$, and $\operatorname{Inj}(I, f)$ if and only if $f\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right)=f\left(\tau_{1}^{\prime}, \ldots, \tau_{m}^{\prime}, \widetilde{x}^{\prime}\right) \neq \perp \Rightarrow \forall j \in I, \tau_{j}=\tau_{j}^{\prime}$.

In $\psi^{\tau}$ and $\phi^{\tau}$, events are labeled with their associated execution step, $\tau_{j}$ for the events in $\psi^{\tau}$ and $f_{j}\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right)$ for the injective events in $\phi^{\tau}$. Therefore, the functions $f_{j}$ map the execution steps of events in $\psi, \tau_{1}, \ldots, \tau_{m}$, and the values of the variables in $\psi, \widetilde{x}$, to the associated execution steps of injective events in $\phi$. (The result $\perp$ corresponds to the case in which the event in $\phi$ is not executed: in case of disjunctions, not all events in $\phi$ are required to be executed.) The correspondence is injective when these functions $f_{j}$ are injective in their arguments that correspond to injective events in $\psi$. The indices of injective events in $\psi$ are collected in the set $I$, and injectivity is guaranteed by $\operatorname{Inj}\left(I, f_{j}\right)$, which means that, ignoring the result $\perp, f_{j}$ is injective in its arguments of indices in $I$.

Definition 11 is unchanged for injective correspondences.
Example 3 The semantics of the correspondence

$$
\begin{equation*}
\forall x: \text { pkey, } y: \text { host, } z: \text { nonce } ; \operatorname{inj} \text {-event }\left(e_{B}(x, y, z)\right) \Rightarrow \operatorname{inj-event}\left(e_{A}(x, y, z)\right) \tag{6}
\end{equation*}
$$

is

$$
\begin{align*}
& \exists f \in \mathbb{N} \times \text { pkey } \times \text { host } \times \text { nonce } \rightarrow \mathbb{N} \cup\{\perp\}, \operatorname{Inj}(\{1\}, f) \wedge \\
& \forall \tau \in \mathbb{N}, \forall x \in \text { pkey, } \forall y \in \text { host }, \forall z \in \text { nonce },  \tag{7}\\
& \quad \text { event }\left(e_{B}(x, y, z)\right) @ \tau \Rightarrow \operatorname{event}\left(e_{A}(x, y, z)\right) @ f(\tau, x, y, z)
\end{align*}
$$

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It means that, with overwhelming probability, each execution of $e_{B}(x, y, z)$ corresponds to a distinct execution of $e_{A}(x, y, z)$. In this case, $f$ is a function that maps the execution step $\tau$ of $e_{B}(x, y, z)$ and the variables $x, y, z$ to the execution step of $e_{A}(x, y, z)$. (This step is never म.) This function is injective in its first argument, the step $\tau$, so if there are $n$ executions of $e_{B}(x, y, z)$, at steps $\tau_{1}, \ldots, \tau_{n}$, then there are at least $n$ executions of $e_{A}(x, y, z)$, at steps $f\left(\tau_{1}, x, y, z\right), \ldots, f\left(\tau_{n}, x, y, z\right)$ and these steps are distinct by injectivity of $f$ in its first argument.

The semantics of the correspondence

$$
\begin{aligned}
\forall x: & T ; \operatorname{event}\left(e_{1}(x)\right) \wedge \operatorname{inj}-\operatorname{event}\left(e_{2}(x)\right) \Rightarrow \exists y: T^{\prime} ; \operatorname{inj}-\text { event }\left(e_{3}(x)\right) \vee \\
& \left(\operatorname{inj}-\operatorname{event}\left(e_{4}(x, y)\right) \wedge \operatorname{inj-event}\left(e_{5}(x, y)\right)\right)
\end{aligned}
$$

is

$$
\begin{aligned}
& \exists f_{1}, f_{2}, f_{3} \in \mathbb{N}^{2} \times T \rightarrow \mathbb{N} \cup\{\perp\}, \operatorname{Inj}\left(\{2\}, f_{1}\right) \wedge \operatorname{Inj}\left(\{2\}, f_{2}\right) \wedge \operatorname{Inj}\left(\{2\}, f_{3}\right) \wedge \\
& \forall \tau_{1}, \tau_{2} \in \mathbb{N}, \forall x \in T, \operatorname{event}\left(e_{1}(x)\right) @ \tau_{1} \wedge \operatorname{event}\left(e_{2}(x)\right) @ \tau_{2} \Rightarrow \exists y \in T^{\prime}, \text { event }\left(e_{3}(x)\right) @ f_{1}\left(\tau_{1}, \tau_{2}, x\right) \vee \\
& \quad\left(\operatorname{event}\left(e_{4}(x, y)\right) @ f_{2}\left(\tau_{1}, \tau_{2}, x\right) \wedge \operatorname{event}\left(e_{5}(x, y)\right) @ f_{3}\left(\tau_{1}, \tau_{2}, x\right)\right)
\end{aligned}
$$

It means that, with overwhelming probability, for all $x$, if $e_{1}(x)$ has been executed, then each execution of $e_{2}(x)$ corresponds to distinct executions of $e_{3}(x)$ or to distinct executions of $e_{4}(x, y)$ and $e_{5}(x, y)$. The functions $f_{1}, f_{2}$, and $f_{3}$ map the execution steps $\tau_{1}$ and $\tau_{2}$ of $e_{1}$ and $e_{2}$ and the variable $x$ to the execution steps of $e_{3}, e_{4}$, and $e_{5}$ respectively. Ignoring the result $\perp$, they are injective in their second argument, which corresponds to the execution step of the injective event $e_{2}$.

When no injective event occurs in $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$, Definition 12 reduces to the definition of non-injective correspondences: there are no functions $f_{j}, \phi^{\tau}=\phi$, and event $(e(\widetilde{M})) @ \tau$ holds for some $\tau$ if and only if $\operatorname{event}(e(\widetilde{M}))$ holds, so $\psi^{\tau}$ holds for some $\tau_{1}, \ldots, \tau_{m}$ if and only if $\psi$ holds.

Well-formedness condition When we consider a correspondence $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T} ; \phi$, with $\widetilde{x}=\operatorname{var}(\psi)$ and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$, we should have

$$
\begin{equation*}
\forall \widetilde{x} \in \widetilde{T}, \forall \widetilde{x}^{\prime} \in \widetilde{T}, \forall \widetilde{y} \in \widetilde{T}^{\prime}, \psi=\psi\left\{\widetilde{x}^{\prime} / \widetilde{x}\right\} \Rightarrow \phi=\phi\left\{\widetilde{x}^{\prime} / \widetilde{x}\right\} \tag{8}
\end{equation*}
$$

where $\widetilde{x}^{\prime}$ are fresh variables, and the equality of terms is the equality of their values, but disjunctions, conjunctions, and events are considered syntactically. This condition guarantees that, given an execution of events in $\psi$, the formula to verify $\exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi^{\tau}$ is uniquely determined. It avoids pathological correspondences such as

$$
\begin{equation*}
\forall x: T ; \operatorname{event}\left(e(f(x)) \Rightarrow \operatorname{event}\left(e^{\prime}(x)\right)\right. \tag{9}
\end{equation*}
$$

with $f(a)=f(b)=c$, for which event $(e(c))$ corresponds to both event $(e(f(a))$ and event $(e(f(b))$, so when event $e(c)$ is executed, $x$ can take both values $a$ and $b$, so (9) requires the execution of events $e^{\prime}(a)$ and $e^{\prime}(b)$. An even more pathological case is when $f(x)=c$ for all $x$ : in this case, when event $e(c)$ is executed, (9) requires the execution of event $e^{\prime}(x)$ for all $x \in T$, which is impossible when $T$ is infinite. However, the condition allows the correspondence (9) when $f$ is injective, so $x$ is uniquely determined, and it also allows the correspondences

$$
\begin{equation*}
\forall x: T ; \operatorname{event}(e(f(x)) \Rightarrow \text { false } \tag{10}
\end{equation*}
$$

and

$$
\begin{equation*}
\forall x: T ; \operatorname{event}\left(e(f(x)) \Rightarrow \operatorname{event}\left(e^{\prime}(f(x))\right)\right. \tag{11}
\end{equation*}
$$

for any function $f$ : 10 requires that event $e(y)$ is never executed with $y$ in the image of $f$, and (11) requires that $e^{\prime}(y)$ is executed when $e(y)$ is executed with $y$ in the image of $f$.

CryptoVerif displays a warning when it does not manage to prove the well-formedness condition (8).

## Property

Lemma 27 If $Q$ satisfies a correspondence $\varphi$ with public variables $V$ up to probability $p$ and $C$ is an acceptable evaluation context for $Q$ with public variables $V$ that does not contain events used in $\varphi$, then for all $V^{\prime} \subseteq V \cup \operatorname{var}(C), C[Q]$ satisfies a correspondence $\varphi$ with public variables $V^{\prime}$ up to probability $p^{\prime}$ such that $p^{\prime}\left(\mathcal{A}, C^{\prime}\right)=p\left(\mathcal{A}, C^{\prime}[C]\right)$.

If $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}, Q$ satisfies a correspondence $\varphi$ with public variables $V$ up to probability $p^{\prime}$, and $\mathcal{E}$ contains all events in $\varphi$, then $Q^{\prime}$ satisfies $\varphi$ with public variables $V$ up to probability $p^{\prime \prime}$ such that $p^{\prime \prime}(\mathcal{A}, C)=p^{\prime}(\mathcal{A}, C)+p\left(\mathcal{A}, C, t_{\varphi}\right)$.

Proof Suppose that $Q$ satisfies a correspondence $\varphi$ with public variables $V, \mathcal{A} \in \mathcal{B B}$ is an attacker, and $C$ is an acceptable evaluation context for $Q$ with public variables $V$ that does not contain events used in $\varphi$. Let $V^{\prime} \subseteq V \cup \operatorname{var}(C)$. Let $C^{\prime}$ be an evaluation context acceptable for $C[Q]$ with public variables $V^{\prime}$ that does not contain events used by $\varphi$. We rename the variables of $C^{\prime}$ not in $V^{\prime}$ so that they are not in $V$; by Property 6, this renaming does not change the probabilities. We have

$$
\operatorname{Adv}_{C[Q]}^{\varphi}\left(\mathcal{A}, C^{\prime}\right)=\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}[C[Q]]: \neg \varphi\right] \leq p\left(\mathcal{A}, C^{\prime}[C]\right)
$$

because $C^{\prime}[C]$ is an evaluation context acceptable for $Q$ with public variables $V$ : there is no common table between $C$ and $Q$, and between $C^{\prime}$ and $C[Q]$, so a fortiori between $C^{\prime}$ and $Q$, so there is no common table between $C^{\prime}[C]$ and $Q$; moreover

$$
\begin{array}{rlrl}
\operatorname{var}\left(C^{\prime}[C]\right) \cap \operatorname{var}(Q) & =\left(\left(\operatorname{var}\left(C^{\prime}\right) \cap \operatorname{var}(Q)\right) \cup \operatorname{var}(C)\right) \cap \operatorname{var}(Q) \\
& \subseteq\left(V^{\prime} \cup \operatorname{var}(C)\right) \cap \operatorname{var}(Q) & \text { since } \operatorname{var}\left(C^{\prime}\right) \cap \operatorname{var}(C[Q]) \subseteq V^{\prime} \\
& \subseteq(V \cup \operatorname{var}(C)) \cap \operatorname{var}(Q) & \text { since } V^{\prime} \subseteq V \cup \operatorname{var}(C) \\
& \subseteq V & \text { since } \operatorname{var}(C) \cap \operatorname{var}(Q) \subseteq V
\end{array}
$$

We also have vardef $\left(C^{\prime}[C[]]\right) \cap V=\left(\operatorname{vardef}\left(C^{\prime}\right) \cap V\right) \cup(\operatorname{vardef}(C) \cap V)=\emptyset$ since vardef $(C) \cap V=\emptyset$ because $C$ is an acceptable evaluation context for $Q$ with public variables $V$ and vardef $\left(C^{\prime}\right) \cap V \subseteq$ vardef $\left(C^{\prime}\right) \cap V^{\prime}=\emptyset$ because we have renamed the variables of $C^{\prime}$ not in $V^{\prime}$ so that they are not in $V$ and $C^{\prime}$ is an acceptable evaluation context for $C[Q]$ and with public variables $V^{\prime}$.

Suppose that $Q \approx_{p}^{V, \mathcal{E}} Q^{\prime}, Q$ satisfies a correspondence $\varphi$ with public variables $V$ up to probability $p^{\prime}$, and $\mathcal{E}$ contains all events in $\varphi$. Let $\mathcal{A} \in \mathcal{B B}$ be an attacker. Let $C$ be an evaluation context acceptable for $Q^{\prime}$ with public variables $V$ that does not contain events used by $\varphi$. We have

$$
\begin{aligned}
\operatorname{Adv}_{Q^{\prime}}^{\varphi}(\mathcal{A}, C) & =\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: \neg \varphi\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}[C[Q]: \neg \varphi]+\left|\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]: \neg \varphi\right]-\operatorname{Pr}^{\mathcal{A}}[C[Q]: \neg \varphi]\right| \\
& \leq p^{\prime}(\mathcal{A}, C)+p\left(\mathcal{A}, C, t_{\varphi}\right)
\end{aligned}
$$

Indeed, by renaming the variables and tables of $C$ that do not appear in $Q^{\prime}$ to variables and tables that also do not occur in $Q, C$ is also an acceptable evaluation context for $Q$ with public variables $V$. Furthermore, by Property 6, this renaming does not change the probabilities.

Reachability secrecy Reachability secrecy aims to show that the adversary cannot compute the secret value. This notion is standard in the symbolic model, but less common than the notion of secrecy as "the adversary cannot distinguish the secret from a random value" (Section 2.8.1) in the computational model. It is still used, e.g. in the property of one-wayness or in the computational Diffie-Hellman assumption.

This notion makes sense only when the secret value is of a large type. Otherwise, the adversary would have a non-negligible probability of finding the secret value just by random guessing.

This notion is in fact encoded as a correspondence property. We distinguish two variants. One-session reachability secrecy of $x$ means that the adversary cannot compute any cell of array $x$, even if it has access to the public variables in $V$. Reachability secrecy of $x$ means that the adversary cannot compute any cell of array $x$, even if it has access to the other cells of $x$ and to the public variables in $V$.

Definition 13 ((One-session) reachability secrecy) Let $Q$ be a process, $x$ a variable, and $V$ a set of variables. Let

$$
\begin{aligned}
Q_{1 \text {-ses.reach.secr. }(x)}= & \text { foreach } i_{t} \leq n_{t} \text { do } O_{s}\left[i_{t}\right]\left(x^{\prime}: T, u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):= \\
& \text { if defined }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \wedge x^{\prime}=x\left[u_{1}, \ldots, u_{m}\right] \text { then event adv_has_x } \\
Q_{\text {Reach.secr. }(x)}= & \text { foreach } i_{r} \leq n_{r} \text { do } O_{r}\left[i_{r}\right]\left(u_{1}^{\prime}:\left[1, n_{1}\right], \ldots, u_{m}^{\prime}:\left[1, n_{m}\right]\right):= \\
& \text { if defined }\left(x\left[u_{1}^{\prime}, \ldots, u_{m}^{\prime}\right]\right) \text { then } \\
& \text { let reveal }: \text { bool }=\operatorname{true} \text { in return }\left(x\left[u_{1}^{\prime}, \ldots, u_{m}^{\prime}\right]\right) \\
\mid & \text { foreach } i_{t} \leq n_{t} \text { do } O_{s}\left[i_{t}\right]\left(x^{\prime}: T, u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):= \\
& \text { find } i \leq i_{r} \text { suchthat defined }\left(\text { reveal }[i], u_{1}^{\prime}[i], \ldots, u_{m}^{\prime}[i]\right) \wedge \\
& u_{1}^{\prime}[i]=u_{1} \wedge \cdots \wedge u_{m}^{\prime}[i]=u_{m} \text { then yield else } \\
& \text { if defined }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \wedge x^{\prime}=x\left[u_{1}, \ldots, u_{m}\right] \text { then event adv_has_x }
\end{aligned}
$$

where $O_{s}, O_{r} \notin \mathrm{fo}(Q), x^{\prime}, u_{1}, \ldots, u_{m}, u_{1}^{\prime}, \ldots, u_{m}^{\prime}$, reveal $\notin \operatorname{var}(Q) \cup V$, adv_has_x does not occur in $Q$, and $\mathcal{E}(x)=\left[1, n_{1}\right] \times \ldots \times\left[1, n_{m}\right] \rightarrow T$.

The process $Q$ satisfies one-session reachability secrecy of $x$ with public variables $V(x \notin V)$ up to probability $p$ if and only if the process $Q \mid Q_{1 \text {-ses.reach.secr.(x) }}$ satisfies the correspondence event $($ adv_has_x $) \Rightarrow$ false with public variables $V$ up to probability $p$.

The process $Q$ satisfies reachability secrecy of $x$ with public variables $V(x \notin V)$ up to probability $p$ if and only if $Q \mid Q_{\text {Reach.secr.(x) }}$ satisfies the correspondence event(adv_has_x) $\Rightarrow$ false with public variables $V$ up to probability $p$.

The process $Q_{1 \text {-ses.reach.secr. }(x)}$ waits for a call to oracle $O_{s}\left[i_{t}\right]$ with a candidate value $x^{\prime}$ and indices $u_{1}, \ldots, u_{m}$. If $x\left[u_{1}, \ldots, u_{m}\right]$ is defined and equal to $x^{\prime}$, the adversary managed to compute $x\left[u_{1}, \ldots, u_{m}\right]$, hence to break one-session reachability secrecy. In this case, we execute event adv_has_x, and our goal will be to bound the probability of this event, by showing the correspondence event(adv_has_x) $\Rightarrow$ false.

The process $Q_{\text {Reach.secr. }(x)}$ additionally provides a reveal query: by calling oracle $O_{r}\left[i_{r}\right]$ with indices $u_{1}^{\prime}, \ldots, u_{m}^{\prime}$, the adversary can obtain the value of $x\left[u_{1}^{\prime}, \ldots, u_{m}^{\prime}\right]$ if it is defined. Obviously, the adversary breaks reachability secrecy if it computes $x\left[u_{1}, \ldots, u_{m}\right]$ without having first made a successful reveal query on the indices $u_{1}, \ldots, u_{m}$. The absence of such a reveal query is verified by find $i \leq i_{r} \ldots$ before executing event adv_has_x.

The bounds on the number of queries $\left(n_{t}, n_{r}\right)$ are chosen large enough that they do not limit the adversary.

### 2.8.4 Computation of Advantages

Definition 14 Let $s p$ be a security property: $s p$ is 1 -ses.secr. $(x)$, Secrecy $(x)$, bit secr. $(x)$, or a trace property, represented by any distinguisher that does not use $S, \overline{\mathrm{~S}}$, nor non-unique events. (Trace properties include correspondences $\varphi$, as well as true, the property that is always true.) Let $D$ be a disjunction of Shoup and non-unique events that does not contain S nor $\overline{\mathrm{S}}$. Let $C$ be an evaluation context acceptable for $Q$ with any public variables and $\mathcal{A}$ an attacker in $\mathcal{B B}$.

When $s p$ is a trace property, we define $V_{s p}=\emptyset$ and

$$
\begin{equation*}
\operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D)=\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:(\neg s p \vee D) \wedge \neg \text { NonUnique }_{Q, D}\right] \tag{12}
\end{equation*}
$$

When $s p$ is 1-ses.secr. $(x)$, Secrecy $(x)$, or bit secr. $(x)$, we define $V_{s p}=\{x\}$ and

$$
\begin{equation*}
\operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D)=\operatorname{Pr}^{\mathcal{A}}[C[Q]: \mathrm{S} \vee D]-\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee \text { NonUnique }_{Q, D}\right] \tag{13}
\end{equation*}
$$

We write $\operatorname{Bound}_{Q}(V, s p, D, p)$ when $V_{s p} \subseteq V$ and for all $\mathcal{A} \in \mathcal{B B}$, for all evaluation contexts $C^{\prime}$ acceptable for $C_{s p}[Q]$ with public variables $V \backslash V_{s p}$ that does not contain events used by $s p$ or $D$ nor non-unique events in $Q$, we have $\operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D) \leq p(\mathcal{A}, C)$ for $C=C^{\prime}\left[C_{s p}[]\right]$.

The events S and $\overline{\mathrm{S}}$ are only executed by event_abort. In (13), we could write $(\mathrm{S} \vee D) \wedge$ $\neg$ NonUnique $_{Q, D}$ instead of $\mathrm{S} \vee D$, to be more similar to 12 . That would be equivalent because the game immediately aborts after executing $S$ as well as events in $D$ and in NonUnique ${ }_{Q, D}$, so only one of these events is executed. In 13], we expect that $C=C^{\prime}\left[C_{s p}[]\right]$ for some context $C^{\prime}$. This is what happens in the definition of $\operatorname{Bound}_{Q}(V, s p, D, p)$. In that definition, $C$ is a context acceptable for $Q$ with public variables $V$.

Lemma 28 1. In the initial game $Q$, let $D_{U}=\bigvee\left\{e \mid\left[\right.\right.$ unique $\left._{e}\right]$ occurs in $\left.Q\right\}=$ NonUnique $_{Q}$. If $\operatorname{Bound}_{Q}\left(V, s p, D_{U}, p\right)$, then $Q$ satisfies property sp with public variables $V \backslash V_{s p}$ up to probability $p^{\prime}$ where $p^{\prime}\left(\mathcal{A}, C^{\prime}\right)=p\left(\mathcal{A}, C^{\prime}\left[C_{s p}[]\right]\right)$.
2. If $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}{ }_{p} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$, the events S and $\overline{\mathrm{S}}$ are not in EvUsed ${ }^{\prime}$, $\operatorname{Bound}_{Q^{\prime}}\left(V, s p, D^{\prime}, p^{\prime}\right)$, and

- either $s p$ is a trace property, $\neg s p \in \mathcal{D}$, and $p^{\prime \prime}(\mathcal{A}, C)=p\left(\mathcal{A}, C, t_{\neg s p}\right)+p^{\prime}(\mathcal{A}, C)$;
- or sp is 1 -ses.secr. $(x)$, Secrecy $(x)$, or bit secr. $(x),\{\mathrm{S}, \neg \overline{\mathrm{S}}\} \subseteq \mathcal{D}$, and $p^{\prime \prime}(\mathcal{A}, C)=$ $2 p\left(\mathcal{A}, C, t_{\mathrm{s}}\right)+p^{\prime}(\mathcal{A}, C)$
then $\operatorname{Bound}_{Q}\left(V, s p, D, p^{\prime \prime}\right)$.

3. Let $D$ and $D^{\prime}$ be disjunctions of Shoup and non-unique events that do not contain S nor $\overline{\mathrm{S}}$.

- If sp is a trace property, $\operatorname{Bound}_{Q}(V, s p, D, p)$, and $\operatorname{Bound}_{Q}\left(V\right.$, true, $\left.D^{\prime}, p^{\prime}\right)$, then we have Bound $_{Q}\left(V, s p, D \vee D^{\prime}, p+p^{\prime}\right)$.
- If sp is 1 -ses.secr. $(x)$, Secrecy $(x)$, or bit secr. $(x), D_{\mathrm{NU}}^{\prime}=\bigvee\left\{e \mid e\right.$ occurs in $D^{\prime}$ and $e$ is a non-unique event $\}, \operatorname{Bound}_{Q}(V, s p, D, p), \operatorname{Bound}_{Q}\left(V, \operatorname{true}, D^{\prime}, p^{\prime}\right)$, and $\operatorname{Bound}_{Q}(V$, true, $\left.D_{\mathrm{NU}}^{\prime}, p^{\prime \prime}\right)$, then $\mathrm{Bound}_{Q}\left(V, s p, D \vee D^{\prime}, p+p^{\prime}+p^{\prime \prime}\right)$.

4. If $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}_{p} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$, the distinguisher $D^{\prime \prime}$ is a disjunction of Shoup and non-unique events in EvUsed that does not contain S nor $\overline{\mathrm{S}}$, and Bound $_{Q}(V$, true, $\left.D^{\prime \prime}, p^{\prime}\right)$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D \vee D^{\prime \prime}$, EvUsed ${ }^{V}{ }_{p+p^{\prime}} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$.

Proof Property 1. We have NonUnique ${ }_{Q, D_{U}}=D_{\text {false }}$. Let $\mathcal{A}$ be an attacker in $\mathcal{B B}$ and $C^{\prime}$ be an evaluation context acceptable for $C_{s p}[Q]$ with public variables $V \backslash V_{s p}$ that does not contain events used by $s p$, and $C=C^{\prime}\left[C_{s p}[]\right]$. Since $\operatorname{Bound}_{Q}\left(V, s p, D_{U}, p\right)$, we have $\operatorname{Adv}_{Q}\left(\mathcal{A}, C, s p, D_{U}\right) \leq$ $p(\mathcal{A}, C)$.

- In case $s p$ is a trace property, $\operatorname{Adv}_{Q}^{s p}\left(\mathcal{A}, C^{\prime}\right)=\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}[Q]: \neg s p\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}[Q]: \neg s p \vee D_{U}\right]=$ $\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C_{s p}[Q]\right]: \neg s p \vee D_{U}\right]=\operatorname{Adv}_{Q}\left(\mathcal{A}, C^{\prime}\left[C_{s p}[]\right], s p, D_{U}\right)$.
- In case $s p$ is 1-ses.secr. $(x)$, $\operatorname{Secrecy}(x)$, or bit secr. $(x), \operatorname{Adv}_{Q}^{s p}\left(\mathcal{A}, C^{\prime}\right)=\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C_{s p}[Q]\right]: \mathrm{S}\right]-$ $\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C_{s p}[Q]\right]: \overline{\mathrm{S}}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C_{s p}[Q]\right]: \mathrm{S} \vee D_{U}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[C_{s p}[Q]\right]: \overline{\mathrm{S}}\right]=\operatorname{Adv}_{Q}\left(\mathcal{A}, C^{\prime}\left[C_{s p}[]\right]\right.$, $\left.s p, D_{U}\right)$.

In both cases, $\operatorname{Adv}_{Q}^{s p}\left(\mathcal{A}, C^{\prime}\right) \leq \operatorname{Adv}_{Q}\left(\mathcal{A}, C^{\prime}\left[C_{s p}[]\right], s p, D_{U}\right)=\operatorname{Adv}_{Q}\left(\mathcal{A}, C, s p, D_{U}\right) \leq p(\mathcal{A}, C)=$ $p^{\prime}\left(\mathcal{A}, C^{\prime}\right)$, so $Q$ satisfies property $s p$ with public variables $V \backslash V_{s p}$ up to probability $p^{\prime}$.

Property 2, case $s p$ is a trace property: Let $\mathcal{A}$ be an attacker in $\mathcal{B B}$ and $C$ be an evaluation context acceptable for $Q$ with public variables $V$ that does not contain events used by $s p$ nor $D$ nor non-unique events of $Q$. Let $C^{\prime}$ be obtained by renaming the variables and tables of $C$ that do not occur in $Q$ to variables and tables that also do not occur in $Q^{\prime}$, and by renaming the events of $C$ so that they are not in EvUsed ${ }^{\prime}$. The context $C^{\prime}$ is then acceptable for $Q$ and $Q^{\prime}$ with public variables $V$ and does not contain events in EvUsed ${ }^{\prime}$. Since $\mathcal{D}, \mathcal{D}_{\text {SNU }}: Q, D$, EvUsed $\xrightarrow{V}_{p}$ $Q^{\prime}, D^{\prime}, E v U s e d^{\prime}$ and $\neg s p \in \mathcal{D}$, we have by taking $D_{1}=D_{\text {false }}$,

$$
\begin{aligned}
\operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D) & =\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:(\neg s p \vee D) \wedge \neg \text { NonUnique }_{Q, D}\right] \\
& =\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}[Q]:(\neg s p \vee D) \wedge \neg \text { NonUnique }_{Q, D}\right]
\end{aligned}
$$

since the renaming of events does not affect the events of the distinguisher

$$
\begin{array}{lr}
\leq p\left(\mathcal{A}, C^{\prime}, t_{\neg s p}\right)+\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime}\left[Q^{\prime}\right]:\left(\neg s p \vee D^{\prime}\right) \wedge \neg \text { NonUnique }_{Q^{\prime}, D^{\prime}}\right] \\
\leq p\left(\mathcal{A}, C^{\prime}, t_{\neg s p}\right)+\operatorname{Adv}_{Q^{\prime}}\left(\mathcal{A}, C^{\prime}, s p, D^{\prime}\right) & \\
\leq p\left(\mathcal{A}, C^{\prime}, t_{\neg s p}\right)+p^{\prime}\left(\mathcal{A}, C^{\prime}\right) & \text { since } \operatorname{Bound}_{Q^{\prime}}\left(V, s p, D^{\prime}, p^{\prime}\right) \\
\leq p\left(\mathcal{A}, C, t_{\neg s p}\right)+p^{\prime}(\mathcal{A}, C) &
\end{array}
$$

since the renaming does not modify the probability formulas by Property 6

$$
\leq p^{\prime \prime}(\mathcal{A}, C)
$$

so $\operatorname{Bound}_{Q}\left(V, s p, D, p^{\prime \prime}\right)$.
Property 2, case $s p$ is 1 -ses.secr. $(x)$, Secrecy $(x)$, or bit secr. $(x)$ : Let $\mathcal{A}$ be an attacker in $\mathcal{B B}$ and $C^{\prime}$ be an evaluation context acceptable for $C_{s p}[Q]$ with public variables $V \backslash V_{s p}$ that does not contain $\mathrm{S}, \overline{\mathrm{S}}$, events used by $D$, nor non-unique events of $Q$. Let $C=C^{\prime}\left[C_{s p}[]\right]$. Let $C^{\prime \prime}$ be obtained by renaming the variables and tables of $C$ that do not occur in $Q$ to variables and tables that also do not occur in $Q^{\prime}$, and by renaming the events of $C$ so that they are not in $E v U s e d^{\prime}$. (The events $S$ and $\bar{S}$ are left unchanged by this renaming; they are not in EvUsed ${ }^{\prime}$.) The context $C^{\prime \prime}$ is then acceptable for $Q$ and $Q^{\prime}$ with public variables $V$ and does not contain events in EvUsed ${ }^{\prime}$. Then we have

$$
\begin{aligned}
\operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D)= & \operatorname{Pr}^{\mathcal{A}}[C[Q]: \mathrm{S} \vee D]-\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee \text { NonUnique }_{Q, D}\right] \\
= & \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}[Q]: \mathrm{S} \vee D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}[Q]: \overline{\mathrm{S}} \vee \text { NonUnique }_{Q, D}\right] \\
& \text { since the renaming of events does not affect the events of the distinguisher } \\
= & \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}[Q]:(\mathrm{S} \vee D) \wedge \neg \text { NonUnique }_{Q, D}\right] \\
& -\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}[Q]:(\overline{\mathrm{S}} \wedge \neg D) \vee \text { NonUnique }_{Q, D}\right]
\end{aligned}
$$

since $\mathrm{S} \vee D$ is equivalent to $(\mathrm{S} \vee D) \wedge \neg$ NonUnique $_{Q, D}$ and $\overline{\mathrm{S}}$ is equivalent to $\overline{\mathrm{S}} \wedge \neg D$ : the game aborts immediately after executing $\mathrm{S}, \overline{\mathrm{S}}$, and the events in $D$ and NonUnique $_{Q, D}$ so only one of them can be executed

$$
\begin{aligned}
= & \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}[Q]:(\mathrm{S} \vee D) \wedge \neg \text { NonUnique }_{Q, D}\right] \\
& +\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}[Q]:(\neg \overline{\mathrm{S}} \vee D) \wedge \neg \text { NonUnique }_{Q, D}\right]-1 \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}\left[Q^{\prime}\right]:\left(\mathrm{S} \vee D^{\prime}\right) \wedge \neg \text { NonUnique }_{Q^{\prime}, D^{\prime}}\right]+p\left(\mathcal{A}, C^{\prime \prime}, t_{\mathrm{S}}\right) \\
& +\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}\left[Q^{\prime}\right]:\left(\neg \overline{\mathrm{S}} \vee D^{\prime}\right) \wedge \neg \text { NonUnique }_{Q^{\prime}, D^{\prime}}\right]+p\left(\mathcal{A}, C^{\prime \prime}, t_{\mathrm{S}}\right)-1 \\
& \text { since } \neg \overline{\mathrm{S}} \text { can be implemented in the same time as } \mathrm{S} \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}\left[Q^{\prime}\right]:\left(\mathrm{S} \vee D^{\prime}\right) \wedge \neg \text { NonUnique }_{Q^{\prime}, D^{\prime}}\right]+p\left(\mathcal{A}, C^{\prime \prime}, t_{\mathrm{S}}\right) \\
& -\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}\left[Q^{\prime}\right]:\left(\overline{\mathrm{S}} \wedge \neg D^{\prime}\right) \vee \text { NonUnique }_{Q^{\prime}, D^{\prime}}\right]+p\left(\mathcal{A}, C^{\prime \prime}, t_{\mathrm{S}}\right) \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}\left[Q^{\prime}\right]: \mathrm{S} \vee D^{\prime}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C^{\prime \prime}\left[Q^{\prime}\right]: \overline{\mathrm{S}} \vee \text { NonUnique }_{Q^{\prime}, D^{\prime}}\right]+2 p\left(\mathcal{A}, C^{\prime \prime}, t_{\mathrm{S}}\right)
\end{aligned}
$$

since $\mathrm{S} \vee D^{\prime}$ is also equivalent to $\left(\mathrm{S} \vee D^{\prime}\right) \wedge \neg \operatorname{NonUnique~}_{Q, D^{\prime}}$ and $\overline{\mathrm{S}}$ is also equivalent to $\overline{\mathrm{S}} \wedge \neg D^{\prime}$

$$
\begin{aligned}
& \leq \operatorname{Adv}_{Q^{\prime}}\left(\mathcal{A}, C^{\prime \prime}, s p, D^{\prime}\right)+2 p\left(\mathcal{A}, C^{\prime \prime}, t_{\mathrm{S}}\right) \\
& \leq p^{\prime}\left(\mathcal{A}, C^{\prime \prime}\right)+2 p\left(\mathcal{A}, C^{\prime \prime}, t_{\mathrm{S}}\right) \\
& \leq p^{\prime}(\mathcal{A}, C)+2 p\left(\mathcal{A}, C, t_{\mathrm{S}}\right)
\end{aligned}
$$

$$
\leq p^{\prime}\left(\mathcal{A}, C^{\prime \prime}\right)+2 p\left(\mathcal{A}, C^{\prime \prime}, t_{\mathrm{s}}\right) \quad \text { since } \operatorname{Bound}_{Q^{\prime}}\left(V, s p, D^{\prime}, p^{\prime}\right)
$$

since the renaming does not modify the probability formulas by Property 6

$$
\leq p^{\prime \prime}(\mathcal{A}, C)
$$

so $\operatorname{Bound}_{Q}\left(V, s p, D, p^{\prime \prime}\right)$.
Property 3, case $s p$ is a trace property: Let $\mathcal{A}$ be an attacker in $\mathcal{B B}$ and $C$ be an evaluation context acceptable for $Q$ with public variables $V$ that does not contain events used by $s p, D$, $D^{\prime}$, nor non-unique events of $Q$. We have NonUnique ${ }_{Q, D}=$ NonUnique $_{Q} \wedge \neg D$. Therefore

$$
\begin{aligned}
\operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D) & =\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:(\neg s p \vee D) \wedge \neg \text { NonUnique }_{Q, D}\right] \\
& =\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:(\neg s p \vee D) \wedge \neg\left(\text { NonUnique }_{Q} \wedge \neg D\right)\right] \\
& =\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:(\neg s p \vee D) \wedge\left(\neg \text { NonUnique }_{Q} \vee D\right)\right] \\
& =\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(\neg s p \wedge \neg \text { NonUnique }_{Q}\right) \vee D\right]
\end{aligned}
$$

In particular, $\operatorname{Adv}_{Q}(\mathcal{A}, C$, true,$D)=\operatorname{Pr}^{\mathcal{A}}[C[Q]: D]$. Hence

$$
\begin{aligned}
\operatorname{Adv}_{Q}\left(\mathcal{A}, C, s p, D \vee D^{\prime}\right) & =\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(\neg s p \wedge \neg \text { NonUnique }_{Q}\right) \vee D \vee D^{\prime}\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(\neg s p \wedge \neg \text { NonUnique }_{Q}\right) \vee D\right]+\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D^{\prime}\right] \\
& \leq \operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D)+\operatorname{Adv}_{Q}\left(\mathcal{A}, C, \operatorname{true}, D^{\prime}\right) \\
& \leq p(\mathcal{A}, C)+p^{\prime}(\mathcal{A}, C)
\end{aligned}
$$

since $\operatorname{Bound}_{Q}(V, s p, D, p)$ and $\operatorname{Bound}_{Q}\left(V\right.$, true, $\left.D^{\prime}, p^{\prime}\right)$. So $\operatorname{Bound}_{Q}\left(V, s p, D \vee D^{\prime}, p+p^{\prime}\right)$.
Property 3, case $s p$ is 1 -ses.secr. $(x)$, $\operatorname{Secrecy}(x)$, or bit secr. $(x)$ : Let $\mathcal{A}$ be an attacker in $\mathcal{B B}$ and $C^{\prime}$ be an evaluation context acceptable for $C_{s p}[Q]$ with public variables $V \backslash V_{s p}$ that does not contain $\mathrm{S}, \overline{\mathrm{S}}$, events used by $D, D^{\prime}$, nor non-unique events of $Q$. Let $C=C^{\prime}\left[C_{s p}[]\right]$. Since NonUnique $_{Q, D}=$ NonUnique $_{Q} \wedge \neg D$, we have

$$
\operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D)=\operatorname{Pr}^{\mathcal{A}}[C[Q]: \mathrm{S} \vee D]-\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\text { NonUnique }_{Q} \wedge \neg D\right)\right]
$$

Hence

$$
\begin{aligned}
\operatorname{Adv}_{Q}\left(\mathcal{A}, C, s p, D \vee D^{\prime}\right)= & \operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \mathrm{S} \vee D \vee D^{\prime}\right] \\
& -\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\operatorname{NonUnique}_{Q} \wedge \neg D \wedge \neg D^{\prime}\right)\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}[C[Q]: \mathrm{S} \vee D]+\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D^{\prime}\right] \\
& -\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\operatorname{NonUnique}_{Q} \wedge \neg D\right)\right]+\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{\mathrm{NU}}^{\prime}\right] \\
\leq & \operatorname{Adv}_{Q}(\mathcal{A}, C, s p, D)+\operatorname{Adv}_{Q}\left(\mathcal{A}, C, \operatorname{true}, D^{\prime}\right)+\operatorname{Adv}_{Q}\left(\mathcal{A}, C, \text { true }, D_{\mathrm{NU}}^{\prime}\right) \\
\leq & p(\mathcal{A}, C)+p^{\prime}(\mathcal{A}, C)+p^{\prime \prime}(\mathcal{A}, C)
\end{aligned}
$$

since $\operatorname{Bound}_{Q}(V, s p, D, p)$, $\operatorname{Bound}_{Q}\left(V\right.$, true $\left., D^{\prime}, p^{\prime}\right)$, $\operatorname{Bound}_{Q}\left(V\right.$, true, $\left.D_{\text {NU }}^{\prime}, p^{\prime \prime}\right)$, and $C$ is also an evaluation context acceptable for $Q$ with public variables $V$. So $\operatorname{Bound}_{Q}\left(V, s p, D \vee D^{\prime}, p+p^{\prime}+p^{\prime \prime}\right)$.

The inequality $-\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\right.\right.$ NonUnique $\left.\left._{Q} \wedge \neg D \wedge \neg D^{\prime}\right)\right] \leq-\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\right.\right.$ NonUnique $_{Q} \wedge$ $\neg D)]+\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{\mathrm{NU}}^{\prime}\right]$ used above is justified as follows:

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\text { NonUnique }_{Q} \wedge \neg D\right)\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\text { NonUnique }_{Q} \wedge \neg D \wedge \neg D^{\prime}\right) \vee\left(\text { NonUnique }_{Q} \wedge D^{\prime}\right)\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\text { NonUnique }_{Q} \wedge \neg D \wedge \neg D^{\prime}\right)\right]+\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \text { NonUnique }_{Q} \wedge D^{\prime}\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C[Q]: \overline{\mathrm{S}} \vee\left(\text { NonUnique }_{Q} \wedge \neg D \wedge \neg D^{\prime}\right)\right]+\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D_{\mathrm{NU}}^{\prime}\right]
\end{aligned}
$$

Property 4 The distinguisher $D \vee D^{\prime \prime}$ is a disjunction of Shoup and non-unique events in EvUsed. Let $\mathcal{A}$ be an attacker in $\mathcal{B B}$ and $C$ be any evaluation context acceptable for $Q$ with public variables $V$ that does not contain events in EvUsed ${ }^{\prime}$. Let $D_{0} \in \mathcal{D} \cup\left\{D_{\text {false }}\right\}$. Let $D_{1}$ be a disjunction of events in $\mathcal{D}_{\mathrm{SNU}}$. We have

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(D_{0} \vee D_{1} \vee D \vee D^{\prime \prime}\right) \wedge \neg \text { NonUnique }_{Q, D_{1} \vee D \vee D^{\prime \prime}}\right] \\
& \quad=\operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(D_{0} \wedge \neg \text { NonUnique }_{Q}\right) \vee D_{1} \vee D \vee D^{\prime \prime}\right]
\end{aligned}
$$

as in Property 3, case $s p$ is a trace property

$$
\begin{aligned}
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(D_{0} \wedge \neg \text { NonUnique }_{Q}\right) \vee D_{1} \vee D\right]+\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D^{\prime \prime}\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C[Q]:\left(D_{0} \vee D_{1} \vee D\right) \wedge \neg \text { NonUnique }_{Q, D_{1} \vee D}\right]+\operatorname{Adv}_{Q}\left(\mathcal{A}, C, \text { true, } D^{\prime \prime}\right)
\end{aligned}
$$

$$
\text { since } \operatorname{Adv}_{Q}\left(\mathcal{A}, C \text {, true, } D^{\prime \prime}\right)=\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: D^{\prime \prime}\right] \text { (see Property } 3 \text {, case } s p \text { is a trace property) }
$$

$$
\leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q^{\prime}\right]:\left(D_{0} \vee D_{1} \vee D^{\prime}\right) \wedge \neg \operatorname{NonUnique~}_{Q, D_{1} \vee D^{\prime}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)+p^{\prime}(\mathcal{A}, C)
$$

since $\operatorname{Bound}_{Q}\left(V\right.$, true, $\left.D^{\prime \prime}, p^{\prime}\right)$. (Note that the context $C$ does not contain events used by $D^{\prime \prime}$ nor non-unique events of $Q$.)

This lemma allows one to bound the advantage of the adversary against secrecy and correspondences. Property 1 is used in the initial game, to express the desired probability from Bound $_{Q}\left(V, s p, D_{U}, p\right)$. (Using the distinguisher $D_{U}$ can also be understood by saying that we consider that the adversary wins if some non-unique event is executed, that is, if a find or get declared unique by the user actually has several possible choices. That allows the implementation to make any choice when a find[unique ${ }_{e}$ ] or get[unique ${ }_{e}$ ] has several possible choices: the security proof remains valid. In particular, a find[unique ${ }_{e}$ ] or get [unique $e_{e}$ ] can be implemented by always choosing the first found element.) Property 2 is used when a game $Q$ is transformed into a game $Q^{\prime}$ during the proof. It allows one to bound the probability in $Q$ from a bound in $Q^{\prime}$. Property 3 is useful when distinct sequences of games are used for bounding the probabilities of breaking $s p$ and of $D$ on one side and of $D^{\prime}$ on the other side. We bound these two

(a) edge, source, and target nodes

(b) node and outgoing edges

Figure 15: Structure of a proof tree
probabilities by Bound $_{Q}(V, s p, D, p)$ and $\operatorname{Bound}_{Q}\left(V\right.$, true, $\left.D^{\prime}, p^{\prime}\right)$ separately, then obtain a bound Bound $_{Q}\left(V, s p, D \vee D^{\prime}, p^{\prime \prime \prime}\right)$ by computing a sum. (When we deal with secrecy and $D_{\mathrm{NU}}^{\prime} \neq D_{\text {false }}$, the probability of $D_{\mathrm{NU}}^{\prime}$ can be bounded by looking at the proof for $D^{\prime}$.)

More formally, consider the following cases, using Lemma 28, Property 1

- If we want to prove that $Q_{0}$ satisfies the correspondence $\varphi$ with public variables $V$, then we let $s p=\varphi$.
- If we want prove that $Q_{0}$ satisfies the (one-session or bit) secrecy of $x$ with public variables $V^{\prime}\left(x \notin V^{\prime}\right)$, then we let $s p$ be 1-ses.secr. $(x)$, Secrecy $(x)$, or bit secr. $(x)$ and $V=V^{\prime} \cup\{x\}$.

In both cases, we show $\operatorname{Bound}_{Q_{0}}\left(V, s p, D_{U}, p\right)$. The proof produced by CryptoVerif can be represented as a tree whose nodes are labeled with quintuples ( $Q, V, s p^{\prime}, D, E v U s e d$ ) and whose edges are labeled with triples $\left(s p^{\prime \prime}, D^{\prime \prime}, p^{\prime \prime}\right)$, where $Q$ is the current game, $V$ is the set of public variables, $s p^{\prime}$ and $s p^{\prime \prime}$ are either the initial property to prove $s p$ or true, $D$ and $D^{\prime \prime}$ are disjunctions of Shoup and non-unique events, EvUsed is the set of events used so far, and $p^{\prime \prime}$ is a probability formula. The edges have a single source node, but may have 0 , 1 , or several target nodes. We associate to each node labeled with $\left(Q, V, s p^{\prime}, D, E v U s e d\right)$ a property Bound ${ }_{Q}\left(V, s p^{\prime}, D, p\right)$, and to each edge labeled with $\left(s p^{\prime \prime}, D^{\prime \prime}, p^{\prime \prime}\right)$ with source node labeled with ( $Q, V, s p^{\prime}, D, E v U s e d$ ) a property Bound $_{Q}\left(V, s p^{\prime \prime}, D^{\prime \prime}, p^{\prime}\right)$. CryptoVerif computes the probabilities $p, p^{\prime}$ such that these properties hold from the leaves of the tree to its root, as explained next.

The root of the tree is labeled with $\left(Q_{0}, V, s p, D_{U}, E v U s e d_{0}\right)$ such that EvUsed $d_{0}$ is the set containing the events used by correspondences to prove or that occur in $Q_{0}$.

When an edge labeled with $\left(s p^{\prime \prime}, D^{\prime \prime}, p^{\prime \prime}\right)$ has a source node labeled with ( $Q, V,,_{,}$, EvUsed $)$ and target nodes labeled with $\left(Q_{j}, V_{j}, s p_{j}^{\prime}, D_{j}, E v U s e d_{j}\right)$ for $j \in\{1, \ldots, l\}$ (Figure 15 (a)), the bound associated to the edge can be computed from the bound associated to the target nodes by the probability formula $p^{\prime \prime}$ that labels the edge: if $\operatorname{Bound}_{Q_{j}}\left(V_{j}, s p_{j}^{\prime}, D_{j}, p_{j}\right)$ for $j \in\{1, \ldots, l\}$, then Bound $_{Q}\left(V, s p^{\prime \prime}, D^{\prime \prime}, p\right)$ where $p(\mathcal{A}, C)=p^{\prime \prime}\left(\mathcal{A}, C, p_{1}(C), \ldots, p_{l}(C)\right)$. This situation corresponds to a game transformation that transforms game $Q$ into games $Q_{j}(j \in\{1, \ldots, l\})$. We can distinguish several cases depending on where the edge comes from:

- For most game transformations, the edge has a single target node $(l=1), V_{1}=V$, $s p_{1}^{\prime}=s p^{\prime \prime}$, and the game transformation transforms $Q$ into $Q_{1}$ and satisfies $\mathcal{D}_{1}, \emptyset$ : $Q, D^{\prime \prime}$, EvUsed $\xrightarrow{V} p_{p^{\prime}} Q_{1}, D_{1}$, EvUsed $_{1}$ where $\mathcal{D}_{1}=\left\{\neg s p^{\prime \prime}\right\}$ when $s p^{\prime \prime}$ is a trace property, $\mathcal{D}_{1}=\{\mathrm{S}, \neg \overline{\mathrm{S}}\}$ when $s p^{\prime \prime}$ is 1 -ses.secr. $(x)$, $\operatorname{Secrecy}(x)$, or bit secr. $(x)$, and $\mathcal{D}_{1}=\emptyset$ when $s p^{\prime \prime}=$ true. (During the building of the proof tree, we have $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}{ }_{p^{\prime}}$ $Q_{1}, D^{\prime}, E v U s e d_{1}$, where the distinguishers $\mathcal{D}$ correspond to the active queries not for introduced Shoup and non-unique events, so $\mathcal{D}_{1} \subseteq \mathcal{D}, \mathcal{D}_{\text {SNU }}$ are the active queries for Shoup and non-unique events both before and after this step so $D^{\prime \prime}$ and $D_{1}$ are disjunctions of events in $\mathcal{D}_{\text {SNU }}, D=D^{\prime \prime} \wedge \neg D_{1}$ are the Shoup/non-unique events proved at this step, $D^{\prime}=D_{1} \wedge \neg D^{\prime \prime}$ are the Shoup/non-unique events introduced at this step. By applying several times Lemma 20 Property 5 , we obtain $\mathcal{D}, \mathcal{D}_{\text {SNU }}: ~ Q, D^{\prime \prime}$, EvUsed $\xrightarrow{V} p_{p^{\prime}} Q_{1}, D_{1}$, EvUsed $_{1}$. By Lemma 20. Property 6, we obtain $\mathcal{D}_{1}, \emptyset: Q, D^{\prime \prime}$, EvUsed $\xrightarrow{V}{ }_{p^{\prime}} Q_{1}, D_{1}, E v U s e d_{1}$.) The bound is inferred by Lemma 28, Property 2 .
If $s p^{\prime \prime}$ is a trace property and $\operatorname{Bound}_{Q_{1}}\left(V, s p^{\prime \prime}, D_{1}, p_{1}\right)$, then $\operatorname{Bound}_{Q}\left(V, s p^{\prime \prime}, D^{\prime \prime}, p\right)$ where $p(\mathcal{A}, C)=p^{\prime}\left(\mathcal{A}, C, t_{\neg s p^{\prime \prime}}\right)+p_{1}(\mathcal{A}, C)$, so we can define $p^{\prime \prime}\left(\mathcal{A}, C, p_{t}\right)=p^{\prime}\left(\mathcal{A}, C, t_{\neg s p^{\prime \prime}}\right)+p_{t}$. If $s p^{\prime \prime}$ is 1 -ses.secr. $(x)$, $\operatorname{Secrecy}(x)$, or bit secr. $(x)$ and $\operatorname{Bound}_{Q_{1}}\left(V, s p^{\prime \prime}, D_{1}, p_{1}\right)$, then we have $\operatorname{Bound}_{Q}\left(V, s p^{\prime \prime}, D^{\prime \prime}, p\right)$ where $p(\mathcal{A}, C)=2 p^{\prime}\left(\mathcal{A}, C, t_{\mathrm{S}}\right)+p_{1}(\mathcal{A}, C)$, so we can define $p^{\prime \prime}\left(\mathcal{A}, C, p_{t}\right)=2 p^{\prime}\left(\mathcal{A}, C, t_{\mathrm{S}}\right)+p_{t}$.
To unify these two cases, we define

$$
\begin{aligned}
& \operatorname{pstd}_{p^{\prime}}^{s p^{\prime \prime}}\left(\mathcal{A}, C, p_{t}\right)= \\
& \qquad \begin{cases}p^{\prime}\left(\mathcal{A}, C, t_{\neg s p^{\prime \prime}}\right)+p_{t} & \text { when } s p^{\prime \prime} \text { is a trace property } \\
2 p^{\prime}\left(\mathcal{A}, C, t_{\mathrm{S}}\right)+p_{t} & \text { when } s p^{\prime \prime} \text { is 1-ses.secr. }(x), \operatorname{Secrecy}(x) \text { or bit secr. }(x)\end{cases}
\end{aligned}
$$

so that, when an edge comes from a transformation $\mathcal{D}_{1}, \emptyset: Q, D^{\prime \prime}$, EvUsed $\xrightarrow{V}{p^{\prime}} Q_{1}, D_{1}$, $E v U_{s e d}^{1} 1$ and the considered security property is $s p^{\prime \prime}$, the edge can be labeled with the probability formula $\operatorname{pstd}_{p^{\prime}}^{s p^{\prime \prime}}$. If $\operatorname{Bound}_{Q_{1}}\left(V, s p^{\prime \prime}, D_{1}, p_{1}\right)$, then $\operatorname{Bound}_{Q}\left(V, s p^{\prime \prime}, D^{\prime \prime}, p\right)$ where $p(\mathcal{A}, C)=\operatorname{pstd}_{p^{\prime}}^{s p^{\prime \prime}}\left(\mathcal{A}, C, p_{1}(C)\right)$.

- When a query is proved (by the command success, Section 4), the edge has no target node $(l=0)$, and we simply obtain $\operatorname{Bound}_{Q}\left(V, s p^{\prime \prime}, D^{\prime \prime}, p^{\prime \prime}\right)$. The probability $p^{\prime \prime}$ that labels the edge is determined by the success command (Proposition 1, 2, or 3).
These propositions require that $D^{\prime \prime}=D_{\text {false }}$. This is obtained by splitting the properties to prove one property at a time (with one edge for each property starting from the source node), yielding bounds of the form $\operatorname{Bound}_{Q}\left(V, s p^{\prime \prime}, D_{\text {false }}, p^{\prime \prime}\right)$ or Bound ${ }_{Q}\left(V\right.$, true, $\left.e, p^{\prime \prime}\right)$. For the first form, $p^{\prime \prime}$ can immediately be computed from Proposition 1, 2, or 3 For the second form, when $e$ is a non-unique event, we use Section 4.2.2 and when $e$ is a Shoup event, we notice that $\operatorname{Adv}_{Q}(\mathcal{A}, C$, true, $e)=\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: e \wedge \neg\right.$ NonUnique $\left._{Q, e}\right]=$ $\operatorname{Pr}^{\mathcal{A}}\left[C[Q]: e \wedge \neg \operatorname{NonUnique}_{Q}\right]=\operatorname{Adv}_{Q}\left(\mathcal{A}, C, \llbracket \operatorname{event}(e) \Rightarrow\right.$ false $\left.\rrbracket, D_{\text {false }}\right)$, so we can use $\operatorname{Bound}_{Q}\left(V, \llbracket \operatorname{event}(e) \Rightarrow\right.$ false $\left.\rrbracket, D_{\text {false }}, p^{\prime \prime}\right)$ instead.
The success command is the only one that removes an event from $D^{\prime \prime}$, which then happens only when we evaluate $\operatorname{Bound}_{Q}\left(V, \operatorname{true}, e, p^{\prime \prime}\right)$, so $D^{\prime \prime}=e, s p^{\prime \prime}=\operatorname{true}, l=0$.
- In case of other transformations such as the guess transformation, the relation between bounds that defines $p^{\prime \prime}$ is given directly in the soundness lemma for the transformation (Lemma 59, 60, or 61). In particular, for the transformation guess_branch, the edge has as
many target nodes as there are branches in the guessed instruction. For the transformation guess $i$, Lemma 59 requires $D^{\prime \prime}=D_{\text {false }}$, which can be achieved as for success above.

When a node labeled with ( $Q, V, s p^{\prime}, D, E v U s e d$ ) has outgoing edges labeled respectively $\left(s p_{1}^{\prime}, D_{1}^{\prime},{ }_{-}\right), \ldots,\left(s p_{l}^{\prime}, D_{l}^{\prime},{ }_{-}\right)$(Figure $\left.15(\mathrm{~b})\right)$, then $D=D_{1}^{\prime} \vee \ldots \vee D_{l}^{\prime}(D$ is a disjunction of the form $e_{1} \vee \ldots \vee e_{m}, D_{1}^{\prime}, \ldots, D_{l}^{\prime}$ are disjunctions that form a partition of the disjuncts of $D$ ), there exists $j_{0} \leq l$ such that $s p_{j_{0}}^{\prime}=s p^{\prime}$ and for all $j \neq j_{0}, s p_{j}^{\prime}=$ true. The bound associated to the node is computed from the bound associated to the edges by Lemma 28, Property 3.

- If $s p^{\prime}$ is a trace property, then we have $\operatorname{Bound}_{Q}\left(V, s p^{\prime}, D, p_{1}^{\prime}+\cdots+p_{l}^{\prime}\right)$, where $\operatorname{Bound}_{Q}(V$, $\left.s p_{j}^{\prime}, D_{j}^{\prime}, p_{j}^{\prime}\right)$ for all $j \in\{1, \ldots, l\}$.
- If $s p^{\prime}$ is 1 -ses.secr. $(x), \operatorname{Secrecy}(x)$, or bit secr. $(x)$, then we have $\operatorname{Bound}_{Q}\left(V, s p^{\prime}, D, \sum_{j=1}^{l} p_{j}^{\prime}+\right.$ $\left.\sum_{j=1, \ldots, l_{; j} \neq j_{0}} p_{j}^{\prime \prime}\right)$, where $\operatorname{Bound}_{Q}\left(V, s p_{j}^{\prime}, D_{j}^{\prime}, p_{j}^{\prime}\right)$ for all $j \in\{1, \ldots, l\}, \operatorname{Bound}_{Q}\left(V, s p_{j}^{\prime}, D_{\text {NU } j}^{\prime}\right.$, $\left.p_{j}^{\prime \prime}\right)$ for all $j \in\{1, \ldots, l\}$ with $j \neq j_{0}$, and $D_{\mathrm{NU} j}^{\prime}$ is obtained from $D_{j}^{\prime}$ by keeping only the non-unique events.
To prove Bound $_{Q}\left(V, s p_{j}^{\prime}, D_{\mathrm{NU}_{j}}^{\prime}, p_{j}^{\prime \prime}\right)$, we build a proof tree with root $Q, V, s p_{j}^{\prime}, D_{\mathrm{NU}_{j}}^{\prime}, E v U s e d$ from the subtree $Q, V, s p^{\prime}, D, E v U s e d ~ \xrightarrow{s p_{j}^{\prime}, D_{j}^{\prime}, p_{j}} \ldots$ by
- replacing the root $Q, V, s p^{\prime}, D, E v U s e d$ with $Q, V, s p_{j}^{\prime}, D_{j}^{\prime}, E v U s e d$.
- removing all Shoup events of $D_{j}^{\prime}$ from distinguishers that label nodes and edges. In particular, the root $Q, V, s p_{j}^{\prime}, D_{j}^{\prime}$, EvUsed then becomes $Q, V, s p_{j}^{\prime}, D_{\mathrm{NU}_{j}}^{\prime}, E v U s e d$.
- removing subtrees that start with an edge labeled $s p_{j}^{\prime}, D_{\mathrm{false}}, p$ for some $p$.

The proof steps remain valid: all proof steps are a fortiori valid when we ignore some Shoup events. That can be verified for each transformation using its soundness lemma. For instance, for proof steps that come from usual transformations that satisfy property preservation with introduction of events and have a Shoup event $e$ of $D_{j}^{\prime}$ both before and after, we can avoid adding that event $e$ when we derive $\mathcal{D}_{1}, \emptyset: Q, D_{j}^{\prime}$, EvUsed ${ }^{V}{ }_{p^{\prime}}$ $Q_{1}, D_{1}$, EvUsed $_{1}$ from $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: Q, D$, EvUsed $\xrightarrow{V}{ }_{p^{\prime}} Q_{1}, D^{\prime}$, EvUsed $_{1}$. For proof steps that prove a Shoup event $e$ of $D_{j}^{\prime}$ (via success), that proof step starts with just event $e$, so it is simply removed. We can then apply the previous reasoning to that proof tree.

When the proof is a basic sequence of games, each node has one son, which is the next game in the sequence, except the last game of the sequence which has no son. Only the final proof step is distinct for each query. However, it may happen that distinct sequences of games are used to bound several events occurring in the game; in this case, there is a branching in the proof and a node has several sons. Examples of proof trees can be found in Figure 16 they are explained below.

The bound associated to the leaves of the tree is computed by success; the bound associated to an edge is computed from the bounds associated to its target nodes, and the bound associated to a node is computed from the bounds associated to its outgoing edges. We can then compute the bounds associated to all nodes of the tree, by induction from the leaves to the root. At the root, we obtain a bound $\operatorname{Bound}_{Q_{0}}\left(V, s p, D_{U}, p\right)$ that yields the desired result.

Lemma 28 allows us to obtain more precise probability bounds than the standard computation of probabilities generally done by cryptographers, when we use Shoup's lemma 68]. By Shoup's lemma, if $G^{\prime}$ is obtained from $G$ by inserting an event $e$ and modifying the code executed after $e$, the probability of distinguishing $G^{\prime}$ from $G$ is bounded by the probability of executing $e$ : for


Figure 16: Examples of proof trees
all attackers $\mathcal{A} \in \mathcal{B B}$ and all contexts $C$ acceptable for $G$ and $G^{\prime}$ (with any public variables) and all distinguishers $D,\left|\operatorname{Pr}^{\mathcal{A}}[C[G]: D]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: D\right]\right| \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: e\right]$. Hence,

$$
\operatorname{Pr}^{\mathcal{A}}[C[G]: D] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: e\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: D\right]
$$

We improve over this computation of probabilities by considering $e$ and $D$ simultaneously instead of making the sum of the two probabilities:

$$
\operatorname{Pr}^{\mathcal{A}}[C[G]: D] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: D \vee e\right]
$$

For example, suppose that we want to bound the probability of event $e_{0}$ in $G_{0}$ : we define $s p=\llbracket \operatorname{event}\left(e_{0}\right) \Rightarrow$ false $\rrbracket=\neg e_{0}$. We transform $G_{0}$ into $G_{1}$ using Shoup's lemma, so that $G_{1}$ differs from $G_{0}$ only when $G_{1}$ executes event $e$, and we have $\left\{e_{0}\right\}, \emptyset: G_{0}, D_{\text {false }}, \operatorname{EvUsed}_{0} \rightarrow_{0} G_{1}$, $e, E v$ Used $_{1}$; then we transform $G_{1}$ into $G_{2}$, so that $G_{1} \approx_{p}^{\left\{e_{0}, e\right\}} G_{2}$, so we have $\left\{e_{0}\right\}, \emptyset: G_{1}, e$, EvUsed $_{1} \rightarrow_{p} G_{2}, e$, EvUsed $_{1}$ by Lemma 20. Property 1 and $G_{2}$ executes neither $e_{0}$ nor $e$. We suppose for simplicity that no [unique $e_{e^{\prime}}$ ] occurs, so that NonUnique ${ }_{G_{i}, D}$ is always false. The corresponding proof tree is given in Figure 16(a).

- Since $e_{0}$ does not occur in $G_{2}$, we have $\operatorname{Adv}_{G_{2}}\left(\mathcal{A}, C, s p, D_{\text {false }}\right)=0$ for all $\mathcal{A} \in \mathcal{B B}$ and all evaluation contexts $C$ acceptable for $G_{2}$ with public variables $V$ that do not contain event $e_{0}$. So Bound ${ }_{G_{2}}\left(V, s p, D_{\text {false }}, 0\right)$. Similarly, Bound $G_{2}(V$, true, $e, 0)$. These two properties are represented in the proof tree by the two edges outgoing from node $G_{2}, V, s p, e,\left\{e_{0}, e\right\}$.
- By Lemma 28, Property 3. Bound $_{G_{2}}\left(V, s p, e, p_{3}^{\prime}\right)$ where $p_{3}^{\prime}(C)=0$.
- Since $\left\{e_{0}\right\}, \emptyset: G_{1}, e, E v U s e d_{1} \rightarrow_{p} G_{2}, e$, EvUsed $_{1}$, by Lemma 28, Property 2, we obtain Bound $_{G_{1}}\left(V, s p, e, p_{2}^{\prime}\right)$ where $p_{2}^{\prime}(\mathcal{A}, C)=p\left(\mathcal{A}, C, t_{\neg s p}\right)+p_{3}^{\prime}(\mathcal{A}, C)$. This is represented in the proof tree by the edge from node $G_{1}, V, s p, e,\left\{e_{0}, e\right\}$ to node $G_{2}, V, s p, e,\left\{e_{0}, e\right\}$ labeled with $s p, e, \operatorname{pstd}_{p}^{s p}$.


Figure 17: Removing subtrees

- Since $\left\{e_{0}\right\}, \emptyset: G_{0}, D_{\text {false }}$, EvUsed $_{0} \rightarrow_{0} G_{1}, e$, EvUsed $_{1}$, by Lemma 28, Property 2 , we obtain Bound $_{G_{0}}\left(V, s p, D_{\text {false }}, p_{1}^{\prime}\right)$ where $p_{1}^{\prime}(\mathcal{A}, C)=0+p_{2}^{\prime}(\mathcal{A}, C)$. This is represented in the proof tree by the edge from node $G_{0}, V, s p, D_{\text {false }},\left\{e_{0}\right\}$ to node $G_{1}, V, s p, e,\left\{e_{0}, e\right\}$ labeled with $s p, D_{\text {false }}, \mathrm{pstd}_{0}^{s p}$.
- Finally, by Lemma 28 , Property 1 we conclude that $G_{0}$ satisfies $s p$ with public variables $V$ up to probability $p_{1}^{\prime}$, where $p_{1}^{\prime}(\mathcal{A}, C)=p_{2}^{\prime}(\mathcal{A}, C)=p\left(\mathcal{A}, C, t_{\neg s p}\right)+p_{3}^{\prime}(\mathcal{A}, C)=p\left(\mathcal{A}, C, t_{e_{0}}\right)$, which means that $\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: e_{0}\right] \leq p\left(\mathcal{A}, C, t_{e_{0}}\right)$ for all evaluation contexts $C$ acceptable for $G_{0}$ with public variables $V$ that do not contain event $e_{0}$.

Let $C$ be an evaluation context acceptable for $G_{0}$ with public variables $V$ that does not contain event $e_{0}$ and $\mathcal{A}$ an attacker in $\mathcal{B B}$. Since we suppose for simplicity that no [unique ${ }_{e^{\prime}}$ ] occurs, so that NonUnique $G_{G_{i}, D}$ is always false, we have $\operatorname{Adv}_{G_{i}}(\mathcal{A}, C, s p, D)=\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{i}\right]: \neg s p \vee D\right]$, so we can write the previous computation simply using probabilities:

$$
\begin{aligned}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: e_{0}\right] & \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: e_{0} \vee e\right] \quad \text { since }\left\{e_{0}\right\}, \emptyset: G_{0}, D_{\text {false }}, \text { EvUsed }_{0} \rightarrow_{0} G_{1}, e, E v U s e d_{1} \\
& \leq p\left(\mathcal{A}, C, t_{e_{0}}\right)+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: e_{0} \vee e\right] \\
& \text { since }\left\{e_{0}\right\}, \emptyset: G_{1}, e, \text { EvUsed }_{1} \rightarrow_{p} G_{2}, e, \text { EvUsed } \\
& \text { since } G_{2} \text { executes neither } e_{0} \text { nor } e .
\end{aligned}
$$

In contrast, the standard computation of probabilities yields

$$
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: e_{0}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: e_{0}\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: e\right] \leq p\left(\mathcal{A}, C, t_{e_{0}}\right)+p\left(\mathcal{A}, C, t_{e}\right)
$$

The runtime $t_{D}$ of $D$ is essentially the same for $e_{0}, e$, and $e_{0} \vee e$, so $\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: e_{0}\right] \leq p\left(\mathcal{A}, C, t_{D}\right)$ by Lemma 28, while $\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: e_{0}\right] \leq 2 p\left(\mathcal{A}, C, t_{D}\right)$ by the standard computation, so we have gained a factor 2 . The probability that comes from the transformation of $G_{1}$ into $G_{2}$ is counted once (for distinguisher $e_{0} \vee e$ ) instead of counting it twice (once for $e_{0}$ and once for $e$ ).

The standard computation of probabilities corresponds to applying point 3 of Lemma 28 to bound each probability separately and compute the sum, as soon as the considered distinguisher $D$ has several disjuncts. Instead, we use point 3 of Lemma 28 only when the proof uses different sequences of games to bound the probabilities of the events, as in Figure 16(b).

Consider a proof tree that consists of a main branch that is a sequence of applications of transformations that satisfy property preservation with introduction of events (properties of the
form $\mathcal{D}, \emptyset: Q_{i}, D_{i}^{\prime}$, EvUsed $_{i} \xrightarrow{V} p_{i} Q_{i+1}, D_{i+1}$, EvUsed $\left._{i+1}\right)$, and side branches that may use any transformation to bound the probability of Shoup and non-unique events. All nodes on the main branch use the same security property $s p$, while nodes on side branches use true as security property. Such a proof tree happens when we prove indistinguishability properties, where $s p$ is any distinguisher used in the definition of indistinguishability (see Section 2.8.5). In particular, the transformations guess, guess_branch, and success simplify are not allowed in the main branch but may be used in side branches. Lemma 28, Property 4 allows one to transform such a proof tree into a single property of the form $\mathcal{D}, \emptyset: Q, D$, EvUsed $\xrightarrow{V}{ }_{p} Q^{\prime}, D^{\prime}$, EvUsed ${ }^{\prime}$. Indeed, the main branch starts from the root $Q, V, s p, D$, EvUsed to a leaf $Q^{\prime}, V, s p, D^{\prime}, E v U s e d$, with additional subtrees starting from various nodes on this branch. Each node on the main branch is labeled $Q_{i}, V, s p, D_{i}, E v U s e d_{i}$, and the edge of the main branch that starts from $Q_{i}, V, s p, D_{i}, E v U s e d_{i}$ is labeled $s p, D_{i}^{\prime}, \operatorname{pstd}_{p_{i}}^{s p}$ (see Figure 17). Suppose an additional subtree starts from a node $Q_{i}, V, s p, D_{i}, E v U s e d_{i}$ with an edge labeled true, $D_{i}^{\prime \prime}$,.. This subtree yields a bound Bound $_{Q_{i}}\left(V\right.$, true, $\left.D_{i}^{\prime \prime}, p_{i}^{\prime}\right)$. The edge of the main branch from $Q_{i}, V, s p, D_{i}$, EvUsed $_{i}$ yields a property $\mathcal{D}, \emptyset: Q_{i}, D_{i}^{\prime}$, EvUsed $_{i} \xrightarrow{V} p_{i} Q_{i+1}, D_{i+1}$, EvUsed $_{i+1}$. By Lemma 28 . Property 4. the additional subtree can then be removed from the proof tree by replacing $s p, D_{i}^{\prime}, \operatorname{pstd}_{p_{i}}^{s p}$ with $s p, D_{i}^{\prime} \vee D_{i}^{\prime \prime}, \operatorname{pstd}_{p_{i}+p_{i}^{\prime}}^{s p}$ as label of the edge of the main branch starting from the node $Q_{i}, V, s p, D_{i},{E v U s e d_{i}}$. By repeating this operation, we remove all additional subtrees, obtaining a proof tree that consists of a single branch with nodes labeled $Q_{i}, V, s p, D_{i}, E v U s e d_{i}$, such that the edge that starts from $Q_{i}, V, s p, D_{i}, E v U s e d_{i}$ is labeled $s p, D_{i}, \operatorname{pstd}_{p_{i}}^{s p}$. This yields a sequence of properties $\mathcal{D}, \emptyset: Q_{i}, D_{i}$, EvUsed $_{i} \xrightarrow{V} p_{i} Q_{i+1}, D_{i+1}$, EvUsed $_{i+1}$, which yields a single such property $\mathcal{D}, \emptyset: Q, D, E v U s e d ~{ }^{V}{ }_{p} Q^{\prime}, D^{\prime}, E v U s e d^{\prime}$ by transitivity (Lemma 20, Property 3).

### 2.8.5 Proof of Indistinguishability

To prove indistinguishability between two games $G_{0}$ and $G_{1}$, CryptoVerif finds a game $G_{2}$ such that $\mathcal{D}, \emptyset: G_{0}, D_{U 0}, E v U s e d \xrightarrow{V}_{p} G_{2}, D_{2}, E v U s e d^{\prime}$ and $\mathcal{D}, \emptyset: G_{1}, D_{U 1}, E v U s e d_{1} \xrightarrow{V}{ }_{p^{\prime}, D^{+}}$ $G_{2}, D_{2}, E v U s e d_{1}^{\prime}$ where $\mathcal{D}$ is the set of all distinguishers, EvUsed $=\operatorname{event}\left(G_{0}\right)$, EvUsed ${ }_{1}=$ event $\left(G_{1}\right), D_{U 0}=\bigvee\left\{e \mid\right.$ [unique $\left.{ }_{e}\right]$ occurs in $\left.G_{0}\right\}$ and $D_{U 1}=\bigvee\left\{e \mid\right.$ [unique $\left.{ }_{e}\right]$ occurs in $\left.G_{1}\right\}$. The active queries $D_{2}$ are also required to be the same in both sequences of games. (In general, CryptoVerif builds proof trees; they can be transformed into the properties above by Lemma 28 , Property 4 as explained above. Only transformations that satisfy property preservation with introduction of events are allowed in the sequence of games that proves indistinguishability. The transformations guess, guess_branch, and success simplify are not allowed in that sequence, but are allowed in side branches that bound the probability of introduced events.) So for all attackers $\mathcal{A} \in \mathcal{B B}$, all evaluation contexts $C$ acceptable for $G_{0}$ and $G_{2}$ with public variables $V$ that do not contain events $E v U s e d^{\prime}$, and all distinguishers $D_{0} \in \mathcal{D}$ that run in time at most $t_{D_{0}}$,

$$
\begin{equation*}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0} \vee D_{U 0}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(D_{0} \vee D_{2}\right) \wedge \neg \operatorname{NonUnique~}_{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right) \tag{14}
\end{equation*}
$$

since NonUnique ${ }_{G_{0}, D_{U 0}}=D_{\text {false }}$, and for all attackers $\mathcal{A} \in \mathcal{B B}$, all evaluation contexts $C$ acceptable for $G_{1}$ and $G_{2}$ with public variables $V$ that do not contain events in $E v U s e d_{1}^{\prime}$, and all distinguishers $D_{0} \in \mathcal{D}$ that run in time at most $t_{D_{0}}$,

$$
\begin{equation*}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: D_{0} \vee D_{U 1}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(D_{0} \vee D_{2}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right) . \tag{15}
\end{equation*}
$$

Let $\mathcal{A}$ be an attacker in $\mathcal{B B}$ and $C$ be an evaluation context acceptable for $G_{0}$ and $G_{1}$ with public variables $V$. After renaming the variables of $C$ that do not occur in $G_{0}$ and $G_{1}$ and the tables of $C$ that do not occur in $G_{0}$ and $G_{1}$ so that they do not occur in $G_{2}, C$ is also acceptable
for $G_{2}$ with public variables $V$. Furthermore, by Property 6, this renaming does not change the probabilities. Let $D_{0} \in \mathcal{D}$ be a distinguisher that runs in time at most $t_{D_{0}}$. We rename the events of $C$ in $E v U s e d^{\prime}$ or $E v U s e d_{1}^{\prime}$ to some fresh events, and modify $D_{0}$ so that it considers the renamed events as if they were the original events. That does not change the probability $\left|\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: D_{0}\right]\right|$, and guarantees that $C$ does not contain events in EvUsed ${ }^{\prime}$ nor in EvUsed ${ }_{1}^{\prime}$. So

$$
\begin{aligned}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0}\right] \leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0} \vee D_{U 0}\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(D_{0} \vee D_{2}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right) \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(\left(D_{0} \wedge \neg D_{2}\right) \vee D_{2}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right) \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(D_{0} \wedge \neg D_{2}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right] \\
& \quad+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2} \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right) \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{0} \wedge \neg D_{2}\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2} \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

By applying (15) to $\neg D_{0}$, which is also in $\mathcal{D}$ and runs in the same time as $D_{0}$, we have

$$
\begin{aligned}
1-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: D_{0}\right] & =\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: \neg D_{0}\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: \neg D_{0} \vee D_{U 1}\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(\neg D_{0} \vee D_{2}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right) \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: \neg D_{0} \vee D_{2}\right]+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right) \\
& \leq 1-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{0} \wedge \neg D_{2}\right]+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

so

$$
-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: D_{0}\right] \leq-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{0} \wedge \neg D_{2}\right]+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

so

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: D_{0}\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2} \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

By applying the formula above to $\neg D_{0}$, which runs in the same time as $D_{0}$, we have

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: D_{0}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0}\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2} \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

so

$$
\begin{aligned}
& \left|\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: D_{0}\right]\right| \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2} \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)+p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

so $G_{0} \approx_{p^{\prime \prime}}^{V} G_{1}$ where $p^{\prime \prime}\left(\mathcal{A}, C, t_{D_{0}}\right)=\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2} \wedge \neg\right.$ NonUnique $\left._{G_{2}, D_{2}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)+$ $p^{\prime}\left(\mathcal{A}, C, t_{D_{0}}\right)$.

### 2.8.6 Proof of query_equiv

Decisional case (query_equiv without [computational] annotation) The situation is similar to the proof of indistinguishability, but the property we want to prove is $\mathcal{D}_{\neg \text { EvUsed }_{1}}, \emptyset$ : $G_{0}, D_{\text {false }}, \emptyset \xrightarrow{V} G_{1}, D_{1}, E v U s e d_{1}$ where $G_{0}$ contains no events, $D_{1}=e_{1} \vee \ldots \vee e_{m}, e_{1}, \ldots, e_{m}$
are the Shoup events occurring in $G_{1}, e_{1}^{\prime}, \ldots, e_{l}^{\prime}$ are the non-unique events occurring in $G_{1}$, EvUsed $_{1}=\left\{e_{1}, \ldots, e_{m}, e_{1}^{\prime}, \ldots, e_{l}^{\prime}\right\}, V=\emptyset$.

We need to show that, for all attackers $\mathcal{A} \in \mathcal{B} \mathcal{B}$, all evaluation contexts $C$ acceptable for $G_{0}$ and $G_{1}$ without public variables that do not contain events in EvUsed ${ }_{1}$ and all distinguishers $D_{0} \in \mathcal{D}_{\neg \text { EvUsed }_{1}}$,

$$
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]:\left(D_{0} \vee D_{1}\right) \wedge \neg \operatorname{NonUnique~}_{G_{1}, D_{1}}\right]+p\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

CryptoVerif finds a game $G_{2}$ such that $\mathcal{D}_{\neg \text { EvUsed }}^{\prime}, \emptyset: G_{0}, D_{\text {false }}, \emptyset \xrightarrow{V} p_{p_{0}} G_{2}, D_{2}, E v U s e d_{0}^{\prime}$ and $\mathcal{D}_{\neg \text { EvUsed }}^{1 \prime}, \emptyset: G_{1}, D_{U 1}$, EvUsed $_{1} \xrightarrow{V}_{p_{1}} G_{2}, D_{2}^{\prime}$, EvUsed $_{1}^{\prime}$ where EvUsed ${ }_{1}^{\prime \prime}=$ EvUsed $_{1}^{\prime} \backslash\left\{e_{1}, \ldots\right.$, $\left.e_{m}\right\}, D_{U 1}=e_{1}^{\prime} \vee \ldots \vee e_{l}^{\prime}=$ NonUnique $_{G_{1}, D_{1}}$, and $D_{2}=D_{1} \vee D_{2}^{\prime}$. (The events $e_{1}, \ldots, e_{m}$ must be preserved by the second proof, hence we allow distinguishers in $\mathcal{D}_{\neg \text { EvUsed }}^{1 \prime}$ to use these events. The events $e_{1}, \ldots, e_{m}$ will be introduced in the first proof, and the active queries in $G_{2}$ are also required to match so $D_{2}=D_{1} \vee D_{2}^{\prime}$.) So for all attackers $\mathcal{A} \in \mathcal{B} \mathcal{B}$, all evaluation contexts $C$ acceptable for $G_{0}$ and $G_{2}$ without public variables that do not contain events in EvUsed ${ }_{0}^{\prime}$, and all distinguishers $D_{0} \in \mathcal{D}_{\neg \text { EvUsed }}^{0}$ that run in time at most $t_{D_{0}}$,

$$
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(D_{0} \vee D_{2}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}}\right]+p_{0}\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

and for all attackers $\mathcal{A} \in \mathcal{B B}$, for all evaluation contexts $C$ acceptable for $G_{1}$ and $G_{2}$ without public variables that do not contain events in EvUsed ${ }_{1}^{\prime}$, and all distinguishers $D_{0} \in \mathcal{D}_{\neg E v U s e d_{1}^{\prime \prime}}$ that run in time at most $t_{D_{0}}$,

$$
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]: D_{0} \vee D_{U 1}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(D_{0} \vee D_{2}^{\prime}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}^{\prime}}\right]+p_{1}\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

In the last equation, we replace $D_{0}$ with $\neg D_{0} \wedge \neg D_{1}$ for $D_{0} \in \mathcal{D}_{\neg \text { EvUsed }}^{1}$, yielding

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]:\left(\neg D_{0} \wedge \neg D_{1}\right) \vee D_{U 1}\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(\left(\neg D_{0} \wedge \neg D_{1}\right) \vee D_{2}^{\prime}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}^{\prime}}\right]+p_{1}\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

so

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(\left(D_{0} \vee D_{1}\right) \wedge \neg D_{2}^{\prime}\right) \vee \text { NonUnique }_{G_{2}, D_{2}^{\prime}}\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]:\left(D_{0} \vee D_{1}\right) \wedge \neg D_{U 1}\right]+p_{1}\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

Then we get

$$
\begin{aligned}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}\right]: D_{0}\right] \leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(D_{0} \vee D_{2}\right) \wedge \neg \operatorname{NonUnique~}_{G_{2}, D_{2}}\right]+p_{0}\left(\mathcal{A}, C, t_{D_{0}}\right) \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(D_{0} \vee D_{1} \vee D_{2}^{\prime}\right) \wedge \neg \text { NonUnique }_{G_{2}, D_{2}^{\prime}}\right]+p_{0}\left(\mathcal{A}, C, t_{D_{0}}\right) \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]:\left(\left(D_{0} \vee D_{1}\right) \wedge \neg D_{2}^{\prime}\right) \vee \text { NonUnique }_{G_{2}, D_{2}^{\prime}}\right] \\
& +\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2}^{\prime} \wedge \neg \text { NonUnique }_{G_{2}, D_{2}^{\prime}}\right]+p_{0}\left(\mathcal{A}, C, t_{D_{0}}\right) \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]:\left(D_{0} \vee D_{1}\right) \wedge \neg D_{U 1}\right] \\
& \quad+p_{1}\left(\mathcal{A}, C, t_{D_{0}}\right)+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2}^{\prime} \wedge \neg \text { NonUnique }_{G_{2}, D_{2}^{\prime}}\right]+p_{0}\left(\mathcal{A}, C, t_{D_{0}}\right) \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}\right]:\left(D_{0} \vee D_{1}\right) \wedge \neg \text { NonUnique }_{G_{1}, D_{1}}\right] \\
& +p_{1}\left(\mathcal{A}, C, t_{D_{0}}\right)+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2}^{\prime} \wedge \neg \text { NonUnique }_{G_{2}, D_{2}^{\prime}}\right]+p_{0}\left(\mathcal{A}, C, t_{D_{0}}\right)
\end{aligned}
$$

so we get the desired result with

$$
p\left(\mathcal{A}, C, t_{D_{0}}\right)=p_{1}\left(\mathcal{A}, C, t_{D_{0}}\right)+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: D_{2}^{\prime} \wedge \neg \operatorname{NonUnique~}_{G_{2}, D_{2}^{\prime}}\right]+p_{0}\left(\mathcal{A}, C, t_{D_{0}}\right)
$$

Computational case (query_equiv with [computational] annotation) As in the decisional case, we want to prove $\mathcal{D}_{\neg \text { EvUsed }_{1}}, \emptyset: G_{0}, D_{\text {false }}, \emptyset \xrightarrow{V} G_{1}, D_{1}, E v U$ sed ${ }_{1}$ where $G_{0}$ contains no events, $D_{1}=e_{1} \vee \ldots \vee e_{m}, e_{1}, \ldots, e_{m}$ are the Shoup events occurring in $G_{1}, e_{1}^{\prime}, \ldots, e_{l}^{\prime}$ are the non-unique events occurring in $G_{1}$, EvUsed $_{1}=\left\{e_{1}, \ldots, e_{m}, e_{1}^{\prime}, \ldots, e_{l}^{\prime}\right\}, V=\emptyset$. Additionally, we want to show that the random values of $G_{0}$ and $G_{1}$ marked [unchanged] can be used in events (different from $e_{1}, \ldots, e_{m}$ since $e_{1}, \ldots, e_{m}$ have no arguments) in the game transformed using this assumption. That corresponds to adding oracles that execute the same arbitrary events using [unchanged] random values to both $G_{0}$ and $G_{1}$. We write $G_{0}^{\prime}$ and $G_{1}^{\prime}$ for the games $G_{0}$ and $G_{1}$ respectively with additional events and show $\mathcal{D}_{\neg \text { EvUsed }_{1},}, \emptyset: G_{0}^{\prime}, D_{\text {false }}$, EvUsed $_{0} \xrightarrow{V}$ $G_{1}^{\prime}, D_{1}, E v U s e d_{1} \cup E v U s e d_{0}$ where $E v U s e d_{0}$ contains these additional events. These additional events can be observed by the adversary, so they are allowed in distinguishers in $\mathcal{D}_{\neg \text { EvUsed }}^{1}$.

Let $D_{U 1}=e_{1}^{\prime} \vee \ldots \vee e_{l}^{\prime}=$ NonUnique $_{G_{1}, D_{1}}$.
Let us write $O_{0}(\widetilde{r}, \widetilde{a r g s})\left(\right.$ resp. $O_{1}(\widetilde{r}, \overrightarrow{a r g s})$ ) for the result of oracle $O$ in game $G_{0}$ (resp. $G_{1}$ ) with randomness $\widetilde{r}$ and arguments $\widetilde{a r g s}$.

In order to establish this property, we show that there exists a mapping $\phi$ of the randomness, such that if random value variable $r$ has value $v$ in $G_{0}$, then it has value $\phi_{r}(v)$ in $G_{1}, \phi_{r}$ is the identity when the variable $r$ is marked [unchanged], $\phi_{r}$ preserves the probability distribution of variable $r$, and we define a game $G_{2}$ in which oracle $O$ with randomness $\widetilde{r}$ and arguments $\widetilde{\arg s}$ returns

$$
\begin{aligned}
& \text { let } x_{0}=O_{0}(\widetilde{r}, \widetilde{\operatorname{args}}) \text { in } \\
& \text { let } x_{1}=O_{1}(\phi(\widetilde{r}), \widetilde{\operatorname{args}}) \text { in } \\
& \text { if } x_{0}=x_{1} \text { then } x_{0} \text { else event_abort distinguish }
\end{aligned}
$$

We bound

$$
\begin{aligned}
p(\mathcal{A}, C) & =\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: \text { distinguish } \vee \text { NonUnique }_{G_{2}, D_{\text {false }}}\right] \\
& =\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: \text { distinguish } \vee D_{U 1}\right] \\
& =\operatorname{Adv}_{G_{2}}\left(\mathcal{A}, C, \text { distinguish } \Rightarrow \text { false, } D_{U 1}\right)
\end{aligned}
$$

From this bound, we infer the desired property.
We consider a game $G_{3}$ in which oracle $O$ returns

$$
\begin{aligned}
& \text { let } x_{0}=O_{0}(\widetilde{r}, \widetilde{\operatorname{args}}) \text { in } \\
& \text { let } x_{1}=O_{1}(\phi(\widetilde{r}), \widetilde{\operatorname{args}}) \text { in } \\
& x_{0}
\end{aligned}
$$

We define $G_{2}^{\prime}$ as $G_{2}$ with the same additional events as in $G_{0}^{\prime}$ and $G_{1}^{\prime}$, and $G_{3}^{\prime}$ as $G_{3}$ with the same additional events as in $G_{0}^{\prime}$ and $G_{1}^{\prime}$. The game $G_{3}^{\prime}$ behaves as $G_{0}^{\prime}$ except that it executes a Shoup event $e_{i}$ or a non-unique event when $G_{1}$ does, so we have, for any $\mathcal{A} \in \mathcal{B B}$ and any evaluation context $C$ acceptable for $G_{0}^{\prime}$ and $G_{3}^{\prime}$ without public variables, and any distinguisher $D_{0}$,

$$
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}^{\prime}\right]: D_{0}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{3}^{\prime}\right]: D_{0} \vee D_{1} \vee D_{U 1}\right]
$$

Moreover, $G_{3}^{\prime}$ behaves as $G_{1}^{\prime}$ except when $G_{2}^{\prime}$ executes event distinguish, that is, when $G_{2}$ executes event distinguish (the additional events introduced in $G_{2}^{\prime}$ are not needed to evaluate the probability of distinguish since we do not consider their probability), so for all $D$,

$$
\begin{equation*}
\left|\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{3}^{\prime}\right]: D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}^{\prime}\right]: D\right]\right| \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: \text { distinguish }\right] \tag{16}
\end{equation*}
$$

Let $C$ be any evaluation context acceptable for $G_{0}^{\prime}$ and $G_{2}^{\prime}$ without public variables and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. By renaming $x_{0}$ and $x_{1}$ to variables not in $C, C$ is also acceptable for $G_{0}^{\prime}$ and $G_{3}^{\prime}$ without public variables. Let $D_{0}$ be any distinguisher. With $D=D_{0} \vee D_{1} \vee D_{U 1}$ in (16), we obtain

$$
\begin{aligned}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{0}^{\prime}\right]: D_{0}\right] \leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{3}^{\prime}\right]: D_{0} \vee D_{1} \vee D_{U 1}\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}^{\prime}\right]: D_{0} \vee D_{1} \vee D_{U 1}\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: \text { distinguish }\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}^{\prime}\right]:\left(D_{0} \vee D_{1}\right) \wedge \neg \operatorname{NonUnique~}_{G_{1}, D_{1}}\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}^{\prime}\right]: D_{U 1}\right] \\
& +\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{2}\right]: \text { distinguish }\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{1}^{\prime}\right]:\left(D_{0} \vee D_{1}\right) \wedge \neg \text { NonUnique }_{G_{1}, D_{1}}\right]+p(\mathcal{A}, C)
\end{aligned}
$$

since $G_{1}^{\prime}$ and $G_{2}$ execute events $D_{U 1}$ in the same cases, and $D_{U 1}$ and distinguish are mutually exclusive. Therefore, we have $\mathcal{D}_{\neg \text { EvUsed }}^{1}$, $\emptyset: G_{0}^{\prime}, D_{\text {false }}$, EvUsed $_{0} \xrightarrow{V}{ }_{p} G_{1}^{\prime}, D_{1}$, EvUsed $_{1} \cup$ EvUsed $_{0}$.

Currently, CryptoVerif can prove query_equiv only when the mapping $\phi$ is the identity for all variables. Other cases can be proved manually and used as assumptions in equiv statements.

## 3 Collecting True Facts

In this section, we consider only processes that satisfy Properties 3 and 4 . We can assume without loss of generality that the adversary context also satisfies these properties: tables (insert and get) can be removed by encoding them using find by transformation expand_tables (Section 5.1.2 and variables defined in conditions of find can be renamed to have distinct names by transformation auto_SArename (Section 5.1.1).

Given a configuration Conf $=E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v$ or Conf $=E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$, we denote by $E_{\text {Conf }}$ the environment $E$ in configuration Conf. We denote by $E_{T r \preceq C o n f}$ the union of $E_{C o n f}$ for all configurations Conf ${ }^{\prime} \preceq_{T r}$ Conf in $\operatorname{Tr}$. It is a set of mappings $x[\overline{\widetilde{a}}] \mapsto b$. At this stage, it may include conflicting mappings $x[\widetilde{a}] \mapsto b$ and $x[\widetilde{a}] \mapsto b^{\prime}$ with $b \neq b^{\prime}$. We prove below (Lemma 29) that this situation never happens. The notation $E_{T r \preceq C o n f}$ is useful because the environment computed in the semantics does not keep the values of variables defined in conditions of find after these conditions are evaluated. Considering the union of all environments of previous configurations allows us to recover the values of these variables, and to use them in the facts that we collect. Given a configuration Conf $=E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v$ or $\operatorname{Conf}=E,(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r$, $\mathcal{T}, \mu \mathcal{E} v$, we denote by $\sigma_{\text {Conf }}$ the mapping sequence for replication indices $\sigma$ in the configuration Conf and by $\mu \mathcal{E} v_{\text {Conf }}$ the sequence of events $\mu \mathcal{E} v$ in configuration Conf.

Let us define Defined as in Section 2.4.3, except that
$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ find $[$ unique $?]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{[i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$ suchthat defined $\left(\widetilde{M_{j}}\right) \wedge M_{j}$ then $\left.N_{j}\right)$ else $\left.N\right)=$

$$
\left.\left(\biguplus_{j=1}^{m} \biguplus_{\widetilde{a} \leq \widetilde{n_{j}}} \operatorname{Defined}\left(\sigma\left[\widetilde{i_{j}} \mapsto \widetilde{a}\right], M_{j}\right)\right) \uplus \max \left(\max _{j=1}^{m}\left(\left\{\widetilde{u_{j}}[\sigma \widetilde{i})\right]\right\} \uplus \operatorname{Defined}\left(\sigma, N_{j}\right)\right), \operatorname{Defined}(\sigma, N)\right)
$$

$\operatorname{Defined}\left(\sigma,{ }^{\mu}\right.$ find $[$ unique $?]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{[i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$ suchthat defined $\left(\widetilde{M_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $\left.P\right)=$

$$
\left(\biguplus_{j=1}^{m} \biguplus_{\widetilde{a} \leq \widetilde{n_{j}}} \operatorname{Defined}\left(\sigma\left[\widetilde{i_{j}} \mapsto \widetilde{a}\right], M_{j}\right)\right) \uplus \max \left(\max _{j=1}^{m}\left(\left\{\widetilde{u_{j}}[\sigma(\widetilde{i})]\right\} \uplus \operatorname{Defined}\left(\sigma, P_{j}\right)\right), \operatorname{Defined}(\sigma, P)\right)
$$

so that the variables defined in conditions of find are now considered as defined forever, and not
temporarily during the evaluation of the considered condition. We also define

$$
\operatorname{Defined}(\operatorname{Tr} \preceq C o n f)=\operatorname{Dom}\left(E_{T r \preceq C o n f}\right) \uplus \text { Defined }^{\text {Fut }}(\text { Conf }) .
$$

Lemma 29 Let $Q_{0}$ be a process that satisfies Properties 3 and 4 Let $\operatorname{Tr}$ be a trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$ and Conf be a configuration in the derivation of Tr. Then the following properties hold:

1. Defined $(\operatorname{Tr} \preceq$ Conf $)$ does not contain duplicate elements.
2. Each variable is defined at most once for each value of its array indices in Tr .
3. $E_{T r \preceq C o n f}$ contains at most one binding for each $x[\widetilde{a}]$.

Proof sketch The proof is similar to the proof of Lemma 9 . We first show as in Lemma 9 that, for all program points $\mu$ in $Q_{0}$, if $\operatorname{Dom}(\sigma)=I_{\mu}$ are the current replication indices at $\mu$ and the process or term $Q$ at $\mu$ satisfies Invariant 1, then all elements of $\operatorname{Defined}(\sigma, Q)$ are of the form $x[\widetilde{a}]$ where $x \in \operatorname{vardef}(Q)$ and $\operatorname{Im}(\sigma)$ is a prefix of $\widetilde{a}$.

Next, we show that, for all program points $\mu$, if $\operatorname{Dom}(\sigma)=I_{\mu}$ are the current replication indices at $\mu$ and the process or term $Q$ at $\mu$ satisfies Invariant 1, then $\operatorname{Defined}(\sigma, Q)$ does not contain duplicate elements. The proof proceeds by induction on $Q$. All multiset unions in the computation of $\operatorname{Defined}(\sigma, Q)$ are disjoint unions by the property above, because either they use different extensions of $\sigma$ (cases of replication and of conditions of find) or they use disjoint variable definitions or subprocesses or subterms in the same branch of find or if, which must define different variables by Invariant 1 and by Property 4.

We show by induction on the derivations that, if Conf $\xrightarrow[\rightarrow]{p}_{t}$ Conf $^{\prime}$, then Defined $(\operatorname{Tr} \preceq \operatorname{Conf}) \supseteq$ Defined ( $\operatorname{Tr} \preceq$ Conf $^{\prime}$ ) and for all semantic configurations Conf ${ }^{\prime \prime}$ in the derivation of Conf $\xrightarrow{p}_{t}$ Conf ${ }^{\prime}$, Defined $(\operatorname{Tr} \preceq \operatorname{Conf}) \supseteq \operatorname{Defined}\left(\operatorname{Tr} \preceq\right.$ Conf $\left.^{\prime \prime}\right)$, and similarly with $\rightsquigarrow$ instead of $\xrightarrow{p}_{t}$.

The first result follows: since $Q_{0}$ satisfies Invariant 1, Defined $\left(\sigma_{0}, Q_{0}\right)$ does not contain duplicate elements, where $\sigma_{0}$ is the empty mapping sequence. Let $\operatorname{Conf}_{0}=\left\{\left(\sigma_{0}, Q_{0}\right)\right\},\left(\mathrm{fo}\left(Q_{0}\right), \emptyset\right)$, $\operatorname{Conf}_{1}=\operatorname{reduce}\left(\left\{\left(\sigma_{0}, Q_{0}\right)\right\},\left(\operatorname{fo}\left(Q_{0}\right), \emptyset\right)\right), \operatorname{Conf}_{2}=\operatorname{initConfig}\left(Q_{0}, \mathcal{A}\right)$, and $\operatorname{Conf}_{3}$ be any other configuration of Tr. Then Defined $\left(\operatorname{Tr} \preceq \operatorname{Conf}_{0}\right)$, Defined $\left(\operatorname{Tr} \preceq \operatorname{Conf}_{1}\right)$, Defined $\left(\operatorname{Tr} \preceq \operatorname{Conf}_{2}\right)$, and therefore $\operatorname{Defined}\left(\operatorname{Tr} \preceq \operatorname{Conf}_{3}\right)$ do not contain duplicate elements.

Let us prove the second result. In order to derive a contradiction, assume that two transitions $\operatorname{Conf}_{1} \xrightarrow{p_{1}}{ }_{t_{1}}$ Conf $_{1}^{\prime}$ and $\operatorname{Conf}_{2} \xrightarrow[t_{2}]{p_{2}} \operatorname{Conf}_{2}^{\prime}$ inside $\operatorname{Tr}$ define the same variable $x[\widetilde{a}]$.

- First case: one transition happens before the other, for instance $\operatorname{Conf}_{1}^{\prime} \preceq{ }_{T r} \operatorname{Conf}_{2}$. (The case $\operatorname{Conf}_{2}^{\prime} \preceq \operatorname{Tr} \operatorname{Conf}_{1}$ is symmetric.) Since $\operatorname{Conf}_{1} \xrightarrow{p_{1}} t_{1} \operatorname{Conf}_{1}^{\prime}$ defines $x[\widetilde{a}]$, we have $x[\widetilde{a}] \in \operatorname{Dom}\left(E_{\text {Conf }_{1}^{\prime}}\right)$, so $x[\widetilde{a}] \in \operatorname{Dom}\left(E_{T r \preceq C o n f_{2}}\right)$. Moreover, since $\operatorname{Conf}_{2} \xrightarrow{p_{2}}{ }_{t_{2}}$ Conf $_{2}^{\prime}$ defines $x[\widetilde{a}]$, we have $x[\widetilde{a}] \in \operatorname{Defined}^{\text {Fut }}\left(\operatorname{Conf}_{2}\right)$, by inspecting all rules that add elements to the environment. Therefore $\operatorname{Defined}\left(\operatorname{Tr} \preceq \operatorname{Conf}_{2}\right)=\operatorname{Dom}\left(E_{T r} \preceq \operatorname{Conf}_{2}\right) \uplus \operatorname{Defined}^{\text {Fut }}\left(\operatorname{Conf}_{2}\right)$ contains twice $x[\widetilde{a}]$. Contradiction.
- Second case: the transitions cannot be ordered. By definition of $\preceq_{T r}$, this can happen only when a semantic rule uses several derivations for its assumptions, which happens only in rules for find. (Recall that get is excluded by Property 3.) Therefore, there exists $k_{1}$ and $k_{2}$ such that $\operatorname{Conf}_{1} \xrightarrow{p_{1}}{t_{1}}^{\operatorname{Conf}}{ }_{1}^{\prime}$ is in the derivation of $\operatorname{Conf}_{0, k}=$ $E, \sigma\left[\widetilde{i_{j_{k}}} \mapsto \widetilde{a}_{k}\right], D_{j_{k}} \wedge M_{j_{k}}, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p_{t}}{ }_{t_{k}}^{*} \operatorname{Conf}{ }_{0, k}^{\prime}=E_{k}, \sigma_{k}, r_{k}, \mathcal{T}, \mu \mathcal{E} v$ with $v_{k}=\left(j_{k}, \widetilde{a}_{k}\right)$
 have $x[\widetilde{a}] \in \operatorname{Defined}\left(\operatorname{Tr} \preceq \operatorname{Conf}_{0, k_{1}}^{\prime}\right) \subseteq \operatorname{Defined}\left(\operatorname{Tr} \preceq \operatorname{Conf}_{0, k_{1}}\right)=\operatorname{Dom}\left(E_{\operatorname{Tr} \preceq \operatorname{Conf}_{0, k_{1}}}\right) \cup$
$\operatorname{Defined}\left(\sigma\left[\widetilde{i_{j_{k_{1}}}} \mapsto \widetilde{a}_{k_{1}}\right], M_{j_{k_{1}}}\right)$. Moreover, $\operatorname{Conf}_{0, k} \preceq \operatorname{Conf}_{1}$, so $\operatorname{Dom}\left(E_{T r \preceq \operatorname{Conf}_{0, k_{1}}}\right) \subseteq$ $\operatorname{Dom}\left(E_{T r} \preceq\right.$ Conf $\left._{1}\right)$. Since $\operatorname{Conf}_{1} \xrightarrow{p_{1}} t_{1} \operatorname{Conf}_{1}^{\prime}$ defines $x[\widetilde{a}]$, we have $x[\widetilde{a}] \in \operatorname{Defined}^{\text {Fut }}\left(\operatorname{Conf}_{1}\right)$, by inspecting all rules that add elements to the environment. Since Defined $\left(\operatorname{Tr} \preceq \operatorname{Conf}_{1}\right)=$ $\operatorname{Dom}\left(E_{T r \preceq \operatorname{Conf}_{1}}\right) \uplus$ Defined $^{\text {Fut }}\left(\operatorname{Conf}_{1}\right)$ does not contain duplicate elements, we have $x[\widetilde{a}] \notin$ $\operatorname{Dom}\left(E_{T r \preceq \operatorname{Conf}_{1}}\right)$, so $x[\widetilde{a}] \notin \operatorname{Dom}\left(E_{T r \preceq C o n f_{0, k_{1}}}\right)$. Hence $x[\widetilde{a}] \in \operatorname{Defined}\left(\sigma\left[\widetilde{i_{j_{k_{1}}}} \mapsto \widetilde{a}_{k_{1}}\right], M_{j_{k_{1}}}\right)$. Similarly, $x[\widetilde{a}] \in \operatorname{Defined}\left(\sigma\left[\widetilde{i_{j_{k_{2}}}} \mapsto \widetilde{a}_{k_{2}}\right], M_{j_{k_{2}}}\right)$. Let us show that the sets Defined $\left(\sigma \widetilde{\left(i_{j_{k_{1}}}\right.} \mapsto\right.$ $\left.\left.\widetilde{a}_{k_{1}}\right], M_{j_{k_{1}}}\right)$ and $\left.\operatorname{Defined}\left(\sigma \widetilde{i_{j_{k_{2}}}} \mapsto \widetilde{a}_{k_{2}}\right], M_{j_{k_{2}}}\right)$ are disjoint. We have $v_{k_{1}} \neq v_{k_{2}}$, so either $j_{k_{1}} \neq j_{k_{2}}$ and in this case these sets are disjoint because $M_{j_{k_{1}}}$ and $M_{j_{k_{2}}}$ define different variables by Property 4, or $j_{k_{1}}=j_{k_{2}}$ and $\widetilde{a}_{k_{1}} \neq \widetilde{a}_{k_{2}}$ and in this case these sets are disjoint because they use different extensions of $\sigma$. Since these sets are disjoint, they cannot both contain $x[\tilde{a}]$. Contradiction.
The last result is an immediate consequence of the second one.
Lemma 30 Let $Q_{0}$ be a process that satisfies Properties 3 and 4 Let $\operatorname{Tr}$ be a trace of $Q_{0}$ for any $\mathcal{A} \in \mathcal{B B}$ and Conf be a configuration in the derivation of Tr. We have $E_{T r} \preceq$ Conf $=E_{\text {Conf }}[x[\widetilde{a}] \mapsto$ $b$ for some variables $x$ defined in a condition of find and some indices $\widetilde{a}$ and values $b$ ].

Proof sketch By induction on the derivation.
The previous lemma shows that the only difference between $E_{C o n f}$ and $E_{T r \preceq C o n f}$ is that variables defined in conditions of find are added to $E_{T r \preceq C o n f}$. These variables have no array accesses, so they do not appear in defined conditions of find. Therefore, these defined conditions yield the same result whether they are evaluated in $E_{\text {Conf }}$ or in $E_{T r \preceq C o n f}$.

We consider the following facts:

- The boolean term $M$ means that $M$ evaluates to true.
- defined $(M)$ means that $M$ is defined (all array accesses in $M$ are defined).
- event $(e(\widetilde{M}))$ means that event $e(\widetilde{M})$ has been executed.
- event $(e(\widetilde{M})) @ \tau$ means that event $e(\widetilde{M})$ has been executed at step $\tau$ (index in the sequence of events $\mu \mathcal{E} v$ ).
- $M_{1}$ : event $(e(\widetilde{M}))$ means that event $e(\widetilde{M})$ has been executed with pair (program point, replication indices) equal to $M_{1}$.
- $M_{1}$ : event $(e(\widetilde{M})) @ \tau$ means that event $e(\widetilde{M})$ has been executed at step $\tau$ with pair (program point, replication indices) equal to $M_{1}$.
- programpoint $(\mu, \widetilde{M})$ means that program point $\mu$ has been executed with replication indices equal to $\widetilde{M}$.
- $\operatorname{programpoint}\left(\mathcal{S}_{1}, \widetilde{M}_{1}\right) \preceq \ldots \preceq \operatorname{programpoint}\left(\mathcal{S}_{m}, \widetilde{M}_{m}\right)$ means that, for $j \leq m$, some program point $\mu_{j} \in \mathcal{S}_{j}$ has been executed with replication indices equal to $\widetilde{M}_{j}$, and furthermore these program points have been executed in the order of increasing $j$.
- lastdefprogrampoint $(\mu, \widetilde{M})$ means that program point $\mu$ has been executed with replication indices equal to $\widetilde{M}$ and the values of variables and replication indices are unchanged since that program point (that is, no variable definition nor oracle call, return, or yield that changes the replication indices was executed since that program point).

Given an environment $E$ mapping process variables to their values, an environment $\rho$ mapping replication indices and non-process variables of the formula $\varphi$ to their values, and a sequence of events $\mu \mathcal{E} v$, we define $E, \rho, \mu \mathcal{E} v \vdash \varphi$, meaning that $E, \rho, \mu \mathcal{E} v$ satisfy $\varphi$, as follows:

- $E, \rho, \mu \mathcal{E} v \vdash M$ if and only if $E, \rho, M \Downarrow$ true.
- $E, \rho, \mu \mathcal{E} v \vdash \operatorname{defined}(M)$ if and only if $E, \rho, M \Downarrow a$ for some $a$.
- $E, \rho, \mu \mathcal{E} v \vdash \operatorname{event}(e(\widetilde{M}))$ if and only if $E, \rho, \widetilde{M} \Downarrow \widetilde{a}$ and $\left(\mu, \widetilde{a^{\prime}}\right): e(\widetilde{a}) \in \mu \mathcal{E} v$ for some $\mu$ and $\widetilde{a^{\prime}}$.
- $E, \rho, \mu \mathcal{E} v \vdash \operatorname{event}(e(\widetilde{M})) @ M_{0}$ if and only if $E, \rho, \widetilde{M} \Downarrow \widetilde{a}, E, \rho, M_{0} \Downarrow a_{0}$, and $\mu \mathcal{E} v\left(a_{0}\right)=$ $\left(\mu, \widetilde{a^{\prime}}\right): e(\widetilde{a})$ for some $\mu$ and $\widetilde{a^{\prime}}$.
- $E, \rho, \mu \mathcal{E} v \vdash M_{1}: \operatorname{event}(e(\widetilde{M}))$ if and only if $E, \rho, \widetilde{M} \Downarrow \widetilde{a}, E, \rho, M_{1} \Downarrow\left(\mu, \widetilde{a^{\prime}}\right)$ and $\left(\mu, \widetilde{a^{\prime}}\right)$ : $e(\widetilde{a}) \in \mu \mathcal{E} v$.
- $E, \rho, \mu \mathcal{E} v \vdash M_{1}: \operatorname{event}(e(\widetilde{M})) @ M_{0}$ if and only if $E, \rho, \widetilde{M} \Downarrow \widetilde{a}, E, \rho, M_{0} \Downarrow a_{0}, E, \rho, M_{1} \Downarrow$ $\left(\mu, \widetilde{a^{\prime}}\right)$, and $\mu \mathcal{E} v\left(a_{0}\right)=\left(\mu, \widetilde{a^{\prime}}\right): e(\widetilde{a})$.
Logical connectives are defined as usual. When $\varphi$ does not contain events, $\mu \mathcal{E} v$ can be omitted, writing $E, \rho \vdash \varphi$.

Let $\mathcal{A}$ be an attacker in $\mathcal{B B}$ and $\operatorname{Tr}$ be a trace of $Q_{0}$ for attacker $\mathcal{A}$. Let $\operatorname{Conf}=E, \sigma, N, \mathcal{T}, \mu \mathcal{E} v$ or Conf $=E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ be a configuration that occurs in the derivation of $\operatorname{Tr}$. We define $\operatorname{Tr} \preceq C o n f, \rho \vdash \varphi$, meaning that the prefix of $\operatorname{Tr}$ until Conf satisfies the formula $\varphi$ with environment $\rho$ (giving values of non-process variables of $\varphi$ ) as follows:

- $\operatorname{Tr} \preceq \operatorname{Conf}, \rho \vdash F$ if and only if $E_{T r \preceq C o n f}, \sigma_{\text {Conf }} \cup \rho, \mu \mathcal{E} v_{\text {Conf }} \vdash F$, when $F$ is a term $M$, a defined fact defined $(M)$, or an event event $(e(\widetilde{M}))$, event $(e(\widetilde{M})) @ M_{0}, M_{1}$ : event $(e(\widetilde{M}))$, or $M_{1}: \operatorname{event}(e(\widetilde{M})) @ M_{0}$.
- $\operatorname{Tr} \preceq \operatorname{Conf}, \rho \vdash \operatorname{programpoint}\left(\mathcal{S}_{1}, \widetilde{M}_{1}\right) \preceq \ldots \preceq \operatorname{programpoint}\left(\mathcal{S}_{m}, \widetilde{M}_{m}\right)$ if and only if, for all $j \in\{1, \ldots, m\}$, there exists $\operatorname{Conf}_{j}$ at program point $\mu_{j} \in \mathcal{S}_{j}$ in $\operatorname{Tr}$ such that $E_{T r} \preceq \operatorname{Conf}, \sigma_{C o n f} \cup \rho, \widetilde{M}_{j} \Downarrow \operatorname{Im}\left(\sigma_{C o n f_{j}}\right)$ and $\operatorname{Conf}_{1} \preceq_{T r} \ldots \preceq_{T r} \operatorname{Conf}_{m} \preceq_{T r} \operatorname{Conf}$.
The fact programpoint $(\mu, \widetilde{M})$ is actually a particular case of programpoint $\left(\mathcal{S}_{1}, \widetilde{M}_{1}\right) \preceq \ldots$ $\preceq \operatorname{programpoint}\left(\mathcal{S}_{m}, \widetilde{M}_{m}\right)$ with $m=1$ and $\mathcal{S}_{1}=\{\mu\}$. Hence, we have $\operatorname{Tr} \preceq \operatorname{Conf}, \rho \vdash$ programpoint $(\mu, \widetilde{M})$ if and only if there is a configuration Conf ${ }^{\prime}$ at program point $\mu$ in $\operatorname{Tr}$ such that Conf $\preceq_{T r}$ Conf and $E_{T r \preceq C o n f}, \sigma_{\text {Conf }} \cup \rho, \widetilde{M} \Downarrow \operatorname{Im}\left(\sigma_{\text {Conf }}\right)$.
- $\operatorname{Tr} \preceq$ Conf,$\rho \vdash$ lastdefprogrampoint $(\mu, \widetilde{M})$ if and only if there is a configuration Conf ${ }^{\prime}$ at program point $\mu$ in $\operatorname{Tr}$ such that $C_{o n f}{ }^{\prime} \preceq \operatorname{Tr}$ Conf, $E_{T r \preceq C o n f^{\prime}}=E_{T r \preceq C o n f}, \sigma_{C o n f^{\prime}}=\sigma_{C o n f}$, and $E_{T r \preceq C o n f}, \sigma_{\text {Conf }} \cup \rho, \widetilde{M} \Downarrow \operatorname{Im}\left(\sigma_{\text {Conf }}\right)$.

Logical connectives are defined as usual. Most facts are evaluated in the environment $E_{T r \preceq C o n f}$ and the mapping sequence $\sigma_{\text {Conf }}$. Events are evaluated using the sequence of events $\mu \mathcal{E} v_{\text {Conf }}$ in Conf, but correspond to an execution of the event at some point before Conf in the trace.

We define that a trace $\operatorname{Tr}$ satisfies a logical formula $\varphi$ with environment $\rho$ (giving values of non-process variables of $\varphi$ ), denoted $\operatorname{Tr}, \rho \vdash \varphi$ as $\operatorname{Tr} \preceq \operatorname{Conf}, \rho \vdash \varphi$, where $\operatorname{Tr}$ ends with Conf. Along the same line, we define $E_{T r}=E_{T r} \preceq C_{o n f}$ and $\mu \mathcal{E} v_{T r}=\mu \mathcal{E} v_{C o n f}$ where $\operatorname{Tr}$ ends with Conf.

When the formula $\varphi$ does not contain free non-process variables, we may write $\operatorname{Tr} \vdash \varphi$ instead of $\operatorname{Tr}, \rho \vdash \varphi$ since the environment $\rho$ is useless. When $\mathcal{F}$ is a set of formulas (in particular, of
facts), we write $\bigwedge \mathcal{F}$ for $\bigwedge_{F \in \mathcal{F}} F$ and $\bigvee \mathcal{F}$ for $\bigvee_{F \in \mathcal{F}} F$. We also write $\operatorname{Tr}, \rho \vdash \mathcal{F}$ when for all $\varphi \in \mathcal{F}, \operatorname{Tr}, \rho \vdash \varphi$. This is equivalent to $\operatorname{Tr}, \rho \vdash \bigwedge \mathcal{F}$. We use similar notations for prefixes $\operatorname{Tr} \preceq$ Conf instead of traces $\operatorname{Tr}$.

Additionally, we define the following facts:

- $\llbracket$ elsefind $\left(\left(i_{1} \leq n_{1}, \ldots, i_{m} \leq n_{m}\right),\left(M_{1}, \ldots, M_{l}\right), M\right) \rrbracket=\forall i_{1} \in\left[1, n_{1}\right], \ldots, \forall i_{m} \in\left[1, n_{m}\right]$, $\neg\left(\right.$ defined $\left(M_{1}\right) \wedge \cdots \wedge$ defined $\left.\left(M_{l}\right) \wedge M\right)$.
- $\llbracket \operatorname{elselet}(\widetilde{x}: \widetilde{T}, N, M) \rrbracket=\forall \widetilde{x} \in \widetilde{T}, N \neq M$.

Extension: The following description is based on the first version of the collection of known facts. Many improvements and extensions have been implemented. In particular, the following description often uses $P$ instead of $\mu$ for program points; the syntax does not allow $\stackrel{R}{\leftarrow}$, if, let, find in terms; events are not handled.

### 3.1 User-defined Rewrite Rules

The user can give two kinds of information:

- claims of the form $\forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m}, M$ which mean that for all environments $E$, if for all $j \leq m, E\left(x_{j}\right) \in T_{j}$, then $E, M \Downarrow$ true.
Such claims must be well-typed, that is, $\left\{x_{1} \mapsto T_{1}, \ldots, x_{m} \mapsto T_{m}\right\} \vdash M$ : bool.
They are translated into rewrite rules as follows:
- If $M$ is of the form $M_{1}=M_{2}$ and $\operatorname{vardef}\left(M_{2}\right) \subseteq \operatorname{vardef}\left(M_{1}\right)$, we generate the rewrite rule $\forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m}, M_{1} \rightarrow M_{2}$.
- If $M$ is of the form $M_{1} \neq M_{2}$, we generate the rewrite rules $\forall x_{1}: T_{1}, \ldots, \forall x_{m}$ : $T_{m},\left(M_{1}=M_{2}\right) \rightarrow$ false, $\forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m},\left(M_{1} \neq M_{2}\right) \rightarrow$ true. (Such rules are used for instance to express that different constants are different.)
- Otherwise, we generate the rewrite rule $\forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m}, M \rightarrow$ true.

The term $M$ reduces into $M^{\prime}$ by the rewrite rule $\forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m}, M_{1} \rightarrow M_{2}$ if and only if $M=C\left[\sigma M_{1}\right], M^{\prime}=C\left[\sigma M_{2}\right]$, where $C$ is a term context and $\sigma$ is a substitution that maps $x_{j}$ to any term of type $T_{j}$ for all $j \leq m$.

- claims of the form $y_{1} \stackrel{R}{\leftarrow} T_{1}^{\prime}, \ldots, y_{l} \stackrel{R}{\leftarrow} T_{l}^{\prime}, \forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m}, M_{1} \approx_{p} \quad M_{2}$ with $\operatorname{vardef}\left(M_{2}\right) \subseteq \operatorname{vardef}\left(M_{1}\right)$. Informally, these claims mean that $M_{1}$ and $M_{2}$ evaluate to the same bitstring except in cases of probability at most $p$, provided that $y_{1}, \ldots, y_{l}$ are chosen randomly with uniform probability and independently among $T_{1}^{\prime}, \ldots, T_{l}^{\prime}$ respectively, and that $x_{1}, \ldots, x_{m}$ are of type $T_{1}, \ldots, T_{m} .\left(x_{1}, \ldots, x_{m}\right.$ may depend on $\left.y_{1}, \ldots, y_{l}.\right)$ Formally, these claims are defined as:

$$
\begin{aligned}
& \operatorname{Pr}\left[E\left(y_{1}\right) \stackrel{R}{\leftarrow} T_{1}^{\prime} ; \ldots E\left(y_{l}\right) \stackrel{R}{\leftarrow} T_{l}^{\prime}\right. \\
& \quad\left(E\left(x_{1}\right), \ldots, E\left(x_{m}\right)\right) \leftarrow \mathcal{A}\left(E\left(y_{1}\right), \ldots, E\left(y_{l}\right)\right) \\
& \left.\quad E, M_{1} \Downarrow a ; E, M_{2} \Downarrow a^{\prime}: a \neq a^{\prime}\right] \leq p(\mathcal{A})
\end{aligned}
$$

where $\mathcal{A}$ is an attacker in $\mathcal{B B}$.
The above claim must be well-typed, that is, $\left\{x_{1} \mapsto T_{1}, \ldots, x_{m} \mapsto T_{m}, y_{1} \mapsto T_{1}^{\prime}, \ldots\right.$, $\left.y_{l} \mapsto T_{l}^{\prime}\right\} \vdash M_{1}=M_{2}$.
This claim is translated into the rewrite rule $y_{1} \stackrel{R}{\leftarrow} T_{1}^{\prime}, \ldots, y_{l} \stackrel{R}{\leftarrow} T_{l}^{\prime}, \forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m}$, $M_{1} \rightarrow M_{2}$.

The prover has built-in rewrite rules for defining boolean functions:

```
\(\neg\) true \(\rightarrow\) false \(\quad \neg\) false \(\rightarrow\) true \(\quad \forall x:\) bool,\(\neg(\neg x) \rightarrow x\)
\(\forall x: T, \forall y: T, \neg(x=y) \rightarrow x \neq y\)
\(\forall x: T, \forall y: T, \neg(x \neq y) \rightarrow x=y\)
\(\forall x: T, x=x \rightarrow\) true \(\quad \forall x: T, x \neq x \rightarrow\) false
\(\forall x\) : bool, \(\forall y\) : bool, \(\neg(x \wedge y) \rightarrow(\neg x) \vee(\neg y)\)
\(\forall x\) : bool, \(\forall y\) : bool, \(\neg(x \vee y) \rightarrow(\neg x) \wedge(\neg y)\)
\(\forall x:\) bool, \(x \wedge\) true \(\rightarrow x \quad \forall x:\) bool, \(x \wedge\) false \(\rightarrow\) false
\(\forall x:\) bool, \(x \vee\) true \(\rightarrow\) true \(\quad \forall x:\) bool, \(x \vee\) false \(\rightarrow x\)
\(\forall x: T, \forall y: T\), if_fun(true, \(x, y) \rightarrow x \quad \forall x: T, \forall y: T\), if_fun(false, \(x, y) \rightarrow y\)
\(\forall x:\) bool, \(\forall y: T\), if_fun \((x, y, y) \rightarrow y\)
\(\forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m}, \forall x:\) bool \(, \forall y: T_{k}, \forall z: T_{k}\),
    \(f\left(x_{1}, \ldots, x_{k-1}\right.\), if_fun \(\left.(x, y, z), x_{k+1}, \ldots, x_{m}\right) \rightarrow\)
    if_fun \(\left(x, f\left(x_{1}, \ldots, x_{k-1}, y, x_{k+1}, \ldots, x_{m}\right), f\left(x_{1}, \ldots, x_{k-1}, z, x_{k+1}, \ldots, x_{m}\right)\right)\)
    when \(f: T_{1} \times \ldots \times T_{m} \rightarrow T\) has option autoSwapIf
```

The prover also has support for commutative function symbols, that is, binary function symbols $f: T \times T \rightarrow T^{\prime}$ such that for all $x, y \in T, f(x, y)=f(y, x)$. For such symbols, all equality and matching tests are performed modulo commutativity. The functions $\wedge, \vee,=$, and $\neq$ are commutative. So, for instance, the rewrite rules above may also be used to rewrite true $\wedge M$ into $M$, false $\wedge M$ into false, true $\vee M$ into true, and false $\vee M$ into $M$. Used-defined functions may also be declared commutative; xor is an example of such a commutative function.

Example 4 For example, considering MAC and encryption schemes as in Definitions 2 and 3 respectively, we have:

$$
\begin{align*}
& \forall k: T_{m k}, \forall m: \text { bitstring }, \\
& \quad \text { verify }(m, k, \operatorname{mac}(m, k))=\text { true }  \tag{mac}\\
& \forall m: \operatorname{bitstring} ; \forall k: T_{k}, \forall r: T_{r}, \\
& \quad \operatorname{dec}(\operatorname{enc}(m, k, r), k)=\mathrm{i}_{\perp}(m) \tag{enc}
\end{align*}
$$

We express the poly-injectivity of the function k 2 b of Example 1 by

$$
\begin{align*}
& \forall x: T_{k}, \forall y: T_{k},(\mathrm{k} 2 \mathrm{~b}(x)=\mathrm{k} 2 \mathrm{~b}(y))=(x=y) \\
& \forall x: T_{k}, \mathrm{k}^{2} \mathrm{~b}^{-1}(\mathrm{k} 2 \mathrm{~b}(x))=x \tag{k2b}
\end{align*}
$$

where $k 2 b^{-1}$ is a function symbol that denotes the inverse of $k 2 b$. We have similar formulas for $\mathrm{i}_{\perp}$.

### 3.2 Collecting True Facts from a Game

We use facts to represent properties that hold at certain program points in processes. We consider two kinds of facts: defined $(M)$ means that $M$ is defined, and a term $M$ means that $M$ is true (the boolean term $M$ evaluates to true). In this section, we show how to compute a set of facts $\mathcal{F}_{\mu}$ that are guaranteed to hold at the program point $\mu$ of the game.

The function collectFacts collects facts that hold at each program point of the game. More precisely, for each program point $\mu$ in the game, it computes a set $\mathcal{F}_{\mu}$ of facts that hold at that program point. The function collectFacts also computes a set $\mathcal{D}$ containing pairs (x[ז्i], $\mu$ ) where $x[\widetilde{i}]$ has been defined immediately above program point $\mu$. (If there are several definitions of $x$, there is one such pair for each definition of $x$.) Finally, for oracle bodies $P$, collectFacts $(P)$ returns a set of facts that will hold when the return is executed and stores this set in $\mathcal{F}_{P}^{\mathrm{Fut}}$. (The superscript Fut stands for future, since these facts do not hold yet at $P$, but will hold in the future.)

The function collectFacts is defined in Figure 18. It is initially called by collectFacts $\left(Q_{0}\right)$. It takes into account that $x \widetilde{i}]$ may be defined by an oracle definition, a random choice, a let, or a find and updates $\mathcal{D}$ accordingly. Furthermore, when we execute let $x \widetilde{i}]: T=M$ in $\left.P^{\prime}, x \widetilde{i}\right]=M$ holds in $P^{\prime}$ and $x[\widetilde{i}]$ is defined in $P^{\prime}$. When we execute find $\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]}=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}}[\widetilde{i}]=\right.$ $i_{j m_{j}} \leq n_{j m_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $\left.P^{\prime}, u_{j 1} \widetilde{[i]}, \ldots, u_{j m_{j}} \widetilde{i}\right], \sigma M_{j 1}, \ldots$, $\sigma M_{j l_{j}}$ are defined in $P_{j}, \sigma M_{j}$ holds in $P_{j}$ where $\left.\sigma=\left\{u_{j 1}[\widetilde{i}] / i_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right] / i_{j m_{j}}\right\}$, and $\neg M_{j}$ holds in $P^{\prime}$ when $m_{j}=l_{j}=0$.

After calling collectFacts $\left(Q_{0}\right)$, we complete the computed sets $\mathcal{F}_{P}$ (where $P$ may be an oracle definition or body) by adding facts that come from processes above $P$ :

$$
\mathcal{F}_{P} \leftarrow \mathcal{F}_{P} \cup \mathcal{F}_{P^{\prime}} \text { if } P \text { is immediately under } P^{\prime}
$$

We also add facts that we can deduce from facts defined $(M)$. Precisely, if defined $(M) \in \mathcal{F}_{P}$ and $x\left[M_{1}, \ldots, M_{m}\right]$ is a subterm of $M$, then we take into account facts that are known to be true at the definitions of $x$ by adding them to $\mathcal{F}_{P}$ as follows:

$$
\mathcal{F}_{P} \leftarrow \mathcal{F}_{P} \cup\left(\begin{array}{ll}
\bigcap_{\left(x\left[i_{1}, \ldots, i_{m}\right], P^{\prime}\right) \in \mathcal{D}} & \left\{\begin{array}{ll}
\sigma\left(\mathcal{F}_{P^{\prime}} \cup\left(\mathcal{F}_{P^{\prime}}^{\mathrm{Fut}} \cap \mathcal{F}_{P}\right)\right) & \text { if } P \text { is under } P^{\prime} \\
\sigma\left(\mathcal{F}_{P^{\prime}} \cup \mathcal{F}_{P^{\prime}}^{\mathrm{Fut}}\right) & \text { otherwise }
\end{array}\right) .
\end{array}\right.
$$

where $\sigma=\left\{M_{1} / i_{1}, \ldots, M_{m} / i_{m}\right\}$. Indeed, if defined $(M) \in \mathcal{F}_{P}$ and $x\left[M_{1}, \ldots, M_{m}\right]$ is a subterm of $M$, then $x\left[M_{1}, \ldots, M_{m}\right]$ is defined at $P$, so some definition of $x\left[M_{1}, \ldots, M_{m}\right]$, immediately above the process $P^{\prime}$, must have been executed before reaching $P$, so the facts that hold at $P^{\prime}$ also hold at $P$, with a suitable substitution of indices: we have $\sigma \mathcal{F}_{P^{\prime}}$, that is, $\mathcal{F}_{P^{\prime}}\left\{M_{1} / i_{1}, \ldots\right.$, $\left.M_{m} / i_{m}\right\}$. Moreover, if the occurrence $P$ is not syntactically under the occurrence $P^{\prime}$, then the code of $P^{\prime}$ must have been executed until the next return before yielding control to some other code and reaching $P$, so in fact $\sigma\left(\mathcal{F}_{P^{\prime}} \cup \mathcal{F}_{P^{\prime}}^{\mathrm{Fut}}\right)$ hold. If $P$ is syntactically under $P^{\prime}$, it is possible that the code of $P^{\prime}$ has been executed until reaching $P$ instead of until reaching the next return or yield, so we have only $\sigma\left(\mathcal{F}_{P^{\prime}} \cup\left(\mathcal{F}_{P^{\prime}}^{\mathrm{Fut}} \cap \mathcal{F}_{P}\right)\right)$. If there are several definitions of $x$, we do not know which one has been executed, so we only add to $\mathcal{F}_{P}$ the facts that hold in all cases, by taking the intersection on all definitions of $x$.

This operation may add new defined facts to $\mathcal{F}_{P}$, so it is executed until a fixpoint is reached, except that, in order to avoid infinite loops, we do not execute this step for definitions defined $(M)$ in which $M$ contains nested occurrences of the same symbol (such as $x[\ldots x[\ldots] \ldots]$ ).

We also consider an additional fact that serves in expressing that the condition part of a find failed. Precisely, the fact elsefind $\left(\left(i_{1} \leq n_{1}, \ldots, i_{m} \leq n_{m}\right),\left(M_{1}, \ldots, M_{l}\right), M\right)$ means that for all $i_{1} \in\left[1, n_{1}\right], \ldots, i_{m} \in\left[1, n_{m}\right]$, the terms $M_{1}, \ldots, M_{l}$ are not all defined or $M$ is false. The function collectElseFind described in Figure 19 collects elsefind facts that hold at each occurrence. The function collectElseFind $(P, \mathcal{F})$ is called when $\mathcal{F}$ is the set of true elsefind facts at occurrence $P$. It sets the value of $\mathcal{F}_{P}^{\text {ElseFind }}$ to $\mathcal{F}$.

```
\(\operatorname{collectFacts}(Q)=\)
    if \(Q=Q_{1} \mid Q_{2}\) then collectFacts \(\left(Q_{1}\right)\); collectFacts \(\left(Q_{2}\right)\)
    if \(Q=\) foreach \(i \leq n\) do \(Q^{\prime}\) then collectFacts \(\left(Q^{\prime}\right)\)
    if \(Q=\) newOracle \(O ; Q^{\prime}\) then collectFacts \(\left(Q^{\prime}\right)\)
    if \(Q=O[\widetilde{i}](x \widetilde{i}]: T):=P\) then
        \(\left.\mathcal{F}_{P}=\{\operatorname{defined}(x \widetilde{i}])\right\} ; \mathcal{F}_{P}^{\text {Fut }}=\operatorname{collectFacts}(P)\)
        \(\mathcal{D}=\mathcal{D} \cup\{(x \widetilde{i}], P)\}\)
collectFacts \((P)=\)
    if \(P=\) return \((N) ; Q\) then collectFacts \((Q)\); return \(\emptyset\)
    if \(P=x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P^{\prime}\) then
        \(\mathcal{F}_{P^{\prime}}=\{\operatorname{defined}(x[\widetilde{i}])\} ; \mathcal{F}_{P^{\prime}}^{\text {Fut }}=\operatorname{collectFacts}\left(P^{\prime}\right)\)
        \(\mathcal{D}=\mathcal{D} \cup\left\{\left(x \widetilde{[i]}, P^{\prime}\right)\right\} ;\) return \(\mathcal{F}_{P^{\prime}} \cup \mathcal{F}_{P^{\prime}}^{\text {Fut }}\)
    if \(P=\) let \(x \widetilde{[i]}: T=M\) in \(P^{\prime}\) then
        \(\mathcal{F}_{P^{\prime}}=\{\operatorname{defined}(x[\widetilde{i}]), x[\widetilde{i}]=M\}\)
        \(\mathcal{F}_{P^{\prime}}^{\mathrm{Fut}}=\operatorname{collectFacts}\left(P^{\prime}\right)\)
        \(\left.\mathcal{D}=\mathcal{D} \cup\left\{(x \widetilde{[i}], P^{\prime}\right)\right\} ;\) return \(\mathcal{F}_{P^{\prime}} \cup \mathcal{F}_{P^{\prime}}^{\text {Fut }}\)
    if \(P=\) find \(\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[ }\right]=i_{j m_{j}} \leq n_{j m_{j}}\)
        suchthat defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}\) then \(\left.P_{j}\right)\) else \(P^{\prime}\)
    then
        for each \(j \leq m\),
            \(\mathcal{F}_{P_{j}}=\left\{\operatorname{defined}\left(u_{j 1} \widetilde{[i]}\right), \ldots, \operatorname{defined}\left(u_{j m_{j}} \widetilde{[i]}\right), \operatorname{defined}\left(\sigma M_{j 1}\right), \ldots, \operatorname{defined}\left(\sigma M_{j l_{j}}\right), \sigma M_{j}\right\}\)
            where \(\sigma=\left\{u_{j 1}[\widetilde{i}] / i_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i]} / i_{j m_{j}}\right\}\)
            \(\mathcal{F}_{P_{j}}^{\text {Fut }}=\operatorname{collectFacts}\left(P_{j}\right)\);
            \(\mathcal{D}=\mathcal{D} \cup\left\{\left(u_{j 1} \widetilde{[i]}, P_{j}\right), \ldots,\left(u_{j m_{j}} \widetilde{[i]}, P_{j}\right)\right\}\)
            \(\mathcal{F}_{P^{\prime}}=\left\{\neg M_{j} \mid m_{j}=l_{j}=0\right\} ; \mathcal{F}_{P^{\prime}}^{\mathrm{Fut}}=\operatorname{collectFacts}\left(P^{\prime}\right)\)
            return \(\left(\mathcal{F}_{P^{\prime}} \cup \mathcal{F}_{P^{\prime}}^{\text {Fut }}\right) \cap \bigcap_{j=1}^{m}\left(\mathcal{F}_{P_{j}} \cup \mathcal{F}_{P_{j}}^{\text {Fut }}\right)\)
```

Figure 18: The function collectFacts

```
collectElseFind \((Q)=\)
    if \(Q=Q_{1} \mid Q_{2}\) then collectElseFind \(\left(Q_{1}\right)\); collectElseFind \(\left(Q_{2}\right)\)
    if \(Q=\) foreach \(i \leq n\) do \(Q^{\prime}\) then collectElseFind \(\left(Q^{\prime}\right)\)
    if \(Q=\) newOracle \(O ; Q^{\prime}\) then collectElseFind \(\left(Q^{\prime}\right)\)
    if \(Q=O \widetilde{[i}](x \widetilde{i}]: T):=P\) then collectElseFind \((P, \emptyset)\)
\(\operatorname{collectElseFind}(P, \mathcal{F})=\)
    \(\mathcal{F}_{P}^{\mathrm{ElseFind}}=\mathcal{F}\)
    if \(P=\) return \((N) ; Q\) then collectElseFind \((Q)\)
    if \(P=x \widetilde{[ }] \stackrel{R}{\leftarrow} T ; P^{\prime}\) or \(P=\) let \(x[\widetilde{i}]: T=M\) in \(P^{\prime}\) then
        \(\mathcal{F}^{\prime}=\left\{\right.\) elsefind \(\left.\left(\widetilde{i^{\prime}} \leq \widetilde{n}\right),\left(M_{1}^{\prime}, \ldots, M_{l}^{\prime}\right), M^{\prime}\right) \in \mathcal{F} \mid x\) does not occur in \(\left.M_{1}^{\prime}, \ldots, M_{l}^{\prime}\right\}\)
        collectElseFind \(\left(P^{\prime}, \mathcal{F}^{\prime}\right)\)
    if \(P=\) find \(\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}\)
        suchthat defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}\) then \(\left.P_{j}\right)\) else \(P^{\prime}\)
    then
        for each \(j \leq m\),
            \(\mathcal{F}_{j}^{\prime}=\left\{\right.\) elsefind \(\left.\left(\widetilde{i^{\prime}} \leq \widetilde{n}\right),\left(M_{1}^{\prime}, \ldots, M_{l}^{\prime}\right), M^{\prime}\right) \in \mathcal{F}\)
                \(\mid u_{j 1}, \ldots, u_{j m_{j}}\) do not occur in \(\left.M_{1}^{\prime}, \ldots, M_{l}^{\prime}\right\}\)
            collectElseFind \(\left(P_{j}, \mathcal{F}_{j}^{\prime}\right)\)
    \(\sigma_{j}=\left\{i_{1} / i_{j 1}, \ldots, i_{m_{j}} / i_{j m_{j}}\right\}\)
    collectElseFind \(\left(P^{\prime}, \mathcal{F} \cup\right.\)
        \(\left.\left\{\operatorname{elsefind}\left(\left(i_{1} \leq n_{j 1}, \ldots, i_{m_{j}} \leq n_{j m_{j}}\right), \sigma_{j}\left(M_{j 1}, \ldots, M_{j l_{j}}\right), \sigma_{j} M_{j}\right) \mid j \in\{1, \ldots, m\}\right\}\right)\)
```

Figure 19: The function collectElseFind

- In the case of random choices, assignments, and then branches of find, it takes into account that a variable $x$ or $u_{j 1}, \ldots, u_{j m_{j}}$ is newly defined. Hence elsefind facts that claim that one of these variables is not defined are removed.
- In the case of the else branch of a find, it adds the new elsefind facts that hold when the conditions of the find fail. These conditions express that each then branch of the find fails by a elsefind fact. To construct this fact, we replace (by applying $\sigma_{j}$ ) the indices $i_{j 1}, \ldots, i_{j m_{j}}$ with fresh indices $i_{1}, \ldots, i_{m_{j}}$, respectively.
- In the case of a return, any code may be executed before the oracle definition under it, so any variable may be defined by that code, and all elsefind facts are removed. That is why the function collectElseFind for oracle definitions has no $\mathcal{F}$ argument (this argument would always be empty) and calls collectElseFind $(P, \emptyset)$ for processes $P$ that follow an oracle definition. The situation is similar for an oracle call inside an oracle body.

The elsefind facts can be used to add new facts to the facts $\mathcal{F}_{P}$. Indeed, if $\mathcal{F}_{P}$ implies that $M_{1}, \ldots, M_{l}$ are defined for some values of $i_{1}, \ldots, i_{m}$, then the fact elsefind $\left(\left(i_{1} \leq n_{1}, \ldots, i_{m} \leq\right.\right.$ $\left.\left.n_{m}\right),\left(M_{1}, \ldots, M_{l}\right), M\right)$ implies that $M$ is false for these values of $i_{1}, \ldots, i_{m}$. Precisely, we define
convert_elsefind $\left(\mathcal{F}^{\text {ElseFind }}, \mathcal{F}\right)=\{\neg \sigma M \mid$
elsefind $\left(\left(i_{1} \leq n_{1}, \ldots, i_{m} \leq n_{m}\right),\left(M_{1}, \ldots, M_{l}\right), M\right) \in \mathcal{F}^{\text {ElseFind }}, \operatorname{Dom}(\sigma)=\left\{i_{1}, \ldots, i_{m}\right\}$, for each $j \in\{1, \ldots, l\}, \sigma M_{j}$ is a subterm of $M_{j}^{\prime}$ and defined $\left.\left(M_{j}^{\prime}\right) \in \mathcal{F}\right\}$

The possible images of $\sigma$ are found by exploring the set of defined facts in $\mathcal{F}_{P}$. We execute:

$$
\mathcal{F}_{P} \leftarrow \mathcal{F}_{P} \cup \text { convert_elsefind }\left(\mathcal{F}_{P}^{\text {ElseFind }}, \mathcal{F}_{P}\right)
$$

In the implementation, an additional fact expresses that a pattern-matching failed: in the else branch of let $N=M$ in $P$ else $Q$, we know that $\forall x_{1}, \ldots, x_{l}, N \neq M$, where $x_{1}, \ldots, x_{l}$ are the variables bound in the pattern $N$. In this report, we consider that the pattern-matching is encoded using assignments and tests, so we do not consider this fact further.

Furthermore, when the previous update of $\mathcal{F}_{P}$ adds facts, we again complete the computed sets $\mathcal{F}_{P}$ by adding facts that come from processes above $P$ :

$$
\mathcal{F}_{P} \leftarrow \mathcal{F}_{P} \cup \mathcal{F}_{P^{\prime}} \text { if } P \text { is immediately under } P^{\prime}
$$

We could also iterate the addition of consequences of defined facts. (However, for simplicity, the current implementation does not perform such an iteration.)

We have $\operatorname{programpoint}\left(\mu, I_{\mu}\right) \in \mathcal{F}_{\mu}$.
Lemma 31 Let $C$ be an evaluation context acceptable for $Q_{0}$, $\mathcal{A}$ an attacker in $\mathcal{B B}$, $\operatorname{Tr}$ be a trace of $C\left[Q_{0}\right]$ for $\mathcal{A}, \mu$ be a program point in $Q_{0}$, and $\mathcal{F}_{\mu}$ be computed in $Q_{0}$. If a configuration Conf is at program point $\mu$ in $\operatorname{Tr}$, then $\operatorname{Tr} \preceq$ Conf $\vdash \mathcal{F}_{\mu}$.

When a single variable can be defined at multiple distinct program points, the basic version presented previously of the collected facts only contains the intersection of what holds at all the possible definitions points. A more refined version of $\mathcal{F}_{\mu}$ has also been implemented, that allows distinguishing cases depending on the multiple possible program points at which a variable is defined, generating several $\mathcal{F}_{\mu, c}$ for the various cases $c$. This more refined version is easily leveraged within proofs, simply by checking that a fact holds in all the possible cases over $c$. Note that more refined versions could be made by increasing the possible set of cases, but this would increase the overall complexity of the proof search. For this version, we have:

Lemma 32 Let $C$ be an evaluation context acceptable for $Q_{0}, \mathcal{A}$ an attacker in $\mathcal{B B}$, $\operatorname{Tr}$ be a trace of $C\left[Q_{0}\right]$ for $\mathcal{A}, \mu$ be a program point in $Q_{0}$, and $\mathcal{F}_{\mu, c}$ be computed in $Q_{0}$. If a configuration Conf is at program point $\mu$ in $\operatorname{Tr}$, then there exists $c$ such that $\operatorname{Tr} \preceq \operatorname{Conf} \vdash \mathcal{F}_{\mu, c}$.
$\mathcal{F}_{\mu}$ can be seen as a particular case of $\mathcal{F}_{\mu, c}$ by considering a single case $c$.
Corollary 3 Let $C$ be an evaluation context acceptable for $Q_{0}, \mathcal{A}$ an attacker in $\mathcal{B B}$, $\operatorname{Tr}$ be a trace of $C\left[Q_{0}\right]$ for $\mathcal{A}, \mu$ be a program point in $Q_{0}$, and $\mathcal{F}_{\mu}\left(\right.$ resp. $\mathcal{F}_{\mu, c}$ ) be computed in $Q_{0}$. Let Conf be a configuration at program point $\mu$ in $\operatorname{Tr}$. Let $\theta$ be a renaming of $I_{\mu}$ to fresh replication indices and $\rho=\left\{\theta I_{\mu} \mapsto \sigma_{\text {Conf }} I_{\mu}\right\}$. Let Conf' be a term or oracle body configuration in $\operatorname{Tr}$ such that Conf $\preceq_{T r}$ Conf $^{\prime}$.

We have $\operatorname{Tr} \preceq$ Conf $^{\prime}, \rho \vdash \theta \mathcal{F}_{\mu}$ and there exists $c$ such that $\operatorname{Tr} \preceq \operatorname{Conf}^{\prime}, \rho \vdash \theta \mathcal{F}_{\mu, c}$.
In particular, Tr, $\rho \vdash \theta \mathcal{F}_{\mu}$ and there exists $c$ such that $\operatorname{Tr}, \rho \vdash \theta \mathcal{F}_{\mu, c}$.
Proof By Lemma 31, $\operatorname{Tr} \preceq \operatorname{Conf} \vdash \mathcal{F}_{\mu}$. By Lemma 32, there exists $c$ such that $\operatorname{Tr} \preceq C o n f \vdash$ $\mathcal{F}_{\mu, c}$. Let $\mathcal{F}=\mathcal{F}_{\mu}$ (resp. $\mathcal{F}=\mathcal{F}_{\mu, c}$ ) such that $\operatorname{Tr} \preceq \operatorname{Conf} \vdash \mathcal{F}$. By definition of $\rho$, we have $\operatorname{Tr} \preceq C o n f, \rho \vdash \theta \mathcal{F}$. Since Conf $\preceq_{T r} C o n f^{\prime}$, the environment $E_{T r \preceq C o n f}$ is an extension of $E_{T r} \preceq C o n f$, so the terms and defined facts in $\theta \mathcal{F}$ are preserved when considering $\operatorname{Tr} \preceq C_{o n f}{ }^{\prime}$ instead of $\operatorname{Tr} \preceq \operatorname{Conf}$. (They do not use $\sigma_{C o n f}$, resp. $\sigma_{\text {Conf }}$, by the renaming $\theta$.) Moreover, by Lemma 3, $\mu \mathcal{E} v_{\text {Conf }}$ is an extension of $\mu \mathcal{E} v_{\text {Conf }}$, so the events are also preserved. By definition of $\operatorname{Tr} \preceq \operatorname{Conf}, \rho \vdash \operatorname{programpoint}\left(\mathcal{S}_{1}, \widetilde{M}_{1}\right) \preceq \ldots \preceq \operatorname{programpoint}\left(\mathcal{S}_{m}, \widetilde{M}_{m}\right)$, the sequences of program points $\operatorname{programpoint}\left(\mathcal{S}_{1}, \widetilde{M}_{1}\right) \preceq \ldots \preceq \operatorname{programpoint}\left(\mathcal{S}_{m}, \widetilde{M}_{m}\right)$ are also preserved. Since $\mathcal{F}$ is a set of facts containing only terms, defined facts, events, and sequences of program points, we conclude that $\operatorname{Tr} \preceq$ Conf $^{\prime}, \rho \vdash \theta \mathcal{F}$.

The last point is obtained by choosing Conf ${ }^{\prime}$ to be the last configuration of Tr .
Lemma 33 Let $C$ be an evaluation context acceptable for $Q_{0}$, $\mathcal{A}$ an attacker in $\mathcal{B B}, \operatorname{Tr}=$ $\operatorname{initConfig}\left(C\left[Q_{0}\right], \mathcal{A}\right) \xrightarrow{p}_{t} \ldots{\xrightarrow{p^{\prime}}}_{t^{\prime}} E,(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ be a trace for $\mathcal{A}$ that does not execute any non-unique event of $Q_{0}$ with $P=$ return (a); $Q$ for some $a$ and $Q$ or $P=$ yield or $P=$ abort, $\mu$ be a program point in $Q_{0}$, and $\mathcal{F}_{\mu}^{\text {Fut }}$ be computed in $Q_{0}$. If the configuration Conf is at program point $\mu$ in $\operatorname{Tr}$ and no executed process in the configurations between the configuration at the end of reduction step that contains Conf (included) and $E,(\sigma, P):: \mathcal{S} t, \mathcal{Q}, \mathcal{O} r$, $\mathcal{T}, \mu \mathcal{E} v$ (excluded) is of the form return (a); $Q$ for some $a$ and $Q$ or yield (when Conf is a process configuration with process return $(a) ; Q$ for some a and $Q$ or yield, we have Conf $=E,(\sigma, P):: \mathcal{S}$, $\mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v)$, then $\operatorname{Tr} \vdash \mathcal{F}_{\mu}^{\text {Fut }}$.

### 3.3 Local Dependency Analysis

For each program point $P$ and each variable $x$, the local dependency analysis tries to find which variables and terms depend on $x \widetilde{i}]$ at program point $P$, where $\widetilde{i}$ denotes the current replication indices at the definition of $x$. It simplifies the game on-the-fly when possible.

For each occurrence of a process $P$ and each variable $x$ such that a random choice $x \stackrel{R}{\leftarrow} T$ occurs above $P$ and $T$ is a large type, we compute a set of terms $\operatorname{indep}_{P}(x)$ that are independent of $x[\widetilde{i}]$ where $\widetilde{i}$ denotes the current replication indices at the definition of $x$.

For each occurrence of a process $P$ and each variable $x$ such that a random choice $x \stackrel{R}{\leftarrow} T$ occurs above $P$ and $T$ is a large type, we also compute $\operatorname{depend}_{P}(x)$ which can be either $T$ (I don't know) or a set of pairs $(y, M)$ where $y \widetilde{[i]}$ depends on $x \widetilde{[i]}$ by assignments, and $M$ is a term defining $y \widetilde{i}]$ as a function of $x \widetilde{i}]$. (The tuple $\widetilde{i}$ denotes the current replication indices at the definition of $x$ and of $y$.)

```
\(\operatorname{dep} \operatorname{Anal}(Q\), indep \()=\)
    \(\forall y, \operatorname{depend}_{Q}(y)=\top ; \operatorname{indep}_{Q}=\) indep
    if \(Q=Q_{1} \mid Q_{2}\) then depAnal \(\left(Q_{1}\right.\), indep); depAnal \(\left(Q_{2}\right.\), indep \()\)
    if \(Q=\) foreach \(i \leq n\) do \(Q^{\prime}\) then \(\operatorname{depAnal}\left(Q^{\prime}\right.\), indep)
    if \(Q=\) newOracle \(O ; Q^{\prime}\) then \(\operatorname{dep} A n a l\left(Q^{\prime}\right.\), indep)
    if \(Q=O \widetilde{i}](x \widetilde{[i}]: T):=P\) then depAnal \((P,\{\forall y, y \mapsto \top\}\), indep \()\)
```

Figure 20: Local dependency analysis (1)

We define " $M$ characterizes a part of $x[\widetilde{i}]$ at $P$ " as follows. Let $\alpha$ be defined by $\alpha\left(f\left(M_{1}, \ldots\right.\right.$, $\left.\left.M_{m}\right)\right)=f\left(\alpha M_{1}, \ldots, \alpha M_{m}\right) ; \alpha(i)=i$ where $i$ is a replication index; $\alpha\left(M^{\prime}\right)=M^{\prime}$ when $M^{\prime} \in$ $\operatorname{indep}_{P}(x) ; \alpha\left(y\left[M_{1}, \ldots, M_{m^{\prime}}\right]\right)=y\left[\alpha M_{1}, \ldots, \alpha M_{m^{\prime}}\right]$ when $y \neq x$ and $y$ either is defined only by random choices or $\operatorname{depend}_{P}(x) \neq \top$ and $\left(y, M^{\prime}\right) \notin \operatorname{depend}_{P}(x)$ for any $M^{\prime} ; \alpha\left(y\left[M_{1}, \ldots, M_{m^{\prime}}\right]\right)=$ $y^{\prime}\left[\alpha M_{1}, \ldots, \alpha M_{m^{\prime}}\right]$ where $y^{\prime}$ is a fresh variable, otherwise. We write $y^{\prime}=\alpha y$ in this case. We say that $M$ characterizes a part of $x[\widetilde{i}]$ at $P$ when $\alpha M=M$ implies $\left.f_{1}\left(\ldots f_{k}((\alpha x) \widetilde{i}]\right)\right)=$ $f_{1}\left(\ldots f_{k}(x[\widetilde{i}])\right)$ for some uniform functions $f_{1}, \ldots, f_{k}$, where $\left.x \widetilde{[i}\right]$ is a subterm of $\left.M,(\alpha x) \widetilde{i}\right]$ is a subterm of $\alpha M, T^{\prime}$ is the type of the result of $f_{1}$ (or of $x$ when $k=0$ ), and $T^{\prime}$ is a large type. In that case, the value of $M$ uniquely determines the value of $\left.f_{1}\left(\ldots f_{k}(x \widetilde{i}]\right)\right)$. This property is shown by a simple rewriting prover, as in the global dependency analysis.

We denote by subterms $(M)$ the set of subterms of the term $M$.
We say that $M$ does not depend on $x$ at $P$ when $M$ is built by function applications from terms in $\operatorname{indep}_{P}(x)$, replications indices, and terms $y\left[M_{1}, \ldots, M_{m}\right]$ such that $M_{1}, \ldots, M_{m}$ do not depend on $x$ at $P, y \neq x$, and either $y$ is defined only by random choices or depend ${ }_{P}(x) \neq \top$ and $y \neq y^{\prime}$ for all $\left(y^{\prime}, M^{\prime}\right) \in \operatorname{depend}_{P}(x)$. Since terms in $\operatorname{indep}_{P}(x)$ do not depend on $x[\widetilde{i}]$ and when depend ${ }_{P}(x) \neq \top$, variables not in the first component of $\operatorname{depend}_{P}(x)$ do not depend on $x \widetilde{i}]$, the conditions above guarantee that $M$ does not depend on $x[\widetilde{i}]$, where $\widetilde{i}$ are the current replication indices at the definition of $x$.

When depend $\neq \top$, we denote by $M$ depend the term obtained from $M$ by replacing $y[\widetilde{i}]$ with $M^{\prime}$ for each $\left(y, M^{\prime}\right) \in$ depend, where $\tilde{i}$ denotes the replication indices at the definition of $y$.

We define simplifyTerm such that simplifyTerm $(M, P)$ is a simplified version of $M$, equal to $M$ except in cases of negligible probability. The term $\operatorname{simplify} \operatorname{Term}(M, P)$ is defined as follows:

- Case 1: $M$ is $M_{1}=M_{2}$. For each $x$, we proceed as follows. If $\operatorname{depend}_{P}(x)=\top$, let $M_{0}=M_{1}$; otherwise, let $M_{0}=M_{1} \operatorname{depend}_{P}(x)$. Let $M_{0}^{\prime}$ and $M_{2}^{\prime}$ be obtained respectively from $M_{0}$ and $M_{2}$ by replacing all array indices that depend on $x$ at $P$ with fresh replication indices. If $M_{0}^{\prime}$ characterizes a part of $x \widetilde{[i]}$ at $P$, and $M_{2}^{\prime}$ does not depend on $x$ at $P$, then simplify $\operatorname{Term}(M, P)=$ false. Indeed, $M$ is equal to false up to negligible probability in this case. We have similar cases swapping $M_{1}$ and $M_{2}$ or when $M$ is $M_{1} \neq M_{2}$. (In the latter case, $\operatorname{simplifyTerm}(M, P)=$ true.)
- Case 2: $M$ is $M_{1} \wedge M_{2}$. Let $M_{1}^{\prime}=\operatorname{simplifyTerm}\left(M_{1}, P\right)$ and $M_{2}^{\prime}=\operatorname{simplifyTerm}\left(M_{2}, P\right)$. If $M_{1}^{\prime}$ or $M_{2}^{\prime}$ are false, we return false. If $M_{1}^{\prime}$ is true, we return $M_{2}^{\prime}$. If $M_{2}^{\prime}$ is true, we return $M_{1}^{\prime}$. Otherwise, we return $M_{1}^{\prime} \wedge M_{2}^{\prime}$. We have similar cases when $M$ is $M_{1} \vee M_{2}$ or $\neg M_{1}$.
- In all other cases, simplifyTerm $(M, P)=M$.

The local dependency analysis is defined in Figures 20 and 21 . The function depAnal is initially called with $\operatorname{dep} \operatorname{Anal}\left(Q_{0}, \emptyset\right)$ where $\emptyset$ designates the function defined nowhere

```
\(\operatorname{depAnal}(P\), depend, indep \()=\)
    depend \(_{P}=\) depend; indep \(_{P}=\) indep
    if \(P=\) return \((N) ; Q\) then depAnal \((Q\), indep)
    if \(P=x \widetilde{i}] \stackrel{R}{\leftarrow} T ; P^{\prime}\) then
        if \(T\) is a large type then
            \(\operatorname{depend}^{\prime}(x)=\emptyset ; \operatorname{indep}^{\prime}(x)=\bigcup_{\text {defined }(M) \in \mathcal{F}_{P}} \operatorname{subterms}(M)\)
        \(\forall y \neq x, \operatorname{depend}^{\prime}(y)=\operatorname{depend}(y), \operatorname{indep}^{\prime}(y)=\operatorname{indep}(y) \cup\{x[\widetilde{i}]\}\)
        depAnal \(\left(P^{\prime}\right.\), depend \({ }^{\prime}\), indep \(\left.{ }^{\prime}\right)\)
    if \(P=\) let \(x \widetilde{[i]}: T=M\) in \(P^{\prime}\) then
        \(\forall y\), if \(M\) does not depend on \(y\) at \(P\) then
                    \(\left.\operatorname{depend}^{\prime}(y)=\operatorname{depend}(y) ; \operatorname{indep}^{\prime}(y)=\{x \widetilde{i}]\right\} \cup \operatorname{indep}(y)\)
            else
                    if depend \((y) \neq \top\) then
                        \(\operatorname{depend}^{\prime}(y)=\operatorname{depend}(y) \cup\{(x, M \operatorname{depend}(y))\}\)
                    else
                    depend \({ }^{\prime}(y)=\top\)
                    \(\operatorname{indep}^{\prime}(y)=\operatorname{indep}(y)\)
        depAnal \(\left(P^{\prime}\right.\), depend \({ }^{\prime}\), indep \(\left.{ }^{\prime}\right)\)
    if \(P=\) find \(\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i}\right]=i_{j m_{j}} \leq n_{j m_{j}}\)
            suchthat defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}\) then \(\left.P_{j}\right)\) else \(P^{\prime}\)
    then
    for each \(j \leq m, M_{j}^{\prime}=\operatorname{simplifyTerm}\left(M_{j}, P\right)\)
        replace \(M_{j}\) with \(M_{j}^{\prime}\)
        if \(M_{j}^{\prime}=\) false then remove the \(j\)-th branch
        if \(M_{j}^{\prime}=\) true and \(l_{j}=0\) then replace \(P^{\prime}\) with yield
    if \(m=0\) then
            replace \(P\) with \(P^{\prime} ; \operatorname{depAnal}\left(P^{\prime}\right.\), depend, indep)
    else if \(m=1, m_{1}=l_{1}=0\), and \(M_{1}=\) true then
            replace \(P\) with \(P_{1} ; \operatorname{dep} \operatorname{Anal}\left(P_{1}\right.\), depend, indep \()\)
    else
    \(\forall y\), if \(\forall j, k, M_{j k}\) and \(M_{j}^{\prime}\) do not depend on \(y\) at \(P\) then
            \(\operatorname{depend}^{\prime}(y)=\operatorname{depend}(y)\)
            for each \(j \leq m, \operatorname{indep}_{j}(y)=\operatorname{indep}(y) \cup\left\{M^{\prime} \mid\right.\)
                \(M^{\prime} \in \operatorname{subterms}(M)\) for some defined \((M) \in \mathcal{F}_{P_{j}}, M^{\prime}\) does not depend on \(y\) at \(\left.P\right\}\)
            else
            \(\operatorname{depend}^{\prime}(y)=\top\); for each \(j \leq m, \operatorname{indep}_{j}(y)=\operatorname{indep}(y)\)
    for each \(j \leq m\), depAnal \(\left(P_{j}\right.\), depend \(^{\prime}\), indep \(\left._{j}\right)\)
    \(\operatorname{dep} A n a l\left(P^{\prime}\right.\), depend \({ }^{\prime}\), indep \()\)
```

Figure 21: Local dependency analysis (2)

- For oracle definitions, depAnal sets depend ${ }_{Q}(y)$ to $T$, so that depend ${ }_{Q}$ gives no information, and propagates indep. Indeed, when $y\left[\widetilde{i^{\prime}}\right]$ is set in some oracle body $P_{0}$, the value of $y\left[\widetilde{i^{\prime}}\right]$ may be passed to another oracle by $P_{0}$ or read by find in other oracle bodies executed after $P_{0}$, so as soon as $P_{0}$ passes control to another oracle by the first return after the definition of $y$, we lose track of exactly which variables depend on $y\left[\widetilde{i^{\prime}}\right]$. However, variables already defined before $P_{0}$ passes control to another oracle and proved to be independent of $\left.y \widetilde{i^{\prime}}\right]$ remain independent of $y\left[\widetilde{i^{\prime}}\right]$, so we can propagate indep in all subprocesses of $P_{0}$.
- In the case of a return, depAnal forgets the information in depend ${ }_{P}$ as mentioned above.
- In the case of a random choice $x[\widetilde{i}] \stackrel{R}{\leftarrow} T$, if $T$ is a large type, we create the dependency information for the newly defined variable $x$ : no variable depends on $x \widetilde{[ }]$, and all terms already defined before the random choice are independent of $x \widetilde{i}]$. We also note that $x \widetilde{i}]$ is independent of $y\left[\widetilde{i^{\prime}}\right]$ for other variables $y$ by adding $x[\widetilde{i}]$ to indep $(y)$.
- In the case of an assignment let $x[\widetilde{i}]: T=M$, if $M$ depends on $y\left[\widetilde{i^{\prime}}\right]$ for some variable $y$, then $x[\widetilde{i}]$ depends on $y\left[\widetilde{i^{\prime}}\right]$, so $x$ is added to depend $(y)$ (if it is not $\top$ ); otherwise, $x[\widetilde{i}]$ does not depend on $y\left[\widetilde{i^{\prime}}\right]$ so it is added to $\operatorname{indep}(y)$.
- In the case of a find, we first simplify each condition of the find, remove branches when we can prove that they are taken with negligible probability, and remove the find itself when we know which branch is taken and this branch of the find does not define variables. Furthermore, if some condition of find depends on $y[\widetilde{i}]$ for some variable $y$, depend ${ }^{\prime}(y)$ is set to $T$ : the control flow depends on $y[\widetilde{i}]$ so future assignments in fact depend on $y[\widetilde{i}]$ even if the assigned expression itself does not, so we can no longer keep track precisely of which variables depend on $y[\widetilde{i}]$. Otherwise, we add all terms that are guaranteed to be defined and independent of $y[\widetilde{i}]$ to indep $(y)$.


### 3.4 Equational Prover

We use an algorithm inspired by the Knuth-Bendix completion algorithm 51, with differences detailed below.

The prover manipulates pairs $\mathcal{F}, \mathcal{R}$ where $\mathcal{F}$ is a set of facts $(M$ or defined $(M))$ and $\mathcal{R}$ is a set of rewrite rules $M_{1} \rightarrow M_{2}$. We say that $M$ reduces into $M^{\prime}$ by $M_{1} \rightarrow M_{2}$ when $M=C\left[M_{1}\right]$ and $M^{\prime}=C\left[M_{2}\right]$ for some term context $C$. (That is, all variables in rewrite rules of $\mathcal{R}$ are considered as constants.) The prover starts with a certain set of facts $\mathcal{F}$ and $\mathcal{R}=\emptyset$. Then the prover transforms the pairs $(\mathcal{F}, \mathcal{R})$ by the following rules (the rule $\frac{\mathcal{F}, \mathcal{R}}{\mathcal{F}^{\prime}, \mathcal{R}^{\prime}}$ means that $\mathcal{F}, \mathcal{R}$ is transformed into $\left.\mathcal{F}^{\prime}, \mathcal{R}^{\prime}\right)$ :

$$
\begin{gather*}
\frac{\mathcal{F} \cup\{F\}, \mathcal{R}}{\mathcal{F} \cup\left\{F^{\prime}\right\}, \mathcal{R}} \quad \begin{array}{c}
\text { if } F \text { reduces into } F^{\prime} \text { by a rule of } \mathcal{R} \text { or } \\
\text { a user-defined rewrite rule knowing } \mathcal{F}, \mathcal{R} \\
\frac{\mathcal{F} \cup\left\{M_{1} \wedge M_{2}\right\}, \mathcal{R}}{\mathcal{F} \cup\left\{M_{1}, M_{2}\right\}, \mathcal{R}}
\end{array}  \tag{17}\\
\frac{\mathcal{F} \cup\left\{x\left[M_{1}, \ldots, M_{m}\right]=x\left[M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right]\right\}, \mathcal{R}}{\mathcal{F} \cup\left\{M_{1}=M_{1}^{\prime}, \ldots, M_{m}=M_{m}^{\prime}\right\}, \mathcal{R}} \quad x \stackrel{R}{\leftarrow} T \text { and } T \text { is a large type }
\end{gather*}
$$

$\frac{\mathcal{F} \cup\left\{M_{1}=M_{2}\right\}, \mathcal{R}}{\{\text { false }\}, \mathcal{R}}$ when one of the following conditions holds:

- denoting by $M_{1}^{\prime}$ the term obtained from $M_{1}$ by replacing all array indices that are not replication indices with fresh replication indices, we have the following properties: $x$ occurs in $M_{1}^{\prime}, x$ is defined only by random choices $x \stackrel{R}{\leftarrow} T, T$ is a large type, $M_{1}^{\prime}$ characterizes a part of $x$, and $M_{2}$ is obtained by optionally applying function symbols to terms of the form $y[\widetilde{M}]$ where $y$ is defined only by random choices and $y \neq x$;
- $\operatorname{simplifyTerm}\left(M_{1}=M_{2}, P\right)=$ false, where $P$ is the current program point.

$$
\begin{equation*}
\frac{\mathcal{F} \cup\left\{M=M^{\prime}\right\}, \mathcal{R}}{\mathcal{F}, \mathcal{R} \cup\left\{M \rightarrow M^{\prime}\right\}} \text { if } M>M^{\prime} \tag{20}
\end{equation*}
$$

$$
\begin{align*}
& \frac{\mathcal{F}, \mathcal{R} \cup\left\{M_{1} \rightarrow M_{2}\right\}}{\mathcal{F} \cup\left\{M_{1}=M_{2}^{\prime}\right\}, \mathcal{R}} \text { if } M_{2} \text { reduces into } M_{2}^{\prime} \text { by a rule of } \mathcal{R} \\
& \frac{\mathcal{F}, \mathcal{R} \cup\left\{M_{1} \rightarrow M_{2}\right\}}{\mathcal{F} \cup\left\{M_{1}^{\prime}=M_{2}\right\}, \mathcal{R}} \text { if } M_{1} \text { reduces into } M_{1}^{\prime} \text { by a rule of } \mathcal{R} \tag{22}
\end{align*}
$$

We also use the symmetrics of Rules 20 and 21) obtained by swapping the two sides of the equality.

Rule (17) simplifies facts using rewrite rules. Let us define when $M$ reduces into $M^{\prime}$ by a userdefined rewrite rule knowing $\mathcal{F}, \mathcal{R}$. For the first kind of rewrite rules of Section 3.1, this is simply when $M$ reduces into $M^{\prime}$ by the considered rewrite rule. For the second kind of rewrite rules of Section 3.1, consider a rewrite rule $y_{1} \stackrel{R}{\leftarrow} T_{1}^{\prime}, \ldots, y_{l} \stackrel{R}{\leftarrow} T_{l}^{\prime}, \forall x_{1}: T_{1}, \ldots, \forall x_{m}: T_{m}, M_{1} \rightarrow M_{2}$. Suppose that $M=C\left[\sigma M_{1}\right]$, where $C$ is a term context and $\sigma$ is a substitution that maps $x_{j}$ to any term of type $T_{j}$ for all $j \leq m$ and $y_{j}$ to terms to the form $z_{j}\left[\widetilde{M}_{j}\right]$ where $z_{j}$ is defined only by random choices $z_{j} \stackrel{R}{\leftarrow} T_{j}^{\prime}$ for all $j \leq l$. Let $\mathcal{C}$ ond $=\left\{\widetilde{M}_{j}=\widetilde{M}_{j^{\prime}} \mid j \neq j^{\prime} \wedge z_{j}=z_{j^{\prime}}\right\}$.

- If $\mathcal{C}$ ond $=\emptyset$, the random choices $z_{j}\left[\widetilde{M}_{j}\right]$ are independent, so $M=C\left[\sigma M_{1}\right]$ reduces into $M^{\prime}=C\left[\sigma M_{2}\right]$.
- If $\mathcal{C}$ ond $\neq \emptyset$, let $\mathcal{C}$ ond $=\left\{\operatorname{cond}_{1}, \ldots, \operatorname{cond}_{k}\right\}$. When $\operatorname{cond}_{1} \vee \ldots \vee$ cond $_{k}$ is true, the random choices $z_{j}\left[\widetilde{M}_{j}\right]$ are not independent, so we must leave $M$ as it is. When $\operatorname{cond}_{1} \vee \ldots \vee \operatorname{cond}_{k}$ is false, $M$ reduces into $M^{\prime}=C\left[\sigma M_{2}\right]$. Suppose that $M^{\prime}=$ false. Hence, we could rewrite $M$ into if $\operatorname{cond}_{1} \vee \ldots \vee \operatorname{cond}_{k}$ then $M$ else false, that is, $\left(\operatorname{cond}_{1} \vee \ldots \vee \operatorname{cond}_{k}\right) \wedge M$, that is, $\left(\operatorname{cond}_{1} \wedge\right.$ $M) \vee \ldots \vee\left(\operatorname{cond}_{k} \wedge M\right)$. However, since this term itself contains $M$, this transformation could lead to a loop. We avoid it as follows. If for all $k^{\prime}=1, \ldots, k, M$ is transformed into $M_{k^{\prime}}^{\prime}$ by rewrite rules generated by our equational prover from $\mathcal{F} \cup\left\{\operatorname{cond}_{k^{\prime}}\right\}, \mathcal{R}$ and userdefined rewrite rules, using only the first kind of user-defined rewrite rules of Section 3.1, and $M_{k^{\prime}}^{\prime} \neq M_{k}$, then we rewrite $M$ into $\left(\operatorname{cond}_{1} \wedge M_{1}^{\prime}\right) \vee \ldots \vee\left(\operatorname{cond}_{k} \wedge M_{k}^{\prime}\right)$. Otherwise, $M$ does not rewrite by the considered user-defined rewrite rule knowing $\mathcal{F}, \mathcal{R}$.

Rule (18) decomposes conjunctions of facts. Rules and 20) exploit the elimination of collisions between random values. Rule (19) takes into account that, when $x$ is defined by a random choice of a large type, two different cells of $x$ have a negligible probability of containing the same value. So when two cells of $x$ contain the same value, we can conclude up to negligible probability that they are the same cell. Rule 20) expresses that $M_{1}$ and $M_{2}$ have a negligible probability of being equal when $x$ is defined by a random choice of a large type, $M_{1}$ characterizes a part of $x$, and $M_{2}$ does not depend of $x$. The first item of 20 establishes these properties without further dependency analysis and the second item exploits the local dependency analysis.

Additionally, in simplification (simplify), if $\mathcal{F}$ contains $M_{1}=M_{2}$ such that $x$ occurs in $M_{1}, x$ is defined only by random choices $x \stackrel{R}{\leftarrow} T, T$ is a large type, and $M_{1}$ characterizes a part of $x$, we trigger the global dependency analysis (Section 5.1.20). If the global dependency analysis succeeds in transforming the game, the simplification is restarted from the game obtained after global dependency analysis.

Rule (21) is applied only when Rules (17) to (20) cannot be applied. Rule (21) transforms equations into rewrite rules by orienting them. We say that $M>M^{\prime}$ when either $M$ is the form $x[\widetilde{M}], x$ does not occur in $M^{\prime}$, and $x$ is not defined only by random choices, or $M=$ $x\left[M_{1}, \ldots, M_{m}\right], M^{\prime}=x\left[M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right]$, and for all $j \leq m, M_{j}>M_{j}^{\prime}$. Intuitively, our goal is to replace $M$ with $M^{\prime}$ when $M^{\prime}$ defines the content of the variable $M$. (Notice that this is not an ordering; the Knuth-Bendix algorithm normally uses a reduction ordering to orient equations. However, we tried some reduction orderings, namely the lexicographic path ordering and the Knuth-Bendix ordering, and obtained disappointing results: the prover fails to prove many equalities because too many equations are left unoriented. The simple heuristic given above succeeds more often, at the expense of a greater risk of non-termination, but that does not cause problems in practice on our examples. We believe that this comes from the particular structure of equations, which come from let definitions and from conditions of find or if, and tend to define variables from other variables without creating dependency cycles.)

Rules (22) and 23) are systematically applied to simplify all rewrite rules of $\mathcal{R}$ after a new rewrite rule has been added by Rule (21). Since all terms in rewrite rules of $\mathcal{R}$ are considered as constants, Rule $\sqrt{23}$ ) in fact includes the deduction of equations from critical pairs done by the standard Knuth-Bendix completion algorithm.

We say that $\mathcal{F}$ yields a contradiction when the prover, starting from $(\mathcal{F}, \emptyset)$, derives false.
Extension: That depends on the program point for local dependency analysis. We ignore that point for now. For the proof of correspondences, local dependency analysis is not used. The current game $Q_{0}$ is used for the basic dependency analysis (rule (19) and first item of 20).

Lemma 34 If for all $j \in J, \mathcal{F}_{j}$ yields a contradiction in a game $Q_{0}$, then CryptoVerif returns a probability $p$ such that for all attackers $\mathcal{A} \in \mathcal{B B}$ and all evaluation contexts $C$ acceptable for $Q_{0}$ with any public variables, $\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right] \preceq \bigvee_{j \in J} \exists \widetilde{x}_{j} \in \widetilde{T}_{j}, \bigwedge \mathcal{F}_{j}\right] \leq p(\mathcal{A}, C)$, where $\widetilde{x}_{j}$ are the replication indices and non-process variables that occur in $\mathcal{F}_{j}$ and $\widetilde{T}_{j}$ are their types.

In particular, the lemma states that, when several sets of facts $\mathcal{F}_{j}$ yield a contradiction in the same game, CryptoVerif counts only once in the probability $p$ the collisions that are eliminated in proofs that $\mathcal{F}_{j}$ yields a contradiction for several $j$.

More generally, let us consider an algorithm $\varphi$ built from the following grammar:

```
\varphi ::=
    F}\mathrm{ yields a contradiction
    \varphi
    \varphi
    \psi
    if \psi then }\mp@subsup{\varphi}{1}{}\mathrm{ else }\mp@subsup{\varphi}{2}{
```

```
algorithm
    equational proof
    conjunction
    disjunction
    mathematical formula
    test
```

The mathematical formulas $\psi$ in such algorithms must not depend on the executed trace. (They may depend on the syntax of the game $Q_{0}$ or on the set of public variables $V$, for instance.)

We translate such algorithms into logical formulas on traces:
$\{[\mathcal{F}$ yields a contradiction $]\}=\neg \exists \widetilde{x} \in \widetilde{T}, \bigwedge \mathcal{F} \quad$ where $\widetilde{x}$ are the replication indices and non-process variables that occur in $\mathcal{F}$ and $\widetilde{T}$ are their types.

$$
\begin{aligned}
& \left\{\left[\varphi_{1} \wedge \varphi_{2}\right]\right\}=\left\{\left\{\varphi_{1}\right\} \wedge \wedge\left\{\left[\varphi_{2}\right\}\right\}\right. \\
& \left\{\left[\varphi_{1} \vee \varphi_{2}\right]\right\}= \begin{cases}\left\{\left[\varphi_{1}\right]\right\} & \text { if } \varphi_{1} \\
\left\{\left\{\varphi_{2}\right]\right\} & \text { otherwise }\end{cases} \\
& \{[\psi\}\}=\psi \\
& \left.\left\{\text { if } \psi \text { then } \varphi_{1} \text { else } \varphi_{2}\right]\right\}=\text { if } \psi \text { then }\left\{\left[\varphi_{1}\right\}\right\} \text { else }\left\{\left[\varphi_{2}\right\}\right\}
\end{aligned}
$$

Intuitively, when algorithm $\varphi$ returns true, CryptoVerif shows that the formula $\{[\varphi]\}$ holds for most traces. It bounds the probability of the traces for which this formula does not hold, as shown by the following lemma.

Lemma 35 If algorithm $\varphi$ returns true in a game $Q_{0}$, then CryptoVerif returns a probability $p$ such that for all attackers $\mathcal{A} \in \mathcal{B B}$ and all evaluation contexts $C$ acceptable for $Q_{0}$ with any public variables, $\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right] \preceq \neg\{[\varphi]\}\right] \leq p(\mathcal{A}, C)$.

Proof We show by induction on the definition of $\varphi$ that, if $\varphi$ returns true and $\operatorname{Tr} \vdash \neg\{[\varphi]\}$, then there exists $\mathcal{F}$ such that " $\mathcal{F}$ yields a contradiction" has been called in the evaluation of $\varphi$ and returned true, and $\operatorname{Tr} \vdash \exists \widetilde{x} \in \widetilde{T}, \bigwedge \mathcal{F}$ where $\widetilde{x}$ are the replication indices and non-process variables that occur in $\mathcal{F}$ and $\widetilde{T}$ are their types.

- Case $\varphi=(\mathcal{F}$ yields a contradiction $)$ : obvious.
- Case $\varphi=\varphi_{1} \wedge \varphi_{2}$ : Since $\varphi$ returns true, $\varphi_{1}$ and $\varphi_{2}$ both return true. Since $\operatorname{Tr} \vdash \neg\left(\left\{\left[\varphi_{1}\right]\right\} \wedge\right.$ $\left\{\left[\varphi_{2}\right]\right\}$ ), we have either $\operatorname{Tr} \vdash \neg\left\{\left[\varphi_{1}\right]\right\}$ or $\operatorname{Tr} \vdash \neg\left\{\left[\varphi_{2}\right]\right\}$. In the first case, by induction hypothesis on $\varphi_{1}$, there exists $\mathcal{F}$ such that " $\mathcal{F}$ yields a contradiction" has been called in the evaluation of $\varphi_{1}$ and returned true, and $\operatorname{Tr} \vdash \exists \widetilde{x} \in \widetilde{T}, \bigwedge \mathcal{F}$ where $\widetilde{x}$ are the replication indices and non-process variables that occur in $\mathcal{F}$ and $\widetilde{T}$ are their types. Moreover, " $\mathcal{F}$ yields a contradiction" has been called in the evaluation of $\varphi$. The second case is symmetric.
- Case $\varphi=\varphi_{1} \vee \varphi_{2}$ : If $\varphi_{1}$ returns true, then $\{[\varphi]\}=\left\{\left[\varphi_{1}\right]\right\}$, so $\operatorname{Tr} \vdash \neg\left\{\left[\varphi_{1}\right]\right\}$. We conclude by induction hypothesis on $\varphi_{1}$, as above. If $\varphi_{1}$ returns false, then $\varphi_{2}$ returns true, since $\varphi$ returns true. Hence $\{[\varphi]\}=\left\{\left[\varphi_{2}\right]\right\}$, so $\operatorname{Tr} \vdash \neg\left\{\left[\varphi_{2}\right]\right\}$. We conclude by induction hypothesis on $\varphi_{2}$.
- Case $\varphi=\psi$ : since $\psi$ evaluates to true, there is no trace $\operatorname{Tr}$ such that $\operatorname{Tr} \vdash \neg \psi$, so the property holds trivially.
- Case $\varphi=$ if $\psi$ then $\varphi_{1}$ else $\varphi_{2}$ : if $\psi$ evaluates to true, then we conclude by induction hypothesis on $\varphi_{1}$. Indeed, since $\varphi$ returns true, $\varphi_{1}$ returns true. Since $\operatorname{Tr} \vdash \neg\{[\varphi]\}$, we have $\operatorname{Tr} \vdash \neg\left\{\left[\varphi_{1}\right]\right\}$. By induction hypothesis, there exists $\mathcal{F}$ such that " $\mathcal{F}$ yields a contradiction" has been called in the evaluation of $\varphi_{1}$ and returned true, and $\operatorname{Tr} \vdash \exists \widetilde{x} \in \widetilde{T}, \bigwedge \mathcal{F}$ where $\widetilde{x}$ are the replication indices and non-process variables that occur in $\mathcal{F}$ and $\widetilde{T}$ are their types. Then " $\mathcal{F}$ yields a contradiction" has also been called in the evaluation of $\varphi$. Similarly, if $\psi$ evaluates to false, then we conclude by induction hypothesis on $\varphi_{2}$.

We conclude by Lemma 34 .

## 4 success: Criteria for Proving Security Properties

The command success tries to prove the active queries, as explained below. We consider an oracle definition $Q_{0}$ that satisfies Properties 3 and 4 , and prove secrecy and correspondence properties for $Q_{0}$.

```
\(C::=[]\)
    \(y\left[M_{1}, \ldots, M_{k-1}, C, M_{k+1}, \ldots, M_{m}\right]\)
    \(f\left(M_{1}, \ldots, M_{k-1}, C, M_{k+1}, \ldots, M_{m}\right)\)
    \(y \widetilde{i}] \stackrel{R}{\leftarrow} T ; C\)
    let \(y[\widetilde{i}]=M\) in \(C\)
    if \(M\) then \(C\) else \(N^{\prime}\)
    if \(M\) then \(N\) else \(C\)
    find \([\) unique? \(]\left(\bigoplus_{j=1, \ldots, m ; j \neq k} \widetilde{u_{j}} \widetilde{[i]}=\widetilde{i_{j}} \leq \widetilde{n_{j}}\right.\) suchthat defined \(\left(\widetilde{M_{j}}\right) \wedge M_{j}\) then \(\left.N_{j}\right)\)
            \(\oplus \widetilde{u_{k}}[\widetilde{i}]=\widetilde{i_{k}} \leq \widetilde{n_{k}}\) suchthat defined \(\left(\widetilde{M_{k}}\right) \wedge M_{k}\) then \(C\) else \(N\)
    find \([\) unique \(?]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{[i]}=\widetilde{i_{j}} \leq \widetilde{n_{j}} \operatorname{suchthat} \operatorname{defined}\left(\widetilde{M_{j}}\right) \wedge M_{j}\right.\) then \(\left.N_{j}\right)\) else \(C\)
    event \(e(\widetilde{M}) ; C\)
```

Figure 22: Event contexts

### 4.1 Secrecy

Let us now define syntactic criteria that allow us to prove secrecy properties of protocols. We first define the function noleak, explained below. This function implicitly depends on the current game $Q_{0}$ and the public variables $V$.

$$
\operatorname{noleak}\left(x\left[\widetilde{M^{\prime}}\right], \mathcal{I}, \mathcal{F}\right)=(\mathcal{F} \text { yields a contradiction }) \vee\left((x \notin V) \wedge \bigwedge_{\mu_{x[\widetilde{M}]} \text { in } Q_{0}}\right.
$$

- if ${ }^{\mu} x[\widetilde{M}]$ is in $M$ in an assignment let $y[\widetilde{i}]=M$ in $Q_{0}, M$ is built from replication indices, variables, function applications, and conditionals, and the current call is not inside a call to noleak $(y[-],-,-)$, then

```
noleak}(y[0\ddot{i}],\mathcal{I}\cup{0\ddot{i}},\mathcal{F}\cup0\mp@subsup{\mathcal{F}}{\mu}{}\cup{0\widetilde{M}=\widetilde{\mp@subsup{M}{}{\prime}}}
```

where $\theta$ is a renaming of $\widetilde{i}$ to fresh replication indices

- if ${ }^{\mu} x[\widetilde{M}]$ is in event $e\left(M_{1}, \ldots, M_{k-1}, C\left[{ }^{\mu} x[\widetilde{M}]\right], M_{k+1}, \ldots, M_{m}\right)$ in $Q_{0}$ for $C$ defined in Figure 22, then true
- otherwise, $\mathcal{F} \cup \theta \mathcal{F}_{\mu} \cup\left\{\theta \widetilde{M}=\widetilde{M}^{\prime}\right\}$ yields a contradiction where $\theta$ is a renaming of $I_{\mu}$ to fresh replication indices)

The function call noleak $\left(x\left[\widetilde{M^{\prime}}\right], \mathcal{I}, \mathcal{F}\right)$ shows that $x\left[\widetilde{M}^{\prime}\right]$ does not leak to the adversary, assuming $\mathcal{F}$ holds. The set $\mathcal{I}$ contains all replication indices that appear in $\mathcal{F}$. If $\mathcal{F}$ yields a contradiction, noleak is true, since it shows the absence of leak assuming $\mathcal{F}$ holds. Otherwise, $x\left[\widetilde{M}^{\prime}\right]$ may leak either because $x \in V$ so $x$ is a public variable, or because of an occurrence of a term $x[\widetilde{M}]$ in the game that reads $x\left[\widetilde{M}^{\prime}\right]$ (so $\widetilde{M}=\widetilde{M^{\prime}}$ holds) and such that the result of $x[\widetilde{M}]$ leaks.

- In case $x[\widetilde{M}]$ occurs in the term $M$ in an assignment let $y[\widetilde{i}]=M$, the function noleak recursively tries to prove that $y[\widetilde{i}]$ does not leak, when $y \widetilde{[i]}$ may use $x\left[\widetilde{M}^{\prime}\right]$, that is, when $\widetilde{M^{\prime}}=\widetilde{M}$. The fact $\widetilde{M^{\prime}}=\widetilde{M}$ and the facts $\mathcal{F}_{\mu}$ that hold at the program point $\mu$ of $x[\widetilde{M}]$
are added to the known facts $\mathcal{F}$ in the recursive call. Indeed, these facts are known to hold in this case. The replication indices are renamed to fresh indices in order to avoid using the same index variable for indices that can actually take different values.
- In case $x[\widetilde{M}]$ occurs in the arguments of an event, the arguments of the event do not leak to the adversary, so this occurrence of $x[\widetilde{M}]$ does not make $x\left[\widetilde{M^{\prime}}\right]$ leak.
- In all other cases, we consider that the result of $x[\widetilde{M}]$ may leak, so, in order to prove that $x\left[\widetilde{M}^{\prime}\right]$ does not leak, we show that the occurrence of $x[\widetilde{M}]$ at $\mu$ cannot read $x\left[\widetilde{M^{\prime}}\right]$, by showing that $\widetilde{M}=\widetilde{M^{\prime}}, \mathcal{F}_{\mu}$, and $\mathcal{F}$ together yield a contradiction.

Definition 15 ( $\mu$ follows a definition of $x$ ) We say that $\mu$ follows a definition of $x$ when $x[\widetilde{i}] \stackrel{R}{\leftarrow} T ;{ }^{\mu} \ldots$, let $x[\widetilde{i}]=M$ in ${ }^{\mu} \ldots$, find $[$ unique? $]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$ suchthat defined $\left(\widetilde{M_{j}}\right) \wedge$ $M_{j}$ then ${ }^{\mu_{j}} \ldots$ ) else $\ldots$ with $\mu_{j}=\mu$ and $x$ in $\widetilde{u_{j}}$ for some $j \leq m$, or $O(x[\widetilde{i}]: T):={ }^{\mu} P$ occurs in $Q_{0}$.

We do not mention get in the previous definition, because it is excluded by Property 3. For each $\mu$ that follows a definition of $x$ in $Q_{0}$, we define $\operatorname{defRand}_{\mu}(x)$ as follows:

$$
\operatorname{defRand}_{\mu}(x)= \begin{cases}x[\widetilde{i}] & \text { if } x \widetilde{[i]} \stackrel{R}{\leftarrow} T ;^{\mu} \ldots \text { occurs in } Q_{0} \\ y[\widetilde{M}] & \text { if let } x[\widetilde{i}]: T=y[\widetilde{M}] \text { in }{ }^{\mu} \ldots \text { occurs in } Q_{0} \text { and } \\ & y \text { is defined only by random choices in } Q_{0}\end{cases}
$$

In all other cases, $\operatorname{defRand}_{\mu}(x)$ is not defined. The variable defRand ${ }_{\mu}(x)$ is the random variable that defines $x$ just before program point $\mu$. When $x$ itself is chosen randomly at that point, $\operatorname{defRand}_{\mu}(x)$ is simply $x[\widetilde{i}]$, where $\widetilde{i}$ are the current replication indices. When $x$ is defined by an assignment of a variable $y[\widetilde{M}]$ that is random, $\operatorname{defRand}_{\mu}(x)$ is that variable. Otherwise, we give up and do not define $\operatorname{defRand}_{\mu}(x)$.

$$
\begin{aligned}
& \text { prove }^{1 \text {-ses.secr. }(x)}(\mu)=\operatorname{defRand}_{\mu}(x) \text { is defined and } \\
& \quad \text { noleak }\left(\theta \operatorname{defRand}{ }_{\mu}(x),\left\{\theta I_{\mu}\right\}, \theta \mathcal{F}_{\mu}\right) \\
& \quad \text { where } \theta \text { is a renaming of } I_{\mu} \text { to fresh replication indices }
\end{aligned}
$$

$$
\operatorname{prove}^{1 \text {-ses.secr. }(x)}(\mathcal{S})=\bigwedge_{\mu \in \mathcal{S}} \text { prove }^{1 \text {-ses.secr. }(x)}(\mu)
$$

The function call prove ${ }^{1 \text {-ses.secr. }(x)}(\mu)$ proves one-session secrecy for the definition of $x$ just before program point $\mu$. It considers only the cases in which $x$ is defined either by a random choice or by an assignment from a random choice. In other cases, the proof fails. (These other cases can typically be handled by first removing assignments as needed.) Intuitively, prove ${ }^{1-\text { ses.secr. }(x)}(\mu)$ guarantees that, when $x[\widetilde{i}]$ is defined just before program point $\mu$, the random variable defRand $\mu(x)$ that defines $x[\widetilde{i}]$ does not leak, knowing that the facts $\mathcal{F}_{\mu}$ hold. Only events and variables $y\left[\widetilde{i^{\prime}}\right]$ that do not leak depend on the random choice that defines $x[\widetilde{i}]$; the sent messages and the control flow of the process are independent of $x \widetilde{[ }]$, so the adversary obtains no information on $x[\widetilde{i}]$. That guarantees the one-session secrecy of $x[\widetilde{i}]$ when it is defined just before $\mu$. This is verified for all program points in $\mathcal{S}$ by prove ${ }^{1 \text {-ses.secr. } .(x)}(\mathcal{S})$. When $x$ is defined by assignment of $z[\widetilde{M}]$, this proof of one-session secrecy allows some array cells of $z$ to leak, provided the array cells $z[\widetilde{M}]$ used to define $x$ do not leak.

In order to prove secrecy, we also define prove ${ }^{\text {distinct }(x)}\left(\mu_{1}, \mu_{2}\right)=\left(z_{1} \neq z_{2}\right) \vee\left(\theta_{1} \mathcal{F}_{\mu_{1}} \cup \theta_{2} \mathcal{F}_{\mu_{2}} \cup\right.$ $\left\{\theta_{1} \widetilde{M}_{1}=\theta_{2} \widetilde{M}_{2}, \widetilde{i}_{1} \neq \widetilde{i}_{2}\right\}$ yields a contradiction), where defRand $\mu_{1}(x)=z_{1}\left[\widetilde{M}_{1}\right]$, defRand $\mu_{2}(x)=$ $z_{2}\left[\widetilde{M}_{2}\right], \widetilde{i}$ are the current replication indices at the definition of $x, \theta_{1}$ and $\theta_{2}$ are two distinct renamings of $\widetilde{i}$ to fresh replication indices, $\widetilde{i}_{1}=\theta_{1} \widetilde{i}$, and $\widetilde{i}_{2}=\theta_{2} \widetilde{i}$. Intuitively, prove ${ }^{\operatorname{distinct}(x)}\left(\mu_{1}, \mu_{2}\right)$ guarantees that, if $x\left[\widetilde{i}_{1}\right]$ is defined at $\mu_{1}$, so $x\left[\widetilde{i_{1}}\right]=z_{1}\left[\theta_{1} \widetilde{M}_{1}\right]$, and $x\left[\widetilde{i}_{2}\right]$ is defined at $\mu_{2}$, so $x\left[\widetilde{i}_{2}\right]=z_{2}\left[\theta_{2} \widetilde{M}_{2}\right]$, with $\widetilde{i}_{1} \neq \widetilde{i}_{2}$, then the random variables that define $x$ in these two cases, $z_{1}\left[\theta_{1} \widetilde{M}_{1}\right]$ and $z_{2}\left[\theta_{2} \widetilde{M_{2}}\right]$, are different, that is, $z_{1} \neq z_{2}$ or $\theta_{1} \widetilde{M_{1}} \neq \theta_{2} \widetilde{M_{2}}$. Therefore, $z_{1}\left[\theta_{1} \widetilde{M}_{1}\right]$ is independent of $z_{2}\left[\theta_{2} \widetilde{M}_{2}\right]$, so $x\left[\widetilde{i}_{1}\right]$ is independent of $x\left[\widetilde{i}_{2}\right]$. Combining this information with the proof of one-session secrecy, we can prove secrecy of $x$ : we define

$$
\operatorname{prove}^{\text {Secrecy }(x)}(\mathcal{S})=\operatorname{prove}^{1 \text {-ses.secr. }(x)}(\mathcal{S}) \wedge \bigwedge_{\mu_{1}, \mu_{2} \in \mathcal{S}} \operatorname{prove}^{\text {distinct }(x)}\left(\mu_{1}, \mu_{2}\right)
$$

The proof of bit secrecy is the same as for one-session secrecy:

$$
\operatorname{prove}^{\text {bit secr. }(x)}(\mathcal{S})=\text { prove }^{1-\text {-ses.secr. }(x)}(\mathcal{S})
$$

The proof of (one-session or bit) secrecy is justified by the following proposition.

Proposition 1 ((One-session or bit) secrecy) Consider an oracle definition $Q_{0}$ that satisfies Properties 3 and 4 . Let sp be 1-ses.secr. $(x)$, Secrecy $(x)$, or bit secr. $(x)$. Let $\mathcal{S}=\{\mu \mid \mu$ follows a definition of $x\}$. If $\operatorname{prove}^{s p}(\mathcal{S})$ and for all attackers $\mathcal{A} \in \mathcal{B B}$ and all evaluation contexts $C$ acceptable for $Q_{0}, \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right] \preceq \neg\left\{\left[\operatorname{prove}^{s p}(\mathcal{S})\right]\right\}\right] \leq p(\mathcal{A}, C)$, then $Q_{0}$ satisfies sp with public variables $V(x \notin V)$ up to probability $p^{\prime}$ such that $p^{\prime}(\mathcal{A}, C)=p\left(\mathcal{A}, C\left[C_{\text {sp }}[]\right]\right)$ and Bound $Q_{0}\left(V \cup\{x\}, s p, D_{\text {false }}, p\right)$.

The proof of Proposition 1 relies on the following definitions and lemma. We have

$$
\left\{\left[\operatorname{noleak}\left(x\left[\widetilde{M^{\prime}}\right], \mathcal{I}, \mathcal{F}\right)\right]\right\}=(\forall \mathcal{I}, \neg \bigwedge \mathcal{F}) \vee\left((x \notin V) \wedge \bigwedge_{\mu_{x[\widetilde{M}] \text { in }} Q_{0}}\right.
$$

- if ${ }^{\mu} x[\widetilde{M}]$ is in $M$ in an assignment let $\left.y \widetilde{i}\right]=M, M$ is built from replication indices, variables, function applications, and conditionals, and the current call is not inside a call to $\operatorname{noleak}\left(y,,_{-}\right)$, then

$$
\left\{\left[\operatorname{noleak}\left(y[\tilde{\theta i}], \mathcal{I} \cup\{\widetilde{\theta i}\}, \mathcal{F} \cup \theta \mathcal{F}_{\mu} \cup\left\{\theta \widetilde{M}=\widetilde{M^{\prime}}\right\}\right)\right]\right\}
$$

where $\theta$ is a renaming of $\widetilde{i}$ to fresh replication indices

- if ${ }^{\mu} x[\widetilde{M}]$ is in event $e\left(M_{1}, \ldots, M_{k-1}, C\left[{ }^{\mu} x[\widetilde{M}]\right], M_{k+1}, \ldots, M_{m}\right)$ for $C$ defined in Figure 22, then true
- otherwise, $\forall\left(\mathcal{I} \cup \theta I_{\mu}\right)$, $\neg \bigwedge\left(\mathcal{F} \cup \theta \mathcal{F}_{\mu} \cup\left\{\theta \widetilde{M}=\widetilde{M^{\prime}}\right\}\right)$
where $\theta$ is a renaming of $I_{\mu}$ to fresh replication indices)
$\left\{\left[\operatorname{noleak}\left(x\left[\widetilde{M}^{\prime}\right], \mathcal{I}, \mathcal{F}\right)\right]\right\}$ is the logical formula that is guaranteed when noleak $\left(x\left[\widetilde{M^{\prime}}\right], \mathcal{I}, \mathcal{F}\right)$ succeeds, up to a small probability computed by the equational prover and that bounds the probability $\left.\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right] \preceq \neg\left\{\operatorname{noleak}\left(x\left[\widetilde{M}^{\prime}\right], \mathcal{I}, \mathcal{F}\right)\right]\right\}\right]$. It is obtained by collecting formulas guaranteed by each call to " $\mathcal{F}$ yields a contradiction": such a call guarantees $\forall \widetilde{z} \in \widetilde{T}$ ",$\neg \bigwedge \mathcal{F}$ up to a small probability that it evaluates, where $\widetilde{z}$ are the non-process variables in $\mathcal{F}$ and $T^{\prime \prime}$ are their types. In the definition of $\left\{\left[\operatorname{noleak}\left(x\left[\widetilde{M}^{\prime}\right], \mathcal{I}, \mathcal{F}\right)\right]\right\}$, the notation $\forall \mathcal{I}$ means that all variables in $\mathcal{I}$ are
universally quantified in their respective types. The notation $\forall\left(\mathcal{I} \cup \theta I_{\mu}\right)$ is similar. We have similarly

$$
\begin{aligned}
\left\{\left[\text { prove }^{1 \text {-ses.secr. }(x)}(\mu)\right]\right\} & =\left\{\begin{array}{c}
\left\{\left[\operatorname{noleak}\left(\theta \operatorname{defRand}(x),\left\{\theta I_{\mu}\right\}, \theta \mathcal{F}_{\mu}\right)\right]\right\} \\
\text { if defRand }(x) \text { is defined }, \\
\text { where } \theta \text { is a renaming of } I_{\mu} \text { to fresh replication indices } \\
\text { false } \quad \text { otherwise }
\end{array}\right. \\
\left\{\left[\text { prove }^{1 \text {-ses.secr. }(x)}(\mathcal{S})\right]\right\} & =\bigwedge_{\mu \in \mathcal{S}}\left\{\left[\operatorname{prove}^{1 \text {-ses.secr. }(x)}(\mu)\right]\right\} \\
\left\{\left[\operatorname{prove}^{\text {distinct }(x)}\left(\mu_{1}, \mu_{2}\right)\right]\right\} & =\left(z_{1} \neq z_{2}\right) \vee\left(\widetilde{i}_{1}, \forall \widetilde{i_{2}}, \neg \bigwedge_{1} \mathcal{F}_{\mu_{1}} \cup \theta_{2} \mathcal{F}_{\mu_{2}} \cup\left\{\theta_{1} \widetilde{M}_{1}=\theta_{2} \widetilde{M}_{2}, \widetilde{i}_{1} \neq \widetilde{i}_{2}\right\}\right) \\
\left\{\left[\operatorname{prove}^{\operatorname{Secrecy}(x)}(\mathcal{S})\right]\right\} & =\left\{\left[\operatorname{prove}^{1 \text {-ses.secr. }(x)}(\mathcal{S})\right]\right\} \wedge \bigwedge_{\mu_{1}, \mu_{2} \in \mathcal{S}}\left\{\left[\operatorname{prove}^{\text {distinct }(x)}\left(\mu_{1}, \mu_{2}\right)\right]\right\} \\
\left\{\left[\operatorname{prove}^{\text {bit secr. }(x)}(\mathcal{S})\right]\right\} & \left.=\left\{\operatorname{prove}^{1 \text {-ses.secr. }(x)}(\mathcal{S})\right]\right\}
\end{aligned}
$$

The only semantic rules that can add $x[\widetilde{a}]$ to the environment $E$ are (NewT), (LetT), (FindT1), (New), (Let), (Find1), OracleCall), Return, AttIO), and AttYield). (get is excluded by Property 3.) By Corollary 1, the target term or process of these rules is a subterm or subprocess of $Q_{0}$ up to renaming of oracles. Hence, the target configuration Conf of these rules is at some program point $\mu$ in $T r$. In this case, we say that $x[\widetilde{a}]$ is defined just before $\mu$ in a trace $\operatorname{Tr}$. Furthermore, given $x[\widetilde{a}]$ and $T r$, there is at most one program point $\mu$ such that $x[\widetilde{a}]$ is defined just before $\mu$ in $\operatorname{Tr}$, by Lemma 29 .

Let $s p$ be 1 -ses.secr. $(x)$, $\operatorname{Secrecy}(x)$, or bit secr. $(x)$. Let $\operatorname{Tr}$ be a trace of $C\left[C_{s p}\left[Q_{0}\right]\right]$. Let $E=E_{T r}$. We define the set $\operatorname{Tidx}(\operatorname{Tr})$ of indices of successful test queries as follows:

- When $s p$ is 1 -ses.secr. $(x)$ : Let $\mu_{t}$ be the program point of the oracle that performs the test query in $Q_{1 \text {-ses.secr. }(x)}$ : ${ }^{\mu_{t}} O_{s}\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right)$. If there is a AttIO or OracleCall reduction in $\operatorname{Tr}$ with $\mu^{\prime}=\mu_{t}$, we define $E^{\prime}$ to be the environment after that reduction. If $x\left[E\left(u_{1}\right), \ldots, E\left(u_{m}\right)\right] \in \operatorname{Dom}\left(E^{\prime}\right)$, we let $\operatorname{Tidx}(\operatorname{Tr})=\{\epsilon\}$ (the empty sequence of indices). Otherwise, $\operatorname{Tidx}(\operatorname{Tr})=\emptyset$.
- When $s p$ is $\operatorname{Secrecy}(x)$ : Let $\mu_{t}$ be the program point of the oracle definition that performs the test query in $Q_{\text {Secrecy }(x)}:{ }^{\mu_{t}} O_{s}\left[i_{s}\right]\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right)$. Let $\operatorname{Tidx}(\operatorname{Tr})=$ $\left\{a \in\left[1, n_{s}\right] \mid\right.$ there is a AttIO or OracleCall reduction in $\operatorname{Tr}$ with $\mu^{\prime}=\mu_{t}, \sigma^{\prime}(\widetilde{i})=a$, and $x\left[E\left(u_{1}[a]\right), \ldots, E\left(u_{m}[a]\right)\right] \in \operatorname{Dom}\left(E^{\prime}\right)$ where $E^{\prime}$ is the environment after that reduction, and for all a AttIO or OracleCall reductions in $\operatorname{Tr}$ before the latter reduction, with $\mu^{\prime}=\mu_{t}, \sigma^{\prime}(\widetilde{i})=a^{\prime}, E\left(u_{1}\left[a^{\prime}\right]\right)=E\left(u_{1}[a]\right), \ldots$, and $E\left(u_{m}\left[a^{\prime}\right]\right)=E\left(u_{m}[a]\right)$, we have $x\left[E\left(u_{1}[a]\right), \ldots, E\left(u_{m}[a]\right)\right] \notin \operatorname{Dom}\left(E^{\prime \prime}\right)$ where $E^{\prime \prime}$ is the environment after that reduction $\}$.
The test query with index $a$ is the first successful test query for $x\left[E\left(u_{1}[a]\right), \ldots, E\left(u_{m}[a]\right)\right]$, so $x\left[E\left(u_{1}[a]\right), \ldots, E\left(u_{m}[a]\right)\right]$ is defined at that test query, that is, $x\left[E\left(u_{1}[a]\right), \ldots, E\left(u_{m}[a]\right)\right] \in$ $\operatorname{Dom}\left(E^{\prime}\right)$. For all previous test queries on the same indices, $x\left[E\left(u_{1}[a]\right), \ldots, E\left(u_{m}[a]\right)\right]$ was not defined, that is, $x\left[E\left(u_{1}[a]\right), \ldots, E\left(u_{m}[a]\right)\right] \notin \operatorname{Dom}\left(E^{\prime \prime}\right)$. The bound $n_{s}$ and the variables $u_{1}, \ldots, u_{m}$ come from $Q_{\text {Secrecy }(x)}$.
- When $s p$ is bit secr. $(x)$ : Let $\mu_{t}$ be the program point of the oracle definition in $Q_{\text {bit secr. }(x)}$ : ${ }^{\mu_{t}} O_{s}^{\prime \prime}\left(b^{\prime}: b o o l\right)$. If there is a AttIO) or OracleCall) reduction in $\operatorname{Tr}$ with $\mu^{\prime}=\mu_{t}$, we define $E^{\prime}$ to be the environment after that reduction. If $x \in \operatorname{Dom}\left(E^{\prime}\right)$, we let $\operatorname{Tidx}(\operatorname{Tr})=\{\epsilon\}$. Otherwise, $\operatorname{Tidx}(\operatorname{Tr})=\emptyset$.

Let $\operatorname{Tpp}(\operatorname{Tr})=\left\{\mu \mid \exists a \in \operatorname{Tidx}(\operatorname{Tr}), x\left[E\left(u_{1}[a]\right), \ldots, E\left(u_{m}[a]\right)\right]\right.$ is defined just before $\mu$ in $\left.\operatorname{Tr}\right\}$. When $s p$ is bit secr. $(x), m=0$, so this definition reduces to $\operatorname{Tpp}(\operatorname{Tr})=\emptyset$ if $\operatorname{Tidx}(\operatorname{Tr})=\emptyset$ and $\operatorname{Tpp}(\operatorname{Tr})=\left\{\mu_{\epsilon}\right\}$ where $x$ is defined just before $\mu_{\epsilon}$ in $\operatorname{Tr}$ otherwise. We write $\operatorname{Tr} \vdash s p$ when $\operatorname{Tr} \vdash\left\{\left[\operatorname{prove}^{s p}(\operatorname{Tpp}(\operatorname{Tr}))\right]\right.$.

Lemma 36 Consider a process $Q_{0}$ that satisfies Properties 3 and 4 Let sp be 1 -ses.secr. $(x)$, $\operatorname{Secrecy}(x)$, or bit secr. $(x)$. Let $C$ be an evaluation context acceptable for $C_{s p}\left[Q_{0}\right]$ with any public variables $V(x \notin V)$ that does not contain S nor $\overline{\mathrm{S}}$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. We have

$$
\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \mathrm{S} \wedge s p\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \overline{\mathrm{S}} \wedge s p\right] .
$$

Proof of the cases $s p=1$-ses.secr. $(x)$ and $s p=\operatorname{Secrecy}(x)$ Let $\operatorname{Tr}$ be a full trace of $C\left[C_{s p}\left[Q_{0}\right]\right]$ for attacker $\mathcal{A}$ such that $\operatorname{Tr} \vdash s p$ and $b$ is defined in $\operatorname{Tr}$, that is, $b \in \operatorname{Dom}\left(E_{T r}\right)$.

Let $E=E_{T r}$. Let $\widetilde{i}$ be the current replication indices at the definition of $x$ in $Q_{0}$. For $j \in$ $\operatorname{Tidx}(\operatorname{Tr})$, let $\widetilde{a}_{j}=E\left(u_{1}[j]\right), \ldots, E\left(u_{m}[j]\right)$, so that the test query at index $j$ tests $x\left[\widetilde{a}_{j}\right]$. Let $\operatorname{Conf}_{j}$ be the target configuration of the semantic rule that adds $x\left[\widetilde{a}_{j}\right]$ to $E$, and $\mu_{j}$ be such that $x\left[\widetilde{a}_{j}\right]$ is defined just before $\mu_{j}$ in $\operatorname{Tr}$. So $\operatorname{Conf}_{j}$ is at program point $\mu_{j}$ in $\operatorname{Tr}$. Let $z_{j}\left[\widetilde{M}_{j}\right]=\operatorname{defRand}_{\mu_{j}}(x)$ (which is always defined since $\mu_{j} \in \operatorname{Tpp}(\operatorname{Tr})$ and $\operatorname{Tr} \vdash s p$, so $\operatorname{Tr} \vdash\left\{\left[\operatorname{prove}^{1-\text { ses.secr. }(x)}\left(\mu_{j}\right)\right\}\right)$. Let $\widetilde{b}_{j}$ be such that $E,\left\{\widetilde{i} \mapsto \widetilde{a}_{j}\right\}, \widetilde{M}_{j} \Downarrow \widetilde{b}_{j}$. Then $x[\widetilde{a}]$ is added to the environment $E$ by NewT, (LetT), (New , or Let), we have $E\left(x\left[\widetilde{a}_{j}\right]\right)=E\left(z_{j}\left[\widetilde{b}_{j}\right]\right)$, and $z_{j}\left[\widetilde{b}_{j}\right]$ is chosen at random by NewT) or New in $\operatorname{Tr}$ by definition of defRand $\mu_{j}(x)$. Let us prove that, for all $j_{1} \neq j_{2}$ in $\operatorname{Tidx}(\operatorname{Tr})$, we have $z_{j_{1}} \neq z_{j_{2}}$ or $\widetilde{b}_{j_{1}} \neq \widetilde{b}_{j_{2}}$.

- When $s p$ is 1 -ses.secr. $(x)$, this is trivially true since $\operatorname{Tidx}(T r)$ contains at most one element.
- When $s p$ is $\operatorname{Secrecy}(x)$, we have $\mu_{j_{1}}, \mu_{j_{2}} \in \operatorname{Tpp}(\operatorname{Tr})$ and $\operatorname{Tr} \vdash \operatorname{Secrecy}(x)$, so we have $\operatorname{Tr} \vdash\left\{\left[\operatorname{prove}^{\operatorname{distinct}(x)}\left(\mu_{j_{1}}, \mu_{j_{2}}\right)\right]\right\}$, so $z_{j_{1}} \neq z_{j_{2}}$ or $\operatorname{Tr} \vdash \forall \widetilde{i_{1}}, \forall \widetilde{i_{2}}, \neg \bigwedge \theta_{1} \mathcal{F}_{\mu_{j_{1}}} \cup \theta_{2} \mathcal{F}_{\mu_{j_{2}}} \cup\left\{\theta_{1} \widetilde{M}_{j_{1}}=\right.$ $\left.\theta_{2} \widetilde{M}_{j_{2}}, \widetilde{i}_{1} \neq \widetilde{i}_{2}\right\}$ where $\theta_{1}$ and $\theta_{2}$ are two distinct renamings of $\widetilde{i}$ to fresh replication indices, $\widetilde{i}_{1}=\theta_{1} \widetilde{i}$, and $\widetilde{i}_{2}=\theta_{2} \widetilde{i}$. In the latter case, let $\rho=\left\{\widetilde{i}_{1} \mapsto \widetilde{a}_{j_{1}}, \widetilde{i}_{2} \mapsto \widetilde{a}_{j_{2}}\right\}$. We have $\left.\sigma_{\text {Conf }_{j_{1}}}=\widetilde{i} \mapsto \widetilde{a}_{j_{1}}\right]$. By Corollary 3, Tr, $\rho \vdash \theta_{1} \mathcal{F}_{\mu_{j_{1}}}$. Similarly, Tr, $\rho \vdash \theta_{2} \mathcal{F}_{\mu_{j_{2}}}$. Since $j_{1} \neq j_{2}, \widetilde{a}_{j_{1}} \neq \widetilde{a}_{j_{2}}$. (By construction of $\operatorname{Tidx}(\operatorname{Tr})$, we consider only the first successful test query for a certain $x\left[\widetilde{a}_{j}\right]$.) So $\operatorname{Tr}, \rho \vdash \widetilde{i}_{1} \neq \widetilde{i}_{2}$. Therefore, $\operatorname{Tr}, \rho \vdash \theta_{1} \widetilde{M}_{j_{1}} \neq \theta_{2} \widetilde{M}_{j_{2}}$, so $\widetilde{b}_{j_{1}} \neq \widetilde{b}_{j_{2}}$.

For $j \in \operatorname{Tidx}(T r)$, let us choose elements $v_{j}$ in $T$, where $T$ is the type of $x$. Let us consider the following two sets of traces:

1. $\operatorname{Tr}$ modified by choosing $b=$ true and $z_{j}\left[\widetilde{b_{j}}\right]=v_{j}$ for all $j \in \operatorname{Tidx}(\operatorname{Tr})$. (The variable $b$ is chosen and used in $Q_{s p}$. Note that the variable $y$ of $Q_{s p}$ is not defined when $b=$ true. This set contains a single trace.)
2. Tr modified by choosing $b=$ false and $y[j]=v_{j}$ and $z_{j}\left[\widetilde{b}_{j}\right]=v_{j}^{\prime}$ for any $v_{j}^{\prime} \in T$, for all $j \in \operatorname{Tidx}(T r)$. (This set contains $|T|^{|\operatorname{Tidx}(T r)|}$ traces.)

The trace $\operatorname{Tr}$ is one of the traces in these two sets: just choose the values of $b, z_{j}\left[\widetilde{b}_{j}\right]$, and $y[j]$ if $b$ is false that are used in Tr .

We show by induction on the derivation of these traces $T r_{s}\left(T r_{1}\right.$ is in set 1 and $T r_{2}$ is in set 22 that they have matching configurations $\operatorname{Conf}_{s}^{\prime}=E_{s}, \sigma, M_{s}, \mathcal{T}, \mu \mathcal{E} v_{s}, \operatorname{Conf}_{s}^{\prime}=\mathcal{Q}_{s}, \mathcal{O} r$, or $\operatorname{Conf}_{s}^{\prime}=E_{s},\left(\sigma, P_{s}\right):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s}$ for $s \in\{1,2\}$ that differ as follows:

- $E_{1}(b)=$ true while $E_{2}(b)=$ false.
- $E_{1}\left(u_{s}^{\prime}[j]\right)$ when $s p$ is $\operatorname{Secrecy}(x)$ and $E_{1}(y[j])$ are undefined even when $E_{2}\left(u_{s}^{\prime}[j]\right)$ and $E_{2}(y[j])$ are defined for some indices $j \in \operatorname{Tidx}(\operatorname{Tr})$.
- $E_{1}(z[\widetilde{a}])$ differs from $E_{2}(z[\widetilde{a}])$ for some $z$ and $\widetilde{a}$ such that for some $\widetilde{M}, \mathcal{I}, \mathcal{F}$, we have $\operatorname{Tr} \vdash\{\operatorname{noleak}(z[\widetilde{M}], \mathcal{I}, \mathcal{F})]\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},(\widetilde{M}=\widetilde{a}) \wedge \bigwedge \mathcal{F}$.
- Values inside $M_{1}$ and $M_{2}$ may differ when $\operatorname{Conf}_{s}^{\prime}$ (for $s \in\{1,2\}$ ) occurs in the derivation of

$$
\begin{aligned}
& E_{s}, \sigma, \text { let } y[\widetilde{i}]=M \text { in } M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} E_{s}\left[y[\sigma \widetilde{i}] \mapsto a_{s}\right], \sigma, M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \\
& \text { or of } E_{s},(\sigma, \text { let } y \widetilde{[i]}=M \text { in } P):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{{ }^{*}} \\
& E_{s}\left[y[\widetilde{\sigma i}] \mapsto a_{s}\right],(\sigma, P):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s}
\end{aligned}
$$

where $M$ is built from replication indices, variables, function applications, and conditionals and for some $\widetilde{M}, \mathcal{I}, \mathcal{F}$, we have $\operatorname{Tr} \vdash\{[\operatorname{noleak}(y[\widetilde{M}], \mathcal{I}, \mathcal{F})]\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},(\widetilde{M}=\widetilde{\sim}) \wedge \wedge \mathcal{F}$.

- Terms $M_{1}$ and $M_{2}$ may differ when $\operatorname{Conf}_{s}^{\prime}$ (for $s \in\{1,2\}$ ) occurs in the derivation of

$$
\begin{aligned}
& E_{s}, \sigma, \text { event } e\left(\widetilde{M}_{s}\right) ; M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} E_{s}, \sigma, \text { event } e\left(\widetilde{M}_{s}^{\prime}\right) ; M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \\
& \text { or of } E_{s},\left(\sigma, \text { event } e\left(\widetilde{M}_{s}\right) ; P\right):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} \\
& E_{s},\left(\sigma, \text { event } e\left(\widetilde{M}_{s}^{\prime}\right) ; P\right):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s}
\end{aligned}
$$

where the terms $M_{s}$ match and the only rules above this reduction and under Conf ${ }_{s}^{\prime}$ are (CtxT) with matching simple contexts any number of times followed by (CtxT) with context event $e\left(a_{s, 1}, \ldots, a_{s, k-1},[], N_{k+1}, \ldots, N_{l}\right) ; N$ or Ctx) with context event $e\left(a_{s, 1}, \ldots\right.$, $\left.a_{s, k-1},[], N_{k+1}, \ldots, N_{l}\right) ; P$ once, where

- a simple context is a context of the form $x\left[a_{1}, \ldots, a_{k-1},[], N_{k+1}, \ldots, N_{m}\right]$ or $f\left(a_{1}, \ldots\right.$, $\left.a_{k-1},[], N_{k+1}, \ldots, N_{m}\right)$ for some $x, f, k, m, a_{1}, \ldots, a_{k-1}, N_{k+1}, \ldots, N_{m}$,
- simple contexts $C_{s}$ (for $s \in\{1,2\}$ ) match when $C_{s}=x\left[a_{s, 1}, \ldots, a_{s, k-1},[], N_{k+1}, \ldots\right.$, $\left.N_{m}\right]$ or $C_{s}=f\left(a_{s, 1}, \ldots, a_{s, k-1},[], N_{k+1}, \ldots, N_{m}\right)$ for some $x, f, k, m, a_{s, 1}, \ldots, a_{s, k-1}$, $N_{k+1}, \ldots, N_{m}$, and
- terms $M_{s}($ for $s \in\{1,2\})$ match when $M_{s}=a_{s, 0}$, or $M_{s}=x\left[a_{s, 1}, \ldots, a_{s, k-1}, M_{s}^{\prime}\right.$, $\left.N_{k+1}, \ldots, N_{m}\right]$ or $M_{s}=f\left(a_{s, 1}, \ldots, a_{s, k-1}, M_{s}^{\prime}, N_{k+1}, \ldots, N_{m}\right)$ for some $x, f, k, m$, $a_{s, 0}, a_{s, 1}, \ldots, a_{s, k-1}, N_{k+1}, \ldots, N_{m}$ and matching $M_{s}^{\prime}$.
- Terms $M_{1}$ and $M_{2}$ (resp. processes $P_{1}$ and $P_{2}$ ) may differ when

$$
\begin{aligned}
M_{s} & =C_{1}\left[\ldots C_{k}\left[\operatorname{event} e\left(\widetilde{M}_{s}\right) ; M^{\prime}\right] \ldots\right] \\
P_{s} & =C_{0}\left[C_{1}\left[\ldots C_{k}\left[\text { event } e\left(\widetilde{M}_{s}\right) ; M^{\prime}\right] \ldots\right]\right] \\
\text { or } P_{s} & =\operatorname{event} e\left(\widetilde{M}_{s}\right) ; P
\end{aligned}
$$

where $k \in \mathbb{N}, C_{1} \ldots ., C_{k}$ are term contexts defined in Figure 7, $C_{0}$ is a process context defined in Figure 12, and the terms $\widetilde{M}_{s}$ match, for $s \in\{1,2\}$.

- Arguments of events in $\mu \mathcal{E} v_{1}$ and $\mu \mathcal{E} v_{2}$ may differ.
- The events S and $\overline{\mathrm{S}}$ are swapped: when $\mu \mathcal{E} v_{1}$ contains $\mathrm{S}, \mu \mathcal{E} v_{2}$ contains $\overline{\mathrm{S}}$, and conversely.
- Some additional configurations corresponding to the execution $Q_{s p}$ differ.

The proof can be sketched as follows. The different choice of $b$ leads to $E_{1}(b)=$ true and $E_{2}(b)=$ false. The only semantic rule that reads the environment is Var), when it evaluates an occurrence of the variable in question. By Definition $7, b \notin \operatorname{var}\left(Q_{0}\right) \cup \bar{V}$, so the only occurrences of $b$ are in $Q_{s p}$.

If the adversary calls oracle $O_{s}[\ldots](\widetilde{a})$ and $x[\widetilde{a}]$ is not defined, then $Q_{s p}$ simply yields. If the adversary calls oracle $O_{s}[\ldots](\widetilde{a})$ and $x[\widetilde{a}]$ is defined, then $\widetilde{a}=\widetilde{a}_{j}$ for some $j \in \operatorname{Tidx}(\operatorname{Tr})$. In set 1 , $E_{1}(b)=$ true, so $Q_{s p}$ returns $E_{1}\left(x\left[\widetilde{a}_{j}\right]\right)=E_{1}\left(z_{j}\left[\widetilde{b}_{j}\right]\right)=v_{j}$. In set $2, E_{2}(b)=$ false, so when it is the first time that the adversary calls oracle $O_{s}[\ldots](\widetilde{a})$ and $x[\widetilde{a}]$ is defined, $Q_{s p}$ chooses a fresh $y[j]$ equal to $v_{j}$, and returns $E_{2}(y[j])=v_{j}$; when the adversary calls again $O_{s}[\ldots](\widetilde{a}), Q_{s p}$ finds $u_{s}^{\prime}=j$ (by construction of $\operatorname{Tidx}(\operatorname{Tr})$ ), and returns $E_{2}(y[j])=v_{j}$. So in both sets, $Q_{s p}$ returns the same value.

If the adversary calls $O_{s}^{\prime}\left(b^{\prime}\right)$, then the result of the test $b^{\prime}=b$ differs between set 1 and set 2 , since $E_{1}(b) \neq E_{2}(b)$, so if set 1 executes $S$, then set 2 executes $\bar{S}$ and conversely. That is why the events $S$ and $\bar{S}$ are swapped.

By Definition 7. $u_{s}^{\prime}, y \notin \operatorname{var}\left(Q_{0}\right) \cup V$, so the only occurrences of $u_{s}^{\prime}$ and $y$ are in $Q_{s p}$. Therefore, the changes that come from differences in the definition of $u_{s}^{\prime}$ and $y$ are already taken into account above.

The value of $E_{1}\left(z_{j}\left[\widetilde{b_{j}}\right]\right)$ is different from the one of $E_{2}\left(z_{j}\left[\widetilde{b_{j}}\right]\right)$. Since $T r \vdash s p$, we have $\operatorname{Tr} \vdash\left\{\left[\right.\right.$ prove $\left.\left.{ }^{1 \text {-ses.secr. }(x)}\left(\mu_{j}\right)\right]\right\}$, so $\operatorname{Tr} \vdash\left\{\left[\operatorname{noleak}\left(\theta z_{j}\left[\widetilde{M}_{j}\right],\left\{\theta I_{\mu_{j}}\right\}, \theta \mathcal{F}_{\mu_{j}}\right)\right]\right\}$ where $\theta$ is a renaming of $I_{\mu_{j}}$ to fresh replication indices. We have $\sigma_{\text {Conf }_{j}}=\left[I_{\mu_{j}} \mapsto \widetilde{a}_{j}\right]$. Let $\rho=\left\{\theta I_{\mu_{j}} \mapsto \widetilde{a}_{j}\right\}$. By Corollary 3. $\operatorname{Tr}, \rho \vdash \theta \mathcal{F}_{\mu_{j}}$. Moreover, $\operatorname{Tr}, \rho \vdash \theta \widetilde{M}_{j}=\widetilde{b}_{j}$. So $\operatorname{Tr} \vdash \exists \theta I_{\mu_{j}},\left(\theta \widetilde{M}_{j}=\widetilde{b}_{j}\right) \wedge \wedge \theta \mathcal{F}_{\mu_{j}}$. Hence, for $\widetilde{M}=\theta \widetilde{M}_{j}, \mathcal{I}=\left\{\theta I_{\mu_{j}}\right\}$, and $\mathcal{F}=\theta \mathcal{F}_{\mu_{j}}$, we have $\left.\operatorname{Tr} \vdash\left\{\operatorname{noleak}\left(z_{j}[\widetilde{M}], \mathcal{I}, \mathcal{F}\right)\right]\right\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},\left(\widetilde{M}=\widetilde{b}_{j}\right) \wedge \bigwedge \mathcal{F}$.

The difference between $E_{1}(z[\widetilde{a}])$ and $E_{2}(z[\widetilde{a}])$ for $z$ and $\widetilde{a}$ such that for some $\widetilde{M}, \mathcal{I}, \mathcal{F}$, we have $\operatorname{Tr} \vdash\{\operatorname{noleak}(z[\widetilde{M}], \mathcal{I}, \mathcal{F})]\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},(\widetilde{M}=\widetilde{a}) \wedge \bigwedge \mathcal{F}$ has consequences when Var evaluates $z[\widetilde{a}]:$

$$
E_{s}, \sigma,{ }^{\mu} z[\widetilde{a}], \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} E_{s}, \sigma, E_{s}(z[\widetilde{a}]), \mathcal{T}, \mu \mathcal{E} v_{s}
$$

By Lemma 8, Property 4 applied to the configuration $\operatorname{Conf}=E_{s}, \sigma,{ }^{\mu} z[\widetilde{a}], \mathcal{T}, \mu \mathcal{E} v_{s}$ with $l=0$, we have

$$
E_{s}^{\prime}, \sigma,{ }^{\mu} z\left[\widetilde{M^{\prime}}\right], \mathcal{T}^{\prime}, \mu \mathcal{E} v_{s}^{\prime} \xrightarrow{1^{*}} E_{s}, \sigma,{ }^{\mu} z[\widetilde{a}], \mathcal{T}, \mu \mathcal{E} v_{s}
$$

by any number of applications of $\left(\mathbb{C t x T}\right.$, where ${ }^{\mu} z\left[\widetilde{M}^{\prime}\right]$ is a subterm of $C\left[C_{s p}\left[Q_{0}\right]\right]$. Furthermore, if the evaluation of $\widetilde{M^{\prime}}$ itself uses $\overline{\operatorname{Var}}$ that evaluates a $z[\widetilde{a}]$ that differs, we replace $z\left[\widetilde{M^{\prime}}\right]$ by the smallest subterm of $\widetilde{M}^{\prime}$ that evaluates a $z[\widetilde{a}]$ that differs. By this replacement, we guarantee that the evaluation of $\widetilde{M}^{\prime}$ proceeds in the same way in set 1 and set 2 and yields the same $\widetilde{a}$. Recall that $\widetilde{M^{\prime}}$ are simple terms by Invariants 2 and 5 , so the evaluation of $\widetilde{M^{\prime}}$ does not change $E_{s}, \mathcal{T}, \mu \mathcal{E} v_{s}$. So we have

$$
E_{s}, \sigma,{ }^{\mu} z\left[\widetilde{M^{\prime}}\right], \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1^{*}} E_{s}, \sigma,{ }^{\mu} z[\widetilde{a}], \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} E_{s}, \sigma, E_{s}(z[\widetilde{a}]), \mathcal{T}, \mu \mathcal{E} v_{s}
$$

for $s \in\{1,2\}$, where ${ }^{\mu} z\left[\widetilde{M}^{\prime}\right]$ is a subterm of $C\left[C_{s p}\left[Q_{0}\right]\right]$, by any number of applications of (CtxT) followed by one application of $\operatorname{Var}$. Let $\theta$ be a renaming of $I_{\mu}$ to fresh replication indices and $\rho=\left\{\theta I_{\mu} \mapsto \sigma I_{\mu}\right\}$. By Corollary 3 , $\operatorname{Tr}_{s}, \rho \vdash \theta \mathcal{F}_{\mu}$. Moreover, $E_{s}, \sigma, \widetilde{M}^{\prime} \Downarrow \widetilde{a}$, so $E_{s}, \rho, \theta \widetilde{M^{\prime}} \Downarrow \widetilde{a}$. Since $E_{T r_{s}}$ extends $E_{s}$, we have $\operatorname{Tr}_{s}, \rho \vdash \theta \widetilde{M^{\prime}}=\widetilde{a}$. Since $\operatorname{Tr}$ is among the traces $\operatorname{Tr}_{s}$, we have
$\operatorname{Tr}, \rho \vdash \theta \mathcal{F}_{\mu}$ and $\operatorname{Tr}, \rho \vdash \theta \widetilde{M^{\prime}}=\widetilde{a}$. There exists $\rho^{\prime}$ with domain $\mathcal{I}$ such that $\operatorname{Tr}, \rho^{\prime} \vdash(\widetilde{M}=$ $\widetilde{a}) \wedge \bigwedge \mathcal{F}$. So $\operatorname{Tr}, \rho \cup \rho^{\prime} \vdash \bigwedge\left(\mathcal{F} \cup \theta \mathcal{F}_{\mu} \cup\left\{\theta \widetilde{M}^{\prime}=\widetilde{a}, \widetilde{M}=\widetilde{a}\right\}\right)$. Since $\left.\operatorname{Tr} \vdash\{\operatorname{noleak}(z[\widetilde{M}], \mathcal{I}, \mathcal{F})]\right\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},(\widetilde{M}=\widetilde{a}) \wedge \bigwedge \mathcal{F}$, we have $\operatorname{Tr} \vdash \neg(\forall \mathcal{I}, \neg \bigwedge \mathcal{F})$, so $\operatorname{Tr}$ satisfies the second disjunct of $\{\operatorname{noleak}(z[\widetilde{M}], \mathcal{I}, \mathcal{F})]\}$. Therefore, $z \notin V$, so the occurrence of ${ }^{\mu} z\left[\widetilde{M}^{\prime}\right]$ evaluated above is either in $Q_{s p}$, and in this case $z$ is actually $x$ and this case has already been studied above, or in $Q_{0}$. In the latter situation, we are in one of the following three cases:

- ${ }^{\mu} z\left[\widetilde{M}^{\prime}\right]$ is in $M$ in an assignment ${ }^{\mu^{\prime}}$ let $y[\widetilde{i}]=M$ in $Q_{0}, M$ is built from replication indices, variables, function applications, and conditionals and $\operatorname{Tr} \vdash\{[\operatorname{noleak}(y[\widetilde{\theta i}], \mathcal{I} \cup\{\widetilde{\theta i}\}, \mathcal{F} \cup$ $\left.\left.\left.\theta \mathcal{F}_{\mu} \cup\left\{\theta \widetilde{M^{\prime}}=\widetilde{M}\right\}\right)\right]\right\}$ where $\theta$ is a renaming of $\widetilde{i}$ to fresh replication indices. Let $\widetilde{M^{\prime \prime}}=\widetilde{\theta i}$, $\mathcal{I}^{\prime}=\mathcal{I} \cup\{\theta \widetilde{\theta i}\}$, and $\mathcal{F}^{\prime}=\mathcal{F} \cup \theta \mathcal{F}_{\mu} \cup\left\{\theta \widetilde{M^{\prime}}=\widetilde{M}\right\}$. Since $\mu^{\prime}$ is above $\mu$, by Lemma 6 , there is a configuration inside $\mu^{\prime}$ before Conf in Tr. By Lemma 8 applied to that configuration (Property 1 when the assignment is a process, Property 4 with $l=0$ when it is a term), the assignment ${ }^{\mu^{\prime}}$ let $y[\widetilde{i}]=M$ is evaluated by

$$
\begin{aligned}
& E_{s}, \sigma,{ }^{\mu^{\prime}} \text { let } y \widetilde{[i]}=M \text { in } M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s}{ }^{*} E_{s}\left[y[\sigma \widetilde{i}] \mapsto a_{s}\right], \sigma, M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \\
& \text { or } E_{s},\left(\sigma,{ }^{\mu^{\prime}} \text { let } y[\widetilde{i}]=M \text { in } P\right):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{{ }^{*}} \\
& E_{s}\left[y[\widetilde{\sigma i}] \mapsto a_{s}\right],(\sigma, P):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s}
\end{aligned}
$$

for $s \in\{1,2\}$. We have $\left.\operatorname{Tr} \vdash\left\{\operatorname{noleak}\left(y\left[\widetilde{M^{\prime \prime}}\right], \mathcal{I}^{\prime}, \mathcal{F}^{\prime}\right)\right]\right\}$. Moreover $\widetilde{i}=I_{\mu}$ and $\operatorname{Tr}, \rho \cup$ $\rho^{\prime} \vdash \vec{i}=\sigma \widetilde{i}$ by definition of $\rho$. Hence $\operatorname{Tr}, \rho \cup \rho^{\prime} \vdash \widetilde{M^{\prime \prime}}=\sigma \widetilde{i}$ and $T r, \rho \cup \rho^{\prime} \vdash \mathcal{F}^{\prime}$, so $\operatorname{Tr} \vdash \exists \mathcal{I}^{\prime},\left(\widetilde{M^{\prime \prime}}=\sigma \widetilde{i}\right) \wedge \bigwedge \mathcal{F}^{\prime}$. Hence we are in a case in which different values inside terms $M_{1}$ and $M_{2}$ are allowed. Furthermore, the added values $E_{s}(y[\sigma \widetilde{i}])=a_{s}$ may differ. Let $\widetilde{a}^{\prime}=\sigma \widetilde{i}$. We have $\operatorname{Tr} \vdash\left\{\left[\operatorname{noleak}\left(y\left[\widetilde{M^{\prime \prime}}\right], \mathcal{I}^{\prime}, \mathcal{F}^{\prime}\right)\right]\right\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I}^{\prime},\left(\widetilde{M^{\prime \prime}}=\widetilde{a}^{\prime}\right) \wedge \wedge \mathcal{F}^{\prime}$, so $E_{1}\left(y\left[\widetilde{a}^{\prime}\right]\right)$ is indeed allowed to differ from $E_{2}\left(y\left[\widetilde{a}^{\prime}\right]\right)$.

- ${ }^{\mu} z\left[\widetilde{M}^{\prime}\right]$ is in ${ }^{\mu^{\prime}}$ event $e\left(M_{1}, \ldots, M_{k-1}, C\left[{ }^{\mu} z\left[\widetilde{M^{\prime}}\right]\right], M_{k+1}, \ldots, M_{m}\right)$ in $Q_{0}$, for $C$ defined in Figure 22, Since $\mu^{\prime}$ is above $\mu$, by Lemma 6, there is a configuration inside $\mu^{\prime}$ before Conf in $T r$. By Lemma 8 applied to that configuration (Property 1 when the event is a process, Property 4 with $l=0$ when it is a term), the evaluation of the event starts from a configuration at $\mu^{\prime}$ in $T r$. The evaluation of event $e\left(M_{1}, \ldots, M_{k-1}, C\left[{ }^{\mu} z\left[\widetilde{M}^{\prime}\right]\right], M_{k+1}, \ldots, M_{m}\right)$ first evaluates $M_{1}, \ldots, M_{k-1}$ to values using CtxT) or Ctx with an event context. (If they evaluated to abort event values, $C\left[{ }^{\mu} z\left[M^{\prime}\right]\right]$ would not be evaluated.) Then if evaluates the context $C: y[\widetilde{i}] \stackrel{R}{\leftarrow} T ; C$ is evaluated by $(\overline{\text { NewT }}$, let $y[\widetilde{i}]=M$ in $C$ is evaluated by (LetT), if $M$ then $C$ else $N^{\prime}$ is evaluated by (IfT1) ( $M$ must evaluate to true because otherwise, ${ }^{\mu} z\left[\widetilde{M}^{\prime}\right]$ would not be evaluated), if $M$ then $N$ else $C$ is evaluated by (IfT2) ( $M$ must not evaluate to true because otherwise, ${ }^{\mu} z\left[\widetilde{M}^{\prime}\right]$ would not be evaluated), event $e(\widetilde{M}) ; C$ is evaluated by EventT), and find contexts are evaluated by rules for find, until we reach

$$
\text { event } e\left(a_{s, 1}, \ldots, a_{s, k-1}, C_{s, 1}\left[\ldots C_{s, l}\left[{ }^{\mu} z\left[\widetilde{M}^{\prime}\right]\right] \ldots\right], M_{k+1}, \ldots, M_{m}\right)
$$

for $s \in\{1,2\}$, where $C_{s, 1}, \ldots, C_{s, l}$ are matching simple contexts. (Values may differ in case $M_{1}, \ldots, M_{k-1}$, or terms in $C$ contain other occurrences of variables whose value differs.) At this point, the reduction proceeds as follows:

$$
\begin{aligned}
& E_{s}, \sigma, \text { event } e\left(\widetilde{M}_{s}\right) ; M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} E_{s}, \sigma, \text { event } e\left(\widetilde{M_{s}^{\prime}}\right) ; M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \\
& \text { or } E_{s},\left(\sigma, \text { event } e\left(\widetilde{M}_{s}\right) ; P\right), \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} E_{s},\left(\sigma, \text { event } e\left(\widetilde{M}_{s}^{\prime}\right) ; P\right), \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s}
\end{aligned}
$$

by Var , CtxT with matching simple contexts any number of times followed by (CtxT) or (Ctx) with context event $e\left(a_{s, 1}, \ldots, a_{s, k-1},[], M_{k+1}, \ldots, M_{m}\right) ; \ldots$ once, where

$$
\begin{aligned}
\widetilde{M}_{s} & =a_{s, 1}, \ldots, a_{s, k-1}, C_{s, 1}\left[\ldots C_{s, l}\left[\mu z\left[\widetilde{M}^{\prime}\right]\right] \ldots\right], M_{k+1}, \ldots, M_{m} \\
\text { and } \widetilde{M}_{s}^{\prime} & =a_{s, 1}, \ldots, a_{s, k-1}, C_{s, 1}\left[\ldots C_{s, l}\left[a_{s}\right] \ldots\right], M_{k+1}, \ldots, M_{m}
\end{aligned}
$$

for $s \in\{1,2\}$. Further reductions still manipulate configurations of the same form until the event itself is executed by (EventT) or Event, which adds the event $e$ with possibly different arguments to $\mu \mathcal{E} v_{s}$.

- $\operatorname{Tr} \vdash \forall\left(\mathcal{I} \cup \theta I_{\mu}\right), \neg \bigwedge\left(\mathcal{F} \cup \theta \mathcal{F}_{\mu} \cup\left\{\theta \widetilde{M^{\prime}}=\widetilde{M}\right\}\right)$ where $\theta$ is a renaming of $I_{\mu}$ to fresh replication indices. We have $\operatorname{Tr}, \rho \cup \rho^{\prime} \vdash \neg \bigwedge\left(\mathcal{F} \cup \theta \mathcal{F}_{\mu} \cup\left\{\theta \widetilde{M}^{\prime}=\widetilde{M}\right\}\right)$. That yields a contradiction, so this case does not happen.

The sequence of events $\mu \mathcal{E} v_{1}$ (resp. $\mu \mathcal{E} v_{2}$ ) is never read by the semantic rules. It is only read by the distinguisher. Therefore, changes in this sequence of events do not modify the rest of the trace.

That concludes the proof that traces in set 1 and set 2 match.
Furthermore, the trace in set 1 and the traces in set 2 have the same probability. All full traces of $C\left[C_{s p}\left[Q_{0}\right]\right]$ for attacker $\mathcal{A}$ that define $b$ and that satisfy $s p$ belong to set 1 or to set 2 for some $\operatorname{Tr}$ (for instance using the trace in question as $\operatorname{Tr}$ ). Therefore, these sets form a partition of the full traces of $C\left[C_{s p}\left[Q_{0}\right]\right]$ for attacker $\mathcal{A}$ that define $b$ and that satisfy $s p$, and the sets that execute S have the same probability as the sets that execute $\overline{\mathrm{S}}$. Moreover, the traces of $C\left[C_{s p}\left[Q_{0}\right]\right]$ that do not define $b$ execute neither S nor $\overline{\mathrm{S}}$. So $\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \mathrm{S} \wedge s p\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \overline{\mathrm{S}} \wedge s p\right]$.

Proof of the case $s p=$ bit secr. $(x) \quad$ Let $\operatorname{Tr}$ be a full trace of $C\left[C_{s p}\left[Q_{0}\right]\right]$ for attacker $\mathcal{A}$ such that $T r \vdash s p$. Let $E=E_{T r}$.

If $\operatorname{Tidx}(\operatorname{Tr})=\emptyset$, then $\operatorname{Tr}$ executes neither S nor $\overline{\mathrm{S}}$.
Otherwise, $\operatorname{Tidx}(\operatorname{Tr})=\{\epsilon\}$ and $x$ is defined in $\operatorname{Tr}$, that is, $x \in \operatorname{Dom}(E)$. Let Conf $\epsilon$ be the target configuration of the semantic rule that adds $x$ to $E$, and $\mu_{\epsilon}$ be such that $x$ is defined just before $\mu_{\epsilon}$ in $\operatorname{Tr}$. So $\operatorname{Conf}_{\epsilon}$ is at program point $\mu_{\epsilon}$ in $\operatorname{Tr}$. Let $z_{\epsilon}\left[\widetilde{M}_{\epsilon}\right]=\operatorname{defRand} \mu_{\epsilon}(x)$ (which is always defined since $\mu_{\epsilon} \in \operatorname{Tpp}(\operatorname{Tr})$ and $\operatorname{Tr} \vdash s p$, so $\left.\operatorname{Tr} \vdash\left\{\left[\operatorname{prove}^{1 \text {-ses.secr. }(x)}\left(\mu_{\epsilon}\right)\right]\right\}\right)$. Let $\widetilde{b}_{\epsilon}$ be such that $E, \emptyset, \widetilde{M}_{\epsilon} \Downarrow \widetilde{b}_{\epsilon}$. Then $x$ is added to the environment $E$ by (NewT), LetT), (New), or (Let), we have $E(x)=E\left(z_{\epsilon}\left[\widetilde{b}_{\epsilon}\right]\right)$, and $z_{\epsilon}\left[\widetilde{b}_{\epsilon}\right]$ is chosen at random by NewT or New in $\operatorname{Tr}$ by definition of defRand $\mu_{\epsilon}(x)$.

Let us consider the following two traces:

1. $\operatorname{Tr} r_{1}$ is $\operatorname{Tr}$ modified by choosing $z_{\epsilon}\left[\widetilde{b_{\epsilon}}\right]=$ true.
2. $\operatorname{Tr}_{2}$ is $\operatorname{Tr}$ modified by choosing $z_{\epsilon}\left[\widetilde{b_{\epsilon}}\right]=$ false.

The trace $\operatorname{Tr}$ is one of these two traces: just choose the value $z_{\epsilon}\left[\widetilde{b}_{\epsilon}\right]$ that is used in $\operatorname{Tr}$.
We show by induction on the derivation of these traces $T r_{s}$ that they have matching configurations $\operatorname{Conf}_{s}^{\prime}=E_{s}, \sigma, M_{s}, \mathcal{T}, \mu \mathcal{E} v_{s}, \operatorname{Conf}_{s}^{\prime}=\mathcal{Q}_{s}, \mathcal{O} r$, or Conf ${ }_{s}^{\prime}=E_{s},\left(\sigma, P_{s}\right):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s}$ for $s \in\{1,2\}$ that differ as follows:

- $E_{1}(z[\widetilde{a}])$ differs from $E_{2}(z[\widetilde{a}])$ for some $z$ and $\widetilde{a}$ such that for some $\widetilde{M}, \mathcal{I}, \mathcal{F}$, we have $\operatorname{Tr} \vdash\{\operatorname{noleak}(z[\widetilde{M}], \mathcal{I}, \mathcal{F})]\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},(\widetilde{M}=\widetilde{a}) \wedge \bigwedge \mathcal{F}$.
- Values inside $M_{1}$ and $M_{2}$ may differ when $\operatorname{Conf}_{s}^{\prime}$ (for $s \in\{1,2\}$ ) occurs in the derivation of

$$
\begin{aligned}
& E_{s}, \sigma, \text { let } y[\widetilde{i}]=M \text { in } M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1}{ }^{*} E_{s}\left[y[\sigma \widetilde{i}] \mapsto a_{s}\right], \sigma, M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \\
& \text { or of } E_{s},(\sigma, \text { let } y \widetilde{[i]}=M \text { in } P):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{{ }^{*}} \\
& E_{s}\left[y[\widetilde{\sigma i}] \mapsto a_{s}\right],(\sigma, P):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s}
\end{aligned}
$$

where $M$ is built from replication indices, variables, function applications, and conditionals and for some $\widetilde{M}, \mathcal{I}, \mathcal{F}$, we have $\operatorname{Tr} \vdash\{[\operatorname{noleak}(y[\widetilde{M}], \mathcal{I}, \mathcal{F})]\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},(\widetilde{M}=\sigma \widetilde{i}) \wedge \bigwedge \mathcal{F}$.

- Terms $M_{1}$ and $M_{2}$ may differ when $\operatorname{Conf}_{s}^{\prime}$ (for $s \in\{1,2\}$ ) occurs in the derivation of

$$
\begin{aligned}
& E_{s}, \sigma, \text { event } e\left(\widetilde{M}_{s}\right) ; M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} E_{s}, \sigma, \text { event } e\left(\widetilde{M}_{s}^{\prime}\right) ; M^{\prime}, \mathcal{T}, \mu \mathcal{E} v_{s} \\
& \text { or of } E_{s},\left(\sigma, \text { event } e\left(\widetilde{M}_{s}\right) ; P\right):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s} \xrightarrow{1} \\
& E_{s},\left(\sigma, \text { event } e\left(\widetilde{M}_{s}^{\prime}\right) ; P\right):: \mathcal{S} t_{s}, \mathcal{Q}_{s}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v_{s}
\end{aligned}
$$

where the terms $M_{s}$ match and the only rules above this reduction and under $\operatorname{Conf}_{s}^{\prime}$ are (CtxT) with matching simple contexts any number of times followed by (CtxT with context event $e\left(a_{s, 1}, \ldots, a_{s, k-1},[], N_{k+1}, \ldots, N_{l}\right) ; N$ or Ctx) with context event $e\left(a_{s, 1}, \ldots\right.$, $\left.a_{s, k-1},[], N_{k+1}, \ldots, N_{l}\right) ; P$ once, where simple contexts and matching are defined as in the cases $s p=1$-ses.secr. $(x)$ and $s p=\operatorname{Secrecy}(x)$.

- Terms $M_{1}$ and $M_{2}$ (resp. processes $P_{1}$ and $P_{2}$ ) may differ when

$$
\begin{aligned}
& \quad M_{s}=C_{1}\left[\ldots C_{k}\left[\text { event } e\left(\widetilde{M}_{s}\right) ; M^{\prime}\right] \ldots\right] \\
& \quad P_{s}=C_{0}\left[C_{1}\left[\ldots C_{k}\left[\text { event } e\left(\widetilde{M}_{s}\right) ; M^{\prime}\right] \ldots\right]\right] \\
& \text { or } P_{s}=\text { event } e\left(\widetilde{M}_{s}\right) ; P
\end{aligned}
$$

where $k \in \mathbb{N}, C_{1} \ldots, C_{k}$ are term contexts defined in Figure 7, $C_{0}$ is a process context defined in Figure 12 , and the terms $\widetilde{M}_{s}$ match, for $s \in\{1,2\}$.

- Arguments of events in $\mu \mathcal{E} v_{1}$ and $\mu \mathcal{E} v_{2}$ may differ.
- The events $S$ and $\bar{S}$ are swapped: when $\mu \mathcal{E} v_{1}$ contains $S$, $\mu \mathcal{E} v_{2}$ contains $\bar{S}$, and conversely.
- Some additional configurations corresponding to the execution $Q_{s p}$ differ.

The proof can be sketched as follows.
If the adversary calls $O_{s}^{\prime \prime}\left(b^{\prime}\right)$, either directly with rule AttIO or through the context with rule OracleCall), then $x$ is defined (since $\operatorname{Tidx}(\operatorname{Tr})=\{\epsilon\}$ ) and the result of the test $x=b^{\prime}$ differs between $\operatorname{Tr}_{1}$ and $\operatorname{Tr}_{2}$, since $E_{\frac{1}{S}}(x)=E_{1}\left(z_{\epsilon}\left[\widetilde{b_{\epsilon}}\right]\right)=$ true $\neq E_{2}(x)=E_{2}\left(z_{\epsilon}\left[\widetilde{b_{\epsilon}}\right]\right)=$ false, so if $\operatorname{Tr}_{1}$ executes S , then $\operatorname{Tr}_{2}$ executes $\overline{\mathrm{S}}$ and conversely. That is why the events S and $\overline{\mathrm{S}}$ are swapped.

The value of $E_{1}\left(z_{\epsilon}\left[\widetilde{b_{\epsilon}}\right]\right)$ is different from the one of $E_{2}\left(z_{\epsilon}\left[\widetilde{b_{\epsilon}}\right]\right)$. Since $T r \vdash s p$, we have $\operatorname{Tr} \vdash\left\{\left[\right.\right.$ prove $\left.\left.{ }^{1 \text {-ses.secr. }(x)}\left(\mu_{\epsilon}\right)\right]\right\}$, so $\operatorname{Tr} \vdash\left\{\left[\operatorname{noleak}\left(\theta z_{\epsilon}\left[\widetilde{M}_{\epsilon}\right],\left\{\theta I_{\mu_{\epsilon}}\right\}, \theta \mathcal{F}_{\mu_{\epsilon}}\right)\right]\right\}$ where $\theta$ is a renaming of $I_{\mu_{\epsilon}}$ to fresh replication indices. Here, $I_{\mu_{\epsilon}}$ is empty since $x$ is defined under no replication. We have $\sigma_{\text {Conf }_{\epsilon}}=[]$. Let $\rho=\emptyset$. By Corollary 3. $\operatorname{Tr}, \rho \vdash \theta \mathcal{F}_{\mu_{\epsilon}}$. Moreover, $\operatorname{Tr}, \rho \vdash \theta \widetilde{M}_{\epsilon}=\widetilde{b}_{\epsilon}$. So $\operatorname{Tr} \vdash \exists \theta I_{\mu_{\epsilon}},\left(\theta \widetilde{M}_{\epsilon}=\widetilde{b}_{\epsilon}\right) \wedge \wedge \theta \mathcal{F}_{\mu_{\epsilon}}$. Hence, for $\widetilde{M}=\theta \widetilde{M}_{\epsilon}, \mathcal{I}=\left\{\theta I_{\mu_{\epsilon}}\right\}$, and $\mathcal{F}=\theta \mathcal{F}_{\mu_{\epsilon}}$, we have $\operatorname{Tr} \vdash\left\{\left[\operatorname{noleak}\left(z_{\epsilon}[\widetilde{M}], \mathcal{I}, \mathcal{F}\right)\right]\right\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},\left(\widetilde{M}=\widetilde{b}_{\epsilon}\right) \wedge \bigwedge \mathcal{F}$.

The difference between $E_{1}(z[\widetilde{a}])$ and $E_{2}(z[\widetilde{a}])$ for $z$ and $\widetilde{a}$ such that for some $\widetilde{M}, \mathcal{I}, \mathcal{F}$, we have $\operatorname{Tr} \vdash\{\operatorname{noleak}(z[\widetilde{M}], \mathcal{I}, \mathcal{F})]\}$ and $\operatorname{Tr} \vdash \exists \mathcal{I},(\widetilde{M}=\widetilde{a}) \wedge \bigwedge \mathcal{F}$ has consequences when Var evaluates $z[\widetilde{a}]$, as in the cases $s p=1$-ses.secr. $(x)$ and $s p=\operatorname{Secrecy}(x)$. That concludes the proof that traces $T r_{1}$ and $T r_{2}$ match.

Furthermore, the traces $\operatorname{Tr}_{1}$ and $\operatorname{Tr}_{2}$ have the same probability. All full traces of $C\left[C_{s p}\left[Q_{0}\right]\right]$ for attacker $\mathcal{A}$ such that $\operatorname{Tidx}$ is non-empty and that satisfy $s p$ are $\operatorname{Tr}_{1}$ or $\operatorname{Tr}_{2}$ for some $\operatorname{Tr}$ (for instance using the trace in question as $\operatorname{Tr}$ ). Therefore, $\operatorname{Tr}_{1}$ and $T r_{2}$ form a partition of the full traces of $C\left[C_{s p}\left[Q_{0}\right]\right]$ for attacker $\mathcal{A}$ such that Tidx is non-empty and that satisfy $s p$, and half of these traces execute S , the other half execute $\overline{\mathrm{S}}$. Moreover, the traces of $C\left[C_{s p}\left[Q_{0}\right]\right]$ such that Tidx is empty execute neither S nor $\overline{\mathrm{S}}$. So $\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \mathrm{S} \wedge s p\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \overline{\mathrm{S}} \wedge s p\right]$.

Proof of Proposition 1 Let $s p$ be 1-ses.secr. $(x)$, Secrecy $(x)$, or bit secr. $(x)$. Let $C$ be an evaluation context acceptable for $C_{s p}\left[Q_{0}\right]$ with public variables $V(x \notin V)$ that does not contain S nor $\overline{\mathrm{S}}$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. We have

$$
\begin{aligned}
\operatorname{Adv}_{Q_{0}}^{s p}(\mathcal{A}, C)= & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \overline{\mathrm{S}}\right] \\
= & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \mathrm{S} \wedge s p\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \mathrm{S} \wedge \neg s p\right] \\
& -\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \overline{\mathrm{S}} \wedge s p\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \overline{\mathrm{S}} \wedge \neg s p\right] \\
= & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \mathrm{S} \wedge \neg s p\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \overline{\mathrm{S}} \wedge \neg s p\right] \quad \text { by Lemma } 36 \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \neg s p\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \neg\left\{\left[\operatorname{prove}^{s p}(\{\mu \mid \mu \text { follows a definition of } x\})\right]\right\}\right] \\
& \text { because, for all } \operatorname{Tr}, \operatorname{Tpp}(\operatorname{Tr}) \subseteq\{\mu \mid \mu \text { follows a definition of } x\} \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right] \preceq \neg\left\{\left[\operatorname{prove}^{s p}(\{\mu \mid \mu \text { follows a definition of } x\})\right]\right\}\right] \text { by Lemma } 1 \\
\leq & p\left(\mathcal{A}, C\left[C_{s p}[]\right]\right)=p^{\prime}(\mathcal{A}, C)
\end{aligned}
$$

So $Q_{0}$ satisfies $s p$ with public variables $V$ up to probability $p^{\prime}$. Moreover,

$$
\begin{aligned}
\operatorname{Adv}_{Q_{0}}\left(\mathcal{A}, C\left[C_{s p}[]\right], s p, D_{\text {false }}\right) & =\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}\left[Q_{0}\right]\right]: \overline{\mathrm{S}} \vee \text { NonUnique }_{Q_{0}}\right] \\
& \leq \operatorname{Adv}_{Q_{0}}^{s p}(\mathcal{A}, C) \leq p\left(\mathcal{A}, C\left[C_{s p}[]\right]\right)
\end{aligned}
$$

so $\operatorname{Bound}_{Q_{0}}\left(V \cup\{x\}, s p, D_{\text {false }}, p\right)$.

Example 5 As we shall see in Example 10, the oracle definition $Q_{0}$ of Example 1 can be transformed into the following oracle definition $Q_{0}^{\prime \prime}$ :

$$
\begin{aligned}
& Q_{0}^{\prime \prime}=\operatorname{Start}():=x_{k} \stackrel{R}{\leftarrow} T_{k} ; x_{m k} \stackrel{R}{\leftarrow} T_{m k} ; \text { return }() ;\left(Q_{A}^{\prime \prime} \mid Q_{B}^{\prime \prime}\right) \\
& Q_{A}^{\prime \prime}=\text { foreach } i \leq n \text { do } O_{A}[i]():=x_{k}^{\prime} \stackrel{R}{\leftarrow} T_{k} ; x_{r} \stackrel{R}{\leftarrow} T_{r} ; \\
& \quad \text { let } x_{m}: \text { bitstring }=\operatorname{enc}^{\prime}\left(\mathrm{Z}_{k}, x_{k}, x_{r}\right) \text { in } \\
& \left.\quad \text { return }\left(x_{m}, \operatorname{mac}^{\prime}\left(x_{m}, x_{m k}\right)\right)\right) \\
& Q_{B}^{\prime \prime}=\text { foreach } i^{\prime} \leq n \text { do } O_{B}\left[i^{\prime}\right]\left(x_{m}^{\prime}, x_{m a}\right):= \\
& \quad \text { find } u \leq n \text { suchthat defined }\left(x_{m}[u], x_{k}^{\prime}[u]\right) \wedge \\
& \quad x_{m}^{\prime}=x_{m}[u] \wedge \text { verify }\left(x_{m}^{\prime}, x_{m k}, x_{m a}\right) \text { then } \\
& \text { let } x_{k}^{\prime \prime}: T_{k}=x_{k}^{\prime}[u] \text { in return }()
\end{aligned}
$$

and $Q_{0} \approx_{p}^{x_{k}^{\prime \prime}} Q_{0}^{\prime \prime}$. In order to prove the one-session secrecy of $x_{k}^{\prime \prime}$, we notice that $x_{k}^{\prime \prime}$ is defined by let $x_{k}^{\prime \prime}: T_{k}=x_{k}^{\prime}[u]$, the only variable access to $x_{k}^{\prime}$ in $Q_{0}^{\prime \prime}$ is let $x_{k}^{\prime \prime}: T_{k}=x_{k}^{\prime}[u]$, and $x_{k}^{\prime \prime}$ is not used in $Q_{0}^{\prime \prime}$. So by Proposition $1 . Q_{0}^{\prime \prime}$ satisfies the one-session secrecy of $x_{k}^{\prime \prime}$ without public variables up to probability 0 . (We have $\operatorname{defRand}_{\mu}\left(x_{k}^{\prime \prime}\right)=x_{k}^{\prime}[u]$ and $\left.\left\{\operatorname{noleak}\left(x_{k}^{\prime}[u], \mathcal{I}, \mathcal{F}\right)\right]\right\}=(\forall \mathcal{I}, \neg \bigwedge \mathcal{F}) \vee\left(\left(x_{k}^{\prime} \notin\right.\right.$ $\left.\left.V) \wedge\left\{\operatorname{noleak}\left(x_{k}^{\prime \prime}[\widetilde{\theta i}], \mathcal{I}^{\prime}, \mathcal{F}^{\prime}\right)\right]\right\}\right)=\operatorname{true}$ since $x_{k}^{\prime} \notin V, x_{k}^{\prime \prime} \notin V$, and $\left\{\left[\operatorname{noleak}\left(x_{k}^{\prime \prime}[\widetilde{\theta i}], \mathcal{I}^{\prime}, \mathcal{F}^{\prime}\right)\right]\right\}=\left(\forall \mathcal{I}^{\prime}\right.$, $\left.\neg \bigwedge \mathcal{F}^{\prime}\right) \vee\left(\left(x_{k}^{\prime \prime} \notin V\right) \wedge\right.$ true $)=$ true. So $\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}^{\prime \prime}\right] \preceq \neg\left\{\left[\right.\right.\right.$ prove $\left.\left.\left.{ }^{1 \text {-ses.secr. }\left(x_{k}^{\prime \prime}\right)}(\mathcal{S})\right]\right\}\right]=0$.) By Lemma 21, the oracle definition $Q_{0}$ of Example 1 also satisfies the one-session secrecy of $x_{k}^{\prime \prime}$ without public variables up to probability $p^{\prime}(\mathcal{A}, C)=2 p\left(\mathcal{A}, C\left[C_{1-\text { ses.secr. }\left(x_{k}^{\prime \prime}\right)}[]\right], t_{\mathrm{s}}\right)$. However, this process does not preserve the secrecy of $x_{k}^{\prime \prime}$, because the adversary can force several sessions of $B$ to use the same key $x_{k}^{\prime \prime}$, by replaying the message sent by $A$. (Accordingly, prove ${ }^{\text {Secrecy }(x)}(\mathcal{S})$ is not satisfied.)

The criteria given in this section might seem restrictive, but in fact, they should be sufficient for all protocols, provided the previous transformation steps are powerful enough to transform the protocol into a simpler protocol, on which these criteria can then be applied.

### 4.2 Correspondences

### 4.2.1 Example

We illustrate the proof of correspondences on the following example, inspired by the corrected Woo-Lam public key protocol 73]:

$$
\begin{aligned}
& B \rightarrow A:(N, B) \\
& A \rightarrow B:\left\{p k_{A}, B, N\right\}_{s k_{A}}
\end{aligned}
$$

This protocol is a simple nonce challenge: $B$ sends to $A$ a fresh nonce $N$ and its identity. $A$ replies by signing the nonce $N, B$ 's identity, and $A$ 's public key (which we use here instead of $A$ 's identity for simplicity: this avoids having to relate identities and keys; CryptoVerif can obviously also handle the version with $A$ 's identity). The signatures are assumed to be (existentially) unforgeable under chosen message attacks (UF-CMA) 49, so, when $B$ receives the signature, $B$ is convinced that $A$ is present. The signature cannot be a replay because the nonce $N$ is signed.

In our calculus, this protocol is encoded by the following oracle definition $G_{0}$, explained below:

$$
\begin{aligned}
G_{0}= & O_{0}():=r k_{A} \stackrel{R}{\leftarrow} \text { keyseed } ; \text { let } p k_{A}=\operatorname{pkgen}\left(r k_{A}\right) \text { in } \\
& \text { let } s k_{A}=\operatorname{skgen}\left(r k_{A}\right) \text { in return }\left(p k_{A}\right) ;\left(Q_{A} \mid Q_{B}\right) \\
Q_{A}= & \text { foreach } i_{A} \leq n \text { do } O_{A}\left[i_{A}\right]\left(x_{N}: \text { nonce }, x_{B}: \text { host }\right):= \\
& \text { event } e_{A}\left(p k_{A}, x_{B}, x_{N}\right) ; r \stackrel{R}{\leftarrow} \text { seed } ; \\
& \text { return }\left(\operatorname{sign}\left(\operatorname{concat}\left(p k_{A}, x_{B}, x_{N}\right), s k_{A}, r\right)\right) \\
Q_{B}= & \text { foreach } i_{B} \leq n \text { do } O_{B 1}\left[i_{B}\right]\left(x_{p k_{A}}: p k e y\right):=N \stackrel{R}{\leftarrow} \text { nonce } ; \\
& \text { return }(N, B) ; O_{B 2}\left[i_{B}\right](s: \text { signature }):=; \\
& \text { if verify }\left(\operatorname{concat}\left(x_{p k_{A}}, B, N\right), x_{p k_{A}}, s\right) \text { then } \\
& \text { if } x_{p k_{A}}=p k_{A} \text { then event } e_{B}\left(x_{p k_{A}}, B, N\right)
\end{aligned}
$$

The oracle definition $G_{0}$ is assumed to run in interaction with an adversary, which also models the network. $G_{0}$ first receives a call to oracle $O_{0}$ without argument, from the adversary. Then, it chooses randomly with uniform probability a bitstring $r k_{A}$ in the type keyseed, by the construct
$r k_{A} \stackrel{R}{\leftarrow}$ keyseed. Then, $G_{0}$ generates the public key $p k_{A}$ corresponding to the coins $r k_{A}$, by calling the public-key generation algorithm pkgen. Similarly, $G_{0}$ generates the secret key $s k_{A}$ by calling skgen. It then returns the public key $p k_{A}$, so that the adversary has this public key.

After this return the control passes to the adversary. Several oracles are then made available, which represent the roles of $A$ and $B$ in the protocol: the oracle definition $Q_{A} \mid Q_{B}$ is the parallel composition of $Q_{A}$ and $Q_{B}$; it makes simultaneously available the oracles defined in $Q_{A}$ and $Q_{B}$. Let $Q_{A}^{\prime}$ and $Q_{B}^{\prime}$ be such that $Q_{A}=$ foreach $i_{A} \leq n$ do $Q_{A}^{\prime}$ and $Q_{B}=$ foreach $i_{B} \leq n$ do $Q_{B}^{\prime}$. The replication foreach $i_{A} \leq n$ do $Q_{A}^{\prime}$ represents $n$ copies of the oracle definition $Q_{A}^{\prime}$, indexed by the replication index $i_{A}$. The oracle definition $Q_{A}^{\prime}$ begins with oracle $O_{A}\left[i_{A}\right]$; the oracle is indexed with $i_{A}$ so that the adversary can choose which copy of oracle $O_{A}$ it calls by calling $O_{A}\left[i_{A}\right]$ for the appropriate value of $i_{A}$. The situation is similar for $Q_{B}^{\prime}$, which expects a call to oracle $O_{B 1}\left[i_{B}\right]$. The adversary can then run each copy of $Q_{A}^{\prime}$ or $Q_{B}^{\prime}$ simply by calling the appropriate oracles $O_{A}\left[i_{A}\right]$ or $O_{B 1}\left[i_{B}\right]$.

The oracle definition $Q_{B}^{\prime}$ first expects a call to oracle $O_{B 1}\left[i_{B}\right]$ with a message $x_{p k_{A}}$ in the type pkey of public keys. This message is not really part of the protocol. It serves for starting a new session of the protocol, in which $B$ interacts with the participant of public key $x_{p k_{A}}$. For starting a session between $A$ and $B$, this message should be $p k_{A}$. Then, $Q_{B}^{\prime}$ chooses randomly with uniform probability a nonce $N$ in the type nonce. The type nonce is large: collisions between independent random numbers chosen uniformly in a large type are eliminated by CryptoVerif. $Q_{B}^{\prime}$ returns the message $(N, B)$ to the adversary and gives it back control. The attacker is expected to call oracle $O_{A}\left[i_{A}\right]$ with this message $(N, B)$, but may proceed differently in order to mount an attack against the protocol.

Upon a call to oracle $O_{A}\left[i_{A}\right]$ with message $\left(x_{N}, x_{B}\right)$, where the bitstring $x_{N}$ is in the type nonce and $x_{B}$ in the type host, the process $Q_{A}^{\prime}$ executes the event $e_{A}\left(p k_{A}, x_{B}, x_{N}\right)$. This event does not change the state of the system. Events just record that a certain program point has been reached, with certain values of the arguments of the event. Then, $Q_{A}^{\prime}$ chooses randomly with uniform probability a bitstring $r$ in the type seed; this random bitstring is next used as coins for the signature algorithm. Finally, $Q_{A}^{\prime}$ returns the signed message $\left\{p k_{A}, x_{B}, x_{N}\right\}_{s k_{A}}$. (The function concat concatenates its arguments, with information on the length of these arguments, so that the arguments can be recovered from the concatenation.) The control then passes to the attacker, which should call oracle $O_{B 2}\left[i_{B}\right]$ with this message if it wishes to run the protocol correctly.

Upon a call to oracle $O_{B 2}\left[i_{B}\right]$ with message $s, Q_{B}^{\prime}$ verifies that the signature $s$ is correct and, if $x_{p k_{A}}=p k_{A}$, that is, if $B$ runs a session with $A$, it executes the event $e_{B}\left(x_{p k_{A}}, B, N\right)$. Our goal is to prove that, if event $e_{B}$ is executed, then event $e_{A}$ has also been executed. However, when $B$ runs a session with a participant other than $A$, it is perfectly correct that $B$ terminates without event $e_{A}$ being executed; that is why event $e_{B}$ is executed only when $B$ runs a session with $A$.

By the unforgeability of signatures, the signature verification with $p k_{A}$ succeeds only for signatures generated with $s k_{A}$. So, when we verify that the signature is correct, we can furthermore check that it has been generated using $s k_{A}$. So, after game transformations explained below, we obtain the following final game:

$$
\begin{aligned}
G_{1}= & O_{0}():=r k_{A} \stackrel{R}{\leftarrow} \text { keyseed; } \\
& \text { let } p k_{A}=\operatorname{pkgen}^{\prime}\left(r k_{A}\right) \text { in return }\left(p k_{A}\right) ;\left(Q_{1 A} \mid Q_{1 B}\right)
\end{aligned}
$$

$$
\begin{aligned}
Q_{1 A}= & \text { foreach } i_{A} \leq n \text { do } O_{A}\left[i_{A}\right]\left(x_{N}: \text { nonce, } x_{B}: \text { host }\right):= \\
& \text { event } e_{A}\left(p k_{A}, x_{B}, x_{N}\right) ; \\
& \text { let } m=\operatorname{concat}\left(p k_{A}, x_{B}, x_{N}\right) \text { in } \\
& r \stackrel{R}{\leftarrow} \text { seed } ; \text { return }\left(\operatorname{sign}^{\prime}\left(m, \operatorname{skgen}^{\prime}\left(r k_{A}\right), r\right)\right) \\
Q_{1 B}= & \text { foreach } i_{B} \leq n \text { do } O_{B 1}\left[i_{B}\right]\left(x_{p k_{A}}: p k e y\right):=N \stackrel{R}{\leftarrow} \text { nonce; } \\
& \text { return }(N, B) ; O_{B 2}\left[i_{B}\right](s: \text { signature }):= \\
& \text { find } u \leq n \text { suchthat defined }\left(m[u], x_{B}[u], x_{N}[u]\right) \\
& \wedge\left(x_{p k_{A}}=p k_{A}\right) \wedge\left(B=x_{B}[u]\right) \wedge\left(N=x_{N}[u]\right) \\
& \wedge \operatorname{verify}^{\prime}\left(\operatorname{concat}\left(x_{p k_{A}}, B, N\right), x_{p k_{A}}, s\right) \text { then } \\
& \text { event } \left.e_{B}\left(x_{p k_{A}}, B, N\right)\right)
\end{aligned}
$$

The assignment $s k_{A}=\operatorname{skgen}\left(r k_{A}\right)$ has been removed and $\operatorname{skgen}\left(r k_{A}\right)$ has been substituted for $s k_{A}$, in order to make the term $\operatorname{sign}\left(m, \operatorname{skgen}\left(r k_{A}\right), r\right)$ appear. This term is needed for the security of the signature scheme to apply.

In $Q_{1 A}$, the signed message is stored in variable $m$, and this variable is used when computing the signature.

Finally, using the unforgeability of signatures, the signature verification has been replaced with an array lookup: the signature verification can succeed only when concat $\left(x_{p k_{A}}, B, N\right)$ has been signed with $s k_{A}$, so we look for the message concat $\left(x_{p k_{A}}, B, N\right)$ in the array $m$ and the event $e_{B}$ is executed only when this message is found. In other words, we look for an index $u \leq n$ such that $m[u]$ is defined and $m[u]=\operatorname{concat}\left(x_{p k_{A}}, B, N\right)$. By definition of $m$, $m[u]=\operatorname{concat}\left(p k_{A}, x_{B}[u], x_{N}[u]\right)$, so the equality $m[u]=\operatorname{concat}\left(x_{p k_{A}}, B, N\right)$ can be replaced with $\left(x_{p k_{A}}=p k_{A}\right) \wedge\left(B=x_{B}[u]\right) \wedge\left(N=x_{N}[u]\right)$. (Recall that the result of the concat function contains enough information to recover its arguments.) This transformation replaces the function symbols pkgen, skgen, sign, and verify with primed function symbols pkgen' ${ }^{\prime}$, skgen ${ }^{\prime}$, sign ${ }^{\prime}$, and verify' respectively, to avoid repeated applications of the unforgeability of signatures with the same key. (The unforgeability of signatures is applied only to unprimed symbols.)

The soundness of the game transformations shows that $G_{0} \approx G_{1}$. We will prove that $G_{1}$ satisfies the correspondences (4) and (6) with any public variables $V$, in particular with $V=\emptyset$. By Lemma 27, $G_{0}$ also satisfies these correspondences with public variables $V=\emptyset$. Let us sketch how the proof of correspondence (4) for the game $G_{1}$ will proceed. Let $Q_{1 A}^{\prime}$ and $Q_{1 B}^{\prime}$ such that $Q_{1 A}=$ foreach $i_{A} \leq n$ do $Q_{1 A}^{\prime}$ and $Q_{1 B}=$ foreach $i_{B} \leq n$ do $Q_{1 B}^{\prime}$. Assume that event $e_{B}$ is executed in the copy of $Q_{1 B}^{\prime}$ of index $i_{B}$, that is, $e_{B}\left(x_{p k_{A}}\left[i_{B}\right], B, N\left[i_{B}\right]\right)$ is executed. (Recall that the variables $x_{p k_{A}}, N, u, \ldots$ are implicitly arrays.) Then the condition of the find above $e_{B}$ holds, that is, $m\left[u\left[i_{B}\right]\right], x_{B}\left[u\left[i_{B}\right]\right]$, and $x_{N}\left[u\left[i_{B}\right]\right]$ are defined, $x_{p k_{A}}\left[i_{B}\right]=p k_{A}, B=x_{B}\left[u\left[i_{B}\right]\right]$, and $N\left[i_{B}\right]=x_{N}\left[u\left[i_{B}\right]\right]$. Moreover, since $m\left[u\left[i_{B}\right]\right]$ is defined, the assignment that defines $m$ has been executed in the copy of $Q_{1 A}^{\prime}$ of index $i_{A}=u\left[i_{B}\right]$. Then the event $e_{A}\left(p k_{A}, x_{B}, x_{N}\right)$, located above the definition of $m$, must have been executed in that copy of $Q_{1 A}^{\prime}$, that is, $e_{A}\left(p k_{A}, x_{B}\left[u\left[i_{B}\right]\right]\right.$, $\left.x_{N}\left[u\left[i_{B}\right]\right]\right)$ has been executed. The equalities in the condition of the find imply that this event is also $e_{A}\left(x_{p k_{A}}\left[i_{B}\right], B, N\left[i_{B}\right]\right)$. To sum up, if $e_{B}\left(x_{p k_{A}}\left[i_{B}\right], B, N\left[i_{B}\right]\right)$ has been executed, then $e_{A}\left(x_{p k_{A}}\left[i_{B}\right], B, N\left[i_{B}\right]\right)$ has been executed, so we have the correspondence (4). This reasoning is typical of the way the prover shows correspondences. In particular, the conditions of array lookups are key in these proofs, because they allow us to relate values in processes that run in parallel (here, the processes that represent $A$ and $B$ ), and interesting correspondences relate events that occur in such processes. Next, we detail and formalize this reasoning, both for non-injective and injective correspondences.

### 4.2.2 Non-unique Events

The only correspondence that involves a non-unique event $e$ is event $(e) \Rightarrow$ false, and it is simply proved by noticing that the event $e$ no longer occurs in the game after the transformation prove_unique (Section 5.1.4). Therefore, non-unique events are not concerned by the proofs of Sections 4.2.3 and 4.2.4.

### 4.2.3 Non-injective Correspondences

Intuitively, in order to prove that $Q_{0}$ satisfies a non-injective correspondence $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}$ : $\widetilde{T^{\prime}} ; \phi$, with $\widetilde{x}=\operatorname{var}(\psi)$ and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$, we collect all facts that hold at events in $\psi$ and show that these facts imply $\phi$ using the equational prover.

When casesInCorresp $=$ false, CryptoVerif uses $\mathcal{F}_{\mu}$ to collect these facts. When casesInCorresp $=$ true (the default), it uses $\mathcal{F}_{\mu, c}$ for more precision. In this section, we detail the proof with $\mathcal{F}_{\mu, c}$. The usage of $\mathcal{F}_{\mu}$ can be considered as using a single case $c$, relying on Lemma 31 instead of Lemma 32. Formally, we collect facts that hold when the event $F$ in $\psi$ has been executed, as follows.

Definition 16 ( $\mu$ executes $F, \mathcal{F}_{F, \mu, c}$ ) When $F=\operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right)$ and ${ }^{\mu}$ event $e\left(M_{1}^{\prime}\right.$, $\left.\ldots, M_{m}^{\prime}\right) ; \ldots$ occurs in $Q_{0}$ or, for $m=0,{ }^{\mu}$ event_abort $e$ or ${ }^{\mu}$ find [unique $\left.{ }_{e}\right] \ldots$ occurs in $Q_{0}$, we say that $\mu$ executes $F$.

If $\mu$ executes $F$ and for all ${ }^{\mu}$ event $e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right) ; \ldots$ in $Q_{0}, M_{1}^{\prime}, \ldots, M_{m}^{\prime}$ are simple terms, then we define $\mathcal{F}_{F, \mu, c}^{0}=\mathcal{F}_{\mu, c} \cup\left\{M_{j}^{\prime}=M_{j} \mid j \leq m\right\} \cup\left\{\right.$ lastdefprogrampoint $\left(\mu, I_{\mu}\right)$ if ${ }^{\mu}$ event_abort $e$ or ${ }^{\mu}$ find $\left[\right.$ unique $\left.{ }_{e}\right] \ldots$ occurs in $\left.Q_{0}\right\}$. If additionally $F$ is not a non-unique event, then we define $\mathcal{F}_{F, \mu, c}=\mathcal{F}_{F, \mu, c}^{0} \cup \mathcal{F}_{\mu}^{\text {Fut }}$.

Intuitively, when the event $F$ in $\psi$ has been executed, it has been executed by some subterm or subprocess of $Q_{0}$, so there exists a subterm or subprocess ${ }^{\mu}$ event $e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right) ; \ldots$ or, for $m=0,{ }^{\mu}$ event_abort $e$ or ${ }^{\mu}$ find $\left[\right.$ unique $\left._{e}\right] \ldots$ in $Q_{0}$ such that, the event $e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right)$ has been executed and it is equal to the event $F$, hence $M_{j}^{\prime}=M_{j}$ holds for $j \leq m$. Moreover, since the program point $\mu$, which executes $F$, has been reached, $\mathcal{F}_{\mu, c}$ holds for some case $c$ (Lemma 32). Furthermore, when the event aborts, it is the last step of the trace, so lastdefprogrampoint ( $\mu, I_{\mu}$ ) also holds. Hence $\mathcal{F}_{F, \mu, c}^{0}$ holds for some case $c$. Additionally, assuming we consider traces that do not execute non-unique events, since the adversary cannot stop execution of the process until the next return, yield, or event_abort $e, \mathcal{F}_{\mu}^{\text {Fut }}$ also holds (Lemma 33 , so $\mathcal{F}_{F, \mu, c}$ holds for some case c. This is proved more formally in Lemma 38 below. (The case of get[unique ${ }_{e}$ ] is not mentioned in Definition 16 because it is excluded by Property 3.)

We restrict ourselves to the case in which $M_{1}^{\prime}, \ldots, M_{m}^{\prime}$ are simple terms because only simple terms allowed in sets of facts.

Let $\theta$ be a substitution equal to the identity on the variables $\widetilde{x}$ of $\psi$. This substitution gives values to existentially quantified variables $\widetilde{y}$ of $\phi$. We say that $\mathcal{F} \Leftrightarrow_{\theta} \phi$ when we can show that $\mathcal{F}$ implies $\theta \phi$. Formally, we define:
$\mathcal{F} \mapsto_{\theta} M$ if and only if $\mathcal{F} \cup\{\neg \theta M\}$ yields a contradiction
$\mathcal{F} \not \mapsto_{\theta}$ event $\left(e\left(M_{1}, \ldots, M_{m}\right)\right)$ if and only if there exist
$M_{0}^{\prime}, \ldots, M_{m}^{\prime}$ such that $M_{0}^{\prime}: \operatorname{event}\left(e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right)\right) \in \mathcal{F}$
and $\mathcal{F} \cup\left\{\bigvee_{j=1}^{m} \theta M_{j} \neq M_{j}^{\prime}\right\}$ yields a contradiction
$\mathcal{F} \models_{\theta} \phi_{1} \wedge \phi_{2}$ if and only if $\mathcal{F} \models_{\theta} \phi_{1}$ and $\mathcal{F} \models_{\theta} \phi_{2}$
$\mathcal{F} \models_{\theta} \phi_{1} \vee \phi_{2}$ if and only if $\mathcal{F} \models_{\theta} \phi_{1}$ or $\mathcal{F} \models_{\theta} \phi_{2}$

Terms $\theta M$ are proved by contradiction, using the equational prover. Events $\theta F$ are proved by looking for some event $F^{\prime}$ in $\mathcal{F}$ and showing by contradiction that $\theta F=F^{\prime}$, using the equational prover.

Let $\varphi=\llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi \rrbracket$ be a non-injective correspondence that does not use nonunique events, with $\psi=F_{1} \wedge \ldots \wedge F_{m}, \widetilde{x}=\operatorname{var}(\psi)$, and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$. Suppose that, in $Q_{0}$, the arguments of the events that occur in $\psi$ are always simple terms. Suppose that, for all $j \leq m, \mu_{j}$ that executes $F_{j}$ and $c_{j}$ is a case for $\mathcal{F}_{\mu_{j}, c_{j}}$. For $j \leq m$, let $\theta_{j}$ be a renaming of $I_{\mu_{j}}$ to fresh replication indices. (The renamings $\theta_{j}$ have pairwise disjoint images.) Let $\theta$ be a family parameterized by $\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}$ of substitutions equal to the identity on $\widetilde{x}$. We define $\operatorname{prove}^{\varphi}\left(\theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)=\left(\theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}} \eta_{\theta\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)} \phi\right)$. This function defines the algorithm that we use to prove the correspondence $\varphi$ assuming for all $j \leq m, F_{j}$ is executed in $\mu_{j}$ and we are in case $c_{j}$. We also define $\operatorname{prove}^{\varphi}(\theta, \mathcal{S})=\bigwedge_{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \in \mathcal{S}} \operatorname{prove}^{\varphi}(\theta$, $\left.\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)$.

Non-injective correspondences are proved as follows.
Proposition 2 Let $\varphi=\llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi \rrbracket$ be a non-injective correspondence that does not use non-unique events, with $\psi=F_{1} \wedge \ldots \wedge F_{m}, \widetilde{x}=\operatorname{var}(\psi)$, and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$. Let $Q_{0}$ be a process that satisfies Properties 3 and 4. Suppose that, in $Q_{0}$, the arguments of the events that occur in $\psi$ are always simple terms. Let $\mathcal{S}=\left\{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \mid \forall j \leq m, \mu_{j}\right.$ executes $F_{j}$ and $c_{j}$ is a case for $\left.\mathcal{F}_{\mu_{j}, c_{j}}\right\}$. If there exists a family of substitutions $\theta$ equal to the identity on $\widetilde{x}$ such that prove $^{\varphi}(\theta, \mathcal{S})$ and for all $\mathcal{A} \in \mathcal{B B}$ and all evaluation contexts $C$ acceptable for $Q_{0}$, $\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right] \preceq \neg\left\{\left[\operatorname{prove}^{\varphi}(\theta, \mathcal{S})\right]\right\}\right] \leq p(\mathcal{A}, C)$, then $\operatorname{Bound}_{Q_{0}}\left(V, \varphi, D_{\text {false }}, p\right)$ for any $V$.

Intuitively, when $\psi=F_{1} \wedge \ldots \wedge F_{m}$ holds, $\theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}}$ hold for some $\mu_{1}$, $c_{1}, \ldots, \mu_{m}, c_{m}$. For some $\theta$ equal to the identity on $\psi, \theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}}$ implies $\theta \phi$, so $\theta \phi$ holds. Hence the correspondence is satisfied. The proof of Proposition 2 relies on the following properties and lemmas. We have

$$
\begin{aligned}
& \left\{\left[\mathcal{F} \Rightarrow_{\theta} M\right]\right\}=\forall \widetilde{z} \in \widetilde{T}^{\prime \prime}, \neg(\bigwedge \mathcal{F} \wedge \neg \theta M) \\
& \left\{\left[\mathcal{F} \models_{\theta} \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right)\right]\right\}=\forall \widetilde{z} \in \widetilde{T}^{\prime \prime}, \neg\left(\bigwedge \mathcal{F} \wedge \bigvee_{j=1}^{m} \theta M_{j} \neq M_{j}^{\prime}\right) \\
& \text { for some } M_{0}^{\prime}: \operatorname{event}\left(e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right)\right) \in \mathcal{F} \\
& \left\{\left[\mathcal{F} \models_{\theta} \phi_{1} \wedge \phi_{2}\right]\right\}=\left\{\left[\mathcal{F} \models_{\theta} \phi_{1}\right]\right\} \wedge\left\{\left[\mathcal{F} \models_{\theta} \phi_{2}\right]\right\} \\
& \left\{\left[\mathcal{F} \models_{\theta} \phi_{1} \vee \phi_{2}\right]\right\}= \begin{cases}\left\{\left[\mathcal{F} \models_{\theta} \phi_{1}\right]\right\} & \text { if } \mathcal{F} \models_{\theta} \phi_{1} \\
\left\{\left[\mathcal{F} \models_{\theta} \phi_{2}\right]\right\} & \text { otherwise }\end{cases}
\end{aligned}
$$

where $\widetilde{z}$ are the non-process variables in $\mathcal{F}$, in the image of $\theta$, and in $\widetilde{x}$, and $\widetilde{T^{\prime \prime}}$ are their types.
Lemma $37\left\{\left[\mathcal{F} \models_{\theta} \phi\right]\right\} \Rightarrow \forall \widetilde{z} \in \widetilde{T}^{\prime \prime}, \neg(\bigwedge \mathcal{F} \wedge \neg \theta \phi)$, where $\widetilde{z}$ are the non-process variables in $\mathcal{F}$, in the image of $\theta$, and in $\widetilde{x}$, and $\widetilde{T}^{\prime \prime}$ are their types.

Proof By induction on $\phi$.
Lemma 38 Let $Q_{0}$ be a process that satisfies Properties 3 and 4 . Let Tr be a full trace of $C\left[Q_{0}\right]$ for some attacker $\mathcal{A} \in \mathcal{B B}$. Let $\mu \mathcal{E} v$ be the sequence of events in the last configuration of Tr . Let $F=\operatorname{event}(e(\widetilde{M}))$ where $\widetilde{M}$ is a tuple of terms and $e$ is an event that does not occur in $C$. Suppose that the arguments of $e$ in $Q_{0}$ are always simple terms. Let $\rho$ be a mapping of the variables of $\widetilde{M}$ and $\tau$ to their values. Suppose that $\operatorname{Tr}, \rho \vdash F @ \tau$.

Then there exist a program point $\mu$ (in $Q_{0}$ ) that executes $F$ and a case $c$ such that, for any $\theta^{\prime}$ renaming of $I_{\mu}$ to fresh replication indices, there exists a mapping $\sigma$ with domain $\theta^{\prime} I_{\mu}$ such that $\mu \mathcal{E} v(\rho(\tau))=\left(\mu, \sigma\left(\theta^{\prime} I_{\mu}\right)\right): e(\ldots)$ and $\operatorname{Tr}, \sigma \cup \rho \vdash \theta^{\prime} \mathcal{F}_{F, \mu, c}^{0}$. If additionally, $\operatorname{Tr}$ does not execute $a$ non-unique event of $Q_{0}$, then $\operatorname{Tr}, \sigma \cup \rho \vdash \theta^{\prime} \mathcal{F}_{F, \mu, c}$.

Proof Let $E=E_{T r}$. Since $T r, \rho \vdash F @ \tau$ and the variables of $\widetilde{M}$ and $\tau$ are defined in $\rho$, there exists $\widetilde{a}$ such that $\rho, \widetilde{M} \Downarrow \widetilde{a}$ and $\mu \mathcal{E} v(\rho(\tau))=\left(\mu, \widetilde{a}_{0}\right): e(\widetilde{a})$ for some $\mu$ and $\widetilde{a}_{0}$. The rule of the semantics that may have added this element to $\mu \mathcal{E} v$ is (Event), (EventAbort), (CtxEvent), (FindE), (Find3), GetE), Get3), or (EventT).

- In case Event, the initial configuration of the rule Event is of the form

$$
E_{1},\left(\sigma_{1},{ }^{\mu} \text { event } e(\widetilde{a}) ; P\right):: \mathcal{S} t_{0}, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}
$$

By Lemma 8, Property 1 applied to this configuration, we have reductions

$$
\begin{aligned}
& \text { Conf }=E_{0},\left(\sigma_{0},{ }^{\mu} \text { event } e\left(\widetilde{M^{\prime}}\right) ; P\right):: \mathcal{S} t_{0}, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \quad{\xrightarrow{p_{0}}}_{t_{0}} \ldots{\xrightarrow{p_{1}}}_{t_{1}} E_{1},\left(\sigma_{1},{ }^{\mu} \text { event } e(\widetilde{a}) ; P\right):: \mathcal{S} t_{0}, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1} \\
& \quad \xrightarrow{1} E_{1},\left(\sigma_{1}, P\right):: \mathcal{S} t_{0}, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{1},\left(\mu \mathcal{E} v_{1},\left(\mu, \operatorname{Im}\left(\sigma_{1}\right)\right): e(\widetilde{a})\right)
\end{aligned}
$$

where ${ }^{\mu}$ event $e\left(\widetilde{M^{\prime}}\right) ; P$ is a subprocess of $C\left[Q_{0}\right]$ up to renaming of oracles, by any number of applications of ( Ctx ) and a final application of (Event).

- In case (EventAbort), Find3), or Get3), the rules that can conclude with a process ${ }^{\mu} P$ with $P=$ event_abort $e, P=$ find[unique $\left.{ }_{e}\right] \ldots$, or $P=\operatorname{get}\left[u_{n i q u e}^{e}\right] \ldots$ are (New), Let), (If1), (If2), (Find1), (Find2), Insert), (Get1), Get2, OracleCall), Return), Yield, (AttIO), AttYield), (Event) and by Corollary 1, their target process is a subprocess of $C\left[Q_{0}\right]$ up to renaming of oracles. So we have a reduction

$$
\begin{aligned}
& \text { Conf }=E_{0},\left(\sigma_{0},{ }^{\mu} P\right):: \mathcal{S} t_{0}, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \quad \xrightarrow{p}_{t} E_{0},\left(\sigma_{0}, \text { abort }\right):: \mathcal{S} t_{0}, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0},\left(\mu \mathcal{E} v_{0},\left(\mu, \operatorname{Im}\left(\sigma_{0}\right)\right): e\right)
\end{aligned}
$$

where ${ }^{\mu} P$ is a subprocess of $C\left[Q_{0}\right]$ up to renaming of oracles, by (EventAbort, (Find3), or Get3.

- In case (EventT), the initial configuration of the rule (EventT) is of the form $E_{1}, \sigma_{1}$, ${ }^{\mu}$ event $e(\widetilde{a}) ; N, \mathcal{T}_{1}, \mu \mathcal{E} v_{1}$. By Lemma 8, Property 4 applied to this configuration with $l=0$, we have reductions

$$
\begin{aligned}
\text { Conf } & =E_{0}, \sigma_{0},{ }^{\mu} \text { event } e\left(\widetilde{M^{\prime}}\right) ; N, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \xrightarrow{p_{0}} t_{0} \ldots \xrightarrow{p_{1}} t_{1} E_{1}, \sigma_{1},{ }^{\mu} \text { event } e(\widetilde{a}) ; N, \mathcal{T}_{1}, \mu \mathcal{E} v_{1} \\
& \xrightarrow{1} E_{1}, \sigma_{1}, N, \mathcal{T}_{1},\left(\mu \mathcal{E} v_{1},\left(\mu, \operatorname{Im}\left(\sigma_{1}\right)\right): e(\widetilde{a})\right)
\end{aligned}
$$

where ${ }^{\mu}$ event $e\left(\widetilde{M^{\prime}}\right) ; N$ is a subterm of $C\left[Q_{0}\right]$, by any number of applications of CtxT and a final application of EventT).

- In case (CtxEvent), the only rule that can conclude with a process $C$ [event_abort ( $\mu, \widetilde{a}_{0}$ ) : $e]$ is Ctx). (The rules (New), Let), (If1), (If2), (Find1), (Find2), Insert), Get1), (Get2), (OracleCall), (Return), (Yield), AttIO),(AttYield), (Event) cannot conclude with
$C\left[\right.$ event_abort $\left.\left(\mu, \widetilde{a}_{0}\right): e\right]$ because, by Corollary 1 their target process is a subprocess of $C\left[Q_{0}\right]$ up to renaming of oracles, and the initial process $C\left[Q_{0}\right]$ does not contain the abort event value event_abort $\left.\left(\mu, \widetilde{a}_{0}\right): e.\right)$ Hence, there is a rule that concludes with a term event_abort $\left(\mu, \widetilde{a}_{0}\right): e$.
In cases FindE) and GetE), there is also a rule that concludes with a term event_abort ( $\mu$, $\left.\widetilde{a}_{0}\right): e$.
The only rules that conclude with a term event abort $\left(\mu, \widetilde{a}_{0}\right): e$ are FindTE, (FindT3), (GetTE), (GetT3), (EventAbortT), and (CtxEventT). (It cannot be (NewT), (LetT), (IfT1), (IfT2), (FindT1), (FindT2), InsertT), (GetT1), GetT2), EventT), (DefinedYes) because, by Corollary 1. their target term is a subterm of $C\left[Q_{0}\right]$, and the initial process $C\left[Q_{0}\right]$ does not contain the abort event value event_abort ( $\mu, \widetilde{a}_{0}$ ) :e.) In cases (FindTE) and GetTE, there is recursively another rule that concludes with event_abort ( $\mu, \widetilde{a}_{0}$ ): $e$. In case (CtxEventT), the only rule that can conclude with $C$ [event_abort $\left.\left(\mu, \widetilde{a}_{0}\right): e\right]$ is $(\mathrm{CtxT})$, so there is recursively another rule that concludes with event_abort $\left(\mu, \widetilde{a}_{0}\right): e$. Therefore, event_abort $\left(\mu, \widetilde{a}_{0}\right): e$ ultimately comes from an application of EventAbortT), FindT3), or GetT3):

$$
\text { Conf }=E_{0}, \sigma_{0},{ }^{\mu} N, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \xrightarrow[\rightarrow]{p}_{t} E_{0}, \sigma_{0}, \text { event_abort }\left(\mu, \operatorname{Im}\left(\sigma_{0}\right)\right): e, \mathcal{T}_{0}, \mu \mathcal{E} v_{0}
$$

where $N=$ event_abort $e, N=$ find $\left[\right.$ unique $\left._{e}\right] \ldots$, or $N=$ get[unique $\left.{ }_{e}\right] \ldots$ Furthermore, the only rules that can conclude with such a term ${ }^{\mu} N$ are (NewT), (IfT1), (IfT2), LLetT), (FindT1), (FindT2), InsertT), GetT1), (GetT2), EventT), (DefinedYes) and, by Corollary 1, their target term is a subterm of $C\left[Q_{0}\right]$.

In all cases, since $e$ does not occur in $C, \mu$ is in fact a program point of $Q_{0}$. Therefore, the process or term at program point $\mu$ in $Q_{0}$ is of the form ${ }^{\mu}$ event $e\left(\widetilde{M^{\prime}}\right) ; \ldots,{ }^{\mu}$ event_abort $e$, ${ }^{\mu}$ find $\left[\right.$ unique $\left._{e}\right] \ldots$, or ${ }^{\mu}$ get $\left[\right.$ unique $\left.{ }_{e}\right] \ldots$. In cases Event and EventT, we have $\sigma_{0}=\sigma_{1}$ by Lemma 3. In all cases, $\operatorname{Dom}\left(\sigma_{0}\right)=I_{\mu}$ are the current replication indices at program point $\mu$ by Lemma 2, and $\operatorname{Im}\left(\sigma_{0}\right)=\widetilde{a}_{0}$, so $\sigma_{0}=\left[I_{\mu} \mapsto \widetilde{a}_{0}\right]$. Moreover, $\widetilde{M^{\prime}}$ are simple terms, so their evaluation can be written $E_{0},\left\{I_{\mu} \mapsto \widetilde{a}_{0}\right\}, \widetilde{M^{\prime}} \Downarrow \widetilde{a}$. Let $\sigma=\left\{\theta^{\prime} I_{\mu} \mapsto \widetilde{a}_{0}\right\}$. We have $\mu \mathcal{E} v(\rho(\tau))=\left(\mu, \sigma\left(\theta^{\prime} I_{\mu}\right)\right): e(\widetilde{a})$.

We have $E_{0}, \sigma_{0}, \widetilde{M^{\prime}} \Downarrow \widetilde{a}$ so $E_{0}, \sigma, \theta^{\prime} \widetilde{M^{\prime}} \Downarrow \widetilde{a}$. The environment $E_{T r}$ extends $E_{0}$, so $E_{T r}, \sigma$, $\theta^{\prime} \widetilde{M^{\prime}} \Downarrow \widetilde{a}$, so $\operatorname{Tr}, \sigma \cup \rho \vdash \theta^{\prime} \widetilde{M^{\prime}}=\widetilde{M}$.

The configuration Conf is at program point $\mu$ in $\operatorname{Tr}$, so by Corollary 3, we have $\operatorname{Tr}, \sigma \vdash \theta^{\prime} \mathcal{F}_{\mu, c}$.
When the process or term at $\mu$ is ${ }^{\mu}$ event_abort $e,{ }^{\mu}$ find $\left.^{\text {[unique }}{ }_{e}\right] \ldots$, or ${ }^{\mu}$ get[unique $\left.{ }_{e}\right] \ldots$, the environment and replication indices in Conf are the same as at the end of the trace, since the execution after Conf applies (EventAbort), (Find3), or (Get3), which terminate the trace keeping the same environment and replication indices as in Conf or (EventAbortT), FindT3), or GetT33 which build an abort event value keeping the same environment and replication indices as in Conf, followed by some rules among (FindTE, (GetTE, (CtxT), CtxEventT, (FindE), (GetE), Ctx, and CtxEvent, which preserve the environment and replication indices that come with the abort event value. So $\operatorname{Tr}, \sigma \vdash$ lastdefprogrampoint $\left(\mu, \theta^{\prime} I_{\mu}\right)$.

Therefore, $\mu$ executes $F$ and $\operatorname{Tr}, \sigma \cup \rho \vdash \theta^{\prime} \mathcal{F}_{F, \mu, c}^{0}$ for some $c$.
Suppose additionally that $\operatorname{Tr}$ does not execute any non-unique event of $Q_{0}$. Let $\operatorname{Tr}^{\prime \prime}$ be the prefix of $\operatorname{Tr}$ that stops at the first evaluated return return (b); $Q$ or yield that follows Conf, or $T r^{\prime \prime}=\operatorname{Tr}$ if $\operatorname{Tr}$ contains no return nor yield after Conf. By Lemma 33, we have $T r^{\prime \prime} \vdash \mathcal{F}_{\mu}^{\text {Fut }}$, so $T r^{\prime \prime}, \sigma \vdash \theta^{\prime} \mathcal{F}_{\mu}^{\text {Fut }}$. Moreover, $E$ extends $E_{T r^{\prime \prime}}$ and by Lemma $3, \mu \mathcal{E} v_{T r}$ extends $\mu \mathcal{E} v_{T r^{\prime \prime}}$, so $\operatorname{Tr}, \sigma \vdash \theta^{\prime} \mathcal{F}_{\mu}^{\text {Fut }}$. Therefore, $\operatorname{Tr}, \sigma \cup \rho \vdash \theta^{\prime} \mathcal{F}_{F, \mu, c}$ for some $c$.

Lemma 39 Let $\varphi=\llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi \rrbracket$ be a non-injective correspondence that does not use non-unique events, with $\psi=F_{1} \wedge \ldots \wedge F_{m}, \widetilde{x}=\operatorname{var}(\psi)$, and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$. Let $Q_{0}$ be a process that satisfies Properties 3 and 4 . Suppose that, in $Q_{0}$, the arguments of the events that occur in $\psi$ are always simple terms.

Let $\mathcal{S}=\left\{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \mid \forall j \leq m, \mu_{j}\right.$ executes $F_{j}$ and $c_{j}$ is a case for $\left.\mathcal{F}_{\mu_{j}, c_{j}}\right\}$. Let $C$ be an evaluation context acceptable for $Q_{0}$ with public variables $V$ that does not contain events used by $\varphi$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Let $\operatorname{Tr}$ be a full trace of $C\left[Q_{0}\right]$ for $\mathcal{A}$ that does not execute any non-unique event of $Q_{0}$. If $\operatorname{Tr} \vdash \neg \varphi$, then for any $\theta$ family of substitutions equal to the identity on $\widetilde{x}, \operatorname{Tr} \vdash \neg\left\{\left[\operatorname{prove}^{\varphi}(\theta, \mathcal{S})\right]\right\}$.

Proof Since $\operatorname{Tr} \vdash \neg \varphi$, we have $\operatorname{Tr} \vdash \exists \widetilde{x} \in \widetilde{T}, F_{1} \wedge \cdots \wedge F_{m} \wedge \forall \widetilde{y} \in \widetilde{T^{\prime}}, \neg \phi$. So there exists $\rho$ that maps $\widetilde{x}$ to elements of $\widetilde{T}$ such that $T r, \rho \vdash F_{1} \wedge \cdots \wedge F_{m} \wedge \forall \widetilde{y} \in \widetilde{T^{\prime}}, \neg \phi$. By Lemma 38, for all $j \leq m$, there exists a program point $\mu_{j}\left(\right.$ in $\left.Q_{0}\right)$ that executes $F_{j}$ and a case $c_{j}$ such that, for any $\theta_{j}$ renaming of $I_{\mu_{j}}$ to fresh replication indices, there exists a mapping $\sigma_{j}$ with domain $\theta_{j} I_{\mu_{j}}$ such that $\operatorname{Tr}, \sigma_{j} \cup \rho \vdash \theta_{j} \mathcal{F}_{F_{j}, \mu_{j}, c_{j}}$. Since $\operatorname{Tr}, \rho \vdash \forall \widetilde{y} \in \widetilde{T^{\prime}}, \neg \phi$, we have $\operatorname{Tr}, \rho \vdash \neg \theta\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \phi$. Therefore, $\operatorname{Tr}, \sigma_{1} \cup \cdots \cup \sigma_{m} \cup \rho \vdash \theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}} \cup\left\{\neg \theta\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \phi\right\}$, so $\operatorname{Tr} \vdash \exists \theta_{1} I_{\mu_{1}}, \ldots, \exists \theta_{m} I_{\mu_{m}}, \exists \widetilde{x} \in \widetilde{T}, \bigwedge \mathcal{F}_{0}\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \wedge \neg \theta\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \phi$ where $\mathcal{F}_{0}\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)=\theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}}$. We have

$$
\begin{aligned}
& \left\{\left[\operatorname{prove}^{\varphi}\left(\theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)\right]\right\} \\
& \quad \Rightarrow \forall \theta_{1} I_{\mu_{1}}, \ldots, \forall \theta_{m} I_{\mu_{m}}, \forall \widetilde{x} \in \widetilde{T}, \neg\left(\bigwedge \mathcal{F}_{0}\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \wedge \neg \theta\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \phi\right)
\end{aligned}
$$

by Lemma 37. (The non-process variables in $\mathcal{F}_{0}\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)$, in the image of $\theta\left(\mu_{1}, c_{1}, \ldots\right.$, $\left.\mu_{m}, c_{m}\right)$, and in $\widetilde{x}$ are in $\theta_{1} I_{\mu_{1}}, \ldots, \theta_{m} I_{\mu_{m}}, \widetilde{x}$.) So $\operatorname{Tr} \vdash \neg\left\{\left[\operatorname{prove}^{\varphi}\left(\theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)\right]\right\}$, so $\operatorname{Tr} \vdash \neg\left\{\left[\operatorname{prove}^{\varphi}(\theta, \mathcal{S})\right]\right\}$.

Proof of Proposition 2 Let $C$ be an evaluation context acceptable for $Q_{0}$ with public variables $V$ that does not contain events used by $\varphi$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. We have

$$
\begin{array}{rlr}
\operatorname{Adv}_{Q_{0}}\left(\mathcal{A}, C, \varphi, D_{\text {false }}\right) & =\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg \varphi \wedge \neg \text { NonUnique }_{Q_{0}}\right] & \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg\left\{\left[\operatorname{prove}^{\varphi}(\theta, \mathcal{S})\right]\right\}\right] & \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0} \preceq \neg\left\{\left[\operatorname{prove}^{\varphi}(\theta, \mathcal{S})\right]\right\}\right]\right. & \text { by Lemma } 39 \\
& \leq p(\mathcal{A}, C) &
\end{array}
$$

So Bound $Q_{0}\left(V, \varphi, D_{\text {false }}, p\right)$.
Example 6 Let us prove that the example $G_{1}$ satisfies (4). We first study the facts $\mathcal{F}_{\mu_{B}}$ that hold at the program point $\mu_{B}$ that executes event $e_{B} . \mathcal{F}_{\mu_{B}}$ contains defined $\left(m\left[u\left[i_{B}\right]\right]\right)$, defined $\left(x_{B}\left[u\left[i_{B}\right]\right]\right)$, defined $\left(x_{N}\left[u\left[i_{B}\right]\right]\right), x_{p k_{A}}\left[i_{B}\right]=p k_{A}, B=x_{B}\left[u\left[i_{B}\right]\right]$, and $N\left[i_{B}\right]=x_{N}\left[u\left[i_{B}\right]\right]$, because the condition of find holds at $\mu_{B}$. Moreover, we have defined $\left(m\left[u\left[i_{B}\right]\right]\right) \in \mathcal{F}_{\mu_{B}}$, and, when $m\left[i_{A}\right]$ is defined, $\left(\mu_{A}, i_{A}\right)$ : event $\left(e_{A}\left(p k_{A}, x_{B}\left[i_{A}\right], x_{N}\left[i_{A}\right]\right)\right)$ holds, so $\left(\mu_{A}, i_{A}\right)$ : event $\left(e_{A}\left(p k_{A}\right.\right.$, $\left.\left.x_{B}\left[i_{A}\right], x_{N}\left[i_{A}\right]\right)\right)\left\{u\left[i_{B}\right] / i_{A}\right\} \in \mathcal{F}_{\mu_{B}}$, that is, $\left(\mu_{A}, u\left[i_{B}\right]\right)$ : event $\left(e_{A}\left(p k_{A}, x_{B}\left[u\left[i_{B}\right]\right], x_{N}\left[u\left[i_{B}\right]\right]\right)\right) \in$ $\mathcal{F}_{\mu_{B}}$. In other words, since $m$ is defined at index $u\left[i_{B}\right]$, event $e_{A}$ has been executed in the copy of $Q_{1 A}^{\prime}$ of index $u\left[i_{B}\right] .\left(\mathcal{F}_{\mu_{B}}\right.$ also contains other facts, which are useless for proving the desired correspondences, so we do not list them.)

For $\psi=F=\operatorname{event}\left(e_{B}(x, y, z)\right), \mu_{B}$ is the only program point that executes $F$, so this event has been executed in some copy of $Q_{1 B}^{\prime}$ of index $i_{B}^{\prime}$, with $x_{p k_{A}}\left[i_{B}^{\prime}\right]=x, B=y, N\left[i_{B}^{\prime}\right]=z$. Then, when $\psi$ holds, the facts $\theta^{\prime} \mathcal{F}_{F, \mu_{B}} \supseteq \theta^{\prime} \mathcal{F}_{\mu_{B}} \cup\left\{x_{p k_{A}}\left[i_{B}^{\prime}\right]=x, B=y, N\left[i_{B}^{\prime}\right]=z\right\}$ hold for some value of $i_{B}^{\prime}$, with $\theta^{\prime}=\left\{i_{B}^{\prime} / i_{B}\right\}$. (We consider a single case $c$ here, so we can simply omit the case $c$.)

Furthermore, the substitution $\theta\left(\mu_{B}\right)$ is the identity since all variables of $\phi$ also occur in $\psi$. Then we just have to show that $\theta^{\prime} \mathcal{F}_{F, \mu_{B}}$ implies $\phi=\operatorname{event}\left(e_{A}(x, y, z)\right)$, that is, $\theta^{\prime} \mathcal{F}_{F, \mu_{B}} \Rightarrow_{\theta\left(\mu_{B}\right)}$ $\operatorname{event}\left(e_{A}(x, y, z)\right)$. Since $\left(\mu_{A}, u\left[i_{B}\right]\right): \operatorname{event}\left(e_{A}\left(p k_{A}, x_{B}\left[u\left[i_{B}\right]\right], x_{N}\left[u\left[i_{B}\right]\right]\right)\right) \in \mathcal{F}_{\mu_{B}}$, we have $\left(\mu_{A}\right.$, $\left.u\left[i_{B}^{\prime}\right]\right): \operatorname{event}\left(e_{A}\left(p k_{A}, x_{B}\left[u\left[i_{B}^{\prime}\right]\right], x_{N}\left[u\left[i_{B}^{\prime}\right]\right]\right)\right) \in \theta^{\prime} \mathcal{F}_{F, \mu_{B}}$, so the equational prover just has to prove by contradiction that $e_{A}\left(p k_{A}, x_{B}\left[u\left[i_{B}^{\prime}\right]\right], x_{N}\left[u\left[i_{B}^{\prime}\right]\right]\right)=e_{A}(x, y, z)$, that is, $p k_{A}=x, x_{B}\left[u\left[i_{B}^{\prime}\right]\right]=y$, and $x_{N}\left[u\left[i_{B}^{\prime}\right]\right]=z$. The proof succeeds using the following equalities of $\theta^{\prime} \mathcal{F}_{F, \mu_{B}}: x_{p k_{A}}\left[i_{B}^{\prime}\right]=x$, $B=y, N\left[i_{B}^{\prime}\right]=z, x_{p k_{A}}\left[i_{B}^{\prime}\right]=p k_{A}, B=x_{B}\left[u\left[i_{B}^{\prime}\right]\right]$, and $N\left[i_{B}^{\prime}\right]=x_{N}\left[u\left[i_{B}^{\prime}\right]\right]$.

Hence, $G_{1}$ satisfies (4) with any public variables $V$ : if $\psi=\operatorname{event}\left(e_{B}(x, y, z)\right)$ has been executed, then $\phi=\operatorname{event}\left(e_{A}(x, y, z)\right)$ has been executed.

In the implementation, the substitution $\theta$ is initially defined as the identity on $\widetilde{x}=\operatorname{var}(\psi)$. It is defined on other variables when checking $\mathcal{F} \Rightarrow_{\theta} M$ by trying to find $\theta$ such that $\theta M \in \mathcal{F}$, and when checking $\mathcal{F} \models_{\theta}$ event $\left(e\left(M_{1}, \ldots, M_{m}\right)\right)$ by trying to find $\theta$ such that $\theta$ event $\left(e\left(M_{1}, \ldots\right.\right.$, $\left.\left.M_{m}\right)\right) \in \mathcal{F}$. When we do not manage to find the image by $\theta$ of all variables of $M$, resp. $M_{1}, \ldots, M_{m}$, the check fails. When there are several suitable facts $\theta M \in \mathcal{F}$ or $\theta$ event $\left(e\left(M_{1}, \ldots\right.\right.$, $\left.\left.M_{m}\right)\right) \in \mathcal{F}$, the system tries all possibilities.

### 4.2.4 Injective Correspondences

Injective correspondences are more difficult to check than non-injective ones, because they require distinguishing between several executions of the same event. We achieve that by relying on the pair (program points, replication indices) that is recorded in the sequence $\mu \mathcal{E} v$ together with each event: distinct executions of events either occur at different program points or have different values of replication indices.

We extend Definition 16 to injective events, with exactly the same definition as for noninjective events.

The proof of injective correspondences extends that for non-injective correspondences: for a correspondence $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$, we additionally prove that distinct executions of the injective events of $\psi$ correspond to distinct executions of each injective event of $\phi$, that is, if the injective events of $\psi$ have different pairs (program point, replication indices), then each injective event of $\phi$ has a different pair (program point, replication indices). In order to achieve this proof, we collect the following information for each injective event of $\phi$ :

- the set of facts $\mathcal{F}$ that are known to hold, which will be used to reason on replication indices of events;
- the program point and replication indices of the considered injective event of $\phi$, stored in a pair $M_{0}$; these program point and indices are computed when we prove that this event is executed;
- the program point and replication indices of the injective events of $\psi$, stored as a mapping $\mathcal{I}=\left\{j \mapsto\left(\mu_{j}, \theta_{j} I_{\mu_{j}}\right) \mid F_{j}\right.$ is an injective event $\}$, where $\psi=F_{1} \wedge \ldots \wedge F_{m}, \mu_{j}$ is the program point that executes $F_{j}$, and $\theta_{j}$ is a renaming of $I_{\mu_{j}}$ to fresh replication indices, for $j \leq m$;
- the set $\mathcal{V}$ containing the replication indices in $\mathcal{F}$ and the variables $\widetilde{x}$ of $\psi$; these variables will be renamed to fresh variables in order to avoid conflicts of variable names between different events.

This information is stored in a set $\mathcal{S}$, which contains quadruples $\left(\mathcal{F}, M_{0}, \mathcal{I}, \mathcal{V}\right)$. We will show that, if the pair (program point, replication indices) of two executions of the injective events of $\psi$ are different, then the pair (program, replication indices) of the corresponding executions of
the considered injective event of $\phi$ are also different. The equality between pairs (program point, replication indices) is obviously defined as the equality between program points and between replication indices. Formally, we consider $\left(\mathcal{F}, M_{0}, \mathcal{I}, \mathcal{V}\right)$ and $\left(\mathcal{F}^{\prime}, M_{0}^{\prime}, \mathcal{I}^{\prime}, \mathcal{V}^{\prime}\right)$ in $\mathcal{S}$. We rename the variables $\mathcal{V}^{\prime}$ of the second element to fresh variables by a substitution $\theta^{\prime \prime}$ and show that, if $\mathcal{I} \neq \theta^{\prime \prime} \mathcal{I}^{\prime}$, then $M_{0} \neq \theta^{\prime \prime} M_{0}^{\prime}$ (knowing $\mathcal{F}$ and $\theta^{\prime \prime} \mathcal{F}^{\prime}$ ). This property implies injectivity.

Since this reasoning is done for each injective event in $\phi$, we collect the associated sets $\mathcal{S}$ in a pseudo-formula $\mathcal{C}$, obtained by replacing each injective event of $\phi$ with a set $\mathcal{S}$ and all other leaves of $\phi$ with $\perp$.

We say that $\vdash \mathcal{C}$ when for all non-bottom leaves $\mathcal{S}$ of $\mathcal{C}$, for all $\left(\mathcal{F}, M_{0}, \mathcal{I}, \mathcal{V}\right),\left(\mathcal{F}^{\prime}, M_{0}^{\prime}, \mathcal{I}^{\prime}, \mathcal{V}^{\prime}\right)$ in $\mathcal{S}, \mathcal{F} \cup \theta^{\prime \prime} \mathcal{F}^{\prime} \cup\left\{\bigvee_{j \in \operatorname{Dom}(\mathcal{I})} \mathcal{I}(j) \neq \theta^{\prime \prime} \mathcal{I}^{\prime}(j), M_{0}=\theta^{\prime \prime} M_{0}^{\prime}\right\}$ yields a contradiction, where the substitution $\theta^{\prime \prime}$ is a renaming of variables in $\mathcal{V}^{\prime}$ to distinct fresh variables. As explained above, the condition $\vdash \mathcal{C}$ guarantees injectivity.

We extend the definition of $\mathcal{F} \models_{\theta} \phi$ used for non-injective correspondences to $\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi$, which means that $\mathcal{F}$ implies $\theta \phi$ and $\mathcal{C}$ correctly collects the tuples $\left(\mathcal{F}, M_{0}, \mathcal{I}, \mathcal{V}\right)$ associated to this proof. Formally, we define:
$\mathcal{F} \not \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \perp} M$ if and only if $\mathcal{F} \cup\{\neg \theta M\}$ yields a contradiction
$\mathcal{F} \not \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \perp} \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right)$ if and only if
there exist $M_{0}^{\prime}, \ldots, M_{m}^{\prime}$ such that $M_{0}^{\prime}: \operatorname{event}\left(e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right)\right) \in \mathcal{F}$ and
$\mathcal{F} \cup\left\{\bigvee_{j=1}^{m} \theta M_{j} \neq M_{j}^{\prime}\right\}$ yields a contradiction
$\mathcal{F} \not \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{S}}$ inj-event $\left(e\left(M_{1}, \ldots, M_{m}\right)\right)$ if and only if
there exist $M_{0}^{\prime}, \ldots, M_{m}^{\prime}$ such that $M_{0}^{\prime}: \operatorname{event}\left(e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right)\right) \in \mathcal{F}$,
$\mathcal{F} \cup\left\{\bigvee_{j=1}^{m} \theta M_{j} \neq M_{j}^{\prime}\right\}$ yields a contradiction, and $\left(\mathcal{F}, M_{0}^{\prime}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S}$.
$\mathcal{F} \models_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1} \wedge \mathcal{C}_{2}} \phi_{1} \wedge \phi_{2}$ if and only if $\mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1}} \phi_{1}$ and $\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{2}} \phi_{2}$
$\mathcal{F} \not \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1} \vee \mathcal{C}_{2}} \phi_{1} \vee \phi_{2}$ if and only if $\mathcal{F} \not \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1}} \phi_{1}$ or $\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{2}} \phi_{2}$
These formulas differ from the non-injective case in that we propagate $\mathcal{I}, \mathcal{V}, \mathcal{C}$ and, in the case of injective events, we make sure that quadruples $\left(\mathcal{F}, M_{0}^{\prime}, \mathcal{I}, \mathcal{V}\right)$ are collected correctly by requiring that $\left(\mathcal{F}, M_{0}^{\prime}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S}$.

Let $\varphi=\llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi \rrbracket$ be a correspondence that does not use non-unique events, with $\psi=F_{1} \wedge \ldots \wedge F_{m}, \widetilde{x}=\operatorname{var}(\psi)$, and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$. Suppose that, in $Q_{0}$, the arguments of the events that occur in $\psi$ are always simple terms. Suppose that, for all $j \leq m$, $\mu_{j}$ executes $F_{j}$ and $c_{j}$ is a case for $\mathcal{F}_{\mu_{j}, c_{j}}$. For $j \leq m$, let $\theta_{j}$ be a renaming of $I_{\mu_{j}}$ to fresh replication indices. (The renamings $\theta_{j}$ have pairwise disjoint images.) Let $\mathcal{C}$ be a pseudo formula and $\theta$ be a family parameterized by $\mu_{1}, c_{1}, \ldots, c_{m}, \mu_{m}$ of substitutions equal to the identity on $\widetilde{x}$. We define $\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)=\left(\mathcal{F} \models_{\theta\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)}^{\mathcal{I}, \mathcal{C}, \mathcal{L}} \phi\right)$ where $\mathcal{F}=\theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup$ $\cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}}, \mathcal{I}=\left\{j \mapsto\left(\mu_{j}, \theta_{j} I_{\mu_{j}}\right) \mid F_{j}\right.$ is an injective event $\}$, and $\mathcal{V}=\operatorname{var}\left(\theta_{1} I_{\mu_{1}}\right) \cup$ $\cdots \cup \operatorname{var}\left(\theta_{m} I_{\mu_{m}}\right) \cup\{\widetilde{x}\}$. The algorithm $\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, \ldots, \mu_{m}\right)$ shows that the non-injective version of the correspondence $\varphi$ holds assuming the events in $\psi=F_{1} \wedge \ldots \wedge F_{m}$ are executed at program points $\mu_{1}, \ldots, \mu_{m}$ respectively. Indeed, in this case, the facts $\mathcal{F}=\theta_{1} \mathcal{F}_{F_{1}, \mu_{1}} \cup \cdots \cup$ $\theta_{m} \mathcal{F}_{F_{m}, \mu_{m}}$ hold and the formula $\mathcal{F} \not{ }_{\theta\left(\mu_{1}, \ldots, \mu_{m}\right)}^{\mathcal{I}, \mathcal{C}, \mathcal{C}}, \phi$ shows that this implies $\theta\left(\mu_{1}, \ldots, \mu_{m}\right) \phi$. (The substitution $\theta\left(\mu_{1}, \ldots, \mu_{m}\right) \phi$ determines the values of $\widetilde{y}$.) Additionally, prove $^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, \ldots, \mu_{m}\right)$ makes sure that $\mathcal{C}$ correctly collects the information needed to prove injectivity. We also define prove ${ }^{\varphi}(\mathcal{C}, \theta, \mathcal{S})=(\vdash \mathcal{C}) \wedge \bigwedge_{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \in \mathcal{S}} \operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)$. This algorithm proves the correspondence $\varphi$ assuming the events in $\psi$ are executed at program points in $\mathcal{S}$. It verifies injectivity via $\vdash \mathcal{C}$.

The following proposition shows the soundness of the proof of injective correspondences based on this algorithm.

Proposition 3 Let $\varphi=\llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi \rrbracket$ be a correspondence that does not use nonunique events, with $\psi=F_{1} \wedge \ldots \wedge F_{m}, \widetilde{x}=\operatorname{var}(\psi)$, and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$. Let $Q_{0}$ be a process that satisfies Properties 3 and 4 Suppose that, in $Q_{0}$, the arguments of the events that occur in $\psi$ are always simple terms.

Let $\mathcal{S}=\left\{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \mid \forall j \leq m, \mu_{j}\right.$ executes $F_{j}$ and $c_{j}$ is a case for $\left.\mathcal{F}_{\mu_{j}, c_{j}}\right\}$. Assume that there exist a pseudo-formula $\mathcal{C}$ and a family of substitutions $\theta$ equal to the identity on $\widetilde{x}$ such that prove ${ }^{\varphi}(\mathcal{C}, \theta, \mathcal{S})$. Assume that for all $\mathcal{A} \in \mathcal{B B}$ and all evaluation contexts $C$ acceptable for $Q_{0}, \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right] \preceq \neg\left\{\left[\operatorname{prove}^{\varphi}(\mathcal{C}, \theta, \mathcal{S})\right]\right\}\right] \leq p(\mathcal{A}, C)$. Then $\operatorname{Bound}_{Q_{0}}\left(V, \varphi, D_{\text {false }}, p\right)$ for any $V$.

In the implementation, the value of $\mathcal{C}$ is computed by adding $\left(\mathcal{F}, M_{0}^{\prime}, \mathcal{I}, \mathcal{V}\right)$ to $\mathcal{S}$ when handling injective events during the checking of prove ${ }^{\varphi}(\mathcal{C}, \theta, \mathcal{S})$. We check $\vdash \mathcal{C}$ incrementally, after each addition of an element to $\mathcal{C}$. The proof of Proposition 3 relies on the following definitions and lemmas. We have

$$
\begin{aligned}
& \left\{\left[\mathcal{F} \models_{\theta}^{\mathcal{I}, \mathcal{V}, \perp} M\right]\right\}=\forall \widetilde{z} \in \widetilde{T}^{\prime \prime}, \neg(\bigwedge \mathcal{F} \wedge \neg \theta M) \\
& \left\{\left[\mathcal{F} \models_{\theta}^{\mathcal{I}, \mathcal{V}, \perp} \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right)\right]\right\}=\forall \widetilde{z} \in \widetilde{T}^{\prime \prime}, \neg\left(\bigwedge \mathcal{F} \wedge \bigvee_{j=1}^{m} \theta M_{j} \neq M_{j}^{\prime}\right) \\
& \text { for some } M_{0}^{\prime}: \operatorname{event}\left(e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right)\right) \in \mathcal{F} \\
& \left\{\left[\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{S}} \operatorname{inj}-\operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right)\right]\right\}=\forall \widetilde{z} \in \widetilde{T}^{\prime \prime}, \neg\left(\bigwedge \mathcal{F} \wedge \bigvee_{j=1}^{m} \theta M_{j} \neq M_{j}^{\prime}\right) \\
& \text { for some } M_{0}^{\prime}: \operatorname{event}\left(e\left(M_{1}^{\prime}, \ldots, M_{m}^{\prime}\right)\right) \in \mathcal{F} \text { and }\left(\mathcal{F}, M_{0}^{\prime}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S} \\
& \left\{\left[\mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1} \wedge \mathcal{C}_{2}} \phi_{1} \wedge \phi_{2}\right]\right\}=\left\{\left[\mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1}} \phi_{1}\right]\right\} \wedge\left\{\left[\mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{2}} \phi_{2}\right]\right\} \\
& \left\{\left[\mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1} \vee \mathcal{C}_{2}} \phi_{1} \vee \phi_{2}\right]\right\}= \begin{cases}\left\{\left[\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1}} \phi_{1}\right]\right\} & \text { if } \mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1}} \phi_{1} \\
\left\{\left[\mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{2}} \phi_{2}\right]\right\} & \text { otherwise }\end{cases}
\end{aligned}
$$

where $\widetilde{z}=\mathcal{V}$ and $\widetilde{T}^{\prime \prime}$ are the types of these variables. We also have

$$
\begin{aligned}
\{[\vdash \mathcal{C}]\}= & \bigwedge_{\mathcal{S} \neq \perp} \bigwedge_{\text {leaf of } \mathcal{C}\left(\mathcal{F}, M_{0}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S}} \bigwedge_{\left(\mathcal{F}^{\prime}, M_{0}^{\prime}, \mathcal{I}^{\prime}, \mathcal{V}^{\prime}\right) \in \mathcal{S}} \forall \widetilde{z} \in \widetilde{T}^{\prime \prime} \\
& \neg\left(\bigwedge \mathcal{F} \wedge \bigwedge^{\prime \prime} \mathcal{F}^{\prime} \wedge\left(\prod_{j \in \operatorname{Dom}(\mathcal{I})} \mathcal{I}(j) \neq \theta^{\prime \prime} \mathcal{I}^{\prime}(j)\right) \wedge M_{0}=\theta^{\prime \prime} M_{0}^{\prime}\right)
\end{aligned}
$$

where the substitution $\theta^{\prime \prime}$ is a renaming of variables in $\mathcal{V}^{\prime}$ to distinct fresh variables, $\widetilde{z}=\mathcal{V} \cup \theta^{\prime \prime} \mathcal{V}^{\prime}$, and $\widetilde{T}^{\prime \prime}$ are the types of these variables.

We define formula $\left(\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right)$ as follows:

$$
\begin{aligned}
& \text { formula }\left(\mathcal{F} \not \bigoplus_{\theta}^{\mathcal{I}, \mathcal{V}, \perp} M\right)=\theta M \\
& \operatorname{formula}\left(\mathcal{F} \not \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \perp} \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right)\right)=\theta \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) \\
& \text { formula }\left(\mathcal{F} \Leftrightarrow{ }_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{S}} \operatorname{inj} \text {-event }\left(e\left(M_{1}, \ldots, M_{m}\right)\right)\right)= \\
& \bigvee_{\left.N_{0}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S}} \exists \tau \in \mathbb{N}, N_{0}: \theta \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ \tau \\
& \text { formula }\left(\mathcal{F} \not \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1} \wedge \mathcal{C}_{2}} \phi_{1} \wedge \phi_{2}\right)=\operatorname{formula}\left(\mathcal{F} \not \models_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1}} \phi_{1}\right) \wedge \operatorname{formula}\left(\mathcal{F} \models_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{2}} \phi_{2}\right) \\
& \text { formula }\left(\mathcal{F} \models_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1} \vee \mathcal{C}_{2}} \phi_{1} \vee \phi_{2}\right)= \begin{cases}\operatorname{formula}\left(\mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1}} \phi_{1}\right) & \text { if } \mathcal{F} \models_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{1}} \phi_{1} \\
\text { formula }\left(\mathcal{F} \Leftrightarrow_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}_{2}} \phi_{2}\right) & \text { otherwise }\end{cases}
\end{aligned}
$$

The formula formula $\left(\mathcal{F} \not{ }_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right)$ generalizes $\theta \phi$ to the case of injective events.

Lemma $40\left\{\left[\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right]\right\} \Rightarrow \forall \widetilde{z} \in \widetilde{T}^{\prime \prime}, \neg\left(\bigwedge \mathcal{F} \wedge \neg \operatorname{formula}\left(\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right)\right)$ where $\widetilde{z}=\mathcal{V}$ and $\widetilde{T}^{\prime \prime}$ are the types of these variables.

Proof By induction on $\phi$. This result is similar to Lemma 37. The case of injective events is new. The case of disjunction differs, but is straightforward by induction hypothesis.

The next lemma shows that, for events $e$ in the considered correspondence, two distinct executions of event $e$ have distinct pairs (program point, replication indices). When the term $M$ contains no array accesses, we define $\sigma(M)$ by $\sigma, M \Downarrow \sigma(M)$.

Lemma 41 Assume that the event $e$ is used in the correspondence $\varphi$. Let $Q_{0}$ be a process that satisfies Property 3. Let $C$ be an evaluation context acceptable for $Q_{0}$ with public variables $V$ that does not contain events used by $\varphi$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. If initConfig $\left(C\left[Q_{0}\right], \mathcal{A}\right) \xrightarrow{p_{1}}{ }_{t_{1}}$ $\ldots \xrightarrow{p_{m-1}} t_{m-1} E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v, \mu \mathcal{E} v(\tau)=(\mu, \widetilde{a}): e\left(a_{1}, \ldots, a_{m}\right), \mu \mathcal{E} v\left(\tau^{\prime}\right)=\left(\mu^{\prime}, \widetilde{a}^{\prime}\right): e\left(a_{1}^{\prime}, \ldots\right.$, $\left.a_{m}^{\prime}\right)$, and $\tau \neq \tau^{\prime}$, then $(\mu, \widetilde{a}) \neq\left(\mu^{\prime}, \widetilde{a}^{\prime}\right)$.

Proof Let us fix the event symbol $e$. We define the multisets Events $(\widetilde{a}, M)$, Events $(\widetilde{a}, P)$, and Events $(\widetilde{a}, Q)$ by
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu} i\right)=\emptyset$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu} x\left[M_{1}, \ldots, M_{m}\right]\right)=\biguplus_{j \in\{1, \ldots, m\}} \operatorname{Events}\left(\widetilde{a}, M_{j}\right)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu} f\left(M_{1}, \ldots, M_{m}\right)\right)=\biguplus_{j \in\{1, \ldots, m\}} \operatorname{Events}\left(\widetilde{a}, M_{j}\right)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu} x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; N\right)=\operatorname{Events}(\widetilde{a}, N)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ let $x[\widetilde{i}]: T=M$ in $\left.N\right)=\operatorname{Events}(\widetilde{a}, M) \uplus \operatorname{Events}(\widetilde{a}, N)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ if $M$ then $N$ else $\left.N^{\prime}\right)=\operatorname{Events}(\widetilde{a}, M) \uplus \max \left(\operatorname{Events}(\widetilde{a}, N)\right.$, Events $\left.\left(\widetilde{a}, N^{\prime}\right)\right)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ find $[$ unique? $]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{[i]}=\widetilde{i_{j}} \leq \widetilde{n_{j}} \operatorname{suchthat~defined~}\left(\widetilde{M_{j}}\right) \wedge M_{j}^{\prime}\right.$ then $\left.N_{j}\right)$ else $\left.N^{\prime}\right)=$ $\biguplus_{j=1}^{m} \biguplus_{\widetilde{a_{j}} \leq \widetilde{n_{j}}} \operatorname{Events}\left(\left(\widetilde{a}, \widetilde{a_{j}}\right), M_{j}^{\prime}\right) \uplus \max \left(\max _{j=1}^{m} \operatorname{Events}\left(\widetilde{a}, N_{j}\right)\right.$, Events $\left.\left(\widetilde{a}, N^{\prime}\right)\right)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ event $\left.e^{\prime}\left(M_{1}, \ldots, M_{m}\right) ; M\right)=\biguplus_{j \in\{1, \ldots, m\}} \operatorname{Events}\left(\widetilde{a}, M_{j}\right) \uplus \operatorname{Events}(\widetilde{a}, M)$ if $e^{\prime} \neq e$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ event $\left.e\left(M_{1}, \ldots, M_{m}\right) ; M\right)=\{(\mu, \widetilde{a})\} \uplus \biguplus_{j \in\{1, \ldots, m\}} \operatorname{Events}\left(\widetilde{a}, M_{j}\right) \uplus \operatorname{Events}(\widetilde{a}, M)$
Events $\left(\widetilde{a},{ }^{\mu}\right.$ event_abort $\left.e^{\prime}\right)=\emptyset$ if $e^{\prime} \neq e$
Events $\left(\widetilde{a},{ }^{\mu}\right.$ event_abort $\left.e\right)=\{(\mu, \widetilde{a})\}$
Events $\left(\widetilde{a},{ }^{\mu} 0\right)=\emptyset$
Events $\left(\widetilde{a},{ }^{\mu}\left(Q_{1} \mid Q_{2}\right)\right)=\operatorname{Events}\left(\widetilde{a}, Q_{1}\right) \uplus \operatorname{Events}\left(\widetilde{a}, Q_{2}\right)$
Events $\left(\widetilde{a},{ }^{\mu}\right.$ foreach $i \leq n$ do $\left.Q\right)=\biguplus_{a \in[1, n]} \operatorname{Events}((\widetilde{a}, a), Q)$
Events $\left(\widetilde{a},{ }^{\mu}\right.$ newOracle $\left.O ; Q\right)=\operatorname{Events}(\widetilde{a}, Q)$
$\left.\operatorname{Events}\left(\widetilde{a},{ }^{\mu} O[\widetilde{i}](x \widetilde{[i}]: T\right):=P\right)=\operatorname{Events}(\widetilde{a}, P)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ return $\left.(N) ; Q\right)=\operatorname{Events}(\widetilde{a}, N) \uplus \operatorname{Events}(\widetilde{a}, Q)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu} x[\widetilde{i}] \stackrel{R}{\leftarrow} T ; P\right)=\operatorname{Events}(\widetilde{a}, P)$
Events $\left(\widetilde{a},{ }^{\mu}\right.$ let $x[\widetilde{i}]: T=M$ in $\left.P\right)=\operatorname{Events}(\widetilde{a}, M) \uplus \operatorname{Events}(\widetilde{a}, P)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ let $\left.x[\widetilde{i}]: T=O\left[M_{1}, \ldots, M_{k}, ? u_{1} \widetilde{[i]} \leq n_{1}, \ldots, ? u_{m} \widetilde{i}\right] \leq n_{m}\right]\left(M_{k+1}\right)$ in $P_{1}$ else $\left.P_{2}\right)=$ $\biguplus_{i=1}^{k+1} \operatorname{Events}\left(\widetilde{a}, M_{i}\right) \uplus \max \left(\operatorname{Events}\left(\widetilde{a}, P_{1}\right), \operatorname{Events}\left(\widetilde{a}, P_{2}\right)\right)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ if $M$ then $P$ else $\left.P^{\prime}\right)=\operatorname{Events}(\widetilde{a}, M) \uplus \max \left(\operatorname{Events}(\widetilde{a}, P), \operatorname{Events}\left(\widetilde{a}, P^{\prime}\right)\right)$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ find $[$ unique $?]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$ suchthat defined $\left(\widetilde{M_{j}}\right) \wedge M_{j}^{\prime}$ then $\left.P_{j}\right)$ else $\left.P\right)=$

$$
\begin{aligned}
& \quad \biguplus_{j=1}^{m} \biguplus_{\widetilde{a_{j}} \leq \widetilde{n_{j}}} \operatorname{Events}\left(\left(\widetilde{a}, \widetilde{a_{j}}\right), M_{j}^{\prime}\right) \uplus \max \left(\max _{j=1}^{m} \operatorname{Events}\left(\widetilde{a}, P_{j}\right) \text {, Events }(\widetilde{a}, P)\right) \\
& \text { Events }\left(\widetilde{a},^{\mu} \text { event } e^{\prime}\left(M_{0}, \ldots, M_{m}\right) ; P\right)=\biguplus_{j \in\{1, \ldots, m\}}^{\operatorname{Events}\left(\widetilde{a}, M_{j}\right) \uplus \operatorname{Events}(\widetilde{a}, P) \text { if } e^{\prime} \neq e} \\
& \text { Events }\left(\widetilde{a},^{\mu} \text { event } e\left(M_{0}, \ldots, M_{m}\right) ; P\right)=\{(\mu, \widetilde{a})\} \uplus \biguplus_{j \in\{1, \ldots, m\}} \operatorname{Events}\left(\widetilde{a}, M_{j}\right) \uplus \operatorname{Events}(\widetilde{a}, P)
\end{aligned}
$$

$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ event_abort $\left.e^{\prime}\right)=\emptyset$ if $e^{\prime} \neq e$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ event_abort $\left.e\right)=\{(\mu, \widetilde{a})\}$
$\operatorname{Events}\left(\widetilde{a},{ }^{\mu}\right.$ yield $)=\emptyset$
(get and insert are omitted because they do not occur in the game by Property 3 and as mentioned in the beginning of Section 3, get and insert in the adversary context can be encoded using find.)

We define the multisets

$$
\begin{aligned}
\text { Events }(\mu \mathcal{E v}) & =\{(\mu, \widetilde{a}) \mid(\mu, \widetilde{a}): e(\ldots) \in \mu \mathcal{E} v\} \\
\text { Events }(E, \sigma, M, \mathcal{T}, \mu \mathcal{E v}) & =\operatorname{Events}(\operatorname{Im}(\sigma), M) \uplus \operatorname{Events}(\mu \mathcal{E v}) \\
\operatorname{Events}(\mathcal{Q}, \mathcal{O} r) & =\biguplus_{\left(\sigma^{\prime}, Q^{\prime}\right) \in \mathcal{Q}} \operatorname{Events}\left(\operatorname{Im}\left(\sigma^{\prime}\right), Q^{\prime}\right) \\
\text { Events }(E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E v}) & =\biguplus_{(\sigma, P) \in \mathcal{S} t} \operatorname{Events}(\operatorname{Im}(\sigma), P) \uplus
\end{aligned}
$$



The latter multiset contains all pairs $(\mu, \widetilde{a})$ (program point, value of replication indices) for events $e(\ldots)$ that may be executed in a trace that contains the configuration $E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$.

The multiset Events $\left(\sigma_{0}, C\left[Q_{0}\right]\right)$ contains no duplicates. Indeed, we show by induction on $M$ that Events $(\widetilde{a}, M)$ is included in the multiset $\left\{\left(\mu, \widetilde{a}^{\prime}\right)\right\}$ where $\mu$ is a program point inside $M$ and $\widetilde{a}$ is a prefix of $\widetilde{a}^{\prime}$, and similarly for $P$ and $Q$. That allows to show that all multiset unions in the computation of Events are disjoint unions, since all recursive calls in the computation of Events are either with disjoint processes or terms, or with different extensions of $\widetilde{a}$.

Moreover, by induction on the derivations, if $E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v \xrightarrow{p}_{t} E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}$, then Events $(E, \sigma, M, \mathcal{T}, \mu \mathcal{E} v) \supseteq \operatorname{Events}\left(E^{\prime}, \sigma^{\prime}, M^{\prime}, \mathcal{T}^{\prime}, \mu \mathcal{E} v^{\prime}\right)$; if $\mathcal{Q}, \mathcal{O} r \rightsquigarrow \mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}$, then Events $(\mathcal{Q}$, $\mathcal{O} r) \supseteq \operatorname{Events}\left(\mathcal{Q}^{\prime}, \mathcal{O} r^{\prime}\right)$; and if Conf $\stackrel{p}{\rightarrow}_{t}$ Conf $^{\prime}$, then Events $($ Conf $) \supseteq \operatorname{Events}\left(\right.$ Conf $\left.{ }^{\prime}\right)$.

Therefore, the multiset $\operatorname{Events}\left(\left\{\left(\sigma_{0}, C\left[Q_{0}\right]\right)\right\},\left(f o\left(C\left[Q_{0}\right]\right), \emptyset\right)\right)$ contains no duplicates, and neither do the multisets Events (reduce $\left.\left(\left\{\left(\sigma_{0}, C\left[Q_{0}\right]\right)\right\},\left(f o\left(C\left[Q_{0}\right]\right), \emptyset\right)\right)\right)$, Events (initConfig $\left(C\left[Q_{0}\right], \mathcal{A}\right)$ ),
and Events (Conf), where Conf $=E, \mathcal{S} t, \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ is the final configuration of the considered trace. Hence, Events $(\mu \mathcal{E} v)$ contains no duplicates, which implies the desired result.

Lemma 42 Let $\varphi=\llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi \rrbracket$ be a correspondence that does not use non-unique events, with $\psi=F_{1} \wedge \ldots \wedge F_{m}, \widetilde{x}=\operatorname{var}(\psi)$, and $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$. Let $Q_{0}$ be a process that satisfies Properties 3 and 4 . Suppose that, in $Q_{0}$, the arguments of the events that occur in $\psi$ are always simple terms.

Let $\mathcal{S}=\left\{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \mid \forall j \leq m, \mu_{j}\right.$ executes $F_{j}$ and $c_{j}$ is a case for $\left.\mathcal{F}_{\mu_{j}, c_{j}}\right\}$. Let $C$ be an evaluation context acceptable for $Q_{0}$ with public variables $V$ that does not contain events used by $\varphi$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Let $\operatorname{Tr}$ be a full trace of $C\left[Q_{0}\right]$ for $\mathcal{A}$ that does not execute any non-unique event of $Q_{0}$. If $\operatorname{Tr} \vdash \neg \varphi$, then for any family of substitutions $\theta$ equal to the identity on $\widetilde{x}$, for any pseudo-formula $\mathcal{C}, \operatorname{Tr} \vdash \neg\left\{\left[\operatorname{prove}^{\varphi}(\mathcal{C}, \theta, \mathcal{S})\right]\right\}$.

Proof By contraposition, we suppose that, $\operatorname{Tr} \vdash\left\{\left[\operatorname{prove}^{\varphi}(\mathcal{C}, \theta, \mathcal{S})\right]\right\}$, so for every $\mu_{1}$ that executes $F_{1}, \ldots$, for every $\mu_{m}$ that executes $F_{m}$, for every $c_{1}, \ldots, c_{m}, \operatorname{Tr} \vdash\left\{\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}\right.\right.$, $\left.\left.\ldots, \mu_{m}, c_{m}\right)\right\}$ and $\left.\operatorname{Tr} \vdash\{\mid \vdash \mathcal{C}]\right\}$, and we show that $\operatorname{Tr} \vdash \varphi$.

Let $\mu \mathcal{E} v$ be the sequence of events in the last configuration of Tr .
We use the notations of Definition 12. We construct the functions $f_{1}, \ldots, f_{k}$ as follows. Let $\rho$ be a mapping of $\tau_{1}, \ldots, \tau_{m}$ to elements of $\mathbb{N}$ and of $\widetilde{x}$ to elements of $\widetilde{T}$. Suppose that $\operatorname{Tr}, \rho \vdash \psi^{\tau}$. Then, for all $j \leq m, T r, \rho \vdash F_{j}^{\tau}$. By Lemma 38, there exists a program point $\mu_{j}$ (in $Q_{0}$ ) that executes $F_{j}$ and a case $c_{j}$ such that, for any $\theta_{j}$ renaming of $I_{\mu_{j}}$ to fresh replication indices, there exists a mapping $\sigma_{j}$ with domain $\theta_{j} I_{\mu_{j}}$ such that $\mu \mathcal{E} v\left(\rho\left(\tau_{j}\right)\right)=\left(\mu_{j}, \sigma_{j}\left(\theta_{j} I_{p p_{j}}\right)\right): \ldots$ and $\operatorname{Tr}, \sigma_{j} \cup \rho \vdash \theta_{j} \mathcal{F}_{F_{j}, \mu_{j}, c_{j}}$. Let $\rho_{1}=\sigma_{1} \cup \cdots \cup \sigma_{m} \cup \rho$. We have $\operatorname{Tr}, \rho_{1} \vdash \theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}}$.

Let $\mathcal{F}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)=\theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}} \cup\left\{\neg\right.$ formula( $\operatorname{prove}^{\varphi}(\mathcal{C}, \theta$, $\left.\left.\left.\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)\right)\right\}$. By Lemma 40, \{[prove $\left.{ }^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)\right\} \Rightarrow \forall \theta_{1} I_{\mu_{1}}, \ldots, \forall \theta_{m} I_{\mu_{m}}$, $\forall \widetilde{x} \in \widetilde{T}, \neg \bigwedge \mathcal{F}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)$. So $\operatorname{Tr} \vdash \forall \theta_{1} I_{\mu_{1}}, \ldots, \forall \theta_{m} I_{\mu_{m}}, \forall \widetilde{x} \in \widetilde{T}, \neg \bigwedge \mathcal{F}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}\right.$, $\left.\ldots, \mu_{m}, c_{m}\right)$.

Then $\operatorname{Tr}, \rho_{1} \vdash \neg \bigwedge \mathcal{F}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)$, so $\operatorname{Tr}, \rho_{1} \vdash$ formula $\left(\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots\right.\right.$, $\left.\mu_{m}, c_{m}\right)$ ), that is, $\operatorname{Tr}, \rho_{1} \vdash \operatorname{formula}\left(\mathcal{F} \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right)$, with $\mathcal{F}=\theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}}$, $\mathcal{I}=\left\{j \mapsto\left(\mu_{j}, \theta_{j} I_{\mu_{j}}\right) \mid F_{j}\right.$ is an injective event $\}, \mathcal{V}=\operatorname{var}\left(\theta_{1} I_{\mu_{1}}\right) \cup \cdots \cup \operatorname{var}\left(\theta_{m} I_{\mu_{m}}\right) \cup\{\widetilde{x}\}$, and $\theta=\theta\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)$.

Consider an injective event in $\phi$, associated to function $f_{l}$.

- If that injective event corresponds to

$$
\bigvee_{\left(\mathcal{F}, N_{0}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S}} \exists \tau \in \mathbb{N}, N_{0}: \theta \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ \tau
$$

in formula $\left(\mathcal{F} \not \mapsto_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right)$, we have

$$
\operatorname{Tr}, \rho_{1} \vdash \bigvee_{\left(\mathcal{F}, N_{0}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S}} \exists \tau \in \mathbb{N}, N_{0}: \theta \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ \tau
$$

since formula $\left(\mathcal{F} \models_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right)$ is a conjunction. So $\operatorname{Tr}, \rho_{1}[\tau \mapsto a] \vdash N_{0}$ : $\theta \operatorname{event}\left(e\left(M_{1}, \ldots\right.\right.$, $\left.\left.M_{m}\right)\right) @ \tau$ for some $a \in \mathbb{N}$ and some $N_{0}$ such that $\left(\mathcal{F}, N_{0}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S}$. We define $f_{l}\left(\rho\left(\tau_{1}\right), \ldots\right.$, $\left.\rho\left(\tau_{m}\right), \rho(\widetilde{x})\right)=a$, so that $T r, \rho_{1} \vdash N_{0}: \theta \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ f_{l}\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right)$.
Moreover, if $j \in I$, then $F_{j}$ is an injective event, $F_{j}=\operatorname{inj}$-event $\left(e_{j}\left(M_{j, 1}, \ldots, M_{j, m}\right)\right)$. Moreover, $\operatorname{Tr}, \rho \vdash \psi^{\tau}$, so $\operatorname{Tr}, \rho \vdash F_{j}^{\tau}$, so $\operatorname{Tr}, \rho \vdash \operatorname{event}\left(e_{j}\left(M_{j, 1}, \ldots, M_{j, m}\right)\right) @ \tau_{j}$. Since $\mu \mathcal{E} v\left(\rho\left(\tau_{j}\right)\right)=\left(p p_{j}, \sigma_{j}\left(\theta_{j} I_{\mu_{j}}\right): \cdots=\left(\mu_{j}, \rho_{1}\left(\theta_{j} I_{\mu_{j}}\right)\right): \ldots\right.$ and $\mathcal{I}(j)=\left(\mu_{j}, \theta_{j} I_{\mu_{j}}\right)$, we have $\operatorname{Tr}, \rho_{1} \vdash \mathcal{I}(j): \operatorname{event}\left(e_{j}\left(M_{j, 1}, \ldots, M_{j, m}\right)\right) @ \tau_{j}$.

- If that injective event is in a removed disjunct in formula $\left(\mathcal{F} \not{ }_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right)$, then we define $f_{l}\left(\rho\left(\tau_{1}\right), \ldots, \rho\left(\tau_{m}\right), \rho(\widetilde{x})\right)=\perp$.

Then we have $T r, \rho_{1} \vdash \theta \phi^{\tau}$, so $T r, \rho_{1} \vdash \exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi^{\tau}$.
Hence, applying this construction for all $\rho$, we obtain $\operatorname{Tr} \vdash \forall \tau_{1}, \ldots, \tau_{m} \in \mathbb{N}, \forall \widetilde{x} \in \widetilde{T},\left(\psi^{\tau} \Rightarrow\right.$ $\left.\exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi^{\tau}\right)$. It remains to show $\operatorname{Inj}\left(I, f_{l}\right)$ for each $l \in\{1, \ldots, k\}$.

Suppose $f_{l}\left(a_{1}, \ldots, a_{m}, \widetilde{a}\right)=f_{l}\left(a_{1}^{\prime}, \ldots, a_{m}^{\prime}, \widetilde{a}^{\prime}\right) \neq \perp$. Let $\rho=\left\{\tau_{1} \mapsto a_{1}, \ldots, \tau_{m} \mapsto a_{m}, \widetilde{x} \mapsto \widetilde{a}\right\}$. Let $\mathcal{S}$ be the leaf of $\mathcal{C}$ corresponding to the event associated to $f_{l}$. By the construction above, we have $\theta,\left(\mathcal{F}, N_{0}, \mathcal{I}, \mathcal{V}\right) \in \mathcal{S}$, and an extension $\rho_{1}$ of $\rho$ such that

$$
\begin{align*}
& \operatorname{Tr}, \rho_{1} \vdash N_{0}: \theta \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ f_{l}\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right)  \tag{24}\\
& \operatorname{Tr}, \rho_{1} \vdash \mathcal{F}  \tag{25}\\
& \text { for } j \in I, \operatorname{Tr}, \rho_{1} \vdash \mathcal{I}(j): \operatorname{event}\left(e_{j}\left(M_{j, 1}, \ldots, M_{j, m}\right)\right) @ \tau_{j} \tag{26}
\end{align*}
$$

Let $\rho^{\prime}=\left\{\tau_{1} \mapsto a_{1}^{\prime}, \ldots, \tau_{m} \mapsto a_{m}^{\prime}, \widetilde{x} \mapsto \widetilde{a^{\prime}}\right\}$. In the same way, we have $\theta^{\prime},\left(\mathcal{F}^{\prime}, N_{0}^{\prime}, \mathcal{I}^{\prime}, \mathcal{V}^{\prime}\right) \in \mathcal{S}$, and an extension $\rho_{1}^{\prime}$ of $\rho^{\prime}$ such that

$$
\begin{aligned}
& \operatorname{Tr}, \rho_{1}^{\prime} \vdash N_{0}^{\prime}: \theta^{\prime} \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ f_{l}\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right) \\
& \operatorname{Tr}, \rho_{1}^{\prime} \vdash \mathcal{F}^{\prime} \\
& \text { for } j \in I, \operatorname{Tr}, \rho_{1}^{\prime} \vdash \mathcal{I}^{\prime}(j): \operatorname{event}\left(e_{j}\left(M_{j, 1}, \ldots, M_{j, m}\right)\right) @ \tau_{j}
\end{aligned}
$$

Let $\theta^{\prime \prime}$ be a renaming of the domain of $\rho_{1}^{\prime}$ to fresh variables. We have

$$
\begin{align*}
& \operatorname{Tr}, \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash \theta^{\prime \prime} N_{0}^{\prime}: \theta^{\prime \prime} \theta^{\prime} \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ f_{l}\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right)  \tag{27}\\
& \operatorname{Tr}, \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash \theta^{\prime \prime} \mathcal{F}^{\prime}  \tag{28}\\
& \text { for } j \in I, \operatorname{Tr}, \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash \theta^{\prime \prime} \operatorname{event}\left(e_{j}\left(\mathcal{I}^{\prime}(j), M_{j, 1}, \ldots, M_{j, m}\right)\right) @ \tau_{j} . \tag{29}
\end{align*}
$$

Therefore, by (24) and 27),

$$
\begin{aligned}
& \operatorname{Tr}, \rho_{1} \cup \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash \theta N_{0}: \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ f_{l}\left(a_{1}, \ldots, a_{m}, \widetilde{a}\right) \\
& \operatorname{Tr}, \rho_{1} \cup \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash \theta^{\prime \prime} N_{0}^{\prime}: \theta^{\prime \prime} \theta^{\prime} \operatorname{event}\left(e\left(M_{1}, \ldots, M_{m}\right)\right) @ f_{l}\left(a_{1}^{\prime}, \ldots, a_{m}^{\prime}, \widetilde{a^{\prime}}\right) .
\end{aligned}
$$

Since $f_{l}\left(a_{1}, \ldots, a_{m}, \widetilde{a}\right)=f_{l}\left(a_{1}^{\prime}, \ldots, a_{m}^{\prime}, \widetilde{a^{\prime}}\right)$, the events are the same, so

$$
\begin{equation*}
\operatorname{Tr}, \rho_{1} \cup \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash N_{0}=\theta^{\prime \prime} N_{0}^{\prime} . \tag{30}
\end{equation*}
$$

We also have by (25) and (28),

$$
\begin{equation*}
\operatorname{Tr}, \rho_{1} \cup \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash \mathcal{F} \cup \theta^{\prime \prime} \mathcal{F}^{\prime} \tag{31}
\end{equation*}
$$

Since $\operatorname{Tr} \vdash\{\vdash \mathcal{C}]\}$, we have

$$
\operatorname{Tr}, \rho_{1} \cup \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash \neg\left(\bigwedge \mathcal{F} \wedge \bigwedge \theta^{\prime \prime} \mathcal{F}^{\prime} \wedge\left(\underset{j \in \operatorname{Dom}(\mathcal{I})}{\bigvee} \mathcal{I}(j) \neq \theta^{\prime \prime} \mathcal{I}^{\prime}(j)\right) \wedge N_{0}=\theta^{\prime \prime} N_{0}^{\prime}\right)
$$

so using (31) and (30), we conclude that

$$
\operatorname{Tr}, \rho_{1} \cup \rho_{1}^{\prime} \theta^{\prime \prime-1} \vdash \bigwedge_{j \in I} \mathcal{I}(j)=\theta^{\prime \prime} \mathcal{I}^{\prime}(j)
$$

since $\operatorname{Dom}(\mathcal{I})=I$. Let $\mu \mathcal{E} v$ be the sequence of events at the end of $\operatorname{Tr}$. For $j \in I$, let $b_{j}=$ $\rho_{1}(\mathcal{I}(j))=\rho_{1}^{\prime}\left(\mathcal{I}^{\prime}(j)\right)$. By (26) and (29), we have $\mu \mathcal{E} v\left(a_{j}\right)=b_{j}: e_{j}(\ldots)$ and $\mu \mathcal{E} v\left(a_{j}^{\prime}\right)=b_{j}: e_{j}(\ldots)$. By Lemma 41, we have $a_{j}=a_{j}^{\prime}$. That proves $\operatorname{Inj}\left(I, f_{l}\right)$, and concludes the proof that $\operatorname{Tr} \vdash \varphi$.

Proof of Proposition 3 Let $C$ be an evaluation context acceptable for $Q_{0}$ with public variables $V$ that does not contain events used by $\varphi$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. We have

$$
\begin{array}{rlr}
\operatorname{Adv}_{Q_{0}}\left(\mathcal{A}, C, \varphi, D_{\text {false }}\right) & =\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg \varphi \wedge \neg \text { NonUnique }_{Q_{0}}\right] & \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg\left\{\left[\operatorname{prove}^{\varphi}(\mathcal{C}, \theta, \mathcal{S})\right]\right\}\right] & \text { by Lemma } 42 \\
& \left.\leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right] \preceq \neg\left\{\operatorname{prove}^{\varphi}(\mathcal{C}, \theta, \mathcal{S})\right]\right\}\right] & \\
& \leq p(\mathcal{A}, C) & \text { by Lemma } 1 \\
\hline
\end{array}
$$

So Bound $Q_{0}\left(V, \varphi, D_{\text {false }}, p\right)$.

Example 7 Let us prove that the example $G_{1}$ satisfies (6). We prove the correspondence $(\forall \widetilde{x}$ : $\left.\widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi\right)=\left(\forall x:\right.$ pkey, $y:$ host, $z:$ nonce $; \operatorname{inj}$-event $\left(e_{B}(x, y, z)\right) \Rightarrow \operatorname{inj}$-event $\left.\left(e_{A}(x, y, z)\right)\right)$. The program point $\mu_{B}$ executes $F=\operatorname{event}\left(e_{B}(x, y, z)\right)$ and $\mathcal{F}=\theta^{\prime} \mathcal{F}_{F, \mu_{B}} \supseteq \theta^{\prime} \mathcal{F}_{\mu_{B}}\left\{i_{B}^{\prime} / i_{B}\right\} \cup$ $\left\{x_{p k_{A}}\left[i_{B}^{\prime}\right]=x, B=y, N\left[i_{B}^{\prime}\right]=z\right\}$ with $\theta^{\prime}=\left\{i_{B}^{\prime} / i_{B}\right\}$.

As in the proof of $\mathcal{F} \Leftrightarrow_{\theta\left(\mu_{B}\right)}$ event $\left(e_{A}(x, y, z)\right)$ in Example 6, we show $\mathcal{F} \not \Leftrightarrow_{\theta\left(\mu_{B}\right)}^{\mathcal{I}, \mathcal{C}, \mathcal{C}} \operatorname{event}\left(e_{A}(x\right.$, $y, z)$ ) where $\mathcal{I}=\left\{1 \mapsto\left(\mu_{B}, i_{B}^{\prime}\right)\right\}$ encodes the program points and replication indices of the events of $\psi, \mathcal{V}=\left\{i_{B}^{\prime}, x, y, z\right\}$ contains the replication indices of $\mathcal{F}$ and the variables of $\psi$, $\mathcal{C}=\mathcal{S}=\left\{\left(\mathcal{F},\left(\mu_{A}, u\left[i_{B}^{\prime}\right]\right), \mathcal{I}, \mathcal{V}\right)\right\} . \quad(\mathcal{C}=\mathcal{S}$ because the formula $\psi$ is reduced to a single event; $M_{0}^{\prime}=\left(\mu_{A}, u\left[i_{B}^{\prime}\right]\right)$ contains the program point and replication indices of the event $e_{A}$ contained in $\mathcal{F}:\left(\mu_{A}, u\left[i_{B}^{\prime}\right]\right): \operatorname{event}\left(e_{A}\left(p k_{A}, x_{B}\left[u\left[i_{B}^{\prime}\right]\right], x_{N}\left[u\left[i_{B}^{\prime}\right]\right]\right)\right) \in \mathcal{F}$.

In order to prove injectivity, it remains to show that $\vdash \mathcal{C}$. Let $\theta^{\prime \prime}=\left\{i_{B}^{\prime \prime} / i_{B}^{\prime}, x^{\prime \prime} / x, y^{\prime \prime} / y\right.$, $\left.z^{\prime \prime} / z\right\}$. We need to show that $\mathcal{F} \cup \theta^{\prime \prime} \mathcal{F} \cup\left\{\left(\mu_{B}, i_{B}^{\prime}\right) \neq\left(\mu_{B}, i_{B}^{\prime \prime}\right),\left(\mu_{A}, u\left[i_{B}^{\prime}\right]\right)=\left(\mu_{A}, u\left[i_{B}^{\prime \prime}\right]\right)\right\}$ yields a contradiction, that is, if the pairs (program point, replication indices) of the event $e_{B}$ in $\psi$ are distinct $\left(\left(\mu_{B}, i_{B}^{\prime}\right) \neq\left(\mu_{B}, i_{B}^{\prime \prime}\right)\right)$, then the pairs (program point, replication indices) of the event $e_{A}$ in $\phi$ are also distinct $\left(\left(\mu_{A}, u\left[i_{B}^{\prime}\right]\right) \neq\left(\mu_{A}, u\left[i_{B}^{\prime \prime}\right]\right)\right)$.
$\mathcal{F}$ contains $N\left[i_{B}^{\prime}\right]=x_{N}\left[u\left[i_{B}^{\prime}\right]\right]$, so $\theta^{\prime \prime} \mathcal{F}$ contains $N\left[i_{B}^{\prime \prime}\right]=x_{N}\left[u\left[i_{B}^{\prime \prime}\right]\right]$. These two equalities combined with $u\left[i_{B}^{\prime}\right]=u\left[i_{B}^{\prime \prime}\right]$ imply that $N\left[i_{B}^{\prime}\right]=x_{N}\left[u\left[i_{B}^{\prime}\right]\right]=x_{N}\left[u\left[i_{B}^{\prime \prime}\right]\right]=N\left[i_{B}^{\prime \prime}\right]$. Since $N$ is defined by random choices of the large type nonce, $N\left[i_{B}^{\prime}\right]=N\left[i_{B}^{\prime \prime}\right]$ implies $i_{B}^{\prime}=i_{B}^{\prime \prime}$ up to probability $n^{2} / 2 \mid$ nonce $\mid$, by eliminating collisions. This equality contradicts $\left(\mu_{B}, i_{B}^{\prime}\right) \neq\left(\mu_{B}, i_{B}^{\prime \prime}\right)$, so we obtain the desired injectivity. Therefore, the game $G_{1}$ satisfies (6) with any public variables $V$ up to probability $n^{2} / 2 \mid$ nonce $\mid$.

## 5 Game Transformations

### 5.1 Syntactic Game Transformations

### 5.1.1 auto_SArename

The transformation auto_SArename renames all variables defined in conditions of find, so that they have distinct names. This transformation is a particular case of SArename (Section 5.1.7) that is particularly simple because these variables do not have array accesses by Invariant 3 .

Lemma 43 The transformation auto_SArename requires and preserves Properties 1, 2, and 3. It preserves Property5. If transformation auto_SArename transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}$ : $G, D$, EvUsed $\xrightarrow{V}_{0} G^{\prime}, D$, EvUsed and $G^{\prime}$ satisfies Property 4.

### 5.1.2 expand_tables 33

The transformation expand_tables transforms insert and get into find, since the other transformations do not support tables. It proceeds by storing the inserted list elements in fresh array variables, and looking up in these arrays instead of performing get. More precisely, when insert $\operatorname{Tbl}\left(M_{1}, \ldots, M_{k}\right) ; P$ is under the replications foreach $i_{1} \leq n_{1}$ do $\ldots$ foreach $i_{l} \leq n_{l}$ do, it is transformed into

$$
\text { let } y_{1}\left[i_{1}, \ldots, i_{l}\right]=M_{1} \text { in } \ldots \text { let } y_{k}\left[i_{1}, \ldots, i_{l}\right]=M_{k} \text { in } P
$$

where $y_{1}, \ldots, y_{k}$ are fresh array variables, and we add $\left(y_{1}, \ldots, y_{k} ; i_{1} \leq n_{1}, \ldots, i_{l} \leq n_{l}\right)$ in a set $S^{\prime}$, to remember them. The construct get[unique? $\operatorname{Tbl}\left(x_{1}: T_{1}, \ldots, x_{k}: T_{k}\right)$ suchthat $M$ in $P$ else $P^{\prime}$ is then transformed into
find[unique?] $\left(\begin{array}{l}u_{1}=i_{1}^{\prime} \leq n_{1}, \ldots, u_{l}=i_{l}^{\prime} \leq n_{l} \text { suchthat } \\ \left.\bigoplus^{\left.\text {defined }\left(y_{1}\left[\widetilde{i^{\prime}}\right], \ldots, y_{k}\left[\widetilde{i^{\prime}}\right]\right) \wedge M\left\{y_{1}\left[\widetilde{i^{\prime}}\right] / x_{1}, \ldots, y_{k} \widetilde{i^{\prime}}\right] / x_{k}\right\}} \begin{array}{ll} \\ \text { then let } x_{1}=y_{1}[\widetilde{u}] \text { in } \ldots \text { let } x_{k}=y_{k}[\widetilde{u}] \text { in } P\end{array}\right) \\ \left(y_{1}, \ldots, y_{k} ; i_{1} \leq n_{1}, \ldots, i_{l} \leq n_{l}\right) \in S^{\prime}\end{array}\right)$
else $P^{\prime}$
where [unique?] is either [unique ${ }_{e}$ ] or empty and has the same value at both occurrences, $\widetilde{u}$ stands for $u_{1}, \ldots, u_{l}$, and $\widetilde{i}^{\prime}$ stands for $i_{1}^{\prime}, \ldots, i_{l}^{\prime}$. This construct looks in all arrays used for translating insertion in table $T b l$, for indices $\widetilde{\tilde{i}^{\prime}}$ such that $\left.y_{1} \widetilde{\left.\tilde{i}^{\prime}\right]}, \ldots, y_{k} \widetilde{\left[^{\prime}\right.}\right]$ are defined, that is, an element has been inserted at indices $\widetilde{i^{\prime}}$, and $M\left\{y_{1}\left[\widetilde{i^{\prime}}\right] / x_{1}, \ldots, y_{k}\left[\widetilde{i^{\prime}}\right] / x_{k}\right\}$ is true, that is, that element satisfies $M$. When it finds such an element, it stores it in $x_{1}, \ldots x_{k}$, and runs $P$. (When it finds several elements, one of them is chosen randomly with uniform probability when [unique?] is empty and the non-unique event $e$ is raised when [unique?] is [unique ${ }_{e}$ ].) When it finds no element, it executes $P^{\prime}$. These transformations are described for processes, but similar transformations are performed for insert and get terms.

After this transformation, expand_tables calls auto_SArename to guarantee Property 4.
Lemma 44 The transformation expand_tables requires and preserves Properties 1 and 2. It preserves Property 5. If transformation expand_tables transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}: G$, $D, E v U s e d \xrightarrow{V} G^{\prime}, D, E v U s e d$, where $p$ is $\epsilon_{\text {find }}$ times the maximal number of executions of get in $G$ that is not obviously unique (that is, such that the insert in that table may be executed several times), and $G^{\prime}$ satisfies Properties 3 and 4.

### 5.1.3 expand

The transformation expand transforms terms $\stackrel{R}{\leftarrow}$, let, if, find, event, and event_abort into processes, so that Property 5 is guaranteed. It simplifies the generated game on the fly, using many of the rules of simplify (Section 5.1.21, to avoid generating branches that can actually not be executed.

After this transformation, expand calls auto_SArename to guarantee Property 4

Lemma 45 The transformation expand requires and preserves Properties 1, 2, 3, and 4 If transformation expand transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, D$, EvUsed $\xrightarrow{V}_{p} G^{\prime}, D$, EvUsed, where $p$ is an upper bound of the probability that the simplification steps modify the execution, and $G^{\prime}$ satisfies Property 5 .

### 5.1.4 prove_unique

The transformation prove_unique tries to prove that each find[unique ${ }_{e}$ ] really has a unique possibility at runtime (up to a small probability), so that event $e$ is executed with at most that probability. More precisely, find[unique] are already proved; find[unique ${ }_{e}$ ] for which no query event $(e) \Rightarrow$ false is active are also considered as already proved (they will be proved elsewhere; with the notations of Definition 6 , e does not occur in $D_{1} \vee D$, so e occurs in NonUnique ${ }_{Q, D_{1} \vee D}$ ), and they are replaced with find unique]. That corresponds to renaming event $e$ to a special nonunique event that is always in NonUnique ${ }_{Q, D_{1} \vee D}$. It remains to prove find[unique $e_{e}$ ] for which a query event $(e) \Rightarrow$ false is active.

Suppose that $P_{0}=$ find $\left[\right.$ unique $\left._{e}\right]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $P_{j}$ ) else $P$ is such a find[unique $e_{e}$. (The same transformation is performed for find [unique ${ }_{e}$ ] terms.) CryptoVerif proves uniqueness by proving

- that we obtain a contradiction if the condition of a certain branch holds for two different values of the indices $\widetilde{i_{j}}$, that is, for all $j \in\{1, \ldots, m\}, \mathcal{F}_{P_{0}} \cup\left\{\operatorname{defined}\left(M_{j 1}\right), \ldots\right.$, defined $\left(M_{j l_{j}}\right)$, $M_{j}$, defined $\left(\theta M_{j 1}\right), \ldots$, defined $\left.\left(\theta M_{j l_{j}}\right), \theta M_{j}, \widetilde{i_{j}} \neq \theta \widetilde{i_{j}}\right\}$ yields a contradiction, where the substitution $\theta$ maps $\widetilde{i_{j}}$ to fresh replication indices;
- and that we obtain a contradiction if the conditions of two different branches hold simultaneously, that is, for all $j, j^{\prime} \in\{1, \ldots, m\}$ with $j<j^{\prime}, \mathcal{F}_{P_{0}} \cup\left\{\operatorname{defined}\left(M_{j 1}\right), \ldots\right.$, defined $\left(M_{j l_{j}}\right)$, $M_{j}$, defined $\left(\theta M_{j^{\prime} 1}\right), \ldots$, defined $\left.\left(\theta M_{j^{\prime} l_{j^{\prime}}}\right), \theta M_{j^{\prime}}\right\}$ yields a contradiction, where the substitution $\theta$ maps $\widetilde{i_{j^{\prime}}}$ to fresh replication indices. (The substitution $\theta$ is useful in case the same replication indices are used in both branches $j$ and $j^{\prime}$.)
When uniqueness is proved, find[unique ${ }_{e}$ ] is replaced with find[unique]. A subsequent call to success (Section 4) will remove the query event $(e) \Rightarrow$ false when event $e$ no longer occurs in the game.

Lemma 46 The transformation prove_unique requires and preserves Properties 1, 2, 3, and 4. It preserves Property 5. If transformation prove_unique transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}$ : $G, D, E v U$ sed $\xrightarrow{V} G^{\prime}, D$, EvUsed, where $p$ is an upper bound on the probability that a find[unique ${ }_{e}$ ] proved in the transformation actually executes event $e$.

### 5.1.5 remove_assign 26]

The transformation remove_assign applied to an assignment let $x\left[i_{1}, \ldots, i_{l}\right]: T=M$ in $P$ replaces $x$ with its value $M$. (The same transformation is performed for assignment terms.) Precisely, the transformation is performed only when $x$ does not occur in $M$ (non-cyclic assignment) and $M$ contains only variables, function applications, and tests (otherwise, copying the definition of $x$ may break the invariant that each variable is assigned at most once). When $x$ has several distinct definitions, we simply replace $x\left[i_{1}, \ldots, i_{l}\right]$ with $M$ in $P$. (For accesses to $x$ guarded by find, we do not know which definition of $x$ is actually used.) When $x$ has a single definition or several identical definitions, we replace everywhere in the game $x\left[M_{1}, \ldots, M_{l}\right]$ with $M\left\{M_{1} / i_{1}, \ldots, M_{l} / i_{l}\right\}$. We additionally update the defined conditions of find to preserve Invariant 2 and to make sure that, if a condition of find guarantees that $x\left[M_{1}, \ldots, M_{l}\right]$ is defined in the initial game, then so does the corresponding condition of find in the transformed game. (Essentially, when $y\left[M_{1}^{\prime}, \ldots, M_{l^{\prime}}^{\prime}\right]$ occurs in $M$, the transformation typically creates new occurrences of $y\left[M_{1}^{\prime \prime}, \ldots, M_{l^{\prime}}^{\prime \prime}\right]$ for some $M_{1}^{\prime \prime}, \ldots, M_{l^{\prime}}^{\prime \prime}$, so the condition that $y\left[M_{1}^{\prime \prime}, \ldots, M_{l^{\prime}}^{\prime \prime}\right]$ is defined must sometimes be explicitly added to conditions of find in order to preserve Invariant 2) Moreover, we replace as often as possible defined conditions $x\left[M_{1}, \ldots, M_{l}\right]$ with defined conditions
$y\left[M_{1}, \ldots, M_{l}\right]$ where $y$ is defined at the same time as $x$. When $x \in V$, its definition is kept unchanged. Otherwise, when $x$ is not referred to at all after the transformation, we remove the definition of $x$. When $x$ is referred to only at the root of defined tests, we replace its definition with a constant. (The definition point of $x$ is important, but not its value.)

This removal of assignments is applied to all variables whose value is not used (those are used only at the root of defined conditions, or not at all). Depending on the argument of the transformation, it is also applied to other assignments:

- findcond: all assignments in conditions of find;
- useless: assignments that store a variable or a replication index, when the setting expandAssignXY is true; otherwise, no other assignment;
- binder $x_{1} \ldots x_{n}$ : the assignments to variables $x_{1}, \ldots, x_{n}$.

After this transformation, remove_assign calls auto_SArename to guarantee Property 4 .
With the arguments findcond and useless, this is repeated as many times as specified by the setting maxIterRemoveUselessAssign. Repetition stops if a fixpoint is reached.

Lemma 47 The transformation remove_assign requires and preserves Properties 1, 2, 3, and 4 . It preserves Property 5. If transformation remove_assign transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}$ : $G, D, E v U s e d{ }^{V} G^{\prime}, D$, EvUsed.

Example 8 In the game $G_{0}$ of Section 4.2.1 the transformation remove_assign binder $s k_{A}$ substitutes $\operatorname{skgen}\left(r k_{A}\right)$ for $s k_{A}$ in the whole process and removes the assignment let $s k_{A}=$ $\operatorname{skgen}\left(r k_{A}\right)$. After this substitution, $\operatorname{sign}\left(\operatorname{concat}\left(p k_{A}, x_{B}, x_{N}\right), s k_{A}, r\right)$ becomes $\operatorname{sign}\left(\operatorname{concat}\left(p k_{A}\right.\right.$, $\left.x_{B}, x_{N}\right)$, $\operatorname{skgen}\left(r k_{A}\right), r$ ) thus exhibiting a term required to apply the security assumption on signatures in the cryptographic transformation of Section 5.2

### 5.1.6 use_variable

The transformation use_variable $x_{1} \ldots x_{m}$ tries to use variables $x_{1}, \ldots, x_{n}$ instead of recomputing their value. More precisely, at each program point that corresponds to a simple term $M$ and where $x_{j}[\widetilde{M}]$ is guaranteed to be defined (because $x_{j}$ is defined above that program point or directly or indirectly because of defined conditions above that program point), if all definitions of $x_{j}$ that can be executed before reaching that program point are let $\left.x_{j} \widetilde{i}\right]=M_{0}$ in, then we test whether $M$ is equal to $M_{0}\{\widetilde{M} / \widetilde{i}\}$ modulo the built-in equations, and if yes, we replace $M$ with $x_{j}[\widetilde{M}]$.

The defined conditions of find above the modified program points are updated to make sure that Invariant 2 is preserved. This is needed in particular to make sure that $x_{j}[\widetilde{M}]$ syntactically occurs in the defined conditions when it is used.

Lemma 48 The transformation use_variable requires and preserves Properties 1. 2, 3, and 4. It preserves Property 5. If transformation use_variable transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}: G$, $D$, EvUsed $\xrightarrow{V} G^{\prime}, D, E v U s e d$.

The transformation use_variable is a convenient way to perform common subexpression elimination, possibly by first inserting the definition of the desired variable(s) by insert (Section 5.1.13). This transformation could also be done by several applications of replace (Section 5.1.14. However, use_variable is easier to use when it performs the desired replacement.

For performance reasons, the equality tests performed by use_variable are considerably less powerful than those performed by replace, so if use_variable does not replace a term with $x_{j}[\widetilde{M}]$ at some occurrence, it is worth trying replace.

### 5.1.7 SArename 26

The transformation SArename $x$ (single assignment rename) aims at renaming $x$ so that distinct definitions of $x$ have different names; this is useful for distinguishing cases depending on which definition of $x$ has set $x[\widetilde{i}]$. This transformation can be applied only when $x \notin V$. When $x$ has $m>1$ definitions, we rename each definition of $x$ to a different variable $x_{1}, \ldots, x_{m}$. Terms $x \widetilde{[i]}$ under a definition of $\left.x_{j} \widetilde{i}\right]$ are then replaced with $\left.x_{j} \widetilde{i}\right]$. Each branch of find $\left.F B=\widetilde{u} \widetilde{i}\right]=\widetilde{i^{\prime}} \leq$ $\widetilde{n}$ suchthat defined $\left(M_{1}^{\prime}, \ldots, M_{l^{\prime}}^{\prime}\right) \wedge M$ then $\ldots$ where $x\left[M_{1}, \ldots, M_{l}\right]$ is a subterm of some $M_{k}^{\prime}$ for $k \leq l^{\prime}$ is replaced with $m$ branches $F B\left\{x_{j}\left[M_{1}, \ldots, M_{l}\right] / x\left[M_{1}, \ldots, M_{l}\right]\right\}$ for $1 \leq j \leq m$.

Moreover, the implementation takes into account that some variables cannot be simultaneously defined, to reduce the number of branches of find to generate.

After this transformation, SArename calls auto_SArename to guarantee Property 4
As a particular case, SArename random performs the following transformation: when $y$ is defined by $y \stackrel{R}{\leftarrow} T$ and has $m>1$ definitions and all variable accesses to $y$ are of the form $y\left[i_{1}, \ldots, i_{l}\right]$ under a definition of $y\left[i_{1}, \ldots, i_{l}\right]$, where $i_{1}, \ldots, i_{l}$ are the current replication indices at this definition of $y$ (that is, $y$ has no array access using find), it renames $y$ to $y_{1}, \ldots, y_{m}$ with a different name for each definition of $y$ by $y \stackrel{R}{\leftarrow} T$.

Lemma 49 The transformation SArename requires and preserves Properties 1, 2, 3, and 4. It preserves Property 5. If transformation SArename transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}: G, D$, EvUsed ${ }^{V}{ }_{p} G^{\prime}, D$, EvUsed, where $p$ is $\epsilon_{\text {find }}$ times the maximal number of executions of a modified find that is not proved unique.

Example 9 Consider the following process

$$
\begin{aligned}
& \text { Start }():=k_{A} \stackrel{R}{\leftarrow} T_{k} ; k_{B} \stackrel{R}{\leftarrow} T_{k} ; \text { return }() ;\left(Q_{K} \mid Q_{S}\right) \\
& Q_{K}= \\
& \quad \text { foreach } i \leq n \text { do } O[i]\left(h: T_{h}, k: T_{k}\right):= \\
& \quad \text { if } h=A \text { then let } k^{\prime}: T_{k}=k_{A} \text { in return () else } \\
& \quad \text { if } h=B \text { then let } k^{\prime}: T_{k}=k_{B} \text { in return () else } \\
& \quad \text { let } k^{\prime}: T_{k}=k \text { in return }() \\
& Q_{S}=\text { foreach } i^{\prime} \leq n^{\prime} \text { do } O^{\prime}\left[i^{\prime}\right]\left(h^{\prime}: T_{h}\right):= \\
& \quad \text { find } u=i^{\prime \prime} \leq n \text { suchthat defined }\left(h\left[i^{\prime \prime}\right], k^{\prime}\left[i^{\prime \prime}\right]\right) \wedge h^{\prime}=h\left[i^{\prime \prime}\right] \text { then } P_{1}\left(k^{\prime}[u]\right) \text { else } P_{2}
\end{aligned}
$$

The process $Q_{K}$ stores in ( $h, k^{\prime}$ ) a table of pairs (host name, key): the key for $A$ is $k_{A}$, for $B$, $k_{B}$, and for any other $h$, the adversary can choose the key $k$. The process $Q_{S}$ queries this table of keys to find the key $k^{\prime}[u]$ of host $h^{\prime}$, then executes $P_{1}\left(k^{\prime}[u]\right)$. If $h^{\prime}$ is not found, it executes $P_{2}$.

By the transformation SArename $k^{\prime}$, we can perform a case analysis, to distinguish the cases in which $k^{\prime}=k_{A}, k^{\prime}=k_{B}$, or $k^{\prime}=k$, by renaming the three definitions of $k^{\prime}$ to $k_{1}^{\prime}, k_{2}^{\prime}$, and $k_{3}^{\prime}$ respectively. After transformation, we obtain the following processes:

$$
\begin{aligned}
Q_{K}^{\prime}= & \text { foreach } i \leq n \text { do } O[i]\left(h: T_{h}, k: T_{k}\right):= \\
& \text { if } h=A \text { then let } k_{1}^{\prime}: T_{k}=k_{A} \text { in return () else } \\
& \text { if } h=B \text { then let } k_{2}^{\prime}: T_{k}=k_{B} \text { in return () else } \\
& \text { let } k_{3}^{\prime}: T_{k}=k \text { in return () }
\end{aligned}
$$

$$
\begin{aligned}
& Q_{S}^{\prime}=\text { foreach } i^{\prime} \leq n^{\prime} \text { do } O^{\prime}\left[i^{\prime}\right]\left(h^{\prime}: T_{h}\right):= \\
& \quad \text { find } u=i^{\prime \prime} \leq n \text { suchthat defined }\left(h\left[i^{\prime \prime}\right], k_{1}^{\prime}\left[i^{\prime \prime}\right]\right) \wedge h^{\prime}=h\left[i^{\prime \prime}\right] \text { then } P_{1}\left(k_{1}^{\prime}[u]\right) \\
& \quad \oplus u=i^{\prime \prime} \leq n \text { suchthat defined }\left(h\left[i^{\prime \prime}\right], k_{2}^{\prime}\left[i^{\prime \prime}\right]\right) \wedge h^{\prime}=h\left[i^{\prime \prime}\right] \text { then } P_{1}\left(k_{2}^{\prime}[u]\right) \\
& \oplus u=i^{\prime \prime} \leq n \text { suchthat defined }\left(h\left[i^{\prime \prime}\right], k_{3}^{\prime}\left[i^{\prime \prime}\right]\right) \wedge h^{\prime}=h\left[i^{\prime \prime}\right] \text { then } P_{1}\left(k_{3}^{\prime}[u]\right) \text { else } P_{2}
\end{aligned}
$$

The find in $Q_{S}$, which looks for elements in array $k^{\prime}$, is transformed in $Q_{S}^{\prime}$ into a find with three branches, one for each new name of $k^{\prime}\left(k_{1}^{\prime}, k_{2}^{\prime}\right.$, and $k_{3}^{\prime}$ respectively). After the simplification (Section 5.1.21), $Q_{S}^{\prime}$ becomes:

$$
\begin{aligned}
& Q_{S}^{\prime \prime}=\text { foreach } i^{\prime} \leq n^{\prime} \text { do } O^{\prime}\left[i^{\prime}\right]\left(h^{\prime}: T_{h}\right):= \\
& \quad \text { find } u=i^{\prime \prime} \leq n \text { suchthat defined }\left(h\left[i^{\prime \prime}\right], k_{1}^{\prime}\left[i^{\prime \prime}\right]\right) \wedge h^{\prime}=A \text { then } P_{1}\left(k_{A}\right) \\
& \qquad u=i^{\prime \prime} \leq n \text { suchthat defined }\left(h\left[i^{\prime \prime}\right], k_{2}^{\prime}\left[i^{\prime \prime}\right]\right) \wedge h^{\prime}=B \text { then } P_{1}\left(k_{B}\right) \\
& \oplus u=i^{\prime \prime} \leq n \text { suchthat defined }\left(h\left[i^{\prime \prime}\right], k_{3}^{\prime}\left[i^{\prime \prime}\right]\right) \wedge h^{\prime}=h\left[i^{\prime \prime}\right] \text { then } P_{1}(k[u]) \text { else } P_{2}
\end{aligned}
$$

since, when $k_{1}^{\prime}[u]$ is defined, $k_{1}^{\prime}[u]=k_{A}$ and $h[u]=A$, and similarly for $k_{2}^{\prime}[u]$ and $k_{3}^{\prime}[u]$.

### 5.1.8 move 26

The transformation move moves random choices and assignments downwards in the code as much as possible. A random choice $x \widetilde{[i]} \stackrel{R}{\leftarrow} T$ or assignment let $x \widetilde{i}]: T=M$ cannot be moved under a replication, or under a parallel composition when both sides use $x$, or a let let $y[\widetilde{i}]: T=M$ in $\ldots$ or a return return $(M)$ when $x$ occurs in $M$, or a find (or if) when the conditions use $x$. It can be moved under the other constructs, duplicating it if necessary, when we move it under a find (or if) that uses $x$ in several branches. Note that when the random choice $x \widetilde{i}] \stackrel{R}{\leftarrow} T$ or assignment let $x \widetilde{i}]: T=M$ cannot be moved under a parallel composition, or a replication, it must be written above the return that is located above the considered parallel composition or replication, so that the syntax of processes is not violated. When there are array accesses to $x$, the random choice $x[\widetilde{i}] \stackrel{R}{\leftarrow} T$ or assignment let $x \widetilde{i}]: T=M$ can be moved only inside the same oracle body, without moving it under a return or under a find that makes an array access to $x$.

The conditions above are necessary for the soundness of the move. Furthermore, the move is considered beneficial when it satisfies the following conditions:

- for random choices, when the random choice can be moved under a find (or if). When this transformation duplicates a $x \widetilde{i}] \stackrel{R}{\leftarrow} T$ by moving it under a find that uses $x$ in several branches, a subsequent SArename $(x)$ enables us to distinguish several cases depending in which branch $x$ is created, which is useful in some proofs.
- for assignments, when there are no array accesses to $x$, the assignment to $x$ can be moved under a find (or if), and $x$ is used in a single branch of that find (or if). In this case, the assignment can be performed only in the branch that uses $x$, so it will be computed in fewer cases thanks to the move.

The performed moves are determined by the argument of the transformation:

- all: moves all random choices and assignments, provided the move is beneficial.
- noarrayref: moves all random choices and assignments that do not have array references, provided the move is beneficial.
- random: moves all random choices, provided the move is beneficial.
- random_noarrayref: moves all random choices that do not have array references, provided the move is beneficial.
- assign: moves all assignments, provided the move is beneficial.
- binder $x_{1} \ldots x_{n}$ : move the variables $x_{1}, \ldots, x_{n}$ (even when the move is not beneficial).

In all cases, only random choices and assignments at the process level (not inside terms) are moved.

Lemma 50 The transformation move requires and preserves Properties 1, 2, 3, and 4 It preserves Property 5. If transformation move transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}: G, D$, EvUsed $\xrightarrow{V}{ }_{0} G^{\prime}, D, E v U s e d$.

### 5.1.9 move array $[27]$

The transformation move array $X$ delays the generation of a random value $X$ until the point at which it is first used (lazy sampling). This transformation is implemented as a particular case of a cryptographic transformation by the following equivalence:

```
foreach \(i \leq n\) do \(X \stackrel{R}{\leftarrow} T\);
    (foreach \(i X \leq n X\) do \(\operatorname{OX}():=\operatorname{return}(X) \mid\)
    foreach ieq \(\leq n e q\) do \(\left.\operatorname{Oeq}\left(X^{\prime}: T\right):=\operatorname{return}\left(X^{\prime}=X\right)\right)\)
\(\approx_{\# \text { Oeq/|T| }} \quad\) [manual]
foreach \(i \leq n\) do
    (foreach \(i X \leq n X\) do OX()\(:=\)
        find[unique] \(j \leq n X\) suchthat defined \((Y[j])\)
        then return \((Y[j])\) else \(Y \stackrel{R}{\leftarrow} T\); return \((Y) \mid\)
    foreach \(i e q \leq n e q\) do \(\operatorname{Oeq}\left(X^{\prime}: T\right):=\)
        find[unique] \(j \leq n X\) suchthat defined \((Y[j])\)
        then return \(\left(X^{\prime}=Y[j]\right)\) else return(false))
```

where $T$ is the type of $X$. Two oracles are defined, OX and Oeq. In the left-hand side, OX returns the random $X$ itself. In the right-hand side, OX uses a lookup to test if the random value was already generated; if yes, it returns the previously generated random value $Y[j]$; if no, it generates a fresh random value $Y$. Transforming the left-hand side into the right-hand side therefore moves the generation of the random number $X$ to the first call to OX, that is, the first usage of $X$. The oracle Oeq provides an optimized treatment of equality tests $X^{\prime}=X$ : when the random value $X$ was not already generated, we return false instead of generating a fresh $X$, so we exclude the case that $X^{\prime}$ is equal to a fresh $X$. This case has probability $1 /|T|$ for each call to Oeq, so the probability of distinguishing the two games is $\# \mathrm{Oeq} /|T|$. (Notice that there never exist several choices of $j$ that satisfy the conditions of the finds in the right-hand side of this equivalence, so these finds can be marked [unique] without modifying their behavior.)

Extension: A generalization of Oeq with other collisions is now supported by CryptoVerif.

### 5.1.10 move up

The transformation move up $x_{1} \ldots x_{n}$ to $\mu$ moves the random number generations or assignments of $x_{1}, \ldots, x_{n}$ upwards in the syntax tree, to the program point $\mu$. This program point must be inside an oracle body.

The program point $\mu$ is an integer, which can be determined using the command show_game occ: this command displays the current game with the corresponding label $\{\mu\}$ at each program point. The command show_game occ also allows one to inspect the game, for instance to know the names of fresh variables created by CryptoVerif during previous transformations. Program points and variable names may depend on the version of CryptoVerif. Since CryptoVerif version 2.01, program points can also be designated by expressions like before regexp, which designates the program point at the beginning of the line that matches the regular expression regexp; after regexp, which designates the program point just after the line that matches regexp; before_nth $n$ regexp, which designates the program point at the beginning of the $n$-th line that matches the regular expression regexp; after_nth $n$ regexp, which designates the program point at the beginning of the first line that has an occurrence number after the $n$-th line that matches the regular expression regexp; at $n^{\prime}$ regexp, which designates the program point at the $n^{\prime}$-th occurrence number that occurs inside the string that matches the regular expression regexp in the displayed game; at_nth $n n^{\prime}$ regexp, which designates the program point at the $n^{\prime}$-th occurrence number that occurs inside the string corresponding to the $n$-th match of the regular expression regexp in the displayed game. This way of designating program points is more stable across versions of CryptoVerif.

After the game transformation, a variable $x$ is defined at program point $\mu$, and all other variables $x_{k}$ are defined by let $x_{k}=x$ in. The variable $x$ is a variable $x_{k}$ itself when $x_{k}$ has no array accesses and the current replication indices at the definition of $x_{k}$ are the same as at $\mu$. Otherwise, the variable $x$ is a fresh variable.

All variables $x_{1}, \ldots, x_{n}$ must have the same type. They must not be defined syntactically above the program point $\mu$. The definitions of the variables $x_{1}, \ldots, x_{n}$ must be in distinct branches of if, find, let, so that they cannot be simultaneously defined. Either all variables $x_{1}, \ldots, x_{n}$ must be defined by random number generations or all of them must be defined by assignments.

- If $x_{1}, \ldots, x_{n}$ are defined by random number generations, this transformation performs eager sampling of $x_{i}$. The random number generation of $x_{1}, \ldots x_{n}$ must be executed at most once for each execution of program point $\mu$. This is proved by combining that the definitions of the variables $x_{1}, \ldots, x_{n}$ are in distinct branches of if, find, let with the fact that each of these definitions (at $\mu_{j}$ ) is executed at most once for each value of the current replication indices at $\mu$. To show the latter fact, we notice that, since $\mu_{j}$ is syntactically under $\mu$, the current replication indices at $\mu$ are a prefix of the replication indices at $\mu_{j}$. If the replication indices at $\mu_{j}$ are the same as at $\mu$, then the fact is proved. Otherwise, the replication indices at $\mu_{j}$ are $\widetilde{i}, \widetilde{i}_{j}$ while the replication indices at $\mu$ are $\widetilde{i}$ and we show that $\mathcal{F}_{\mu_{j}} \cup \mathcal{F}_{\mu_{j}}\left\{\widetilde{i}_{j}^{\prime} / \widetilde{i}_{j}\right\} \cup\left\{\widetilde{i}_{j} \neq \widetilde{i}_{j}^{\prime}\right\}$ yields a contradiction, where $\widetilde{i}_{j}^{\prime}$ are fresh replication indices.
- If $x_{1}, \ldots, x_{n}$ are defined by assignments of terms $M_{j}$, then all $M_{j}$ must consist of variables, function applications, and tests; there must be one $M_{j}$ defined at program point $\mu$, using all defined variables collected in $\mathcal{F}_{\mu}$ (let $M_{j_{0}}$ be that $M_{j}$, which will be used as the definition of $x$ : let $x=M_{j_{0}}$ in); and all terms $M_{j}$ must be equal: for all $j \neq j_{0}, M_{j}=M_{j_{0}}$ knowing the facts $\mathcal{F}_{\mu_{j}}$ that hold at the program point $\mu_{j}$ of $M_{j}$.
The defined conditions of find above $\mu$ are updated to syntactically guarantee the definition of $M_{j_{0}}$, as required by Invariant 2 .

Lemma 51 The transformation move up requires and preserves Properties 1, 2, 3, and 4, It preserves Property 5. If transformation move up transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, D$, EvUsed ${ }^{V}{ }_{p} G^{\prime}, D$, EvUsed, where $p$ is an upper bound of the probability of collisions eliminated
in the proof that each $\mu_{j}$ is executed at most once for each execution of $\mu$ or that for all $j \neq j_{0}$, $M_{j}=M_{j_{0}}$.

### 5.1.11 move_if_fun

The transformation move_if_fun moves the predefined function if_fun or transforms it into a term if ... then ... else... It supports the following variants:

- move_if_fun $l o c_{1} \ldots l o c_{n}$, where each $l o c_{j}$ is either a program point or a function symbol. When $l o c_{j}$ is a program point, it moves occurrences of if fun from inside the term at that program point to the root of that term. (The program point $\mu$ is designated as explained in Section 5.1.10.) When $l o c_{j}$ is a function symbol, it moves occurrences of if_fun from under that function symbol to just above it. The move corresponds to rewriting $C\left[\right.$ if_fun $\left.\left(M_{1}, M_{2}, M_{3}\right)\right]$ into if_fun $\left(M_{1}, C\left[M_{2}\right], C\left[M_{3}\right]\right)$, where $C$ is a term context built from the following grammar:

$$
\begin{aligned}
& C::= \\
& {[] } \\
& x\left[M_{1}, \ldots, M_{k-1}, C, M_{k+1}, \ldots, M_{m}\right] \\
& f\left(M_{1}, \ldots, M_{k-1}, C, M_{k+1}, \ldots, M_{m}\right)
\end{aligned}
$$

simple term context
hole
variable
function application
and the root of $C$ corresponds to a $l o c_{j}$. (It is at program point $l o c_{j}$ when $l o c_{j}$ is a program point; its root symbol is $l o c_{j}$ when $l o c_{j}$ is a function symbol.) These moves are possible only when $C$ is a simple term context, since otherwise they might lead to defining several times the same variable or repeating events since the context $C$ is duplicated in the second and third arguments of if fun and if fun evaluates all its arguments. For simplicity, we allow them only when $C\left[\operatorname{if} \_f u n\left(M_{1}, M_{2}, M_{3}\right)\right]$ is a simple term.

- move_if_fun level $n$, where $n$ is a positive integer, moves occurrences of if_fun $n$ function symbols up in the syntax tree (provided those if_fun occur under at least $n$ function symbols). As above, these moves are allowed only when they occur inside a simple term.
- move_if_fun to_term $\mu_{1} \ldots \mu_{n}$ transforms terms if_fun $\left(M_{1}, M_{2}, M_{3}\right)$ that occur at program points $\mu_{1}, \ldots, \mu_{n}$ into terms if $M_{1}$ then $M_{2}$ else $M_{3}$. When no program point is given, it performs that transformation everywhere in the game.

When $M_{2}$ and $M_{3}$ have a visible effect, that is, they define some variable with array accesses (including by their usage in various kinds of secrecy queries) or they execute events, the transformation above would not be correct, because if_fun $\left(M_{1}, M_{2}, M_{3}\right)$ evaluates both $M_{2}$ and $M_{3}$ while if $M_{1}$ then $M_{2}$ else $M_{3}$ evaluates either $M_{2}$ or $M_{3}$. In this case, we transform if fun $\left(M_{1}, M_{2}, M_{3}\right)$ into let xcond $=M_{1}$ in let xthen $=M_{2}$ in let xelse $=$ $M_{3}$ in if xcond then xthen else xelse to make sure that $M_{1}, M_{2}$, and $M_{3}$ are always evaluated, and in that order.
When autoExpand $=$ true (the default), a call to expand is automatically performed after move_if_fun, which transforms the terms let $\ldots=\ldots$ in ... and if ... then ... else ... into processes.

Lemma 52 The transformation move_if_fun requires and preserves Properties 1. 2, 3, and 4. The variants move_if_fun $l o c_{1} \ldots l o c_{n}$ and move_if_fun level $n$ preserve Property 5 . If transformation move_if_fun transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, D$, EvUsed ${ }_{\mathrm{T}_{0}} G^{\prime}, D$, EvUsed.

### 5.1.12 insert_event [27]

The transformation insert_event $e \mu$ inserts event_abort $e$ at program point $\mu$. (The program point $\mu$ is designated as explained in Section 5.1.10.

The transformation insert_event $e \mu$ also adds to query event $(e) \Rightarrow$ false in order to bound the probability of event $e$.

Lemma 53 The transformation insert_event requires and preserves Properties 1, 2, 3, and 4. It preserves Property 5 if the event is inserted at the process level. If transformation insert_event e $\mu$ transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}: G, D$, EvUsed $\xrightarrow{V} G^{\prime}, D \vee e$, EvUsed $\cup\{e\}$.

### 5.1.13 insert $[27$

The transformation insert $\mu$ ins adds instruction ins at the program point $\mu$. The program point $\mu$ is designated as explained in Section 5.1.10. The instruction ins can for instance be a test, in which case all branches of the test will be copies of the code that follows program point $\mu$ (so that the semantics of the game is unchanged). It can also be an assignment or a random generation of a fresh variable or an event_abort instruction. In all cases, CryptoVerif checks that this instruction preserves the semantics of the game except when we execute an inserted Shoup event, and rejects it with an error message if it does not.

After this transformation, insert calls auto_SArename to guarantee Property 4 .
When the user inserts event_abort $e$, the transformation insert adds a query event $(e) \Rightarrow$ false in order to bound the probability of event $e$.

When the user inserts a find[unique ${ }_{e}$ ] (the user actually types find[unique] but CryptoVerif automatically generates a fresh event $e$ and inserts find [unique $e_{e}$ ] instead, since uniqueness is not proved yet), the transformation insert adds a query event $(e) \Rightarrow$ false and calls prove_unique (Section 5.1.4) in order to try proving uniqueness.

Lemma 54 The transformation insert requires and preserves Properties 1, 2, 3, 4, and 5. If transformation insert transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, D$, EvUsed $\xrightarrow{V}_{p} G^{\prime}, D \vee e_{1} \vee$ $\cdots \vee e_{m}$, EvUsed $\cup\left\{e_{1}, \ldots, e_{m}\right\}$ where $e_{1}, \ldots, e_{m}$ are the events in the inserted instruction (event_abort $e_{j}$, find $\left[\right.$ unique $\left._{e_{j}}\right]$ ) and the probability $p$ comes from prove_unique.

### 5.1.14 replace

The transformation replace $\mu M$ replaces the term $M_{0}$ at program point $\mu$ with the term $M$. ( $M_{0}$ and $M$ must be simple. The program point $\mu$ is designated as explained in Section 5.1.10.) Before performing the replacement, it checks that $M$ is equal to $M_{0}$ at that program point (up to a small probability): first, it collects all facts $\mathcal{F}_{\mu}$ that hold at program point $\mu$; second, it tests equality between $M_{0}$ and $M$ using $\mathcal{F}_{\mu}$ and built-in equations (it uses equalities inferred from $\mathcal{F}_{\mu}$ to replace variables with their values, trying to make the terms equal); third, it simplifies $M_{0}$ and $M$ using user-defined rewrite rules of Section 3.1, and tests equality between the results using $\mathcal{F}_{\mu}$ and built-in equations; fourth, it rewrites $M_{0}$ and $M$ at most maxReplaceDepth times using equalities inferred from $\mathcal{F}_{\mu}$ and user-defined rewrite rules of Section 3.1, until it finds a common term modulo the built-in equations. The transformation is performed as soon as the equality between $M_{0}$ and $M$ is proved.

The defined conditions of find above the program point $\mu$ are updated to make sure that Invariant 2 is preserved. This is needed in particular when $M$ makes array accesses that $M_{0}$ does not make.

Lemma 55 The transformation replace requires and preserves Properties 1, 2, 3, and 4. It preserves Property 5. If transformation replace $\mu M$ transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G$, $D$, EvUsed $\xrightarrow{V}_{p} G^{\prime}, D$, EvUsed, where $p$ is an upper bound of the probability that $M$ is different from $M_{0}$ at $\mu$.

The variant assume replace $\mu M$ performs the same replacement, without checking the equality between $M_{0}$ and $M$. This transformation is obviously not sound, but can be used to experiment with modifications in the games. As soon as this transformation is used, CryptoVerif does not claim that any property is proved.

### 5.1.15 merge_branches 27

The transformation merge_branches performs the following transformations:

1. If some then branches of a find[unique] execute the same code as the else branch (up to renaming of variables defined in these branches and that do not have array accesses, and up to equality of terms proved using facts $\mathcal{F}_{\mu}$ that hold at the program point $\mu$ of the considered find[unique]), the index variables bound in these then branches have no array accesses, and the conditions of these then branches do not contain event_abort nor unproved find [unique $e_{e}$ ], then we remove these then branches.
Indeed, these then branches have the same effect as the else branch. The hypotheses are needed for the following reasons:

- The renamed variables must not have array accesses because renaming variables that have array accesses requires transforming these array accesses. The transformation merge_arrays presented in Section 5.1.16 can rename variables with array accesses.
- The index variables bound in the removed branches must not have array accesses, because removing the definitions of these variables would modify the behavior of the array accesses.
- The conditions must not contain event_abort nor unproved find[unique ${ }_{e}$ ], because if they do, the find may abort while code after transformation would not abort.

2. If all branches of if, let with pattern matching, or find execute the same code (up to renaming of variables defined in these branches and that do not have array accesses, and up to equality of terms proved using facts $\mathcal{F}_{\mu}$ that hold at the program point $\mu$ of the considered if, let, or find), and in case of find, it is not marked [unique ${ }_{e}$ ], the index variables bound in the then branches have no array accesses, and the conditions of the then branches do not contain event_abort nor unproved find[unique $e_{e}$, then we replace that if or find with its else branch.
In this transformation, we ignore the array accesses that occur in the conditions of the find under consideration, since these conditions will disappear after the transformation.

Furthermore, merge_branches applies these transformations globally to all finds of the game for which the simplification is possible. As a consequence, one can ignore array accesses to all variables in conditions of find that will be removed, so more transformations are enabled.

Lemma 56 The transformation merge_branches requires and preserves Properties 1, 2, 3, 4, and 5. If transformation merge_branches transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}: G, D$, EvUsed ${ }^{V}{ }_{p} G^{\prime}, D$, EvUsed, where $p$ is an upper bound on the probability that equalities between terms of merged branches do not hold.

### 5.1.16 merge_arrays [27]

The transformation merge_arrays $x_{11} \ldots x_{1 n}, \ldots, x_{m 1} \ldots x_{m n}$ merges the variables $x_{j 1}, \ldots$, $x_{j n}$ into a single variable $x_{j 1}$ for each $j \leq m$. Each variable $x_{j k}$ must have a single definition. For each $j \leq n$, the variables $x_{j 1}, \ldots, x_{j n}$ must have the same type and indices of the same type. They must not be defined for the same value of their indices (that is, $x_{j k}$ and $x_{j k^{\prime}}$ must be defined in different branches of if or find when $k \neq k^{\prime}$ ). The arrays $x_{j 1}, \ldots, x_{j n}$ are merged into a single array $x_{j 1}$ for each $j \leq m$. The transformation proceeds as follows:

- If, for each $k \leq n, x_{1 k}$ is defined above $x_{j k}$ for all $1<j<m$, we introduce a fresh variable $b_{k}$ defined by $\bar{b}_{k} \leftarrow$ mark just after the definition of $x_{1 k}$. We call $b_{k}$ a branch variable; it is used to detect that $x_{j k}$ has been defined: $x_{j k}[\tilde{M}]$ is defined before the transformation if and only if $x_{j 1}[\tilde{M}]$ and $b_{k}[\tilde{M}]$ are defined after the transformation, and $x_{j 1}[\tilde{M}]$ after the transformation is equal to $x_{j k}[\tilde{M}]$ before the transformation.
- For each find that requires that some variables $x_{j k}$ are defined, we leave the branches that do not require the definition of $x_{j k}$ unchanged and we try to transform the other branches $F B_{l}=\left(\tilde{u}_{l}=\tilde{i}_{l} \leq \tilde{n}_{l}\right.$ suchthat defined $\left(\tilde{M}_{l}\right) \wedge M_{l}$ then $\left.P_{l}\right)$ as follows.

1. We require that, for each $l$, there exists a distinct $k$ such that the defined condition of $F B_{l}$ refers to $x_{j k}$ for some $j$ but not to $x_{j k^{\prime}}$ for any other $k^{\prime}$. (Otherwise, the transformation fails.) We denote by $l(k)$ the value of $l$ that corresponds to $k$.
2. We choose a "target" branch $F B_{\mathrm{T}}=(\tilde{u}=\tilde{i} \leq \tilde{n}$ suchthat defined $(\tilde{M}) \wedge M$ then $P)$ : if the defined condition of some branch $F B_{l}$ refers to $x_{j 1}$ for some $j$, we choose that branch $F B_{l}$. Otherwise, we choose any branch $F B_{l}$ and rename its variables $x_{j k}$ to $x_{j 1}$. We require that the references $x_{j 1}[\tilde{M}]$ to the variables $x_{j 1}$ in the defined condition of the target branch all have the same indices $\tilde{M}$. If the transformation succeeds, we will replace all branches $F B_{l}$ with the target branch.
3. The branch $F B_{\mathrm{T}}$ after transformation is equivalent to branches $\bigoplus_{k=1}^{n} F B_{\mathrm{T}}\left\{x_{j k} / x_{j 1}\right.$, $j=1, \ldots, m\}$ before transformation. We show that these branches are equivalent to the branches $F B_{l}$.
For each $k \leq n$,

- if $l(k)$ exists, then we show that $F B_{\mathrm{T}}\left\{x_{j k} / x_{j 1}, j=1, \ldots, m\right\}$ is equivalent to $F B_{l(k)}$. Let $l=l(k)$. We first rename the variables $\tilde{u}_{l}$ of $F B_{l}$ to the variables $\tilde{u}$ of the target branch. For simplicity, we still denote by $F B_{l}=\left(\tilde{u}_{l}=\tilde{i}_{l} \leq \tilde{n}_{l}\right.$ suchthat defined $\left(\tilde{M}_{l}\right) \wedge M_{l}$ then $\left.P_{l}\right)$ the obtained branch. Then we show that, if the variables of $\tilde{M}_{l}$ are defined, then the variables of $\tilde{M}\left\{x_{j k} / x_{j 1}, j=1, \ldots, m\right\}$ are defined, and conversely; $M_{l}=M\left\{x_{j k} / x_{j 1}, j=1, \ldots, m\right\}$ (knowing the equalities that hold at that program point), and $P_{l}$ and $P\left\{x_{j k} / x_{j 1}, j=1, \ldots, m\right\}$ execute the same code up to renaming of variables defined in $P_{l}$ or $P\left\{x_{j k} / x_{j 1}, j=1, \ldots, m\right\}$ and that do not have array accesses, and up to equality of terms proved using facts $\mathcal{F}_{\mu}$ that hold at the program point $\mu$ of the considered find.
- if $l(k)$ does not exist, then we show that $F B_{\mathrm{T}}\left\{x_{j k} / x_{j 1}, j=1, \ldots, m\right\}$ can in fact not be executed, because its condition cannot hold: the variables of $\tilde{M}\left\{x_{j k} / x_{j 1}\right.$, $j=1, \ldots, m\}$ cannot be simultaneously defined or $M\left\{x_{j k} / x_{j 1}, j=1, \ldots, m\right\}$ cannot hold.

If the transformation above fails and we have introduced branch variables, we replace each condition defined $\left(x_{j k}[\tilde{M}]\right)$ with defined $\left(x_{j 1}[\tilde{M}], b_{k}[\tilde{M}]\right)$.

If the transformation above fails and we have not introduced branch variables, the whole merge_arrays transformation fails.

- The definition of $x_{j k}$ is renamed to $x_{j 1}$ and each reference to $x_{j k}[\tilde{M}]$ is renamed to $x_{j 1}[\tilde{M}]$.

Lemma 57 The transformation merge_arrays requires and preserves Properties 1, 2, 3, 4, and 5. If transformation merge_arrays transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, D$, EvUsed $\longrightarrow_{p} G^{\prime}, D$, EvUsed, where $p$ is an upper bound on the probability that required equalities do not hold.

### 5.1.17 guess $i$

When guessRemoveUnique $=$ true and some (one-session) secrecy queries are present, the transformation guess $i$ first transforms the game $G$ into $G_{\mathrm{RU}}$, by replacing all proved find[unique] with find. Lemma 58 shows the soundness of this preliminary transformation. It may be advantageous for (one-session) secrecy proofs because the removed find[unique] do not need to be proved, while the remaining ones must be reproved after the transformation, as we show below.

Lemma 58 Let $G_{\mathrm{RU}}$ be the game obtained from $G$ by replacing all proved find[unique] with find. Let sp be a security property (sp is 1 -ses.secr. $(x)$, Secrecy $(x)$, bit secr. $(x)$, or a correspondence $\varphi$, which does not use $\mathrm{S}, \overline{\mathrm{S}}$, nor non-unique events). Let $D$ be a disjunction of Shoup events and a subset of non-unique events $e_{i}$ corresponding to unproved find[unique ${ }_{e_{i}}$ ] in $G$ ( $D$ does not contain S nor $\overline{\mathrm{S}})$. If $\operatorname{Bound}_{G_{\mathrm{RU}}}(V, s p, D, p)$, then $\operatorname{Bound}_{G}(V, s p, D, p)$.

Proof Let $C^{\prime}$ be an evaluation context acceptable for $C_{s p}[G]$ with public variables $V \backslash V_{s p}$ that does not contain events used by $s p$ or $D$ nor non-unique events in $G$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Let $C=C^{\prime}\left[C_{s p}[]\right]$. The context $C^{\prime}$ is also acceptable for $C_{s p}\left[G_{\mathrm{RU}}\right]$ with public variables $V \backslash V_{s p}$, and a fortiori does not contain non-unique events in $G_{\mathrm{RU}}$. Since Bound ${ }_{G_{\mathrm{RU}}}(V, s p, D, p)$, we have $\operatorname{Adv}_{G_{\mathrm{RU}}}(\mathcal{A}, C, s p, D) \leq p(\mathcal{A}, C)$.

First case: $s p$ is a correspondence $\varphi$. We have

$$
\begin{aligned}
\operatorname{Adv}_{G}(\mathcal{A}, C, s p, D) & =\operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \operatorname{NonUnique~}_{G, D}\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{\mathrm{RU}}\right]:(\neg \varphi \vee D) \wedge \neg \operatorname{NonUnique}_{G_{\mathrm{RU}}, D}\right]=\operatorname{Adv}_{G_{\mathrm{RU}}}(\mathcal{A}, C, s p, D)
\end{aligned}
$$

because traces of $G$ that satisfy $(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G, D}$ correspond to similar traces of $G_{\mathrm{RU}}$ that satisfy $(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G_{\mathrm{RU}}, D}$. Only traces that satisfy $e$ for some proved find[unique ${ }_{e}$ ] in $G$ are mapped to different traces in $G_{\mathrm{RU}}$. These traces satisfy NonUnique ${ }_{G, D}$.

Second case: $s p$ is 1 -ses.secr. $(x)$, $\operatorname{Secrecy}(x)$, or bit secr. $(x)$. We have

$$
\operatorname{Pr}^{\mathcal{A}}[C[G]: \mathrm{S} \vee D] \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{\mathrm{RU}}\right]: \mathrm{S} \vee D\right]
$$

since the traces of $C[G]$ that execute an event in $\mathrm{S} \vee D$ correspond to similar traces of $C\left[G_{\mathrm{RU}}\right]$ that also execute an event in $\mathrm{S} \vee D(\mathrm{~S} \vee D$ does not contain any proved non-unique event of $G)$, and

$$
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{\mathrm{RU}}\right]: \overline{\mathrm{S}} \vee \text { NonUnique }_{G_{\mathrm{RU}}, D}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C[G]: \overline{\mathrm{S}} \vee \text { NonUnique }_{G, D}\right]
$$

since the traces of $C\left[G_{\mathrm{RU}}\right]$ that execute $\overline{\mathrm{S}}$ or an event in NonUnique ${G_{\mathrm{RU}}, D}$ correspond to either to similar traces of $C[G]$ that execute the same event or to traces that execute a proved non-unique
event in $C[G]$, so an event in NonUnique ${ }_{G, D}$. Therefore,

$$
\begin{aligned}
\operatorname{Adv}_{G}(\mathcal{A}, C, s p, D) & =\operatorname{Pr}^{\mathcal{A}}[C[G]: \mathrm{S} \vee D]-\operatorname{Pr}^{\mathcal{A}}\left[C[G]: \overline{\mathrm{S}} \vee \text { NonUnique }_{G, D}\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{\mathrm{RU}}\right]: \mathrm{S} \vee D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{\mathrm{RU}}\right]: \overline{\mathrm{S}} \vee \text { NonUnique }_{G_{\mathrm{RU}}, D}\right] \\
& \leq \operatorname{Adv}_{G_{\mathrm{RU}}}(\mathcal{A}, C, s p, D)
\end{aligned}
$$

In both cases, we obtain $\operatorname{Adv}_{G}(\mathcal{A}, C, s p, D) \leq p(\mathcal{A}, C)$ and $\operatorname{Bound}_{G}(V, s p, D, p)$.
Next, the main guessing transformation is performed. The transformation guess $i$ consists in guessing the tested session of a principal in a protocol, which is a step frequently done in cryptographic proofs. In CryptoVerif, we consider a game $G$ and define a transformed game $G^{\prime}$ by guessing a replication index $i$ : we replace foreach $i \leq n$ do $Q$ with foreach $i \leq n$ do $Q^{\prime}$ where $Q^{\prime}$ is obtained from $Q$ by replacing the processes $P$ under the first inputs with if $i=i_{\text {tested }}$ then $P^{\prime}$ else $P^{\prime \prime}$ and $i_{\text {tested }}$ is a constant. The constant $i_{\text {tested }}$ is the index of the tested session. We distinguish the process executed in the tested session, $P^{\prime}$, on which we are going to prove security properties, from the process $P^{\prime \prime}$ for other sessions which are executed, but for which we do not prove security properties. (In case diff_constants $=$ true, the constant $i_{\text {tested }}$ must not be considered different from other constants of the same type.) The process $P^{\prime}$ is obtained from $P$ by

- duplicating all events: event $e(\widetilde{M})$ is replaced with event $e(\widetilde{M})$; event $e^{\prime}(\widetilde{M})$ and similarly event_abort $e$ is replaced with event $e$; event_abort $e^{\prime}$. We require that in the game $G$, the same event $e$ cannot occur both under the modified replication foreach $i \leq n$ do $Q$ and elsewhere in the game. (Otherwise, queries that use $e$ are left unchanged.)
- duplicating definitions of every variable $x$ used in queries for secrecy and one-session secrecy: let $x^{\prime}=x$ in is added after each definition of $x$. We require that in the game $G$, the same variable $x$ used in queries for secrecy or one-session secrecy cannot be defined both under the modified replication foreach $i \leq n$ do $Q$ and elsewhere in the game. (Otherwise, the considered query is left unchanged.)

The process $P^{\prime \prime}$ is obtained from $P$ by duplicating definitions of every variable $x$ used in queries for secrecy (not one-session secrecy): let $x^{\prime \prime}=x$ in is added after each definition of $x$.

We replace variables $x$ in secrecy and one-session secrecy queries with their duplicated version $x^{\prime}$. For secrecy queries, the duplicated version $x^{\prime \prime}$ is added to public variables. In both cases, we prove (one-session) secrecy for the variable $x^{\prime}$ defined in the tested session. In case of one-session secrecy, that is enough: it shows that $x^{\prime}$ is indistinguishable from a random value, and that proves one-session secrecy of $x$ for all sessions by symmetry. However, for secrecy, we additionally want to show that the values of $x$ in the various sessions are independent of each other; this is achieved by considering the value of $x$ in sessions other than the tested session (that is, $x^{\prime \prime}$ ) as public: if $x^{\prime}$ is indistinguishable from random even when $x^{\prime \prime}$ is public, then $x^{\prime}$ is independent of $x^{\prime \prime}$.

In non-injective correspondence queries, we replace one non-injective event $e$ before the arrow $\Rightarrow$ with its duplicated version $e^{\prime}$. Hence, we prove the query for the tested session, which uses event $e^{\prime}$. The proof is valid for all sessions by symmetry.

The probability of attack must basically be multiplied by $n$ for all modified queries. The proof depends on the considered query and is detailed below.

For queries that are left unchanged, i.e. secrecy and one-session secrecy queries for variables not defined under the modified replication, non-injective correspondence queries with no event before the arrow $\Rightarrow$ under the modified replication (the previous queries prove properties about other roles than the one for which we guess the tested session), bit secrecy queries (because
the secret is defined under no replication, so it is not under the guessed replication), as well as injective correspondence queries (see details below), the probability is unchanged. It is clear that these queries are not affected by the transformation.

After this transformation, guess calls auto_SArename to guarantee Property 4

Lemma 59 The transformation guess i requires and preserves Properties 1, 2, 3, and 4 It preserves Property 5.

Suppose the game $G$ is transformed into $G^{\prime}$ by the transformation guess $i$, where $i$ is a replication index bounded by n. Below, we consider only the modified queries.

Let $\varphi$ and $\varphi^{\prime}$ be respectively the semantics of a non-injective correspondence and its transformed correspondence. If $\operatorname{Bound}_{G^{\prime}}\left(V, \varphi^{\prime}, D_{\text {false }}, p\right)$ and $p$ is independent of the value of $i_{\text {tested }}$, then Bound $_{G}\left(V, \varphi, D_{\text {false }}, n p\right)$.

If $G^{\prime}$ satisfies the one-session secrecy of $x^{\prime}$ with public variables $V\left(x, x^{\prime}, x^{\prime \prime} \notin V\right)$ up to probability $p$ and $p$ is independent of the value of $i_{\text {tested }}$, then $G$ satisfies the one-session secrecy of $x$ with public variables $V$ up to probability $n p$.

If $G^{\prime}$ satisfies the secrecy of $x^{\prime}$ with public variables $V \cup\left\{x^{\prime \prime}\right\}\left(x, x^{\prime}, x^{\prime \prime} \notin V\right)$ up to probability $p$ and $p$ satisfies Property [6, then $G$ satisfies the secrecy of $x$ with public variables $V$ up to probability $n \times p$ (neglecting a small additional runtime of the context).

If $\operatorname{Bound}_{G^{\prime}}\left(V \cup\left\{x^{\prime}\right\}, 1\right.$-ses.secr. $\left(x^{\prime}\right)$, NonUnique $\left.{ }_{G^{\prime}}, p\right)$ and $p$ satisfies Property 6, then we have Bound $_{G}\left(V \cup\{x\}, 1\right.$-ses.secr. $\left.(x), D_{\text {false }}, n p\right)$.

If Bound $_{G^{\prime}}\left(V \cup\left\{x^{\prime}, x^{\prime \prime}\right\}\right.$, $\operatorname{Secrecy}\left(x^{\prime}\right)$, NonUnique $\left.{ }_{G^{\prime}}, p\right)$ and $p$ satisfies Property $\sqrt{6}$, then we have $\operatorname{Bound}_{G}\left(V \cup\{x\}\right.$, Secrecy $\left.(x), D_{\text {false }}, n p\right)$ (neglecting a small additional runtime of the context).

Property 6 guarantees that $p$ is independent of the value of $i_{\text {tested }}$, as well as other independence conditions needed for secrecy and for the properties on Bound because we modify the context in the proof. Since the third argument of Bound is always $D_{\text {false }}$ in the conclusion of Lemma 59, we cannot use the optimization of considering the disjunction of several properties simultaneously, as outlined in Section 2.8.4 we must consider each property and event separately. Indeed, if we applied guessing to several properties at once, we might need to guess the tested session for each property, which would introduce several factors $n$. Since the third argument of Bound is NonUnique ${ }_{G^{\prime}}$ in the hypothesis of Lemma 59 for (one-session) secrecy properties, uniqueness of find [unique $e_{e}$ ] must be reproved in game $G^{\prime}$ after the guess transformation (that is, the probability that these find [unique $e_{e}$ ] have several successful choices must be bounded again in $\left.G^{\prime}\right)$.

## Proof

Non-injective correspondences We suppose that the events under the transformed replication contain as argument the replication index $i$ of that replication. (CryptoVerif implicitly adds the current program point and replication indices to each event, and uses fresh distinct variables for the added replication indices in the queries. That does not change the meaning of the query.)

Let $\forall i_{0}:[1, n], \widetilde{x}: \widetilde{T} ; \operatorname{event}(e(\widetilde{M})) \wedge \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$ be the initial query and $\forall i_{0}:[1, n], \widetilde{x}:$ $\widetilde{T} ; \operatorname{event}\left(e^{\prime}(\widetilde{M})\right) \wedge \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi$ be the transformed query, where $\left\{i_{0}, \widetilde{x}\right\}=\operatorname{var}\left(\operatorname{event}\left(e^{\prime}(\widetilde{M})\right) \wedge \psi\right)$, $\widetilde{y}=\operatorname{var}(\phi) \backslash \operatorname{var}\left(\operatorname{event}\left(e^{\prime}(\widetilde{M})\right) \wedge \psi\right)$, and $i_{0}$ be the variable for the index of the transformed replication in $\widetilde{M}$.

Let $C$ be an evaluation context acceptable for $G$ with public variables $V$ that does not contain
events used by $\varphi$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$.

$$
\begin{aligned}
\operatorname{Adv}_{G}\left(\mathcal{A}, C, \varphi, D_{\text {false }}\right)= & \operatorname{Pr}^{\mathcal{A}}\left[C[G]: \neg \varphi \wedge \neg \text { NonUnique }_{G}\right] \\
& =\operatorname{Pr}^{\mathcal{A}}\left[\begin{array}{c}
C[G]:\left(\exists i_{0} \in[1, n], \exists \widetilde{x} \in \widetilde{T}, \text { event }(e(\widetilde{M}))\right. \\
\left.\wedge \psi \wedge \neg \exists \widetilde{y} \in \widetilde{T^{\prime}}, \phi\right) \wedge \neg \text { NonUnique }_{G}
\end{array}\right] \\
= & \sum_{i_{\text {val }}=1}^{n} \operatorname{Pr}^{\mathcal{A}}\left[\begin{array}{c}
C[G]:\left(\exists i_{0} \in[1, n], \exists \widetilde{x} \in \widetilde{T}, i_{0}=i_{\text {val }} \wedge \text { event }(e(\widetilde{M}))\right. \\
\left.\wedge \psi \wedge \neg \exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi\right) \wedge \neg \operatorname{NonUnique~}_{G}
\end{array}\right] \\
& =\sum_{i_{\text {val }}=1}^{n} \operatorname{Pr}^{\mathcal{A}}\left[\begin{array}{c}
C\left[G^{\prime}\right]:\left(\exists i_{0} \in[1, n], \exists \widetilde{x} \in \widetilde{T}, \text { event }\left(e^{\prime}(\widetilde{M})\right)\right. \\
\left.\wedge \psi \wedge \neg \exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi\right) \wedge \neg \operatorname{NonUnique}_{G^{\prime}}
\end{array}\right] \text { for } i_{\text {tested }}=i_{\text {val }} \\
= & \sum_{i_{\text {val }}=1}^{n} \operatorname{Adv}_{G^{\prime}}\left(\mathcal{A}, C, \varphi^{\prime}, D_{\text {false }}\right) \text { for } i_{\text {tested }}=i_{\text {val }}
\end{aligned}
$$

Since $\operatorname{Bound}_{G^{\prime}}\left(V, \varphi^{\prime}, D_{\text {false }}, p\right)$, we have $\operatorname{Adv}_{G^{\prime}}\left(\mathcal{A}, C, \varphi^{\prime}, D_{\text {false }}\right) \leq p(\mathcal{A}, C)$ and the probability $p$ is independent of the value of $i_{\text {tested }}$, so we obtain $\operatorname{Adv}_{G}\left(\mathcal{A}, C, \varphi, D_{\text {false }}\right) \leq n \times p(\mathcal{A}, C)$. Therefore Bound $_{G}\left(V, \varphi, D_{\text {false }}, n p\right)$.

One-session secrecy Let $C$ be an evaluation context acceptable for $C_{1 \text {-ses.secr. }(x)}[G]$ with public variables $V$ that does not contain S nor $\overline{\mathrm{S}}$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Suppose that the modified replication corresponds to the $j$-th index of variable $x$. We have

$$
\begin{aligned}
\operatorname{Adv}_{G}^{1 \text {-ses.secr. }(x)}(\mathcal{A}, C)= & \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr. }(x)}[G]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr.(x) }}[G]\right]: \overline{\mathrm{S}}\right] \\
& =\sum_{v=1}^{n} \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr. }(x)}[G]\right]: \mathrm{S} \wedge \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr.(x) }}[G]\right]: \overline{\mathrm{S}} \wedge u_{j}=v\right]\right. \\
& =\sum_{v=1}^{n} \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr. }\left(x^{\prime}\right)}\left[G^{\prime}\right]\right]: \mathrm{S} \wedge \operatorname{Pr}_{j}\left[C\left[C_{1 \text {-ses.secr. }\left(x^{\prime}\right)}\left[G^{\prime}\right]\right]: \overline{\mathrm{S}} \wedge u_{j}=v\right] \quad \text { for } i_{\text {tested }}=v\right.
\end{aligned}
$$

because in $G^{\prime}$ with $i_{\text {tested }}=v, x^{\prime}\left[u_{1}, \ldots, u_{m}\right]=x\left[u_{1}, \ldots, u_{m}\right]$ when $u_{j}=v$, so $C_{1 \text {-ses.secr. }(x)}[G]$ behaves like $C_{1 \text {-ses.secr. (x }}$ ) $\left[G^{\prime}\right]$ (the events added in $G^{\prime}$ are not used).

Moreover, $\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr. }\left(x^{\prime}\right)}\left[G^{\prime}\right]\right]: \mathrm{S} \wedge\left(u_{j}\right.\right.$ not defined $\left.\left.\vee u_{j} \neq v\right)\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{\left.1 \text {-ses.secr.( } x^{\prime}\right)}\left[G^{\prime}\right]\right]:\right.$ $\overline{\mathrm{S}} \wedge\left(u_{j}\right.$ not defined $\left.\left.\vee u_{j} \neq v\right)\right]$ when $i_{\text {tested }}=v$. Indeed, when $u_{j}$ is not defined or $u_{j} \neq v=i_{\text {tested }}$, the query on $O_{s}$ either is not executed or always yields, independently of the value of $b$. Hence, changing the value of $b$ just swaps the events $S$ and $\bar{S}$. So

$$
\begin{gathered}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr. }\left(x^{\prime}\right)}\left[G^{\prime}\right]\right]: \mathrm{S} \wedge\left(u_{j} \text { not defined } \vee u_{j} \neq v\right) \wedge b=\text { true }\right]= \\
\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr. }\left(x^{\prime}\right)}\left[G^{\prime}\right]\right]: \overline{\mathrm{S}} \wedge\left(u_{j} \text { not defined } \vee u_{j} \neq v\right) \wedge b=\text { false }\right] \\
\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr. }\left(x^{\prime}\right)}\left[G^{\prime}\right]\right]: \overline{\mathrm{S}} \wedge\left(u_{j} \text { not defined } \vee u_{j} \neq v\right) \wedge b=\text { true }\right]= \\
\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{1 \text {-ses.secr. }\left(x^{\prime}\right)}\left[G^{\prime}\right]\right]: \mathrm{S} \wedge\left(u_{j} \text { not defined } \vee u_{j} \neq v\right) \wedge b=\text { false }\right] .
\end{gathered}
$$

We obtain the announced result by swapping the two sides of the second equality and adding the first equality to it. (The variable $b$ is always defined when S or $\overline{\mathrm{S}}$ is executed.)

Therefore,

$$
\begin{aligned}
\operatorname{Adv}_{G}^{1-\text { ses.secr. }(x)}(\mathcal{A}, C)= & \sum_{v=1}^{n} \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{\left.1 \text {-ses.secr.( } x^{\prime}\right)}\left[G^{\prime}\right]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{\left.1 \text {-ses.secr.( } x^{\prime}\right)}\left[G^{\prime}\right]\right]: \overline{\mathrm{S}}\right] \\
& \text { for } i_{\text {tested }}=v \\
= & \sum_{v=1}^{n} \operatorname{Adv}_{G^{\prime}}^{\left.1-\text { ses.secr.( } x^{\prime}\right)}(\mathcal{A}, C) \text { for } i_{\text {tested }}=v
\end{aligned}
$$

Since $G^{\prime}$ satisfies the one-session secrecy of $x^{\prime}$ with public variables $V$ up to probability $p$, we have $\operatorname{Adv}_{G^{\prime}}^{1 \text {-ses.secr. }\left(x^{\prime}\right)}(\mathcal{A}, C) \leq p(\mathcal{A}, C)$ and the probability $p$ is independent of the value of $i_{\text {tested }}$, so we obtain $\operatorname{Adv}_{G}^{1 \text {-ses.secr. }(x)}(\mathcal{A}, C) \leq n \times p(\mathcal{A}, C)$. Therefore, $G$ satisfies the one-session secrecy of $x$ with public variables $V$ up to probability $n p$.

Secrecy Let $C$ be an evaluation context acceptable for $C_{\text {Secrecy }(x)}[G]$ with public variables $V$ that does not contain $S$ nor $\bar{S}$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Suppose that the modified replication corresponds to the $j$-th index of variable $x$. We have

$$
\begin{aligned}
& \operatorname{Adv}_{G} \operatorname{Secrecy~}(x)^{(\mathcal{A}, C)} \\
& \quad=\frac{1}{2}\binom{\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x)}\right]: \mathrm{S} \mid b=\text { true }\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x)}\right]: \mathrm{S} \mid b=\text { false }\right]}{-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x)}\right]: \overline{\mathrm{S}} \mid b=\text { true }\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x)}\right]: \overline{\mathrm{S}} \mid b=\text { false }\right]}
\end{aligned}
$$

Let

$$
\begin{aligned}
Q_{\text {Secrecy }(x), \text { real }}= & O_{s 0}():=\text { return }() ; \\
& \left(\text { foreach } i_{s} \leq n_{s} \text { do } O_{s}\left[i_{s}\right]\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):=\right. \\
& \text { if defined }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \text { then } \\
& \text { return }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \\
& \left.\mid O_{s}^{\prime}\left(b^{\prime}: \text { bool }\right):=\text { if } b^{\prime} \text { then event_abort } S \text { else event_abort } \overline{\mathrm{S}}\right) \\
Q_{\text {Secrecy }(x), \text { random }}= & O_{s 0}():=\operatorname{return}() ; \\
& \left(\text { foreach } i_{s} \leq n_{s} \text { do } O_{s}\left[i_{s}\right]\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):=\right. \\
& \text { if defined }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \text { then } \\
& \text { find } u_{s}^{\prime}=i_{s}^{\prime} \leq n_{s} \text { suchthat defined }\left(y\left[i_{s}^{\prime}\right], u_{1}\left[i_{s}^{\prime}\right], \ldots, u_{m}\left[i_{s}^{\prime}\right]\right) \wedge \\
& u_{1}\left[i_{s}^{\prime}\right]=u_{1} \wedge \ldots \wedge u_{m}\left[i_{s}^{\prime}\right]=u_{m} \\
& \text { then return }\left(y\left[u_{s}^{\prime}\right]\right) \\
& \text { else } y R_{\leftarrow}^{R} T ; \text { return }(y) \\
& \left.O S^{\prime}\left(b^{\prime}: \text { bool }\right):=\text { if } b^{\prime} \text { then event_abort } \mathrm{S} \text { else event_abort } \overline{\mathrm{S}}\right)
\end{aligned}
$$

Then

$$
\operatorname{Adv}_{G}^{\text {Secrecy }(x)}(\mathcal{A}, C)=\frac{1}{2}\binom{\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x) \text {,real }}\right]: \mathrm{S}\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), \text { random }}\right]: \overline{\mathrm{S}}\right]}{-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), \text { real }}\right]: \overline{\mathrm{S}}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), \text { random }}\right]: \mathrm{S}\right]}
$$

Let

$$
\begin{aligned}
Q_{\text {Secrecy }(x), v}= & O_{s 0}():=\operatorname{return}() ; \\
& \left(\text { foreach } i_{s} \leq n_{s} \text { do } O_{s}\left[i_{s}\right]\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):=\right. \\
& \text { if defined }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \text { then } \\
& \text { if } u_{j} \leq v \text { then return }\left(x\left[u_{1}, \ldots, u_{m}\right]\right) \text { else } \\
& \text { find } u_{s}^{\prime}=i_{s}^{\prime} \leq n_{s} \text { suchthat defined }\left(y\left[i_{s}^{\prime}\right], u_{1}\left[i_{s}^{\prime}\right], \ldots, u_{m}\left[i_{s}^{\prime}\right]\right) \wedge \\
& u_{1}\left[i_{s}^{\prime}\right]=u_{1} \wedge \ldots \wedge u_{m}\left[i_{s}^{\prime}\right]=u_{m} \\
& \text { then return }\left(y\left[u_{s}^{\prime}\right]\right) \\
& \text { else } y \stackrel{R}{\leftarrow} T ; \text { return }(y) \\
& \left.\mid O_{s}^{\prime}\left(b^{\prime}: \text { bool }\right):=\text { if } b^{\prime} \text { then event_abort } \mathrm{S} \text { else event_abort } \overline{\mathrm{S}}\right)
\end{aligned}
$$

The process $Q_{\text {Secrecy }(x), 0}$ behaves like $Q_{\text {Secrecy }(x), \text { random }}$ and $Q_{\text {Secrecy }(x), n}$ behaves like $Q_{\text {Secrecy }(x), \text { real }}$ $\left(n_{j}=n\right)$. Therefore,

$$
\begin{aligned}
\operatorname{Adv}_{G}^{\text {Secrecy }(x)}(\mathcal{A}, C) & =\frac{1}{2}\binom{\left(\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), n}\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), 0}\right]: \mathrm{S}\right]\right)}{-\left(\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), n}\right]: \overline{\mathrm{S}}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), 0}\right]: \overline{\mathrm{S}}\right]\right)} \\
& =\frac{1}{2}\binom{\sum_{v=1}^{n}\left(\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), v}\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), v-1}\right]: \mathrm{S}\right]\right)}{-\sum_{v=1}^{n}\left(\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), v}\right]: \overline{\mathrm{S}}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), v-1}\right]: \overline{\mathrm{S}}\right]\right)}
\end{aligned}
$$

We define a context $C_{v}^{\prime}$ that returns a random value for $u_{j}>v$, the real value of $x$ obtained from the public variable $x^{\prime \prime}$ in $G^{\prime}$ for $u_{j}<v$, and calls $Q_{\text {Secrecy }\left(x^{\prime}\right) \text {,real }}$ or $Q_{\text {Secrecy }\left(x^{\prime}\right) \text {,random }}$ for $u_{j}=v$.

$$
\begin{aligned}
& C_{v}^{\prime}=\text { new } O \text { racle } O_{s 1} ;\left([] \mid \text { foreach } i_{s} \leq n_{s} \text { do } O_{s}\left[i_{s}\right]\left(u_{1}:\left[1, n_{1}\right], \ldots, u_{m}:\left[1, n_{m}\right]\right):=\right. \\
& \text { if } \left.u_{j}=v \text { then (let } z: T=O_{s 1}\left[i_{s}\right]\left(u_{1}, \ldots, u_{m}\right) \text { in return }(z)\right) \text { else } \\
& \text { if defined }\left(x^{\prime \prime}\left[u_{1}, \ldots, u_{m}\right]\right) \text { then } \\
& \text { if } u_{j}<v \text { then return }\left(x^{\prime \prime}\left[u_{1}, \ldots, u_{m}\right]\right) \text { else } \\
& \text { find } u_{s}^{\prime}=i_{s}^{\prime} \leq n_{s} \text { suchthat defined }\left(y\left[i_{s}^{\prime}\right], u_{1}\left[i_{s}^{\prime}\right], \ldots, u_{m}\left[i_{s}^{\prime}\right]\right) \wedge \\
& \quad u_{1}\left[i_{s}^{\prime}\right]=u_{1} \wedge \ldots \wedge u_{m}\left[i_{s}^{\prime}\right]=u_{m} \\
& \text { then return }\left(y\left[u_{s}^{\prime}\right]\right) \\
& \quad \text { else } y \stackrel{R}{\leftarrow} T ; \text { return }(y))
\end{aligned}
$$

where the processes $Q_{\text {Secrecy }\left(x^{\prime}\right) \text {,real }}$ and $Q_{\text {Secrecy }\left(x^{\prime}\right) \text {,random }}$ use oracle $O_{s 1}$ instead of $O_{s}$. When $u_{j}=v$, the query on $O_{s}\left[i_{s}\right]$ is forwarded to $Q_{\text {Secrecy }\left(x^{\prime}\right) \text {,real }}$ (resp. $Q_{\text {Secrecy }\left(x^{\prime}\right), \text { random }}$ ) on oracle $O_{s 1}\left[i_{s}\right]$. The values of $x$ for sessions other than $v$ are collected in $x^{\prime \prime}$ by $G^{\prime}$; these are the values returned by the query on $O_{s}\left[i_{s}\right]$ when $u_{j}<v$. Finally, when $u_{j}>v$, the query on $O_{s}\left[i_{s}\right]$ is answered with a random value $y$.

Then

$$
\begin{aligned}
& \operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), v}\right]: \mathrm{S}\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{v}^{\prime}\left[G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right), \text { real }}\right]\right]: \mathrm{S}\right], \\
& \operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), v}\right]: \overline{\mathrm{S}}\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{v}^{\prime}\left[G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right), \text { real }}\right]\right]: \overline{\mathrm{S}}\right], \\
& \operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), v-1}\right]: \mathrm{S}\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{v}^{\prime}\left[G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right), \text { random }}\right]\right]: \mathrm{S}\right], \text { and } \\
& \operatorname{Pr}^{\mathcal{A}}\left[C\left[G \mid Q_{\text {Secrecy }(x), v-1}\right]: \overline{\mathrm{S}}\right]=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{v}^{\prime}\left[G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right), \text { random }}\right]\right]: \overline{\mathrm{S}}\right],
\end{aligned}
$$

for $i_{\text {tested }}=v$.
Then

$$
\begin{aligned}
& \operatorname{Adv}_{G}^{\text {Secrecy }(x)}(\mathcal{A}, C) \\
& \quad=\sum_{v=1}^{n} \frac{1}{2}\binom{\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{v}^{\prime}\left[G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right), \text { real }}\right]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{v}^{\prime}\left[G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right), \text { random }}\right]\right]: \mathrm{S}\right]}{-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{v}^{\prime}\left[G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right), \text { real }}\right]\right]: \overline{\mathrm{S}}\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{v}^{\prime}\left[G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right), \text { random }}\right]\right]: \overline{\mathrm{S}}\right]} \\
& \quad \text { for } i_{\text {tested }}=v \\
& =\sum_{v=1}^{n} \operatorname{Adv}_{G^{\prime}}^{\text {Secrecy }\left(x^{\prime}\right)}\left(\mathcal{A}, C\left[C_{v}^{\prime}\right]\right) \text { for } i_{\text {tested }}=v
\end{aligned}
$$

by the link between the advantage for secrecy and $Q_{\text {Secrecy }\left(x^{\prime}\right), \text { real }}, Q_{\text {Secrecy }\left(x^{\prime}\right) \text {,random }}$ shown above. Since $G^{\prime}$ satisfies the secrecy of $x^{\prime}$ with public variables $V \cup\left\{x^{\prime \prime}\right\}$ up to probability $p$ and $C\left[C_{v}^{\prime}\right]$ is an evaluation context acceptable for $G^{\prime} \mid Q_{\text {Secrecy }\left(x^{\prime}\right)}$ with public variables $V \cup\left\{x^{\prime \prime}\right\}$ that does not contain S nor $\overline{\mathrm{S}}$, we have $\operatorname{Adv}_{G^{\prime}}^{\operatorname{Secrecy}\left(x^{\prime}\right)}\left(\mathcal{A}, C\left[C_{v}^{\prime}\right]\right) \leq p\left(\mathcal{A}, C\left[C_{v}^{\prime}\right]\right)$. Moreover, by Property 6 , the probability $p\left(\mathcal{A}, C\left[C_{v}^{\prime}\right]\right)$ is independent of $i_{\text {tested }}=v$ (because the type of $i_{\text {tested }}$ is bounded) and depends only on the runtime of $C$, the number of calls $C$ makes to the various oracles (which determine replication bounds), and the length of bitstrings, so we have $p\left(\mathcal{A}, C\left[C_{v}^{\prime}\right]\right)=p(\mathcal{A}, C)$ (the runtime of $C_{v}^{\prime}$ can be neglected). Hence, we obtain $\operatorname{Adv}_{G} \operatorname{Secrecy}^{(x)}(\mathcal{A}, C) \leq n \times p(\mathcal{A}, C)$. Therefore, $G$ satisfies the secrecy of $x$ with public variables $V$ up to probability $n \times p$.

One-session secrecy, secrecy, and bit secrecy In this lemma, bit secrecy queries do not occur. However, we reuse this proof in Lemmas 60 and 61 where bit secrecy queries occur, so we also handle them here. Let $s p$ be 1 -ses.secr. $(x)$, Secrecy $(x)$, or bit secr. $(x)$, and $s p^{\prime}$ be the same property with $x^{\prime}$ instead of $x$. Let $V^{\prime}=V$ when $s p$ is 1 -ses.secr. $(x)$ or bit secr. $(x)$, and $V^{\prime}=V \cup\left\{x^{\prime \prime}\right\}$ when $s p$ is $\operatorname{Secrecy}(x)$. Since $\operatorname{Bound}_{G^{\prime}}\left(V^{\prime} \cup\left\{x^{\prime}\right\}, s p^{\prime}\right.$, NonUnique $\left.{ }_{G^{\prime}}, p\right)$, then by Lemma 28, Property 1, $G^{\prime}$ satisfies $s p^{\prime}$ with public variables $V^{\prime}$ up to probability $p^{\prime}$ such that $p^{\prime}(\mathcal{A}, C)=p\left(\mathcal{A}, C\left[C_{s p^{\prime}}\right]\right)$. So by the previous result for (one-session or bit) secrecy, $G$ satisfies $s p$ with public variables $V$ up to probability $n p^{\prime}$. Let $C$ be an evaluation context acceptable for $C_{s p}[G]$ with public variables $V$ that does not contain S nor $\overline{\mathrm{S}}$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Hence

$$
\begin{aligned}
& \operatorname{Adv}_{G}\left(\mathcal{A}, C\left[C_{s p}[]\right], s p, D_{\text {false }}\right) \\
& \quad=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \vee \text { NonUnique }_{G}\right] \\
& \quad \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}}\right] \\
& \quad=\operatorname{Adv}_{G}^{s p}(\mathcal{A}, C) \leq n \times p^{\prime}(\mathcal{A}, C)=n \times p\left(\mathcal{A}, C\left[C_{s p}[]\right]\right)
\end{aligned}
$$

Indeed, replacing $C_{s p^{\prime}}$ with $C_{s p}$ in the argument of $p$ does not change its result, by Property 6 . Therefore, we have Bound ${ }_{G}\left(V \cup\{x\}, s p, D_{\text {false }}, n p\right)$.

In the guess transformation, we cannot modify injective correspondence queries, because two executions of some injective event $e$ with different indices $i$ could be mapped to the same events in the conclusion of the query. In general, it even does not work for non-injective events inside injective queries. As a counter-example, consider the query: $\forall i:[1, n], x: T^{\prime} ; \operatorname{event}\left(e_{1}(i, x)\right) \wedge$ $\operatorname{inj}$-event $\left(e_{2}(x)\right) \Rightarrow \operatorname{inj}$-event $\left(e_{3}()\right)$ with events $e_{1}\left(i_{1}, x_{1}\right), e_{1}\left(i_{2}, x_{2}\right), e_{2}\left(x_{1}\right), e_{2}\left(x_{2}\right)$ and $e_{3}$ each executed once. This query is false: we have two executions of $e_{2}$ (with matching executions of $e_{1}$ ) for a single execution of $e_{3}$. That contradicts injectivity. However, it is true if we restrict ourselves to one value of $i$ (the index of the tested session), because we consider $e_{1}\left(i_{1}, x_{1}\right), e_{2}\left(x_{1}\right)$ and $e_{3}$ for $i=i_{1}$ and $e_{1}\left(i_{2}, x_{2}\right), e_{2}\left(x_{2}\right)$ and $e_{3}$ for $i=i_{2}$. Requiring the same value of $x$ in $e_{1}$ and
$e_{2}$ restricts the events $e_{2}$ that we consider when we guess the session for $e_{1}$. Therefore, proving the query for the tested session does not allow us to prove it in the initial game.

Hence, for injective correspondence queries $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi$, we proceed as follows: we define a non-injective query noninj $\left(\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi\right)$ simply obtained by replacing injective events with non-injective events, and we try to prove that noninj $\left(\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi\right)$ implies $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi$ in the current game. This proof is a modified version of the proof of injective queries (Section4.2.4): we define the pseudo-formula $\mathcal{C}(\psi, \phi)$ by
$\mathcal{C}(\psi, M)=\perp$
$\mathcal{C}(\psi, \operatorname{event}(e(\widetilde{M})))=\perp$
$\mathcal{C}\left(\psi, \operatorname{inj}\right.$-event $(e(\widetilde{M}))=\mathcal{S}$ such that assuming $\psi=F_{1} \wedge \cdots \wedge F_{m}$,
for every $\mu_{1}$ that executes $F_{1}, \ldots$, for every $\mu_{m}$ that executes $F_{m}$, letting
$\mathcal{F}=\theta_{1} \mathcal{F}_{F_{1}, \mu_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}}$,
$\mathcal{I}=\left\{j \mapsto\left(\mu_{j}, \theta_{j} I_{\mu_{j}}\right) \mid F_{j}\right.$ is an injective event $\}$,
$\mathcal{V}=\operatorname{var}\left(\theta_{1} I_{\mu_{1}}\right) \cup \cdots \cup \operatorname{var}\left(\theta_{m} I_{\mu_{m}}\right) \cup\{\widetilde{x}, \widetilde{y}\}$,
where for $j \leq m, \theta_{j}$ is a renaming of $I_{\mu_{j}}$ to fresh replication indices,
we have $(\mathcal{F},(\widetilde{M}), \mathcal{I}, \mathcal{V}) \in \mathcal{S}$.
$\mathcal{C}\left(\psi, \phi_{1} \wedge \phi_{2}\right)=\mathcal{C}\left(\psi, \phi_{1}\right) \wedge \mathcal{C}\left(\psi, \phi_{2}\right)$
$\mathcal{C}\left(\psi, \phi_{1} \vee \phi_{2}\right)=\mathcal{C}\left(\psi, \phi_{1}\right) \vee \mathcal{C}\left(\psi, \phi_{2}\right)$
Given a pseudo-formula $\mathcal{C}$, we define $\vdash \mathcal{C}$ as in Section4.2.4.
Proposition 4 Let $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi$ be a correspondence, with $\widetilde{x}=\operatorname{var}(\psi)$ and $\widetilde{y}=$ $\operatorname{var}(\phi) \backslash \operatorname{var}(\psi)$. Let $\varphi=\llbracket \forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi \rrbracket$ be the semantics the correspondence $\forall \widetilde{x}:$ $\widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi$ (Definition 12), and $\varphi_{\mathrm{ni}}=\llbracket \operatorname{noninj}\left(\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi\right) \rrbracket$ be the semantics of the correspondence $\operatorname{noninj}\left(\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi\right)$. Let $Q_{0}$ be a process that satisfies Properties 3 and 4 Suppose that, in $Q_{0}$, the arguments of the events that occur in $\psi$ are always simple terms.

Assume that $\vdash \mathcal{C}(\psi, \phi)$ and for all $\mathcal{A} \in \mathcal{B B}$ and all evaluation contexts $C$ acceptable for $Q_{0}$, $\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right] \preceq \neg\{[\vdash \mathcal{C}(\psi, \phi)]\}\right] \leq p(\mathcal{A}, C)$. If $\operatorname{Bound}_{Q_{0}}\left(V, \varphi_{\mathrm{ni}}, D_{\text {false }}, p^{\prime}\right)$, then $\operatorname{Bound}_{Q_{0}}\left(V, \varphi, D_{\text {false }}\right.$, $\left.p^{\prime}+p\right)$.

Proposition 4 proves injectivity much like in Section 4.2.4, but using the arguments $\widetilde{M}$ of the events in $\phi$ instead of the program points and replication indices at their execution (which we do not have since in $Q_{0}$ we are not able to prove that these events have been executed; otherwise we would simply prove the correspondence in $\left.Q_{0}\right)$. Intuitively, $\vdash \mathcal{C}(\psi, \phi)$ shows that, if we have different executions of injective events in $\psi$, that is, executions of such events with different pairs (program point, replication indices), then the arguments $\widetilde{M}$ of each injective event in $\phi$ must be different, which implies different executions of this event.

Proof Let $C$ be an evaluation context acceptable for $Q_{0}$ with public variables $V$ that does not contain events used by $\varphi$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Let $\mathcal{C}=\mathcal{C}(\psi, \phi)$. Consider a trace $\operatorname{Tr}$ of $C\left[Q_{0}\right]$ for $\mathcal{A}$ such that $\operatorname{Tr} \vdash \varphi_{\mathrm{ni}}, \operatorname{Tr} \vdash\{[\vdash \mathcal{C}]\}, \operatorname{Tr}$ does not execute a non-unique event of $Q_{0}$, and the last configuration of $\operatorname{Tr}$ cannot be reduced. Let $\mu \mathcal{E} v$ be the sequence of events in the last configuration of $\operatorname{Tr}$. Since $\mu \mathcal{E} v \vdash \varphi_{\mathrm{ni}}$,

$$
\mu \mathcal{E} v \vdash \forall \tau_{1}, \ldots, \tau_{m} \in \mathbb{N}, \forall \widetilde{x} \in \widetilde{T},\left(\psi^{\tau} \Rightarrow \exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi\right)
$$

with the notations of Definition 12 By defining functions $f_{j} \in \mathbb{N}^{m} \times \prod \widetilde{T} \rightarrow \mathbb{N} \cup\{\perp\}$ that map $\tau_{1}, \ldots, \tau_{m}, \widetilde{x}$ to the execution steps of injective events in the proof of $\phi$, and to $\perp$ when the
event is not used in the proof of $\phi$, we have

$$
\begin{equation*}
\mu \mathcal{E} v \vdash \exists f_{1}, \ldots, f_{k} \in \mathbb{N}^{m} \times \prod \widetilde{T} \rightarrow \mathbb{N} \cup\{\perp\}, \forall \tau_{1}, \ldots, \tau_{m} \in \mathbb{N}, \forall \widetilde{x} \in \widetilde{T},\left(\psi^{\tau} \Rightarrow \exists \widetilde{y} \in \widetilde{T}^{\prime}, \phi^{\tau}\right) \tag{32}
\end{equation*}
$$

It remains to show $\operatorname{Inj}(I, f)$ for all $f \in\left\{f_{1}, \ldots, f_{k}\right\}$.
Let $f \in\left\{f_{1}, \ldots, f_{k}\right\}$ and $\operatorname{event}(e(\widetilde{M})) @ f\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right)$ be the event labeled with $f$ in $\phi^{\tau}$. Suppose that $f\left(\tau_{1}^{\prime}, \ldots, \tau_{m}^{\prime}, \widetilde{a}^{\prime}\right)=f\left(\tau_{1}^{\prime \prime}, \ldots, \tau_{m}^{\prime \prime}, \widetilde{a}^{\prime \prime}\right) \neq \perp$ and there exists $j \in I$ such that $\tau_{j}^{\prime} \neq \tau_{j}^{\prime \prime}$, and let us prove a contradiction.

Since $f\left(\tau_{1}^{\prime}, \ldots, \tau_{m}^{\prime}, \widetilde{a}^{\prime}\right) \neq \perp$, event $(e(\widetilde{M})) @ f\left(\tau_{1}^{\prime}, \ldots, \tau_{m}^{\prime}, \widetilde{a}^{\prime}\right)$ is used in the proof of 32), so letting $\rho_{1}=\left\{\tau_{1} \mapsto \tau_{1}^{\prime}, \ldots, \tau_{m} \mapsto \tau_{m}^{\prime}, \widetilde{x} \mapsto \widetilde{a}^{\prime}\right\}, \rho_{1}, \mu \mathcal{E} v \vdash \psi^{\tau}$ and there exists an extension $\rho_{1}^{\prime}$ of $\rho_{1}$ to $\widetilde{y}$ such that $\rho_{1}^{\prime}, \mu \mathcal{E} v \vdash \phi^{\tau}$ and $\rho_{1}^{\prime}, \mu \mathcal{E} v \vdash \operatorname{event}(e(\widetilde{M})) @ f\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right)$.

Since $\rho_{1}, \mu \mathcal{E} v \vdash \psi^{\tau}$, for all events $F_{\ell}=\operatorname{event}\left(e_{\ell}\left(\widetilde{M}_{\ell}\right)\right) @ \tau_{\ell}$ in $\psi^{\tau}, T r, \rho_{1} \vdash F_{\ell}$ and $\mu \mathcal{E} v\left(\tau_{\ell}^{\prime}\right)=$ $(\ldots): e_{\ell}\left(\widetilde{a}_{\ell, 1}\right)$ for $\widetilde{a}_{\ell, 1}$ such that $\rho_{1}, \widetilde{M}_{\ell} \Downarrow \widetilde{a}_{\ell, 1}$. By Lemma 38 , there exists a program point $\mu_{\ell, 1}$ that executes $F_{\ell}\left(\right.$ in $\left.Q_{0}\right)$ and a case $c_{\ell, 1}$ such that, for any $\theta_{\ell, 1}$ renaming of $I_{\mu_{\ell, 1}}$ to fresh replication indices, there exists a mapping $\sigma_{\ell, 1}$ with domain $\theta_{\ell, 1} I_{\mu_{\ell, 1}}$ such that $\mu \mathcal{E} v\left(\rho_{1}\left(\tau_{\ell}\right)\right)=$ $\left(\mu_{\ell, 1}, \sigma_{\ell, 1}\left(\theta_{\ell, 1} I_{\mu_{\ell, 1}}\right)\right): \ldots$ and $\operatorname{Tr}, \sigma_{\ell, 1} \cup \rho_{1} \vdash \theta_{\ell, 1} \mathcal{F}_{F_{\ell}, \mu_{\ell, 1}, c_{\ell, 1}}$. So $\mu \mathcal{E} v\left(\tau_{\ell}^{\prime}\right)=\left(\mu_{\ell, 1}, \sigma_{\ell, 1}\left(\theta_{\ell, 1} I_{\mu_{\ell, 1}}\right)\right):$ $e_{\ell}\left(\widetilde{a}_{\ell, 1}\right)$.

Let $\mathcal{S}$ be the label of $\mathcal{C}$ at the occurrence corresponding to $f$, and inj-event $(e(\widetilde{M}))$ be the injective event at that occurrence in $\phi$. Let $\mathcal{F}_{1}=\bigcup_{\ell} \theta_{\ell, 1} \mathcal{F}_{F_{\ell,}, \mu_{\ell, 1}, c_{\ell, 1}}, \mathcal{I}_{1}=\left\{\ell \mapsto\left(\mu_{\ell, 1}, \theta_{\ell, 1} I_{\mu_{\ell, 1}}\right) \mid\right.$ $F_{\ell}$ is an injective event $\}$, and $\mathcal{V}_{1}=\operatorname{var}\left(\theta_{1,1} I_{\mu_{1,1}}\right) \cup \cdots \cup \operatorname{var}\left(\theta_{m, 1} I_{\mu_{m, 1}}\right) \cup\{\widetilde{x}, \widetilde{y}\}$. By construction of $\mathcal{C}$, we have $\left(\mathcal{F}_{1},(\widetilde{M}), \mathcal{I}_{1}, \mathcal{V}_{1}\right) \in \mathcal{S}$.

So we have $\operatorname{Tr}, \bigcup_{\ell} \sigma_{\ell, 1} \cup \rho_{1} \vdash \bigcup_{\ell} \theta_{\ell, 1} \mathcal{F}_{F_{\ell}, \mu_{\ell, 1}, c_{\ell, 1}}$. Letting $\sigma_{1}=\bigcup_{\ell} \sigma_{\ell, 1}$, we have $\operatorname{Tr}, \sigma_{1} \cup \rho_{1}^{\prime} \vdash \mathcal{F}_{1}$; for $\ell$ such that $F_{\ell}$ is an injective event, $\mu \mathcal{E} v\left(\tau_{\ell}^{\prime}\right)=\sigma_{1} \mathcal{I}_{1}(\ell): e_{\ell}(\ldots) ; \mathcal{V}_{1}=\operatorname{Dom}\left(\sigma_{1}\right) \cup\{\widetilde{x}, \widetilde{y}\}$. Since $\rho_{1}^{\prime}, \mu \mathcal{E} v \vdash \operatorname{event}(e(\widetilde{M})) @ f\left(\tau_{1}, \ldots, \tau_{m}, \widetilde{x}\right)$, we have $\rho_{1}^{\prime}, \widetilde{M} \Downarrow \widetilde{a}_{1}$ and $\mu \mathcal{E} v\left(f\left(\tau_{1}^{\prime}, \ldots, \tau_{m}^{\prime}, \widetilde{a}^{\prime}\right)\right)=(\ldots)$ : $e\left(\widetilde{a}_{1}\right)$ for some $\widetilde{a}_{1}$.

Since $f\left(\tau_{1}^{\prime \prime}, \ldots, \tau_{m}^{\prime \prime}, \widetilde{a}^{\prime \prime}\right) \neq \perp$, we have similarly $\left(\mathcal{F}_{2},(\widetilde{M}), \mathcal{I}_{2}, \mathcal{V}_{2}\right) \in \mathcal{S}, \rho_{2}^{\prime}$, and $\sigma_{2}$ such that $\operatorname{Tr}, \sigma_{2} \cup \rho_{2}^{\prime} \vdash \mathcal{F}_{2}$; for $\ell$ such that $F_{\ell}$ is an injective event, $\mu \mathcal{E} v\left(\tau_{\ell}^{\prime \prime}\right)=\sigma_{2} \mathcal{I}_{2}(\ell): e_{\ell}(\ldots) ; \mathcal{V}_{2}=$ $\operatorname{Dom}\left(\sigma_{2}\right) \cup\{\widetilde{x}, \widetilde{y}\} ; \rho_{2}^{\prime}, \widetilde{M} \Downarrow \widetilde{a}_{2}$ and $\mu \mathcal{E} v\left(f\left(\tau_{1}^{\prime \prime}, \ldots, \tau_{m}^{\prime \prime}, \widetilde{a}^{\prime \prime}\right)\right)=(\ldots): e\left(\widetilde{a}_{1}\right)$ for some $\widetilde{a}_{2}$.

Let $\theta^{\prime \prime}$ be a renaming of variables in $\mathcal{V}_{2}$. Then $\operatorname{Tr}, \sigma_{2} \theta^{\prime \prime-1} \cup \rho_{2}^{\prime} \theta^{\prime \prime-1} \vdash \theta^{\prime \prime} \mathcal{F}_{2}$; for $\ell$ such that $F_{\ell}$ is an injective event, $\mu \mathcal{E} v\left(\tau_{\ell}^{\prime \prime}\right)=\sigma_{2} \theta^{\prime \prime-1} \theta^{\prime \prime} \mathcal{I}_{2}(\ell): e_{\ell}(\ldots) ; \rho_{2}^{\prime} \theta^{\prime \prime-1}, \theta^{\prime \prime} \widetilde{M} \Downarrow \widetilde{a}_{2}$ and $\mu \mathcal{E} v\left(f\left(\tau_{1}^{\prime \prime}, \ldots\right.\right.$, $\left.\left.\tau_{m}^{\prime \prime}, \widetilde{a}^{\prime \prime}\right)\right)=(\ldots): e\left(\widetilde{a}_{2}\right)$ for some $\widetilde{a}_{2}$.

Then $\operatorname{Tr}, \sigma_{1} \cup \sigma_{2} \theta^{\prime \prime-1} \cup \rho_{1}^{\prime} \cup \rho_{2}^{\prime} \theta^{\prime \prime-1} \vdash \mathcal{F}_{1} \cup \theta^{\prime \prime} \mathcal{F}_{2}$.
There exists $j \in I$ such that $\tau_{j}^{\prime} \neq \tau_{j}^{\prime \prime}$, so $\sigma_{1} \mathcal{I}_{1}(j) \neq \sigma_{2} \theta^{\prime \prime-1} \theta^{\prime \prime} \mathcal{I}_{2}(j)$ (distinct events have distinct pairs (program point, replication indices) by Lemma41), so there exists $j \in \operatorname{Dom}\left(\mathcal{I}_{1}\right)=I$ such that $\operatorname{Tr}, \sigma_{1} \cup \sigma_{2} \theta^{\prime \prime-1} \cup \rho_{1}^{\prime} \cup \rho_{2}^{\prime} \theta^{\prime \prime-1} \vdash \mathcal{I}_{1}(j) \neq \theta^{\prime \prime} \mathcal{I}_{2}(j)$.

Since $f\left(\tau_{1}^{\prime}, \ldots, \tau_{m}^{\prime}, \widetilde{a}^{\prime}\right)=f\left(\tau_{1}^{\prime \prime}, \ldots, \tau_{m}^{\prime \prime}, \widetilde{a}^{\prime \prime}\right), \mu \mathcal{E} v\left(f\left(\tau_{1}^{\prime}, \ldots, \tau_{m}^{\prime}, \widetilde{a}^{\prime}\right)\right)=\mu \mathcal{E} v\left(f\left(\tau_{1}^{\prime \prime}, \ldots, \tau_{m}^{\prime \prime}, \widetilde{a}^{\prime \prime}\right)\right)$, so $\widetilde{a}_{1}=\widetilde{a}_{2}$, so $T r, \sigma_{1} \cup \sigma_{2} \theta^{\prime \prime-1} \cup \rho_{1}^{\prime} \cup \rho_{2}^{\prime} \theta^{\prime \prime-1} \vdash \widetilde{M}=\theta^{\prime \prime} \stackrel{\rightharpoonup}{M}$.

So $\operatorname{Tr}, \sigma_{1} \cup \sigma_{2} \theta^{\prime \prime-1} \cup \rho_{1}^{\prime} \cup \rho_{2}^{\prime} \theta^{\prime \prime-1} \vdash \mathcal{F}_{1} \cup \theta^{\prime \prime} \mathcal{F}_{2} \cup\left\{\bigvee_{j \in \operatorname{Dom}\left(\mathcal{I}_{1}\right)} \mathcal{I}_{1}(j) \neq \theta^{\prime \prime} \mathcal{I}_{2}(j), \widetilde{M}=\theta^{\prime \prime} \widetilde{M}\right\}$.
Since the trace satisfies $\{\mid \vdash \mathcal{C}]\}$, this is a contradiction. Therefore, we conclude that the considered trace satisfies $\varphi$. Hence, every full trace of $C\left[Q_{0}\right]$ that satisfies $\left.\varphi_{\mathrm{ni}},\{\mid \vdash \mathcal{C}]\right\}$, and does not execute a non-unique event of $Q_{0}$ also satisfies $\varphi$. Therefore, every full trace of $C\left[Q_{0}\right]$ that satisfies $\neg \varphi$ satisfies $\neg\left(\varphi_{\mathrm{ni}} \wedge\{\mid \vdash \mathcal{C}]\right\} \wedge \neg$ NonUnique $\left._{Q_{0}}\right)$, so every full trace of $C\left[Q_{0}\right]$ that satisfies $\neg \varphi \wedge \neg$ NonUnique $_{Q_{0}}$ satisfies $\neg\left(\varphi_{\mathrm{ni}} \wedge\{[\vdash \mathcal{C}]\} \wedge \neg\right.$ NonUnique $\left._{Q_{0}}\right) \wedge \neg$ NonUnique $_{Q_{0}}=\left(\neg \varphi_{\mathrm{ni}} \vee \neg\{\mid \vdash\right.$ $\mathcal{C}]\}) \wedge \neg$ NonUnique $_{Q_{0}}=\left(\neg \varphi_{\mathrm{ni}} \wedge \neg\right.$ NonUnique $\left._{Q_{0}}\right) \vee(\neg\{\mid \vdash \mathcal{C}]\} \wedge \neg$ NonUnique $\left._{Q_{0}, D_{\text {false }}}\right)$, so it satisfies

$$
\begin{aligned}
\left(\neg \varphi_{\mathrm{ni}} \wedge \neg \text { NonUnique }_{Q_{0}}\right) \vee & \neg\{[\vdash \mathcal{C}]\} \text {. So } \\
\operatorname{Adv}_{Q_{0}}\left(\mathcal{A}, C, \varphi, D_{\text {false }}\right) & =\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg \varphi \wedge \neg \text { NonUnique }_{Q_{0}}\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]:\left(\neg \varphi_{\mathrm{ni}} \wedge \neg \text { NonUnique }_{Q_{0}}\right) \vee \neg\{[\vdash \mathcal{C}]\}\right] \\
& \left.\left.\leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg\{\vdash \vdash \mathcal{C}]\right\}\right]+\operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg \varphi_{\mathrm{ni}} \wedge \neg \text { NonUnique }_{Q_{0}}\right)\right] \\
& \left.\leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg\{\vdash \mathcal{C}]\right\}\right]+\operatorname{Adv}_{Q_{0}}\left(\mathcal{A}, C, \varphi_{\mathrm{ni}}, D_{\text {false }}\right) \\
& \left.\leq \operatorname{Pr}^{\mathcal{A}}\left[C\left[Q_{0}\right]: \neg\{\vdash \mathcal{C}]\right\}\right]+p(\mathcal{A}, C) \quad \text { since Bound }{ }_{Q_{0}}\left(V, \varphi_{\mathrm{ni}}, D_{\text {false }}, p\right) \\
& \leq p^{\prime}(\mathcal{A}, C) .
\end{aligned}
$$

Therefore $\operatorname{Bound}_{Q_{0}}\left(V, \varphi, D_{\text {false }}, p^{\prime}\right)$.
If the proof that noninj $\left(\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi\right)$ implies $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi$ works, we just have to prove $\operatorname{noninj}\left(\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi\right)$ and we can apply the guess transformation for non-injective correspondences. Otherwise, we simply leave the query $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T^{\prime}} ; \phi$ unchanged.

A transformation guess $i \& \&$ above, similar to guess $i$, can be used to guess the whole sequence $\widetilde{i}$ of replication indices above and including the modified replication, by testing the equality $\widetilde{i}=\widetilde{i}_{\text {tested }}$ instead of $i=i_{\text {tested }}$.

### 5.1.18 guess $x\left[c_{1}, \ldots, c_{m}\right]$

Like the transformation guess $i$, when guessRemoveUnique $=$ true and some (one-session or bit) secrecy queries are present, the transformation guess $x\left[c_{1}, \ldots, c_{m}\right]$ first transforms the game $G$ into $G_{\mathrm{RU}}$, by replacing all proved find[unique] with find. Lemma 58 shows the soundness of this preliminary transformation.

Next, the transformation guess $x\left[c_{1}, \ldots, c_{m}\right]$ transforms a game $G$ into a game $G^{\prime}$ by guessing the value of a variable $x\left[c_{1}, \ldots, c_{m}\right]$ : it replaces the processes $P$ under the definition of $x\left[c_{1}, \ldots, c_{m}\right]$ with

$$
\text { if } x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }} \text { then } P \text { else event_abort bad_guess }
$$

and $v_{\text {tested }}$ is a constant, which is the guessed value of $x\left[c_{1}, \ldots, c_{m}\right]$. (At each definition of $x$, CryptoVerif must be able to determine whether it is a definition of $x\left[c_{1}, \ldots, c_{m}\right]$ or not. The variable $x$ must not be defined inside a term. In case diff_constants $=$ true, the constant $v_{\text {tested }}$ must not be considered different from other constants of the same type.)

In case there is a (one-session or bit) secrecy query, it uses instead
let guess_x_defined $=$ true in if $x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }}$ then $P$ else event_abort bad_guess
where guess_x_defined is a fresh variable, and we add guess_x_defined to the public variables of (one-session or bit) secrecy queries. That gives the adversary knowledge of whether the guessed variable is defined or not. This is useful because the adversary may need to swap its answer differently depending on whether the guessed variable is defined or not, so that the cases in which this variable is not defined always increase the probability of breaking (one-session or bit) secrecy.

When there are only correspondence queries, we can actually execute any code when $x\left[c_{1}, \ldots\right.$, $\left.c_{m}\right]$ is different from the guessed value $v_{\text {tested }}$. In particular, we can execute $P$ with $x\left[c_{1}, \ldots, c_{m}\right]$ set to $v_{\text {tested }}$, which has the effect of replacing the definition of $x\left[c_{1}, \ldots, c_{m}\right]$ with let $x=v_{\text {tested }}$ and removing the test $x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }}$.

To sum up, we also define a transformation guess $x\left[c_{1}, \ldots, c_{m}\right]$ no_test that can be applied when there are only correspondence queries and when $x\left[c_{1}, \ldots, c_{m}\right]$ is defined only by definitions of the form let $x=M$. (This is the most useful case, since the definition of $x$ can then be simplified.) This transformation replaces these definitions let $x=M$ with let $x=v_{\text {tested }}$ when $M$ is a simple term and with let ignore $=M$ in let $x=v_{\text {tested }}$ otherwise, where ignore is a fresh variable whose value is not used.

The transformation guess $x\left[c_{1}, \ldots, c_{m}\right]$ no_test would not be valid in the presence of secrecy queries (at least not with the same probability), because before transformation the value of $x\left[c_{1}, \ldots, c_{m}\right]$ may contain part of the secret variable and this value may leak, while after transformation, that leaks disappears and the variable may be perfectly secret for all values $x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }}$.

Lemma 60 The transformations guess $x\left[c_{1}, \ldots, c_{m}\right]$ and guess $x\left[c_{1}, \ldots, c_{m}\right]$ no_test require and preserve Properties 1, 2, 3, and 4. They preserve Property 5.

Suppose the game $G$ is transformed into $G^{\prime}$ by the transformation guess $x\left[c_{1}, \ldots, c_{m}\right]$ or guess $x\left[c_{1}, \ldots, c_{m}\right]$ no_test, where $x$ is of type $T$ and $T \neq \emptyset$.

Let $\varphi$ be the semantics of a correspondence. Let $D$ be a disjunction of Shoup and non-unique events that does not contain S nor $\overline{\mathrm{S}}$. If $\operatorname{Bound}_{G^{\prime}}(V, \varphi, D, p)$ and $p$ is independent of the value of $v_{\text {tested }}$, then $\operatorname{Bound}_{G}(V, \varphi, D,|T| p)$.

Let sp be 1-ses.secr. $(y)$, Secrecy $(y)$, or bit secr. $(x)$. Then $G$ is transformed into $G^{\prime}$ by the transformation guess $x\left[c_{1}, \ldots, c_{m}\right]$. If $G^{\prime}$ satisfies sp with public variables $V \cup\{$ guess_x_defined $\}$ ( $y \notin V$ ) up to probability $p$ and $p$ satisfies Property 6, then $G$ satisfies sp with public variables $V$ up to probability $|T| \times p$ (neglecting a small additional runtime of the con-
 Bound $_{G}\left(V^{\prime}, s p, D_{\text {false }},|T| p\right)$ (neglecting a small additional runtime of the context).

## Proof

Correspondences Let $C$ be an evaluation context acceptable for $G$ with any public variables that does not contain events used by $\varphi$ or $D$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$.

$$
\begin{aligned}
& \operatorname{Adv}_{G}(\mathcal{A}, C, \varphi, D) \\
&= \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D}\right] \\
&= \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D} \wedge x\left[c_{1}, \ldots, c_{m}\right] \text { not defined }\right]+ \\
& \sum_{v \in T} \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D} \wedge x\left[c_{1}, \ldots, c_{m}\right]=v\right] \\
& \leq \sum_{v \in T} \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D} \wedge\left(x\left[c_{1}, \ldots, c_{m}\right]=v \vee x\left[c_{1}, \ldots, c_{m}\right] \text { not defined }\right)\right]
\end{aligned}
$$

Moreover,

$$
\begin{aligned}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:(\neg \varphi \vee D)\right. & \left.\wedge \neg \text { NonUnique }_{G^{\prime}, D}\right] \geq \\
\operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D}\right. & \left.\wedge\left(x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }} \vee x\left[c_{1}, \ldots, c_{m}\right] \text { not defined }\right)\right]
\end{aligned}
$$

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This property holds because $G^{\prime}$ behaves like $G$ when $x\left[c_{1}, \ldots, c_{m}\right]$ is not defined or $x\left[c_{1}, \ldots, c_{m}\right]=$ $v_{\text {tested }}$, in both transformations guess $x\left[c_{1}, \ldots, c_{m}\right]$ and guess $x\left[c_{1}, \ldots, c_{m}\right]$ no_test. So

$$
\begin{aligned}
\operatorname{Adv}_{G}(\mathcal{A}, C, \varphi, D) & \leq \sum_{v \in T} \operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G^{\prime}, D}\right] \text { for } v_{\text {tested }}=v \\
& \leq \sum_{v \in T} \operatorname{Adv}_{G^{\prime}}(\mathcal{A}, C, \varphi, D) \text { for } v_{\text {tested }}=v
\end{aligned}
$$

Since Bound $_{G^{\prime}}(V, \varphi, D, p)$, we have $\operatorname{Adv}_{G^{\prime}}(\mathcal{A}, C, \varphi, D) \leq p(\mathcal{A}, C)$ and $p$ is independent of the value of $v_{\text {tested }}$, so we obtain $\operatorname{Adv}_{G}(\mathcal{A}, C, \varphi, D) \leq|T| \times p(\mathcal{A}, C)$. Therefore Bound ${ }_{G}(V, \varphi, D,|T| p)$.
(One-session or bit) secrecy Let $C$ be an evaluation context acceptable for $C_{s p}[G]$ with public variables $V$ that does not contain S nor $\overline{\mathrm{S}}$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. We have
$\operatorname{Adv}_{G}^{s p}(\mathcal{A}, C)$
$=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}}\right]$
$=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge x\left[c_{1}, \ldots, c_{m}\right]\right.$ not defined $]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge x\left[c_{1}, \ldots, c_{m}\right]\right.$ not defined $]$
$+\sum_{v=1}^{|T|} \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge x\left[c_{1}, \ldots, c_{m}\right]=v\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge x\left[c_{1}, \ldots, c_{m}\right]=v\right]$
From the adversary $C$, we define four adversaries $C^{\prime}$ that call oracle $O_{s}^{\prime}$ ( $O_{s}^{\prime \prime}$ for bit secrecy) with $b^{\prime \prime}$ instead of $b^{\prime}$, where $b^{\prime \prime}=$ if defined (guess_x_defined) then $f_{1}\left(b^{\prime}\right)$ else $f_{2}\left(b^{\prime}\right)$ where $f_{1}\left(b^{\prime}\right)$ is either $b^{\prime}$ or $\neg b^{\prime}$, and similarly for $f_{2}$, and consider the adversary $C_{\text {max }, v_{\text {tested }}}^{\prime}$ among those four that yields the maximum $\operatorname{Adv}_{G^{\prime}}^{s p}\left(\mathcal{A}, C^{\prime}\right)$. Changing $b^{\prime}$ into $\neg b^{\prime}$ swaps the events S and $\overline{\mathrm{S}}$, and therefore swaps their probabilities. Hence, for this adversary $C_{\text {max }, v_{\text {tested }}}^{\prime}$,
$\operatorname{Adv}_{G^{\prime}}^{s p}\left(\mathcal{A}, C_{\text {max }, v_{\text {tested }}}^{\prime}\right)=$
$\left|\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }}\right]\right|+$
$\mid \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge x\left[c_{1}, \ldots, c_{m}\right]\right.$ not defined $]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge x\left[c_{1}, \ldots, c_{m}\right]\right.$ not defined $] \mid$
Since $G^{\prime}$ satisfies $s p$ with public variables $V \cup\{$ guess_x_defined $\}(y \notin V)$ up to probability $p$ and $C_{\max , v_{\text {tested }}}^{\prime}$ is an evaluation context acceptable for $C_{s p}\left[G^{\prime}\right]$ with public variables $V \cup\{$ guess_x_defined $\}$ that does not contain $S$ nor $\bar{S}$, we have $\operatorname{Adv}_{G^{\prime}}^{s p}\left(\mathcal{A}, C_{\max , v_{\text {tested }}}^{\prime}\right) \leq p(\mathcal{A}$, $\left.C_{\text {max }, v_{\text {tested }}}^{\prime}\right)$. So we have

$$
\begin{aligned}
\sum_{v_{\text {tested }}=1}^{|T|} p\left(\mathcal{A}, C_{\text {max }, v_{\text {tested }}}^{\prime}\right) \geq & \sum_{v_{\text {tested }}=1}^{|T|} \operatorname{Adv}_{G^{\prime}}^{s p}\left(\mathcal{A}, C_{\text {max }, v_{\text {tested }}}^{\prime}\right) \\
\geq & \sum_{v_{\text {tested }}=1}^{|T|}\left|\begin{array}{l}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }}\right] \\
-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge x\left[c_{1}, \ldots, c_{m}\right]=v_{\text {tested }}\right]
\end{array}\right| \\
& +|T| \times \left\lvert\, \begin{array}{l}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge x\left[c_{1}, \ldots, c_{m}\right] \text { not defined }\right] \\
-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge x\left[c_{1}, \ldots, c_{m}\right] \text { not defined }\right]
\end{array}\right. \\
\geq & \operatorname{Adv}_{G}^{s p}(\mathcal{A}, C)
\end{aligned}
$$

Moreover, by Property 6, $p$ is independent of the value of $v_{\text {tested }}$ (since the type $T$ is bounded) and $p(\mathcal{A}, C)$ depends only on the runtime of $C$, the number of calls $C$ makes to the various oracles
(which determine replication bounds), and the length of bitstrings, so we have $p\left(\mathcal{A}, C_{\max , v_{\text {tested }}}^{\prime}\right)=$ $p(\mathcal{A}, C)$. (The additional runtime of the context can be neglected.) So $\operatorname{Adv}_{G}^{s p}(\mathcal{A}, C) \leq|T| p(\mathcal{A}, C)$. Therefore, $G$ satisfies $s p$ with public variables $V$ up to probability $|T| \times p$. The proof of the second property for (one-session or bit) secrecy proceeds as for guess $i$ in Lemma 59

### 5.1.19 guess_branch

Like the transformation guess $i$, when guessRemoveUnique $=$ true and some (one-session or bit) secrecy queries are present, the transformation guess_branch $\mu$ first transforms the game $G$ into $G_{\mathrm{RU}}$, by replacing all proved find[unique] with find. Lemma 58 shows the soundness of this preliminary transformation.

Next, the transformation guess_branch $\mu$ guesses the branch taken by a branching instruction (if, let, find) at program point $\mu$. The program point $\mu$ is designated as explained in Section 5.1.10 The instruction at $\mu$ must be executed at most once (either because it is not under replication or because this is proved by CryptoVerif, showing that two executions with distinct replication indices lead to a contradiction: $\mathcal{F}_{\mu} \cup \mathcal{F}_{\mu}\left\{\widetilde{i^{\prime}} / \widetilde{i}\right\} \cup\left\{\widetilde{i^{\prime}} \neq \widetilde{i}\right\}$ yields a contradiction, where $\widetilde{i}$ are the current replication indices at $\mu$ and $\widetilde{i}^{\prime}$ are fresh replication indices, using a mode of the equational prover of Section 3.4 that does not allow elimination of collisions, so that this property is proved without probability loss). Suppose this instruction has $k$ branches.

We consider a game $G$ and define transformed games $G_{j}^{\prime}(0 \leq j<k)$ in which branch $j$ of the instruction at $\mu$ is kept and all other branches are replaced with event_abort bad_guess.

In case there is a (one-session or bit) secrecy query, let guess_br_defined $=$ true in is added before the instruction at $\mu$ where guess_br_defined is a fresh variable, and we add guess_br_defined to the public variables of (one-session or bit) secrecy queries. That gives the adversary knowledge of whether the instruction at $\mu$ is executed or not. This is useful because the adversary may need to swap its answer differently depending on whether that instruction is executed or not, so that the cases in which that instruction is not executed always increase the probability of breaking (one-session or bit) secrecy.

When there are only correspondence queries, we can actually execute any code when the taken branch is different from the guessed one. In particular, we can execute the same code as in the tested branch, which has the effect of removing the test at $\mu$ when that test is if. (The tests find and let with pattern-matching have additional effects: guaranteeing the definition of variables for find; defining variables for let. In general, that prevents their removal.)

To sum up, we also define a transformation guess_branch $\mu$ no_test that can be applied when there are only correspondence queries and the instruction at $\mu$ is if $M$ then $P_{1}$ else $P_{0}$. This transformation defines two transformed games $G_{j}^{\prime}(j \in\{0,1\})$ in which the instruction at $\mu$ is replaced with $P_{j}$ when $M$ is a simple term and with let ignore $=M$ in $P_{j}$ otherwise, where ignore is a fresh variable whose value is not used.

The transformation guess_branch $\mu$ no_test would not be valid in the presence of secrecy queries (at least not with the same probability), because before transformation the test at $\mu$ may make the value of $M$ leak, which can reveal for instance one bit of the secret variable, while after transformation, that leaks disappears and the variable may be perfectly secret both when $P_{0}$ and when $P_{1}$ are executed.

Lemma 61 The transformations guess_branch $\mu$ and guess_branch $\mu$ no_test require and preserve Properties 1, 2, 3, and 4. They preserve Property 5.

Suppose the game $G$ is transformed into games $G_{j}^{\prime}(0 \leq j<k)$ by the transformation guess_branch $\mu$ or guess_branch $\mu$ no_test.

Let $\varphi$ be the semantics of a correspondence. Let $D$ be a disjunction of Shoup and nonunique events that does not contain S nor $\overline{\mathrm{S}}$. If for all $0 \leq j<k$, $\operatorname{Bound}_{G_{j}^{\prime}}\left(V, \varphi, D, p_{j}\right)$, then Bound $_{G}\left(V, \varphi, D, \sum_{j=0}^{k-1} p_{j}\right)$.

Let sp be 1-ses.secr. $(y)$, Secrecy $(y)$, or bit secr. $(x)$. Then $G$ is transformed into $G_{j}^{\prime}$ by the transformation guess_branch $\mu$. If $G_{j}^{\prime}$ satisfies sp with public variables $V \cup\{$ guess_br_defined $\}$ ( $y \notin V$ ) up to probability $p_{j}$ for $0 \leq j<k$ and the probabilities $p_{j}$ satisfy Property $\sqrt{6}$, then $G$ satisfies sp with public variables $V$ up to probability $\sum_{j=0}^{k-1} p_{j}$ (neglecting a small additional runtime of the context). If for all $0 \leq j<k$, $\operatorname{Bound}_{G_{j}^{\prime}}\left(V^{\prime} \cup\{\right.$ guess_br_defined $\}$, sp, NonUnique $\left.{ }_{G_{j}^{\prime}}, p_{j}\right)$ and the probabilities $p_{j}$ satisfy Property 6, then $\operatorname{Bound}_{G}\left(V^{\prime}, s p, D_{\text {false }}, \sum_{j=0}^{k-1} p_{j}\right)$ (neglecting a small additional runtime of the context).

## Proof

Correspondences Let $C$ be an evaluation context acceptable for $G$ with any public variables that does not contain events used by $\varphi$ or $D$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$.

$$
\begin{align*}
& \operatorname{Adv}_{G}(\mathcal{A}, C, \varphi, D)= \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D}\right] \\
&= \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D} \wedge \mu \text { not executed }\right]+ \\
& \sum_{j=0}^{k-1} \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D} \wedge \text { branch } j \text { is taken at } \mu\right] \\
& \leq \sum_{j=0}^{k-1} \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D} \wedge\right. \\
&\left.(\mu \text { not executed } \vee \text { branch } j \text { is taken at } \mu){ }^{(\neg)}\right]  \tag{33}\\
& \leq \sum_{j=0}^{k-1} \operatorname{Pr}^{\mathcal{A}}\left[C\left[G_{j}^{\prime}\right]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G_{j}^{\prime}, D}\right] \\
& \leq \sum_{j=0}^{k-1} \operatorname{Adv}_{G_{j}^{\prime}}(\mathcal{A}, C, \varphi, D) \\
& \leq \sum_{j=0}^{k-1} p_{j}(\mathcal{A}, C) \quad \text { since Bound }{ }_{G_{j}^{\prime}}\left(V, \varphi, D, p_{j}\right)
\end{align*}
$$

The step (33) is valid because $G_{j}^{\prime}$ behaves like $G$ when $\mu$ is not executed or branch $j$ is taken at $\mu$, in both transformations guess_branch $\mu$ and guess_branch $\mu$ no_test. Therefore, we obtain $\operatorname{Bound}_{G}\left(V, \varphi, D, \sum_{j=0}^{k-1} p_{j}\right)$.
(One-session or bit) secrecy Let $C$ be an evaluation context acceptable for $C_{s p}[G]$ with public variables $V$ that does not contain S nor $\overline{\mathrm{S}}$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. We have
$\operatorname{Adv}_{G}^{s p}(\mathcal{A}, C)$
$=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S}\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}}\right]$
$=\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge \mu\right.$ not executed $]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge \mu\right.$ not executed $]$
$+\sum_{j=0}^{k-1} \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge\right.$ branch $j$ is taken at $\left.\mu\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge\right.$ branch $j$ is taken at $\left.\mu\right]$

From the adversary $C$, we define four adversaries $C^{\prime}$ that call oracle $O_{s}^{\prime}\left(O_{s}^{\prime \prime}\right.$ for bit secrecy) with $b^{\prime \prime}$ instead of $b^{\prime}$, where $b^{\prime \prime}=$ if defined (guess_br_defined) then $f_{1}\left(b^{\prime}\right)$ else $f_{2}\left(b^{\prime}\right)$ where $f_{1}\left(b^{\prime}\right)$ is either $b^{\prime}$ or $\neg b^{\prime}$, and similarly for $f_{2}$, and consider the adversary $C_{\max , j}^{\prime}$ among those four that yields the maximum $\operatorname{Adv}_{G_{j}^{\prime}}^{s p}\left(\mathcal{A}, C^{\prime}\right)$. Changing $b^{\prime}$ into $\neg b^{\prime}$ swaps the events S and $\overline{\mathrm{S}}$, and therefore swaps their probabilities. Hence, for this adversary $C_{\max , j}^{\prime}$,

$$
\begin{aligned}
& \operatorname{Adv}_{G_{j}^{\prime}}^{s p}\left(\mathcal{A}, C_{\max , j}^{\prime}\right) \\
& =\mid \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge \text { branch } j \text { is taken at } \mu\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge \text { branch } j \text { is taken at } \mu\right] \mid \\
& +\mid \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge \mu \text { not executed }\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge \mu \text { not executed }\right] \mid
\end{aligned}
$$

So

$$
\begin{aligned}
& \sum_{j=0}^{k-1} \operatorname{Adv}_{G_{j}^{\prime}}^{s p}\left(\mathcal{A}, C_{\max , j}^{\prime}\right) \\
& \geq \sum_{j=0}^{k-1}\left|\begin{array}{l}
\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge \text { branch } j \text { is taken at } \mu\right] \\
-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge \text { branch } j \text { is taken at } \mu\right]
\end{array}\right| \\
& \quad+\sum_{j=0}^{k-1} \mid \operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \mathrm{S} \wedge \mu \text { not executed }\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[C_{s p}[G]\right]: \overline{\mathrm{S}} \wedge \mu \text { not executed }\right] \mid \\
& \geq \operatorname{Adv}_{G}^{s p}(\mathcal{A}, C)
\end{aligned}
$$

Since $G_{j}^{\prime}$ satisfies $s p$ with public variables $V \cup\{$ guess_br_defined $\}$ up to probability $p_{j}$ and $C_{\max , j}^{\prime}$ is an evaluation context acceptable for $C_{s p}\left[G_{j}^{\prime}\right]$ with public variables $V \cup\{$ guess_br_defined $\}$ that does not contain S nor $\overline{\mathrm{S}}$, we have $\operatorname{Adv}_{G_{j}^{\prime}}^{s p}\left(\mathcal{A}, C_{\max , j}^{\prime}\right) \leq p_{j}\left(\mathcal{A}, C_{\max , j}^{\prime}\right)$. Moreover, by Property 6 , $p_{j}(C)$ depends only on the runtime of $C$, the number of calls $C$ makes to the various oracles (which determine replication bounds), and the length of bitstrings, so we have $p_{j}\left(C_{\max , j}^{\prime}\right)=p_{j}(C)$. (The additional runtime of the context can be neglected.) So $\operatorname{Adv}_{G}^{s p}(\mathcal{A}, C) \leq \sum_{j=0}^{k-1} p_{j}(C)$. Therefore, $G$ satisfies $s p$ with public variables $V$ up to probability $\sum_{j=0}^{k-1} p_{j}$. The proof of the second property for (one-session or bit) secrecy proceeds as for guess $i$ in Lemma 59 .

### 5.1.20 global_dep_anal 26

Extension: A few minor extensions have been implemented with respect to the following description.

The global dependency analysis global_dep_anal $x$ tries to find a set of variables $S$ such that only variables in $S$ depend on $x$. In particular, when the global dependency analysis succeeds, the control flow and the view of the adversary do not depend on $x$, except in cases of negligible probability.

Let $x$ be a variable defined only by random choices $x \stackrel{R}{\leftarrow} T$ where $T$ is a large type. Let $S_{\text {def }}$ be a set of variables defined only by assignments. Let $S_{\text {dep }}$ be a set of variables containing $x$. (Intuitively, $S_{\text {dep }}$ will be a superset of variables that depend on $x$.)

We say that a function $f: T \rightarrow T^{\prime}$ is uniform when each element of $T^{\prime}$ has at most $|T| /\left|T^{\prime}\right|$ antecedents by $f$. In particular, this is true in the following two cases:

- $f$ is such that $f(x)$ is uniformly distributed in $T^{\prime}$ if $x$ is uniformly distributed in $T$.
- $f$ is the restriction to the image of $f^{\prime}$ of an inverse of $f^{\prime}$, where $f^{\prime}$ is a poly-injective function. (We consider that $f(x)$ is undefined when $x$ is not in the image of $f^{\prime}$. Here, in contrast to the rest of the paper, we allow $f: T \rightarrow T^{\prime}$ to be defined only on a subset of $T$.) Precisely, when $x_{k} \in S_{\text {def }}$ is defined by a pattern-matching let $f^{\prime}\left(x_{1}, \ldots, x_{n}\right)=M$ in $P$ else $P^{\prime}$, we have $x_{k}=f_{k}^{\prime-1}(M)$, but furthermore when $x_{k}$ is defined we know that the value of $M$ is in the image of $f^{\prime}$, so we have $x_{k}=f(M)$ where $f=f^{\prime-1}{ }_{\mid \mathrm{im} f^{\prime}}$.

We say that $M$ characterizes a part of $x$ with $S_{\text {def }}, S_{\text {dep }}$ when for all $M_{0}$ obtained from $M$ by substituting variables of $S_{\text {def }}$ with their definition (when there is a dependency cycle among variables of $S_{\text {def }}$, we do not substitute a variable inside its definition), $\alpha M_{0}=M_{0}$ implies $f_{1}\left(\ldots f_{k}\left((\alpha x)\left[\widetilde{M^{\prime}}\right]\right)\right)=f_{1}\left(\ldots f_{k}(x[\widetilde{M}])\right)$ for some uniform functions $f_{1}, \ldots, f_{k}$ and for some $\widetilde{M}$ and $\widetilde{M^{\prime}}$, where $\alpha$ is a renaming of variables of $S_{\text {dep }}$ to fresh variables, $x[\widetilde{M}]$ is a subterm of $M_{0}$, $(\alpha x)\left[\widetilde{M^{\prime}}\right]$ is a subterm of $\alpha M_{0}$, the variables in $S_{\text {dep }}$ do not occur in $\widetilde{M}$ or $\widetilde{M^{\prime}}, T$ is the type of the result of $f_{1}$ (or of $x$ when $k=0$ ), and $T$ is a large type. In that case, the value of $M$ uniquely determines the value of $f_{1}\left(\ldots f_{k}(x[\widetilde{M}])\right)$.

We use a simple rewriting prover to determine that. We consider the set of terms $\mathcal{M}_{0}=$ $\left\{\alpha M_{0}=M_{0}\right\}$, and we rewrite elements of $\mathcal{M}_{0}$ using the first kind of user-defined rewrite rules mentioned in Section 3.1 and the rule $\left\{M_{1} \wedge M_{2}\right\} \cup \mathcal{M}^{\prime} \rightarrow\left\{M_{1}, M_{2}\right\} \cup \mathcal{M}^{\prime}$.

When $\mathcal{M}_{0}$ can be rewritten to a set that contains an equality of the form $f_{1}\left(\ldots f_{k}(x[\widetilde{M}])\right)=$ $f_{1}\left(\ldots f_{k}\left((\alpha x)\left[\widetilde{M^{\prime}}\right]\right)\right)$ or $f_{1}\left(\ldots f_{k}\left((\alpha x)\left[\widetilde{M^{\prime}}\right]\right)\right)=f_{1}\left(\ldots f_{k}(x[\widetilde{M}])\right)$ for some $\widetilde{M}$ and $\widetilde{M^{\prime}}$ such that the variables in $S_{\text {dep }}$ do not occur in $\widetilde{M}$ or $\widetilde{M^{\prime}}$, we have that $M$ characterizes a part of $x$ with $S_{\text {def }}, S_{\text {dep }}$.

We say that $M$ characterizes a part of $x$ when $M$ characterizes a part of $x$ with $\emptyset, S^{\prime}$ where $S^{\prime}$ is $\{x\}$ union the set of all variables except those defined by random choices. (We know that variables different from $x$ and defined by random choices do not depend on $x$, so in the absence of more precise information, we can set $S_{\text {dep }}=S^{\prime}$.)

We say that $\operatorname{only} \operatorname{dep}(\mathcal{A}, x)=S$ when intuitively, only variables in $S$ depend on $x$, and the adversary cannot see the value of $x$. Formally, only_dep $(\mathcal{A}, x)=S$ when

- $S \cap V=\emptyset$.
- Variables of $S$ do not occur in a term $N$ of a return value return ( $N$ ).
- Variables of $S$ except $x$ are defined only by assignments.
- If a variable $y \in S$ occurs in $M$ in let $z: T=M$ in $P$, then $z \in S$.
- Variables in $S$ may occur in defined conditions of find but only at the root of them.
- All terms $M_{j}$ in processes find $\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{[i]} \leq \widetilde{n_{j}}\right.$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $P_{j}$ ) else $P^{\prime}$ are combinations by $\wedge, \vee$, or $\neg$ of terms that either do not contain variables in $S$ or are of the form $M_{1}=M_{2}$ or $M_{1} \neq M_{2}$ where $M_{1}$ characterizes a part of $x$ with $S \backslash\{x\}, S$ and no variable of $S$ occurs in $M_{2}$, or $M_{2}$ characterizes a part of $x$ with $S \backslash\{x\}, S$ and no variable of $S$ occurs in $M_{1}$.

The last item implies that the result of tests does not depend on the values of variables in $S$, except in cases of negligible probability. Indeed, the tests $M_{1}=M_{2}$ with $M_{1}$ characterizes a part of $x$ with $S \backslash\{x\}, S$ and $M_{2}$ does not depend on variables in $S$ are false except in cases of negligible probability, since the value of $M_{1}$ uniquely determines the value of $f_{1}\left(\ldots f_{k}(x[\widetilde{M}])\right)$ and $M_{2}$ does not depend on $f_{1}\left(\ldots f_{k}(x[\widetilde{M}])\right)$, so the equality $M_{1}=M_{2}$ happens for a single value of $f_{1}\left(\ldots f_{k}(x[\widetilde{M}])\right)$, which yields a negligible probability because $f_{1}, \ldots, f_{k}$ are uniform, $x$
is chosen with uniform probability, and the type of the result of $f_{1}$ is large. Similarly, the tests $M_{1} \neq M_{2}$ are true except in cases of negligible probability.

In checking the conditions of only_dep $(\mathcal{A}, x)=S$, we do not consider the parts of the code that are unreachable due to tests whose result is known by the conditions above.

The set $S$ is computed by a fixpoint iteration, starting from $\{x\}$ and adding variables defined by assignments that depend on variables already in $S$.

If we manage to show that only_dep $(\mathcal{A}, x)=S$, we transform the game as follows:

- We replace with false terms $M_{1}=M_{2}$ in conditions of find where $M_{1}$ characterizes a part of $x$ with $S \backslash\{x\}, S$ and no variable of $S$ occurs in $M_{2}$, or symmetrically.
- We replace with true terms $M_{1} \neq M_{2}$ in conditions of find where $M_{1}$ characterizes a part of $x$ with $S \backslash\{x\}, S$ and no variable of $S$ occurs in $M_{2}$, or symmetrically.

Lemma 62 The transformation global_dep_anal requires and preserves Properties 1, 2, 3, 4, and 5. If transformation global_dep_anal transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\text {SNU }}: G, D, E v U s e d$ $\xrightarrow{V} G^{\prime}, D$, EvUsed, where $p$ is an upper bound on the probability that required equalities do not hold.

### 5.1.21 simplify 26,27

Extension: Some extensions have been implemented with respect to the following description.
We use the following transformations in order to simplify games. These transformations exploit the information collected as explained in Section 3

1. Each term $M$ in the game is replaced with a simplified term $M^{\prime}$ obtained by reducing $M$ by user-defined rewrite rules knowing $\mathcal{F}_{P_{M}}$ (see Sections 3.1 and 3.4) and the rewrite rules obtained from $\mathcal{F}_{P_{M}}$ by the above equational prover where $P_{M}$ is the smallest process containing $M$. The replacement is performed only when at least one user-defined rewrite rule has been used, to avoid complicating the game by substituting all variables with their value.
2. When setting inferUnique is true, CryptoVerif tries to prove uniqueness of find[unique ${ }_{e}$ ], as in transformation prove_unique (Section 5.1.4).
3. If $P=$ find[unique?] $\left.\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i}\right]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $P^{\prime}, M_{j}$ does not contain event_abort nor unproved find[unique ${ }_{e}$ ], $\left.u_{j k} \widetilde{i}\right]$ reduces into $M^{\prime}$ by user-defined rewrite rules knowing $\mathcal{F}_{P_{j}}$ (see Sections 3.1 and 3.4 and the rewrite rules obtained from $\mathcal{F}_{P_{j}}$, and $u_{j k}$ does not occur in $M^{\prime}$, then $u_{j k}$ is removed from the $j$-th branch of this find, $i_{j k}$ is replaced with $M^{\prime}\left\{i_{j^{\prime} k^{\prime}} / u_{j^{\prime} k^{\prime}}, j^{\prime} \leq\right.$ $\left.m, k^{\prime} \leq m_{j}\right\}$ in $M_{j 1}, \ldots, M_{j l_{j}}, M_{j}$ and $P_{j}$ is replaced with let $\left.u_{j k} \widetilde{i}\right]:\left[1, n_{j k}\right]=M^{\prime}$ in $P_{j}$. (Intuitively, $\left.u_{j k} \widetilde{i}\right]=M^{\prime}$, so the value of $u_{j k} \widetilde{[i]}$ can be computed by evaluating $M^{\prime}$ instead of performing an array lookup. We remove $u_{j k} \widetilde{[i]}$ from the variables looked up by find and replace $u_{j k}[\widetilde{i}]$ with its value $M^{\prime}$.)
4. Suppose that $P=$ find $[$ unique? $]\left(\bigoplus_{j=1}^{m} u_{j 1}[\widetilde{i}]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{i}\right]=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $P^{\prime}$, there exists a term $M$ such that defined $(M) \in \mathcal{F}_{P_{j}}, x\left[N_{1}, \ldots, N_{l}\right]$ is a subterm of $M, x \neq u_{j k}$ for all $k \leq m_{j}$, and none of the following conditions holds: a) $P$ is under a definition of $x$ in $Q_{0}$; b) $Q_{0}$ contains $Q_{1} \mid Q_{2}$ such that a definition of $x$ occurs in $Q_{1}$ and $P$ is under $Q_{2}$ or a definition of $x$ occurs in $Q_{2}$ and $P$ is under $Q_{1}$; c) $Q_{0}$ contains $l p+1$ replications above a process $Q$
that contains a definition of $x$ and $P$, where $l p$ is the length of the longest common prefix between $N_{1}, \ldots, N_{l}$ and the current replication indices at the definitions of $x$. Then the $j$-th branch of the find is removed. (In this case, $x\left[N_{1}, \ldots, N_{l}\right]$ cannot be defined at $P$, so the $j$-th branch of the find cannot be taken.)
5. Suppose that $P=$ find[unique?] $\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{i}\right]=i_{j 1} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i]}=i_{j m_{j}} \leq n_{j m_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $P^{\prime}$, there exist terms $M, M^{\prime}$ such that $\operatorname{defined}(M) \in \mathcal{F}_{P_{j}}, x\left[N_{1}, \ldots, N_{l}\right]$ is a subterm of $M$, defined $\left(M^{\prime}\right) \in \mathcal{F}_{P_{j}}, x^{\prime}\left[N_{1}^{\prime}, \ldots, N_{l^{\prime}}^{\prime}\right]$ is a subterm of $M^{\prime}, N_{k}=N_{k}^{\prime}$ for all $k \leq \min \left(l, l^{\prime}\right), x \neq x^{\prime}$, and $x$ and $x^{\prime}$ are incompatible, then the $j$-th branch of the find is removed. Two variables $x$ and $x^{\prime}$ are said to be compatible when either there exists $Q_{1} \mid Q_{2}$ in the game such that $x$ is defined in $Q_{1}$ and $x^{\prime}$ is defined in $Q_{2}$, or there is a definition of $x^{\prime}$ under a definition of $x$, or symmetrically.
6. If $P=\operatorname{find}[$ unique? $]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}} \operatorname{suchthat~defined}\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $P^{\prime}$ and $\mathcal{F}_{P_{j}}$ yields a contradiction, then the $j$-th branch of the find is removed if $M_{j}$ does not contain event_abort nor unproved find[unique ${ }_{e}$ ], and $P_{j}$ is replaced with yield if $M_{j}$ contains event_abort or some unproved find[unique $e_{e}$.
7. If $P=$ find $\left[u n i q u e\right.$ ?] else $P^{\prime}$, then $P$ is replaced with $P^{\prime}$.
8. If find [unique?] $\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{i}\right]=\widetilde{i_{j}} \leq \widetilde{n_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then $\left.P_{j}\right)$ else $P^{\prime}$ and $\mathcal{F}_{P^{\prime}}$ yields a contradiction, then $P^{\prime}$ is replaced with yield.
9. If $P=\operatorname{find}[$ unique? $] \widetilde{u}[\widetilde{i}]=\widetilde{i^{\prime}} \leq \widetilde{n}$ suchthat defined $\left(M_{1}, \ldots, M_{l}\right) \wedge M$ then $P_{1}$ else $P^{\prime}$, [unique?] is not [unique ${ }_{e}$ ] for some non-unique event $e$ that is not proved yet to have negligible probability, $\mathcal{F}_{P^{\prime}}$ yields a contradiction, $M$ is simple (so $M$ never aborts), and the variables in $\widetilde{u}$ are not used outside $P$ and are not in $V$, then $P$ is replaced with $P_{1}$. (When the find defines variables $\widetilde{u}$ used elsewhere, we cannot remove it.)
10. If $P=$ find $[$ unique? $]\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \widetilde{i}\right] \leq \widetilde{n_{j}}$ suchthat defined $\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}$ then yield) else yield, [unique?] is not [unique ${ }_{e}$ ] for some non-unique event $e$ that is not proved yet to have negligible probability, the terms $M_{j}$ do not contain event_abort nor unproved find[unique ${ }_{e}$ ], and the variables in $\widetilde{u_{j}}$ are not used outside $P$ and are not in $V$, then $P$ is replaced with yield.
11. The defined conditions of find are updated so that Invariant 2 is satisfied. (When such a defined condition guarantees that $M$ is defined, defined $(M)$ implies defined $\left(M^{\prime}\right)$, and after simplification $M^{\prime}$ appears in the scope of this condition, then $M^{\prime}$ has to be added to this condition if it is not already present.)
12. If $P=x \stackrel{R}{\leftarrow} T ; P^{\prime}$ or let $x: T=M$ in $P^{\prime}$ and $x$ is not used in the game and is not in $V$, then $P$ is replaced with $P^{\prime}$.
13. If one of the then branches of a find[unique] always succeeds and the conditions of this find [unique] do not contain event_abort nor unproved find[unique $e_{e}$ ], then we keep only that branch.

Indeed, the other branches are never taken: the conditions of this find[unique] never abort in traces counted in the probability, and the find itself aborts when there are several successful choices.
14. We reorganize a find[unique] that occurs in a then branch of a find[unique]: we transform

$$
\text { find }[\text { unique }]\left(\bigoplus_{j=1}^{k} \tilde{u}_{j}=\tilde{i}_{j} \leq \tilde{n}_{j} \text { suchthat } c_{j} \text { then } P_{j}\right) \text { else } P
$$

where $P_{j_{0}}=$ find [unique] $\left(\bigoplus_{j^{\prime}=1}^{k^{\prime}} F B_{j^{\prime}}\right)$ else $P_{j_{0}}^{\prime \prime}$ into

$$
\begin{aligned}
& \text { find [unique }]\left(\bigoplus_{j=1, \ldots, k ; j \neq j_{0}} \tilde{u}_{j}=\tilde{i}_{j} \leq \tilde{n}_{j} \text { suchthat } c_{j} \text { then } P_{j}\right) \\
& \oplus\left(\bigoplus_{j^{\prime}=1}^{k^{\prime}} \bigoplus_{\left(\tilde{u}^{\prime}=\tilde{i}^{\prime} \leq \tilde{n}^{\prime} \text { suchthat } c^{\prime} \text { then } P^{\prime}\right) \in \mathbf{b}\left(F B_{j^{\prime}}, L_{j^{\prime}}\right)}\right. \\
& \left.\qquad \tilde{u}_{j_{0}}=\tilde{i}_{j_{0}} \leq \tilde{n}_{j_{0}}, \tilde{u}^{\prime}=\tilde{i}^{\prime} \leq \tilde{n}^{\prime} \text { suchthat } c_{j_{0}} \wedge c^{\prime} \text { then } P^{\prime}\right) \\
& \text { else find [unique } \tilde{u}_{j_{0}}=\tilde{i}_{j_{0}} \leq \tilde{n}_{j_{0}} \text { suchthat } c_{j_{0}} \text { then } P_{j_{0}}^{\prime \prime} \text { else } P
\end{aligned}
$$

where

- either for all $j \leq k, c_{j}$ does not contain event_abort nor unproved find[unique ${ }_{e}$ ] or $c_{j_{0}}$ never aborts (this is true in particular when $c_{j_{0}}$ does not contain event_abort nor proved or unproved find[unique $e$ ])
$-\tilde{i}$ are the current replication indices at the transformation point
- for all $j^{\prime}, F B_{j^{\prime}}=\left(\tilde{u}_{j^{\prime}}^{\prime}=\tilde{i}_{j^{\prime}}^{\prime} \leq \tilde{n}_{j^{\prime}}^{\prime}\right.$ suchthat $c_{j^{\prime}}^{\prime}$ then $\left.P_{j^{\prime}}^{\prime}\right), c_{j^{\prime}}^{\prime}=\operatorname{defined}\left(\tilde{M}_{j^{\prime}}\right) \wedge \ldots, c_{j^{\prime}}^{\prime}$ never aborts, and $L_{j^{\prime}}$ is the list of $x[\tilde{N}]$ subterm of $\tilde{M}_{j^{\prime}}$ with $x \in \tilde{u}_{j_{0}}$ and $\tilde{N} \neq \tilde{i}$, ordered by increasing size
$-\mathrm{b}\left(\tilde{u}^{\prime}=\tilde{i}^{\prime} \leq \tilde{n}^{\prime}\right.$ suchthat $c^{\prime}$ then $\left.P^{\prime},[]\right)=\left\{\tilde{u}^{\prime}=\tilde{i}^{\prime} \leq \tilde{n}^{\prime}\right.$ suchthat $c^{\prime}\left\{\tilde{i}_{j_{0}} / \tilde{u}_{j_{0}}\right\}$ then $\left.P^{\prime}\right\}$
${ }_{\sim}^{-} \mathrm{b}(F B, x[\tilde{N}]:: L)=\mathrm{b}(F B, L) \cup\left\{\tilde{u}^{\prime}=\tilde{i}^{\prime} \leq \tilde{n}^{\prime}\right.$ suchthat $c^{\prime}\{i / x[\tilde{N}]\} \wedge \tilde{N}=\tilde{i}$ then $P^{\prime} \mid\left(\tilde{u}^{\prime}=\right.$ $\tilde{i}^{\prime} \leq \tilde{n}^{\prime}$ suchthat $c^{\prime}$ then $\left.\left.P^{\prime}\right) \in \mathrm{b}(F B, L)\right\}$ where $i=x\left\{\tilde{i}_{j_{0}} / \tilde{u}_{j_{0}}\right\}$.
The function b takes into account that, before the transformation, $\tilde{u}_{j_{0}}[\tilde{i}]$ is defined when we test defined $\left(\tilde{M}_{j^{\prime}}\right)$ in $F B_{j^{\prime}}$, while after the transformation, $\tilde{u}_{j_{0}}[\tilde{i}]$ is not defined yet when we perform this test. Furthermore, the value of $\tilde{u}_{j_{0}}[\tilde{i}]$ will be $\tilde{i}_{j_{0}}$. Therefore, 1) when we access $x[\tilde{i}]$ in $c_{j^{\prime}}^{\prime}=\operatorname{defined}\left(\tilde{M}_{j^{\prime}}\right) \wedge \ldots$, we replace this access with $i$, where $i=x\left\{\tilde{i}_{j_{0}} / \tilde{u}_{j_{0}}\right\}$; this is done in $\mathrm{b}(F B,[])$ by the substitution $\left\{\tilde{i}_{j_{0}} / \tilde{u}_{j_{0}}\right\}$; and 2$)$ when we access $x[\tilde{N}]$ in $c_{j^{\prime}}^{\prime}=\operatorname{defined}\left(\tilde{M}_{j^{\prime}}\right) \wedge \ldots$ for $\tilde{N}$ not syntactically equal to $\tilde{i}$, we need to distinguish two cases: either at runtime $\tilde{N}=\tilde{i}$ and we replace this access with $i$ (second part of the union in $\mathrm{b}(F B, x[\tilde{N}]:: L)$ ), or at runtime $\tilde{N} \neq \tilde{i}$ and we continue using $x[\tilde{N}]$ (first part of the union in $\mathrm{b}(F B, x[\tilde{N}]:: L))$. The array accesses $x[\tilde{N}]$ in $L_{j^{\prime}}$ are ordered by increasing size because, in case of nested array accesses, we need to handle the bigger array access first (so it must occur last in the list), because after substitution of the smaller one with $i$, we would not recognize the bigger one.
This transformation cannot be performed when the outer find is not unique because it might change the probability of taking each branch. Moreover, we tried performing such a transformation when the inner find is not unique (in this case, after transformation, the outer find is not unique), but it had a negative impact in some examples. Furthermore, in the latter case, the transformation can be performed manually by inserting the desired outer find and simplifying the game: CryptoVerif will remove the useless branches of find.
The conditions $c_{j_{0}}$ and $c_{j^{\prime}}^{\prime}$ are conjunctions of defined conditions and a term. In the current implementation, the transformation is not performed when the term in $c_{j_{0}}$ is false (the branch of find will be removed by another transformation), and the branches such that the terms in $c_{j^{\prime}}^{\prime}$ are false are first removed. Furthermore, the transformation is performed only when one of the following conditions holds: the terms in $c_{j_{0}}$ and all $c_{j^{\prime}}^{\prime}$ are simple, or
the term in $c_{j_{0}}$ is true and all $c_{j^{\prime}}^{\prime}$ never abort, or the terms in $c_{j^{\prime}}^{\prime}$ are all true and $c_{j_{0}}$ never aborts. With the usual simplification of $\wedge$ true, this guarantees that the transformed game satisfies Property 5 . Moreover, this implies the abortion conditions ( $c_{j_{0}}$ and all $c_{j^{\prime}}^{\prime}$ never abort).
After this transformation, we advise renaming the variables $\tilde{u}_{j_{0}}$ to distinct names, since they now have multiple definitions.

15. We reorganize a find[unique] that occurs in a condition of a find: we transform

$$
\operatorname{find}[u n i q u e ?]\left(\bigoplus_{j=1}^{k} \tilde{u}_{j}=\tilde{i}_{j} \leq \tilde{n}_{j} \text { suchthat } c_{j} \text { then } P_{j}\right) \text { else } P
$$

where

$$
c_{j_{0}}=\operatorname{defined}\left(\tilde{M}^{\prime}\right) \wedge \text { find }[\text { unique }]\left(\bigoplus_{j^{\prime}=1}^{k^{\prime}} \tilde{u}_{j^{\prime}}^{\prime}=\tilde{i}_{j^{\prime}}^{\prime} \leq \tilde{n}_{j^{\prime}}^{\prime} \text { suchthat } c_{j^{\prime}}^{\prime} \text { then } M_{j^{\prime}}^{\prime}\right) \text { else false }
$$

for all $j^{\prime} \leq k^{\prime}, M_{j^{\prime}}^{\prime}$ never aborts and either for all $j \leq k, c_{j}$ does not contain event_abort nor unproved find [unique ${ }_{e}$ ] or for all $j^{\prime} \leq k^{\prime}, c_{j^{\prime}}^{\prime}$ never aborts, into

$$
\begin{aligned}
& \text { find }[\text { unique } ?]\left(\bigoplus_{j=1, \ldots, k ; j \neq j_{0}} \tilde{u}_{j}=\tilde{i}_{j} \leq \tilde{n}_{j} \text { suchthat } c_{j} \text { then } P_{j}\right) \\
& \oplus\left(\bigoplus_{j^{\prime}=1}^{k^{\prime}} \tilde{u}_{j_{0}}=\tilde{i}_{j_{0}} \leq \tilde{n}_{j_{0}}, \tilde{u}_{j^{\prime}}^{\prime}=\tilde{i}_{j^{\prime}}^{\prime} \leq \tilde{n}_{j^{\prime}}^{\prime}\right. \text { suchthat } \\
& \left.\quad \operatorname{defined}\left(\tilde{M}^{\prime}\right) \wedge c_{j^{\prime}}^{\prime} \wedge M_{j^{\prime}}^{\prime}\left\{\tilde{i}_{j^{\prime}}^{\prime} / \tilde{u}_{j^{\prime}}^{\prime}\right\} \text { then } P_{j_{0}}\right)
\end{aligned}
$$

The indication [unique?] corresponds to either [unique] or empty. The find is marked [unique] after transformation if the outer find was [unique] before transformation.
The variables $\tilde{u}_{j^{\prime}}^{\prime}$ are defined inside the condition of a find so by Invariant 3 , they have no array accesses. The transformation performed by function $b$ above is therefore not needed here.
The conditions $c_{j^{\prime}}^{\prime}$ are conjunctions of defined conditions and a term. The current implementation first removes the branches such that one of the following two conditions holds: the terms in $c_{j^{\prime}}^{\prime}$ are false or $M_{j^{\prime}}^{\prime}$ is false and $c_{j^{\prime}}^{\prime}$ never aborts. Furthermore, the transformation is performed only when for all $j^{\prime}$, one of the following conditions holds: the term in $c_{j^{\prime}}^{\prime}$ and $M_{j^{\prime}}$ are simple, or the term in $c_{j^{\prime}}^{\prime}$ is true and $M_{j^{\prime}}^{\prime}$ never aborts, or $M_{j^{\prime}}^{\prime}$ is true or false and the term in $c_{j^{\prime}}^{\prime}$ never aborts. With the usual simplification of $\wedge$ true and $\wedge$ false, this guarantees that the transformed game satisfies Property 5. Moreover, this implies the abortion conditions ( $c_{j^{\prime}}^{\prime}$ and $M_{j^{\prime}}^{\prime}$ never abort).

The simplification is iterated at most maxIterSimplif times. The iteration stops earlier in case a fixpoint is reached.

Lemma 63 The transformation simplify requires and preserves Properties 1, 2, 3, and 4, It preserves 5. If transformation simplify transforms $G$ into $G^{\prime}$, then $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, D$, EvUsed $\xrightarrow{V}_{p} G^{\prime}, D$, EvUsed, where $p$ is an upper bound on the probability that required equalities do not hold.

Extension: When the game is not expanded, simplify is actually a weaker simplification transformation. We plan to improve that.

### 5.1.22 all_simplify

all_simplify perform several simplifications on the game, as if

- simplify,
- move all if autoMove $=$ true,
- remove_assign useless if autoRemoveAssignFindCond $=$ false, remove_assign findcond if autoRemoveAssignFindCond $=$ true,
- SArename random if autoSARename $=$ true,
- and merge_branches if autoMergeBranches $=$ true
had been called.


### 5.1.23 success simplify

The transformation success simplify is a combination of success (Section 4) and simplify (Section 5.1.21), with the following addition. First, in the success step, the command success simplify collects information that is known to be true when the adversary manages to break at least one of the desired properties. Then, the first iteration of the simplify step removes parts of the game that contradict this information and replaces them with event_abort adv_loses.

In more detail, success simplify collects a set $\mathcal{L}^{-}$of $(\mathcal{V}, \mathcal{F})$ and a set of formulas $\mathcal{L}^{+}$. If the adversary breaks a desired security property, then either there exists a set of facts $\mathcal{F}$ in $\mathcal{L}^{-}$ that holds or there exists a formula in $\mathcal{L}^{+}$that holds. The sets of facts $\mathcal{L}^{-}$correspond to cases in which the proof of the security property failed; their probability may be high. The associated variables $\mathcal{V}$ are replication indices and non-process variables that occur in $\mathcal{F}$. The formulas in $\mathcal{L}^{+}$correspond to cases in which the security property was proved (up to a certain probability); these formulas are negations of the formulas that prove the security property in the considered case; the probability that they hold is bounded by the equational prover of CryptoVerif. The contents of $\mathcal{L}^{+}$does not influence the game obtained after the transformation. It is useful to compute the probability difference coming from the transformation. The sets $\mathcal{L}^{-}$and $\mathcal{L}^{+}$are computed as follows:

- In case there is an indistinguishability query, or a (one-session or bit) secrecy query on a variable $x$ not defined only by $\stackrel{R}{\leftarrow}$ or by assignments of variables defined by $\stackrel{R}{\leftarrow}$, or a correspondence query $\forall \widetilde{x}: \widetilde{T} ; \psi \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$ with some event $e$ in $\psi$ such that the game contains event $e(\widetilde{M})$ and some term in $\widetilde{M}$ is not simple, no information is collected at all and simplify is not performed.
- For each correspondence query event $(e) \Rightarrow$ false where $e$ is a non-unique event, for every $\mu$ that executes event $(e)$, for every $c,\left(\theta^{\prime} I_{\mu}, \theta^{\prime} \mathcal{F}_{\text {event }(e), \mu, c}^{0}\right)$ is added to $\mathcal{L}^{-}$, for some $\theta^{\prime}$ renaming of $I_{\mu}$ to fresh replication indices. (Indeed, in order to break event $(e) \Rightarrow$ false, event $e$ must be executed, so the facts $\mathcal{F}_{\text {event }(e), \mu, c}^{0}$ at some execution of event $e$ hold.)
- For each other correspondence query $\forall \widetilde{x}: \widetilde{T} ; F_{1} \wedge \cdots \wedge F_{m} \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$, let $\varphi=\llbracket \forall \widetilde{x}$ : $\widetilde{T} ; F_{1} \wedge \cdots \wedge F_{m} \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi \rrbracket$ and $\mathcal{S}_{0}=\left\{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \mid \forall j \leq m, \mu_{j}\right.$ executes $F_{j}$ and $c_{j}$ is a case for $\left.\mathcal{F}_{\mu_{j}, c_{j}}\right\}$; by trying to prove the correspondence, we build a subset $\mathcal{S}_{1}$ of $\mathcal{S}_{0}$, a family of substitutions $\theta$, and a pseudo-formula $\mathcal{C}$ such that prove ${ }^{\varphi}\left(\mathcal{C}, \theta, \mathcal{S}_{1}\right)$. ( $\theta$ and $\mathcal{C}$ are computed incrementally on the successful cases in the proof of the correspondence.)

For all $\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \in \mathcal{S}_{0} \backslash \mathcal{S}_{1}$ (success fails to prove the correspondence for those cases):

- If the query is $\forall \widetilde{x}: \widetilde{T} ; \operatorname{event}(e(\widetilde{N})) \Rightarrow$ false and the process or term at $\mu_{1}$ is event $e(\widetilde{M})$; $\ldots$, then $\left(\widetilde{x} \cup \theta^{\prime} I_{\mu_{1}}, \theta^{\prime} \mathcal{F}_{\mu_{1}, c_{1}} \cup\left\{\right.\right.$ lastdefprogrampoint $\left.\left.\left(\mu_{1}, \theta^{\prime} I_{\mu_{1}}\right), \widetilde{N}=\theta^{\prime} \widetilde{M}\right\}\right)$ is added to $\mathcal{L}^{-}$, where $\theta^{\prime}$ is a renaming of $I_{\mu_{1}}$ to fresh replication indices. (We can stop the trace just after event $e$ without changing the truth of the query, and that is more precise because we can use the elsefind facts at $e$.)
- Otherwise, $\left(\widetilde{x} \cup \bigcup_{j=1}^{m} \theta_{j} I_{\mu_{j}}, \bigcup_{j=1}^{m} \theta_{j} \mathcal{F}_{F_{j}, \mu_{j}, c_{j}}\right)$ is added to $\mathcal{L}^{-}$, where for $j \leq m, \theta_{j}$ is a renaming of $I_{\mu_{j}}$ to fresh replication indices. (Indeed, in order to break the correspondence $\forall \widetilde{x}: \widetilde{T} ; F_{1} \wedge \cdots \wedge F_{m} \Rightarrow \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$, the events $F_{1}, \ldots, F_{m}$ must be executed, so the facts $\mathcal{F}_{F_{j}, \mu_{j}, c_{j}}$ for $j \leq m$ that hold when $F_{1}, \ldots, F_{m}$ are executed certainly hold when the correspondence is broken. In principle, we could add $\neg \exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$ to the facts $\bigcup_{j=1}^{m} \theta_{j} \mathcal{F}_{F_{j}, \mu_{j}, c_{j}}$ added to $\mathcal{L}^{-}$. However, we have no way to express universal quantification in general in known facts, so when $\widetilde{y}$ is not empty, we could not add $\forall \widetilde{y}: \widetilde{T^{\prime}} ; \neg \phi$ but would end up adding $\neg \phi$ which in fact means $\exists \widetilde{y}: \widetilde{T}^{\prime} ; \neg \phi$. That would remain sound assuming the types in $\widetilde{T}^{\prime}$ are not empty, but would be weaker. Moreover, in practice, we end up having to distinguish precisely the case in which $\exists \widetilde{y}: \widetilde{T}^{\prime} ; \phi$ can be proved from the case in which it cannot, which can typically be done by inserting an appropriate find. We generally insert a Shoup event $e$ in the else branch of that find, triggered when the correspondence cannot be proved, a case for which we want to bound the probability. After that, it remains to prove event $(e) \Rightarrow$ false: we apply success simplify to that correspondence. Adding $\neg \phi=$ true would not change anything for that correspondence, and we exploit that the condition of the inserted find is false at event $e$, which gives us more precise information than having added $\neg \phi$ for the initial correspondence.)

Moreover, $\neg\left\{\left[\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mathcal{S}_{1}\right)\right]\right\}$ is added to $\mathcal{L}^{+}$. (success proves the correspondence for the cases in $\mathcal{S}_{1}$.)

- For each secrecy, one-session secrecy, or bit secrecy query on a variable $x$ defined only by $\stackrel{R}{\leftarrow}$ or by assignments of variables defined by $\stackrel{R}{\leftarrow}$, let $\mathcal{S}_{0}=\{\mu \mid \mu$ follows a definition of $x\}$ and $\mathcal{S}_{1}=\left\{\mu \in \mathcal{S}_{0} \mid\right.$ prove $\left.^{1 \text {-ses.secr. }(x)}(\mu)\right\}$.
For each $\mu \in \mathcal{S}_{0} \backslash \mathcal{S}_{1}$ (success fails to prove one-session secrecy for those cases), $\left(\theta I_{\mu}, \theta \mathcal{F}_{\mu}\right)$ is added to $\mathcal{L}^{-}$, where $\theta$ is a renaming of $I_{\mu}$ to fresh replication indices. (Indeed, if secrecy, one-session secrecy, or bit secrecy of $x$ is broken, a definition of $x$ must have been executed, so the facts $\mathcal{F}_{\mu}$ at that definition hold.)
Moreover, $\neg\left\{\left[\right.\right.$ prove $\left.{ }^{1 \text {-ses.secr. }(x)}\left(\mathcal{S}_{1}\right)\right\}$ is added to $\mathcal{L}^{+}$. (success proves one-session secrecy for the cases in $\mathcal{S}_{1}$.)
Additionally, if the considered query is a secrecy query, then for each $\mu_{1}, \mu_{2} \in \mathcal{S}_{0}$, let $z_{1}\left[\widetilde{M}_{1}\right]=\operatorname{defRand}_{\mu_{1}}(x)$ and $z_{2}\left[\widetilde{M}_{2}\right]=\operatorname{defRand}_{\mu_{2}}(x)$. If $z_{1} \neq z_{2}$, then the definitions at $\mu_{1}$ and $\mu_{2}$ are proved to be independent, and nothing is added to $\mathcal{L}^{-}$nor $\mathcal{L}^{+}$. If $z_{1}=z_{2}$, let $\widetilde{i}$ be the current replication indices at the definition of $x$, let $\theta_{1}$ and $\theta_{2}$ be two distinct renamings of $\widetilde{i}$ to fresh replication indices, let $\widetilde{i}_{1}=\theta_{1} \widetilde{i}$ and $\widetilde{i}_{2}=\theta_{2} \widetilde{i}$, let $\mathcal{F}=\theta_{1} \mathcal{F}_{\mu_{1}} \cup \theta_{2} \mathcal{F}_{\mu_{2}} \cup\left\{\theta_{1} \widetilde{M}_{1}=\theta_{2} \widetilde{M}_{2}, \widetilde{i}_{1} \neq \widetilde{i}_{2}\right\}$. If $\mathcal{F}$ yields a contradiction, then the definitions at $\mu_{1}$ and $\mu_{2}$ are proved to be independent up to a small probability, $\exists \widetilde{i_{1}}, \exists \widetilde{i_{2}}, \bigwedge \mathcal{F}$ is added to $\mathcal{L}^{+}$. Otherwise, $\left(\widetilde{i_{1}} \cup \widetilde{i_{2}}, \mathcal{F}\right)$ is added to $\mathcal{L}^{-}$.

In the simplify step, the set $\mathcal{L}^{-}$is used as follows: for each program point $\mu$ not in a condition of find, if for all $(\mathcal{V}, \mathcal{F}) \in \mathcal{L}^{-}, \mathcal{F}_{\mu} \cup \mathcal{F}$ yields a contradiction, then the code at $\mu$ is replaced with event_abort adv_loses. (The reason why $\mathcal{V}$ is needed in the implementation is for the optimization of probabilities of collisions: we determine using which indices in $\mathcal{V}$ we get the smaller bound for the number of collisions.)

The probability that a security property is broken before the transformation and not after is then bounded by the probability that a modified program point $\mu$ is reached and the adversary breaks the property. If that breach corresponds to a case in $\mathcal{L}^{+}$, the probability of the breach itself is bounded by construction of $\mathcal{L}^{+}$. If that breach corresponds to a case in $\mathcal{L}^{-}$, the probability of the breach and reaching $\mu$ is bounded because for all $(\mathcal{V}, \mathcal{F}) \in \mathcal{L}^{-}, \mathcal{F}_{\mu} \cup \mathcal{F}$ yields a contradiction, which bounds the probability that the facts $\mathcal{F}_{\mu} \cup \mathcal{F}$ hold for some $(\mathcal{V}, \mathcal{F}) \in \mathcal{L}$, and $\mathcal{F}_{\mu}$ holds when $\mu$ is reached while some $\mathcal{F}$ in $\mathcal{L}$ holds when the adversary breaks the property. This is formalized by the following lemma.

Lemma 64 The transformation success simplify requires and preserves Properties 1, 2, 3, 4, and 5 .

If transformation success simplify transforms $G$ into $G^{\prime}$, the distinguisher $D$ is a disjunction of Shoup and non-unique events, the property sp and the disjuncts in $D$ correspond to active queries, $\mathcal{L}^{-}=\left\{\left(\mathcal{V}_{j}, \mathcal{F}_{j}\right) \mid j \in J\right\}$, the modified program points are $\mu_{k}$ for $k \in K$, $\mathcal{F}_{k}^{\bmod }=\mathcal{F}_{\mu_{k}}$, for all $\mathcal{A} \in \mathcal{B B}$ and all evaluation contexts $C$ acceptable for $G$, $\operatorname{Pr}^{\mathcal{A}}[C[G] \preceq$ $\left.\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \bigwedge \mathcal{F}_{k}^{\bmod }\right) \vee\left(\bigvee \mathcal{L}^{+}\right)\right] \leq p(\mathcal{A}, C)$, and $\operatorname{Bound}_{G^{\prime}}\left(V, s p, D, p^{\prime}\right)$, then we have $\operatorname{Bound}_{G}\left(V, s p, D, p+p^{\prime}\right)$.

Unfortunately, we cannot prove $\mathcal{D}, \mathcal{D}_{\mathrm{SNU}}: G, D$, EvUsed $\xrightarrow{V}{ }_{p} G^{\prime}, D$, EvUsed $\cup\{$ adv_loses $\}$ for the transformation success simplify, because, in case of (one-session or bit) secrecy of a variable $x$, the inequality needed for this property may not hold: we need to take into account that, when $x$ is not defined, traces that execute S and those that execute $\overline{\mathrm{S}}$ compensate in the computation of $\operatorname{Adv}_{G}(\mathcal{A}, C, s p, D)$ in order to prove the soundness of this transformation. We cannot prove this soundness independently for $\operatorname{Pr}^{\mathcal{A}}[C[G]: \mathrm{S}]$ and for $\operatorname{Pr}^{\mathcal{A}}[C[G]: \neg \overline{\mathrm{S}}]$.

Moreover, in the implementation, for (one-session or bit) secrecy properties, a probability $2 p(\mathcal{A}, C)$ is added instead of just $p(\mathcal{A}, C)$ as shown by the lemma above. The factor 2 is difficult to avoid because other simplifications are performed at the same time as described in the transformation simplify (Section 5.1.21), and the factor 2 is needed for these transformations.

## Proof

Fact 1. Let $\varphi$ be a correspondence not of the form $\forall \widetilde{x} \in \widetilde{T}$, event $(e(\widetilde{N})) \Rightarrow$ false, or the correspondence event $(e) \Rightarrow$ false for some Shoup event $e$. Let $C$ be any evaluation context acceptable for $G$ with public variables $V$ that does not contain events used by $\varphi$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Let $\operatorname{Tr}$ be any full trace of $C[G]$ for $\mathcal{A}$ that does not execute any non-unique event of $G$ and such that $\operatorname{Tr} \vdash \neg \varphi$. Then $\operatorname{Tr} \vdash\left(\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.

Proof of Fact 1. By Lemma 42, for any substitutions $\theta\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)$ equal to the identity on $\widetilde{x}$, for any pseudo-formula $\mathcal{C}$,

$$
\operatorname{Tr} \vdash \neg\left\{\left[\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mathcal{S}_{0}\right)\right]\right\}
$$

So

$$
\left.\left.\operatorname{Tr} \vdash\left(\neg\left\{\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mathcal{S}_{1}\right)\right]\right\}\right) \vee\left(\bigvee_{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \in \mathcal{S}_{0} \backslash \mathcal{S}_{1}} \neg\left\{\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)\right]\right\}\right)
$$

Moreover, $\neg\left\{\left[\mathcal{F} \models_{\theta}^{\mathcal{I}, \mathcal{V}, \mathcal{C}} \phi\right]\right\} \Rightarrow \exists \widetilde{z} \in \widetilde{T}^{\prime \prime}, \bigwedge \mathcal{F}$ where $\widetilde{z}=\mathcal{V}$ and $\widetilde{T}^{\prime \prime}$ are the types of these variables, by an easy induction on $\phi$, so $\left.\neg\left\{\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right)\right]\right\} \Rightarrow \exists \theta_{1} I_{\mu_{1}}, \ldots, \exists \theta_{m} I_{\mu_{m}}, \exists \widetilde{x} \in \widetilde{T}$, $\bigwedge \theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}}$ where, for $j \leq m, \theta_{j}$ is a renaming of $I_{\mu_{j}}$ to fresh replication indices. So

$$
\begin{aligned}
& \operatorname{Tr} \vdash\left(\neg\left\{\left[\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mathcal{S}_{1}\right)\right]\right\}\right) \vee \\
& \quad\left(\bigvee_{\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \in \mathcal{S}_{0} \backslash \mathcal{S}_{1}} \exists \theta_{1} I_{\mu_{1}}, \ldots, \exists \theta_{m} I_{\mu_{m}}, \exists \widetilde{x} \in \widetilde{T}, \bigwedge \theta_{1} \mathcal{F}_{F_{1}, \mu_{1}, c_{1}} \cup \cdots \cup \theta_{m} \mathcal{F}_{F_{m}, \mu_{m}, c_{m}}\right)
\end{aligned}
$$

The formula $\neg\left\{\left[\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta, \mathcal{S}_{1}\right)\right]\right\}$ is added to $\mathcal{L}^{+}$and $\left(\widetilde{x} \cup \bigcup_{j=1}^{m} \theta_{j} I_{\mu_{j}}, \bigcup_{j=1}^{m} \theta_{j} \mathcal{F}_{F_{j}, \mu_{j}, c_{j}}\right)$ is added to $\mathcal{L}^{-}$when $\left(\mu_{1}, c_{1}, \ldots, \mu_{m}, c_{m}\right) \in \mathcal{S}_{0} \backslash \mathcal{S}_{1}$ (recall that, when $e$ is Shoup event, $e$ is always executed by event_abort $e)$ so $\operatorname{Tr} \vdash\left(\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.

Fact 2. Let $e$ be a non-unique event. Let $C$ be any evaluation context acceptable for $G$ with public variables $V$ that does not contain $e$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Let $\operatorname{Tr}$ be any full trace of $C[G]$ for $\mathcal{A}$ such that $\operatorname{Tr} \vdash e$. Then $\operatorname{Tr} \vdash\left(\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.

Proof of Fact 2. By Lemma 38, there exist a program point $\mu($ in $G$ ) and a case $c$ such that, for any $\theta^{\prime}$ renaming of $I_{\mu}$ to fresh replication indices, there exists a mapping $\sigma$ with domain $\theta^{\prime} I_{\mu}$ such that $\operatorname{Tr}, \sigma \vdash \theta^{\prime} \mathcal{F}_{\text {event }(e), \mu, c}^{0}$. Let $(\mathcal{V}, \mathcal{F})=\left(\theta^{\prime} I_{\mu}, \theta^{\prime} \mathcal{F}_{\text {event }(e), \mu, c}^{0}\right)$ be the element of $\mathcal{L}^{-}$for $\mu$ and $c$, in the treatment of correspondence event $(e) \Rightarrow$ false. We have $\operatorname{Tr} \vdash \exists \mathcal{V}, \bigwedge \mathcal{F}$. Therefore, $\operatorname{Tr} \vdash \bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}$.

Fact 3. Let $C$ be any evaluation context acceptable for $G$ with public variables $V$ and $\mathcal{A}$ be an attacker in $\mathcal{B B}$. Let $\operatorname{Tr}$ be any trace of $C[G]$ for $\mathcal{A}$. If $\operatorname{Tr} \vdash \neg \bigvee_{k \in K} \exists I_{\mu_{k}}, \bigwedge \mathcal{F}_{k}^{\text {mod }}$, then there is no configuration in $T r$ at a modified program point $\mu_{k}$.

Proof of Fact 3. By contraposition, if there is a configuration $\operatorname{Conf}=E, \sigma,{ }^{\mu_{k}} M, \mathcal{T}, \mu \mathcal{E} v$ or Conf $=E,\left(\sigma,{ }^{\mu_{k}} P\right), \mathcal{Q}, \mathcal{O} r, \mathcal{T}, \mu \mathcal{E} v$ at a modified program point $\mu_{k}$ in trace $\operatorname{Tr}$, then let $\theta$ be a renaming of $I_{\mu_{k}}$ to fresh indices and $\rho=\left\{\theta I_{\mu_{k}} \mapsto \sigma I_{\mu_{k}}\right\}$; by Corollary 31, $\operatorname{Tr}, \rho \vdash \theta \mathcal{F}_{\mu_{k}}$. So $\operatorname{Tr}, \rho \vdash \theta \mathcal{F}_{k}^{\bmod }$, so $\operatorname{Tr} \vdash \exists I_{\mu_{k}}, \bigwedge \mathcal{F}_{k}^{\bmod }$.

We perform the proof for each query separately.
Case 1: $s p$ is some correspondence $\varphi$ different from $\forall \widetilde{x} \in \widetilde{T}$, event $(e(\widetilde{N})) \Rightarrow$ false (including $s p$ is true). Let $C$ be any evaluation context acceptable for $G$ with public variables $V$ that does not contain events used by $\varphi, D$, nor non-unique events of $G$, and $\mathcal{A}$ be an attacker in $\mathcal{B B}$.

Consider any full trace $\operatorname{Tr}$ of $C[G]$ for $\mathcal{A}$ such that $\operatorname{Tr} \vdash(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G, D}$. Let us show that $\operatorname{Tr} \vdash\left(\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.

Case 1.1: $\operatorname{Tr}$ does not execute any non-unique event of $G$. Then $\operatorname{Tr} \vdash \neg \varphi \vee D_{s}$ where $D_{s}$ is the disjunction of Shoup events in $D$.

Case 1.1.1: $\operatorname{Tr} \vdash \neg \varphi$ We conclude by Fact 1 .
Case 1.1.2: $\operatorname{Tr} \vdash e$ for some Shoup event $e$ in $D_{s}$. We conclude by Fact 1 for the correspondence event $(e) \Rightarrow$ false.

Case 1.2: $\operatorname{Tr}$ executes a non-unique event of $G$. Then $\operatorname{Tr} \vdash e$ for some non-unique event $e$ in $G$ and in $D$. We conclude by Fact 2 .

If $\operatorname{Tr} \vdash \bigvee_{k \in K} \exists I_{\mu_{k}}, \bigwedge \mathcal{F}_{k}^{\bmod }$, then $\operatorname{Tr} \vdash\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \bigwedge \mathcal{F}_{k}^{\bmod }\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.
Otherwise, by Fact 3, there is no configuration in $\operatorname{Tr}$ at a modified program point $\mu_{k}$, so $\operatorname{Tr}$ has a matching trace in $C\left[G^{\prime}\right]$ that also satisfies $(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G^{\prime}, D}$.

We conclude that

$$
\begin{aligned}
\operatorname{Adv}_{G}(\mathcal{A}, C, \varphi, D) \leq & \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D}\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C[G]:\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \bigwedge \mathcal{F}_{k}^{\bmod }\right) \vee\left(\bigvee \mathcal{L}^{+}\right)\right] \\
& +\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G^{\prime}, D}\right] \\
\leq & \operatorname{Pr}^{\mathcal{A}}\left[C[G] \preceq\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \bigwedge \mathcal{F}_{k}^{\bmod }\right) \vee\left(\bigvee \mathcal{L}^{+}\right)\right] \\
& +\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G^{\prime}, D}\right]
\end{aligned}
$$ by Lemma 1

$$
\leq p(\mathcal{A}, C)+\operatorname{Adv}_{G^{\prime}}(\mathcal{A}, C, \varphi, D)
$$

$$
\leq p(\mathcal{A}, C)+p^{\prime}(\mathcal{A}, C)
$$

Hence, we have $\operatorname{Bound}_{G}\left(V, s p, D, p+p^{\prime}\right)$.

Case 2: $s p$ is some correspondence $\varphi=\forall \widetilde{x} \in \widetilde{T}$, event $(e(\widetilde{N})) \Rightarrow$ false. Let $C$ be any evaluation context acceptable for $G$ with public variables $V$ that does not contain events used by $\varphi, D$, nor non-unique events of $G$, and $\mathcal{A}$ be an attacker in $\mathcal{B B}$.

Consider a full trace $\operatorname{Tr}$ of $C[G]$ for $\mathcal{A}$ such that $\operatorname{Tr} \vdash(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G, D}$. Let us show that either some prefix of $\operatorname{Tr}$ satisfies $\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \wedge \mathcal{F}_{k}^{\bmod }\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$or there is a matching trace in $C\left[G^{\prime}\right]$ that satisfies $(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G^{\prime}, D}$.

We have $\operatorname{Tr} \vdash \exists \widetilde{x} \in \widetilde{T}$, event $(e(\widetilde{N})) \vee D$.
Case 2.1: $\operatorname{Tr}$ executes a Shoup event $e^{\prime}$ of $D$. Then $\operatorname{Tr} \vdash e^{\prime}$ and $\operatorname{Tr}$ is actually a full trace that does not execute any non-unique event of $G$. By Fact $1, \operatorname{Tr} \vdash\left(\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge_{F \in \mathcal{F}_{j}} F\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.

Case 2.2: $\operatorname{Tr}$ executes a non-unique event of $G$. Then $\operatorname{Tr} \vdash e^{\prime}$ for some non-unique event $e^{\prime}$ in $G$ and in $D$. Then $\operatorname{Tr}$ is actually a full trace. By Fact $2, \operatorname{Tr} \vdash\left(\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge_{F \in \mathcal{F}_{j}} F\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.

In cases 2.1 and 2.2,

- If $\operatorname{Tr} \vdash \bigvee_{k \in K} \exists I_{\mu_{k}}, \wedge \mathcal{F}_{k}^{\bmod }$, then $\operatorname{Tr} \vdash\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \wedge \mathcal{F}_{j} \wedge \wedge \mathcal{F}_{k}^{\bmod }\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.
- Otherwise, by Fact 3, there is no configuration in $\operatorname{Tr}$ at a modified program point $\mu_{k}$, so $\operatorname{Tr}$ has a matching trace in $C\left[G^{\prime}\right]$ that also satisfies $(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G^{\prime}, D}$.

Case 2.3: $\operatorname{Tr}$ does not execute any non-unique event of $G$ nor any Shoup event of $D$. Then $T r \vdash \exists \widetilde{x} \in \widetilde{T}$, event $(e(\widetilde{N}))$.

Let $\mu \mathcal{E} v$ be the sequence of events and $E$ be the environment in the last configuration of $T r$. There is a mapping $\rho$ of the variables $\widetilde{x}$ to their values such that $\operatorname{Tr}, \rho \vdash e(\widetilde{N})$. As in the proof of Lemma 38, there exist $\widetilde{a}$ and $\tau \in \mathbb{N}$ such that $\rho, \widetilde{N} \Downarrow \widetilde{a}$ and $\mu \mathcal{E} v(\tau)=\left(\mu, \widetilde{a}_{0}\right): e(\widetilde{a})$ for some $\mu$ and $\widetilde{a}_{0}$. The rule of the semantics that may have added this element to $\mu \mathcal{E} v$ is (Event), (EventAbort), CtxEvent, FindE) or (EventT). (It cannot be Find3 nor Get3) because $e$ is not a non-unique event. It cannot be (GetE) because $G$ does not contain get by Property 3.)

- Case 2.3.1: In case Event, we have reductions

$$
\begin{aligned}
& \text { Conf }=E_{0},\left(\sigma_{0},{ }^{\mu} \text { event } e(\widetilde{M}) ; P\right):: \mathcal{S} t, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \xrightarrow{p_{0}} t_{0} \ldots{\xrightarrow{p_{1}}}_{t_{1}} E_{1},\left(\sigma_{1},{ }^{\mu} \text { event } e(\widetilde{a}) ; P\right):: \mathcal{S} t, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{1}, \mu \mathcal{E} v_{1} \\
& \quad \xrightarrow{1} C o n f^{\prime}=E_{1},\left(\sigma_{1}, P\right):: \mathcal{S} t, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{1},\left(\mu \mathcal{E} v_{1},\left(\mu, \operatorname{Im}\left(\sigma_{1}\right)\right): e(\widetilde{a})\right)
\end{aligned}
$$

where ${ }^{\mu}$ event $e(\widetilde{M}) ; P$ is a subprocess of $C[G]$ up to renaming of oracles, by any number of applications of ( $\overline{\mathrm{Ctx}}$ ) and a final application of (Event). The terms $\widetilde{M}$ are simple terms (when some term in $\widetilde{M}$ is not simple, no information is collected at all and simplify is not performed), so in fact

$$
\begin{aligned}
\operatorname{Conf} & =E_{0},\left(\sigma_{0},{ }^{\mu} \text { event } e(\widetilde{M}) ; P\right):: \mathcal{S} t, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& { }^{1}{ }^{*} E_{0},\left(\sigma_{0},{ }^{\mu} \text { event } e(\widetilde{a}) ; P\right):: \mathcal{S} t, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
\quad & { }^{1} \text { Conf }^{\prime}=E_{0},\left(\sigma_{0}, P\right):: \mathcal{S} t, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0},\left(\mu \mathcal{E} v_{0},\left(\mu, \operatorname{Im}\left(\sigma_{0}\right)\right): e(\widetilde{a})\right)
\end{aligned}
$$

- Case 2.3.2: In case EventAbort, we have a reduction

$$
\begin{aligned}
& \text { Conf }=E,\left(\sigma_{0},{ }^{\mu} P\right):: \mathcal{S} t, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \quad \quad_{t} \text { Conf }^{\prime}=E,\left(\sigma_{0}, \text { abort }\right):: \mathcal{S} t, \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0},\left(\mu \mathcal{E} v_{0},\left(\mu, \operatorname{Im}\left(\sigma_{0}\right)\right): e\right)
\end{aligned}
$$

where ${ }^{\mu} P$ is a subprocess of $C[G]$ up to renaming of oracles, by (EventAbort).

- Case 2.3.3: In case EventT, we have reductions

$$
\begin{aligned}
\text { Conf } & =E_{0}, \sigma_{0},{ }^{\mu} \text { event } e(\widetilde{M}) ; N, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \xrightarrow{p_{0}} t_{0} \ldots \xrightarrow{p_{1}} t_{1} E_{1}, \sigma_{1},{ }^{\mu} \text { event } e(\widetilde{a}) ; N, \mathcal{T}_{1}, \mu \mathcal{E} v_{1} \\
& \xrightarrow{1} E_{1}, \sigma_{1}, N, \mathcal{T}_{1},\left(\mu \mathcal{E} v_{1},\left(\mu, \operatorname{Im}\left(\sigma_{1}\right)\right): e(\widetilde{a})\right)
\end{aligned}
$$

where ${ }^{\mu}$ event $e(\widetilde{M}) ; N$ is a subterm of $C[G]$, by any number of applications of (CtxT) and a final application of EventT). The terms $\widetilde{M}$ are simple terms, so in fact

$$
\begin{aligned}
\operatorname{Conf} & =E_{0}, \sigma_{0},{ }^{\mu} \text { event } e(\widetilde{M}) ; N, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \xrightarrow{1^{*}} E_{0}, \sigma_{0},{ }^{\mu} \text { event } e(\widetilde{a}) ; N, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \xrightarrow[\rightarrow]{1} E_{0}, \sigma_{0}, N, \mathcal{T}_{0},\left(\mu \mathcal{E} v_{0},\left(\mu, \operatorname{Im}\left(\sigma_{0}\right)\right): e(\widetilde{a})\right)
\end{aligned}
$$

By Invariant 4, $\mu$ is not inside a condition of find or get, so by Lemma 5, Conf is not in the derivation of an hypothesis of a rule for find or get. The only rule for processes other than those for find or get that evaluates a non-simple term is (Ctx) and similarly, the only rule for terms other than those for find or get that evaluates a term is CtxT, so we have

$$
\begin{aligned}
& E_{0},\left(\sigma_{0}, C_{0}\left[C_{1}\left[\ldots C_{k}\left[{ }^{\mu} \text { event } e(\widetilde{M}) ; N\right] \ldots\right]\right]\right), \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \\
& \quad \xrightarrow{*} C_{0 n f}=E_{0},\left(\sigma_{0}, C_{0}\left[C_{1}\left[\ldots C_{k}[N] \ldots\right]\right]\right), \mathcal{Q}_{0}, \mathcal{O} r_{0}, \mathcal{T}_{0},\left(\mu \mathcal{E} v_{0},\left(\mu, \operatorname{Im}\left(\sigma_{0}\right)\right): e(\widetilde{a})\right)
\end{aligned}
$$

for some $C_{0}$ context defined in Figure $12, k \in \mathbb{N}$, and $C_{1}, \ldots, C_{k}$ contexts defined in Figure 7, by $k$ applications of CtxT and one application of Ctx .

- Case 2.3.4: In case CtxEvent, we have

$$
\text { Conf }=E_{0}, \sigma_{0},{ }^{\mu} \text { event_abort } e, \mathcal{T}_{0}, \mu \mathcal{E} v_{0} \xrightarrow{p}_{t} E_{0}, \sigma_{0}, \text { event_abort }\left(\mu, \operatorname{Im}\left(\sigma_{0}\right)\right): e, \mathcal{T}_{0}, \mu \mathcal{E} v_{0}
$$

by (EventAbortT) where ${ }^{\mu}$ event_abort $e$ is a subterm of $C[G]$, followed by applications (FindTE), CtxT), CtxEventT), FindE, Ctx, and CtxEvent). We let Conf ${ }^{\prime}$ be the last configuration of Tr.

Let $\theta^{\prime}$ be a renaming of $I_{\mu}$ to fresh replication indices. We have

$$
\begin{aligned}
& \operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta_{0}, \mu, c\right)=\left(\theta^{\prime} \mathcal{F}_{\text {event }(e(\widetilde{N})), \mu, c} \text { yields a contradiction }\right), \\
& \left\{\left[\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta_{0}, \mu, c\right)\right]\right\}=\forall \theta^{\prime} I_{\mu}, \forall \widetilde{x} \in \widetilde{T}, \neg \bigwedge \theta^{\prime} \mathcal{F}_{\operatorname{event}(e(\widetilde{N})), \mu, c},
\end{aligned}
$$

$\mathcal{C}$ is a pseudo-formula with all leaves $\perp$, so $\{\mid \vdash \mathcal{C}]\}=$ true .
If $(\mu, c) \in \mathcal{S}_{0} \backslash \mathcal{S}_{1}$, then in cases 2.3.1 and 2.3.3, $\left(\widetilde{x} \cup \theta^{\prime} I_{\mu}, \theta^{\prime} \mathcal{F}_{\mu, c} \cup\left\{\right.\right.$ lastdefprogrampoint $\left(\mu, \theta^{\prime} I_{\mu}\right)$, $\left.\left.\widetilde{N}=\theta^{\prime} \widetilde{M}\right\}\right)$ is added to $\mathcal{L}^{-}$and in cases 2.3.2 and 2.3.4, $\left(\theta^{\prime} I_{\mu}, \theta^{\prime} \mathcal{F}_{\text {event }(e), \mu, c}\right)$ is added to $\mathcal{L}^{-}$. Moreover, $\neg\left\{\left[\operatorname{prove}^{\varphi}\left(\mathcal{C}, \theta_{0}, \mathcal{S}_{1}\right)\right]\right\}=\bigvee_{(\mu, c) \in \mathcal{S}_{1}} \exists \theta^{\prime} I_{\mu}, \exists \widetilde{x} \in \widetilde{T}, \bigwedge \theta^{\prime} \mathcal{F}_{\text {event }(e(\widetilde{N})), \mu, c}$ is added to $\mathcal{L}^{+}$.

As in the proof of Lemma 38, we have $\sigma_{0}=\left[I_{\mu} \mapsto \widetilde{a}_{0}\right]$. Let $\sigma=\left\{\theta^{\prime} I_{\mu} \mapsto \widetilde{a}_{0}\right\}$. As in the proof of Lemma 38, we have $\operatorname{Tr}, \sigma \cup \rho \vdash \theta^{\prime} \mathcal{F}_{\text {event }(e(\widetilde{N})), \mu, c}$, since $\operatorname{Tr}$ does not execute any non-unique event of $G$.

- In cases 2.3.1 and 2.3.3 when $(\mu, c) \in \mathcal{S}_{1}$ and in cases 2.3.2 and 2.3.4, we have $\operatorname{Tr} \vdash$ $\left(\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$
- If $\operatorname{Tr} \vdash \bigvee_{k \in K} \exists I_{\mu_{k}}, \bigwedge \mathcal{F}_{k}^{\bmod }$, then $\operatorname{Tr} \vdash\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \wedge \mathcal{F}_{k}^{\bmod }\right) \vee$ $\left(V \mathcal{L}^{+}\right)$.
- Otherwise, by Fact 3, there is no configuration in $\operatorname{Tr}$ at a modified program point $\mu_{k}$, so $\operatorname{Tr}$ has a matching trace in $C\left[G^{\prime}\right]$ that also satisfies $(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G^{\prime}, D}$.
- In cases 2.3.1 and 2.3.3 when $(\mu, c) \in \mathcal{S}_{0} \backslash \mathcal{S}_{1}$, let $\operatorname{Tr}^{\prime}$ be the prefix of $\operatorname{Tr}$ that stops at Conf ${ }^{\prime}$. We have Conf $\preceq_{\operatorname{Tr}} \operatorname{Conf}^{\prime}$, so by Corollary 3, $\operatorname{Tr} \preceq \operatorname{Conf}^{\prime}, \sigma \vdash \theta^{\prime} \mathcal{F}_{\mu, c}$, that is, $T r^{\prime}, \sigma \vdash \theta^{\prime} \mathcal{F}_{\mu, c}$. We have $E_{0}, \sigma_{0}, \widetilde{M} \Downarrow \widetilde{a}$, so $E_{0}, \sigma, \theta^{\prime} \widetilde{M} \Downarrow \widetilde{a}$. The environment $E_{T r^{\prime}}$ extends $E_{0}$, so $E_{T r^{\prime}}, \sigma, \theta^{\prime} \widetilde{M} \Downarrow \widetilde{a}$, so $\operatorname{Tr}^{\prime}, \sigma \cup \rho \vdash \theta^{\prime} \widetilde{M}=\widetilde{N}$. Since $E_{T r \preceq C o n f^{\prime}}=E_{T r \preceq C o n f}$ and $\sigma_{\text {Conf }}{ }^{\prime}=\sigma_{\text {Conf }}, T r^{\prime}, \sigma \vdash$ lastdefprogrampoint $\left(\mu, \theta^{\prime} \boldsymbol{i}\right)$. Hence $\operatorname{Tr}^{\prime} \vdash \bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}$.
- If $T r^{\prime} \vdash \bigvee_{k \in K} \exists I_{\mu_{k}}, \bigwedge \mathcal{F}_{k}^{\bmod }$, then $\operatorname{Tr}^{\prime} \vdash\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \bigwedge \mathcal{F}_{k}^{\bmod }\right) \vee$ $\left(\bigvee \mathcal{L}^{+}\right)$and $T r^{\prime}$ is a prefix of $T r$.
- Otherwise, by Fact 3, there is no configuration in $T r^{\prime}$ at a modified program point $\mu_{k}$, so $\operatorname{Tr}$ has a matching trace in $C\left[G^{\prime}\right]$ that also satisfies $(\neg \varphi \vee D) \wedge \neg$ NonUnique $_{G^{\prime}, D}$. (Note that $\operatorname{Tr}$ may still be modified by success simplify: the matching trace in $C\left[G^{\prime}\right]$ may execute a modified program point $\mu_{k}$ after Conf ${ }^{\prime}$, but still the matching trace executes $e(\widetilde{M})$, so satisfies $\neg \varphi$, and it does not execute any non-unique event of $G^{\prime}$.)

We conclude that

$$
\begin{aligned}
& \operatorname{Adv}_{G}(\mathcal{A}, C, \varphi, D)= \operatorname{Pr}^{\mathcal{A}}\left[C[G]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G, D}\right] \\
& \leq \operatorname{Pr}^{\mathcal{A}}\left[C[G] \preceq\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \bigwedge \mathcal{F}_{k}^{\bmod }\right) \vee\left(\bigvee \mathcal{L}^{+}\right)\right] \\
&+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:(\neg \varphi \vee D) \wedge \neg \text { NonUnique }_{G^{\prime}, D}\right] \\
& \leq p(\mathcal{A}, C)+\operatorname{Adv}_{G^{\prime}}(\mathcal{A}, C, \varphi, D) \\
& \leq p(\mathcal{A}, C)+p^{\prime}(\mathcal{A}, C) \quad \text { since Bound }{ }_{G^{\prime}}\left(V, s p, D, p^{\prime}\right)
\end{aligned}
$$

Hence, we have $\operatorname{Bound}_{G}\left(V, s p, D, p+p^{\prime}\right)$.
Case 3: $s p$ is 1-ses.secr. $(x)$, $\operatorname{Secrecy}(x)$, or bit secr. $(x)$ with $C=C^{\prime}\left[C_{s p}[]\right]$ and $x$ is defined only by $\stackrel{R}{\leftarrow}$ or by assignments of variables defined by $\stackrel{R}{\leftarrow}$. Let $C^{\prime}$ be any evaluation context acceptable for $C_{s p}[G]$ with public variables $V \backslash V_{s p}$ that does not contain S , $\overline{\mathrm{S}}$, any event in $D$, nor any non-unique event of $G$, and $\mathcal{A}$ be an attacker in $\mathcal{B B}$.

$$
\begin{aligned}
& \operatorname{Adv}_{G}(\mathcal{A}, C, s p, D) \\
& \quad=\operatorname{Pr}^{\mathcal{A}}[C[G]: \mathrm{S} \vee D]-\operatorname{Pr}^{\mathcal{A}}\left[C[G]: \overline{\mathrm{S}} \vee \text { NonUnique }_{G, D}\right] \\
& =\operatorname{Pr}^{\mathcal{A}}[C[G]: \mathrm{S}]+\operatorname{Pr}^{\mathcal{A}}[C[G]: D]-\operatorname{Pr}^{\mathcal{A}}[C[G]: \overline{\mathrm{S}}]-\operatorname{Pr}^{\mathcal{A}}\left[C[G]: \text { NonUnique }{ }_{G, D}\right] \\
& \quad \begin{array}{l}
\text { since these events are mutually exclusive } \\
= \\
\\
\\
\quad \operatorname{Pr}^{\mathcal{A}}[C[G]: \mathrm{S} \wedge \neg s p]+\operatorname{Pr}^{\mathcal{A}}[C[G]: D] \quad \operatorname{Pr}^{\mathcal{A}}[C[G]: \overline{\mathrm{S}} \wedge \neg s p]-\operatorname{Pr}^{\mathcal{A}}\left[C[G]: \text { NonUnique }_{G, D}\right] \quad \text { by Lemma } 36 \\
= \\
=\operatorname{Pr}^{\mathcal{A}}[C[G]:(\mathrm{S} \wedge \neg s p) \vee D]-\operatorname{Pr}^{\mathcal{A}}[C[G]: \overline{\mathrm{S}} \wedge \neg s p]-\operatorname{Pr}^{\mathcal{A}}\left[C[G]: \text { NonUnique }_{G, D}\right]
\end{array}
\end{aligned}
$$

We have

- $\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:\right.$ NonUnique $\left._{G^{\prime}, D}\right] \leq \operatorname{Pr}^{\mathcal{A}}\left[C[G]:\right.$ NonUnique $\left._{G, D}\right]$,
- $\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: \overline{\mathrm{S}} \wedge \neg s p\right] \leq \operatorname{Pr}^{\mathcal{A}}[C[G]: \overline{\mathrm{S}} \wedge \neg s p]$
since a trace that executes a non-unique event or $\overline{\mathrm{S}}$ in $G^{\prime}$ cannot execute event adv_loses, so it executed without change in $G$. Let us show that $\operatorname{Pr}^{\mathcal{A}}[C[G]:(\mathrm{S} \wedge \neg s p) \vee D] \leq p(\mathcal{A}, C)+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:\right.$ $(\mathrm{S} \wedge \neg s p) \vee D]$. Let $\operatorname{Tr}$ be a full trace of $C[G]$ for $\mathcal{A}$ such that $\operatorname{Tr} \vdash(\mathrm{S} \wedge \neg s p) \vee D$. Let us show that $\operatorname{Tr} \vdash\left(\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.

Case 3.1: $\operatorname{Tr}$ executes a non-unique event of $G$. Then $\operatorname{Tr} \vdash e$ for some non-unique event $e$ in $G$ and in $D$. We conclude by Fact 2 .

Case 3.2: $\operatorname{Tr} \vdash e$ for some Shoup event $e$ in $D$. Then $\operatorname{Tr}$ does not execute any non-unique event of $G$. We conclude by Fact 1 for the correspondence event $(e) \Rightarrow$ false.

Case 3.3: $\operatorname{Tr} \vdash \mathrm{S} \wedge \neg s p$. Since $\operatorname{Tr} \vdash \neg s p$, we have $\operatorname{Tr} \vdash \neg\left\{\left[\operatorname{prove}^{s p}(\operatorname{Tpp}(\operatorname{Tr}))\right\}\right\}$, so we are in one of the following two cases:

- There exists $\mu \in \operatorname{Tpp}(\operatorname{Tr})$ such that $\operatorname{Tr} \vdash \neg\left\{\left[\operatorname{prove}^{1-\text { ses.secr. }(x)}(\mu)\right]\right\}$.
- If $\mu \in \mathcal{S}_{1}$, then $\operatorname{Tr} \vdash \bigvee \mathcal{L}^{+}$since $\neg\left\{\right.$ prove $\left.\left.{ }^{1 \text {-ses.secr. }(x)}\left(\mathcal{S}_{1}\right)\right]\right\}$ is added to $\mathcal{L}^{+}$.
- If $\mu \in \mathcal{S}_{0} \backslash \mathcal{S}_{1}$, then $\left(\theta I_{\mu}, \theta \mathcal{F}_{\mu}\right)$ is added to $\mathcal{L}^{-}$, where $\theta$ is a renaming of $I_{\mu}$ to fresh replication indices. Moreover, we have $\left.\neg\left\{\operatorname{noleak}\left(z\left[\widetilde{M}^{\prime}\right], \mathcal{I}, \mathcal{F}\right)\right]\right\} \Rightarrow \exists \mathcal{I}, \bigwedge \mathcal{F}$, so $\neg\left\{\left[\right.\right.$ prove $\left.^{1 \text {-ses.secr. } .(x)}(\mu)\right\} \Rightarrow \exists \theta I_{\mu}, \bigwedge \theta \mathcal{F}_{\mu}$ since defRand ${ }_{\mu}(x)$ is defined. Therefore, $\operatorname{Tr} \vdash$ $\bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}$.
- In case $s p=\operatorname{Secrecy}(x)$, there exist $\mu_{1}, \mu_{2} \in \operatorname{Tpp}(\operatorname{Tr})$ such that $\operatorname{Tr} \vdash \neg\left\{\left[\operatorname{prove}^{\mathrm{distinct}(x)}\left(\mu_{1}\right.\right.\right.$, $\left.\left.\left.\mu_{2}\right)\right]\right\}$. Let $z_{1}\left[\widetilde{M}_{1}\right]=\operatorname{defRand}_{\mu_{1}}(x), z_{2}\left[\widetilde{M_{2}}\right]=\operatorname{defRand}_{\mu_{2}}(x), \widetilde{i}$ be the current replication indices at the definition of $x, \theta_{1}$ and $\theta_{2}$ be two distinct renamings of $\widetilde{\sim} i$ to fresh replication indices, $\widetilde{i}_{1}=\theta_{1} \widetilde{i}, \widetilde{i}_{2}=\theta_{2} \widetilde{i}$, and $\mathcal{F}=\theta_{1} \mathcal{F}_{\mu_{1}} \cup \theta_{2} \mathcal{F}_{\mu_{2}} \cup\left\{\theta_{1} \widetilde{M}_{1}=\theta_{2} \widetilde{M}_{2}, \widetilde{i}_{1} \neq \widetilde{i}_{2}\right\}$ Then $z_{1}=z_{2}$ and $\operatorname{Tr} \vdash \exists \widetilde{i}_{1}, \exists \widetilde{i_{2}}, \bigwedge \mathcal{F}$.
- If $\mathcal{F}$ yields a contradiction, then $\exists \widetilde{i}_{1}, \exists \widetilde{i_{2}}, \bigwedge \mathcal{F}$ is added to $\mathcal{L}^{+}$, so $\operatorname{Tr} \vdash \bigvee \mathcal{L}^{+}$.
- Otherwise, $\left(\widetilde{i}_{1} \cup \widetilde{i}_{2}, \mathcal{F}\right)$ is added to $\mathcal{L}^{-}$, so $\operatorname{Tr} \vdash \bigvee_{j \in J} \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j}$.

If $\operatorname{Tr} \vdash \bigvee_{k \in K} \exists I_{\mu_{k}}, \bigwedge \mathcal{F}_{k}^{\bmod }$, then $\operatorname{Tr} \vdash\left(\bigvee_{j \in J, k \in K} \exists I_{\mu_{k}}, \exists \mathcal{V}_{j}, \bigwedge \mathcal{F}_{j} \wedge \bigwedge \mathcal{F}_{k}^{\bmod }\right) \vee\left(\bigvee \mathcal{L}^{+}\right)$.
Otherwise, by Fact 3, there is no configuration in $\operatorname{Tr}$ at a modified program point $\mu_{k}$, so $\operatorname{Tr}$ has a matching trace in $C\left[G^{\prime}\right]$ that also satisfies $(\mathrm{S} \wedge \neg s p) \vee D$.

Therefore, $\operatorname{Pr}^{\mathcal{A}}[C[G]:(\mathrm{S} \wedge \neg s p) \vee D] \leq p(\mathcal{A}, C)+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:(\mathrm{S} \wedge \neg s p) \vee D\right]$, so
$\operatorname{Adv}_{G}(\mathcal{A}, C, s p, D)$

$$
\leq p(\mathcal{A}, C)+\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:(\mathrm{S} \wedge \neg s p) \vee D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: \overline{\mathrm{S}} \wedge \neg s p\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: \text { NonUnique }_{G^{\prime}, D}\right]
$$

Moreover, by applying on $G^{\prime}$ the same steps as on $G$ at the beginning of this proof, we have

$$
\begin{aligned}
& \operatorname{Adv}_{G^{\prime}}(\mathcal{A}, C, s p, D) \\
& =\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]:(\mathrm{S} \wedge \neg s p) \vee D\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: \overline{\mathrm{S}} \wedge \neg s p\right]-\operatorname{Pr}^{\mathcal{A}}\left[C\left[G^{\prime}\right]: \text { NonUnique }_{G^{\prime}, D}\right]
\end{aligned}
$$

so

$$
\operatorname{Adv}_{G}(\mathcal{A}, C, s p, D) \leq p(\mathcal{A}, C)+\operatorname{Adv}_{G^{\prime}}(\mathcal{A}, C, s p, D) \leq p(\mathcal{A}, C)+p^{\prime}(\mathcal{A}, C)
$$

since $\operatorname{Bound}_{G^{\prime}}\left(V, s p, D, p^{\prime}\right)$. Therefore, we have $\operatorname{Bound}_{G}\left(V, s p, D, p+p^{\prime}\right)$.

## 5.2 crypto: Applying the Security Assumptions on Primitives

Extension: This description is based on the first version of the crypto transformation. Some extensions and improvements have been implemented since then.

### 5.2.1 Basic Transformation

The security of cryptographic primitives is defined using observational equivalences given as axioms. Importantly, this formalism allows us to specify many different primitives in a generic way. Such equivalences are then used by the prover in order to transform a game into another, observationally equivalent game, as explained below in this section.

The primitives are specified using equivalences of the form $G_{1}|\ldots| G_{m} \approx G_{1}^{\prime}|\ldots| G_{m}^{\prime}$ where $G$ is defined by the following grammar, with $l \geq 0$ and $m \geq 1$ :

```
G::= group of oracles
    foreach }i\leqn\mathrm{ do }\mp@subsup{y}{1}{}\stackrel{R}{\leftarrow}\mp@subsup{T}{1}{};\ldots;\mp@subsup{y}{l}{}\stackrel{R}{\leftarrow}\mp@subsup{T}{l}{};(\mp@subsup{G}{1}{}|\ldots|G\mp@subsup{G}{m}{}
    O(\mp@subsup{x}{1}{}:\mp@subsup{T}{1}{},\ldots,\mp@subsup{x}{l}{}:\mp@subsup{T}{l}{}):=FP\quad\mathrm{ oracle}
FP ::=
    oracle body
    return (M)
    x[\widetilde{i}]\stackrel{R}{\leftarrow}T;FP
    return
    random number
```

```
let \(x[\widetilde{i}]: T=M\) in \(F P \quad\) assignment
find \(\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}}[\widetilde{i}] \leq \widetilde{n_{j}}\right.\) suchthat defined \(\left(M_{j 1}, \ldots, M_{j l_{j}}\right) \wedge M_{j}\) then \(\left.F P_{j}\right)\) else \(F P\)
    array lookup
```

Intuitively, $O\left(x_{1}: T_{1}, \ldots, x_{l}: T_{l}\right):=F P$ represents an oracle that takes as argument values $x_{1}, \ldots, x_{l}$ of types $T_{1}, \ldots, T_{l}$ respectively and returns a result computed by $F P$. The observational equivalence $G_{1}|\ldots| G_{m} \approx G_{1}^{\prime}|\ldots| G_{m}^{\prime}$ expresses that the adversary has a negligible probability of distinguishing oracles in the left-hand side from corresponding oracles in the right-hand side. Formally, groups of oracles can be encoded as oracle definitions that take as input their arguments and return their result, as shown in Figure $23 \llbracket G \rrbracket \widetilde{\tilde{j}}$ denotes the translation of the group of oracles $G$ into an oracle definition. The translation of foreach $i \leq n$ do $y_{1} \stackrel{R}{\leftarrow} T_{1} ; \ldots ; y_{l} \stackrel{R}{\leftarrow} T_{l} ;\left(G_{1}|\ldots|\right.$ $G_{m}$ ) defines oracle $O_{\tilde{j}}$ so that the context can trigger the generation of random numbers $y_{1}, \ldots, y_{l}$. (In the left-hand side of equivalences, the result $F P$ of oracles must simply be a return return $(M)$ where $M$ is a simple term.) The observational equivalence $G_{1}|\ldots| G_{m} \approx G_{1}^{\prime}|\ldots| G_{m}^{\prime}$ is then an abbreviation for $\llbracket G_{1}|\ldots| G_{m} \rrbracket \approx \llbracket G_{1}^{\prime}|\ldots| G_{m}^{\prime} \rrbracket$.

For example, the security of a MAC (Definition 2) is represented by the equivalence $L \approx R$ where:

```
\(L=\) foreach \(i^{\prime \prime} \leq n^{\prime \prime}\) do \(k \stackrel{R}{\leftarrow} T_{m k} ;(\)
    foreach \(i \leq n\) do \(O_{m}(x:\) bitstring \():=\operatorname{return}(\operatorname{mac}(x, k))\)
    \(\mid\) foreach \(i^{\prime} \leq n^{\prime}\) do \(O_{v}\left(m:\right.\) bitstring, \(\left.\left.m a: T_{m s}\right):=\operatorname{return}(\operatorname{verify}(m, k, m a))\right)\)
\(R=\) foreach \(i^{\prime \prime} \leq n^{\prime \prime}\) do \(k \stackrel{R}{\leftarrow} T_{m k} ;(\)
    foreach \(i \leq n\) do \(O_{m}(x:\) bitstring \():=\) return \(\left(\operatorname{mac}^{\prime}(x, k)\right)\),
    foreach \(i^{\prime} \leq n^{\prime}\) do \(O_{v}\left(m:\right.\) bitstring, \(\left.m a: T_{m s}\right):=\)
        find \(u \leq n\) suchthat defined \((x[u]) \wedge(m=x[u])\)
        \(\wedge \operatorname{verify}^{\prime}(m, k, m a)\) then return (true) else return (false))
```

where mac ${ }^{\prime}$ and verify ${ }^{\prime}$ are function symbols with the same types as mac and verify respectively. (We use different function symbols on the left- and right-hand sides, just to prevent a repeated application of the transformation induced by this equivalence. Since we add these function symbols, we also add the equation

$$
\forall k: T_{m k}, \forall m: \text { bitstring }, \text { verify }{ }^{\prime}\left(m, k, \operatorname{mac}^{\prime}(m, k)\right)=\text { true } \quad\left(\mathrm{mac}^{\prime}\right)
$$

which restates $\left(\mathrm{mac}\right.$ for $\mathrm{mac}^{\prime}$ and verify'.) Intuitively, the equivalence $L \approx R$ leaves MAC computations unchanged (except for the use of primed function symbols in $R$ ), and allows one to replace a MAC checking verify $(m, k, m a)$ with a lookup in the array $x$ of messages whose mac has been computed with key $k$ : if $m$ is found in the array $x$ and verify $(m, k, m a)$, we return true; otherwise, the check fails (up to negligible probability), so we return false. (If the check succeeded with $m$ not in the array $x$, the adversary would have forged a MAC.) Obviously, the form of $L$ requires that $r$ is used only to compute or check MACs, for the equivalence to be correct. Formally, the following result shows the correctness of our modeling. It is a fairly easy consequence of Definition 2, and is proved in [26, Appendix E.3].

Proposition 5 If (mac, verify) is a UF-CMA message authentication code, $\mathrm{mac}^{\prime}=\mathrm{mac}$, and verify ${ }^{\prime}=$ verify, then $\llbracket L \rrbracket \approx \llbracket R \rrbracket$.

$$
\begin{aligned}
& \llbracket G_{1}|\ldots| G_{m} \rrbracket=\llbracket G_{1} \rrbracket^{1}|\ldots| \llbracket G_{m} \rrbracket^{m} \\
& \llbracket \text { foreach } i \leq n \text { do } y_{1} \stackrel{R}{\leftarrow} T_{1} ; \ldots ; y_{l} \stackrel{R}{\leftarrow} T_{l} ;\left(G_{1}|\ldots| G_{m}\right) \rrbracket_{\tilde{i}}^{\widetilde{j}}= \\
& \left.\quad \text { foreach } i \leq n \text { do } O_{\widetilde{j}} \widetilde{i}, i\right]():=y_{1} \stackrel{R}{\leftarrow} T_{1} ; \ldots ; y_{l} \stackrel{R}{\leftarrow} T_{l} ; \text { return }() ;\left(\llbracket G_{1} \rrbracket_{\tilde{i}, i}^{\widetilde{j}, 1}|\ldots| \llbracket G_{m} \rrbracket_{\tilde{i}, i}^{\widetilde{j}, m}\right) \\
& \llbracket O\left(x_{1}: T_{1}, \ldots, x_{l}: T_{l}\right):=F P \rrbracket_{i}^{\widetilde{j}}=O \widetilde{[i}\left(x_{1}: T_{1}, \ldots, x_{l}: T_{l}\right):=F P
\end{aligned}
$$

where $O_{\tilde{j}}$ are pairwise distinct oracles, $\widetilde{i}=i_{1}, \ldots, i_{l^{\prime}}$, and $\widetilde{j}=j_{0}, \ldots, j_{l^{\prime}}$.
Figure 23: Translation from groups of oracles to oracle definitions

Similarly, if (enc, dec) is an IND-CPA symmetric encryption scheme (Definition 3), then we have the following equivalence:

$$
\begin{aligned}
& \text { foreach } i^{\prime} \leq n^{\prime} \text { do } k \stackrel{R}{\leftarrow} T_{k} ; \text { foreach } i \leq n \text { do } \\
& \qquad O_{e}(x: \text { bitstring }):=r \stackrel{R}{\leftarrow} T_{r} ; \text { return }(\operatorname{enc}(x, k, r)) \\
& \approx \text { foreach } i^{\prime} \leq n^{\prime} \text { do } k \stackrel{R}{\leftarrow} T_{k} ; \text { foreach } i \leq n \text { do } \\
& \quad O_{e}(x: \text { bitstring }):=r \stackrel{R}{\leftarrow} T_{r} ; \text { return }\left(\operatorname{enc}^{\prime}(\mathrm{Z}(x), k, r)\right)
\end{aligned}
$$

where enc ${ }^{\prime}$ is a function symbol with the same type as enc, and Z : bitstring $\rightarrow$ bitstring is the function that returns a bitstring of the same length as its argument, consisting only of zeroes. Using equations such as $\forall x: T, \mathrm{Z}(\mathrm{T} 2 \mathrm{~b}(x))=\mathrm{Z}_{T}$, we can prove that $\mathrm{Z}(\mathrm{T} 2 \mathrm{~b}(x))$ does not depend on $x$ when $x$ is of a fixed-length type and $\mathrm{T} 2 \mathrm{~b}: T \rightarrow$ bitstring is the natural injection. The equivalences that formalize the security assumptions on primitives are designed and proved correct by hand from security assumptions in a more standard form, as in the MAC example. Importantly, these manual proofs are done only once for each primitive, and the obtained equivalence can be reused for proving many different protocols automatically.

We use such equivalences $L \approx R$ in order to transform a process $Q_{0}$ observationally equivalent to $C[\llbracket L \rrbracket]$ into a process $Q_{0}^{\prime}$ observationally equivalent to $C[\llbracket R \rrbracket]$, for some evaluation context $C$. In order to check that $Q_{0} \approx^{V} C[\llbracket L \rrbracket]$, the prover uses sufficient conditions, which essentially guarantee that all uses of certain secret variables of $Q_{0}$, in a set $S$, can be implemented by calling oracles of $L$. Let $\mathcal{M}$ be a set of occurrences of terms, corresponding to uses of variables of $S$. Informally, the prover shows the following properties.

- For each $M \in \mathcal{M}$, there exist a term $N_{M}$, which is the return value of an oracle of $L$, and a substitution $\sigma_{M}$ such that $M=\sigma_{M} N_{M}$. (Precisely, $\sigma_{M}$ applies to the abbreviated form of $N_{M}$ in which we write $x$ instead of $x[\widetilde{i}]$.) Intuitively, the evaluation of $M$ in $Q_{0}$ will correspond to a call to the oracle returning $N_{M}$ in $C[\llbracket L \rrbracket]$.
- The variables of $S$ do not occur in $V$, are bound by random choices in $Q_{0}$, and occur only in terms $M=\sigma_{M} N_{M} \in \mathcal{M}$ in $Q_{0}$, at occurrences that are images by $\sigma_{M}$ of variables bound by random choices in $L$. (To be precise, the variables of $S$ are also allowed to occur at the root of defined conditions; in that case, their value does not matter, just the fact that they are defined.)
- Let $\widetilde{i}$ and $\widetilde{i^{\prime}}$ be the sequences of current replication indices at $N_{M}$ in $L$ and at $M$ in $Q_{0}$, respectively. The prover shows that there exists a function mapIdx ${ }_{M}$ that maps the array indices at $M$ in $Q_{0}$ to the array indices at $N_{M}$ in $L$ : the evaluation of $M$ when
$\widetilde{i^{\prime}}=\widetilde{a}$ will correspond in $C[\llbracket L \rrbracket]$ to the evaluation of $N_{M}$ when $\widetilde{i}=\operatorname{mapIdx}_{M}(\widetilde{a})$. Thus, $\sigma_{M}$ and $\operatorname{mapIdx}_{M}$ induce a correspondence between terms and variables of $Q_{0}$ and variables of $L$ : for all $M \in \mathcal{M}$, for all $x\left[\widetilde{i^{\prime \prime}}\right]$ that occur in $N_{M},\left(\sigma_{M} x\right)\left\{\widetilde{a} / \widetilde{i^{\prime}}\right\}$ corresponds to $x\left[\widetilde{i^{\prime \prime}}\right]\left\{\operatorname{mapIdx}_{M}(\widetilde{a}) / \widetilde{i}\right\}$, that is, $\left(\sigma_{M} x\right)\left\{\widetilde{a} / \widetilde{i^{\prime}}\right\}$ in a trace of $Q_{0}$ has the same value as $x\left[\widetilde{i^{\prime \prime}}\right]\left\{\operatorname{mapIdx}_{M}(\widetilde{a}) / \widetilde{i}\right\}$ in the corresponding trace of $C[\llbracket L \rrbracket]\left(\widetilde{i^{\prime \prime}}\right.$ is a prefix of $\left.\widetilde{i}\right)$. We detail below conditions that this correspondence has to satisfy.

For example, consider a process $Q_{0}$ that contains $M_{1}=\operatorname{enc}\left(M_{1}^{\prime}, x_{k}, x_{r}^{\prime}\left[i_{1}\right]\right)$ under a replication foreach $i_{1} \leq n_{1}$ do and $M_{2}=\operatorname{enc}\left(M_{2}^{\prime}, x_{k}, x_{r}^{\prime \prime}\left[i_{2}\right]\right)$ under a replication foreach $i_{2} \leq n_{2}$ do , where $x_{k}, x_{r}^{\prime}, x_{r}^{\prime \prime}$ are bound by random choices. Let $S=\left\{x_{k}, x_{r}^{\prime}, x_{r}^{\prime \prime}\right\}, \mathcal{M}=\left\{M_{1}, M_{2}\right\}$, and $N_{M_{1}}=N_{M_{2}}=\operatorname{enc}\left(x\left[i^{\prime}, i\right], k\left[i^{\prime}\right], r\left[i^{\prime}, i\right]\right)$. The functions mapIdx $M_{M_{1}}$ and mapIdx $M_{M_{2}}$ are defined by

$$
\begin{aligned}
& \operatorname{mapIdx}_{M_{1}}\left(a_{1}\right)=\left(1, a_{1}\right) \text { for } a_{1} \in\left[1, n_{1}\right] \\
& \operatorname{mapIdx}_{M_{2}}\left(a_{2}\right)=\left(1, a_{2}+n_{1}\right) \text { for } a_{2} \in\left[1, n_{2}\right]
\end{aligned}
$$

Then $M_{1}^{\prime}\left\{a_{1} / i_{1}\right\}$ corresponds to $x\left[1, a_{1}\right], x_{k}$ to $k[1], x_{r}^{\prime}\left[a_{1}\right]$ to $r\left[1, a_{1}\right], M_{2}^{\prime}\left\{a_{2} / i_{2}\right\}$ to $x\left[1, a_{2}+n_{1}\right]$, and $x_{r}^{\prime \prime}\left[a_{2}\right]$ to $r\left[1, a_{2}+n_{1}\right]$. The functions mapIdx $M_{M_{1}}$ and mapIdx $M_{M_{2}}$ are such that $x_{r}^{\prime}\left[a_{1}\right]$ and $x_{r}^{\prime \prime}\left[a_{2}\right]$ never correspond to the same cell of $r$; indeed, $x_{r}^{\prime}\left[a_{1}\right]$ and $x_{r}^{\prime \prime}\left[a_{2}\right]$ are independent random numbers in $Q_{0}$, so their images in $C[\llbracket L \rrbracket]$ must also be independent random numbers.

The above correspondence must satisfy the following soundness conditions:

- when $x$ is an oracle argument in $L$, the term that corresponds to $x\left[\widetilde{a^{\prime}}\right]$ must have the same type as $x\left[\widetilde{a^{\prime}}\right]$, and when two terms correspond to the same $x\left[\widetilde{a^{\prime}}\right]$, they must evaluate to the same value;
- when $x$ is bound by $x \stackrel{R}{\leftarrow} T$ in $L$, the term that corresponds to $x\left[\widetilde{a^{\prime}}\right]$ must evaluate to $z\left[\widetilde{a^{\prime \prime}}\right]$ where $z \in S$ and $z$ is bound by $z \stackrel{R}{\leftarrow} T$ in $Q_{0}$, and the relation that associates $z\left[\widetilde{a^{\prime \prime}}\right]$ to $x\left[\widetilde{a^{\prime}}\right]$ is an injective function (so that independent random numbers in $L$ correspond to independent random numbers in $Q_{0}$ ).

It is easy to check that, in the previous example, these conditions are satisfied.
The transformation of $Q_{0}$ into $Q_{0}^{\prime}$ consists in two steps. First, we replace the random choices that define variables of $S$ with random choices that define fresh variables corresponding to variables bound by $\stackrel{R}{\leftarrow}$ in $R$. The correspondence between variables of $Q_{0}$ and variables of $C[\llbracket L \rrbracket]$ is extended to include these fresh variables. Second, we reorganize $Q_{0}$ so that each evaluation of a term $M \in \mathcal{M}$ first stores the values of the arguments $x_{1}, \ldots, x_{m}$ of the oracle $O\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right):=C\left[\right.$ return $\left.\left(N_{M}\right)\right]$ in fresh variables, then computes $N_{M}$ and stores its result in a fresh variable, and uses this variable instead of $M$; then we simply replace the computation of $N_{M}$ with the corresponding oracle call of $R$, taking into account the correspondence of variables.

Next, we formalize this transformation. We require the following conditions for the equivalences $L \approx R$ that model cryptographic primitives:

H0. $\llbracket L \rrbracket$ and $\llbracket R \rrbracket$ satisfy Invariants 1, 2, and 8. The oracle names in $L$ (resp. $R$ ) are pairwise distinct. Furthermore, the return value of each oracle in $R$ has the same type as the return value of the corresponding oracle of $L$.

H1. In $L$, the oracles bodies $F P$ are simply returns of terms $M$; all their array accesses use the current replication indices. (Allowing let or find in $L$ is difficult, because we need to recognize the terms $M$ in a context and in a possibly syntactically modified form.)

H2. $L$ and $R$ have the same structure: same replications, same number of oracles, same oracle names, same number of arguments with the same types for each oracle.

H3. The variables $y_{j}$ defined by $\stackrel{R}{\leftarrow}$ and $x_{j}$ defined by oracle arguments in $L$ and $R$ are distinct from other variables defined in $R$.

H4. Under foreach $i \leq n$ do with no random choice in $L$, one can have only a single oracle $O\left(x_{1}: T_{1}, \ldots, x_{l}: T_{l}\right):=F P$. (One can transform foreach $i \leq n$ do $\left(O_{1}\left(\widetilde{x_{1}}: \widetilde{T_{1}}\right):=F P_{1} \mid\right.$ $\ldots\left|O_{m}\left(\widetilde{x_{m}}: \widetilde{T_{m}}\right):=F P_{m}\right|$ foreach $i_{1} \leq n_{1}$ do $\ldots|\ldots|$ foreach $i_{m^{\prime}} \leq n_{m^{\prime}}$ do $\ldots$ ) into (foreach $i \leq n$ do $O_{1}\left(\widetilde{x_{1}}: \widetilde{T_{1}}\right):=F P_{1}|\ldots|$ foreach $i \leq n$ do $O_{m}\left(\widetilde{x_{m}}: \widetilde{T_{m}}\right):=F P_{m} \mid$ foreach $i_{1} \leq n_{1}^{\prime}$ do $\ldots|\ldots|$ foreach $i_{m^{\prime}} \leq n_{m^{\prime}}^{\prime}$ do $\ldots$ ) in order to eliminate situations that do not satisfy this requirement.)

H5. Replications in $L$ (resp. $R$ ) must have pairwise distinct bounds $n$. (This strengthens the typing: the typing then guarantees that, if several variables are accessed with the same array indices, then these variables are defined under the same replication.)

H6. For all random choices $y \stackrel{R}{\leftarrow} T$ that occur above a term $M$ in $L, y$ occurs in $M$. (This guarantees that, in Hypothesis $\mathrm{H}^{\prime} 3.1$ below, $z_{j k}\left[M_{j 1}, \ldots, M_{j q_{j}}\right]$ is defined for all $j \leq l$ and $k \leq m_{j}$. With Hypothesis H4, this guarantees that index ${ }_{j}$ is well-defined in Hypothesis $\mathrm{H}^{\prime} 3.1 .3$ below.)

H7. Finds in $R$ are of the form

$$
\text { find }\left(\bigoplus_{j=1}^{m} \widetilde{u_{j}} \leq \widetilde{n_{j}} \text { suchthat defined }\left(z_{j 1}\left[\widetilde{u_{j 1}}\right], \ldots, z_{j l_{j}}\left[\widetilde{u_{j l_{j}}}\right]\right) \wedge M_{j} \text { then } F P_{j}\right) \text { else } F P^{\prime}
$$

where the following conditions are satisfied:

- For all $1 \leq k \leq l_{j}, \widetilde{u_{j k}}$ is the concatenation of a prefix of the current replication indices (the same prefix for all $k$ ) and a non-empty prefix of $\widetilde{u_{j}}$.
- When $\widetilde{u_{j}}$ is non-empty, at least one $\widetilde{u_{j k}}$ for $1 \leq k \leq l_{j}$ is the concatenation of a prefix of the current replication indices with the whole sequence $\widetilde{u_{j}}$.
- When $l_{j} \neq 0$, there exists $k \in\left\{1, \ldots, l_{j}\right\}$ such that for all $k^{\prime} \neq k, z_{j k^{\prime}}$ is defined syntactically above all definitions of $z_{j k}$ and $\widetilde{u_{j k^{\prime}}}$ is a prefix of $\widetilde{u_{j k}}$. (This implies that the same find cannot access variables defined in different oracles under the same replication in $R$.)
- Finally, variables $z_{j k}$ are not defined by a find in $R$. (Otherwise, the transformation would be considerably more complicated.)

Such equivalences $L \approx R$ are used by the prover by replacing a process $Q_{0}$ observationally equivalent to $C[\llbracket L \rrbracket]$ with a process $Q_{0}^{\prime}$ observationally equivalent to $C[\llbracket R \rrbracket]$, for some evaluation context $C$. We now give sufficient conditions for a process to be equivalent to $C[\llbracket L \rrbracket]$. These conditions essentially guarantee that all uses of certain secret variables of $Q_{0}$, in a set $S$, can be implemented by calling oracles of $L$. These conditions are explained in more detail below.

We first define the function extract used in order to extract information from the left- or right-hand sides of the equivalence.

$$
\begin{gathered}
\operatorname{extract}\left(O\left(x_{1}: T_{1}, \ldots, x_{l}: T_{l}\right):=F P,()\right)= \\
O\left(x_{1}: T_{1}, \ldots, x_{l}: T_{l}\right):=F P
\end{gathered}
$$

```
extract(foreach \(i \leq n\) do \(\left.y_{1} \stackrel{R}{\leftarrow} T_{1} ; \ldots ; y_{l} \stackrel{R}{\leftarrow} T_{l} ;\left(G_{1}|\ldots| G_{m}\right),\left(j_{1}, \ldots, j_{k}\right)\right)=\)
    \(\left(y_{1}: T_{1}, \ldots, y_{l}: T_{l}\right), \operatorname{extract}\left(G_{j_{1}},\left(j_{2}, \ldots, j_{k}\right)\right)\)
\(\operatorname{extract}\left(\left(G_{1}|\ldots| G_{m}\right),\left(j_{0}, \ldots, j_{k}\right)\right)=\)
    \(\operatorname{extract}\left(G_{j_{0}},\left(j_{1}, \ldots, j_{k}\right)\right)\)
```

We rename the variables of $Q_{0}$ such that variables of $L$ and $R$ do not occur in $Q_{0}$. Assume that there exist a set of variables $S$ and a set $\mathcal{M}$ of occurrences of terms in $Q_{0}$ such that:
$\mathrm{H}^{\prime} 1 . S \cap V=\emptyset$.
$\mathrm{H}^{\prime} 2$. No term in $\mathcal{M}$ occurs in the condition part of a find $\left(\operatorname{defined}\left(M_{1}, \ldots, M_{l}\right) \wedge M\right)$.
$H^{\prime} 3$. For each $M \in \mathcal{M}$, there exist a sequence $B L(M)=\left(j_{0}, \ldots, j_{l}\right)$ such that $\operatorname{extract}(L$, $B L(M))=\left(y_{11}: T_{11}, \ldots, y_{1 m_{1}}: T_{1 m_{1}}\right), \ldots,\left(y_{l 1}: T_{l 1}, \ldots, y_{l m_{l}}: T_{l m_{l}}\right), O\left(x_{1}: T_{1}, \ldots, x_{m}:\right.$ $\left.T_{m}\right):=$ return $(N)$ and a substitution $\sigma$ such that $M=\sigma N(\sigma$ applies to the abbreviated form of $N$ in which we write $x$ instead of $x[\widetilde{i}])$ and the following conditions hold:
$\mathrm{H}^{\prime}$ 3.1. For all $j \leq l$ and $k \leq m_{j}, \sigma y_{j k}$ is a variable access $z_{j k}\left[M_{j 1}, \ldots, M_{j q_{j}}\right]$, with $z_{j k} \in S$. We define $z_{j k}=\operatorname{varImL}\left(y_{j k}, M\right)$.
$\mathrm{H}^{\prime}$ 3.1.1. All definitions of $z_{j k}$ in $Q_{0}$ are of the form $z_{j k}[\ldots] \stackrel{R}{\leftarrow} T_{j k}$, and for all $k \leq m_{j}$, they occur under the same replications (but they may occur under different replications for different values of $j$ ).
$\mathrm{H}^{\prime}$ 3.1.2. When $j \neq j^{\prime}$ or $k \neq k^{\prime}, z_{j k} \neq z_{j^{\prime} k^{\prime}}$.
$\mathrm{H}^{\prime}$ 3.1.3. The sequence of array indices $M_{j 1}, \ldots, M_{j q_{j}}$ is the same for all $k \leq m_{j}$ (but may depend on $j$ ). We denote by $\operatorname{index}_{j}(M)$ a substitution that maps the current replication indices at the definition of $z_{j k}$ to $M_{j 1}, \ldots, M_{j q_{j}}$ respectively. If $m_{l}=0, \operatorname{index}_{l}(M)$ is not set by the previous definition, so we set index $(M)$ to map the current replication indices at $M$ to themselves. For each $j<l$, there exists a substitution $\rho_{j}(M)$ such that $\operatorname{index}_{j}(M)=\operatorname{index}_{j+1}(M) \circ \rho_{j}(M)$ and the image of $\rho_{j}(M)$ does not contain the current replication indices at $M$. We denote by $\operatorname{im} \operatorname{index}_{j}(M)$ the sequence image by $\operatorname{index}_{j}(M)$ of the sequence of current replication indices at the definition of $z_{j k}\left(\operatorname{so}, \operatorname{im} \operatorname{index}_{j}(M)=\left(M_{j 1}, \ldots, M_{j q_{j}}\right)\right)$. We define im $\rho_{j}(M)$ similarly.
$\mathrm{H}^{\prime}$ 3.2. For all $j \leq m, \sigma x_{j}$ is a term of type $T_{j}$.
$\mathrm{H}^{\prime} 3.3$. All occurrences in $Q_{0}$ of a variable in $S$ are either as $z_{j k}$ above or at the root of an argument of a defined test in a find process.

To make it precise which term $M$ each element refers to, we add $M$ as a subscript, writing $y_{j k, M}$ for $y_{j k}, z_{j k, M}$ for $z_{j k}, T_{j k, M}$ for $T_{j k}, x_{j, M}$ for $x_{j}, T_{j, M}$ for $T_{j}, N_{M}$ for $N$, and $\sigma_{M}$ for $\sigma$. We also define $\mathrm{nNew}_{j, M}=m_{j}$, nNewSeq $_{M}=l$, and nInput ${ }_{M}=m$.
$\mathrm{H}^{\prime} 4$. We say that two terms $M, M^{\prime} \in \mathcal{M}$ share the first $l^{\prime}$ sequences of random variables when $y_{j k, M}=y_{j k, M^{\prime}}$ and $z_{j k, M}=z_{j k, M^{\prime}}$ for all $j \leq l^{\prime}$ and $k \leq \mathrm{nNew}_{j, M}=\mathrm{nNew}_{j, M^{\prime}} \neq 0$. Let $l^{\prime}$ be the greatest integer such that $M$ and $M^{\prime}$ share the first $l^{\prime}$ sequences of random variables. Then we require:
$\mathrm{H}^{\prime}$ 4.1. The sets of variables $\left\{z_{j k, M} \mid j>l^{\prime}\right.$ and $\left.k \leq \operatorname{nNew}_{j, M}\right\}$ and $\left\{z_{j k, M^{\prime}} \mid j>l^{\prime}\right.$ and $k \leq$ $\left.\mathrm{nNew}_{j, M^{\prime}}\right\}$ must be disjoint.
$\mathrm{H}^{\prime}$ 4.2. $\rho_{j}(M)=\rho_{j}\left(M^{\prime}\right)$ for all $j<l^{\prime}$.
$\mathrm{H}^{\prime}$ 4.3. If $l^{\prime}=\mathrm{nNewSeq}_{M}$ and $N_{M}=N_{M^{\prime}}$, then there exists $M_{0}$ such that we have $M=$ $\left(\operatorname{index}_{l^{\prime}}(M)\right) M_{0}, M^{\prime}=\left(\operatorname{index}_{l^{\prime}}\left(M^{\prime}\right)\right) M_{0}$, and $M_{0}$ does not contain the current replication indices at $M$ or $M^{\prime}$.

When these conditions are satisfied, there exists a context $C$ such that $Q_{0} \approx_{0}^{V} C[\llbracket L \rrbracket]$.
Terms in $\mathcal{M}$ must not occur in conditions of find (Hypothesis $\mathrm{H}^{\prime} 2$ ) because such terms may refer to variables defined by find, and by the transformation, these variables might be moved outside their scope, thus violating Invariant 2 .

In Hypothesis $\mathrm{H}^{\prime} 3$, the sequence $B L(M)$ indicates which branch of $L$ corresponds to the term $M$.

Hypothesis $\mathrm{H}^{\prime} 3.2$ checks that the values received as arguments in $L$ are of the proper type. Hypothesis $H^{\prime} 3.1 .1$ checks that variables $z_{j k, M}$ that correspond to variables defined by $\stackrel{R}{\leftarrow}$ in $L$ are of the proper type. The variables $y_{j k}$ defined by $\stackrel{R}{\leftarrow}$ in $L$ are used only in terms $N$ in $L$. Correspondingly, Hypothesis $H^{\prime} 3.3$ checks that the corresponding variables $z_{j k, M} \in S$ are not used elsewhere in $Q_{0}$ and Hypothesis $H^{\prime} 1$ checks that they cannot be used directly by the context.

In $L$, for distinct $j, k$, the variables $y_{j k}$ correspond to independent random numbers. Correspondingly, Hypothesis $\mathrm{H}^{\prime} 3.1 .2$ requires that the variables $z_{j k, M}$ are created by different random choices for distinct $j, k$. In $L$, the variables $y_{j k}$ are accessed with the same indices for any $k$ (but a fixed $j$ ). Correspondingly, Hypothesis $\mathrm{H}^{\prime} 3.1 .3$ requires that the variables $z_{j k, M}$ are accessed with the same indices $\operatorname{im} \operatorname{index}_{j}(M)$ for any $k$. When instances of $N$ and $N^{\prime}$ both refer to $y_{j k}$ with the same indices, then they also refer to $y_{j^{\prime} k^{\prime}}$ with the same indices when $j^{\prime} \leq j$. Correspondingly, if $M$ and $M^{\prime}$ refer to the same $z_{j k}$, by Hypothesis $\mathrm{H}^{\prime} 4.1$, they also refer to the same $z_{j^{\prime} k^{\prime}}$ for $j^{\prime} \leq j$. Moreover, if $\operatorname{index}_{j}(M)$ and $\operatorname{index}_{j}\left(M^{\prime}\right)$ evaluate to the same bitstrings, then $\operatorname{index}_{j^{\prime}}(M)$ and $\operatorname{index}_{j^{\prime}}\left(M^{\prime}\right)$ also evaluate to the same bitstrings, since $\operatorname{index}_{j^{\prime}}(M)=\operatorname{index}_{j}(M) \circ \rho_{j-1}(M) \circ \ldots \circ \rho_{j^{\prime}}(M)$ by Hypothesis $\mathrm{H}^{\prime} 3.1 .3$ and $\rho_{k}(M)=\rho_{k}\left(M^{\prime}\right)$ for $k<j$ by Hypothesis $\mathrm{H}^{\prime} 4.2$. These conditions guarantee that we can establish a correspondence from the array cells of variables of $S$ in $Q_{0}$ to the array cells of variables defined by $\stackrel{R}{\leftarrow}$ in $L$, and that this correspondence is an injective function, as required in Section 5.2 .

Finally, a term $N$ in $L$ is evaluated at most once for each value of the indices of $y_{l 1}, \ldots, y_{l m_{l}}$, so $N$ is computed for a single value of the arguments $x_{1}, \ldots, x_{m}$. Correspondingly, by Hypothesis $\mathrm{H}^{\prime} 4.3$, when $M$ and $M^{\prime}$ share the $l=\mathrm{nNewSeq}_{M}$ sequences of random variables and $\operatorname{index}_{l}(M)$ and $\operatorname{index}_{l}\left(M^{\prime}\right)$ evaluate to the same bitstring, then $M$ and $M^{\prime}$ evaluate to the same bitstring.

We compute the possible values of the sets $S$ and $\mathcal{M}$ by fixpoint iteration. We start with $\mathcal{M}=\emptyset$ and $S$ containing a single variable of $Q_{0}$ bound by a random choice. (We try all possible variables.) When a term $M$ of $Q_{0}$ contains a variable in $S$, we try to find an oracle in $L$ that corresponds to $M$, and if we succeed, we add $M$ to $\mathcal{M}$, and add to $S$ variables in $M$ that correspond to variables bound by random choices in $L$. (If we fail, the transformation is not possible.) We continue until a fixpoint is reached, in which case all occurrences of variables of $S$ are in terms of $\mathcal{M}$.

We now describe how we construct a process $Q_{0}^{\prime}$ such that $Q_{0}^{\prime} \approx_{0}^{V} C[\llbracket R \rrbracket]$.

1. We first move random choices in the right-hand side of the equivalence, so that they occur above oracle definitions instead of inside oracle bodies. As explained below, this is necessary for the correctness of the subsequent transformation of $Q_{0}$, when random choices appear in the corresponding part of the left-hand side. More precisely, we transform the right-hand side of the equivalence, $R$, as follows: for each $j_{1}, \ldots, j_{l}$, if extract $\left(L,\left(j_{1}, \ldots, j_{l}\right)\right)=\left(y_{11}\right.$ : $\left.T_{11}, \ldots, y_{1 m_{1}}: T_{1 m_{1}}\right), \ldots,\left(y_{l 1}: T_{l 1}, \ldots, y_{l m_{l}}: T_{l m_{l}}\right), O\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right):=$ return $(N)$ with $m_{l} \neq 0$ and $\operatorname{extract}\left(R,\left(j_{1}, \ldots, j_{l}\right)\right)=\left(y_{11}^{\prime}: T_{11}^{\prime}, \ldots, y_{1 m_{1}^{\prime}}^{\prime}: T_{1 m_{1}^{\prime}}^{\prime}\right), \ldots,\left(y_{l 1}^{\prime}: T_{l 1}^{\prime}, \ldots\right.$,
$\left.y_{l m_{l}^{\prime}}^{\prime}: T_{l m_{l}^{\prime}}^{\prime}\right), O\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right):=F P$, for each $z \stackrel{R}{\leftarrow} T$ in $F P$,

- we add $z: T$ in the sequence of random variables $y_{l 1}^{\prime}: T_{l 1}^{\prime}, \ldots, y_{l m_{l}^{\prime}}^{\prime}: T_{l m_{l}^{\prime}}^{\prime}$;
- if $z$ does not occur in defined conditions of find in $R$, we remove $z \stackrel{R}{\leftarrow} T$ from $F P$;
- otherwise, we replace $z \stackrel{R}{\leftarrow} T$ with let $z^{\prime}: T=$ cst for some constant cst and add $z^{\prime}[\widetilde{M}]$ to each defined condition of $R$ that contains $z[\widetilde{M}]$.

This transformation is needed, because in the right-hand side, a new random number must be chosen exactly for each different call to the oracle $O\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right):=F P$. This would not be guaranteed without that transformation, because when the left-hand side $N$ is evaluated at several occurrences with the same random numbers $y_{l 1}: T_{l 1}, \ldots, y_{l m_{l}}: T_{l m_{l}}$ $\left(m_{l} \neq 0\right)$, these occurrences all correspond to a single call to $O\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right):=$ return $(N)$, so a single call to $O\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right):=F P$, but we create a copy of $F P$ for each occurrence. After the transformation, $F P$ contains no choice of random numbers, so we can evaluate it several times without changing the result. When $m_{l}=0$, evaluations of $N$ at several occurrences can correspond to different calls to $O\left(x_{1}: T_{1}, \ldots, x_{m}: T_{m}\right):=$ return $(N)$, so the transformation is not necessary.
2. Next, we create fresh variables corresponding to variables of the right-hand side of the equivalence. For each $M \in \mathcal{M}$, let $\operatorname{extract}(R, B L(M))=\left(y_{11, M}^{\prime}: T_{11, M}^{\prime}, \ldots, y_{1 m_{1}^{\prime}, M}^{\prime}:\right.$ $\left.T_{1 m_{1}^{\prime}, M}^{\prime}\right), \ldots,\left(y_{l 1, M}^{\prime}: T_{l 1, M}^{\prime}, \ldots, y_{l m_{l}^{\prime}, M}^{\prime}: T_{l m_{l}^{\prime}, M}^{\prime}\right), O\left(x_{1, M}: T_{1, M}, \ldots, x_{m, M}: T_{m, M}\right):=$ $F P_{M}$ with $l=\mathrm{nNewSeq}_{M}, m=$ nInput $_{M}$ and we define $\mathrm{nNew}_{j, M}^{\prime}=m_{j}^{\prime}$. We create fresh variables $z_{j k, M}^{\prime}=\operatorname{varImR}\left(y_{j k, M}^{\prime}, M\right)$ for each $j \leq \mathrm{nNewSeq}_{M}, k \leq \mathrm{nNew}_{j, M}^{\prime}$, and $M \in \mathcal{M}$, such that if $M$ and $M^{\prime}$ share the first $l^{\prime}$ sequences of random variables, then $z_{j k, M}^{\prime}=z_{j k, M^{\prime}}^{\prime}$ for $j \leq l^{\prime}$ and $k \leq \mathrm{nNew}_{j, M}^{\prime}$. All variables $z_{j k, M}^{\prime}$ are otherwise pairwise distinct.
We also create a fresh variable $\operatorname{varImR}\left(x_{j, M}, M\right)$ for each $j \leq \operatorname{nInput}_{M}$ and each $M \in \mathcal{M}$, and a fresh variable $\operatorname{var} \operatorname{ImR}(z, M)$ for each variable $z$ defined by let or $\stackrel{R}{\leftarrow}$ in $F P_{M}$ and each $M \in \mathcal{M}$.
3. We update the defined conditions of finds, in order to preserve Invariant 2 More precisely, if a defined condition of a find contains $z_{j 1, M}\left[M_{1}, \ldots, M_{l^{\prime}}\right]$ for some $M$, we add defined $\left(z_{j k^{\prime}, M}^{\prime}\left[M_{1}, \ldots, M_{l^{\prime}}\right]\right)$ for all $k^{\prime} \leq \mathrm{nNew}_{j, M}^{\prime}$ to this condition. (So that accesses to $z_{j k^{\prime}, M}^{\prime}\left[M_{1}, \ldots, M_{l^{\prime}}\right]$ created when transforming term $M$ satisfy Invariant 2 , since accesses to $z_{j 1, M}\left[M_{1}, \ldots, M_{l^{\prime}}\right]$ occur in $M$ and satisfy Invariant 2.)
4. We update random choices corresponding to random choices of the left-hand side of the equivalence: we either remove them or replace them with random choices corresponding to the right-hand side of the equivalence. More precisely, when $x \in S$ occurs at the root of a term $M_{k}$ in a condition defined $\left(M_{1}, \ldots, M_{l}\right)$, we replace its definition $x \stackrel{R}{\leftarrow} T ; Q$ with let $x: T=$ cst in $Q$ for some constant cst; when it does not occur in defined tests, we remove its definition. If $x=z_{j 1, M}$ for some $M$, we add $z_{j k, M}^{\prime} \stackrel{R}{\leftarrow} T_{j k, M}^{\prime}$ for each $k \leq \mathrm{nNew}_{j, M}^{\prime}$ where $x \stackrel{R}{\leftarrow} T$ was.
5. Finally, we transform the terms $M \in \mathcal{M}$ corresponding to oracles of the left-hand side of the equivalence into their corresponding oracle in the right-hand side. For each term $M \in \mathcal{M}$, let $l=\mathrm{nNewSeq}_{M}$. We replace $M$ with $\left(z_{l k, M}^{\prime} \stackrel{R}{\leftarrow} T_{l k, M}^{\prime} ;\right)_{k \leq \mathrm{nNew}_{l, M}^{\prime}} M^{\prime}$ if $\mathrm{nNew}_{l, M}=0$ and $\mathrm{nNew}_{l, M}^{\prime}>0$, and with $P_{M}^{\prime}$ otherwise, where
$-M^{\prime}=\left(\text { let } \operatorname{varImR}\left(x_{k, M}, M\right): T_{k, M}=\sigma_{M} x_{k, M} \text { in }\right)_{k \leq \text { nInput }_{M}} \operatorname{transf}_{\phi_{0}}\left(F P_{M}\right)$.

- $\phi_{0}$ is defined as follows:

$$
\begin{aligned}
& \phi_{0}\left(x_{j, M}\left[i_{1}, \ldots, i_{l}\right]\right)=\operatorname{varImR}\left(x_{j, M}, M\right)\left[i_{1}^{\prime}, \ldots, i_{l^{\prime}}^{\prime}\right] \\
& \phi_{0}\left(z\left[i_{1}, \ldots, i_{l}\right]\right)=\operatorname{varImR}(z, M)\left[i_{1}^{\prime}, \ldots, i_{l^{\prime}}^{\prime}\right] \\
& \phi_{0}\left(y_{j k, M}^{\prime}\left[i_{1}, \ldots, i_{j}\right]\right)=\operatorname{varImR}\left(y_{j k, M}^{\prime}, M\right)\left[\operatorname{index}_{j}(M)\right]
\end{aligned}
$$

where $i_{1}, \ldots, i_{l}$ are the current replication indices at the definition of $x_{j, M}$ in $R, i_{1}^{\prime}, \ldots, i_{l^{\prime}}^{\prime}$ are the current replication indices at $M$ in $Q_{0}$, and $z$ is a variable defined by let or $\stackrel{R}{\leftarrow}$ in $F P_{M}$.

- A function $\phi$ from array accesses to array accesses is extended to terms as a substitution, by $\phi\left(f\left(M_{1}, \ldots, M_{m}\right)\right)=f\left(\phi\left(M_{1}\right), \ldots, \phi\left(M_{m}\right)\right)$.
$-\operatorname{transf}_{\phi}(F P)$ is defined recursively as follows:

$$
\left.\begin{array}{l}
\operatorname{transf}_{\phi}\left(\operatorname{return}\left(M^{\prime}\right)\right)=\phi\left(M^{\prime}\right) \\
\operatorname{transf}_{\phi}\left(z \stackrel{R}{\leftarrow} T ; F P^{\prime}\right)=\operatorname{varImR}(z, M) \stackrel{R}{\leftarrow} T ; \operatorname{transf}_{\phi}\left(F P^{\prime}\right) \\
\operatorname{transf}_{\phi}\left(\operatorname{let} z: T=M^{\prime} \text { in } F P^{\prime}\right)=\text { let } \operatorname{varImR}(z, M): T=\phi\left(M^{\prime}\right) \text { in } \operatorname{transf}_{\phi}\left(F P^{\prime}\right) \\
\operatorname{transf}_{\phi}\left(\operatorname{find}\left(\bigoplus_{j=1}^{m} F B_{j}\right) \text { else } F P^{\prime}\right)=\operatorname{find}\left(\bigoplus_{j=1}^{m} \operatorname{transf}_{\phi}\left(F B_{j}\right)\right) \text { else } \operatorname{transf} \\
\phi
\end{array} F P^{\prime}\right) .
$$

and for find branches $F B$, $\operatorname{transf}_{\phi}(F B)$ is defined as follows:

$$
\begin{aligned}
& \operatorname{transf}_{\phi}\left(\text { suchthat } M^{\prime} \text { then } F P^{\prime}\right)=\text { suchthat } \phi\left(M^{\prime}\right) \text { then } \operatorname{transf}_{\phi}\left(F P^{\prime}\right) \\
& \operatorname{transf}_{\phi}\left(\widetilde{u} \leq \widetilde{n} \text { suchthat defined }\left(z_{k}\left[M_{k 1}, \ldots, M_{k l_{k}^{\prime}}\right]_{1 \leq k \leq l}\right) \wedge M_{1} \text { then } F P^{\prime}\right)= \\
& \bigoplus_{M^{\prime} \in \mathcal{M}^{\prime}} \widetilde{u^{\prime}} \leq \widetilde{n^{\prime}} \text { suchthat defined }\left(\phi^{\prime}\left(z_{k}\left[M_{k 1}, \ldots, M_{k l_{k}^{\prime}}\right]_{1 \leq k \leq l}\right) \wedge\right. \\
& \quad \operatorname{im} \operatorname{index}_{j_{1}}\left(M^{\prime}\right)\left\{\widetilde{u^{\prime}} / \widetilde{i^{\prime}}\right\}=\operatorname{im} \operatorname{index}_{j_{1}}(M) \wedge \phi^{\prime}\left(M_{1}\right) \text { then transf } \\
& \phi^{\prime}\left(F P^{\prime}\right)
\end{aligned}
$$

where $l \neq 0 ; j_{1}$ is the length of the prefix of the current replication indices that occurs in $M_{k 1}, \ldots, M_{k l_{k}^{\prime}}$ (by Hypothesis H7); $\mathcal{M}^{\prime}$ is the set of $M^{\prime} \in \mathcal{M}$ such that $\operatorname{varImR}\left(z_{k}, M^{\prime}\right)$ is defined for $k \leq l$ and $M^{\prime}$ and $M$ share the first $j_{\mathcal{1}}$ sequences of random variables; $\widetilde{i^{\prime}}$ is the sequence of current replication indices at $M^{\prime} ; \widetilde{u^{\prime}}$ is a sequence formed with a fresh variable for each variable in $\widetilde{i^{\prime}} ; \widetilde{n^{\prime}}$ is the sequence of bounds of replications above $M^{\prime} ; \phi^{\prime}$ is an extension of $\phi$ with $\phi^{\prime}\left(z_{k}\left[M_{k 1}, \ldots, M_{k l_{k}^{\prime}}\right]\right)=\operatorname{varImR}\left(z_{k}, M^{\prime}\right)\left[\operatorname{im} \operatorname{index}_{j}\left(M^{\prime}\right)\left\{\widetilde{u^{\prime}} / \widetilde{i^{\prime}}\right\}\right]$ if $z_{k}=y_{j k^{\prime}, M^{\prime}}^{\prime}$ for some $k^{\prime}$, and $\phi^{\prime}\left(z_{k}\left[M_{k 1}, \ldots, M_{k l_{k}^{\prime}}\right]\right)=\operatorname{var} \operatorname{ImR}\left(z_{k}, M^{\prime}\right)\left[\widetilde{u^{\prime}}\right]$ if $z_{k}$ is defined by let or by an oracle input. Optimizations for the definition of $\operatorname{transf}_{\phi}(F B)$ are presented in Section 5.2.2.

The two essential parts of the transformation are the last two ones, numbered 4 and 5 . In step 4 , we add the random choices to create random variables that correspond to random variables of $R$. We create the variables $z_{j k, M}^{\prime}$ at the place where $z_{j 1, M}$ was created in the initial game (We could have chosen $z_{j k^{\prime}, M}$ for any $k^{\prime}$.), or when there is no $z_{j 1, M}$, we have $j=\mathrm{nNewSeq}{ }_{M}$ and we create $z_{j k, M}^{\prime}$ just before evaluating $M$. In step 5 we transform the term $M$ itself into the corresponding oracle process of $R, F P_{M}$. The only delicate part for evaluating $F P_{M}$ is the case of find: instead of looking up arrays of $R$, we look up the corresponding arrays of $Q_{0}^{\prime}$ given by the mapping $\phi$.

This transformation may replace a simple term $M$ with a term that is not simple, since the oracle bodies in $R$ may contain random number generations, assignments and find. Therefore, it may break Property 5 . Hence, by default, CryptoVerif calls expand (Section 5.1.3) after the crypto transformation, in order to recover Property 5.

### 5.2.2 Optimizations for $\operatorname{transf}_{\phi}(F B)$

We can apply two optimizations to the definition of $\operatorname{transf}_{\phi}(F B)$ :

- When im $\operatorname{index}_{j_{1}}\left(M^{\prime}\right)$ is a prefix of $\widetilde{i^{\prime}}$, im $\operatorname{index}_{j_{1}}\left(M^{\prime}\right)\left\{\widetilde{u^{\prime}} / \widetilde{i^{\prime}}\right\}$ is a prefix of $\widetilde{u^{\prime}}$, so the equality im $\operatorname{index}_{j_{1}}\left(M^{\prime}\right)\left\{\widetilde{u^{\prime}} / \widetilde{i^{\prime}}\right\}=\operatorname{im} \operatorname{index}_{j_{1}}(M)$ defines the value of a prefix of $\widetilde{u^{\prime}}$. We simply substitute the fixed elements of $\widetilde{u^{\prime}}$ with their value, and remove them from the sequence of variables to be looked up by find.
- When all variables $z_{k}$ are $y_{j k^{\prime}, M^{\prime}}$ for some $j, k^{\prime}$, and $M^{\prime}$, with $\max j=j_{0}$, we use the following definition instead:

$$
\begin{aligned}
& \operatorname{transf}_{\phi}\left(\widetilde{i} \leq \widetilde{n} \text { suchthat defined }\left(z_{k}\left[M_{k 1}, \ldots, M_{k l_{k}^{\prime}}\right]_{1 \leq k \leq l}\right) \wedge M_{1} \text { then } F P^{\prime}\right)= \\
& \bigoplus_{M^{\prime} \in \mathcal{M}^{\prime}} \widetilde{u^{\prime}} \leq \widetilde{n^{\prime}} \text { suchthat defined }\left(\phi^{\prime}\left(z_{k}\left[M_{k 1}, \ldots, M_{k l_{k}^{\prime}}\right]\right]_{1 \leq k \leq l}\right) \wedge \\
& \quad \operatorname{im}\left(\rho_{j_{0}-1}\left(M^{\prime}\right) \circ \ldots \circ \rho_{j_{1}}\left(M^{\prime}\right)\right)\left\{\widetilde{u^{\prime}} / \widetilde{i^{\prime}}\right\}=\operatorname{im~index} \\
& j_{1}
\end{aligned}(M) \wedge \phi^{\prime}\left(M_{1}\right) \text { then } \operatorname{transf}_{\phi^{\prime}}\left(F P^{\prime}\right) \text {. }
$$

where $j_{1}$ is the length of the prefix of the current replication indices that occurs in $M_{k 1}, \ldots, M_{k l_{k}^{\prime}}$ (by Hypothesis H7); $\mathcal{M}^{\prime}$ is the set of $M^{\prime} \in \mathcal{M}$ such that $\operatorname{varImR}\left(z_{k}, M^{\prime}\right)$ is defined for $k \leq l$ and $M^{\prime}$ and $M$ share the $j_{1}$ first sequences of random variables; $\widetilde{i^{\prime}}$ is the sequence of current replication indices at the definition of $z_{j_{0} k, M^{\prime}} ; \widetilde{u^{\prime}}$ is a sequence formed with a fresh variable for each variable in $\widetilde{i^{\prime}} ; \widetilde{n^{\prime}}$ is the sequence of bounds of replications above the definition of $z_{j_{0} k, M^{\prime}} ; \phi^{\prime}$ is an extension of $\phi$ with $\phi^{\prime}\left(z_{k}\left[M_{k 1}, \ldots, M_{k l_{k}}\right]\right)=$ $\operatorname{varImR}\left(z_{k}, M^{\prime}\right)\left[\operatorname{im}\left(\rho_{j_{0}-1}\left(M^{\prime}\right) \circ \ldots \circ \rho_{j}\left(M^{\prime}\right)\right)\left\{\widetilde{u^{\prime}} / \widetilde{\dot{i}^{\prime}}\right\}\right]$ if $z_{k}=y_{j k, M^{\prime}}^{\prime}$.
The composition $\rho_{j_{0}-1}\left(M^{\prime}\right) \circ \ldots \circ \rho_{j}\left(M^{\prime}\right)$ computes the indices of $z_{j k^{\prime}, M^{\prime}}^{\prime}$ for any $k^{\prime}$ from the indices of $z_{j_{0} k^{\prime \prime}, M^{\prime}}^{\prime}$ for any $k^{\prime \prime}$.
When several terms $M^{\prime} \in \mathcal{M}$ share the first $j_{0}$ sequences of random variables, they generate the same $\phi^{\prime}$, so only one find branch needs to be added for all of them, which can reduce considerably the number of find branches to add.

An optimization similar to the first one above also applies to this case, when im ( $\rho_{j_{0}-1}\left(M^{\prime}\right)$ 。 $\left.\ldots \circ \rho_{j_{1}}\left(M^{\prime}\right)\right)$ is a prefix of $\widetilde{i^{\prime}}$.

### 5.2.3 Guiding the Application of Equivalences

We introduce a small extension to the equivalences $G_{1}|\ldots| G_{m} \approx G_{1}^{\prime}|\ldots| G_{m}^{\prime}$ described in Section 5.2. These equivalences become $G_{1}$ mode $_{1}|\ldots| G_{m}$ mode $_{m} \approx G_{1}^{\prime}|\ldots| G_{m}^{\prime}$, where mode $_{j}$ is either empty or $[$ all $]$. The mode $[$ all $]$ is an indication for the prover, to guide the application of the equivalence without changing its semantics. When mode $_{j}=[$ all $], \mathcal{M}$ must contain all occurrences in the initial game $Q$ of the root function symbols of terms $M$ inside $G_{j}$. When mode ${ }_{j}$ is empty, at least one variable defined by $\stackrel{R}{\leftarrow}$ in $G_{j}$ must correspond to a variable in $S$.

The following hypotheses guarantee the good usage of modes:
H8. At most one mode $j_{j}$ can be empty. (Otherwise, when several sets of random variables can be chosen for each $G_{j}$, there are many possible combinations for applying the transformation.)

H9. If $G_{j}$ is of the form foreach $i \leq n$ do $O\left(x_{1}: T_{1}, \ldots, x_{l}: T_{l}\right):=F P$ without any random choice, then mode $_{j}=[$ all $]$. (A random choice is needed in the definition of empty mode.)

An equivalence can be declared [manual]. In this case, this equivalence is not applied by the automatic proof strategy. It can be used only by manual proof indications. This is useful, for instance, if applying the equivalence would yield an infinite loop.

Each oracle in the left-hand side can also be labeled with an integer [ $n$ ], which represents a priority: CryptoVerif preferably uses oracles labeled with a lower integer. (The absence of label corresponds to the label [0].) Each oracle in the left-hand side can finally be labeled with [useful_change]. This indication is also used for the proof strategy: if at least one [useful_change] indication is present, CryptoVerif applies the transformation defined by the equivalence only when at least one [useful_change] oracle is called in the game.

### 5.2.4 Relaxing Hypothesis H6

Hypothesis H6 requires that for all random choices $y \stackrel{R}{\leftarrow} T$ that occur above a term $N$ in the lefthand side of an equivalence, $y$ occurs in $N$. We can relax this hypothesis, by allowing that some random variables $y$ do not occur in $N$, provided that the missing variables can be determined using Hypothesis $\mathrm{H}^{\prime} 4.1$ when some term $M$ shares some variable $y$ in the $l^{\prime}$-th sequence of random variables with some other term $M^{\prime}$, we know that it must also share with $M^{\prime}$ all random variables in sequences above and including the $l^{\prime}$-th sequence; so, knowing the random variables associated to $M^{\prime}$, we can determine some of those associated to $M$. The transformation simply fails when the algorithm described above cannot fully determine the random variables associated to some term $M$.

With this extension, we additionally need to make sure that, when an expression of the right-hand side uses a variable $y$ defined by a random choice, this variable will be defined in the transformed game before the expression is evaluated. To do that, we establish a correspondence between the random choices before the transformation and the random choices after, such that, as far as possible, if a variable is used in a transformed expression, the corresponding variable before transformation is also used in the initial expression. For variables that appear in a transformed expression but are not used in the initial expression, we check when performing the game transformation that they will correctly be defined. If they are not correctly defined, the transformation fails.

### 5.2.5 Relaxing Hypothesis $\mathbf{H}^{\prime} \mathbf{2}$

Hypothesis $\mathrm{H}^{\prime} 2$ requires that no term $N$ transformed by the equivalence occurs in the condition part of a find (defined $\left.\left(M_{1}, \ldots, M_{l}\right) \wedge M\right)$. We can relax this hypothesis by allowing $N$ to occur in $M$ (but not in the defined test), provided

- the variables $\widetilde{u}$ bound by this find do not occur in the following terms in the transformed expression of $N$ :
- $N^{\prime}$ in processes of the form let $x: T=N^{\prime}$ in $\ldots$;
$-N_{j k}^{\prime}$ and $N_{j}^{\prime}$ in processes of the form find $\left(\bigoplus_{j=1}^{m} u_{j 1} \widetilde{[i]} \leq n_{j 1}, \ldots, u_{j m_{j}} \widetilde{[i}\right] \leq n_{j m_{j}}$ suchthat defined $\left(N_{j 1}^{\prime}, \ldots, N_{j l_{j}}^{\prime}\right) \wedge N_{j}^{\prime}$ then $\ldots$ ) else $\ldots$.
(If the variables $\widetilde{u}$ bound by find occurred in such terms, the transformation would move them outside the scope of their definition.)
- if $N$ depends on the variables $\widetilde{u}$ bound by this find, then the corresponding left-hand side of the equivalence $N^{\prime}$ is under a replication foreach $i \leq n$ do with no random choice in $L$. (Otherwise, $L$ contains $y_{1} \stackrel{R}{\leftarrow} T_{1} ; \ldots ; y_{l} \stackrel{R}{\leftarrow} T_{l} ;\left(\ldots\left|O\left(x_{1}: T_{1}^{\prime}, \ldots, x_{l^{\prime}}: T_{l^{\prime}}^{\prime}\right):=\operatorname{return}\left(N^{\prime}\right)\right|\right.$
...) and $L$ allows a single evaluation of $N^{\prime}$ for each execution of the random choices $y_{1} \stackrel{R}{\leftarrow}$ $T_{1} ; \ldots ; y_{l} \stackrel{R}{\leftarrow} T_{l}$, while the term $N$ is evaluated several times, once for each value of $\widetilde{u}$, so the transformation is impossible. In other words, the variables $\widetilde{u}$ must be considered as replication indices in this transformation.)


### 5.2.6 Soundness and Example

The following proposition shows the soundness of the transformation.
Proposition 6 Let $Q_{0}$ be a process that satisfies Invariants 1, 2, and 8 and $Q_{0}^{\prime}$ the process obtained from $Q_{0}$ by the above transformation. Then $Q_{0}^{\prime}$ satisfies Invariants 1, 2, and 8 and, if $\llbracket L \rrbracket \approx \llbracket R \rrbracket$ for all polynomials maxlen $\eta_{\eta}\left(c_{j_{0}, \ldots, j_{l}}\right)$ and $n$ where $n$ is any replication bound of $L$ or $R$, then $Q_{0} \approx^{V} Q_{0}^{\prime}$.

Example 10 In order to treat Example 1 the prover is given as input the indication that $T_{m k}$, $T_{k}$, and $T_{r}$ are fixed-length types; the type declarations for the functions mac, mac ${ }^{\prime}$ : bitstring $\times$ $T_{m k} \rightarrow T_{m s}$, verify, verify' : bitstring $\times T_{m k} \times T_{m s} \rightarrow$ bool, enc, enc' : bitstring $\times T_{k} \times T_{r} \rightarrow T_{e}$, dec : $T_{e} \times T_{k} \rightarrow$ bitstring $_{\perp}, \mathrm{k} 2 \mathrm{~b}: T_{k} \rightarrow$ bitstring, $\mathrm{i}_{\perp}:$ bitstring $\rightarrow$ bitstring $_{\perp}, \mathrm{Z}:$ bitstring $\rightarrow$ bitstring, and the constant $\mathrm{Z}_{k}$ : bitstring; the equations (mac), mac'), and $\forall x: T_{k}, \mathrm{Z}(\mathrm{k} 2 \mathrm{~b}(x))=\mathrm{Z}_{k}$ (which expresses that all keys have the same length); the indication that k 2 b and $\mathrm{i}_{\perp}$ are polyinjective (which generates the equations (k2b) and similar equations for $\mathrm{i}_{\perp}$ ); equivalences $L \approx R$ for MAC $\mathrm{mac}_{\mathrm{eq}}$ ) and encryption $\mathrm{enc}_{\mathrm{eq}}$; and the process $Q_{0}$ of Example 1 .

The process $Q_{0}$ of Example 1 can be transformed using the security of the MAC. Let $S=$ $\left\{x_{m k}\right\}, M_{1}=\operatorname{mac}\left(x_{m}[i], x_{m k}\right), M_{2}=\operatorname{verify}\left(x_{m}^{\prime}\left[i^{\prime}\right], x_{m k}, x_{m a}\left[i^{\prime}\right]\right)$, and $\mathcal{M}=\left\{M_{1}, M_{2}\right\}$. We have $N_{M_{1}}=\operatorname{mac}\left(x\left[i^{\prime \prime}, i\right], k\left[i^{\prime \prime}\right]\right), N_{M_{2}}=\operatorname{verify}\left(m\left[i^{\prime \prime}, i^{\prime}\right], k\left[i^{\prime \prime}\right], m a\left[i^{\prime \prime}, i^{\prime}\right]\right), \operatorname{mapIdx}_{M_{1}}\left(a_{1}\right)=\left(1, a_{1}\right)$, and $\operatorname{mapIdx}_{M_{2}}\left(a_{2}\right)=\left(1, a_{2}\right)$, so $x_{m}\left[a_{1}\right]$ corresponds to $x\left[1, a_{1}\right], x_{m k}$ to $k[1], x_{m}^{\prime}\left[a_{2}\right]$ to $m\left[1, a_{2}\right]$, and $x_{m a}\left[a_{2}\right]$ to $m a\left[1, a_{2}\right]$.

After transformation, we get the following process $Q_{0}^{\prime}$ :

```
\(Q_{0}^{\prime}=\operatorname{Start}():=x_{k} \stackrel{R}{\leftarrow} T_{k} ; x_{m k} \stackrel{R}{\leftarrow} T_{m k} ;\) return ()\(;\left(Q_{A}^{\prime} \mid Q_{B}^{\prime}\right)\)
\(Q_{A}^{\prime}=\) foreach \(i \leq n\) do \(O_{A}[i]():=x_{k}^{\prime} \stackrel{R}{\leftarrow} T_{k} ; x_{r} \stackrel{R}{\leftarrow} T_{r} ;\)
    let \(x_{m}:\) bitstring \(=\operatorname{enc}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime}\right), x_{k}, x_{r}\right)\) in
    return \(\left(x_{m}, \operatorname{mac}^{\prime}\left(x_{m}, x_{m k}\right)\right)\)
\(Q_{B}^{\prime}=\) foreach \(i^{\prime} \leq n\) do \(O_{B}\left[i^{\prime}\right]\left(x_{m}^{\prime}, x_{m a}\right):=\)
    find \(u \leq n\) suchthat defined \(\left(x_{m}[u]\right) \wedge x_{m}^{\prime}=x_{m}[u] \wedge \operatorname{verify}^{\prime}\left(x_{m}^{\prime}, x_{m k}, x_{m a}\right)\) then
        (
            if true then let \(\mathrm{i}_{\perp}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime \prime}\right)\right)=\operatorname{dec}\left(x_{m}^{\prime}, x_{k}\right)\) in return ()
        )
    else
        (
            if false then let \(\mathrm{i}_{\perp}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime \prime}\right)\right)=\operatorname{dec}\left(x_{m}^{\prime}, x_{k}\right)\) in return ()
        )
```

The initial definition of $x_{m r}$ is removed and replaced with a new definition, which we still call $x_{m r}$. The term $\operatorname{mac}\left(x_{m}, x_{m k}\right)$ is replaced with $\operatorname{mac}^{\prime}\left(x_{m}, x_{m k}\right)$. The term verify $\left(x_{m}^{\prime}, x_{m k}, x_{m a}\right)$ becomes find $u \leq n$ suchthat defined $\left(x_{m}[u]\right) \wedge x_{m}^{\prime}=x_{m}[u] \wedge \operatorname{verify}^{\prime}\left(x_{m}^{\prime}, x_{m k}, x_{m a}\right)$ then true else
false, which yields $Q_{B}^{\prime}$ after the call to expand, which transforms the find term into a process. The process looks up the message $x_{m}^{\prime}$ in the array $x_{m}$, which contains the messages whose MAC has been computed with key $x_{m k}$. If the MAC of $x_{m}^{\prime}$ has never been computed, the check always fails (it returns false) by the definition of security of the MAC. Otherwise, it returns true when $\operatorname{verify}^{\prime}\left(x_{m}^{\prime}, x_{m k}, x_{m a}\right)$.

After applying simplify, $Q_{A}^{\prime}$ is unchanged and $Q_{B}^{\prime}$ becomes

$$
\begin{aligned}
& Q_{B}^{\prime \prime}=\text { foreach } i^{\prime} \leq n \text { do } O_{B}\left[i^{\prime}\right]\left(x_{m}^{\prime}, x_{m a}\right):= \\
& \quad \text { find } u \leq n \text { suchthat defined }\left(x_{m}[u], x_{k}^{\prime}[u]\right) \wedge x_{m}^{\prime}=x_{m}[u] \wedge \operatorname{verify}^{\prime}\left(x_{m}^{\prime}, x_{m k}, x_{m a}\right) \text { then } \\
& \text { let } x_{k}^{\prime \prime}: T_{k}=x_{k}^{\prime}[u] \text { in return }()
\end{aligned}
$$

First, the tests if true then $\ldots$ and if false then $\ldots$ are simplified. The term $\operatorname{dec}\left(x_{m}^{\prime}, x_{k}\right)$ is simplified knowing $x_{m}^{\prime}=x_{m}[u]$ by the find condition, $x_{m}[u]=\operatorname{enc}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime}[u]\right), x_{k}, x_{r}[u]\right)$ by the assignment that defines $x_{m}$, and $\operatorname{dec}(\operatorname{enc}(m, k, r), k)=\mathrm{i}_{\perp}(m)$ by (enc). So we have $\operatorname{dec}\left(x_{m}^{\prime}, x_{k}\right)=$ $\mathrm{i}_{\perp}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime}[u]\right)\right)$. By injectivity of $\mathrm{i}_{\perp}$ and k 2 b , the assignment to $x_{k_{1}}^{\prime \prime}$ simply becomes $x_{k}^{\prime \prime}=x_{k}^{\prime}[u]$, using the equations $\forall x$ : bitstring, $\mathrm{i}_{\perp}^{-1}\left(\mathrm{i}_{\perp}(x)\right)=x$ and $\forall x: T_{k}, \mathrm{k} 2 \mathrm{~b}^{-1}(\mathrm{k} 2 \mathrm{~b}(x))=x$.

Then we apply the security of encryption: $\operatorname{enc}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime}\right), x_{k}, x_{r}\right)$ becomes $\operatorname{enc}^{\prime}\left(\mathrm{Z}\left(\mathrm{k} 2 \mathrm{~b}\left(x_{k}^{\prime}\right)\right), x_{k}\right.$, $\left.x_{r}\right)$. After simplify, it becomes enc ${ }^{\prime}\left(\mathrm{Z}_{k}, x_{k}, x_{r}\right)$, using $\forall x: T_{k}, \mathrm{Z}(\mathrm{k} 2 \mathrm{~b}(x))=\mathrm{Z}_{k}$ (which expresses that all keys have the same length).

So we obtain the following game:

$$
\begin{aligned}
& Q_{0}^{\prime \prime}=\operatorname{Start}():=x_{k} \stackrel{R}{\leftarrow} T_{k} ; x_{m k} \stackrel{R}{\leftarrow} T_{m k} ; \text { return }() ;\left(Q_{A}^{\prime \prime} \mid Q_{B}^{\prime \prime}\right) \\
& Q_{A}^{\prime \prime}=\text { foreach } i \leq n \text { do } O_{A}[i]():=x_{k}^{\prime} \stackrel{R}{\leftarrow} T_{k} ; x_{r} \stackrel{R}{\leftarrow} T_{r} ; \\
& \quad \text { let } x_{m}: \text { bitstring }=\operatorname{enc}^{\prime}\left(\mathrm{Z}_{k}, x_{k}, x_{r}\right) \text { in } \\
& \quad \text { return }\left(x_{m}, \operatorname{mac}^{\prime}\left(x_{m}, x_{m k}\right)\right)
\end{aligned}
$$

where $Q_{B}^{\prime \prime}$ remains as above.

## 6 Proof Strategy

Extension: This description is based on the initial proof strategy. Additional advice has been added since then.

Up to now, we have described the available game transformations. Next, we explain how we organize these transformations in order to prove protocols.

At the beginning of the proof and after each successful cryptographic transformation (that is, a transformation of Section 5.2 , the prover executes simplify and tests whether the desired security properties are proved, as described in Section 4. If so, it stops.

In order to perform the cryptographic transformations and the other syntactic transformations, our proof strategy relies of the idea of advice. Precisely, the prover tries to execute each available cryptographic transformation in turn. When such a cryptographic transformation fails, it returns some syntactic transformations that could make the desired transformation work. (These are the advised transformations.) Then the prover tries to perform these syntactic transformations. If they fail, they may also suggest other advised transformations, which are then executed. When the syntactic transformations finally succeed, we retry the desired cryptographic transformation, which may succeed or fail, perhaps with new advised transformations, and so on.

The prover determines the advised transformations as follows:

- Assume that we try to execute a cryptographic transformation, and need to recognize a certain term $M$ of $L$, but we find in $Q_{0}$ only part of $M$, the other parts being variable accesses $x[\ldots]$ while we expect function applications. In this case, we advise remove_assign binder $x$. For example, if $Q_{0}$ contains $\operatorname{sign}\left(M^{\prime}, x_{s k}, x_{r}\right)$ and we look for $\operatorname{sign}\left(x_{m}, \operatorname{skgen}\left(x_{r k}\right)\right.$, $x_{r}$ ), we advise remove_assign binder $x_{s k}$. (The transformation of Example 8 is advised for this reason.)
- When we try to execute remove_assign binder $x, x$ has several definitions, and there are accesses to variable $x$ guarded by find in $Q_{0}$, we advise SArename $x$.
- When we check whether $x$ is secret or one-session secret, we have an assignment let $x \widetilde{[i]}: T$ $=y[\widetilde{M}]$ in $P$, and there is at least one assignment defining $y$, we advise remove_assign binder $y$.
When we check whether $x$ is secret or one-session secret, we have an assignment let $x \widetilde{i}]: T$ $=y[\widetilde{M}]$ in $P, y$ is defined by random choices, $y$ has several definitions, and some variable accesses to $y$ are not of the form let $y^{\prime}\left[\widetilde{i^{\prime}}\right]: T=y\left[\widetilde{M^{\prime}}\right]$ in $P^{\prime}$, we advise SArename $y$.


## 7 Conclusion

The tool CryptoVerif produces proofs by sequences of games like those manually written by cryptographers. It generates the games, using an automatic proof strategy or guidance from the user, who specifies the transformations to perform. It supports a wide variety of cryptographic primitives specified by indistinguishability axioms. Many of these primitives are included in a library so that the user does not have to redefine them. It can prove secrecy, correspondence, and indistinguishability properties. It has been applied to substantial case studies, including Signal 52], TLS 1.3 [23], and WireGuard [58].

CryptoVerif still has limitations. In particular, the size of games tends to grow too fast, which limits its ability to deal with large examples, especially because some game transformations require the game to be expanded first by the expand transformation, which duplicates the code from each test until the end of protocol. Planed improvements include allowing more game transformations to work without previous application of expand; allowing internal oracle calls in games, in order to share code between different parts of the game; using composition results in order to make proofs more modular. Moreover, some game transformations could be generalized. For instance, the transformation merge_branches merges branches of a test when they execute the same code; the detection that several branches execute equivalent code could be made more flexible, by allowing reorderings of instructions for instance. CryptoVerif only considers blackbox adversaries: it does not support proofs that manipulate the code of the adversary, such as the forking lemma 65].

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[^1]:    ${ }^{1}$ if_fun $\left(b_{0}, M, M^{\prime}\right)$ differs from if $b_{0}$ then $M$ else $M^{\prime}$ in that it evaluates both $M$ and $M^{\prime}$. Since diff $\left[M, M^{\prime}\right]$ evaluates either $M$ or $M^{\prime}$ but not both, we translate it into if $b_{0}$ then $M$ else $M^{\prime}$ when the evaluation of $M$ or $M^{\prime}$ may modify the semantic state, e.g. by executing an event or by defining a variable. The evaluation of simple terms does not modify the semantic state.

