





Efficient high-order discrete geometric model from CAD

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Context

High-order FEM analyses in complex domains would benefit from a correspondingly high-order representation of domain boundaries.

CAD systems are not well suited for direct integration in mesh generation and analysis processes:

- Parametrization dependencies,
- Computational cost of CAD requests,
- Parallelization difficulties,
- Platform portability and licencing issues.

Need for a CAD-system independent high-order representation of computational domains.



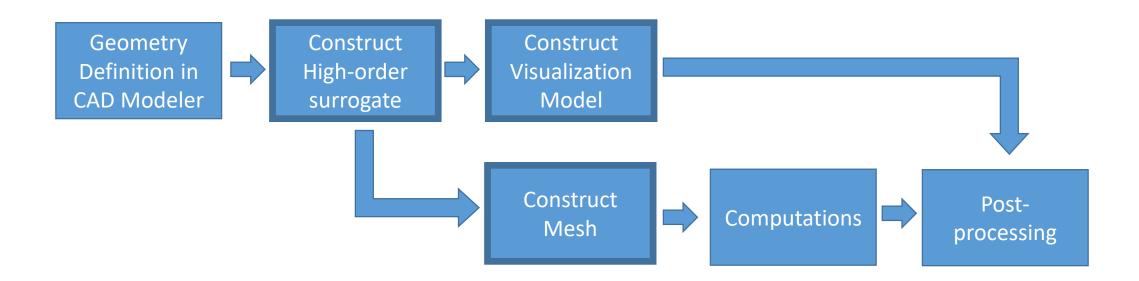
Objectives

- 1. Construct a high-order surrogate geometric representation using piecewise polynomials of a user-specified degree.
- 2. Ensure that the resulting representation is suitable for mesh generation and visualization purposes:
 - → Provide discrete primitives to graphic systems,
 - → Guarantee conformity between patches for meshing,
 - → Enforce user-specified geometric tolerances,
 - → Reduce required number of elements.
- 3. Isolate subsequent meshing, computing and visualization processes from the original CAD representation.



Constraints

- 1. Rely on curve and surface evaluation of CAD entities only (no derivatives required).
- 2. Cope with ill-defined parameterization of CAD entities.
- Accept definitions of CAD entities from several CAD systems and in several standard formats: STEP, IGES, etc.





1. B-Rep Geometry

CAD representation

- An object is defined from its boundary = collection of surface patches (faces)
- Each patch is defined by a parametric domain and a continuous parametric function (typically NURBS) $\sigma:\mathbb{R}^2\to\mathbb{R}^3$



2. Discrete representation (construction)

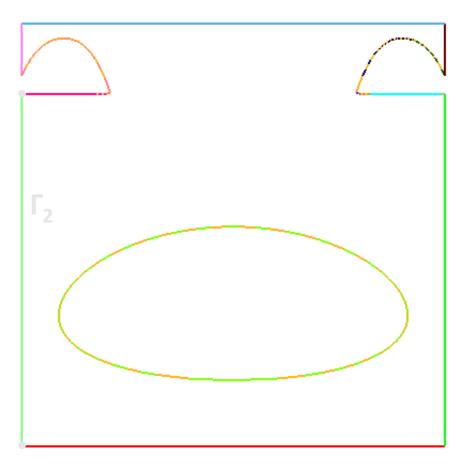
• Curve $\omega : \mathbb{R} \to \mathbb{R}^2$ $t \mapsto (u,v)$

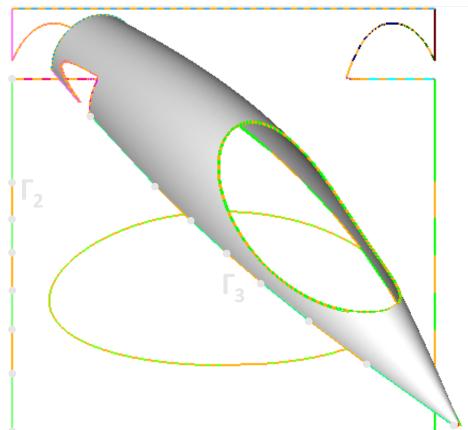
• Surface $\sigma: \mathbb{R}^2 \to \mathbb{R}^3$ $(u,v) \mapsto \sigma(u,v)$

- We want to build a "triangulation" that accurately reflects the geometry of the surface (proximity and regularity)
- Iso-parametric curves (for $u = u_i$ or $v = v_j$) generally give an accurate description of the geometry \Rightarrow we will use them as privileged directions for edges of the triangulation



2.1. Make a discrete model of curves in 2D and 3D





In 2D: geometric support for

$$\Gamma_2 = \omega([a,b])$$
 $\omega : \mathbb{R} \to \mathbb{R}^2$

$$\omega: \mathbb{R} \to \mathbb{R}^2$$

In 3D: geometric support for

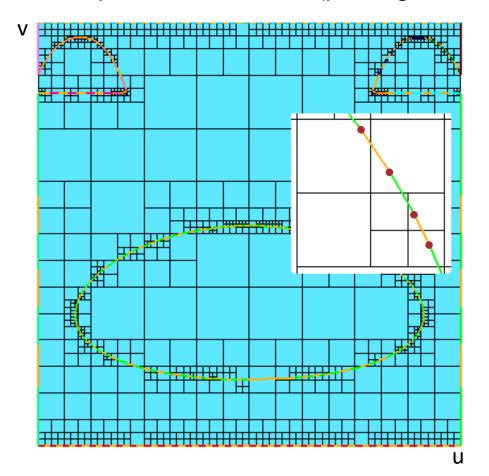
$$\sigma_3 = \sigma(\Gamma_2)$$

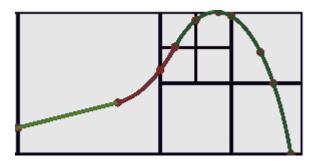
$$\Gamma_3 = \sigma(\Gamma_2)$$
 $\sigma: \mathbb{R}^2 \to \mathbb{R}^3$



2.2. Build a quadtree from the previous vertices

- The interior of each leaf contains at most one vertex
- Iso-parametric curves (privileged directions) appear here!

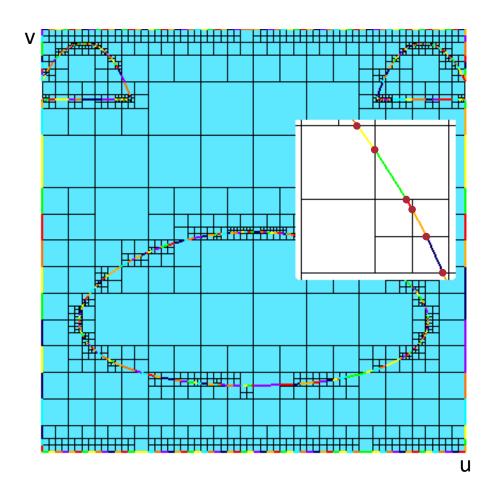


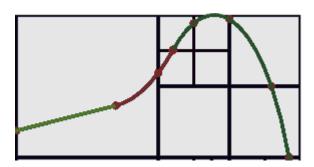




2.3. Insert and merge edges into the quadtree

Generally one trace per leaf

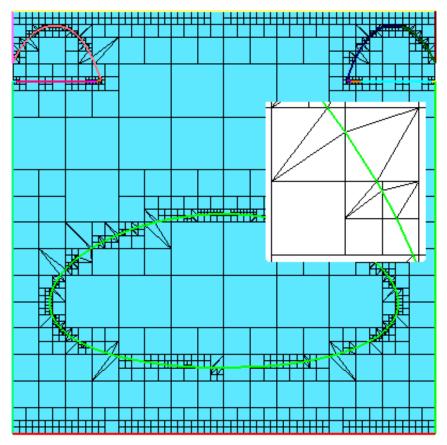


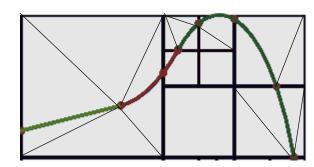




2.4. Build a leaf-triangulation

- Constrained "triangulations": in fact triangles and quadrilaterals
- If there is an interior vertex, it is "starred"
- Otherwise, simple general algorithm (with particular cases for 0, 1 or 2 traces crossing the leaf)





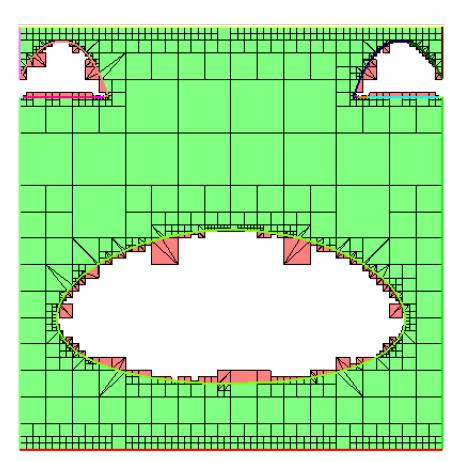


2.5. Identify all the elements of the leaf-triangulation

- Seed touching the contour of the unit square: inside or outside
- Grow by adjacency between elements or leaves

inside

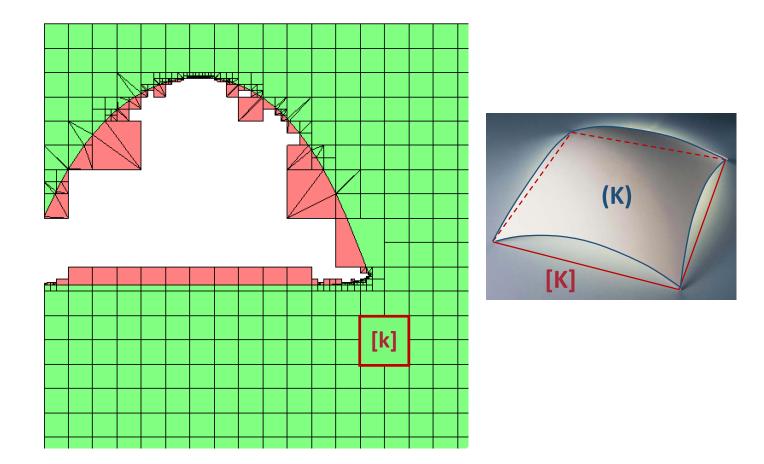
outside





2.6. Make a surface geometric support

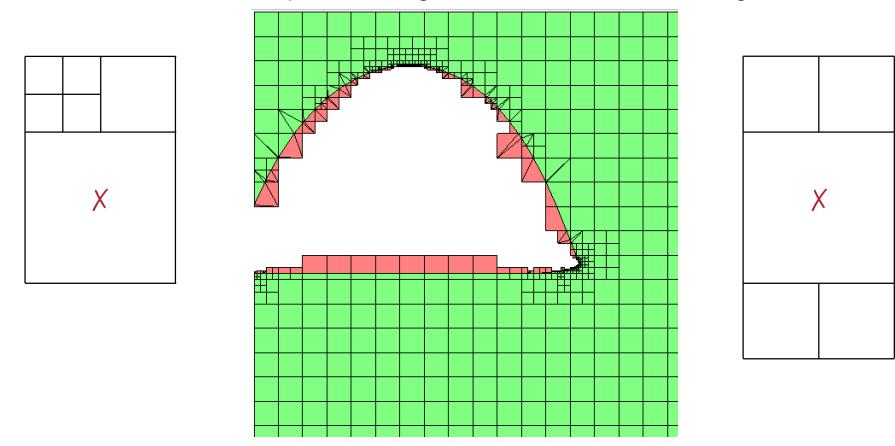
- [k] element in 2D, [K] element in 3D images of vertices, (K) = $\sigma([k])$
- Proximity d₀((K), [K]) where d₀ is a distance





2.7. Balance the quadtree

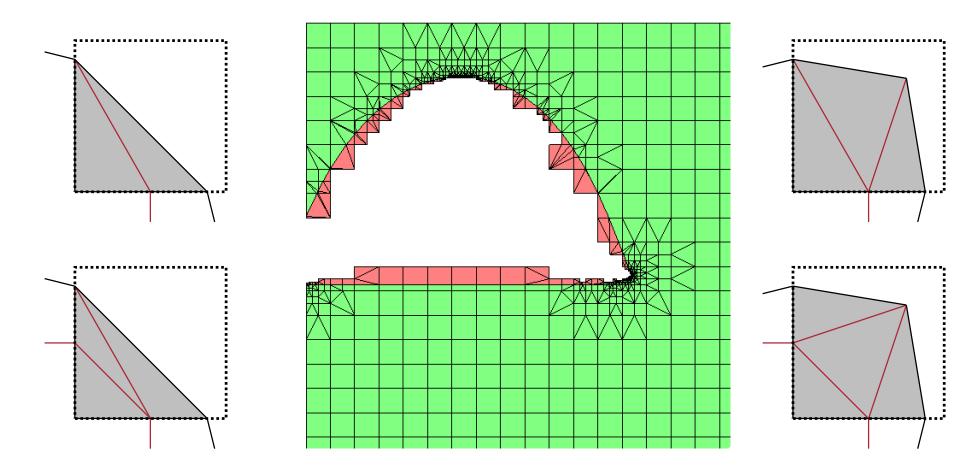
- Impose 2:1 rule between neighboring leaves (in fact a stricter rule)
- This makes the next step of building a conformal domain-triangulation easier





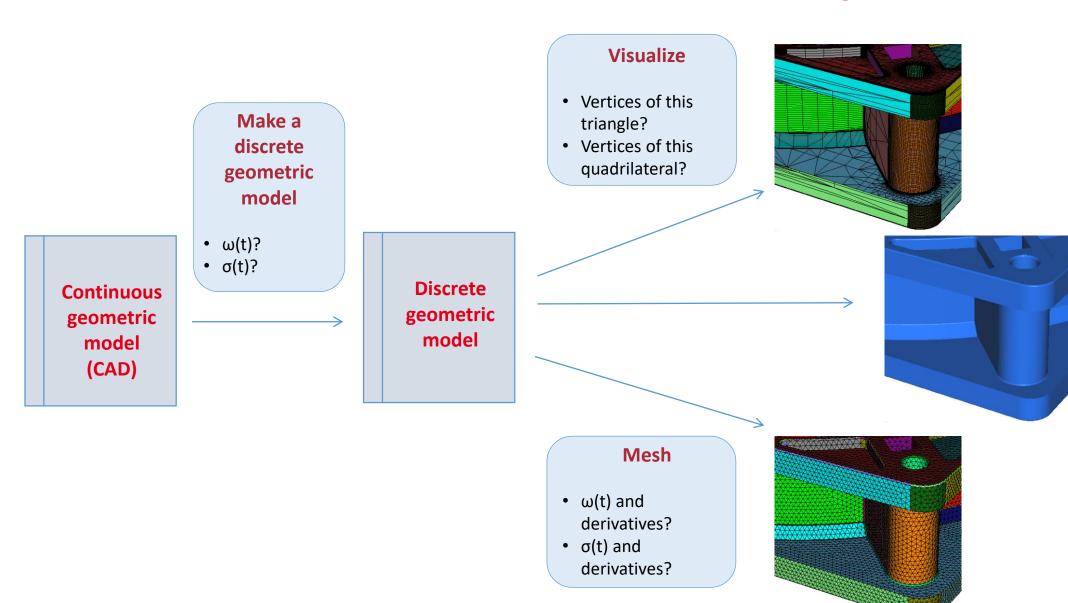
2.8. Make a conformal domain-triangulation

- [k] is a triangle or a quadrilateral
- Only 0, 1, or 2 hanging points on 2 adjacent edges





Geometric model, visualization, meshing



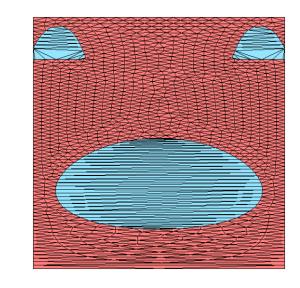


3. Surface meshing

• Idea: mesh parametric domain Ω w.r.t induced metric in Ω

$$M_{2} = \begin{pmatrix} S_{u}^{T} \\ S_{v}^{T} \end{pmatrix} M_{3} \begin{pmatrix} S_{u} & S_{v} \end{pmatrix} \qquad M_{2} = \frac{1}{h^{2}(P)} \begin{pmatrix} \langle S_{u}, S_{u} \rangle & \langle S_{u}, S_{v} \rangle \\ \langle S_{v}, S_{u} \rangle & \langle S_{v}, S_{v} \rangle \end{pmatrix} = \frac{1}{h^{2}(P)} M_{S}$$

- For each surface patch, σ(u,v) is approximated by a piecewise polynomial function
- Similarly for each **curve**, $\omega(t)$ is approximated by a piecewise polynomial function
- First order derivatives of σ ($\sigma_u(u,v)$, $\sigma_v(u,v)$ and $M_{\sigma}(u,v)$) and ω ($\omega_t(t)$), are approximated by polynomial functions
- Second order derivatives of σ and ω are also approximated by polynomial functions, for curvature dependent meshes

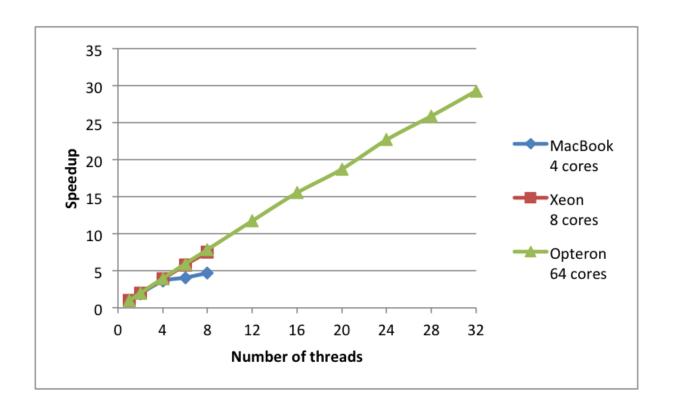




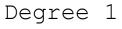


4. Examples

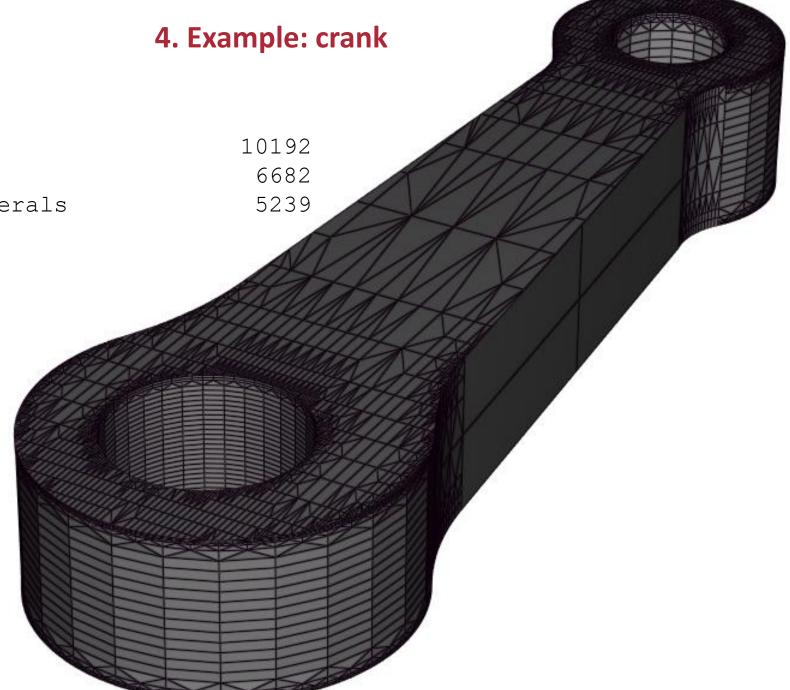
- Two examples: crank and aircraft
- Parallel meshing: almost linear scaling



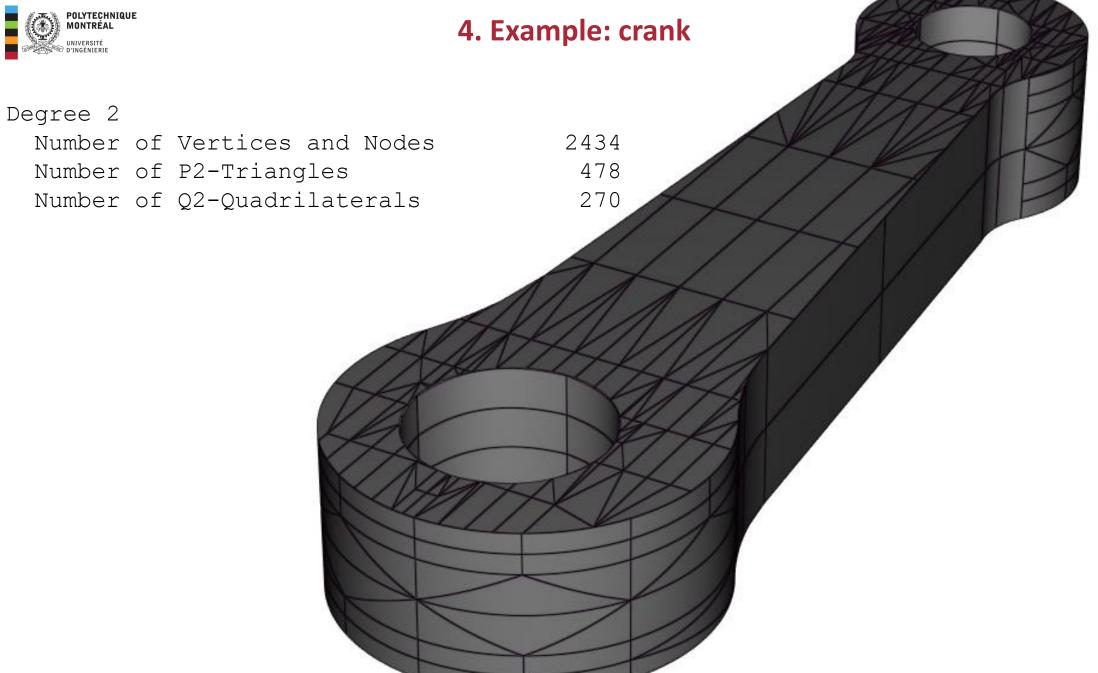




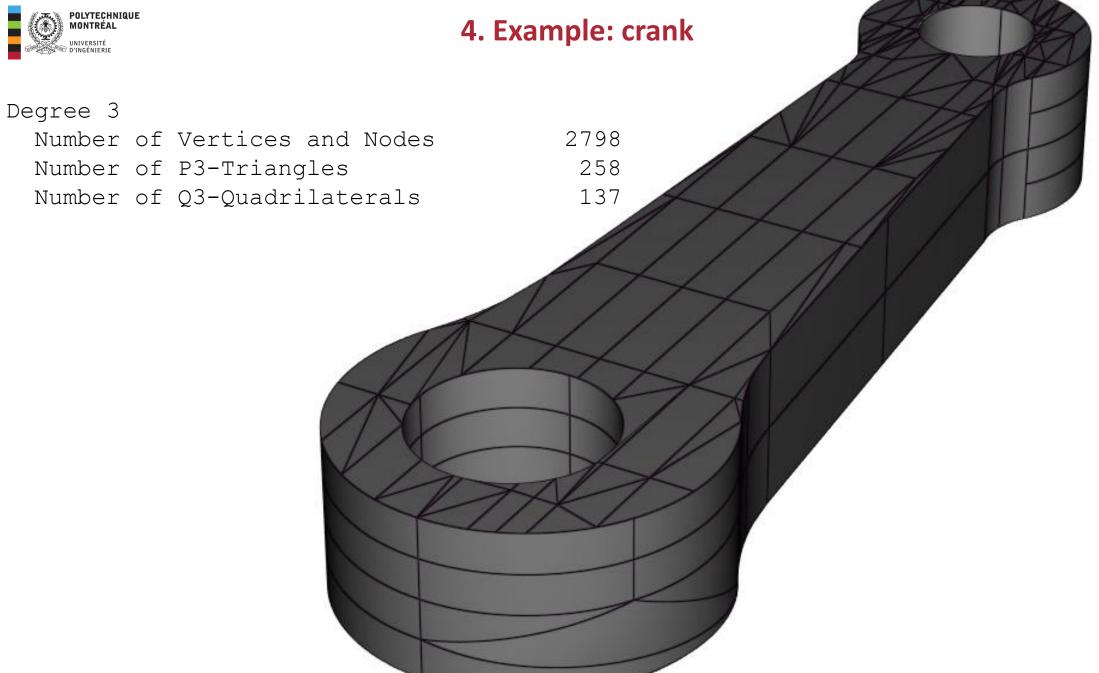
Number of Vertices Number of Triangles Number of Quadrilaterals



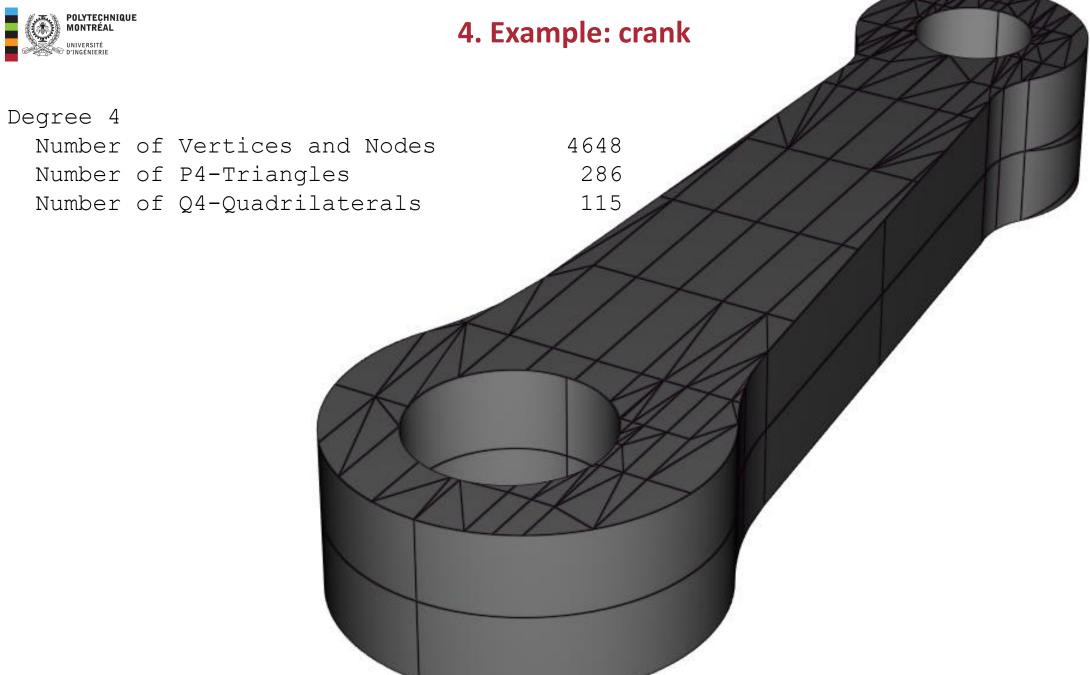














5. Conclusions

- New method for building a high-order discrete CAD model
- Most elements are aligned with iso-parametric curves ⇒ accurate description of the surface geometry
- Fast and robust ⇒ visualization
- Also meshing for numerical simulations: efficiency, non-degenerate and piecewise constant derivatives, parallelism
- Work in progress:
 - Complete distance evaluation
 - Parallelization of high-order meshing



THANK YOU!





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