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A prediction of COVID-19 development in France based on a modified SEIR epidemic model

Denis Efimov¹ and Rosane Ushirobira¹

Abstract—The goal of this brief report is to identify the parameters of a modified SEIR model for the epidemics course of COVID-19 in France, and to use such an identified model for the prediction of the virus propagation under different conditions of confinement. An interval predictor is also designed, allowing to take into account variations and uncertainties in the model parameters.

I. INTRODUCTION

The SEIR model is one of the most elementary compartmental model of epidemics [1]. It describes the evolution of the relative proportions of four classes of individuals in a population of constant size, namely the susceptible S , capable of contracting the disease and becoming infectious; the asymptomatic E and symptomatic I infectious, capable of transmitting the disease to susceptibles; and the recovered R , permanently immune (after healing or dying). Such a simple model represents well a generic behavior of epidemics, and a related advantage consists in a small number of parameters to identify. This is an important outcome in the case of a virus attack with a limited amount of data available. That is the case of the current¹ situation in France under the presence of the COVID-19 virus.

There are many types and variations of SEIR models [1]. This note is based on the modified SEIR discrete-time model proposed in [2], where it has been used to model the epidemics trend of COVID-19 in China. The selected model is proposed² as follows (we will not consider the influence of the natural birth and mortality, since for a short period of analysis considered here the population may be assumed quasi-constant):

$$S_{t+1} = S_t - b \frac{(pcI_t + r_t E_t)}{N} S_t, \quad (1a)$$

$$E_{t+1} = (1 - \sigma)E_t + b \frac{(pcI_t + r_t E_t)}{N} S_t, \quad (1b)$$

$$I_{t+1} = (1 - \gamma)I_t + \sigma E_t, \quad (1c)$$

$$R_{t+1} = R_t + \gamma I_t, \quad (1d)$$

where $t \in \mathbb{N}$ (the set of nonnegative integers) is the time counted in days ($t = 0$ corresponds to the beginning of measurements or prediction), N denotes the total population, the

parameter $0 < \gamma < +\infty$ represents the mortality and recovery rates, the parameter $0 < b < +\infty$ corresponds to the infection rate of the virus transmission from infectious to susceptibles, $0 < \sigma < +\infty$ is the incubation rate by which the exposed develop symptoms; $0 < pc < +\infty$ corresponds to the number of contacts for the infectious I (it is supposed that infected people with symptoms are in quarantine, then the number of contacts is decreased), $pc \leq r_t < +\infty$ is the number of contacts per person per day for the exposed population E (in the presence of confinement and depending on its severity, this number is time-varying).

Roughly speaking the SEIR model (1) has just three parameters to identify: σ , γ and b . These parameters σ , γ and b then represent, respectively, the rate of change between the states E to I , I to R and $E + I$ to S . The parameter σ has a physical meaning: $\sigma = \frac{1}{T_s}$, where T_s is the average duration of incubation period of the virus after contamination, which can be well identified in patients. The numbers of contacts pc and r_t can be evaluated heuristically based on the population density and social practices. The identification of these parameters must be performed using statistics published by authorities.

Since the measured data and parameters contain numerous uncertainties and perturbations, it is then difficult to make a reasonable prediction based on the simulation of such a model with fixed values of parameters (also taking into account the model simplicity). However, the interval predictor and observer framework [3], [4] allows a set of trajectories to be obtained corresponding to interval values of parameters and inputs, increasing the model validity without augmenting its complexity. This approach has already been applied to different SEIR models (see, e.g. [5], [6]). In this report we apply the interval predictor method for the considered model (1) to improve its forecasting quality.

Furthermore, in this note we describe the measured data used for parameter identification in Section II, together with some hypotheses used in the sequel. The parameters obtained in [2] for China are tested for France and validated on this data in Section III. The method for parameter identification is presented in Section IV, with validation and some experiments on the influence of confinement parameters on COVID-19 development. An interval predictor is designed in Section V, which allows us to evaluate the situation under variation of parameters.

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²This note was written on March 24th, 2020.

³Compared to the model in [2], the inflow/outflow variables for each state were not considered in our analysis.

Day t	\mathcal{I}_t	\mathcal{D}_t	\mathcal{H}_t
1	2876	61	0
2	3661	79	0
3	4499	91	0
4	5423	127	0
5	6633	148	3
6	7730	175	3
7	9134	244	6
8	10995	372	9
9	12612	450	12
10	14459	562	12
11	16018	674	2200
12	19856	860	2200

TABLE I
DATA FOR FRANCE

II. AVAILABLE DATA ON COVID-19 IN FRANCE

The current population in France is $N = 67064000^3$. The incubation period T_s , that is widely reported in the literature for COVID-19, is considered to be between 2 and 14 days [2], so

$$\frac{1}{2} \leq \sigma \leq \frac{1}{14}.$$

The data available from public sources⁴, and which is used in this note, for the time period between March 12th and 23rd is provided in the Table I⁵, where \mathcal{I} , \mathcal{D} and \mathcal{H} represent the number of detected infected, dead and recovered individuals, respectively.

Obviously, not all cases can be detected and documented by the public health services, then there is a ratio between populations I and \mathcal{I} , R and $\mathcal{D} + \mathcal{H}$ as well, which is denoted in this work by α with the estimates from different sources⁶:

$$5 \leq \alpha \leq 20.$$

Formally, such an α has to be time-varying and different for I and R . Due to strict requirements of France Health Services, in this report we take the following hypotheses:

$$I_t = \alpha_1 \mathcal{I}_t, R_t = \mathcal{D}_t + \alpha_2 \mathcal{H}_t, \quad (2)$$

i.e. the deaths are reported exactly, but the actual number of infected cases and the related recovered individuals can be masked due to the complexity of examination and the actual confirmation of the virus presence. An additional reason is that in many cases the virus symptoms result in a mild reaction of patients (approximately in 80% of cases, see the sources above), hence with no official virus confirmation in such a situation.

In this work, we assume modest values for these parameters:

$$\alpha_1 = 5, \alpha_2 = 10;$$

so the two variables of the model (1), I and R , are available from the beginning of the epidemics via (2). We also select another average value for the incubation rate:

$$\sigma = \frac{1}{8}$$

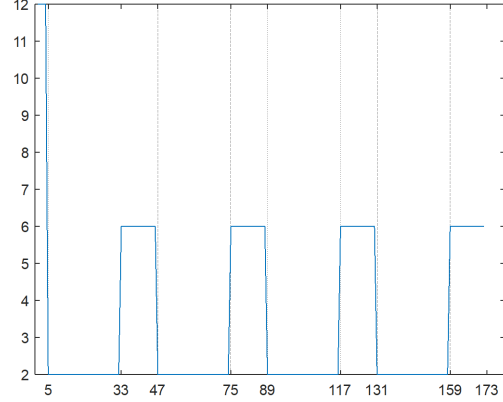


Fig. 1. Variation of the number of contacts r_t in the first scenario

to simplify further identification (the variation in this value will be taken into account later in the interval predictor).

III. NUMERICAL EXPERIMENTS WITH PARAMETERS OF [2]

In [2], using the data available for the Chinese provinces of Zhejiang, Guangdong and Hubei, which have been impacted by the virus differently, the following parameter bounds have been evaluated:

$$0.0721 \leq \gamma \leq 0.238,$$

$$0.05068 \leq b \leq 0.05429,$$

$$p_C = 3 \text{ (number of contacts in quarantine),}$$

$$p_N = 15 \text{ (number of contacts in normal mode),}$$

$$p_R = 10 \text{ (number of contacts in relaxed quarantine).}$$

Selecting the average values $\gamma = 0.155$ and $b = 0.0525$, we also choose to decrease the number of contacts for France as follows:

$$p_C = 2, p_N = 12, p_R = 6,$$

which is related with smaller population density in France.

Following the ideas presented in [7], for simulation we consider two scenarios of confinement:

- 1) Four weeks of strict quarantine and two weeks of a relaxed one, which is further periodically repeated.
- 2) Six weeks of strict quarantine and two weeks of a relaxed one, which is further periodically repeated.

These scenarios will impact only the variable r_t , the corresponding example of behavior of the number of contacts for asymptomatic infectious is shown in Fig. 1.

Remark 1. In other words, r_t can be considered as a kind of control for the virus propagation, by imposing different periods and strictness levels for the confinement.

The results of simulation of the model (1) with the described above parameters for both scenarios 1 and 2 are given in Fig. 2. As we can conclude from these results, both scenarios of confinement do not lead to a stabilization of COVID-19 development in France (the dotted line in the top of the

³https://en.wikipedia.org/wiki/Demographics_of_France.

⁴See www.santepubliquefrance.fr/ and www.data.gouv.fr.

⁵Sources: Eciens, Johns Hopkins University

⁶Coronalinks-3-19-20

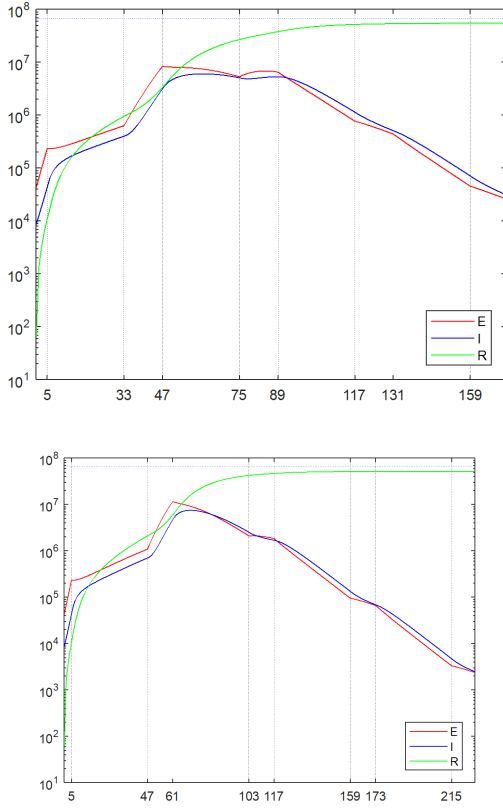


Fig. 2. The results of simulation with parameters of [2] for scenarios 1 and 2

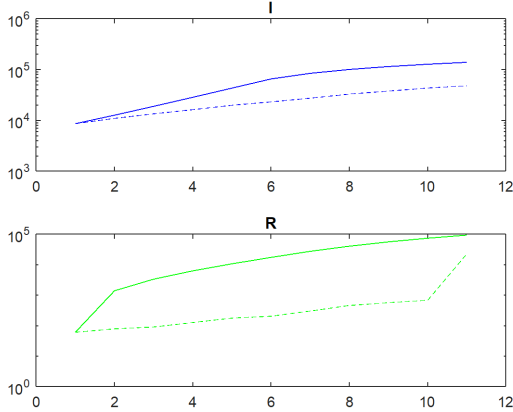


Fig. 3. The results of verification with parameters of [2]

plots correspond to N (the total population), then according to these graphics the epidemics is going to stop after a total infection of the country). However, a short analysis on how close the obtained curves are to the measured data (see Fig. 3 where dashed lines correspond to the measurements), then we recognize that the model with these parameters from [2] does not correspond well to the situation in France. Therefore, an identification of parameters is needed.

IV. PARAMETER IDENTIFICATION

For the parameter identification, we assume that the incubation rate σ is fixed as above, and that the symptomatic infectious I_t and the recovered people R_t are measured for the first J days of the virus attack as in (2) for $t = 0, 1, \dots, J$.

From the equation (1d) we can identify the value of the parameter γ :

$$\gamma = \frac{R_{t+1} - R_t}{I_t},$$

whose least squares estimation is

$$\gamma = \frac{\sum_{t=0}^{J-1} I_t (R_{t+1} - R_t)}{\sum_{t=0}^{J-1} I_t^2} = 0.0650.$$

Next, the equation (1c) allows us to calculate the related number of asymptomatic infectious (σ is chosen and γ is estimated):

$$E_t = \frac{1}{\sigma} (I_{t+1} - (1 - \gamma)I_t),$$

while the number of susceptible individuals can be evaluated using the total population:

$$S_t = N - I_t - R_t - E_t.$$

Finally, from the equation (1b) we can derive the infection rate (for the selected p_C and r_i):

$$b = N \frac{E_{t+1} - (1 - \sigma)E_t}{(p_C I_t + r_i E_t) S_t},$$

whose least squares estimation is

$$b = N \frac{\sum_{t=0}^{J-1} (p_C I_t + r_i E_t) (E_{t+1} - (1 - \sigma)E_t) S_t}{\sum_{t=0}^{J-1} (p_C I_t + r_i E_t)^2 S_t^2} = 0.0425.$$

The identified values for γ and b lie out the confidence intervals obtained for China in [2].

The results of simulation of the model (1) with the identified parameters for both scenarios 1 and 2 are given in Fig. 4, a verification on the measured and reconstructed data is shown in Fig. 5 (in this case the model approximates reasonably well the virus propagation). These results are more consistent with the available statistics for France, and also demonstrate the lack of efficiency of the confinement (even of a long length).

Let us enlarge the validity of the model by considering intervals of admissible values for parameters.

V. INTERVAL PREDICTION

The idea of interval prediction can be illustrated on a simple scalar system:

$$x_{t+1} = a_t x_t + d_t,$$

where $x_t \in \mathbb{R}_+$ is a non-negative system state, whose initial conditions belong to a given interval:

$$x_0 \in [\underline{x}_0, \bar{x}_0];$$

$a_t \in \mathbb{R}_+$ and $d_t \in \mathbb{R}$ are uncertain inputs, which also take values in known intervals:

$$a_t \in [\underline{a}_t, \bar{a}_t], d_t \in [\underline{d}_t, \bar{d}_t]$$

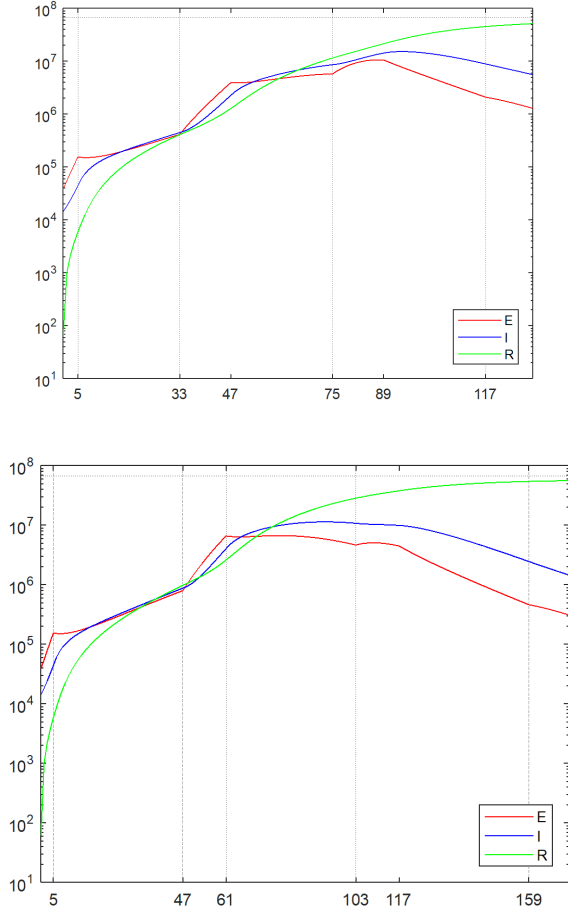


Fig. 4. The results of simulation with identified parameters

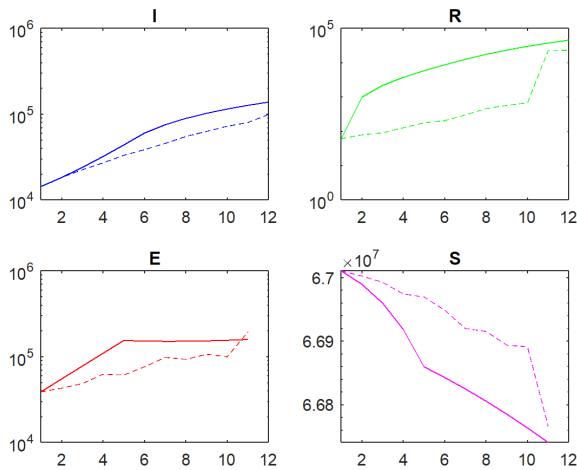


Fig. 5. The results of verification with identified parameters

for all $t \geq 0$. So, we assume that $x_0 \leq \bar{x}_0$, $0 \leq a_t \leq \bar{a}_t$ and $d_t \leq \bar{d}_t$ are known for all $t \geq 0$. The imposed non-negativity constraints on x_t and a_t correspond to the case of the model (1). We would like to calculate the lower \underline{x}_t and upper \bar{x}_t predictions on the state x_t of this system under the introduced hypotheses on all uncertain variables, which have to satisfy the relations:

$$\underline{x}_t \leq x_t \leq \bar{x}_t \quad \forall t \geq 0.$$

The theory of interval observers and predictors [4] answers this question, and a possible solution (that utilizes the non-negativity of x_t and a_t) is as follows:

$$\begin{aligned} \underline{x}_{t+1} &= \underline{a}_t \underline{x}_t + \underline{d}_t, \\ \bar{x}_{t+1} &= \bar{a}_t \bar{x}_t + \bar{d}_t, \end{aligned}$$

which is rather straightforward. Let us apply this method to the model (1) (clearly, each equation there has the form as above).

To this end we assume that all parameters belong to the known intervals:

$$\begin{aligned} \sigma &\in [\underline{\sigma}, \bar{\sigma}], \quad \gamma \in [\underline{\gamma}, \bar{\gamma}], \quad b \in [\underline{b}, \bar{b}], \\ r_t &\in [\underline{r}_t, \bar{r}_t] \quad \forall t \geq 0, \end{aligned}$$

together with the initial conditions in (1):

$$S_0 \in [\underline{S}_0, \bar{S}_0], \quad I_0 \in [\underline{I}_0, \bar{I}_0], \quad E_0 \in [\underline{E}_0, \bar{E}_0], \quad R_0 \in [\underline{R}_0, \bar{R}_0],$$

where all values $\underline{\sigma}, \bar{\sigma}, \underline{\gamma}, \bar{\gamma}, \underline{b}, \bar{b}, \underline{r}_t, \bar{r}_t, \underline{S}_0, \bar{S}_0, \underline{I}_0, \bar{I}_0, \underline{E}_0, \bar{E}_0$ and $\underline{R}_0, \bar{R}_0$ are obtained from the values used in the previous section by applying $\pm\delta\%$ deviation from those nominal quantities. Then applying the approach explained just above, we derive the equations of the interval predictor:

$$\begin{aligned} \underline{S}_{t+1} &= \max \left\{ 0, 1 - \bar{b} \frac{(p_C \bar{I}_t + \bar{r}_t \bar{E}_t)}{N} \right\} \underline{S}_t, \\ \underline{E}_{t+1} &= \left(1 - \bar{\sigma} + \underline{b} \frac{\underline{r}_t \underline{S}_t}{N} \right) \underline{E}_t + p_C \underline{b} \frac{\underline{I}_t \underline{S}_t}{N}, \\ \underline{I}_{t+1} &= (1 - \bar{\gamma}) \underline{I}_t + \underline{\sigma} \underline{E}_t, \\ \underline{R}_{t+1} &= \underline{R}_t + \underline{\gamma} \underline{I}_t, \\ \bar{S}_{t+1} &= \min \left\{ N, \max \left\{ 0, 1 - \underline{b} \frac{(p_C \underline{I}_t + \underline{r}_t \underline{E}_t)}{N} \right\} \bar{S}_t \right\}, \\ \bar{E}_{t+1} &= \min \left\{ N, \left(1 - \underline{\sigma} + \bar{b} \frac{\bar{r}_t \bar{S}_t}{N} \right) \bar{E}_t + p_C \bar{b} \frac{\bar{I}_t \bar{S}_t}{N} \right\}, \\ \bar{I}_{t+1} &= \min \left\{ N, (1 - \underline{\gamma}) \bar{I}_t + \bar{\sigma} \bar{E}_t \right\}, \\ \bar{R}_{t+1} &= \min \left\{ N, \bar{R}_t + \bar{\gamma} \bar{I}_t \right\}, \end{aligned}$$

where for all $t \geq 0$ we obtain the interval inclusions for the state of (1):

$$S_t \in [\underline{S}_t, \bar{S}_t], \quad I_t \in [\underline{I}_t, \bar{I}_t], \quad E_t \in [\underline{E}_t, \bar{E}_t], \quad R_t \in [\underline{R}_t, \bar{R}_t],$$

and $\underline{S}_t, \bar{S}_t, \underline{I}_t, \bar{I}_t, \underline{E}_t, \bar{E}_t$ and $\underline{R}_t, \bar{R}_t$ are the interval lower and upper bound predictions.

Remark 2. The boundedness of these variables are not discussed in this note.

The results of simulation of this interval predictor (3) with $\delta = 15$ are presented in Fig. 6 (the dashed and dotted lines represent, respectively, upper and lower interval bounds, the

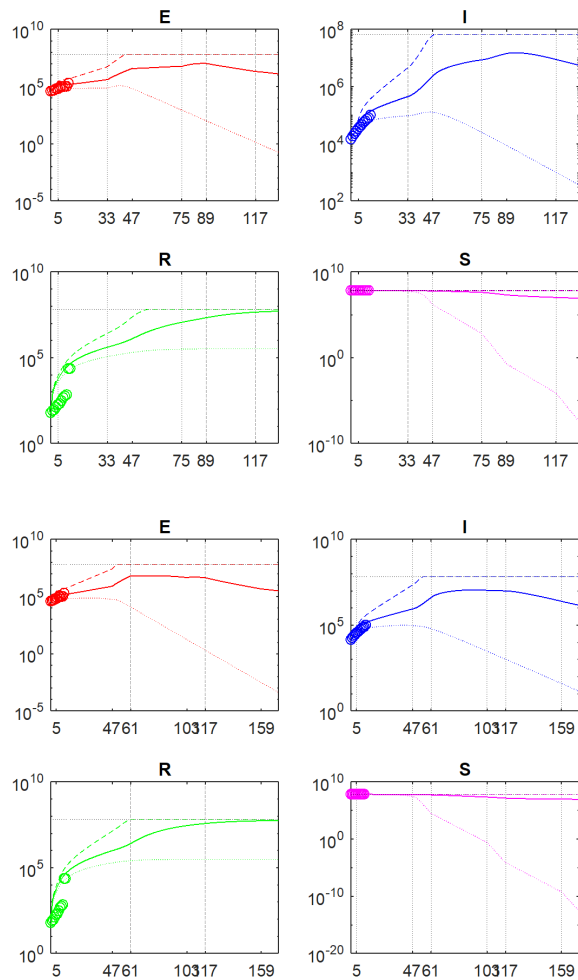


Fig. 6. The results of simulation of the interval predictor (3) for scenarios 1 and 2

solid lines correspond to the results of simulation obtained in the previous section, the circles depict measured and re-constructed data points used for identification and validation). As we can conclude from these curves, under sufficiently big deviations of the parameters (which correspond to the small amount of data publicly available now), the confinement may be efficient. The measurements are nearly included in the obtained interval predictions. In general, a further precision of the model is needed, but as a recommendation after these preliminary simulations: an augmentation of severity of the quarantine is desirable.

VI. CONCLUSION

A simple discrete-time SEIR epidemic model was identified and used to predict the influence of the quarantine on the COVID-19 virus propagation in France. To enlarge the model prediction performance an interval predictor was also used. The prediction showed that a six-week confinement may be more efficient, but under the current level of uncertainty, a more strict as possible confinement seems to be advisable.

Machine learning tools can be further used to identify and optimize time profile for the confinement.

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