

# Utilisation de la compression low-rank pour réduire la complexité du solveur PaStiX

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# Utilisation de la compression low-rank pour réduire la complexité du solveur PaStiX

26 Septembre 2018 - JCAD 2018 - Lyon

Grégoire Pichon, Mathieu Faverge, Pierre Ramet, Jean Roman

#### **Outline**

- 1. Context
- Block Low-Rank solver
  From full-rank to low-rank
  Impact of ordering techniques
- 3. Application: HORSE
- 4. Conclusion and future works



Context



#### The PASTIX solver

#### Factorization

- sparse direct solver
- real and complex arithmetic
- $LU, LL^t, LDL^t, LL^H$  and  $LDL^H$  factorizations
- Static pivoting
- Refinement with BICGSTAB, CG, GMRES

#### Parallelism

- Supernodal approach
- Native static scheduling (used in next experiments)
- Runtime systems: PARSEC and STARPU
- Heterogeneous architectures (GPUs, KNL)
- Distributed (Ongoing work)

https://gitlab.inria.fr/solverstack/pastix



# **Objectives**

#### Current sparse direct solver costs for 3D problems

- $\Theta(n^2)$  time complexity
- $\Theta(n^{\frac{4}{3}})$  memory complexity
- BLAS Level 3 operations with block computations

#### Current status

- Direct solver suffer from their high complexities
- Iterative or hybrid method are often problem dependent
- Machine precision is not required with inaccurate measures

#### Objectives: low-rank compression in a sparse direct solver

- Introduce compression of dense blocks
- Reduce time and/or memory complexity
- · Keep the same level of parallelism



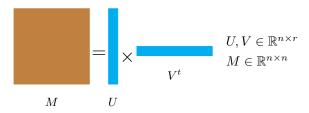
**Block Low-Rank solver** 



From full-rank to low-rank



# Low-rank compression



Storage in 2nr instead of  $n^2$ .







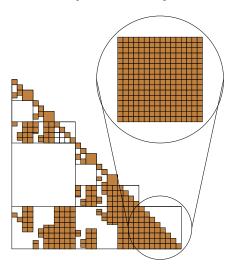
Original picture.

r = 10.

r = 50.

Compression of an image with n=500.

# BLR compression – Symbolic factorization



# Approach

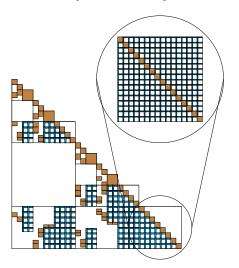
- Large supernodes are split
- It increases the level of parallelism

# Operations

- Dense diagonal blocks
- TRSM are performed on dense off-diagonal blocks
- GEMM are performed between dense off-diagonal blocks



# BLR compression – Symbolic factorization



# Approach

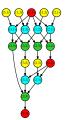
- Large supernodes are split
- Large off-diagonal blocks are low-rank

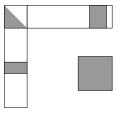
# Operations

- Dense diagonal blocks
- TRSM are performed on low-rank off-diagonal blocks
- GEMM are performed between low-rank off-diagonal blocks

- 1. Eliminate each column block
  - 1.1 Factorize the dense diagonal block Compress off-diagonal blocks belonging to the supernode
  - 1.2 Apply a TRSM on LR blocks (cheaper)
  - 1.3 LR update on dense matrices (LR2GE extend-add)
- 2. Solve triangular systems with low-rank blocks



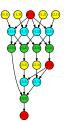


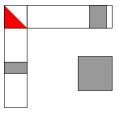




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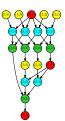


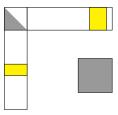




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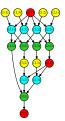


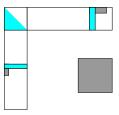




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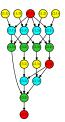


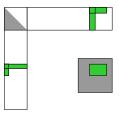




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# Summary of the Just-In-Time strategy

#### Assets

- The most expensive operation, the update, is less expensive with LR2GE kernel
- The formation of the dense update and its application is not expensive
- The size of the factors is reduced, as well as the solve cost

#### A limitation of this approach

- All blocks are allocated in full-rank before being compressed
- Limiting this constraint reduces the level of parallelism



Just-In-Time





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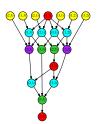


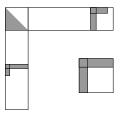
Minimal Memory



- **1.** Compress large off-diagonal blocks in A (exploiting sparsity)
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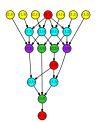


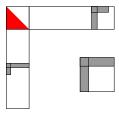




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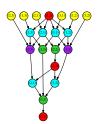


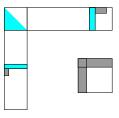




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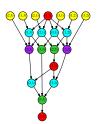


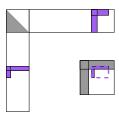




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# **Experimental setup - architectures**

# GENCI - Occigen

- ullet 2 INTEL Xeon E5-2680v3 at 2.50 GHz
- 128 GB
- 2 × 12 cores

#### MCIA - Avakas

- 2 INTEL Xeon *x*5675 at 3.06 GHz
- 48 GB
- $2 \times 12$  cores

#### PlaFRIM - Miriel

- 2 INTEL Xeon E5-2680v3 at 2.50 GHz
- 128 GB
- 2 × 12 cores



# **Experimental setup - matrices**

#### Large (33 matrices)

- Square matrices issued from the SuiteSparse Matrix Collection
- real or complex
- $50K \le N \le 5M$
- $nb_{ops} > 1$  TFlops
- Web and DNA matrices were removed

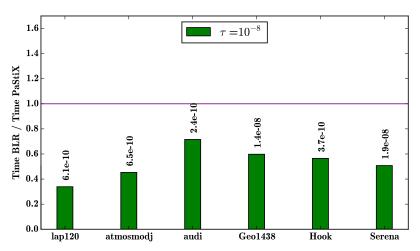
# Small (6 matrices)

Matrix	Fact.	Size	Field
Atmosmodj	LU	1 270 432	atmospheric model
Audi	$LL^t$	$943\ 695$	structural problem
Hook	$LDL^t$	$1\ 498\ 023$	model of a steel hook
Serena	$LDL^t$	1 391 349	gas reservoir simulation
Geo1438	$LL^t$	$1\ 437\ 960$	geomechanical model of earth
lap120	$LDL^t$	$120^{3}$	Poisson problem





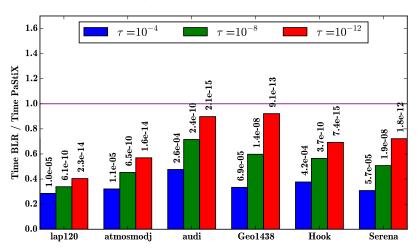
#### Performance of RRQR/Just-In-Time wrt full-rank version



Factorization time reduced by a factor of 2 for  $\tau=10^{-8}.$ 



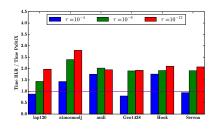
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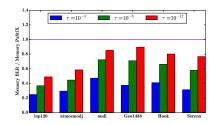


# Behavior of RRQR/Minimal Memory wrt full-rank version





- Increase by a factor of 1.9 for  $\tau = 10^{-8}$
- Better for a lower accuracy



#### Memory footprint

- Reduction by a factor of 1.7 for  $\tau = 10^{-8}$
- Close to the results obtained using SVD





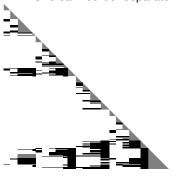
# 2.2

Impact of ordering techniques



# Ordering for sparse matrices

One can reorder separators without modifying the fill-in.



Symbolic factorization of a  $8 \times 8 \times 8$  Laplacian.

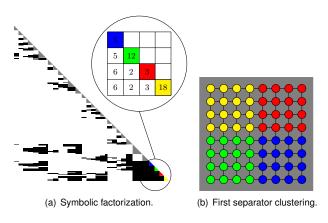
# Enhance ordering

- Modify the partitioning process to enhance compressibility
- Reorder unknowns within a separator:
  - ► To enhance clustering within the separator
  - ► To enhance the coupling part



# Clustering techniques: existing solutions

k-way partitioning (dense, multifrontal)

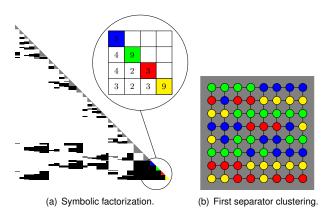


 $8\times8\times8$  Laplacian partitioned using Scotch and k-way clustering on the first separator.



# Clustering techniques: existing solutions

- k-way partitioning (dense, multifrontal)
- Supernode reordering techniques (supernodal)



 $8\times8\times8$  Laplacian partitioned using SCOTCH and Reordering clustering on the first separator.



# Performance gain of the TSP ordering in full-rank

#### Results

- Reduce the number of off-diagonal blocks and thus the overhead associated with low-rank updates
- Lead to larger data blocks suitable for modern architectures
- Always increase performance wrt Scotch

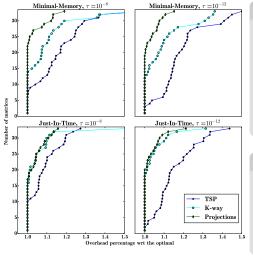
Architecture	Nb. units	Mean gain	Max gain
Westmere	12 cores	2%	6%
Xeon E5	24 cores	7%	13%
Fermi	12 cores + 1 to 3 M2070	10%	20%
Kepler	24 cores + 1 to 4 K40	15%	40%
Xeon Phi	64 cores	20%	40%

Performance gain when using PARSEC runtime system with TSP





# Performance profile of the factorization time



#### Method

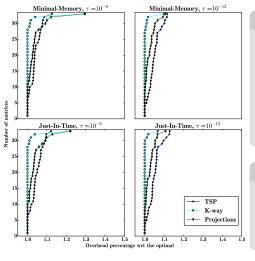
- For each matrix, percentage wrt the best method
- Percentage are sorted increasingly
- A curve close to x = 1 is close to optimal

#### Results

- K-way outperforms TSP by 6%
- Projections outperforms k-way by 6% for Minimal Memory strategy



# Performance profile of the memory consumption



#### Method

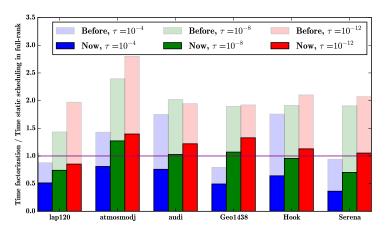
- For each matrix, percentage wrt the best method
- Percentage are sorted increasingly
- A curve close to x = 1 is close to optimal

#### Results

- K-way outperforms TSP by 4%
- K-way outperforms Projections by 2%



# Behavior of RRQR/Minimal Memory with PARSEC and Projections



Adding Projections and the use of PARSEC runtime system reduces factorization time.



**Application: HORSE** 

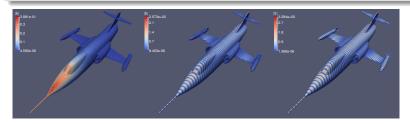


# Hybridizable DG method in 3D

#### Scattering of a plane wave by a jet

- Unstructured tetrahedral mesh: 1,645,874 elements / 3,521,251 faces
- Frequency: 600 MHz, Wavelength:  $\lambda \simeq 0.5$  m, Penalty parameter:  $\tau = 1$

HDG method	# DoF $\Lambda$ field	# DoF EM field
$HDG ext{-}\mathbb{P}_1$	21,127,506	39,500,976
$HDG ext{-}\mathbb{P}_2$	42,255,012	98,752,440
$HDG ext{-}\mathbb{P}_3$	70,425,020	197,504,880



Contour line of  $|\mathbf{E}|$  - HDG $-\mathbb{P}_1$  to HDG $-\mathbb{P}_3$ 



# Impact on HORSE - Case HDG- $\!\mathbb{P}_2$

Subs	$\tau$	Method	Fact(s)	Nb. of iters	Refinement (s)	HDGM (s)	Memory (GB)
32	-	Full-rank	526.0	9	254.5	814.0	41.7
	1e-4	Just-In-Time	209.3	9	164.8	405.8	41.7 (22.3)
		Minimal-Memory	516.7	15	273.2	822.0	24.5
	1e-8	Just-In-Time	325.2	9	192.9	550.4	41.7 (29.4)
		Minimal-Memory	600.1	9	193.2	825.8	30.5
48	-	Full-rank	237.3	8	118.6	374.6	24.9
	1e-4	Just-In-Time	112.2	9	106.1	237.1	24.9 (14.1)
	16-4	Minimal-Memory	229.3	13	159.7	407.5	15.3
	1e-8	Just-In-Time	171.5	8	105.8	296.1	24.9 (18.1)
		Minimal-Memory	319.4	8	109.8	447.9	18.8
64	-	Full-rank	179.8	9	104.7	298.3	17.4
	1e-4	Just-In-Time	79.7	10	91.1	184.1	17.4 (10.0)
		Minimal-Memory	138.1	13	120.7	272.2	11.0
	1e-8	Just-In-Time	124.6	9	90.0	228.2	17.4 (12.9)
		Minimal-Memory	239.2	9	91.5	344.5	13.7



**Conclusion and future works** 



#### Conclusion

- Block low-rank allows to reduce time and memory complexity of sparse direct solver
- Possible to control the final accuracy
- Exploit the same level of parallelism as the full-rank solver
- Benefit from the dynamic scheduling of the runtime systems implementation for free
- May accelerate hybrid solvers such as HORSE





#### **Future work**

#### Ordering strategies - E. Korkmaz (PhD)

- Target hierarchical compression formats
- Try to apply the strategy ine the ordering library (Scotch, Metis)

#### Others

- Distributed version (load balancing)
  Looking for an intern student/Engineer
- Low-rank operations on GPUs
- Use other low-rank compression kernels, such as randomization
- Integration in new applications



Thank you.

Questions?



