

From triangles to curves Monique Teillaud

▶ To cite this version:

Monique Teillaud. From triangles to curves. EuroCG 2006 - 22nd European Workshop on Computational Geometry, Mar 2006, Delphi, Greece. hal-02934805

HAL Id: hal-02934805 https://inria.hal.science/hal-02934805v1

Submitted on 9 Sep 2020

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

From triangles to curves

Monique Teillaud



22nd European Workshop on Computational Geometry March 2006 - $\Delta \varepsilon \lambda \varphi o i$

(日)
 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)
 (日)

 (日)
 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)
 </p

Warning

- focus on practical methods
- non exhaustive, biased

mostly (not only)





▲□▶ ▲□▶ ▲目▶ ▲目▶ 三目 のへで

Warning

- focus on practical methods
- non exhaustive, biased

mostly (not only)





◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

"Commercial": ECG book coming out soon...

Warning

- focus on practical methods
- non exhaustive, biased

mostly (not only)





◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

Advice to people having some knowledge of Computer Algebra: you may leave the room

non technical, superficial...

Circles are never far from triangles



Construction of curves from lines

Parabola: smooth connection between line segments

Du point Q on peut mener deux tangentes. II. - Tracer, parallèlement à une droite donnée RR', une tangente à la parabole (fig. 107). Abaisser du foyer F une perpendiculaire FM sur RR', puis élever une perpendiculaire QS au milieu de MF. S 93. Raccord obtenu par un are de parabole. --- Décrire une parabole, et mener deux tangentes OC et QC' (fig. 408); tracer la corde des contacts CC', soit ED une tangente quelconque. Porter CD en OD .. et joindre D, E : constater que D.E est Fig. 108. parallèle à CC'. De cette constatation nous tirons la conclusion suivante :

$$\frac{\mathrm{QD}_1}{\mathrm{QC}} = \frac{\mathrm{QE}}{\mathrm{QC}'},$$

que nous pouvons énoncer ainsi :

Les points d'intersection D et E partagent les tangentes QC et QC en segments proportionnels inversement placés par rapport au point Q.

Proposons-nous de raccorder par un arc de parabole les deux directrices concourantes QC et QC' (\hat{fg} , 109) :

Partager les distances QC et QC' en un même nombre de parties égales, cinq par exemple, et numéroter les points de division de

Construction of curves from lines

Parabola: smooth connection between line segments

248

CHAPITRE 11.

l'une à partir du sommet, et de l'autre à partir du raccord ; joindre les points portant le même numéro.

Toutes les droites ainsi tracées seront tangentes à l'arc de parabole, et chaque contact se trouvera au milieu de la portion de



tangente comprise entre les tangentes voisines. On aura ainsi autant de points de la courbe qu'on voudra, et de plus, en chacun de ces points une tangente qui servira de limite, il sera donc très facile de tracer la courbe.

APPLICATIONS. — Ce raccord présente l'avantage de ne pas offrir de brusque changement de direction, la courbure variant graduel-

lement du sommet aux points de raccordement.

Les cintres constituent de véritables raccordements opérés entre deux pieds-droits, au moyen d'une courbe. Quand les pieds-droits ont même hauteur, on emploie un demi-cercle, ou une moitié d'ellipse donnée par le grand axe si le cintre est surhaussé, et par le petit, s'il est surbaissé. Quand les pieds-droits sont inégaux et parallèles, on se sert pour l'arc rampant d'une demi-ellipse donnée par deux diamètres conjugués, mais si les pieds-droits ne sont ni égaux ni parallèles, le raccordement se fait suivant un arc de parahole tracé comme il vient d'être indiqué ci-dessus.

Construction of curves from lines



⇒ ↓ ≡ ↓ ≡ √QQ

Triangles and curves



[Florence, 1997] Triangular period

ъ

A B > A B >

Curves already appear for linear input



Bisecting curve

2D line segments arcs of parabolas

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

Curves already appear for linear input



Voronoi diagram

2D line segments arcs of parabolas

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

© Karavelas - CGAL

Curves already appear for linear input



Voronoi diagram

3D line segments patches of quadric surfaces

◆□▶ ◆□▶ ◆□▶ ◆□▶ ▲□ ◆ ○ ◆ ○ ◆

More generally:

manipulations of algebraic curves and surfaces

More generally:

manipulations of algebraic curves and surfaces

Only considered here Exact Geometric Computation

[Yap][...]

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

Why we should not be afraid of Computer Algebra

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

- useful
- interesting
- not so hard to understand

Why we should not be afraid of Computer Algebra

▲□▶▲□▶▲□▶▲□▶ □ のQ@

- useful
- interesting
- not so hard to understand
- people are nice

Why we should not be afraid of Computer Algebra trying to convice myself...

◆□▶ ◆□▶ ◆□▶ ◆□▶ ▲□ ◆ ○ ◆ ○ ◆

- useful
- interesting
- not so hard to understand (?)
- some people are nice

One tool: Resultant

Resultant of a system of polynomial equations

= necessary and sufficient condition such that it has a root.



One tool: Resultant

Resultant of a system of polynomial equations

= necessary and sufficient condition such that it has a root.

How to compute the resultant?

hard problem

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Sylvester resultant

Univariate case

$$\begin{cases} P = a_0 x^m + \dots + a_m \\ Q = b_0 x^n + \dots + b_n \end{cases}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

 $a_0 \neq 0, b_0 \neq 0, m > n$, coefficients in a field K (algebraically closed).

Sylvester resultant

$$\begin{cases} P = a_0 x^m + \dots + a_m \\ Q = b_0 x^n + \dots + b_n \end{cases}$$

Sylvester resultant =



◆ロ▶ ◆母▶ ◆臣▶ ◆臣▶ 「臣」 の々で

Sylvester resultant

$$\begin{cases} P = a_0 x^m + \dots + a_m \\ Q = b_0 x^n + \dots + b_n \end{cases}$$

Sylvester resultant =

= 0 iff *P* and *Q* have a common root in K.



$$\begin{cases} ax + by - c = 0 \\ dx + ey - f = 0 \end{cases}$$

seen as: x unknown, y parameter



$$\begin{cases} ax + by - c = 0 \\ dx + ey - f = 0 \end{cases}$$

seen as: x unknown, y parameter

Sylvester Resultant =
$$\begin{vmatrix} a & d \\ by - c & ey - f \end{vmatrix}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

$$\begin{cases} ax + by - c = 0 \\ dx + ey - f = 0 \end{cases}$$

seen as: x unknown, y parameter

Sylvester Resultant =
$$\begin{vmatrix} a & d \\ by - c & ey - f \end{vmatrix}$$

= $a(ey - f) - d(by - c)$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

Boils down to eliminate x

p, q, s three points in the plane, t a fourth point.



◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○



 C_{pqs} center (x_c, y_c) radius r

$$(x - x_c)^2 + (y - y_c)^2 = r^2$$

$$iff \begin{cases} 2x_px_c + 2y_py_c + (r^2 - x_c^2 - y_c^2) - (x_p^2 + y_p^2) &= 0\\ 2x_qx_c + 2y_qy_c + (r^2 - x_c^2 - y_c^2) - (x_q^2 + y_q^2) &= 0\\ 2x_sx_c + 2y_sy_c + (r^2 - x_c^2 - y_c^2) - (x_s^2 + y_s^2) &= 0\\ 2x_tx_c + 2y_ty_c + (r^2 - x_c^2 - y_c^2) - (x_t^2 + y_t^2) &= 0 \end{cases}$$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ▶

$$iff \begin{cases} 2x_{p}X + 2y_{p}Y + R - (x_{p}^{2} + y_{p}^{2})Z = 0\\ 2x_{q}X + 2y_{q}Y + R - (x_{q}^{2} + y_{q}^{2})Z = 0\\ 2x_{s}X + 2y_{s}Y + R - (x_{s}^{2} + y_{s}^{2})Z = 0\\ 2x_{t}X + 2y_{t}Y + R - (x_{t}^{2} + y_{t}^{2})Z = 0 \end{cases}$$

has a non-trivial solution (X, Y, R, Z) and

$$\begin{array}{rcl} X/Z &=& x_c \\ Y/Z &=& y_c \\ R/Z &=& r^2 - x_c^2 - y_c^2. \end{array}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

$$q \bigoplus_{q} \bigoplus_{s}^{p} \inf_{s} \inf_{s} \inf_{s} \left\{ \begin{array}{l} 2x_{p}x_{c} + 2y_{p}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{p}^{2} + y_{p}^{2}) = 0\\ 2x_{q}x_{c} + 2y_{q}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{q}^{2} + y_{q}^{2}) = 0\\ 2x_{s}x_{c} + 2y_{s}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{s}^{2} + y_{s}^{2}) = 0\\ 2x_{t}x_{c} + 2y_{t}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{t}^{2} + y_{t}^{2}) = 0 \end{array} \right.$$

$$iff \begin{vmatrix} x_p & y_p & 1 & x_p^2 + y_p^2 \\ x_q & y_q & 1 & x_q^2 + y_q^2 \\ x_s & y_s & 1 & x_s^2 + y_s^2 \\ x_t & y_t & 1 & x_t^2 + y_t^2 \end{vmatrix} = 0$$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ○ □ ○ ○ ○ ○

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

= resultant of the system Allows to eliminate x_c, y_c, r^2



Resultant often used in simple cases without noticing



Resultant

Resultant often used in simple cases without noticing

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

Linear algebra helps solve non-linear problems

Digression on algebraic degree

One measure of efficiency and precision of a predicate: algebraic degree

▲□▶▲圖▶▲≣▶▲≣▶ 差 のへで

If predicate = sign of a resultant

Resultant has minimal degree \implies optimal predicate?

If predicate = sign of a resultant

Resultant has minimal degree \implies optimal predicate?

No:

methods often return a multiple of the resultant
 → resultant hard to compute

(日)
 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)
 (日)

 (日)
 (日)

 (日)
 (日)

 (日)

 (日)

 (日)

 (日)
 (日)

 (日)
 (日)

 (日)
 (日)

 (日)
 (日)

 (日)

 (日)
If predicate = sign of a resultant

Resultant has minimal degree \implies optimal predicate?

No:

- methods often return a multiple of the resultant

 — resultant hard to compute
- the resultant may be factored

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

If predicate = sign of a resultant

Resultant has minimal degree \implies optimal predicate?

No:

- methods often return a multiple of the resultant → resultant hard to compute
- the resultant may be factored
- a factor may be $P^2 + Q^2$

 \longrightarrow the degree does not mean so much

Digression on algebraic degree

• filtering techniques used for efficiency

 \longrightarrow maybe not such an interesting measure ?

(日)
 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)
 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

Digression on algebraic degree

- Degree of a predicate
 not trivial
- Degree of an algorithm

 \rightarrow ?

 \longrightarrow depends on the algebraic expressions of predicates

Degree of a geometric problem

$\text{Digression}\mapsto\text{thread}$

◆□▶ ◆□▶ ◆□▶ ◆□▶ ▲□ ◆ ○ ◆ ○ ◆

Another tool: Sturm sequences

- $\mathcal{P} = \mathcal{P}_0, \mathcal{P}_1, \dots, \mathcal{P}_d \in \mathbb{R}[X]$
- $\alpha,\beta\in\mathbb{R}\cup\{-\infty,+\infty\}$

 $Var(\mathcal{P}; \alpha) =$ number of sign variations in the sequence $P_0(\alpha), P_1(\alpha), \dots, P_d(\alpha)$

 $Var(\mathcal{P}; \alpha, \beta) = Var(\mathcal{P}; \alpha) - Var(\mathcal{P}; \beta)$

◆□▶ ◆□▶ ◆□▶ ◆□▶ ▲□ ◆ ○ ◆ ○ ◆

Sturm sequences

 $P, Q \in \mathbb{K}[X]$ signed remainder sequence of P and Q = sequence $S(P, Q) : P_0, P_1, \dots, P_k$

$$P_{0} = P$$

$$P_{1} = Q$$

$$P_{2} = -Rem(P_{0}, P_{1})$$

$$\vdots$$

$$P_{k} = -Rem(P_{k-2}, P_{k-1})$$

$$P_{k+1} = -Rem(P_{k-1}, P_{k}) = 0$$

where

Rem(A, B) = remainder of the Euclidean division of A by B

(日)
 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (日)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)
 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

 (1)

Sturm sequences

Sturm sequence of P =sequence S(P, P') of signed reminders of P and P'

> $Var(\mathcal{S}(P, P'); \alpha, \beta)$ is the number of roots of *P* in the interval $[\alpha, \beta]$

> > (日)
> > (日)
> > (日)
> > (日)
> > (日)
> > (日)
> > (日)
> > (日)
> > (日)
> > (日)
> > (日)
> >
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)
> >
> > (1)

Sturm sequences for dummies

◆□▶ ◆□▶ ◆□▶ ◆□▶ ▲□ シのへで

Sturm sequences for dummies by a dummy

$$P = aX^2 + bX + c$$

$$P' = 2aX + b$$
$$P = P' \cdot \left(\frac{X}{2} + \frac{b}{4a}\right) - \left(\frac{b^2}{4a} - c\right)$$

▲□▶▲圖▶▲≣▶▲≣▶ . 差 . 釣�?

Sturm sequences for dummies by a dummy

$$P = aX^2 + bX + c$$



▲□▶▲□▶▲□▶▲□▶ □ のへで

Sturm sequences

Sequence S(P, P'Q) of signed reminders of *P* and *P'Q* counts the number of roots of *P* at which *Q* is positive



◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

Sturm sequences allow to compare roots of P and Q

Comparing intersection points



◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

signs of polynomial expressions

Comparing intersection points





◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

signs of polynomial expressions

comparison of algebraic numbers

Comparing intersection points



signs of polynomial expressions

 \neq \uparrow

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

comparison of algebraic numbers

Sturm sequences → signs of polynomial expressions

Practical efficiency

Arithmetic filters for sign computations:



Exact geometric computation \neq Exact arithmetics

Practical efficiency

Comparison of algebraic numbers of degree 2:



▲□▶▲□▶▲□▶▲□▶ □ のQ@

polynomial expressions pre-computed static Sturm sequences

Algebra is not just "computations" it has a meaning...!



Algebra is not just "computations" it has a meaning...!



Geometric interpretation in more complicated cases...?

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Algebra is not just "computations" it has a meaning...!



Geometric interpretation in more complicated cases...?

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ●

• Optimal degree ...?



Open Source Project www.cgal.org





Open Source Project www.cgal.org

Release 3.2 soon





Open Source Project www.cgal.org

Release 3.2 soon

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Exclusive news: Out before Microsoft new OS!



Open Source Project www.cgal.org

Release 3.2 soon

▲□▶▲□▶▲□▶▲□▶ □ のQ@

 new: 2D Circular Kernel manipulations of circular arcs



Open Source Project www.cgal.org

Release 3.2 soon

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

- new: 2D Circular Kernel manipulations of circular arcs
- Arrangement package redesigned
- . . .



VLSI - CAD



Intersection of two quadrics Q_S and Q_T

Levin's pencil method

- find a "good" quadric in the pencil Q_{R(λ)=λS-T}
 λ root of degree 3 pol.
- Diagonalize R(λ).
 Eigenvalues = roots of degree 2 pol. ∈ Q(λ).
 Normalize eigenvectors.
- Plug the parameterization of Q_R(λ) in Q_T.
 Degree 2 in one of the parameters. Solve

"good" = simple ruled $\begin{vmatrix} x & x & x \\ x & x & x \\ x & x & x \end{vmatrix}$

principal subdeterminant =0

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ● ● のへで

Intersection of two quadrics Q_S and Q_T

Levin's pencil method

- find a "good" quadric in the pencil Q_{R(λ)=λS-T}
 λ root of degree 3 pol.
- Diagonalize R(λ).
 Eigenvalues = roots of degree 2 pol. ∈ Q(λ).
 Normalize eigenvectors.
- Plug the parameterization of Q_R(λ) in Q_T.
 Degree 2 in one of the parameters. Solve

Improvement

- work in \mathbb{P}^3
- Relax the constraint on $Q_{R(\lambda)}$ Rational, ruled.
- Apply Gauss reduction of the quadratic form: *P^TRP* diagonal. Rational transformation.
- Plug the parameterization in Q_T.
 Degree 2 in one of the parameters. Solve

Intersection of quadrics

Levin's pencil method



New parameterization

- rational when it exists, involves $\sqrt{\text{pol.}}$ otherwise.
- quasi-optimal in $\sqrt{}$.

Implemented



© Dupont et al

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

Arrangement of quadrics

Projection approach



© Wolpert

Planar arrangement of curves of degree 4 a curve can have 6 singular points Sort out (upper, lower) \rightarrow arrangement on each quadric

Surfacic approach



Sweeping plane: Trapezoidal map of evolving conics

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

Volumic approach: vertical decomposition

Events:

- new quadric
- features in the map intersect

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ○ □ ○ ○ ○ ○

Events:

- new quadric
- features in the map intersect

x solution of



◆□▶ ◆□▶ ◆□▶ ◆□▶ ▲□ ◆ ○ ◆ ○ ◆

$$\exists y, z_1, z_2 \text{ s.t. } \begin{cases} Q_i(x, y, z_1) = 0 \\ Q_j(x, y, z_1) = 0 \end{cases} \text{ and } \begin{cases} Q_k(x, y, z_2) = 0 \\ Q_l(x, y, z_2) = 0 \end{cases}$$

x in an extension field of degree 16

Events:

- new quadric
- features in the map intersect

x solution of

$$\exists y, z_1, z_2 \text{ s.t. } \begin{cases} Q_i(x, y, z_1) = 0 \\ Q_j(x, y, z_1) = 0 \end{cases} \text{ and } \begin{cases} Q_k(x, y, z_2) = 0 \\ Q_l(x, y, z_2) = 0 \end{cases}$$

x in an extension field of degree 16

Comparison of events:

difference of events in an extension field of degree 256...

• Optimal degree...?



Apollonius diagram

Additively weighted Voronoi diagram

Weighted points $\sigma_i = (p_i, r_i), p_i \in \mathbb{R}^2, r_i \in \mathbb{R}$

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - \mathbf{r}_i$

(日)

Apollonius diagram Additively weighted Voronoi diagram

Weighted points $\sigma_i = (p_i, r_i), p_i \in \mathbb{R}^2, r_i \in \mathbb{R}$

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$ $C_i \subset \mathbb{R}^3: \quad \mathbf{x}_3 = \|\mathbf{x} - \mathbf{p}_i\| - r_i$ $\iff \quad (\mathbf{x}_3 + r_i)^2 = (\mathbf{x} - \mathbf{p}_i)^2 \quad \mathbf{x}_3 + r_i > 0 \quad \text{half-cone}$

◆□▶ ◆□▶ ◆□▶ ◆□▶ ▲□ ◆ ○ ◆ ○ ◆

Apollonius diagram Additively weighted Voronoi diagram

Weighted points $\sigma_i = (p_i, r_i), p_i \in \mathbb{R}^2, r_i \in \mathbb{R}$

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$

◆□▶ ◆□▶ ◆□▶ ◆□▶ ▲□ ◆ ○ ◆ ○ ◆

$$egin{array}{lll} C_i \subset \mathbb{R}^3: & x_3 = \|x-p_i\|-r_i \ & \Longleftrightarrow & (x_3+r_i)^2 = (x-p_i)^2 & x_3+r_i > 0 & ext{half-cone} \end{array}$$

Apollonius diagram =

lower envelope of the half-cones.

Bisector of σ_i and $\sigma_j =$

projection of a plane conic section $C_i \cap C_j$.
Apollonius diagram Additively weighted Voronoi diagram

Weighted points $\sigma_i = (p_i, r_i), p_i \in \mathbb{R}^2, r_i \in \mathbb{R}$

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$

(日)

$$egin{array}{lll} C_i \subset \mathbb{R}^3: & x_3 = \|x-p_i\|-r_i \ \Leftrightarrow & (x_3+r_i)^2 = (x-p_i)^2 & x_3+r_i > 0 & ext{half-cone} \end{array}$$

Apollonius diagram =

lower envelope of the half-cones.

Bisector of σ_i and $\sigma_j =$

projection of a plane conic section $C_i \cap C_j$.

 Σ_i sphere $\subset \mathbb{R}^3$, center (p_i, r_i) radius $\sqrt{2}r_i$

Apollonius diagram Additively weighted Voronoi diagram

Weighted points $\sigma_i = (p_i, r_i), \ p_i \in \mathbb{R}^2, r_i \in \mathbb{R}$

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$

$$egin{array}{lll} C_i \subset \mathbb{R}^3: & x_3 = \|x-p_i\|-r_i \ & \Longleftrightarrow & (x_3+r_i)^2 = (x-p_i)^2 & x_3+r_i > 0 & ext{half-cone} \end{array}$$

Apollonius diagram =

lower envelope of the half-cones.

Bisector of σ_i and $\sigma_j =$

projection of a plane conic section $C_i \cap C_j$.

 $\begin{array}{l} \Sigma_i \text{ sphere } \subset \mathbb{R}^3, \text{ center } (p_i, r_i) \text{ radius } \sqrt{2}r_i \\ X_i \text{ projection of } x \text{ onto } C_i \\ x \in \mathcal{A}(\sigma_i) \quad \textit{iff} \quad \|x - p_i\| - r_i < \|x - p_j\| - r_j \quad (\forall j) \\ \quad \textit{iff} \quad pow(X_i, \Sigma_i) < pow(X_i, \Sigma_j) \end{array}$

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

Apollonius diagram Additively weighted Voronoi diagram

Weighted points $\sigma_i = (p_i, r_i), p_i \in \mathbb{R}^2, r_i \in \mathbb{R}$

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ◆ ○○

$$egin{array}{lll} C_i \subset \mathbb{R}^3: & x_3 = \|x-p_i\|-r_i \ & \Longleftrightarrow & (x_3+r_i)^2 = (x-p_i)^2 & x_3+r_i > 0 & ext{half-cone} \end{array}$$

Apollonius diagram =

lower envelope of the half-cones.

Bisector of σ_i and $\sigma_j =$

projection of a plane conic section $C_i \cap C_j$.

 Σ_i sphere $\subset \mathbb{R}^3$, center (p_i, r_i) radius $\sqrt{2}r_i$ $A(\sigma_i)$ = projection of the intersection of the half-cone C_i with the power region of Σ_i

Same in \mathbb{R}^d





© Karavelas

Tricky predicates Degree 16

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ○ □ ○ ○ ○ ○





Tricky predicates Degree 16

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)
(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)
(日)

(日)

(日)

(日)

(日)

(日)

(日)

(日)
</p

© Karavelas

- Implementation degree 20: degree 16 requires ~ 100 times as many arithmetic operations...
- Optimal degree...?



• theoretical: questions on degree...





- theoretical: questions on degree...
- Robust (Exact?) computation on higher degree curves and surfaces

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ○ □ ○ ○ ○ ○

Challenges

- theoretical: questions on degree...
- Robust (Exact?) computation on higher degree curves and surfaces
- Improvement of practical efficiency for low degree curves CAD-VLSI (circular arcs):

 \sim 10 times slower than industrial non-robust code good start!

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

Challenges

 Applications to Structural biology Manipulations of a large number of spheres (low degree surfaces...)



C Halperin et al.

(日) (日) (日) (日) (日) (日) (日)

ευχαριστώ

Material taken from:

• Greece

National University of Athens University of Crete

Germany

Max-Planck Institut für Informatik Universität des Saarlandes

◆□▶ ◆□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

Israel

Tel-Aviv University

- France
 - Loria INRIA Sophia Antipolis

$\varepsilon \upsilon \chi \alpha \rho \iota \sigma \tau \dot{\omega}$

