Remarks on spatio-temporal spike correlations

B. Cessac, Université Côte d'Azur, INRIA, Biovision team and Neuromod Institute Sophia Antipolis, France

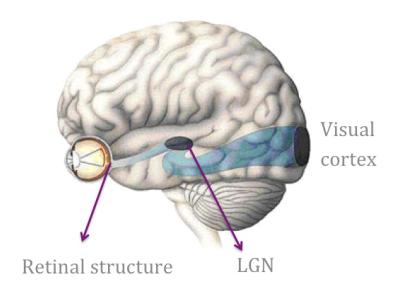


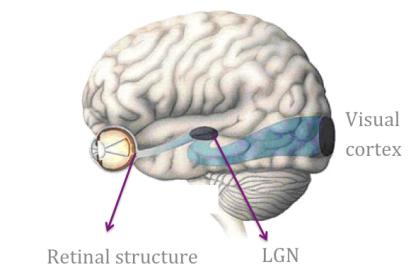


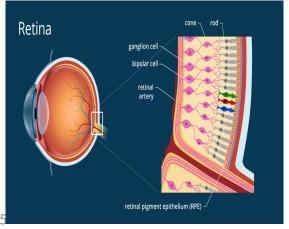
Goal of the talk

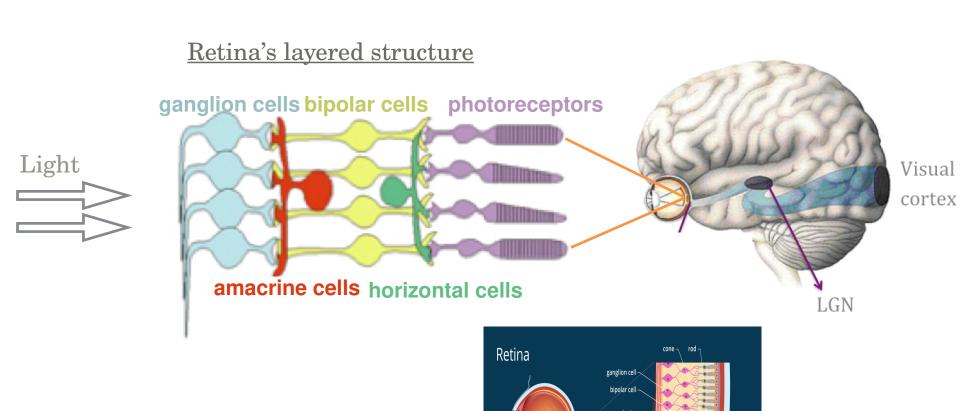
Here we ask some mathematically grounded questions about the potential structure of spike trains processed at the entrance of the visual system : retina-(LGN)-V1.

The retina and its dynamics

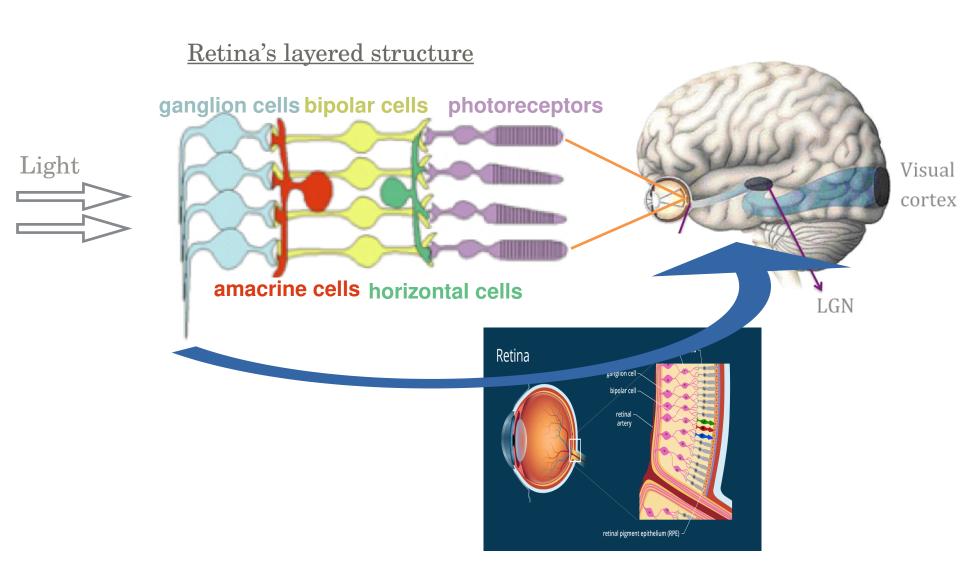


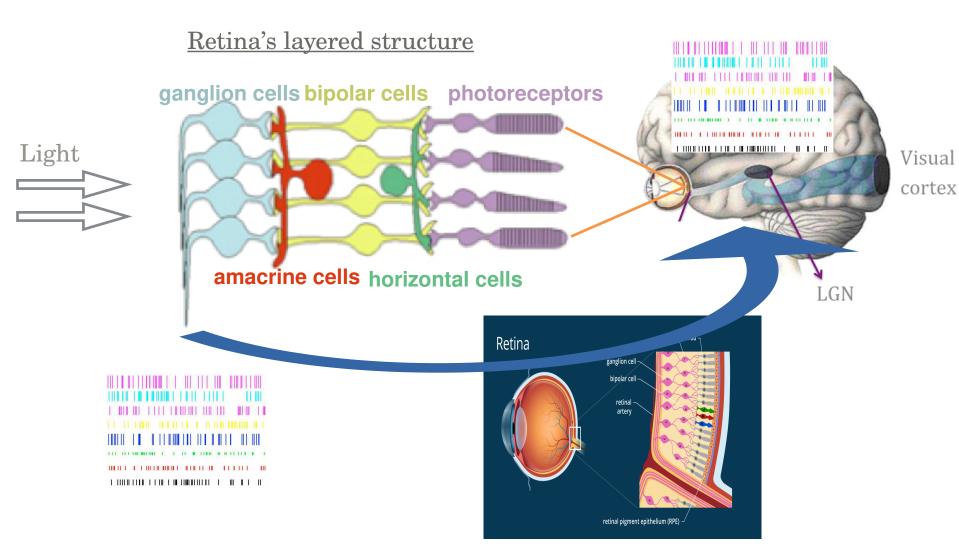


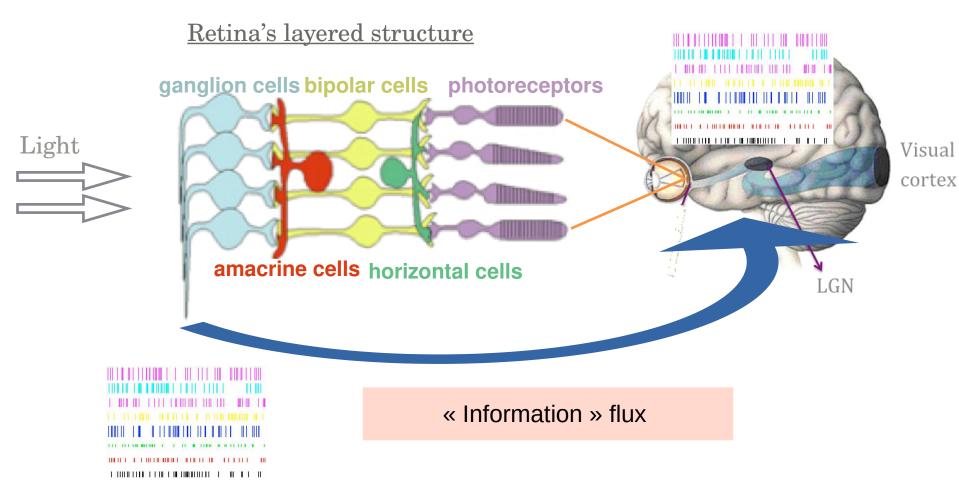


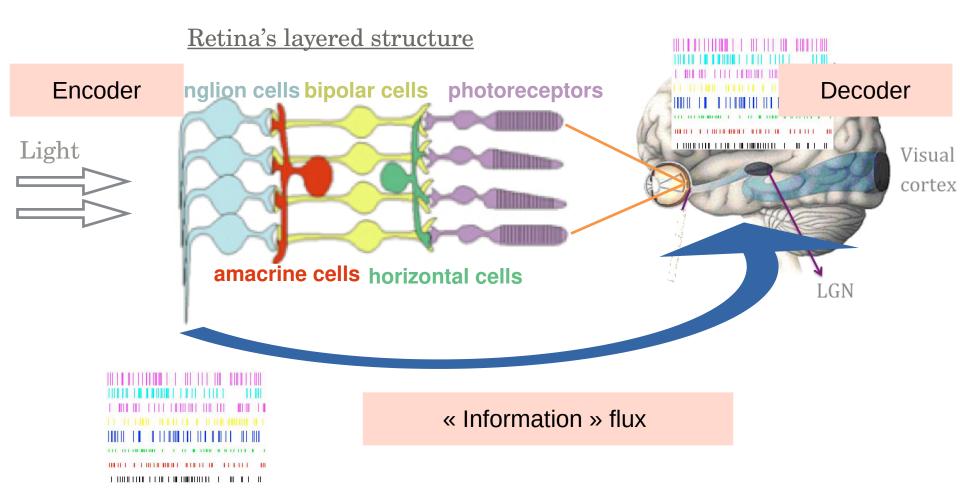


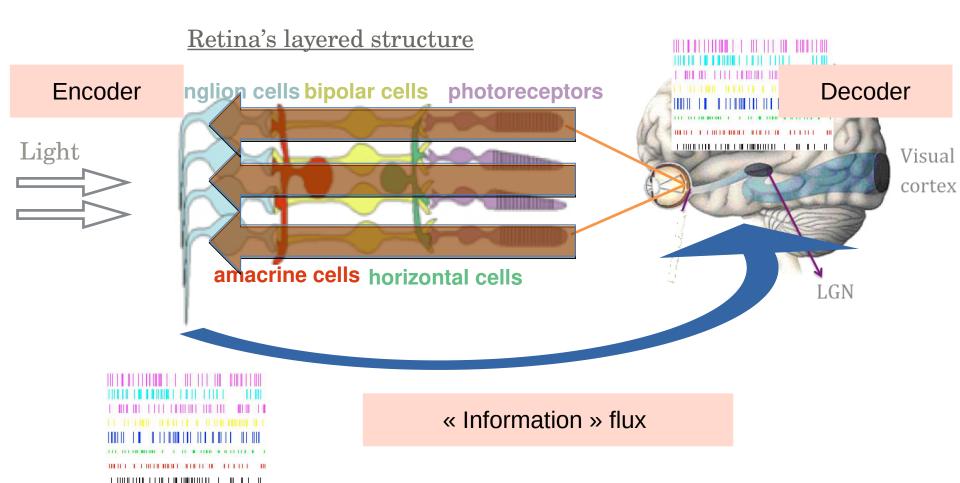
retinal pigment epithelium (RPE) -

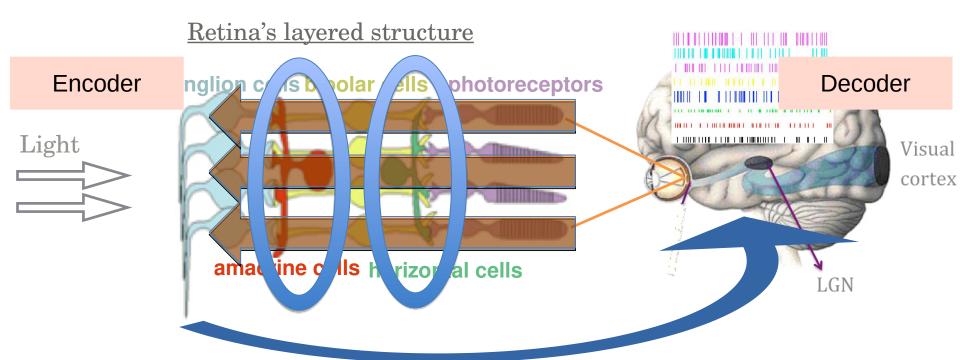




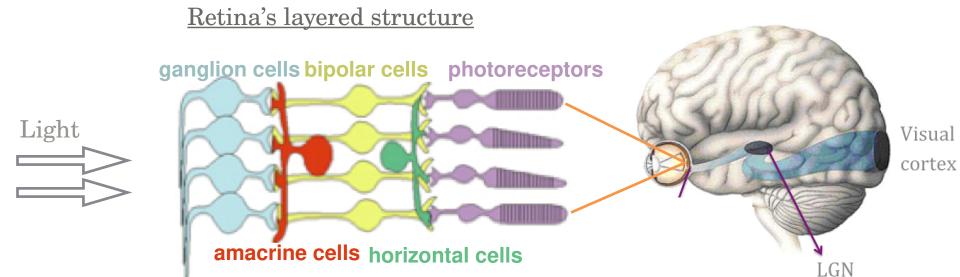








« Information » flux

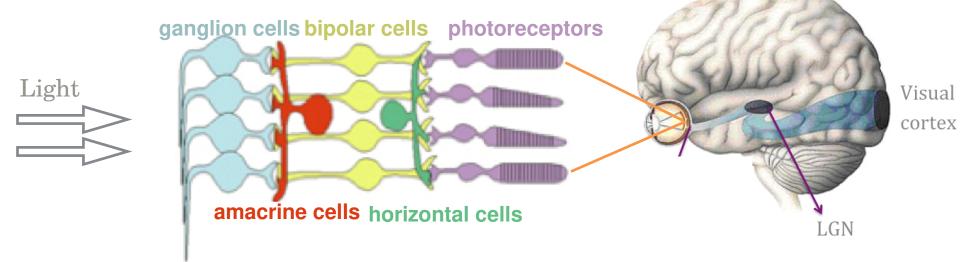


« Information » is processed by spikes.

Individual neurons and synapses do not matter.

Population dynamics, Mean-Field equations, PDEs, statistical physics, large deviations ...

Retina's layered structure



Analogic computing.

No spikes except at GCells

Individual neurons and synapses DO matter.

Dedicated circuits made of a few neurons and synapses process the local visual information. « Information » is processed by spikes.

Individual neurons and synapses do not matter.

Population dynamics, Mean-Field equations, PDEs, statistical physics, large deviations ...

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- 3. The conjunction of non linearities and regular structure can produce a highly complex *spatio-temporal* dynamics.

- 1. The retina is a **high dimensional**, **non autonomous and noisy** dynamical system, layered and structured, with **non stationary and spatially inhomogeneous entries** (visual scenes).
 - **2.** Local circuits of non linear cells, connected with non linear synapses efficiently process the local visual information. These local circuits are connected together, spanning the whole retina in a regular tiling.
- 3. The conjunction of non linearities and regular structure can produce a highly complex *spatio-temporal* dynamics.
 - 4. The retina is sensitive to *changes in its physiology* (development, pharmacology, pathologies). These changes can be addressed from the point of view of *bifurcations theory*.

Questions

I. Spatio-temporal spike correlations.

- 1. What could be the **spatio-temporal distribution of spikes** emitted from the retina to the LGN-cortex, considering that inputs are *non stationary* (moving objects)?
- 2. What could be the non stationary structure of spatio-temporal correlations?
- 3. In particular is it possible to disentangle the effects of:
 - i. Stimulus induced correlations;
 - **ii. Network** induced correlations;
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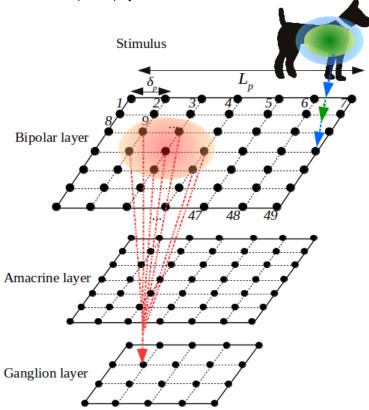
II. Cortical model

- 1. Which **mechanism/principle** is used to decipher "at best" the trajectory of a moving object from the retinal spike trains?
 - i. Firing rates?
 - ii. Individual spikes?
 - iii.Both?
- 2. What could be the implications of questions/answers in item 1 with respect to the theory of **efficient coding**?

A retina model

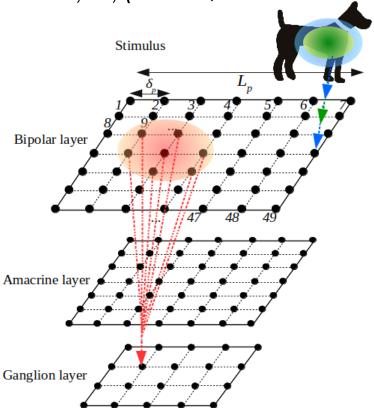
Souihel S., Cessac B., "On the potential role of lateral connectivity in retinalanticipation", Journal of Mathematical Neuroscience, BioMed Central, 2021, 11, (10.1186/s13408-020-00101-z)

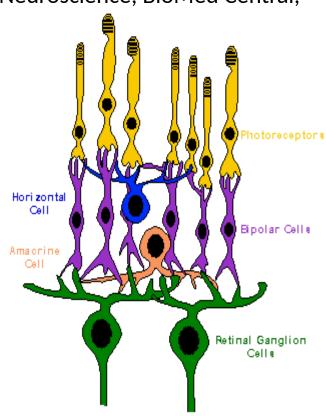
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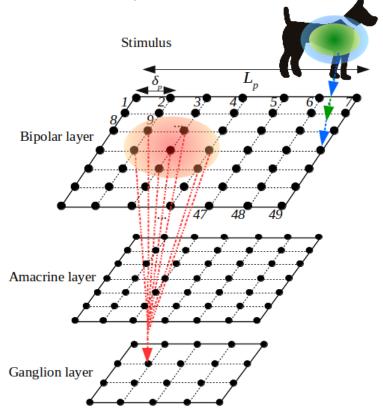
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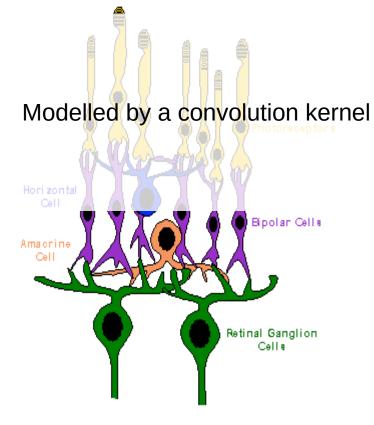




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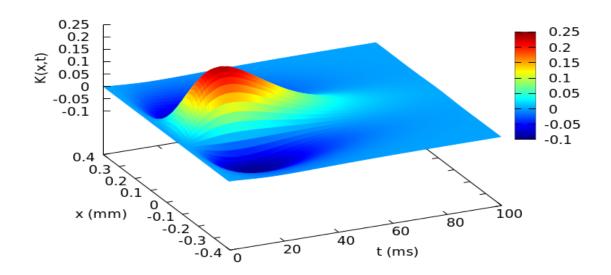
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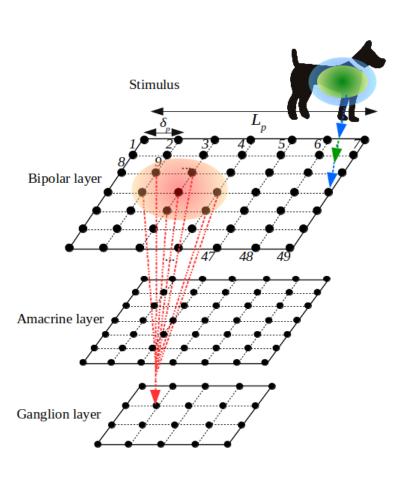




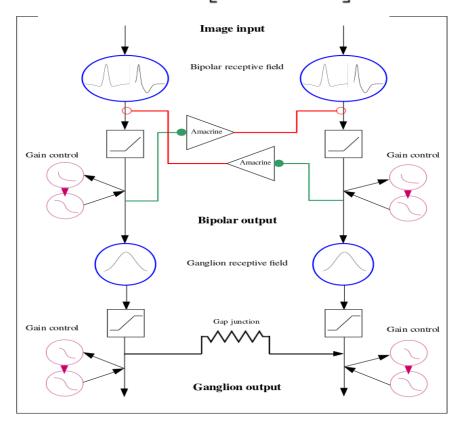
$$V_{i_{drive}}(t) = \left[\mathcal{K}_{B_i} \overset{x,y,t}{*} \mathcal{S} \right] (t)$$

$$=\int_{x=-\infty}^{+\infty}\int_{y=-\infty}^{+\infty}\int_{s=-\infty}^{t}\mathcal{K}_{B_{i}}(x-x_{i},y-y_{i},t-s)\mathcal{S}(x,y,s)dx\,dy\,ds.$$



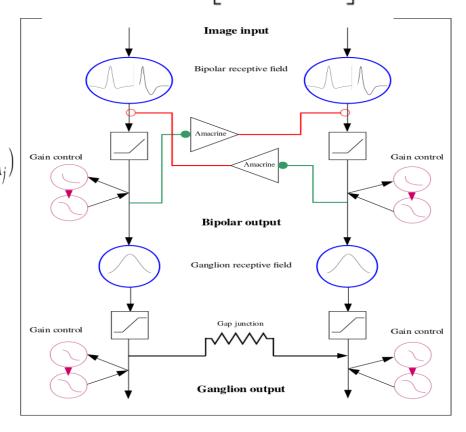


$$V_{i_{drive}}(t) = \left[\mathcal{K}_{B_i} \overset{x,y,t}{*} \mathcal{S} \right](t)$$



$$\begin{cases} \frac{dV_{B_{i}}}{dt} &= -\frac{1}{\tau_{B}}V_{B_{i}} + \sum_{j=1}^{N_{A}}W_{B_{i}}^{A_{j}}\mathcal{N}_{A}(V_{A_{j}}) + F_{B_{i}}(t), \\ \frac{dV_{A_{j}}}{dt} &= -\frac{1}{\tau_{A}}V_{A_{j}} + \sum_{i=1}^{N_{B}}W_{A_{j}}^{B_{i}}\mathcal{N}_{B}(V_{B_{i}}), \\ \frac{dV_{G_{k}}}{dt} &= -\frac{1}{\tau_{G}}V_{G_{k}} + \sum_{i=1}^{N_{B}}W_{G_{k}}^{B_{i}}\mathcal{N}_{B}(V_{B_{i}}) + \sum_{j=1}^{N_{A}}W_{G_{k}}^{A_{j}}\mathcal{N}_{A}(V_{A_{j}}) \end{cases}$$

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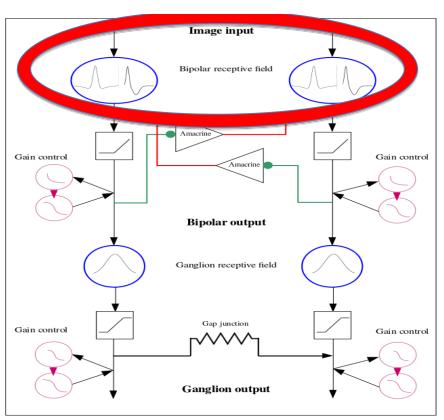
Stimulus dependent drive

$$\frac{dV_{B_i}}{dt} = -\frac{1}{\tau_B}V_{B_i} + \sum_{j=1}^{N_A} W_{B_i}^{A_j} \mathcal{N}_A(V_{A_j}) - F_{B_i}(t),$$

$$\frac{dV_{A_j}}{dt} = -\frac{1}{\tau_A}V_{A_j} + \sum_{i=1}^{N_B} W_{A_j}^{B_i} \mathcal{N}_B(V_{B_i}),$$

$$\frac{dV_{G_k}}{dt} = -\frac{1}{\tau_G} V_{G_k} + \sum_{i=1}^{N_B} W_{G_k}^{B_i} \mathcal{N}_B(V_{B_i}) + \sum_{j=1}^{N_A} W_{G_k}^{A_j} \mathcal{N}_A(V_{A_j})$$

$$F_{B_i}(t) = \frac{V_{i_{drive}}}{\tau_B} + \frac{dV_{i_{drive}}}{dt}$$



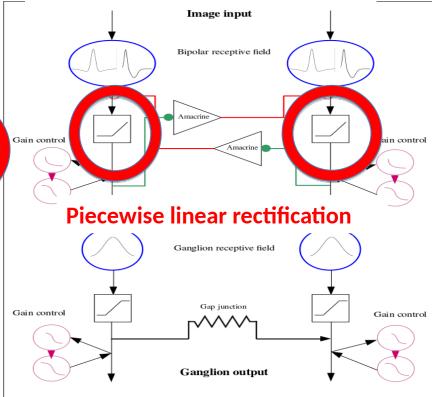
$$\frac{dV_{B_i}}{dt} = -\frac{1}{\tau_B}V_{B_i} + \sum_{j=1}^{N_A} W_{B_i}^{A_j} V_A(V_{A_j}) - F_{B_i}(t),$$

$$\frac{dV_{A_j}}{dt} = -\frac{1}{\tau_A}V_{A_j} + \sum_{i=1}^{N_B} W_i^T \mathcal{N}_B(V_{B_i})$$

$$\frac{dV_{G_k}}{dt} = -\frac{1}{\tau_G}V_{G_k} + \sum_{i=1}^{N_B} W_i^P \mathcal{N}_B(V_{B_i}) - \sum_{j=1}^{N_A} W_i^A \mathcal{N}_A(V_{A_j})$$
Gain control

$$\mathcal{N}_A(V) = \left\{ egin{array}{ll} V - heta_A, & ext{if } V_A > heta_A; \\ 0, & ext{otherwise} \end{array} \right.$$

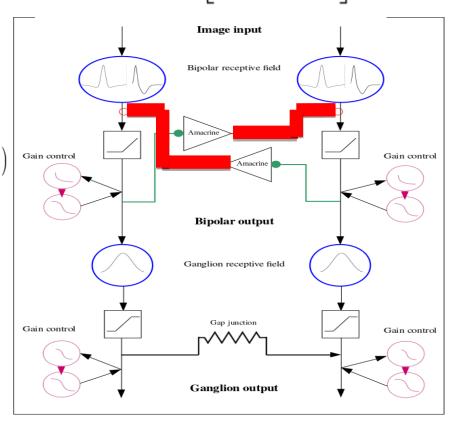
$$V_{i_{drive}}(t) = \left[\mathcal{K}_{B_i} \overset{x,y,t}{*} \mathcal{S} \right](t)$$



Inhibition

$$\begin{cases} \frac{dV_{B_{i}}}{dt} &= -\frac{1}{\tau_{B}} V_{B_{i}} + \sum_{j=1}^{N_{A}} W_{B_{i}}^{A_{j}} \mathcal{N}_{A} \left(V_{A_{j}} \right) + F_{B_{i}}(t), \\ \frac{dV_{A_{j}}}{dt} &= -\frac{1}{\tau_{A}} V_{A_{j}} + \sum_{i=1}^{N_{B}} W_{A_{j}}^{B_{i}} \mathcal{N}_{B} \left(V_{B_{i}} \right), \\ \frac{dV_{G_{k}}}{dt} &= -\frac{1}{\tau_{G}} V_{G_{k}} + \sum_{i=1}^{N_{B}} W_{G_{k}}^{B_{i}} \mathcal{N}_{B} \left(V_{B_{i}} \right) + \sum_{j=1}^{N_{A}} W_{G_{k}}^{A_{j}} \mathcal{N}_{A} \left(V_{A_{j}} \right) \end{cases}$$

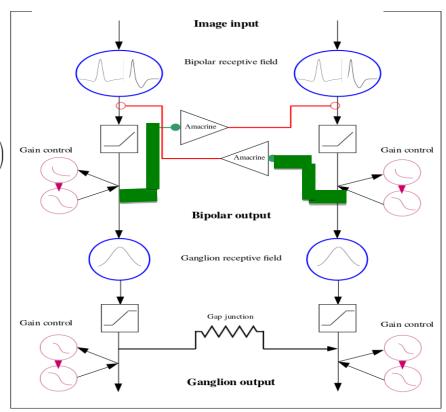
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Excitation

$$\begin{cases} \frac{dV_{B_{i}}}{dt} &= -\frac{1}{\tau_{B}}V_{B_{i}} + \sum_{j=1}^{N_{A}}W_{B_{i}}^{A_{j}}\mathcal{N}_{A}(V_{A_{j}}) + F_{B_{i}}(t), \\ \frac{dV_{A_{j}}}{dt} &= -\frac{1}{\tau_{A}}V_{A_{j}} + \sum_{i=1}^{N_{A}}W_{A_{j}}^{B_{i}}\mathcal{N}_{B}(V_{B_{i}}), \\ \frac{dV_{G_{k}}}{dt} &= -\frac{1}{\tau_{G}}V_{G_{k}} + \sum_{i=1}^{N_{B}}W_{G_{k}}^{B_{i}}\mathcal{N}_{B}(V_{B_{i}}) + \sum_{j=1}^{N_{A}}W_{G_{k}}^{A_{j}}\mathcal{N}_{A}(V_{A_{j}}) \end{cases}$$

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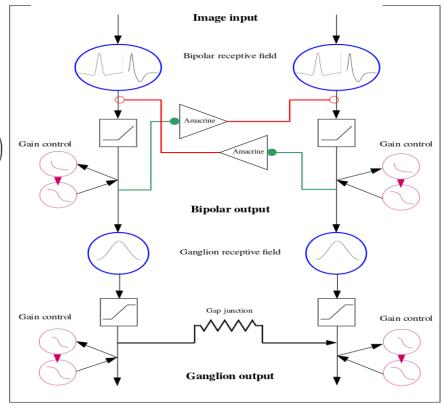
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Voltage dynamics

$$\mathcal{N}_{G}(V_{G}) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\frac{V_{G} - \theta_{G}}{\sigma_{G}}} e^{-\frac{x^{2}}{2}} dx.$$

Spike rate

$$V_{i_{drive}}(t) = \left[\mathcal{K}_{B_i} \overset{x,y,t}{*} \mathcal{S} \right](t)$$



Dynamical system representation

$$\begin{cases} \frac{dV_{B_{i}}}{dt} &= -\frac{1}{\tau_{B}} V_{B_{i}} + \sum_{j=1}^{N_{A}} W_{B_{i}}^{A_{j}} \mathcal{N}_{A} \left(V_{A_{j}} \right) + F_{B_{i}}(t), \\ \frac{dV_{A_{j}}}{dt} &= -\frac{1}{\tau_{A}} V_{A_{j}} + \sum_{i=1}^{N_{B}} W_{A_{j}}^{B_{i}} \mathcal{N}_{B} \left(V_{B_{i}} \right), \\ \frac{dV_{G_{k}}}{dt} &= -\frac{1}{\tau_{G}} V_{G_{k}} + \sum_{i=1}^{N_{B}} W_{G_{k}}^{B_{i}} \mathcal{N}_{B} \left(V_{B_{i}} \right) + \sum_{j=1}^{N_{A}} W_{G_{k}}^{A_{j}} \mathcal{N}_{A} \left(V_{A_{j}} \right) \end{cases}$$

$$\mathcal{F}_{\alpha}(t) = \begin{cases} F_{B_i}(t), & \alpha = i, & i = 1 \dots N_B; \\ 0, & \alpha > N_B; \end{cases}$$

$$\mathcal{X}_{\alpha} = \begin{cases} V_{B_{i}}, & \alpha = i, & i = 1 \dots N_{B}; \\ V_{A_{j}}, & \alpha = N_{B} + j, & j = 1 \dots N_{A}; \\ V_{G_{k}}, & \alpha = N_{B} + N_{A} + k, & k = 1 \dots N_{G}. \end{cases}$$

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$$\mathcal{W} = \left(egin{array}{cccc} 0_{N_BN_B} & W_B^A & 0_{N_BN_G} \ W_A^B & 0_{N_AN_A} & 0_{N_AN_G} \ W_G^B & W_G^A & 0_{N_GN_G} \ \end{array}
ight)$$

Dynamics of the 2D retina model

Dynamical system representation

$$rac{dec{\mathcal{X}}}{dt} = \mathcal{T}^{-1}.ec{\mathcal{X}} + \mathcal{W}.ec{\mathcal{R}}(ec{\mathcal{X}}) + ec{\mathcal{F}}(t).$$

$$\mathcal{T} = \begin{pmatrix} -\operatorname{diag}[\tau_{B_{i}}]_{i=1...N_{B}} & 0_{N_{B}N_{A}} & 0_{N_{B}N_{G}} \\ 0_{N_{A}N_{B}} & -\operatorname{diag}[\tau_{A_{j}}]_{j=1...N_{A}} & 0_{N_{A}N_{G}} \\ 0_{N_{G}N_{B}} & 0_{N_{G}N_{A}} & -\operatorname{diag}[\tau_{G_{k}}]_{k=1...N_{G}} \end{pmatrix}$$

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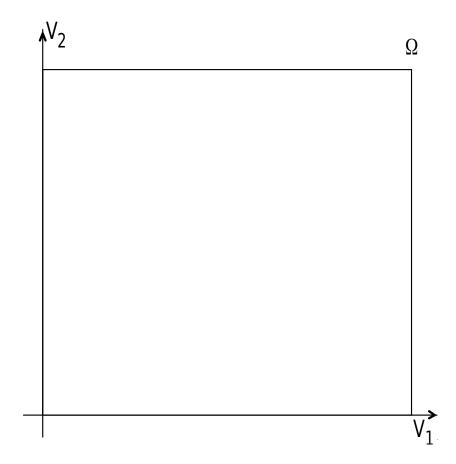
Dynamics of the 2D retina model

$$rac{dec{\mathcal{X}}}{dt} = \mathcal{T}^{-1}.ec{\mathcal{X}} + \mathcal{W}.ec{\mathcal{R}}(ec{\mathcal{X}}) + ec{\mathcal{F}}(t).$$

Piecewise linear dynamical system

$$\mathcal{R}_{\alpha}(\vec{\mathcal{X}}) = \begin{cases} \mathcal{N}_{B}(V_{B_{i}}), & \alpha = i, & i = 1 \dots N_{B}; \\ \mathcal{N}_{A}(V_{A_{j}}), & \alpha = N_{B} + j, & j = 1 \dots N_{A}; \\ 0, & \alpha = N_{B} + N_{A} + k, & k = 1 \dots N_{G}. \end{cases}$$

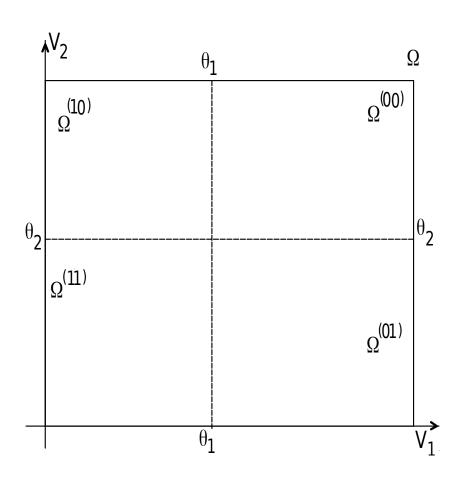
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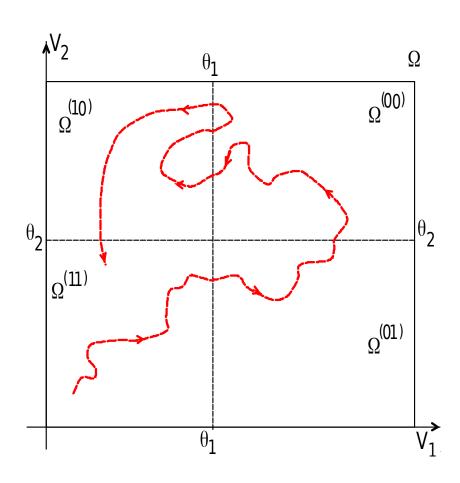
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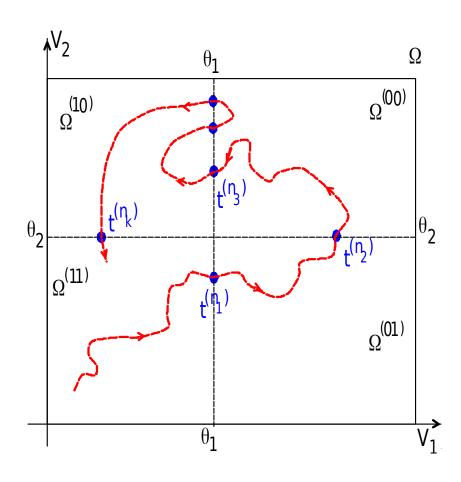
$$\mathcal{N}_A(V) = \left\{ egin{array}{ll} V - \theta_A, & \mbox{if } V_A > \theta_A; \\ 0, & \mbox{otherwise} \end{array} \right.$$



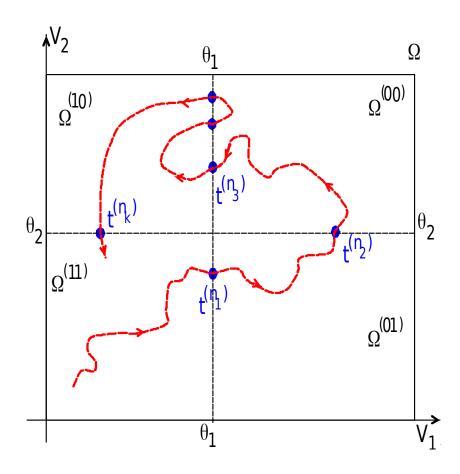
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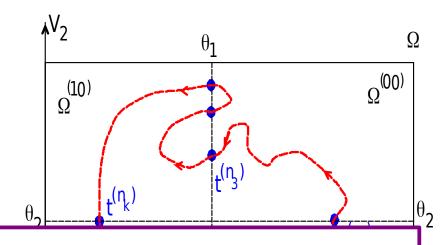
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$$rac{dec{\mathcal{X}}}{dt} = \mathcal{L}^{(n)}.ec{\mathcal{X}} + ec{\mathcal{F}}^{(n)}(t), \quad ec{\mathcal{X}} \in \Omega^{(n)}$$



$$rac{d\vec{\mathcal{X}}}{dt} = \mathcal{L}^{(n)}.\vec{\mathcal{X}} + \vec{\mathcal{F}}^{(n)}(t), \quad \vec{\mathcal{X}} \in \Omega^{(n)}$$



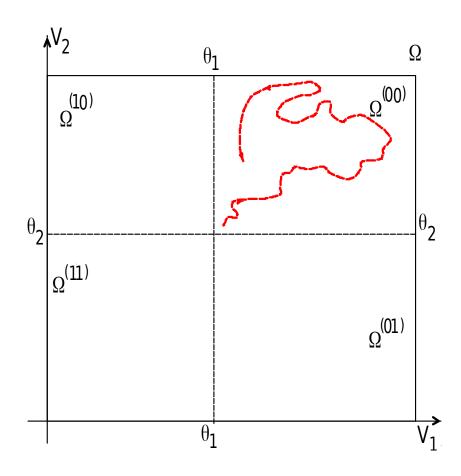
$$\vec{\mathcal{X}}(t) = e^{\mathcal{L}^{(n_{k+1})}(t - t_{-}^{(n_{k+1})})} \cdot \vec{\mathcal{X}}(t_{-}^{(n_{k+1})}) + \int_{t_{-}^{(n_{k+1})}}^{t} e^{\mathcal{L}^{(n_{k+1})}(t - s)} \cdot \vec{\mathcal{F}}^{(n_{k+1})}(s) \, ds, \quad t \in \left[t_{-}^{(n_{k+1})}, t_{+}^{(n_{k+1})}\right]$$

$$rac{dec{\mathcal{X}}}{dt} = \mathcal{L}^{(0)}.ec{\mathcal{X}} + ec{\mathcal{F}}^{(0)}(t), \quad ec{\mathcal{X}} \in \Omega^{(0)}$$

Non rectified dynamical system

We assume:

- 1) All eigenvalues are stable;
- 2) The rest state is in $\Omega^{(0)}$. We set it to 0.

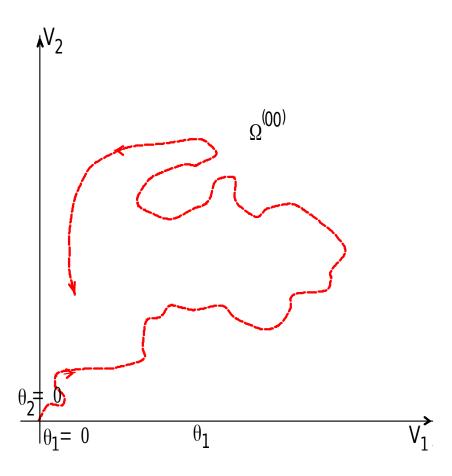


$$rac{dec{\mathcal{X}}}{dt} = \mathcal{L}^{(0)}.ec{\mathcal{X}} + ec{\mathcal{F}}^{(0)}(t), \quad ec{\mathcal{X}} \in \Omega^{(0)}$$

Non rectified dynamical system

We assume:

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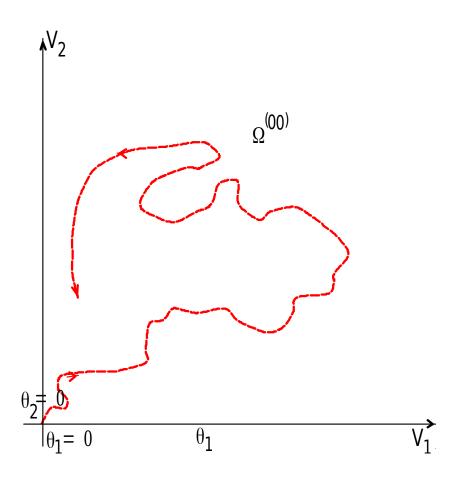
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Non rectified dynamical system

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- 1) All eigenvalues are stable;
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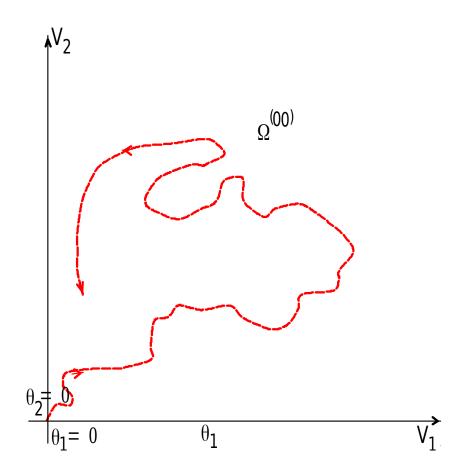


$$rac{dec{\mathcal{X}}}{dt} = \mathcal{L}^{(0)}.ec{\mathcal{X}} + ec{\mathcal{F}}^{(0)}(t), \quad ec{\mathcal{X}} \in \Omega^{(0)}$$

The eigenvalues and eigenvectors of can be computed in some specific cases as well as conditions for stability.

S. Souihel, B. Cessac, Journal of Mathematical Neuroscience, BioMed Central, 2021, 11, (10.1186/s13408-020-00101-z)

B. Cessac, Journal of Imaging, 2022, Special Issue Mathematical Modeling of Human Vision and Its Application to Image Processing, 8 (1), pp.14. (10.3390/jimaging8010014)



$$S(x,y,t) = S_d(x,y,t) + \sigma_S \, \xi(x,y,t)$$

$$V_{i_{drive}}(t) = \left[\mathcal{K}_{B_i} \overset{x,y,t}{*} \mathcal{S} \right](t)$$

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$$\mathbb{E}\left[\left(V_{i_{drive}}(t) - \mathbb{E}\left[V_{i_{drive}}(t)\right]\right)\left(V_{j_{drive}}(t') - \mathbb{E}\left[V_{j_{drive}}(t')\right]\right)\right]$$

$$= \sigma_S^2 \int_{x=-\infty}^{+\infty} \int_{y=-\infty}^{+\infty} \int_{s=-\infty}^{t} \mathcal{K}_{B_i}(x - x_i, y - y_i, t - s) \mathcal{K}_{B_j}(x - x_j, y - y_j, t' - s) dx dy ds$$

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Drive correlations do not depend on the **stimulus**, only on the **receptive fields**, via the overlap of the spatial and temporal part.

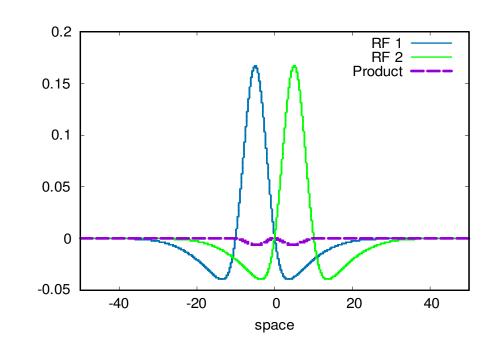
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Lateral inhibition weakens these correlations.

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 - **II. Network effects** (mixture of exponentials decaying in time);

$$C_{\vec{\mathcal{X}}}(t,t') = \int_{s=-\infty}^{t} \int_{s'=-\infty}^{t'} e^{\mathcal{L}^{(0)}(t-s)} . C_{\mathcal{F}}(s,s') \left(e^{\tilde{\mathcal{L}}^{(0)}(t'-s')} ds \, ds' \right)$$

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- 2) Voltages correlations are due to :
 - I. Stimuli correlations;
 - II. Network effects (mixture of exponentials decaying in time);
 - III. For a **moving object** correlations propagate with the stimulus in a **wave like-form** with a network contribution.

$$C_{\vec{\mathcal{X}}}(t,t') = \int_{s=-\infty}^{t} \int_{s'=-\infty}^{t'} e^{\mathcal{L}^{(0)}(t-s)} . C_{\mathcal{F}}(s,s') . e^{\tilde{\mathcal{L}}^{(0)}(t'-s')} ds ds'$$

Motion anticipation

Souihel S., Cessac B., "On the potential role of lateral connectivity in retinal anticipation", Journal of Mathematical Neuroscience, BioMed Central, 2021, 11, (10.1186/s13408-020-00101-z)

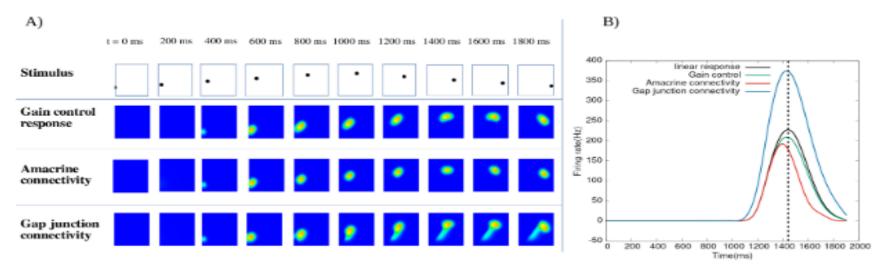


Figure 15: Effect of anticipatory mechanisms on a parabolic trajectory. A) Response to a dot moving along a parabolic trajectory. The first line shows the stimulus, the second line shows the GCells response with gain control, the third line presents the effect of lateral ACells connectivity with $w=0.3\ ms^{-1}$, and the last line shows the effect of asymmetric gap junctions with $v_{gap}=9\ mm/s$. B) Time course response of a cell responding to the dot near the trajectory turning point. Linear response corresponds to the response to the stimulus without gain control.

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$$\mathcal{N}_G(V_{G_k}) = f\left(\frac{V_{G_k}(t) - \theta_G}{\sigma_G}\right) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\frac{V_{G_k} - \theta_G}{\sigma_G}} e^{-\frac{x^2}{2}} dx$$

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- I. High order correlations can be computed (X is Gaussian).
- II. They depend on stimulus correlations and network induced correlations in an explicit way.

$$\nu_{\alpha_1 \alpha_2 \dots \alpha_k} \left(t_1, t_2, \dots t_k \right) \equiv \mathbb{E} \left[f \left(\frac{V_{G_{\alpha_1}}(t_1) - \theta_G}{\sigma_G} \right) f \left(\frac{V_{G_{\alpha_2}}(t_2) - \theta_G}{\sigma_G} \right) \dots f \left(\frac{V_{G_{\alpha_k}}(t_k) - \theta_G}{\sigma_G} \right) \right]$$

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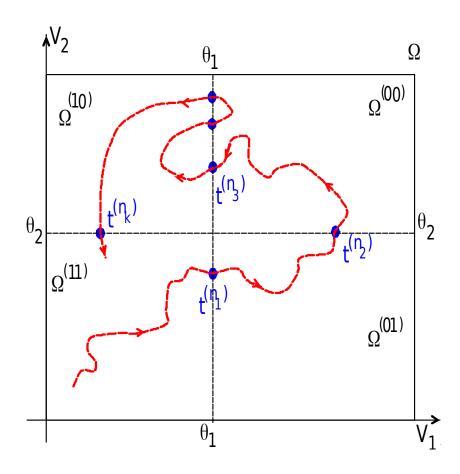
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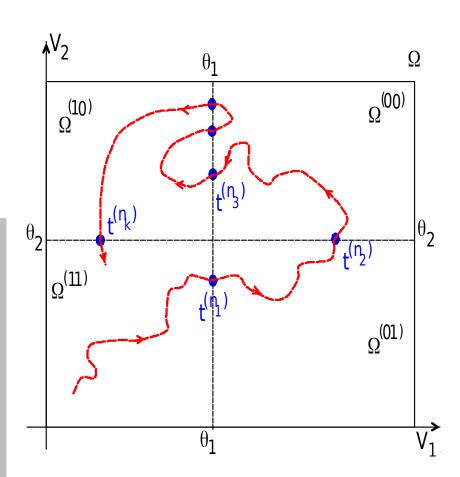
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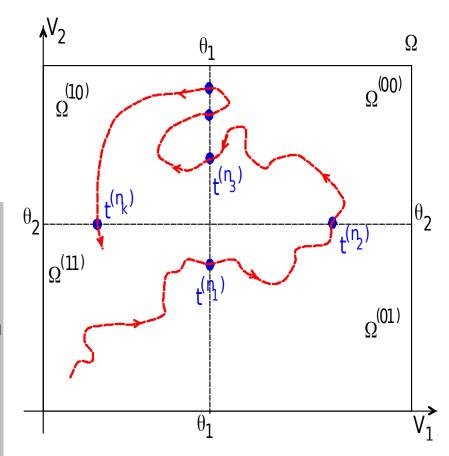
Piecewise linear dynamical system

I. Rectification generates **null eigenvalues** that actually prevent **exponential instability**;



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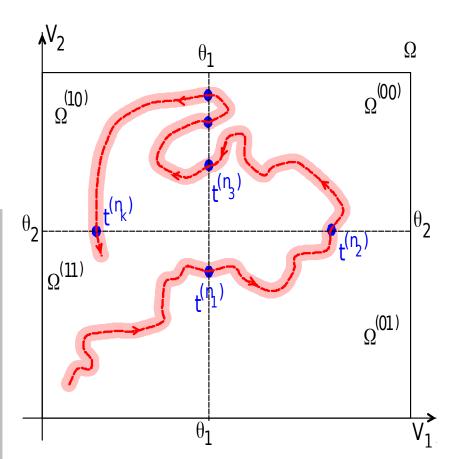
- I. Rectification generates **null eigenvalues** that actually prevent **exponential instability**;
- II. In the deterministic case times of exit from continuity domains can be explicitly computed. They depend on the stimulus;



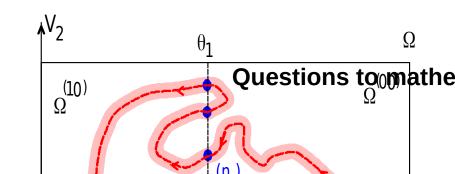
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Piecewise linear stochastic system

- I. Rectification generates null eigenvalues that actually prevent exponential instability;
- II. In the deterministic case times of exit from continuity domains can be explicitly computed. They depend on the stimulus;
 - III. In the stochastic case these times become **random**.



$$\frac{d\vec{\mathcal{X}}}{dt} = \mathcal{L}^{(n)}.\vec{\mathcal{X}} + \vec{\mathcal{F}}^{(n)}(t), \quad \vec{\mathcal{X}} \in \Omega^{(n)}$$



Piecewise linear stochastic system

$$\vec{\mathcal{X}}(t) = e^{\mathcal{L}^{(n_{k+1})}(t - t_{-}^{(n_{k+1})})} \cdot \vec{\mathcal{X}}(t_{-}^{(n_{k+1})}) + \int_{t_{-}^{(n_{k+1})}}^{t} e^{\mathcal{L}^{(n_{k+1})}(t - s)} \cdot \vec{\mathcal{F}}^{(n_{k+1})}(s) \, ds, \quad t \in \left[t_{-}^{(n_{k+1})}, t_{+}^{(n_{k+1})}\right]$$

II. In the deterministic case times of exit from continuity domains can be explicitly computed. They depend on the stimulus;

 $\Omega^{(01)}$

III. In the

Correlations depend now on the stimulus.

Questions to mathematicians

Can we compute, in this setting:

The law of the exit times (say for a bar moving with a constant speed)?

The voltages correlations (are they still Gaussian?)

The spike correlations?

 $dec{\mathcal{X}}$

 $\frac{}{dt} =$

Piece

$$\vec{\mathcal{X}}(t) = e^{\lambda}$$

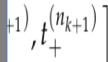
II. In the decont

III. In the

Correlations depend now on the stimulus.

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Partial conclusion

I. Spatio-temporal spike correlations.

- 1. What could be the **spatio-temporal distribution of spikes** emitted from the retina to the LGN-cortex, considering that inputs are *non stationary* (moving objects)?
- 2. What could be the non stationary structure of spatio-temporal correlations?
- 3. In particular is it possible to disentangle the effects of:
 - i. Stimulus induced correlations;
 - **ii. Network** induced correlations;
 - iii. Non linearities.

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I. Spatio-temporal spike correlations.

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In this model,

- 1. Lateral inhibition decorellates the stimulus input in the linear case only;
- **2. Voltage correlations** are integrating stimulus **correlations**/ **network/rectification** effects in a way that can be mathematically analysed;
- 3. A moving object generates a wave of activity which also impacts spatiotemporal spike correlations;
- **4. Rectification/Gain control** have a strong impact on these correlations (some cell become suddendly silent).

Spike response to correlated inputs

A spiking model

- B. Cessac, Viéville T., "On Dynamics of Integrate-and-Fire Neural Networks with Adaptive Conductances.", Front. Comput. Neurosci. (2008) 2:2.
 - R. Cofré and B. Cessac « Dynamics and spike trains statistics in conductance-based Integrate-and-Fire neural networks with chemical and electric synapses », Chaos, Solitons & Fractals, Volume 50, May 2013, Pages 13-31.
 - B. Cessac and R. Cofré, « Spike train statistics and Gibbs distributions », J. Physiol. Paris, Volume 107, Issue 5, Pages 360-368 (November 2013). Special issue: Neural Coding and Natural Image Statistics.
 - B. Cessac, I. Ampuero, R. Cofre, « Linear response for spiking neuronal networks with unbounded memory ». Entropy, MDPI, 2021, 23 (2), pp.155. (10.3390/e23020155)

A conductance-based Integrate and Fire model

Sub-threshold dynamics:

$$C_k \frac{dV_k}{dt} + g_k(t, \omega) V_k = i_k(t, \omega).$$

- Linear in V.
- Spike history-dependent.

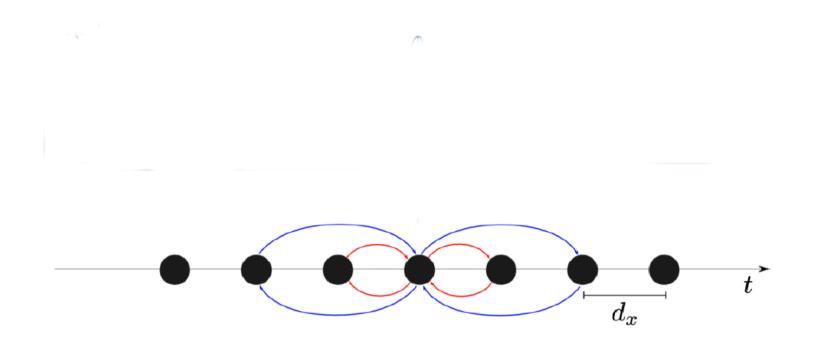
Dynamics integration

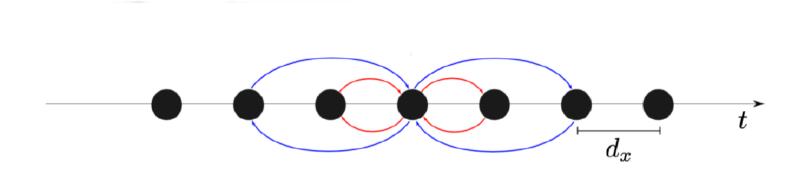
$$\Gamma_k(t_1, t, \omega) = e^{-\frac{1}{C_k} \int_{t_1 \vee \tau_k(t, \omega)}^t g_k(u, \omega) du}$$

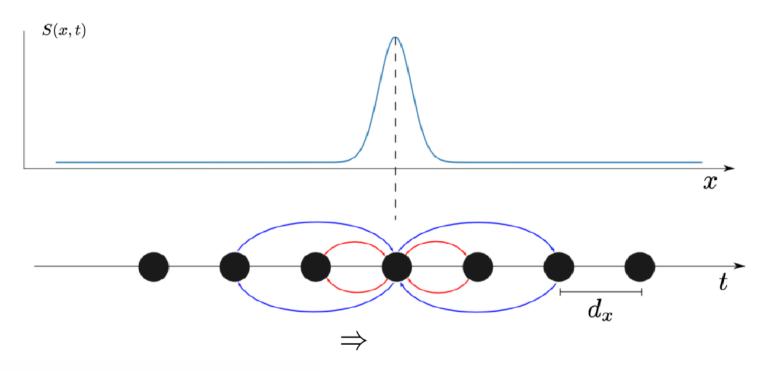
$$V_k(t,\omega) = \underbrace{V_k^{(sp)}(t,\omega) + V_k^{(S)}(t,\omega)}_{V_k^{(det)}(t,\omega)} + V_k^{(noise)}(t,\omega)$$

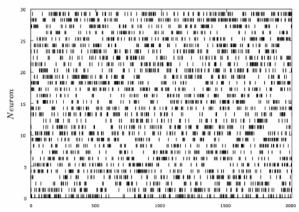
$$V_k^{(sp)}(t,\omega) = V_k^{(syn)}(t,\omega) + V_k^{(L)}(t,\omega),$$

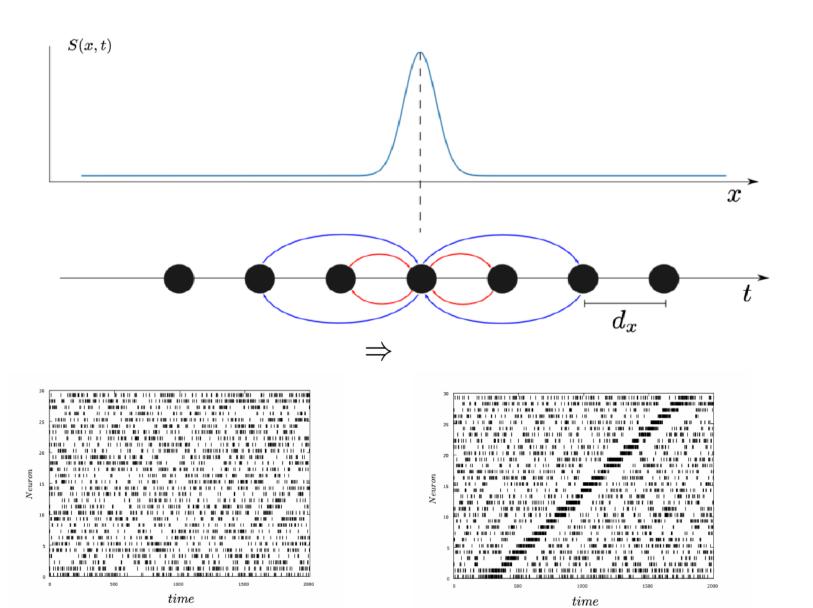
$$V_k^{(syn)}(t,\omega) = \frac{1}{C_k} \sum_{i=1}^N W_{kj} \int_{\tau_k(t,\omega)}^t \Gamma_k(t_1,t,\omega) \alpha_{kj}(t_1,\omega) dt_1$$

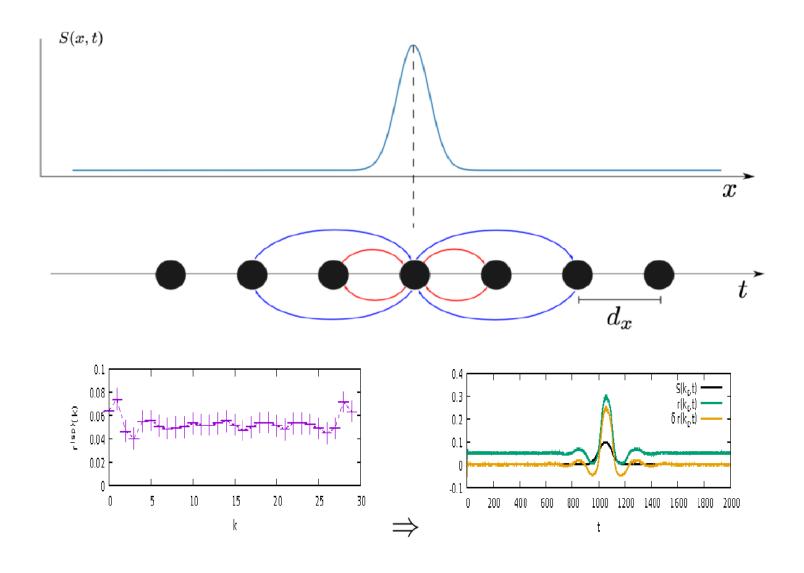




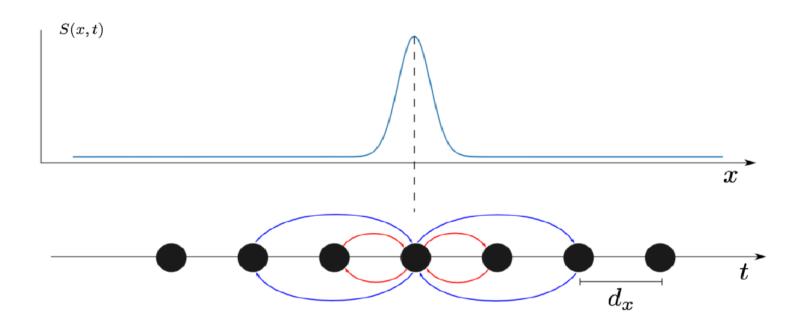


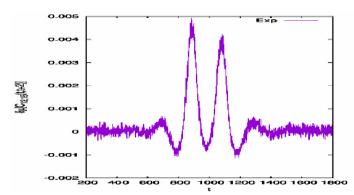






Sample averaging (non stationary)





Variation in the correlation $C_{12,15}(t, t+2)$

Correlation variations are triggered by the stimulus, but they are constrained by the network dynamics.



Question

How to compute the spatio-temporal response of a neuronal network to a time dependent stimulus ?

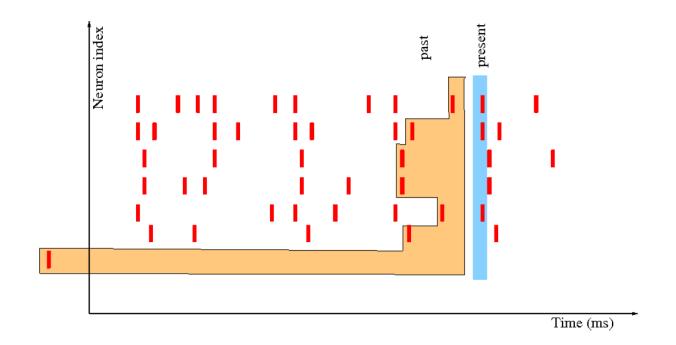
Can we compute the time variation of spike-observables as a function of the stimulus and spontaneous dynamics ?

B. Cessac, I. Ampuero, R. Cofre, Linear response for spiking neuronal networks with unbounded memory. Entropy, MDPI, 2021, 23 (2), pp.155.

A conductance-based Integrate and Fire model

Variable length Markov chain with unbounded memory

$$P_n\left[\omega(n) \mid \omega_{-\infty}^{n-1}\right] \equiv \Pi\left(\omega(n), \frac{\theta - V_k^{(det)}(n-1, \omega)}{\sigma_k(n-1, \omega)}\right)$$



Response to stimuli

B. Cessac, I. Ampuero, R. Cofre, Linear response for spiking neuronal networks with unbounded memory. Entropy, MDPI, 2021, 23 (2), pp.155.

GIF model without stimulus \Rightarrow stationary Gibbs distribution.

time-dependent stimulus $S(t) \Rightarrow non stationary Gibbs distribution$.

How is the average of an observable $f(\omega, t)$ affected by the stimulus ?

If S is weak enough: $\delta \mu [f(t)] = [\kappa_f * S](t)$, (linear response).

$$\kappa_{k,f}(t-t_1) = \frac{1}{C_k} \sum_{r=-\infty}^{n=\lfloor t \rfloor} \mathcal{C}^{(sp)} \left[f(t,\cdot), \frac{\mathcal{H}_k^{(1)}(r,\cdot)}{\sigma_k(r-1,\cdot)} \int_{\tau_k(r-1,\cdot)}^{r-1} S_k(t_1) \Gamma_k(t_1,r-1,\cdot) dt_1 \right]$$

Firing rates

Computations have been done using the INRIA Pranas software, B. Cessac et al, Frontiers in Neuroinformatics, Vol 11, page 49, (2017).

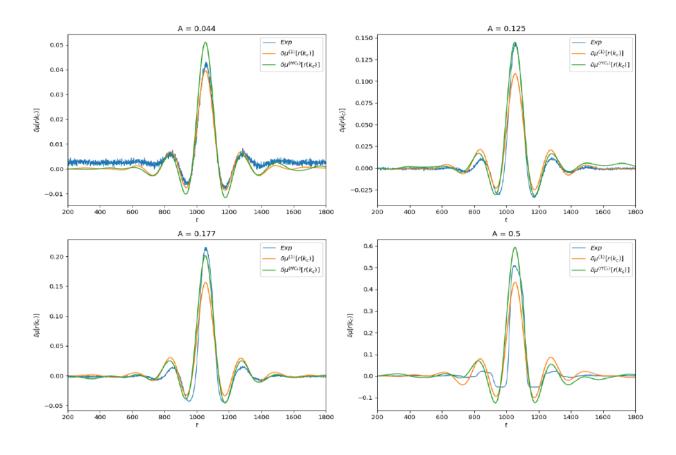


Figure: Linear response of $f(\omega, n) = \omega_{k_c}(n)$ for different values of stimulus amplitude A.

Higher order observable

Computations have been done using the INRIA Pranas software, B. Cessac et al, Frontiers in Neuroinformatics, Vol 11, page 49, (2017).

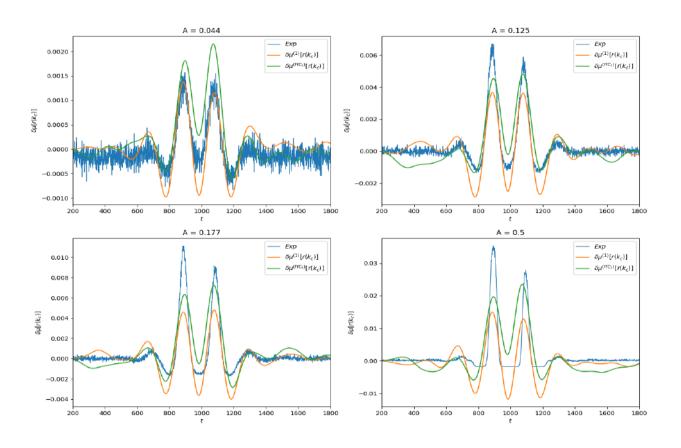


Figure: Linear response of the observable $f(n, \omega) = \omega_{k_c-2}(n-3)\omega_{k_c}(n)$.

Higher order observable

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Suggestion to mathematicians:

Would it be possible to extend this linear response in a more general context (Hawkes processes, Galves-Löcherbach model)?

Figure: Linear response of the observable $f(n, \omega) = \omega_{k_c-2}(n-3)\omega_{k_c}(n)$.

Partial conclusion

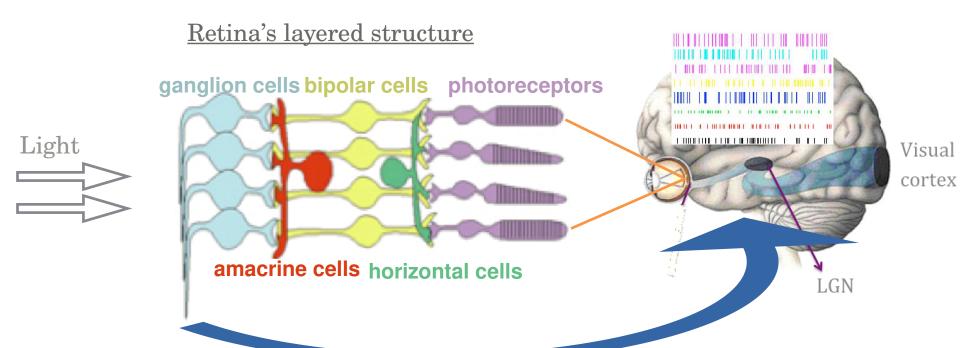
I. Spatio-temporal spike correlations.

- 1. What could be the **spatio-temporal distribution of spikes** emitted from the retina to the LGN-cortex, considering that inputs are *non stationary* (moving objects)?
- 2. What could be the non stationary structure of spatio-temporal correlations?
- 3. In particular is it possible to disentangle the effects of:
 - i. Stimulus induced correlations;
 - ii. Network induced correlations;
 - iii. Non linearities.

Moving stimuli, network dynamics and nonlinear effects (thresholding, gain control) not only affect firing rates, they also modify the spatio-temporal spike correlations.

How to decode the information contained in these correlations?

The visual system

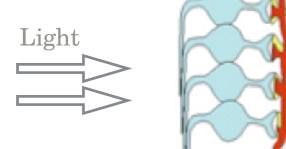


The cortex has no clue of what is happening in the retina. It only receives spikes and has to extract all the visual information from them.

The visual system

Retina's layered structure

ganglion cells bipolar cells photoreceptors



Which cortical model?

Firing rates?

Individual spikes?

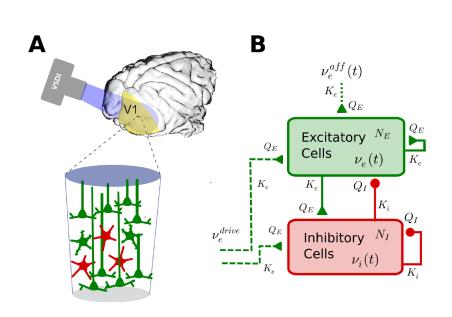


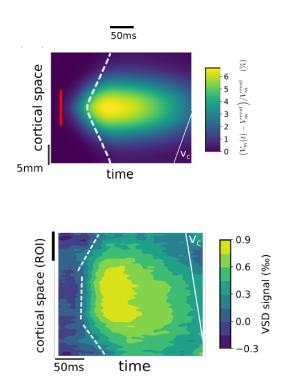
Visual cortex

amacrine

A mean field model to reproduce VSDI recordings

Collaboration with Institut des Neurosciences de la Timone (F. Chavane), NeuroPsi (A. Destexhe), Institut de la Vision (O. Marre)





Single neuron model (The adaptative exponential integrate and fire model Brette and Gerstner, 2005)

$$\begin{cases} C_m \frac{dV}{dt} = g_L (E_L - V) + I_{syn}(V, t) + k_a e^{\frac{V - V_{thre}}{k_a}} - I_w \\ \tau_w \frac{dI_w}{dt} = -I_w + a \cdot (V - E_L) + \sum_{t_s \in \{t_{spike}\}} b \, \delta(t - t_s) \end{cases}$$

The conductance-based exponential synapse

$$I_{syn}(V,t) = \sum_{s \in \{e,i\}} \sum_{t_s \in \{t_s\}} Q_s \left(E_s - V\right) e^{-\frac{t - t_s}{\tau_s}} \, \mathcal{H}(t - t_s)$$

Semi analytical transfer function:

$$\nu_{out} = \mathcal{F}(\nu_{e}, \nu_{i}) = \frac{1}{2 \tau_{V}} \cdot Erfc(\frac{V_{thre}^{eff} - \mu_{V}}{\sqrt{2} \sigma_{V}}) \quad \text{with} \quad V_{thre}^{eff}(\mu_{V}, \sigma_{V}, \tau_{V}^{N}) = P_{0} + \sum_{x \in \{\mu_{V}, \sigma_{V}, \tau_{V}^{N}\}^{2}} P_{x} \cdot \left(\frac{x - x^{0}}{\delta x^{0}}\right) \left(\frac{y - y^{0}}{\delta y^{0}}\right) + \sum_{x, y \in \{\mu_{V}, \sigma_{V}, \tau_{V}^{N}\}^{2}} P_{xy} \cdot \left(\frac{x - x^{0}}{\delta x^{0}}\right) \left(\frac{y - y^{0}}{\delta y^{0}}\right)$$

Master equation for first and second moments local population dynamics (El Boustani and Destexhe, 2009) read :

$$\begin{cases} T \frac{\partial \nu_{\mu}}{\partial t} = (\mathcal{F}_{\mu} - \nu_{\mu}) + \frac{1}{2} c_{\lambda \eta} \frac{\partial^{2} \mathcal{F}_{\mu}}{\partial \nu_{\lambda} \partial \nu_{\eta}} \\ T \frac{\partial c_{\lambda \eta}}{\partial t} = A_{\lambda \eta} + (\mathcal{F}_{\lambda} - \nu_{\lambda}) (\mathcal{F}_{\eta} - \nu_{\eta}) + \\ c_{\lambda \mu} \frac{\partial \mathcal{F}_{\mu}}{\partial \nu_{\lambda}} + c_{\mu \eta} \frac{\partial \mathcal{F}_{\mu}}{\partial \nu_{\eta}} - 2c_{\lambda \eta} \end{cases}$$

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Entangles firing rates and time dependent pairwise correlations

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$$\textbf{AffOrdS}_{c_{\lambda\mu}}^{\mu} = (\mathcal{F}_{\mu} - \nu_{\mu}) + \frac{1}{2} c_{\lambda\eta} \frac{\partial^{2} \mathcal{F}_{\mu}}{\partial \nu_{\lambda} \partial \nu_{\eta}}$$

$$\textbf{AffOrdS}_{c_{\lambda\mu}}^{\lambda\eta} = A^{\lambda\eta} + (\mathcal{F}_{r} - \nu_{r}) + D^{\mu}_{r} - 2c_{\lambda\eta}$$

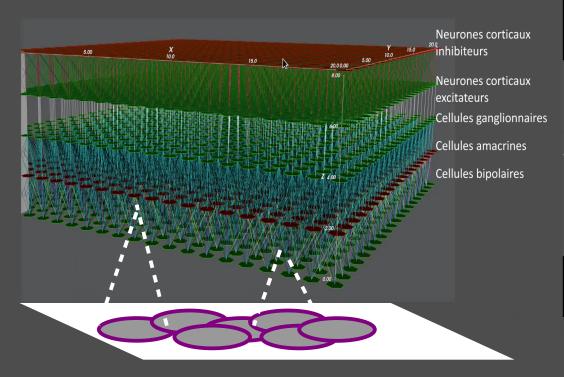
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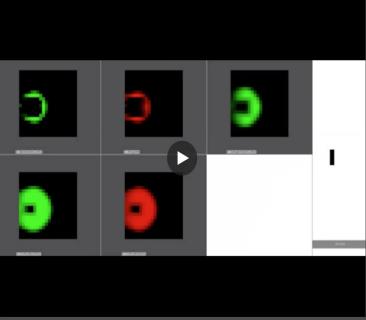
A retino-cortical model

Logiciel Macular

Modèle rétino-cortical de Macular



Simulation du modèle de Macular



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- This leads to a paradigm very different from the « **efficient coding** » paradigm where longitudinal pathways are assumed to be independent. We switch from a paradigm of « rate » decoding to **« correlations » decoding**.

Thanks