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# A Wearable Neuro-Degenerative Diseases Classification System using Human Gait Dynamics

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**Abstract.** The increasing prevalence of neurodegenerative diseases (NDDs) impose substantial medical and public health burdens on populations throughout the world. NDDs are chronic diseases that affect the human central nervous system causing loss of neurons within the brain and/or spinal cord. This causes deterioration in movement and mental functioning of the patients. The current medications for this group of disorders are limited and aim to treat the symptoms only. A better understanding of the mechanisms underlying neurodegeneration should lead to more effective, disease-modifying treatments in the future. Continuous assessment of NDD patients is a key element of future care and treatment. This contribution proposes a wearable NDD detection system based on patient's gait dynamics using an unobtrusive force resistive sensor embedded in patient's shoe. The NDD classification is based on 3 fundamental gait features: stride time, stride time's fluctuation and the autocorrelation decay factor. It is designed to discriminate between healthy subjects and NDD patients and moreover identify the NDD type: (Huntington's disease (HD), Parkinson Disease (PD), and Amyotrophic Lateral Sclerosis (ALS)). The proposed NDD classification algorithm is implemented on FPGA and verified experimentally using Gait Dynamics dataset from Physionet. It offers a classification accuracy of 93.8%, 89.1%, 94% and 93.3%, for ALS, HD, PD, and healthy person, respectively, from a total set of 64 subjects.

**Keywords:** Amyotrophic Lateral Sclerosis (ALS), Huntington's disease, Parkinson disease, Neurodegenerative disorders, classifier, wearable sensor.

## 1 Introduction

Patients with Neurodegenerative diseases (NDDs) suffer from medical conditions that directly affect the neurons within the brain [1]. NDDs cause changes in neuromuscular control causing degradation in muscle movements control, muscle tone, involuntary movements and smoothness of movement. One of the key diagnostic approaches for defining the NDD is the study of patient's gait [2-4]. Parkinson's disease

(PD), Huntington's disease (HD) and Amyotrophic Lateral Sclerosis (ALS) are the main types of NDDs deteriorating the patient's gait [1].

### **1.1 Parkinson's disease**

PD is a chronic and progressive movement disorder causing trembling in the hands, arms, legs, jaw, and face, stiffness the limbs and trunk, slowed movement, and impaired balance and coordination [5]. After Alzheimer, PD is the second most common neurodegenerative disease affecting approximately 1 million Americans (estimates range between 4 and 6.5 million people worldwide) and about 1% of older adults. It usually affects people over the age of 50 [5]. In the US alone, 60,000 new cases are diagnosed with PD each year. There is currently no accurate test for the diagnosis of PD and it is highly uncertain in the early stages of the disease. These symptoms usually begin gradually and worsen with time. The gait of PD patients is characterized by small shuffling steps and a general slowness of movement [3]. The stride length and walking speed during free ambulation are also reduced.

### **1.2 Huntington's disease**

HD is a genetic NDD that affects muscle coordination and leads to cognitive decline and physical, mental and emotional changes [6]. It is estimated that around 30,000 people in the US only are affected by HD, and more than 150,000 people have ~50% potential risk of developing HD. Patients with HD are not able to think, talk and move properly [6-7]. This disease is responsible for destroying the cells in the basal ganglia, the part of the brain that controls these capacities. HD usually develops at mid-age and can cause a very wide range of symptoms. The general symptoms in early stages can include a poor memory; difficulty in making decisions; mood changes such as depression, anger or irritability; a growing lack of coordination, twitching or other uncontrolled movements; difficulty in walking, speaking or swallowing [8-9].

### **1.3 Amyotrophic Lateral Sclerosis (ALS)**

ALS is known as motor neuron disease characterized by progressive weakness, difficulty in speaking, swallowing, breathing, muscle twitching (involuntary muscle contraction and relaxation), and muscle stiffness. The patients suffering from ALS have difficulty in maintaining regular normal locomotion [10]. The earliest signs of ALS include muscles weakness of arms and legs that eventually, prevent the patients from walking and talking and be bedridden. The spreading rate of ALS disease is 1 to 2 per 100,000 each year, most cases of which are sporadic while 5%-10% are inherited. The treatment of ALS is very limited. It becomes necessary to understand the pathological mechanism of this disease.

#### **1.4 The fall risk**

An important risk factor for NDDs at old age is the increasing fall chances. PD-old patients suffer falls more frequently compared to healthy old people which increase the chances of injuries and may lead to death [9],[11-12]. Currently, the most common practice to analyze and evaluate the progress of the treatment in NDD patients is mainly based on interviewing the patients. However, depending only on the information provided by patients can produce misleading data. A more practical and successful approach is to assess the physical functional performance of patients', which helps the physicians to create a more effective treatment plan and more technical assessment of the results of the treatment [1]. Therefore, it is desirable to have a non-invasive wearable continuous gait monitoring system that provides quantitative analysis to detect and classify any movement disorders through monitoring the gait dynamics of the NDD patient. For such system, it is more applicable to utilize wearable sensors with a detection algorithm since it can be used anywhere and not limited to certain location and it does not cause discomfort for the patient.

#### **1.5 Goal of this work**

The primary goal of this work is to study and distinguish the gait dynamics of the NDD patients and compare it with healthy individuals. Specifically, we compare how the three different types of NDDs (PD, HD, and ALS) degrade the patient's ability to control the movement of two feet. This contribution proposes a wearable gait dynamics detection system that will be utilized with foot sensors implanted on the shoe of the patient to analyze the gait dynamics and identify the corresponding NDD disease.

The contribution is structured as follows. First, we give an overview of related work that covers approaches for classifying the gait dynamics in each NDD in Sec. 2. Following this, we explain the proposed Wearable NDD Detection System in Sec. 3. In Sec. 4, we describe the NDD classification algorithm and define a number of comparison criteria in order to show the strengths of our approach. Finally, the results of the discussion are presented in Sec. 5 in which we point out the achieved benefits.

### **2 Previous Work**

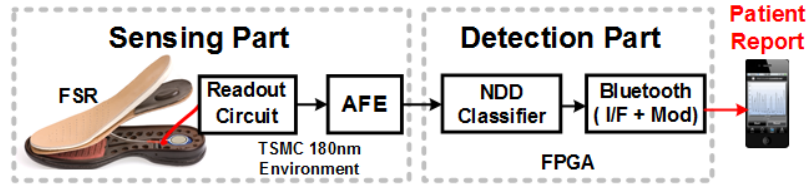
The analysis of the gait dynamics of NDD patients has been widely applied for studying movement patterns in NDD patients. Multiple recent studies record the gait dynamics in different NDD patients and extract various features to distinguish each NDD [12-20]. Ref. [1] utilized a deterministic learning method that divides the classification process into two phases: a training phase followed by a classification phase using neural networks to categorize the gait dynamics. The gait data of the patients suffering from NDDs were recorded using foot switches with Support Vector Machine (SVM) classifier. The classification results that ALS can be more easily distinguished from PD with an accuracy of 85.47%, HD with an accuracy of 86.52% and the healthy subjects with an accuracy of 93.96% [15]. The swing time series from a patient with PD and a control subject under usual walking conditions were studied in [12] and classified based

on Coefficient of variability (CV). Detrended Fluctuation Analysis (DFA) was also used to analyze the fluctuation of the gait cycle based on 200 meters walk of 17 PD patients and 12 healthy young people tests as reported in [16]. The least-squares support vector machine (LS-SVM) was used to distinguish the stride patterns between the ALS patients and healthy controls with an accuracy of 82.8% using data recordings from Physionet.org [17]. An Associated Discrete Index (ADI) was defined in [18] in order to measure the discrete degree at the same frequency. 93 patients with PD and 72 healthy controls were selected. Foot pressure was analyzed including vertical ground reaction force. Power spectra were obtained to compare gait signals of PD and control subjects. Compared with PD patient, the frequency features of gait in control subject are more random, since the spectral lines are loose as well as different with others. On the other hand, those lines in PD patient are comparatively close to each other. This feature can be indicated by ADI, which shows that PD patients always possess larger ADI than that of control subjects [18]. Ref. [19] presented an algorithm to analyze a gait pattern in PD patients using deep brain stimulation (DBS). Features were extracted to classify the PD subjects from healthy control subjects with deep brain stimulation (DBS). A mobile sensor based gait analysis system to measure gait patterns in PD and to distinguish mild and severe impairment of gait was proposed in [20]. Gait test was performed using sports shoes equipped with inertial sensors. The signals were recorded for both left and right foot, and the features were extracted and classified using different classification algorithm. The sensitivity and specificity were obtained 88% and 86% respectively.

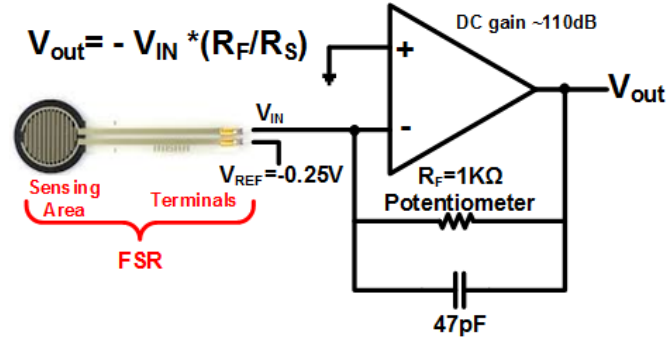
### 3 Proposed Wearable NDD Detection System

The proposed wearable NDD detection system is composed of a sensing part simulated using CMOS 180nm technology and a detection algorithm implemented on Field Programmable Gate Array (FPGA) as shown in Fig. 1 [25]. The sensing part is based on Flexi-force resistor (FSR) that measure the force between two surfaces. FSR is robust against most environmental variations [26]. The FSR single element force sensor acts as a force sensing resistor in an electrical circuit. The resistance can be read by connecting a multimeter to the outer two pins, then applying a force to the sensing area. The FSR force sensor is an ultra-thin, flexible printed circuit where the force sensor is constructed of two layers of substrate (polyester/polyamide) film, which does not hinder the normal routine of the person or cause any discomfort. On each layer, a conductive material (silver) is applied, followed by a layer of pressure-sensitive ink. The active sensing area is defined by the silver circle on top of the pressure-sensitive ink. It is renowned for its versatility, ease of integration, and cost-effectiveness. It can be attached to many surfaces and can be combined with plastic or metal films for increased stiffness or for added protection from abrasion. The sensing area is 9.53 mm (0.375 in.) diameter located at the end of the sensor and placed in the shoe sole. It can measure a force ranging up to (1000lb.) using the readout circuit shown in Fig. 2. In order to measure forces above 100 lb (up to 1000 lb), a lower drive voltage (-0.5 V,-

0.25 V, etc.) should be applied with a feedback resistor (1k $\Omega$  min.) The FSR data is acquired and processed using Analog Front End (AFE) and then forwarded to NDD classifier to classify the subject's condition as ALS, HD, PD patient or healthy person. The NDD classifier is implemented on FPGA. The processed information will be then transferred to the doctor's/care-giver mobile through Bluetooth/Cloud network associated with the proposed system.



**Fig. 1.** System Level Diagram of the proposed wearable system for the NDD detection.



**Fig. 2.** FSR Readout circuit to measure more than 100lb. force.

**Fig. 3** shows the power comparison of FSR based NDD detection system for two different approaches. Transmitting the FSR raw data for off-sensor processing via a low power Bluetooth interface consumes 1.09mW [27]. However, if the NDD detection is performed on-sensor, the power consumption is reduced by 72% (0.31mW), which proves the advantage of on-sensor processing for the wearable systems [27- 29].

The block diagram of the proposed on-sensor wearable NDD classifier and AFE is shown in Fig. 4. The proposed processing system is comprised of Instrumentation Amplifier (AMP) to ensure operating of FSR in the desired weight range, followed by a buffer (BUF), an Analog-to-Digital Converter (ADC), a classifier (detection of disorder), and Bluetooth module/interface for communication with the external world. Since the target is a wearable environment, a 12 bits Successive Approximation (SAR) ADC is utilized as an optimum choice with a sampling rate of 300 Samples/s. The digitized data is then collected and filtered with a median filter to eliminate the noise; followed by an NDD classifier. Based on the captured gait features, the NDD classifier categorize the person into 1) ALS, 2) PD, 3) HD or 4) Normal Person (NP). In addition, the proposed classifier also identifies the severity of the disease.

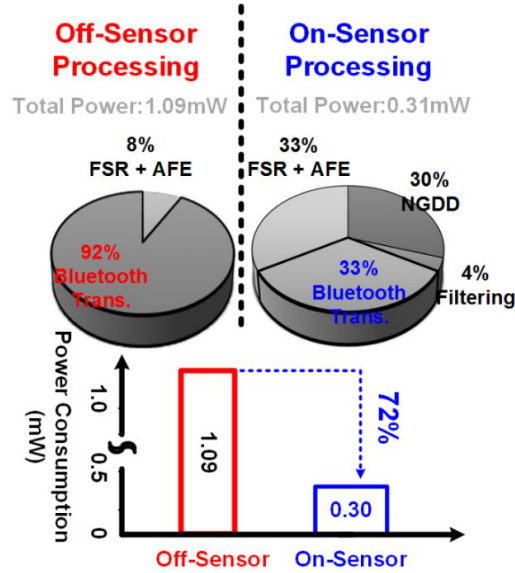


Fig. 3. Power breakdown for two possible on-sensor processing scenarios.

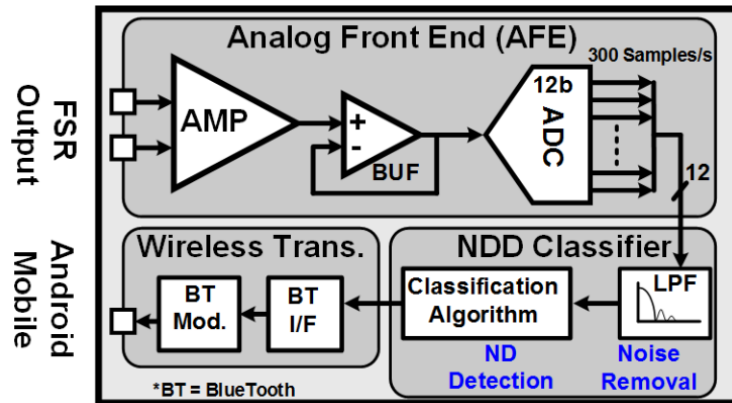
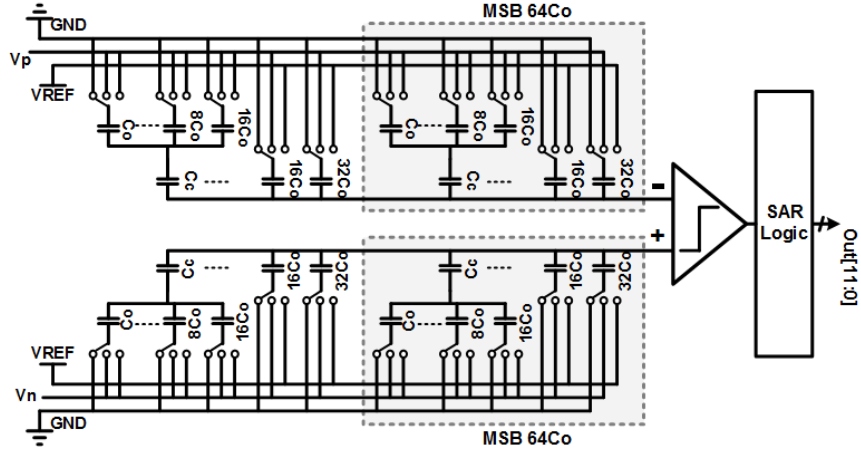


Fig. 4. Block diagram of NDD AFE and the detection processor.

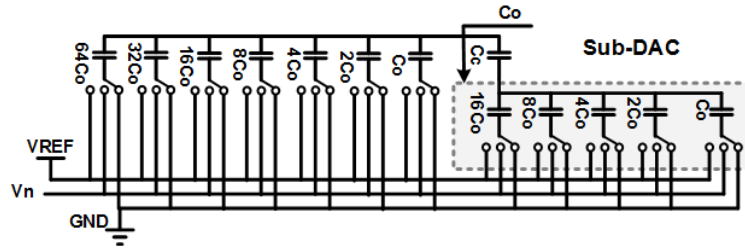
A successive approximation register (SAR) ADC architecture is the natural choice for the wearable/portable biomedical systems [30]. SAR ADC is suited for low speed, moderate resolution, and ultra-low power applications. The designed ADC has a fixed resolution of 12 bits and has a sampling rate of 2.4 KHz. To enhance the common-mode rejection ratio (CMRR) and to eliminate the second order harmonics, a full differential architecture is adopted with the minimal overhead of doubling the digital to analog converter (DAC) power [31]. Fig. 5 depicts the architecture of the fully differential ADC which includes differential capacitive DAC, digital comparator, SAR Logic, and switches. The 12b SAR ADC is implemented and simulated using CMOS 180nm process.



**Fig. 5.** The architecture diagram of the designed 12b SAR ADC.

The designed 12b SAR ADC utilizes a binary weighted fully differential capacitive DAC. To minimize the power and area consumption sub-DAC and split-capacitor for the most significant bit (MSB) is utilized [32].

The DAC is composed of 7-bit main DAC and 5 bit sub-DAC. The proposed 7/5 division minimize the power consumption while utilizing the same area as 6/6 division. Moreover, 6/6 division suffers from the high differential non-linearity (DNL)/ integral non-linearity (INL) due to the parasitic capacitance on the top plate of the sub-DAC. The MSB capacitor is split into the capacitor array identical to the least significant bit (LSB) capacitor as shown in the Fig. 6.

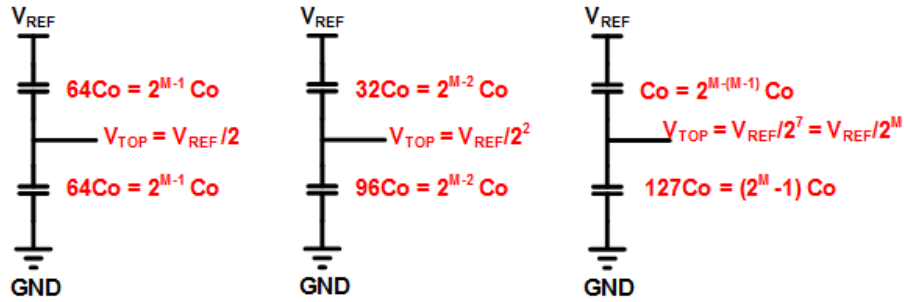


**Fig. 6.** Binary weighted DAC with 7-bit main-DAC and 5-bit sub-DAC.

The SAR ADC area is mainly dominated by the area of the capacitive DAC. In a binary weighted DAC of  $N$  bit resolution, the ratio of MSB to LSB is equal to  $2^{N-1}$ , which is equal to 2048 for 12 bit SAR ADC. To reduce the area of the capacitor array, the capacitive DAC is divided into an  $M$ -bit main-DAC and an  $L$ -bit sub-DAC that is connected to the main-DAC through a coupling capacitor [33], where the SAR ADC resolution  $N$  is equal to  $M+L$ . Fig. 6 shows the single-sided capacitive DAC split in  $M$  bit main-DAC and  $L$  bit sub-DAC where  $M$  and  $L$  are equal to 7 and 5, respectively, in

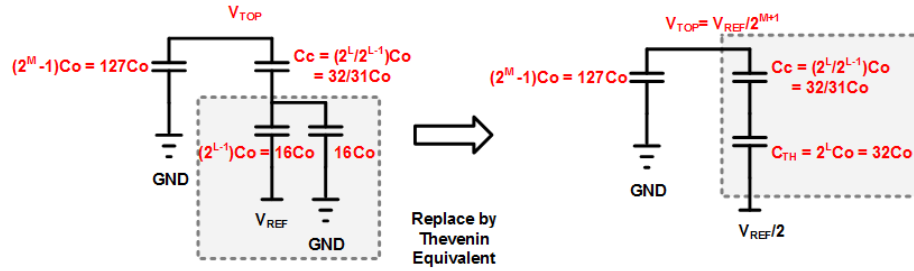


the implemented design. The coupling capacitor has a value of  $2^L C_o / 2^{L-1}$  which is the  $32C_o/31$ . Therefore, the overall effective capacitance of the sub-DAC and coupling capacitor is equal to  $C_o$ . Fig. 7 shows the utilization of superposition principle to depict the effect of voltage  $V_{TOP}$  based on each capacitor in the main-DAC and sub-DAC. The effective capacitive divider individually connects the bottom plate of each capacitor in the main-DAC  $V_{REF}$ . First, if the bottom plate of the MSB capacitor ( $64 C_o$ ) is connected to  $V_{REF}$  and the bottom plate plates of the rest of the capacitors are connected to the GND. A capacitive divider with two capacitors each is equal to  $64 \cdot C_o$  occurs and voltage  $V_{TOP}$  is equal to half the  $V_{REF}$  value. If the capacitor  $32C_o$  is the one connected to  $V_{REF}$  instead the voltage is equal to quarter  $V_{REF}$  and so on.



**Fig. 7.** Explanation of the DAC effective capacitive divider while individually connecting the bottom plate of each capacitor in the main-DAC to  $V_{REF}$  and the rest of capacitors to GND.

Thevenin equivalent is utilized to apply same procedure for the sub-DAC evaluation. Fig. 8 shows the effective capacitive divider while connecting the bottom plate of the MSB capacitor of the sub-DAC to  $V_{REF}$  and the rest of capacitors to the GND. The voltage  $V_{TOP}$  is equal to  $V_{REF}/2$  divided by  $2^M$  which is the half the value yielded by the LSB of main-DAC. The same analysis can be applied to the rest of the capacitors of the sub-DAC. It should be noted the Thevenin equivalent capacitance shown in Fig. 8 is the same while switching any of sub-DAC capacitors.



**Fig. 8.** Thevenin equivalent circuit for analyzing passive sub-DAC.

The only problem with sub-DAC interpolation is its sensitivity to the parasitic capacitance at the top plate of sub-DAC capacitors. This leads to INL/DNL errors due

to the compression of transition steps by the sub-DAC. However, this problem can be compensated by an increase in the size of the coupling capacitor by RTP [33] as given in the following equation where  $C_P$  is the extracted parasitic capacitance from the top plate of subDAC to GND and  $C_{sub\ DAC}$  is the total capacitance of the sub-DAC which is equal to  $2^L C_0$  (32  $C_0$  in this case).

$$R_{RP} = 1 + \frac{C_P}{C_{subDAC}} \quad (1)$$

To reduce the power consumption, dynamic comparators are utilized which are highly power efficient and thus cut down one of the main sources of power dissipation in the SAR ADC. The two main problems of this type of comparators are the input-referred offset and kick-back noise. The transistors are sized to keep the  $3\sigma$  offset close to 50 mV. Kickback noise has little effect on the operation of the ADC as it roughly common mode when the outputs begin to rise [33]. The SAR Logic is responsible for generating the switch control signals during the different phases of operations. The SAR logic consists of three main blocks, first the sequencer for providing timing control. It sets the period of purging, sampling and bit-cycling and timing for latching the output of the comparator. The second part is the data register which is used to store the output of digital comparator during the bit-cycling phase to form the digital output vector. The third part utilizes outputs of the sequencer and data register to generate the switches control signals of the main-DAC and sub-DAC.

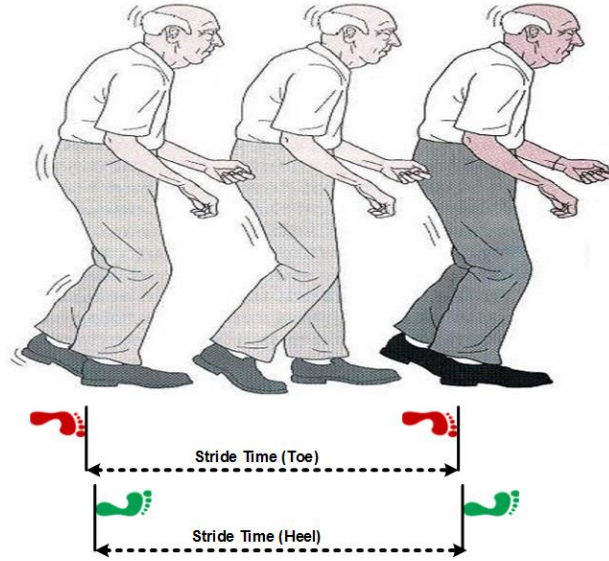
The performance summary of implemented SAR ADC is shown in Table 1. The SAR ADC achieves an effective number of bits (ENOB) of 11.4, signal-to-noise-distortion ratio (SNDR) of 60dB, spurious free dynamic range (SFDR) of 72 dBFS which provides information about the difference between maximum amplitude tone in frequency spectrum and the fundamental input tone, DNL and INL of 0.275 LSB and 0.3 LSB, respectively, which gives deviation of actual conversion from the ideal one.

**Table 1.** 12b SAR ADC performance summary.

<b>Power Consumption</b>	<b>57nW</b>
<b>ENOB</b>	<b>11.4</b>
<b>SNDR</b>	<b>60 dB</b>
<b>SFDR</b>	<b>72 dB</b>
<b>DNL</b>	<b>0.275 LSB</b>
<b>INL</b>	<b>0.3 LSB</b>

## 4 NDD Classification Algorithm

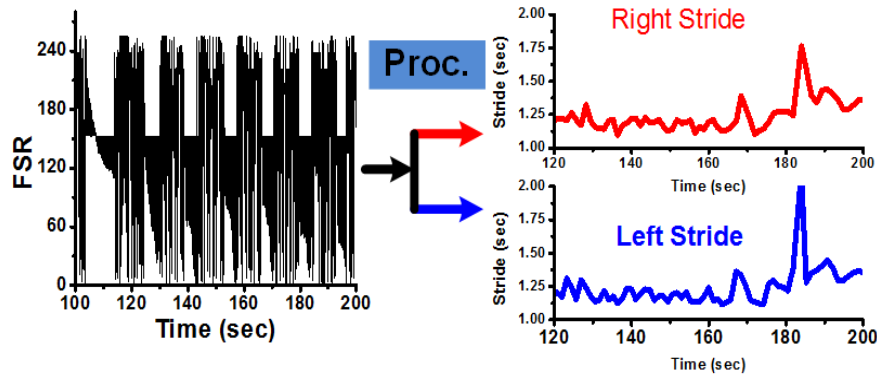
The main goal is to extract the discriminating features to classify the different NDDs. The gait cycle duration (known as stride-time), is considered as one of the main features to identify person's gait dynamics [1]. The heel strike is defined as the heel first touches the ground and ends until the whole foot touches the ground. As shown in the Fig. 9, the early flatfoot strike occurs, when the whole foot is on the ground. The late flatfoot stages end when the heel lifts off the ground. The rise begins when the heel starts to leave the ground. The toe-off phase occurs when the toe leaves the ground. 60% of the walking consists of stance phase. The Stance phase occurs when the whole foot is on the ground. Swing phase is basically defined as the one foot is on the ground and the other is in the air. Fig. 10 shows the digitized FSR output from the ADC for an ALS patient for a duration of 100 sec along with right and left stride intervals in red and blue, respectively. Close analysis of the graph shows that stride interval of both left and right foot gives same information about the human behavior. Moreover, the left stride time seems to be more sensitive and gives more details in comparison to the right. These results are consistent among all the patients (ALS, HD, PD) and therefore in this work only left stride is utilized in the processing to save power and area utilization.



**Fig. 9.** Gait abnormality in Neurodegenerative diseases and stride time.

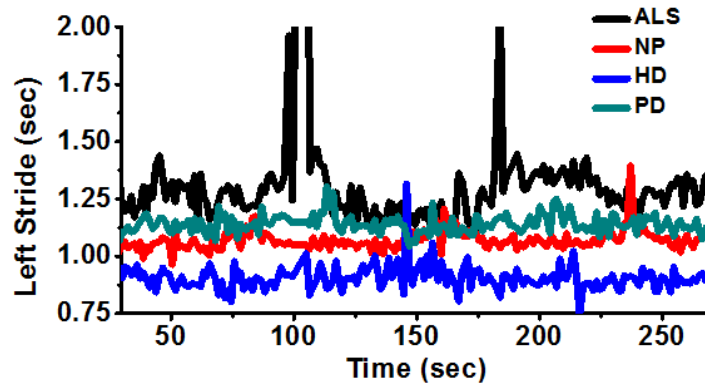
Fig. 11 shows the average left stride time interval for different NDD i.e. ALS, PD, HD and NP. Subjects with ALS, have longer average stride time interval compared with that of the HD, PD and the healthy subjects. Therefore, the average stride time interval is an effective feature for the NDD detection that is used in our proposed NDD classifier. It is also observed that the stride-time interval is a key feature to distinguish between ALS and other NDDs based on Fig. 11. Another important feature for NDD

detection is the stride-time fluctuation w.r.t corresponding mean which is more dominant in the HD relative to other NDDs [23] except ALS as shown in the Fig. 12. But the ALS can be detected based on stride time, therefore stride time fluctuations can be treated as a feature for the HD detection. Stride time fluctuation is calculated by taking the derivative of the stride time and the Fig. 12 shows the relative maximum and continuous fluctuation in the stride time compared to the NP, ALS, and PD.



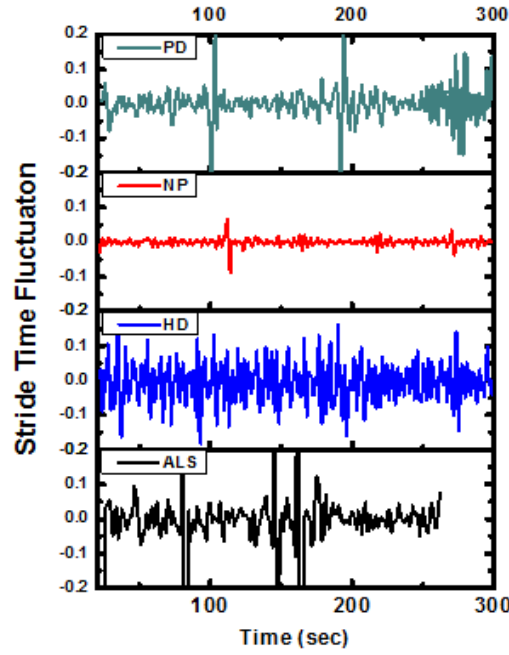
**Fig. 10.** Digitized FSR output with extraction into left and right stride time.

The selection of stride time fluctuation as feature reduces the overall feature set compared to [1] and [12] by more than 60%. Furthermore, to discriminate the PD and NP, a detailed analysis is performed to carefully select feature which significantly distinguishes the PD from NP. For this purpose, the autocorrelation of the decay time for the NDD is done with the healthy subject, and the value came out to be greatest for the PD patients. Therefore, the autocorrelation is also considered as a discriminatory feature for the PD patients.

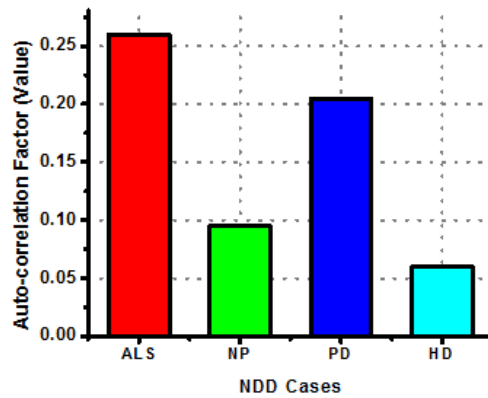


**Fig. 11.** Average stride time comparison of different NDD (ALS PD, HD) and NP.

Fig. 13 shows the computed auto-correlation factor value of different NDD's used in this work. The values show ALS achieves maximum value but since stride time alone is enough to determine the ALS, therefore, stride time along with auto-correlation factor discriminate PD from all other NDD's and NP with good classification accuracy, since PD has the second maximum value of auto-correlation factor among NP and HD.

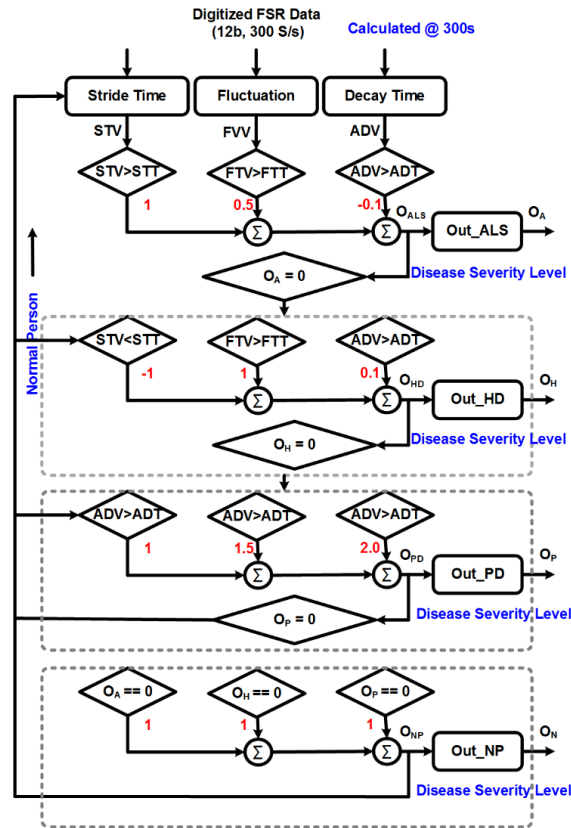


**Fig. 12.** Average stride time fluctuation comparison of different NDD (ALS, PD, HD) and NP.



**Fig. 13.** Average auto-correlation factor comparison of different NDD (ALS PD, HD) and NP.

Fig. 14 and Fig. 15 shows the state flow diagram and the algorithm for the proposed NDD classification method based on 3 features: 1) stride-time, 2) fluctuation in the stride time and 3) autocorrelation decay factor. The stride time value is the duration of gait cycle which is the time interval between two consecutive heel strikes of the same foot in milliseconds. Fluctuation in the stride time is an indication of the inconsistent limb movements. Therefore, the mean and standard deviation of stride time are utilized to estimate the fluctuation variation value (FVV). The FVV can be considered as a measure of the variability of temporal stride dynamics caused by the imbalanced rhythmic walking mechanism. Low FVV indicates automated rhythmic characteristics of gait dynamics and is utilized by physicians as a clinical index for stable gait dynamics. FVV among healthy individuals is low and usually below 3% [34]. Explicitly can be determining a factor for ALS and HD patients. The autocorrelation function indicates how the stride time series of each patient is correlated with itself over different time delays and gives a measure of the memory in the system. The autocorrelation decay-time value (ADV) is defined as the number of strides required for the autocorrelation of the stride time series to fall to 63% ( $1 - 1/e$ ) of its initial value [35].



**Fig. 14.** State flow diagram of the proposed NDD classifier.

The  $O_A$ ,  $O_H$ ,  $O_P$ , and  $O_N$  are outputs of corresponding NDD and their values are calculated based on the STV (Stride time value), FVV, and ADV (Autocorrelation decay-time value) in relation to the STT (Stride time threshold), FVT (Fluctuation variation threshold), and ADT (Autocorrelation decay-time threshold). The detection time for one cycle of evaluation is 5 min (300sec) and will continue repeating if NDD goes undetected.

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**Algorithm** Proposed NDD Classification Algorithm

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1: Input: STV, STT, FVV, FVT, ADV, and ADT
2: Output:  $O_A, O_H, O_P, O_N$ 
3: for the kth iteration do
4:   Load the original 300 sec data
5:    $O_{ALS} \leftarrow (STV > STT) + 0.5 * (FVV > FVT) - 0.1 * (ADV > ADT)$ 
6:   if  $O_{ALS} \leq 0.5$  then
7:      $O_A \leftarrow 0$ 
8:   else if  $O_{ALS} > 0.5$  and  $O_{ALS} < 1.0$  then
9:      $O_A \leftarrow 1$ 
10:  else if  $O_{ALS} > 1$  and  $O_{ALS} < 1.4$  then
11:     $O_A \leftarrow 2$ 
12:  else
13:     $O_A \leftarrow 3$ 
14:  end if
15:  if ( $O_A = 0$  or  $O_A = 3$ ) then
16:    Load the original 300 sec data
17:     $O_{HD} \leftarrow (FVV > FVT) - 1 * (STV < STT) + 0.1 * (ADV > ADT)$ 
18:    if ( $O_{HD} > -0.2$  and  $O_{HD} < 0.2$ ) then
19:       $O_H \leftarrow 0$ 
20:    else if  $O_{HD} > 0.9$  then
21:       $O_H \leftarrow 2$ 
22:    else
23:       $O_H \leftarrow 3$ 
24:    end if
25:  end if
26:  if ( $O_H = 0$  or  $O_H = 3$ ) then
27:    Load the original 300 sec data
28:     $O_{PD} \leftarrow (ADV > ADT) + (ADV > 1.5 * ADT) + (ADV > 2 * ADT)$ 
29:    if  $O_{PD} = 0$  then
30:       $O_P \leftarrow 0$ 
31:    else if  $O_{PD} = 1.0$  then
32:       $O_P \leftarrow 1$ 
33:    else if ( $O_{PD} > 1.0$  and  $O_{PD} < 2.6$ ) then
34:       $O_P \leftarrow 2$ 
35:    else
36:       $O_P \leftarrow 3$ 
37:    end if
38:  end if
39: end for
40: if ( $O_A = 0$  and  $O_H = 0$  and  $O_P = 0$ ) then
41:    $O_N \leftarrow 1$ 
42: else
43:    $O_N \leftarrow 0$ 
44: end if

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**Fig. 15.** Proposed NDD classification algorithm.

Additionally, based on threshold level and the proposed NDD algorithm, the two bits output of the classifier also describe the severity of the corresponding disorder. If none of the diseases is detected, the patient will be claimed as a normal scenario. Since it's also important to detail severity level of ND and action item, therefore the relation of NDD output, the severity of the disorder and corresponding action are detailed in Table 2. This information will be presented to the concerned person himself, caregiver and physician via cloud/Bluetooth link. The NDD classifier output is 2 (two)-bit with binary encoding utilized for each corresponding NDD, for example, the 2'b11 means a high score of specific NDD, meaning the person has the severe symptom of that NDD and needs to take precautionary measures on urgent basis.

**Table 2.** NDD output with score description and action item.

NDD Output	Score Description	Action Item
2'b00	Low Score of NDD	Need to monitor Situation
2'b01	Medium Score of NDD	Need to visit Doctor
2'b11	High Score of NDD	<b>Emergency Situation</b>
2'b10	Not enough data	Need further analysis

To form a mathematical model for the detection based on the above discrimination, the fall detection algorithm is as follows. The decision weights are carefully selected based on the rigorous simulation for the Neuro-Degenerative Disease Data Base [35].

## 5 Results and Discussion

The system is verified with the Gait Dynamics in Neuro-Degenerative Disease Data Base 35, which contains 64 subjects having ALS, HD, PD and Healthy Subjects of 13, 20, 15 and 16, respectively. To measure the real-time performance and working, the complete implementation is also done on FPGA. The average overall classification accuracy was computed using the Xilinx Virtex 5 LX-110T FPGA board and Logic analyzers were used to display and verify the NDD classification. The sensitivity and specificity are defined by (2) and (3), respectively, along with the definition of True Positive, True Negative, False Positive, and False Negative in (4) – (7).

$$\text{Sensitivity} = \frac{\text{True Positive}}{\text{True Positive} + \text{False Negative}} \quad (2)$$

$$\text{Specificity} = \frac{\text{True Negative}}{\text{False Positive} + \text{True Negative}} \quad (3)$$



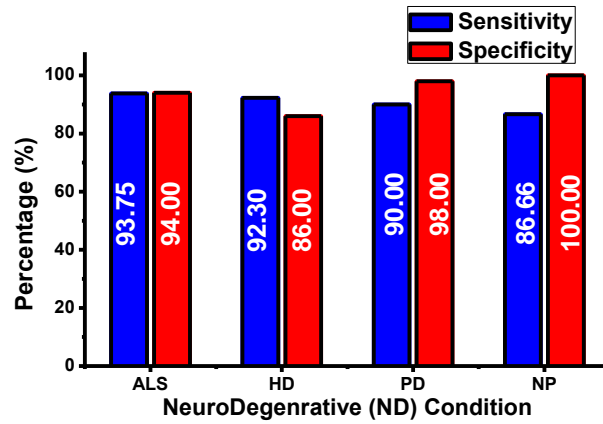
$$\text{True Positive} = \frac{\# \text{ of pattern classified Normal}}{\text{Total \# of Normal Patterns}} \quad (4)$$

$$\text{True Negative} = \frac{\# \text{ of pattern classified Abnormal}}{\text{Total \# of Abnormal Pattern}} \quad (5)$$

$$\text{False Negative} = \frac{\# \text{ of pattern classified Abnormal}}{\text{Total \# of Normal Pattern}} \quad (6)$$

$$\text{False Positive} = \frac{\# \text{ of pattern classified Normal}}{\text{Total \# of Abnormal Pattern}} \quad (7)$$

The evaluation shows the proposed system achieves an averaged sensitivity and specificity of 90.8% and 94.5%, respectively for total 64 subjects. The verification results of the proposed system are shown in Fig. 16. It also achieves a classification accuracy of 93.8%, 89.1%, 94% and 93.3%, for ALS, HD, PD, and normal person, respectively.



**Fig. 16.** Measured sensitivity and specificity of NDD.

Fig. 17 shows the performance of the proposed system, the digitized FSR data is processed to evaluate the stride time and based on the stride time, fluctuation in the stride and autocorrelation decay time; the specific NDD is determined and the final information is transferred to the doctor/caretaker mobile via Bluetooth. Different scenarios are shown in the Fig. 17 for the working of the proposed NDD classification system along with the computed values (STV, ADV, and FVV) and their corresponding threshold values (STT, ADT, and FVT). The message showing the severity level of the

disease along with proposed action item is displayed on caregiver or physician smartphone through a low-energy Bluetooth link. Table 3 compares the performance of the proposed NDD processor with the state-of-the-art works. All other works focus on software implementation only whereas this work target a wearable device with on-sensor processing. It also utilizes only 3 features to distinguish between the different NDDs and healthy persons. The system achieves an overall sensitivity, specificity and classification accuracy of 90.8%, 94.5%, and 92.9%, respectively. Since the proposed system is targeting a wearable environment, therefore an area and power efficient 12b-SAR ADC are implemented using 65nm CMOS technology consuming  $< 60\text{nW}$ .

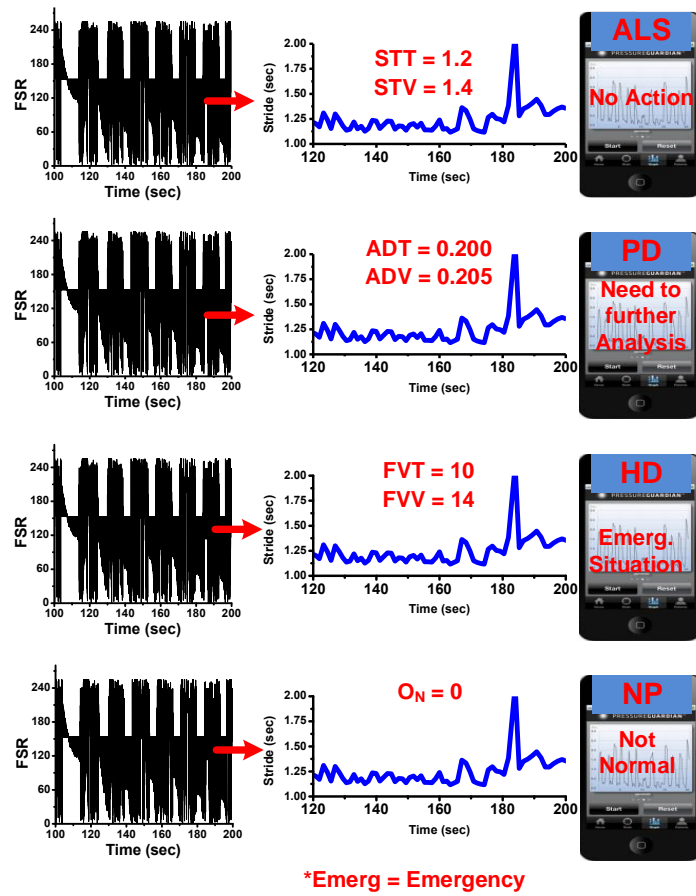


Fig. 17. The measured result showing the system working.

**Table 3.** Comparison with State-of-the-art works.

Parameter	W. Zeng [1]	P. Ren [2]	Y. Wu [16]	J. Barth [19]	W. Aziz [20]	This Work
Sensor Type	FSR	FSR	FSR	inertial sensors	FSR	FSR
Sensor Location	Foot	Foot	Foot	Foot	Foot	Foot
On Sensor Detection	X	X	X	X	X	O
No. of Features	12	10	1	12	1	3
Avg. Sensitivity	91.7%	93.7%	76.9%	88%	89.3%	90.8%
Avg. Specificity	100%	78.3%	87.5%	86%	78.3%	94.5%
Target Application	NDD	NDD	ALS	PD	NDD	Wearable :NDD

## 6 Conclusion

This contribution proposes a wearable novel NDD detection system for the detection and classification of ALS, HD, and PD. The proposed system is based on the minimum feature set of 3 features which will ensure lower power and area implementation without affecting the overall detection performance. The proposed system aims to provide a solution for the next generation of miniaturized wearable devices to detect the NDD at an early stage and may help in reducing the severity of NDD. The proposed system is tested on patient's recordings from Physionet Gait Dynamics dataset and achieves a classification accuracy of 93.8%, 89.1%, 94% and 93.3%, for ALS, HD, PD, and healthy person, respectively, from a total set of 64 subjects.

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