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Efficient Renaming in Sequence CRDTs

Matthieu Nicolas, Gérald Oster and Olivier Perrin

Abstract—To achieve high availability, large-scale distributed systems have to replicate data and to minimise coordination between nodes. For these purposes, literature and industry increasingly adopt Conflict-free Replicated Data Types (CRDTs) to design such systems. CRDTs are new specifications of existing data types, e.g. Set or Sequence. While CRDTs have the same behaviour as previous specifications in sequential executions, they actually shine in distributed settings as they natively support concurrent updates. To this end, CRDTs embed in their specification conflict resolution mechanisms. These mechanisms usually rely on identifiers attached to elements of the data structure to resolve conflicts in a deterministic and coordination-free manner. Identifiers have to comply with several constraints, such as being unique or belonging to a dense total order. These constraints may hinder the identifier size from being bounded. Identifiers hence tend to grow as the system progresses, which increases the overhead of CRDTs over time and leads to performance issues. To address this issue, we propose a novel Sequence CRDT which embeds a renaming mechanism. It enables nodes to reassign shorter identifiers to elements in an uncoordinated manner. Experimental results demonstrate that this mechanism decreases the overhead of the replicated data structure and eventually minimises it.

Index Terms—CRDTs, replication, real-time collaborative editing, eventual consistency, memory-wise optimisation, performance.

1 INTRODUCTION

W hen creating distributed systems, designers have to make a trade-off between consistency and latency [1]. Many systems choose to favour latency and thus adopt optimistic replication techniques [2]. This approach ensures the high availability of the system, even in case of network partitions. To this end, it relaxes consistency constraints and minimises coordination between nodes. In this approach, every node owns a copy of the data, can modify it and then propagate updates to others. Replicas are thus allowed to temporarily diverge. To ensure that they eventually reach equivalent states despite concurrently generated updates, a conflict resolution mechanism is required.

Several approaches were introduced to design efficient conflict resolution mechanisms. We propose to use Conflict-free Replicated Data Types (CRDTs) [3]. CRDTs are new specifications of abstract data types, e.g. Set or Sequence. From users’ perspective, CRDTs share the same semantics and interfaces as non-replicated specifications. However, the particularity of CRDTs is that they are designed to natively support concurrent modifications. CRDTs thus have the same behavior as previous specifications in sequential executions, but also define additional semantics for scenarios that may occur in distributed executions.

CRDTs embed a conflict resolution mechanism directly in their specification. It enables them to respect the Strong Eventual Consistency (SEC) model [3]. This consistency model defines that replicas reach equivalent states as soon as they observe the same set of updates, without any further communications required and in spite of possible different reception orders. This property makes CRDTs particularly suitable for the design of highly available large-scale distributed systems.

CRDTs have been widely adopted by literature and industry since their conceptualisation. CRDTs corresponding to more powerful data types were designed and made available as libraries to developers [4], [5], [6], [7]; distributed data stores relying on CRDTs were released [8], [9], [10], [11]; and a new paradigm of applications using CRDTs as their keystone technology has been specified: Local-First Softwares [12], [13].

Additionally, CRDTs have become an important research topic in the domain of real-time collaborative editing. Real-time collaborative editors allow users to share and edit text documents, often represented as Sequences. The design of such applications faces many challenges. It requires the definition of correct and efficient conflict resolution mechanisms that preserve users’ intention [14]. Collaborative systems must guarantee privacy and be resilient to censorship. Recent work [15], [16], [17] has demonstrated the relevance of Sequence CRDTs to address these issues, notably thanks to their compatibility with peer-to-peer approaches.

Still, Sequence CRDTs exhibit some limitations. In particular, Sequence CRDTs suffer from the accumulation of large amount of metadata over time due to their internal conflict resolution mechanisms. While the ever-growing metadata decreases the memory efficiency of these data structures, it also increases their bandwidth consumption and computational overhead. Some previous work proposed renaming mechanisms [18], [19] to reduce periodically this overhead. However, these mechanisms require synchronous coordination.

In this work, we propose a new Sequence CRDT: RenamableLogSplit (RLS). This data structure allows nodes to insert or remove elements into a replicated sequence. It embeds a renaming mechanism to periodically minimise the memory overhead induced by metadata. To avoid costly and blocking consensus algorithms, we instead adopt an optimistic approach: nodes perform renaming without any coordination. This new feature is designed as an additional type of operation: the rename one. Since this operation is not intrinsically commutative with others, conflicts may arise. Therefore, we use Operational Transfor-
To deterministically solve conflicts and ensure convergence of all nodes, CRDTs rely on metadata. In the context of Sequence CRDTs, two different approaches were proposed, both trying to minimise the overhead introduced. The first one [15], [22], [23], [24], [25] attaches fixed size identifiers to each element in the sequence and uses them to represent the sequence as a linked list. The downside of this approach is an ever-growing overhead, as it needs to keep removed elements to deal with potential concurrent updates, effectively turning them into tombstones. The second one [26], [27], [28], [29], [30], [31] avoids the need of tombstones by attaching identifiers from a dense total order to elements. Elements are ordered into the sequence by comparing their respective identifiers. A new element can always be inserted in between with a proper identifier according to the dense order. However this approach suffers from an ever-increasing overhead, as the size of such identifiers is unbounded and grows over time.

Despite several comparisons [15], [25], [31], literature has provided no decisive evidence of the superiority of one approach on the other, but simply trade-offs. The tombstone approach offers a smaller network footprint since its identifiers are of fixed size, while the variable-size identifiers approach offers a better latency since updates can be delivered out of order. In this paper, we focus on the variable-size identifiers approach and more specifically on the LogootSplit algorithm. The general idea of the presented work is not specific to any technical aspects of this approach. As so, it might be applied on the other approach with some additional research work.

### 2.1 LogootSplit

LogootSplit (LS) [29] is the state of the art of the variable-size identifiers approach of Sequence CRDT. As explained previously, it uses identifiers from a dense total order to position elements into the replicated sequence.

To this end, LogootSplit assigns identifiers made of a list of tuples to elements. These tuples have four components: (i) a position, which embodies the intended position of the element (ii) a node identifier (iii) a node sequence number and (iv) an offset, which are combined to make identifiers unique. By comparing identifiers using the lexicographical order, LogootSplit is able to determine the position of the element relatively to others. In this paper, we represent identifiers using the following notation: \( \text{position}_\text{node_id} \text{node_seq} \) where position is a lowercase letter, node_id an uppercase one and both node_seq and offset integers.

Instead of storing an identifier for each element of the sequence, the main insight of LogootSplit is to dynamically aggregate elements into blocks. Grouping elements into blocks enables LogootSplit to logically assign an identifier to each element, using intervals of identifiers, while effectively storing only the block length and the identifier of its first element. LogootSplit gathers elements with contiguous identifiers into a block. We call contiguous two identifiers that are identical except for their last offset, and with both offsets being consecutive. We denote the interval of identifiers corresponding to a block using the following notation: \( \text{position}_{\text{begin..end}} \) where begin is the offset of the first identifier of the block and end the offset of its last identifier.

Figure 1 illustrates such a case: in Figure 1a, the element identifiers \( i^0_0, i^0_1, i^0_2 \) form a chain of contiguous identifiers. LogootSplit is then able to group them into one block \( i^0_0.i^0_2 \) to minimise the metadata stored, as shown in Figure 1b.

![Fig. 1: Representation of a LogootSplit sequence containing the elements "HLO"](image)

This feature reduces the number of identifiers stored in the data structure, since identifiers are kept at the level of blocks rather than on every individual element. It enables to significantly reduce the memory overhead of the data structure.

### 2.2 Limits

As previously stated, the size of identifiers from a dense total order is variable. When nodes insert new elements between two others with the same position value, LogootSplit has no other option but to increase the size of the resulting identifiers. Figure 2 illustrates such cases. In this example, since node A inserts a new element between the contiguous identifiers \( i^0_0 \) and \( i^0_2 \), LogootSplit cannot generate a proper identifier of the same size. To comply with the intended order, LogootSplit generates a new identifier by appending a new tuple to the identifier of the predecessor: \( i^0_0 f A^0 \). As a result, the size of identifiers tends to grow as the system progresses. This growth reduces the performance of the data structure on several aspects. Since identifiers attached to values become longer, the memory overhead of the data structure increases accordingly. This also increases
the bandwidth consumption as nodes have to broadcast identifiers to others.

Additionally, during the lifetime of the replicated sequence, the number of blocks increases. Indeed, several constraints on identifier generation prevent nodes from adding new elements to existing blocks. For example, only the node that generated the block can append elements to it. These limitations cause the generation of new blocks. The sequence ends up fragmented into many blocks of only few characters each. However no mechanism to merge blocks a posteriori is provided. The efficiency of the data structure hence decreases as each block introduces its own overhead.

As shown later in Section 7, we measured that content eventually represents less than 1% of the whole data structure size. Remaining 99% of the data structure hence correspond to metadata. It is thus necessary to address the previously highlighted issues.

3 Overview

We propose a new Sequence CRDT belonging to the variable-size identifiers approach: RenamableLogootSplit [32], [33]. This data structure allows nodes to insert or remove elements into a replicated sequence. We introduce a rename operation to reassign shorter identifiers to elements and to group them into blocks to minimise the memory overhead of the whole sequence.

3.1 System Model

The system is composed of a dynamic set of nodes, as nodes dynamically join and leave the collaboration during its lifetime. Nodes collaborate to build and maintain a sequence using RenamableLogootSplit. Each node owns a copy of the sequence and edits it without any coordination. Nodes’ updates take the form of operations that are immediately applied to nodes’ replicas. Operations are then asynchronously broadcast to other nodes so that they also integrate updates.

Nodes communicate through a Peer-to-Peer (P2P) network, which is unreliable. Messages can be lost, re-ordered or delivered multiple times. The network is also vulnerable to partitions, which split nodes into disjoined subgroups. To overcome failures of the network, nodes rely on a message-passing layer. As RenamableLogootSplit is built on top of LogootSplit, it shares the same requirements for the operation delivery. This layer is thus used to deliver messages to the application exactly-once. The layer also ensures that remove operations are delivered after corresponding insert operations. No other constraints exist on the delivery order of operations. Nodes use an anti-entropy mechanism [34] to synchronise in a pairwise manner, by detecting and re-exchanging lost operations.

3.2 Definition of the rename operation

The purpose of the rename operation is to reassign new identifiers to elements of the replicated sequence without altering its content. Since identifiers are metadata used by the data structure solely for conflict resolution, users are unaware of their existence. Rename operations are thus system operations: they are issued and applied by nodes behind the scenes, without any user initiative.

In order to ensure the SEC property of the replicated sequence, we define several safety properties that the rename operation must respect. These properties are mainly inspired by those presented in [19].

Property 1. (Determinism) Rename operations are applied by each node without any coordination. To ensure that each node eventually reaches the same state, a given rename operation must always output the same new identifier from the current identifier.

Property 2. (User-intention Preservation) Although the rename operations itself has no user intention attached, it must not conflict with users actions. Notably, rename operations must not cancel or alter the outcome, from users’ points of view, of insert and remove operations.

Property 3. (Well-formed Sequence) The replicated sequence must be well-formed. Applying a rename operation to a well-formed sequence must then output a well-formed sequence. A well-formed sequence ensures the following properties:

Property 3.1. (Uniqueness Preservation) Each identifier must be unique. Thus, for a given rename operation, each identifier should be mapped to a distinct new identifier.

Property 3.2. (Order Preservation) The elements of the sequence must be sorted according to their identifiers. Therefore, the existing order between initial identifiers must be preserved by the rename operation.

Property 4. (Commutativity with Concurrent Operations) Concurrent operations may be delivered in different orders to each node. To ensure convergence of replicas, the order of application of a set of concurrent operations should not have any impact on the resulting state. The rename operation must then be commutative with any other concurrent operation.

Property 4 is particularly difficult to achieve. This is due to the fact that rename operations modify identifiers assigned to elements. However, other operations such as insert and remove ones rely on these identifiers to specify where to insert elements or which ones to remove. Rename operations are thus intrinsically incompatible with concurrent insert and remove ones. Likewise, concurrent rename operations may reassign different identifiers to given elements. Concurrent rename operations are hence not commutative. Therefore, it is required to design and use conflict resolution strategies to achieve Property 4.

For the sake of simplicity, the presentation of the rename operation is divided into two parts. In Section 4, we present the proposed rename operation under the assumption that no concurrent rename operations may be issued. This assumption enables us to focus on the inner working of the
rename operation and on how to deal with concurrent insert and remove operations. Then, in Section 5, we remove this assumption and present our approach to handle scenarios with concurrent rename operations.

4 RenamableLogootSplit without concurrent rename operations

4.1 Proposed rename operation

Our rename operation enables RenamableLogootSplit to reduce the overhead of nodes replica. To do so, it reassigns arbitrary identifiers to elements. Its behaviour is illustrated in Figure 3.

![Diagram](image)

(a) Selecting the new identifier of the first element

(b) Selecting the new identifiers of the remaining ones

(c) Final state obtained

Fig. 3: Renaming the sequence on node A

In this example, node A initiates a rename operation on its local state. First, node A reuses the id of the first element of the sequence ($i_0^{B0}$) but modifies it with its own node id (A) and current sequence number (1). Also the offset is set to 0. Node A reassigns the resulting id ($i_0^{A1}$) to the first element of the sequence as described in Figure 3a. Then, node A derives contiguous identifiers for all remaining elements by successively incrementing the offset ($i_1^{A1}$, $i_2^{A1}$ and $i_3^{A1}$), as shown in Figure 3b. As we assign contiguous identifiers to all elements of the sequence, we eventually group them into one block as illustrated in Figure 3c. It allows nodes to benefit the most from the block feature and to minimise the overhead of the resulting state. Proceeding this way also enables us to assign an unique triplet (node id, seq, offset) to every identifier, thus ensuring their uniqueness as required by Property 3.1.

To converge, other nodes have to rename their states identically. However, they cannot simply replace their current state with the new renamed one. Indeed, they may have performed concurrent updates on their states. In order not to discard these updates (with regard to Property 2 and Property 4), nodes have to process the rename operation themselves. However, the applied renaming depends on the state' – called former state – of the node when the rename operation was generated. Other nodes need this information to compute the new renamed identifiers. The rename operation thus embeds the former state to propagate it.

4.2 Dealing with concurrent updates

After applying rename operations on their local states, nodes may receive concurrent updates. Figure 4 illustrates such cases. In this example node B inserts the new element “L”, assigns the id $i_0^{B0} m_0^{B1}$ to it and broadcasts its update, concurrently to the rename operation described in Figure 3. Upon reception of the insert operation, node A adds the inserted element into its sequence, using the element id to determine its position. However, since identifiers were modified by the concurrent rename operation, node A inserts the new element at the end of its sequence (since $i_3^{A1} < i_0^{B0} m_0^{B1}$) instead of at the intended position. As described by this example, naively applying concurrent updates would result in inconsistencies and conflict with Property 2. It is thus necessary to handle concurrent operations to rename operations in a particular manner.

First, nodes have to detect concurrent operations to rename ones. To this end, we use an epoch-based system. Initially, the replicated sequence starts at the origin epoch noted $\varepsilon_0$. Each rename operation introduces a new epoch and enables nodes to advance their states to it from the previous epoch. The generated epoch is characterised using the node id and its current sequence number upon the generation of the rename operation. For example, the rename operation described in Figure 4 enables nodes to advance their states from $\varepsilon_0$ to $\varepsilon_{A1}$.

As they receive rename operations, nodes build and maintain the epoch chain, a data structure ordering epochs according to their parent-child relation. Additionally, nodes tag every operation with their current epoch at the time the operation is generated. Upon the reception of an operation, nodes compare the operation epoch to their current one. If they differ, nodes have to transform the operation before applying it. Nodes determine against which rename operations to transform the received operation by computing the path between the operation epoch and their current one using the epoch chain. For this purpose, it is required to add the following rule to existing constraints upon the delivery of operations: operations must now be delivered after the rename operation which introduced their epoch.

Nodes use the function RENAMEID, described in Algorithm 1, to transform insert or remove operations against rename ones. This algorithm maps identifiers from a parent epoch to corresponding ones in the child epoch. The main idea of this algorithm is to deterministically rename unknown identifiers at the time of the rename operation generation using their predecessor. An example is provided in Figure 5. This figure depicts the same scenario as in Figure 4, except that node A uses RENAMEID to rename the concurrently generated id before inserting it in its state.

The algorithm proceeds as follows. First, node A retrieves the predecessor of the given id $i_0^{B0} m_0^{B1}$ in the former state: $i_0^{B0} f_0^{A0}$. Then it computes the counterpart of $i_0^{B0} f_0^{A0}$ in the renamed state: $i_0^{A1}$. Finally, node A prepends it to the given id to generate the renamed id: $i_0^{T1} i_0^{A1} m_0^{B1}$. By reassigning this id to the concurrently added element, node
A is able to insert it in its state while preserving the intended order.

```plaintext
function RENAMEId(id, renamedIds, nId, nSeq)
    length ← renamedIds.length
    firstId ← renamedIds[0]
    lastId ← renamedIds[length - 1]
    pos ← position(firstId)
    if id < firstId then
        newFirstId ← new Id(pos, nId, nSeq, 0)
        return renIdLessThanFirstId(id, newFirstId)
    else if id ∈ renamedIds then
        index ← findIndex(id, renamedIds)
        return new Id(pos, nId, nSeq, index)
    else if lastId < id then
        newLastId ← new Id(pos, nId, nSeq, length - 1)
        return renIdGreaterThanLastId(id, newLastId)
    else
        return renIdFromPredId(id, renamedIds, pos, nId, nSeq)
    end if
end function
```

**Algorithm 1**: Main functions to rename an identifier

RENAMEID also enables nodes to handle the opposite case: to integrate remote rename operations on their local states while they have previously concurrent update. This case corresponds to node B's one in Figure 5. Upon the delivery of node A's rename operation, applying RENAMEID to every identifier of its state would enable node B to reach an equivalent state to node A's one. RENAMEID thus makes rename operations commutative with insert and remove ones.

Note that nodes rely on the former state – called here renamedIds – to apply RENAMEID. As such, nodes have to store it to be able to transform concurrent operations. The identifiers composing the former state are hence tombstones. But unlike those of the tombstone approach, these tombstones are not kept directly in the sequence but in the node of the epoch chain. They have thus no impact on integration times of future operations. Additionally, we present a mechanism to garbage collect them in Section 6.

Algorithm 1 features only the main case of RENAMEID, i.e. when the identifier to rename is in the range of renamed identifiers (firstId ≤ id ≤ lastId). Functions to deal with other cases, i.e. when the identifier to rename is out of the range of renamed identifiers (id < firstId or lastId < id), are presented in Appendix B.

The algorithm we present here enables nodes to rename their states identifier by identifier. A possible extension is to design RENAMEBLOCK, an improved version that renames the state block by block. RENAMEBLOCK would reduce the integration times of rename operations, since its time complexity would no longer depend on the number of identifiers (i.e. the number of elements) but on the number of blocks. Additionally, its execution would reduce the integration time of the next rename operation since the renaming mechanism merges existing blocks into one.

### 5 RenamableLogSplit with Concurrent rename Operations

To prevent the generation of concurrent rename operations, nodes must achieve a consensus. However, consensus protocols suffer from their poor scalability and cost. To address these issues, previous work [18], [19] proposed to limit the number of nodes involved in the consensus. This responsibility is therefore assigned to a selected small set of stable and well-connected nodes. In contrast, our goal is to design a solution suitable for distributed systems whose nodes are equal in rights and duties. We therefore choose to handle concurrent rename operations and present a corresponding coordination-free conflict resolution mechanism.

#### 5.1 Concurrent rename operations

We now consider scenarios with concurrent rename operations. Figure 6 expands the scenario previously described in Figure 5.

After broadcasting its insert operation, node B performs a rename operation on its state. This operation reassigns new identifiers to every element based on the id of the first element of the sequence $(i^B_0)$, its node id (B) and current sequence number (2). This operation also introduces a new epoch: $\varepsilon_{B2}$. Since node A's rename operation was not yet delivered to node B at that moment, both rename operations are concurrent.

As concurrent epochs are generated, epochs now form the epoch tree. We represent in Figure 7 the epoch tree that nodes obtain once they eventually synchronize. Epochs are displayed as nodes of the tree and the parent-child relation between them displayed as black arrows.

![Fig. 4: Concurrent update leading to inconsistency](image-url)
As the target epoch. In order to avoid performance issues due to coordination, nodes should select this epoch in a coordination-free manner, i.e., solely using data from the epoch tree. We propose such a mechanism in Section 5.2.

At the end of the scenario described in Figure 6, nodes A and B are at epochs $\varepsilon_A^1$ and $\varepsilon_B^1$ respectively. In order to converge, every node should eventually reach the same epoch. However, the function RENAMEID described in Algorithm 1 only enables nodes to move from a parent epoch to one of its children epoch. Node A (resp. B) is then unable to progress towards the epoch of node B (resp. A). It is therefore necessary to extend our renaming mechanism to break this deadlock and to make rename operations commutative.

First, nodes have to agree on a common epoch from the epoch tree as the target epoch. In order to avoid performance issues due to coordination, nodes should select this epoch in a coordination-free manner, i.e., solely using data from the epoch tree. We propose such a mechanism in Section 5.2.

Second, nodes have to move through the epoch tree to reach the target epoch. The function RENAMEID already enables nodes to move down the tree. Remaining cases to be handled are the ones in which nodes currently are on another branch of the epoch tree. In these cases, nodes have to be able to move up the epoch tree to return to the Lowest Common Ancestor (LCA) of the current epoch and the target one. This move is actually akin to reverting the effect of previously applied rename operations. We propose an algorithm that fulfills this purpose in Section 5.3.

5.2 Breaking tie between concurrent rename operations

To enable every node to select the same target epoch in a coordination-free manner, we define the priority relation.

**Definition 1 (Priority relation).** The priority relation is a strict total order on the set of epochs. It enables nodes to compare any pair of epochs.

Using the priority relation, we define the target epoch as follows:

**Definition 2 (Target epoch).** The epoch from the set of epochs towards which nodes should progress. Nodes select the maximum epoch according to the priority relation as the target epoch.

To define the priority relation, we can actually select different strategies. In this work, we use the lexicographical order on the path of epochs in the epoch tree. Figure 8 provides an example.

Figure 8a describes an execution in which the three nodes A, B and C issue several operations before eventually synchronising. As solely rename operations are relevant to the problem at hand, only them are represented in this figure. Initially, node A issues a rename operation introducing the epoch $\varepsilon_A^1$. This operation is delivered to node C, which later issues its own rename operation creating $\varepsilon_B^1$. Concurrently to these operations, node B issues two rename operations, generating $\varepsilon_B^2$ then $\varepsilon_B^3$. 

Fig. 7: The epoch tree corresponding to the scenario of Figure 6
Once nodes synchronised, they obtain the epoch tree represented in Figure 8b. In this figure, the red dashed arrow represents the order between epochs according to the priority relation while the selected target epoch is displayed as a red node.

To determine the target epoch, nodes rely on the priority relation. According to the lexicographical order on the path of epochs in the epoch tree, \( \varepsilon_0 < \varepsilon_0\varepsilon_{A1} < \varepsilon_0\varepsilon_{A1}\varepsilon_{C6} < \varepsilon_0\varepsilon_{B2} < \varepsilon_0\varepsilon_{B2}\varepsilon_{B7} \). Therefore every node selects \( \varepsilon_{B7} \) as the target epoch in a coordination-free manner.

Other strategies could be proposed to define the priority relation. For example, priority could rely on metrics embedded in rename operations representing the accumulated work on the document. It would enable favouring the branch from the epoch tree with the more and more active collaborators to minimise the overall amount of computations performed by nodes of the system.

### 5.3 Reverting rename operations

We now extend the scenario described in Figure 6. In Figure 9, node A receives node B’s rename operation, which is concurrent to the rename operation node A previously applied. According to the proposed priority relation, node A determines the introduced epoch \( \varepsilon_{B2} \) as the target one. Therefore, it should revert its state to an equivalent one at \( \varepsilon_0 \), the LCA of its current epoch \( \varepsilon_{A1} \) and the target epoch \( \varepsilon_{B2} \). Hence, we need to consider a mechanism enabling nodes to revert a previously applied rename operation.

This is precisely the objective of \texttt{REVERTRENAMEID}, which maps identifiers from the child epoch to equivalent ones in its parent epoch. The function is described in Alg 2.

The goals of \texttt{REVERTRENAMEID} are the following: (i) To revert identifiers generated causally before the reverted rename operation to their former value (ii) To revert identifiers generated concurrently to the reverted rename operation to their former value (iii) To assign new identifiers complying with the intended order to elements inserted causally after the reverted rename operation.

The first subcase is when we have \( \text{tail} \in [\text{predId}, \text{succId}] \). In this context, \( \text{newId} \) may be the result of a concurrent insert operation to the rename one (i.e. Case (i)). We have \( \text{newId} \in [\text{newPredId predId}, \text{newPredId succId}] \). In such case, \( \text{newId} \) has been obtained using \texttt{RENAMEFROMPREDDID} and we have \( \text{id} = \text{tail} \). We thus note that by returning \( \text{tail} \), \texttt{REVERTRENAMEID} meets the two constraints, i.e. preserving the intended order and restoring to its original value the identifier.

The second subcase is when \( \text{tail} \in \text{predId } \text{newId} \) could only been inserted causally after the rename

2. We name \( \text{newX} \) identifiers in the resulting epoch of the rename operation, while \( X \) refer to their counterpart in the preceding epoch.
operation (i.e. Case (iii)), and we have $newId \in [newPredId, newPredId, predId]$. Since $newId$ has been inserted after the $rename$ operation, there is no existing constraint on the returned identifier except the Property 3.2. To handle this case, we introduce two new tuples exclusive to the renaming mechanism: $MIN\_TUPLE$ and $MAX\_TUPLE$. They are respectively the minimal tuple and the maximal one available to generate identifiers. Thanks to $MIN\_TUPLE$, $REVERT\_RENAMOID$ is able to return $id$ fitting the intended order (with $id = predId\_MIN\_TUPLE\_tail$).

The last subcase is the counterpart of the previous subcase and occurs when $succId < tail$. We have $newId \in [newPredId, succId, newSuccId]$. The strategy is the same and consists in adding a prefix to enforce the intended order. To generate this prefix, $REVERT\_RENAMOID$ uses $predOfSuccId$ and $MAX\_TUPLE$. $predOfSuccId$ is obtained by decrementing the last offset of $succId$. Hence, to preserve the intended order, $REVERT\_RENAMOID$ returns $id$ with $id = predOfSuccId\_MAX\_TUPLE\_tail$.

Once node $A$ mapped its state to the equivalent one at $\varepsilon_0$ using $REVERT\_RENAMOID$, it can now apply $RENAMOID$ to compute the corresponding state at $\varepsilon_B$.

As with Algorithm 1, Algorithm 2 only features the main case of $REVERT\_RENAMOID$. It corresponds to the case where the identifier to revert is in the range of renamed identifiers ($newFirstId \leq id \leq newLastId$). Functions to handle remaining cases are featured in Appendix C.

Note that $RENAMOID$ and $REVERT\_RENAMOID$ are not inverse functions. $REVERT\_RENAMOID$ reverts to their original value identifiers inserted causally before or concurrently to the $rename$ operation. On the other hand, $RENAMOID$ does not do the same for identifiers inserted causally after the $rename$ operation. Thus redoing a previously undone $rename$ operation alters these identifiers. This modification can cause a divergence between nodes, as the same element will be referred to using different identifiers.

This issue is however prevented in our system by the proposed $priority$ relation. Since the $priority$ relation is defined using the lexicographical order on the path of epochs in the epoch tree, nodes only move towards the rightmost epoch of the epoch tree when switching epochs. Nodes thus avoid going back and forth between different epochs and undoing then redoing corresponding $rename$ operations.

6 GARBAGE COLLECTION OF FORMER STATES

Nodes store epochs and corresponding former states to transform identifiers through different epochs. But as the system progresses, some epochs and associated metadata become unnecessary since no more operations are issued from these epochs. Nodes can then garbage collect these epochs. In this section, we present a mechanism enabling nodes to identify obsolete epochs.

To propose such a mechanism, we rely on the notion of causal stability of operations [35]. An operation is causally stable once it was delivered to every node. In the context of a $rename$ operation, it implies that every node progressed to the epoch introduced by this operation or to a greater one according to the $priority$ relation. Using this knowledge, nodes determine the potential current epochs:

Definition 3 (Potential current epochs). The set of epochs on which nodes may currently be and from which they could issue operations, according to a node’s own knowledge. It is a subset of the set of epochs, made of the maximum epoch introduced by a causally stable $rename$ operation and of every epoch that is greater according to the $priority$ relation.

To handle next operations, nodes have to maintain the paths between every epoch of potential current epochs. We denote as required epochs the corresponding set of epochs:

Definition 4 (Required epochs). The set of epochs that a node has to maintain to handle potential next operations. It is the set of epochs that form the paths between every potential current epochs and their LCA.

It follows that any epoch that does not belong to the set of required epochs can be garbage collected by nodes. Figure 10 illustrates a use case of the proposed garbage collection mechanism.

In Figure 10a, we represent an execution in which two nodes $A$ and $B$ respectively issue several $rename$ operations. In Figure 10b, we represent nodes’ respective epoch trees. Epochs introduced by causally stable $rename$ operations are displayed using double circles. The set of potential current epochs is shown as a dashed black rectangle while the set of required epochs is represented as a dotted green rectangle.

Node $A$ first generates a $rename$ operation to $\varepsilon_{A1}$ and later a $rename$ operation to $\varepsilon_{A8}$. It thereafter receives from node $B$ a $rename$ operation that introduces $\varepsilon_{B2}$. Since $\varepsilon_{B2}$ is greater than its current epoch ($\varepsilon_{0} \varepsilon_{A1} \varepsilon_{A8} \varepsilon_{B2}$), node $A$ selects it as its new current epoch and proceeds to $rename$
It then receives from node A the this, nodes B derives that these epochs and their LCA determines the LCA of A then proceeds to compute epochs and nodes can now only issue operations from these ε operation to priority From this point, node A knows that every node progressed introducing a causally stable rename to its state accordingly. Finally, node A issues a third rename operation to εA9. Concurrently, node B issues the rename operation to εB2. It then receives from node A the rename operation to εA1. However, node B keeps εB2 as its current epoch (since ε0εA1 < ε0εB2). Afterwards, node B issues another rename operation to εB7.

Upon the delivery of the rename operation introducing epoch εB2 to node A, this operation becomes causally stable. From this point, node A knows that every node progressed to this epoch or a greater one according to the priority relation. Epochs εB2 and εA9 form the set of potential current epochs and nodes can now only issue operations from these epochs or one of their not yet known descendants. Node A then proceeds to compute required epochs. To this end, it determines the LCA of potential current epochs : εB2. It then generates required epochs by adding every epoch forming the paths between εB2 and potential current epochs. Epochs εB2 and εA9 thus form the set of required epochs. Node A infers that epochs ε0, εA1 and εA8 can safely be garbage collected.

On the other hand, the delivery of the rename operation introducing εA1 to node B does not enable it to garbage collect any data. From its knowledge, node B computes that εA1, εB2 and εB7 form the potential current epochs. From this, nodes B derives that these epochs and their LCA ε0 constitute required epochs. Every known epoch thus belong to the set of required epochs, preventing their garbage collection.

Eventually, once the system becomes idle, nodes reach the same epoch and the corresponding rename operation becomes causally stable. Nodes can then garbage collect all other epochs and associated metadata, effectively suppressing the overhead of the renaming mechanism.

Note that the garbage collection mechanism can be simplified in systems preventing concurrent rename operations. Since epochs form a chain in such systems, the latest epoch introduced by a causally stable rename operation becomes the LCA of potential current epochs. It follows that this epoch and its descendants constitute the required epochs, and that its ancestors may be garbage collected. Nodes thus only need to track causally stable rename operations to determine which epochs to garbage collect in systems without concurrent rename operations.

To determine that a given rename operation is causally stable, nodes have to be aware of others and of their progress. A group membership protocol such as [36], [37] is thus required.

Causal stability may take some time to be achieved. Meanwhile, nodes can actually offload former states onto the disk since they are only required to handle concurrent operations to rename ones. We discuss this topic further in Section 8.2.

7 Evaluation

In order to validate the proposed approach, we proceed to an experimental evaluation. The aims of this evaluation are to measure (i) the memory overhead of the replicated sequence (ii) the computational overhead added to insert and remove operations by the renaming mechanism (iii) the cost of integrating rename operations.

Our evaluation focuses on the comparison between the performance of RenamableLogootSplit and LogootSplit for the following reasons. First, it highlights the impact of the renaming mechanism on the performance of the replicated sequence. Second, other Sequence CRDTs [24], [25], [31] suffer from similar drawbacks as LogootSplit (tombstones, fragmentation into blocks of a few elements, ever-growing identifiers). Thus, the mechanism proposed for LogootSplit could offer the same advantages to these approaches. Since we are interested in the impact of the renaming mechanism, the baseline Sequence CRDT used is of little importance. Third, since the main difference between Renamable-LogootSplit and consensus protocol-based approaches lies in their respective system model (i.e. systems with equal nodes versus systems with privileged nodes), we do not compare them experimentally. Instead, we compare them in the form of a discussion in Section 9.1.

7.1 Simulations and benchmarks

By means of simulations, we generated the dataset used to run our benchmarks. These simulations mimic the following scenario.

Several authors collaboratively write an article in real-time. First of all, the authors mainly specify the content of the article. Few remove operations are issued in order to simulate spelling mistakes. Once the document reaches an arbitrary given critical length, collaborators move on to the second phase of the simulation. During this phase, authors stop adding new content but instead focus on revamping existing parts. This is simulated by balancing the ratio between insert and remove operations. Every author has to issue a given number of insert and remove operations. The simulation ends once every collaborators received all operations. During the simulation, we take snapshots of the replicas’ state at given steps to follow their evolution.

We ran simulations with the following experimental settings: we deployed 10 bots as separate Docker containers on
a single workstation. Each container corresponds to a single mono-threaded Node.js process simulating an author. Bots share and collaboratively edit the document using either LogootSplit or RenamableLogootSplit according to the session. In both cases, each bot locally performs an insert or a remove operation every 200 ± 50ms and immediately broadcasts it to other nodes using a P2P full mesh network. During the first phase, the probability of issuing insert (resp. remove) operations is of 80% (resp. 20%). Once the document reaches 60k characters (around 15 pages), bots switch to the second phase and set both probabilities to 50%. After each local operation, the bot may move its cursor to another random position in the document with a probability of 5%. Every bot generates 15k insert or remove operations and stops once it observed 150k operations. Snapshots of the state of bot are taken periodically every 10k observed operations.

Additionally, in the case of RenamableLogootSplit, 1 to 4 bots are arbitrarily designated as renaming bots according to the session. Renaming bots issue rename operations every time they observe 30k operations overall. These rename operations are generated in a way ensuring that they are concurrent.

For the purpose of reproducibility, we make the code, benchmarks and results available at: https://github.com/coast-team/mute-bot-random/.

### 7.2 Results

Using generated snapshots, we performed several benchmarks. These benchmarks evaluate RenamableLogootSplit’s performance and compare it to LogootSplit’s ones. Results are presented and analysed below.

**Convergence** We first proceeded to verify the convergence of nodes states at the end of simulations. For each simulation, we compared the final state of every node using their respective snapshots. We were able to confirm that nodes converged without any communication other than operations, thus satisfying the SEC consistency model.

This result sets a first milestone in the validation of the correctness of RenamableLogootSplit. It is however only empirical. Further work to formally prove its correctness should be undertaken.

**Memory overhead** We then proceeded to measure the evolution of the document’s memory consumption throughout the simulations, according to the CRDT used and the number of renaming bots. We present the obtained results in Figure 11.

For each plot displayed in Figure 11, we represent 4 different data. The blue dashed line illustrates the size of the actual content of the document, i.e. the text, while the red solid line corresponds to the size of the whole LogootSplit document.

The green dashed-dotted line represents the size of the RenamableLogootSplit document in the best case scenario. In this scenario, nodes assume that rename operations are garbage-collectable as soon as they receive them. Nodes are thus able to benefit the effects of the renaming mechanism while removing its own metadata, such as former states and epochs. In doing so, nodes are able to periodically minimise the metadata overhead of the data structure, independently of the number of renaming bots and concurrent rename operations issued.

On the other hand, the orange dotted line represents the size of the RenamableLogootSplit document in the worst case scenario. In this scenario, nodes assume that rename operations never become causally stable and can thus never be garbage-collected. Nodes have to permanently store the metadata introduced by the renaming mechanism. The performance of RenamableLogootSplit thus decreases as the number of renaming bots and rename operations issued increases. Nonetheless, we observe that RenamableLogootSplit can outperform LogootSplit even in this worst case scenario while the number of renaming bots remains low (1 or 2). This result is explained by the fact that the renaming mechanism enables nodes to scrap the overhead of the internal data structure used to represent the document.

To summarise the results presented, the renaming mechanism introduces a temporary metadata overhead which increases with each rename operations. But the overhead will eventually subsides once the system becomes quiescent and rename operations become causally stable. In Section 8.2, we discuss that former states may be offloaded until causal stability is achieved to address the temporary memory overhead.

**Integration times of standard operations** Next, we compared the evolution of integration times of standard operations, i.e. insert and remove operations, on LogootSplit and RenamableLogootSplit documents. Since both types of operation share the same time complexity, we used solely insert ones in our benchmarks. We do however distinguish local and remote updates. Conceptually, local updates can be decomposed as presented in [38] in the two following steps: (i) the generation of the corresponding operation (ii) the application of the resulting operation on the local replica. However, for performance reasons, we merged these two steps in our implementation. We thus make a distinction between local and remote updates in our benchmarks. Figure 12 displays the results.
In these figures, orange boxplots correspond to integration times on LogootSplit documents while blue ones correspond to times on RenamableLogootSplit documents. While both are initially equivalent, integration times on RenamableLogootSplit documents are then reduced when compared to LogootSplit ones once rename operations have been applied. This improvement is explained by the fact that rename operations optimise the internal representation of the sequence.

Additionally, in the case of remote operations, we measured specific integration times for RenamableLogootSplit: integration times of remote operations from previous epochs and from concurrent epochs, respectively displayed as white and red boxplots in Figure 12b.

Operations from previous epochs are operations generated concurrently to the rename operation but applied after it. Since the operation has to be transformed beforehand using RENAMEID, we observe a computational overhead compared to other operations. But this overhead is actually compensated by the optimisation of the internal representation of the sequence performed by rename operations.

Regarding operations from concurrent epochs, we observe an additional overhead as nodes have first to reverse the effect of the concurrent rename operation using REVERTRENAMEID. Because of this overhead, RenamableLogootSplit’s performance for these operations is comparable to LogootSplit ones.

To summarise, transformation functions introduce an overhead to integration times of concurrent operations to rename ones. Despite this overhead, RenamableLogootSplit achieves better performance than LogootSplit as long as the distance between the epoch of generation of the operation and the current epoch of the node remains limited. As the distance between both epochs increases, it leads to cases presenting worse performance than LogootSplit ones since the overhead is multiplied. Nonetheless, the renaming mechanism reduces the integration times of the majority of operations, i.e. the operations issued between two rounds of rename operations.

Integration time of rename operation  
Afterward, we measured the evolution of integration times of rename operation according to the number of operations, which relates to the number of elements in the sequence. As before, we distinguish performance of local and remote updates. The case of remote rename operations is subdivided into three categories. Direct remote denotes a remote rename operation that introduces a new epoch child of the current node epoch. Concurrent introducing greater (resp. lesser) epoch designates a remote rename operation that introduces a new epoch sibling of the current node epoch. According to the priority relation, the introduced epoch is greater (resp. lesser) than the current node epoch. The results are displayed in Table 1.

The main outcome of these measures shows that rename operations are generally expensive when compared to others, since nodes have to browse and rename their whole current state. Local rename operations take hundreds of milliseconds while direct remote ones and concurrent introducing greater epoch ones may last seconds if delayed for too long. It is thus necessary to take this result into account when designing strategies to trigger rename operations to prevent them from negatively impacting user experiences. In parallel, several improvements may be made to reduce these integration times:

- Instead of using RENAMEID, which renames the state identifier by identifier, one could design and use RENAMEBLOCK. This function would rename the state block per block, achieving a better time complexity. Additionally, since rename operations merge existing blocks into one, this would set up a virtuous circle,

### TABLE 1: Integration time of rename operations

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Integration Time (ms)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Mean</td>
</tr>
<tr>
<td>Type</td>
<td>Nb Ops (k)</td>
</tr>
<tr>
<td>Local</td>
<td>30</td>
</tr>
<tr>
<td></td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>90</td>
</tr>
<tr>
<td></td>
<td>120</td>
</tr>
<tr>
<td></td>
<td>150</td>
</tr>
<tr>
<td>Direct remote</td>
<td>30</td>
</tr>
<tr>
<td></td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>90</td>
</tr>
<tr>
<td></td>
<td>120</td>
</tr>
<tr>
<td></td>
<td>150</td>
</tr>
<tr>
<td>Cc. int. greater epoch</td>
<td>30</td>
</tr>
<tr>
<td></td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>90</td>
</tr>
<tr>
<td></td>
<td>120</td>
</tr>
<tr>
<td></td>
<td>150</td>
</tr>
<tr>
<td>Cc. int. lesser epoch</td>
<td>30</td>
</tr>
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<td></td>
<td>60</td>
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<td></td>
<td>90</td>
</tr>
<tr>
<td></td>
<td>120</td>
</tr>
<tr>
<td></td>
<td>150</td>
</tr>
</tbody>
</table>
where each rename operation reduces the cost of the next one.

- Since each call to rename or revertrename is independent from others, these functions are well-suited for parallel programming. Instead of renaming identifiers (or blocks) sequentially, one could slice the sequence into chunks and rename them in parallel.

Another interesting result from this benchmark is that concurrent introducing lesser epoch operations are cheap to apply. Since these operations introduce epochs that are not selected as the new target epoch, nodes do not actually proceed to rename their states. The application of concurrent introducing lesser epoch operations hence solely consists of adding the introduced epoch and the corresponding former state into the epoch tree. Thus nodes can significantly reduce the overall computations of a set of concurrent rename operations by applying them in the most suitable order given the context.

**Time to replay operation log** In order to compare the performance of RenamableLogootSplit to LogootSplit on a whole, we measured the time needed by both to replay a log of operations. Obtained results are shown in Figure 13.

![Fig. 13: Evolution of time needed to replay operation log](Image)

We observe that gains on integration times of insert and remove operations thanks to the renaming mechanism initially help to counterbalance the integration times of rename operations. But as the collaboration progresses, integration times of rename operations slightly increase since more elements are involved. This tendency is even more pronounced in scenarios with concurrent rename operations. Fortunately, in real-world applications, such a scenario (i.e., replaying the entire log) will not be the usual case and could be mitigated, for example, by using snapshot mechanisms. The snapshot mechanisms could even benefit from the naming mechanism since the transferred states will be compressed.

**Impact on performance of the frequency of rename operations** To evaluate the impact on performance of the frequency of rename operations, we conducted another benchmark. This benchmark consists in replaying operation logs from simulations using diverse settings of CRDT: either LogootSplit, RenamableLogootSplit with rename operations issued every 30k operations or RenamableLogootSplit with rename operations issued every 7.5k operations. As the benchmark replays the operation log, it measures the integration times of operations and their sizes. Results are displayed in Table 2.

Regarding integration times, we observe that more frequently issuing rename operations improves integration times of insert and remove operations. This confirms our expected results since the rename operation reduces integration times of these operations by reducing the size of identifiers and the number of blocks in the sequence.

We also note that the frequency has no significant impact on the performance of the rename operation itself. This was also an expected result since the time complexity of the implemented rename operation depends on the number of elements, which is not impacted by rename operations.

Regarding the size of operations, we observe that insert and remove operations of RenamableLogootSplit are initially bigger than their counterpart in LogootSplit since they embed their epoch of generation as additional data. But while LogootSplit’s operations grow indefinitely, the frequency of rename operations sets an upper-bound to the size of RenamableLogootSplit’s ones. It enables RenamableLogootSplit to have a smaller footprint per operation.

On the other hand, we observe that rename operations are much bigger than other types of operation. It is explained by the fact that this operation embeds the former state, i.e., the list of all blocks at its time of generation. However, we observe the same phenomenon regarding rename operations as for other operations: the frequency of rename operations sets a limit to the size of the rename operation itself. One can therefore choose to frequently issue rename operations to limit their individual size. However, this induces additional computation for each rename operation in the current implementation. Another solution, which we present in Section 8.3, is to implement a compression mechanism to send only the needed components to identify each block of the former state.

### 7.3 Complexity analysis of the epochs garbage collection mechanism

In previous sections, we evaluated in an experimental manner our implementation of RenamableLogootSplit and compared its performance to LogootSplit’s one. However, our implementation of RenamableLogootSplit does not provide an implementation of the garbage collection mechanism of epochs. To complete our evaluation, we propose a complexity analysis of it.

The algorithm of the garbage collection mechanism consists of the following steps. First, it establishes the version vector of causally stable operations. To this end, each node has to maintain a matrix of version vectors of every node. The algorithm computes the version vector of causally stable operations by keeping the minimal value for each entry of the vectors. This step consists thus in merging \( n \) version vectors of \( n \) entries, it is thus executed in \( O(n^2) \).

The second step consists in browsing the epoch tree in the reverse order of the one set by the priority relation until it finds the maximal epoch with the corresponding rename operation being causally stable. For each epoch browsed, the garbage collection mechanism computes and stores its path to the root of the epoch tree. This step is thus executed in \( O(e \cdot h) \), with \( e \) being the number of epochs in the tree and \( h \) the height of the tree.

From these paths, the mechanism computes the LCA. To do so, the algorithm computes in a successive manner
the last intersection between the path from the root to the current LCA and the paths computed previously. The LCA is the last epoch composing the resulting path. This step is executed in $O(e \cdot h)$ too.

The algorithm is now able to compute the set of required epochs. To this end, it browses the paths computed during the second step. For each path, it adds epochs that are after the LCA to the set of required epochs. Again, this step is executed in $O(e \cdot h)$.

Having determined the required epochs, the mechanism can now remove obsolete epochs. It browses the epoch tree and deletes every epoch that is not contained in the set. This final step is executed in $O(e)$.

Thus, we obtain that the time complexity of the garbage collection mechanism of epochs is $O(n^2 + e \cdot h)$. We summarise this result in Table 3.

### Table 3: Time complexity of the garbage collection mechanism of epochs

<table>
<thead>
<tr>
<th>Step</th>
<th>Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>computing stable version vector</td>
<td>$n^2$</td>
</tr>
<tr>
<td>computing paths from root to potential current epochs</td>
<td>$e \cdot h$</td>
</tr>
<tr>
<td>identifying LCA</td>
<td>$e \cdot h$</td>
</tr>
<tr>
<td>computing required epochs</td>
<td>$e \cdot h$</td>
</tr>
<tr>
<td>deleting obsolete epochs</td>
<td>$e$</td>
</tr>
<tr>
<td>total</td>
<td>$n^2 + e \cdot h$</td>
</tr>
</tbody>
</table>

$n$: number of nodes of the system, $e$: number of epochs in the epoch tree, $h$: height of the epoch tree

Despite its time complexity, the garbage collection mechanism should have a limited impact on the performance of the application. Indeed, this mechanism does not belong to the critical path of the application, i.e. the integration of updates. It may be triggered rarely, in the background and we may even target specific windows to do so, e.g. during idle times. As such, we thus did not delve on this part of RenamableLogootSplit in this work.

### 8 DISCUSSION

#### 8.1 Issuing rename operations

As stated in Section 3.2, rename operations are system operations. It is thus up to the designers of the system to determine when nodes should issue rename operations and to define a corresponding strategy. However, there is no silver bullet since each system has its own constraints.

Several aspects should be taken into account to define the strategy. The first one is the size of the data structure. As displayed in Figure 11, metadata progressively increases to represent 99% of the data structure. Using rename operations, nodes can discard metadata and reduce the size of the data structure to an acceptable amount. To determine when to issue rename operations, nodes may monitor the number of operations performed since the last rename one, the number of blocks composing the sequence or the length of identifiers.

A second aspect to take into account is the integration times of rename operations. As reported in Table 1, integrating remote rename operations takes up to seconds if delayed for too long. Although rename operations work behind the scenes, they can still negatively impact the user experience. Indeed, nodes cannot integrate operations from others while they are processing rename operations. From users’ points of view, rename operations can thus be perceived as latency peaks. In the domain of real-time collaborative editing, user experiments have shown that delay degrades the quality of collaborations [39], [40]. It thus important to frequently issue rename operations to keep their integration times below the perceptible limit.

Finally, the last aspect to consider is the amount of concurrent rename operations. Figure 11 shows that concurrent rename operations decrease RenamableLogootSplit’s performance. The proposed strategy must then aim to minimise the number of concurrent rename operations issued. However, it should avoid relying on synchronous coordination between nodes to do so. To reduce the likelihood of issuing concurrent rename operations, several techniques can be proposed. For example, nodes can monitor to which other nodes they are currently connected and delegate to the one with the highest node identifier the duty to issue rename operations.

To recap, we can propose strategies aiming to individually minimise each of these parameters. And while some of these goals converge (to minimise the size of the data structure and to minimise the integration times of rename operations), others conflict (to issue a rename operation as soon as a threshold is reached vs. to minimise the amount of concurrent rename operations). System designers have thus to propose a trade-off between parameters according
to the constraints of the system (real-time application or not, nodes’ hardware limitations...). It is hence necessary to deploy the system to evaluate its performance on each aspect, its usage and to find the right trade-off between all the parameters of the renaming strategy. For instance, in the context of real-time collaborative editing systems, [39] have shown that delay decreases the quality of the collaboration. In such systems, we would thus aim to keep the integration times of operations (including rename ones) below the limit corresponding to their perception by users.

8.2 Offloading on disk unused former states
Nodes have to store former states corresponding to rename operations to transform operations from previous or concurrent epochs. Nodes may receive such operations given 2 different cases: (i) nodes recently have issued rename operations (ii) nodes logged back in the collaboration. Between these specific events, former states are actually not needed to handle operations.

We can thus propose the following trade-off: to offload former states on the disk until their next use or until they can be garbage collected. It would enable nodes to mitigate the temporary memory overhead introduced by the renaming mechanism but increases integration times of operations requiring one of these former states. Nodes could adopt various strategies to deem former states offloadable and to preemptively retrieve them according to their constraints. The design of these strategies could be based on several heuristics: epochs of currently online nodes, number of nodes still able to issue concurrent operations, time elapsed since last use of the former state...

8.3 Compression technique for rename operations
To limit bandwidth consumption of rename operations, we propose the following compression technique. Node may broadcast only necessary components to uniquely identify blocks instead of whole identifiers. Indeed, an identifier can be uniquely identified from the node identifier, node sequence number and offset of its last tuple. A block can therefore be uniquely identified from these components and its length. This reduces the data to send to a fixed amount per block.

To decompress the received operation, nodes browse their current state and log of concurrent remove operations. This allows them to retrieve whole identifiers and to reconstruct the original rename operation. Additionally, we can set an upper-bound to the size of rename operations by issuing them as soon as the state reaches a given number of blocks.

9 Related Work
Several works were proposed to address our problem of growth of identifiers in variable-size identifiers Sequence CRDTs. We present in this section the most relevant ones.

9.1 The core-nebula approach
The core-nebula approach [18], [19] was proposed to reduce the size of identifiers in Treedoc [26], another variable-size identifiers Sequence CRDT.

In this work, authors introduce a rebalance operation enabling nodes to reassign shorter identifiers to elements of the document. However, this rebalance operation is not commutative with insert and remove operations nor with itself. To achieve Eventual Consistency (EC) [41], the core-nebula approach prevents concurrent rebalance operations by regulating them using a consensus protocol. Operations such as insert and remove can still be issued without coordination and can thus be concurrent to rebalance ones. To deal with this issue, authors propose a catch-up protocol to transform these concurrent operations against the effects of rebalance ones.

Since consensus protocols do not scale well, the core-nebula approach proposes to split nodes among two groups: the core and the nebula. The core is a small set of stable and highly connected nodes while the nebula is an unbounded set of dynamic nodes. Only nodes from the core participate in the execution of the consensus protocol. Nodes from the nebula can still contribute to the document by issuing insert and remove operations.

Our work can be seen as an extension of this work. It adapts the rebalance mechanism and the catch-up protocol to LogootSplit and takes advantage of its block feature. Furthermore, it integrates a mechanism to deal with concurrent rename operations, removing the requirement of a consensus protocol. It is thus a more generic solution as one can use RenamableLogootSplit in systems composed of a core and a nebula, as well as in systems without stable nodes to form a core.

In systems with a core, one can still combine RenamableLogootSplit with a consensus protocol to prevent the generation of concurrent rename operations. This approach provides the following benefits: it enables to discard all parts dedicated to the handling of concurrent rename operations, i.e. the design of a priority relation and the implementation of revertRENAMENID. It also simplifies the implementation of the garbage collection mechanism of epochs and former states. Regarding performance, this solution behaves as RenamableLogootSplit with one renaming bot (cf. Section 7.2), but with an additional overhead corresponding to the cost of the chosen consensus protocol.

9.2 The LSEQ approach
The LSEQ approach [30], [31] is another approach proposed to address the growth of identifiers in variable-size identifiers Sequence CRDT. Instead of periodically reducing the identifier metadata using an expensive renaming mechanism, the authors define new identifier allocation strategies to reduce their growth rate.

In this work, authors observe that the identifier allocation strategy proposed in Logoot [27] is suited to a single editing pattern: from left to right, top to bottom. If insertions are made according to other patterns, generated identifiers quickly saturate the space of possible identifiers for a given size. Following insertions therefore trigger an increase of the identifier size. As a result, Logoot identifiers grow linearly with the number of insertions instead of the expected logarithmic progression.

LSEQ thus defines several identifier allocation strategies fitted to different editing pattern. Nodes randomly pick one of these strategies for each identifier size. Additionally LSEQ adopts an exponential tree model for identifiers: the
range of possible identifiers doubles as the identifier size increases. It enables LSEQ to fine-tune the size of identifiers according to needs. By combining the different allocation strategies to the exponential tree model, LSEQ achieves a polylogarithmic growth of identifiers according to the number of insertions.

While the LSEQ approach reduces the growth rate of identifiers in variable-size identifier Sequence CRDT, the sequence’s overhead is still proportional to its number of elements. On the other hand, RenamableLogootSplit’s renaming mechanism enables to reduce metadata to a fixed amount, independently of the number of elements.

These two approaches are actually orthogonal and can, as in the previous approach, be combined. The resulting system would periodically reset the sequence’s metadata using rename operations while LSEQ’s identifier allocation strategies would reduce their growth in-between. This would also enable reducing the frequency of rename operations, decreasing the system computations overall.

## 10 Conclusions and Future Work

Conflict-free Replicated Data Types (CRDTs) enable the design of highly available large-scale distributed systems while ensuring the Strong Eventual Consistency (SEC) model. Still, some of these data structures, notably Sequence CRDTs, suffer from a continuous growth of their metadata.

In this paper, we introduced a novel Sequence CRDT belonging to the variable-size identifiers approach: RenamableLogootSplit. This new data structure embeds a renaming mechanism in its specification. This mechanism enables nodes to reassign shorter identifiers to elements and to group them into one block to minimise metadata. The renaming mechanism takes the form of rename operations, system operations that are automatically triggered by nodes when deemed necessary. Since the proposed rename operation is not commutative with insert and remove operations, we use OT techniques to solve resulting conflicts.

Experiments show that the renaming mechanism enables nodes to reduce the size of their data structure by several hundred times compared to previous work. RenamableLogootSplit achieves this result even in the case where several concurrent rename operations are issued, since the introduced overhead is eventually removed.

In future work, we plan to propose other strategies than the lexicographical one to define priority, the strict total order relation on the set of epochs. These new strategies could for example favour the branch of the epoch tree with the most nodes and work. The use of these strategies would then reduce the overall computations of the system.

### References


APPENDIX A
HELPER FUNCTIONS

position : Retrieves the value of the position of the first tuple of the given id. e.g. position(id1, id2) returns 1.
findFirst : Retrieves the index of the first tuple of the given id.
findIndex : Retrieves the index of the given id in the given list of ids renamedIds.
findIndexOfPred : Retrieves the index of the predecessor of the given id in the given list of ids renamedIds.
concat : Returns a new id made of the tuples of given ids. e.g. concat(id1, id2, id3) returns id1, id2, id3.
isPrefix : Indicates if the given id is part of the block resulting of the rename operation. i.e. id is of the form
newLastId. e.g. isPrefix(id1, id2) returns true.
isRenamedId : Indicates if the given id is part of the block resulting of the rename operation. i.e. id is of the form
newFirstId. e.g. isRenamedId(id1, id2) returns true.
getFirstOffset : Retrieves the value of the offset of the first tuple of the given id. e.g. getFirstOffset(id1, id2) returns 1.
getTail : Returns a new id obtained by removing the n first tuples of the given id. e.g. getTail(id1, id2) returns id1, id2, id3.
getLastOffset : Retrieves the value of the offset of the last tuple of the given id. e.g. getLastOffset(id1, id2) returns 0.
createIdFromBase : Returns a new id by copying the given id and replacing its last offset with the given one. e.g.
createIdFromBase(id1, id2, id3) returns id1, id2, id3.
isPrefix : Indicates if the given id is a prefix of the other given id. e.g. isPrefix(id1, id2) returns true.

APPENDIX B
REMAINING FUNCTIONS OF RENAMEID

Algorithm 3 illustrates the remaining functions composing
RENAMEID. RENIDLESS THANFIRSTID (resp. RENIDGREATER THANLASTID) enables to rename identifiers with
id such as id < firstId (resp. lastId < id).

function RENIDLESS THANFIRSTID(id, newFirstId)
if id < newFirstId then
return id
else
pos ← position(newFirstId)
nId ← nodeid(newFirstId)
nSeq ← nodeSeq(newFirstId)
predNewFirstId ← new Id(pos, nId, nSeq, -1)
return concat(predNewFirstId, id)
end if
end function

function RENIDGREATER THANLASTID(id, newLastId)
if id = newLastId then
return concat(newLastId, id)
else
return id
end if
end function

Alg 3: Remaining functions to rename an identifier

The main insight of these functions is that it is not necessary to modify identifiers out of the range of renamed identifiers and of resulting identifiers ([min(firstId, predNewFirstId), max(lastId, succNewLastId)]).

In other cases, like RENIDFROMPREID, these functions prepend a suitable prefix to the given id to preserve the intended order (the predecessor of newFirstId for RENIDLESS THANFIRSTID, newLastId for RENIDGREATER THANLASTID).

APPENDIX C
REMAINING FUNCTIONS OF REVERPRENAMEID

Algorithm 4 features the remaining functions composing
REVERPRENAMEID. REVRENI DLESS THANNEWFIRSTID (resp. REVRENI DGREATER THANNEWLASTID) enables to rev-
vert the effects of a previously applied rename operation on identifiers with id such as id < newFirstId (resp.
newLastId < id).

function REVRENI DLESS THANNEWFIRSTID(id, newId, newFirstId)
predNewFirstId ← createIdFromBase(newFirstId, -1)
if isPrefix(predNewFirstId, id) then
tail ← getTail(id, 1)
else if tail < firstId then
return tail
else
return id
end if
end function

function REVRENI DGREATER THANNEWLASTID(id, lastId)
if id < lastId then
return id
end if
end function

Alg 4: Remaining functions to revert an identifier renaming operation