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# Virtual network function forwarding graph embedding in 5g and post 5g networks

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# VIRTUAL NETWORK FUNCTION FORWARDING GRAPH EMBEDDING IN 5G AND POST 5G NETWORKS

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IRISA Lab./INRIA Dionysos team-project

# PLAN

- What are the challenges facing network operators today?
- Challenges related to network slicing
- On using Deep Reinforcement Learning for network slicing
- Conclusions

# WHAT ARE THE CHALLENGES FACING NETWORK OPERATORS TODAY?

Complex  
networks

High  
costs

Lack of  
agility

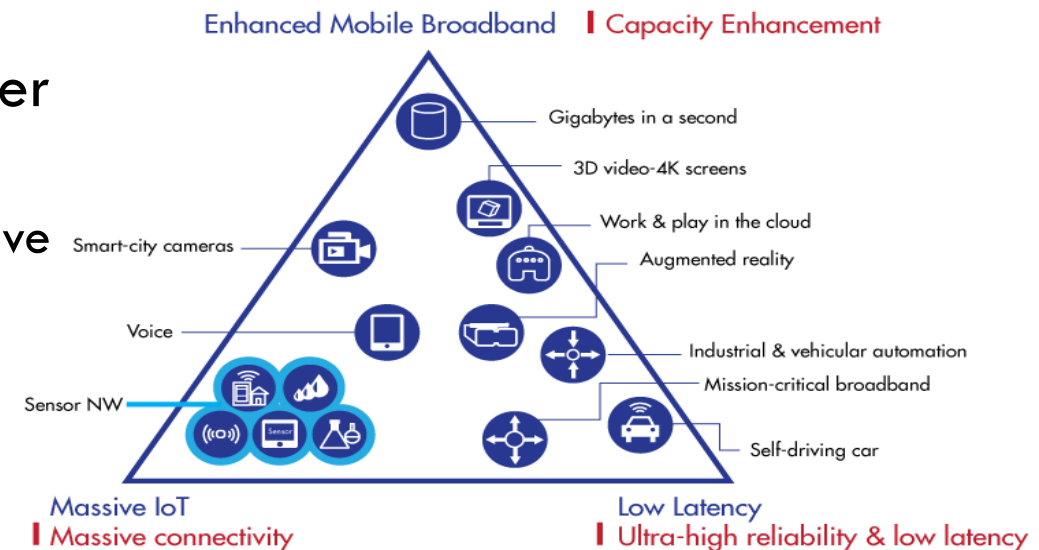
No  
growth

# WHAT ARE THE CHALLENGES FACING NETWORK OPERATORS TODAY?

Ever-increasing infrastructure **complexity**

- **Diversification** of services (IoT, Smart cars, ...)
  - Very diverse needs in terms of QoS (SLA)
  - Within the same network infrastructure
- **Limits of the human being** to manage a large number of equipments (10K, 100K devices, ...)
  - Very **high risk of mistakes**, the cost of which can be prohibitive
  - Very slow service provisioning (not automated)

Complex networks



# WHAT ARE THE CHALLENGES FACING NETWORK OPERATORS TODAY?

## Very high investment (CAPEX) cost

- Equipment excessively expensive to purchase

## Very high operational (OPEX) cost

- Significant operational costs with the human factor at the different levels of control and supervision



High  
costs

# WHAT ARE THE CHALLENGES FACING NETWORK OPERATORS TODAY?



Lack of  
agility

## Lack of agility

- Equipment that can **hardly be adapted** to the needs and of which any **update** is complex and **not always possible**
- **Scaling is not always possible** and oversizing is costly (unlike the Cloud)

# WHAT ARE THE CHALLENGES FACING NETWORK OPERATORS TODAY?

It is very **difficult to grow**

- **Renting** infrastructure is **no** longer as **profitable**
  - Difficult to be profitable when you don't decide on the rates
  - It's difficult to get a return on investment when having a continuous evolution of the infrastructure ...
- Operators are not part of the delivery chain of the service, which is very profitable (e.g. CDN)

No  
growth





# OPERATORS' NEEDS

## Automated network infrastructure

- Self configuration, self healing, self scaling, self \*, ...

## Supporting current and future services within the same infrastructure

- With **very diverse constraints** (latency, bandwidth, loss, CPU, FPGA, ...)

## Softwarization of the network and the services

- Ability to lease infrastructure to third parties without compromising the network and its efficiency
- Higher programmability (e.g. Yang, P4 ...)

## Being part of the service delivery value chain

Complex  
networks

High  
costs

Lack of  
agility

No  
growth

# ENABLING TECHNOLOGIES

## Automated network infrastructure

- Towards autonomic networks or even Zero-touch networks
- Intent driven networking

## Supporting current and future services

- On demand service composition

## Being part of the service delivery value chain

- Multi-access Edge Computing (MEC)

## Softwarization of the network and the services

- Software defined networks (SDN)
- Network Function Virtualization (NFV)

## High level network description and programming

- E.g. Yang, P4

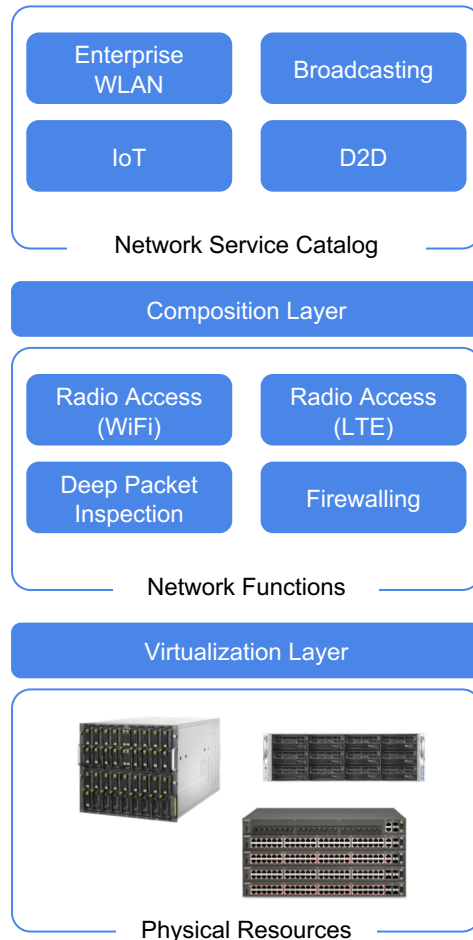
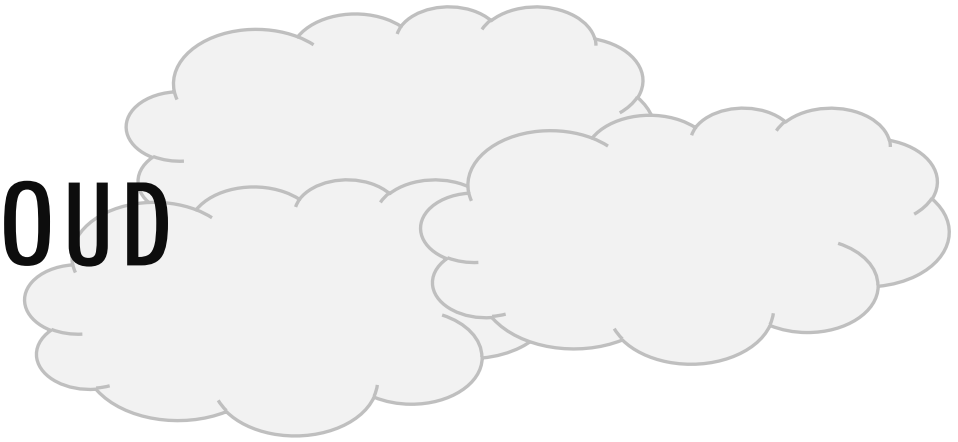
Complex  
networks

High  
costs

Lack of  
agility

No  
growth

# INSPIRATION CAME FROM THE CLOUD



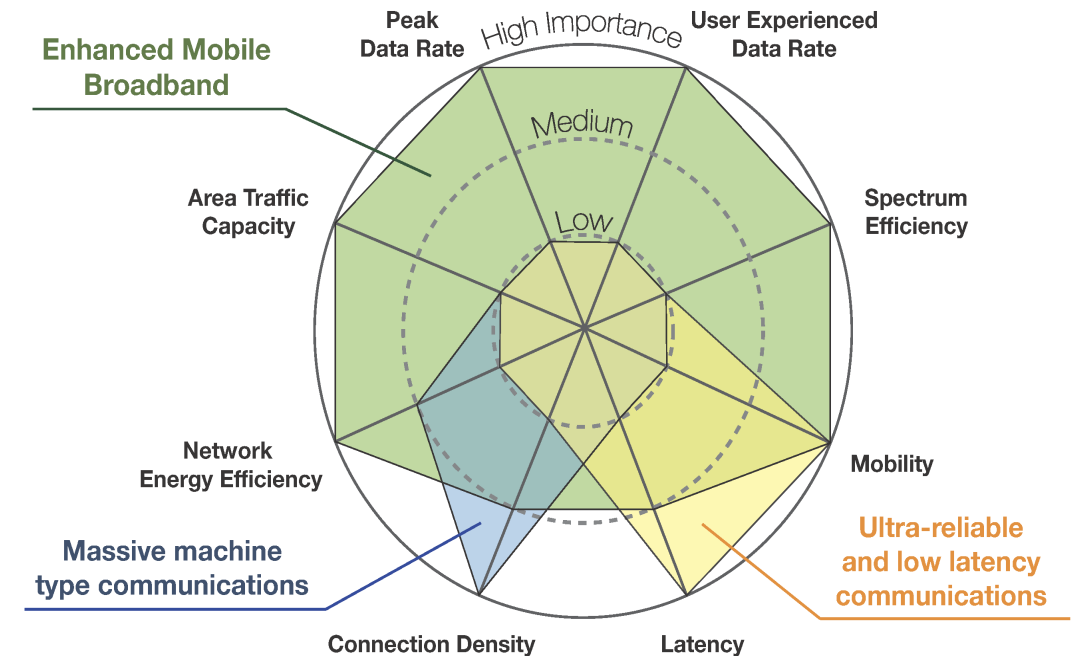
## The four NFV Pillars

- Virtualized network functions
- Reuse hardware across tenants
- Chain virtual functions
- Dynamic scaling of network services

# WHERE'S 5G IN ALL THIS?

5G is trying to integrate several of these **building blocks** to meet the needs of the NOs

- For this purpose the concept of **network slicing** is introduced.



# MY DEFINITION OF NETWORK SLICING

Network slicing is the process that allows a dynamic and personalized sharing of network operators' infrastructure

**Target:** Carrier grade virtual network

# WHY ARE OPERATORS INTERESTED IN NETWORK SLICING? (1)

Network slicing is seen as an opportunity for NO to get a lot more from their infrastructure

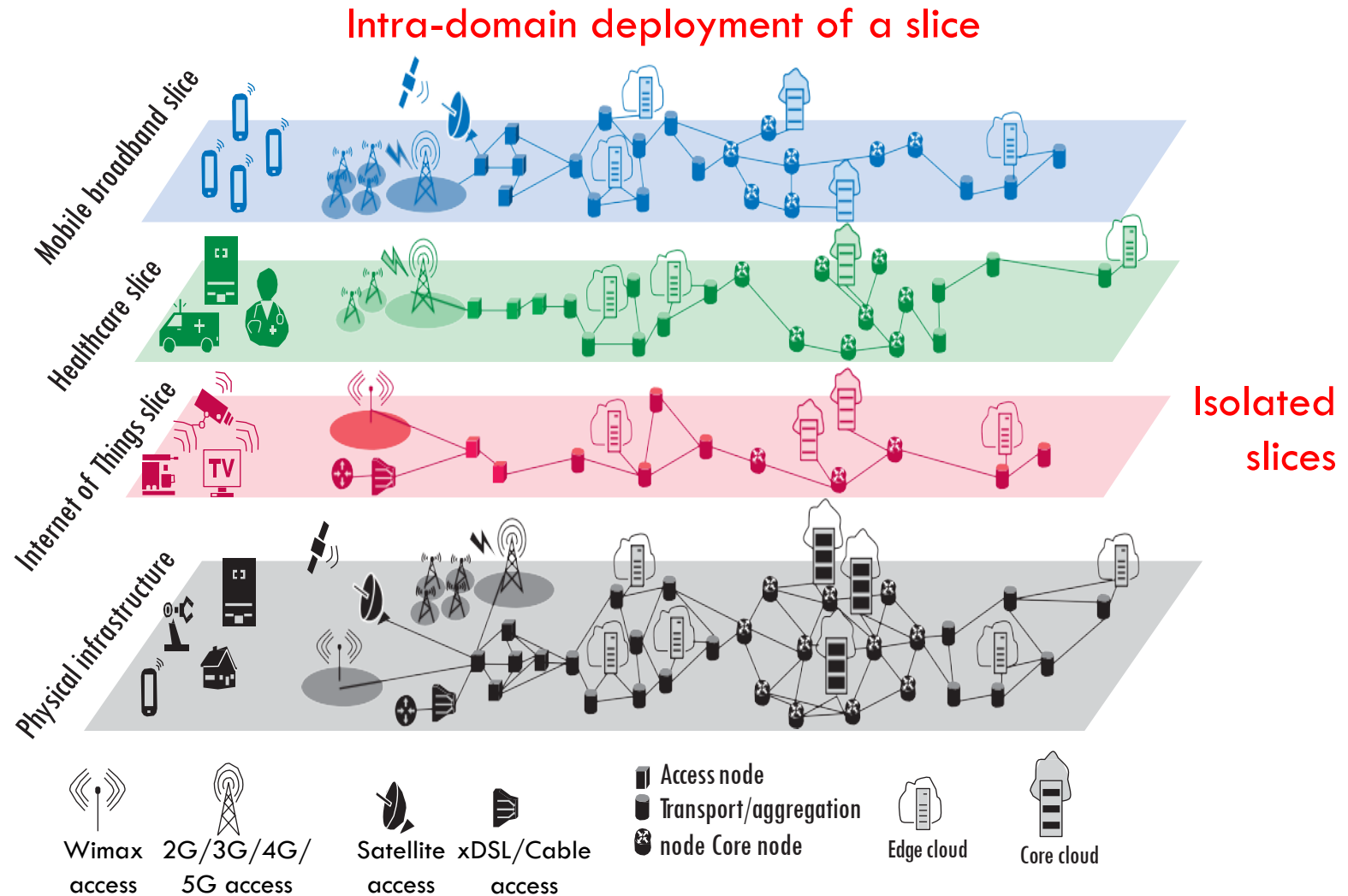
- by offering numerous **dedicated virtual networks** specifically tailored towards a service or customer
- by operating on virtual network architecture and borrows from the principles behind **SDN** and **NFV**

# WHY ARE OPERATORS INTERESTED IN NETWORK SLICING? (2)

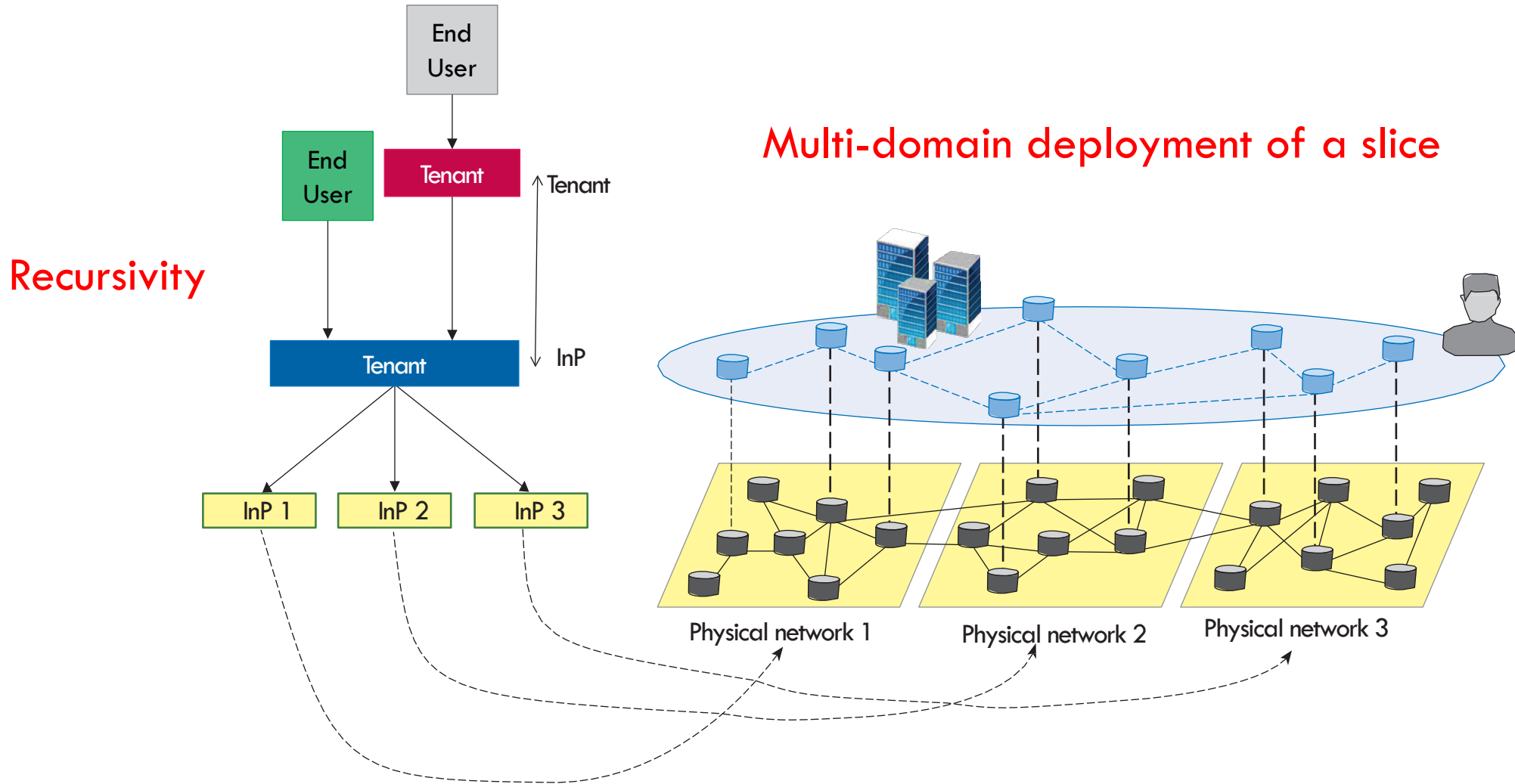
Network slicing allows to simultaneously accommodate a wide range of services

- over a **common network infrastructure**

May support new services on-demand and in near real-time



# NETWORK SLICING: AN ARCHITECTURE





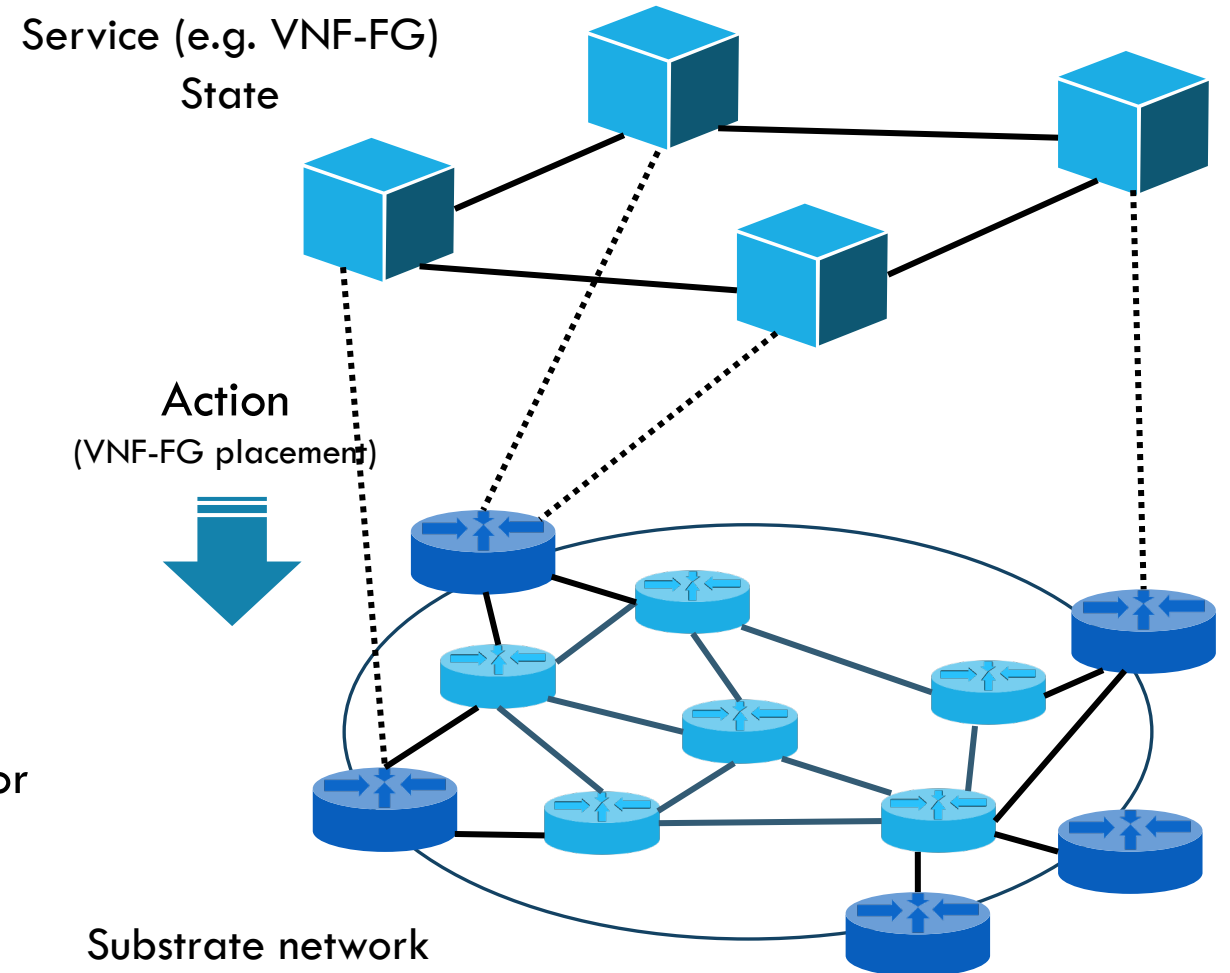
# IN PRACTICE, WHAT DOES SLICING A NETWORK CONSIST OF? (1)

## 1 Most simple form

- Placement of services consisting in one VNF
  - **Offline vs online problem** (bin packing problem)
    - May consider 1 or several metrics for the placement (e.g. latency, load, reliability, ...)
  - **NP-complete problem**

## 2 More advanced form (more complex)

- Placement of services in a **VNF-FG** form
  - Involves not only the **placement of VNFs** but also addressing a **routing** problem
    - Addressing the VNFs placement then the routing ... or simultaneously
  - Need to consider several metrics (QoS requirements)
  - Intra-domain or multi-domain placement



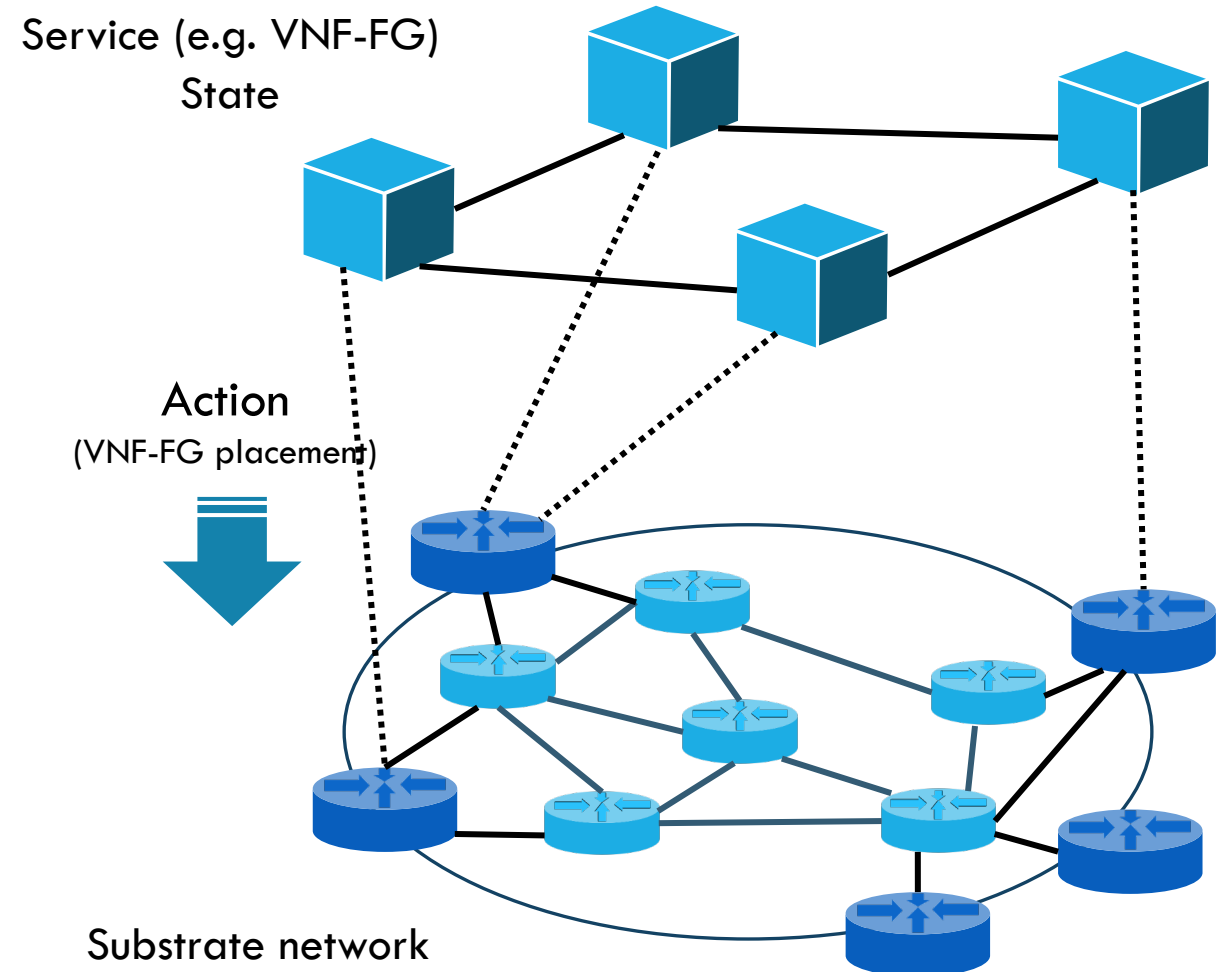
# IN PRACTICE, WHAT DOES SLICING A NETWORK CONSIST OF? (2)

## 3 More advanced form

- Placement and scalability of services
  - Involves the placement of services while automatically managing their scalability
    - Determining the number of instances of each VNF?
    - Could be also managed at runtime, which make the placement even harder

## 4 Most advanced forms

- Slices could be isolated (waste of resources) or may share the resources (risk of outage)
- Consists in considering the sharing of VNFs between different services
- Considering microservices, ...



# WHAT METRICS ARE CONSIDERED FOR PLACEMENT?

This naturally depends on the problem being addressed (SLA) ...

- Reliability
  - Loss
  - K-connectivity, average connectivity, ...
- Service requirements
  - Bandwidth
  - System requirements (CPU, RAM, Disk, FPGA, ...)
  - QoS/QoE
  - Load balancing
- Scalability
- Energy/power saving

Some problems require addressing **one metric** and others **several metrics at a same time** ... with the risk of a combinatorial explosion.

# SERVICES PLACEMENT: A WELL STUDIED PROBLEM!

The problem of placement is an old and well-studied problem

- Many papers in the Cloud context
- Conventional service placement comes down to a problem of bin-packing or knap-sack
  - NP-hard problem
- Realistic placement of services, like the VNF-FG placement is much more complex
  - Services are composite, since they include several sub-services, and multi-constrained
    - Must be added the multiple constraints on the links

Less attention has been paid to the placement of VNF-FG, which is actually a fairly recent issue

# CLASSIFICATION OF EXISTING APPROACHES FOR THE PLACEMENT

1. Mathematical optimisation-based approaches
  - Most of the paper fall in this category
  - Use of: Integer Linear Program (ILP) or Mixed ILP (MILP) ...
    - Integer Programming is an NP-complete problem. So:
      - There is no known polynomial-time algorithm
      - **Even small problems may be hard to solve**
      - Propose more efficient heuristics for solving the problem, so they fall into another category.

## Main limitation:

Some parameters are only obtained during run-time (latency and loss) which makes these approaches sometimes ineffective in a real context.

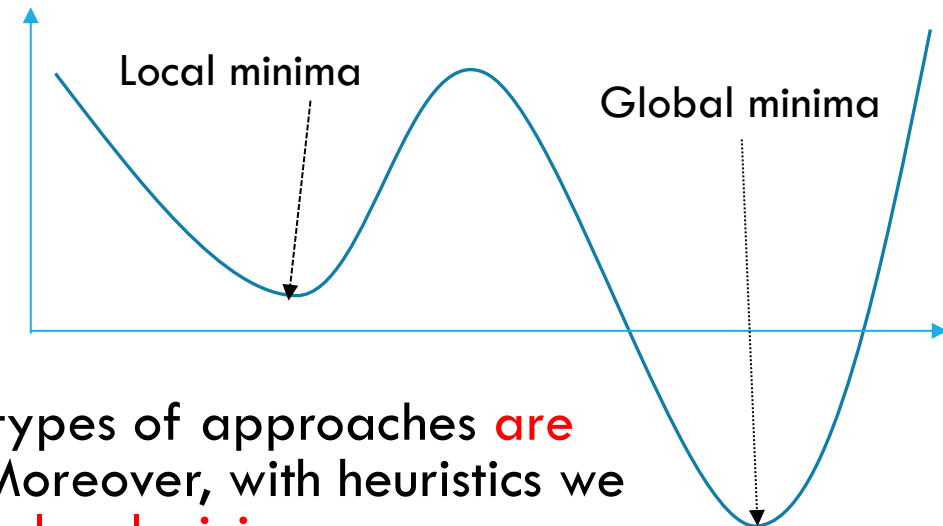
# CLASSIFICATION OF EXISTING APPROACHES FOR THE PLACEMENT

## 2. Heuristics-based approaches

- Most of the paper fall in this category
- Use generally : a two step approach
  - Placing VNFs using traditional algorithm (First Fit, Best Fit, nearest search procedure, ...)
  - Then placing VLs (using Shortest path "SP", K-SP, ...)
  - **Very fast, effective and deal with very large problems**
    - For some industrials, this is the best solution

### Main limitation:

In systems where **constraints and objectives are changing**, these types of approaches **are not very suitable** since they generally require a **total redesign**. Moreover, with heuristics we have a rapid convergence at the price of the risk of sticking at a **local minima**.



# CLASSIFICATION OF EXISTING APPROACHES FOR THE PLACEMENT

## 3. Metaheuristics-based approaches

- Use generally : a two step approach
  - Placing VNFs using an evolutionary, greedy, ... algorithm
  - Then placing VLs using Shortest path "SP", ...) or using a metaheuristic
  - **Slow, very effective and deal with very large problems**
    - Explore all solutions, or only feasible solutions (faster with risk of stacking at a local optimum)
    - Can be used in a real or simulated system
  - With enough time this may converges to **global optimum**
- But ...
  - As the fitness (cost) function is function of VNFs + VLs placement ... it comes to placing both at the same time ...

# CLASSIFICATION OF EXISTING APPROACHES FOR THE PLACEMENT

## 3. Metaheuristics-based approaches

Features and main limitation:

Metaheuristics make it possible to respond effectively to the problem VNF-FG placement. They can very easily integrate new objectives or constraints without reconsidering the solution, unlike heuristics. It should also be noted that there is some research work that shows the convergence of these algorithms towards the optimum under certain conditions.

However, to address a new placement you almost always need to start from the beginning ... as there is **no learning**



# CLASSIFICATION OF EXISTING APPROACHES FOR THE PLACEMENT

## 4. Learning-based approaches

- Only very few approaches
- Use generally : a two step approach but ... the reward function concerns VNFs + VLs placement, which means that we are addressing both at the same time.
  - **Very slow**
    - For some industrials, this is the best solution

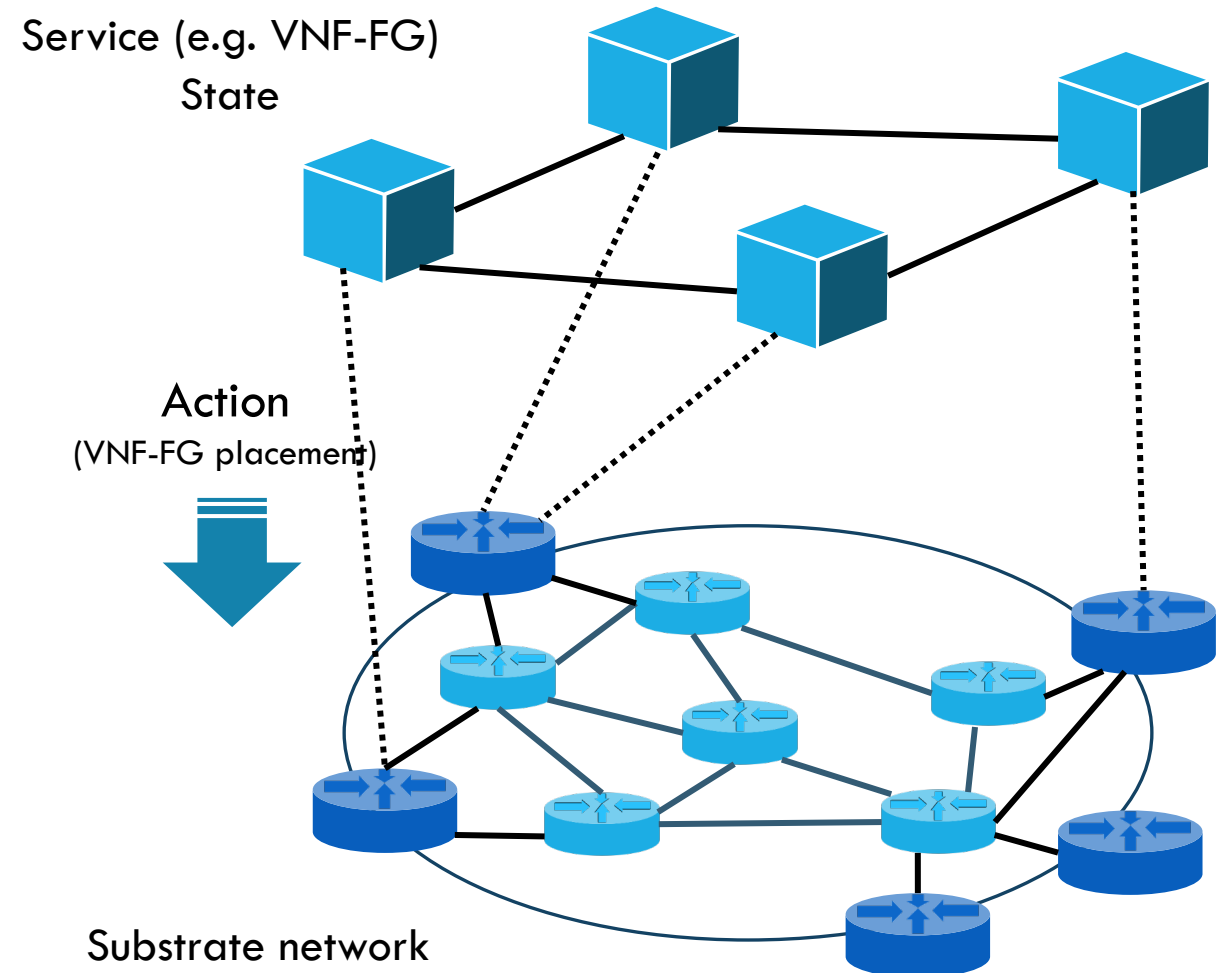
Main limitation:

Efficient approaches still **need to be developed**.

# OUR OBJECTIVE

## Problem 2-~3-~4

- Placement of services in the form of **VNF-FG**
- **Shared resources**
- **Intra** and multi-domain
- **Constrained services' placement**
  - Networking requirements: bandwidth, latency, loss, ...
  - System requirements: CPU, RAM, DISK, FPGA, ...



# MANY COLLABORATIONS WITH INDUSTRY ...

## Orange

- Yue Li (MEC)
  - Heuristics – Water filling, Control theory
- Jean-Michel Sanner (Controllers' placement)
  - Heuristics, Evolutionary Algo.
- Farah Slim (Online VNFs placement)
  - Heuristics, Evolutionary Algo.

## TDF

- Imad Alawe (Times series forecasting)
  - Deep learning

## INRIA

- Hamza Ben Ammar (Cache placement)
  - GRASP

## Nokia Bell Labs

- Anouar Rkhami (VNF-FG placement) ... ongoing
- Quang Pham Tran Anh (VNF-FG placement + routing) – Post doc
  - Evolutionary algo., Deep learning

## EXFO

- Reliable placement (will start soon)

# CHALLENGE IN VNF-FG PLACEMENT

Extremely large number of possibilities of placement (very large action space)

- Difficulty in finding an optimal placement (i.e. NP-hard problem), excepting for very small instances

Limits of existing work

- Optimization problems (i.e. MILP) have the limitation of not always being applicable in a real context, given the latency of resolution or unsuitability in a real context
- Problem of convergence of classical Meta-heuristics towards more or less good solutions ... and **no learning** ...
  - Previous work on Evolutionary Algorithms

**Objective (short and mid-term)**

- **Exploring the potential of deep learning in the placement of VNF-FG**

# BEST ACTION SELECTION USING ML ...

## Classification of machine learning algorithms

Supervised  
learning

Knowing input  $X$  and output  $y$  (labels), we try to find  $f$ ,  $y = f(X)$   
(**mapping**)

Unsupervised  
learning

Knowing  $X$ , we **classify** them regarding some cost function

Our focus here

Reinforcement  
learning

We learn how to take actions (**policy**) to maximize a reward function

« When solving a problem of interest, do not solve a more general problem as an intermediate step »

Vladimir Vapnik

Value-based

Learn the **value of being in a given state**, and taking a specific action there

Policy-based

Learn **functions**, which directly map an observation to an action

# DEEP LEARNING APPROACH

## Machine Learning or Optimization-based?

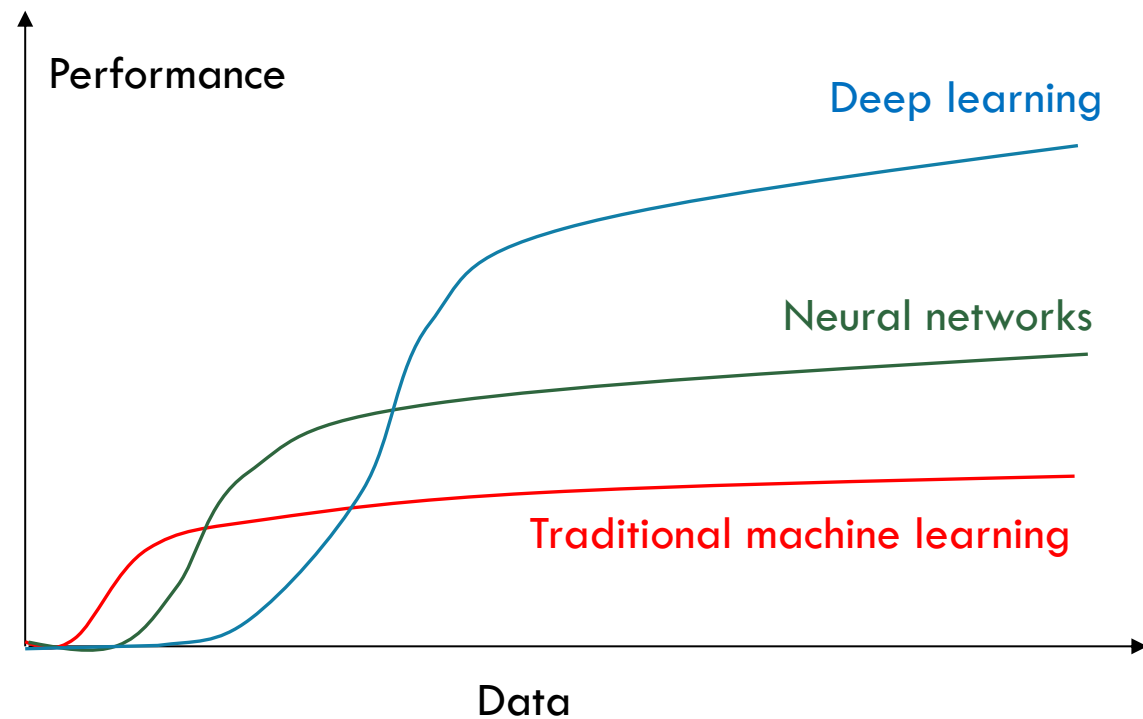
- Optimization-based approaches need accurate models
- Difficulties in determining accurate models for complex networks (multi-hop)(\*)
- Machine learning addresses this by learning hidden characteristics of any network

(\*) Z. Xu *et al.*, "Experience-driven Networking: A Deep Reinforcement Learning based Approach," *IEEE INFOCOM 2018 - IEEE Conference on Computer Communications*, Honolulu, HI, 2018, pp. 1871-1879.

# DEEP LEARNING APPROACH

## Why go deep?

- Data dependency



# WHY REINFORCEMENT LEARNING

Can be used even in the absence of labels.

Recent advances in deep reinforcement learning have shown their effectiveness to deal with the credit assignment problem

- Example: chess game,...

Recent techniques are stable

- Mix between traditional RL and supervised learning (**experience replay**)

Very suitable for operating in an unknown or uncontrolled environment

- Can learn and evolve in changing environments or partially observable environments (**multi-domain strategy**)



# REINFORCEMENT LEARNING

Reinforcement learning is about mapping situations to actions to maximize a reward

- Learner is not told which actions to take, but instead must discover which actions yield the most reward

Finding the best actions involves a fairly broad exploration

- Agent must try a variety of actions and progressively favor those that appear to be best (trade-off between exploration and exploitation)
- **Knowledge about the model** can reduce this space
  - e.g. if we do not succeed in placing a VM of a particular size on a node, it means that we will not be able to place a machine of a larger size ... **not easy to learn such rules**

# SOME EXISTING STRATEGIES ...

Q-learning algorithm is able to achieve an optimal policy

- when the state **space and action space are limited** (tables don't scale)

Deep Q-learning algorithm overcomes the limits of Q-learning by approximating the Q-value using a Neural Network

- But presents instabilities
  - Could be improved by improving the exploration + experience replay
- Presents some **limits for problems with large action space**

Deep Deterministic Policy Gradients (DDPG) – Google 2016 –  
obsoleted DQN

- More robust, and **able to achieve much better scores** on the standard battery of Deep RL tasks

# SOME EXISTING STRATEGIES ...

## Q-learning

Q-Learning is a table (Q-table) of values for every state (row) and action (column) possible in the environment.

Recursive process to converge to the best Q-table

- using for example Temporal Difference Learning (TD) :

$$Q(s, a) = Q(s, a) + \alpha(R + \gamma \max(Q(s', :)) - Q(s, a))$$

Current  
state

Obtained

Q-learning algorithm is able to achieve an optimal policy  
when the state space and action space are limited (tables don't scale)

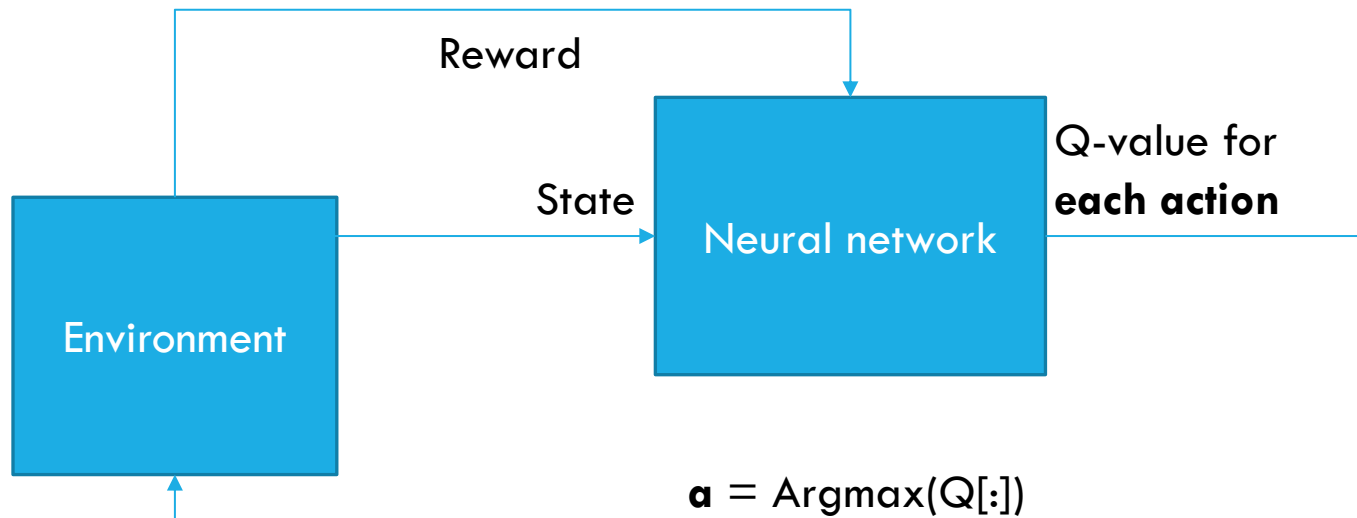
		Actions					
		a <sub>1</sub>	a <sub>2</sub>	a <sub>3</sub>	a <sub>4</sub>	a <sub>5</sub>	a <sub>6</sub>
States	s <sub>1</sub>						
	s <sub>2</sub>			Q values			
	s <sub>3</sub>						
	s <sub>4</sub>						

# SOME EXISTING STRATEGIES ...

Deep Q-learning algorithm overcomes the limits of Q-learning by approximating the Q-value using a Neural Network

But presents instabilities

Could be improved by improving the exploration (epsilon-greedy), experience replay, target network



$$Loss = \sum (Q_{target} - Q)^2$$

- Q-target: Q-value of selected action
- Q: output of the NN

# SOME EXISTING STRATEGIES ...

**Deep Deterministic Policy Gradients (DDPG)** – Google 2015 –  
obsoleted DQN

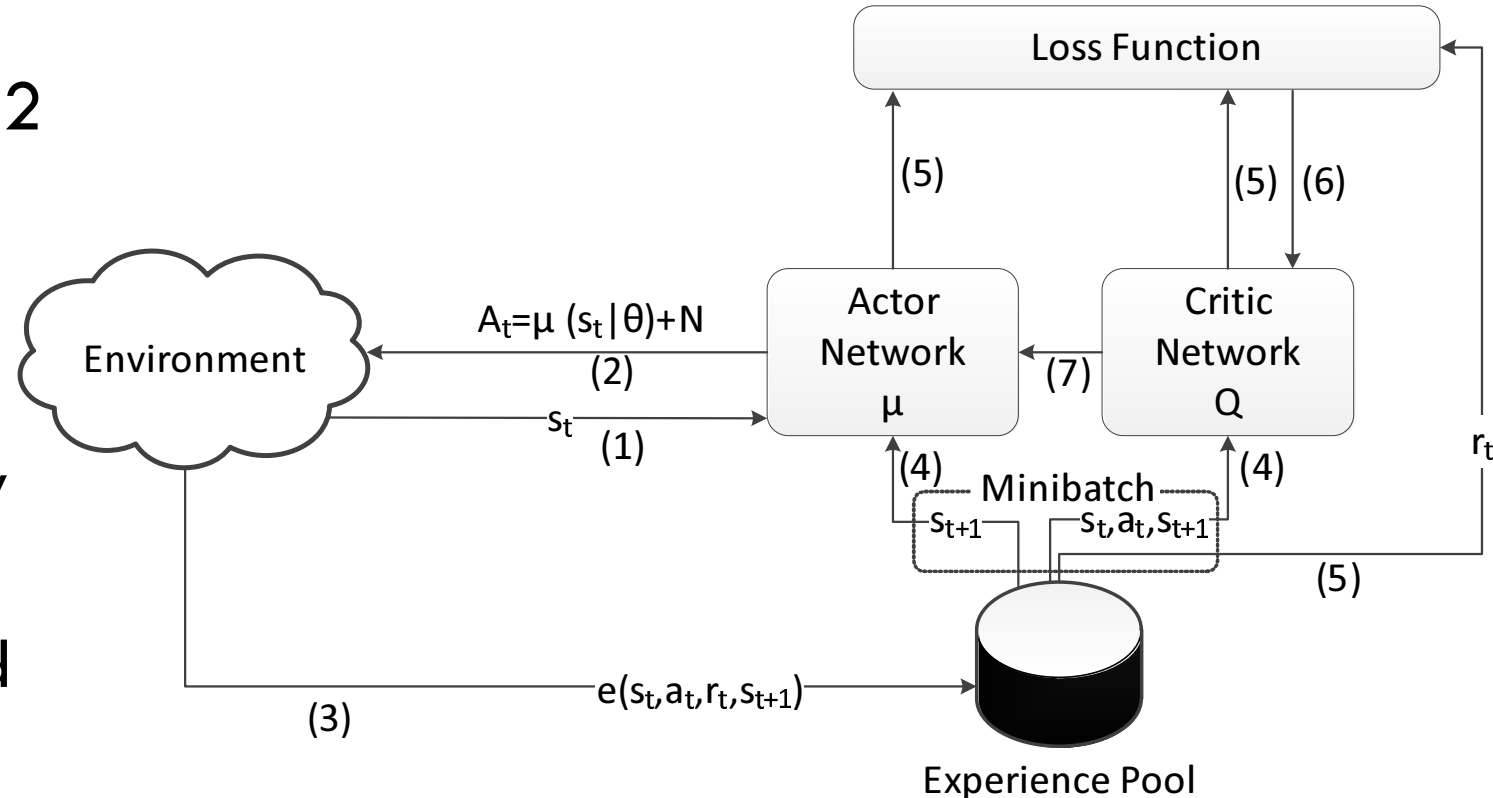
- More robust, and **able to achieve much better scores** on the standard battery of Deep RL tasks

# FOCUS ON DDPG

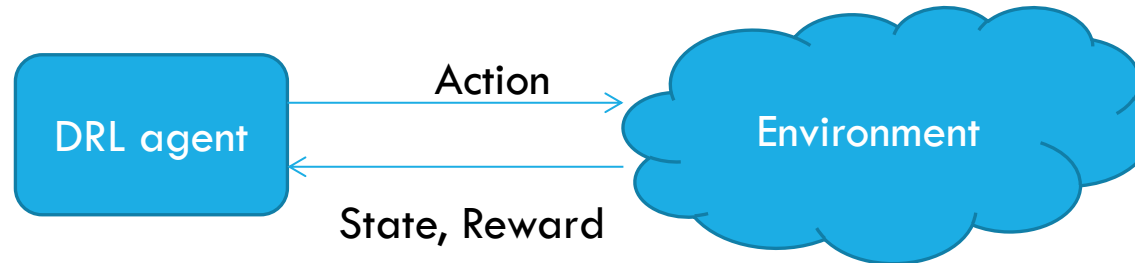
2 neural nets (Actor, Critic) + 2 target nets :

- Critic network learns Value function
  - Based on state + action
- Actor network learns the Policy

The output of the critic drives learning in both the actor and the critic



# APPLYING DDPG FOR NETWORK SLICING



**State:** VNF-FG description  $[U, V]$

$U = [u_{11}, u_{12}, \dots, u_{1K}, \dots, u_{N'1}, u_{N'2}, \dots, u_{N'K}]$ : description of VNFs,  $u_{ij}$ : requirement of  $j^{\text{th}}$  resource of VNF  $i$

$V = [v_{11}, v_{12}, \dots, v_{1H}, \dots, v_{L'1}, \dots, v_{L'H}]$ : description of VLs,  $v_{ij}$ : requirement of  $j^{\text{th}}$  QoS metric of VL  $i$

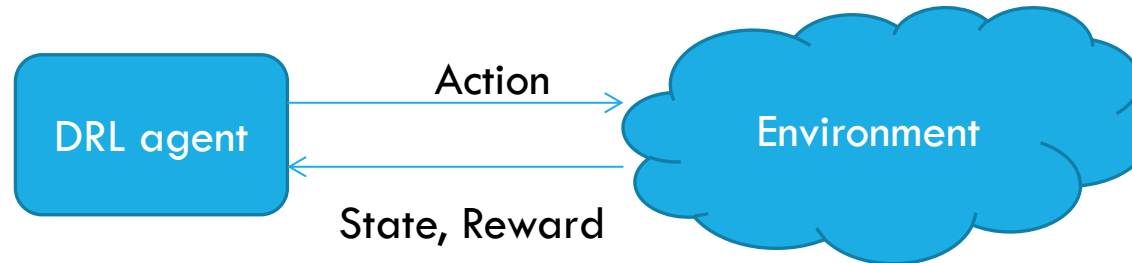
**Action:**  $A = [a_{11}, \dots, a_{1N}, \dots, a_{N'1}, \dots, a_{N'N}, w_{11}, \dots, w_{1L}, \dots, w_{L'1}, \dots, w_{L'L}]$

$a_{ij}$ : metric to select substrate node  $j$  for VNF  $i$

$w_{ij}$ : weight of link  $j$  to determine path for VL  $i$   $\rightarrow$  Each VL has unique routing policy

**Reward:** **Acceptance Rate** =  $(\# \text{ Successful Deployed VNF-FG}) / \# \text{ VNF-FG}$

# APPLYING DDPG FOR NETWORK SLICING



**State:** VNF-FG description  $[U, V]$

$U = [u_{11}, u_{12}, \dots, u_{1K}, \dots]$

$V = [v_{11}, v_{12}, \dots, v_{1H}, \dots]$

**Action:**  $A = [a_{11}, \dots]$

$a_{ij}$ : metric to select  $s$

$w_{ij}$ : weight of link  $j$

## Characteristics

- **Large action space**
- For VNF mapping: from  $a_{ij}$  select one substrate node to host the VNF
- For VL mapping: from  $w_{ij}$  select a set of links connecting 2 VNFs

ce of VNF  $i$   
f VL  $l$

**Reward:** **Acceptance Rate** =  $(\# \text{ Successful Deployed VNF-FG}) / \# \text{ VNF-FG}$

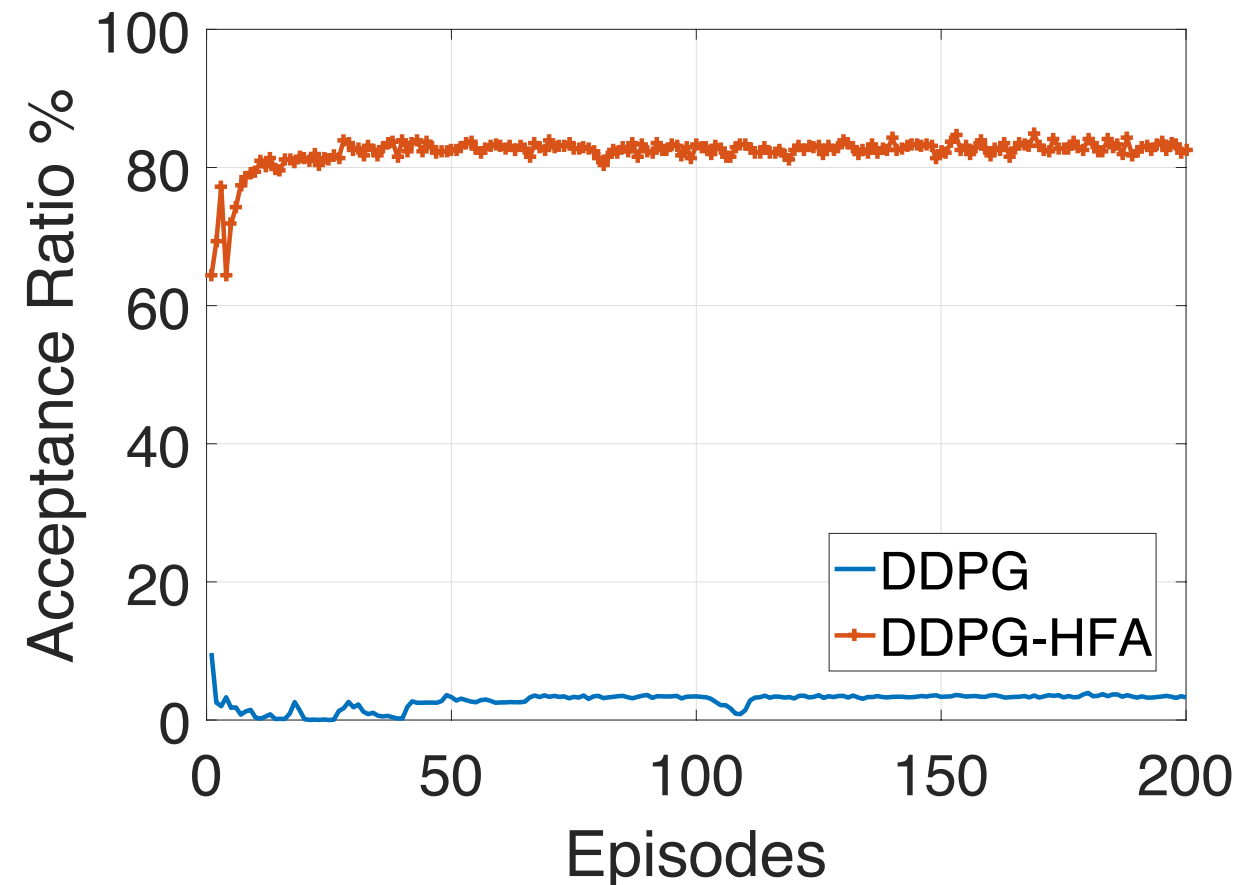


# RESULTS ON THE APPLICATION OF DDPG

- The vanilla DDPG is **not suitable** for **very large-scale discrete action space**
- In VNF-FG embedding problem, there are constraints of resources such that **some discrete actions are not feasible**.

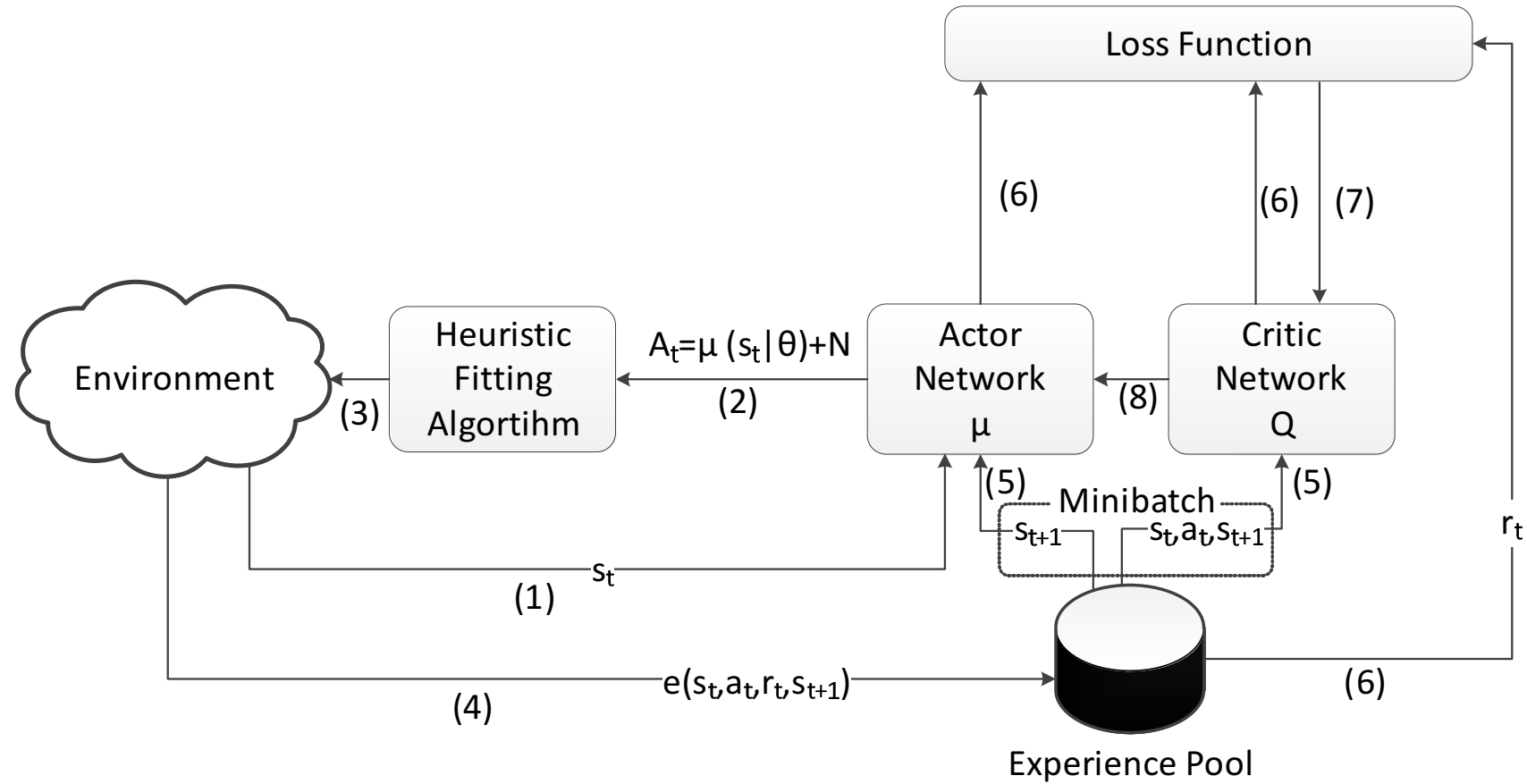


Proposing to add to DDPG a **Heuristic Fitting Algorithm (HFA)**



# DDPG-HFA

HFA allows **improving the Reward**



# IMPROVING EXPLORATION WITH EEDDPG

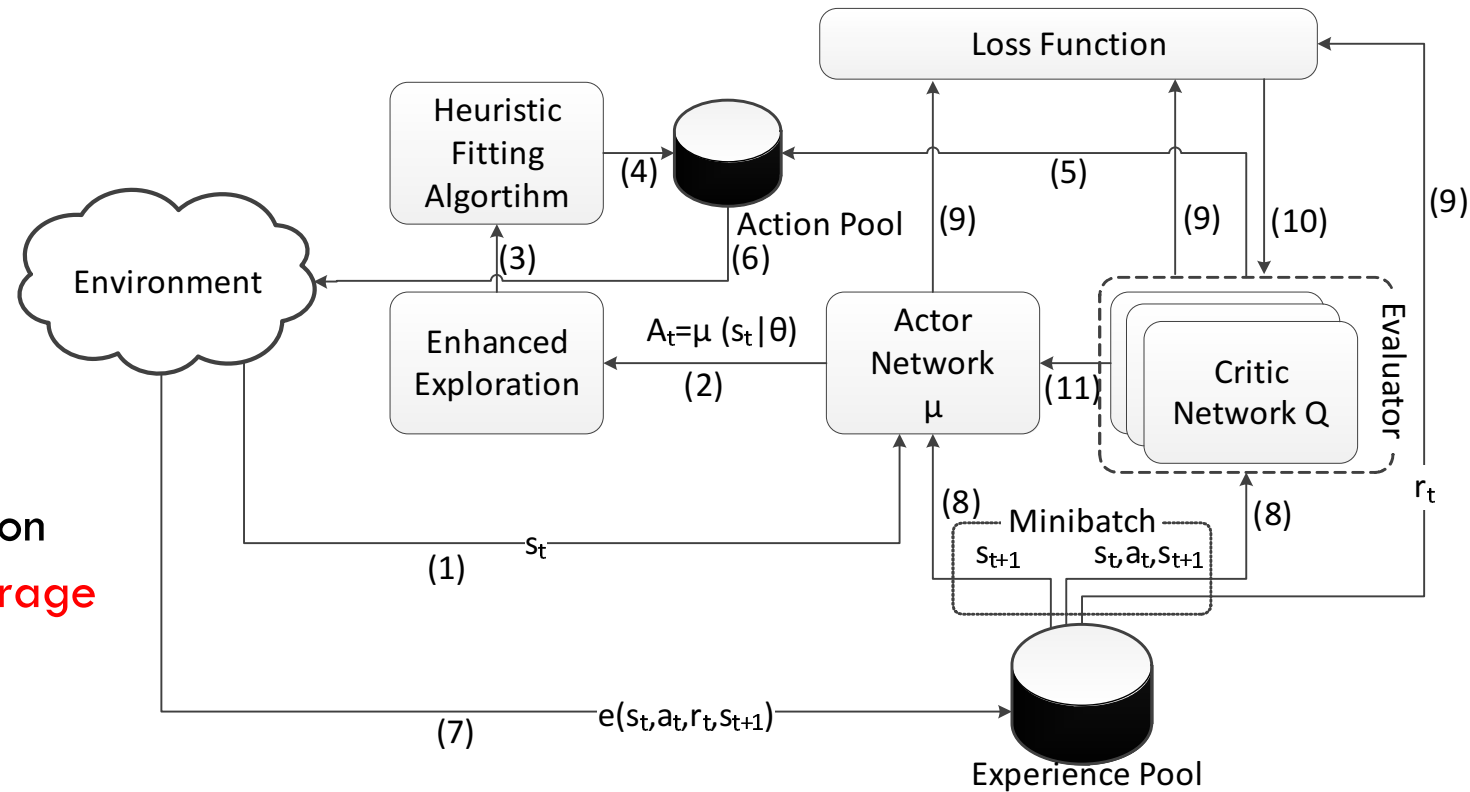
- **Noise** is added to the proto-action to create **H noisy actions**.
  - Each proto action is fed into **HFA** in order to **determine the feasible allocation of VNFs**.

## Evaluation:

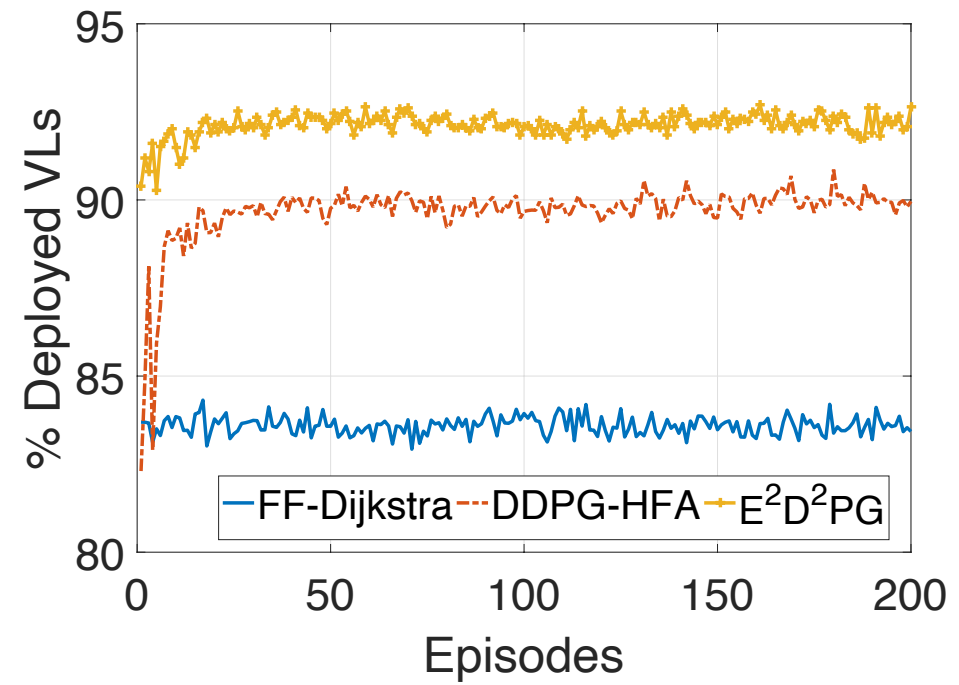
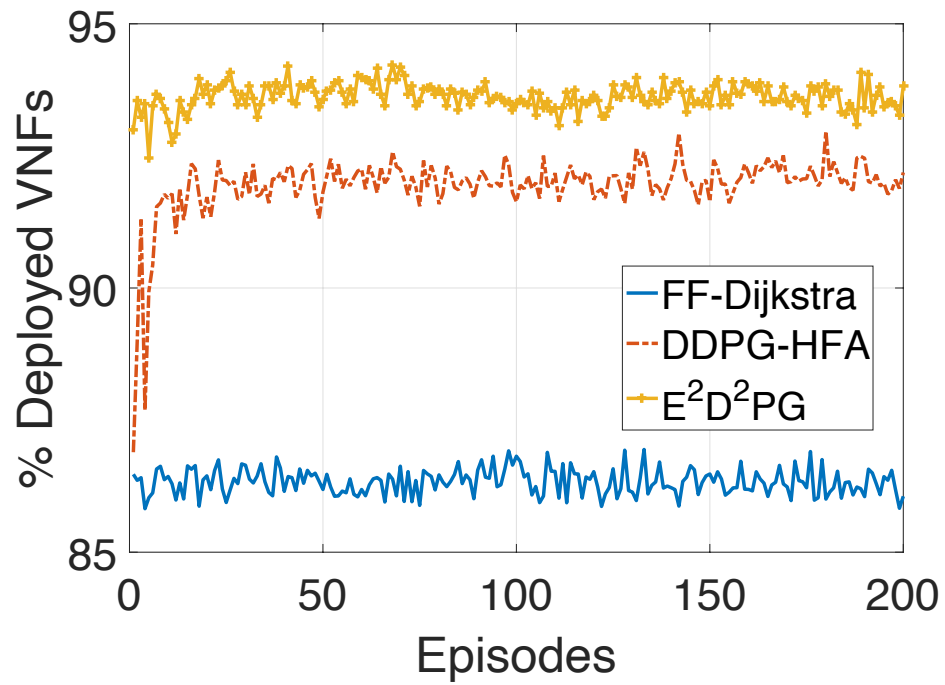
- **Multi-critic**
  - Different nets due to the arbitrary initialization
  - The **best action identified (best Q value/average Q value)** by the evaluator will be executed

## Updates of actor:

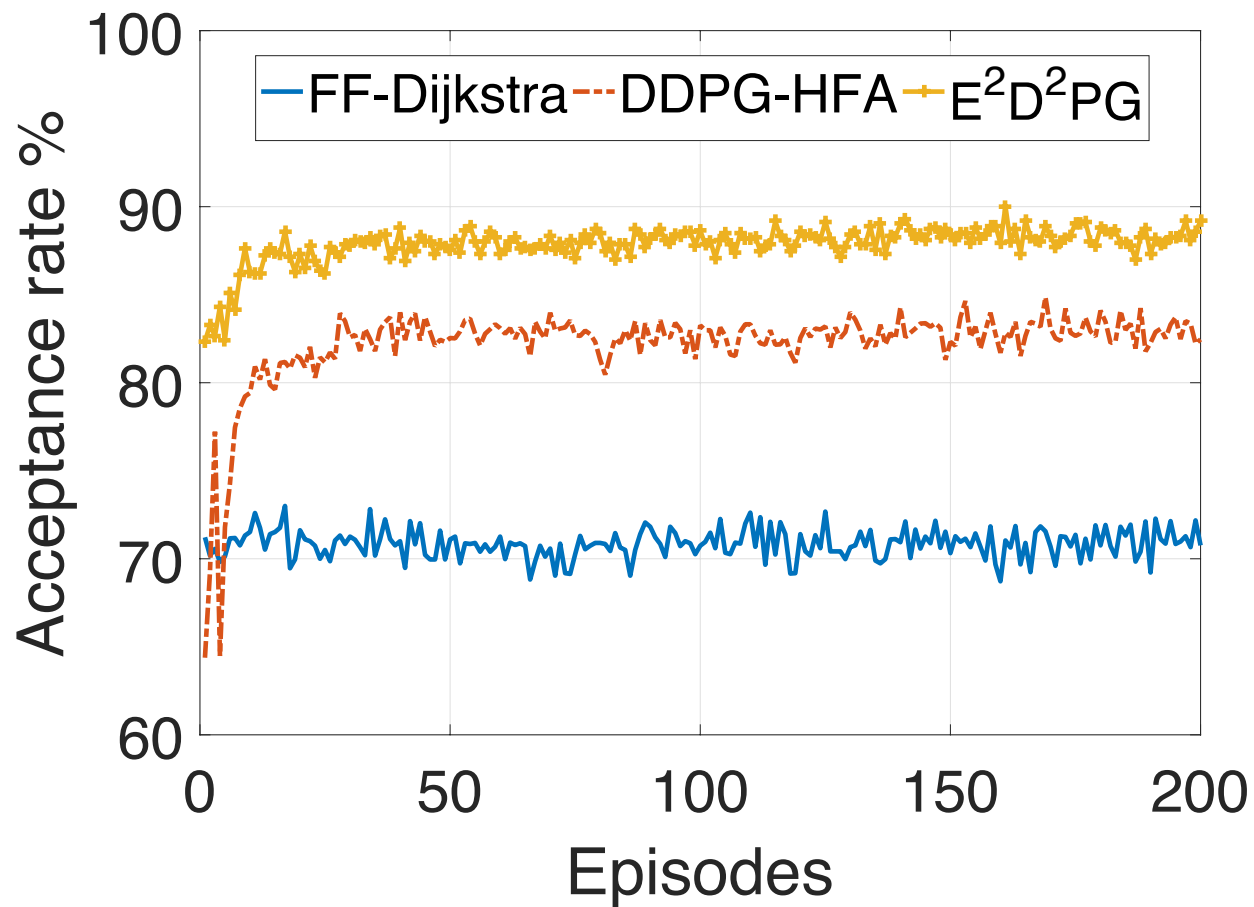
- Best critic network



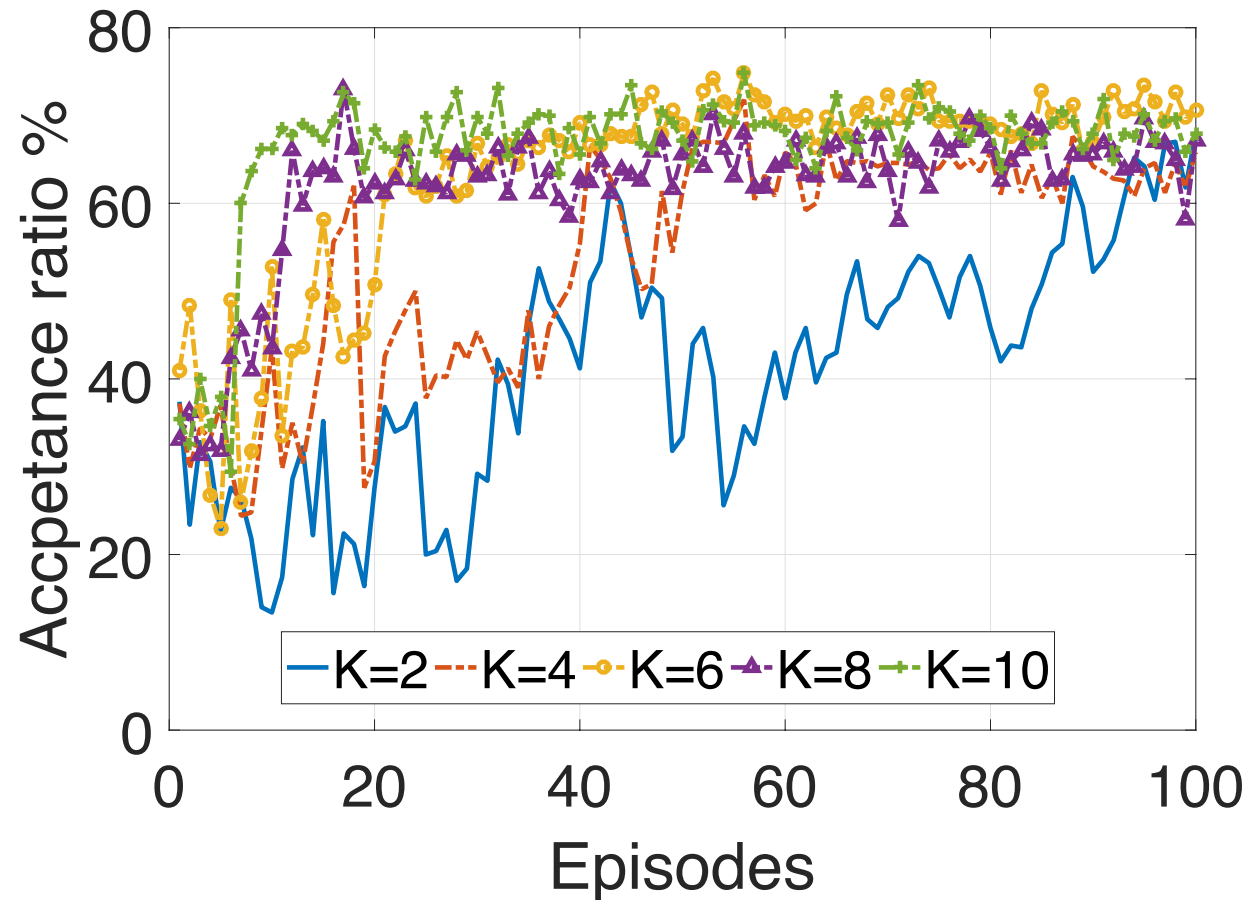
# RESULTS ON THE APPLICATION OF EDDPG (1)



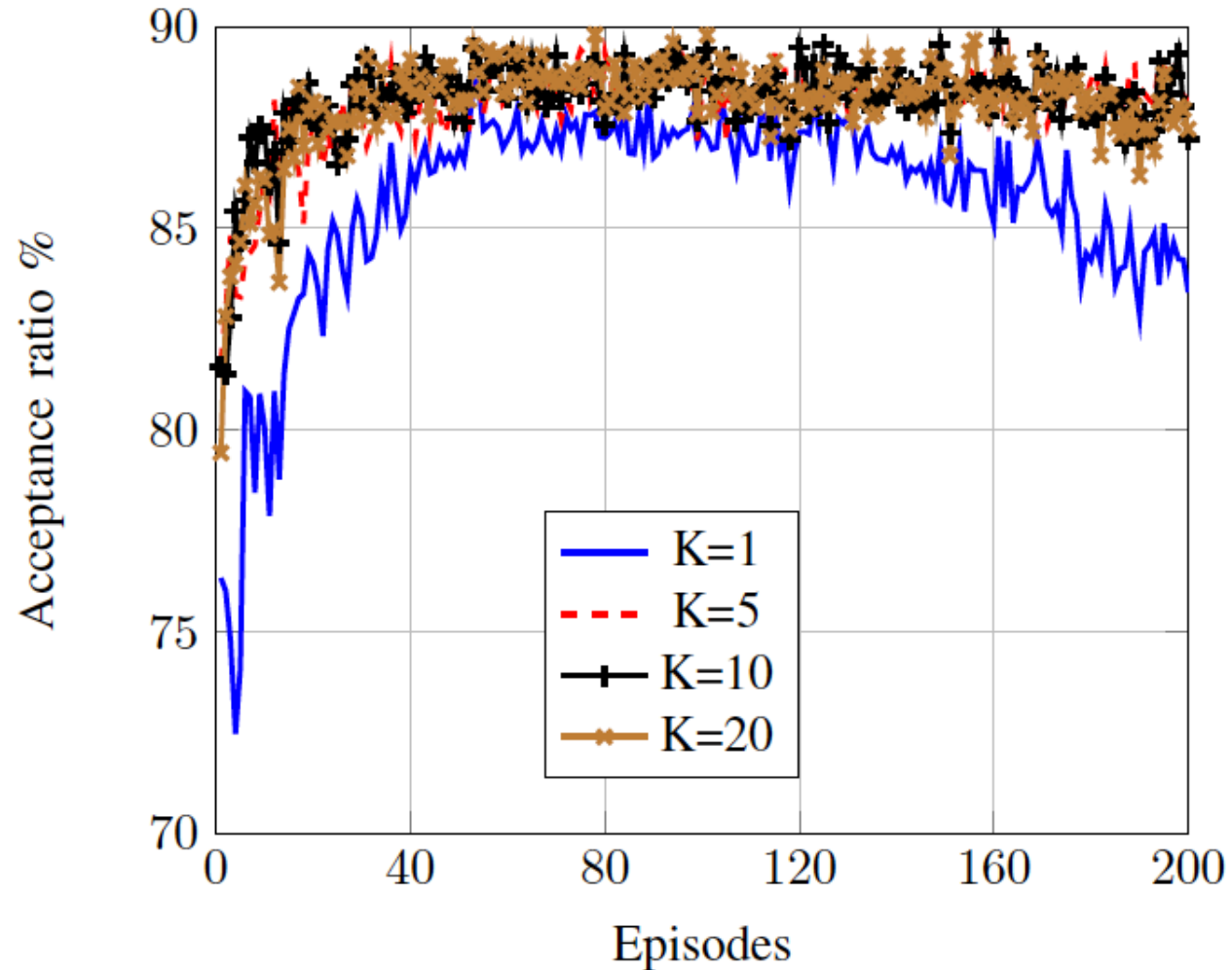
# RESULTS ON THE APPLICATION OF EDDPG (2)



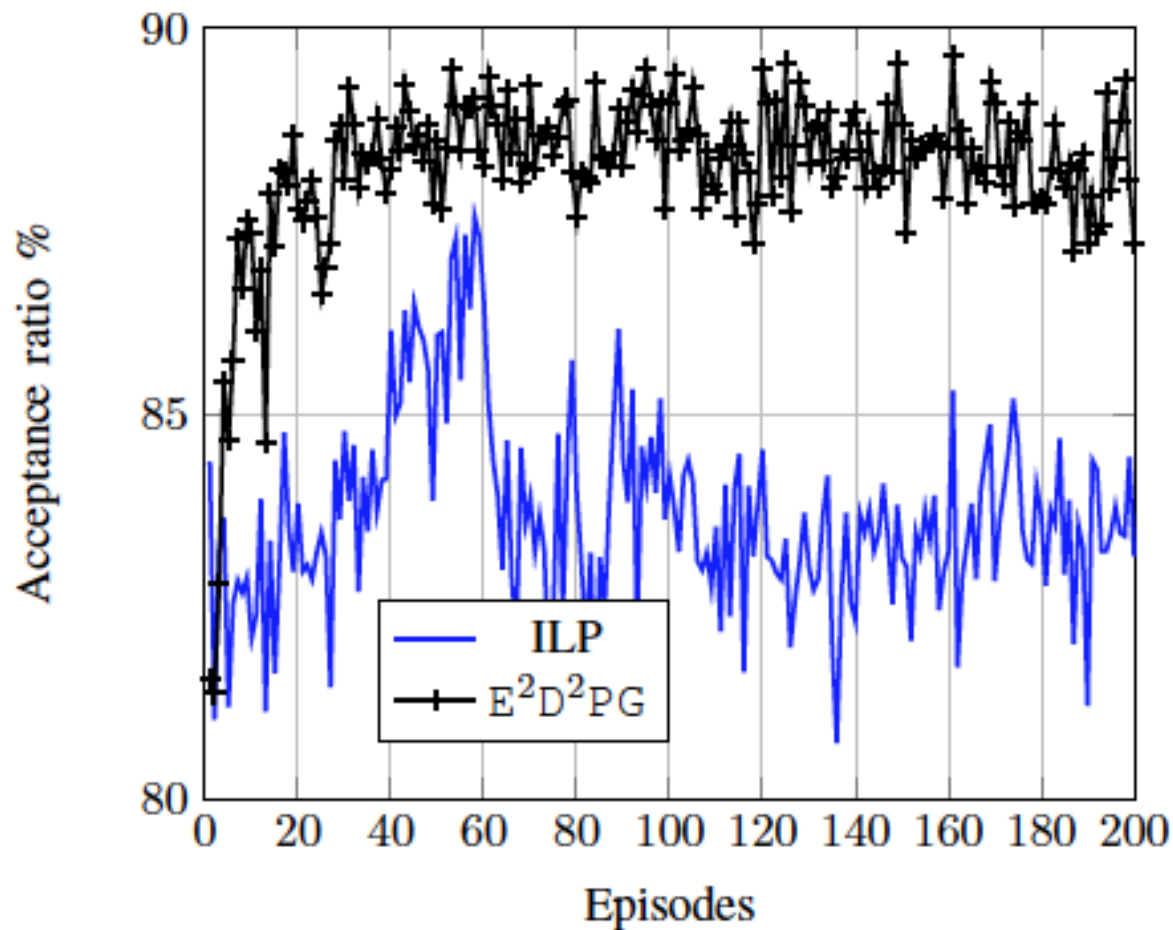
# IMPACT OF THE NUMBER OF FULLY CONNECTED LAYERS



# IMPACT OF THE NUMBER OF CRITIC NETS

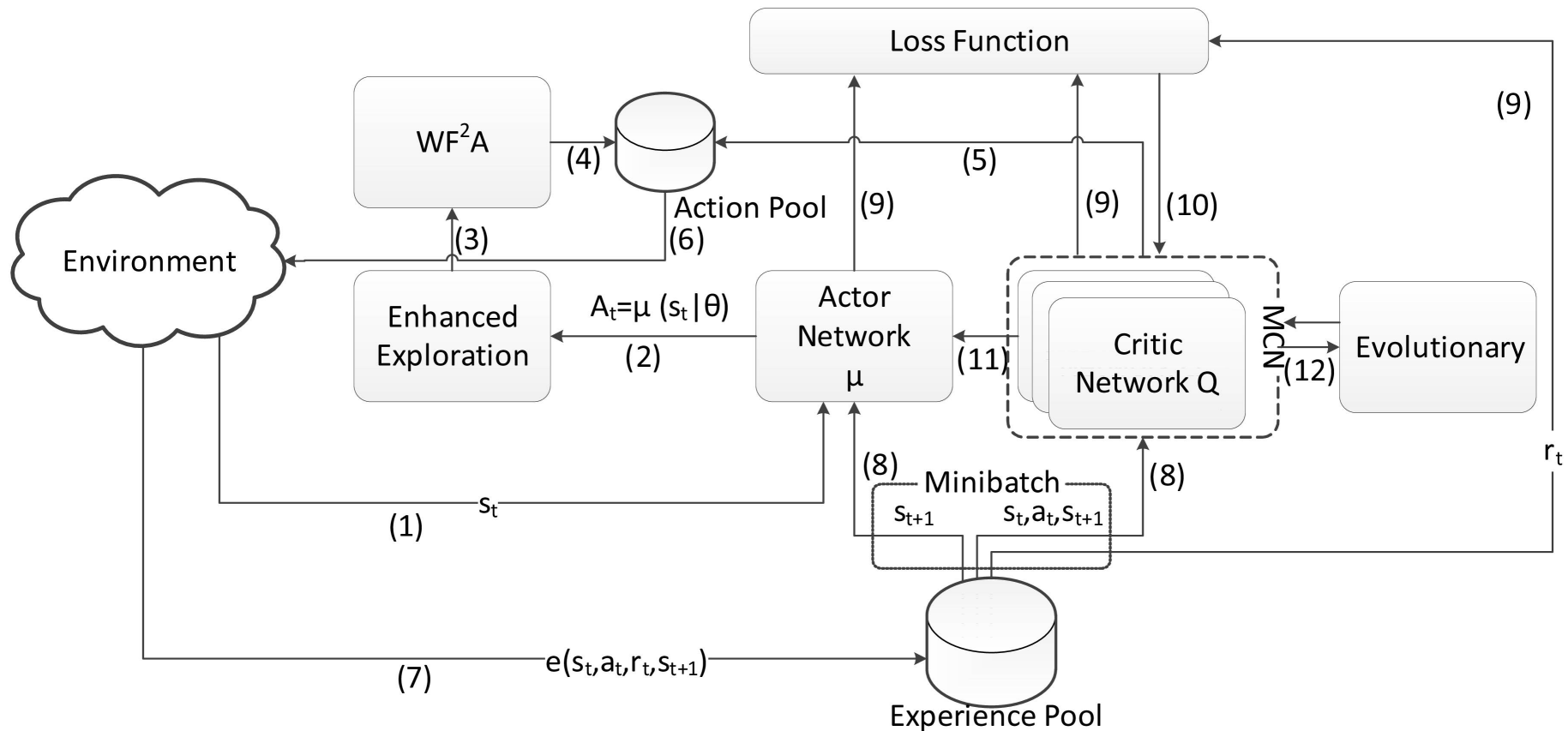


# RESULTS ON THE APPLICATION OF EDDPG (3)





# EVOLUTIONARY ACTOR-MULTI-CRITIC MODEL



# WEIGHTED FIRST FIT ALGORITHM (WF2A)(\*)

## For VNF embedding:

**Step 1:** Sort substrate nodes in terms of their weights

**Step 2:** Attempt deploying VNF at the lowest weight substrate node

If the substrate node can host the VNF

**Step 3a:** Update remaining resources of the substrate node

If the substrate node cannot host the VNF:

**Step 3b:** Remove that node from the selection process and back to step 2

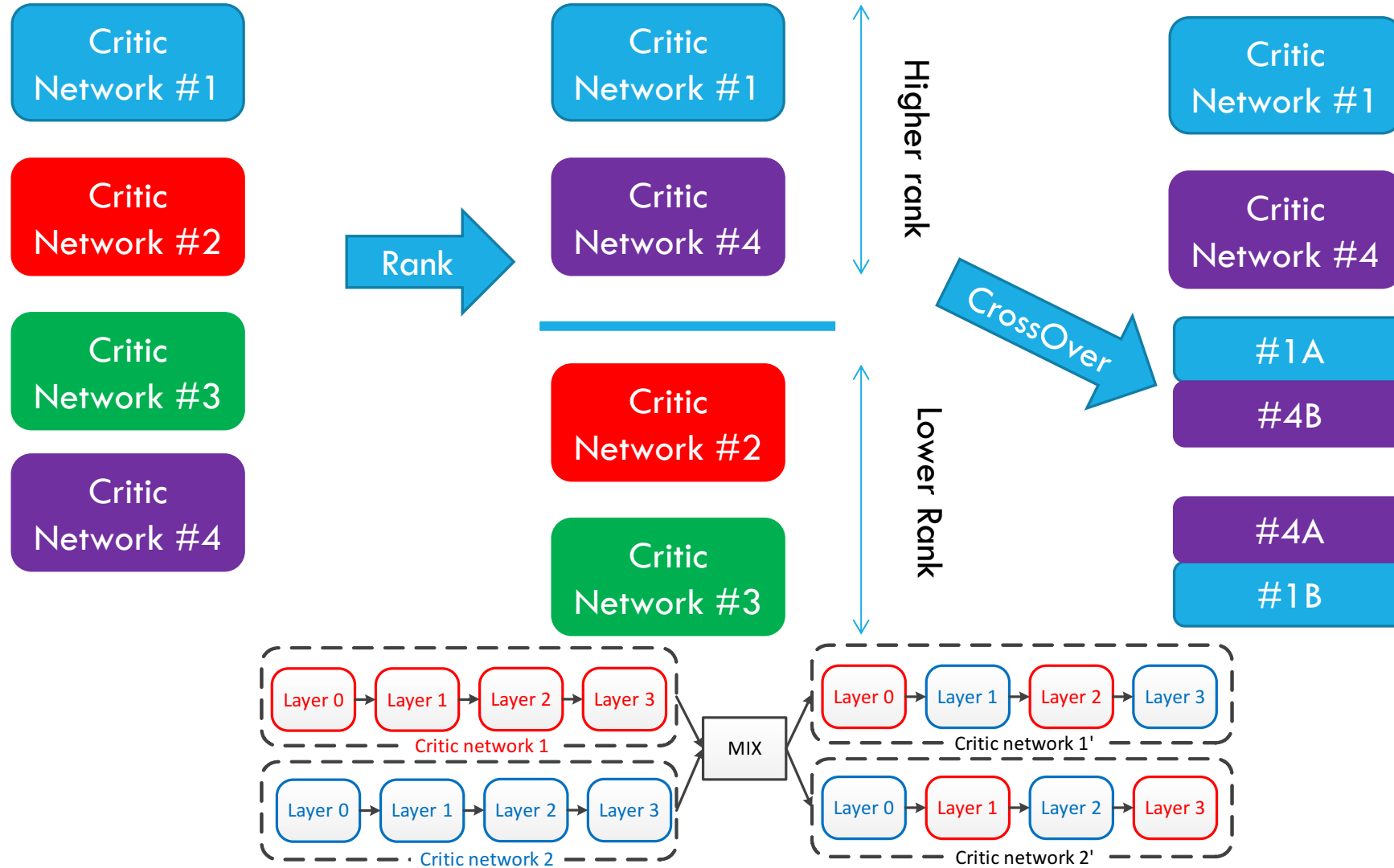
## For VL embedding:

Use Dijkstra algorithm to identify the lowest cost path to connect VNFs

## Final allocation decision

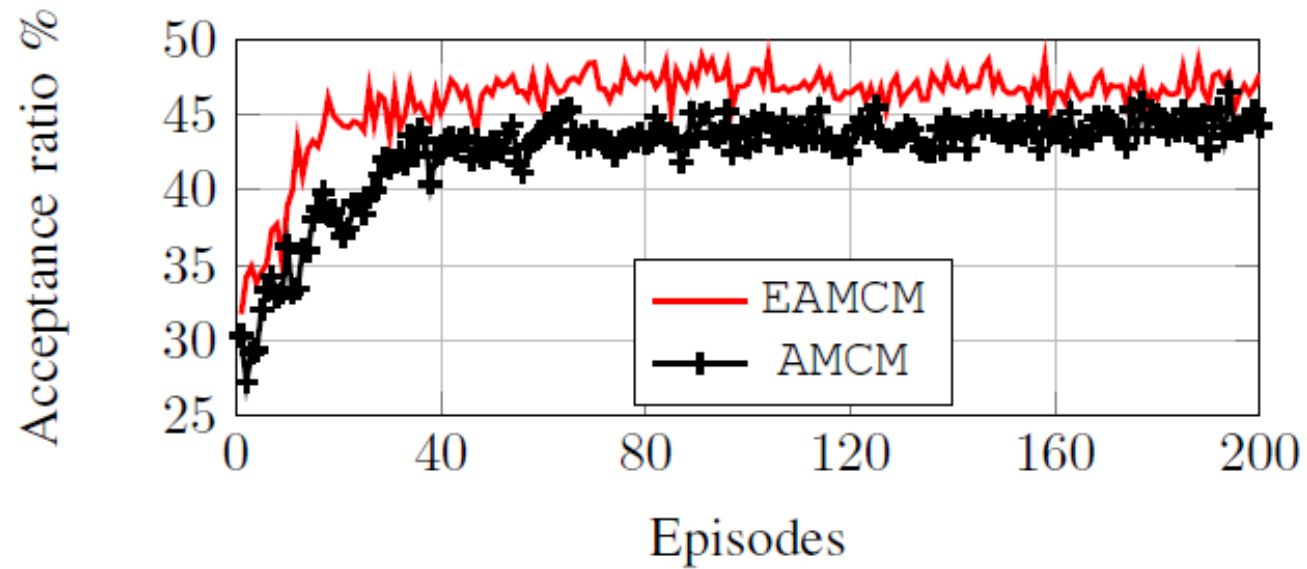
(\*) P. T. A. Quang, Y. Hadjadj-Aoul and A. Outtagarts, "A Deep Reinforcement Learning Approach for VNF Forwarding Graph Embedding," in *IEEE Transactions on Network and Service Management*, vol. 16, no. 4, pp. 1318-1331, Dec. 2019.

# EVOLUTIONARY ACTOR-MULTI-CRITIC MODEL



# SOME RESULTS

EAMCM: Evolutionary Actor-Multi-Critic Model



# ENVIRONMENT

## Simulated environment

- Python, Tensorflow, Keras
- OMNET++
- REST interfaces

## Emulated environment

- Python, Tensorflow, Keras
- MININET (ContainedNet - Docker)
- Orchestrator + SDN
- REST interfaces

# CONCLUSIONS

DRL are very efficient in addressing the targeted issue

Considering resources variation between episodes (ongoing work)

Lack of explainability

- DNN are inherently black boxes.
- We don't know:
  - When it will work, when it will fail
  - No guarantees

Efforts are still needed ...