Mitigating Unintended Bias in Masked Language Models
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Mitigating Unintended Bias in Masked Language Models

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A thesis submitted in fulfillment of the requirements for the degree of Master of Science in LACODAM, INRIA Rennes-Bretagne Orpailleur, LORIA

September 9, 2021
Declaration of Authorship

I, Mohammed Rameez Qureshi, declare that this thesis titled, “Mitigating Unintended Bias in Masked Language Models” and the work presented in it are my own. I confirm that:

- This work was done wholly or mainly while in candidature for a research degree at this University.
- Where any part of this thesis has previously been submitted for a degree or any other qualification at this University or any other institution, this has been clearly stated.
- Where I have consulted the published work of others, this is always clearly attributed.
- Where I have quoted from the work of others, the source is always given. With the exception of such quotations, this thesis is entirely my own work.
- I have acknowledged all main sources of help.
- Where the thesis is based on work done by myself jointly with others, I have made clear exactly what was done by others and what I have contributed myself.

Signed:  

Date: 24/08/2021
“It is what you read when you don’t have to that determines what you will be when you can’t help it.”

Oscar Wilde
Algorithmic fairness is currently one of the most debated topics in artificial intelligence. Primarily because of its massive importance and critical impact on various aspects of human lives. One of its highly discussed drawbacks is the unintended bias we observe in complex machine learning models, and that carries adverse effects on various fields ranging from healthcare to legal policing.

This work focused on devising novel methodologies for mitigating unintended bias found in language models. Our work mainly concerned the gender bias associated with occupations. However, it can be extended to other kinds such as demographic, racial, etc. As the definition of bias is subjective and varies case by case, it is challenging to measure and reduce biases in pre-trained language models.

This work proposes an advanced architecture based on Deep Reinforcement Learning to mitigate unintended bias in pre-trained language models. The proposed architecture tackles withstanding challenges without compromising performance and defines a system that is portable and easy to adapt.

The thesis is organised as follows. After defining the problem statement in Chapter 1, we lay down the pre-requisites required for this study in Chapter 2. In the following two chapters, we detail the proposed architecture and the experimental setup used for evaluation. Chapter 5 comprises a discussion based on the results and possible explanations of the model’s behaviour. Finally, in Chapter 6, we discuss the limitations as well as promising perspectives for future work.
Mitigating Unintended Bias in Masked Language Models

by Mohammed Rameez Qureshi
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# Contents

Declaration of Authorship ........................................................................................................ iii

Abstract ........................................................................................................................................ vii

Acknowledgements ................................................................................................................... xi

## 1 Introduction

1.1 Problem Statement .................................................................................................................... 1

1.2 Background Study .................................................................................................................... 2

1.3 Research Environment .......................................................................................................... 4

1.3.1 Orpailleur ......................................................................................................................... 4

1.3.2 LACODAM ...................................................................................................................... 5

## 2 Preliminaries

2.1 NLP and Language Models .................................................................................................... 7

2.1.1 Language Models ............................................................................................................. 7

2.1.2 Transformers ................................................................................................................... 8

2.1.3 BERT Fine-Tuning and Distillation ................................................................................. 9

2.2 Deep Reinforcement Learning ............................................................................................... 10

2.2.1 Policy .............................................................................................................................. 10

2.2.2 Expected Rewards .......................................................................................................... 11

2.2.3 How to learn a Policy? .................................................................................................... 11

2.2.4 Policy Gradient methods ............................................................................................... 12

2.2.5 Contextual Bandits ........................................................................................................ 12

2.3 Evaluating Racial Bias in LM ............................................................................................... 13

2.3.1 Metrics to calculate Bias in QA/LM models ................................................................... 13

2.3.2 Calculating Bias ............................................................................................................. 15

2.3.2.1 Positional Dependence ............................................................................................ 15

2.3.2.2 Attribute Independence .......................................................................................... 16

2.3.3 Aggregated Metrics ........................................................................................................ 17

## 3 Contribution

3.1 Architecture ........................................................................................................................... 19

3.1.1 Language Model as Contextual Bandit ......................................................................... 19

3.1.2 Reward Function ........................................................................................................... 20

3.1.3 Policy Updation ............................................................................................................. 21
4 Experimental Setup .................................................. 25
   4.1 Dataset ............................................................. 25
   4.2 Baselines .......................................................... 25
   4.3 Training Settings .................................................. 26
   4.4 Hyperparameters .................................................. 28

5 Results ................................................................. 29
   5.1 Bias Evaluation ...................................................... 29
      5.1.1 Overall Performance ......................................... 29
      5.1.2 Reasoning Errors ............................................ 30
      5.1.3 Understanding the reward function ....................... 31
      5.1.4 Learning Rate ............................................... 34

6 Conclusion .......................................................... 35
   6.1 Limitations ......................................................... 35
   6.2 Future Directions .................................................. 35
   6.3 Broader Impact ..................................................... 36

Bibliography ............................................................ 37
Chapter 1

Introduction

1.1 Problem Statement

With the onset of complex language modelling architectures and large text corpora, we are witnessing a massive leap in terms of tasks automation in the field of Natural Language Processing. With such nuanced deep learning techniques, it seems like we are more equipped than ever to tackle the arising problems in NLP. However, solutions seldom come with new problems, and this statement seems true when it comes to modern language models used at production levels nowadays. One such problem is the presence of stereotypical bias in almost every leading language model we use.

Several works have reported the evidence of biases present in language models. Whether geographical or gender-oriented, modern language models represent biased opinions in various settings and use cases. Although having an ample amount of evidence, relatively fewer works have been proposed to mitigate these biases. Mitigating bias in language models is a crucial aspect of the artificial intelligence domain. The reason being promoting the trustworthiness of AI. The more we rely on AI models, the more critical it is to win users’ confidence. The motive is to generate reliable technologies and does not carry forward the societal bias with it. Works like Caliskan, Bryson, and Narayanan, 2017 illustrated how human-like biases could be incorporated in semantics, leading to a biased language model. The fiasco associated with Microsoft’s Chatbot Tay is a glaring example of this issue. Tay managed to become racist within a day of its deployment, after which it had to be taken down with an apology from Microsoft. Another interesting case is related to the case management and decision support tool COMPAS 1 used by US courts to assess the likelihood of a defendant becoming a repeat offender. Recent reports published by a non-profit new organisation, ProPublica 2, suggests that there is an inherent bias in COMPAS raising false flags for Black defendants. With these examples, one can imagine the potential these biased models have of adversely affecting ordinary lives. Concerning bias in the language models, recently, a team at AllenAI 3 reported how language models are biased demographically. Figure 1.1 shows the areas in red to which the language models associate with negative attributes (or sentiments) while blue areas are often associated with positive attributes. Observe that most of the red coloured regions are located Middle-East, Central-America and some in Western Asia.

There are several challenges one could face while mitigating bias in machine learning models. One of them is that bias is a subjective topic and could vary case by case. Hence, it is not easy to come up with a general definition of the same.

1 Correctional Offender Management Profiling for Alternative Sanctions
2 Machine Bias in Criminal Sentencing
3 Allen Institute for AI
Chapter 1. Introduction

Figure 1.1: Map showing the attribute association of language model demographically. Red colour labels the areas associated with negative attributes, while blue colour represents association with positive attributes (Li et al., 2020).

Secondly, even after defining bias, the concern should be to reduce only the negative bias/prejudice [Caliskan, Bryson, and Narayanan, 2017] while retaining the model’s performance. Thirdly, most of the approaches proposed for debiasing language models include fine-tuning handcrafted datasets and downstream tasks. Such a process demands human resources, hence expensive, and are potentially vulnerable to qualitative issues.

This project aims to develop an approach to mitigate bias in advanced language models without relying on downstream tasks and handcrafted datasets. Another target is to design a framework adapted to a broader range of biases and use cases to enhance the portability of the developed architecture. Therefore, we intend to avoid retraining the model from scratch, perhaps relying on Deep Reinforcement Learning to fine-tune the already available models.

1.2 Background Study

As stated in the previous section, the problem discussed in this work has two main facets. The first one, and the most important one, is to reduce the racial bias in language models. Secondly, the process should not rely on human intervention as much as possible while fine-tuning the models. The reason being, no matter how carefully one can plan to have a human supervised dataset/framework, it is prone to inherent human biases. In this section, related works to these two facets will be discussed one by one.

Starting with the work done to study racial bias in language models, one of the most celebrated works is by Davidson, Bhattacharya, and Weber, 2019. In this work,
the authors examine the racial bias in five different sets of Twitter data annotated for hate speech and abusive language. This work reports evidence of systematic racial bias in all the analysed datasets. For instance, the tweet was written in African American English (AAE) are more prone to false-positive results for being abusive than Standard American English (SAE) Tweets. These findings hint at a potential threat to hate speech monitoring systems because the systems that are designed to protect the target of online abuse might discriminate against the same group due to such inherent biases. Similar findings have been reported in the work Mozafari, Farahbakhsh, and Crespi, 2020, in which they trained a classifier on two Twitter datasets. Results suggest that tweets written in AAE are tagged sexist, racist and offensive more often than similar tweets written in SAE.

Therefore, it is evident that a systematic bias is induced in datasets and, subsequently, machine learning models. However, to mitigate such biases, the first challenge is defining and tracing bias to its source. Caselli et al., 2020 suggests that however various datasets are available to study different kinds of abuses, there are still no datasets that take into account the degree of explicitness, i.e., the extent to which the text is perceived as abusive without deciphering any possible hidden meaning it may have. This classification can further lead to a more nuanced study of bias, differentiating implicit and explicit abuse. Another challenge is defining “bias”, as bias is subjective and may vary case by case. Caliskan, Bryson, and Narayanan, 2017 gave an interesting take on this matter and suggested that ‘bias’ refers to prior information, and hence it is an essential part of intelligence. Also, measures should be taken to mitigate only a particular case of bias, which they termed as prejudice. The authors defined prejudice as the particular case of bias that is identifiable of its negative consequences. Also, as the definition of negative varies by use case, it is challenging to eliminate prejudice fully algorithmically. Nevertheless, there are still some rational ways of defining bias to machines for common bias categories, as can be seen in works like Li et al., 2020.

Although mitigating bias is a challenging task, as explained above, various works have been dedicated to eradicating bias in language models. For instance, Mozafari, Farahbakhsh, and Crespi, 2020 used a pretrained BERT-based model and fine-tuned it on annotated datasets based on Twitter. They showed reduced bias using the F1-measure on the test datasets provided by Davidson, Bhattacharya, and Weber, 2019. However, while testing their de-biased models using a cross-domain approach, they found that the de-biased models still have systematic and substantial biases. After further analysis, the authors hint at the general inherent knowledge of BERT pretrained models as the reason behind the prevailing bias. Hence, it is challenging to track down the inherent model’s biases and mitigate them for a general use case. This indicates that the varying definition of bias limits the portability of such models.

Other measures to mitigate racial bias include the work of Zhao et al., 2019, and Basta, Costa-jussà, and Casas, 2019, where the authors discovered bias in ELMo contextual embeddings and showed that bias translates into downstream tasks as well. However, they did not consider the language generation by ELMo for evaluation. In contrast to these works, Huang et al., 2019 presents another effective strategy for mitigating bias. In this work, the authors probed test generated by language models (GPT-2) using a sentiment analysis system. Once the model’s fairness has been quantified using a metric based on Wasserstein distance to reduce counterfactual sentiments bias, the work suggested the use of embedding and sentiment-prediction derived regularisation on the language model’s latent representations to mitigate bias associated with sentiments. This work deals with comparatively complex language...
model, although, only targeted sensitive attributes with minor impacts, such as occupation, country names, etc., and skips more general attributes such as religion, ethnicity, etc., and multiple attributes simultaneously.

1.3 Research Environment

During the internship, I carried out my research work in INRIA within the framework of the Orpailleur (LORIA) and LACODAM (IRISA) teams. These teams are a part of Inria Project Lab called HyAIAI, which conducts research in novel interpretable approaches for Artificial Intelligence. Due to the broad competencies ranging from knowledge discovery and neural networks to explainability and fairness of the teams, I thoroughly enjoyed the rich and engaging work environment at both places. Below is a short brief description of both teams and their areas of expertise.

1.3.1 Orpailleur

The three main scientific objectives of the Orpailleur Team are: (1) Fundamentals of Knowledge Discovery in Databases (KDD), (2) KDD in practice, and (3) Explanations and Fairness in KDD. KDD aims at discovering intelligible and reusable patterns in possibly large and complex databases. From an operational point of view, the KDD process is based on three main steps: (i) selection and preparation of the data, (ii) data mining, (iii) interpretation of the discovered patterns. Moreover, the KDD process is iterative, interactive, and “exploratory”, i.e. controlled by an expert of the data domain, called the analyst. As implemented in the Orpailleur team, the KDD process is based on data mining methods that are either symbolic or subsymbolic (numerical). Symbolic methods are based on pattern mining, Formal Concept Analysis (FCA) and extensions. Subsymbolic methods are based on classifiers such as Random Forests, SVM, and Neural Networks. Then the main objective is to mine complex and possibly large data in combining symbolic and subsymbolic data mining methods to improve KDD’s applicability and explainability and make KDD more “reliable”. In this way, domain knowledge may improve and guide the KDD process, leading to “Knowledge Discovery guided by Domain Knowledge” (KDDK). The discovered patterns can be interpreted as knowledge units and reused for problem-solving activities in knowledge systems. Thus, knowledge discovery can be considered a key task in knowledge engineering, impacting various semantic activities, e.g. information retrieval, recommendation, and ontology engineering. Recent advances in KDD and in Machine Learning (ML) are primarily due to the success of deep learning methods in recognition tasks. However, deep learning and, in general, subsymbolic data mining methods are based on complex models whose outputs and proposed decisions, as accurate as they are, cannot be easily explained to the layman. Accordingly, we are studying how to design hybrid and more interpretable KDD methods, combining complex subsymbolic models and explainable symbolic models. In addition, explanations can be used to assess algorithmic fairness, which is a critical point, especially in decision support systems with societal and scientific impacts. That became another topic in the team. Regarding applications, the team mainly works in life sciences, i.e. agronomy, biology, chemistry, medicine, pharmacogenomics, and as well in astronomy and in the web of data. Text mining is of major interest for the team and appears to be a ground task in many applications. Indeed it has gained a lot of attention in the last years, especially with the progress due to deep learning systems. The Orpailleur team has a
rich experience in KDD and intends to improve and to extend this experience, also paying more attention to the impact of knowledge discovery in the real world. This should lead to the design of interpretable (Molnar, 2019), explainable (Bazin et al., 2020, Garreau and Luxburg, 2020), and fair (Alves et al., 2021, Bhargava, Couceiro, and Napoli, 2020, Speicher et al., 2018) data mining systems.

### 1.3.2 LACODAM

LACODAM\(^4\), which stands for LArge scale COllaborative Data Mining, is a research team at the IRISA/Inria research lab in Rennes. The objective of the LACODAM is to facilitate the process of making sense out of (large) amounts of data. This can serve the purpose of deriving knowledge and insights for better decision-making. The approaches developed by the team are mostly dedicated to provide novel tools to data scientists, that can either perform tasks not addressed by any other tools, or that improve the performance in some area for existing tasks (for instance reducing execution time, improving accuracy or better handling imbalanced data).

The research of the LACODAM project team is organised around four research axes, the first three being based on the long-standing research interests of the team members, and the last one (interpretability) being a topic that emerged more recently in the machine learning community:

- **The first research axis** is dedicated to the design of novel pattern mining and machine learning methods. Pattern mining is one of the most important approaches to discover novel knowledge in data, and one of the team’s strongest areas of expertise. Machine learning (ML), especially classification, is the basis for many decision support systems. The work on this axis will thus serve as foundations for work on the other two axes.

- **The second axis** tackles another aspect of knowledge discovery in data: the interaction between the user and the system in order to co-discover novel knowledge. The team has plenty of experience collaborating with domain experts and is therefore aware of the need to improve such interaction.

- **The third axis concerns decision support.** With the help of methods from the two previous axes, the goal here is to design systems that can either assist humans with making decisions or make relevant decisions in situations where extremely fast reaction is required.

- **The fourth axis concerns interpretable machine learning** and can be considered as a transversal axis that has roots in all the other three axes.

\(^4\)https://team.inria.fr/lacodam/
Chapter 2

Preliminaries

This chapter discusses the preliminary concepts our project builds upon and establishes the necessary notations used in this work. The methodologies used are based on two major machine learning fields, namely Natural Language Processing (NLP) and Reinforcement Learning (RL). Apart from the machine learning related concepts, another significant part of this work revolves around "How to evaluate the racial bias in LM?". Hence the following sections are divided into these three sections, respectively. The first section deals with the concepts related to NLP and language models used in this work. Similarly, the second section covers the basic formulations of reinforcement learning leading to the more nuanced Deep Reinforcement Learning concepts. Finally, we will discuss the evaluation methods we have used in this study to quantify racial bias in language models.

2.1 NLP and Language Models

As the objective of this work deals with the racial bias mitigation in language models, it is logical to understand the functioning of these models before proceeding to fine-tuning them. Hence, this section deals with the basic terminologies used for natural language models and their working.

2.1.1 Language Models

Language modelling is a well-known technique used to model the probabilities of a given word sequence. Language models use various statistical and probabilistic techniques to formulate the probability distribution of input words or word sequences. These are heavily used in NLP for a wide variety of tasks, including natural language generation and question answering. Generally, language models can be divided into two major categories, viz., probabilistic and neural network-based methods. Although probabilistic methods are relatively older and have more limitations, they own the credit to lay down the foundation of the methods used even today as the reference for advanced models. One of the most common approaches is calculating n-gram probabilities. Here, the n-gram probability is the conditional probability of the n-gram in a given word sequence. Such methods proved helpful in most essential tasks such as classification and part of speech (POS) tagging; however, they fall behind in performance where longer dependencies are required to be modelled—the reason being the limitation of the windows of words to be considered for calculating the conditional probability. Therefore, probabilistic methods suffer from capturing contextual information present in a word sequence. This factor affects the scalability of these methods.

Additionally, non-occurring n-grams result in sparsity problem, i.e., the words occurring less ends up having a similar probability to the other less frequent but
different words. To solve this challenge, neural network-based approaches are employed and has been successful so far. Common approaches include Continuous Bag of Words (CBOW), Recurrent Neural Network (RNN) based approaches including LSTM and GRU and more recently, the transformers based models. Given the state of the art performance of transformer-based models, we decided to base our hypothesis on the most widely used models to enhance the impact of this work. Hence, this work is based on the racial bias found in pretrained BERT architecture. Although, the hypothesis can be easily adapted to other architectures as well. More details about the transformers and the variant used in this work can be found in the following section.

### 2.1.2 Transformers

As discussed above, to model contextual information, RNN based models are preferred above probabilistic models. The reason being their capability to model longer sequential information and retaining context. This can be achieved due to the RNN’s sequential architecture, where information flows in steps where certain mechanisms are used to carry forward the important information in the subsequent cells and dissipate the information which is not useful. This architecture thrived in retaining the context due to its unique architecture and gracefully handles the sparsity problem. However, RNNs still struggle in retaining context when a long sentence is fed. It has been observed that they often forget the first part once the whole output is processed. This drawback motivated the arrival of attention mechanisms.

The sole purpose of the attention mechanism is to memorise the longer sentence. More formally, attention is introduced as a component in the network that quantifies the interdependence between the input and output elements (irrespective of their individual lengths). If this interdependence is calculated within the input, it is termed as *self-attention*. This is the secret sauce behind the widely acclaimed work "Attention Is All You Need" by Vaswani et al., 2017. This work proposed a novel architecture, called a transformer, which is based on an attention mechanism to learn contextual
2.1. NLP and Language Models

Figure 2.2: Pre-training and fine-tuning procedures for BERT. Devlin et al., 2018

relations between words (or sub-words) in a given text. This work proposes an alternative method to do seq2seq modelling without recurrent network units. This architecture utilises self-attention entirely without being dependent on sequential recurrent networks. Therefore, reading text sequentially, the transformers encoder reads the entire sequence at once; hence it is non-directional. This allows the model to capture the information irrespective of the direction of the words, i.e., both from left and right, simultaneously.

2.1.3 BERT Fine-Tuning and Distillation

Building upon the idea of self-attention, Devlin et al., 2018 proposed an architecture called BERT. The novelty of this architecture comes with its capability to model the language bidirectionally with the help of the Masked LM technique, which was impossible before. Another advantage of this architecture is its capability to adapt to different use cases. During fine-tuning the BERT model, most of the hyper-parameters can remain the same. Just with training final additional task-specific layers, BERT outperformed various state of the art models. An overview of the pre-training and fine-tuning process can be found in the figure 2.2. Please observe that the same architecture has been used during pre-training and fine-tuning except for the output layers. Therefore, the same pre-trained parameters can be used to initialise the model for fine-tuning irrespective of the downstream task. One can also freeze several layers for fine-tuning and choose not to update the parameters in the chosen layers apart from the output layer. This allows the user more control over the performance of the models.

This impressive performance comes with a cost, and that is, in this case, is the cost and energy inefficiency of such complex models. However, to tackle this problem, researchers proposed various knowledge distillation techniques. Knowledge distillation is defined as the compression technique which is used to train a smaller model with the help of a larger model to replicate its behaviour. In this manner, we can get a lighter and responsive model with almost equal performances. One such widely variant of BERT is known as DistilBERT. DistilBERT has around half of the total number of parameters of BERT and still retains 95% of the original BERT’s performance. Due to its cost-effectiveness, Masked Language Model based on DistilBERT is used. However, the methodology is still applicable to other variants of the same.
2.2 Deep Reinforcement Learning

Another important aspect of this work is the application of Deep Reinforcement Learning (DRL). Reinforcement learning was proposed to tackle the problems where there is an agent that needs to interact with the environment, more commonly in robotics or self-driving cars. However, with the advent of DRL, various avenues have been opened up more recently. Due to the involvement of neural networks, it has become easier to implement RL techniques in a plethora of deep learning problems, including NLP. Before discussing the details of our implementation of DRL in NLP, let us discuss some crucial concepts of RL in the remaining part of this chapter.

As the name suggests, DRL combines deep neural networks with reinforcement learning to help the agents learn to reach their goals. This is achieved by merging the function approximation and target optimisation. As reinforcement learning algorithms are goal-oriented algorithms trying to maximise the outcome of the series of actions, in the long run, the neural network helps to models these outcomes at each step to guide the agent towards a profitable path. Below are some standard terms used in DRL literature and could come in handy in the sections to follow.

The general setting of RL includes an agent with an action set $A$. The challenge is to train the agent to choose the action from $A$ to maximise the final outcome while interacting within the environment. More formally, the agent starts at state $s_0 \in S$ ($S$ is the state space in the environment) with the initial observation $w_0$. At each time step, the agent has to choose an action $a_t \in A$. Subsequently, based on the action taken, the agent receives a reward and the agent moves to state $s_{t+1}$ with the observation $w_{t+1}$. This process is illustrated in the figure 2.3.

2.2.1 Policy

A policy is the set of rules, which decides how the model would react in a given condition. Formally, the policy defines how an agent selects actions. Policies can be categorised as deterministic or stochastic.

- In the deterministic case, the policy is described by a function $\pi(s) : S \rightarrow A$.

- In the stochastic case, the policy is described by a function $\pi(s, a) : S \times A \rightarrow [0, 1]$ where $\pi(s, a)$ denotes the probability that action $a$ may be chosen in state $s$.

As we are dealing with language models, our problem falls in the category of stochastic policies.
2.2.2 Expected Rewards

Here, we consider an RL agent whose goal is to define a policy \( \pi(s,a) \in \Pi \), so as to optimise an expected return \( V^\pi(s) : S \to \mathbb{R} \) (also called the V-value function) such that:

\[
V^\pi(s) = \mathbb{E}\left[ \sum_{k=0}^{\infty} \gamma^k r_{t+k} | s_t = s, \pi \right]
\]  

(2.1)

where:

- \( r_t = \mathbb{E}_{a \sim \pi(s_t, \cdot)} R(s_t, a, s_{t+1}) \). This function gives the expected reward when the agent chooses an action \( a \) to transition from state \( s_t \) to state \( s_{t+1} \) at time \( t \), where the expectation \( \mathbb{E} \) is based on the distribution given by the policy \( \pi \).

- \( \mathbb{P}(s_{t+1}|s_t, a_t) = T(s_t, a_t, s_{t+1}) \) with \( a_t \sim \pi(s_t, \cdot) \). Here \( T(s_{t+1}, s_t, a_t) \) is the transition probability for reaching the state \( s_{t+1} \) from state \( s_t \) with action \( a \). \( \mathbb{P}(s_{t+1}|s_t, a_t) \) is used to calculate the expectation of the agent’s trajectory in 2.1.

Therefore, the optimal expected return can be defined as

\[
V^*(s) = \max_{\pi \in \Pi} V^\pi(s).
\]

A few other functions of interest are based on Q-value. The Q-value function \( Q^\pi(s, a) : S \times A \to \mathbb{R} \) can be defined as follows:

\[
Q^\pi(s, a) = \mathbb{E}\left[ \sum_{k=0}^{\infty} \gamma^k r_{t+k} | s_t = s, a_t = a, \pi \right].
\]  

(2.2)

Intuitively, Q-value allows us to find the best action for each given state in the trajectory to gain the maximum reward in the end while following a policy \( \pi \). Similarly to the V-value function, this optimal Q value function can also be written as:

\[
Q^*(s, a) = \max_{\pi \in \Pi} Q^\pi(s, a).
\]

The particularity of the Q-value function as compared to the V-value function is that the optimal policy can be obtained directly from \( Q^*(s, a) \):

\[
\pi^*(s) = \arg\max_{a \in A} Q^*(s, a).
\]

The optimal V-value function \( V^*(s) \) is the expected discounted reward when in a given state \( s \) while following the policy \( \pi^* \) thereafter. The optimal Q value \( Q^*(s, a) \) is the expected discounted reward when in a given state \( s \) and for a given action \( a \) while following the policy \( \pi^* \) thereafter. Another vital function is the advantage function which is used to describe how much better action is, as compared to the expected return when following directly policy \( \pi \). The advantage function is defined as:

\[
A^\pi(s, a) = Q^\pi(s, a) - V^\pi(s).
\]

2.2.3 How to learn a Policy?

So far, we have discussed the basic terminologies of RL; however, the crucial part of devising a suitable strategy is to learn a policy. There are three different components attached to an RL agent which can be learned, namely,
• a representation of a value function that provides a prediction of how good each state or each state/action pair is,

• a direct representation of the policy \( \pi(s) \) or \( \pi(s,a) \), or

• a model of the environment (the estimated transition function and the estimated reward function) in conjunction with a planning algorithm.

The first two approaches come under the section model free RL, whereas the third one is classified as model-based RL. Given the nature of our problem that deals with the language models, we will only be concentrating on model-free RL. Language models can be treated as policies that furnishes a probability distribution when given inputs based on the tasks. Therefore, we can rely on model-free RL techniques, specifically Policy Gradient methods, for updating the policy (or, say, fine-tuning language models). More details about the Policy Gradient methods can be found in the following sections.

2.2.4 Policy Gradient methods

Policy gradient methods comprise the most common techniques for policy learning and belong to a broader class of policy-based methods, including evolution strategies. These methods are used to optimise a parameterised policy in order to maximise the cumulative reward with the help of gradient ascent.

Stochastic Gradient Policy

The expected return of a stochastic policy \( \pi \) starting from a given state \( s_0 \) from the above equation of \( V^\pi(s_0) \) can be written as

\[
V^\pi(s_0) = \int_s \rho^\pi(s) \int_a \pi(s,a)R'(s,a)dads, \tag{2.3}
\]

where \( R'(s,a) = \int_{s' \in S} T(s,a,s')R(s,a,s') \) and \( \rho^\pi(s) \) is the discounted state distribution defined as

\[
\rho^\pi(s) = \sum_{t=0}^\infty \gamma^t Pr\{s_t = s|s_0, \pi\} \tag{2.4}
\]

With these equations, we can derive a fundamental result for the differentiable policy \( \pi_w \) given by

\[
\nabla_w V^{\pi_w}(s_0) = \int_s \rho^{\pi_w}(s) \int_a \nabla_w \pi_w(s,a)Q^{\pi_w}(s,a)dads. \tag{2.5}
\]

With the above equation, one can modify the policy parameters \( w : \nabla w \propto \nabla_w V^{\pi_w}(s_0) \) as we gain experience. With further simplification, the above equation can be modified to a simpler version, which is used to derive a general method of estimating gradients from expectations.

\[
\nabla_w V^{\pi_w}(s_0) = E_{s \sim \rho^{\pi_w}, a \sim \pi_w}[\nabla_w (\log \pi_w(s,a))Q^{\pi_w}(s,a)]. \tag{2.6}
\]

With the approach, it is clear that the policy gradients method includes two steps. First is the policy evaluation step, in which we estimate the \( Q^{\pi_w} \). Secondly, the policy
2.3. Evaluating Racial Bias in LM

The improvement step takes a gradient step of optimising the policy $\pi_w(s,a)$ concerning the value function estimation. Also, usually advantage value function $A^\pi_w(s,a)$ is used instead of $Q^\pi_w(s,a)$, as it compares each action with the expected return at the stats $s$, and is of lower magnitude.

2.2.5 Contextual Bandits

Contextual Bandits (CB) architecture is the simplification of general RL architecture where there is only one state, and hence no state transition occurs. In CB, our agent still chooses an action to act to obtain the respective reward. However, the difference here is that the agent can take multiple consecutive actions and the rewards are sparse. For example, given a context to the agent, the agent will choose a series of actions until it reaches the final stage to achieve the reward. Hence, assigning rewards to individual actions is complex, and thus this leads to slow training as well sometimes. However, in our setting, this approach matches the reward function we used (described in Chapter 3) and hence, the contextual bandit is the optimum approach to implement in this work. An overview of how RL and CB are different is outlined in figure 2.4.

2.3 Evaluating Racial Bias in LM

As discussed in Section 1.2, the usual approach to quantify bias is by human evaluation. Given the proper demographic distribution of the annotators, this approach allows researchers to have a fair perspective of the problem at hand. However, various recent works, including Davidson, Bhattacharya, and Weber, 2019, suggests that even domain experts and activists as annotators are prone to racial bias. Also, it is challenging to develop a "one size fits all" approach for every kind of bias without any involvement of human subjects. Another challenge is to develop a stable definition of bias that suits as much as possible use cases.

Given the above challenges, the most promising approach to quantify racial bias is proposed by Li et al., 2020. In this work, the authors proposed a framework, UnQover, to quantify racial bias in question answering and masked language models. The UnQovering framework revolves around the inconsistencies of models’ predictions when asked a set of questions with a single context. More formally, the authors introduced "under-specified questions" to estimate the bias in language models. With this approach, authors demonstrated a wide array of biases present in
UnQovering framework puts forward two interesting ideas to study stereotypical bias in language models. Firstly, it argues that basing a new hypothesis just on the predicted probabilities from the models might lead us to the wrong way. The reason being inconsistencies in the model predictions due to two confounding factors: (1) position of subjects in the context and (2) negation of the question. Authors showed that language models are prone to such changes, and using predictions straight out of the model may be destructive. Secondly, to probe the bias, authors defined underspecified questions to make sure that the bias represented due to the model prediction is indeed its inherent bias, not something induced by external factors.

**Underspecified Questions**

The basic structure of an underspecified question includes three main elements. Firstly, the paragraph that includes neutral information about the scene or context is used to guide the prediction and quantify any bias in the prediction. Secondly, the subjects or the potential answers we want to observe, such as John/Mary or he/she. Thirdly, the attributes are the information being asked to model about the subjects (e.g., occupation, religion, etc.). Some examples of possible templates of underspecified questions can be found in the figure 2.5

Underspecified questions are introduced to ensure that the stereotypical does not inadvertently introduce them in the context/template. For this, underspecified questions are designed in such a way that:

- each subject in the context is equally likely as the answer (for instance, no demographic information provided).
2.3. Evaluating Racial Bias in LM

- attributes included in the template should not favour any subject in an ideal (unbiased) case.

The recipe to form such templates is to follow a standard procedure while using different combinations of context, subjects and attributes. Also, similar to QA models, one can also calculate the bias in masked language models with some changes in the standard recipe. That is, instead of asking a question, one can mask the required word to calculate the score in masked language models. A comparison between the differences between templates for QA models and masked language models can be seen in the figure 2.6.

2.3.1 Metrics to calculate Bias in QA/LM models

After discussing the nature of the underspecified question templates, the next step is to understand the reasoning errors the authors suggested. Furthermore, they laid out a metric to quantify the stereotypical bias in LM while taking consideration of reasoning errors. Regarding reasoning errors, the UnQover framework considers two kinds of errors: Positional Dependence and Attribute Independence. These two conditions have been discussed below briefly. Nevertheless, before that, let us define some useful notations. Let $S(x_1|\tau_{1,2}(a))$ denote the probability assigned by the model for $x_1$ being the answer when served with the template $\tau_{1,2}(a)$ with subjects $x_1$ and $x_2$ and attribute $a$. Please check table 2.1 for brief definitions of notations and their examples. For QA models, unnormalised probabilities of the span $x_1$ and $x_2$ have been used, as normalisation can amplify the biases. Similarly, for Masked LM, unnormalised scores for a single token has been considered.

**Positional Dependence**

This dependence stresses the performance of the model when the subjects get flipped in the template. More formally, let us say if the model is tested in two different conditions with two different templates. In first case, we provide the model with the template $\tau_{1,2}(a)$ with the subject $x_1, x_2$ and attribute $a$. Similarly, the second template is the same as the first one, but the subjects flipped, i.e., $\tau_{2,1}(a)$. Ideally, a language model with perfect understanding would give similar answers in both the conditions, more formally, expectations are $S(x_1|\tau_{1,2}(a)) = S(x_1|\tau_{2,1}(a))$. However, that is not the case as per what is reported in the work Li et al., 2020. An example of such a case can be observed in the figure 2.7.

[FIGURE 2.6: Unspecified question template in case of QA model (upper) and Masked Language Model (below).]

- \( [x_1] = \text{John}, [x_2] = \text{Mary}, [a] = \text{was a senator} \)
- **Paragraph:** John got off the flight to visit Mary.
- **Question:** Who was a senator?
- **Template:** \([x_1] \text{ got off the flight to visit } [x_2].\)
- **[MASK]** \([a].\)
- **Example:** John got off the flight to visit Mary.
- **[MASK]** was a senator.
Chapter 2. Preliminaries

Notation | Definition
---|---
Template \((\tau_{1,2}(a))\) | It is the combination of context \(\tau\) with two subjects \(x_1, x_2\) and attribute \(a\). Check figure 2.6 for example.

Context \((\tau)\) | Defines the scene which encompasses the event including two subjects. Examples: sent a letter, got off the flight to visit, etc.

Subjects \((x_1, x_2)\) | Comprises the pair of nouns related to the concerned property (gender in our case) to evaluate the bias. Examples: (James, Mary), (Patricia, John), etc.

Attributes \((a)\) | Defines the property on which the bias is measured (occupation in our case). Examples: dentist, accountant, etc.

| Table 2.1: Common notations and their definitions.

To quantify the positional dependence, authors suggested a metric \(\rho(x_1, x_2, a, \tau)\) which is calculated as follows:

\[
\rho(x_1, x_2, a, \tau) = |S(x_1|\tau_{1,2}(a)) - S(x_1|\tau_{2,1}(a))|
\]  

(2.7)

Intuitively, if we want to aggregate this metric across all the templates to quantify model’s positional dependence, another metric \(\bar{\rho}\) that is the average of \(\rho(x_1, x_2, a, \tau)\) can be defined.

\[
\bar{\rho} = \text{avg}_{x_1 \in X_1, x_2 \in X_2, a \in A, \tau \in T} \rho(x_1, x_2, a, \tau)
\]  

(2.8)

where \(\text{avg}\) is the arithmetic mean over subject sets \(X_1, X_2\), attribute set \(A\) and Template set \(T\). An overview of sets \(X_1, X_2, A\) and \(T\) can be found in table 4.2 and figure 4.3.

Attribute Independence
Another unusual snag is the model inability to capture the changes made to attribute, more specifically if we negate the attribute. That is, if the model is posed with the template \(\tau_{1,2}(\overline{a})\) instead of \(\tau_{1,2}(a)\), the model expected to capture this subtle difference and act accordingly. For example, in the figure 2.7, the value of \(S(\text{Gerald}|\tau_{1,2}(a))\) should be similar to the value of \(S(\text{Jennifer}|\tau_{1,2}(\overline{a}))\) (i.e., when the attribute is negated). However, it is not the case as can be observed in the figure 2.7. Please observe that \(S(\text{Gerald}|\tau_{1,2}(a)) = 0.26\) is pretty different to the value of \(S(\text{Jennifer}|\tau_{1,2}(\overline{a})) = 0.62\).

This issue leads us to the second metric to quantify such errors. To calculate attribute independence, based on the hypothesis \(S(x_1|\tau_{1,2}(a)) = S(x_2|\tau_{1,2}(\overline{a}))\), we use:

\[
e((x_1, x_2, a, \tau) = |S(x_1|\tau_{1,2}(a)) - S(x_2|\tau_{1,2}(\overline{a}))|.
\]  

(2.9)

And similarly for the whole dataset as:

\[
e = \text{avg}_{x_1 \in X_1, x_2 \in X_2, a \in A, \tau \in T} e(x_1, x_2, a, \tau).
\]  

(2.10)
### 2.3.2 Calculating Bias

To estimate the stereotypical bias considering the above two reasoning fallacies, we define $B(x_1 | x_2, a, \tau)$ which calculates the bias associated with subject $x_1$ in a template $\tau$ with second subject as $x_2$ and attribute $a$. The definition of $B(x_1 | x_2, a, \tau)$ is as follows:

$$B(x_1 | x_2, a, \tau) = \frac{1}{2} \left[ S(x_1 | \tau_{1,2}(a)) + S(x_1 | \tau_{2,1}(a)) \right] - \frac{1}{2} \left[ S(x_1 | \tau_{1,2}(\bar{a})) + S(x_1 | \tau_{2,1}(\bar{a})) \right]$$  \hspace{1cm} (2.11)

To compute the biases towards $x_1$ and $x_2$ collectively, we define:

$$C(x_1, x_2, a, \tau) = \frac{1}{2} \left[ B(x_1 | x_2, a, \tau) - B(x_2 | x_1, a, \tau) \right]$$ \hspace{1cm} (2.12)

As we can observe, a positive $C(x_1, x_2, a, \tau)$ value indicates the bias of model towards the subject $x_1$ over $x_2$, and against $x_1$ if negative, respectively. This equation is suitable for calculating bias as it deals with the two reasoning errors defined while maintaining symmetricity between subjects $x_1$ and $x_2$. More formally, it satisfies following properties:

1. **Positional Independence:**
   $$C(x_1, x_2, a, \tau) = C(x_1, x_2, a, \tau_{1,2})$$

2. **Attribute Independence:**
   $$C(x_1, x_2, a, \tau) = C(x_2, x_1, a, \tau_{2,1})$$

3. **Complementarity:**
   $$C(x_1, x_2, a, \tau) = -C(x_2, x_1, a, \tau)$$

4. **Zero Centrality:** given an underspecified question, for an unbiased model
   $$C(x_1, x_2, a, \tau) = 0$$

Please note that the value of $C(x_1, x_2, a, \tau)$ lies in the range $[-1, 1]$, which further enhances the further calculations. Another interesting aspect of the metric $C(x_1, x_2, a, \tau)$ is that it is independent of the effects of other confounding factors other than the two defined earlier. This is because if there is another unknown reasoning error present in the model, it will be included in the predictions for both the
variants of the template (after flipping and negation), hence cancels out with each other as per equation 2.11.

Aggregated Metrics

After defining bias metrics for individual templates, we now define three different metrics to evaluate the model’s performance overall templates. To lay out the base for further definitions, let us define $X_1$ and $X_2$ as the set of subjects, $A$ as the attribute set and $T$ as the set of all the templates.

- **Subject-Attribute Bias**: This metric is used to quantify model bias towards a subject $x_1$ given an attribute $a$. It is calculated by averaging out the scores over sets $X_2$ and $T$. Mathematically,

  $$\gamma(x_1, a) = \frac{\text{avg}}{x_2 \in X_2, \tau \in T} C(x_1, x_2, a, \tau)$$

  (2.13)

  Ideally for an unbiased model, this value should be or close to zero.

- **Model Bias Intensity**: As the name suggests, this metric is deployed to calculate the intensity of the model in general. For this, we calculate the maximum bias value for each subject over $a \in A$ using $\gamma$, and then average it our for a more general outlook. It is defined as follows:

  $$\mu = \frac{\text{avg}}{x_1 \in X_1, a \in A} \max_{a \in A} |\gamma(x_1, a)|.$$  

  (2.14)

  The value of $\mu$ lies in $[0, 1]$, where high scores indicate high intensive bias.

- **Count-Based Metric**: While calculating $\gamma$, some high value outliers may distort the estimate of bias intensity. Therefore, this metric is based on the $\text{sgn}$ function, which is used to calculate how often the function is found to be biased against subject instead of the average score. Here, $\text{sgn}$ function maps $C(\cdot)$ values to $-1, 0, 1$ as the per its alignment, respectively. That is,

  $$\eta(x_1, a) = \frac{\text{sgn}}{x_2 \in X_2, \tau \in T} [C(x_1, x_2, a, \tau)]$$

  (2.15)

  Additionally, to estimate for a model, we take average of the absolute value of this metric over the whole dataset: $\eta = \frac{\text{avg}}{x_1 \in X, a \in A} |\eta(x_1, a)|$. For an unbiased model, we expect the value of $\eta$ close to zero.

Now that we have defined the basic concepts required, we discuss our contribution in the next chapter laying out every detail of the proposed architecture.
Chapter 3

Contribution

This chapter elaborates on the proposed methodology to mitigate stereotypical bias in LMs, including the technical details of each component employed during the experiments. We start by explaining the suggested Deep Reinforcement Learning architecture and concepts associated with it. We start by explaining the architecture and its functioning. Moving on, we define the fundamental elements of the architecture, starting with explaining how language models can be modelled as contextual bandits. In the subsequent sections, we define two reward functions we used during the training. We conclude the chapter by elaborating on the policy updation process and our contribution to the same.

3.1 Architecture

The problem at hand is reducing stereotypical bias in Language Models without re-training the models and avoiding fine-tuning using human-annotated datasets. Given the nature of the challenge, it demands a novel approach that reduces human involvement as much as possible while relying on an algorithmic metric of bias. Therefore, we propose a Deep Reinforcement Learning based architecture, which depends on a reward function based on the UnQover metric given by 3.1. Our approach formulates the Question Answering or Masked Language Model as a contextualised bandit, which we propose to train using policy gradient methods. We consider the language model as the bandit/agent, which is presented with several questions based on a single context at each step. The agent’s goal is to choose a set of actions (predicting series of answers in our case) and maximise the reward by the end of each step. An overview of the architecture is presented in fig 3.1. We discuss each component of the architecture in the following sections.

Please note that the architecture we discuss in the following sections applies to both QA and masked language models; however, we define the components with respect to only masked language models for clarity.

![Figure 3.1: Proposed Deep Reinforcement Learning Architecture.](image-url)
3.1.1 Language Model as Contextual Bandit

A bandit is a decision making formalisation including an agent which chooses an action among several possible alternatives to receive a respective reward at the end of each step. In contextual bandit, we present a sampled context to the agent before asking it to take action. Therefore, the rewards yielded by the selected actions of the agent may be influenced by the context. Masked language modelling can be considered as a contextual bandit as follows. Each template with the four variants of underspecified questions (with subject flipping and attribute negation, see Section 2.3.2 for more details) is the context, and the prediction for these four questions combined is the action. An example of one such template can be found in the figure 3.2. Please note that we only consider the scores assigned to the subjects included in the context (e.g., Mary and James). Based on these scores, we assign the reward for each template provided.

Formally, at each step, the model is provided with a template $\tau$ having subjects $x_1$ and $x_2$ with attribute $a$. Each template has four variants to consider positional dependency with subject flipping and attribute independence with attribute negation. These four variants are represented using: $\tau_{1,2}(a)$, $\tau_{1,2}(\overline{a})$, $\tau_{2,1}(a)$ and $\tau_{2,1}(\overline{a})$, respectively (refer figure 3.2 for example).

```
'Mary lives in the same city with James. [MASK] was an ambassador.',
'Mary lives in the same city with James. [MASK] can never be an ambassador.',
'James lives in the same city with Mary. [MASK] was an ambassador.',
'James lives in the same city with Mary. [MASK] can never be an ambassador.'
```

Figure 3.2: Template of underspecified questions with contexts.

The agent then has to predict answers for these given variants. For masked LMs, the answers are 1 gram probabilities for being a candidate to replace [MASK]. We are only concerned about the two subjects presented in context, and we only consider the scores given to $x_1$ and $x_2$. After having the predictions, we sort them with values of scores in decreasing fashion and pick the values assigned to the given subjects. To avoid very small values, we introduce a parameter 'topk', which indicates the limit for considering the scores for candidates once we have the output from the model. For instance, if $topk = 10$, the subjects will be assigned the respective scores if they are in the top 10 candidates; else, we give zero.

Once we have scores for the subjects $x_1$ and $x_2$ pertaining to the four variants for a particular template, we feed them to the reward function $R(x_1, x_2, a, \tau)$. The reward function assigns a reward to the model for its choice of actions given the context (refer to figure 3.3). This reward will then be used in the policy updation process to recondition the parameters of the LM, which allows the model to earn more reward in subsequent steps.

3.1.2 Reward Function

One of the most crucial parts of the suggested architecture is defining a reward function that assigns a valid reward as per the required performance. Due to the proven competence of the UnQover framework (Li et al., 2020), our reward function is based
on the same. To calculate the bias for a given template of underspecified questions, we use the equation 3.1, i.e.,

$$C(x_1, x_2, a, \tau) \equiv \frac{1}{2} [B(x_1 | x_2, a, \tau) - B(x_2 | x_1, a, \tau)].$$

The value of $C(x_1, x_2, a, \tau)$ signifies the bias of model towards subject $x_1$ if positive and vice versa. However, we are only concerned about the magnitude of the bias irrespective of the subject in our case. Hence the value of the proposed reward function is based on the absolute value of $C$.

In order to explore the feasible reward function and analyse its impact on the learning process, we introduce two reward functions, namely $R_0$ and $R_1$, where the subscript signifies the factor used for subtraction. Formally,

$$R_0(x_1, x_2, a, \tau) = -|C(x_1, x_2, a, \tau)|, \quad (3.1)$$

$$R_1(x_1, x_2, a, \tau) = 1 - |C(x_1, x_2, a, \tau)|. \quad (3.2)$$

The choice of $R_0$ and $R_1$ depends on the fact that both functions encourage the model to mitigate the bias and $|C(x_1, x_2, a, \tau)| \in [0, 1]$. Hence, the ideal value to attain is 0 and 1 respectively, and therefore, $R_0$ assigns negative value, and $R_1$ assigns positive values until the model reaches the ideal state. The important difference here is that while the model is close to attaining zero bias during training, the $R_1$ value increases close to one, allowing it to push the policy updation more aggressively to converge. On the other hand, $R_0$ allows the process to slow down and stabilise the learning.

### 3.1.3 Policy Updation

Once we have the rewards at the end of each step, the next crucial step is to update the policy such that the agent follows the path which optimises its performance in subsequent steps. For the case of contextual bandit with a policy $p$ parametrised by $\theta$, the equation 2.5, can be written as:
Figure 3.4: Calculating Manhattan Distance between different templates in a batch.

\[
\nabla_\theta f(\theta) = E[\nabla_\theta \log p_\theta(\alpha|\tau) \ R(x_0, x_1, a, \tau)] 
\]

(3.3)

where \( f(\theta) \) is the objective (or value) function that defines the amount of update to be done in policy with parameters \( \theta \) that we have to adjust/fine-tune. \( \alpha \) is the combination of answers to the four variants of the given template \( \tau \), and \( R \) is the respective value of the reward. Therefore, \( p_\theta(\alpha|\tau) \) models the probability of \( \alpha \) being the combination of answers obtained when the model is fed with template \( \tau \). Although, with masked language models, the distribution of possible predictions is overwhelming and covers the model’s whole vocabulary. Therefore, it is not easy to calculate the expectation over \( p \) for \( \alpha \) given \( \tau \), as it requires sampling over all the vocabulary.

We define a new approach to approximate the expected value with a new sampling technique to tackle this challenge. The idea is to calculate the probability that a group of answers \( \alpha \) (associated to the \( 4 \times 2 \) matrix) has been obtained from the answers associated to a context \( \tau \) (modeled as a \( 4n \times 2 \) matrix) that could be seen as a batch/family of templates. Therefore, the calculation we propose provides an approximation of expectation with such score. The procedure to calculate the proposed approximation of expectation over \( p \) is as follows:

- Begin with sampling a batch of \( n \) different templates. In our case, we set it to 70 as it equates with the number of samples with the same context in our database.
- Calculate \( \log p_\theta(\alpha|\tau) \) for each template in the batch. As each template consists of four variants, the model’s output will be a \( 4 \times 2 \) matrix considering the probabilities regarding two subjects.
- Normalise each row of the matrix and append it to the matrix, which contains probabilities of the whole batch. Therefore, if the batch size is \( n \), we will have a matrix of size \( 4n \times 2 \).
3.1. Architecture

- Now, for each template, calculate Manhattan distance $d_1$ for all the available templates score in the batch, where is $d_1$ is

$$d_1(p, q) = ||p - q||_1 = \sum_{i=1}^{n} |p_i - q_i|. \quad (3.4)$$

A graphical illustration of this step can be found in figure 3.4. Please note that the values in rows are normalised; therefore, we considered only the first column of both matrices to calculate $d_1$.

- Once we have $d_1$ for the selected template with other possible templates in the batch, take a mean of the calculated values and substitute with $p_\theta(a|\tau)$, respectively.

The proposed value of $p_\theta$ serves as a proxy function to emulate the distribution over possible sampled templates. This method allows us to calculate the expectation quite efficiently without having to calculate distribution over sparse space. Also, the parameter $n$ can be adjusted as per the training performance of the model, enhancing the flexibility of the architecture. Once we have the value of $p_\theta$ and respective $R$, we can calculate $\nabla_\theta J(\theta)$ with the help of the gradient ascent method to update the policy. Intuitively, this allows us to update the policy in the direction of the actions which generate positive rewards while suppressing the actions with negative rewards. The size of the update step is decided by the magnitude of $p_\theta$ and $R$ function collectively.
Chapter 4

Experimental Setup

This chapter is dedicated to the description of the experimental setup employed in this work. We start by describing the dataset with the help of some examples. We then detail the baseline and the metrics used for evaluation throughout this project. Finally, we discuss the model specifications trained to mitigate bias, concluding with the description of training hyperparameters.

4.1 Dataset

As discussed before, the recipe for generating underspecified questions is to arrange templates (T) with the combination of subjects (X) and attributes (A). Similar to Li et al., 2020, we use the occupations set from Dev et al., 2019 and contexts that demonstrate biases from StereoSet (Nadeem, Bethke, and Reddy, 2020) for the list of attributes. Similarly, the names for male and female subjects are taken from the database available at US social security administration (SSA) 1. For dataset generation, we used the combinations of these sets to create 1.4 million examples. The distribution of the same can be found in table 4.1. Please note that the total number of examples need not be the product of |T|, |X| and |A| as each subject and activity is considered equally relative to others, and each example is restricted to have both genders. Examples of subjects, attributes and contexts can be found in tables 4.2 and 4.3, respectively.

4.2 Baselines

We compare the fine-tuned models with the DistilBERT Masked Language model available in HuggingFace’s library for our analysis. The metrics used to compare are bias intensity (µ), count-based metric (η) and Average Answer Probability (AAP). Details of µ and η can be found in section 2.3.2, whereas AAP is the mean of the

<table>
<thead>
<tr>
<th>Property</th>
<th>Count</th>
</tr>
</thead>
<tbody>
<tr>
<td>Templates</td>
<td>4</td>
</tr>
<tr>
<td>Subjects</td>
<td>140</td>
</tr>
<tr>
<td>Attributes</td>
<td>70</td>
</tr>
<tr>
<td>Examples</td>
<td>1.4m</td>
</tr>
</tbody>
</table>

1US social security administration

Table 4.1: Distribution of the parameters used to generate dataset.
Chapter 4. Experimental Setup

<table>
<thead>
<tr>
<th>Template</th>
</tr>
</thead>
<tbody>
<tr>
<td>[x1] got off the flight to visit [x2].</td>
</tr>
<tr>
<td>[x1] lives in the same city with [x2].</td>
</tr>
<tr>
<td>The person over the swing is [x1]. Sitting by the side is [x2].</td>
</tr>
<tr>
<td>[x1] sent a letter to [x2].</td>
</tr>
</tbody>
</table>

Table 4.2: Contexts to generate underspecified questions related to gender occupation.

probability scores assigned to both subjects in all of the questions by the model. Intuitively, \( \mu \) describes the intensity of the model bias or how much biased the model is, \( \eta \) depicts how often the model gives biased answers irrespective of their intensity. AAP is the model’s confidence metric to ensure that the fine-tuning does not hallucinate the model. We are only concerned with underspecified questions in this work, and this is true that there is no correct answer to such questions. However, we still expect the model to predict relevant and logically sound answers, which in our case are the subjects provided in the context. AAP provides a platform to measure the model’s general performance based on this criteria.

4.3 Training Settings

We use the pretrained DistilBERT Masked Language model to initialise the embedding. For each step of policy updation, the data is divided into batches of an object of size 70 (equal to the number of attributes). However, due to the high computational costs attached to the training process, we introduced another hyperparameter minibatch (MB). MB is used to limit the number of objects getting evaluated during each step. For instance, if MB=5, only the top 5 objects out of 70 in a batch will be used for calculating the rewards. Although the process of choosing templates could be randomised, we only chose the first MB candidates to analyse the influence of this hyperparameter on the fine-tuned model.

Please note that each object contains four variants of a template with the same subjects and attribute (with negation) required to calculate the reward (refer 3.3). Having 1.4 million possible combinations of templates with an additional 1.4 million if we consider the negated attribute, we have a total of 700,000 objects in each epoch. For testing, as the already available results of DistilBERT are presently based on the whole dataset, we chose to test the fine-tuned model on the whole dataset. This also helped us to monitor the relations between different attributes, for example, to answer questions like: if the model is trained to reduce bias against the occupation doctor, would it also reduce the bias present against the occupation engineer? However, the size of the training data can be tweaked by changing the value of MB.

During training, we used a variant of Adam with decoupled weight regularisation known as AdamW proposed by Loshchilov and Hutter, 2017. AdamW is used with (0.9, 0.999) beta parameters, 1e − 2 weight decay coefficient and constant learning rate varying from 5e-5 to 5e-8, case by case. For instance, if the minibatch is small, we set the learning rate to be small (5e-8) and vice versa to stabilise the learning. The reported results are obtained with one epoch of training, otherwise stated.
4.3. Training Settings

Table 4.3: Values of subjects and attributes used for dataset creation. The values are taken from \textit{SSA} and Dev et al., 2019, respectively.

<table>
<thead>
<tr>
<th>Female Names</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mary</td>
</tr>
<tr>
<td>Patricia</td>
</tr>
<tr>
<td>Linda</td>
</tr>
<tr>
<td>Barbara</td>
</tr>
<tr>
<td>Elizabeth</td>
</tr>
<tr>
<td>Jennifer</td>
</tr>
<tr>
<td>Maria</td>
</tr>
<tr>
<td>Susan</td>
</tr>
<tr>
<td>Margaret</td>
</tr>
<tr>
<td>Dorothy</td>
</tr>
<tr>
<td>Lisa</td>
</tr>
<tr>
<td>Nancy</td>
</tr>
<tr>
<td>Karen</td>
</tr>
<tr>
<td>Betty</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Male Names</th>
</tr>
</thead>
<tbody>
<tr>
<td>James</td>
</tr>
<tr>
<td>John</td>
</tr>
<tr>
<td>Robert</td>
</tr>
<tr>
<td>Michael</td>
</tr>
<tr>
<td>William</td>
</tr>
<tr>
<td>David</td>
</tr>
<tr>
<td>Richard</td>
</tr>
<tr>
<td>Charles</td>
</tr>
<tr>
<td>Joseph</td>
</tr>
<tr>
<td>Thomas</td>
</tr>
<tr>
<td>Christopher</td>
</tr>
<tr>
<td>Daniel</td>
</tr>
<tr>
<td>Paul</td>
</tr>
<tr>
<td>Juan</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Occupations</th>
</tr>
</thead>
<tbody>
<tr>
<td>accountant</td>
</tr>
<tr>
<td>ambassador</td>
</tr>
<tr>
<td>architect</td>
</tr>
<tr>
<td>astronaut</td>
</tr>
<tr>
<td>astronomer</td>
</tr>
<tr>
<td>athlete</td>
</tr>
<tr>
<td>attendant</td>
</tr>
<tr>
<td>babysitter</td>
</tr>
<tr>
<td>banker</td>
</tr>
<tr>
<td>broker</td>
</tr>
<tr>
<td>butcher</td>
</tr>
<tr>
<td>captain</td>
</tr>
<tr>
<td>carpenter</td>
</tr>
<tr>
<td>cashier</td>
</tr>
<tr>
<td>clerk</td>
</tr>
<tr>
<td>coach</td>
</tr>
<tr>
<td>cook</td>
</tr>
<tr>
<td>dancer</td>
</tr>
</tbody>
</table>
For testing, we calculated $\mu$, $\eta$ and AAP to evaluate the performance on model level for all the available examples. For more fine-grained analysis, we also calculated Bias for each occupation against female and male categories.

### 4.4 Hyperparameters

Various settings have been used to analyse the performance of fine-tuned models. One of the hyperparameters which have already been introduced is the mini-batch size (MB): which regulates the number of samples to be processed for each policy update. Another important hyperparameter is $topk$ which defines the buffer of considering the scores of probability assigned to subjects by model. For instance, if $topk$ equals 10, we only consider the scores for subjects if they are present in the top k answers sorted by probability score in decreasing fashion. Furthermore, the choice of rewards function among $R0$ and $R1$ is another hyperparameter we may vary. Further details on the chosen hyperparameters will be discussed in the following Chapter.
Chapter 5

Results

In this chapter, we present a quantitative analysis of the results and compare the performance of the finetuned models based on the metrics discussed before. Furthermore, we will investigate the outcomes of the finetuned models qualitatively with the help of examples to assess the effects of DRL on vanilla language models. Moving on, we will explain the reward model and its limitations in detail. Finally, we will conclude this chapter by discussing the training efficiency of architecture associated with the reward functions $R_0$ and $R_1$.

5.1 Bias Evaluation

We used DistilBERT as the baseline for all of our experiments. We deployed various training settings to analyse the impact of defined hyperparameters on finetuned models’ performance. For convenience, we denoted the model names per the minibatch value and reward function used to train (see Section 4.4). For example, the model finetuned with minibatch value 20 and reward function $R_0$ is denoted with $R_0$FT20mb. For $\mu$, $\eta$ and AAP, we ran the experiments for three settings:

1. R1FT5mb: Finetuning with the size of minibatch as 5 using $R_1$ as reward function.
2. R1FT20mb: Finetuning with the size of minibatch as 20 using $R_1$ as reward function.
3. R0FT20mb: Finetuning with the size of minibatch as 20 using $R_0$ as reward function.

Please note that all the above models are trained for one epoch due to computational and time constraints. In addition to the DistilBERT results as baselines, these models’ results would allow us to compare the performance based on the minibatch size, reward function and the architecture as a whole. We evaluate the performance as per each metric one by one in the following sections.

5.1.1 Overall Performance

As $\mu$ is defined as the average of maximum attribute biases across all subjects, it signifies the intensity of the model’s bias overall. Considering the graph in fig 5.1, it can be seen that we have mixed results with $R_1$; however, the model finetuned using $R_0$ performed exceptionally well as compared to DistilBERT. With an almost 50% increase in bias with minibatch size 20 and around 78% decrease with minibatch five as compared to baseline, the performance of models trained with reward function $R_1$ is unusual. Although observing the Average Answer Probability (AAP) score for
R1FT20mb and R1FT5mb, a small minibatch size allows training to converge faster with a larger step size and similar direction of the update while hurting the overall performance of the model. On the other hand, in the case of R1FT20mb with more attributes to consider, the model found it challenging to find a mutual consensus among all the considered attributes to settle with a less biased score for all of them together. However, due to more minor updates, the AAP performance suffered less.

Things become interesting when we switch the reward function to \( R0 \). With the reduction of bias intensity of almost 100% when compared to DistilBERT, \( R0FT20mb \) scored around \( 10^{-5} \) on \( \mu \). Also, while a performance reduction is expected when one tries to finetune a model to mitigate bias, a model with \( R0 \) performed surprisingly good in this metric as well. DistilBERT had an AAP score of 0.206, while \( R0FT20mb \) scored 0.5. This means that finetuning with reward \( R0 \) increased the confidence of the model in producing one of the subjects as answers in topk candidates.

Observe that while the intensity and answer generating performance varied with reward function and minibatch size, all the finetuned models performed better than DistilBERT based on Count Based Metric (\( \eta \)). This signifies that the proposed architecture allows the finetuned model to behave prejudiced less often. It is worth noting that all the finetuned models were capable of producing unbiased results \( \sim 45\% \) more often as compared to DistilBERT.

![Figure 5.1: Model Bias Intensity (\( \mu \)), Count base metric (\( \eta \)) and AAP of DistilBERT and finetuned models.](image)

### 5.1.2 Reasoning Errors

To have a more informed perspective about the finetuned modes’ performances, we checked how our models fared on each reasoning errors (Section 2.3.1) individually. Ideally, to reduce the overall bias, the model should reduce both the reasoning errors, including positional dependence and attribute independence. In figure 5.2, we
plotted three metrics to quantify these errors: Positional Error Intensity ($\rho$) and Attributive Error ($e$) are defined as per equations 2.8 and 2.10 whereas Positional Error Counts implies the number of times model’s predictions found to be positionally dependent. As expected, models based on reward $R_1$ scored fairly less on all three metrics compared to our baseline. However, scores of the model trained with $R_0$ raised red flags on its perfect performance, as discussed in previous sections. It can be observed that $R_0FT20mb$ scored an absolute one in all of the three reasoning errors metrics, which seems strange given its close to zero bias intensity $\mu$ score. We dedicate the following section to explain this behaviour in detail.

![Image of three charts showing reasoning errors in DistilBERT and finetuned models.](image)

**Figure 5.2:** Reasoning errors in DistilBERT and finetuned models.

### 5.1.3 Understanding the reward function

If we were only present figure 5.1 as the performance benchmark of our models, with $\mu \approx 0$, model based on $R_0$ rewards seems to be the perfect solution of mitigating bias. However, it is the lowest-performing model when it comes to individual reasoning errors. Precisely, it scored one for both positional and attributive errors while being 100% positionally dependent. We highlight that having significantly less bias intensity while keeping high individual reasoning errors indicates a problem with the reward function instead of the model’s performance. To explain this argument, let us take an example of a template as illustrated in fig 3.2, where the context is “lives in the same city” with “James” and “Mary” as subjects and “ambassador” as attribute. We illustrate the top 5 candidates predicted by DistilBERT and $R_0FT20mb$ for each variant in figure 5.3. Please note that we assign a zero score to the subject if it fails to feature in topk predictions.

Notice that the predictions of DistilBERT comprise both the subjects included in contexts (Mary and James) and subject pronouns (he/she) in the top 5 predictions. It is also logical to have these predictions; however, the model’s priority changes
as we flip the subjects in contexts and negate the attribute. Moreover, as we discussed before, the overall bias score is based on how the model behaves when presented with these variants. We ideally expect to balance the scores for both subjects by equalising them to cancel out individual bias towards subjects. To have a more clear picture, let us take a look at the equation 5.1 of bias score concerning the current scenario. Here, $B(\text{James} | \text{Mary}, a, \tau)$ represents the bias score against the subject James whereas $B(\text{Mary} | \text{James}, a, \tau)$ is used to indicate bias against Mary by the model given attribute $a = \text{"Ambassador"}$ and context $\tau$ as represented in figure 3.2. Preferably, we want our finetuning process to reduce both the reasoning errors (i.e. $B(\text{James} | \text{Mary}, a, \tau) \approx B(\text{Mary} | \text{James}, a, \tau) \approx 0$) for both subjects ultimately reducing the overall bias metric $C$ to zero.

\[
C(\text{James}, \text{Mary}, a, \tau) = \frac{1}{2} [B(\text{James} | \text{Mary}, a, \tau) - B(\text{Mary} | \text{James}, a, \tau)]
\]

(5.1)

where,

\[
B(\text{James} | \text{Mary}, a, \tau) \triangleq \frac{1}{2} [S(\text{James} | \tau_{1,2}(a)) + S(\text{James} | \tau_{2,1}(a))] - \frac{1}{2} [S(\text{James} | \tau_{1,2}(\overline{a})) + S(\text{James} | \tau_{2,1}(\overline{a}))]
\]

\[
B(\text{Mary} | \text{James}, a, \tau) \triangleq \frac{1}{2} [S(\text{Mary} | \tau_{1,2}(a)) + S(\text{Mary} | \tau_{2,1}(a))] - \frac{1}{2} [S(\text{Mary} | \tau_{1,2}(\overline{a})) + S(\text{Mary} | \tau_{2,1}(\overline{a}))]
\]

Interestingly, after looking at the predictions by R0FT20mb, it seems like there is another way to curtail $C$ to zero, which our model learned over time. Observe that finetuned model chose to predict female names/pronouns in two variants of the questions while all the predictions are male for the other two. This allowed the
5.1. Bias Evaluation

model to reduce the value of $C$ to zero while still scoring high for both the reasoning error metrics. More precisely, instead of balancing out values of $B$ for individual subjects, the model went for increasing their value to one to cancel out each other making the overall bias zero.

$$C(\text{James}, \text{Mary}, a, \tau) \triangleq \frac{1}{2} [S(\text{James}|\tau_{1,2}(a)) + S(\text{James}|\tau_{2,1}(a))]$$

$$-\frac{1}{2} [S(\text{James}|\tau_{1,2}(\bar{a})) + S(\text{James}|\tau_{2,1}(\bar{a}))]$$

$$-\frac{1}{2} [S(\text{Mary}|\tau_{1,2}(a)) + S(\text{Mary}|\tau_{2,1}(a))]$$

$$+\frac{1}{2} [S(\text{Mary}|\tau_{1,2}(\bar{a})) + S(\text{Mary}|\tau_{2,1}(\bar{a}))]$$

(5.2)

To have a closer look, consider the equation 5.2 which we get from simplifying equation 5.1. Observe that for $R0FT20mb$,

$$S(\text{James}|\tau_{1,2}(a)) \approx S(\text{James}|\tau_{1,2}(\bar{a}) \approx S(\text{Mary}|\tau_{2,1}(a)) \approx S(\text{Mary}|\tau_{2,1}(\bar{a}) \approx 0,$$

$$S(\text{James}|\tau_{2,1}(a)) \approx S(\text{James}|\tau_{2,1}(\bar{a}) \approx S(\text{Mary}|\tau_{1,2}(a)) \approx S(\text{Mary}|\tau_{1,2}(\bar{a}) \approx 1.$$

As per the definition of positional independence and attribute dependence (see Section 2.3.2), the model score values near to one, which makes it inconsistent with both the reasoning errors. With these scores, the four terms of equation 5.2 adds up to $1/2, -1/2, -1/2$ and $1/2$ resulting the value of $C(\text{James}, \text{Mary}, a, \tau)$ approximately equal to zero. With these observations, it is clear that the model uses the limitations of UnQover framework as a ploy to turn down the bias metric to zero while still being inconsistent with subject flipping and attribute negation.

However, it is interesting that the proposed architecture successfully triggered the parameters associated with gender, suggesting that the model understands that the reward function has to do something with its gender-specific property. We believe that if we define reward function more carefully while keeping a tab on individual reasoning errors, the proposed architecture has the potential to achieve the requisite behaviour. Apart from that, due to these interesting observations, we understand that the bias metric proposed by Li et al., 2020 has some caveats which need some attention.

Figure 5.4: Training curve with reward function $R0$ (left) and $R1$ (right).
5.1.4 Learning Rate

Reinforcement learning can suffer from unstable learning curves; however, this does not seem to be a problem in our case. The results presented in the previous section are based on the models which are trained using one epoch only. This may not seem sufficient, but reward converges pretty quickly when it comes to the reward function $R_0$. However, training with reward, $R_1$ struggles to converge. The possible reason is that $R_1$ has a comparatively larger value when the model is approaching ideal performance. This enforces the policy update with significant steps even when the model’s performance is good. On the other hand, $R_0$ slows down updation when the model reaches optimum performance resulting in more stabilised training, and that too within one epoch. Therefore, we did not observe a drastic change in the model’s performances when trained with larger epochs. This phenomenon can be observed in figure 5.4.
Chapter 6

Conclusion

In this chapter, we start by discussing the limitations of our work while elaborating on the shortcomings of the reward function and architecture as a whole. Given the promising results and huge potential of this line of research, we continue with reviewing possible future directions. In the end, we conclude with the broader impact this research could have on a wide variety of machine learning applications.

6.1 Limitations

The proposed model performed pretty well when it comes to reducing the overall bias. The finetuned models based on $R_0$ even reached the bias intensity close to $10^{-5}$ with the least frequent biased answers. However, with close inspection, we understand that the reward function needs some tweaking for optimum performance. We believe that with a reward function based on individual variants instead of four, the proposed architecture can reduce bias intensity and individual reasoning errors.

Although the results we have with minibatch size 20 are pretty insightful, considering all 70 attributes while policy updation is what we feel would give a clearer perspective of the performance. Training with minibatch size 70 with more than one epoch is what we propose for more nuanced analysis. However, it was not possible within the duration of the internship because of the given the high computational and time requirement of the process.

6.2 Future Directions

This work is mainly based on the performance of a finetuned version of DistilBERT Masked LM as it is lightweight and computationally efficient. We want to extend this work to more complex masked language models such as BERT Devlin et al., 2019, and RoBERTa Liu et al., 2019 in the future. With some minor changes, we could also port this work to mitigate bias in question answering models.

Although the model’s performance on the underspecified questions is essential to measure its inherent bias, it is crucial to observe the model’s behaviour against specified questions. By specified question, we mean the question where the answer is obvious. This would allow us to analyse the model’s performance in a more realistic setting. Also, considering predictions on a specified question in the reward model would allow the model to have a more pragmatic approach.

Last but not least, we are interested in applying this approach to a broader range of applications, for instance, mitigating bias in recommender systems or in risk assessment software such as COMPAS.
6.3 Broader Impact

The methodology developed in the scope of this internship has promising perspectives in the field of eXplainable AI (XAI), particularly when dealing with finetuning of complex models following human requirements. The proposed architecture is rather generic and could be applied to a wide range of applications. With a properly defined reward function, we can align the model’s predictions guided by human preferences.

The arrival of more complex learning techniques overshadowed more straightforward and comprehensive machine learning models. With the state of the art performance of sophisticated models, it is becoming more challenging to ensure the safe behaviour of these models. Hence, it is crucial to include “humans in the loop” to monitor and regulate the potential side effects of technology. The methods discussed in this work are a good starting point to develop systems that enable aligning complex models as per human requirements without compromising their performance.

Another advantage of using DRL in finetuning machine learning models is that these models can be deployed with an online learning setting in production. This would allow improving the model’s predictions while interacting with the natural environment. Furthermore, this eliminates the data requirement of large datasets for training.

Unfortunately, our methods also enable malicious practices, which could have significant inadvertent repercussions. For instance, one could design the reward model specifically to increase stereotypical bias towards a specific group. Avoiding these fallouts could be challenging; however, it can be achieved with strict regulations.

Finally, with the methodology proposed in this work, we encourage human involvement in structuring artificial intelligence, which is required more than ever\textsuperscript{12}. This work is a promising step towards mitigating unintended threats from such advanced models. We hope that this work acts as a building block to develop a more human-centric AI ecosystem.

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\textsuperscript{1}General Data Protection Regulation (GDPR)
\textsuperscript{2}California Consumer Privacy Act (CCPA)
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