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On Using RSA/ECC Coprocessor for Ideal Lattice-Based Key Exchange

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Abstract. Polynomial multiplication is one of the most costly operations of ideal lattice-based cryptosystems. In this work, we study its optimizations when one of the operands has coefficients close to 0. We focus on this structure since it is at the core of lattice-based Key Encapsulation Mechanisms submitted to the NIST call for post-quantum cryptography. In particular, we propose optimization of this operation for embedded devices by using a RSA/ECC coprocessor that provides efficient and secure large-integer arithmetic. In this context, we compare Kronecker Substitution, already studied in [AHH⁺19], with two specific algorithms that we introduce: KSV, a variant of this substitution, and an adaptation of the schoolbook multiplication, denoted SHIFT&ADD. All these algorithms rely on the transformation of polynomial multiplication to large-integer arithmetic. Then, thanks to these algorithms, existing secure coprocessors dedicated to large-integer can be re-purposed in order to speed-up post-quantum schemes. The efficiency of these algorithms depends on the component specifications and the cryptosystem parameters set. Thus, we establish a methodology to determine which algorithm to use, for a given component, by only implementing basic large-integer operations. Moreover, the three algorithms are assessed on a chip ensuring that the theoretical methodology matches with practical results.

1 Introduction

The emergence of academic and industrial projects on the design of a potential quantum computer that can break most of the current public-key cryptosystems with Shor’s Algorithm [Sho97], led national agencies to study new proposals (e.g. [BSI]) and start standardization of quantum safe algorithms [Moo16,fCR18]. In particular, the National Institute of Standards and Technology (NIST) in 2016 launched a standardization call for post-quantum safe key exchange and signature [Moo16]. In July 2020, they announced seven finalists including four Key Encapsulation Mechanisms (KEMs) for a future standardization. Among these four KEMs, three are based on lattice problems [MAA⁺20]. For the Chinese

competition, the lattice-based KEM LAC [XYD⁺19], won the first prize in January 2020 [fCR20]. Hence international post-quantum cryptography standards are very likely to include lattice-based cryptosystems. Thus, optimizing and ensuring the practical security of these algorithms is an important area of research.

Constrained environments like smart cards can be very limited in terms of CPU frequency or amount of RAM, especially when compared to regular computers. Working on specific optimizations is often necessary to get an efficient implementation. These devices may embed dedicated hardware coprocessors to accelerate symmetric and asymmetric cryptographic computations. Moreover, these coprocessors offer security features (hardware and software countermeasures against faults and various leaks) and are Common Criteria EAL5+ or EAL6+ certified [Lom16]: they are not subject to "obvious" leaks, e.g. single trace attacks without prior learning phase are hard in practice. However, most of today's asymmetric coprocessors are designed for RSA or elliptic curve cryptography (ECC) and are not adapted for lattice-based cryptography. Performance, security and ease of deployment are part of the NIST selection criteria. Therefore, re-purposing existing secure components to optimize lattice-based KEM can facilitate the transition to quantum safe algorithms.

Motivation & previous works. Polynomial multiplication is one of the most costly operation for ideal lattice-based algorithms. A lot of research has been done on the design of efficient hardware to speed-up polynomial multiplication, see e.g. [YZMZBY⁺20,DFA⁺20,SRB20]. However, the transition period should rely on hybrid mechanisms, mixing both classical and post-quantum asymmetric cryptography. Thus, both large modular arithmetic and operations related with post-quantum cryptography, like polynomial multiplication, have to be handled.

Nowadays, hardware accelerating large modular arithmetic are designed and deployed. Then, re-purposing these coprocessors to optimize polynomial multiplication is relevant in terms of costs and ease of deployment for an hybrid cryptography world.

The previous work of Albrecht *et al.* in [AHH⁺19] optimizes Kyber 1st round algorithm with a RSA/ECC coprocessor, which handles large-integer arithmetic. They use and adapt techniques introduced in [Har07] which transform polynomial multiplication to an integer multiplication with Kronecker Substitution. The work of Wang *et al.* in [WGY20] re-use the Kronecker Substitution with such a coprocessor to optimize Saber algorithm.

More recently, an independent work of Bos *et al.* in [JWBJRCvV20] introduced **Kronecker+**, an algorithm using a variant of Nussbaumer allowing to combine with Kronecker Substitution. Theoretically, **Kronecker+** allows a faster polynomial multiplication than Kronecker Substitution. However, the theoretical approach does not provide an estimation of the costs of the polynomial transformations required to apply **Kronecker+**, which does not ensure a faster algorithm in practice.

Contribution. In this paper we follow the approach initiated in [AHH⁺19] to improve polynomial multiplication for lattice-based KEMs using a RSA/ECC

coprocessor. Such coprocessors usually provide a few basic operations on large integers: multiplication, addition, subtraction, right/left shift.

Our work focuses on the core operation: unreduced polynomial multiplication, i.e. without reduction mod q or $x^n + 1$. Indeed, optimizations for modular reductions can be used on top of any unreduced polynomial multiplication.

More precisely, our work focuses on the unreduced polynomial multiplication when one of the operands has small coefficients. To take advantage of this structure, we introduce a variant of Kronecker Substitution and an adaptation of the schoolbook multiplication, called SHIFT&ADD. Both methods allow to handle polynomial multiplication with operations on large integers.

Compared to Kronecker Substitution, its variant replaces large integer multiplications with additions, shifts and multiplications between a large integer and a coefficient. For small coefficients, the latter is expected to be cheaper than a regular multiplication. SHIFT&ADD handles polynomial multiplications with only integer additions and shifts. With SHIFT&ADD, the smaller the coefficients are, the fewer operations are performed.

Thereafter, we propose a methodology to help the comparison between Kronecker Substitution, its variant and SHIFT&ADD, for a given KEM and a given coprocessor. To this end, we give theoretical complexity estimates for the three algorithms, expressed in terms of basic operations like addition, multiplication, shift and evaluation. Then, by measuring the performance of these basic operations, a developer can determine the fastest algorithm without having to fully develop each algorithm.

Finally, we verify that practical results are in accordance with this methodology for seven parameter sets from the NIST PQC process. In particular, we show that for a given secure comparable component, SHIFT&ADD and Kronecker Substitution variant are faster than Kronecker Substitution as used in [AHH⁺19]. We also compare our results with reference software implementations for information purposes only: it is not our aim to compare the efficiency of our implementation with algorithms using specific CPU instructions set as one could find in e.g. [GKS20,CHK⁺20]. Hence, we are here interested by the challenge to re-purpose secure certified coprocessor deployed in several real-life components for an hybrid transition approach.

Organization. In Section 2 we introduce some notations and describe the three algorithms that we use to perform polynomial multiplication with a coprocessor. Section 3 is devoted to discuss the side-channel aspects of the proposed algorithms. In Section 4, we show how to determine the evaluation point and establish the complexity of the three algorithms in terms of basic coprocessor operations. Finally, in Section 5, we assess our algorithms with different set of parameters and show that our practical results are consistent with our theoretical study.

2 Algorithms

In this section we present the algorithmic material used in this work. We first detail some notations and well known algorithmic techniques that will be developed in our contributions presented at the end of this section.

2.1 Notation and Preliminaries

The arithmetic that we study comes naturally from the definition of the ideal lattice-based cryptography and is given as follows.

Rings. For an integer $q \geq 1$, let \mathbb{Z}_q be the residue class group modulo q such that \mathbb{Z}_q can be represented as $\{0, \dots, q-1\}$. We define R_q being the polynomial ring $R_q = \mathbb{Z}_q[x]/(x^n + 1)$.

Modular reduction. Let $a, b \in \mathbb{N}$, we denote by $a \bmod^{(+)} b$ the unique integer $a' \equiv a \bmod b$ such that $0 \leq a' < b$ and $a \bmod^{(-)} b$ the unique integer $a' \equiv a \bmod b$ such that $-\frac{b}{2} \leq a' < \frac{b}{2}$. In the following, we denote by $a \bmod b = a \bmod^{(+)} b$.

Polynomials. A polynomial in R_q is represented by a polynomial of degree at most $(n-1)$ with coefficients in \mathbb{Z}_q . Given $f \in R_q$, we denote by f_i the coefficient associated with the monomial x^i .

Polynomial representation. Polynomials are represented as byte strings. Let $f(x)$ be a polynomial of degree $n-1$ with all its coefficients $0 \leq f_i \leq \beta$. Then, each coefficient is encoded on $\lfloor \log_2(\beta) \rfloor + 1$ bits. The coefficients are packed as a string of size $n(\lfloor \log_2(\beta) \rfloor + 1)$ bits to represent $f(x)$.

Let $g(x)$ be a polynomial of degree $n-1$ with all its coefficients $-\frac{\delta}{2} \leq g_i \leq \frac{\delta}{2}$. Then, each coefficient is encoded on $\lfloor \log_2(\delta) \rfloor + 1$ such that it is represented as $g_i \bmod^{(+)} 2^{\lfloor \log_2(\delta) \rfloor + 1}$. As previously, all the coefficients are packed as a string of size $n(\lfloor \log_2(\delta) \rfloor + 1)$ bits to represent $g(x)$.

Example 1. Let $f(x)$ be a polynomial with non-negative coefficients lower or equal to $q-1 = 3328$, then each coefficient is encoded on $\lfloor \log_2(3328) \rfloor + 1 = 12$ bits:

...	f_2	f_1	f_0
	35	23	11
			0

Large integer operations. In the remainder of this paper, we introduce three algorithms: Kronecker Substitution (Alg. 3), Kronecker Substitution Variant (Alg. 4) and Shift&Add (Alg. 5). For these algorithms the integer operations (multiplication, addition, subtraction, shift) are implicitly performed on large integers and correspond to the operations provided by a hardware coprocessor.

Number Theoretic Transform (NTT). NTT is an algorithm allowing to perform fast polynomial multiplication in R_q [Nus82, LN16]. Given a and $b \in R_q$, $a \times b$ is computed as $\text{NTT}^{-1}(\text{NTT}(a) \circ \text{NTT}(b))$, where \circ is the coefficient-wise multiplication.

Theoretically, NTT has the best asymptotic complexity for multiplication in R_q . However, in constrained environments (e.g. smart cards), devices may have dedicated hardware to perform fast large-integer arithmetic. In this context, NTT can be outperformed by an algorithm relying on integer arithmetic, even if its theoretical complexity is worse than NTT.

In the following paragraph, we describe a well known technique coming from computer algebra that allows to perform polynomial multiplication with integer arithmetic.

Kronecker Substitution. The main idea of this substitution, introduced by Kronecker in [Kro82] and first applied in the univariate polynomial context by Schönhage in [Sch82], is to transform polynomial multiplication to an integer multiplication by evaluating the operands and to get back to the result using a radix conversion. More precisely if $f = \sum_{i=0}^{n-1} f_i X^i$ and $g = \sum_{i=0}^{n-1} g_i X^i$ are two polynomials with non-negative coefficients, by considering the product of their evaluations at an integer B we obtain the integer $\tilde{f}\tilde{g} = \left(\sum_{i=0}^{n-1} f_i B^i\right) \left(\sum_{i=0}^{n-1} g_i B^i\right)$, that can be expressed in the base B by radix conversion. Then one obtains the evaluation of fg at B , $\tilde{f}\tilde{g} = \sum_{j=0}^{2n-2} \left(\sum_{i=0}^j f_i g_{j-i}\right) B^j$, and thus deduces the value of each coefficient of the corresponding polynomial fg . This radix conversion is possible only if each of the resulting coefficients are smaller than B . The integer B is usually chosen as a power b^ℓ where b is equal to 2 or 10 depending on the context. In all cases, ℓ has to be chosen sufficiently large in order to make the radix conversion effective. More precisely, ℓ could be chosen as the smallest integer such that b^ℓ is greater than the maximum size of the coefficients of the resulting polynomial.

When some of the coefficients of the polynomials are negative, we have to adapt this reconstruction. In the following algorithms, we present the evaluation process and the radix conversion for a general polynomial of degree $n-1$. We take care of the sign of the coefficients by storing this information in a variable that is given as one of the outputs of the first algorithm. We explain more precisely this procedure in the following.

The integer obtained after evaluation at 2^ℓ of a polynomial of degree $n-1$, can be viewed as the concatenation of n integers of bitsize ℓ .

...	$f(2^\ell)_2$	$f(2^\ell)_1$	$f(2^\ell)_0$
$3\ell - 1$	$2\ell - 1$	$\ell - 1$	0

EVALUATION algorithm 1 always returns a non-negative integer. Indeed, if the highest degree coefficient of a polynomial $g(x)$ is negative then the algorithm returns the evaluation of $-g(x)$. The parameter **neg** indicates, for the latter radix conversion, if the evaluation algorithm returned the evaluation of $g(x)$ or $-g(x)$. In the following we denote $f(2^\ell)_i = (f(2^\ell) \gg (i\ell)) \& (2^\ell - 1)$.

Algorithm 1 EVALUATION

Input: $f(x) \in \mathbb{Z}[x]$ of degree $n - 1$,
 $\ell \in \mathbb{N}$

Output: $(-1)^{\text{neg}} \times f(2^\ell)$, $\text{neg} \in \{0, 1\}$

```

1: carry  $\leftarrow 0$ 
2: if  $f_{n-1} < 0$  then
3:   neg  $\leftarrow 1$ 
4: else
5:   neg  $\leftarrow 0$ 
6: end if
7: for  $i = 0$  to  $n - 1$  do
8:   tmp  $\leftarrow (-1)^{\text{neg}} f_i + \text{carry}$ 
      mod  $(+ ) 2^\ell$ 
9:   if tmp  $> 2^{\ell-1}$  then
10:    carry  $\leftarrow -1$ 
11:   else
12:    carry  $\leftarrow 0$ 
13:   end if
14:    $f(2^\ell) \leftarrow f(2^\ell) + \text{tmp} \times 2^{i\ell}$ 
15: end for
```

Algorithm 2 RADIX CONVERSION

Input: $r(2^\ell) = (r(2^\ell)_0, r(2^\ell)_1, \dots,$
 $r(2^\ell)_{n-1})$ and $n, \ell, \text{neg} \in \mathbb{N}$

Output: $r(x) = r_0 + r_1x + \dots +$
 $r_{n-1}x^{n-1} \in \mathbb{Z}[x]$

```

1: carry  $\leftarrow 0$ 
2: for  $i = 0$  to  $n - 1$  do
3:    $r_i \leftarrow r(2^\ell)_i + \text{carry} \bmod (+) 2^\ell$ 
4:   if  $r_i > 2^{\ell-1}$  then
5:      $r_i \leftarrow (-1)^{\text{neg}+1} (2^\ell - r_i)$ 
6:     carry  $\leftarrow 1$ 
7:   else
8:      $r_i \leftarrow (-1)^{\text{neg}} r_i$ 
9:     carry  $\leftarrow 0$ 
10:  end if
11: end for
```

The following example presents Kronecker Substitution by using a decimal radix.

Example 2. Let $f(x) = 8x^2 + 3x + 2$ and $g(x) = -5x^2 - 4x + 1$. Note that the coefficients r_i of the result are such that $-\frac{10^2}{2} \leq r_i \leq \frac{10^2}{2}$. Hence, we evaluate f and g at 10^2 in order to compute $f(x) \times g(x)$ using integer multiplication: $f(10^2) = 080302$, $\text{neg}_f = 0$ and $g(10^2) = 050399$, $\text{neg}_g = 1$. After this evaluation, these two integers can be multiplied:

$$f(10^2) \times g(10^2) = 080302 \times 050399 = 4047140498$$

Since the evaluation was done at 10^2 , the resulting polynomial can be interpolated by reading the coefficients 2 digits by 2 digits. The two first digits are $98 \geq \frac{10^2}{2}$, that represents the negative number $-(10^2 - 98) = -2$ and propagates a carry for the next coefficient. After that, we got $4 < 50$ plus the previous carry to obtain 5. And so on for the other coefficients. However, $\text{neg}_g = 1$, then reading the coefficients like this gives $-(f(x)g(x))$.

$$\begin{aligned}
-(f(x) \times g(x)) &= 40x^4 + 47x^3 + 14x^2 + (4 + 1)x - (10^2 - 98) \\
&= 40x^4 + 47x^3 + 14x^2 + 5x - 2 \\
f(x) \times g(x) &= -40x^4 - 47x^3 - 14x^2 - 5x + 2
\end{aligned}$$

For sake of clarity, examples are given in 10-radix but in our algorithms and implementation, a power of 2 is used as the integer B . In the following Kronecker Substitution or KS refer to the Algorithm 3.

Algorithm 3 KRONECKER SUBSTITUTION

Input: $f(x) \in \mathbb{N}[x], g(x) \in \mathbb{Z}[x]$ and $\ell \in \mathbb{N}$

Output: $r(x) = f(x)g(x)$

1: $(f(2^\ell), \mathbf{neg}_f), (g(2^\ell), \mathbf{neg}_g) \leftarrow$ evaluation of $f(x), g(x)$ at 2^ℓ

2: $r(2^\ell) \leftarrow f(2^\ell)g(2^\ell)$

3: $r(x) \leftarrow$ radix conversion of $(r(2^\ell), \mathbf{neg}_f \oplus \mathbf{neg}_g)$

2.2 Polynomial Multiplication Using the Structure

The polynomials arising in ideal lattice based cryptosystems are structured, we show in the sequel how to gain in efficiency by using them.

Notations To perform an arithmetic operation using a hardware accelerator, the operands and an opcode for the operation to perform must be set into the coprocessor. When the choice of the operation depends on the value of a secret, we denote these sequences of instructions by $\mathbf{c} \leftarrow \mathbf{Op}(\mathbf{a}, \mathbf{b})$, where $\mathbf{Op} \in \{\mathbf{Add}, \mathbf{Sub}\}$ represents the opcode. This notation allows to simplify the constant-time implementation of an algorithm (see Section 2.2 below).

In the following algorithm descriptions, $\mathbf{@var}$ denotes the address of the variable \mathbf{var} . Given a pointer \mathbf{ptr} , $\mathbf{*ptr}$ stands for the value stored at address \mathbf{ptr} . The bitwise exclusive-or is denoted by \oplus , the bitwise logical **and** by $\&$ and $a \gg \ell$ (resp. $a \ll \ell$) stands for the logical right shift (resp. logical left shift) by ℓ bits of the value a .

Kronecker Substitution Variant Classical Kronecker Substitution multiplies two integers of length $b^\ell \times n$, where b^ℓ is the evaluation point B and $n - 1$ the degree of the polynomials. As mentioned above, ℓ is determined by the maximum coefficient value of the result. In this variant, n multiplications are done on an integer of length $b^\ell \times n$ by an integer of length b^k with $k < \ell$.

A multiplication of two large integers is replaced with 3 multiplications of a large integer by a small coefficient and some additions and shifts. This technique is of interest when considering the multiplication of a polynomial with small coefficients by a generic polynomial. Such multiplications are used in some lattice-based key exchanges. Algorithm 4 multiplies two polynomials of degree $n - 1$ such that $(|fg(x)|)_i < 2^\ell$.

Algorithm 4 KRONECKER SUBSTITUTION VARIANT

Input: $f(x) \in \mathbb{N}[x], g(x) \in \mathbb{Z}[x]$ and $n, \ell \in \mathbb{N}$

Output: $r(x) = f(x)g(x)$

```
1:  $(f(2^\ell), \mathbf{neg}_f) \leftarrow$  evaluation of  $f(x)$  at  $2^\ell$ 
2: for  $i = n - 1$  to  $0$  do
3:   if  $g_i \geq 0$  then
4:      $\mathbf{Op} \leftarrow \mathbf{Add}$  // Addition will be performed line 9
5:   else
6:      $\mathbf{Op} \leftarrow \mathbf{Sub}$  // Subtraction will be performed line 9
7:   end if
8:    $c \leftarrow |g_i|$ 
9:    $r(2^\ell) \leftarrow \mathbf{Op}(r(2^\ell), c \times f(2^\ell))$ 
10:   $r(2^\ell) \leftarrow r(2^\ell) \ll \ell$ 
11: end for
12:  $r(x) \leftarrow$  radix conversion of  $(r(2^\ell), \mathbf{neg}_f)$ 
```

Example 3. Let $f(x) = 8x^2 + 3x + 2$ and $g(x) = g_2x^2 + g_1x + g_0 = 5x^2 + 4x + 1$.

$$\begin{aligned} \text{Then, } f(10^2)g(10^2) &= (f(10^2) \times g_2)(10^2)^2 + (f(10^2)g_1)10^2 + f(10^2)g_0 \\ &= (080302 \times 5)(10^2)^2 + (080302 \times 4)10^2 + 080302 \times 1 \\ &= 4015100000 + 32120800 + 080302 = 4047301102 \end{aligned}$$

The resulting polynomial is recovered with radix conversion like in classical Kronecker.

Shift&Add We now present an adaptation of the schoolbook polynomial multiplication, denoted SHIFT&ADD, where polynomials are represented as integers, after a Kronecker-like evaluation. It relies only on additions and left shifts. This technique is of interest when one of the operands has small coefficients.

The basic idea is explained in Example 4 while a full description is given in Algorithm 5.

Example 4. Let $f(x) = 9x^2 + 8x + 3$ and $g(x) = g_2x^2 + g_1x + g_0 = 2x^2 - 1$. Let $r = 0$. The computation of $f(x) \times g(x)$ is done as follows:

Step 1. Evaluate f : $f(10^3) = 009008003$

Step 2. Since $g_2 = 2$:

1. $r \leftarrow r + f(10^3) \times (10^3)^2$;

2. $r \leftarrow r + f(10^3) \times (10^3)^2$;

Step 3. Since $g_1 = 0$, do nothing;

Step 4. Since $g_0 = -1$, $r \leftarrow r - f(10^3) \times (10^3)^0$;

$$\begin{aligned} \text{This leads to } f(10^3)g(10^3) &= 2f(10^3)(10^3)^2 - f(10^3) \\ &= 2(009008003 \times (10^3)^2) - 009008003 = 18015996991997 \end{aligned}$$

By radix conversion, $f(x)g(x) = 18x^4 + (15 + 1)x^3 - (10^3 - (996 + 1))x^2 - (10^3 - (991 + 1))x - (10^3 - 997) = 18x^4 + 16x^3 - 3x^2 - 8x - 3$.

Algorithm 5 Shift&Add

Input: $f(x) \in \mathbb{N}[x], g(x) \in \mathbb{Z}[x]$ with all $g_i \in \{-\frac{\delta}{2}, \dots, 0, \dots, \frac{\delta}{2}\}$ and $n, \ell, q \in \mathbb{N}$

Output: $r(x) = f(x)g(x)$

```
1:  $(f(2^\ell), \text{neg}_f) \leftarrow$  evaluation of  $f(x)$ 
2:  $\text{tmp} \leftarrow []$  // dummy buffer for constant time implementation
3: for  $i = n - 1$  to  $0$  do
4:   if  $g_i \geq 0$  then
5:      $\text{Op} \leftarrow \text{Add}$  // addition will be done line 15
6:   else
7:      $\text{Op} \leftarrow \text{Sub}$  // subtraction will be done line 15
8:   end if
9:   for  $j = 0$  to  $\frac{\delta}{2} - 1$  do
10:    if  $j < |g_i|$  then
11:       $\text{buff} \leftarrow \text{Op}(2^\ell)$  //  $\text{Op}$  in line 15 will be kept
12:    else
13:       $\text{buff} \leftarrow \text{tmp}$  //  $\text{Op}$  in line 15 will be discarded
14:    end if
15:     $*\text{buff} \leftarrow \text{Op}(r(2^\ell), f(2^\ell))$ 
16:  end for
17:   $r(2^\ell) \leftarrow r(2^\ell) << \ell$ 
18: end for
19:  $r(x) \leftarrow$  radix conversion of  $(r(2^\ell), \text{neg}_f)$ 
```

Isochronous implementations. As it will be explained in Section 3, side-channel attacks must be taken into consideration. Hence, Algorithms 4 and 5 are intended to be isochronous: the execution time does not depend on a secret value. In the sequel we assume that for a given operands size, additions and subtractions have same execution time.

At each loop iteration, the same number of additions or subtractions and shifts are performed. However, the time taken to execute conditional assignments (lines 3 to 7 in Algo. 4, lines 4 to 8 and lines 10 to 14 in Algo. 5) can depend on the condition, that itself depends on a secret. Likewise, the computation of absolute value (line 8 in Algo. 4 and line 10 in Algo. 5) must be handled carefully to be isochronous.

We show in Algorithm 6 how to achieve the pointer selection for lines 10 to 14 in Algorithm 5. This pointer selection is done without branches and without table accesses. Thus, its execution time depends neither on any secret value nor on cache access. Since Algorithm 6 computes an absolute value and performs a conditional assignment, the same techniques can be used to make Algorithms 4 and 5 isochronous.

3 Considerations on Side-Channel Attacks

This work focuses on implementations on embedded devices, thus the side-channel aspect must be considered.

Algorithm 6 Isochronous pointers selection

Input: Coefficient $g_i \in \{-\frac{\delta}{2}, \dots, \frac{\delta}{2}\}$ encoded on $k = \lfloor \log_2(\delta) \rfloor + 1$ bits, $j \in \mathbb{N}$, $R = \text{bitsize of CPU registers}$.

Output: $\text{buff} \leftarrow \begin{cases} \text{@r}(2^\ell) & \text{if } |g_i| < j \\ \text{@tmp} & \text{else.} \end{cases}$

```
1:  $s \leftarrow g_i \gg (k - 1)$  // 0 if  $g_i \geq 0$ , 1 else
2:  $t \leftarrow (s \oplus 1) - 1$  // 0 if  $g_i \geq 0$ ,  $2^R - 1 = \text{0xFF} \dots \text{FF}$  else
3:  $t \leftarrow t \ \& \ (2^k - 1)$  // previous result on  $k$  bits
4:  $\text{abs} = (t \oplus g_i) + s$  //  $|g_i| = g_i$  if  $g_i \geq 0$ ,  $\overline{g_i} + 1 = (g_i \oplus (2^k - 1)) + 1$  else
5:  $t \leftarrow ((\text{abs} - j) \gg (R - 1)) - 1$  // 0 if  $|g_i| < j$ ,  $2^R - 1 = \text{0xFF} \dots \text{FF}$  else
6:  $\text{switch} = \text{@r}(2^\ell) \oplus \text{@tmp}$ 
7:  $\text{buff} = (\text{switch} \ \& \ t) \oplus \text{@r}(2^\ell)$  //  $\text{@r}(2^\ell)$  if  $|g_i| < j$ ,  $\text{@tmp}$  else
```

Simple Attacks. To avoid simple attacks like SPA, we make our multiplication algorithms isochronous: the execution time does not depend on any secret. For most of the hardware accelerators, large-integer arithmetic timings depend only on the operands size. Hence, we assume that the execution time of shift, addition, subtraction and multiplication on large integers does not depend on the processed data. Moreover, exploiting secure coprocessors leaks by SPA during their computation is hard in practice. Then, we assume that an hardware addition cannot be distinguished from a hardware subtraction with a simple power consumption or EM attack. In addition, in our experiments, the CPU is set to perform the multiplication and division between registers in constant time. These instructions are used to compute modular reductions.

Under these assumptions, it is clear that a straightforward implementation of Kronecker Substitution does not have any operation depending on the manipulated data.

In addition, we explained in Section 2.2 and showed in Algorithm 4 and 5 how to compute isochronous KSV and SHIFT&ADD, based on techniques described in Algorithm 6. With such techniques and since by assumption, addition cannot be distinguished from a subtraction, from an attacker point of view, the execution of the same instructions are performed at each loop iteration in Algorithm 5 regardless of the secret. Thus, SPA-like attack cannot reveal secret information.

Differential/Correlation Attacks. Several physical attacks against Post-Quantum cryptosystems have been studied [CCA⁺20]. Among them, some correlation attacks have been done on polynomial multiplication, see e.g. [EFGT17,OSPG18][RJH⁺18,RdCR⁺16,RRDC⁺16] and references therein.

These attacks are based on the fact that power consumption or electromagnetic emissions are correlated with the data being manipulated. Such attack targets an intermediate variable of the form $s \times m$, where s is a small part of the secret and m a known input, like a message or a public key. Since s is small and m is known, the attacker can make a guess on s , compute $s \times m$ and predict, for a given leakage model, the expected consumptions or emissions for a series of different m 's. Then, using physical measurements, like power consumption

traces, and statistical tools, the correct key guess can be found: it is likely to be the one for which the correlation between predictions and real measurements is the strongest.

Masking is the classical countermeasure against such attacks [MOP08]. The sensitive data is split in two shares, each share being manipulated individually. For multiplication in lattice-based cryptography, the secret polynomial s has a structure, e.g. small coefficients, that can be exploited for performance optimization. Hence, to keep this structure, one can split the known part: for a given public value m , consider a random m_1 and set $m_2 = m - m_1$. Then $s \times m$ can be computed as $(s \times m_1) + (s \times m_2)$, each $(s \times m_i)$ being processed independently. Since m_1 and m_2 are unknown and appear to be uniformly distributed, the computation of $(s \times m_i)$ can not be correlated to $s \times m$, so that order 1 attacks will fail [MOP08]. With this countermeasure, the overhead is roughly an extra polynomial addition and an extra polynomial multiplication.

In [RdCR⁺16], the additively-homomorphic property of R-LWE schemes is used to mask, by adding the encryption of a random message before the decryption process. This random message encryption can be precomputed, so that the overhead is only an extra addition.

Recall that our goal is to determine, given a lattice-based scheme and a device, the fastest polynomial multiplication. For both kind of masking, the overhead does not depend on the choice of the multiplication algorithm: if unmasked multiplication A is faster than unmasked multiplication B, then the same result holds for their masked versions. Then in the sequel, we focus on comparing the basic unmasked versions of polynomial multiplication algorithms.

4 Complexity

This section is devoted to compare the performance of Kronecker substitution (KS), Kronecker substitution variant (KSV) and SHIFT&ADD when using an existing RSA/ECC hardware accelerator. Hence, the complexity is given in terms of basic arithmetic operations performed by such accelerators: addition, multiplication and multiplication by a power of 2 (left shift) on large integers. Moreover, the number of evaluation differs between KS, KSV and SHIFT&ADD. Then, the evaluation step is considered in the following complexities. Since the cost of these operations depends on the operand sizes, we first determine the minimal value for the parameter ℓ .

Our work is focused on lattice-based key exchange submitted to the NIST PQC standardization process. The polynomial multiplication of these key exchanges is over $R_q = \mathbb{Z}_q[x]/(x^n + 1)$. To compute such a multiplication, we first multiply over $\mathbb{Z}[x]$. The result is then reduced modulo $x^n + 1$ and each coefficient is reduced modulo q . Since this reduction step is the same for the three methods, its cost is not relevant for a theoretical comparison between them. Hence, it is not included in the complexity computation. Likewise, radix conversion step is the same and is not included in the complexity. However, these costs are considered in the performance results of Section 5.

4.1 Choice of ℓ

As explained in Section 2, polynomial multiplication can be reduced to integer multiplication. To this end, the polynomials are evaluated at a point such that the result can be recovered by radix conversion. This evaluation point is determined by the maximum coefficient of the multiplication result.

In the following, we suppose that the polynomial evaluation is done by Algorithm 1. Then, each evaluated polynomial is represented as a non-negative integer.

Proposition 1. *Let f and g be polynomials of degree $n - 1$ such that for all $i \in \{0, \dots, n - 1\}$, $0 \leq f_i \leq \beta$ and $-\frac{\delta}{2} \leq g_i \leq \frac{\delta}{2}$. Then*

- $\forall i \in \{0, \dots, 2n - 2\}, |(f(x)g(x))_i| < 2^{\ell-1}$, where $\ell = \lfloor \log_2(n\beta\delta) \rfloor + 1$.
- Each coefficient of $f(x)g(x)$ is encoded on at most ℓ bits.
- $\log_2(f(2^\ell)) < n\ell$ and $\log_2(|g(2^\ell)|) < n\ell$.

Proof. Let $r(x) = f(x)g(x)$. Then $r(x)$ is of degree $2n - 2$ and its k -th coefficient is $r_k = \sum_{i=0}^k f_i g_{k-i}$. To prove the first assertion, we first consider the coefficients r_k for $k \leq n - 1$. Since for all i , $0 \leq f_i \leq \beta$ and $|g_i| \leq \delta/2$, we get, for $k \leq n - 1$:

$$|r_k| = \left| \sum_{i=0}^k f_i g_{k-i} \right| \leq \sum_{i=0}^k |f_i| |g_{k-i}| \leq \sum_{i=0}^k \beta \frac{\delta}{2} \leq \sum_{i=0}^{n-1} \beta \frac{\delta}{2} \leq n\beta \frac{\delta}{2}.$$

For $k \geq n$, note that since f (resp. g) has degree $n - 1$, $f_i = 0$ (resp. $g_i = 0$) for $i \geq n$. Hence,

$$|r_k| = \left| \sum_{i=0}^k f_i g_{k-i} \right| = \left| \sum_{i=0}^{n-1} f_i g_{k-i} + \sum_{i=n}^k f_i g_{k-i} \right| = \left| \sum_{i=0}^{n-1} f_i g_{k-i} \right| \leq n\beta \frac{\delta}{2}.$$

Thus, for $k \in \{0, \dots, 2n - 2\}$, $|r_k| \leq n\beta \frac{\delta}{2} < 2^{\lfloor \log_2(n\beta \frac{\delta}{2}) \rfloor + 1} = 2^{\ell-1}$. Each coefficient of the result is $-n\beta \frac{\delta}{2} \leq r_k \leq n\beta \frac{\delta}{2} < 2^{\ell-1}$, then to handle the negative case each coefficient of the result is at most encoded on ℓ bits.

We prove now the third assertion.

$$f(2^\ell) = \sum_{i=0}^{n-1} f_i 2^{i\ell} \leq (2^\ell - 1) \sum_{i=0}^{n-1} 2^{i\ell} = (2^\ell - 1) \frac{2^{n\ell} - 1}{(2^\ell - 1)} = 2^{n\ell} - 1 < 2^{n\ell}$$

Thus, $\log_2(f(2^\ell)) \leq n\ell$. Likewise, $\log_2(|g(2^\ell)|) \leq n\ell$.

Remark 1. The previous proposition applies with polynomial $f(x)$ with non-negative coefficients. In our context, the negative coefficients of a polynomial in R_q can be replaced with their non-negative equivalent in $\{0, \dots, q - 1\}$.

4.2 Complexity Estimates

In this section, we estimate the complexity of our multiplication algorithms. We express them in terms of the following basic operations. Let $E(n)$ be the evaluation complexity function for a polynomial of degree $n-1$. Let $M(x, y)$ and $A(x, y)$ be the multiplication and addition (or subtraction) of integers complexity functions depending on the bitsize of the inputs.

Example 5. Let a and b be two integers, let $x = \lfloor \log_2(a) \rfloor + 1$ and $y = \lfloor \log_2(b) \rfloor + 1$. Then the cost of computing $a \times b$ (resp. $a + b$) is $M(x, y)$ (resp. $A(x, y)$).

Likewise, $S(x, s)$ denotes the shift complexity function where x is the bitsize of the integer to shift on s bits.

Kronecker Substitution (KS)

Proposition 2. *Let $f(x)$ and $g(x)$ be two polynomials of degree $n-1$. Each coefficient of $f(x)$ is defined over \mathbb{N} and each coefficient of $g(x)$ is defined over \mathbb{Z} . If for a given ℓ every coefficient $|(f(x)g(x))_i|$ is lower than $2^{\ell-1}$, then the multiplication complexity of $f(x)g(x)$ with Kronecker substitution is $2E(n) + M(n\ell, n\ell)$.*

Proof. Let $f(x)$ and $g(x)$ be polynomials of degree $n-1$. To compute $f(x) \times g(x)$ with Kronecker Substitution, the following steps are performed:

1. Evaluation of $f(x)$ and $g(x)$ at 2^ℓ . According to Proposition 1,
 $\log_2(f(2^\ell)) \leq n\ell$ and $\log_2(|g(2^\ell)|) \leq n\ell$.
2. Multiplication of two integers of bitsize $n\ell$.
3. Radix conversion of the coefficients.

Then, Kronecker Substitution complexity is $2E(n) + M(n\ell, n\ell)$.

Kronecker Substitution Variant (KSV)

Proposition 3. *Let $f(x)$ and $g(x)$ be polynomials of degree $n-1$. Each coefficient of $f(x)$ are defined over \mathbb{N} and each coefficient of $g(x)$ are defined over \mathbb{Z} . If for a given ℓ every coefficient $|(f(x)g(x))_i|$ is lower than $2^{\ell-1}$ and all coefficients of $g(x)$ fit on k bits, then the polynomial multiplication complexity of $f(x)g(x)$ with Kronecker substitution variant is $E(n) + n(M(n\ell, k) + S(n\ell, \ell) + A(n\ell, n\ell))$.*

Proof. Let $f(x)$ and $g(x)$ be polynomials of degree $n-1$, such that each bit representation for g_i fits on k bits. Computing $f(x) \times g(x)$ with Kronecker Substitution Variant is done by doing:

1. The evaluation of $f(x)$ at 2^ℓ . Then, $\log_2(f(2^\ell)) \leq n\ell$.
2. A "for" loop with n iterations, each step being:
 - A multiplication between an integer of bitsize $n\ell$ and a coefficients of bitsize k ,
 - An addition or subtraction between two integers of size $n\ell$,
 - A ℓ -shift of an integer of bitsize $n\ell$.
3. A radix conversion of the coefficients.

Then the complexity of the multiplication using Kronecker Substitution Variant is $E(n) + n(M(n\ell, k) + S(n\ell, \ell) + A(n\ell, n\ell))$.

Shift&Add

Proposition 4. *Let $f(x)$ and $g(x)$ be polynomials of degree $n - 1$ with coefficients in \mathbb{Z} . If for a given ℓ every coefficient $|(f(x)g(x))_i|$ is lower than $2^{\ell-1}$ and all coefficients of $g(x)$ belong to $\{-\frac{\delta}{2}, \dots, 0, \dots, \frac{\delta}{2}\}$, then the polynomial multiplication in SHIFT&ADD costs $E(n) + n(S(n\ell, \ell) + \frac{\delta}{2}A(n\ell, n\ell))$.*

Proof. Let $f(x)$, $g(x)$ be polynomials of degree $n - 1$. Algorithm SHIFT&ADD computes the multiplication as follow:

1. Evaluate $f(x)$ at 2^ℓ . Then, $\log_2(f(2^\ell)) \leq n\ell$.
2. A "for" loop called n times. For the three cases, SHIFT&ADD computes:
 - $\frac{\delta}{2}$ additions or subtractions between two integers of size $n\ell$.
3. Radix conversion of the coefficients.

Then SHIFT&ADD complexity is $E(n) + n(S(n\ell, \ell) + \frac{\delta}{2}A(n\ell, n\ell))$.

Complexities comparison Let $f(x)$ and $g(x)$ be polynomial of degree $n - 1$. Assume that the coefficients of $g(x)$ belong to $\{-\frac{\delta}{2}, \dots, 0, \dots, \frac{\delta}{2}\}$ and that for all $i \in \{0, \dots, 2n - 1\}$, $|(f(x)g(x))_i| \leq 2^{\ell-1}$. To choose the most efficient algorithm for polynomial multiplication we need to compare the three following complexities, depending on the component specification.

- SHIFT&ADD: $E(n) + n(S(n\ell, \ell) + \frac{\delta}{2}A(n\ell, n\ell))$.
- Kronecker substitution: $2E(n) + M(n\ell, n\ell)$.
- Kronecker substitution variant: $E(n) + n(M(n\ell, k) + S(n\ell, \ell) + A(n\ell, n\ell))$.

In Section 5.2, we explain how to instantiate the different basic complexities in order to compare the above estimations. We focus our study on the execution time and do not provide memory consumption estimates.

4.3 Time-memory trade-offs

The amount of RAM in embedded devices can be very limited. However, some devices allow a larger RAM consumption which can be utilized to speed-up our algorithms.

Polynomial representation. In Section 2 we describe our compact polynomial representation. This representation is useful to optimize our memory consumption but not to access to the polynomial coefficients. The evaluation and radix conversion require a lot of accesses to the coefficients, thus representing these coefficients as a machine word (e.g 32-bit) improves significantly the performance of these algorithms. Moreover, for some components, using a machine word representation allows to replace shift by pointers arithmetic.

Precomputation. In our context, polynomial multiplication is between $f(x)$ which is a random polynomial over R_q and $g(x)$ which has coefficients in $\{-\frac{\delta}{2}, \dots, \frac{\delta}{2}\}$, where δ is close to 0. Then, we can precompute $\frac{\delta}{2} - 1$ multiples of $f(x)$: $2 \times f(x), \dots, \frac{\delta}{2} \times f(x)$ to reduce the number of operation to one addition/subtraction and one shift of each iteration of SHIFT&ADD loop "for".

Positive case. As mentioned above, one of the polynomials can have negative coefficients. That implies to handle carry propagation during the evaluation, radix conversion or the subdivision. The carry propagation requires an important amount of software implementation to be handled. However, KSV and SHIFT&ADD can perform the polynomial multiplication without negative coefficient and then without carry propagation. Indeed, as the cost of a supplementary evaluation/storage of $-f(x) \bmod q$, which is the computation $q - f_i$ for all the coefficients of f , KSV (resp. SHIFT&ADD) multiplies (resp. add) $f(x)$ when the coefficient of $g(x)$ is non-negative and $-f(x) \bmod q$ when the coefficient is negative.

4.4 Polynomial subdivisions

RSA/ECC coprocessors perform large integers arithmetic with data in buffer whose size has a fixed limit. In our algorithms, after polynomial evaluation, the resulting integer is generally too large to fit in these buffers. In this case, a subdivision is performed on the polynomials before evaluation. Let $f(x) = f_I + f_S x^{n/2}$ and $g(x) = g_I + g_S x^{n/2}$, where f_I, f_S, g_I and g_S have degree $< n/2$. We consider the following methods to subdivide:

Naive: $f(x)g(x) = f_I g_I + (f_I g_S + f_S g_I)x^{n/2} + f_S g_S$

Karatsuba: $f(x)g(x) = f_I g_I + ((f_I + f_S)(g_I + g_S) - f_I g_I - f_S g_S)x^{n/2} + f_S g_S x^n$

Karatsuba performs fewer multiplications at the cost of extra additions, subtractions and memory usage. Depending on the coprocessor specification, it can be slower than the naive subdivision.

Impact on ℓ Subdividing d times divides the value of n by 2^d . However, for the naive subdivision it does not reduce the value of $\ell = \lfloor \log_2(n\beta\delta) \rfloor + 1$. Indeed, after recombination the result's bitsize is the same as a multiplication without subdivision.

Karatsuba requires the multiplication $(f_I + f_S)(g_I + g_S)$, which increases the value of $\ell = \lfloor \log_2(n\beta\delta) \rfloor + 1$. In fact, let f_I, f_S have coefficients in $\{0, \dots, \beta\}$ and g_I, g_S have coefficients in $\{-\frac{\delta}{2}, \dots, \frac{\delta}{2}\}$. Then, $(f_I + f_S)$ have coefficients in $\{0, \dots, 2\beta\}$ and $(g_I + g_S)$ have coefficients in $\{-\delta, \dots, \delta\}$. Thus, $\ell' = \lfloor \log_2(\frac{n}{2} \cdot 2\beta \cdot 2\delta) \rfloor + 1 = \ell + 1$. More generally, if d subdivisions are required, then $\ell' = \ell + d$ must be used instead of ℓ .

Impact on the complexities Subdividing allows to perform a large integer multiplication by few multiplications, additions and subtractions on smaller integers. KS can require one more subdivision than KSV and SHIFT&ADD to avoid a lot of load, store and addition in software. Hence, to determine the most efficient algorithm, with the requirement of d subdivisions for KSV and SHIFT&ADD and d' subdivisions for KS, we only need to compare the following complexities, depending on the component specification.

$$- \text{SHIFT\&ADD: } E(n) + x^d \left(\frac{y}{x} A\left(\frac{n}{2^d}\ell, \frac{n}{2^d}\ell\right) + \frac{n}{2^d} (S(\frac{n}{2^d}\ell, \ell) + \frac{\delta}{2} A(\frac{n}{2^d}\ell, \frac{n}{2^d}\ell)) \right).$$

- Kronecker substitution: $2E(n) + x^{d'} \left(\frac{y}{x} A(\frac{n}{2^d} \ell, \frac{n}{2^d} \ell) + M(\frac{n}{2^{d+1}} \ell, \frac{n}{2^{d+1}} \ell) \right)$.
- Kronecker substitution variant: $E(n) + x^d \left(\frac{y}{x} A(\frac{n}{2^d} \ell, \frac{n}{2^d} \ell) + \frac{n}{2^d} [M(\frac{n}{2^d} \ell, k) + S(\frac{n}{2^d} \ell, \ell) + A(\frac{n}{2^d} \ell, \frac{n}{2^d} \ell)] \right)$.

The values x and y are, respectively, the number of sub-multiplications and the number of additions (or subtractions) required by the subdivision method. Hence, for the naive subdivision $x = 4$ and $y = 3$ and for Karatsuba $x = 3$ and $y = 6$.

In this paper we use the naive or Karatsuba to subdivide but the subdivision can be achieved with other methods.

5 Assessment

5.1 Context

We evaluate three lattice-based algorithms: Saber, LAC and Kyber. They have been submitted to the NIST PQC standardization [DKRV19,XYD⁺19,ABD⁺19]. Saber and Kyber passed the 2nd round and they are finalists of the 3rd round. LAC did not pass the NIST 2nd round but won the Chinese cryptographic competition and thus remains relevant to study.

Parameters In the following, the Kyber 1st round specifications are considered for Kyber512R1 and Kyber1024R1, in order to compare our results with the previous work in [AHH⁺19]. For the other schemes, 2nd round specifications are considered. However, Saber 3rd round parameters and the last two Kyber’s 3rd round security levels parameters are the same as 2nd round. Our results come from a device with dedicated hardware coprocessor for large-integer operations (multiplication, addition, subtraction, right/left shift).

In the following results we consider the multiplication of $f(x)$ by $g(x)$ over $R_q = \mathbb{Z}_q[x]/(x^n + 1)$, where:

1. $f(x)$ is of degree $n - 1$ with coefficients in $\{0, \dots, q - 1\}$.
2. $g(x)$ is of degree $n - 1$ with coefficients in $\{\frac{-\delta}{2}, \dots, \frac{\delta}{2}\}$.
3. The evaluation point is 2^ℓ , where the value of ℓ is given by Proposition 1.

Parameters for each candidate are represented in the following table.

Set/Param	n	q	δ	ℓ
Kyber512R1	256	7681	10	25
Kyber1024R1	256	7681	6	24
KyberR2	256	3329	4	22
Light Saber	256	2^{13}	10	25
Fire Saber	256	2^{13}	6	24
Lac128	512	251	2	18
Lac256	1024	251	2	19

Target Assessments are done on a smart card component. Due to intellectual properties reasons, the component name or a detailed description cannot be given. However, details on our analysis are given, allowing it to be reproduced on any component embedding a similar coprocessor designed for large integer arithmetic. This component is used in real-life products like bank cards, passports, secure elements, etc. It embeds hardware accelerators for asymmetric cryptography computations, including large-integer arithmetic.

In the following, the chip is referred as "Component A".

Component A. The Component A is a ARM 32-bit architecture. Its asymmetric coprocessor can handle 2048-bit operands. The addition of two 2048-bit integers is done in less than ten cycles, while the multiplication takes several thousand cycles. Since the addition is several thousand times cheaper than the multiplication, SHIFT&ADD is expected to be faster than Kronecker Substitution when one operand has coefficients close to 0.

The coprocessor can also multiply a coefficient to a 2048-bit operand, that is of interest with Kronecker Substitution Variant. Then, KSV is expected to be faster than SHIFT&ADD and Kronecker Substitution when one operand has small coefficients but not too close to 0.

5.2 From theory to practice: a methodology

In this section, we propose a methodology to determine, with a minimal amount of implementation, which polynomial multiplication algorithm is the fastest on a given component and for a given set of parameters. This is done by measuring the timings of basic operations (integer multiplication, addition and subtraction, shift and evaluation) and plugging them into the complexities from Section 4. Hence, this ease the algorithm choice without coding all the multiplication algorithms. This can help a developer to quickly decide which algorithm is the best choice.

We detail the methodology for Kyber512R1 parameters on component A. We focus on the comparison between Kronecker Substitution and SHIFT&ADD and between Kronecker Substitution Variant and SHIFT&ADD.

Component A's coprocessor can handle operands of about 2048 bits. For Kyber512R1 parameters $n = 256$ and $\ell = 25$, the polynomials after evaluation are of size $n\ell = 6400$ bits. Thus, we subdivide it to perform our algorithms (see Section 4.4).

On this component, the naive subdivision is more efficient than Karatsuba. For Kronecker Substitution we subdivide until the result $f(x)g(x)$ can fit in the coprocessor. That requires 3 subdivisions to get $\frac{n}{2^3}\ell = 800$ bitsize per operand. For SHIFT&ADD and KSV, we subdivide until the subdivisions of polynomial $f(x)$ can fit in the coprocessor. That requires 2 subdivisions of size 1600-bit. Then, KS requires one more subdivision than KSV and SHIFT&ADD to avoid a lot of load, store and addition in software. Indeed, KS result doubles the size of the operand while each iteration of KSV and SHIFT&ADD increases only by ℓ

the result size, which can be handled without an important amount of software manipulation.

Naive subdivision transforms large arithmetic operations to 4^d smaller arithmetic operations, where d is the required depth. This leads to the following expressions for SHIFT&ADD, KS and KSV complexities:

$$\text{S\&A} : 4^2 \left(\frac{n}{2^2} \left[\frac{\delta}{2} A(1600, 1600) + S(1600, \ell) \right] \right) + 12A(1600, 1600) + E(n)$$

$$\text{KS} : 4^3 M(800, 800) + 48A(1600, 1600) + 2E(n)$$

$$\text{KSV} : 4^2 \left(\frac{n}{2^2} [M(1600, \ell) + S(1600, \ell) + A(1600, 1600)] \right) + 12A(1600, 1600) + E(n)$$

The value $12A(1600, 1600)$ and $48A(1600, 1600)$ are due to the recombination of the naive subdivision but they are negligible. Let $C(S\&A) = \frac{n}{2^2} (\frac{\delta}{2} A(1600, 1600) + S(1600, \ell)) + 3A(1600, 1600)$. We measure the execution time corresponding to $C(S\&A)$ as a reference. Then we measure $E(n)$, $M(800, 800)$ and $M(1600, \ell) + S(1600, \ell) + A(1600, 1600)$ and express them in terms of $C(S\&A)$. These measurements are obtained with an emulator. We get that:

$$E(n) \simeq 1.34 \times C(S\&A)$$

$$M(800, 800) \simeq 0.20 \times C(S\&A)$$

$$\frac{n}{2^2} (M(1600, \ell) + S(1600, \ell) + A(1600, 1600)) \simeq 0.86 \times C(S\&A).$$

It follows the following estimations for SHIFT&ADD, KS and KSV:

$$\text{S\&A} : 4^2 C(S\&A) + E(n) \simeq 17.34 \times C(S\&A)$$

$$\text{KS} : 4^3 M(800, 800) + 2E(n) \simeq 15.48 \times C(S\&A)$$

$$\text{KSV} : 4^2 (0.86 \times C(S\&A)) + E(n) \simeq 15.1 \times C(S\&A)$$

Hence, in this configuration, KSV is expected to be the fastest algorithm for these parameters.

Following this methodology, we get the expected ratios in Table 1 between Kronecker Substitution and SHIFT&ADD and between KSV and SHIFT&ADD, all measurements being obtained with emulators.

	KS/S&A	KSV/S&A		KS/S&A	KSV/S&A
Kyber512R1	0.89	0.87	Fire Saber	1.17	1.1
Kyber1024R1	1.17	1.1	Lac128	1.45	1.37
KyberR2	1.26	1.2	Lac256	1.41	1.42
Light Saber	0.89	0.87			

Table 1. Expected ratio based on basic operations performances for component A

5.3 Experiments

In the sequel, assessments are done using an emulator and we measure the performance of the following:

- algorithms relying on hardware coprocessors (KS, KSV, SHIFT&ADD)
- software implementation of schoolbook multiplication (Saber, Lac)
- software implementation of NTT (Kyber)

The NTT implementation used for Kyber512R1 and Kyber1024R1 is detailed in [LN16]. For KyberR2, the reference implementation of Kyber 2nd round is used [ABD⁺19]. We measure NTT performance with the requirement of frequency transformations of both polynomials (w/ NTT(A)) or with only one frequency transformation (w/o NTT(A)).

Our hardware polynomial multiplications consider that the inputs are not in the NTT domain. Hence, in the case of a Kyber specification compliant implementation additional inverses NTT would have to be performed, which implies that a slower hardware polynomial multiplication than a NTT one.

For LAC software naive multiplication, we report the result for a C implementation and an optimized version in assembly (asm).

Software implementation results are given for information purposes and are not specifically optimized. Indeed, our objective is to provide algorithms which can be applied on many as possible components using a RSA/ECC coprocessors. Therefore, optimizations for software polynomial multiplication using specific instructions set is out of our scope.

Our results are obtained by computing a complete polynomial multiplication over R_q with a compact representation as mentioned in Section 2. The following timings take into account the computation done by the CPU and the coprocessor. Moreover, any optimization of the reduction modulo q and $x^n + 1$ are done. For the same reason, we avoid any optimization which requires a specific software instructions set. However, software optimizations for modular reductions can be used on top of any polynomial multiplication algorithm.

Param/Algo	KS	KSV	S&A	NTT (w / w/o NTT(A))	NAIVE
Kyber512R1	588k	556k	594k	1139k / 793k	N/A
Kyber1024R1	572k	539k	500k	1139k / 793k	N/A
KyberR2	535k	512k	441k	998k / 704k	N/A
Light Saber	580k	546k	585k	N/A	11691k
Fire Saber	563k	530k	493k	N/A	11440k
Lac128	1594k	1586k	1285k	N/A	15560k / 1683k (asm)
Lac256	6209k	6310k	4980k	N/A	62340k / 7494k (asm)

Table 2. Polynomial multiplication over R_q cycle count on component A

Practical results are given in Table 2. As expected for the component A regarding Table 1, SHIFT&ADD is the fastest algorithm for 5/7 parameter sets and KSV is the fastest algorithm for the 2 others. Hence, for this component and these parameters, SHIFT&ADD or KSV are faster than the hardware multiplication introduced in [AHH⁺19].

Note that the theoretical ratios from Table 1 are not the exact same ratios between the practical results. This is because radix conversion and reduction over R_q are not taken into account in the theoretical complexity (see Section 4), while these operations are part of the timings in Table 2. Nevertheless, the fastest algorithm is always the expected one and proves that our methodology introduced in Section 5.2 is relevant.

Positive time/memory trade-off. The positive time/memory trade-off is presented in Section 4.3. This trade-off ensures that any carry propagation must be handled during polynomial multiplication, at cost of a supplementary storage ($n\ell$ bits). However, this trade-off only applies to KSV and S&A algorithms.

The Table 3 shows the practical results obtained on component A, with the highest security parameters of Kyber, Saber and LAC. Furthermore, $\text{KSV}_{\geq 0}$ (resp. $\text{S\&A}_{\geq 0}$) denotes the algorithm Kronecker Substitution Variant (resp. Shift&Add) using the positive trade-off. For the three parameters sets, a significant performance gain on hardware polynomial multiplication is achieved (at least 1.35), at cost of an additional storage of $n\ell$ bits.

Param/Algo	$\text{KSV}_{\geq 0}$	$\text{S\&A}_{\geq 0}$	$\text{KSV}/\text{KSV}_{\geq 0}$	$\text{S\&A}/\text{S\&A}_{\geq 0}$
KyberR2	362k	326k	1.41	1.35
Fire Saber	363k	354k	1.46	1.39
Lac256	4437k	3455k	1.42	1.44

Table 3. Positive trade-off polynomial multiplication over R_q cycle count on component A

6 Conclusion

In this paper, we pursue the work initiated in [AHH⁺19]. We propose two additional methods to compute polynomial multiplications using a RSA/ECC accelerator, when one operand has small coefficients. We introduce a methodology to compare the different methods, based on the implementation on a minimal set of basic functions. This methodology can help to quickly choose the most efficient multiplication algorithm on a given platform, depending on the cryptosystem parameters.

Then, we assess the polynomial multiplication algorithms for several NIST KEM candidates parameters on a smart card chip. The practical results are consistent with the expected behavior from our methodology. In our study, we show that hybrid cryptography can be realized with other methods than the Kronecker Substitution. Moreover, we show that the most optimized method for a given component can be determined with the implementation of few basic operations.

This attest that re-purposing standard asymmetric coprocessor to speed-up lattice-based cryptography is of interest especially in a context of hybrid cryptography deployment.

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