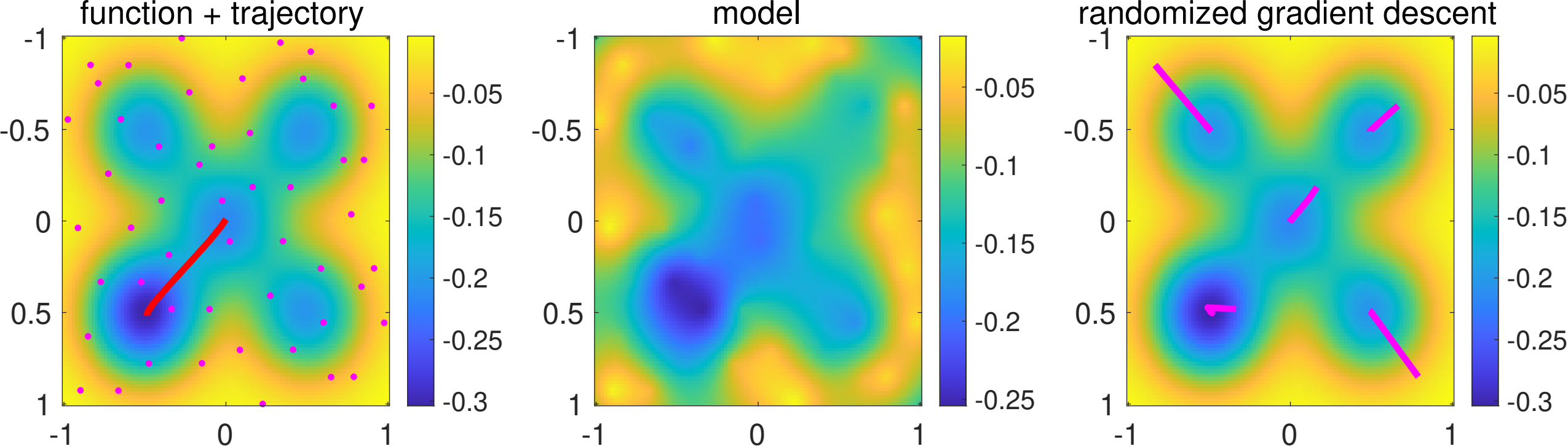
function + trajectory
model
randomized gradient descent
-1
-0.5
0
0.5
1
-1
0
1
-0.05
-0.1
-0.15
-0.2
-0.25
-0.3