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Utilisation de la compression low-rank pour réduire la complexité du solveur PaStiX

26 Septembre 2018 - JCAD 2018 - Lyon

Grégoire Pichon, *Mathieu Faverge*, Pierre Ramet, Jean Roman

Outline

1. Context
2. Block Low-Rank solver
 - From full-rank to low-rank
 - Impact of ordering techniques
3. Application: HORSE
4. Conclusion and future works

1

Context

The PASTIX solver

Factorization

- sparse direct solver
- real and complex arithmetic
- LU , LL^t , LDL^t , LL^H and LDL^H factorizations
- Static pivoting
- Refinement with BICGSTAB, CG, GMRES

Parallelism

- Supernodal approach
- Native static scheduling (used in next experiments)
- Runtime systems: PARSEC and STARPU
- Heterogeneous architectures (GPUs, KNL)
- Distributed (Ongoing work)

<https://gitlab.inria.fr/solverstack/pastix>

Objectives

Current sparse direct solver costs for 3D problems

- $\Theta(n^2)$ time complexity
- $\Theta(n^{\frac{4}{3}})$ memory complexity
- BLAS Level 3 operations with block computations

Current status

- Direct solver suffer from their high complexities
- Iterative or hybrid method are often problem dependent
- Machine precision is not required with inaccurate measures

Objectives: low-rank compression in a sparse direct solver

- Introduce compression of dense blocks
- Reduce time and/or memory complexity
- Keep the same level of parallelism

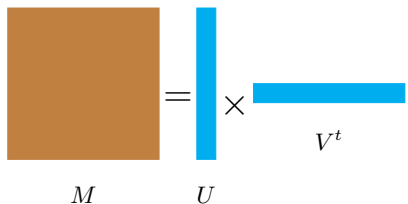
2

Block Low-Rank solver

2.1

From full-rank to low-rank

Low-rank compression


$$M = U \times V^t$$

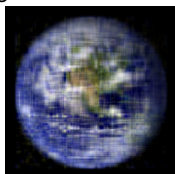
$U, V \in \mathbb{R}^{n \times r}$
 $M \in \mathbb{R}^{n \times n}$

M U

Storage in $2nr$ instead of n^2 .



Original picture.



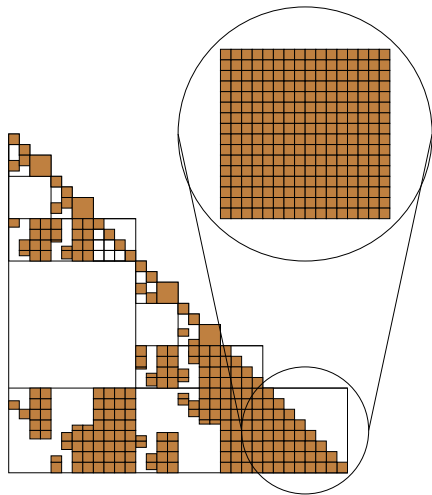
$r = 10$.



$r = 50$.

Compression of an image with $n = 500$.

BLR compression – Symbolic factorization



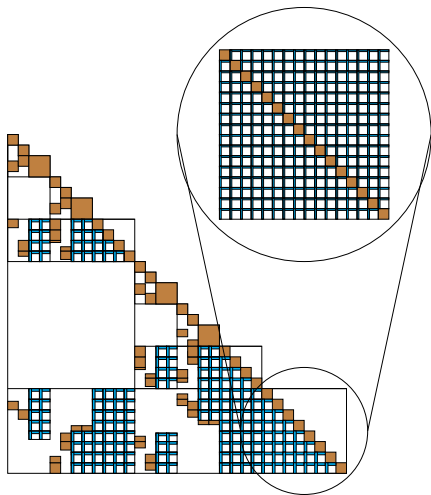
Approach

- Large supernodes are split
- It increases the level of parallelism

Operations

- Dense diagonal blocks
- TRSM are performed on dense off-diagonal blocks
- GEMM are performed between dense off-diagonal blocks

BLR compression – Symbolic factorization



Approach

- Large supernodes are split
- Large off-diagonal blocks are **low-rank**

Operations

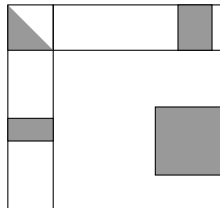
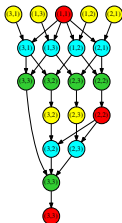
- Dense diagonal blocks
- TRSM are performed on **low-rank** off-diagonal blocks
- GEMM are performed between **low-rank** off-diagonal blocks

Strategy *Just-In-Time*

Compress L

1. Eliminate each column block
 - 1.1 Factorize the dense diagonal block
Compress off-diagonal blocks belonging to the supernode
 - 1.2 Apply a TRSM on LR blocks (cheaper)
 - 1.3 LR update on dense matrices (*LR2GE* extend-add)
2. Solve triangular systems with low-rank blocks

Yellow	Compression
Red	GETRF (Facto)
Cyan	TRSM (Solve)
Purple	LR2LR (Update)
Green	LR2GE (Update)

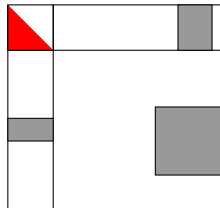
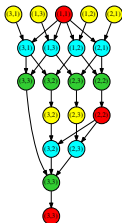


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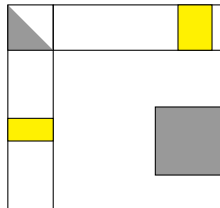
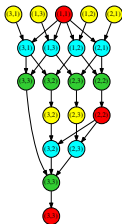


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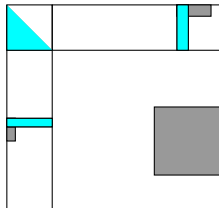
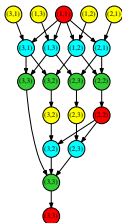


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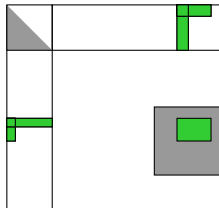
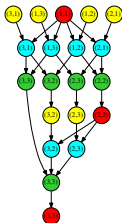


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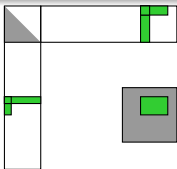
Summary of the *Just-In-Time* strategy

Assets

- The most expensive operation, the update, is less expensive with *LR2GE* kernel
- The formation of the dense update and its application is not expensive
- The size of the factors is reduced, as well as the solve cost

A limitation of this approach

- All blocks are allocated in full-rank before being compressed
- Limiting this constraint reduces the level of parallelism



Just-In-Time

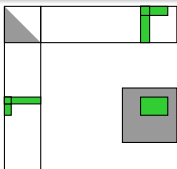
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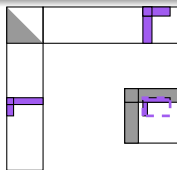
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Just-In-Time



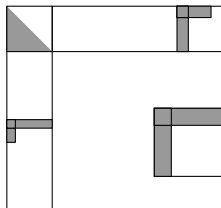
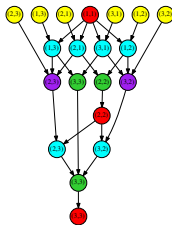
Minimal Memory

Strategy *Minimal Memory*

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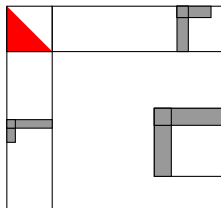
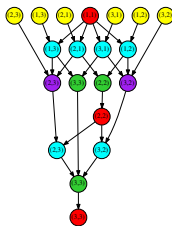


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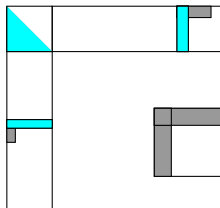
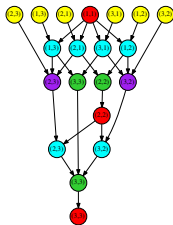


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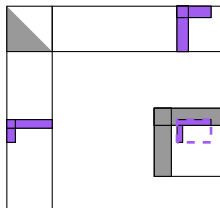
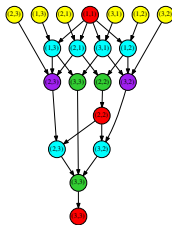


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Experimental setup - architectures

GENCI - Occigen

- 2 INTEL Xeon *E5 – 2680v3* at 2.50 GHz
- 128 GB
- 2 × 12 cores

MCIA - Avakas

- 2 INTEL Xeon *x5675* at 3.06 GHz
- 48 GB
- 2 × 12 cores

PlaFRIM - Miriel

- 2 INTEL Xeon *E5 – 2680v3* at 2.50 GHz
- 128 GB
- 2 × 12 cores

Experimental setup - matrices

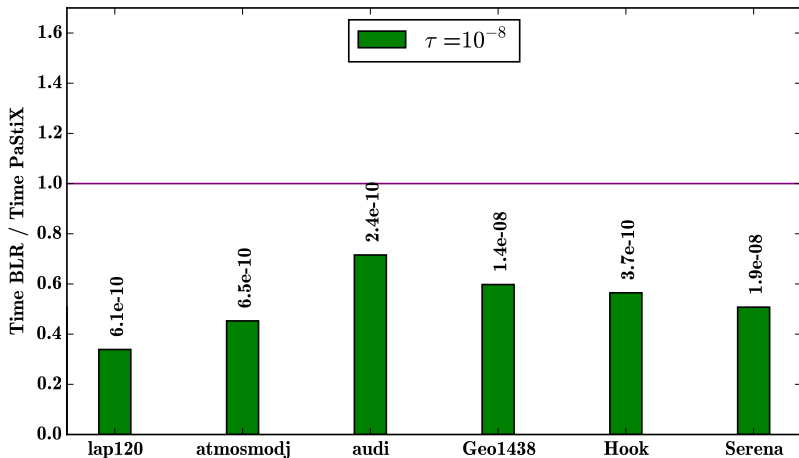
Large (33 matrices)

- Square matrices issued from the SuiteSparse Matrix Collection
- real or complex
- $50K \leq N \leq 5M$
- $nb_{ops} > 1$ TFlops
- Web and DNA matrices were removed

Small (6 matrices)

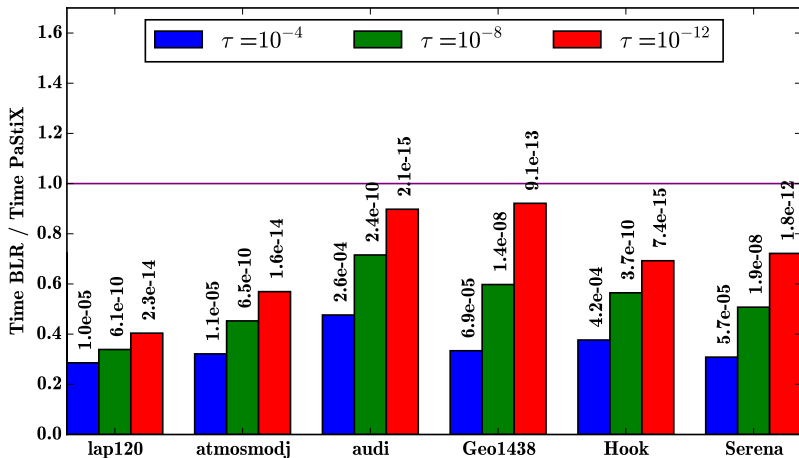
Matrix	Fact.	Size	Field
<i>Atmosmodj</i>	<i>LU</i>	1 270 432	atmospheric model
<i>Audi</i>	<i>LL^t</i>	943 695	structural problem
<i>Hook</i>	<i>LDL^t</i>	1 498 023	model of a steel hook
<i>Serena</i>	<i>LDL^t</i>	1 391 349	gas reservoir simulation
<i>Geo1438</i>	<i>LL^t</i>	1 437 960	geomechanical model of earth
<i>lap120</i>	<i>LDL^t</i>	120 ³	Poisson problem

Performance of RRQR/*Just-In-Time* wrt full-rank version



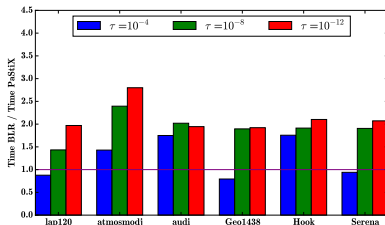
Factorization time reduced by a factor of 2 for $\tau = 10^{-8}$.

Performance of RRQR/*Just-In-Time* wrt full-rank version



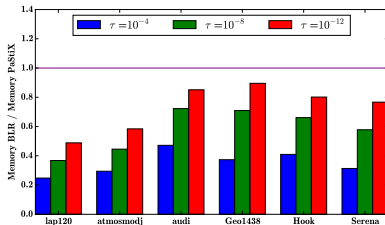
Factorization time reduced by a factor of 2 for $\tau = 10^{-8}$.

Behavior of RRQR/*Minimal Memory* wrt full-rank version



Performance

- Increase by a factor of 1.9 for $\tau = 10^{-8}$
- Better for a lower accuracy



Memory footprint

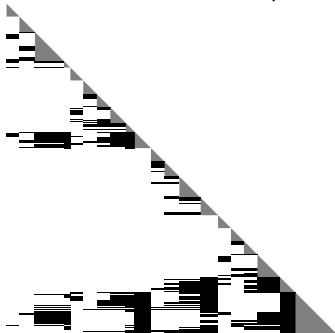
- Reduction by a factor of 1.7 for $\tau = 10^{-8}$
- Close to the results obtained using SVD

2.2

Impact of ordering techniques

Ordering for sparse matrices

One can reorder separators without modifying the fill-in.



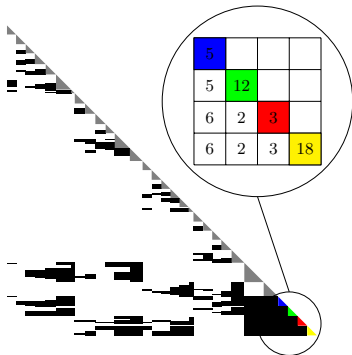
Symbolic factorization of a $8 \times 8 \times 8$ Laplacian.

Enhance ordering

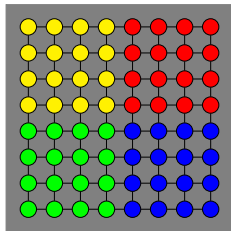
- Modify the partitioning process to enhance compressibility
- Reorder unknowns within a separator:
 - ▶ To enhance clustering within the separator
 - ▶ To enhance the coupling part

Clustering techniques: existing solutions

- k-way partitioning (dense, multifrontal)



(a) Symbolic factorization.

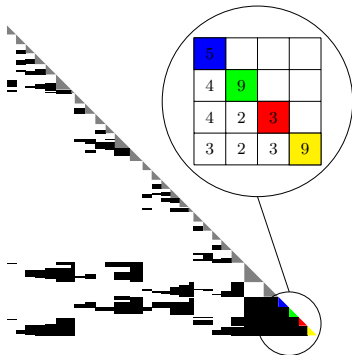


(b) First separator clustering.

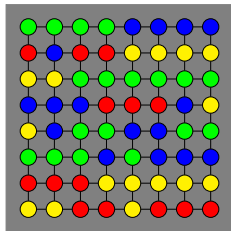
$8 \times 8 \times 8$ Laplacian partitioned using SCOTCH and k-way clustering on the first separator.

Clustering techniques: existing solutions

- k-way partitioning (dense, multifrontal)
- Supernode reordering techniques (supernodal)



(a) Symbolic factorization.



(b) First separator clustering.

$8 \times 8 \times 8$ Laplacian partitioned using SCOTCH and Reordering clustering on the first separator.

Performance gain of the TSP ordering in full-rank

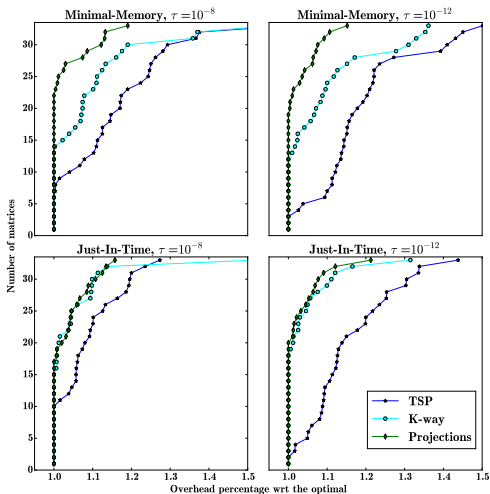
Results

- Reduce the number of off-diagonal blocks and thus the overhead associated with low-rank updates
- Lead to larger data blocks suitable for modern architectures
- Always increase performance wrt SCOTCH

Architecture	Nb. units	Mean gain	Max gain
Westmere	12 cores	2%	6%
Xeon E5	24 cores	7%	13%
Fermi	12 cores + 1 to 3 M2070	10%	20%
Kepler	24 cores + 1 to 4 K40	15%	40%
Xeon Phi	64 cores	20%	40%

Performance gain when using PARSEC runtime system with TSP

Performance profile of the factorization time



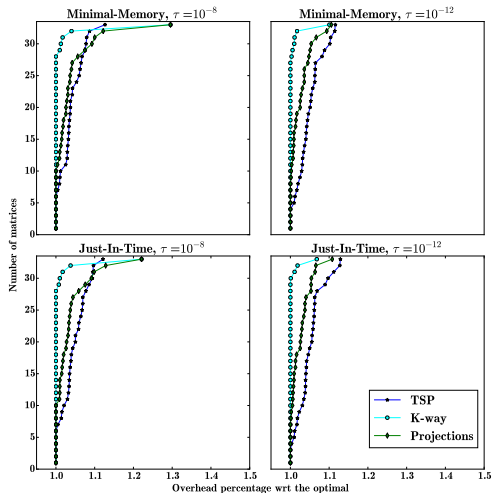
Method

- For each matrix, percentage wrt the best method
- Percentage are sorted increasingly
- A curve close to $x = 1$ is close to optimal

Results

- K-way outperforms TSP by 6%
- Projections outperforms k-way by 6% for *Minimal Memory* strategy

Performance profile of the memory consumption



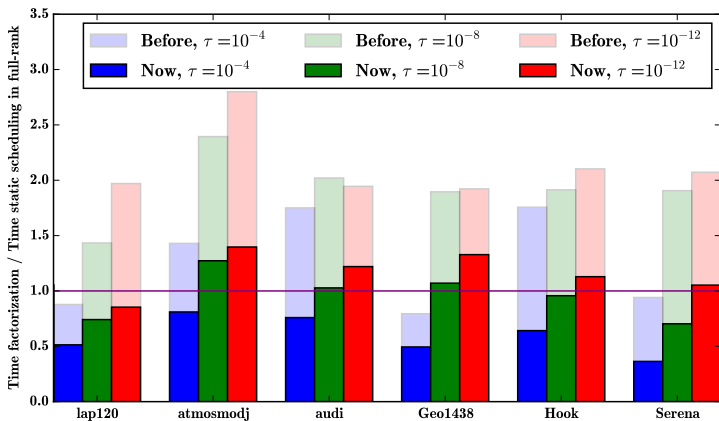
Method

- For each matrix, percentage wrt the best method
- Percentage are sorted increasingly
- A curve close to $x = 1$ is close to optimal

Results

- K-way outperforms TSP by 4%
- K-way outperforms Projections by 2%

Behavior of RRQR/*Minimal Memory* with PARSEC and Projections



Adding Projections and the use of PARSEC runtime system reduces factorization time.

3

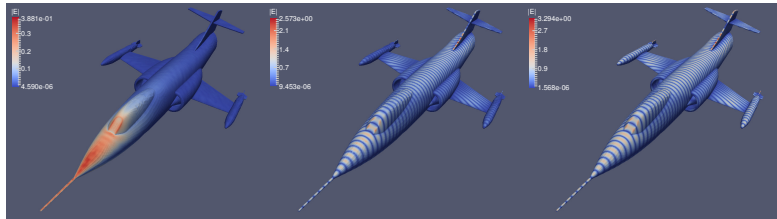
Application: HORSE

Hybridizable DG method in 3D

Scattering of a plane wave by a jet

- Unstructured tetrahedral mesh: 1,645,874 elements / 3,521,251 faces
- Frequency: 600 MHz, Wavelength: $\lambda \simeq 0.5$ m, Penalty parameter: $\tau = 1$

HDG method	# DoF Λ field	# DoF EM field
HDG- \mathbb{P}_1	21,127,506	39,500,976
HDG- \mathbb{P}_2	42,255,012	98,752,440
HDG- \mathbb{P}_3	70,425,020	197,504,880



Contour line of $|\mathbf{E}|$ - HDG- \mathbb{P}_1 to HDG- \mathbb{P}_3

Impact on HORSE - Case HDG- \mathbb{P}_2

Subs	τ	Method	Fact(s)	Nb. of iters	Refinement (s)	HDGM (s)	Memory (GB)
32	-	Full-rank	526.0	9	254.5	814.0	41.7
	1e-4	Just-In-Time	209.3	9	164.8	405.8	41.7 (22.3)
		Minimal-Memory	516.7	15	273.2	822.0	24.5
	1e-8	Just-In-Time	325.2	9	192.9	550.4	41.7 (29.4)
		Minimal-Memory	600.1	9	193.2	825.8	30.5
	48	-	Full-rank	237.3	8	118.6	374.6
1e-4		Just-In-Time	112.2	9	106.1	237.1	24.9 (14.1)
		Minimal-Memory	229.3	13	159.7	407.5	15.3
1e-8		Just-In-Time	171.5	8	105.8	296.1	24.9 (18.1)
		Minimal-Memory	319.4	8	109.8	447.9	18.8
64		-	Full-rank	179.8	9	104.7	298.3
	1e-4	Just-In-Time	79.7	10	91.1	184.1	17.4 (10.0)
		Minimal-Memory	138.1	13	120.7	272.2	11.0
	1e-8	Just-In-Time	124.6	9	90.0	228.2	17.4 (12.9)
		Minimal-Memory	239.2	9	91.5	344.5	13.7

4

Conclusion and future works

Conclusion

- Block low-rank allows to reduce time and memory complexity of sparse direct solver
- *Possible to control* the final accuracy
- Exploit the same level of parallelism as the full-rank solver
- Benefit from the dynamic scheduling of the runtime systems implementation for free
- May accelerate hybrid solvers such as HORSE

Future work

Ordering strategies - E. Korkmaz (PhD)

- Target hierarchical compression formats
- Try to apply the strategy in the ordering library (Scotch, Metis)

Others

- Distributed version (load balancing)
Looking for an intern student/Engineer
- Low-rank operations on GPUs
- Use other low-rank compression kernels, such as randomization
- Integration in new applications

Thank you.

Questions?