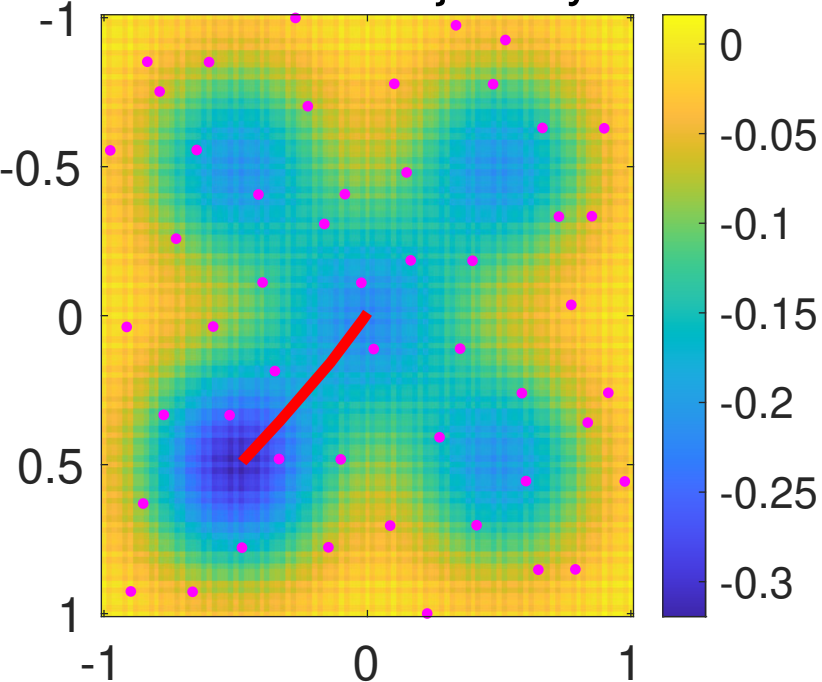
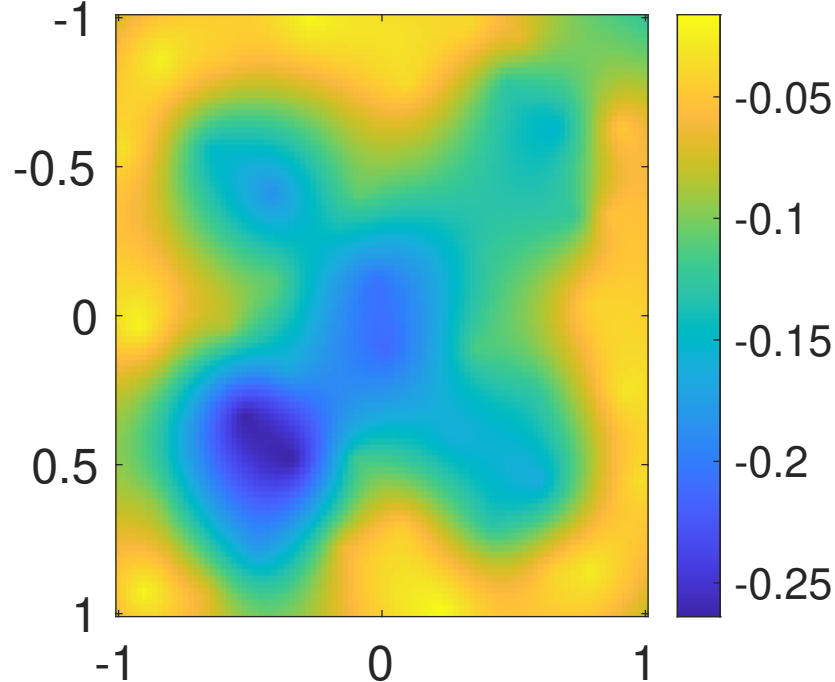


function + trajectory



model



randomized gradient descent

