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▶ To cite this version:

Théophile Chaumont-Frelet, Alexandre Ern, Simon Lemaire, Frédéric Valentin. Bridging the multiscale hybrid-mixed and multiscale hybrid high-order methods. GS21 - SIAM Conference on Mathematical and Computational Issues in the Geosciences, Jun 2021, Milan / Virtual, Italy. hal-03403903

HAL Id: hal-03403903 https://inria.hal.science/hal-03403903

Submitted on 26 Oct 2021

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Bridging the multiscale hybrid-mixed and multiscale hybrid high-order methods

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2 The multiscale hybrid-mixed (MHM) method

3 The multiscale hybrid high-order (MsHHO) method

$4 \quad MHM = HHO?$

What are multiscale methods?

Consider $\Omega \subset \mathbb{R}^d$. Given $f : \Omega \to \mathbb{R}$, find $u : \Omega \to \mathbb{R}$ such that $\begin{cases}
-\nabla \cdot (\mathbf{A}_{\varepsilon} \nabla u) &= f & \text{in } \Omega, \\
u &= 0 & \text{on } \partial\Omega,
\end{cases}$

where the diffusion tensor A_{ε} exhibits "multiscale" features.

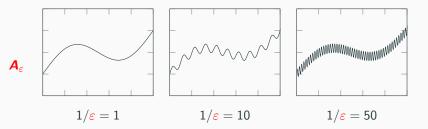
A key applications is Darcy equations, modeling flows in porous rocks.

For the sake, of simplicity, we will consider here the case where

$$\mathbf{A}_{\varepsilon}(\mathbf{x}) := \widehat{\mathbf{A}}\left(\mathbf{x}, \left\{\frac{\mathbf{x}}{\varepsilon}\right\}\right),$$

where $\widehat{\mathbf{A}}: \Omega imes (0,1)^d
ightarrow \mathbb{R}^{d imes d}$ is smooth, and

 $\widehat{A}(x, y)$ is y-periodic for all $x \in \Omega$.



Resolving the fine scale with a mesh size $h \simeq \varepsilon$ is to expensive.

We want to capture the "macroscopic behavior" of u, with a mesh size H.

We would like error estimates in $\mathcal{O}(H)$, with $H \gg \varepsilon$.

Standard FEM fails. Indeed, we have

$$-f =
abla \cdot (oldsymbol{A}_{arepsilon}
abla u) = (oldsymbol{\nabla} \cdot oldsymbol{A}_{arepsilon}) \cdot oldsymbol{\nabla} u + oldsymbol{A}_{arepsilon} : oldsymbol{
abla}^2 u$$

with $| {oldsymbol
abla} \cdot {oldsymbol A}_arepsilon | \simeq 1/arepsilon$, leading to

$$\| \boldsymbol{\nabla}^2 \boldsymbol{u} \|_{\Omega} \lesssim rac{1}{arepsilon} \| f \|_{\Omega},$$

and

$$\| \mathbf{\nabla} (\mathbf{u} - \mathbf{u}_{H}) \|_{\Omega} \lesssim rac{H}{arepsilon} \| f \|_{\Omega},$$

with \mathcal{P}_1 elements.

This is sharp: standard FEM needs to resolve the small scales $(H \leq \varepsilon)$.

We would like to keep the same number of dofs as the standard \mathcal{P}_1 FEM.

Hence, we preserve the mesh size H, but we modify the shape functions.

These modified basis functions will "upscale" fine scale information.

New shape functions via local problems

Consider a simplex $K \in \mathcal{T}_H$, one if its vertices **a** and

$$\psi^{\boldsymbol{a}} \in \mathcal{P}_1(K), \qquad \psi^{\boldsymbol{a}}(\boldsymbol{a}') = \delta_{\boldsymbol{a}\boldsymbol{a}'} \quad \forall \boldsymbol{a}' \in \mathcal{V}_K$$

the "hat function" associated with **a**.

An alternate definition of $\psi^{\pmb{a}}$ is that it satisfies

$$\begin{cases} -\Delta \psi^{a} = 0 & \text{in } K, \\ \psi^{a} = \psi^{a} & \text{on } \partial K. \end{cases}$$

This motivates the definition

$$\begin{pmatrix} -\nabla \cdot (\mathbf{A}_{\varepsilon} \nabla \psi_{\varepsilon}^{\mathbf{a}}) &= 0 & \text{in } K, \\ \psi_{\varepsilon}^{\mathbf{a}} &= \psi^{\mathbf{a}} & \text{on } \partial K. \end{cases}$$

for the multiscale shape functions.

Multiscale shape functions

Recall that:

$$\begin{pmatrix} -\nabla \cdot (\mathbf{A}_{\varepsilon}\psi_{\varepsilon}^{a}) = 0 & \text{in } K, \\ \psi_{\varepsilon}^{a} = \psi^{a} & \text{on } \partial K. \end{cases}$$
 (1)

Since we preserved the boundary conditions at each element, we automatically construct an $H_0^1(\Omega)$ -conforming basis.

The ψ_{ϵ}^{a} will incorporate some ϵ -scale oscilations.

In practice, (1) is approximated numerically on a fine mesh, which is possible because the problem is local to the element K.

Step 1: compute for each vertex the hat function ψ_{ϵ}^{a} .

This is done by uncoupled solving fine scale problems on small domains.

Step 2: compute the multiscale approxiation $u_{\varepsilon,H} \in \operatorname{span}_{\boldsymbol{a} \in \mathcal{V}_H} \{\psi_{\varepsilon}^{\boldsymbol{a}}\}$

$$(\boldsymbol{A}_{\varepsilon}\boldsymbol{\nabla}\boldsymbol{u}_{\varepsilon,\boldsymbol{H}},\boldsymbol{\nabla}\psi_{\varepsilon}^{\boldsymbol{a}'})_{\Omega}=(f,\boldsymbol{\nabla}\psi_{\varepsilon}^{\boldsymbol{a}'})_{\Omega}\quad\forall\boldsymbol{a}'\in\mathcal{V}_{\boldsymbol{H}}.$$

Multiscale error estimates

Standard FEM

$$\| oldsymbol{
abla} (oldsymbol{u} - oldsymbol{u}_{oldsymbol{H}}) \|_{\Omega} \lesssim rac{H}{arepsilon} \| f \|_{\Omega}$$

Multiscale FEM

$$\| \nabla (\boldsymbol{u} - \boldsymbol{u}_{\varepsilon, \boldsymbol{H}}) \|_{\Omega} \lesssim \left(\boldsymbol{H} + \sqrt{\frac{\varepsilon}{H}} \right) \| f \|_{\Omega}$$



T.Y. Hou, X.H Wu, Z. Cai, 1999.

Multiscale methods are robust when $H \gg \varepsilon$.

Modified shape functions are computed via local fine scale problems. Here, we will assume these problems are exatcly solved for simplicity.

The MHM and MsHHO are two multiscale methods recently introduced and able to handle polytopal meshes.

The multiscale hybrid-mixed (MHM) method

- P.A. Raviart and J.M. Thomas, 1977: A source of inspiration.
- R. Araya, C. Harder, D. Paredes and F. Valentin, 2013: Darcy equations.
- D. Paredes, F. Valentin and H. Versieux, 2017: Multiscale error analysis.
- R. Araya, C. Harder, A.H. Pozas and F. Valentin, 2017: Stoke's equations.
- T. Chaumont-Frelet and F. Valentin, 2020: Helmholtz problems.

The multiscale hybrid-mixed (MHM) method

The primal hybrid formulation

The primal hybrid formulation

Consider the energy functional

$$J(\mathbf{v}) := rac{1}{2} (\mathbf{A} \nabla \mathbf{v}, \mathbf{v}) - (\mathbf{f}, \mathbf{v})_{\Omega}.$$

Then, we have the characterization

$$\boldsymbol{u} = \arg\min_{\boldsymbol{v}\in H^1_0(\Omega)} J(\boldsymbol{v}).$$

The key idea of the primal hybrid formulation is to relax continuity through the use of a Lagrange multiplier.



P.A. Raviart and J.M. Thomas, 1977.

Consider a polytopal mesh \mathcal{T}_{H} of Ω and the "broken" space

$$\mathbf{V} := \left\{ \mathbf{v} \in L^2(\Omega) \mid \mathbf{v}|_{\mathcal{K}} \in H^1(\mathcal{K}) \ \forall \mathcal{K} \in \mathcal{T}_{\mathbf{H}}
ight\}.$$

We would like to characterize $H_0^1(\Omega) \subset V$.

Let $\mathbf{v} \in \mathbf{V}$. Then $\mathbf{v} \in H_0^1(\Omega)$ iff

$$\sum_{K\in\mathcal{T}_H}\int_{\partial K}\boldsymbol{\sigma}\cdot\boldsymbol{n}_K\boldsymbol{v}=0$$

for all $\boldsymbol{\sigma} \in \boldsymbol{H}(\operatorname{div}, \Omega)$.

We see that traces of $\boldsymbol{H}(\operatorname{div},\Omega)$ are involved. We thus set

$$\Lambda := \left\{ \lambda \in \prod_{K \in \mathcal{T}_H} H^{-1/2}(\partial K) \mid \exists \boldsymbol{\sigma} \in \boldsymbol{H}(\mathsf{div}, \Omega); \ \lambda|_{\partial K} = \boldsymbol{\sigma} \cdot \boldsymbol{n}_K \ \forall K \in \mathcal{T}_H \right\},\$$

and

$$\langle \lambda, \mathbf{v} \rangle := \sum_{K \in \mathcal{T}_H} \int_{\partial K} \lambda \mathbf{v}.$$

Hence $\mathbf{v} \in \mathbf{V}$ belongs to $H_0^1(\Omega)$ iff

 $\langle \lambda, \mathbf{v} \rangle = \mathbf{0} \quad \forall \lambda \in \mathbf{\Lambda}.$

We have

$$u = \arg\min_{\boldsymbol{\nu}\in H_0^1(\Omega)} J(\boldsymbol{\nu}) = \arg\min_{\substack{\boldsymbol{\nu}\in\boldsymbol{\mathcal{V}}\\\langle\boldsymbol{\mu},\boldsymbol{\nu}\rangle=0}} \min_{\forall\boldsymbol{\mu}\in\Lambda} J(\boldsymbol{\nu}).$$

The primal hybrid formulation is the Euler-Lagrange equations: Find $(u, \lambda) \in V \times \Lambda$ such that

$$\begin{cases} (\mathbf{A}\nabla u, \nabla v)_{\mathcal{T}_{H}} + \langle \lambda, v \rangle &= (\mathbf{f}, v) \quad \forall v \in \mathbf{V}, \\ \langle \mu, u \rangle &= 0 \quad \forall \mu \in \Lambda. \end{cases}$$

 \boldsymbol{u} is the original solution, and $\lambda|_{\partial K} = \boldsymbol{\nabla} \boldsymbol{u} \cdot \boldsymbol{n}_{K}$.

The multiscale hybrid-mixed (MHM) method

The MHM formulation

We can rewrite the first equation of the primal hybrid formulation as

$$(\mathbf{A} \nabla u, \nabla v)_{\mathcal{T}_{H}} = (\mathbf{f}, \mathbf{v})_{\Omega} - \langle \lambda, \mathbf{v} \rangle \quad \forall \mathbf{v} \in \mathbf{V},$$

which we may rewrite element-wise as

$$\begin{cases} -\nabla \cdot (\mathbf{A} \nabla u) = \mathbf{f} & \text{in } K, \\ \mathbf{A} \nabla u \cdot \mathbf{n}_{K} = \lambda & \text{on } \partial K, \end{cases}$$

for all $K \in \mathcal{T}_{H}$.

If λ is known, we obtain u via Neumann problems. This idea is behind the definition of multiscale shape functions. Neumann problems have a kernel: we need to extract constants.

Let
$$\mathbf{V} = \mathcal{P}_0(\mathcal{T}_H) \stackrel{\perp}{\oplus} \mathbf{V}^{\perp}$$
 and $\mathbf{u} = \mathbf{u}_0 + \mathbf{u}^{\perp}$. We have
 $(\mathbf{A} \nabla \mathbf{u}^{\perp}, \nabla \mathbf{v})_{\mathcal{T}_H} + \langle \lambda, \mathbf{v} \rangle = (\nabla \mathbf{u}, \nabla \mathbf{v})_{\mathcal{T}_H} + \langle \lambda, \mathbf{v} \rangle = \langle \mathbf{f}, \mathbf{v} \rangle$

Hence, $\mathbf{u}^{\perp} = T\lambda + \widehat{T}\mathbf{f}$, where the operators

 $(\mathbf{A}\nabla(\mathbf{T}\mu),\mathbf{v}^{\perp}) = -\langle \mu,\mathbf{v}^{\perp}\rangle \quad (\mathbf{A}\nabla(\widehat{\mathbf{T}}k),\mathbf{v}^{\perp}) = (\mathbf{k},\mathbf{v}^{\perp})_{\Omega} \quad \forall \mathbf{v}^{\perp} \in \mathbf{V}^{\perp}$

for $\mu \in \Lambda$ and $\mathbf{k} \in L^2(\Omega)$ are defined via local Neumann problem.

Recall the primal hybrid formulaion

$$\begin{cases} (\mathbf{A}\nabla u, \nabla v)_{\mathcal{T}_{H}} + \langle \lambda, v \rangle &= (\mathbf{f}, v) \quad \forall v \in \mathbf{V}, \\ \langle \mu, u \rangle &= 0 \qquad \forall \mu \in \Lambda. \end{cases}$$

the decomposition $\mathbf{u} = \mathbf{u}_0 + \mathbf{u}^{\perp}$, and $\mathbf{u}^{\perp} = T\lambda + \widehat{T}\mathbf{f}$.

It gives: Find $(\underline{u}_0, \lambda) \in \mathcal{P}_0(\mathcal{T}_H) \times \Lambda$ such that

$$\begin{cases} \langle \mu, \boldsymbol{u}_{0} \rangle + \langle \mu, T\lambda \rangle &= -\langle \mu, \widehat{T}\boldsymbol{f} \rangle \quad \forall \mu \in \Lambda, \\ \langle \lambda, \boldsymbol{v}_{0} \rangle &= (\boldsymbol{f}, \boldsymbol{v}_{0})_{\Omega} \quad \forall \boldsymbol{v}_{0} \in \mathcal{P}_{0}(\mathcal{T}_{H}). \end{cases}$$

This global saddle point problem is the MHM formulation.

The multiscale hybrid-mixed (MHM) method

The MHM method

Recall that

$$\begin{cases} \langle \mu, \boldsymbol{u}_{0} \rangle + \langle \mu, T\lambda \rangle &= -\langle \mu, \widehat{T}\boldsymbol{f} \rangle \quad \forall \mu \in \Lambda, \\ \langle \lambda, \boldsymbol{v}_{0} \rangle &= (\boldsymbol{f}, \boldsymbol{v}_{0})_{\Omega} \quad \forall \boldsymbol{v}_{0} \in \mathcal{P}_{0}(\mathcal{T}_{\mathcal{H}}). \end{cases}$$

The space $\mathcal{P}_0(\mathcal{T}_H)$ is already discrete. We thus need $\Lambda_H \subset \Lambda$.

Fixing $k \ge 0$, we consider

 $\Lambda_{H} := \{ \mu_{H} \in \Lambda \mid \mu|_{F} \in \mathcal{P}_{k}(F) \; \forall F \in \mathcal{F}_{H} \} \,.$

The MHM method consists in finding $(u_{0,H}, \lambda_H) \in \mathcal{P}_0(\mathcal{T}_H) \times \Lambda_H$ s.t.

$$\begin{cases} \langle \mu_{H}, \mathbf{u}_{0,H} \rangle + \langle \mu_{H}, T\lambda \rangle &= -\langle \mu_{H}, \widehat{T} \mathbf{f} \rangle \quad \forall \mu_{H} \in \Lambda_{H}, \\ \langle \lambda_{H}, \mathbf{v}_{0} \rangle &= (\mathbf{f}, \mathbf{v}_{0})_{\Omega} \quad \forall \mathbf{v}_{0} \in \mathcal{P}_{0}(\mathcal{T}_{H}). \end{cases}$$

and then setting

 $u_H := u_{0,H} + T\lambda_H + \widehat{T}f.$

Implementation

Step 1: consider a basis $(\mu^{\ell})_{\ell=1}^{N}$ of Λ_{H} .

Step 2: solve the local Neumann problems: find $\eta^\ell|_{\mathcal{K}}\in H^1_\star(\mathcal{K})$

$$(\mathbf{A}\nabla\eta^{\ell},\nabla\mathbf{v}_{\star})_{\mathcal{K}}=-\int_{\partial\mathcal{K}}\mu^{\ell}\mathbf{v}_{\star}\quad\forall\mathbf{v}_{\star}\in H^{1}_{\star}(\mathcal{K})$$

for all $K \in \mathcal{T}_H$. Compute $\widehat{\mathcal{T}}_f$ similarly.

Step 3: $T\lambda = \eta = \sum_{\ell=1}^{N} R_{\ell} \eta^{\ell}$, $u_{0,H} = \sum_{K \in \mathcal{T}_{H}} V_{K} \mathbf{1}_{K}$, and $\begin{cases} \langle \mu_{H}, u_{0,H} \rangle + \langle \mu_{H}, \eta \rangle &= \langle \mu_{H}, \widehat{T} \mathbf{f} \rangle \quad \forall \mu_{H} \in \Lambda_{H} \\ \langle \lambda_{H}, \mathbf{v}_{0,H} \rangle &= (\mathbf{f}, \mathbf{v}_{0,H}) \quad \forall \mathbf{v}_{0,H} \in \mathcal{P}_{0}(\mathcal{T}_{H}) \end{cases}$

Step 4: Assemble the solution

$$\boldsymbol{u}_{H} = \boldsymbol{u}_{0,H} + T\lambda_{H} + \widehat{T}\boldsymbol{f} = \sum_{K \in \mathcal{T}_{H}} V_{K}\boldsymbol{1}_{K} + \sum_{\ell=1}^{N} R_{\ell}\eta^{\ell} + \widehat{T}\boldsymbol{f}.$$

The multiscale hybrid high-order (MsHHO) method

- D. Di Pietro, A. Ern and S. Lemaire, 2014: original HHO article.
- D. Di Pietro and A. Ern, 2015: Elasticity.
- D. Di Pietro, and J. Droniou, 2017: Leray-Lions equations.
- M. Cicuttin, A. Ern and S. Lemaire, 2019: multiscale extension.

The HHO method relies on the following set of discrete uknowns

 $\widehat{\boldsymbol{U}}_{\boldsymbol{H}} := \mathcal{P}_k(\mathcal{T}_{\boldsymbol{H}}) \times \mathcal{P}_k(\mathcal{F}_{\boldsymbol{H}})$

These unknowns are respectively meant to represent $u|_{K}$ and $u|_{F}$.

The method "normally" hinges on a discrete reconstruction operator. $\mathscr{G}: \widehat{U}_H \to \nabla \mathcal{P}_{k+1}(\mathcal{T}_H)$, defined for $u := (u_T, u_F) \in \widehat{U}_H$ by

$$(\mathscr{G}\boldsymbol{u}, \nabla \boldsymbol{v})_{\mathcal{K}} = (\nabla \boldsymbol{u}_{\mathcal{K}}, \nabla \boldsymbol{v})_{\mathcal{K}} + \sum_{F \subset \partial \mathcal{K}} (\boldsymbol{u}_{F} - \boldsymbol{u}_{\mathcal{K}}, \nabla \boldsymbol{v} \cdot \boldsymbol{n}_{\mathcal{K}})_{F}$$

for all $v \in \mathcal{P}_{k+1}(K)$ and all $K \in \mathcal{T}_H$.

In the MsHHO, the "discrete" operator is replaced by local PDEs. This enables to upscale fine scale details onto the coarse mesh.

Consider the finite-dimensional space

 $\mathscr{U}_k(K) := \left\{ \mathbf{v} \in H^1(K) \mid \boldsymbol{\nabla} \cdot (\boldsymbol{A} \boldsymbol{\nabla} \mathbf{v}) \in \mathcal{P}_k(K), \ \boldsymbol{A} \boldsymbol{\nabla} \mathbf{v} \cdot \boldsymbol{n}_K |_F \in \mathcal{P}_k(F) \right\}$

and $\mathscr{U}_k(\mathcal{T}_H) := \prod_{K \in \mathcal{T}_H} \mathscr{U}_k(K).$

For all $\widehat{u} := (u_T, u_F) \in \widehat{U}_H$ and $K \in \mathcal{T}_H$, $\exists ! r_K(u) \in \mathscr{U}_k(K)$ such that

$$(\mathbf{A} \nabla r_{\mathcal{K}}(\widehat{u}), \nabla \mathbf{v})_{\mathcal{K}} = -(\mathbf{v}_{\mathcal{K}}, \nabla \cdot (\mathbf{A} \nabla \mathbf{v}))_{\mathcal{K}} + \sum_{F \subset \partial \mathcal{K}} (u_F, \mathbf{A} \nabla \mathbf{v} \cdot \mathbf{n}_{\mathcal{K}})_F (r_{\mathcal{K}}(\widehat{u}), \mathbf{1}_{\mathcal{K}})_{\mathcal{K}} = \sum_{F \subset \partial \mathcal{K}} (u_F, \mathbf{1}_F)_F$$

for all $\mathbf{v} \in \mathscr{U}_k(K)$.

Step 1: Assemble the $\mathscr{U}_k(K)$ spaces by solving local Neumann problems.

Step 2: Find dofs $\hat{u} \in \widehat{U}_H$ such that

$$\sum_{K\in\mathcal{T}_{H}}(\boldsymbol{A}\boldsymbol{\nabla}r_{K}(\widehat{\boldsymbol{u}}),\boldsymbol{\nabla}r_{K}(\widehat{\boldsymbol{v}}))_{K}=\sum_{K\in\mathcal{T}_{H}}(\boldsymbol{f},\widehat{\boldsymbol{v}}_{K})_{K}$$

for all $\widehat{\mathbf{v}} \in \widehat{\mathbf{U}}_{\mathbf{H}}$.

Step 3: Assemble the solution

$$\boldsymbol{u}_{\boldsymbol{H}} = \sum_{\boldsymbol{K}\in\mathcal{T}_{\boldsymbol{H}}} r_{\boldsymbol{K}}(\widehat{\boldsymbol{u}}).$$

MHM = HHO?

Cons:

The number of dofs does not match! The dofs of MHM correspond $u_{0,K} := \int_{K} u$ and $\lambda|_{\partial K} = \mathbf{A} \nabla u \cdot \mathbf{n}_{K}$. The dofs of MsHHO correspond to $u|_{K}$ and $u|_{\partial K}$.

The global linear systems have different features: Saddle-point for MHM, SPD for MsHHO.

Pros:

Both methods employ Neumann problems to construct the multiscale basis functions.

Theorem

For all $\mathbf{f} \in L^2(\Omega)$, there exists a unique $\mathbf{u} \in H^1(\mathcal{T}_H)$ s.t.

 $-\boldsymbol{\nabla}\cdot(\boldsymbol{A}\boldsymbol{\nabla}_{\boldsymbol{H}}\boldsymbol{u})=\boldsymbol{f}\text{ in }\boldsymbol{\Omega}$

and

$$\boldsymbol{A} \nabla_{H} \boldsymbol{u} \cdot \boldsymbol{n}_{F} \in \mathcal{P}_{k}(F) \quad (\llbracket \boldsymbol{u} \rrbracket, q)_{F} = 0 \quad \forall q \in \mathcal{P}_{k}(F)$$

for all $F \in \mathcal{T}_{H}$.

This u is linked to the solutions of MHM and MsHHO methods.

The MHM solution (1/2)

Recall that for the MHM method

$$\boldsymbol{u}_{\boldsymbol{H}} := \boldsymbol{u}_{0,\boldsymbol{H}} + T\lambda_{\boldsymbol{H}} + \widehat{T}\boldsymbol{f}.$$

Hence,

$$-\boldsymbol{\nabla}\cdot(\boldsymbol{A}\boldsymbol{\nabla}_{\boldsymbol{H}}\boldsymbol{u}_{\boldsymbol{H}}) = -\boldsymbol{\nabla}\cdot(\boldsymbol{A}\boldsymbol{\nabla}_{\boldsymbol{H}}\boldsymbol{T}\boldsymbol{\lambda}_{\boldsymbol{H}}) - \boldsymbol{\nabla}\cdot(\boldsymbol{A}\boldsymbol{\nabla}_{\boldsymbol{H}}\boldsymbol{\widehat{T}}\boldsymbol{f}) = \boldsymbol{f}$$

and

$$(\mathbf{A}\nabla_{H} u_{H}) \cdot \mathbf{n}_{F} = (\mathbf{A}\nabla_{H} T \lambda_{H}) \cdot \mathbf{n}_{F} + (\mathbf{A}\nabla_{H} \widehat{T} f) \cdot \mathbf{n}_{F} = \lambda_{H}|_{F} \in \mathcal{P}_{k}(F)$$

for all $F \in \mathcal{F}_{H}$.

By construction, the MHM solution automatically fullfils two conditions.

The MHM solution (2/2)

Recall the global MHM saddle point problem

$$\begin{cases} \langle \mu_H, \mathbf{u}_{0,H} \rangle + \langle \mu_H, T \lambda_H \rangle &= -\langle \mu_H, \widehat{T} \mathbf{f} \rangle \quad \forall \mu_H \in \Lambda_H, \\ \langle \lambda_H, \mathbf{v}_0 \rangle &= (\mathbf{f}, \mathbf{v}_0)_{\Omega} \quad \forall \mathbf{v}_0 \in \mathcal{P}_0(\mathcal{T}_H). \end{cases}$$

We may rewrite the first line as

$$\langle \mu_H, \mathbf{u}_H \rangle = 0 \quad \forall \mu_H \in \Lambda_H,$$

or after breaking the elementwise integrals, as

$$\sum_{F\in\mathcal{F}_H}(\mu_H, \llbracket \boldsymbol{u}_H \rrbracket)_F = 0 \quad \forall \mu_H \in \Lambda_H.$$

The MHM solution is the unique function of the main theorem!

One easily shows that

$$(r_{\mathcal{K}}(\widehat{\boldsymbol{\nu}}), q_{\mathcal{K}})_{\mathcal{K}} = (\widehat{\boldsymbol{\nu}}_{\mathcal{K}}, q_{\mathcal{K}})_{\mathcal{K}} \quad \forall q_{\mathcal{K}} \in \mathcal{P}_{k}(\mathcal{K})$$
$$(r_{\mathcal{K}}(\widehat{\boldsymbol{\nu}}), q_{\mathcal{F}})_{\mathcal{F}} = (\widehat{\boldsymbol{\nu}}_{\mathcal{F}}, q_{\mathcal{F}})_{\mathcal{F}} \quad \forall q_{\mathcal{F}} \in \mathcal{P}_{k}(\mathcal{F})$$

for all $\widehat{\mathbf{v}} \in \widehat{\mathbf{U}}_{\mathbf{H}}$

Since the $\widehat{\mathbf{v}}_F$ are univalued on faces, we see that

$$(\llbracket r_{\mathcal{K}}(\widehat{\mathbf{v}}) \rrbracket, q)_F = 0 \quad \forall q \in \mathcal{P}_k(F)$$

for all $F \in \mathcal{F}_{H}$.

The MsHHO solution satisfies the third condition by construction.

Recall global MsHHO problem

ŀ

$$\sum_{K\in\mathcal{T}_H} (\mathbf{A}\nabla r_K(\widehat{u}), \nabla r_K(\widehat{v}))_K = \sum_{K\in\mathcal{T}_H} (\mathbf{f}, \mathbf{v}_K)_K,$$

which we may rewrite as

$$-\sum_{K\in\mathcal{T}_{H}}(\nabla\cdot(\mathbf{A}\nabla r_{K}(\widehat{\boldsymbol{u}})),\widehat{\boldsymbol{v}}_{K})_{K}+\sum_{F\in\mathcal{T}_{H}}(\llbracket\mathbf{A}\nabla r_{K}(\widehat{\boldsymbol{u}})\rrbracket\cdot\boldsymbol{n}_{F},\widehat{\boldsymbol{v}}_{F})_{F}=\sum_{K\in\mathcal{T}_{H}}(\Pi_{k}\boldsymbol{f},\boldsymbol{v}_{K})_{K},$$

since $\nabla \cdot (\mathbf{A} \nabla r_{\mathcal{K}}(\widehat{u})) \in \mathcal{P}_k(\mathcal{K})$ and $\mathbf{A} \nabla r_{\mathcal{K}}(\widehat{u}) \cdot \mathbf{n}_F \in \mathcal{P}_k(F)$.

It follows that

$$-\nabla \cdot (\mathbf{A} \nabla_H u_H) = \prod_k \mathbf{f} \qquad \mathbf{A} \nabla u_H \cdot \mathbf{n}_F \in \mathcal{P}_k(F).$$

What have we learnt?

Whenever $f \in \mathcal{P}_k(\mathcal{T}_H)$, the MHM and MsHHO methods produce the same solution u_H .

This solution can be clearly indentified by conditions on the flux, the normal traces and the jumps.

The two methods may be seen as "dual" to each other.

The MHM method spans a space of functions such that

$$-\boldsymbol{\nabla}\cdot(\boldsymbol{A}\boldsymbol{\nabla}_{H}\boldsymbol{v}_{H})=\boldsymbol{f}\quad(\boldsymbol{A}\boldsymbol{\nabla}_{H}\boldsymbol{v}_{H})\cdot\boldsymbol{n}_{F}\in\mathcal{P}_{k}(F)$$

for all $F\in \mathcal{F}_{H}.$ Weak continuity is enforced by the global system

$$(\llbracket u_H \rrbracket, q)_F = 0 \quad \forall q \in \mathcal{P}_k(F).$$

The MsHHO method works exactly the other way around.

We hope this work will shed a new light on the design of skeletal based multiscale methods.

We believe that several opportunities of improvement will arise in the future. For example, saddle-point MHM problems can be replaced by MsHHO SPD problems.

Thanks for you attention!