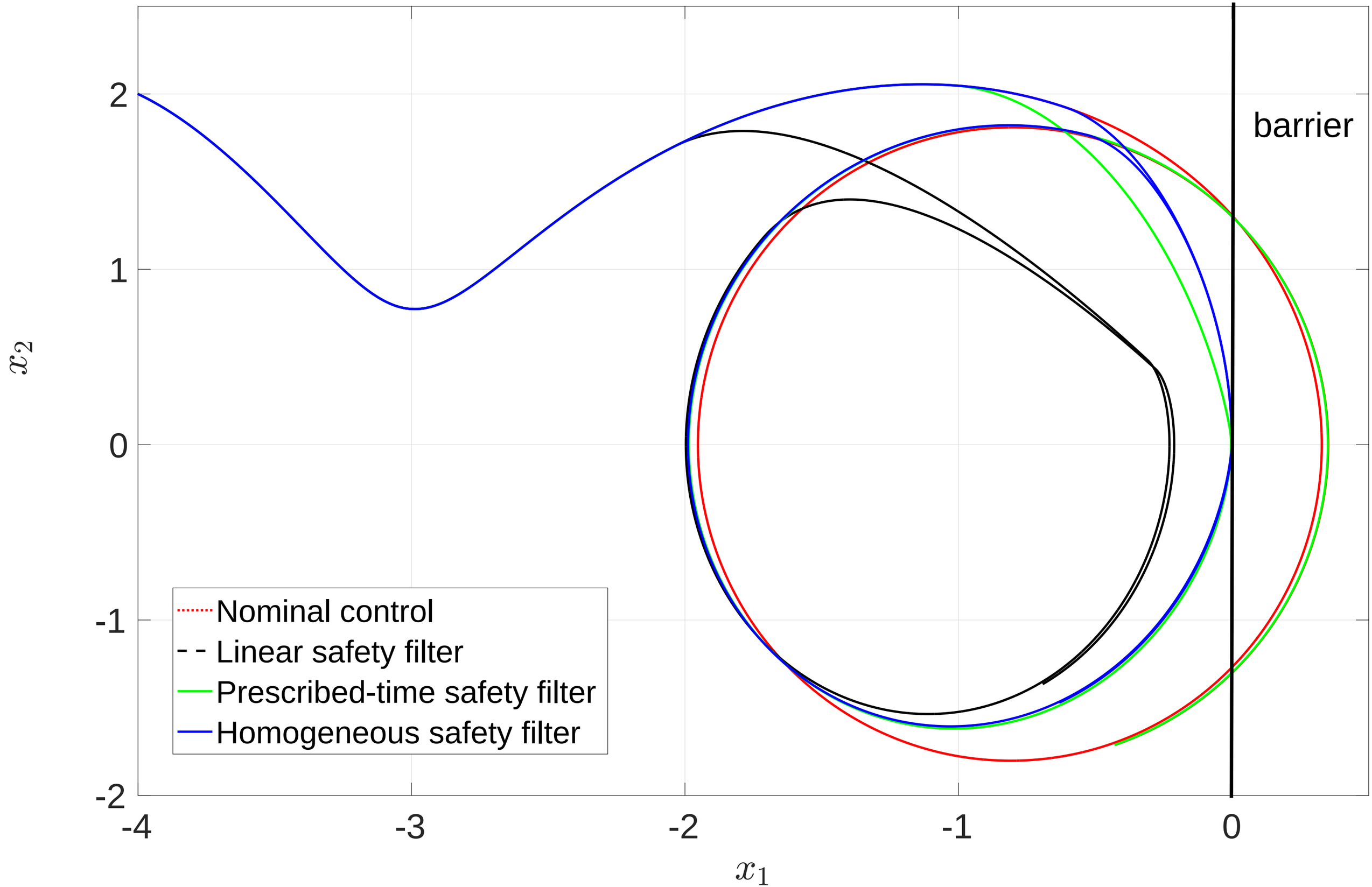
barrier
Nominal control
Linear safety filter
Prescribed-time safety filter
Homogeneous safety filter
2
1
0
-1
-2
-4
-3
-2
-1
0
x_1
x_2