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# Quantum Query Complexity of Boolean Functions under Indefinite Causal Order

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The standard model of quantum circuits assumes operations are applied in a fixed sequential “causal” order. In recent years, the possibility of relaxing this constraint to obtain causally indefinite computations has received significant attention. The quantum switch, for example, uses a quantum system to coherently control the order of operations. Several *ad hoc* computational and information-theoretical advantages have been demonstrated, raising questions as to whether advantages can be obtained in a more unified complexity theoretic framework. In this paper, we approach this problem by studying the query complexity of Boolean functions under general higher order quantum computations. To this end, we generalise the framework of query complexity from quantum circuits to quantum supermaps to compare different models on an equal footing. We show that the recently introduced class of quantum circuits with quantum control of causal order cannot lead to any reduction in query complexity, and that any potential advantage arising from causally indefinite supermaps can be bounded by the polynomial method, as is the case with quantum circuits. Nevertheless, we find some functions for which the minimum error with which they can be computed using two queries is strictly lower when exploiting causally indefinite supermaps.

*Introduction.*—The query model of computation is a simplified framework that offers a way to evaluate the complexity of different computational problems and to probe and compare different computational frameworks. Notably, it has been used to prove various separations between classical and quantum computations, and to provide non-trivial lower bounds on some important computational problems, such as the optimality of Grover’s algorithm or the complexity of graph problems [1–3]. This model was thus far only studied in the context of quantum circuits, in which queries and unitary operations are performed in a fixed sequential order, implying an underlying fixed causal structure. Several recent works have proposed ways of computing beyond fixed causal structures using, for example, the quantum switch [4], where a quantum control system can put different sequences of operations into superposition, leading to what is called an indefinite causal order. Such scenarios can be studied in the higher order framework of quantum supermaps [4] (or “process matrices” [5]) which describes the most general transformations taking some given input operations into a valid output operation in a consistent manner. Although some quantum supermaps are compatible with a fixed causal order, and thus represent quantum circuits [6], others, like the quantum switch, have indefinite causal order or, more formally, are *causally nonseparable* [5, 7, 8].

Causal indefiniteness was shown to provide advantages over quantum circuits in several *ad hoc* tasks in quantum information theory [9–15]. However, much less is known about its potential advantages in a general complexity theoretic sense except that its computational complexity is upper bound by PP (which includes both NP and BQP) [16].

In this letter, we address this problem by proposing query complexity as a natural way of comparing the relative power of quantum circuits and causally indefinite

supermaps. After recalling the standard query model of computation in terms of quantum circuits, we formulate three different families of quantum supermaps that can be understood as query computations with different causal structures. We show that allowing for superpositions or coherent control of the order of queries in so-called *quantum circuits with quantum control of causal order* [17] cannot reduce the query complexity of Boolean functions compared to quantum circuits. Furthermore, through a generalisation of the polynomial method to general quantum supermaps, we give a lower bound on any possible reduction that could be obtained with causally indefinite supermaps. Then, using semidefinite programming techniques, we show that an advantage can be obtained with some such supermaps: for some functions, causal indefiniteness can reduce the minimum error with which they can be computed given a fixed number of queries.

*The query model of computation.*—In the quantum query model of computation (see [18] or [19] for a survey), the goal is to compute a Boolean function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  with a quantum circuit having access to an oracle  $O_x$ . Here without loss of generality we use the phase oracle [19, 20], defined as the unitary that takes as input a state  $|i\rangle$  in an  $(n + 1)$ -dimensional Hilbert space  $\mathcal{H}^Q$ , with  $i$  serving as an index,  $0 \leq i \leq n$  such that:

$$O_x |i\rangle = \begin{cases} (-1)^{x_i} |i\rangle & \text{if } i \neq 0, \\ |i\rangle & \text{otherwise.} \end{cases} \quad (1)$$

Note that the special case  $|i\rangle = |0\rangle$  is needed to ensure  $O_x$  is equivalent to the more common form oracle  $O'_x |j, b\rangle = |j, b \oplus x_j\rangle$ , with  $1 \leq j \leq n$ ,  $b \in \{0, 1\}$  and  $\oplus$  denoting addition modulo 2. A quantum circuit with  $T$  queries to the oracle is specified by a series of  $T + 1$  unitaries  $(U_1, \dots, U_{T+1})$  each acting on the space  $\mathcal{H}^{Q\alpha} = \mathcal{H}^Q \otimes \mathcal{H}^\alpha$ , with  $\mathcal{H}^\alpha$  an ancillary space of arbi-

trary dimension. By extending the oracle on the ancillary space,  $\tilde{O}_x = O_x \otimes \mathbb{1}^\alpha$ , we say the circuit computes  $f$  (exactly) if for all  $x$ , measuring the left most qubit of  $U_{T+1}\tilde{O}_x U_T \cdots U_1 \tilde{O}_x U_1 |0 \cdots 0\rangle$  gives the outcome  $f(x)$  with probability one. We similarly say that the circuit computes  $f$  with a bounded error  $\varepsilon$  if the measurement result gives, for all  $x$ ,  $f(x)$  with a probability at least  $1 - \varepsilon$  with some fixed  $\varepsilon < 1/2$ ; typically one takes  $\varepsilon = 1/3$ . The exact quantum query complexity of a Boolean function, written  $Q_E(f)$ , is the minimal value of  $T$  for which there exists a quantum query circuit computing  $f$  exactly, while  $Q_2(f)$  is the (two-sided) bounded error quantum query complexity, defined as the minimal  $T$  for which a quantum query circuit exists computing  $f$  with bounded error  $\varepsilon = 1/3$ .

This definition of quantum query complexity is the usual one considered in the literature, and is based on the standard formalism of quantum circuits. In this letter, we show that translating this definition into the framework of quantum supermaps leads to a natural generalisation of the notion of quantum query complexity to study the relative power of causal indefiniteness. Let us first introduce the tools and notation we will use throughout this letter.

*Mathematical tools and notation.*—We denote the space of linear operators on a Hilbert space  $\mathcal{H}^X$  as  $\mathcal{L}(\mathcal{H}^X)$ . To define quantum supermaps we first introduce *quantum channels*, which are completely positive (CP) trace-preserving (TP) maps  $\mathcal{M} : \mathcal{L}(\mathcal{H}^X) \rightarrow \mathcal{L}(\mathcal{H}^Y)$ . A channel is conveniently represented as a positive semidefinite matrix  $M^{XY} \in \mathcal{L}(\mathcal{H}^{XY})$  using the Choi isomorphism [21] (see Appendix A), where we adopt the shorthand  $\mathcal{H}^{XY} = \mathcal{H}^X \otimes \mathcal{H}^Y$ . The composition of two CP maps, potentially over a subset of their input/output systems, can be computed directly via their Choi matrices using the “link product” [6, 22], denoted ‘ $*$ ’ and defined for any matrices  $M^{XY} \in \mathcal{L}(\mathcal{H}^{XY})$  and  $N^{YZ} \in \mathcal{L}(\mathcal{H}^{YZ})$  as  $M^{XY} * N^{YZ} = \text{Tr}_Y[(M^{XY} \otimes \mathbb{1}^Z)^{\text{T}_Y}(\mathbb{1}^X \otimes N^{YZ})] \in \mathcal{L}(\mathcal{H}^{XZ})$ , where  $\text{Tr}_Y$  is the partial trace over the subsystem  $\mathcal{H}^Y$  and  $\cdot^{\text{T}_Y}$  the partial transpose over  $\mathcal{H}^Y$ . The link product is commutative and associative and reduces to the tensor product on maps acting on disjoint Hilbert spaces (see Appendix B).

A  $T$ -input *quantum supermap*  $\mathcal{S}$  is then a  $T$ -linear, completely CP-preserving, and TP-preserving map [23]. That is, a supermap is the most general transformation that transforms any  $T$  input channels  $\mathcal{M}_t : \mathcal{L}(\mathcal{H}^{A_k^t}) \rightarrow \mathcal{L}(\mathcal{H}^{A_k^o})$  into another quantum channel:  $\mathcal{S}(\mathcal{M}_1, \dots, \mathcal{M}_T) : \mathcal{L}(\mathcal{H}^P) \rightarrow \mathcal{L}(\mathcal{H}^F)$ . Writing  $\mathcal{H}^{A_k^{tO}} = \mathcal{H}^{A_k^t A_k^o}$  and, with  $\mathcal{T} := \{1, \dots, T\}$ ,  $\mathcal{H}^{A_{\mathcal{T}}^{tO}} = \bigotimes_{k \in \mathcal{T}} \mathcal{H}^{A_k^{tO}}$ , a supermap can be represented in the Choi picture as a “process matrix” [5], a positive semidefinite matrix  $W \in \mathcal{L}(\mathcal{H}^{PA_{\mathcal{T}}^{tO}F})$  belonging to a specific subspace  $\mathcal{L}^{\text{Gen}}$  (see Appendix C) and normalised such that  $\text{Tr} W = d^P \prod_{k=1}^T d_k^O$ , with  $d^P = \dim(\mathcal{H}^P)$  and  $d_k^O = \dim(\mathcal{H}^{A_k^o})$  [8, 24]. We denote the set of all such process matrices  $\mathcal{W}^{\text{Gen}}$ . The process matrix  $W$  fully char-

acterises  $\mathcal{S}$ , and the Choi matrix of the channel resulting from applying  $\mathcal{S}$  to some input channels  $(\mathcal{M}_1, \dots, \mathcal{M}_T)$  is obtained as  $\mathcal{S}(\mathcal{M}_1, \dots, \mathcal{M}_T) = (M_1 \otimes \cdots \otimes M_T) * W \in \mathcal{L}(\mathcal{H}^{PF})$ .

*Fixed order and quantum controlled supermaps.*—The general framework of quantum supermaps allows us to compare, on an equal footing, specific classes of quantum supermaps of particular interest, and to understand their computational capabilities. Here we present two sub-classes of particular interest: supermaps with a fixed causal order (sometimes termed quantum combs [6] and which are equivalent to quantum circuits), and quantum supermaps with quantum control of causal order [17].

The class of supermaps compatible with a fixed causal order (or *FO-supermaps*) has been extensively studied. Any such  $T$ -input supermap  $\mathcal{S}$  can be described by  $T + 1$  channels  $\mathcal{V}_1 : \mathcal{L}(\mathcal{H}^P) \rightarrow \mathcal{L}(\mathcal{H}^{A_1^{\alpha_1}})$ ,  $\mathcal{V}_t : \mathcal{L}(\mathcal{H}^{A_t^{\alpha_t}}) \rightarrow \mathcal{L}(\mathcal{H}^{A_{t+1}^{\alpha_{t+1}}})$  for  $2 \leq t \leq T$ , and  $\mathcal{V}_{T+1} : \mathcal{L}(\mathcal{H}^{A_T^{\alpha_T}}) \rightarrow \mathcal{L}(\mathcal{H}^F)$  composed sequentially in a circuit structure [6]. Here, the  $\mathcal{H}^{\alpha_t}$  are an ancillary spaces, and  $\mathcal{H}^P$  and  $\mathcal{H}^F$  are the input and output spaces of the circuit. In the Choi picture, the action of  $\mathcal{S}$  on  $T$  input channels  $(\mathcal{M}_1, \dots, \mathcal{M}_T)$  is

$$\begin{aligned} \mathcal{S}(\mathcal{M}_1, \dots, \mathcal{M}_T) &= \mathcal{V}_{T+1} * \mathcal{M}_T * \mathcal{V}_T * \cdots * \mathcal{V}_2 * \mathcal{M}_1 * \mathcal{V}_1 \\ &= (M_1 \otimes \cdots \otimes M_T) * W \in \mathcal{L}(\mathcal{H}^{PF}), \quad (2) \end{aligned}$$

where  $W = \mathcal{V}_{T+1} * \cdots * \mathcal{V}_1 \in \mathcal{L}(\mathcal{H}^{PA_{\mathcal{T}}^{tO}F})$  is the process matrix of  $\mathcal{S}$ . Process matrices of this specific form—which can be decomposed as the link product of quantum channels—belong to a subset  $\mathcal{W}^{\text{FO}} \subset \mathcal{W}^{\text{Gen}}$  [6, 17, 22] (see Appendix D). It is easy to see that quantum query circuits, as defined above, can readily be represented as FO-supermaps.

Another family of supermaps, those with quantum control of causal order (or *QC-supermaps*), can be formulated as generalised quantum circuits in which a quantum system controls the order of application of the different input operations [17]. QC-supermaps are of particular interest as they are the most general type of quantum supermap with a clear physical realisation [17, 25, 26], and include supermaps such as the quantum switch that are causally indefinite [4].

A QC-supermap alternates between applying some controlled “internal” operations on a “target” system and some ancillary systems, potentially correlating these systems with the quantum control, and using this control system to control which input operations to apply to the target system at time-step  $t$ . More precisely, throughout the computation the control system, at time-step  $t$ , has basis states  $|\mathcal{K}_{t-1}, k_t\rangle$  specifying that operation  $k_t \notin \mathcal{K}_{t-1}$  will be applied next and that the operations  $\mathcal{K}_{t-1} \subsetneq \mathcal{T}$  have already been applied. This system controls coherently the application of the different input operations  $\mathcal{M}_{k_t}$  at time-step  $t$  and the pure internal operations  $\mathcal{V}_{\mathcal{K}_{t-1}, k_t}^{\rightarrow k_{t+1}} : \mathcal{L}(\mathcal{H}^{A_{k_t}^{\alpha_t}}) \rightarrow \mathcal{L}(\mathcal{H}^{A_{k_{t+1}}^{\alpha_{t+1}}})$  between time-steps, and is the minimal control system required to

ensure that no operation is applied more than once, while maintaining the possibility for superpositions of causal orders and interference of different causal histories (i.e., permutations of the operations in  $\mathcal{K}_{t-1}$ ); see Appendix E or [17] for a more detailed description of QC-supermaps. Process matrices of QC-supermaps belong to a subset  $\mathcal{W}^{\text{QC}} \subset \mathcal{W}^{\text{Gen}}$  [17], whose characterisation is also given in Appendix E.

*Quantum query complexity under indefinite causal order.*—We can now define what it means for a quantum supermap to compute a Boolean function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$ , allowing us to compare the different type of supermaps on an equal footing.

Let us consider a  $T$ -input supermap  $\mathcal{S}^{\mathcal{C}}$  of class  $\mathcal{C} \in \{\text{FO}, \text{QC}, \text{Gen}\}$ , with trivial input space  $\dim(\mathcal{H}^P) = 1$  and output space of dimension  $\dim(\mathcal{H}^F) = 2$ . These dimensional constraints reflect the fact that, as in the initial definition of quantum query complexity, any fixed input to the supermap can be absorbed directly into it, and only a single output qubit—that will be measured to define the output of the computation—is needed.

To differentiate the different input and output spaces of each query, we label (without imposing a particular order) the  $T$  queries to the phase oracle (1) as  $\mathcal{O}_x^{(1)}, \dots, \mathcal{O}_x^{(T)}$ , with  $\mathcal{O}_x^{(i)} : \mathcal{L}(\mathcal{H}^{A_i}) \rightarrow \mathcal{L}(\mathcal{H}^{A_i^O})$ , where  $\mathcal{H}^{A_i}$  and  $\mathcal{H}^{A_i^O}$  are of dimension  $n + 1$ . (Here  $\mathcal{O}_x$  is the quantum channel corresponding to the unitary oracle  $O_x$ .) Then for every  $x$ , the output of  $\mathcal{S}^{\mathcal{C}}$  is the qubit state  $\mathcal{S}^{\mathcal{C}}(\mathcal{O}_x^{(1)}, \dots, \mathcal{O}_x^{(T)}) \in \mathcal{L}(\mathcal{H}^F)$ . The probability that one obtains  $f(x)$  when measuring this qubit in the computational basis is then given by the Born rule as

$$p(f(x)) = \text{Tr} \left[ \mathcal{S}^{\mathcal{C}}(\mathcal{O}_x^{(1)}, \dots, \mathcal{O}_x^{(T)}) \cdot \Pi_{f(x)} \right] \quad (3)$$

$$= \text{Tr} \left[ (\mathcal{O}_x^{\otimes T} * W^{\mathcal{C}}) \cdot \Pi_{f(x)} \right] \quad (4)$$

$$= \text{Tr} \left[ (\mathcal{O}_x^T \otimes \Pi_{f(x)}) \cdot W^{\mathcal{C}} \right], \quad (5)$$

with  $\Pi_{f(x)} = |f(x)\rangle\langle f(x)|$  and  $\mathcal{O}_x^{\otimes T} = \bigotimes_{i=1}^T \mathcal{O}_x^{(i)}$ . We say that  $\mathcal{S}^{\mathcal{C}}$  computes  $f$  with a bounded error  $\varepsilon$  if for all  $x$ ,  $p(f(x)) \geq 1 - \varepsilon$ . We can now define  $Q_E^{\mathcal{C}}(f)$  as the minimum value  $T$  for which there exists a quantum supermap  $\mathcal{S}^{\mathcal{C}}$  computing  $f$  exactly (i.e., with error  $\varepsilon = 0$ ). Similarly, the corresponding bounded-error complexity  $Q_2^{\mathcal{C}}(f)$  is the minimum  $T$  for which there exists a quantum supermap  $\mathcal{S}^{\mathcal{C}}$  computing  $f$  with bounded error  $\varepsilon = 1/3$ . By definition we have the following inequalities:

$$Q_E^{\text{Gen}}(f) \leq Q_E^{\text{QC}}(f) \leq Q_E^{\text{FO}}(f) = Q_E(f), \quad (6)$$

$$Q_2^{\text{Gen}}(f) \leq Q_2^{\text{QC}}(f) \leq Q_2^{\text{FO}}(f) = Q_2(f). \quad (7)$$

To compare the power of the different classes of quantum supermaps in terms of query complexity, we need to understand how these inequalities can be refined.

*Quantum control over  $T$  copies of the same unitary channel.*—QC-supermaps are known to provide advantages over FO-supermaps in several tasks, some of which are sometimes expressed as query complexity advantages

(albeit of a different kind than studied here), such as in the discrimination between pairs of commuting and anti-commuting unitaries [9] and generalisations of that task [10, 12]. Here we show that they cannot provide any advantage in query complexity of Boolean functions through the generalisation of a recent result for “switch-like” supermaps, a strict subclass of QC-supermaps which generalises the quantum switch. In particular, we build on a result of Ref. [13] showing that such supermaps are equivalent to FO-supermaps when acting on  $T$  copies of the same unitary channel. Here we prove the following theorem.

**Theorem 1.** *For any  $T$ -input QC-supermap  $\mathcal{S}^{\text{QC}}$ , there exists an FO-supermap  $\mathcal{S}^{\text{FO}}$  such that  $\mathcal{S}^{\text{QC}}$  and  $\mathcal{S}^{\text{FO}}$  have the same action whenever applied to  $T$  copies of the same unitary channel. That is, for all unitary channels  $\mathcal{U}$ ,  $\mathcal{S}^{\text{QC}}(\mathcal{U}, \dots, \mathcal{U}) = \mathcal{S}^{\text{FO}}(\mathcal{U}, \dots, \mathcal{U})$ .*

The proof of Theorem 1 is detailed in Appendix F. A direct corollary is that  $Q_E^{\text{QC}} = Q_E^{\text{FO}}$  and  $Q_2^{\text{QC}} = Q_2^{\text{FO}}$ . Thus, no advantage in query complexity can be found using QC-supermaps instead of FO-supermaps, and for that matter, in any task where  $T$  copies of the same unitary channel are considered, such as the reversal of unknown unitary transformations [27] or unitary channel discrimination [13]. In both these tasks, however, advantages were obtained using more general causally indefinite quantum supermaps beyond QC-supermaps. This raises the prospect of nevertheless obtaining advantages in query complexity from causally indefinite supermaps. In order to better target where to look for such an advantage, we first provide a lower bound on any potential reduction of query complexity of Boolean functions with general supermaps by generalising a well-studied bound for quantum circuits, the polynomial method.

*Polynomial bound for general quantum supermaps.*—The polynomial method makes a connection between the output of an FO-supermap and a multivariate polynomial  $g$ , and is an important method for proving lower bounds on the quantum query complexity of Boolean functions [28]. A polynomial  $g$  is said to represent a Boolean function  $f$  if for all  $x \in \{0, 1\}^n$ ,  $f(x) = g(x)$ . As an example, consider the polynomial  $g(x_1, x_2) = x_1 + x_2 - x_1 x_2$ , which represents the Boolean OR function. This polynomial has degree 2, and we denote  $\deg(f)$  the smallest degree of any polynomial representing  $f$ . Similarly, we write  $\widetilde{\deg}(f)$  the degree of the smallest polynomial approximating  $f$  with a bounded error  $\varepsilon = 1/3$ , i.e., such that for all  $x$ ,  $|g(x) - f(x)| \leq 1/3$ . The polynomial method states that for all Boolean functions we have  $\deg(f)/2 \leq Q_E^{\text{FO}}(f)$ , and likewise for the bounded-error counterpart, that  $\widetilde{\deg}(f)/2 \leq Q_2^{\text{FO}}(f)$ . Here, we generalise this lower bound to general supermaps and thereby bound the potential advantage obtainable with causally indefinite supermaps over standard quantum circuits.

**Theorem 2.** *For any Boolean function  $f$ , we have  $\deg(f)/2 \leq Q_E^{\text{Gen}}(f)$  and  $\widetilde{\deg}(f)/2 \leq Q_2^{\text{Gen}}(f)$ .*

The proof is similar to that of the original result; we provide the full details in Appendix G and simply outline the argument here. Supposing that  $Q_E^{\text{Gen}}(f) = T$ , there is a  $T$ -input supermap  $\mathcal{S}^{\text{Gen}}$  with process matrix  $W^{\text{Gen}}$  such that  $f(x) = \text{Tr}[(\mathcal{O}_x^{\otimes T} * W^{\text{Gen}}) \cdot \Pi_1]$ . Proceeding by induction, one finds that the Choi matrix of the  $T$  queries,  $\mathcal{O}_x^{\otimes T}$ , has coefficients that are multivariate polynomials of degree at most  $2T$ . Since both the trace and link product are linear, it immediately follows that  $f(x)$  is also a multivariate polynomial of degree at most  $2T$ , completing the proof. An analogous proof gives us the bounded error version of the statement.

These results mean that for functions whose polynomial bound is tight for FO-supermaps, i.e., when  $\deg(f)/2 = Q_E^{\text{FO}}(f)$  or  $\widetilde{\deg}(f)/2 = Q_2^{\text{FO}}(f)$ , causal indefiniteness cannot provide any advantage. This is the case, for example, of the OR function [28] (which is computed with a bounded error by Grover's algorithm). Theorems 1 and 2 thus allows us to refine the inequalities (6) and (7) as follows:

$$\deg(f)/2 \leq Q_E^{\text{Gen}}(f) \leq Q_E^{\text{QC}}(f) = Q_E^{\text{FO}}(f) = Q_E(f) \quad (8)$$

$$\widetilde{\deg}(f)/2 \leq Q_2^{\text{Gen}}(f) \leq Q_2^{\text{QC}}(f) = Q_2^{\text{FO}}(f) = Q_2(f). \quad (9)$$

Still, it is known that some Boolean functions do not have a tight polynomial bound [29], meaning that Theorem 2 does not rule out a potential advantage from causal indefiniteness using general supermaps. This motivates us to study explicit Boolean functions to look for such an advantage. In general, we lack an understanding of general supermaps beyond QC-supermaps, so trying to develop analytically supermaps providing such an advantage for general  $n$ -bit Boolean functions is extremely challenging. Instead, we study exhaustively Boolean functions up to 4 bits, building on the extensive literature on the optimisation of quantum supermaps using semidefinite programs (SDPs) [8, 24].

*Advantage of general supermaps over FO-supermaps.*—In the remainder of this letter, we show an advantage of causally indefinite supermaps over fixed order ones by considering the minimum bounded error computation of a function  $f$ . Let us denote by  $\varepsilon_T^{\text{FO}}(f)$  (resp.  $\varepsilon_T^{\text{Gen}}(f)$ ) the minimum error  $\varepsilon$  for which there exists a  $T$ -query FO-supermap (resp. a general supermap) computing  $f$  with a bounded error  $\varepsilon$ . We prove the following theorem for  $T = 2$ .

**Theorem 3.** *There exists some function  $f$  for which  $\varepsilon_2^{\text{Gen}}(f) < \varepsilon_2^{\text{FO}}(f)$ .*

To prove Theorem 3, we use SDPs to look for such a gap on all Boolean functions up to 4 input bits. A systematic study for quantum circuits of the minimum bounded error computation of functions using SDPs was already performed in Ref. [30] for functions up to 4 bits, and for symmetric functions up to 6 bits. Their SDP formulation keeps track of the evolution of the state through

the quantum circuit by defining  $T$  Gram matrices, one for each additional query [31]. Unfortunately this method fails to extend to general supermaps as it exploits the sequential structure of a FO-supermap which has no analogue in generic quantum supermaps.<sup>1</sup> Here, using the characterisation of supermaps in the Choi picture as process matrices  $W$ , we give an SDP formulation of the minimum error bound for both FO-supermaps and general ones.

Let us consider a Boolean function  $f$  and a  $T$ -query supermap  $\mathcal{S}^{\mathcal{C}}$  with  $\mathcal{C} \in \{\text{FO}, \text{Gen}\}$ . Because we measure the output of the supermap to obtain the value of  $f(x)$ , it is convenient to consider, instead of the process matrix  $W$ , the quantum superinstrument  $\{W^{[i]}\}_{i \in \{0,1\}}$  such that  $W^{[i]} = W * \Pi_i$  [17], so that  $p(f(x)) = \text{Tr}[W^{[f(x)]} \cdot \mathcal{O}_x^{\otimes T}]$ . This has the advantage of reducing the size of the matrices being optimised numerically; for  $T = 2$  and  $n = 4$ ,  $W$  is a matrix of size 1250, whereas the  $W^{[i]}$  are of size 625, a difference crucial for rendering the SDPs we present below tractable. Writing  $F^{[i]} = \{x : f(x) = i\}$ , the minimum error bound  $\varepsilon_T^{\mathcal{C}}(f)$  is given by the SDP

$$\begin{aligned} \varepsilon_T^{\mathcal{C}}(f) &= \max_{\varepsilon, W^{[0]}, W^{[1]}} 1 - \varepsilon \\ \text{s.t. } \forall x \in F^{[0]}, \text{Tr}[W^{[0]} \cdot \mathcal{O}_x^{\otimes T}] &\geq 1 - \varepsilon, \\ \forall x \in F^{[1]}, \text{Tr}[W^{[1]} \cdot \mathcal{O}_x^{\otimes T}] &\geq 1 - \varepsilon, \quad (10) \\ W^{[0]} \geq 0, W^{[1]} \geq 0, \varepsilon \geq 0, \\ W^{[0]} + W^{[1]} &\in \mathcal{W}^{\mathcal{C}}. \end{aligned}$$

Note that the size of the  $W^{[i]}$ 's scale as  $(n+1)^{2T}$  making the SDP difficult to solve for even moderate  $n$  and  $T$ . We solved it numerically for 2 queries and for all Boolean functions up to 4 bits (including constant functions and functions depending on fewer bits). By exploiting the symmetries inherent in the SDP, one can further reduce the number of variables and constraints, but we were still unable to solve it for 3 queries or 5 bits.

For 3 bits and 2 queries it is known that FO-supermaps are sufficient to exactly compute all functions except the AND function [30] which has an exact query complexity  $Q_E^{\text{FO}}(\text{AND}) = n$ . For this function, no advantage was found with 2-query general supermaps.

For 4-bit functions, as in Ref. [30], we reduced the number of functions to look at by considering the so-called negate, permute, negate (NPN) equivalence relation. We say that two Boolean functions are equivalent if they are the same up to negation and permutation of the input bits, and negation of the output. These transformations correspond to a relabelling of the input and output bits, leaving unchanged the query complexity of a function.

<sup>1</sup> Indeed, for the same reason a more powerful method of bounding query complexity for quantum circuits, the adversarial method [20, 32], is not readily generalisable to generic supermaps, in contrast to the polynomial bound.

The results are summarised in Table I of Appendix J where the ID of a function corresponds to its truth table converted into an integer, and the results of the SDPs for both FO- and general supermaps are rounded to the fifth decimal place. Our results for FO-supermaps coincide, as expected, with those of Ref. [30]. Out of the 222 NPN representatives, we observe a gap between the minimum error bounds  $\varepsilon_2^{\text{FO}}(f)$  and  $\varepsilon_2^{\text{Gen}}(f)$  for 179 functions, the maximum gap being 0.00947 (close to 1%) for the functions with IDs 5783, 5865 and 6630. The simplest of the three functions (ID 5865), can be written as the polynomial  $f(x) = x_1 + x_2x_3 + x_2x_4 + x_3x_4 + x_2x_3x_4$ .

This numerical evidence is not an analytical proof of Theorem 3 as the constraints of the SDPs are only satisfied up to numerical precision. However, extracting an FO- or general supermap that rigorously verifies the constraints is possible by rationalising the numerical results and perturbing the SDPs' solutions. Such a method was developed in Ref. [33] and allows us to obtain upper bounds with the primal SDP (10), and lower bounds with the corresponding dual SDP which can be derived with Lagrangian method (see Appendix H). Using the extraction methods (detailed in Appendix I) for the function ID 5865, we find the bounds

$$0.0324 \leq \varepsilon_2^{\text{Gen}}(f) \leq 0.0377 < 0.0465 \leq \varepsilon_2^{\text{FO}}(f) \leq 0.0467, \quad (11)$$

which proves Theorem 3.

*Discussion.*—By generalising the notion of query complexity to general supermaps, we provide a natural tool to probe, in a unified complexity theoretic framework and on equal footing, the power and the potential advantages that different types of causal structure can provide. Until now, it was unclear whether causal indefiniteness could provide any advantage in such a fundamental model of computation. We found a separation between FO-supermaps and general, potentially causally indefinite, supermaps in the minimum error probability with

which they can compute a Boolean function using two queries. While this separation does not directly translate into an asymptotic query complexity separation, it is a crucial first step in this direction. One possible such approach would be to explore whether the separation we found can be amplified by recursively composing supermaps in a suitably well-defined manner [34, 35], similar to the advantage in query complexity obtained with quantum circuits in Ref. [29]. These results also raise the question of whether it is possible to find a separation in exact query complexity.

Along the way, we also showed some important results limiting the power of causal indefiniteness, generalising the polynomial method, and proving the equivalence of FO-supermaps and QC-supermaps on certain problems, including query complexity. This raises natural questions about the power of specific classes of supermaps beyond QC-supermaps, such as that of purifiable processes [36].

With QC-supermaps being the most general supermaps we currently know how to implement, it will be interesting to study further settings. For instance, can advantages over quantum circuits be obtained when given multiple different oracles, and can our results be used to obtain advantages in quantum communication complexity in more standard settings than those studied with causal indefiniteness previously [37]?

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## Appendix A: Choi isomorphism

The Choi–Jamiołkowski isomorphism [21, 38] (here we use the “Choi version”) is an isomorphism between two different representations of CPTP maps. The Choi matrix of a linear map  $\mathcal{M} : \mathcal{L}(\mathcal{H}^X) \rightarrow \mathcal{L}(\mathcal{H}^Y)$  is defined as

$$\mathbf{M} = \mathcal{I} \otimes \mathcal{M}(|\mathbb{1}\rangle\rangle\langle\langle\mathbb{1}|^{XX}) = \sum_{i,i'} |i\rangle\langle i'| \otimes \mathcal{M}(|i\rangle\langle i'|) \in \mathcal{L}(\mathcal{H}^X \otimes \mathcal{H}^Y), \quad (\text{A1})$$

where  $|\mathbb{1}\rangle\rangle^{XX} = \sum_i |i\rangle \otimes |i\rangle \in \mathcal{H}^{XX}$  is the (unnormalised) maximally entangled state,  $\{|i\rangle\}_i$  the computational basis of  $\mathcal{H}^X$ , and  $\mathcal{I} : \mathcal{L}(\mathcal{H}^X) \rightarrow \mathcal{L}(\mathcal{H}^X)$  the identity channel. Here, as throughout, we use the shorthand notation  $\mathcal{H}^{XY} := \mathcal{H}^X \otimes \mathcal{H}^Y$ , etc. Several important properties of a linear map  $\mathcal{M}$  can be directly described through its Choi matrix  $\mathbf{M}$ . In particular,  $\mathcal{M}$  is completely positive (CP) if and only if  $\mathbf{M}$  is positive semidefinite (i.e.,  $\mathbf{M} \geq 0$ ), and  $\mathcal{M}$  is trace preserving (TP) if and only if  $\text{Tr}_Y(\mathbf{M}) = \mathbb{1}^X$ . These two properties make the Choi isomorphism a useful tool for optimising over quantum channels in semidefinite programs (SDPs). Finally, the action of  $\mathcal{M}$  can be described in terms of its Choi matrix via the inverse Choi isomorphism as

$$\mathcal{M}(\rho) = \text{Tr}_X [(\rho^{\text{T}} \otimes \mathbb{1}^Y)\mathbf{M}], \quad (\text{A2})$$

where  $\cdot^{\text{T}}$  is the partial transpose with respect to the computational basis, and  $\text{Tr}_X$  denotes the partial trace over the system  $X$ .

It is often convenient to manipulate unitary (or isometric) channels at the level of their so-called Choi vectors. For an isometric channel  $\mathcal{U}$ , corresponding to the isometry  $U : \mathcal{H}^X \rightarrow \mathcal{H}^Y$ , its Choi vector is given as

$$|U\rangle\rangle = \mathbb{1}^X \otimes U(|\mathbb{1}\rangle\rangle^{XX}) = \sum_i |i\rangle \otimes U|i\rangle \in \mathcal{H}^{XY}, \quad (\text{A3})$$

and its Choi matrix can be recovered as  $\mathbf{U} = |U\rangle\rangle\langle\langle U|$ .

## Appendix B: Link product

The link product [6, 22] is a useful tool allowing the composition of CP maps, potentially over a subset of their input/output systems, to be computed directly in the Choi picture. It is defined, for any matrices  $\mathbf{M}^{XY} \in \mathcal{L}(\mathcal{H}^{XY})$  and  $\mathbf{N}^{YZ} \in \mathcal{L}(\mathcal{H}^{YZ})$ , as

$$\mathbf{M}^{XY} * \mathbf{N}^{YZ} = \text{Tr}_Y [(\mathbf{M}^{XY} \otimes \mathbb{1}^Z)^{\text{T}_Y} (\mathbb{1}^X \otimes \mathbf{N}^{YZ})] \in \mathcal{L}(\mathcal{H}^{XZ}), \quad (\text{B1})$$

where  $\cdot^{\text{T}_Y}$  denotes the partial transpose over the Hilbert space  $\mathcal{H}^Y$ . Because of the invariance of the trace under cyclic permutations, the link product is commutative,  $\mathbf{M}^{XY} * \mathbf{N}^{YZ} = \mathbf{N}^{YZ} * \mathbf{M}^{XY}$ , while in  $n$ -fold link products it is also associative as long as each Hilbert space appears at most twice in the product. This will notably allow us to write unambiguously, for example,  $\mathbf{M}_1 * \dots * \mathbf{M}_T$ , and is likewise why we differentiate, for instance, between the Hilbert spaces  $\mathcal{H}^{\alpha_i}$  and  $\mathcal{H}^{\alpha_{i'}}$  of the ancillary systems at different places in a quantum circuit (or QC-supermap), even if these spaces are isomorphic.

When  $\mathcal{H}^Y$  is trivial (so that  $\mathbf{M}^{XY}$  and  $\mathbf{N}^{YZ}$  do not share any Hilbert spaces), the link product reduces to the tensor product as  $\mathbf{M}^X * \mathbf{N}^Z = \mathbf{M}^X \otimes \mathbf{N}^Z$ . If, on the other hand,  $\mathcal{H}^X$  and  $\mathcal{H}^Z$  are trivial (so that the operations act on the same Hilbert space  $\mathcal{H}^Y$ ), then  $\mathbf{M}^Y * \mathbf{N}^Y = \text{Tr}[(\mathbf{M}^Y)^{\text{T}} \mathbf{N}^Y]$ .

A version of the link product can also be formulated for vectors, allowing the composition of unitaries (or, more generally, isometries) to be described directly on their Choi vectors [17]. The link product between two vectors  $|U\rangle\rangle \in \mathcal{H}^{XY}$  and  $|V\rangle\rangle \in \mathcal{H}^{YZ}$  is given as

$$|U\rangle\rangle * |V\rangle\rangle = (|U\rangle\rangle^{\text{T}_Y} \otimes \mathbb{1}^Z) |V\rangle\rangle \in \mathcal{H}^{XZ}. \quad (\text{B2})$$

## Appendix C: Characterisation of general supermaps

Recall that, as described in the main text, a general  $T$ -input quantum supermap  $\mathcal{S}$  is a  $T$ -linear completely CP-preserving and TP-preserving map. Such a supermap can be represented in the Choi picture by its process matrix



$W \in \mathcal{L}(\mathcal{H}^{PA_T^{IO}F})$  [5, 24]. Let us write the set of all process matrices of general  $T$ -input quantum supermaps<sup>2</sup> as  $\mathcal{W}^{\text{Gen}}$ .

The process matrices of quantum supermaps are positive semidefinite matrices normalised to satisfy  $\text{Tr} W = d^P \prod_{k=1}^T d_k^O$  (with  $d^P = \dim(\mathcal{H}^P)$  and  $d_k^O = \dim(\mathcal{H}^{A_k^O})$ ), and which belong to a specific linear subspace  $\mathcal{L}^{\text{Gen}}$ . This subspace can be nicely characterised through linear constraints on  $W^{\text{Gen}}$ , allowing one to optimise over general supermaps in SDPs. This characterisation can be nicely expressed using the ‘‘trace-out-and-replace’’ notation [24] defined as

$${}_X W = \frac{\mathbb{1}^X}{d_X} \otimes \text{Tr}_X W \quad \text{and} \quad [1-X] W = W - \frac{\mathbb{1}^X}{d_X} \otimes \text{Tr}_X W, \quad (\text{C1})$$

with  $d_X = \dim(\mathcal{H}^X)$ . Let us also define the ‘‘reduced’’ process matrices  $W^{[P]} = \text{Tr}_{A_T^{IO}F} W \in \mathcal{L}(\mathcal{H}^P)$  and, for any nonempty subset  $\mathcal{K} \subseteq \mathcal{T}$ ,

$$W^{[P\mathcal{K}]} = \text{Tr}_{A_{\mathcal{T} \setminus \mathcal{K}}^{IO}F} W \in \mathcal{L}(\mathcal{H}^{PA_{\mathcal{K}}^{IO}}). \quad (\text{C2})$$

**Proposition 1** (From [17, 24]). *A matrix  $W \in \mathcal{L}(\mathcal{H}^{PA_T^{IO}F})$  is the process matrix of a  $T$ -input quantum supermap (i.e.,  $W \in \mathcal{W}^{\text{Gen}}$ ) if and only if  $W$  is positive semidefinite ( $W \geq 0$ ),  $\text{Tr} W = d^P \prod_{k=1}^T d_k^O$ , and  $W \in \mathcal{L}^{\text{Gen}}$ , where the linear subspace  $\mathcal{L}^{\text{Gen}}$  is defined as*

$$W \in \mathcal{L}^{\text{Gen}} \iff \forall \emptyset \subsetneq \mathcal{K} \subseteq \mathcal{T}, \quad \Pi_{k \in \mathcal{K}} [1-A_k^O] W^{[P\mathcal{K}]} = 0 \quad \text{and} \quad [1-P] W^{[P]} = 0. \quad (\text{C3})$$

#### Appendix D: Characterisation of FO-supermaps

In a  $T$ -input fixed order quantum supermap, the input operations are applied in a fixed sequential order. For example, the order  $(1, \dots, T)$  means that the input operations are applied in the order they are passed as arguments. Such a supermap can be represented in the Choi picture by its process matrix  $W \in \mathcal{L}(\mathcal{H}^{PA_T^{IO}F})$  [6, 22], which can be decomposed as the link product of some quantum channels,  $W = \mathcal{V}_{T+1} * \dots * \mathcal{V}_1$ , with the  $\mathcal{V}_i$ 's, for  $2 \leq t \leq T$ , being the Choi matrices of quantum channels  $\mathcal{V}_t : \mathcal{L}(\mathcal{H}^{A_t^{O\alpha_t}}) \rightarrow \mathcal{L}(\mathcal{H}^{A_{t+1}^{O\alpha_{t+1}}})$ , and  $\mathcal{V}_1 : \mathcal{L}(\mathcal{H}^P) \rightarrow \mathcal{L}(\mathcal{H}^{A_1^{O\alpha_1}})$  and  $\mathcal{V}_{T+1} : \mathcal{L}(\mathcal{H}^{A_T^{O\alpha_T}}) \rightarrow \mathcal{L}(\mathcal{H}^F)$ , where the  $\mathcal{H}^{\alpha_t}$  are ancillary Hilbert spaces and can, without loss of generality, be taken to be isomorphic (we differentiate them for clarity and to write unambiguously the link product of all  $\mathcal{V}_t$  as above). Let us write the set of all process matrices of  $T$ -input FO-supermaps as  $\mathcal{W}^{\text{FO}}$ .

A nice characterisation of the set  $\mathcal{W}^{\text{FO}}$  is obtained by combining the trace-preserving conditions on the Choi matrices of the  $\mathcal{V}_t$  and the decomposition of  $W$  into their link product.

**Proposition 2** (From [6, 17]). *A matrix  $W \in \mathcal{L}(\mathcal{H}^{PA_T^{IO}F})$  is the process matrix of a  $T$ -input quantum supermap with fixed order  $(1, \dots, T)$  (i.e.,  $W \in \mathcal{W}^{\text{FO}}$ ) if and only if it is positive semidefinite and its reduced matrices, defined for  $1 \leq t \leq T$  as*

$$W_{(t)} = \frac{1}{d_t^O d_{t+1}^O \dots d_T^O} \text{Tr}_{A_t^O A_{\{t+1, \dots, T\}}^{IO}F} W \in \mathcal{L}(\mathcal{H}^{PA_{\{1, \dots, t-1\}}^{IO}A_t^I}), \quad (\text{D1})$$

satisfy

$$\begin{aligned} \text{Tr}_{A_1^I} W_{(1)} &= \mathbb{1}^P, \\ \forall n = 1, \dots, T-1, \quad \text{Tr}_{A_{t+1}^I} W_{(t+1)} &= W_{(t)} \otimes \mathbb{1}^{A_t^O}, \\ \text{and } \text{Tr}_F W &= W_{(T)} \otimes \mathbb{1}^{A_T^O}. \end{aligned} \quad (\text{D2})$$

#### Appendix E: Description and characterisation of QC-supermaps

Supermaps with quantum control of causal order (or QC-supermaps) are a form of generalised quantum circuits where a quantum system is used to coherently control the order in which the input operations are applied. For

<sup>2</sup> For a given (in general, implicitly) scenario, i.e., specification of  $T$  and the dimensions of the Hilbert spaces  $\mathcal{H}^P, \mathcal{H}^{A_k^I}, \mathcal{H}^{A_k^O}, \mathcal{H}^F$ .

simplicity, we will assume throughout the presentation of QC-supermaps here that the input operations are unitaries  $(U_1, \dots, U_T)$ . For a more detailed presentation and the (rather simple) generalisation to generic channels as input operations (which leads to the same set of corresponding process matrices), see [17].

A QC-supermap alternates between applying some controlled “internal” operations on a “target” system and some ancillary systems, potentially correlating these systems with the quantum control, and using this control system to control which input operations to apply at time-step  $t$ . More precisely, throughout the computation the control system takes, at time-step  $t$ , the basis states  $|\mathcal{K}_{t-1}, k_t\rangle^{C_t^{(i)}} \in \mathcal{H}^{C_t^{(i)}}$ , specifying that operation  $k_t \notin \mathcal{K}_{t-1}$  will be applied and that the operations  $\mathcal{K}_{t-1} \subsetneq \mathcal{T}$  have already been applied. This control system controls the application of the different  $U_{k_t}$  and the pure operations  $V_{\mathcal{K}_{t-1}, k_t}^{\rightarrow k_{t+1}}$  between time-steps, and is the minimal control system required to ensure that no operation is applied more than once, while maintaining the possibility for superpositions of causal orders and interference of different causal histories (i.e., permutations of the operations in  $\mathcal{K}_{t-1}$ ).

A QC-supermap is completely specified by the composites of the internal operations,  $V_{\emptyset, \emptyset}^{\rightarrow k_1} : \mathcal{H}^P \rightarrow \mathcal{H}^{A_{k_1}^I \alpha_1}$ ,  $V_{\mathcal{K}_{t-1}, k_t}^{\rightarrow k_{t+1}} : \mathcal{H}^{A_{k_t}^O \alpha_t} \rightarrow \mathcal{H}^{A_{k_{t+1}}^I \alpha_{t+1}}$  (for  $1 \leq t \leq T-1$ ) and  $V_{\mathcal{K}_{T-1}, k_T}^{\rightarrow F} : \mathcal{H}^{A_{k_T}^O \alpha_T} \rightarrow \mathcal{H}^{F \alpha_F}$ , where the  $\mathcal{H}^{\alpha_t}$  and  $\mathcal{H}^{\alpha_F}$  are again ancillary spaces which, without loss of generality, can be assumed to be isomorphic at each time-step. In order to formally express the control of both the internal and external (input) operations – which act on *a priori* different spaces – it is necessary to embed these operations in some generic input and output spaces  $\mathcal{H}^{\tilde{A}_t^I}$  and  $\mathcal{H}^{\tilde{A}_t^O}$  for each time-step  $t$  [17]. We denote the corresponding operators  $\tilde{U}_{k_t}^{[t]} : \mathcal{H}^{\tilde{A}_t^I} \rightarrow \mathcal{H}^{\tilde{A}_t^O}$  (for each  $k_t \in \mathcal{T}$ ),  $\tilde{V}_{\emptyset, \emptyset}^{\rightarrow k_1} : \mathcal{H}^P \rightarrow \mathcal{H}^{\tilde{A}_1^I \alpha_1}$ ,  $\tilde{V}_{\mathcal{K}_{t-1}, k_t}^{\rightarrow k_{t+1}} : \mathcal{H}^{\tilde{A}_t^O \alpha_t} \rightarrow \mathcal{H}^{\tilde{A}_{t+1}^I \alpha_{t+1}}$  (for  $1 \leq t \leq T-1$ ) and  $\tilde{V}_{\mathcal{K}_{T-1}, k_T}^{\rightarrow F} : \mathcal{H}^{\tilde{A}_T^O \alpha_T} \rightarrow \mathcal{H}^{F \alpha_F}$ .

A QC-supermap thus proceeds by applying, at each time-step  $t$ , the coherently controlled input operations

$$\tilde{U}^{[t]} = \sum_{\mathcal{K}_{t-1}, k_t} \tilde{U}_{k_t}^{[t]} \otimes |\mathcal{K}_{t-1}, k_t\rangle^{C_t^{(i)}} \langle \mathcal{K}_{t-1}, k_t |^{C_t^{(i)}}, \quad (\text{E1})$$

while between time-steps it applies the internal operations,

$$\tilde{V}_1 = \sum_{k_1} \tilde{V}_{\emptyset, \emptyset}^{\rightarrow k_1} \otimes |\emptyset, k_1\rangle^{C_1} : \mathcal{H}^P \rightarrow \mathcal{H}^{\tilde{A}_1^I \alpha_1 C_1}, \quad (\text{E2})$$

$$\tilde{V}_{t+1} = \sum_{\substack{\mathcal{K}_{t-1}, \\ k_t, k_{t+1}}} \tilde{V}_{\mathcal{K}_{t-1}, k_t}^{\rightarrow k_{t+1}} \otimes |\mathcal{K}_{t-1} \cup k_t, k_{t+1}\rangle^{C_{t+1}^{(i)}} \langle \mathcal{K}_{t-1}, k_t |^{C_t^{(i)}} : \mathcal{H}^{\tilde{A}_t^O \alpha_t C_t^{(i)}} \rightarrow \mathcal{H}^{\tilde{A}_{t+1}^I \alpha_{t+1} C_{t+1}^{(i)}}, \quad (\text{E3})$$

$$\tilde{V}_{T+1} = \sum_{k_T} \tilde{V}_{\mathcal{T} \setminus \{k_T, k_T\}}^{\rightarrow F} \otimes \langle \mathcal{T} \setminus k_T, k_T |^{C_T^{(i)}} : \mathcal{H}^{\tilde{A}_T^O \alpha_T C_T^{(i)}} \rightarrow \mathcal{H}^{F \alpha_F}, \quad (\text{E4})$$

which are required to be pure isometries.

The process matrix is obtained from the internal operations as

$$W = \text{Tr}_{\alpha_F} |w_{(\mathcal{T}, F)}\rangle \langle w_{(\mathcal{T}, F)}| \in \mathcal{L}(\mathcal{H}^{PA_{\mathcal{T}}^{IO} F}), \quad (\text{E5})$$

with  $|w_{(\mathcal{T}, F)}\rangle = \sum_{(k_1, \dots, k_T)} |w_{(k_1, \dots, k_T, F)}\rangle$  and

$$|w_{(k_1, \dots, k_T, F)}\rangle = |V_{\emptyset, \emptyset}^{\rightarrow k_1}\rangle * |V_{\emptyset, k_1}^{\rightarrow k_2}\rangle * |V_{\{k_1\}, k_2}^{\rightarrow k_3}\rangle * \dots * |V_{\{k_1, \dots, k_{T-2}\}, k_{T-1}}^{\rightarrow k_T}\rangle * |V_{\{k_1, \dots, k_{T-1}\}, k_T}^{\rightarrow F}\rangle \in \mathcal{H}^{PA_{\mathcal{T}}^{IO} F \alpha_F}. \quad (\text{E6})$$

Let us write the set of all process matrices of  $T$ -input QC-supermaps as  $\mathcal{W}^{\text{QC}}$ .

One can readily verify that the action of a QC-supermap  $\mathcal{S}$  on input operations  $(U_1, \dots, U_T)$ , as calculated through the process matrix, indeed coincides with that obtained by applying iteratively the internal operations  $\tilde{V}_t$  and controlled operations  $\tilde{U}^{[t]}$  in the generic input and output spaces. That is,

$$\mathcal{S}(U_1, \dots, U_T) = (U_1 \otimes \dots \otimes U_T) * W \quad (\text{E7})$$

$$= \text{Tr}_{\alpha_F} [\tilde{V}_{T+1} * \tilde{U}^{[T]} * \tilde{V}_T * \dots * \tilde{V}_2 * \tilde{U}^{[1]} * \tilde{V}_1]. \quad (\text{E8})$$

As for the other classes of supermaps we presented, one can obtain a nice characterisation of  $\mathcal{W}^{\text{QC}}$  from the requirement for the internal operations (E2) to be trace-preserving isometries.

**Proposition 3** (From [17]). *A matrix  $W \in \mathcal{L}(\mathcal{H}^{PA_{\mathcal{T}}^{IO} F})$  is the process matrix of a  $T$ -input QC-supermap (i.e.,  $W \in \mathcal{W}^{\text{QC}}$ ) if and only if there exist some positive semidefinite matrices  $W_{(\mathcal{K}_{t-1}, k_t)} \in \mathcal{L}(\mathcal{H}^{PA_{\mathcal{K}_{t-1}}^{IO} A_{k_t}^I})$ , for all strict*

subsets  $\mathcal{K}_{t-1}$  of  $\mathcal{T}$  and all  $k_t \in \mathcal{T} \setminus \mathcal{K}_{t-1}$ , satisfying

$$\begin{aligned} \sum_{k_1 \in \mathcal{T}} \text{Tr}_{A_{k_1}^I} W_{(\emptyset, k_1)} &= \mathbb{1}^P, \\ \forall \emptyset \subsetneq \mathcal{K}_t \subsetneq \mathcal{T}, \quad \sum_{k_{t+1} \in \mathcal{T} \setminus \mathcal{K}_t} \text{Tr}_{A_{k_{t+1}}^I} W_{(\mathcal{K}_t, k_{t+1})} &= \sum_{k_t \in \mathcal{K}_t} W_{(\mathcal{K}_t \setminus k_t, k_t)} \otimes \mathbb{1}^{A_{k_t}^O}, \\ \text{and } \text{Tr}_F W &= \sum_{k_T \in \mathcal{T}} W_{(\mathcal{T} \setminus k_T, k_T)} \otimes \mathbb{1}_{k_T}^O. \end{aligned} \quad (\text{E9})$$

### Appendix F: Proof of Theorem 1

In this appendix, we give a proof of Theorem 1. This theorem states that for any  $T$ -input QC-supermap, one can define a  $T$ -input FO-supermap such that their action on  $T$  copies of any unitary  $U$  is the same.

**Theorem 1.** *For any  $T$ -input QC-supermap  $\mathcal{S}^{\text{QC}}$ , there exists an FO-supermap  $\mathcal{S}^{\text{FO}}$  such that  $\mathcal{S}^{\text{QC}}$  and  $\mathcal{S}^{\text{FO}}$  have the same action whenever applied to  $T$  copies of the same unitary channel. That is, for all unitary channels  $\mathcal{U}$ ,  $\mathcal{S}^{\text{QC}}(\mathcal{U}, \dots, \mathcal{U}) = \mathcal{S}^{\text{FO}}(\mathcal{U}, \dots, \mathcal{U})$ .*

*Proof.* Let us consider a  $T$ -input QC-supermap  $\mathcal{S}^{\text{QC}}$ , as well as  $T$  copies of some unitary  $U$  labelled from 1 to  $T$  as  $(U^{(1)}, \dots, U^{(T)})$ , with  $U^{(t)} : \mathcal{H}^{A_t^I} \rightarrow \mathcal{H}^{A_t^O}$  (for  $1 \leq t \leq T$ ) to distinguish which Hilbert spaces they act on. We emphasise that all the  $\mathcal{H}^{A_t^I}$  and  $\mathcal{H}^{A_t^O}$  are isomorphic, and the  $U^{(t)}$  have formally the same action on their respective spaces. Following Eqs. (E2)–(E4), the QC-supermap  $\mathcal{S}^{\text{QC}}$  can be represented as a generalised quantum circuit whose internal operations are defined on some generic input and output spaces  $\mathcal{H}^{\tilde{A}_t^I}$  and  $\mathcal{H}^{\tilde{A}_t^O}$  (which again are here all isomorphic to the  $\mathcal{H}^{A_{k_t}^I}$  and  $\mathcal{H}^{A_{k_t}^O}$ ) for each time-step  $t$ :

$$\tilde{V}_1 = \sum_{k_1} \tilde{V}_{\emptyset, \emptyset}^{\rightarrow k_1} \otimes |\emptyset, k_1\rangle^{C_1} : \mathcal{H}^P \rightarrow \mathcal{H}^{\tilde{A}_1^I \alpha_1 C_1}, \quad (\text{F1})$$

$$\tilde{V}_{t+1} = \sum_{\substack{\mathcal{K}_{t-1}, \\ k_t, k_{t+1}}} \tilde{V}_{\mathcal{K}_{t-1}, k_t}^{\rightarrow k_{t+1}} \otimes |\mathcal{K}_{t-1} \cup k_t, k_{t+1}\rangle^{C_{t+1}} \langle \mathcal{K}_{t-1}, k_t |^{C_t'} : \mathcal{H}^{\tilde{A}_t^O \alpha_t C_t'} \rightarrow \mathcal{H}^{\tilde{A}_{t+1}^I \alpha_{t+1} C_{t+1}}, \quad (\text{F2})$$

$$\tilde{V}_{T+1} = \sum_{k_T} \tilde{V}_{\mathcal{T} \setminus k_T, k_T}^{\rightarrow F} \otimes \langle \mathcal{T} \setminus k_T, k_T |^{C_T'} : \mathcal{H}^{\tilde{A}_T^O \alpha_T C_T'} \rightarrow \mathcal{H}^{F \alpha_F}. \quad (\text{F3})$$

From these internal operations let us define an FO-supermap  $\mathcal{S}^{\text{FO}}$ , independent of  $U$ , whose action on  $T$  copies of any unitary  $U$  will be the same as that of the QC-supermap  $\mathcal{S}^{\text{Gen}}$ . Recall (see Appendix D) that, to define  $\mathcal{S}^{\text{FO}}$ , it suffices to specify the  $T+1$  quantum channels (or, equivalently, their Choi matrices)  $\mathcal{V}_t$  (for  $1 \leq t \leq T$ ) and  $\mathcal{V}_{T+1}$  which are applied in alternation with the input operations. To this end, let us consider the operations  $V_{\emptyset, \emptyset}^{\rightarrow k_1} : \mathcal{H}^P \rightarrow \mathcal{H}^{A_1^I \alpha_1}$ ,  $V_{\mathcal{K}_{t-1}, k_t}^{\rightarrow k_{t+1}} : \mathcal{H}^{A_t^O \alpha_t} \rightarrow \mathcal{H}^{A_{t+1}^I \alpha_{t+1}}$  and  $V_{\mathcal{T} \setminus k_T, k_T}^{\rightarrow F} : \mathcal{H}^{A_T^O \alpha_T} \rightarrow \mathcal{H}^F$  which have the same action as the corresponding operations in Eqs. (F1)–(F3) but act now on the non-tilded spaces  $\mathcal{H}^{A_t^I} \cong \mathcal{H}^{\tilde{A}_t^I}$  and  $\mathcal{H}^{A_t^O} \cong \mathcal{H}^{\tilde{A}_t^O}$  (for  $1 \leq t \leq T$ ). Note that this is possible precisely because all the input and output spaces are isomorphic. By relabelling the control spaces  $C_t'$  to  $C_t$  (since, in a FO-supermap, the input operations are not controlled and there is thus no need to distinguish the control system before and after it is used), we hence define the isometries

$$V_1 = \sum_{k_1} V_{\emptyset, \emptyset}^{\rightarrow k_1} \otimes |\emptyset, k_1\rangle^{C_1} : \mathcal{H}^P \rightarrow \mathcal{H}^{A_1^I \alpha_1 C_1}, \quad (\text{F4})$$

$$V_{t+1} = \sum_{\substack{\mathcal{K}_{t-1}, \\ k_t, k_{t+1}}} V_{\mathcal{K}_{t-1}, k_t}^{\rightarrow k_{t+1}} \otimes |\mathcal{K}_{t-1} \cup k_t, k_{t+1}\rangle^{C_{t+1}} \langle \mathcal{K}_{t-1}, k_t |^{C_t} : \mathcal{H}^{A_t^O \alpha_t C_t} \rightarrow \mathcal{H}^{A_{t+1}^I \alpha_{t+1} C_{t+1}}, \quad (\text{F5})$$

$$\hat{V}_{T+1} = \sum_{k_T} V_{\mathcal{T} \setminus k_T, k_T}^{\rightarrow F} \otimes \langle \mathcal{T} \setminus k_T, k_T |^{C_T} : \mathcal{H}^{A_T^O \alpha_T C_T} \rightarrow \mathcal{H}^{F \alpha_F}. \quad (\text{F6})$$

For the FO-supermap we then reinterpret the control systems  $\mathcal{H}^{C_t}$  as part of the ancillary spaces, taking  $\mathcal{H}^{\alpha_t} := \mathcal{H}^{\alpha_t C_t}$ , so that the Choi matrices of the channels defining  $\mathcal{S}^{\text{FO}}$  are  $V_t' = |V_t'\rangle\rangle\langle\langle V_t'|$  (for  $1 \leq t \leq T$ ) and  $V_{T+1}' =$

$\text{Tr}_{\alpha_F} |\hat{V}'_{T+1}\rangle\rangle\langle\langle \hat{V}'_{T+1}|$ . The fact that these are indeed valid channels follows from the fact that Eqs. (F1)–(F3) specify valid isometries and the isomorphisms between the generic (tilded) and specific (non-tilded) input and output spaces. The action this  $\mathcal{S}^{\text{FO}}$  on  $T$  copies of  $U$ , according to Eq. (2), is

$$\mathcal{S}^{\text{FO}}(\mathbf{U}^{(1)}, \dots, \mathbf{U}^{(T)}) = \mathbf{V}'_{T+1} * \mathbf{U}^{(T)} * \dots * \mathbf{V}'_2 * \mathbf{U}^{(1)} * \mathbf{V}'_1. \quad (\text{F7})$$

We now show that the action of the QC-supermap  $\mathcal{S}^{\text{QC}}$  on  $T$ -copies of  $U$  is equivalent to that of  $\mathcal{S}^{\text{FO}}$  given by Eq. (F7). Recall (see Appendix E) that, at each time-step  $t$ ,  $\mathcal{S}^{\text{QC}}$  proceeds by applying the coherently controlled operations  $\tilde{U}^{[t]} = \sum_{\mathcal{K}_{t-1}, k_t} \tilde{U}_{k_t}^{[t]} \otimes |\mathcal{K}_{t-1}, k_t\rangle^{C'_t} \langle \mathcal{K}_{t-1}, k_t|^{C_t}$ , where  $\tilde{U}_{k_t}^{[t]} : \mathcal{H}^{\tilde{A}_t^I} \rightarrow \mathcal{H}^{\tilde{A}_t^O}$  (for  $1 \leq k_t \leq T$ ) is an embedding of  $U^{(k_t)}$  into the generic spaces. Since each  $U^{(k_t)}$  has formally the same action, all the  $\tilde{U}_{k_t}^{[t]}$  (for a given  $t$ ) are in fact identically the same operation; let us denote these unitary  $\tilde{U}^{(t)} : \mathcal{H}^{\tilde{A}_t^I} \rightarrow \mathcal{H}^{\tilde{A}_t^O}$ . The coherently controlled operations  $\tilde{U}^{[t]} : \mathcal{H}^{\tilde{A}_t^I C_t} \rightarrow \mathcal{H}^{\tilde{A}_t^O C'_t}$  can thus be written in the factorised form

$$\tilde{U}^{[t]} = \tilde{U}^{(t)} \otimes \sum_{\mathcal{K}_{t-1}, k_t} |\mathcal{K}_{t-1}, k_t\rangle^{C'_t} \langle \mathcal{K}_{t-1}, k_t|^{C_t} \quad (\text{F8})$$

$$= \tilde{U}^{(t)} \otimes \mathbf{1}^{C_t \rightarrow C'_t}. \quad (\text{F9})$$

Then following Eq. (E8), the action of the QC-supermap on the  $T$  copies of  $U$  is

$$\mathcal{S}^{\text{QC}}(\mathbf{U}^{(1)}, \dots, \mathbf{U}^{(T)}) = \text{Tr}_{\alpha_F} [\tilde{\mathbf{V}}_{T+1} * \tilde{\mathbf{U}}^{[T]} * \tilde{\mathbf{V}}_T * \dots * \tilde{\mathbf{V}}_2 * \tilde{\mathbf{U}}^{[1]} * \tilde{\mathbf{V}}_1] \quad (\text{F10})$$

$$= \text{Tr}_{\alpha_F} [\tilde{\mathbf{V}}_{T+1} * (\tilde{\mathbf{U}}^{(T)} * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_t \rightarrow C'_t}) * \tilde{\mathbf{V}}_T * \dots * \tilde{\mathbf{V}}_2 * (\tilde{\mathbf{U}}^{(1)} * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_1 \rightarrow C'_1}) * \tilde{\mathbf{V}}_1] \quad (\text{F11})$$

$$= \text{Tr}_{\alpha_F} [\tilde{\mathbf{V}}_{T+1} * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_t \rightarrow C'_t} * \tilde{\mathbf{U}}^{(T)} * \tilde{\mathbf{V}}_T * \dots * \tilde{\mathbf{V}}_2 * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_1 \rightarrow C'_1} * \tilde{\mathbf{U}}^{(1)} * \tilde{\mathbf{V}}_1] \quad (\text{F12})$$

$$= \text{Tr}_{\alpha_F} [\tilde{\mathbf{V}}_{T+1} * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_t \rightarrow C'_t}] * \tilde{\mathbf{U}}^{(T)} * \tilde{\mathbf{V}}_T * \dots * \tilde{\mathbf{V}}_2 * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_1 \rightarrow C'_1} * \tilde{\mathbf{U}}^{(1)} * \tilde{\mathbf{V}}_1, \quad (\text{F13})$$

where the second line follows from Eq. (F9), the third from the commutation of the link product, and the fourth from the fact that only  $\tilde{\mathbf{V}}_{T+1}$  is defined on  $\mathcal{H}^{\alpha_F}$ . Now by defining  $\tilde{\mathbf{V}}'_{T+1} = \text{Tr}_{\alpha_F} [\tilde{\mathbf{V}}_{T+1} * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_t \rightarrow C'_t}]$ ,  $\tilde{\mathbf{V}}'_{t+1} = \tilde{\mathbf{V}}_{t+1} * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_t \rightarrow C'_t}$  (for  $1 \leq t \leq T-1$ ) and  $\tilde{\mathbf{V}}'_1 = \tilde{\mathbf{V}}_1$ , we have

$$\mathcal{S}^{\text{QC}}(\mathbf{U}^{(1)}, \dots, \mathbf{U}^{(T)}) = \tilde{\mathbf{V}}'_{T+1} * \tilde{\mathbf{U}}^{(T)} * \dots * \tilde{\mathbf{V}}'_2 * \tilde{\mathbf{U}}^{(1)} * \tilde{\mathbf{V}}'_1. \quad (\text{F14})$$

For  $1 < t \leq T$ , the link product  $\tilde{\mathbf{V}}_{t+1} * |\mathbf{1}\rangle\rangle\langle\langle \mathbf{1}|^{C_t \rightarrow C'_t}$  is the composition of  $\tilde{\mathbf{V}}_{t+1} : \mathcal{H}^{\tilde{A}_{t+1}^O \alpha_t C'_t} \rightarrow \mathcal{H}^{\tilde{A}_{t+1}^I \alpha_{t+1} C_{t+1}}$  and an identity channel between  $\mathcal{H}^{C_t}$  and  $\mathcal{H}^{C'_t}$ , which effectively relabels  $\mathcal{H}^{C'_t}$  to  $\mathcal{H}^{C_t}$  in  $\tilde{\mathbf{V}}_{t+1}$ . Finally, because the spaces  $\mathcal{H}^{\tilde{A}_t^I}$  and  $\mathcal{H}^{\tilde{A}_t^O}$  are isomorphic to  $\mathcal{H}^{A_t^I}$  and  $\mathcal{H}^{A_t^O}$ , we have that

$$\mathcal{S}^{\text{QC}}(\mathbf{U}^{(1)}, \dots, \mathbf{U}^{(T)}) = \mathbf{V}'_{T+1} * \mathbf{U}^{(T)} * \dots * \mathbf{V}'_2 * \mathbf{U}^{(1)} * \mathbf{V}'_1 \quad (\text{F15})$$

$$= \mathcal{S}^{\text{FO}}(\mathbf{U}^{(1)}, \dots, \mathbf{U}^{(T)}), \quad (\text{F16})$$

as desired.  $\square$

## Appendix G: Proof of Theorem 2

In this appendix, we prove a generalisation of the polynomial bound from FO-supermaps (or quantum circuits) to general supermaps.

**Theorem 2.** *For any Boolean function  $f$ , we have  $\deg(f)/2 \leq Q_E^{\text{Gen}}(f)$  and  $\widetilde{\deg}(f)/2 \leq Q_2^{\text{Gen}}(f)$ .*

The proof is similar to that of the original statement of the polynomial bound for FO-supermaps [28]. Let us first prove the following lemma.

**Lemma 4.** *For  $x \in \{0, 1\}^n$ ,  $|O_x^{\otimes T}\rangle\rangle$  is a vector whose coefficients are multivariate polynomials in  $x$  of degree at most  $T$ .*

*Proof.* We proceed by induction. If  $T = 1$  we have

$$|O_x\rangle\rangle = \sum_i |i\rangle \otimes O_x |i\rangle = \sum_i (-1)^{x_i} |i\rangle \otimes |i\rangle = \sum_i (1 - 2x_i) |i\rangle \otimes |i\rangle, \quad (\text{G1})$$

which is indeed a multivariate polynomial of degree 1. Let us note that, for any  $T \geq 1$ ,  $|O_x^{\otimes T}\rangle\rangle$  is of the form  $|O_x^{\otimes T}\rangle\rangle = \sum_z \alpha_z(x) |z\rangle \otimes |z\rangle$ . Now let us suppose, for some  $T$ , that the coefficients  $\alpha_z(x)$  are multivariate polynomials of degree at most  $T$ . Then

$$|O_x^{\otimes(T+1)}\rangle\rangle = |O_x^{\otimes T}\rangle\rangle \otimes |O_x\rangle\rangle \quad (\text{G2})$$

$$= \sum_z \alpha_z(x) |z\rangle \otimes |z\rangle \otimes \sum_i (1 - 2x_i) |i\rangle \otimes |i\rangle \quad (\text{G3})$$

$$= \sum_{z,i} (1 - 2x_i) \alpha_z(x) |z\rangle \otimes |z\rangle \otimes |i\rangle \otimes |i\rangle. \quad (\text{G4})$$

But  $(1 - 2x_i)\alpha_z(x)$  is then a multivariate polynomial of degree at most  $T + 1$ , which concludes the proof of the lemma.  $\square$

The proof of the theorem is now straightforward. Let  $f$  be a Boolean function on  $n$  bits and  $\mathcal{S}$  a supermap with trivial input space and a qubit output space characterised by a process matrix  $W$ . Let us define, for  $x \in \{0, 1\}^n$ ,

$$g(x) = \text{Tr}[(O_x^{\otimes T} * W) \cdot \Pi_1], \quad (\text{G5})$$

where  $\Pi_1 = |1\rangle\langle 1|$ . The function  $g$  corresponds to the probability of obtaining the outcome 1 when measuring the qubit  $S(O_x^{(1)}, \dots, O_x^{(T)})$  in the computational basis (cf. Eq. (3)). Now, it follows from Lemma 4 that  $O_x^{\otimes T} = |O_x^{\otimes T}\rangle\rangle\langle\langle O_x^{\otimes T}|$  is a matrix whose coefficient are multivariate polynomials in  $x$  of degree at most  $2T$ , and, since the trace and link product are linear,  $g(x)$  is also a multivariate polynomial in  $x$  of degree at most  $2T$ . If  $\mathcal{S}$  computes  $f$  then  $g(x) = f(x)$  for all  $x$ , so that  $g$  represents  $f$ , and hence  $2Q_2^{\text{Gen}}(f) \geq \deg(f)$ . Similarly, in the bounded error case, if  $\mathcal{S}$  computes  $f$  with bounded error  $\varepsilon = 1/3$ , then  $|g(x) - f(x)| \leq 1/3$  for all  $x$  and  $g$  approximates  $f$  with bounded error  $\varepsilon = 1/3$  also, from which we likewise obtain  $2Q_2^{\text{Gen}}(f) \geq \deg(f)$ .

## Appendix H: Dual form of the SDP

In this appendix, we derive the dual form of the primal SDP (10) for the minimum error  $\varepsilon_T^{\mathcal{C}}(f)$  with which  $f$  can be computed by a  $T$  query supermap in the class  $\mathcal{C}$ . This dual SDP will be used in Appendix I to convert the numerical solutions of the SDP (10) into analytic proofs that  $\varepsilon_T^{\mathcal{C}}(f)$  lies within a given interval. We obtain the dual form using the Lagrangian method and some techniques previously used in Ref. [33] for a slightly different SDP.

First, for any class  $\mathcal{C} \in \{\text{FO}, \text{QC}, \text{Gen}\}$ , by identifying  $\mathcal{L}(H^{PA_T^{IOF}})$  with its dual space, one can define the dual affine space of  $W^{\mathcal{C}} \subseteq \mathcal{L}(H^{PA_T^{IOF}})$  as

$$\overline{W}^{\mathcal{C}} = \{\overline{W} \in \mathcal{L}(H^{PA_T^{IOF}}) : \text{Tr}[\overline{W} \cdot W] = 1 \quad \forall W \in W^{\mathcal{C}}\}. \quad (\text{H1})$$

For finite dimensional spaces (as is the case here), because  $W^{\mathcal{C}}$  is an affine set we have  $\overline{W}^{\mathcal{C}} = W^{\mathcal{C}}$ , and moreover the characterisation of Eq. (H1) can be written using a basis  $\overline{W}_B^{\mathcal{C}} = \{\overline{W}_k\}_k$  as

$$W^{\mathcal{C}} = \{W \in \mathcal{L}(H^{PA_T^{IOF}}) : \text{Tr}[W \cdot \overline{W}_k] = 1 \quad \forall \overline{W}_k \in \overline{W}_B^{\mathcal{C}}\}. \quad (\text{H2})$$

Using this characterisation of  $W^{\mathcal{C}}$  and writing the primal (10) in a different but equivalent form (see [39], p. 264) one obtains the following canonical form of the primal SDP,

$$\begin{aligned} \min_{\varepsilon, W^{[0]}, W^{[1]}} & \quad - (1 - \varepsilon), \\ \text{s.t.} & \quad \forall x \in F^{[0]}, \quad 1 - \varepsilon - \text{Tr}[W^{[0]} O_x^{\otimes T}] \leq 0, \\ & \quad \forall x \in F^{[1]}, \quad 1 - \varepsilon - \text{Tr}[W^{[1]} O_x^{\otimes T}] \leq 0, \\ & \quad -W^{[0]} \leq 0, \quad -W^{[1]} \leq 0, \quad -\varepsilon \leq 0, \\ & \quad \text{Tr}[(W^{[0]} + W^{[1]}) \overline{W}_k] = 1, \quad \forall \overline{W}_k \in \overline{W}_B^{\mathcal{C}}. \end{aligned} \quad (\text{H3})$$

To write the Lagrangian of (H3) we introduce, for  $i = 0, 1$  and for all  $x \in F^{[i]}$ , the scalar dual variables  $\lambda_x^{[i]} \geq 0$ , and for each basis element  $\overline{W}_k \in \overline{W}_B^{\mathcal{C}}$ , the scalar dual variable  $\mu_k \geq 0$ . We also introduce, as slack variables, the scalar

$\delta \geq 0$  and two real matrices  $\Gamma^{[i]} \geq 0$ . Writing  $\boldsymbol{\lambda} := \{\lambda_x^{[i]}\}_{i=0,1;x \in F^{[i]}}$ ,  $\boldsymbol{\Gamma} := \{\Gamma^{[i]}\}_{i=0,1}$  and  $\boldsymbol{\mu} := \{\mu_k\}_k$ , the Lagrangian is then a function of the primal, dual, and slack variables given as

$$\begin{aligned} \mathcal{L}(\varepsilon, W^{[0]}, W^{[1]}, \delta, \boldsymbol{\lambda}, \boldsymbol{\Gamma}, \boldsymbol{\mu}) &= -(1 - \varepsilon) - \delta\varepsilon - \sum_{i=0}^1 \text{Tr} \left[ W^{[i]} \Gamma^{[i]} \right] + \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} \left( 1 - \varepsilon - \text{Tr} \left[ W^{[i]} \mathbf{O}_x^{\otimes T} \right] \right) + \sum_k \mu_k \left( \text{Tr} \left[ (W^{[0]} + W^{[1]}) \overline{W}_k \right] - 1 \right) \\ &= -1 + \varepsilon \left( 1 - \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} - \delta \right) + \sum_{i=0}^1 \text{Tr} \left[ W^{[i]} \left( -\Gamma^{[i]} - \sum_{x \in F^{[i]}} \lambda_x^{[i]} \mathbf{O}_x^{\otimes T} + \sum_k \mu_k \overline{W}_k \right) \right] + \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} - \sum_k \mu_k. \end{aligned} \quad (\text{H4})$$

Because any optimal solution  $(\varepsilon^*, W^{[0]*}, W^{[1]*})$  of the primal SDP necessarily satisfies the constraints of (H3), for any positive  $(\delta, \boldsymbol{\lambda}, \boldsymbol{\Gamma}, \boldsymbol{\mu})$  we have  $\mathcal{L}(\varepsilon^*, W^{[0]*}, W^{[1]*}, \delta, \boldsymbol{\lambda}, \boldsymbol{\Gamma}, \boldsymbol{\mu}) \leq -(1 - \varepsilon^*)$ . Therefore, by considering the function obtained when minimising over all possible values of  $(\varepsilon, W^{[0]}, W^{[1]})$  (even those not corresponding to feasible solutions of (H3)), one obtains a lower bound on the objective function  $1 - \varepsilon^*$  as

$$g(\delta, \boldsymbol{\lambda}, \boldsymbol{\Gamma}, \boldsymbol{\mu}) = \min_{\varepsilon, W^{[0]}, W^{[1]}} \mathcal{L}(\varepsilon, W^{[0]}, W^{[1]}, \delta, \boldsymbol{\lambda}, \boldsymbol{\Gamma}, \boldsymbol{\mu}) \leq 1 - \varepsilon^*. \quad (\text{H5})$$

To obtain non-trivial lower bounds, i.e., finite values of  $g$ , certain conditions must be satisfied, as  $g$  can be rewritten

$$g(\delta, \boldsymbol{\lambda}, \boldsymbol{\Gamma}, \boldsymbol{\mu}) = \begin{cases} \sum_i \sum_{x \in F^{[i]}} \lambda_x^{[i]} - 1 - \sum_k \mu_k & \text{if } \begin{cases} 1 - \sum_i \sum_{x \in F^{[i]}} \lambda_x^{[i]} - \delta = 0, & \text{and} \\ -\Gamma^{[i]} - \sum_{x \in F^{[i]}} \lambda_x^{[i]} \mathbf{O}_x^{\otimes T} + \sum_k \mu_k \overline{W}_k = 0, & i \in \{0, 1\}, \end{cases} \\ -\infty & \text{otherwise.} \end{cases} \quad (\text{H6})$$

Then, the solution to the primal SDP  $\varepsilon_T^C(f)$  can be alternatively obtained by maximising this lower bound, which can be cast as the optimisation problem

$$\begin{aligned} \max_{\delta, \boldsymbol{\lambda}, \boldsymbol{\Gamma}, \boldsymbol{\mu}} & \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} - 1 - \sum_k \mu_k, \\ \text{s.t.} & \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} + \delta = 1, \\ & \Gamma^{[i]} + \sum_{x \in F^{[i]}} \lambda_x^{[i]} \mathbf{O}_x^{\otimes T} = \sum_k \mu_k \overline{W}_k, \quad i \in \{0, 1\}, \\ & \boldsymbol{\lambda} \geq 0, \boldsymbol{\Gamma} \geq 0, \boldsymbol{\mu} \geq 0, \delta \geq 0, \end{aligned} \quad (\text{H7})$$

where  $\boldsymbol{\lambda} \geq 0$  means that  $\lambda_x^{[i]} \geq 0$  for all  $i = 0, 1$  and  $x \in F^{[i]}$ , similarly for  $\boldsymbol{\Gamma} \geq 0$  and  $\boldsymbol{\mu} \geq 0$ . It can be simplified through the removal of the slack variables  $\boldsymbol{\Gamma}$  and  $\delta$  to obtain

$$\begin{aligned} \min_{\boldsymbol{\lambda}, \boldsymbol{\mu}} & 1 + \sum_k \mu_k - \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]}, \\ \text{s.t.} & \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} \leq 1, \\ & \sum_{x \in F^{[i]}} \lambda_x^{[i]} \mathbf{O}_x^{\otimes T} \leq \sum_k \mu_k \overline{W}_k, \quad i \in \{0, 1\}, \\ & \boldsymbol{\lambda} \geq 0, \boldsymbol{\mu} \geq 0. \end{aligned} \quad (\text{H8})$$

This SDP can be further simplified by defining  $\nu := \sum_k \mu_k$  and  $\overline{W} := \frac{1}{\nu} \sum_k \mu_k \overline{W}_k$ , where we note that  $\overline{W} \in \overline{\mathcal{W}}^C$  since

$\overline{\mathcal{W}}_B^{\mathcal{C}} = \{\overline{W}_k\}_k$  is a basis of this space. One then obtains

$$\begin{aligned}
& \min_{\lambda, \nu, \overline{W}} 1 + \nu - \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]}, \\
& \text{s.t.} \quad \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} \leq 1, \\
& \quad \sum_{x \in F^{[i]}} \lambda_x^{[i]} \mathbf{O}_x^{\otimes T} \leq \nu \overline{W}, \quad i \in \{0, 1\}, \\
& \quad \lambda \geq 0, \quad \nu \geq 0, \\
& \quad \overline{W} \in \overline{\mathcal{W}}^{\mathcal{C}}.
\end{aligned} \tag{H9}$$

The above optimisation problem is not yet an SDP due to the nonlinear term  $\nu \overline{W}$ . However, one can absorb  $\nu$  into the unnormalised process  $\overline{W}_* = \nu \overline{W}$ , which then satisfies  $\frac{1}{d} \text{Tr}(\overline{W}_*) = \nu$ , where  $d = d^P \prod_{k=1}^T d_k^O$  (with  $d^P = \dim(\mathcal{H}^P)$  and  $d_k^O = \dim(\mathcal{H}^{A_k^O})$ ) corresponds to the trace of the normalised processes (cf. Appendix C). Then, writing  $\overline{W}_*^{\mathcal{C}}$  the dual affine space of  $W_*^{\mathcal{C}}$  (the space of unnormalised processes of class  $\mathcal{C}$ , see Ref. [33] for characterisations of  $\overline{W}_*^{\text{FO}}$  and  $\overline{W}_*^{\text{Gen}}$  in the bipartite case), one obtains the SDP

$$\begin{aligned}
& \min_{\lambda, \overline{W}_*} 1 + \frac{1}{d} \text{Tr}(\overline{W}_*) - \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]}, \\
& \text{s.t.} \quad \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} \leq 1, \\
& \quad \sum_{x \in F^{[i]}} \lambda_x^{[i]} \mathbf{O}_x^{\otimes T} \leq \overline{W}_*, \quad i \in \{0, 1\}, \\
& \quad \lambda \geq 0, \\
& \quad \overline{W} \in \overline{\mathcal{W}}_*^{\mathcal{C}},
\end{aligned} \tag{H10}$$

which is the dual of (H3). This dual SDP minimises an objective function whose optimal value is  $1 - \varepsilon_T^{\mathcal{C}}(f)$ , and so for any solution of (H10) we have  $\sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_x^{[i]} - \frac{1}{d} \text{Tr}(\overline{W}_*) \leq \varepsilon_T^{\mathcal{C}}(f)$ . That is, any feasible solution to (H10) provides a lower bound on  $\varepsilon_T^{\mathcal{C}}(f)$ , while any feasible solution to the primal SDP (10) (or, equivalently, (H3)) provides an upper bound on  $\varepsilon_T^{\mathcal{C}}(f)$ .

### Appendix I: Mathematical proofs from numerical results

In this appendix, we describe two algorithms to extract strictly feasible solutions to the primal SDP (10) and its dual (H10) from numerical solutions to these SDPs. This will allow us to extract analytical bounds on  $\varepsilon_T^{\mathcal{C}}(f)$  and provide a rigorous mathematical proof of Theorem 3.

The nature of numerical SDP solvers means that the solutions they provide only satisfy the constraints of the SDP up to some numerical precision. Since, strictly speaking, the constraints are not satisfied, we cannot directly conclude anything about the precision of the numerical result of the optimisation problem. In Ref. [33], the authors propose an algorithm that takes a numerical (floating point), approximate solution of an SDP and returns an exact rational solution that is not specified with floating point numbers and rigorously satisfies the constraints of the SDP. While this alternative solution is no longer guaranteed to be optimal, it gives an upper or lower bound (depending on whether one maximises or minimises the objective function). By applying this approach to both the primal and dual forms of an SDP, one can obtain both lower and upper bounds on the true optimal solutions; i.e., an interval within which that solution is certified to lie. Here we adapt the algorithm described in Ref. [33] to our specific problem.

We start with an algorithm to extract an exact solution from the dual SDP (H10) specified in Appendix H. For a Boolean function  $f$ , this will provide a lower bound on  $\varepsilon_T^{\mathcal{C}}(f)$ , i.e., the minimal error with which one can compute  $f$  using a fixed number  $T$  of queries. A solution of the SDP (H10) consists of a tuple  $(\lambda^{[0]}, \lambda^{[1]}, S)$ , where for  $i = 0, 1$ ,  $\lambda^{[i]} = \{\lambda_x^{[i]}\}_{x \in F^{[i]}}$  and  $S$  is a matrix in the dual affine space  $\overline{\mathcal{W}}_*^{\mathcal{C}}$  of the space of unnormalised processes

$\mathcal{W}_*^C$  (see Appendix H and Ref. [33]). The output of the following algorithm will be a tuple  $(\lambda_{\text{final}}^{[0]}, \lambda_{\text{final}}^{[1]}, S_{\text{final}})$  with  $\lambda_{\text{final}}^{[i]} = \{\lambda_{x,\text{final}}^{[i]}\}_{x \in F^{[i]}}$ , which rigorously satisfies the constraints of the SDP (H10). Note that the output of the algorithm depends on the precision to which one rationalises the variables, which is a freely chosen parameter of the algorithm.

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**Algorithm 1**


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1. Define each  $\lambda_{x,\text{frac}}^{[i]}$  as a rationalisation of  $\lambda_x^{[i]}$ , stored in an exact representation.
  2. Define  $\delta = 1 - \sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_{x,\text{frac}}^{[i]}$  and let  $\lambda_{x,\text{final}}^{[i]} = \begin{cases} \lambda_{x,\text{frac}}^{[i]} + \delta/2^n & \text{if } \delta < 0, \\ \lambda_{x,\text{frac}}^{[i]} & \text{otherwise.} \end{cases}$
  3. Define  $S_{\text{frac}}$  as a rationalisation of  $S$ .
  4. Define  $S_{\text{Herm}} = \frac{1}{2}(S_{\text{frac}} + S_{\text{frac}}^\dagger)$ .
  5. Define  $S_{\text{valid}} = P_{\overline{\mathcal{W}}_*^C}(S_{\text{Herm}})$ , where  $P_{\overline{\mathcal{W}}_*^C}$  is the projection onto  $\overline{\mathcal{W}}_*^C$ .
  6. Find the smallest  $\mu$  such that  $S_{\text{pos}} = D_\mu(S_{\text{valid}})$  is positive semidefinite, where  $D_\mu(S) = \mu S + (1 - \mu)\mathbf{1}$ .
  7. For  $i = 0, 1$ , find the smallest  $\eta_i$ 's such that  $F_{\eta_i}(S_{\text{pos}})$  is positive semidefinite, where  $F_{\eta_i}(S) = \eta_i S + (1 - \eta_i)\mathbf{O}^{[i]}$  with  $\mathbf{O}^{[i]} = \sum_{x \in F^{[i]}} \lambda_{x,\text{final}}^{[i]} \mathbf{O}_x^{\otimes T}$ , and define  $S_{\text{final}} = S + \eta_0 \mathbf{O}^{[0]} + \eta_1 \mathbf{O}^{[1]}$ .
- 

The first and second steps of the algorithm ensure that the final lambdas  $\lambda_{x,\text{final}}^{[i]}$  are rational (stored, for example, as fractions that can be manipulated exactly) and satisfy the constraints  $\sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_{x,\text{final}}^{[i]} \leq 1$ . Steps 3 to 6 ensure that the matrix  $S_{\text{final}}$  is rational, Hermitian, belongs to the subspace  $\overline{\mathcal{W}}_*^C$ , and is positive semidefinite. Finally the last step ensures that for  $i \in \{0, 1\}$ ,  $S_{\text{final}} - \mathbf{O}^{[i]}$  is positive semidefinite. Note that while the minimisation in Step 6 can be performed analytically, the minimisation in Step 7 typically needs to be performed numerically and thus approximately. This is not an issue, as one simply needs to find the smallest  $\eta_i$  up to some desired precision that make the respective matrices  $F_{\eta_i}(S)$  strictly positive semidefinite. Note also that for Steps 6 and 7, the matrices  $S_{\text{pos}}$  and  $S_{\text{final}}$  stay in the space  $\overline{\mathcal{W}}_*^C$ , which follows from the linearity of  $P_{\overline{\mathcal{W}}_*^C}$  and because, for any class  $\mathcal{C} \in \{\text{FO}, \text{Gen}\}$ , the identity  $\mathbf{1}$  and the  $\mathbf{O}^{[i]}$ 's are elements of  $\overline{\mathcal{W}}_*^C$  [33]. The output of the algorithm  $S_{\text{final}}$  is hence guaranteed to satisfy all the constraints of the dual SDP (H10). Furthermore, as stated in Appendix H, the dual SDP (H10) minimises an objective function whose optimal is  $1 - \varepsilon_T^C(f)$ , meaning that the output of Algorithm (1) will provide a lower bound on  $\varepsilon_T^C(f)$ , i.e.,

$$\sum_{i=0}^1 \sum_{x \in F^{[i]}} \lambda_{x,\text{final}}^{[i]} - \frac{1}{d} \text{Tr}[S_{\text{final}}] \leq \varepsilon_T^C(f). \quad (\text{I1})$$

The corresponding upper bound is obtained from a similar algorithm whose input is a solution of the primal SDP (10), which is a superinstrument of two elements  $\{W^{[i]}\}_{i=0,1}$  such that  $W^{[0]} + W^{[1]} \in \mathcal{W}^C$ . Then, the output of the following algorithm will be a superinstrument  $\{W_{\text{final}}^{[i]}\}_{i=0,1}$  that rigorously satisfies all the constraints of the primal SDP (10).

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**Algorithm 2**


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1. Define  $W_{\text{frac}}^{[0]}$  and  $W_{\text{frac}}^{[1]}$  as rationalisations of  $W^{[0]}$  and  $W^{[1]}$ , stored in an exact representation.
  2. For  $i = 0, 1$ , define  $W_{\text{Herm}}^{[i]} = \frac{1}{2}(W_{\text{frac}}^{[i]} + W_{\text{frac}}^{[i]\dagger})$ .
  3. Define  $W_{\text{proj}} = P_{\mathcal{W}^C}(W_{\text{Herm}}^{[0]} + W_{\text{Herm}}^{[1]})$ , where  $P_{\mathcal{W}^C}$  is the projection onto  $\mathcal{W}^C$ .
  4. Define  $W_{\text{corr}} = W_{\text{proj}} - W_{\text{Herm}}^{[0]} - W_{\text{Herm}}^{[1]}$ .
  5. Define for  $i = 0, 1$ ,  $W_{\text{valid}}^{[i]} = W_{\text{Herm}}^{[i]} - \frac{1}{2}W_{\text{corr}}$ .
  6. Find the smallest  $\mu$  such that for  $i = 0, 1$ ,  $W_{\text{pos}}^{[i]} = D_\mu(W_{\text{valid}}^{[i]})$  is positive semidefinite, where  $D_\mu(W) = \mu W + (1 - \mu)\mathbf{1}$ .
  7. Re-normalise, for  $i = 0, 1$ ,  $W_{\text{final}}^{[i]} = \frac{d^P \prod_{k=1}^T d_k^O}{\text{Tr}[W_{\text{pos}}^{[0]} + W_{\text{pos}}^{[1]}]} W_{\text{pos}}^{[i]}$ .
-



The first and second steps of the algorithm make sure that the superinstrument elements  $W_{\text{final}}^{[i]}$  are rational and Hermitian. Steps 3 to 5 ensure that their sum lies in the subspace  $\mathcal{W}^{\mathcal{C}}$ . Step 6 ensures that they are positive semidefinite, while Step 7 ensures that they are properly normalised. The output of the algorithm  $\{W_{\text{final}}^{[i]}\}_{i \in \{0,1\}}$  is then a superinstrument that satisfies all the constraints of the primal SDP (10). Because this SDP is a maximisation of the objective function  $1 - \varepsilon$  with optimal value  $1 - \varepsilon_T^{\mathcal{C}}(f)$ , the output of Algorithm (2) provides an upper bound on  $\varepsilon_T^{\mathcal{C}}(f)$ , i.e.,

$$\varepsilon_T^{\mathcal{C}}(f) \leq \min_{i \in \{0,1\}} \min_{x \in F^{[i]}} \text{Tr} \left[ W_{\text{final}}^{[i]} \mathbf{O}_x^{\otimes T} \right]. \quad (\text{I2})$$

### Appendix J: Numerical results

In Table I we summarise the numerical results obtained by solving the semidefinite program (10) for  $n = 4$  and  $T = 2$ . The ID of a function  $f$  corresponds to the integer obtained from its binary truth table,  $\varepsilon_2^{\text{FO}}(f)$  is the numerical value corresponding to the minimum probability of error for which it can be computed using two queries with FO-supermaps and  $\varepsilon_2^{\text{Gen}}(f)$  with general supermaps. Table I lists the 222 NPN representatives of Boolean functions on 4 input bits (note that it also contains functions that are constants or whose output depends on less than 4 input bits). For  $\varepsilon_2^{\text{FO}}(f)$ , our results coincide with those obtained in Ref. [30], but we observe that for 179 representatives,  $\varepsilon_2^{\text{Gen}}(f) < \varepsilon_2^{\text{FO}}(f)$ , with a gap of 0.00947 (close to 1%) for functions of Id: 5783, 5865 and 6630. To solve the SDPs we use the Matlab toolbox `Yalmip` [40] with the solver `SCS` [41]; our code is freely accessible on Github.<sup>3</sup>

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<sup>3</sup> [https://github.com/pierrepocreau/QuantumQueryComplexity\\_IC0](https://github.com/pierrepocreau/QuantumQueryComplexity_IC0)

TABLE I. Numerical results for 2 queries and all Boolean functions of 4 input bits

ID	$\varepsilon_2^{FO}$	$\varepsilon_2^{Gen}$	Gap	ID	$\varepsilon_2^{FO}$	$\varepsilon_2^{Gen}$	Gap	ID	$\varepsilon_2^{FO}$	$\varepsilon_2^{Gen}$	Gap	ID	$\varepsilon_2^{FO}$	$\varepsilon_2^{Gen}$	Gap
0	0.00000	0.00000	0.00000	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮
1	0.03846	0.03846	0.00000	409	0.02383	0.02000	0.00383	982	0.04884	0.04358	0.00526	1972	0.03147	0.02782	0.00364
3	0.02000	0.02000	0.00000	410	0.03637	0.03595	0.00041	983	0.03499	0.02990	0.00510	1973	0.03434	0.03279	0.00155
6	0.06897	0.06897	0.00000	411	0.03079	0.03061	0.00018	984	0.03436	0.02900	0.00536	1974	0.03836	0.03714	0.00122
7	0.04620	0.04620	0.00000	414	0.04510	0.04483	0.00027	985	0.02652	0.02587	0.00065	1980	0.03399	0.03175	0.00224
15	0.00000	0.00000	0.00000	415	0.03527	0.03294	0.00233	985	0.02652	0.02587	0.00065	2016	0.00000	0.00000	0.00000
22	0.09380	0.09380	0.00000	424	0.07409	0.07409	0.00000	987	0.03499	0.02990	0.00510	2017	0.02807	0.02529	0.00279
23	0.07409	0.07409	0.00000	425	0.04136	0.04126	0.00010	988	0.02807	0.02529	0.00279	2018	0.02351	0.02304	0.00047
24	0.06897	0.06897	0.00000	426	0.03043	0.02964	0.00080	989	0.01396	0.01122	0.00274	2019	0.01396	0.01122	0.00274
25	0.03957	0.03957	0.00000	427	0.02000	0.02000	0.00000	990	0.03434	0.03279	0.00155	2022	0.03499	0.02990	0.00510
27	0.03475	0.03475	0.00000	428	0.04136	0.04126	0.00010	1020	0.00000	0.00000	0.00000	2025	0.03399	0.03175	0.00224
30	0.04411	0.04411	0.00000	429	0.03079	0.03061	0.00018	1632	0.00000	0.00000	0.00000	2032	0.02858	0.02858	0.00000
31	0.03043	0.02964	0.00080	430	0.03436	0.02900	0.00536	1633	0.03846	0.03846	0.00000	2033	0.02000	0.02000	0.00000
60	0.00000	0.00000	0.00000	431	0.02351	0.02304	0.00047	1634	0.02383	0.02000	0.00383	2034	0.02000	0.02000	0.00000
61	0.02383	0.02000	0.00383	444	0.02000	0.02000	0.00000	1635	0.02000	0.02000	0.00000	2040	0.05410	0.05410	0.00000
63	0.00000	0.00000	0.00000	445	0.03499	0.03066	0.00433	1638	0.05263	0.05263	0.00000	4080	0.00000	0.00000	0.00000
105	0.10000	0.10000	0.00000	446	0.03147	0.02782	0.00364	1639	0.03499	0.03066	0.00433	5736	0.00000	0.00000	0.00000
107	0.05936	0.05919	0.00016	447	0.02000	0.02000	0.00000	1641	0.06387	0.06387	0.00000	5737	0.03846	0.03846	0.00000
111	0.03254	0.02853	0.00400	448	0.10061	0.10061	0.00000	1643	0.03449	0.03288	0.00162	5738	0.02521	0.02268	0.00253
126	0.05263	0.05263	0.00000	488	0.05985	0.05834	0.00151	1647	0.00000	0.00000	0.00000	5739	0.02000	0.02000	0.00000
127	0.02858	0.02858	0.00000	489	0.05475	0.05475	0.00000	1650	0.03079	0.03061	0.00018	5742	0.05258	0.05063	0.00194
255	0.00000	0.00000	0.00000	490	0.03527	0.03294	0.00233	1651	0.02652	0.02587	0.00065	5758	0.07790	0.07790	0.00000
278	0.11611	0.11611	0.00000	491	0.02807	0.02529	0.00279	1654	0.03499	0.03066	0.00433	5761	0.14045	0.14045	0.00000
279	0.10061	0.10061	0.00000	495	0.02000	0.02000	0.00000	1656	0.04408	0.04051	0.00357	5763	0.09363	0.09363	0.00000
280	0.09380	0.09380	0.00000	510	0.05410	0.05410	0.00000	1657	0.03568	0.02975	0.00593	5766	0.06387	0.06387	0.00000
281	0.04411	0.04411	0.00000	828	0.00000	0.00000	0.00000	1658	0.03430	0.03065	0.00366	5767	0.06735	0.06296	0.00440
282	0.06387	0.06387	0.00000	829	0.02521	0.02268	0.00253	1659	0.03836	0.03714	0.00122	5769	0.09363	0.09363	0.00000
283	0.04136	0.04126	0.00010	831	0.00000	0.00000	0.00000	1662	0.04641	0.04247	0.00394	5771	0.05363	0.05341	0.00022
286	0.06842	0.06842	0.00000	854	0.04508	0.04399	0.00110	1680	0.10000	0.10000	0.00000	5774	0.03449	0.03288	0.00162
287	0.05475	0.05475	0.00000	855	0.03109	0.02707	0.00402	1681	0.08382	0.08382	0.00000	5782	0.03846	0.03846	0.00000
300	0.06387	0.06387	0.00000	856	0.03637	0.03595	0.00041	1683	0.05375	0.05059	0.00316	<b>5783</b>	<b>0.04647</b>	<b>0.03700</b>	<b>0.00947</b>
301	0.03637	0.03595	0.00041	857	0.03880	0.03880	0.00000	1686	0.06387	0.06387	0.00000	5784	0.05375	0.05059	0.00316
303	0.03436	0.02900	0.00536	858	0.02000	0.02000	0.00000	1687	0.03568	0.02975	0.00593	5785	0.06735	0.06296	0.00440
316	0.03846	0.03846	0.00000	859	0.02652	0.02587	0.00065	1695	0.00000	0.00000	0.00000	5786	0.03568	0.02975	0.00593
317	0.02000	0.02000	0.00000	862	0.03430	0.03065	0.00366	1712	0.05936	0.05919	0.00016	5787	0.04518	0.04286	0.00232
318	0.04408	0.04051	0.00357	863	0.01396	0.01122	0.00274	1713	0.04510	0.04483	0.00027	5790	0.02000	0.02000	0.00000
319	0.02807	0.02529	0.00279	872	0.06842	0.06842	0.00000	1714	0.05985	0.05834	0.00151	5801	0.06735	0.06296	0.00440
360	0.11611	0.11611	0.00000	873	0.05375	0.05059	0.00316	1715	0.04884	0.04358	0.00526	5804	0.03870	0.03674	0.00196
361	0.08382	0.08382	0.00000	874	0.04508	0.04399	0.00110	1716	0.04510	0.04483	0.00027	5805	0.04518	0.04286	0.00232
362	0.06842	0.06842	0.00000	875	0.04884	0.04358	0.00526	1717	0.03870	0.03674	0.00196	5820	0.04491	0.04053	0.00438
363	0.04510	0.04483	0.00027	876	0.04408	0.04051	0.00357	1718	0.03449	0.03288	0.00162	<b>5865</b>	<b>0.04647</b>	<b>0.03700</b>	<b>0.00947</b>
366	0.04408	0.04051	0.00357	877	0.03870	0.03674	0.00196	1719	0.03836	0.03714	0.00122	6014	0.12571	0.12571	0.00000
367	0.03147	0.02782	0.00364	878	0.03430	0.03065	0.00366	1721	0.03568	0.02975	0.00593	6030	0.00000	0.00000	0.00000
382	0.07739	0.07739	0.00000	879	0.03434	0.03279	0.00155	1725	0.04491	0.04053	0.00438	6038	0.02000	0.02000	0.00000
383	0.05410	0.05410	0.00000	892	0.02521	0.02268	0.00253	1776	0.03254	0.02853	0.00400	6040	0.04884	0.04358	0.00526
384	0.02000	0.02000	0.00000	893	0.03399	0.03175	0.00224	1777	0.03147	0.02782	0.00364	6042	0.03836	0.03714	0.00122
385	0.04620	0.04620	0.00000	894	0.05258	0.05063	0.00194	1778	0.03527	0.03294	0.00233	6060	0.03434	0.03279	0.00155
386	0.03957	0.03957	0.00000	960	0.00000	0.00000	0.00000	1782	0.00000	0.00000	0.00000	6120	0.00000	0.00000	0.00000
387	0.03475	0.03475	0.00000	961	0.03043	0.02964	0.00080	1785	0.00000	0.00000	0.00000	6375	0.10000	0.10000	0.00000
390	0.06387	0.06387	0.00000	963	0.00000	0.00000	0.00000	1910	0.04641	0.04247	0.00394	6625	0.05363	0.05341	0.00022
391	0.04136	0.04126	0.00010	965	0.02000	0.02000	0.00000	1912	0.07739	0.07739	0.00000	6627	0.04518	0.04286	0.00232
393	0.03475	0.03475	0.00000	966	0.03436	0.02900	0.00536	1913	0.04491	0.04053	0.00438	<b>6630</b>	<b>0.04647</b>	<b>0.03700</b>	<b>0.00947</b>
395	0.03679	0.03679	0.00000	967	0.02351	0.02304	0.00047	1914	0.05258	0.05063	0.00194	7128	0.00000	0.00000	0.00000
399	0.02000	0.02000	0.00000	975	0.00000	0.00000	0.00000	1918	0.07790	0.07790	0.00000	7140	0.00000	0.00000	0.00000
406	0.08382	0.08382	0.00000	980	0.05475	0.05475	0.00000	1968	0.03254	0.02853	0.00400	7905	0.10000	0.10000	0.00000
407	0.05985	0.05834	0.00151	981	0.03109	0.02707	0.00402	1969	0.03527	0.03294	0.00233	15555	0.00000	0.00000	0.00000
408	0.04411	0.04411	0.00000	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	27030	0.00000	0.00000	0.00000
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮				