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Extensive Infinite Games and Escalation, an exercice in Agda

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Escalation in games is when agents keep playing forever. Based on formal proofs we claim that *if agents assume that resource are infinite, escalation is rational.*

Keywords: extensive game, infinite game, sequential game, escalation coinduction, Agda, proof assistant, formal proof.

1 Introduction

Escalation in games is the phenomenon where agents keep playing (or betting if the game consists in bets) forever, leading to their ruin. Since Shubik[12] people claim that such an attitude is not rational. Based on formal proofs we are able to refute such a claim and to say that *if agents assume that resource are infinite, escalation is rational.* Since our first work[4] which took place before the 2008 financial crisis, evidence[1] show that stating the rationality of escalation makes sense. The only solution for avoiding escalation is then to assume that resource are finite.

In previous works[6,5] we used an approach based on Coq[2] and coinduction (a dual of induction aimed at reasoning on infinite data structures[3]). Especially in[7] we used dependent types together with coinduction. In this paper, we use coinduction in Agda[9], because it allows a terse style closed to this of mathematicians. Agda is a formal proof computer environment as well as a dependently typed programming language.

Notice other works using proof assistants for proving properties of agents. For instance, Stéphane Le Roux proved the existence of Nash equilibria using Coq and Isabelle[10,11]. In a somewhat connected area, Tobias Nipkow proved Arrows theorem in HOL[8]. Agda code of this development are available on GitHub¹.

2 Games and Strategy Profiles

Since we study game theory, lest us first define games. A *game* is either a *leaf* or a *node*. A leaf is a assignment to each agent of a *Utility* (sometime called a *payoff*). Note that the type of utility depends on the agent (dependent type). A node contains two entities, put in a record: an *agent* (the agent who has the trait) and a function *next* which tells the next positions to be played.

¹ https://github.com/PierreLescanne/DependentTypesForExtensiveGames-in-Agda

```
mutual
Game = ((a : Agent) → Utility a) ⊎ NodeG
record NodeG : Set where
coinductive
field
ag : Agent
next : Choice → Game
```

Notice the key word coinductive which shows that we deal with infinite games. The main concept in game theory is this of *strategy profiles*. Strategy profiles are like games with at each node a choice, which is the choice of the agent who continues the game. In Agda the sum comes with to unctions inj_1 and inj_2 . In our case, if u is a utility assignment of type $((a : Agent) \rightarrow Utility a)$ then $inj_1 u$ is a Game and n is a NodeG then $inj_2 n$ is a Game. Strategy profiles are abbreviated StratProf.

```
mutual
StratProf = ((a : Agent) → Utility a) ⊎ NodeS
record NodeS : Set where
coinductive
field
    ag : Agent
    next : Choice → StratProf
    ch : Choice
```

We can define the underlying game of a strategy profile

The underlying game of a leaf (strategy profile) is the same utility assignment, i.e., a leaf (game). For nodes, games are attributed corecursively. Now let us look at another concept. Given two strategy profiles, one may wonder whether they have the same underlying game. This is given by the binary relation $_{\approx}^{sg}$.

```
mutual

data \_\approx^{sg}\_: StratProf \rightarrow StratProf \rightarrow Set where

\approx^{sg}Leaf : u : (a : Agent) \rightarrow Utility a \rightarrow inj<sub>1</sub> u \approx^{sg} inj<sub>1</sub> u

\approx^{sg}Node : n n' : NodeS \rightarrow n \circ\approx^{sg} n' \rightarrow inj<sub>2</sub> n \approx^{sg} inj<sub>2</sub> n'

record \_\circ\approx^{sg}\_ (n n' : NodeS) : Set where

coinductive

field

is\circ\approx^{sg} : ag n \equiv ag n' \rightarrow ((c : Choice) \rightarrow next n c \approx^{sg} next n' c)
```

A leaf has the same game as itself, two nodes have the same game if all their "next" strategy profiles have the same games. Notice that we use the symbol \circ for concepts associated with NodeS, when the concept without \circ is associated with StratProf. Given a strategy profile, we may want to compute the utility of an agent. This assumes that the path that follows the choices of the agents leads to a leaf. A strategy profile s with such a property is said convergent, written \downarrow s. This is defined as follows:

```
\begin{array}{l} \mbox{mutual} \\ \mbox{data} \downarrow : \mbox{StratProf} \rightarrow \mbox{Set where} \\ \downarrow \mbox{Leaf} : u : (a : \mbox{Agent}) \rightarrow \mbox{Utility} a \rightarrow \downarrow \mbox{(inj}_1 u) \\ \downarrow \mbox{Node} : n : \mbox{NodeS} \rightarrow \circ \downarrow n \rightarrow \downarrow \mbox{(inj}_2 n) \\ \\ \mbox{record} \circ \downarrow \mbox{(n : NodeS)} : \mbox{Set where} \\ \mbox{inductive} \\ \mbox{field} \\ \mbox{is} \circ \downarrow : \downarrow \mbox{(next n (ch n))} \end{array}
```

Notice that not all the strategy profile are convergent, for instance the strategy profile AcBc of Section 4 is not convergent.

We define the utility assignment (\underline{u}) of a convergent strategy profile. (\underline{u}) takes two parameters: a strategy profile s and a proof that s is convergent.

Subgame perfect equilibria are very interesting strategy profiles. They are strategy profiles in which the choices of the agents are the best. A leaf is always a subgame perfect equilibrium. A node is a subgame perfect equilibrium if the next strategy profile for the choice of the agent is convergent and is a subgame perfect equilibrium, if for any other node which has the same game and whose next strategy profile is also convergent and is a subgame perfect equilibrium, if for any other node which has the same game and whose next strategy profile is also convergent and is a subgame perfect equilibrium, the utility of the agent of the given node is not less than the utility of the agent of this other node. This is defined formally in Agda as follows, where we use \rightleftharpoons s to tell that s is a subgame perfect equilibrium.

```
\begin{array}{l} \text{data}\rightleftharpoons_{-}: \text{StratProf} \rightarrow \text{Set where} \\ \rightleftharpoons \text{Leaf}: u: (a: \text{Agent}) \rightarrow \text{Utility } a \rightarrow \rightleftharpoons \text{inj}_1 u \\ \rightleftharpoons \text{Node}: n n': \text{NodeS} \rightarrow \\ n \circ \approx^{sg} n' \rightarrow \\ \rightleftharpoons (\text{next n (ch n)}) \rightarrow \\ \rightleftharpoons (\text{next n (ch n)}) \rightarrow \\ (p: \downarrow (\text{next n (ch n)})) \rightarrow (p': \downarrow (\text{next n' (ch n')})) \rightarrow \\ ((u) (\text{next n (ch n)}) p (\text{ag n})) \not< ((u) (\text{next n' (ch n')}) p' (\text{ag n})) \rightarrow \\ \rightleftharpoons \text{inj}_2 n \end{array}
```

3 Escalation

We are now interested in strategy profile leading to escalation.

3.1 Good strategy profile

A first property toward escalation is what we call *goodness*. A strategy profile is *good* if at each node, there is a subgame perfect equilibrium with the same game and the same choice.

```
 \begin{array}{l} \texttt{mutual} \\ \texttt{data} \ \textcircled{o}_{-} : (\texttt{s} : \texttt{StratProf}) \rightarrow \texttt{Set where} \\ \textcircled{o} \texttt{Node} : \texttt{n} : \texttt{NodeS} \rightarrow & \textcircled{o} \textcircled{o} \texttt{n} \rightarrow \textcircled{o} (\texttt{inj}_2 \texttt{n}) \\ \texttt{record} \ & \textcircled{o}_{-} (\texttt{n} : \texttt{NodeS}) : \texttt{Set where} \\ \texttt{coinductive} \\ \texttt{field} \\ \texttt{iso} \textcircled{o} : (\texttt{n'} : \texttt{NodeS}) \rightarrow \rightleftharpoons (\texttt{inj}_2 \texttt{n'}) \rightarrow \texttt{n} \ & \textcircled{o} \approx^{sg} \texttt{n'} \rightarrow \texttt{ch n} \equiv \texttt{ch n'} \rightarrow \\ \textcircled{o} (\texttt{next n} (\texttt{ch n})) \end{array}
```

In other words, this strategy profile is not itself a subgame perfect equilibrium, in particular, it can be non convergent, but each of its choices is dictated by a subgame perfect equilibrium. Goodness can be considered as *rationality* in the choices of the agents. Reader may notice that goodness is of interest only in infinite games, because in a finite game, there is no difference between a good strategy and a subgame perfect equilibrium.

3.2 Divergent strategy profile

Another property of strategy profiles is *divergence*. In a divergent strategy profile, if one follows the choices of the agents, one never gets to a leaf, but, on the opposite, one runs forever. A divergent strategy profile is written $\uparrow s$. The formal definition in Agda of divergence looks like this of convergence, but the test for divergence is based on a coinductive record and never hits a leaf, therefore there is no \uparrow Leaf case.

An escalation is a strategy profile which is both good and divergent.

4 Strategies with two agents and two choices

To build escalating strategy profiles, we consider the case of two agents Alice and Bob and two choices down and right.

```
data AliceBob : Set where
  Alice Bob : AliceBob
```

```
data DorR : Set where
   down right : DorR
```

We take the natural numbers \mathbb{N} as utility ² for both agents ³ and for the $\not\lt$ relation we take the \succcurlyeq relation defined as:

```
data _>_ : \mathbb{N} \to \mathbb{N} \to \text{Set where}

z \ge z : zero \ge zero

s \ge z : n : \mathbb{N} \to \text{suc } n \ge \text{zero}

s \ge s : n m : \mathbb{N} \to n \ge m \to \text{suc } n \ge \text{suc } m
```

A utility assignment is for instance this which assigns 1 to Alice and 0 to Bob:

```
uA1BO : AliceBob \rightarrow \mathbb{N}
uA1BO Alice = 1
uA1BO Bob = 0
```

from which we can build a leaf strategy profile:

```
A1BO : StratProf
A1BO = inj_1 uA1BO
```

which is convergent.

 \downarrow A1B0 : \downarrow A1B0 \downarrow A1B0 = \downarrow Leaf

From the utility assignment which assigns 0 to Alice and 1 to Bob on can build the convergent strategy profile AOB1.

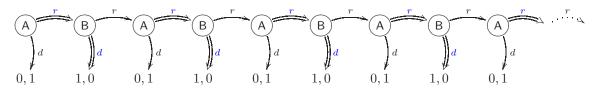
Moreover, we build an infinite strategy AcBs, in which Alice continues always and Bob stops always:

 $^{^2}$ We could have taken a utility with only two values, but we feel that the reader is more acquainted with natural numbers for utilities.

 $^{^3}$ In this case, the type of utility does not depend on the agent.

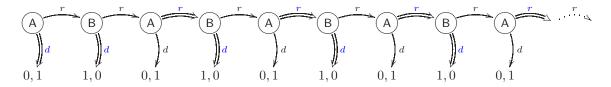
```
mutual
AcBs : StratProf
AcBs = inj<sub>2</sub> oAcBs
oAcBs : NodeS
ag oAcBs = Alice
ch oAcBs = right
next oAcBs down = AOB1
next oAcBs right = BsAc
BsAc : StratProf
BsAc = inj<sub>2</sub> oBsAc
oBsAc : NodeS
ag oBsAc = Bob
ch oBsAc = down
next oBsAc down = A1B0
next oBsAc right = AcBs
```

We notices that by mutual co-recursion, AcBs is defined together with an infinite strategy profile BsAc which starts with a node of which Bob is the agent. Those strategies are like infinite combs.



With down one reaches always a leaf and with right one goes always to a new strategy profile, which is a node. There is a variant of the node $\circ AcBs$, in which the first choice of Alice is down instead of right.

```
VaroAcBs : NodeS
ag VaroAcBs = Alice
ch VaroAcBs = down
next VaroAcBs down = AOB1
next VaroAcBs right = BsAc
```



We prove that $\circ AcBs$ and Var $\circ AcBs$ have the same game. Likewise we prove that AcBs is convergent i.e., \downarrow AcBs. Those two facts are key steps in the proof that AcBs is subgame prefect equilibrium i.e., that \rightleftharpoons AcBs.

On the same paradigm we built a strategy profile AsBc in which A stops and B continues and which is proved to be convergent and to be a subgame perfect equilibrium. We also build a strategy profile in which A and B both continue.

```
mutual
AcBc : StratProf
AcBc = inj<sub>2</sub> oAcBc
oAcBc : NodeS
ag oAcBc = Alice
ch oAcBc = right
next oAcBc down = AOB1
next oAcBc right = BcAc
BcAc : StratProf
BcAc = inj<sub>2</sub> oBcAc
oBcAc : NodeS
ag oBcAc = Bob
ch oBcAc = right
next oBcAc down = A1B0
next oBcAc right = AcBc
```

AcBs, AcBc and AsBc have the same game. Unlike AcBs and AsBc, the strategy profile AcBc is divergent, i.e., \uparrow AcBc. Moreover AcBc is good which means \odot AcBc.

5 Conclusion

Since AcBc is good and divergent, AcBc is an escalation. Hence we proved formally the claim of the introduction, namely *if agents assume that resource are infinite, escalation is rational.*

In the current implementation, the type of choices is the same for all the agents. However, one may imagine that this type may depend on the agents. Making the type of choices depending on the agents is object of the current investigation.

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