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Novel computational methods for electromagnetic problems in complex nonlinear materials

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Novel computational methods for electromagnetic problems in complex perilinear materials



Guide the drilling trajectory using "real-time" magnetic measurements

Geosteering



Reproduce the measurements using finite element discretizations

Finite element discretizations are build on a mesh of the domain.

A mesh is fitting if the physical interfaces are aligned with faces. The physical coefficients are constant (or smooth) inside each element.

A non-fitting mesh is generated independently of the physical coefficients.

Fitting mesh vs non-fitting mesh





Non-fitting mesh



Non-fitting mesh for geosteering



Main advantages of non-fitting meshes:

- simplified mesh generation (Cartesian grids)
- minimize remeshing
- larger elements

Possible drawbacks of non-fitting meshes:

- quadrature schemes to integrate the linear system coefficients
- possible accuracy loss

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- possible accuracy loss



- 1 Maxwell's equations
- 2 The magnetic formulation
- 3 The electric formulation
- 4 Numerical results
- 5 Conclusions

Outline

1 Maxwell's equations

- 2 The magnetic formulation
- 3 The electric formulation
- 4 Numerical results
- **5** Conclusions

Find $\boldsymbol{E}, \boldsymbol{H}: \Omega \to \mathbb{C}^3$ such that

$$\left\{ \begin{array}{rcl} \boldsymbol{\nabla} \times \boldsymbol{\boldsymbol{\mathsf{E}}} & - & i\omega\mu_0\boldsymbol{\boldsymbol{\mathsf{H}}} & = & \boldsymbol{\boldsymbol{\mathsf{M}}}, \\ \boldsymbol{\nabla} \times \boldsymbol{\boldsymbol{\mathsf{H}}} & + & \sigma\boldsymbol{\boldsymbol{\mathsf{E}}} & = & \boldsymbol{\boldsymbol{\mathsf{J}}}, \end{array} \right.$$

where

■ *M*, *J* are given load terms (electric and/or magnetic dipoles),

 $\blacksquare~\omega$ is the operating frequency,

• $\mu_0 = 4\pi \times 10^{-7} \text{ NA}^{-2}$ is the vacuum permeability,

• $\sigma: \Omega \to \mathbb{R}$ is the conductivity model.

The medium is strongly dissipative $(i\epsilon\omega + \sigma \simeq \sigma)$. The conductivity σ is piecewise constant.

The permeability μ_0 is **constant**.

We are mostly interested in magnetic measurements.

In the following, we focus on the case where:

- Ω is convex,
- the medium is layered ($\sigma \simeq \sigma(z)$).

Magnetic field regularity

$$\pmb{H} \in \left(H^1(\Omega) \right)^3$$

Electric field regularity

$${oldsymbol E}|_{\Omega_l}\in \left(H^1(\Omega_l)
ight)^3 \qquad {oldsymbol E}\in \left(H^{1/2-arepsilon}(\Omega)
ight)^3$$

Approximation of \pmb{H}

$$\|\boldsymbol{H}-\boldsymbol{\pi}_{h}\boldsymbol{H}\|_{0,\Omega}\simeq h$$

Approximation of *E* with fitting meshes

$$\|\boldsymbol{E} - \boldsymbol{\pi}_h \boldsymbol{E}\|_{0,\Omega} \simeq h$$

Approximation of *E* with non-fitting meshes

$$\|\boldsymbol{\boldsymbol{\mathcal{E}}}-\boldsymbol{\pi}_h\boldsymbol{\boldsymbol{\mathcal{E}}}\|_{0,\Omega}\simeq h^{1/2-arepsilon}$$

Standard approximation theory (Céa's Lemma) yields:

Fitting meshes $\|\boldsymbol{E} - \boldsymbol{E}_h\|_{0,\Omega} + \|\boldsymbol{H} - \boldsymbol{H}_h\|_{0,\Omega} \simeq h$

Non-fitting meshes

$$\|\boldsymbol{E} - \boldsymbol{E}_h\|_{0,\Omega} + \|\boldsymbol{H} - \boldsymbol{H}_h\|_{0,\Omega} \simeq h^{1/2}$$

Given that H is globally regular, is the convergence rate of H_h sharp?

Remark on the general case

In general, the regularity of *E* depends on σ

Regularity of *E*

$${\pmb E} \in \left(H^{ au(\sigma)}(\Omega)
ight)^3$$

where $0 < \tau(\sigma) < 1/2$.

Interpolation errors

$$\|\boldsymbol{H} - \boldsymbol{\pi}_h \boldsymbol{H}\|_{0,\Omega} \simeq h \qquad \|\boldsymbol{E} - \boldsymbol{\pi}_h \boldsymbol{E}\|_{0,\Omega} \simeq h^{\tau(\sigma)}$$

Interpolation errors

$$\|\boldsymbol{E} - \boldsymbol{\pi}_h \boldsymbol{E}\|_{0,\Omega} + \|\boldsymbol{H} - \boldsymbol{\pi}_h \boldsymbol{H}\|_{0,\Omega} \simeq h^{\tau(\sigma)}$$



1 Maxwell's equations

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We recast Maxwell's equation into a second-order system:

$$\begin{cases} -i\omega\mu_0\boldsymbol{H} + \boldsymbol{\nabla} \times \left(\sigma^{-1}\boldsymbol{\nabla} \times \boldsymbol{H}\right) &= \boldsymbol{M} \quad \text{in } \Omega, \\ \left(\sigma^{-1}\boldsymbol{\nabla} \times \boldsymbol{H}\right) \times \boldsymbol{n} &= \boldsymbol{0} \quad \text{on } \partial\Omega \end{cases}$$

We obtain $\boldsymbol{E} \simeq \boldsymbol{\nabla} \times \boldsymbol{H}$ by post-processing.

Variational formulation

Find $H \in H(\mathbf{curl}, \Omega)$ such that

$$b(\boldsymbol{H},\boldsymbol{v})=(\boldsymbol{M},\boldsymbol{v})$$

for all $\mathbf{v} \in H(\mathbf{curl}, \Omega)$.

$$b(\boldsymbol{H},\boldsymbol{v}) = -i\omega\mu_0(\boldsymbol{H},\boldsymbol{v}) + (\sigma^{-1}\boldsymbol{\nabla}\times\boldsymbol{H},\boldsymbol{\nabla}\times\boldsymbol{v})$$

We consider first-order Nédélec elements on a mesh $\mathcal{T}_h = \{K\}$:

$$\boldsymbol{V}_h = \left\{ \boldsymbol{v}_h \in H(\operatorname{curl}, \Omega) \mid \boldsymbol{v}_h|_{\mathcal{K}} = \boldsymbol{a} \times \boldsymbol{x} + \boldsymbol{b}, \ \boldsymbol{a}, \boldsymbol{b} \in \mathbb{C}^3
ight\}.$$

Discrete variational formulation

Find $H_h \in V_h$ such that

$$b(\boldsymbol{H}_h, \boldsymbol{v}_h) = (\boldsymbol{M}, \boldsymbol{v}_h)$$

for all $\boldsymbol{v}_h \in \boldsymbol{V}_h$.

Assuming that $\boldsymbol{M} \in H(\operatorname{div}, \Omega)$:

Regularity

$$oldsymbol{H} \in \left(H^1(\Omega)
ight)^3 \qquad oldsymbol{
abla} imes oldsymbol{H} \in \left(H^{1/2-arepsilon}(\Omega)
ight)^3$$

Interpolation error

$$\|oldsymbol{H}-oldsymbol{\pi}_{h}oldsymbol{H}\|_{0,\Omega}\lesssim h\|oldsymbol{M}\|_{ ext{div},\Omega} \quad \|oldsymbol{
abla} imes(oldsymbol{H}-oldsymbol{\pi}_{h}oldsymbol{H})\|_{0,\Omega}\lesssim h^{1/2-arepsilon}\|oldsymbol{M}\|_{0,\Omega}$$

Error estimate (Céa's Lemma)

$$\|oldsymbol{H}-oldsymbol{H}_{h}\|_{0,\Omega}+\|oldsymbol{
abla} imes(oldsymbol{H}-oldsymbol{H}_{h})\|_{0,\Omega}\lesssim h^{1/2-arepsilon}\|oldsymbol{M}\|_{ ext{div},\Omega}$$

We have

Interpolation error

$$\|oldsymbol{H}-oldsymbol{\pi}_{h}oldsymbol{H}\|_{0,\Omega}\lesssim h\|oldsymbol{M}\|_{ extsf{div},\Omega}$$

but only

Error estimate

$$\|oldsymbol{H}-oldsymbol{H}_{h}\|_{0,\Omega}\lesssim h^{1/2-arepsilon}\|oldsymbol{M}\|_{ extsf{div},\Omega}$$

Can we improve this error estimate? Yes!

Consider the simpler problem

$$\begin{cases} \boldsymbol{u} - \Delta \boldsymbol{u} = \boldsymbol{f} & \text{in } \Omega, \\ \boldsymbol{\nabla} \boldsymbol{u} \cdot \boldsymbol{n} = \boldsymbol{0} & \text{on } \partial \Omega, \end{cases}$$

where $f \in L^2(\Omega)$.

Using Lagrange elements, we are in the similar situation where:

Interpolation error

$$\|\boldsymbol{u}-\pi_{\boldsymbol{h}}\boldsymbol{u}\|_{0,\Omega}\lesssim h^2\|f\|_{0,\Omega}$$

Error estimate (Céa's lemma)

$$\|\boldsymbol{u}-\boldsymbol{u}_h\|_{0,\Omega}\lesssim h\|f\|_{0,\Omega}$$

Introduce ξ as the unique solution to

$$a(w,\xi) = (w, u - u_h), \quad \forall w \in H^1(\Omega).$$

Then, selecting $w = u - u_h$

$$\|\boldsymbol{u}-\boldsymbol{u}_h\|_{0,\Omega}^2 = \boldsymbol{a}(\boldsymbol{u}-\boldsymbol{u}_h,\xi) = \boldsymbol{a}(\boldsymbol{u}-\boldsymbol{u}_h,\xi-\pi_h\xi) \lesssim \|\boldsymbol{u}-\boldsymbol{u}_h\|_{1,\Omega}\|\xi-\pi_h\xi\|_{1,\Omega}.$$

We observe that ξ is solution to

$$\begin{cases} \boldsymbol{\xi} - \Delta \boldsymbol{\xi} &= \boldsymbol{u} - \boldsymbol{u}_h & \text{ in } \Omega, \\ \boldsymbol{\nabla} \boldsymbol{\xi} \cdot \boldsymbol{n} &= \boldsymbol{0} & \text{ on } \partial \Omega, \end{cases}$$

and $\pmb{\xi}\in H^2(\Omega)$ with

$$|\boldsymbol{\xi}|_{2,\Omega} \lesssim \|\boldsymbol{u} - \boldsymbol{u}_h\|_{0,\Omega}$$

since $\mathbf{u} - \mathbf{u}_h \in L^2(\Omega)$.

Hence,

$$\begin{aligned} \|u - u_h\|_{0,\Omega}^2 &\lesssim \|u - u_h\|_{1,\Omega} \|\xi - \pi_h \xi\|_{1,\Omega} \\ &\lesssim h \|u - u_h\|_{1,\Omega} |\xi|_{2,\Omega} \\ &\lesssim h \|u - u_h\|_{1,\Omega} \|u - u_h\|_{0,\Omega}. \end{aligned}$$

Error estimate

$$\|\boldsymbol{u}-\boldsymbol{u}_h\|_{0,\Omega}\lesssim h\|\boldsymbol{u}-\boldsymbol{u}_h\|_{1,\Omega}\lesssim h^2\|f\|_{0,\Omega}$$

Direct application fails. Indeed, if we let $\boldsymbol{\xi}$ solve

$$m{b}(m{w},m{\xi})=(m{w},m{H}-m{H}_h), \quad orall m{w}\in H(ext{curl},\Omega),$$

then $\boldsymbol{\xi} \notin (H^1(\Omega))^3$ because $\boldsymbol{H} - \boldsymbol{H}_h \notin H(\operatorname{div}, \Omega)$.

The key idea is to introduce the Helmhotlz-Hodge decomposition

$$H - H_h = \phi + \nabla p.$$

with $\nabla \cdot \phi = 0$.

We employ the "Aubin-Nitsche trick" to estimate $\|\phi\|_{0,\Omega}$.

Additional "orthogonality" arguments are used to estimate $\|\nabla p\|_{0,\Omega}$.



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For regular solution $\tau(\sigma) > 1/2$:



L. Zhong, S. Shu, G. Wittum and J. Xu J. Computational Mathematics 2009

General case (done in the same time):



A. Ern and J.L. Guermond Computer & Mathematics with Applications 2018

Error estimate

$$\|oldsymbol{H}-oldsymbol{H}_h\|_{0,\Omega}\lesssim h^{1-2arepsilon}\|oldsymbol{M}\|_{ ext{div},\Omega}$$

We can remove the " -2ε " if we employ "non-Sobolev" interpolation spaces.

The convergence rate is linear, as in the case of fitting meshes.



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Another option is to consider the second-order system:

$$\begin{cases} -i\omega\mu_0\sigma\mathbf{E} + \nabla\times\nabla\times\mathbf{E} &= \mathbf{J} \quad \text{in } \Omega, \\ \mathbf{E}\times\mathbf{n} &= \mathbf{0} \quad \text{on } \partial\Omega, \end{cases}$$

and post-process $\boldsymbol{H} \simeq \boldsymbol{\nabla} \times \boldsymbol{\boldsymbol{E}}.$

Variational formulation

Find $\boldsymbol{E} \in H_0(\operatorname{curl}, \Omega)$ such that

$$b(\boldsymbol{E}, \boldsymbol{v}) = (\boldsymbol{J}, \boldsymbol{v})$$

for all $\mathbf{v} \in H_0(\mathbf{curl}, \Omega)$.

$$b(\boldsymbol{E}, \boldsymbol{v}) = -i\omega\mu_0(\sigma \boldsymbol{E}, \boldsymbol{v}) + (\boldsymbol{\nabla} \times \boldsymbol{E}, \boldsymbol{\nabla} \times \boldsymbol{v})$$

We consider first-order Nédélec elements on a mesh $\mathcal{T}_h = \{K\}$:

$$oldsymbol{V}_h = \left\{oldsymbol{v}_h \in H_0(\operatorname{curl},\Omega) \mid oldsymbol{v}_h|_{K} = oldsymbol{a} imes oldsymbol{x} + oldsymbol{b}, \ oldsymbol{a}, oldsymbol{b} \in \mathbb{C}^3
ight\}.$$

Discrete variational formulation

Find $\boldsymbol{E}_h \in \boldsymbol{V}_h$ such that

$$b(\boldsymbol{E}_h, \boldsymbol{v}_h) = (\boldsymbol{J}, \boldsymbol{v}_h)$$

for all $\boldsymbol{v}_h \in \boldsymbol{V}_h$.

Error estimate

Assuming that $J \in H(\operatorname{div}, \Omega)$

Regularity

$$oldsymbol{E}\in \left(H^{1/2-arepsilon}(\Omega)
ight)^3 \qquad oldsymbol{
abla} imesoldsymbol{E}\in \left(H^1(\Omega)
ight)^3$$

Interpolation error

$$\|m{E}-m{\pi}_hm{E}\|_{0,\Omega}\lesssim h^{1/2-arepsilon}\|m{J}\|_{ ext{div},\Omega} \quad \|m{
abla} imes(m{E}-m{\pi}_hm{E})\|_{0,\Omega}\lesssim h\|m{J}\|_{0,\Omega}$$

Error estimate (Céa's Lemma)

$$\|oldsymbol{E}-oldsymbol{E}_{h}\|_{0,\Omega}+\|oldsymbol{
abla} imes(oldsymbol{E}-oldsymbol{E}_{h})\|_{0,\Omega}\lesssim h^{1/2-arepsilon}\|oldsymbol{J}\|_{ ext{div},\Omega}$$

We have

Interpolation error

$$\|oldsymbol{
abla} imes(oldsymbol{E}-oldsymbol{\pi}_holdsymbol{E})\|_{0,\Omega}\lesssim h\|oldsymbol{J}\|_{ ext{div},\Omega}$$

but only

Error estimate

$$\|oldsymbol{
abla} imes(oldsymbol{E}-oldsymbol{E}_{h})\|_{0,\Omega}\lesssim h^{1/2-arepsilon}\|oldsymbol{J}\|_{ ext{div},\Omega}$$

Can we improve this error estimate? Yes!

Let $\phi \in H_0(\operatorname{curl}, \Omega)$ solve

$$b(w, \phi) = (\nabla \times w, \nabla \times (\boldsymbol{E} - \boldsymbol{E}_h)), \quad \forall w \in H_0(\operatorname{curl}, \Omega),$$

so that

$$\|\boldsymbol{\nabla} \times (\boldsymbol{E} - \boldsymbol{E}_h)\|_{0,\Omega}^2 = b(\boldsymbol{E} - \boldsymbol{E}_h, \boldsymbol{\phi}) = b(\boldsymbol{E} - \boldsymbol{E}_h, \boldsymbol{\phi} - \boldsymbol{\pi}_h \boldsymbol{\phi}).$$

Intermediate error estimate

$$\|oldsymbol{
abla} imes(oldsymbol{E}-oldsymbol{E}_h)\|_{0,\Omega}^2\lesssim h^{1/2-arepsilon}\left(\|oldsymbol{\phi}-oldsymbol{\pi}_holdsymbol{\phi}\|_{0,\Omega}+\|oldsymbol{
abla} imes(oldsymbol{\phi}_h-oldsymbol{\pi}_holdsymbol{\phi})\|_{0,\Omega}
ight)\|oldsymbol{J}\|_{ ext{div},\Omega}.$$

It remains to estimate the interpolation errors in the right-hand side.

Since $\phi \in H_0(\mathbf{curl}, \Omega)$ is solution to

$$b(\mathbf{w}, \phi) = (\mathbf{\nabla} imes \mathbf{w}, \mathbf{\nabla} imes (\mathbf{E} - \mathbf{E}_h)), \quad \forall \mathbf{w} \in H_0(\operatorname{curl}, \Omega),$$

we can show that $\phi \in (H^{1/2 - \varepsilon}(\Omega))^3$ with
 $|\phi|_{1/2 - \varepsilon, \Omega} \lesssim ||\mathbf{\nabla} imes (\mathbf{E} - \mathbf{E}_h)||_{0,\Omega}.$

First interpolation error estimate

$$\| oldsymbol{\phi} - oldsymbol{\pi}_h oldsymbol{\phi} \|_{0,\Omega} \lesssim h^{1/2-arepsilon} \| oldsymbol{
abla} imes (oldsymbol{E} - oldsymbol{E}_h) \|_{0,\Omega}$$

We have

$$\|oldsymbol{
abla} imesoldsymbol{\phi}\|_{0,\Omega}\lesssim\|oldsymbol{
abla} imes(oldsymbol{E}-oldsymbol{E}_h)\|_{0,\Omega},$$

but we cannot extend this result to

 $|\mathbf{\nabla} \times \boldsymbol{\phi}|_{s,\Omega}$

for s > 0, because $\nabla \times (\boldsymbol{E} - \boldsymbol{E}_h) \notin H(\operatorname{curl}, \Omega)$.

We cannot estimate

 $\| \boldsymbol{\nabla} imes (\boldsymbol{\phi} - \boldsymbol{\pi}_h \boldsymbol{\phi}) \|_{0,\Omega}$

directly.

We introduce $\psi = \phi - (\boldsymbol{E} - \boldsymbol{E}_h)$. We see that

$$b(\mathbf{v}, \boldsymbol{\psi}) = b(\mathbf{v}, \boldsymbol{\phi}) - b(\mathbf{v}, \mathbf{E} - \mathbf{E}_h)$$

= $(\nabla \times \mathbf{v}, \nabla \times (\mathbf{E} - \mathbf{E}_h)) - b(\mathbf{v}, \mathbf{E} - \mathbf{E}_h)$
= $-i\omega\mu_0(\mathbf{v}, \sigma(\mathbf{E} - \mathbf{E}_h)).$

We can show that ${oldsymbol
abla} imes {oldsymbol \psi} \in (H^1(\Omega))^3$ with

 $|\mathbf{\nabla} imes \psi|_{1,\Omega} \lesssim \|\mathbf{E} - \mathbf{E}_h\|_{0,\Omega}.$

Intermediate interpolation result

$$\|oldsymbol{
abla} imes (oldsymbol{\psi}-oldsymbol{\pi}_holdsymbol{\psi})\|_{0,\Omega}\lesssim h\|oldsymbol{E}-oldsymbol{E}_h\|_{0,\Omega}\lesssim h^{3/2-arepsilon}\|oldsymbol{J}\|_{ ext{div},\Omega}$$

We have $\phi = \mathbf{E} - \mathbf{E}_h + \psi$, thus

$$\phi - \pi_h \phi = \mathbf{E} - \pi_h \mathbf{E} - \underbrace{(\mathbf{E}_h - \pi_h \mathbf{E}_h)}_{=0} + \psi - \pi_h \psi,$$

and

$$\| oldsymbol{
abla} imes (oldsymbol{\phi} - oldsymbol{\pi}_h oldsymbol{\phi}) \|_{0,\Omega} \lesssim \| oldsymbol{
abla} imes (oldsymbol{E} - oldsymbol{\pi}_h oldsymbol{E}) \|_{0,\Omega} + \| oldsymbol{
abla} imes (oldsymbol{\psi} - oldsymbol{\pi}_h oldsymbol{\psi}) \|_{0,\Omega}.$$

Second interpolation error estimate

$$\|oldsymbol{
abla} imes (oldsymbol{\phi}-oldsymbol{\pi}_holdsymbol{\phi})\|_{0,\Omega}\lesssim \left(h+h^{3/2-arepsilon}
ight)\|oldsymbol{J}\|_{{
m div},\Omega}.$$

We regroup the intermediate results:

$$\| oldsymbol{
abla} imes (oldsymbol{E} - oldsymbol{E}_h) \|_{0,\Omega} \lesssim h^{1/2-arepsilon} \left(h^{1/2-arepsilon} + h + h^{3/2-arepsilon}
ight) \| oldsymbol{J} \|_{ ext{div},\Omega}.$$

Error estimate

$$\|oldsymbol{
abla} imes(oldsymbol{E}-oldsymbol{E}_{h})\|_{0,\Omega}\lesssim h^{1-2arepsilon}\|oldsymbol{J}\|_{{
m div},\Omega}$$

We can remove the " -2ε " if we employ "non-Sobolev" interpolation spaces.

The convergence rate is linear, as in the case of fitting meshes.

Surprisingly $\nabla \times \boldsymbol{E}_h$ converges faster than \boldsymbol{E}_h in $L^2(\Omega)$ -norm!



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We assume that $\sigma(x, y, z) = \sigma(x, z)$.

$$\hat{H}_a^{\xi}(x,z) = \int_{y=-\infty}^{+\infty} \boldsymbol{H}_a(x,y,z) e^{-i\xi y} dy, \quad \hat{\boldsymbol{H}}^{\xi} = (\hat{H}_x^{\xi}, \hat{H}_y^{\xi})$$

2.5D formulation Find $(\hat{H}_{y}^{\xi}, \hat{H}^{\xi}) \in H^{1}(\hat{\Omega}) \times H(\operatorname{curl}, \hat{\Omega})$ $\begin{cases} (i\omega\mu_{0} + \xi^{2}\sigma^{-1})\hat{H}^{\xi} + \operatorname{curl}\left(\sigma^{-1}\operatorname{curl}\hat{H}^{\xi}\right) - i\xi\sigma^{-1}\nabla H_{y}^{\xi} &= M^{\xi}, \\ i\omega\mu_{0}H_{y}^{\xi} - \nabla \cdot (\sigma^{-1}\nabla H_{y}^{\xi}) + i\xi\nabla \cdot (\sigma^{-1}H^{\xi}) &= M_{y}^{\xi}. \end{cases}$

$$oldsymbol{\mathcal{H}}_{a}(x,y,z)\simeq\sum_{j=1}^{N}w_{j}\hat{oldsymbol{\mathcal{H}}}_{a}(x,z)e^{i\xi_{j}y}$$



Logging tool $(d_{TX} = 0.6 \text{ m}, d_{RX} = 0.1 \text{ m})$

$$P_{log} = \frac{1}{2} \operatorname{Im} \left(\log \frac{H_{zz}^{11}}{H_{zz}^{12}} + \log \frac{H_{zz}^{22}}{H_{zz}^{21}} \right) \quad A_{log} = \frac{1}{2} \operatorname{Re} \left(\log \frac{H_{zz}^{11}}{H_{zz}^{12}} + \log \frac{H_{zz}^{22}}{H_{zz}^{21}} \right)$$

Benchmark



Fitting (left) and non-fitting (right) meshes

Two layers: Apparent resistivity (P-log)



Two layers: Apparent resistivity (A-log)



Thin layer: Apparent resistivity (P-log)



Thin layer: Apparent resistivity (A-log)





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Assume that $\mu = \mu_0$ is constant. Assume that σ represents a layered media. Assume that J and M are sufficiently smooth. Assume that the linear system coefficients are exactly integrated.

Error estimates for fitting meshes

$$\|\boldsymbol{E} - \boldsymbol{E}_h\|_{L^2(\Omega)} = \mathcal{O}(h) \qquad \|\boldsymbol{H} - \boldsymbol{H}_h\|_{L^2(\Omega)} = \mathcal{O}(h)$$

Error estimates for non-fitting meshes

$$\|\boldsymbol{E} - \boldsymbol{E}_h\|_{L^2(\Omega)} = \mathcal{O}(h^{1/2}) \qquad \|\boldsymbol{H} - \boldsymbol{H}_h\|_{L^2(\Omega)} = \mathcal{O}(h)$$

The use of non-fitting meshes deteriorates the convergence rate of \boldsymbol{E}_h .

The convergence rate of H_h is preserved.



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Non-fitting meshes can simulate tools based on magnetic field measurements.

We have tested different quadrature schemes.

Non-fitting meshes provide accurate results with an appropriate scheme.



T. Chaumont-Frelet, D. Pardo and A. Rodrìguez-Rozàs Computational Geosciences 2018