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ConnectionLens: Finding Connections Across Heterogeneous Data Sources

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1 MOTIVATION AND OUTLINE

The explosion of digital data sources on about every aspect of modern life has led journalists to collaborate with computer scientists, statisticians, and social scientists of various disciplines, aiming at novel digital tools to analyze and exploit this data. Since a seminal interdisciplinary study [3], the field of *data journalism* [12], that is, journalistic work significantly based on digital data, increasingly attracts the attention of journalists and computer scientists alike.

In this work, we focus on a core data journalism problem: *identifying connections across a set of heterogeneous, independently produced data sources*. We are inspired by investigative journalism work, which seeks out and explores connections between individuals, organizations, companies etc. Such work requires, first, getting access to data sources, through any means (from verbal or phone communication, to paper mail, fax, and any electronic transmission method); second, analyzing this data, to find out what valuable information it may contain. For instance, consider an example raised by journalists at Le Monde, a leading French national newspaper, with which we currently collaborate: France’s national elections in 2017 brought about an unprecedented ratio of first-time National Assembly elected members. Journalists scrambled to learn as much as possible about the nation’s new representatives, in particular asking e.g., “*what connections the new representatives have (or have had) with companies?*” This question is interesting to identify areas of economic competence, but also possible conflicts of interest. By law, French representatives must disclose direct financial interests, but more indirect connections (e.g., being, for many years, a close collaborator of a company’s current CEO) must be dug out by the press.

Many digital data sources which could be used to answer such questions are publicly available today. However, finding answers to journalists’ queries is challenging for many reasons. (i) The data is **large**, precluding the use of the hand-crafted tools (often spreadsheets) that journalists are used to; (ii) there are **many, structurally heterogeneous**, independently-produced data sources; some sources, e.g. national company registry, are relational, some others, e.g. contracts, discourses are text, social media content comes as JSON documents, open data is often structured in RDF graphs etc.; (iii) an answer stating, e.g., that a certain representative has studied with the CEO of a given company, may require **interconnecting information from several data sources**, e.g.,

the history of company C , the Wikipedia page of A , and the public information available on D and its CEO, namely B ; (iv) journalists do not know the shape, size, and structure of the connections they are seeking out, thus they need the ability to **search through keywords**; (v) the set of data sources is highly **dynamic**, as journalists collect various data sources and try to see what insights they can get by combining them with existing ones. It is also worth stressing that newsrooms function under extreme time constraints, making it unfeasible to clean, consolidate and integrate all data sources in a unified warehouse. Finally, (vi) a staple of professional journalism is to be able to show evidence for a published claim. Thus, in an answer such as the one outlined in (iii) above, it is important to be able to **show where each piece of information came from and how the connections were made**.

CONNECTIONLENS is a prototype addressing the above challenges. At its core is a novel algorithm for keyword search across a set \mathcal{D} of heterogeneous data sources, each of which can be: a relational table; a JSON document; a text file; or an RDF graph.

For instance, Figure 1 shows a JSON datasource DS_1 containing information about elected representatives, a text dataset DS_2 listing the alumni of Ecole polytechnique, where many French company executives have studied, and a relational source DS_3 providing information about companies and their CEOs. A **query** Q is a set of keywords $\{w_1, \dots, w_n\}$ for some integer $n \geq 1$. In Figure 1, the query “En Marche company” seeks to find out connections between elected representatives from the “En Marche” political party, and some company. An **answer tree** to Q over \mathcal{D} is a tree, part of a **virtual graph** (which, as we explain later, is the way we view \mathcal{D}). Each answer tree node n_i comes from a dataset $D_i \in \mathcal{D}$, and each edge e_j either comes from a dataset $D_j \in \mathcal{D}$, or is a link between two nodes (from the same or from two different datasets) whose data content we find sufficiently similar to consider them “the same” for the purpose of our querying. Further, each Q keyword matches a *node or an edge* of the answer tree. For example, in Figure 1, the red lines trace an answer tree to the sample query: one of the elected representatives of the party “En Marche” (node matching “En Marche” in DS_1) is Anne Martin, who studied at Ecole Polytechnique (alumni information from DS_2) just like Philippe Varin, the CEO of the Areva company (edge labeled “company” from DS_3).

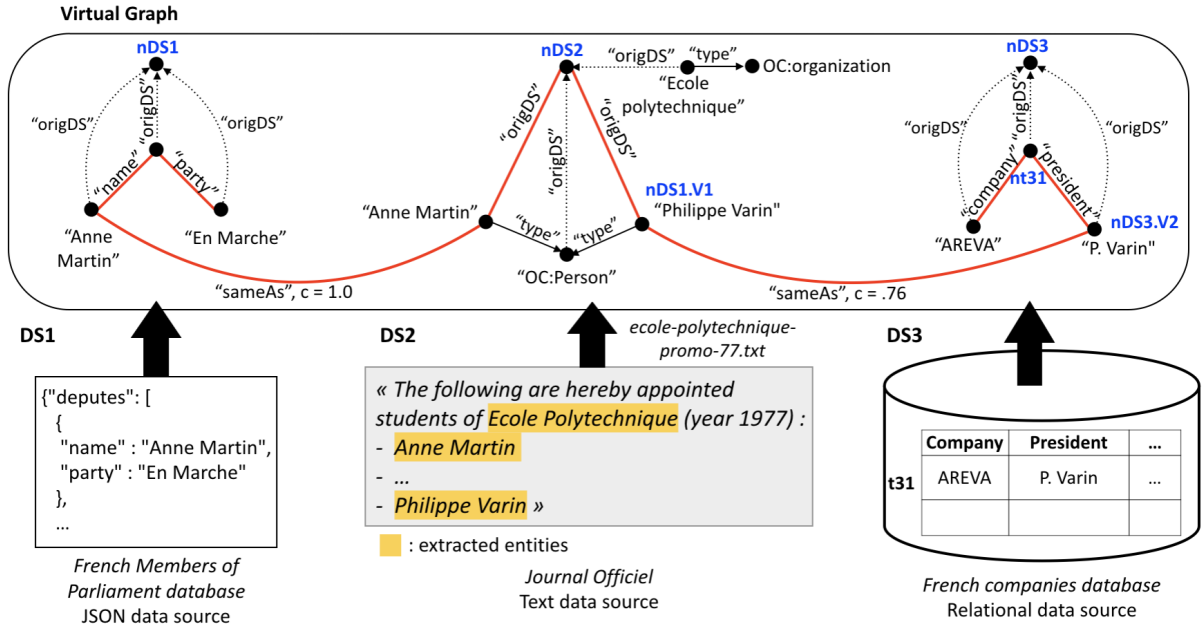


Figure 1: Motivating example: data source collection \mathcal{D} , corresponding virtual graph \mathcal{G} , and an answer tree (red).

A query Q may have several answer trees on a given \mathcal{D} , some more interesting than others; this can be captured by a **answer tree score** function s associating to every answer tree a number reflecting its interest (the higher, the better). The problem solved by CONNECTIONLENS then, is: *given \mathcal{D} , Q , the score function s and an integer k , find the k answer trees across \mathcal{D} with the highest s scores.*

A novel contribution of our system is its keyword search approach capable of finding answers *across* heterogeneous data sources, approach based on a *virtual graph* we describe next. Our score function, tailored toward journalistic interests (Section 3) is also novel.

2 VIRTUAL GRAPH

To be able to exploit data connections occurring within and across all data sources $D \in \mathcal{D}$, we view all data sources as a *single, virtual graph* \mathcal{G} , and answer keyword search queries with subtrees of this graph. Each \mathcal{G} node has a (globally unique) identifier, some of which are shown in Figure 1, in blue. A **label function** λ assigns to every node a (possibly empty) text label, reflecting its content in D . \mathcal{G} edges are directed; each edge e carries a text label (we use λ also to denote the edge labeling function) and a *confidence* c_e which is between 0 and 1, whose usage will be shortly explained below. Node and edge labels appear as quoted strings in Figure 1. Based on this figure, we explain below how \mathcal{G} nodes and edges are (conceptually!) derived from each data source D .

2.1 Nodes and edges derived from a source

First, a *dataset node* n_D is created in \mathcal{G} to represent D itself, e.g., n_{DS1} to n_{DS3} . Every \mathcal{G} node corresponding to data from D (see below) is connected to n_D , through an edge labeled *origDS* (standing for *originating data source*); we show such edges with dotted lines in the figure. They ensure that any two virtual graph nodes coming from the same data source D are connected at least through n_D .

The other nodes and edges of \mathcal{G} are defined as follows:

(i) If D is an RDF graph, then \mathcal{G} contains all its nodes and edges of D ; λ attaches to each node its URI or literal (constant) label in D . The property labeling every edge becomes an edge label in \mathcal{G} .

(ii) If D is a JSON document such as DS_1 , \mathcal{G} has a node for each constant, list and map occurring in D , and an edge labeled *origDS* connects the node representing D , to the one corresponding to the top list or map in D . For each (n_1, v_1) name-value pair in a map, n_1 becomes the label of the edge leading to the node corresponding to v_1 .

(iii) If D is a text such as DS_2 , we apply *entity and relationship extraction* to identify in D occurrences of *entities* (such as people, places, organizations etc.) and of *relationships* (such as *bornIn*, *worksFor* etc.) Any off-the-shelf extractor (or set of extractors) can be used; CONNECTIONLENS currently uses OpenCalais (<http://www.opencalais.com>) for entity extraction. A \mathcal{G} node is created to each extracted entity (resp. relationship) occurrence; its λ label is the exact text snippet identified by the extractor; it has a *type* edge pointing to the entity type identified by the extractor, e.g., *OC:Person* stands for OpenCalais' Person type URI, and child nodes containing the offset and length of its appearance in the original text (omitted in Figure 1 to avoid clutter). Further, each node corresponding to an occurrence of a relationship between two entities, is connected to the nodes corresponding to the respective entity occurrences by edges identifying the entity roles in the relationship.

(iv) If D is a relational database such as DS_3 , for each relation $R(a_1, a_2, \dots) \in D$ and each tuple $r \in R$, \mathcal{G} contains a node n_r , with outgoing edges labeled a_1, a_2 etc. toward \mathcal{G} nodes, labeled with the values of the respective attributes of r . The label of n_r is one of its primary keys (we add such a primary key attribute if R doesn't have one). Further, for any two relations $S, T \in D$ such that $S.a$ is a foreign key corresponding to the primary key $T.b$, and tuples $s \in S, t \in T$ such that $s.a = t.b$, \mathcal{G} comprises an edge $n_s \xrightarrow{a} n_t$.

For instance, if $S.spouse$ is a foreign key on $T.id$, then \mathcal{G} comprises $n_s \xrightarrow{\text{spouse}} n_t$. This graph view of a relational database is often used for keyword search, e.g. [14, 17].

(v) Any \mathcal{G} node whose label $\lambda(n)$ is longer than a threshold θ_{text} is treated like a text data source, i.e., entity and relationship occurrences are extracted as in (iii); however, the \mathcal{G} nodes created from these occurrences are all descendants of n , and their original data source is that of n . This both provides a uniform treatment of text regardless of where it appears, and records the origin of each text content.

All virtual \mathcal{G} edges described above have a confidence of 1.0. Some extractors provide a confidence value for the extraction: this can be attached to the edges between the nodes, e.g. **nDS1.V1**, and their types, e.g. OC:Person.

2.2 SameAs edges

We add to \mathcal{G} an edge labeled *sameAs* between nodes n_1, n_2 (from the same or from different data sources), as soon as they are similar beyond a certain threshold θ_{sim} ; the confidence of such an edge is the similarity score, normalized to $[0, 1]$. Identifying when two data objects represent the same thing (aka approximate duplicate detection, etc.) is a thoroughly studied data integration problem [8], for which many solutions exist, especially among similarly-structured objects, e.g. [13, 18]. CONNECTIONLENS interconnects disparate sources that may not even have the same data model, e.g., an extracted entity may match with a JSON value (e.g., “Anne Martin”), or with an attribute in a relational tuple, e.g. “Philippe Varin” and “P. Varin”; or, an interesting link may exist between, say, a person and a company, if they both mention a certain user in their tweets etc. We seek to find all such value connections, and distinguish the trivial from the interesting ones using a score (Section 3).

CONNECTIONLENS uses the labels $\lambda(n_1), \lambda(n_2)$ of two \mathcal{G} nodes to decide if they are the same. If the labels are shorter than a certain size limit L , the Jaro distance between them is compared with θ_{sim} . If $\lambda(n_1)$ or $\lambda(n_2)$ are longer than L , we turn them both into bags of words and then compute their set-based Jaccard distance. If $\lambda(n_1), \lambda(n_2)$ are identical URIs, we connect them through *sameAs* with a confidence of 1.0. Different distance functions or comparisons can be plugged in as users get familiar with data sources, in pay-as-you-go data integration fashion [4].

We do not build *sameAs* links based on nodes’ adjacent edges and neighbor nodes. However, *sameAs* links based on labels alone, e.g., a common last name of two people, suffice to establish the data connections we are interested in.

2.3 Virtual graph indexing

We encode, index and store the \mathcal{G} nodes and edges derived from a source D in a set of data structures, as follows.

1. We compute an ID id_D for the dataset.
2. We derive nodes and edges as explained above from D . For each node n , we compute an ID id_n prefixed with id_D . This de facto encodes the edge $n_D \xrightarrow{\text{origD}} n$ into id_n .
3. We compute $\lambda(n)$ from the original text content of n , through stop word and punctuation removal, and stemming.

4. For each word $w \in \lambda(n)$, we insert (w, id_n) in the **index** $I(\text{word}, \text{node})$. Similarly, $\lambda(e)$ is computed for each edge e and its words indexed in I .

5. We seek to find *sameAs* edges to which a node n derived from D may participate. We look up all the nodes n' whose labels share at least a word with n , that is, (w, id_n) and $(w, id_{n'})$ belong to I , and compute the similarity between $\lambda(n)$ and $\lambda(n')$. All *sameAs* edges are stored in a **bridge** table $B(id_1, id_2, c)$ which records that the nodes identified by n_1, n_2 are judged the same with confidence c . For instance, the $B(\mathbf{nDS1.V1}, \mathbf{nDS3.V2}, 0.76)$ tuple encodes the *sameAs* link between the two nodes corresponding to Philippe Varin in Figure 1.

3 ANSWERING KEYWORD QUERIES

Given a query $Q = \{w_1, \dots, w_n\}$, the problem of finding the k answer trees (recall their definition in Section 1; we call them ATs, in short) with the best score is known to be NP-hard, by reduction to the Steiner tree problem. Thus, CONNECTIONLENS adopts a heuristic method to enumerate answer trees and returns the k highest-score ones.

The AT enumeration algorithm starts by looking up in the index I for the *potentially interesting data sources for Q* , denoted $P(Q)$, that is: the data sources from which \mathcal{G} nodes matching some query keywords are derived. For each subquery Q' of Q , and each source $D \in P(Q)$ containing exactly the keyword set Q' , the procedure **localSearch** (D, Q') returns the ATs (if any) whose nodes and edges derive only from D . The implementation of **localSearch** (D, Q) depends on the nature of D : it follows the lines of [14] for relational sources, [2] for JSON, and [15] for RDF data. The algorithm starts by optimistically asking each $D \in P(Q)$ for ATs for the largest subset of Q for which D has matches. If D has only one connected component, it is sure to contain at one such AT; also note that ATs are *undirected*, that is, \mathcal{G} edges form an AT as soon as they share a node, regardless of the direction of the edges. For instance, an AT may consist of three \mathcal{G} edges $n_1 \xleftarrow{a} n_2 \xrightarrow{b} n_3 \xleftarrow{c} n_4$. This is because we are interested in *data connections*, and find an edge such as $n_1 \xrightarrow{a} n_2$ interesting as a link, in both directions.

Partial ATs (initially, those local to each data source) are inserted in a **priority queue** U , based on their score (discussed below). The algorithm greedily picks the top-score AT t from U , and adds it to the result set if it is an answer to Q and its score is among the k best so far. If t is just a partial answer, we try to find another partial tree t' to combine with t , through a *sameAs* edge between a node from t and one from t' . The AT t'' resulting from t and t' is again added to U and the process continues, until a time-out occurs or there are no ATs left to add in U . If answers to Q are not found after a certain time, **localSearch** calls are made with smaller Q subqueries, in the hope that the resulting ATs may participate to more *sameAs* edges allowing to combine them in answers to Q .

The **score** $s(t)$ of an AT t comprises for each $w_i \in Q$, a **match-score** $ms(t, w_i)$ reflecting the extent to which the labels of all t nodes and edges match w_i , as well as a **structure score** $\xi(t)$ depending on the AT structure. We quickly found that *unlike many previous keyword search works, small ATs are not always preferable* because they may bring trivial (uninteresting) information. For instance, any French representative may be connected to any French

