

# **From triangles to curves** Monique Teillaud

## **To cite this version:**

Monique Teillaud. From triangles to curves. EuroCG 2006 - 22nd European Workshop on Computational Geometry, Mar 2006, Delphi, Greece. hal-02934805

# **HAL Id: hal-02934805 <https://inria.hal.science/hal-02934805v1>**

Submitted on 9 Sep 2020

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# From triangles to curves

Monique Teillaud



22nd European Workshop on Computational Geometry March 2006 -  $\Delta \varepsilon \lambda \varphi$ οί

**KORKARYKERKE PORCH** 

# Warning

- **o** focus on practical methods
- o non exhaustive, biased

mostly (not only)





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# Warning

- **o** focus on practical methods
- o non exhaustive, biased

mostly (not only)





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"Commercial": ECG book coming out soon...

# **Warning**

- focus on practical methods
- o non exhaustive, biased

mostly (not only)





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Advice to people having some knowledge of Computer Algebra: you may leave the room

• non technical, superficial...

#### Circles are never far from triangles



#### Construction of curves from lines

#### Parabola: smooth connection between line segments

Du point Q on peut mener ucux tangemes.  $H. - Trace$ , parallèlement à une droite donnée RR', une tangente à la parabole (fig. 107). Abaisser du foyer F une perpendiculaire FM sur RR', puis élever une perpendiculaire OS au milieu de MF. S 93. Raccord obtenu par un are de parabole. -Décrire une parahole, et mener deux tangentes OC et QC (fig. 108); tracer la corde des contacts CC'. soit ED une tangente quelconque. Porter CD en OD., et joindre D.E: constater que D.E est Fig. 108. parallèle à CC'. De cette constatation nous tirons la conclusion suivante :  $\frac{QD_1}{OC} = \frac{QE}{OC'}$ 

que nous pouvons énoncer ainsi :

Les points d'intersection D et E partagent les tangentes QC et OC en segments proportionnels inversement placés par rapport au point Q.

Proposons-nous de raccorder par un arc de parabole les deux directrices concourantes QC et QC' ( $\beta g$ . 109):

Partager les distances QC et QC' en un même nombre de parties égales, cinq par exemple, et numéroter les points de division de

**CONTRACT A BIKE BIKAO** 

#### Construction of curves from lines

#### Parabola: smooth connection between line segments

#### $0.19$

#### CHAPITRE 11.

l'une à partir du sommet, et de l'autre à partir du raccord; joindre les points portant le même numéro.

Toutes les droites ainsi tracées seront tangentes à l'arc de parabole, et chaque contact se trouvera au milieu de la portion de



tangente comprise entre les tangentes voisines. On aura ainsi autant de points de la courbe qu'on voudra, et de plus, en chacun de ces points une tangente qui servira de limite, il sera donc très facile de tracer la courbe.

APPLICATIONS. - Ce raccord présente l'avantage de ne pas offrir de brusque changement de direction, la courbure variant graduel-

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lement du sommet aux points de raccordement.

Les cintres constituent de véritables raccordements opérés entre deux pieds-droits, au moyen d'une courbe. Quand les pieds-droits ont même hauteur, on emploie un demi-cercle, ou une moitié d'ellipse donnée par le grand axe si le cintre est surhaussé, et par le petit, s'il est surbaissé. Quand les pieds-droits sont inégaux et parallèles, on se sert pour l'arc rampant d'une demi-ellipse donnée par deux diamètres conjugués, mais si les pieds-droits ne sont ni égaux ni parallèles, le raccordement se fait suivant un arc de parabole tracé comme il vient d'être indiqué ci-dessus.

## Construction of curves from lines



## Triangles and curves



#### [Florence, 1997] Triangular period

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 $\Rightarrow$ 

B

 $2Q$ 

## Curves already appear for linear input



Bisecting curve

2D line segments arcs of parabolas

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## Curves already appear for linear input



Voronoi diagram

2D line segments arcs of parabolas

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c Karavelas - CGAL

## Curves already appear for linear input



Voronoi diagram

3D line segments patches of quadric surfaces

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More generally:

manipulations of algebraic curves and surfaces

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More generally:

manipulations of algebraic curves and surfaces

Only considered here Exact Geometric Computation [Yap][...]

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# Why we should not be afraid of Computer Algebra

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- **o** useful
- **•** interesting
- not so hard to understand

# Why we should not be afraid of Computer Algebra

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- useful
- interesting
- **o** not so hard to understand
- **o** people are nice

#### Why we should not be afraid of Computer Algebra trying to convice myself...

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- useful
- interesting
- not so hard to understand (?)
- o some people are nice

#### One tool: Resultant

#### Resultant of a system of polynomial equations

= necessary and sufficient condition such that it has a root.



#### One tool: Resultant

#### Resultant of a system of polynomial equations

#### = necessary and sufficient condition such that it has a root.

How to compute the resultant? hard problem

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#### Sylvester resultant

#### Univariate case

$$
\left\{\n \begin{array}{rcl}\n P & = & a_0 x^m + \dots + a_m \\
 Q & = & b_0 x^n + \dots + b_n\n \end{array}\n\right.
$$

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 $a_0 \neq 0, b_0 \neq 0, m > n$ coefficients in a field  $K$  (algebraically closed).

# Sylvester resultant

$$
\left\{\n \begin{array}{ccc}\n P & = & a_0 x^m + \cdots + a_m \\
 Q & = & b_0 x^n + \cdots + b_n\n \end{array}\n\right.
$$



# Sylvester resultant

$$
\left\{\n \begin{array}{ccc}\n P & = & a_0 x^m + \dots + a_m \\
 Q & = & b_0 x^n + \dots + b_n\n \end{array}\n\right.
$$

Sylvester resultant =

 $= 0$  iff P and Q have a common root in K



$$
\begin{cases}\nax + by - c &= 0 \\
dx + ey - f &= 0\n\end{cases}
$$

seen as: x unknown, y parameter



$$
\begin{cases}\nax + by - c &= 0 \\
dx + ey - f &= 0\n\end{cases}
$$

seen as: x unknown, y parameter

$$
Sylvester Resultant = \begin{vmatrix} a & d \\ by -c & ey - f \end{vmatrix}
$$

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$$
\begin{cases}\nax + by - c &= 0 \\
dx + ey - f &= 0\n\end{cases}
$$

seen as: x unknown, y parameter

Sylvester Resultant 
$$
=\begin{vmatrix} a & d \\ by -c & ey - f \end{vmatrix}
$$
  
 $= a(ey - f) - d(by - c)$ 

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Boils down to eliminate x

 $p, q, s$  three points in the plane,  $t$  a fourth point.



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 $C_{pqs}$  center  $(x_c, y_c)$  radius r

$$
(x-x_c)^2 + (y-y_c)^2 = r^2
$$

$$
iff \begin{cases} 2x_p x_c + 2y_p y_c + (r^2 - x_c^2 - y_c^2) - (x_p^2 + y_p^2) = 0 \\ 2x_q x_c + 2y_q y_c + (r^2 - x_c^2 - y_c^2) - (x_q^2 + y_q^2) = 0 \\ 2x_s x_c + 2y_s y_c + (r^2 - x_c^2 - y_c^2) - (x_s^2 + y_s^2) = 0 \\ 2x_t x_c + 2y_t y_c + (r^2 - x_c^2 - y_c^2) - (x_t^2 + y_t^2) = 0 \end{cases}
$$

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$$
t \text{ on } C_{pqs}
$$
\n
$$
2x_qX + 2y_qY + R - (x_q^2 + y_q^2)Z = 0
$$
\n
$$
2x_sX + 2y_sY + R - (x_s^2 + y_s^2)Z = 0
$$
\n
$$
2x_tX + 2y_tY + R - (x_t^2 + y_t^2)Z = 0
$$

has a non-trivial solution  $(X, Y, R, Z)$  and

$$
X/Z = x_c
$$
  
\n
$$
Y/Z = y_c
$$
  
\n
$$
R/Z = r^2 - x_c^2 - y_c^2.
$$

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$$
q \left( \begin{array}{c} \sum_{g}^{p} t^{\gamma} \\ \sum_{g}^{p} \end{array} \right) = \begin{array}{c} 2x_{p}x_{c} + 2y_{p}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{p}^{2} + y_{p}^{2}) = 0 \\ 2x_{q}x_{c} + 2y_{q}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{q}^{2} + y_{q}^{2}) = 0 \\ 2x_{s}x_{c} + 2y_{s}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{s}^{2} + y_{s}^{2}) = 0 \\ 2x_{t}x_{c} + 2y_{t}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{t}^{2} + y_{t}^{2}) = 0 \end{array}
$$

$$
iff \begin{vmatrix} x_p & y_p & 1 & x_p^2 + y_p^2 \\ x_q & y_q & 1 & x_q^2 + y_q^2 \\ x_s & y_s & 1 & x_s^2 + y_s^2 \\ x_t & y_t & 1 & x_t^2 + y_t^2 \end{vmatrix} = 0
$$

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$$
\int_{q}^{p} \mathbf{f}^{2} \mathbf{f}^{2} \quad \text{iff} \quad\n\begin{cases}\n2x_{p}x_{c} + 2y_{p}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{p}^{2} + y_{p}^{2}) &= 0 \\
2x_{q}x_{c} + 2y_{q}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{q}^{2} + y_{q}^{2}) &= 0 \\
2x_{s}x_{c} + 2y_{s}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{s}^{2} + y_{s}^{2}) &= 0 \\
2x_{t}x_{c} + 2y_{t}y_{c} + (r^{2} - x_{c}^{2} - y_{c}^{2}) - (x_{t}^{2} + y_{t}^{2}) &= 0\n\end{cases}
$$
\n
$$
\int_{\text{iff}} \begin{vmatrix}\nx_{p} & y_{p} &= 1 & x_{p}^{2} + y_{p}^{2} \\
x_{q} & y_{q} &= 1 & x_{q}^{2} + y_{q}^{2} \\
x_{s} & y_{s} &= 1 & x_{s}^{2} + y_{s}^{2} \\
x_{t} & y_{t} &= 1 & x_{t}^{2} + y_{t}^{2}\n\end{vmatrix} = 0
$$

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= resultant of the system Allows to eliminate  $x_c, y_c, r^2$ 



#### • Resultant often used in simple cases without noticing



#### **Resultant**

• Resultant often used in simple cases without noticing

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Linear algebra helps solve non-linear problems

Digression on algebraic degree

#### One measure of efficiency and precision of a predicate: algebraic degree



If predicate  $=$  sign of a resultant

Resultant has minimal degree  $\Longrightarrow$  optimal predicate?

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If predicate  $=$  sign of a resultant

Resultant has minimal degree  $\implies$  optimal predicate?

No:

methods often return a multiple of the resultant −→ resultant hard to compute
If predicate  $=$  sign of a resultant

Resultant has minimal degree  $\Longrightarrow$  optimal predicate?

No:

- methods often return a multiple of the resultant −→ resultant hard to compute
- the resultant may be factored
	- −→ predicate can have a lower degree

If predicate  $=$  sign of a resultant

Resultant has minimal degree  $\Longrightarrow$  optimal predicate?

No:

- methods often return a multiple of the resultant −→ resultant hard to compute
- the resultant may be factored
	- −→ predicate can have a lower degree
- a factor may be  $P^2 + \mathsf{Q}^2$

 $\longrightarrow$  the degree does not mean so much

# Digression on algebraic degree

## **•** filtering techniques used for efficiency

→ maybe not such an interesting measure?

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# Digression on algebraic degree

- Degree of a predicate → not trivial
- Degree of an algorithm

 $\longrightarrow$  ?

 $\longrightarrow$  depends on the algebraic expressions of predicates

• Degree of a geometric problem

#### Digression  $\mapsto$  thread

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## Another tool: Sturm sequences

$$
\mathcal{P} = P_0, P_1, \ldots, P_d \in \mathbb{R}[X]
$$

 $\alpha, \beta \in \mathbb{R} \cup \{-\infty, +\infty\}$ 

 $Var(\mathcal{P}; \alpha)$  = number of sign variations in the sequence  $P_0(\alpha)$ ,  $P_1(\alpha)$ , ...,  $P_d(\alpha)$ 

 $Var(\mathcal{P}; \alpha, \beta) = Var(\mathcal{P}; \alpha) - Var(\mathcal{P}; \beta)$ 

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## Sturm sequences

 $P, Q \in \mathbb{K}[X]$  signed remainder sequence of P and Q = sequence  $S(P, Q): P_0, P_1, \ldots, P_k$ 

$$
P_0 = P
$$
  
\n
$$
P_1 = Q
$$
  
\n
$$
P_2 = -Rem(P_0, P_1)
$$
  
\n
$$
\vdots
$$
  
\n
$$
P_k = -Rem(P_{k-2}, P_{k-1})
$$
  
\n
$$
P_{k+1} = -Rem(P_{k-1}, P_k) = 0
$$

#### where

 $Rem(A, B)$  = remainder of the Euclidean division of A by B

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## Sturm sequences

Sturm sequence of  $P =$ sequence  $\mathcal{S}(P,P')$  of signed reminders of P and P'

## $Var(S(P, P'); \alpha, \beta)$ is the number of roots of P in the interval  $[\alpha, \beta]$

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# Sturm sequences for dummies

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## Sturm sequences for dummies by a dummy

$$
P=aX^2+bX+c
$$

$$
P' = 2aX + b
$$
  
 
$$
P = P'.(\frac{X}{2} + \frac{b}{4a}) - (\frac{b^2}{4a} - c)
$$

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## Sturm sequences for dummies by a dummy

$$
P=aX^2+bX+c
$$



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# Sturm sequences

Sequence  $\mathcal{S}(P,P'\mathsf{Q})$  of signed reminders of P and P'Q counts the number of roots of  $P$  at which  $Q$  is positive



Sturm sequences allow to compare roots of P and Q

# Comparing intersection points



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signs of polynomial expressions

# Comparing intersection points



signs of polynomial expressions

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comparison of algebraic numbers

# Comparing intersection points



signs of polynomial expressions



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comparison of algebraic numbers

Sturm sequences  $→$ signs of polynomial expressions

# Practical efficiency

Arithmetic filters for sign computations:



#### Exact geometric computation  $\neq$  Exact arithmetics

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# Practical efficiency

Comparison of algebraic numbers of degree 2:



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polynomial expressions pre-computed static Sturm sequences

# Algebra is not just "computations"

it has a meaning...!



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# Algebra is not just "computations"

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**• Geometric interpretation in more complicated cases...?** 

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# Algebra is not just "computations"

it has a meaning...!



**• Geometric interpretation in more complicated cases...?** 

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• Optimal degree...?



Open Source Project www.cgal.org





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Release 3.2 soon

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Open Source Project www.cgal.org

Release 3.2 soon

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#### Exclusive news: Out before Microsoft new OS!



Open Source Project www.cgal.org

Release 3.2 soon

**KOD KAD KED KED E YOUR** 

new: 2D Circular Kernel manipulations of circular arcs



Open Source Project www.cgal.org

Release 3.2 soon

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- new: 2D Circular Kernel manipulations of circular arcs
- Arrangement package redesigned
- $\bullet$  . . .



# VLSI - CAD



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# Intersection of two quadrics  $Q_S$  and  $Q_T$

Levin's pencil method

- **•** find a "good" quadric in the pencil  $Q_{R(\lambda)=\lambda S-T}$  $\lambda$  root of degree 3 pol.
- $\bullet$  Diagonalize  $R(\lambda)$ . Eigenvalues = roots of degree 2 pol.  $\in \mathbb{Q}(\lambda)$ . Normalize eigenvectors.
- Plug the parameterization of  $Q_R(\lambda)$  in  $Q_T$ . Degree 2 in one of the parameters. Solve

"good" = simple ruled  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  $\overline{\phantom{a}}$  x x x x x x x x x . . . . . . ·  $\overline{\phantom{a}}$ principal subdeterminant =0

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# Intersection of two quadrics  $Q_S$  and  $Q_T$

Levin's pencil method

- find a "good" quadric in the pencil  $Q_{R(\lambda)=\lambda S-T}$  $\lambda$  root of degree 3 pol.
- $\bullet$  Diagonalize  $R(\lambda)$ . Eigenvalues = roots of degree 2 pol.  $\in \mathbb{Q}(\lambda)$ . Normalize eigenvectors.
- Plug the parameterization of  $Q_R(\lambda)$  in  $Q_T$ . Degree 2 in one of the parameters. Solve

Improvement

- work in  $\mathbb{P}^3$
- Relax the constraint on  $Q_{R(\lambda)}$ Rational, ruled.
- **Apply Gauss reduction of** the quadratic form:  $P<sup>T</sup>$ RP diagonal. Rational transformation.
- Plug the parameterization in  $Q_T$ . Degree 2 in one of the parameters. Solve

# Intersection of quadrics

#### Levin's pencil method



#### New parameterization

- rational when it exists, involves  $\sqrt{\mathsf{pol.}}$  otherwise.
- quasi-optimal in  $\sqrt{ }$ .

#### Implemented



 $\circledR$  Dupont et al

# Arrangement of quadrics

Projection approach



c Wolpert

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Planar arrangement of curves of degree 4 a curve can have 6 singular points Sort out (upper, lower)  $\rightarrow$  arrangement on each quadric

Surfacic approach



Sweeping plane: Trapezoidal map of evolving conics

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Volumic approach: vertical decomposition

Events:

- new quadric
- features in the map intersect

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Events:

- new quadric
- features in the map intersect

## x solution of



x in an extension field of degree 16



Events:

- new quadric
- features in the map intersect

```
x solution of
```

$$
\exists
$$
 y, z<sub>1</sub>, z<sub>2</sub> s.t.  $\begin{cases} Q_i(x, y, z_1) = 0 \\ Q_j(x, y, z_1) = 0 \end{cases}$  and  $\begin{cases} Q_k(x, y, z_2) = 0 \\ Q_l(x, y, z_2) = 0 \end{cases}$ 

x in an extension field of degree 16

Comparison of events:

difference of events in an extension field of degree 256...

• Optimal degree...?



#### Apollonius diagram Additively weighted Voronoi diagram

Weighted points  $\sigma_i=(\rho_i,r_i),\; \pmb{\rho}_i\in\mathbb{R}^2,$   $r_i\in\mathbb{R}$ 

 $\delta_i(x) = ||x - p_i|| - r_i$ 

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#### Apollonius diagram Additively weighted Voronoi diagram

Weighted points  $\sigma_i=(\rho_i,r_i),\; \pmb{\rho}_i\in\mathbb{R}^2,$   $r_i\in\mathbb{R}$ 

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$  $C_i \subset \mathbb{R}^3: \; \; x_3 = ||x - p_i|| - r_i$  $\iff$   $(x_3+r_i)^2=(x-p_i)^2$   $x_3+r_i>0$  half-cone

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#### Apollonius diagram Additively weighted Voronoi diagram

Weighted points  $\sigma_i=(\rho_i,r_i),\; \pmb{\rho}_i\in\mathbb{R}^2,$   $r_i\in\mathbb{R}$ 

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$ 

$$
C_i \subset \mathbb{R}^3: \quad x_3 = ||x - p_i|| - r_i
$$
  

$$
\iff (x_3 + r_i)^2 = (x - p_i)^2 \quad x_3 + r_i > 0 \quad \text{half-cone}
$$

Apollonius diagram =

lower envelope of the half-cones.

Bisector of  $\sigma_i$  and  $\sigma_i$  =

projection of a plane conic section  $C_i \cap C_j.$
## Apollonius diagram Additively weighted Voronoi diagram

Weighted points  $\sigma_i=(\rho_i,r_i),\; \pmb{\rho}_i\in\mathbb{R}^2,$   $r_i\in\mathbb{R}$ 

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$$
C_i \subset \mathbb{R}^3: \quad x_3 = ||x - p_i|| - r_i
$$
  

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Apollonius diagram =

lower envelope of the half-cones. Bisector of  $\sigma_i$  and  $\sigma_i$  =

projection of a plane conic section  $C_i \cap C_j.$ 

 $\Sigma_i$  sphere  $\subset$   $\mathbb{R}^3$ , center  $(\rho_i, r_i)$  radius  $\sqrt{2}r_i$ 

## Apollonius diagram Additively weighted Voronoi diagram

Weighted points  $\sigma_i=(\rho_i,r_i),\; \pmb{\rho}_i\in\mathbb{R}^2,$   $r_i\in\mathbb{R}$ 

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$ 

$$
C_i \subset \mathbb{R}^3: \quad x_3 = ||x - p_i|| - r_i
$$
  

$$
\iff (x_3 + r_i)^2 = (x - p_i)^2 \quad x_3 + r_i > 0 \quad \text{half-cone}
$$

Apollonius diagram =

lower envelope of the half-cones.

Bisector of  $\sigma_i$  and  $\sigma_i$  =

projection of a plane conic section  $C_i \cap C_j.$ 

 $\Sigma_i$  sphere  $\subset$   $\mathbb{R}^3$ , center  $(\rho_i, r_i)$  radius  $\sqrt{2}r_i$  $X_i$  projection of x onto  $C_i$  $x \in A(\sigma_i)$  iff  $\|x - p_i\| - r_i < \|x - p_i\| - r_i$  (∀j) iff  $pow(X_i, \Sigma_i) < pow(X_i, \Sigma_j)$ 

## Apollonius diagram Additively weighted Voronoi diagram

Weighted points  $\sigma_i=(\rho_i,r_i),\; \pmb{\rho}_i\in\mathbb{R}^2,$   $r_i\in\mathbb{R}$ 

 $\delta_i(\mathbf{x}) = \|\mathbf{x} - \mathbf{p}_i\| - r_i$ 

$$
C_i \subset \mathbb{R}^3: \quad x_3 = ||x - p_i|| - r_i
$$
  

$$
\iff (x_3 + r_i)^2 = (x - p_i)^2 \quad x_3 + r_i > 0 \quad \text{half-cone}
$$

Apollonius diagram =

lower envelope of the half-cones. Bisector of  $\sigma_i$  and  $\sigma_i$  =

projection of a plane conic section  $C_i \cap C_j.$ 

 $\Sigma_i$  sphere  $\subset$   $\mathbb{R}^3$ , center  $(\rho_i, r_i)$  radius  $\sqrt{2}r_i$  $A(\sigma_i)$  = projection of the intersection of the half-cone  $C_i$  with the power region of  $\Sigma_i$ 

Same in  $\mathbb{R}^d$ 





 $@$  Karavelas

Tricky predicates Degree 16

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Tricky predicates Degree 16

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c Karavelas

- **o** Implementation degree 20: degree 16 requires ∼ 100 times as many arithmetic operations...
- Optimal degree...?



**• theoretical: questions on degree...** 





- theoretical: questions on degree...
- Robust (Exact?) computation on higher degree curves and surfaces

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## **Challenges**

- **o** theoretical: questions on degree...
- Robust (Exact?) computation on higher degree curves and surfaces
- Improvement of practical efficiency for low degree curves CAD-VLSI (circular arcs):

 $\sim$  10 times slower than industrial non-robust code good start!

## **Challenges**

• Applications to Structural biology Manipulations of a large number of spheres (low degree surfaces. . . )



c Halperin et al.

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Material taken from:

**o** Greece

National University of Athens University of Crete

**• Germany** 

Max-Planck Institut für Informatik Universität des Saarlandes

**o** Israel

Tel-Aviv University

- **•** France
	- Loria INRIA Sophia Antipolis

# ευχαριστω´



 $\mathcal{A} \oplus \mathcal{B} \rightarrow \mathcal{A} \oplus \mathcal{B} \rightarrow \mathcal{A} \oplus \mathcal{B}$ 

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