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Tree Diet: Reducing the Treewidth to Unlock FPT Algorithms in RNA Bioinformatics

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¹³ — Abstract

Hard graph problems are ubiquitous in Bioinformatics, inspiring the design of specialized Fixed-14 Parameter Tractable algorithms, many of which rely on a combination of tree-decomposition and 15 16 dynamic programming. The time/space complexities of such approaches hinge critically on low values for the treewidth tw of the input graph. In order to extend their scope of applicability, we 17 introduce the TREE-DIET problem, *i.e.* the removal of a minimal set of edges such that a given 18 tree-decomposition can be slimmed down to a prescribed treewidth tw'. Our rationale is that the 19 time gained thanks to a smaller treewidth in a parameterized algorithm compensates the extra 20 21 post-processing needed to take deleted edges into account. Our core result is an FPT dynamic programming algorithm for TREE-DIET, using $2^{O(tw)}n$ time

Our core result is an FPT dynamic programming algorithm for TREE-DIET, using $2^{O(tw)}n$ time and space. We complement this result with parameterized complexity lower-bounds for stronger variants (e.g., NP-hardness when tw' or tw-tw' is constant). We propose a prototype implementation for our approach which we apply on difficult instances of selected RNA-based problems: RNA design, sequence-structure alignment, and search of pseudoknotted RNAs in genomes, revealing very encouraging results. This work paves the way for a wider adoption of tree-decomposition-based algorithms in Bioinformatics.

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32 Keywords and phrases RNA, treewidth, FPT algorithms, RNA design, structure-sequence alignment

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³⁶ **1** Introduction

³⁷ Graph models and parameterized algorithms are found at the core of a sizable proportion of

algorithmic methods in bioinformatics addressing a wide array of subfields, spanning sequence
 processing [40], structural bioinformatics [42], comparative genomics [7], phylogenetics [2],

and further examples that can be found in a review by Bulteau and Weller [8]. RNA

bioinformatics is no exception, with the prevalence of the secondary structure, an outer

⁴² planar graph [39], as an abstraction of RNA conformations, and the notable utilization of

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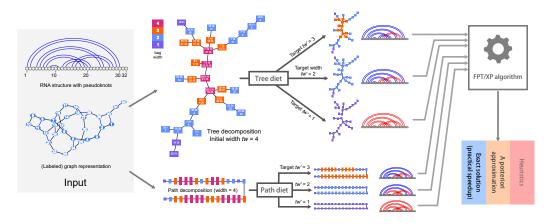


Figure 1 General description of our approach and rationale. Starting from a structured instance, e.g. an RNA structure with pseudoknots, our tree diet/path diet algorithms extract simplified tree/path decompositions, having prescribed target width tw'. Those can be used within existing parameterized algorithms to yield efficient heuristics, *a posteriori* approximations or even exact solutions.

⁴³ graph models to represent complex topological motifs called pseudoknots [41], inducing the ⁴⁴ hardness of several tasks, such as structure prediction [1, 23, 29], structure alignment [5], or ⁴⁵ structure/sequence alignment [25]. Such motifs are functionally important and conserved, as ⁴⁶ witnessed by their presence in the consensus structure of 336 RNA families in the 14.5 edition ⁴⁷ of the RFAM database [18]. Moreover, methods in RNA bioinformatics [28] are increasingly ⁴⁸ considering non-canonical base pairs and modules [20, 24], further increasing the density of ⁴⁹ RNA structural graphs and outlining the need for scalable algorithms.

A parameterized complexity approach can be used to circumvent the frequent NP-50 hardness of relevant problems. It generally considers one or several parameters, whose 51 values are naturally bounded (or much smaller than the length) within real-life instances. 52 Once identified, one aims to design a Fixed Parameter Tractable (FPT) algorithm, having 53 polynomial complexity for any fixed value of the parameter, and reasonable dependency on 54 the parameter value. The treewidth is a classic parameter for FPT algorithms, and intuitively 55 captures a notion of distance of the input to a tree. It is popular in bioinformatics due to the 56 existence of exact FPT algorithms (and efficient heuristics) for computing a tree-decomposition 57 that minimizes the treewidth. Given a tree-decomposition, many combinatorial optimization 58 tasks can be solved using dynamic programming (DP), in time/space complexities that 59 remain polynomial for any fixed treewidth value. Resulting algorithms remain correct upon 60 (almost) arbitrary modifications of the objective function parameters, and can be adapted to 61 study statistical properties of search spaces through changes of algebra. 62

Unfortunately, the existence of a parameterized (or FPT) algorithm does not necessarily 63 imply that of a practically-efficient implementation, even when the parameter takes low 64 typical values. Indeed, the dependency of the complexity on the treewidth may be prohibitive, 65 both in terms of time and memory requirements. This limitation is particularly obvious while 66 searching and aligning structured RNAs, giving rise to an algorithmic problem called the 67 RNA structure-sequence alignment [31, 16, 25], for which the best known exact algorithm 68 is in $\Theta(n.m^{tw+1})$, where n is the structure length, m the sequence/window, and tw is the 69 treewidth of the structure (inc. backbone). Similar complexities hold for problems that 70 can be expressed as (weighted) constraint satisfaction problems, with m representing the 71 cardinality of the variable domains. Such frameworks are frequently used for molecular 72

⁷³ design, both in proteins [36] and RNA [43], and may require the consideration of tree-widths
⁷⁴ up to 20 or more [15].

In this paper, we investigate a pragmatic strategy to increase the practicality of para-75 meterized algorithms based on the treewidth parameter [6]. We put our instance graphs 76 on a diet, *i.e.* we introduce a preprocessing that reduces their treewidth to a prescribed 77 value by removing a minimal cardinality/weight set of edges. As shown above, the prac-78 tical complexity of many algorithms greatly benefits from the consideration of simplified 79 instances, having lower treewidth. Moreover, specific countermeasures can sometimes be 80 used to preserve the correctness of the algorithm. For instance, searching structured RNAs 81 using RNA structure-sequence alignment [31], a iterated filtering strategy could use instances 82 of increasing treewidth to restrict potential hits, weeding them early so that a – costly 83 full structure is reserved to (quasi-)hits. This strategy could remain exact while saving 84 substantial time. Alternative countermeasures could be envisioned for other problems, such 85 as a rejection approach to correct a bias introduced by simplified instances in RNA design. 86 After stating our problem(s) in Section 2, we study in Section 3 the parameterized 87 complexity of the GRAPH-DIET problem, the removal of edges to reach a prescribed treewidth. 88 We propose in Section 4 two DP practical FPT algorithms for TREE-DIET and PATH-89 DIET, two natural simplifications of the GRAPH-DIET problem, where a tree (resp. path) 90 decomposition is provided as input and used as a guide. Finally, we show in Section 5 how 91 our algorithm can be used to extract hierarchies of graphs/structural models of increasing 92 complexity to provide alternative sampling strategies for RNA design, and speed-up the search 93 for pseudoknotted non-coding RNAs. We conclude in Section 6 with future considerations 94 and open problems. 95

⁹⁶ 2 Statement of the problem(s) and results

A tree-decomposition \mathcal{T} (over a set V of vertices) is a tree where nodes are subsets of V, and the bags containing any $v \in V$ induce a (connected) sub-tree of \mathcal{T} . A path-decomposition is a tree-decomposition whose underlying tree is a path. The width of \mathcal{T} (denoted $w(\mathcal{T})$) is the size of its largest bag minus 1. An edge $\{u, v\}$ is visible in \mathcal{T} if some bag contains both uand v, otherwise it is lost. \mathcal{T} is a tree-decomposition of G if all edges of G are visible in \mathcal{T} . The treewidth of a graph G is the minimum width over all tree-decompositions of G.

¹⁰³ ▶ **Problem** (GRAPH-DIET). Given a graph G = (V, E) of treewidth tw, and an integer ¹⁰⁴ tw' < tw, find a tree-decomposition over V of width at most tw' losing a minimum number ¹⁰⁵ of edges from G.

¹⁰⁶ A tree diet of \mathcal{T} is any tree-decomposition \mathcal{T}' obtained by removing vertices from the ¹⁰⁷ bags of \mathcal{T} . \mathcal{T}' is a *d*-tree diet if $w(\mathcal{T}') \leq w(\mathcal{T}) - d$.

Problem (TREE-DIET). Given a graph G, a tree-decomposition \mathcal{T} of G of width tw, and an integer tw' < tw, find a (tw − tw')-tree diet of \mathcal{T} losing a minimum number of edges.

We define BINARY-TREE-DIET and PATH-DIET analogously, where \mathcal{T} is restricted to be a binary tree (respectively, a path). An example is given in Figure 2.

¹¹² Parameterized Complexity in a Nutshell

¹¹³ The basics of parameterized complexity can be loosely defined as follows (see [13] for the ¹¹⁴ formal background). A *parameter* k for a problem is an integer associated with each instance ¹¹⁵ which is expected to remain small in practical instances (especially when compared to the

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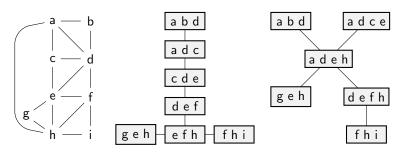


Figure 2 Illustrations for the GRAPH-DIET and TREE-DIET problems. Given a graph G on the left (treewidth 3), an optimal solution for GRAPH-DIET yields the tree-decomposition in the middle (width 2, edge ah is lost). On the other hand, any 1-tree diet for the tree-decomposition on the right loses at least 3 edges

¹¹⁶ input size n). An exact algorithm, or the problem it solves, is FPT if it takes time f(k) poly(n), ¹¹⁷ and XP if it takes time $n^{g(k)}$ (for some functions f, g). Under commonly accepted conjectures, ¹¹⁸ W[1]-hard problems may not be FPT, and Para-NP-hard problems (NP-hard even for some ¹¹⁹ fixed value of k) may not be FPT nor XP.

120 2.1 Our results

Our results are summarized in Table 1. Although the GRAPH-DIET problem would give the most interesting tree-decompositions in theory, it seems unlikely to admit efficient algorithms in practice (see Section 3.1).

Thus we focus on the TREE-DIET relaxation, where an input tree-decomposition is given, 124 which we use as a guide / a restriction towards a thinner tree-decomposition. Seen as an 125 additional constraint, it makes the problem harder (the case tw' = 1 becomes NP-hard, 126 Theorem 2, although for GRAPH-DIET it corresponds to Spanning Tree and is polynomial), 127 however it does help reduce the search space, especially with parameter tw. In Theorem 8 we 128 give an $O((6\Delta)^{tw}\Delta^2 n)$ Dynamic Programming algorithm, where Δ is the maximum number 129 of children of any bag in the tree-decomposition. This algorithm can thus be seen as XP in 130 general, but FPT on bounded-degree tree-decompositions (e.g. binary trees and paths). This 131 is not a strong restriction, since the input tree may safely and efficiently be transformed into 132 a binary one (see Appendix A for more details). 133

We also consider the case where the treewidth needs to be reduced by d = 1 only, this without constraining the source treewidth. We give a polynomial-time algorithm for PATH-DIET in this setting (Theorem 11) which generalizes into an XP algorithm for larger values of d, noting that an FPT algorithm for d is out of reach by Theorem 4. We also show that the problem is NP-hard if the tree degree is unbounded (Theorem 3).

¹³⁹ **3** Algorithmic Limits: Parameterized Complexity Considerations

¹⁴⁰ 3.1 The intricate Graph-Diet Problem

GRAPH-DIET can be seen as a special case of the EDGE DELETION PROBLEM (EDP) for the family of graphs \mathcal{H} of treewidth tw': given a graph G, remove as few edges as possible to obtain a graph in \mathcal{H} . Such edge modification problems are more often parameterized by the number k of edited edges (see [11] for a complete survey). Given our focus on increasing the practicality of treewdith-based algorithms in bioinformatics, we restrict our focus to treewidth related parameters tw, tw' and d = tw - tw'.

| Parameter | Source treewidth | | Target treewidth | Difference | |
|----------------------|--|----------|--------------------------------------|------------------------------------|---|
| Problem | tw | | tw' | d = tw - tw' | |
| | open | | Para-NP-hard | Para-NP-hard* | |
| Graph-Diet | | | tw' = 2 | d = 1 | |
| | | | $EDP(K_4)$ [14] | Theorem 1 | |
| Tree-Diet | $\begin{array}{c} XP \\ O^*((6\Delta)^{tw}) \\ The constant O \end{array}$ | FPT open | | Para-NP-hard d = 1 Theorem 3 | |
| Binary-Tree- Diet | Theorem 8 FPT $O^*(12^{tw})$ Theorem 8 | | Para-NP-hard tw' = 1 Theorem 2 | W[1]-hard Theorem 4 | XP open |
| Path-Diet | | | | | $\begin{array}{c} XP \\ O^*(tw^d) \\ \text{Theorem 11} \end{array}$ |

Table 1 Parameterized results for our problems. Algorithm complexities are given up to polynomial time factors, Δ denotes the maximum number of children in the input tree-decomposition. (*) see Theorem 1 statement for a more precise formulation.

¹⁴⁷ Considering the target treewidth tw', we note that EDP is NP-hard when \mathcal{H} is the family ¹⁴⁸ of treewidth-2 graphs [14], namely K_4 -free graphs, hence the notation EDP(K_4). It follows ¹⁴⁹ that GRAPH-DIET is Para-NP-hard for the target treewidth parameter tw'.

Regarding the source graph treewidth tw, and as it is often the case with treewidth-based problems, graph minor theorems may "freely" give parameterized algorithms. In this respect, GRAPH-DIET corresponds to deciding if a graph G belongs to the family Treewidth-tw'+ke, representing the graphs of treewidth tw', augmented by k additional edges. However, this family is not minor-closed: for some graphs in the family, there is an edge contraction that yields a new graph G' that is not in Treewidth-tw'+ke, as illustrated by Figure 3.

Another theoretical approach is via Courcelle's Theorem [10] and Monadic Second Order 156 (MSO) formulas: it is sufficient to express the property of being in Treewidth-tw'+ke using 157 MSO to prove that GRAPH-DIET is FPT for tw. We presume this is feasible (the main brick 158 being minor testing, which is expressible in MSO), however it is not clear whether this is 159 doable with formulas independent of k, in order to obtain an algorithm for the treewidth 160 alone. In any case, this approach would probably not yield practical algorithms. Indeed, 161 Courcelle's theorem typically lead to running times involving towers of exponentials on the 162 163 relevant parameters, so we do not investigate it further within the scope of this paper.

Another meta-theorem by Cai [9] may yield an FPT algorithm if Treewidth-tw'+ke can be described through forbidden induced subgraphs, but again k would most likely be a parameter as well. On a related note, it is worth noting that Edge Deletion to other graph classes (interval, permutation, ...) does admit efficient algorithms when parameterized by the treewidth alone [27], painting a contrasted picture.

The vertex deletion equivalent of GRAPH-DIET, where one asks for a minimum subset of vertices to remove to obtain a given treewidth, is known as a TREEWIDTH MODULATOR. This problem has been better-studied than its edge-deletion counterpart [12], and has been shown to be FPT for the treewidth [3], with a reasonable dependency in the parameter. However, it is currently unclear how this can be adapted into an edge deletion algorithm.

Overall an FPT algorithm for GRAPH-DIET does not seem out of reach, and could result from one of the above-mentioned meta-theorems. However it seems unlikely to induce a "practical" exact algorithms. Indeed, any algorithm for GRAPH-DIET can be used to compute the TREEWIDTH of an arbitrary graph, for which current state-of-the-art exact algorithms

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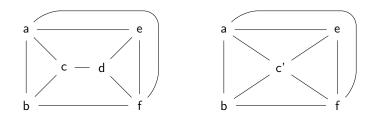


Figure 3 A graph G (left) with treewidth 3. Deleting edge cd gives treewidth 2. However, if one contracts edge cd, then the resulting graph (right) has treewidth 3, and deleting any single edge does not decrease the treewidth. This example shows that the graph family Treewidth 2+1e is not minor-closed.

require time in $tw^{O(tw^3)}$ [6]. We thus have the following conjecture, which motivates the TREE-DIET relaxation of the problem.

Conjecture 1. GRAPH-DIET is FPT for the source treewidth parameter (tw), but no algorithm with single-exponential running time exists.

Finally, for parameter *d*, any polynomial-time algorithm for constant *d* would allow to compute the treewidth of any graph in polynomial time, so we have the following result (see Appendix B for more details).

Theorem 1. There is no XP algorithm for GRAPH-DIET with parameter d unless P = NP.

3.2 Lower Bounds for Tree-Diet

Parameters tw' and d would be the most interesting in practice, since parameterized algorithms would be efficient for small diets *or* small target treewidth. However, we prove strong lowerbounds for TREE-DIET on each of these parameters, leaving very little hope for parameterized algorithms (we thus narrow down the possible algorithms to the combined parameter tw' + d, i.e. tw, see Section 4). Only XP for parameter d when \mathcal{T} has a constant degree remains open (cf. Table 1).

Theorem 2. TREE-DIET and PATH-DIET are Para-NP-hard for the target treewidth parameter tw' (i.e. NP-hard for tw' = 1).

Proof. By reduction from the NP-hard problem SPANNING CATERPILLAR TREE [34]: given a graph G, does G has a spanning tree C that is a caterpillar? Given G = (V, E) with n = |V|, we build a tree-decomposition \mathcal{T} of G consisting of n-1 bags containing all vertices connected in a path. Then (G, \mathcal{T}) admit a tree diet to treewidth 1 with n-1 visible edges if, and only if, G admits a caterpillar spanning tree. Indeed, the subgraph of G with visible edges must be a graph with pathwidth 1, i.e. a caterpillar. With n-1 visible edges, the caterpillar connects all n vertices together, i.e. it is a spanning tree.

▶ **Theorem 3.** TREE-DIET is Para-NP-hard for parameter d. More precisely, it is W[1]-hard for parameter Δ even when d = 1.

Proof. By reduction from MULTI-COLORED CLIQUE. Consider a k-partite graph G = (V, E) with $V = \bigcup_{i=1}^{k} V_i$. We assume that G is regular (each vertex has degree δ and that each V_i has the same size n (MULTI COLORED CLIQUE is W[1]-hard under these restrictions [13]). Let $L := \delta k - {k \choose 2}$ and $N = \max\{|V|, L+1\}$. We now build a graph G' and a tree-decomposition

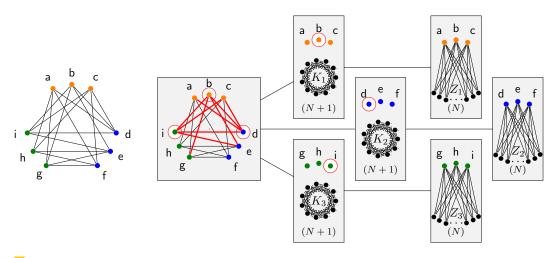


Figure 4 Reduction for Theorem 3 showing that TREE-DIET is NP-hard even for d = 1, from a graph G (left) with k = 3 and n = 3 to a graph G' (right, given by its tree-decomposition of width N + n + 1): a 1-tree diet for G' amounts to selecting a k-clique in the root bag, i.e. in G.

 \mathcal{T}' : start with G' := G. Add k independent cliques K_1, \ldots, K_k of size N + 1. Add k sets of N vertices Z_i $(i \in [k])$ and, for each $i \in [k]$, add edges between each $v \in V_i$ and each $z \in Z_i$. Build \mathcal{T} using 2k + 1 bags $T_0, T_{1,i}, T_{2,i}$ for $i \in [k]$, such that $T_0 = V, T_{1,i} = V_i \cup K_i$ and $T_{2,i} = V_i \cup Z_i$. The tree-decomposition is completed by connecting $T_{2,i}$ to $T_{1,i}$ and $T_{1,i}$ to T_0 for each $i \in [k]$. Thus, \mathcal{T} is a tree-decomposition of G' with $\Delta = k - 1$ and maximum bag size n + N + 1 (vertices of V induce a size-3 path in \mathcal{T} , other vertices appear in a single bag, edges of G appear in T_0 , edges of K_i in $T_{1,i}$, and finally edges between V_i and Z_i appear in $T_{2,i}$). The following claim completes the reduction:

 \mathcal{T} has a 1-tree diet losing at most L edges from $G' \Leftrightarrow G$ has a k-clique.

Assume G has a k-clique $X = \{x_1, \ldots, x_k\}$ (with $x_i \in V_i$). Build \mathcal{T}' by removing each x_i from bags T_0 and $T_{1,i}$. Then \mathcal{T}' is a 1-tree diet of \mathcal{T} . There are no edges lost by removing x_i from $T_{1,i}$ (since x_i is not connected to K_i), and the edges lost in T_0 are all edges of G adjacent to any x_i . Since X form a clique and each x_i has degree d, there are $L = kd - {k \choose 2}$ such edges.

Theorem 4. PATH-DIET is W[1]-hard for parameter d.

²¹⁷ By a straightforward reduction from Clique, see Appendix B for more details.

²¹⁸ **4 FPT Algorithm**

4.1 For general tree-decompositions

We describe here a $O(3^{tw}n)$ -space, $O(\Delta^{tw+2} \cdot 6^{tw}n)$ -time dynamic programming algorithm for the TREE-DIET problem, with Δ and tw being respectively the maximum number of children of a bag in the input tree-decomposition and its width. On *binary* tree-decompositions (where each bag has at most 2 children), it yields a $O(3^{tw}n)$ -space $O(12^{tw}n)$ -time FPT algorithm.

4.1.1 Coloring formulation

We aim at solving the following problem: given a tree-decomposition \mathcal{T} of width tw of a 225 graph G, we want to remove vertices from the bags of \mathcal{T} in order to reach a target width tw', 226 while losing as few edges from G as possible. We tackle the problem through an equivalent 227 coloring formulation: our algorithm will assign a color to each occurrence of a vertex in a 228 bag. We work with three colors: red, orange and green. Green means that the vertex is kept 229 in the bag, while orange and red means removal. To ensure equivalence with the original 230 problem (specifically, that bags where a given vertex is green form a connected subtree), the 231 colors will be assigned following local rules, which we now describe. 232

We first root the tree-decomposition arbitrarily. A coloring of vertices in the bags of the decomposition is said to be *valid* if it follows, when going down the tree, the following rules:

 $_{235}$ = A vertex not present in the parent may be green orange in a child (R1)

 $_{236}$ A green vertex in the parent may be either green or red in the child (R2)

 $_{237}$ = A red vertex in the parent must stay red in the child (R3)

An orange vertex in the parent has to be either orange or green in exactly one child (unless there is no child with this vertex), and must be red in the other children (R4)

²⁴⁰ These rules are summarized in Figure 5 (a).

Since the output tree \mathcal{T}' must form a valid tree-decomposition, for each vertex u, the set 241 of bags containing u must form a (possibly empty) connected sub-tree within \mathcal{T}' . The rules 242 verifiably enforce that green occurrences of a vertex form a connected sub-tree. Informally, 243 orange vertices are locally absent but "may potentially be found further down the tree", 244 while red vertices are removed from both the current bag and its entire sub-tree. Figure 5 (b) 245 shows an example sketch for a valid coloring of the occurrences of a given vertex in the 246 tree-decomposition. A vertex may only be orange along a path starting form its highest 247 occurrence in the tree, with any part branching off that path entirely red. It ends at the top 248 of a (potentially empty) green sub-tree, whose vertices may also be parents to entirely red 249 sub-trees. 250

We will now more formally prove the equivalence of the coloring formulation to the original problem. Let us first introduce two definitions. Given a valid coloring C of a tree-decomposition of G, an edge (u, v) of G is said to be *realizable* if there exists a bag in which both u and v are green per C. Given an integer d, a coloring C of T is said to be d-diet-valid if removing red/orange vertices reduces the width of T from w(T) to w(T) - d.

Proposition 5. Given a graph G, a tree-decomposition \mathcal{T} of width tw, and a target width tw' < tw, The TREE-DIET problem is equivalent to finding a (tw − tw')-diet-valid coloring C of \mathcal{T} allowing for a number of realizable edges in G as large as possible.

²⁵⁹ **Proof.** Given a (tw - tw')-tree-diet of \mathcal{T} , specifying which vertices are removed from which ²⁶⁰ bags, we obtain a valid coloring \mathcal{C} for \mathcal{T} incurring the same number of lost (unrealizable) ²⁶¹ edges. To start with, a vertex u is colored green in the bags where it is not removed. By the

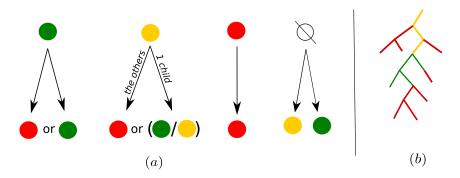


Figure 5 (a) Color assignation rules for vertices, when going down-tree. (b) Sketch of the general pattern our color assignation rules create on \mathcal{T}_u , the sub-tree of bags containing a given vertex u

validity of \mathcal{T}' as a decomposition, this set of bags forms a connected sub-tree, that we denote 262 \mathcal{T}_{u}^{g} . We also write \mathcal{T}_{u} for the sub-tree of bags containing u in the original decomposition \mathcal{T} . 263 If \mathcal{T}_{u}^{g} and \mathcal{T}_{u} do not have the same root, then u is colored orange on the the path in \mathcal{T} from 264 the root of \mathcal{T}_u (included) and the root of \mathcal{T}_u^{g} (excluded). u is colored red in any other bag of 265 \mathcal{T}_u not covered by these two cases. The resulting coloring follows rules (R1-4) and induces 266 the same set of lost/non-realizable edges as the original (tw - tw')-tree-diet. Conversely, an 267 equivalent (tw - tw')-tree-diet is obtained from a (tw - tw')-diet-valid coloring by removing 268 red/orange vertices and keeping green ones. 269

4.1.2 Decomposition of the search space and sub-problems

²⁷¹ Based on this coloring formulation, we now describe a dynamic programming scheme for the ²⁷² TREE-DIET problem. We work with sub-problems indexed by tuples (X_i, f) , with X_i a bag ²⁷³ of the input tree decomposition and f a coloring of the vertices of X_i in green, orange or red ²⁷⁴ (in particular, $f^{-1}(g)$ denote the green vertices of X_i , and similarly for o and r).

Consider an edge (u, v) of G, realizable when coloring a tree-decomposition \mathcal{T} of G with \mathcal{C} , we write \mathcal{T}_{uv}^{g} the subtree of \mathcal{T} in which both u and v are green. We denote by \mathcal{T}_{i} the sub-tree-decomposition rooted at X_{i} , G_{i} the subgraph induced by the vertices present in \mathcal{T}_{i} , and C(i, f) the colorings of \mathcal{T}_{i} agreeing with f on i. Our dynamic programming table is then defined as:

$$c(X_i, f) = \max_{\mathcal{C} \in C(i, f)} \left| \begin{cases} \text{Edges } (u, v) \text{ of } G_i, \text{ realizable within } \mathcal{T}_i \text{ colored with } \mathcal{C} \\ \text{such that } \mathcal{T}_{uv}^{g} \text{ is entirely contained strictly below } X_i \end{cases} \right|$$

Let us more concisely use $RE_{\downarrow}(\mathcal{T}_i, \mathcal{C}, G)$ to denote the set of edges (u, v) of G, realizable under the coloring \mathcal{C} of \mathcal{T}_i , such that \mathcal{T}_{uv}^{g} is entirely contained strictly below X_i . We have:

$$c(X_i, f) = \max_{\mathcal{C} \in C(i, f)} |RE_{\downarrow}(\mathcal{T}_i, \mathcal{C}, G)|$$

The cell $c(X_i, f)$ therefore aggregates all edges realizable *strictly below* X_i . As we shall see through the recurrence relations below and its proof, edges with both ends green in X_i will be accounted for *above* X_i in \mathcal{T} .

The following theorem presents a recurrence relation obeyed by $c(X_i, f)$:

We assume w.l.o.g that the tree-decomposition is rooted at an empty bag R. Given the definition of the table, the maximum number of realizable edges, compatible with a tree diet of (tw - tw') to \mathcal{T} , can clearly be found in $c(R, \emptyset)$.

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▶ **Theorem 6.** For a bag X_i of \mathcal{T} , with children $Y_1, ..., Y_\Delta$, we have:

$$c(X_i, f) = \max_{m: f^{-1}(o) \to [1..\Delta]} \left[\sum_{1 \le j \le \Delta} \left(\max_{f'_j \in comp(Y_j, f, m)} c(Y_j, f'_j) + \left| count(f, f'_j) \right| \right) \right]$$

289 with

- m: a map from the orange vertices in X_i to the children of X_i . It decides for each orange vertex u, which child, among those which contain u, will color u orange or green;
- $_{292}$ = $comp(Y_j, f, m)$: the set of colorings of Y_j compatible with f on X_i and m;

count (f, f'_j) : set of edges of G involving two vertices of Y_j green by f'_j , but such that one of them is either not in X_i or not green by f.

Theorem 6 relies on the following separation lemma for realizable edges under a valid coloring of a tree-decomposition. Recall that we suppose w.l.o.g that the tree-decomposition is rooted at an empty bag.

▶ Lemma 7. An edge (u, v) of G, realizable in \mathcal{T} under \mathcal{C} , is contained in exactly one set of the form $count(C_{|P}, C_{|X})$ with X a bag of \mathcal{T} and P its parent, $C_{|P}, C_{|X}$ the restrictions of \mathcal{C} to P and X, respectively, and "count" defined as above. In addition, X is the root of the sub-tree of \mathcal{T} in which both u and v are green.

³⁰² The proofs of Theorem 6 and Lemma 7 are postponed to Appendix C.

303 4.1.2.1 Dynamic programming algorithm

The recurrence relation of Theorem 6 naturally yields a dynamic programming algorithm for the TREE-DIET problem, as stated below:

Theorem 8. There exists a $O(\Delta^{tw+2} \cdot 6^{tw} \cdot n)$ -time, $O(3^{tw} \cdot n)$ -space algorithm for the TREE-DIET problem, with Δ the maximum number of children of a bag in the input treedecomposition, and tw its width.

³⁰⁹ The proof of this theorem is postponed to Appendix C.

Solution Corollary 9. BINARY-TREE-DIET ($\Delta = 2$) admits an FPT algorithm for the tw parameter.

A pseudo-code implementation of the algorithm, using memoization, is included in Appendix E

4.2 For path decompositions

In the context of paths decompositions, we note that the number of removed vertices per bag can be restricted limited to at most 2d without losing the optimality. More precisely, we say that a coloring C is *d*-simple if any bag has at most *d* orange and *d* red vertices. We obtain the following result, using transformations given in Figure 6.

Proposition 10. Given a graph G and a path-decomposition \mathcal{T} , if C is a d-diet-valid coloring of \mathcal{T} losing k edges, then \mathcal{T} has a d-diet-valid coloring that is d-simple, and loses at most k edges.

The proof of this result is postponed to Appendix D. Together with Proposition 5, this shows

that it is sufficient to restrict our algorithm to *d*-simple colorings. (See also Figure 6). In particular, for any set X_i , the number of such colorings is bounded by $O(tw^{2d})$. Applying

 $_{\tt 323}$ $\,$ this remark to our algorithm presented in Section 4.1 yields the following result:

Theorem 11. PATH-DIET can be solved in $O(tw^{2d}n)$ -space and $O(tw^{4d}n)$ -time.

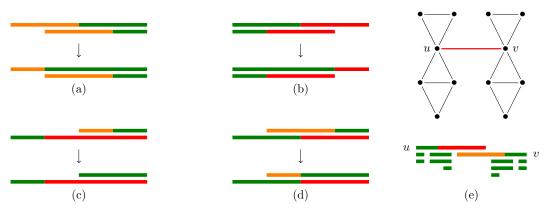


Figure 6 Five cases where two vertices are deleted in the same bag with d = 1. Bags are points in the line, and an interval covering all bags containing v is drawn for each v (with an equivalent coloring, see Proposition 5). Cases (a) to (d) can be safely avoided by applying the given transformations. In the example for case (e), however, it is necessary to delete both vertices u and v form a central bag. It is sufficient to avoid cases (a) and (b) in order to obtain an XP algorithm for d.

325 **5** Proofs of concept

We now illustrate the relevance of our approach, and the practicality of our algorithm for 326 TREE-DIET, by using it in conjunction with FPT algorithms for three problems in RNA 327 bioinformatics. We implemented in C++ the dynamic programming scheme described in 328 Theorem 8 and Appendix E. Its main primitives are made available for Python scripting 329 through pybind11 [17]. It actually allows to solve a generalized weighted version of TREE DIET, 330 as explained in Appendix E. This feature allows to favour the conservation of important edges 331 (e.g. RNA backbone) during simplification, by assigning them a much larger weight compared 332 to other edges. Our implementation is freely available at https://gitlab.inria.fr/amibio/tree-333 diet. 334

5.1 Memory-parsimonious unbiased sampling of RNA designs

As a first use case for our simplification algorithm, we strive to ease the sampling phase of a 336 recent method, called RNAPond [43], addressing RNA negative design. The method targets 337 a set of base pairs S, representing a secondary structure of length n, and infers a set \mathcal{D} of m 338 disruptive base pairs (DBPs) that must be avoided. It relies on a $\Theta(k.(n+m))$ time algorithm 339 for sampling k random sequences (see App. F for details) after a preprocessing in $\Theta(n.m.4^{tw})$ 340 time and $\Theta(n.4^{tw})$ space, where tw is the treewidth of the graph $G = ([1,n], S \cup \mathcal{D})$. In 341 practice, the preprocessing largely dominates the overall runtime, even for large values of k, 342 and its large memory consumption represents the main bottleneck. 343

This discrepancy in the complexities/runtimes of the preprocessing and sampling suggests 344 an alternative strategy: relaxing the set of constraints to (S', \mathcal{D}') , with $(S' \cup \mathcal{D}') \subset (S \cup \mathcal{D})$, 345 and compensating it through a rejection of sequences violating constraints in $(S, \mathcal{D}) \setminus (S', \mathcal{D}')$. 346 The relaxed algorithm remains unbiased, while the average-case time complexity of the 347 rejection algorithm is in $\Theta(k \cdot \overline{q} \cdot (n+m))$ time, where \overline{q} represents the relative increase of the 348 partition function (\approx the sequence space) induced by the relaxation. The preprocessing step 349 retains the same complexity, but based on the reduced treewidth $tw' \leq tw$ of the relaxed 350 graph $G' = ([1, n], S' \cup \mathcal{D}')$. These complexities enable a tradeoff between the rejection 351 (time), and the preprocessing (space), which may be critical to unlock future applications of 352

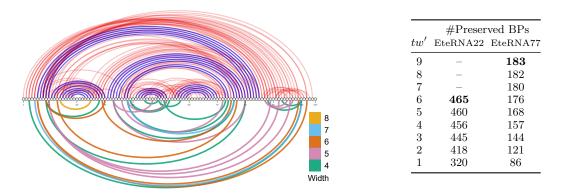


Figure 7 (Left) Target secondary structure (blue BPs), full set of disruptive base pairs (DPB; top) inferred by RNAPond on the Eterna77 puzzle, and subsets of DBPs (bottom) cumulatively removed by the tree-diet algorithm to reach prescribed treewidths. (Right) Number of BPs retained by our algorithm, targeting various treewidth values for the EteRNA22 and EteRNA77 puzzles.

RNA design. Indeed, the treewidth can be decreased by removing relatively few base pairs,
 as demonstrated below using our algorithm on pairs inferred for hard design instances.

We considered sets of DBPs inferred by RNAPond over two puzzles in the EteRNA 355 benchmark. The EteRNA22 puzzle is an empty secondary structure spanning 400 nts, for 356 which RNAP od obtains a valid design after inferring 465 DBPs (tw = 6). The EteRNA77 357 puzzle is 105 nts long, and consists in a collection of helices interspersed with destabilizing 358 internal loops. RNApond failed to produce a solution, and its final set of DBPs consists of 359 183 pairs, forming a graph of treewidth tw = 9. Executing the tree-diet algorithm (Th. 8) 360 on both graphs, we obtained a simplified graphs, having lower treewidth while typically 361 losing few edges, as illustrated and reported in Figure 7. Remarkably, the treewidth of the 362 DBPs inferred for EteRNA22 can be decreased to tw' = 5 by only removing 5 DBPs/edges 363 (460/465 retained), and to tw' = 4 by removing 4 further DBPs (456/465). For EteRNA77, 364 our algorithm reduces the treewidth from 9 to 6 by only removing 7 DBPs. 365

Rough estimates can be provided for the tradeoff between the rejection and preprocessing 366 complexities, by assuming that removing a DBP homogeneously increases the value of \mathcal{Z} by 367 a factor $\alpha := 16/10$ (#pairs/#incomp. pairs). The relative increase in partition function is 368 then $\overline{q} \approx \alpha^b$, when b base pairs are removed. For EteRNA22, reducing the treewidth by 2 369 units $(6 \rightarrow 4)$, *i.e.* a 16 fold reduction of the memory and preprocessing time, can be achieved 370 by removing 9 DBPs, *i.e.* a 69 fold expected increase in the time of the generation phase. For 371 EteRNA77, the same 16 fold $(tw' = 9 \rightarrow 7)$ reduction of the preprocessing time/space can 372 be achieved through an estimated 4 fold increase of the generation time. A more aggressive 373 256 fold memory gain can be achieved at the expense of an estimated 1 152 fold increase 374 in generation time. Given the large typical asymmetry in runtimes and implementation 375 constants between the computation-heavy preprocessing and, relatively light, generation 376 phases, the availability of an algorithm for the TREE-DIET problem provides new options, 377 especially to circumvent memory limitations. 378

5.2 Structural alignment of complex RNAs

Structural homology is often posited within functional families of non-coding RNAs, and is foundational to algorithmic methods for multiple RNA alignments [18], considering RNA base pairs while aligning distant homologs. In the presence of complex structural features

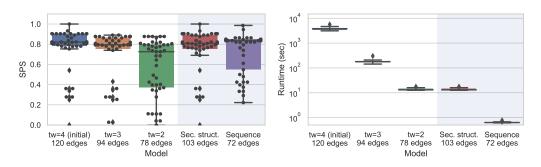


Figure 8 Impact on alignment quality (SPS; Left) and runtime (Right) of simplified instances for the RNA sequence-structure alignment of the pseudoknotted c-di-GMP-II riboswitch. The impact of simplifications on the quality of predicted alignments, using RFAM RF01786 as a reference, appears limited while the runtime improvement is substantial.

(pseudoknots, base triplets), the sequence-structure alignment problem becomes hard, yet 383 admits XP solutions based on the treewidth of the base pair + backbone graph. In particular, 384 Rinaudo et al [25] describe a $\Theta(n.m^{tw+1})$ algorithm for optimally aligning a structured 385 RNA of length n onto a genomic region of length m. It optimizes an alignment score that 386 includes: i) substitution costs for matches/mismatches of individual nucleotides and base 387 pairs (including arc-breaking) based on the RIBOSUM matrices [19]; and ii) an affine gap 388 cost model [26]. We used the implementation of the Rinaudo et al algorithm, implemented 389 in the LicoRNA software package [37, 38]. 390

³⁹¹ 5.2.1 Impact of treewidth on the structural alignment of a riboswitch

In this case study, we used our tree-diet algorithm to modulate the treewidth of complex 392 RNA structures, and investigate the effect of the simplification on the quality and runtimes of 393 structure-sequence alignments. We considered the Cyclic di-GMP-II riboswitch, a regulatory 394 motif found in bacteria that is involved in signal transduction, and undergoes conformational 305 change upon binding the second messenger c-di-GMP-II [32, 33]. A 2.5Å resolution 3D model 396 of the c-di-GMP-II riboswitch in C. acetobutylicum, proposed by Smith et al [30] based on 397 X-ray crystallography, was retrieved from the PDB [4] (PDBID: 3Q3Z). We annotated its base 398 pairs geometrically using the DSSR method [22]. The canonical base pairs, supplemented 399 with the backbone connections, were then accumulated in a graph, for which we heuristically 400 computed an initial tree decomposition \mathcal{T}_4 , having treewidth tw = 4. 401

We simplified our the initial tree decomposition \mathcal{T}_4 , and obtained simplified models \mathcal{T}_3 , and \mathcal{T}_2 , having width tw' = 3 and 2 respectively. As controls, we included tree decompositions based on the secondary structure (max. non-crossing set of BPs; \mathcal{T}_{2D}) and sequence (\mathcal{T}_{1D}). We used LicoRNA to predict an alignment $a_{\mathcal{T},w}$ of each original/simplified tree decomposition \mathcal{T} onto each sequence w of the c-di-GMP-II riboswitch family in the RFAM database [18] (RF01786). Finally, we reported the LicoRNA runtime, and computed the Sum of Pairs Score (SPS) [35] as a measure of the accuracy of $a_{\mathcal{T},w}$ against a reference alignment a_w^* :

$$\mathsf{SPS}(a_{\mathcal{T},w}; a_w^{\star}) = \frac{|\mathsf{MatchedCols}(a_{\mathcal{T},w}) \cap \mathsf{MatchedCols}(a_w^{\star})|}{|\mathsf{MatchedCols}(a_w^{\star})|},$$

using as reference the alignment a_w^{\star} between the 3Q3Z sequence and w induced by the manually-curated RFAM alignment of the RF01786 family.

The results, presented in Figure 8, show a limited impact of the simplification on the quality of the predicted alignment, as measured by the SPS in comparison with the RFAM

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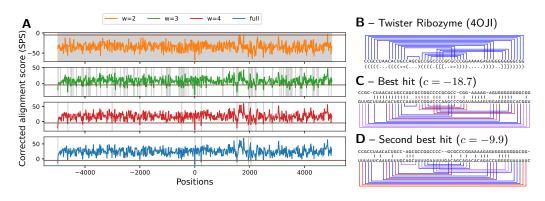


Figure 9 Corrected costs associated with the search for structured homologs of the Twister ribozyme in chromosome 5 of *S. bicolor*, using simplified instances of various treewidth (A). Gray areas represent scores which, upon correction, remain below the cutoff, and have to be considered for further steps of the iterated filtering. Canonical base pairs of the ribozyme (PDBID 40JI; B), mapped onto to the best hit (C) and second best hit (D) found along the search colored depending on their support in the target sequence (Red: incompatible; Purple: unstable G-U; Blue: stable).

alignment. The best average SPS (77.3%) is achieved by the initial model, having treewidth 406 of 4, but the average difference with simplified models appears very limited (e.g. 76.5% for 407 \mathcal{T}_3), especially when considering the median. Meanwhile, the runtimes mainly depend on the 408 treewidth, ranging from 1h for \mathcal{T}_4 to 300ms for \mathcal{T}_{1D} . Overall, \mathcal{T}_{2D} seems to represent the 409 best compromise between runtime and SPS, although its SPS may be artificially inflated by 410 our election of RF01786 as our reference (built from a covariance model, *i.e.* essentially a 2D 411 structure). Finally, the difference in number of edges (and induced SPS) between \mathcal{T}_{2D} and 412 \mathcal{T}_2 , both having tw = 2, exemplifies the difference between the TREE-DIET and GRAPH-DIET 413 problems, and motivates further work on the latter. 414

5.2.2 Exact iterative strategy for the genomic search of ncRNAs

In this final case study, we consider an exact filtering strategy to search new occurrences of a structured RNA within a given genomic context. In this setting, one attempts to find all ε -admissible (cost $\leq \varepsilon$) occurrences/hits of a structured RNA *S* of length *n* within a given genome of length $g \gg n$, broken down in windows of length $\kappa.n, \kappa > 1$. Classically, one would align *S* against individual windows, and report those associated with an admissible alignment cost. This strategy would have an overall $\Theta(g \cdot n^{tw+2})$ time complexity, applying for instance the algorithm of [25].

Our instance simplification framework enables an alternative strategy, that incrementally 423 filters out unsuitable windows based on models of increasing granularity. Indeed, for any given 424 target sequence, the min alignment cost c_{δ} obtained for a simplified instance of treewidth 425 $tw - \delta$ can be corrected (cf Appendix G) into a lower bound c^{\star}_{δ} for the min alignment 426 cost c_0^* of the full-treewidth instance tw. Any window such that $c_0^* > \varepsilon$ thus also obeys 427 $c_0^{\star} > \varepsilon$, and can be safely discarded from the list of putative ε -admissible windows, without 428 having to perform a full-treewidth alignment. Given the exponential growth of the alignment 429 runtime for increasing treewidth values (see Figure 8-right) this strategy is expected to yield 430 substantial runtime savings. 431

We used this strategy to search occurrences of the Twister ribozyme (PDBID 40JI), a highly-structured (tw = 5) 54nts RNA initially found in *O. sativa* (asian rice) [21]. We targeted the *S. bicolor* genome (sorghum), focusing on a 10kb region centered on the 2,485,140

⁴³⁵ position of the 5th chromosome, where an instance of the ribozyme was suspected within ⁴³⁶ an uncharacterized transcript (LOC110435504). The 4OJI sequence and structure were ⁴³⁷ extracted from the 3D model as above, and included into a tree decomposition \mathcal{T}_5 (73 edges), ⁴³⁸ simplified into \mathcal{T}_4 (71 edges), \mathcal{T}_3 (68 edges) and \mathcal{T}_2 (61 edges) using the tree-diet algorithm.

We aligned all tree decompositions against all windows of size 58nts using 13nts offset, and 439 measured the score and runtime of the iterative filtering strategy using a cost cutoff $\varepsilon = -5$. 440 The search recovers the suspected occurrence of twister as its best result (Figure 9.C), but 441 produced hits (cf Figure 9.D) with comparable sequence conservation that could be the 442 object of further studies. Regarding the filtering strategy, while \mathcal{T}_2 only allows to rule out 443 3 windows out of 769, \mathcal{T}_3 allows to eliminate an important proportion of putative targets, 444 retaining only 109 windows, further reduced to 15 windows by \mathcal{T}_4 , 6 of which end up as final 445 hits for the full model \mathcal{T}_5 (cf Figure 9.A). The search remains exact, but greatly reduces the 446 overall runtime from 24 hours to 34 minutes (42 fold!). 447

6 Conclusion and discussion

We have established the parameterized complexity of three treewidth reduction problems, 449 motivated by applications in Bioinformatics, as well as proposed practical algorithms for 450 instances of reasonable treewidths. The reduced widths obtained by our proposed algorithm 451 can be used to obtain: i) sensitive heuristics, owing to the consideration of a maximal 452 amount of edges/information in the thinned graphs; ii) a posteriori approximation ratios, by 453 comparing the potential contribution of removed edges to the optimal score obtained of the 454 thinned instance by a downstream FPT/XP algorithm; iii) substantial practical speedups 455 without loss of correctness, e.g. when partial filtering can be safely achieved based on 456 simplified input graphs. 457

Open questions. Regarding the parameterized complexity of GRAPH-DIET and TREE-458 DIET, some questions remain open (see Table 1): an FPT algorithm algorithm for TREE-DIET 459 (ideally, with $2^{O(tw)}$ running time), would be the most desirable, if possible satisfying the 460 backbone constraints. We also aim at settling the parameterized complexity of the GRAPH-461 DIET problem, and try to give efficient exact algorithms for this problem (possibly using 462 some tree-decomposition in input). Finally, we did not include the number of deleted edges 463 in our multivariate analysis: even though in practice it is more difficult, a priori, to guarantee 464 it has a small value, we expect it can be used to improve the running time in many cases. 465

Backbone Preservation. In two of our applications, the RNA secondary structure graph 466 contains two types of edges: those representing the *backbone* of the sequence (i.e., between 467 consecutive bases) and those representing base pair bounds. In practice, we want all backbone 468 edges to be visible in the resulting tree-decomposition, and only base pairs may be lost. 469 This can be integrated to the TREE-DIET model (and to our algorithms) using weighted 470 edges, using the total weight rather than the count of deleted edges for the objective function. 471 Note that some instances might be unrealizable (with no tree diet preserving the backbone, 472 especially for low tw'). In most cases, ad-hoc bag duplications can help avoid this issue. 473

From a theoretical perspective, weighted edges may only increase the algorithmic complexity of the problems. However, a more precise model could consider graphs which already include a hamiltonian path (the backbone), and the remaining edges form a degree-one or two subgraph. Such extra properties may, in some cases, actually reduce the complexity of the problem. As an extreme case, we conjecture the PATH-DIET problem for tw' = 1becomes polynomial in this setting.

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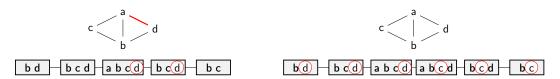


Figure 10 Left: A graph and a path-decomposition whose optimal 1-tree diet loses an edge (ad). However, duplicating the bag abcd (right) yields a tree-decomposition with a lossless 1-tree diet.

A Editing Trees before the Diet

The goal of TREE-DIET is to fix the tree-decomposition structure in order to help achieve 610 faster algorithms: finding the best tree-decomposition to give in input would a priori be 611 a difficult task. However, given a tree-decomposition \mathcal{T} , some editions can be performed 612 to obtain a tree-decomposition \mathcal{T}' , that (1) take linear time and (2) may only improve the 613 tree-diet solution. In particular, duplicating nodes may only improve the solution (and may 614 strictly improve it in some cases, see Figure 10). The same applies to common operations 615 to obtain *nice* tree-decompositions (i.e. binary with at most 1 vertex difference between 616 adjacent bags), except joining identical nodes (by the example of Figure 10 again). So overall 617 it is safe to assume that the input tree-decomposition satisfies the properties of \mathcal{T}' such as 618 being binary with small bag differences. 619

B Postponed Proofs in Section 3.2

Proof of Theorem 1. We consider the decision version of GRAPH-DIET where a bound k621 on the number of deleted edges is given. We build a Turing reduction from TREEWIDTH: 622 more precisely, assuming an oracle for GRAPH-DIET with d = 1 is available, we build a 623 polynomial-time algorithm to compute the treewidth of a graph G. This is achieved by 624 computing GRAPH-DIET(G, tw, d = 1, k = 0) for decreasing values of tw (starting with 625 tw = |V|: the first value of tw for which this call returns no solution is the treewidth of 626 G. Note that this is not a many-one reduction, since several calls to GRAPH-DIET may be 627 necessary (so this does not precisely qualify as an NP-hardness reduction, even though a 628 polynomial-time algorithm for GRAPH-DIET(G, tw, d = 1, k = 0) would imply P=NP). -629

Proof of Theorem 4. By reduction from CLIQUE. Given a δ -regular graph G with n vertices and m edges and an integer k, consider the trivial tree-decomposition \mathcal{T} of G with a single bag containing all vertices of G (it has width n-1). Then (\mathcal{T}, G) has a k-tree diet losing $\delta k - {k \choose 2}$ edges if and only if G has a k-clique. Indeed, such a tree diet \mathcal{T}' would remove a set X of k vertices from G and losing $\delta k - {k \choose 2}$ edges, so X induces ${k \choose 2}$ edges and is a k-clique of G.

C Postponed proofs of dynamic programming scheme

⁶³⁷ **Proof of Lemma 7.** Given, in a tree-decomposition, a bag P colored with f, with a child X⁶³⁸ colored with h, a more precise definition for count(f, h) is:

$$_{_{640}}^{_{639}} \qquad count(f,h) = \left\{ (u,v) \in E \mid \begin{array}{c} h(u) = h(v) = green \quad \text{and} \\ (u \notin f^{-1}(*) \text{ or } f(u) \neq g \text{ or } v \notin f^{-1}(*) \text{ or } f(v) \neq g) \right\}$$

Now, given a realizable edge (u, v), in a tree-decomposition \mathcal{T} colored with \mathcal{C} , the set of bags in which both u and v are green forms a connected sub-tree of \mathcal{T} . This sub-tree has a

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⁶⁴³ root, or *lowest common ancestor*, that we denote $R_{(u,v)}$. Since we assumed \mathcal{T} to be rooted ⁶⁴⁴ at an empty bag, $R_{(u,v)}$ is not the root of \mathcal{T} , and has a parent. We call this parent $P_{(u,v)}$. ⁶⁴⁵ Clearly, (u,v) belongs to the "count set" associated to the edge $(P_{(u,v)}) \to (R_{(u,v)})$ of \mathcal{T} , ⁶⁴⁶ while for any other edge $X \to Y$ of \mathcal{T} , the colors of u and v cannot verify the conditions to ⁶⁴⁷ belong to the associated "count set".

648 Proof of Theorem 6.

⁶⁵⁰ $\leq \leq$ By definition, $c(X_i, f) = \max_{\mathcal{C} \in C(\mathcal{T}_i, f)} |RE_{\downarrow}(\mathcal{T}_i, \mathcal{C}, G)|$ is the maximum number of realiz-⁶⁵¹ able edges in the sub-tree-decomposition rooted at X_i , such that all green-green occurences ⁶⁵² of the edge occur strictly below X_i , and under the constraint that f colors X_i . Let \mathcal{C} be a ⁶⁵³ coloring for \mathcal{T}_i realizing the optimum $c(X_i, f)$. Its restrictions to $Y_1 \dots Y_\Delta$ yield colorings ⁶⁵⁴ $f'_1 \dots f'_\Delta$. Likewise, its restrictions to the sub-tree-decompositions $\mathcal{T}'_1 \dots \mathcal{T}'_\Delta$ rooted at ⁶⁵⁵ $Y_1 \dots Y_\Delta$ yield colorings $\mathcal{C}'_1 \dots \mathcal{C}'_\Delta$ compatible with $f'_1 \dots f'_\Delta$. $\mathcal{C}'_1 \dots \mathcal{C}'_\Delta$ cannot be better ⁶⁵⁶ than the optimal, so $\forall j$, $|RE_{\downarrow}(\mathcal{T}'_j, \mathcal{C}'_j, G)| \leq c(Y_j, f'_j)$

Let (u, v) be an edge of $RE_{\downarrow}(\mathcal{T}_i, \mathcal{C}, G)$. Per Lemma 7, either $(u, v) \in count(f, f'_j)$ for some j (if Y_j is the root of \mathcal{T}^{g}_{uv}) and $(u, v) \notin \cup_j RE_{\downarrow}(\mathcal{T}'_j, \mathcal{C}'_j, G)$ or $(u, v) \in count(f, f'_j)$ and $\exists j$ such that $(u, v) \in RE_{\downarrow}(\mathcal{T}'_j, \mathcal{C}'_j, G)$. Therefore:

$$\begin{aligned} c(X_i, f) &= |RE_{\downarrow}(\mathcal{T}_i, \mathcal{C}, G)| = \sum_{1 \le j \le \Delta} \left[|RE_{\downarrow}(\mathcal{T}'_j, \mathcal{C}'_j, G)| + count(f, f'_j) \right] \\ &\leq \sum_{1 \le j \le \Delta} \left(c(Y_j, f'_j) + count(f, f'_j) \right) \end{aligned}$$

661 662 663

664 665

660

649

and, a fortiori

$$c(X_i, f) \le \max_{m: f^{-1}(o) \to [1...\Delta]} \sum_{1 \le j \le \Delta} \max_{f'_j \in comp(Y_j, f, m)} \left(c(Y_j, f'_j) + count(f, f'_j) \right)$$

Conversely, given f, let m be an assignation map for orange vertices and $f'_1 \dots f'_\Delta$ colorings of $Y_1 \dots Y_\Delta$ compatible with f and m, and let $\mathcal{C}'_1 \dots \mathcal{C}'_\Delta$ be colotings of $\mathcal{T}'_1 \dots \mathcal{T}'_\Delta$ realizing the optima $c(Y_1, f'_1) \dots c(Y_\Delta, f'_\Delta)$. The union of $\mathcal{C}'_1 \dots \mathcal{C}'_\Delta$ and f is a coloring \mathcal{C} for \mathcal{T}_i , the sub-tree-decomposition rooted at X_i , which can not be better than optimal $|RE_{\downarrow}(\mathcal{T}_i, \mathcal{C}, G)| \leq c(X_i, f)|$. As before, an edge (u, v) either belongs to $\cup_j count(f, f'_j)$ or to $\cup_j RE_{\downarrow}(\mathcal{T}'_j, \mathcal{C}'_j, G)$ but not both. In any case, it belongs to $RE_{\downarrow}(\mathcal{T}_i, \mathcal{C}, G)$. Therefore:

$$\sum_{1 \le j \le \Delta} \left(c(Y_j, f'_j) + count(f, f'_j) \right) = \sum_{1 \le j \le \Delta} \left(|RE_{\downarrow}(\mathcal{T}'_j, \mathcal{C}'_j, G)| + count(f, f'_j) \right)$$

$$= |RE_{\downarrow}(\mathcal{T}_i, \mathcal{C}, G)|$$

$$\leq c(X_i, f)$$

This is true for any choice of $m, f'_1 \dots f'_{\Delta}$, therefore:

$$\max_{m:f^{-1}(o)\to[1\dots\Delta]}\sum_{1\leq j\leq\Delta}\max_{f'_j\in comp(Y_j,f,m)}\left(c(Y_j,f'_j)+count(f,f'_j)\right)\leq c(X_i,f)$$

which concludes the proof.

678

⁶⁷⁹ **Proof of Theorem 8.** Given the sub-problems and $c(X_i, f)$ -table definitions, with R the ⁶⁸⁰ (empty) root of the tree-decomposition, $c(R, \emptyset)$ is indeed the maximum possible number of

<

realizable edges when imposing a (tw - tw')-diet to \mathcal{T} . The recurrence relation of Theorem 6 therefore for a dynamic programming approach, over the tree-decomposition \mathcal{T} following leaf-to-root order, for the problem.

The number of entries to the table is $O(3^{tw}n)$, given that a bag X may be colored in $3^{|X|}$ ways, and that the maximum size of X is tw + 1. For a given entry X_i , one must first enumerate all possible choices of $m: f^{-1}(o) \to [1...\Delta]$, map assigning one child of X_i to each orange vertex in X_i . There are $O(\Delta^{tw+1})$ possibilities for m in the worst case, as $|f^{-1}(o)| \leq tw + 1$. Then, for each child Y_j , one must enumerate all possible colorings f'_j compatible with f. Possibilities for $f'_j(u)$ depend on the color by f:

690 if
$$u \notin X_i \to f'_j(u) = o$$
 or g

$$f_{g_{j_1}} = f(u) = g \to f'_j(u) = g \text{ or } r$$

⁶⁹² if $f(u) = o \to f'_j(u) = o$ or g if m[u] = j or $f'_j(u) = r$ otherwise.

⁶⁹³ if $f(u) = r \to f'_j(u) = r$ or Overall as there are at most Λ children

⁶⁹⁴ Overall, as there are at most Δ children, w + 1 vertices in each child, and 2 possibilities (see ⁶⁹⁵ enumeration of cases above) of color for each vertex in a child, yielding a total number of ⁶⁹⁶ compatible colorings bounded by $O(\Delta \cdot 2^{tw+1})$. Multiplying these contributions, the overall ⁶⁹⁷ time complexity of our algorithm is therefore $O(\Delta^{tw+2} \cdot 6^{tw} \cdot n)$.

D Postponed proofs of path decomposition case

Proof of Proposition 10. Consider such a coloring \mathcal{C} with a maximal number of green 699 vertices. We show that it is d-simple. Assume the path-decomposition \mathcal{T} is rooted in bag 700 X_1 and each X_i is the parent of X_{i+1} . Pick i to be the smallest index so that at least d+1701 vertices in X_i are colored red by \mathcal{C} , assume any such *i* exists. Then one of these vertices, 702 say u, is not colored red in X_{i-1} (either because i = 1, or it is not in X_{i-1} , or it is orange 703 or green in X_{i-1}). Consider \mathcal{C}' obtained by \mathcal{C} and coloring u green in X_i . Then \mathcal{C}' satisfies 704 local rules R1 through R4 (a green vertex may be absent, green or orange in the parent bag, 705 and a red vertex may be green in the parent bag). Furthermore, it is d-diet-valid since it 706 still removes at least d (red) vertices in X_i . Overall \mathcal{C}' is another d-diet-valid coloring with 707 more green vertices: a contradiction, so no such i exist (and no bag has d+1 red vertices). 708 The same argument works symmetrically for orange vertices. Overall, \mathcal{C} is d-simple. 709

710 **E** Pseudo-code

⁷¹¹ Algorithm 1 and 2 present a pseudo-code of our dynamic programming algorithm for TREE
⁷¹² DIET, with a memoization approach. The C++/pybind11 [17] implementation is available
⁷¹³ at https://gitlab.inria.fr/amibio/tree-diet.

Note that the implementation allows to solve a more general *weighted* version of TREE DIET, where each edge is given a weight, and the objective is to find a (tw - tw')-diet of the input tree decomposition preserving a set of edges of maximum total weight.

In the context of RNA applications, this feature allows to favour as much as possible preservation of the backbone of RNA molecules, i.e. edges between consecutive nucleotides along the string, by assigning them a weight greater than the number of non-backbone edges. Edge weights are passed to the function in the form of a dictionary/map W associating a real weight to each edge. Within Algorithms 1 and 2, the only place where it is taken into account is the the *count* function, which computes the weight of edges accounted for by the bag that is currently visited. **Algorithm 1** Dynamic programming algorithm for TREE-DIET.

```
: Tree-decomposition \mathcal{T}, graph G, target width tw', edge weights W
    Input
    Output
                     : Maximum total weight of a set of realizable/non-lost edges in a
                      (tw - tw')-diet of \mathcal{T}
   Side-Product: A filled table c[X_i, f], \forall X_i bag and f coloring of X_i
 1 Function optim_num_real_edges(X_i, f, G, tw', W):
       if c[X_i, f] already computed then return c[X_i, f];
 \mathbf{2}
       if |f^{-1}(o) \cup f^{-1}(r)| \le (|X_i| - tw' - 1) then
 3
 4
           //not enough removals.;
           c[X_i, f] = -\infty;
 \mathbf{5}
 6
           return c[X_i, f];
 7
       end
       if X_i == leaf then
 8
           c[X_i, f] = 0;
 9
           return c[X_i, f];
\mathbf{10}
       end
11
12
       int ans = -\infty;
       for m \in orange\_maps(X_i, f) do
13
           int ans_m = 0;
\mathbf{14}
           for Y_j \in X_i.children do
15
               int ans_j = -\infty;
16
                for f'_j \in compatible(f, m, X_i, Y_j) do
17
                    int val = 0;
18
                    val += count(f, f'_i, W);
19
                    val += optim_num_real_edges(Y_j, f'_j, G, tw');
20
                    if val \geq ans_j then
\mathbf{21}
                       ans_j = val;
\mathbf{22}
                   end
23
                \mathbf{end}
24
\mathbf{25}
               ans_m += ans_j;
26
            end
           if ans\_m \ge ans then
27
               ans = ans m;
28
29
           end
       \mathbf{end}
30
       c[X_i, f] = ans
31
       return c[X_i, f];
\mathbf{32}
33 end
```

```
\label{eq:algorithm} Algorithm \ 2 \ \ {\rm Backtracking \ procedure \ for \ TREE-DIET}.
                        : Tree-decomposition \mathcal{T}, graph G, target width tw', table c, edge
    Input
                          weights W
                        : Optimal (tw - tw')-diet-valid coloration for \mathcal{T}
    Output
 1 Function optim_coloring(X_i, f, G, tw', c):
        if X_i == leaf then
 2
         return \emptyset;
 3
         end
 4
         coloring \mathcal{C} = \emptyset;
 \mathbf{5}
         for m \in orange\_maps(X_i, f) do
 6
             int ans_m = 0;
 7
             coloring best_fjs = [];
 8
             for Y_i \in X_i.children do
 9
                  int best_valj = -\infty;
10
                  int best_fj = \emptyset;
11
                  for f'_j \in compatible(f, m, X_i, Y_j) do
\mathbf{12}
                      int val = 0;
\mathbf{13}
                      val += count(f, f'_i, W);
\mathbf{14}
                      val += c[Y_j, f'_j];
\mathbf{15}
                      if val \geq best_valj then
16
                           best_valj = val;
17
                           best_fj = f'_j;
18
19
                      \mathbf{end}
                  end
20
                  ans_m += best_valj;
21
\mathbf{22}
                  best_fjs.add(best_fj);
             end
23
             if ans\_m == c[X_i, f] then
\mathbf{24}
                  \mathcal{C} + = [f'_j \text{ for } f'_j \text{ in } best\_fjs];
\mathbf{25}
                  \mathcal{C} + = [\texttt{optim\_coloring}(Y_j, f'_j, G, tw', c) \text{ for } f'_j \text{ in } best\_fjs];
26
                  break;
                                                                                    // break loop over m
27
             end
28
         end
29
         return C;
30
31 end
```

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F Correctness of the rejection-based sampling of candidate RNA designs

A recent method for RNA design, called RNAPond [43], implements a sampling approach to tackle the inverse folding of RNA. Targeting a secondary structure *S* of length *n*, it performs a Boltzmann-weighted sampling of sequences and, at each iteration, identifies Disruptive Base Pairs (DBPs) that are not in *S*, yet are recurrent in the Boltzmann ensemble of generated sequences. Those base pairs are then added to a set \mathcal{D} of DBPs, and excluded in subsequent generations through an assignment of non-binding pairs of nucleotides, outside of $\mathcal{B} := \{(\mathsf{G},\mathsf{C}), (\mathsf{C},\mathsf{G}), (\mathsf{A},\mathsf{U}), (\mathsf{U},\mathsf{A}), (\mathsf{G},\mathsf{U}), (\mathsf{U},\mathsf{G})\}$.

At the core of the method, one finds a random generation algorithm which takes as input a secondary structure S and a set \mathcal{D} of DBPs. The algorithm generates from the set $\mathcal{W}_{S,\mathcal{D}}$ of sequences $w \in \{A, C, G, U\}^n$ which are: i) compatible with all $(i, j) \in S$, *i.e.* $(w_i, w_j) \in \mathcal{B}$; and ii) incompatible with all $(k, l) \in \mathcal{D}$, *i.e.* $(w_k, w_l) \notin \mathcal{B}$. The algorithm then enforces a (dual) Boltzmann distribution over the sequences in $\mathcal{W}_{S,\mathcal{D}}$:

$$\forall w \in \mathcal{W}_{S,\mathcal{D}} : \mathbb{P}(w \mid \mathcal{D}, S) = \frac{e^{-\beta \cdot E_{w,S}}}{\mathcal{Z}_{S,\mathcal{D}}} \quad \text{with} \quad \mathcal{Z}_{S,\mathcal{D}} := \sum_{w' \in \mathcal{W}_{S,\mathcal{D}}} e^{-\beta \cdot E_{w',S}}$$
(1)

where $\beta > 0$ is an arbitrary constant akin to a temperature. Yao *et al* describe an algorithm which generates k sequences in $\Theta(k(n + |\mathcal{D}|))$ time, after a preprocessing in $\Theta(n.|\mathcal{D}|.4^{tw})$ time and $\Theta(n.4^{tw})$ space, where tw is the treewidth of the graph having edges in $S \cup \mathcal{D}$.

The discrepancy in the preprocessing and sampling complexities suggests an alternative strategy, utilizing rejection on top of a relaxed sampling. Namely, we consider a rejection algorithm, which starts from a relaxation (S', \mathcal{D}') of the initial constraints $(S' \cup \mathcal{D}' \subset S \cup \mathcal{D})$, and iterates Yao *et al*'s algorithm to generate sequences in $\mathcal{W}_{S',\mathcal{D}'} \supset \mathcal{W}_{S,\mathcal{D}}$, rejecting those outside of $\mathcal{W}_{S,\mathcal{D}}$, until k suitable ones are obtained. The rejection algorithm generates a given sequence $w \in \mathcal{W}_{S,\mathcal{D}}$ on its first attempt with probability $p := e^{-\beta \cdot E_{w,S}}/\mathcal{Z}_{S',\mathcal{D}'}$ and, more generally, after r rejections with probability $(1-q)^r p$ with $q := \mathcal{Z}_{S,\mathcal{D}}/\mathcal{Z}_{S',\mathcal{D}'}$. The overall probability of emitting w is thus

$$p \cdot \sum_{r>0} (1-q)^r = \frac{p}{q} = \frac{e^{-\beta \cdot E_{w,S}}}{\mathcal{Z}_{S,\mathcal{D}}} = \mathbb{P}(w \mid \mathcal{D}, S).$$

⁷⁴² In other words, our relaxed generator coupled with the rejection step, represents an unbiased ⁷⁴³ algorithm for the Boltzmann distribution of Eq. (1) over $W_{S,\mathcal{D}}$.

Meanwhile, the average-case complexity can be impacted by the strategy. Indeed, 744 the relaxed instance (S', \mathcal{D}') can accelerate the preprocessing due to a reduced treewidth 745 $tw' \leq tw$. The rejection step only increases the expected number of generations by a factor 746 $\overline{q} := \mathcal{Z}_{S',\mathcal{D}'}/\mathcal{Z}_{S,\mathcal{D}}$, representing the inflation of the sequence space, induced by the relaxation 747 of the constraints. Overall, the average-case time complexity of the rejection algorithm is in 748 $\Theta(n \cdot |\mathcal{D}'| \cdot 4^{tw'} + k \cdot \overline{q} \cdot (n + |\mathcal{D}'|))$ time and $\Theta(n \cdot 4^{tw'})$ space. This space improvement is notable 749 when tw' < tw, and could be key for the practical applicability of the method, especially 750 given that memory represents the bottleneck of most treewidth-based DP algorithms. 751

⁷⁵² **G** Lower bound for the min. alignment cost from simplified models

Here, we justify the filtering strategy described in Section 5.2.2. Namely, we formally prove that, given a structured RNA S and a targeted genomic region w, a lower bound for the

minimal alignment cost of S and w can be obtained from the minimal alignment cost of some $S' \subseteq S$ and w. If this lower bound for $S' \subseteq S$ is higher than the specified cutoff ε , then there is no need to align w to S the full model, as the resulting cost is guaranteed to stay above the selection cutoff ε .

Let S be an arc-annotated sequence of length m (S_i denotes the *i*th character of S), w be a target (flat) sequence of length m, and $\mu : [1, n] \to [1, m] \cup \{\bot\}$ represents an alignment². We consider the following cost function, adapted from [25], which quantifies the quality of an alignment μ for S and w:

$$C(S, w, \mu) = \sum_{\substack{i \text{ unpaired in } S, \\ k:=\mu_i}} \gamma(S_i, w_k) + \sum_{\substack{(i,j) \in S, \\ (k,l):=(\mu_i,\mu_j)}} \phi(S_i, S_j, w_k, w_l) + \sum_{\substack{i \in gaps(S)}} \lambda_q(g) + \sum_{g \in gaps(w)} \lambda_T(g)$$

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 $\gamma_{67} = \gamma(a, b)$ returns the *substitution cost* which penalizes (mismatches) or rewards (matches) the substitution of a into b (set to 0 and handled in gaps if $b = \perp$);

 $\phi(a, b, c, d)$ return a base pair substitution cost, penalizing (arc breaking) or rewarding (conservation or compensatory mutations) the transformation of nucleotides (a, b) into nucleotides/gaps (c, d) (set to 0 and handled in gaps if $(c, d) = (\bot, \bot)$);

 $\pi_2 = \lambda_S$ and λ_T penalize gaps introduced by μ respectively in S and w (affine cost model).

Given this definition, consider a simplified model $S' \subset S$, associated with a minimal cost

$$c' := \min_{\mu} C(S, w, \mu)$$

and denote by c^* the minimal cost of the full model S, we have the following inequality.

Proposition 12.

$$r_{4} \qquad c' - \sum_{\substack{i \text{ unpaired in } S, \\ paired in } S}} \max_{b} \gamma(S_{i}, b) + \sum_{(i,j) \in S \setminus S'} \min_{a, b} \phi(S_{i}, S_{j}, a, b) \le c^{\star}$$
(2)

Proof. For any alignment, we have, per the definition of $C(S, w, \mu)$:

$$C(S, w, \mu) = C(S', w, \mu) - \sum_{\substack{i \text{ unpaired in } S, \\ \text{paired in } S, \\ \text{and } k:=\mu_i}} \gamma(S_i, w_k) + \sum_{\substack{(i,j) \in S \setminus S' \\ \text{s.t. } (k,l):=(\mu_i, \mu_j)}} \phi(S_i, S_j, w_k, w_l).$$

⁷⁷⁸ Minimizing over all alignment μ , one obtains

$$\min_{\mu} C(S, w, \mu) = \min_{\mu} C(S', w, \mu) - \sum_{\substack{i \text{ unpaired in } S, \\ \text{paired in } S, \\ \text{and } k:=\mu_i}} \gamma(S_i, w_k) + \sum_{\substack{(i,j)\in S\setminus S' \\ \text{s.t. } (k,l):=(\mu_i,\mu_j)}} \phi(S_i, S_j, w_k, w_l).$$

² An alignment μ is subject to further constraints, notably including some restricted form of monotonicity, when represented as a function. However, those constraints are reasonably intuitive and we omit them is this discussion for the sake of simplicity.

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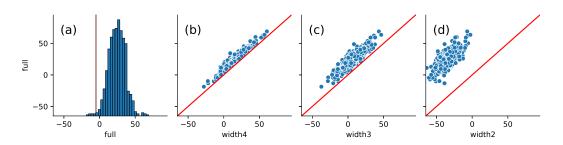


Figure 11 (a) Histogram of alignment scores obtained by aligning the full structure (tw = 5) model of the Twister ribozyme (pdb-id: 4OJI) with $\kappa \cdot n$ -sized windows in a 10kb region of the 5th chromosome of *S. bicolor*. A vertical line is positioned at the ϵ threshold. (b;c;d) Corrected alignment scores obtained for reduced-treewidth models for each window, plotted against the corresponding score of the full model. The corrected alignment score indeed acts as a lower bound to the full-model score (points above the y = x red line), allowing a iterative filtering strategy.

⁷⁸¹ Independently minimizing each term of the right-hand-side, we obtain a first lower bound

$$\sum_{\substack{\mu \in S \\ \text{res}}} c^{\star} \geq c' - \max_{\substack{\mu \\ \text{paired in } S, \\ \text{and } k := \mu_i}} \sum_{\substack{\gamma(S_i, w_k) + \min_{\mu} \\ \text{s.t. } (k,l) := (\mu_i, \mu_j)}} \sum_{\substack{(i,j) \in S \setminus S' \\ \text{s.t. } (k,l) := (\mu_i, \mu_j)}} \phi(S_i, S_j, w_k, w_l).$$

⁷⁸⁴ further coarsened by an independent optimization of the elements in the sums

$$c^{\star} \ge c' - \sum_{\substack{i \text{ unpaired in } S,' \\ \text{paired in } S}} \max_{\mu} \gamma(S_i, w_k) + \sum_{\substack{(i,j) \in S \setminus S' \\ \mu}} \min_{\mu} \phi(S_i, S_j, w_k, w_l)$$

$$= c' - \sum_{\substack{i \text{ unpaired in } S, \\ \text{paired in } S}} \max_{a} \gamma(S_i, a) + \sum_{\substack{(i,j) \in S \setminus S' \\ a,b}} \min_{a,b} \phi(S_i, S_j, a, b).$$

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where the last line is obtained by considering the worst-case contributors to nucleotides and base pairs substitutions. Importantly, the right-hand side no longer depends on μ any more, and can be used to easily computed a corrected score/lower bound.

The corrected expression, shown in the left hand side of Equation (2) allows, when lower than a cutoff ε , to safely discard w as a potential hit for the full model S. This corrected score score is plotted in Figure 9A, allowing for a gradual reduction of the search space for ε -admissible hits. We show in Figure 11 the corrected scores obtained for simplified structures S' of various treewidths, plotted against the scores of the full target structure.