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# Interactive Multimodal System Characterization in the Internet of Things Context

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**Abstract:** The internet of things (IoT) is a chance to provide users with pervasive environments in which they can interact naturally with the environment. Multimodal interaction is the domain that provides this naturalness by using different senses to interact. However, the IoT context requires a specific process to create such multimodal systems. In this article, we investigate the process of creating multimodal systems with connected devices as interaction mediums, and provide an analysis of the existing tools to complete this process. We discuss tools that could be designed to support the creation process when the existing ones are not sufficient.

## 1 INTRODUCTION

Since Bolt experiment (Bolt, 1980), multimodal interactions became a topic of interest to provide more natural and human-like interactions (Turk, 2014). This naturalness comes from the selection of the most appropriate modalities according to the context of use (Caschera et al., 2015). Here, the context of use refers to information about the target platform, the user, and the environment (Calvary et al., 2005) that can be used to adapt the interaction to each situation.

At the same time, we are increasingly surrounded by smart devices networked to form the Internet of Things (IoT). The IoT can provide to multimodal interactive systems valuable interfaces to communicate with end-users in smart environments (smart homes, smart buildings, smart cities, etc.). Indeed, compared to devices that are statically selected and associated with specific user interactions (Ferri et al., 2018), these devices are distributed, can be more numerous, possibly mobile or carried, offer a wider range of capabilities, and could be shared among multiple stakeholders (e.g. administrators and employees in offices) (Pruvost, 2013). Therefore, they contribute to the realization of Weiser’s “ubiquitous computing” paradigm (Weiser, 1991) in which computers vanish from the users’ perspective and are considered as a natural part of their environment.

However, the process of creating multimodal IoT-based systems (hereafter referred to as MIBS) is still complex. Indeed, MIBS are heavily dependent on connected objects to interact with users. However, from one smart environment to another, these objects will be different, placed in different locations, with different specifications. Moreover, the diversity of interaction capabilities offered by the IoT leads to the possibility of deploying a wide variety of interaction techniques in such environments. All this has an impact on the user-system interactions and more globally on the usability of the system. To evolve from *ad hoc* solutions to a more generic and less expensive MIBS creation process, it is necessary to make multimodal services independent from interaction devices, as previously suggested by Avouac et al. (Avouac et al., 2011). In this way, services can adapt to connected objects in the smart environment where they are deployed. The link between interaction devices and multimodal services once deployed is referred to as interaction chains. They include all the components necessary for the interpretation and expression of commands between the user and services.

Let us take the example of a service to book meeting rooms in an office environment. In our example, connected displays, presence sensors, and microphones are installed in a crowded hall and each meeting room. Each employee (i.e. end-user) has a professional smartphone and smartwatch that could be used for the service. Based on these objects, several interaction techniques can be considered for the booking

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interaction. For instance, the method to select a room could be to point at this room with a smartphone or simply to enter the room and be detected by the corresponding presence sensors. However, the administrators' choices aren't known beforehand, and designing services for each combination of devices would be too burdensome due to the combinatorial complexity.

The complexity to create such systems can be alleviated with software tools. Our goal is to provide a comparative study of the existing tools to create MIBS. However, these tools are not designed according to a unique creation process, thus they are rarely interoperable. Moreover, these tools only provide support for specific tasks in their respective processes. Therefore, we first need to propose a synthesis of the processes to create MIBS.

For this purpose, we first introduce the tasks usually related to the MIBS life cycle. Then, we propose a literature review of the existing tools that correspond to this life cycle and these tasks. Then we discuss about the lack of tools in the creation process. We finally conclude on the process and software tools related to MIBS creation. We illustrate the different tasks and analyze the existing tools with the meeting room booking service previously presented.

## 2 TASKS RELATED TO THE LIFE CYCLE OF MIBS

As expressed by the W3C community<sup>1</sup>, multimodal systems are composed of the following elementary components, which will be referred to as "canonical components" thereafter:

- Input and output modalities. The input modalities detect the users' actions, and the output modalities transmit to the users the system messages, forming the user interface (UI) in the process;
- An interpretation (including the fusion process) component. Its role is to provide meaning from the detected user' actions;
- A dialogue manager. It reacts to the provided interpretation and contextual information to further the dialogue and decide what content to send back to the user (Bui, 2006). The dialogue is the representation of the service that the system must provide;
- A restitution (including the fission process) component. It selects the most suitable output modalities for the message to be sent back to the user;

<sup>1</sup><https://www.w3.org/TR/mmi-framework/>

- A context manager. It tracks changes in the contextual information and provides the necessary information to the other components.

The term UI has multiple definitions (Pruvost, 2013), but we use the definition of the W3C which describes it as the technology "that allows users to effectively perceive and express information"<sup>2</sup>. It includes, for instance, graphical UI (GUI), vocal UI (VUI), or tangible UI (TUI).

Several approaches exist in the literature to provide MIBS that can feature these canonical components. In the next sections, we analyze these different approaches to define the MIBS life cycle. As we will see afterward, the proposed processes in the literature correspond to the systems development life cycle (SDLC)<sup>3</sup>. Here, we consider that the requirement specifications are already stated and we do not consider the system end of life. Thus, we consider the following stages to categorize and describe the processes and their associated tasks in the literature:

- The *design* stage to describe all the system models from the specified requirement;
- The *development* stage to create the necessary software components according to the design;
- The *integration* stage to assemble the components in a fully operational system;
- The *deployment* stage to install the system in the desired environment;
- The operation and maintenance, or *execution* stage to monitor the running system.

The resulting process is synthesized in figure 1.

### 2.1 Design Stage

The design stage mainly encompasses context analysis, dialogue design, and user interface design. Moreover, formative evaluations can help to validate these designs (Wechsung, 2014). The synthesis of the design process is detailed in figure 1.

#### 2.1.1 Context analysis

In the field of MIBS, the adaptation to contextual information is essential when connected devices may be mobile or dynamically included in an interaction chain. Therefore, the first step is usually for HCI designers to analyze and define the contextual information that will impact the system design including the adaptation process (Pruvost, 2013). There is no single

<sup>2</sup><https://www.w3.org/UI/>

<sup>3</sup><https://www.justice.gov/archive/jmd/irm/lifecycle/ch1.htm>

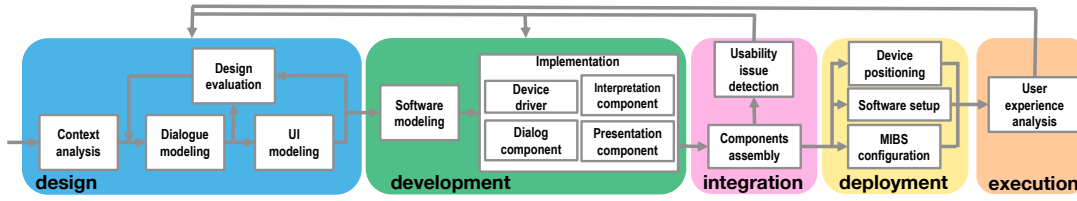


Figure 1: Overview of the synthesized process to provide MIBS from requirement specifications to execution. The gray loops represent the possibility from the integration and execution stage to impact the previous stages.

way to represent the context, but there are important classes of concepts in MIBS.

Device models as included in the ATRACO ontologies (Goumopoulos, 2016) are essential for quickly defining the capabilities of connected devices and simplify their associations with the system. Environmental information is not required for all services, but is essential for localized interactions. In the design process of Lemmelä et al. for multi-modal systems with mobile devices (Lemmelä et al., 2008), designers define the impact of possible environments on the users' perceptual and cognitive abilities. In addition, designers and architects could work together to model physical environments, as proposed by Pittarello et al. (Pittarello and Celentano, 2007). The situational context should also be defined in their approach. It could represent, among other things, the proximity between users. This specific situational information could be used to consider nearby persons in automatic adaptation processes or the shared aspect of IoT systems. The content of each context category could be decided based on observations of target audience' behaviors, from the designers' experiences, or user experiments with prototypes (see sections 2.3 and 2.5).

In the meeting room booking service, to let the choice between voice and gesture commands with the connected microphones and smartphones, designers could represent the connected microphones as devices that can provide VUI and smartphones as GUI and VUI providers. Moreover, pointing gestures to select rooms require a representation of the environment, and the smartphones positions and rotations relative to it. Alternatively, the crowdedness situation of the hall could be considered.

### 2.1.2 Dialogue design

Once all the contextual information is modeled, designers can define the dialogue. They have access to the requirements and the contextual information to describe the interaction tasks the users could perform, as well as their sequencing. Methods to define interaction tasks include user walkthrough from observation, storyboarding (Lemmelä et al., 2008) or or

the participation of domain expert in the design (Barricelli et al., 2009). The UIs must be abstracted in the task representation, as it is impossible to anticipate which connected devices will be used in the MIBS context. For instance, in the CAMELEON reference framework (Calvary et al., 2003) interaction tasks models are defined without specifying any information about the UI.

In our example, designers could represent the room booking service dialogue in four successive interaction tasks: trigger the service to start interacting, select the room, express the need to book the room, and confirm the result. The second and third tasks can be realized in any order, but both are required to proceed to the last one.

### 2.1.3 User interface design

Once the dialogue model is designed, the corresponding UIs could be defined. However, the exact UIs end-users will interact with are not known at design time. Thus, the existing approaches in the literature propose several solutions to encompass this issue. Designers could define the different UIs that may be used and select the preferred one during deployment or execution. Alternatively, they could design elementary UI elements that can be combined with a UI generation process, like the "Comet" paradigm (Calvary et al., 2005) for GUI.

Four types of devices can provide UI in our room booking service: the connected displays, the speakers, and the users' smartphones and smartwatches. Designers could draw what would be the elementary GUI corresponding to each task. They could also define the voice commands to inform the user to initiate the interaction, select a room, or confirm the success of the booking process.

### 2.1.4 Design evaluation

The modeled dialogue and its UIs theoretically meet the requirements. However, it is likely that the produced designs do not match the actual users' needs. As a first step, designers could detect flaws in the dialogue model. Then, they can assess the consistency

of the models with respect to the initial requirements.

Some rules and metrics could be used to predict flaws in the dialogue models with analytical methods such as interaction path analysis (Bernhaupt et al., 2008) or multimodal UI viability (Chang et al., 2019). In a survey, Abdulwakel and Nabil (Abdulwakel and nabil, 2021) proposed a classification of IoT-based services conflicts with an a priori conflicts detection method. This method could be used to evaluate UI adaptation based on rules.

To check that the dialogue and UIs models are consistent with the initial requirements, Oviatt and Cohen (Oviatt and Cohen, 2015) suggest that designers should experiment on these models with low fidelity prototypes. It could be with cognitive walk-through or guidelines review on the designed system, as presented by Bernhaupt et al. (Bernhaupt et al., 2008). MIBS compatible guidelines could be recommendations such as those for adaptive multimodal mobile input design in (Dumas et al., 2013), or standards in the industry like the ISO norms. Once the designs are considered satisfactory, they are ready for implementation.

In our previously described use case, designers could assess the aforementioned tasks by starting with the room selection task or the booking order task to find what would be the most suitable based on the selected modalities or context. Then, end-users could experiment on the room booking service models. Designers could provide multiple drawn GUIs and audio files, and the end-users could follow scenarios while following the drawings and the audio tracks. After the experimentation, the end-users could fill out usability questionnaires or any other type of feedback.

## 2.2 Development Stage

Following the design stage, the development stage consists in defining the software components and implementing them. The preferred architecture in MIBS is the components-oriented one for its high adaptation capabilities (Avouac et al., 2011).

### 2.2.1 Software components modeling

From the UIs and the dialogue models, developers can define the components necessary for building interaction chains. There are different approaches to categorize these components, and each provides modeling languages to define the components' inputs and outputs interfaces, as well as their features. These components could follow the canonical representation as in DynaMo (Avouac et al., 2011), but this isn't the sole approach for MIBS. For instance, in DAME (Pruvost, 2013), interaction chains include

*media controller* components that abstract the interaction capabilities of devices or set of devices, and *language controller* components that act as a bridge between these device-specific components and the device-independent dialogue components.

Developers frequently use off-the-shelf software programs when working with IoT ecosystems from various vendors, and for the modality-specific interpretation algorithms. Thus, rigid components definitions could complicate the work of developers when they want to include these software programs. This is one of the reasons Cronel et al. (Cronel et al., 2019) consider a tailoring process before implementing the necessary components. The other option is to not differentiate between components, with weaker development support as a trade-off.

In the room booking service, the VUI providers and the presence sensors in each room could have their own components providing input data, and could depend on the devices API for the implementation. A fusion component could use user location and commands to infer user needs in our use case. Moreover, all four interaction tasks of the dialogue could be included in a unique component.

### 2.2.2 Software components development

The next task for developers is to implement the components from their designs. Components are usually implemented in the same development environment, but the toolkit may be different according to their proximity to devices or interaction techniques.

Indeed, in the canonical representation, input and output modalities components are implemented with manufacturers' APIs to communicate with the associated devices while following standard APIs on the MIBS side. Therefore, developers mainly need knowledge about IoT characteristics. If we take the fusion component in our use case as an example, the developers need to implement a tracking algorithm from the user detection, and when a command is received, send it with the tracked information. The tracking method needs to be tailored to the presence sensors data to avoid false positives and negatives.

The software components that correspond to the dialogue model are usually the center of the literature propositions. The dialogue could be implemented as a set of components included in the composition chain as in Openinterface (Lawson et al., 2009) or DAME (Pruvost, 2013). It could also be the part of the system that manages the composition itself, as in DynaMo (Avouac et al., 2011).

The interpretation and presentation components between the devices and the dialogue are the least consensual in their exact definitions. For instance,

interpretation components are separated from fusion components in SIAM-DP (Neßelrath, 2015). The former components transform the data from the devices into a semantic representation, whereas the latter ones only fuse the semantic information. The DAME (Pruvost, 2013) approach represents with the same components input and output capabilities. Thus, it considers the potential dependency between input and output modality.

## 2.3 Integration Stage

At the integration stage, all the necessary software components have been produced, and developers and interaction designers can assemble fully functional prototypes with them. This assembly task is necessary for the static approaches, where applications are adapted manually between sessions according to the target context. However, dynamic approaches (i.e. runtime adaptation to context) can provide prototypes without manually assembling components, as it will be done automatically. In either case, the prototypes can then be assessed by UX designers and ergonomists in realistic environments.

Partial prototypes could also be created to perform these evaluations, or to prospect future interaction techniques or modalities unavailable at the moment (Taib and Ruiz, 2007). Besides, Working with partial prototypes reduces the reaction time to correct components issues, thereby reducing their production costs (Oviatt and Cohen, 2015; Vilimek, 2008). Finally, once a prototype is satisfactory, it can be packaged and provided to administrators for deployment.

### 2.3.1 Components assembly

Assembly refers to the composition of the developed software components to produce the interaction chains that provide the services according to the application specifications. The assembly process could be assigned to interaction designers or developers depending on the simplicity of the selected tool, as detailed in section 3.2.

In the room booking service, designers could decide to test the room selection interaction task with a smartphone. To do so, they connect a smartphone-associated component, an interpretation component for speech recognition, the previously presented fusion component, a dialogue component representing the service, and a presentation component to transform a message into an elementary GUI element. Then, they assemble them. For Instance, the presence sensors and speech detected in each room are linked to the fusion component.

### 2.3.2 Usability issue detection

Designers and ergonomists could assess the prototypes to detect flaws in the MIBS (i.e. issues in the interaction chains, components implementation, or design models), patterns in users' behaviors, or if the prototypes still comply with the guidelines presented in section 2.1.4. Thus, it could require changes in the previous stages. This technique doesn't provide exhaustive and complete analyses (Pruvost, 2013) but is the closest observation of the system anticipated use so far. Prototype experiments can be separated between model-based and user-based ones.

The first type is based on the system simulation with modeled users and environments (Bernhaupt et al., 2008; Pruvost, 2013). Compared to the other approaches, simulations are cheap, harmless, flexible, and could create situations and environments difficult or even impossible to reproduce in reality (Pruvost, 2013; Oviatt and Cohen, 2015). However, they are simplified, if not distorted, versions of their real-world counterparts, reducing the validity of the results and introducing biases. Moreover, simulations without real end-users lack the limit testing only they can do (Pruvost, 2013).

The second type consists of user experiments. Designers could assess beforehand the prototypes to check if they are still compliant with the guidelines considered in the section 2.1.4. The advantage is to evaluate the components composition alternatives in partially or fully functional prototypes (Vilimek, 2008; Bernhaupt et al., 2008) according to trusted standards and the designers' experience. Then, real users could experiment with the prototypes. The participants' behaviors are analyzed (Vilimek, 2008; Oviatt and Cohen, 2015) and their experience feedbacks are recorded (Bernhaupt et al., 2008), as in the rapid prototyping process of Lemmelä et al. (Lemmelä et al., 2008). With a complete prototype in the hands of real users, these experiments are the closest to the ground truth, but their costs, limitations to environments the experimenters can create, and their configurations rigidity is their downsides (Vilimek, 2008; Oviatt and Cohen, 2015).

In the room booking service, it would be during these experiments that designers could face practical issues. For example, rays of light in the afternoon could make the display of one of the envisioned meeting rooms impossible to use.

It should be noted that simulation is sometimes followed by experiments with users to get the best of both worlds (Kirisci et al., 2011). Indeed, starting with simulations reduces the cost and the time necessary for issues that experts can detect, and then exper-

iments can be performed to detect issues only end-users interactions analysis can find. However, this doesn't reduce the cost, and the duration is still the addition of the two duration necessary for these experiments.

## 2.4 Deployment Stage

Deployment revolves around the installation of the interactive system in the execution environment by administrators, who could be the users of the services (e.g. home services) or IT managers (e.g. offices environments). They must manage the devices' spatial layout, handle the MIBS configuration, and connect the connected devices to the MIBS. The order in which the previous three tasks are performed is arbitrary and could change whether the system can adapt to a change in devices position, or if there is an order between the system and the devices' startup.

### 2.4.1 Device positioning

As connected devices are more and more common in our surroundings, they are usually already installed. However, the administrators could need more devices for a particular service. They could also move some of the installed ones. This implies a careful placement of those devices, as they need to blend in the user surroundings (Burzagli et al., 2007). Administrators could follow instructions from the previous stages or generic installation recommendations. However, multiple trials and errors may be required before a satisfactory positioning is achieved. Moreover, the devices need to be hidden in ubiquitous environments, so relative positioning between the devices and the environment geometry is also important.

### 2.4.2 MIBS configuration setup

The environment geometry, the characteristics of the available interaction devices, and the network quality are among the concerns in MIBS. These contextual considerations are only known at the deployment stage. Thus, administrators could configure the system based on the context of use before starting a session. They could customize the system according to the current context as proposed by Burzagli et al. in their requirements (Burzagli et al., 2007). For instance, connected devices with their locations in the environment could be registered in the system. For static approaches, they could also select the interaction chains with the available devices, as in ICARE (Bouchet et al., 2004).

In our use case, we consider that the IT managers select the devices. Thus, they could select an interac-

tion chain from those recommended by the designers. For instance, they could select the interaction chain that uses microphones and presence sensors, and then associate the connected devices in each meeting room with the service.

### 2.4.3 Device software setup

Finally, the connected devices must be started, configured, and connected to the system depending on the architecture discovery and registration capabilities.

Regarding the communication process, Rodriguez et al. (Rodriguez and Moissinac, 2017) explain that there is no single protocol in the IoT, as each vendor usually has its own network ecosystem. As a result, devices deployment is generally not addressed in MIBS-related literature, and they resort to ad hoc solutions. Nevertheless, they propose in their work a model of modality component and a process for discovery and registration that could lead to a consensus in the IoT community. Administrators could also specify here the location of the devices if they have no way of knowing their location in the environment.

In our use case, smartphones are accessible via Wifi or mobile networks, while presence sensors might only be available with Z-wave<sup>4</sup> or other low-level protocols and technologies. Thus, IT managers could use an IoT platform such as OpenHAB<sup>5</sup> to allow the MIBS to communicate with all devices through a unique network and protocol.

## 2.5 Execution Stage

Once the MIBS is running, end-users can finally interact with it. However, the MIBS can be further evaluated with the extensive data available at this stage to identify user preferences or dislikes regarding the interactive system. It should be mentioned that the MIBS maintenance remains a challenge (Chang et al., 2019): the IoT is composed of various networks evolving at different rates, and each device in these networks has its own hardware and software lifespan.

### 2.5.1 User experience analysis

The evaluation can be separated into user observation and user feedback. For the latter, techniques such as user improvement propositions (Barricelli et al., 2009) or questionnaires (Bernhaupt et al., 2008) could be used to detect defects that were not previously detected. User preferences (Bernhaupt et al., 2008)

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<sup>4</sup><https://www.z-wave.com/>

<sup>5</sup><https://www.openhab.org/>

could also be detected, for instance with log files analysis on field observations.

These evaluation methods are similar to the user-based experiments in the integration stage, but the lack of controlled settings, the larger number of users, and the potentially greater diversity of environments lead to more in-depth insights on the system (Bernhaupt et al., 2008; Wechsung, 2014) at the cost of a higher cost and the product reputation (Oviatt and Cohen, 2015; Carlsson and Schiele, 2007). Moreover, the interaction devices could be hidden in MIBS. Therefore users are less aware of how the system collects data about them and could be less willing to share their data.

In our use case, the IT manager could be the only one to have access to users' usage rate of the room booking service. Furthermore, the data could be anonymized to ensure user ownership over the data.

The result of the data analysis could be taken into account at any stage. Indeed, it could lead to new requirements, thus starting a whole new cycle. Implementation issues could be discovered when facing specific situations. New interaction chains could be inferred from users' feedback, while administrators could change some parameters to better tailor the system to the users' needs.

### 3 TOOLS IN LITERATURE

Completing the life cycle of MIBS requires multiple stages, however the tasks associated with each stage may require advanced design and development knowledge, can be time-consuming, and sometimes repetitive. Therefore, dedicated tools are needed to ease the work of the different stakeholders.

In this section we present the software tools that have been used to create multimodal systems and are compatible with IoT-based systems, according to the tasks they help to accomplish at each stage.

#### 3.1 Design tools

As detailed in section 2.1, the MIBS design stage consists of the definition of the contextual information, the dialogue model, and the UIs. Design tools are less concerned with the IoT aspect of MIBS. Indeed, the only specific requirements are to separate the dialogue from the devices, and to provide UIs for a larger set of interactive devices.

As presented in section 2.1.1, there are different classes of contextual information. Therefore the representation should be flexible enough to support the diversity of contexts. Ontology is said to be the

best data representation in MIBS for its extensibility and structure that eases the context reasoning process (Pruvost, 2013). For instance, the environment geometry could be described as an ontology, as in (Pittarello and Celentano, 2007). Tools such as the ontology editor Protégé<sup>6</sup> provide easy management of generic standard ontologies. Protégé in particular was used to represent knowledge bases in multimodal systems (Mendonça et al., 2009; Pruvost, 2013) and supports the W3C language standard<sup>7</sup>. However, Pruvost (Pruvost, 2013) asserts that this tool is complex to learn and too permissive. Thus, he has built on its API the "Describe" tool (Pruvost, 2013) to simplify the edition of ontologies, and to forbid the edition of their architecture core ontologies. Ontologies have some shortcomings compared to other context representations (Perttunen et al., 2009). For instance, it is relatively easy to create inconsistency in the context representation, and consistency checks are expensive.

Once the context is defined, numerous tools are proposed to model the dialogue tasks (Nigay et al., 2015). For example, CTTe (Mori et al., 2002) helps interaction designers to specify the dialogue as interaction tasks based on a task tree representation. This tool also offers low fidelity prototyping (Oviatt and Cohen, 2015) functionality to check if the dynamic functioning of the task model corresponds to the interaction requirements. The complementarity between the room selection task and the booking order task in the room booking service could easily be described as subtasks linked by a temporal operator.

The designed dialogue could be analyzed to predict its flaws. Just as CTTe and IMBuilder have simulation capabilities, two other tools can help to ease the system analysis. Silva et al. (Silva et al., 2013) use Petshop (Navarre et al., 2009) and Colored Petri-net tools (Jensen et al., 2007) for formal verification of the interaction paths, and MIGTool (Brajnik and Harper, 2016) helps to transform scenario specifications into interaction paths to analyze and compare abstract interaction models according to metrics such as UI flexibility or consistency.

With the tasks defined and validated, designers can model the UIs. UI design could be separated between graphical and non-graphical device-dependent representations. Graphical user interfaces (Pruvost, 2013; Neßelrath, 2015) in multimodal systems are designed with UI description languages and associated tools. For web-based interfaces, tools such as Bootstrap<sup>8</sup> support HTML5 and CSS edition, and various

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<sup>6</sup><https://protege.stanford.edu/>

<sup>7</sup><https://www.w3.org/TR/owl2-overview/>

<sup>8</sup><https://getbootstrap.com/>

tools such as the markup validation service<sup>9</sup> complement the editors with useful features. Apple Interface Builder<sup>10</sup> and Sketch<sup>11</sup> are tools to create UIs for the Apple ecosystem. Grundy and Yang (Grundy and Yang, 2003) developed an editor in which UI designers can model graphical interfaces in multiple layout views and custom-made tags for adaptation. TERESA (Paternò et al., 2008) allows constructing UIs from a task model composed of graphical and vocal elements. Alternatively, the graphical tool MOSTe (Rousseau et al., 2005; Rousseau et al., 2006) helps to specify any interaction components (i.e. the device components) in an abstract representation, and even provides an editor to define rules for dynamic selection of UIs. This rule-based interface selection strategy is also present in the Behave tool (Pruvost, 2013) or in the authoring environment of Ghiani et al. (Ghiani et al., 2015). For VUIs, the interface is not based on the spatial distribution of elementary components, but the succession of temporal dialogue elements. Therefore, it could be considered as a part of the dialogue model, or as a separate entity. In the latter case, many commercialized tools could be used. For instance, VUIs could be represented as decision diagrams with the graphical tool Voiceflow<sup>12</sup>. In addition, tools such as BotSociety<sup>13</sup> could help designers to preview VUIs. Other UIs are less standardized than the previous two. Therefore, the first tools were associated with a limited set of devices, or required technical knowledge (Moussette, 2007). However, the field has matured since then, and tools that are easy-to-use and non-technical start to emerge. For instance, the process to design haptic UI is simplified by the graphical tool Felix (van Oosterhout et al., 2020): it requires no prior technical knowledge to design UIs and includes an intuitive sketch editor.

From these models, designers could experiment the system with users. They could use the SIHMM simulator (Bodic et al., 2004) to observe virtual users interacting with simulated mobile devices in a modeled environment. In this tool, designers have to model multimodal properties of devices, physical and social perturbations environment entities could generate, the scenario to follow, and the user model dictating their interaction preferences. In the same way, MuMoWOz (Ardito et al., 2009) is a tool to evaluate design choices with Wizard of Oz experiments. However, designers have to define the concrete content to provide to users during experiments, and this

tool only covers mobile multimodal systems. An interaction designer can also evaluate the system without modeling everything beforehand, as in the tool CrossWeaver (Sinha and Landay, 2003). Here, interaction designers create a storyboard by defining the system state as drawings, possible transitions according to user inputs, and the system feedbacks to users. Then, end-user experiments are performed to produce logs that designers can view and replay.

### 3.2 Development tools

As detailed in Section 2.2.1, the process to define the components inputs, outputs, and features prior to the actual implementation helps to clarify the purpose of each component. Therefore, it ensures the necessity of each component and providing better documentation. System designers could use SKEMMI (Lawson et al., 2009) to describe components with a simplified component representation, whereas developers could work on these components on their specific level. The possibility to work on the same components on different views for system designers and developers is beneficial for cooperation, but, to our knowledge, this feature is only present in this software tool.

To develop the device drivers, services, presentation, and interpretation software components, existing approaches often offer the same editor and require to follow code patterns to match their component model and functionalities. In SIAM-DP (Neßelrath, 2015), they propose plugins for Eclipse to help developers generate code templates, visualize the dialogue flow and preview the GUI. Identically, the AsTeRICS toolkit<sup>14</sup> also provides templates with Eclipse extensions to implement compatible components. Then, it is up to the developers to fill the component patterns with the necessary code, using service API and SDKs.

Before implementing the dialogue components, developers could transform the model into a machine-readable dialogue. To do this, developers have access to various interactive system editors. IM-Builder (Bourguet, 2002), FSM translator (Chang and Bourguet, 2008) and MyUI editor (Peissner et al., 2011) are some of these tools that permit the implementation of the dialogue as a finite state machine (FSM). Petshop (Navarre et al., 2009) provides the same service, but with a Petri-net representation.

### 3.3 Integration tools

At this stage, developers and designers can use the developed components in integration tools to create prototypes. To assemble software components in interac-

<sup>9</sup><https://validator.w3.org/>

<sup>10</sup><https://developer.apple.com/xcode/interface-builder/>

<sup>11</sup><https://www.sketch.com/>

<sup>12</sup><https://www.voiceflow.com/>

<sup>13</sup><https://botsociety.io/>

<sup>14</sup><https://www.asterics.eu/>

tion chains, most tools adopt a graphical representation of components, and the components can be linked to each other through their interfaces. ICON (Dragicevic and Fekete, 2001) is a graphical editor that helps to create interaction chains. However, it requires a good understanding of its components representation and implementation, and can therefore be difficult to master quickly. ICARE (Bouchet et al., 2004) improves on this concept and enables creation without the need of extensive knowledge thanks to the CARE paradigm representation (Coutaz et al., 1995). Indeed, interaction chains are presented here from the end-user perspective, which is more intuitive to work with than abstract implementation variables such as cursors x or y positions. ACS<sup>15</sup> is another graphical tool for assistance services development similar to SKEMMI (Lawson et al., 2009). In addition, ACS provides a GUI editor based on the component instantiated. The system construction workbench of Shen et al. (Shen et al., 2011) also enables developers to define interaction chains with a debugging tool. However, its publish-subscribe architecture permits the complex and dynamic association of components. Finally, the prototyping tool in (Seiger et al., 2015) differs from the previous tools. First, it enables developers to modify the composition of the components during execution. Second, it integrates the attributes of the components in their graphical representation which eases the configuration process. However, the publish-subscribe architecture is lost here. The level of expertise to use these tools isn't high: it only consists in graphically adding and linking components.

From the developed prototypes, designers and ergonomists could assess their usability before delivering the best one to the administrators. There are multiple methods to assess these multimodal prototypes (see section 2.3), but software tools are not used for methods other than simulation. Indeed, the designers rely on their personal experience for the guidelines compliance assessment. For the users' experiments, designers only need to observe users and collect their feedback with questionnaires.

For the simulation method, only one tool was found to assess MIBS prototypes. Pruvost (Pruvost, 2013) created the "Simulate" tool that a designer could use to simulate the system behavior in a schematic representation of the environment. This representation is easy to create but is far from the real world condition.

The deployment and execution tools (see sections 3.4 and 3.5) can also be used in the integration phase during field or laboratory experiments.

### 3.4 Deployment tools

The final prototype is sent to the administrator for deployment. Some processes present the deployment phase as being simple as starting a software program. One example is the ARE tool<sup>16</sup> that provides a simple menu to handle the system execution. Even if there are systems that dynamically select their interaction devices, most approaches still need an administrator to place the hardware, start and configure the interactive system and the devices. To do this, administrators could be assisted in their tasks.

The assembly tools presented in the integration stage (e.g. ICON (Dragicevic and Fekete, 2001)) could also be used here. However, users need knowledge about multimodality and data representation to be able to use them. Moreover, they still need to know how to install the devices in the environment, as no spatial information is provided.

Finally, the MIBO Interactive Editor (Peters et al., 2016) offers two features for an administrator. This graphical programming tool enables instantiating simple services rapidly without expertise. It even provides a debugging tool to determine if the defined services conflict with each other. Nevertheless, it doesn't handle multimodal output (i.e. it only controls connected devices), nor does it provides spatial installation guidelines.

Therefore, the existing tools provide some support to the deployment stage but don't perform all the tasks identified in the section 2.4: the tasks of placing devices and configuring their software programs are not addressed.

### 3.5 Execution tools

Once the system is started, administrators and vendors might monitor users to detect behavior patterns, preferences, or undetected flaws until then. For example, in the MMWA authoring environment (Neto and de Mattos Fortes, 2010), designers can access the user interaction log. Augmented Reality monitoring tools such as presented by Lacoche et al. (Lacoche et al., 2019) could also be adapted to multimodal systems. Indeed, immersion could help to better understand the state of the system. It is a common practice nowadays to monitor users to hasten hotfix patches development with network updates, but the privacy and security requirements depend on the service and target audience. Thus it seems that runtime monitoring is usually restricted to the prototyping evaluation strategy in the integration phase.

<sup>15</sup><https://www.asterics.eu/manuals/ACS/>

<sup>16</sup><https://www.asterics.eu/get-started/Overview.html#are>

## 4 DISCUSSION

From our analysis of the tasks and tools for MIBS development, we can see that some aspects are still not sufficiently addressed. Below we discuss the tasks that could be better supported.

Devices representations, which define their interaction capabilities, and their corresponding components are properly handled when they provide graphical or vocal modalities, but other modalities, which are numerous in IoT systems, are considered more as providers or consumers of events without further support. Works such as the DOG ontology (Bonino and Corno, 2008) could be used as a basis to provide standard representations of connected devices, and thus could improve the tools support.

System testing in the integration phase still lacks a tool to assess a multimodal system in a realistic simulation with real users. Indeed, field and laboratories experiments are difficult and costly to perform, but they guarantee results close to the ground truth. Simulation is a good strategy to quickly test several configuration chains, but existing tools rely on modeled users, so the results are more likely to be biased. Simulation with real users could bring the reliability of laboratory experiments with the ease of use of the simulation approach, and Virtual Reality (VR) could be a promising technology in this aspect. Works on simulated interactive systems such as the VUMS project (Peissner et al., 2011) or the Augmented Reality (AR) application pipeline in (Soedji et al., 2020) could provide a basis to assess user interactions in MIBS simulations.

Deployment tools only consider the software configuration, but they lack a mean to help the administrator place the interaction devices without relying on trial and error. Perhaps a companion system such as the one presented by Bercher et al. (Bercher et al., 2018) could help administrators during installation: localized visual cues in a simulated environment could lead to a better understanding of the positioning to do. This also means that we need a method to describe beforehand the real environment and its ability to host the desired services. The environment capture and device configuration in AR proposed by Soedji et al. (Soedji et al., 2020) could solve this issue. Therefore, an augmented reality-based companion system could fill the gap in the deployment stage.

Finally, there are only a few supports for multimodal systems monitoring, which could be useful for multimodal services. Indeed, some multimodal applications could use online services or IoT systems accessible from everywhere. Thus online monitoring tools could be used for maintenance in case of service

outage or IoT malfunction, in addition to application flaw detection. The Smart Space Solution of Softengi<sup>17</sup>, which eases IoT monitoring using AR technology, could be adapted to the multimodal paradigm.

## 5 CONCLUSION

Our identification of the tasks and software tools associated with the SDLC of multimodal systems using connected devices as interactive mediums leads to a proposition of the tools that could be designed to fill the gap in the identified process. This is synthesised in table 1.

User interfaces design other than graphical or vocal ones require more standardized and easy-to-use tools than the existing ones. The integration stage could benefit from better simulation tools to evaluate such environment-dependent systems without relying on the costly laboratory or field experiments. Deployment is also not well explored, and improved installation tools could ease this part of the process. The effort could be focused on providing tools to easily identify and place connected devices in the environment. More intuitive monitoring tools could also be beneficial for multimodal systems where interaction devices are distributed.

The identified process and our analysis could guide the creation of a framework and new tools for future researchers in the field of multimodal interaction who want to use connected devices as mediums of interaction.

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<sup>17</sup><https://softengi.com/projects/public-sector/smart-space-solution-for-the-softengi-office/>

Table 1: This table summarizes what are the tasks in the SLDC of MIBS that aren't well supported by software tools. "✓", "?" and "X" represent the tasks that are well supported, could be improved or not supported (respectively).

| Design              | Development                 | Integration                 | Deployment           | Execution                  |
|---------------------|-----------------------------|-----------------------------|----------------------|----------------------------|
| Context analysis ✓  | Software modeling ✓         | Components assembly ✓       | Device positioning X | User experience analysis ? |
| Dialogue modeling ✓ | Components implementation ✓ | Usability issue detection ? | Software setup X     |                            |
| UI modeling ?       |                             |                             | MIBS configuration ✓ |                            |
| Design evaluation ✓ |                             |                             |                      |                            |

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