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A forward-backward probabilistic algorithm for the incompressible Navier-Stokes equations

Antoine Lejay*

Hernán Mardones González†

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Abstract

We study a probabilistic numerical scheme to solve the incompressible Navier-Stokes equations, in which we approximate a generalized nonlinear Feynman-Kac formula. The velocity field is interpreted as the mean value of a stochastic process ruled by Forward-Backward Stochastic Differential Equations (FBSDEs). Using a representation by Delbaen, Qiu and Tang introduced in 2015, the pressure term is obtained from the velocity by solving a Poisson problem as the expectation of an integral functional associated to an extra BSDE. The FBSDEs components are numerically solved by following a forward-backward algorithm based on Euler type schemes for the local time integration and the quantization of the increments of Brownian motion following the algorithm proposed by Delarue and Menozzi in 2006. Numerical results are reported on spatially periodic analytic solutions of the Navier-Stokes equations for incompressible fluids. We illustrate the proposed algorithm on a two dimensional Taylor-Green vortex and three dimensional Beltrami flows.

Keywords: Navier-Stokes equations • Brownian motion • Feynman-Kac formula • forward-backward stochastic differential equations • incompressible fluids • numerical solution

1 Introduction

The Navier-Stokes equations system allows us to model the movement of fluids. It was introduced by C.-L. Navier in 1822 [1] and G. G. Stokes in 1849 [2] by incorporating a pressure term and the fluid viscosity to the Euler equations due to L. Euler in 1757 [3]. Nowadays, technological and scientific computing developments provide a suitable way for the simulation of mathematical models, and in turn research and analysis of efficient numerical methodologies to approximate exact solutions. With this in mind, we study the numerical simulation of the Navier-Stokes equations for incompressible fluids in \mathbb{R}^d (for space dimension $d \in \{2, 3\}$)

$$\begin{cases} \frac{\partial u}{\partial t} + (u \cdot \nabla) u = \nu \Delta u - \nabla p + f; & 0 < t \leq T, \\ \nabla \cdot u = 0, & u(0) = g, \end{cases} \quad (1)$$

where $T > 0$ is a fixed time, $\nu > 0$ is the kinematic viscosity, f is the external force field and g is a given initial divergence-free vector field. The system of equations (1) describes

*Université de Lorraine, CNRS, Inria, IECL, F-54000 Nancy, France; antoine.lejay@univ-lorraine.fr

†Universidad de La Serena, Facultad de Ciencias, Departamento de Matemáticas, La Serena, Chile; hmardo@gmail.com

the motion of an incompressible fluid by means of unknown fields of velocity $u(t, x) \in \mathbb{R}^d$ and pressure $p(t, x) \in \mathbb{R}$ defined for each time $t \in [0, T]$ and position $x \in \mathbb{R}^d$. It involves a nonlinear convective term $(u \cdot \nabla)u$, a diffusion term $\nu \Delta u$ and the incompressibility condition $\nabla \cdot u = 0$. Although being introduced in the nineteenth century, there are still open problems concerning the Navier-Stokes equations. Nonetheless it is usual to find works that deal with the fluid dynamics using the Navier-Stokes model (ocean modelling, atmosphere of Earth, gas dynamics, dynamic of storms, etc.) [4, 5, 6, 7].

The Itô stochastic differential equations (SDEs) introduced during the 1940s by K. Itô's seminal works [8, 9] are connected with partial differential equations (PDEs) by means of the celebrated Feynman-Kac formula due to R. Feynman [10] and M. Kac [11]. More recently, the theory of backward stochastic differential equations (BSDEs), initiated by É. Pardoux and S. Peng in [12], permits to obtain probabilistic representations for the solutions of a broad class of PDEs by means of systems of forward-backward SDEs (FBSDEs) through a nonlinear Feynman-Kac formula. Hence, the numerical solution of FBSDEs provides a stochastic algorithm to approximate solutions of nonlinear PDEs. Among the theory of SDEs, FBSDEs associated to the unsteady Navier-Stokes equations is a novel approach.

Let us assume that the solution u of (1) is known on a time interval $[0, T]$, which means that the pressure term p is also known (the force field f is considered as given). We define by X the d -dimensional diffusion process associated to the differential operator $u \rightarrow (u \cdot \nabla)u + \nu \Delta u$. With $Y_s := -u(T - s, X_s)$ and $Z_s := -Du(T - s, X_s)$, the process (X, Y, Z) is solution to the FBSDEs

$$\begin{cases} X_s = x + \int_t^s Y_r dr + \int_t^s \sqrt{2\nu} dW_r, \\ Y_s = -g(X_T) + \int_s^T [\nabla p(T - r, X_r) - f(T - r, X_r)] dr - \int_s^T \sqrt{2\nu} Z_r dW_r, \end{cases} \quad (2)$$

where W_s is a d -dimensional standard Brownian motion. The numerical solution of the incompressible Navier-Stokes equations (1) involves various difficulties due to the presence of a nonlinear term, the incompressibility condition as well as the computation of the pressure term. The simplified model obtained by removing the pressure term from the FBSDEs (2) is associated to the Burgers equation [13], which remains a nonlinear equation due to the term $(u \cdot \nabla)u$. Under appropriate conditions, the pressure term p is given by solving a Poisson problem $-\Delta p = \mathcal{P}(u)$ for a given functional of the solution.

Recently F. Delbaen, J. Qiu and S. Tang introduced in [14] a new class of coupled FBSDEs associated to the incompressible Navier-Stokes equations. Since their probabilistic approach involves an extra BSDE defined on an infinite time interval for the stochastic representation of the pressure term, Delbaen *et al.* deduced an approximated solution to the velocity field by truncating the infinite interval of the associated FBSDEs system. Hence they proposed a numerical simulation algorithm, that follows a methodology of F. Delarue and S. Menozzi [15, 16] for FBSDEs, to simulate the incompressible Navier-Stokes equations in the whole Cartesian space.

Specialized literature on probabilistic representations to the solution of PDEs is presented through Feynman-Kac formulae or well by means of branching processes. In general, the deterministic solutions of particular equations are obtained through the expectation of functionals of stochastic processes. During the last years some probabilistic approaches have been proposed to deal with the Navier-Stokes equations. The random vortex methods study the incompressible Navier-Stokes system in vorticity form [17, 18, 19]. Branching processes and stochastic cascades present another way of interpretation [20, 21, 22, 23, 24]. The stochastic Lagrangian paths provide additional representations [25, 26, 27]. Moreover, stochastic particle systems arise from the McKean-Vlasov equations in both two and three dimensional contexts [28, 29, 30]. Recently the systems of FBSDEs appear as a novel approach [31, 14]. The problem of relating boundary conditions on probabilistic representations presents additional challenges [32, 33, 34, 35].

Our motivation is to develop a suitable numerical framework based on the new representation of Delbaen *et al* to solve the incompressible Navier-Stokes equation (1) in 2 and 3 spatial dimensions. By considering the numerical solution associated to the system of FBSDEs and their approximation by mean values, we consider a backward regression based on the Euler-Maruyama scheme and the quantization method. The pressure gradient is recovered from the expected value of an integral functional of Brownian motion. To do this, we use the Riemann sum estimation and the quantization of the Brownian increments. We test the performance of the novel algorithm to the simulation of spatially-periodic solutions.

Outline

Section 2 details the link between FBSDEs driven by Brownian motion and deterministic PDEs through the nonlinear Feynman-Kac formula. The incompressible Navier-Stokes equations are associated to the novel FBSDEs system. Section 3 presents the numerical methodology to solve FBSDEs. We detail the approximation of mean values and the numerical treatment of integral functionals of Brownian motion. Section 4 illustrates the proposed probabilistic methodology by solving a two-dimensional Taylor-Green vortex and three-dimensional Beltrami flows as numerical examples. Finally Section 5 is devoted to concluding remarks.

Notations

We use the following notations and conventions:

- We consider a filtered complete probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$.
- For each $q \geq 1$, we set

$$L^q_{\mathcal{F}}(\Omega; \mathbb{R}^d) := \{\xi : \Omega \rightarrow \mathbb{R}^d : \xi \text{ is } \mathcal{F}\text{-measurable and } \mathbb{E} \|\xi\|^q < \infty\}.$$

- For each $m, n \in \mathbb{Z}_+$ and $A \in \mathbb{R}^{m \times n}$, we denote by A^\top its transpose matrix while I_m represents the $m \times m$ identity matrix. The matrix $A \in \mathbb{R}^{n \times n}$ is said to be *elliptic* if there exists $\lambda > 0$ such that

$$\langle x, Ax \rangle \geq \lambda \|x\|^2; \quad \forall x \in \mathbb{R}^n.$$

The set of $m \times m$ real valued symmetric non-negative matrices is

$$\mathbb{S}_+^m := \{Q \in \mathbb{R}^{m \times m} : Q = Q^\top \text{ and } \langle x, Qx \rangle \geq 0; \quad \forall x \in \mathbb{R}^m\}.$$

- The symbol “ \approx ” means “is numerically approximated by”.
- The symbol \mathcal{O} means the order of estimation. For example, $h = \mathcal{O}(\delta^2)$ means that $h > 0$ is depending on $\delta > 0$ and less than $K\delta^2$, with constant K independent of δ . From now on $K > 0$ stands for constants independent on the discretization parameters.
- The indicator function of a set A is $\mathbf{1}_A$.
- In general, we use the Einstein summation convention through this paper.
- The space $C^{k, \alpha}(\mathbb{R}^d, \mathbb{R}^n)$, or simply as $C^{k, \alpha}$, of k -continuously differentiable functions $\phi : \mathbb{R}^d \rightarrow \mathbb{R}^n$ with α Hölder continuity for each k -order partial derivatives equipped with the norm

$$\|\phi\|_{C^{k, \alpha}} := \sup_{x \in \mathbb{R}^d} \|\phi(x)\| + \sum_{|\beta|=1}^k \sup_{x \in \mathbb{R}^d} \|D^\beta \phi(x)\| + \sum_{|\beta|=k} \sup_{x, y \in \mathbb{R}^d, x \neq y} \frac{\|D^\beta \phi(x) - D^\beta \phi(y)\|}{\|x - y\|^\alpha}.$$

The multi-index notation is considered.

- For $T > 0$ and $t \in [0, T]$ we denote by $C([t, T]; \mathbb{R}^{m \times n})$ the space of continuous functions ψ with norm

$$\|\psi\|_{C([t, T]; \mathbb{R}^{m \times n})} := \sup_{s \in [t, T]} \|\psi(s)\|.$$

Similarly we have the space $C([t, T]; C^{k, \alpha})$ of continuous functions with

$$\|\psi\|_{C([t, T]; C^{k, \alpha})} := \sup_{s \in [t, T]} \|\psi(s)\|_{C^{k, \alpha}}.$$

- Let $L^2_{\mathcal{F}}(\Omega; C([t, T]; \mathbb{R}^{m \times n}))$ be the set of all $\{\mathcal{F}_t\}_{t \geq 0}$ -progressively measurable stochastic processes Ψ with continuous trajectories taking values in $\mathbb{R}^{m \times n}$ such that

$$\mathbb{E} \sup_{s \in [t, T]} \|\Psi_s\|^2 < \infty.$$

- For $m \in \mathbb{N}$ and $q \in [1, \infty)$ we denote by $L^q(\mathbb{R}^\ell)$ and $H^{m, q}(\mathbb{R}^\ell)$ the usual \mathbb{R}^ℓ -valued Lebesgue and Sobolev spaces on \mathbb{R}^d , respectively. When $\ell = d$ we just write L^q and $H^{m, q}$, or H^m when $q = 2$.
- The space H^m_σ is the completion of $\{\phi \in C^\infty_c(\mathbb{R}^d) : \operatorname{div} \phi = 0\}$ under the norm

$$\|\phi\|_{H^m_\sigma} := \sup_{x \in \mathbb{R}^d} \|\phi(x)\| + \sum_{|\beta|=1}^m \sup_{x \in \mathbb{R}^d} \|D^\beta \phi(x)\|.$$

The space $C([0, T]; H^m_\sigma)$ of continuous functions ψ is equipped with

$$\|\psi\|_{C([0, T]; H^m_\sigma)} := \sup_{s \in [0, T]} \|\psi(s)\|_{H^m_\sigma}.$$

2 Forward-backward stochastic differential equations

Diffusion processes are linked to PDEs through the celebrated Feynman-Kac formula. The theory of Itô SDEs together Backward SDEs constitute systems of FBSDEs that are connected with deterministic nonlinear PDEs through a nonlinear Feynman-Kac formula, generalizing the classical Feynman-Kac formula (see *e.g.* [36, 37, 38]).

Let $T > 0$, $t \in [0, T]$ and $x \in \mathbb{R}^d$ be fixed. Consider the FBSDEs on $[t, T]$ of the form

$$\begin{cases} X_s = x + \int_t^s b(r, X_r, Y_r, Z_r) dr + \int_t^s \sigma(r, X_r, Y_r) dW_r, \\ Y_s = g(X_T) + \int_s^T h(r, X_r, Y_r, Z_r) dr - \int_s^T Z_r dW_r, \end{cases} \quad (3)$$

where $b : [0, T] \times \mathbb{R}^d \times \mathbb{R}^n \times \mathbb{R}^{n \times m} \rightarrow \mathbb{R}^d$, $\sigma : [0, T] \times \mathbb{R}^d \times \mathbb{R}^n \rightarrow \mathbb{R}^{d \times m}$, $g : \mathbb{R}^d \rightarrow \mathbb{R}^n$, $h : [0, T] \times \mathbb{R}^d \times \mathbb{R}^n \times \mathbb{R}^{n \times m} \rightarrow \mathbb{R}^n$ are given and $W = (W^1, \dots, W^m)^\top$ is a m -dimensional Wiener process defined on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$. An adapted solution of the FBSDEs (3) is defined by a triple of processes

$$(X, Y, Z) \in L^2_{\mathcal{F}}(\Omega; C([t, T]; \mathbb{R}^d)) \times L^2_{\mathcal{F}}(\Omega; C([t, T]; \mathbb{R}^n)) \times L^2_{\mathcal{F}}(\Omega; C([t, T]; \mathbb{R}^{n \times m}))$$

that satisfies (3) \mathbb{P} -almost surely. The BSDE in the system (3) depends on the diffusion process X that solves the *forward* SDE. When the coefficients of the diffusion process X do not depend on Y nor Z , (3) is referred as a *decoupled* FBSDEs. Otherwise we have a *coupled* FBSDEs. From now on, we denote by $(X^{t, x}, Y^{t, x}, Z^{t, x})$ to recall the dependence on the parameters $(t, x) \in [0, T] \times \mathbb{R}^d$. We refer for example to [39, 40] for the classic theory of FBSDEs.

2.1 Nonlinear Feynman-Kac formula

As in the spirit of the Feynman-Kac formula, it is possible to obtain a probabilistic representation for the solution $u = (u_1, \dots, u_n)^\top : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^n$ of the backward quasilinear PDE

$$\begin{cases} \frac{\partial u}{\partial t}(t, x) + \mathcal{L}(t, x, u(t, x)) + h(t, x, u(t, x), Du(t, x) \sigma(t, x, u(t, x))) = 0 & ; \forall (t, x) \in [0, T] \times \mathbb{R}^d, \\ u(T, x) = g(x) & ; \forall x \in \mathbb{R}^d, \end{cases} \quad (4)$$

where $Du = \left(\frac{\partial u_i}{\partial x_j} \right)_{i,j}$, with $i \in \{1, \dots, n\}, j \in \{1, \dots, d\}$, and Itô diffusion generator

$$\mathcal{L}(t, x, u) := \begin{pmatrix} L(t, x, u, Du_1, D^2u_1) \\ \vdots \\ L(t, x, u, Du_n, D^2u_n) \end{pmatrix},$$

with $Du_k = \left(\frac{\partial u_k}{\partial x_1}, \dots, \frac{\partial u_k}{\partial x_d} \right)^\top$, $D^2u_k = \left(\frac{\partial^2 u_k}{\partial x_i \partial x_j} \right)_{i,j}$ and

$$L(t, x, u, p, Q) := \frac{1}{2} \text{tr} \{ \sigma \sigma^\top(t, x, u) Q \} + \langle b(t, x, u, Du(t, x) \sigma(t, x, u)), p \rangle,$$

for $p \in \mathbb{R}^d$ and $Q \in \mathbb{S}_+^d$. More precisely, if the FBSDEs (3) admits unique adapted solutions $(X^{t,x}, Y^{t,x}, Z^{t,x})$ on each subintervals $[t, T] \subseteq [0, T]$ then

$$Y_s^{t,x} = u(s, X_s^{t,x}), Z_s^{t,x} = Du(s, X_s^{t,x}) \sigma(s, X_s^{t,x}, Y_s^{t,x}) \quad ; \forall (s, x) \in [t, T] \times \mathbb{R}^d.$$

Therefore, the function $u(t, x) := Y_t^{t,x}$ is a viscosity solution to the associated PDE (4) (see [41]). The relation $u(t, x) = Y_t^{t,x}$ is called the *nonlinear Feynman-Kac formula*.

From now on, we assume that $\sigma \sigma^\top$ is uniformly elliptic *i.e.* the diffusion matrices $\sigma \sigma^\top(t, x, y)$ are elliptic for all $(t, x, y) \in [0, T] \times \mathbb{R}^d \times \mathbb{R}^n$. In particular, when $h(t, x, y, z) = c(t, x)y + f(t, x)$ and $n = 1$, the BSDE in (3) has explicit solution

$$\begin{aligned} Y_s^{t,x} = & \exp \left\{ \int_s^T c(r, X_r^{t,x}) dr \right\} g(X_T^{t,x}) + \int_s^T \exp \left\{ \int_s^r c(\theta, X_\theta^{t,x}) d\theta \right\} f(r, X_r^{t,x}) dr \\ & - \int_s^T \exp \left\{ \int_s^r c(\theta, X_\theta^{t,x}) d\theta \right\} Z_r^{t,x} dW_r. \end{aligned}$$

In this case, the solution $u : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}$ of the concerned PDE (4) can be expressed as $u(t, x) = Y_t^{t,x} = \mathbb{E}(Y_t^{t,x} | X_t = x)$, that is

$$u(t, x) = \mathbb{E} \left[\exp \left\{ \int_t^T c(r, X_r^{t,x}) dr \right\} g(X_T^{t,x}) + \int_t^T \exp \left\{ \int_t^s c(r, X_r^{t,x}) dr \right\} f(s, X_s^{t,x}) ds \right],$$

which corresponds to the well-known Feynman-Kac formula (see *e.g.* [42, 43, 44]).

In the case of the d -dimensional viscous Burgers equation (from now on, we use $\nu/2$ as viscosity instead of ν for the sake of simplicity)

$$\begin{cases} \frac{\partial u}{\partial t} + (u \cdot \nabla) u + \frac{\nu}{2} \Delta u + f = 0 & ; 0 \leq t < T, \\ u(T) = g, \end{cases} \quad (5)$$

where $f : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, $g : \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $\nu > 0$, we can associate the coupled FBSDEs

$$\begin{cases} X_s^{t,x} = x + \int_t^s Y_r^{t,x} dr + \int_t^s \sqrt{\nu} dW_r, \\ Y_s^{t,x} = g(X_T^{t,x}) + \int_s^T f(r, X_r^{t,x}) dr - \int_s^T \sqrt{\nu} Z_r^{t,x} dW_r. \end{cases} \quad (6)$$

Then, $Y_s^{t,x} = u(s, X_s^{t,x})$ and $Z_s^{t,x} = Du(s, X_s^{t,x})$ for all $(s, x) \in [t, T] \times \mathbb{R}^d$ (see *e.g.* Theorem 4.1 in [45]). Alternatively, (5) admits the decoupled FBSDEs representation

$$\begin{cases} X_s^{t,x} = x + \int_t^s \sqrt{\nu} dW_r, \\ Y_s^{t,x} = g(X_T^{t,x}) + \int_s^T \left[f(r, X_r^{t,x}) + \frac{1}{\sqrt{\nu}} Z_r^{t,x} Y_r^{t,x} \right] dr - \int_s^T \sqrt{\nu} Z_r^{t,x} dW_r. \end{cases} \quad (7)$$

In the coupled FBSDEs (6) the process $Z^{t,x}$ can be removed by considering the conditional expectation $\mathbb{E}(\cdot \mid X_t^{t,x} = x)$, so that it is not necessary to compute it in order to estimate $Y^{t,x}$. This is an advantage compared to the decoupled representation (7) if we only are interested in the estimation of the process $Y_s^{t,x}$ without information about $Z_s^{t,x}$.

2.2 The Incompressible Navier-Stokes equations

From now on, by abuse of notation, we consider the backward Navier-Stokes equations for incompressible fluids in \mathbb{R}^d , for $d \in \{2, 3\}$,

$$\begin{cases} \frac{\partial u}{\partial t} + (u \cdot \nabla) u + \frac{\nu}{2} \Delta u + \nabla p + f = 0 & ; 0 \leq t < T, \\ \nabla \cdot u = 0, \quad u(T) = g, \end{cases} \quad (8)$$

which is equivalent to the classical formulation (1) by a time-reversing transformation (still with $\nu/2$ as viscosity). The Burgers equation (5) can be seen as a simplified version of the incompressible Navier-Stokes equations (8). Under regularity assumptions and supposing a divergence-free external force field f , an approach to incorporate both the pressure term ∇p and the incompressibility condition $\nabla \cdot u = 0$ into the Burgers equation (5) is to consider the Poisson problem

$$-\Delta p = \operatorname{div} \operatorname{div} (u \otimes u),$$

where $\operatorname{div} := \nabla \cdot$ represents the divergence operator and \otimes the tensor product (see *e.g.* [46, 47]). Then the incompressible Navier-Stokes equations system (8) is equivalent to

$$\begin{cases} \frac{\partial u}{\partial t} + \frac{\nu}{2} \Delta u + (u \cdot \nabla) u + \nabla (-\Delta)^{-1} \operatorname{div} \operatorname{div} (u \otimes u) + f = 0 & ; 0 \leq t < T, \\ u(T) = g. \end{cases} \quad (9)$$

F. Delbaen *et al* [14] introduced a coupled FBSDEs system (FBSDEs) associated to (9) through the nonlinear Feynman-Kac formula $u(t, x) = Y_t^{t,x}$ and the probabilistic representation $\nabla p = \tilde{Y}_0$ where \tilde{Y} is itself solution to a BSDE involving a Brownian motion B independent from the one of the diffusion. The nonlocal operator $\nabla (-\Delta)^{-1} \operatorname{div} \operatorname{div}$ is represented by means of the BSDE defined on the infinite time interval $(0, \infty)$. Then, incorporating this extra BSDE to the FBSDEs (6) it is obtained a stochastic representation to the unsteady Navier-Stokes equations. More precisely, this new FBSDEs representation is

$$\begin{cases} dX_s^{t,x} = Y_s^{t,x} ds + \sqrt{\nu} dW_s & ; s \in [t, T], \\ X_t^{t,x} = x, \\ -dY_s^{t,x} = \left[f(s, X_s^{t,x}) + \tilde{Y}_0(s, X_s^{t,x}) \right] ds - \sqrt{\nu} Z_s^{t,x} dW_s & ; s \in [t, T], \\ Y_T^{t,x} = g(X_T^{t,x}), \\ -d\tilde{Y}_r^{s,x} = \frac{27}{2r^3} Y_s^i \cdot Y_s^j(s, x + B_r) \left(B_r - B_{\frac{2r}{3}} \right)^i \left(B_{\frac{2r}{3}} - B_{\frac{r}{3}} \right)^j B_{\frac{r}{3}} dr - \tilde{Z}_r^{s,x} dB_r & ; r \in (0, \infty), \\ \tilde{Y}_\infty^{s,x} = 0, \end{cases} \quad (10)$$

where W and B are two independent d -dimensional Brownian motions. Here $\tilde{Y}_0(s, X_s^{t,x})$ and $Y_s(s, x + B_r)$ means $\tilde{Y}_0^{s, X_s^{t,x}}$ and $Y_s^{s, x+B_r}$, respectively.

In [14], the infinite interval $(0, \infty)$ of the probabilistic representation for the operator $\nabla(-\Delta)^{-1} \operatorname{div} \operatorname{div}$ is restricted to $[\frac{1}{N}, N]$, for $N \in (1, \infty)$. Hence the solution u of (9) on $(T_0, T]$, with $T_0 \in [0, T)$, is approximated by u^N which solves the PDE

$$\begin{cases} \frac{\partial u^N}{\partial t} + \frac{\nu}{2} \Delta u^N + (u^N \cdot \nabla) u^N + \mathbf{Q}^N(u^N \otimes u^N) + f = 0 & ; T_0 \leq t < T, \\ u^N(T) = g, \end{cases} \quad (11)$$

where for $N \in (1, \infty)$ and $\forall \phi, \psi \in H^m$, with $m > \frac{d}{2} + 1$,

$$\mathbf{Q}^N(\phi \otimes \psi)(x) := \mathbb{E} \int_{\frac{1}{N}}^N \frac{27}{2s^3} \phi^i \cdot \psi^j(x + B_s) \left(B_s - B_{\frac{2s}{3}}\right)^i \left(B_{\frac{2s}{3}} - B_{\frac{s}{3}}\right)^j B_{\frac{s}{3}} ds; \quad \forall x \in \mathbb{R}^d.$$

Given $\nu > 0$, $g \in H_\sigma^m$ and $f \in C([0, T]; H_\sigma^{m-1})$ with sufficient regularity $m > \frac{d}{2} + 1$,

$$\|u - u^N\|_{C([t, T]; C^{k, \alpha})} \leq \frac{K}{N^{\frac{\alpha}{4}}}; \quad \forall t \in (T_0, T], \quad (12)$$

for some $k \in \mathbb{Z}_+$, $\alpha \in (0, 1)$ and $K > 0$ independent of N (see Theorem 6.6 in [14]). Then, the PDE (11) is associated through the nonlinear Feynman-Kac formula

$$u^N(t, x) = Y_t^{t, x}$$

to the following FBSDE

$$\begin{cases} dX_s^{t, x} = Y_s(s, X_s^{t, x}) ds + \sqrt{\nu} dW_s & ; s \in [t, T], \\ X_t^{t, x} = x, \\ -dY_s(s, X_s^{t, x}) = [f(s, X_s^{t, x}) + \mathbf{Q}^N(Y_s \otimes Y_s)(s, X_s^{t, x})] ds - \sqrt{\nu} Z_s^{t, x} dW_s & ; s \in [t, T], \\ Y_T(T, x) = g(x), \\ \mathbf{Q}^N(Y_s \otimes Y_s)(s, x) = \mathbb{E} \int_{\frac{1}{N}}^N \frac{27}{2r^3} Y_s^i \cdot Y_s^j(s, x + B_r) \left(B_r - B_{\frac{2r}{3}}\right)^i \left(B_{\frac{2r}{3}} - B_{\frac{r}{3}}\right)^j B_{\frac{r}{3}} dr, \end{cases} \quad (13)$$

where W and B are independent d -dimensional Wiener processes and, by abuse of notation, we write $Y_s(t, y) := Y_s^{t, y}$. Moreover, it is worth pointing out that $Y_s^{t, \cdot} = Y_s^{s, X_s^{t, \cdot}}$ (see Theorem 6.4 and Remark 6.2 in [14]).

3 Numerical methodology

In this section, we precise some probabilistic algorithms for the numerical solution of FBSDEs. The stochastic representations for the solutions of the Burgers equation and the incompressible Navier-Stokes equations follow from systems (6) and (10), respectively. In the first case, we consider the approach by F. Delarue and S. Menozzi [15, 16], and then we incorporate quantization as a control variate variable to reduce the variance of the Monte Carlo estimation of the expected values. Then, we study the incompressible Navier-Stokes equations. To this end, we consider the numerical algorithm introduced by F. Delbaen *et al* [14] and then we propose a novel probabilistic algorithm by incorporating the numerical treatment of the pressure term. The rest of the section is devoted to the probabilistic tools used in the numerical algorithms.

We begin with some preliminaries to the numerical approximation of FBSDEs. More precisely, let $T > 0$ be fixed and given $N_T \in \mathbb{Z}_+$ consider a regular mesh of $[0, T]$ with time-step $h := T/N_T$ i.e. set the temporal nodes $[0, T] \cap \mathcal{T}_h$, with $\mathcal{T}_h := h \cdot \mathbb{Z}$, or well

$$t_k := k \cdot h; \quad \forall k \in \{0, \dots, N_T\},$$

and the infinite Cartesian grid $\mathcal{C}_\delta := \delta \cdot \mathbb{Z}^d$ of uniform spatial-step $\delta > 0$. From now on, we consider sufficient small discretization parameters of time $h > 0$ and space $\delta > 0$ such that $\delta < h$. Moreover, let Π_δ be the projection mapping on the grid \mathcal{C}_δ defined by

$$\Pi_\delta(x) := \arg \min\{\|x - \bar{x}\| : \bar{x} \in \mathcal{C}_\delta\}; \quad \forall x \in \mathbb{R}^d.$$

Observe that for α -Hölder continuous functions $F : \mathbb{R}^d \rightarrow \mathbb{R}^d$ the projection error results

$$\|F(x) - F(\Pi_\delta(x))\| \leq K\delta^\alpha.$$

For all $k \in \{0, \dots, N_T - 1\}$, we denote $\Delta W_k = W_{t_{k+1}} - W_{t_k}$ and refer as $q(\Delta W_k) = \sqrt{h} q\left(\frac{\Delta W_k}{\sqrt{h}}\right)$ to the optimal quantization of the underlying Gaussian variable ΔW_k . Similarly, $q(W_s) = \sqrt{s} q\left(\frac{W_s}{\sqrt{s}}\right)$ (see Subsection 3.3 below).

3.1 Burgers equation

As a first point, since the Burgers equation representation (6) we are interested in systems of FBSDEs (3) whose drift terms b and h are independent of the diffusion coefficient Z *i.e.* FBSDEs of the form

$$\forall s \in [t, T], \quad \begin{cases} X_s = x + \int_t^s b(r, X_r, Y_r) dr + \int_t^s \sigma(r, X_r, Y_r) dW_r, \\ Y_s = g(X_T) + \int_s^T h(r, X_r, Y_r) dr - \int_s^T Z_r dW_r. \end{cases} \quad (14)$$

As usual, we can remove the martingale part of the BSDE by taking the conditional expectation $\mathbb{E}(\cdot | X_t = x)$ and so the dependence of Y on the process Z . Thus we focus on the numerical solution of the process Y and, since the nonlinear Feynman-Kac formula, the estimation of the strong solution u of the related PDE (4) by means of a probabilistic numerical algorithm.

Usually the numerical schemes for FBSDEs involve backward regressions to compute estimations of the processes (X, Y, Z) (see *e.g.* [45, 48]). The following numerical scheme \bar{u} approximates the process Y involved in the FBSDEs (14).

Algorithm 3.1 (F. Delarue and S. Menozzi [15]). **Define**

$$\bar{u}(T, x) = g(x); \quad \forall x \in \mathcal{C}_\delta.$$

For each temporal node t_k with $k \in \{0, \dots, N_T - 1\}$ and any spatial position $x \in \mathcal{C}_\delta$, compute recursively

$$\begin{aligned} \mathcal{T}(t_k, x) &= b(t_{k+1}, x, \bar{u}(t_{k+1}, x)) \cdot h + \sigma(t_{k+1}, x, \bar{u}(t_{k+1}, x)) q(\Delta W_k), \\ \bar{u}(t_k, x) &= \mathbb{E}[\bar{u}(t_{k+1}, \Pi_\delta(x + \mathcal{T}(t_k, x)))] + h(t_{k+1}, x, \bar{u}(t_{k+1}, x)) \cdot h. \end{aligned}$$

The process $\mathcal{T}(t_k, x)$ corresponds to the Euler-Maruyama scheme applied to the Itô SDE. Its convergence is well known in a Hölder continuous setting when the quantization of ΔW_k is not considered (see [49]). Quantizing the underlying Gaussian variables $q(\Delta W_k)$ provides us with an efficient method to deal with the expectation approximations to the terms $\bar{u}(t_k, x)$, instead of the classical Monte Carlo procedure. By its way the projection operator Π_δ onto the spatial grid incorporates an extra source of error to the order of convergence of the numerical algorithm. All this elements are bounded to the computation of Algorithm 3.1 (see Section 4 of [15] and [16] for details and convergence).

We incorporate quantization as a control variate variable to the Monte Carlo computation of mean values (see Subsection 3.3 for details). More precisely, we introduce the following numerical scheme:

Algorithm 3.2. Define

$$\bar{u}(T, x) = g(x); \quad \forall x \in \mathcal{C}_\delta.$$

For each time node $k \in \{0, \dots, N_T - 1\}$ and any position $x \in \mathcal{C}_\delta$, compute

$$\begin{aligned} \mathcal{T}(t_k, x) &= b(t_{k+1}, x, \bar{u}(t_{k+1}, x)) \cdot h + \sigma(t_{k+1}, x, \bar{u}(t_{k+1}, x)) q(\Delta W_k), \\ \bar{u}(t_k, x) &= \mathbb{E}[\bar{u}(t_{k+1}, \Pi_\delta(x + \mathcal{T}(t_k, x)))] + h(t_{k+1}, x, \bar{u}(t_{k+1}, x)) \cdot h \\ &\quad + \frac{1}{\mathcal{M}} \sum_{l=1}^{\mathcal{M}} \left[\bar{u}(t_{k+1}, \Pi_\delta(x + \mathcal{T}^{(l)}(t_k, x))) - \bar{u}(t_{k+1}, \Pi_\delta(x + \widehat{\mathcal{T}}^{(l)}(t_k, x))) \right]. \end{aligned}$$

Here $\Delta W_k^{(l)} = W_{t_{k+1}}^{(l)} - W_{t_k}^{(l)}$ are $\mathcal{M} \in \mathbb{Z}_+$ independent realizations of the Gaussian variable ΔW_k . Moreover, $\mathcal{T}^{(l)}(t_k, x) := b(t_{k+1}, x, \bar{u}(t_{k+1}, x)) \cdot h + \sigma(t_{k+1}, x, \bar{u}(t_{k+1}, x)) \Delta W_k^{(l)}$ and $\widehat{\mathcal{T}}^{(l)}(t_k, x) := b(t_{k+1}, x, \bar{u}(t_{k+1}, x)) \cdot h + \sigma(t_{k+1}, x, \bar{u}(t_{k+1}, x)) q(\Delta W_k^{(l)})$.

Note that the convergence of Algorithm 3.1 involves the optimality of quantization parameters to the underlying Gaussian random variables. However, the quantization as control variates to the Monte Carlo method can reduce the approximation error or improve the computational effort to the calculation of the conditional expectations. In [50], Algorithm 3.2 have been tested with success to the Burgers equation in some numerical tests proposed by [15, 16].

3.2 Incompressible Navier-Stokes equations

Delbaen *et al* [14] propose a numerical algorithm \bar{u}^N to approximate the process Y that solves (13) and then the solution u^N of (11). Hence the numerical approximation \bar{u}^N of the velocity field u of the incompressible Navier-Stokes equations (8). In particular, we consider the following scheme:

Algorithm 3.3. Define

$$\bar{u}^N(T, x) = g(x); \quad \forall x \in \mathcal{C}_\delta.$$

Then for each $k \in \{0, \dots, N_T - 1\}$ and all $x \in \mathcal{C}_\delta$, compute

$$\begin{aligned} \mathcal{T}^N(t_k, x) &= \bar{u}^N(t_{k+1}, x) \cdot h + \sqrt{\nu} q(\Delta W_k), \\ Q^N(t_{k+1}, x) &= \mathbb{E} \int_{\frac{1}{3N}}^{\frac{N}{3}} \frac{3}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N \left(t_{k+1}, \Pi_\delta \left(x + q(\bar{B}_r) + q(\tilde{B}_r) + q(\widehat{B}_r) \right) \right) q^i(\bar{B}_r) q^j(\tilde{B}_r) q(\widehat{B}_r) dr, \\ \bar{u}^N(t_k, x) &= \mathbb{E}[\bar{u}^N(t_{k+1}, \Pi_\delta(x + \mathcal{T}^N(t_k, x)))] + (f(t_{k+1}, x) + Q^N(t_{k+1}, x)) \cdot h. \end{aligned}$$

For each time $t_k \in [0, T]$, Algorithm 3.3 computes the approximation $\bar{u}^N(t_k, \cdot)$ of $u^N(t_k, \cdot)$ over the spatial grid, being u^N the solution of (11) an estimation to the exact velocity field u of the backward Navier-Stokes equations (9). Therefore the velocity field $u(t_k, \cdot)$ of the incompressible Navier-Stokes equations (1) is approximated by $-\bar{u}^N(T - t_k, \cdot)$.

Given the vector field $\bar{u}^N(t_{k+1}, \cdot) \approx Y_{t_{k+1}}^{t_{k+1}, \cdot}$, the algorithm constructs the approximation $\bar{u}^N(t_k, x)$ of $Y_{t_k}(t_k, x)$ for all $x \in \mathcal{C}_\delta$, with Y solving (13). This procedure involves the local

time integration

$$\begin{aligned}
& \int_{t_k}^{t_{k+1}} \mathbf{Q}^N(Y_s \otimes Y_s)(s, X_s^{t_k, x}) \, ds \\
& \approx \mathbb{E} \int_{\frac{1}{N}}^N \frac{27}{2r^3} Y_{t_{k+1}}^i \cdot Y_{t_{k+1}}^j(t_{k+1}, x + B_r) \left(B_r - B_{\frac{2r}{3}}\right)^i \left(B_{\frac{2r}{3}} - B_{\frac{r}{3}}\right)^j B_{\frac{r}{3}} \, dr \cdot h \\
& \approx \mathbb{E} \int_{\frac{1}{N}}^N \frac{27}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, x + B_r) \left(B_r - B_{\frac{2r}{3}}\right)^i \left(B_{\frac{2r}{3}} - B_{\frac{r}{3}}\right)^j B_{\frac{r}{3}} \, dr \cdot h \\
& = \mathbb{E} \int_{\frac{1}{3N}}^{\frac{N}{3}} \frac{3}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, x + \bar{B}_r + \tilde{B}_r + \hat{B}_r) \bar{B}_r^i \tilde{B}_r^j \hat{B}_r \, dr \cdot h \\
& \approx \mathbb{E} \int_{\frac{1}{3N}}^{\frac{N}{3}} \frac{3}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, \Pi_\delta(x + \bar{B}_r + \tilde{B}_r + \hat{B}_r)) \bar{B}_r^i \tilde{B}_r^j \hat{B}_r \, dr \cdot h.
\end{aligned}$$

Here the increments of B are replaced by three independent d -dimensional Brownian motions \bar{B} , \tilde{B} and \hat{B} independent of W . Then, involving the quantization of the underlying Gaussian random variables we obtain

$$\int_{t_k}^{t_{k+1}} \mathbf{Q}^N(Y_s \otimes Y_s)(s, X_s^{t_k, x}) \, ds \approx \mathbf{Q}^N(t_{k+1}, x) \cdot h. \quad (15)$$

Computing expectations of integrals depending on paths of Brownian motions introduces an additional source of error in the numerical treatment of the pressure term. Hence the problem of design an efficient estimation which provides us the convergence of \bar{u}^N defined by Algorithm 3.3 to the strong solution u^N of (11) (see Subsection 3.4).

The quantization of the underlying Gaussian variables permits us to compute mean values easily, with its estimation error depending on the dimension d and the number of quantization points. As in the Burgers equation, we can use quantization as a control variate to the estimation of the pressure term, but increasing considerably the computational effort of the algorithm especially when $d = 3$. Hence, a convenient variance reduction technique needs to be considered to deal with path-dependent functionals of Brownian motion. We mention for example variance reduction techniques in [51, 52].

3.3 Estimation of conditional expectations

Suppose that $U : \Omega \rightarrow \mathbb{R}^m$ is a square integrable random variable and $F : \mathbb{R}^m \rightarrow \mathbb{R}^d$ is uniformly α -Hölder continuous with Hölder exponent $\alpha \in (0, 1]$, such that $F(U) \in L_{\mathcal{F}}^2(\Omega; \mathbb{R}^d)$. The usual way to estimate expectations is by means of the Monte Carlo approximation

$$\mathbb{E}[F(U)] \approx \frac{1}{\mathcal{M}} \sum_{i=1}^{\mathcal{M}} F(U^{(i)}), \quad (16)$$

where $U^{(i)}$ are \mathcal{M} independent realizations of the underlying random variable U . From now on, the averages are computed in a component-wise manner. It is well-known that the Monte Carlo method (16) converges in law to the mean $\mathbb{E}[F(U)]$ with estimation error depending on $\sqrt{\text{Var } F(U)}/\sqrt{\mathcal{M}}$ as \mathcal{M} tends to ∞ .

We use the *quantization method* to estimate mean values. Indeed, let $q(U)$ be a *quantizer* of U i.e. an approximation of U by a discrete random variable $q(U)$ taking values in a finite set $\Gamma = \{v_1, \dots, v_Q\} \subset \mathbb{R}^m$. Suppose that $q(U) = \sum_{i=1}^Q v_i \mathbf{1}_{C_i}(U)$ where $C = \{C_1, \dots, C_Q\}$ is a

partition of \mathbb{R}^m associated to Γ be means of $v_i \in C_i$ for all $i \in \{1, \dots, Q\}$. Then

$$\mathbb{E}[F(U)] \approx \mathbb{E}[F(q(U))] = \sum_{i=1}^Q \mathbb{P}(U \in C_i) \cdot F(v_i). \quad (17)$$

Since F is α -Hölder continuous, Jensen's inequality implies that the error of estimation is bounded by

$$\|\mathbb{E}[F(U)] - \mathbb{E}[F(q(U))]\| \leq K (\mathbb{E}[\|U - q(U)\|^2])^{\alpha/2},$$

where the quantization error in the L^2 -norm (to the power 2) is given by

$$\|U - q(U)\|_2^2 = \sum_{i=1}^Q \mathbb{E}[\|U - v_i\|^2 \mathbf{1}_{C_i}(U)].$$

Thus, the key point is to provide convenient sets Γ and C such that the quadratic quantization error is optimal. An optimal quantizer is found through a stochastic gradient procedure over the positions of the points v_1, \dots, v_Q . The cells C_i are then given by a Voronoï partition of the space. Hence, for a given realization $u \in \mathbb{R}^m$ of U , we set

$$q(u) := v_i \text{ such that } \|u - v_i\| \leq \|u - v_j\|; \forall j = 1, \dots, Q, j \neq i.$$

In other words, $q(u)$ is the closest point to u among the v_i 's. We refer to [53, 54, 55, 56] for details on optimal quantization. In particular, the case of a m -dimensional Gaussian random variable $\xi \sim \mathcal{N}(0, I_m)$ is treated in details in [54].

A consequence from the Zador theorem [53] is that

$$\mathbb{E}[\|\xi - q(\xi)\|^2]^{1/2} \leq K(m)Q^{-1/m}$$

where $K(m)$ is a constant which depends from the dimension m . Hence we have a non-asymptotic error bound

$$\|\mathbb{E}[F(U)] - \mathbb{E}[F(q(U))]\| \leq \frac{K}{Q^{\alpha/m}},$$

depending on the dimension m and the number Q of quantizer points. We see that quantization is better in low dimension.

Tables for optimal quantizers are provided in the web site [55], which we use for our numerical implementations¹. Thus, given an application q which gives the optimal quantizer for $\xi \sim \mathcal{N}(0, I_m)$, we set

$$q(\zeta) := \mu + \Sigma q(\Sigma^{-1}(\zeta - \mu)) \text{ for } \zeta \sim \mathcal{N}(\mu, \Sigma \Sigma^T).$$

Quantization is also a convenient tool for constructing a *control variate* in order to perform a variance reduction technique in Monte Carlo simulations (see *e.g.* [57] for an introduction to control variates). More precisely, we use

$$\mathbb{E}[F(U)] \approx \mathbb{E}[F(q(U))] + \frac{1}{\mathcal{M}} \sum_{i=1}^{\mathcal{M}} [F(U^{(i)}) - F(q(U^{(i)}))]. \quad (18)$$

The error of the estimation (18) is then $\sqrt{\text{Var}(F(U) - F(q(U)))}/\sqrt{\mathcal{M}}$ as \mathcal{M} goes to ∞ . Thus, the error is reduced when $q(U)$ is close enough to U . The order $\mathcal{M}^{-1/2}Q^{-1/m}$ is obtained for the Gaussian case. We refer to [58, 51, 56] for reduction variance techniques that use quantization.

¹There exists several ways to consider the quantization of a vector: we could quantize each components, the vector as a whole, or sub-vectors.

As a special case, let U^1, \dots, U^ℓ be ℓ independent and identically distributed square integrable random variables $U^k : \Omega \rightarrow \mathbb{R}^m$ and $F : (\mathbb{R}^m)^\ell \rightarrow \mathbb{R}^d$ an α -Hölder continuous function such that $F(U^1, \dots, U^\ell)$ belongs to $L^2_{\mathcal{F}}(\Omega; \mathbb{R}^d)$. Then, we compute

$$\begin{aligned} \mathbb{E}[F(U^1, \dots, U^\ell)] &\approx \mathbb{E}[F(q(U^1), \dots, q(U^\ell))] \\ &= \sum_{i_1, \dots, i_\ell=1}^Q \mathbb{P}(U^1 \in C_{i_1}) \times \dots \times \mathbb{P}(U^\ell \in C_{i_\ell}) F(v_{i_1}, \dots, v_{i_\ell}) \end{aligned}$$

because U^1, \dots, U^ℓ are independent. The same quantizers points are taken for each random variable.

3.4 Integrals involving paths of Brownian motions

In the FBSDS (10) the pressure term is represented by

$$\nabla p(s, X_s^{t,x}) = \tilde{Y}_0(s, X_s^{t,x}).$$

Then the approximated solution u^N is estimated by means of the stochastic process Y of the *truncated* FBSDS (13) and involves its approximation $\mathbf{Q}^N(Y_s \otimes Y_s)(s, X_s^{t,x})$, for $N \in \mathbb{Z}_+$. Given the estimations $\bar{u}^N(t_{k+1}, x)$ of $Y_{t_{k+1}}(t_{k+1}, x)$ for all $x \in \mathcal{C}_\delta$, we approximate $Y_{t_k}(t_k, x)$ over the spatial grid by locally integrating the BSDE that defines $(Y_s^{t_k, x})_{s \in [t_k, t_{k+1}]}$. Concerning to the gradient of the pressure, for each $k \in \{0, \dots, N_T - 1\}$ and $x \in \mathcal{C}_\delta$,

$$\begin{aligned} \mathbb{E} \int_{t_k}^{t_{k+1}} \mathbf{Q}^N(Y_s \otimes Y_s)(s, X_s^{t,x}) ds \\ \approx \mathbb{E} \int_{\frac{1}{N}}^N \frac{27}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, x + B_r) \left(B_r - B_{\frac{2r}{3}}\right)^i \left(B_{\frac{2r}{3}} - B_{\frac{r}{3}}\right)^j B_{\frac{r}{3}} dr \cdot h. \end{aligned}$$

In [14], the increments of B are replaced by three independent d -dimensional Brownian motions \bar{B}, \tilde{B} and \hat{B} independent of W . This procedure involves the local time integration

$$\begin{aligned} \int_{t_k}^{t_{k+1}} \mathbf{Q}^N(Y_s \otimes Y_s)(s, X_s^{t,x}) ds \\ \approx \mathbb{E} \int_{\frac{1}{N}}^N \frac{27}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, x + B_r) \left(B_r - B_{\frac{2r}{3}}\right)^i \left(B_{\frac{2r}{3}} - B_{\frac{r}{3}}\right)^j B_{\frac{r}{3}} dr \cdot h \\ = \mathbb{E} \int_{\frac{1}{3N}}^{\frac{N}{3}} \frac{3}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, x + \bar{B}_r + \tilde{B}_r + \hat{B}_r) \bar{B}_r^i \tilde{B}_r^j \hat{B}_r dr \cdot h \\ \approx \mathbb{E} \int_{\frac{1}{3N}}^{\frac{N}{3}} \frac{3}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, \Pi_\delta(x + \bar{B}_r + \tilde{B}_r + \hat{B}_r)) \bar{B}_r^i \tilde{B}_r^j \hat{B}_r dr \cdot h. \end{aligned}$$

Hence denoting

$$F(r, \bar{B}_r, \tilde{B}_r, \hat{B}_r) := \frac{3}{2r^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, \Pi_\delta(x + \bar{B}_r + \tilde{B}_r + \hat{B}_r)) \bar{B}_r^i \tilde{B}_r^j \hat{B}_r,$$

we aim at computing numerically the term

$$\mathcal{Q}^N(t_{k+1}, x) = \mathbb{E} \int_{\frac{1}{3N}}^{\frac{N}{3}} F(r, \bar{B}_r, \tilde{B}_r, \hat{B}_r) dr \quad (19)$$

for $\bar{u}^N = (\bar{u}_1^N, \dots, \bar{u}_d^N)^\top$ and three independent d -dimensional standard Brownian motions. The size of the interval $[\frac{1}{3N}, \frac{N}{3}]$ determines the quality of the approximation in (12) so that accurate estimations are obtained for large values of N , leading to costly Monte Carlo approximations.

A first intent to compute the term Q^N is to use the quantization of the underlying Gaussian processes together with Riemann sum approximations to the integrals. Indeed, let $N_R \in \mathbb{Z}_+$ and define an uniform time step $\tau := (\frac{N}{3} - \frac{1}{3N}) / N_R$, with equidistant nodes

$$s_\ell := \frac{1}{3N} + (\ell - 1) \cdot \tau; \quad \forall \ell \in \{1, \dots, N_R\}.$$

Therefore, denoting by $\bar{\xi}_r := \frac{\bar{B}_r}{\sqrt{r}}$, $\tilde{\xi}_r := \frac{\tilde{B}_r}{\sqrt{r}}$ and $\hat{\xi}_r := \frac{\hat{B}_r}{\sqrt{r}}$, the pressure gradient term is estimated from $Q^N(t_{k+1}, x) \approx \hat{Q}^N(t_{k+1}, x)$ with

$$\begin{aligned} \hat{Q}^N(t_{k+1}, x) := \mathbb{E} \sum_{\ell=1}^{N_R} \frac{3}{2(\sqrt{s_\ell})^3} \bar{u}_i^N \cdot \bar{u}_j^N \left(t_{k+1}, \Pi_\delta \left(x + \sqrt{s_\ell} \left[q(\bar{\xi}_{s_\ell}) + q(\tilde{\xi}_{s_\ell}) + q(\hat{\xi}_{s_\ell}) \right] \right) \right) \\ \times q^i(\bar{\xi}_{s_\ell}) q^j(\tilde{\xi}_{s_\ell}) q(\hat{\xi}_{s_\ell}) \cdot \tau. \end{aligned} \quad (20)$$

Remark 1. In case of α -Hölder continuous function $\phi : \mathbb{R}^d \rightarrow \mathbb{R}^d$ we consider

$$F(r, \bar{B}_r, \tilde{B}_r, \hat{B}_r) := \frac{3}{2r^3} \phi_i \cdot \phi_j \left(\Pi_\delta \left(x + \bar{B}_r + \tilde{B}_r + \hat{B}_r \right) \right) \bar{B}_r^i \tilde{B}_r^j \hat{B}_r^j$$

and take

$$\begin{aligned} \mathbb{E} \int_{\frac{1}{3N}}^{\frac{N}{3}} F(r, \bar{B}_r, \tilde{B}_r, \hat{B}_r) dr &\approx \mathbb{E} \sum_{\ell=1}^{N_R} F(s_\ell, \bar{B}_{s_\ell}, \tilde{B}_{s_\ell}, \hat{B}_{s_\ell}) \cdot \tau \\ &\approx \mathbb{E} \sum_{\ell=1}^{N_R} F(s_\ell, q(\bar{B}_{s_\ell}), q(\tilde{B}_{s_\ell}), q(\hat{B}_{s_\ell})) \cdot \tau \end{aligned}$$

for all $x \in \mathcal{C}_\delta$, which involves simulating $N_R \times 3 \times d$ Gaussian random variables. The error of estimation depends on $d \in \{2, 3\}$, $\alpha \in (0, 1)$, and the discretization parameters $\tau > 0$ and $Q \in \mathbb{Z}_+$.

3.5 Computer implementation

The velocity field u that solves the Navier-Stokes equations system (1) is estimated by

$$u(t_k, x) \approx -\bar{u}^N(T - t_k, x); \quad \forall (t_k, x) \in [0, T] \cap \mathcal{T}_h \times [0, 2\pi]^d \cap \mathcal{C}_\delta.$$

To do this, we initialize

$$\bar{u}^N(T, x) = -u(0, x); \quad \forall x \in [0, 2\pi]^d \cap \mathcal{C}_\delta.$$

Then for each k from $N_T - 1$ to 0, we compute

$$\bar{u}^N(t_k, x); \quad \forall x \in [0, 2\pi]^d \cap \mathcal{C}_\delta,$$

from the velocity field $\bar{u}^N(t_{k+1}, \cdot)$ and the optimal quantizers for standard Gaussian random variables $\mathcal{N}(0, I_d)$. In this procedure, let $\hat{\Pi}_\delta$ be the projection mapping on the computational grid $[0, 2\pi]^d \cap \mathcal{C}_\delta$ defined by

$$\hat{\Pi}_\delta(x) := \arg \min \left\{ \left\| \left(x - 2\pi \cdot \left\lfloor \frac{x}{2\pi} \right\rfloor \right) - \bar{x} \right\| : \bar{x} \in [0, 2\pi]^d \cap \mathcal{C}_\delta \right\}; \quad \forall x \in \mathbb{R}^d.$$

Here $\lfloor \cdot \rfloor$ denotes the floor function. The approximation \bar{u}^N is extended by periodicity from $[0, 2\pi]^d \cap \mathcal{C}_\delta$ to the complete spatial grid \mathcal{C}_δ .

More precisely, we present the following algorithm:

Algorithm 3.4. (1) Define the dimension $d \in \{2, 3\}$, a final time $T > 0$ and the viscosity parameter $\nu > 0$. Fix the truncation parameter $N \in \mathbb{N}$, time-step $h = \frac{T}{N_T}$; with $N_T \in \mathbb{N}$, and spatial-step $\delta = \frac{2\pi}{N_\delta}$, with $N_\delta \in \mathbb{N}$. Define the initial velocity field $g(x)$ and the external force $f(t, x)$ for each $t \in [0, T] \cap \mathcal{T}_h$ and for all $x \in [0, 2\pi]^d \cap \mathcal{C}_\delta$. Consider $Q \in \mathbb{N}$ grid points for quantization, and $N_R \in \mathbb{N}$ subintervals of $[\frac{1}{3N}, \frac{N}{3}]$ with step size $\tau = (\frac{N}{3} - \frac{1}{3N}) / N_R$.

(2) Initialize

$$\bar{u}^N(T, x) = -g(x); \quad \forall x \in [0, 2\pi]^d \cap \mathcal{C}_\delta.$$

(3) For each k from $N_T - 1$ to 0, do for all $x \in [0, 2\pi]^d \cap \mathcal{C}_\delta$:

$$\begin{aligned} \hat{X}_{t_{k+1}}^N(t_k, x) &= x + \bar{u}^N(t_{k+1}, x) \cdot h + \sqrt{2\nu} \cdot \sqrt{h} \, q\left(\frac{W_{t_{k+1}} - W_{t_k}}{\sqrt{h}}\right), \\ \hat{Y}_{t_k}^N(t_k, x) &= \mathbb{E} \left[\bar{u}^N(t_{k+1}, \hat{\Pi}_\delta(\hat{X}_{t_{k+1}}^N(t_k, x))) \right], \end{aligned}$$

$$\begin{aligned} \hat{Q}^N(t_{k+1}, x) &= \mathbb{E} \left[\sum_{\ell=1}^{N_R} \frac{3}{2(\sqrt{s_\ell})^3} \bar{u}_i^N \cdot \bar{u}_j^N(t_{k+1}, \hat{\Pi}_\delta(x + \sqrt{s_\ell} [q(\bar{\xi}_{s_\ell}) + q(\tilde{\xi}_{s_\ell}) + q(\hat{\xi}_{s_\ell})])) \right. \\ &\quad \left. \times q^i(\bar{\xi}_{s_\ell}) q^j(\tilde{\xi}_{s_\ell}) q(\hat{\xi}_{s_\ell}) \cdot \tau \right], \end{aligned}$$

$$\bar{u}^N(t_k, x) = \hat{Y}_{t_k}^N(t_k, x) + [\hat{Q}^N(t_{k+1}, x) - f(T - t_{k+1}, x)] \cdot h.$$

Remark 2. Algorithm 3.4 involves the approximation of the velocity field for each position. Hence the velocity field $\bar{u}^N(t_k, \cdot)$ can be constructed by using a parallel computer implementation based on a space partition in order to reduce the computing time.

4 Numerical tests

Let $u(t, x) = (u_1(t, x), \dots, u_d(t, x))^\top$ be the exact velocity field that solves the incompressible Navier-Stokes equations (1). Since the equivalent backward form (8), by abuse of notation, we denote in the same way $\bar{u}^N(t, x) = (\bar{u}_1^N(t, x), \dots, \bar{u}_d^N(t, x))^\top$ the estimation of $u(t, x)$ obtained from Algorithm 3.4 *i.e.* by means of Algorithm 3.3 with Q^N estimated as in (20). As in Algorithm 3.1, we only consider discretization-steps $\delta, h \in (0, 1)$ such that $\delta < h$ to make the ‘‘Burgers equation part’’ estimation valid. The pressure term is computed with step size $\tau \in (0, 1)$. The data of the L^2 -optimal Q -quantizer of the $\mathcal{N}(0, I_d)$ distribution are provided by Corlay, Pagès and Printems [55]. We consider the estimation errors

$$e(t_k) := \sup_{x \in \mathcal{C}_\delta} \|u(t_k, x) - \bar{u}^N(t_k, x)\|^2$$

for each $k \in \{1, \dots, N_T\}$ and

$$e_i(t_k) := \sup_{x \in \mathcal{C}_\delta} |u_i(t_k, x) - \bar{u}_i^N(t_k, x)|^2 \quad ; \quad \forall i \in \{1, \dots, d\}.$$

Algorithm 3.4										
k	1	2	3	4	5	6	7	8	9	10
$\hat{e}_1(t_k)$	0.2080	0.6509	1.2064	1.8993	2.6558	3.3847	4.0197	4.6681	5.4006	6.0757
$\hat{e}_2(t_k)$	0.2129	0.6627	1.3068	2.0936	2.9979	3.9497	4.9062	5.8747	6.8223	7.7452
$\hat{e}(t_k)$	0.2139	0.6628	1.3153	2.1040	3.0136	3.9691	4.9306	5.9109	6.8528	7.7768

Table 1: Estimation errors $\hat{e}(t_k) := e(t_k) \cdot 10^3$ and $\hat{e}_i(t_k) := e_i(t_k) \cdot 10^3$ to the two-dimensional Taylor-Green vortex performed by Algorithm 3.4 with $N = 6$, $h = 1/40$, $\delta = \pi/126$, $Q = 6$ and $N_R = 18$.

4.1 Taylor-Green vortex

We begin by studying the Taylor-Green vortices introduced by G. I. Taylor and A. E. Green in 1937 [59]. It is a classical turbulence model useful to test numerical schemes for the incompressible Navier-Stokes equations. More precisely, we consider the vortex flow given by the incompressible Navier-Stokes equations (1) without external force field and initial condition

$$\begin{cases} g_1(x) = \frac{2}{\sqrt{3}} \sin\left(\theta + \frac{2\pi}{3}\right) \sin(x_1) \cos(x_2) \cos(x_3), \\ g_2(x) = \frac{2}{\sqrt{3}} \sin\left(\theta - \frac{2\pi}{3}\right) \cos(x_1) \sin(x_2) \cos(x_3), \\ g_3(x) = \frac{2}{\sqrt{3}} \sin(\theta) \cos(x_1) \cos(x_2) \sin(x_3), \end{cases}$$

where $x = (x_1, x_2, x_3)^\top$ and $\theta \in [0, 2\pi]$. In particular, by a shift of origin $(0, 0, 0) \rightarrow (\pi/2, \pi/2, 0)$ and choosing $\theta = 0$ and $x_3 \equiv 0$, we have the explicit 2d Taylor-Green vortex flow

$$\begin{cases} u_1(t, x) = -\cos(x_1) \sin(x_2) \exp(-2\nu t), \\ u_2(t, x) = \sin(x_1) \cos(x_2) \exp(-2\nu t), \\ p(t, x) = -\frac{1}{4} (\cos(2x_1) + \cos(2x_2)) \exp(-4\nu t), \end{cases} \quad (21)$$

for $x \in [0, 2\pi]^2$, that solves the incompressible Navier-Stokes equations (1) with viscosity parameter $\nu > 0$ and $f \equiv 0$ [60].

The exact solution (21) gives us a benchmark to Algorithm 3.4 with respect to a finite difference method [61, 62]. As in [61], we estimate numerically (21) with viscosity parameter $\nu = 1$. We apply Algorithm 3.4 by using $N = 6$, time-step $h = 1/40$, space-discretization step $\delta = \pi/126$ and $Q = 6$ quantization points, until a final time $T = 10h$. We compute the term \hat{Q}^N by taking a left Riemann sum approximation of the integrals using $N_R = \frac{N - \frac{1}{3N}}{\tau} = 18$ uniform subintervals of $[\frac{1}{3N}, \frac{N}{3}]$. Table 1 depicts the numerical results. The discretization steps are related linearly, instead of the restrictive assumption $h = \mathcal{O}(\delta^2)$ in the case of the finite-difference scheme [62].

4.2 Beltrami flows

The Beltrami flows, introduced by E. Beltrami in 1889 [63], are the ones for which the vorticity vector $\omega = \text{curl } u$, with rotational operator $\text{curl} := \nabla \times$, satisfies $\omega = \lambda u$ for some parameter λ . That is, the vorticity and the velocity vectors are aligned, or well the vorticity is an eigenvector of the rotational operator.

In particular, we study the three-dimensional viscous Beltrami flow

$$\begin{cases} u(t, x) = g(x) e^{-\nu \lambda^2 t}, \\ p(t, x) = p_s - \rho \left[\frac{\|u(t, x)\|^2}{2} + g x_3 \right], \end{cases} \quad (22)$$

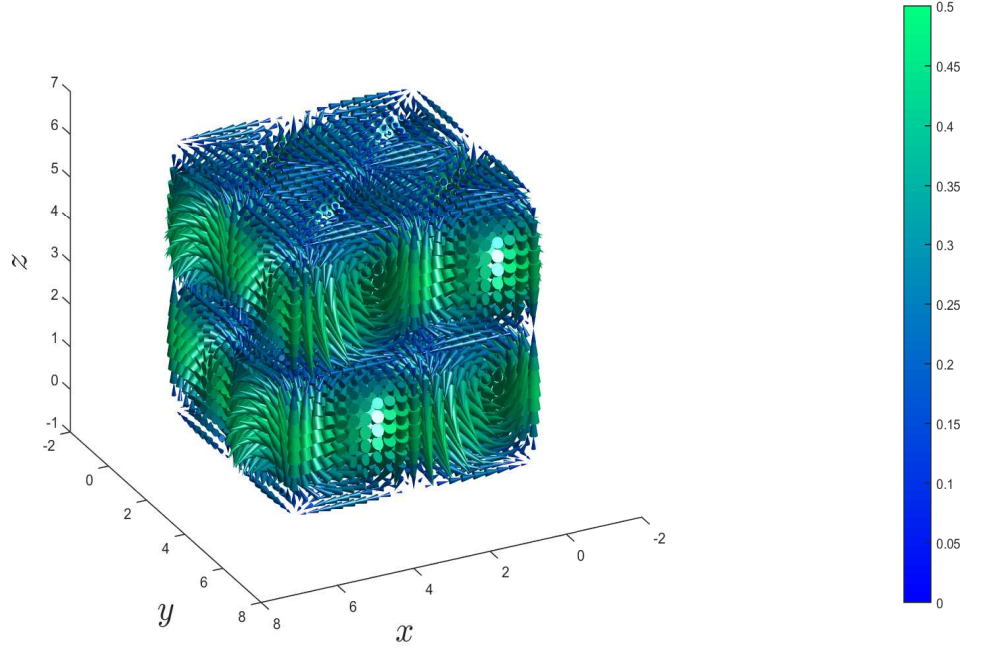


Figure 1: Initial velocity field to the three-dimensional Beltrami flow (22).

with non-divergence initial velocity field

$$\begin{cases} g_1(x) = -\frac{A}{k^2 + \ell^2} [\lambda \ell \cos(kx_1) \sin(\ell x_2) \sin(mx_3) + mk \sin(kx_1) \cos(\ell x_2) \cos(mx_3)], \\ g_2(x) = \frac{A}{k^2 + \ell^2} [\lambda k \sin(kx_1) \cos(\ell x_2) \sin(mx_3) - m\ell \cos(kx_1) \sin(\ell x_2) \cos(mx_3)], \\ g_3(x) = A \cos(kx_1) \cos(\ell x_2) \sin(mx_3), \end{cases}$$

where $x = (x_1, x_2, x_3)^\top$, $p_s \geq 0$ a time-independent stagnation pressure at ground level, A the amplitude of the vertical velocity and Beltrami coefficient

$$\lambda = \sqrt{k^2 + \ell^2 + m^2}.$$

Here, $g > 0$ is the acceleration due to gravity and $\rho > 0$ is the density of the fluid which is assumed, as the kinematic viscosity $\nu > 0$, to be constant. The Beltrami flow (22) solves the incompressible Navier-Stokes equations (1) with $\nu > 0$, external force field $f(t, x) = -g(0, 0, 1)^\top$ and initial divergence-free vector field $g(x)$ as above (see [64]). Defining the potential $\phi(t, x) = -gx_3$, observe that $f(t, x) = \nabla\phi(t, x)$. Thus, the constant density $\rho > 0$ and the conservative external force field f are considered as part of the pressure term $p(t, x)$. That is

$$\begin{cases} u(t, x) = g(x) e^{-2\nu\lambda^2 t}, \\ p(t, x) = \frac{p_s}{\rho} - \left[\frac{\|u(t, x)\|^2}{2} + gx_3 - \phi(t, x) \right] = \frac{p_s}{\rho} - \frac{\|u(t, x)\|^2}{2}, \end{cases} \quad (23)$$

for $t \in [0, T]$ and $x \in [0, \frac{2\pi}{k}] \times [0, \frac{2\pi}{\ell}] \times [0, \frac{2\pi}{m}]$, solves the incompressible Navier-Stokes equations (1) with viscosity parameter $\nu > 0$ and external force $f \equiv 0$.

We consider the numerical approximation of the 3d space-periodic velocity field u of the Beltrami flow (23) with $\nu = 0.1$, $A = 0.5$, $k = \ell = m = 1$ until $T = 2$. Note that the parameters ρ , g and p_s have no influence on the results. Table 2 shows the performance of Algorithm 3.4

Algorithm 3.4										
k	1	2	3	4	5	6	7	8	9	10
$\tilde{e}_1(t_k)$	0.0994	0.2719	0.5046	0.7557	1.0427	1.3278	1.6278	1.8934	2.1408	2.3464
$\tilde{e}_2(t_k)$	0.0762	0.2097	0.3906	0.5483	0.7490	0.8825	1.0559	1.2134	1.3037	1.3780
$\tilde{e}_3(t_k)$	0.0661	0.1944	0.3166	0.4872	0.6616	0.7902	1.0241	1.1166	1.2321	1.3769
$\tilde{e}(t_k)$	0.1159	0.2954	0.5503	0.8002	1.1048	1.4035	1.6854	1.9386	2.1779	2.4098

Table 2: Estimation errors $\tilde{e}(t_k) := e(t_k) \cdot 10^2$ and $\tilde{e}_i(t_k) := e_i(t_k) \cdot 10^2$ to the three-dimensional Beltrami flow by using Algorithm 3.4 ($N = 6$, time-step $h = 1/5$, spatial discretization $\delta = \pi/20$, $Q = 6$ quantization points and $N_R = 18$ subintervals).

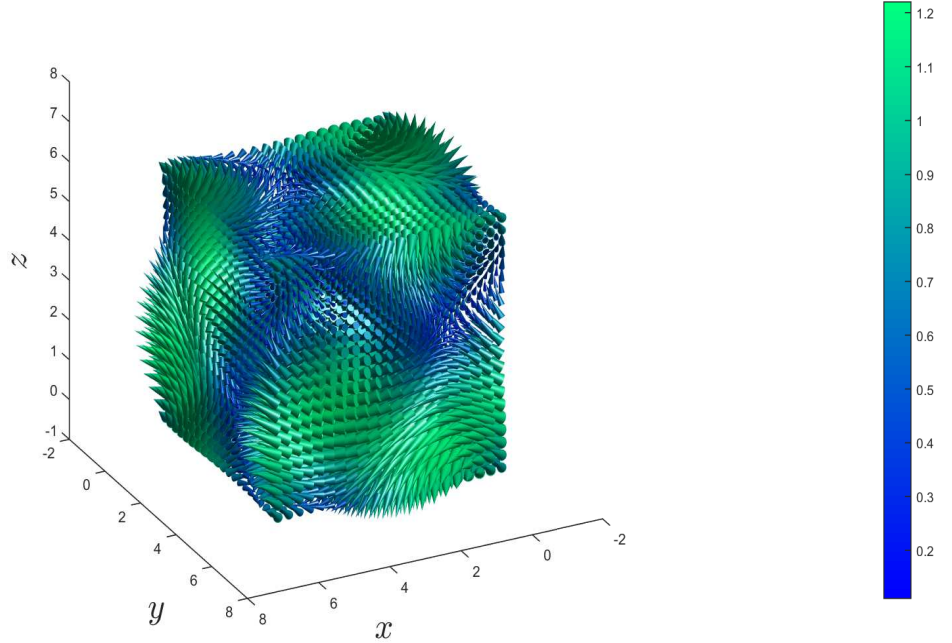


Figure 2: Initial velocity field to the three-dimensional ABC flow (24).

with $N = 6$, time-step $h = T/10$, spatial discretization $\delta = \pi/20$, $Q = 6$ quantization points and $N_R = 18$ subintervals to the Riemann sum estimations.

Finally, we consider the Arnold-Beltrami-Childress flow [47]

$$\begin{cases} u_1(t, x) = (A \sin(x_3) + C \cos(x_2)) \exp(-\nu t), \\ u_2(t, x) = (B \sin(x_1) + A \cos(x_3)) \exp(-\nu t), \\ u_3(t, x) = (C \sin(x_2) + B \cos(x_1)) \exp(-\nu t), \\ p(t, x) = -(BC \cos(x_1) \sin(x_2) + AB \sin(x_1) \cos(x_3) + AC \sin(x_3) \cos(x_2)) \exp(-2\nu t) + c, \end{cases} \quad (24)$$

for $(t, x) \in [0, T] \times [0, 2\pi]^3$, with final time $T > 0$, parameters $A, B, C \in \mathbb{R}$ and constant $c \in \mathbb{R}$. The ABC flow was introduced by Arnold [65] and Childress [66] as a class of Beltrami flow (with Beltrami coefficient $\lambda = 1$). The three-dimensional velocity field u and pressure term p defined by (24) solve the incompressible Navier-Stokes equations (1) with viscosity parameter $\nu > 0$ and external force $f \equiv 0$.

We simulate the ABC flow (24) with $\nu = 0.01$ and $A = B = C = 0.5$ until $T = 7/10$. Table 3 presents the estimation errors of Algorithm 3.4 with $N = 6$, time-step $h = T/10$, spatial

Algorithm 3.4										
k	1	2	3	4	5	6	7	8	9	10
$\tilde{e}_1(t_k)$	0.0400	0.1449	0.3178	0.5553	0.8433	1.1800	1.5744	2.0311	2.5400	3.0662
$\tilde{e}_2(t_k)$	0.0574	0.1990	0.4256	0.7479	1.1740	1.6526	2.3021	2.9373	3.8502	4.6322
$\tilde{e}_3(t_k)$	0.0427	0.1564	0.3434	0.5954	0.9202	1.3296	1.8393	2.3489	3.0317	3.7326
$\tilde{e}(t_k)$	0.1001	0.3661	0.8010	1.3877	2.1203	3.0003	4.1640	5.2858	6.9379	8.6758

Table 3: Estimation errors $\tilde{e}(t_k) := e(t_k) \cdot 10^2$ and $\tilde{e}_i(t_k) := e_i(t_k) \cdot 10^2$ to the three-dimensional ABC flow by using Algorithm 3.4 ($N = 6$, time-step $h = 7/100$, spatial discretization $\delta = \pi/45$, $Q = 6$ quantization points and $N_R = 18$ subintervals).

discretization $\delta = \pi/45$, $Q = 6$ quantization points and $N_R = 18$ subintervals to the Riemann sum estimations.

5 Conclusions

Forward-backward SDEs driven by Brownian motion are linked to nonlinear PDEs by means of the Feynman-Kac formula. The deterministic solution is interpreted as the conditional expectation of a diffusion process, and a stochastic algorithm to compute estimations is deduced from its probabilistic representation. A novel system of FBSDEs due to F. Delbaen, J. Qiu and S. Tang [14] introduces a probabilistic approach associated to the incompressible Navier-Stokes equations in dimensions $d = 2, 3$. The Burgers equation is bounded to Itô and Backward SDEs on $[0, T]$. Then the pressure term and the incompressibility condition are incorporated by an additional BSDE on the time interval $(0, +\infty)$. Therefore an estimation of the velocity field that solves the unsteady Navier-Stokes equations follows from the numerical simulation of stochastic particles governed by a coupled forward-backward SDEs system (FBSDEs) driven by independent Brownian motions.

Motivated by Delbaen *et al.* the infinite interval of the extra BSDE is truncated to $[\frac{1}{N}, N]$; with $N \in \mathbb{N}$, thus the velocity field is approximated by u^N . The resulting FBSDEs system is computationally simulated by positioning particles onto an uniform temporal-spatial grid with discretization parameters in time $h > 0$ and space $\delta > 0$ such that $h, \delta \in (0, 1)$ and $h > \delta$. The forward-backward SDEs are numerically solved by using a methodology in the spirit of [15] *i.e.* by means a local discretization in time and taking Euler type integration schemes and optimal quantizers to the Wiener increments to approximate the conditional expectations on each temporal-spatial node. The pressure term demands to solve the BSDE associated to its Poisson problem, and the approximation of expectations of integrals involving path of Brownian motions appears as an additional challenge. In our numerical tests, the quantization of the underlying Gaussian processes together with a Riemann sum estimation of integrals appear as a good approach to deal with this problem. The integrals on the truncated interval $[\frac{N}{3}, \frac{1}{3N}]$ are approximated by taking Riemann sum approximations with step size $\tau \in (0, 1)$.

In this work, we study the numerical simulation of spatially periodic solutions to the Navier-Stokes equations. We present a two dimensional Taylor-Green vortex simulation with order 10^{-3} estimation errors to the velocity field. Moreover we report numerical results on three dimensional Beltrami flows achieving order 10^{-2} for the approximation errors. The quantity of particles increases as the space dimension grows, and additional computation is demanded to simulate the exact solutions. Moreover, from Morrey's inequality

$$H^m \subset C^{m - [\frac{d}{2}] - 1, \alpha},$$

with Hölder exponent $\alpha = \frac{1}{2}$ when $d = 3$ or any number $\alpha \in (0, 1)$ if $d = 2$. Observe a loss of accuracy to the order of estimation $\mathcal{O}(1/N^{\frac{\alpha}{4}})$ in the three dimensional context, hence the

truncation parameter N must increase to obtain theoretical errors as in the two dimension case.

The expected values are computed by replacing the underlying Gaussian random variables with optimal quantizers of the Normal distribution available in the website [55]. In practice, the quantization approach presents an advantage to the traditional Monte Carlo simulation because its non-asymptotic error bound of estimation $\mathcal{O}\left(1/Q^{\frac{1}{d}}\right)$. Given a codebook of size Q , the quantization error is better in low dimension. We consider a few quantizer points instead of the usage of many independent realizations of random variables.

We report numerical results by using the truncation parameter $N = 6$ and $Q = 6$ optimal quantizer points in two and three dimensions. The Riemann sum estimations on the interval $\left[\frac{1}{3N}, \frac{N}{3}\right]$ are computed by using the uniform discretization step $\tau = \left(\frac{N}{3} - \frac{1}{3N}\right)/N_R$ with $N_R = 18$ subintervals. The Euler-Maruyama method is considered to approximate the Itô SDEs components with additive noise $\nu \in \{1, 0.1, 0.01\}$. The time discretization step is essential to the performance of numerical solutions. It is well-known that Euler-Maruyama scheme could not be appropriate for turbulent flows as in the case of passive tracers model with low viscosity parameter. A convenient numerical scheme needs to be considered in the case of vanishing viscosity (see *e.g.* [67]).

The rate of convergence of Algorithm 3.4 depends on the initial data f, g and $\nu > 0$, the parameter N , the discretization steps on $[0, T]$, \mathbb{R}^d and $\left[\frac{N}{3}, \frac{1}{3N}\right]$, and the optimal quantization of the independent Brownian motions W and B . Roughly we have

$$\|u - \bar{u}^N\| \leq \|u - u^N\| + \|u^N - \bar{u}^N\| = \mathcal{O}\left(\frac{1}{N^{\frac{\alpha}{4}}}\right) + \text{error}(N, h, \delta, \tau, Q),$$

with α depending on $d \in \{2, 3\}$. The estimation **error** involves the dimension d and the α Hölder regularity. The reported numerical tests motivate us to the theoretical study and numerical analysis of the probabilistic algorithm associated to the incompressible Navier-Stokes equations. Moreover they suggest the extension of reduction variance methods to contexts as computing conditional expectations to solve systems of FBSDEs. Dealing with more general boundary conditions will be subject to future works.

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