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Randomized incremental construction of Delaunay triangulations of nice point sets

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— Abstract

Randomized incremental construction (RIC) is one of the most important paradigms for building geometric data structures. Clarkson and Shor developed a general theory that led to numerous algorithms that are both simple and efficient in theory and in practice.

Randomized incremental constructions are most of the time space and time optimal in the worst-case, as exemplified by the construction of convex hulls, Delaunay triangulations and arrangements of line segments. However, the worst-case scenario occurs rarely in practice and we would like to understand how RIC behaves when the input is nice in the sense that the associated output is significantly smaller than in the worst-case. For example, it is known that the Delaunay triangulations of nicely distributed points in \mathbb{E}^d or on polyhedral surfaces in \mathbb{E}^3 has linear complexity, as opposed to a worst-case complexity of $\Theta(n^{\lfloor d/2 \rfloor})$ in the first case and quadratic in the second. The standard analysis does not provide accurate bounds on the complexity of such cases and we aim at establishing such bounds in this paper. More precisely, we will show that, in the two cases above and variants of them, the complexity of the usual RIC is $O(n \log n)$, which is optimal. In other words, without any modification, RIC nicely adapts to good cases of practical value.

Along the way, we prove a probabilistic lemma for sampling without replacement, which may be of independent interest.

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1 1

Introduction

The randomized incremental construction (RIC) is an algorithmic paradigm introduced by Clarkson and Shor [11], which has since found immense applicability in computational geometry, e.g. [27, 26]. The general idea is to process the input points sequentially in a random order, and to analyze the expected complexity of the resulting procedure. The theory developed by Clarkson and Shor is quite general and led to numerous algorithms that are simple and efficient, both in theory and in practice. On the theory side, randomized incremental constructions are most of the time space and time optimal in the worst-case, as exemplified by the construction of convex hulls, Delaunay triangulations and arrangements of line segments. Randomized incremental constructions appear also to be very efficient in practice, which, together with their simplicity, make them the most popular candidates for implementations. Not surprisingly, the CGAL library includes several randomized incremental algorithms, e.g. for computing Delaunay triangulations.

Experimental evidence has shown that randomized incremental constructions work very well beyond the worst-case, which is fortunate since worst-case situations are rare in many applications. This paper aims at extending the analysis of RIC to the case of average-case complexity. More precisely, our goal is to understand how randomized incremental constructions behave when the input is nice in the sense that the associated construction is significantly smaller than in the worst-case.

We need a model of good point sets to describe the input data and analyze the algorithms. This will be done through the notion of ε -nets, which have a long and rich history since their introduction in the 1950's in the works of Kolmogorov and others on functional analysis and topological vector spaces (see e.g. [31]). ε -nets have become ubiquitous in many theoretical as well as applied areas, from geometry, functional analysis to probability theory, statistics etc., where they are often used as countable or finite approximations of continuous spaces.

When we enforce such a hypothesis of "nice" distribution of the points in space, a volume counting argument ensures that the local complexity of the Delaunay triangulation around a vertex is bounded by a constant (dependent only on the dimension).

Unfortunately, to be able to control the complexity of the usual randomized incremental algorithms [14, 9, 11, 3], it is not enough to control the final complexity of the Delaunay triangulation. We need to control also the complexity of the triangulation of random subsets. One might expect that a random subsample of size k of an ε -net is also an ε' -net for $\varepsilon' = \varepsilon \sqrt[d]{\frac{n}{k}}$. Actually this is not quite true, it may happen with reasonable probability that a ball of radius $O(\varepsilon')$ contains $O(\log k/\log\log k)$ points or that a ball of radius $O(\varepsilon')$ does not contain any point. For the convenience of the reader, we briefly sketch the proofs in the Appendix (Lemma 43). However, it can only be shown that such a subsample is an $O(\log 1/\varepsilon)$ -covering and an $O(\varepsilon')$ -covering and an $O(\varepsilon')$ -covering, with high probability. Thus this approach can transfer the complexity of an ε -net to the one of a random subsample of an ε -net but with an extra multiplicative factor of $O(\log 1/\varepsilon) = O(\log n)$. It follows that, in the two cases we consider, the standard analysis does not provide accurate bounds on the complexity of the (standard) randomized incremental construction.

Related Work: The Delaunay triangulations of nicely-distributed points have been studied since the 50's, e.g. in the work of Meijering [22], Gilbert [20], Miles [23] Møller [25], Golin-Na [21], for Poisson-distributed points, Dwyer [16, 15] for uniformly distributed points, Attali-Boissonnat [4], Attali-Boissonnat-Lieutier [5], Amenta-Attali-Devillers [2], and others for (ε, κ) -samples, and Erickson [17, 18] for points with bounded spread (the ratio between

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the maximum to minimum distance between any two points). Except for a few authors such as Dwyer [16] and Erickson [18], most of the above results discuss only the combinatorial 67 aspects and not the algorithmic ones. For Poisson and uniformly distributed point samples, we observe that the standard analysis of the RIC procedure immediately implies a bound on the expected run-time, of the order of the expected number of simplices times a logarithmic factor, which is optimal. However, for deterministic notions of nice distributions such as ε 71 nets, (ε, κ) samples, and bounded spread point sets, the standard RIC analysis is not optimal, 72 since, as we observed, it gives at least an extra logarithmic factor for (ε, κ) samples and 73 even worse for bounded spread point-sets, as stated in an open problem by Erickson [18]. Miller, Sheehy and Velingker [24] follow a very different approach, giving an algorithm to compute the approximate Delaunay graph of nicely-spaced superset of points for an arbitrary input point-set, with optimal time complexity and a $2^{O(d)}$ -dependence on the dimension. However their algorithm is quite complicated and uses several subroutines that have varying difficulties of implementation. The RIC, while having a worse $2^{O(d^2)}$ dependence on the dimension (which Miller et al. observe, may be impossible to avoid for computing the exact Delaunay graph), computes the entire Delaunay triangulation of the given point set, i.e. not 81 a superset, is easy to implement and works efficiently in practice.

Our contribution: We consider two main questions in this paper. First, we consider the case of an ε -net in the periodic space of dimension d, which, as mentioned before, have linear complexity instead of the worst-case $\Theta(n^{\lfloor d/2 \rfloor})$. The reason to consider a periodic space is to avoid dealing with boundary effects that would distract us from the main point, and the fact that periodic spaces are often used in practice, e.g. in simulations in astronomy, biomedical computing, solid-state chemistry, condensed matter physics, etc. [10, 12, 28, 19, 32]. Following this, we deal with ε -nets on a polyhedral surface of \mathbb{E}^3 , which is also a commonly-occuring practical scenario in e.g. surface reconstruction [1, 8], and has Delaunay triangulations with linear, as opposed to the worst-case quadratic, complexity. In this case, the boundary effects need to be explicitly controlled, which requires a more careful handling along with some new ideas. In both cases, we establish tight bounds and show that the complexity of the usual RIC is $O(n \log n)$, which is optimal. Hence, without any modification, the standard RIC nicely adapts to the good cases above.

Our main new technical development is a general bound for the probability of certain non-monotone events in sampling without replacement, which may be of independent interest.

Extensions We also give some extensions of our results for periodic spaces. Our extensions are in four directions: (i) a more general notion of well-distributed point sets, the (ε, κ) samples (ii) a different notion of subsampling - the Bernoulli or i.i.d. sample where each point is selected to be in $\mathcal Y$ independently of the others, with probability q=s/n, (iii) a more general class of spaces - Euclidean d-orbifolds, and (iv) a more general class of metrics - those having bounded-distortion with respect to the Euclidean metric. Precisely, for all the above cases, we show that the Delaunay triangulation of a random subsample has a linear size in expectation. We believe that our methods should work for an even larger classes of spaces, though this might require more delicate handling of boundary effects and other features specific to the metric space under consideration.

Outline The rest of the paper is as follows. In Section 2, we define the basic concepts of Delaunay triangulation, ε -net, flat torus and random samples. We state our results in Section 3. In Section 4, we bound the size of the Delaunay triangulation of a uniform random sample of a given size extracted from an ε -net on the flat torus \mathbb{T}^d . In Section 5, we analyse

the case when the uniform random subsample is drawn from an ε -net on a polyhedral surface in \mathbb{E}^3 . In Section 6, we use the size bounds established in Sections 4 and 5, to compute the space and time complexity of the randomized incremental construction for constructing Delaunay triangulations of ε -nets. Finally, in Section 7, we state and prove some extensions. Proofs missing from the main sections are given in the Appendix.

2 Background

2.1 Notations

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We denote by $\Sigma(p,r)$, B(p,r) and B[p,r], the sphere, the open ball, and the closed ball of center p and radius r respectively. For $x \in \mathbb{E}^2$, $y \geq 0$, D(x,r) denotes the disk with center x 122 and radius r, i.e. the set of points $\{y \in \mathbb{E}^2 : \|y - x\| < r\}$, and similarly D[x, r] denotes the corresponding closed disk. The volume of the unit Euclidean ball of dimension d is denoted 124 V_d and the area of the boundary of such a ball is denoted S_{d-1} . It is known that $V_d = \frac{\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2}+1)}$ and $S_d = 2\pi V_{d-1}$, where $\Gamma(t) := \int_0^\infty e^{-x} x^{t-1} dx$, (t > 0) denotes the Gamma function. For $d \in \mathbb{Z}^+$, $\Gamma(d+1) = d!$. We note that $2^d d^{-d/2} \le V_d \le 2^{4d} d^{-d/2}$ (see e.g. [33]). For an event \mathcal{E} in some probability space Ω , we use $\mathbf{1}_{[\mathcal{E}]}$ to denote the indicator variable $\mathbf{1}_{[\mathcal{E}]} = \mathbf{1}_{[\mathcal{E}]}(\omega)$ which 128 is 1 whenever $\omega \in \mathcal{E}$, and zero otherwise. We use [n] to mean the set $\{1, 2, \ldots, n\}$. Given a 129 discrete set A, $\sharp(A)$ denotes its cardinality and, for $k \in \mathbb{Z}^+$, $\binom{A}{k}$ denotes the set of k-sized subsets of A. Given an event A in some probability space, $\mathbb{P}[A]$ denotes the probability of A 131 occurring. For a random variable Z in a probability space, $\mathbb{E}[Z]$ denotes the expected value of Z. Lastly, e = 2.7182... denotes the base of the natural logarithm. 133

2.2 ε -nets

A set \mathcal{X} of n points in a metric space \mathcal{M} , is an ε -packing if any pair of points in \mathcal{X} are at least distance ε apart, and an ε -cover if each point in \mathcal{M} is at distance at most ε from some point of \mathcal{X} . \mathcal{X} is an ε -net if it is an ε -cover and an ε -packing simultaneously.

The definition of ε -net applies for any metric space. In the case of the Euclidean metric, we can prove some additional properties. We shall use $\|.\|$ to denote the Euclidean ℓ_2 norm.

- **Lemma 1** (Maximum packing size). Let $\rho \leq 1$, then any packing of the ball of radius $r \geq \rho$ in dimension d by disjoint balls of radius $\rho/2$ has a number of balls smaller than $\left(\frac{3r}{\rho}\right)^d$.
- ▶ **Lemma 2** (Minimum cover size). Any covering of a ball of radius r in dimension d by balls of radius ρ has a number of balls greater than $\left(\frac{r}{\rho}\right)^d$.
- For $d \in \mathbb{Z}^+$, the flat d-torus \mathbb{T}^d is the compact quotient group $\mathbb{E}^d/\mathbb{Z}^d$, with addition as the group action. More generally, for $k \in \mathbb{Z}^+$, the flat torus of length k is $\mathbb{T}^d_k := \mathbb{E}^d/(k\mathbb{Z})^d$.
- Lemma 3 (ε -net size bounds). Given $\varepsilon \in (0,1]$, let \mathcal{X} be an ε -net over the flat torus \mathbb{T}^d .

 Then, $\sharp (\mathcal{X}) \in [d^{d/2}2^{-3d} \cdot \varepsilon^{-d}, d^{d/2}\varepsilon^{-d}]$.

2.3 Delaunay triangulation

For simplicity of exposition and no real loss of generality, all finite point sets considered in this paper will be assumed to be in *general position*, i.e. no set of d+2 points lie on a sphere. Given a set \mathcal{X} in Euclidean space \mathbb{E}^d in general position, the *Delaunay triangulation* of \mathcal{X} , or $Del(\mathcal{X})$, is the geometric simplicial complex with vertex set \mathcal{X} such that any d-simplex σ can

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be circumscribed by an empty ball, i.e. a ball whose bounding sphere contains the vertices of σ and whose interior contains no points of \mathcal{X} . It is known that such a triangulation exists, 154 is unique, and is embedded in \mathbb{E}^d under the general position assumption. Given a set \mathcal{X} in 155 Euclidean space \mathbb{E}^d , having its Delaunay triangulation $Del(\mathcal{X})$, the star of a subset $S \in \mathcal{X}$, or star(S), is the set of all simplices in Del(X) which are incident to at least one point in 157 S. For a point $p \in \mathcal{X}$, we shall use the shorthand expression star(p) to mean $star(\{p\})$, 158 and $star^2(p)$ to mean $star(star(\{p\}))$ respectively. Given topological spaces S and C, and 159 a continuous map $\pi: \mathcal{C} \to \mathcal{S}$, \mathcal{C} is a covering space of \mathcal{S} if π is such that for every point 160 $x \in \mathcal{S}$, there exists an open neighbourhood U of x, such that the pre-image $\pi^{-1}(U)$ is a disjoint union of open neighbourhoods in \mathcal{C} , each of which is homeomorphically mapped onto 162 U by π . The cardinality of the pre-image of any point $x \in \mathcal{S}$ under the covering map π is 163 the multiplicity of x. A covering space of S, with a covering map having multiplicity m is 164 referred to as an *m*-sheeted covering of S. 165

For example, \mathbb{T}_k^d forms a k^d -sheeted covering space of \mathbb{T}^d , with the covering map $x\mapsto x$ mod 1, the modulus operation being defined coordinate-wise. Caroli and Teillaud [10] showed

▶ **Theorem 4** (Caroli-Teillaud [10]). The Delaunay triangulation of any finite point set in \mathbb{T}^d embeds in the 3^d -sheeted covering of \mathbb{T}^d . If the maximum circumradius of a simplex is at most 1/2, then the triangulation embeds in the one-sheeted covering of \mathbb{T}^d .

A key property of ε -nets is that their Delaunay triangulations have linear size.

Lemma 5 ([29]). Let $\varepsilon \in (0,1]$ be given, and let \mathcal{X} be an ε -net over \mathbb{T}^d . Then the Delaunay triangulation of \mathcal{X} , $Del(\mathcal{X})$ has at most $4^{d^2}\varepsilon^{-d}$ simplices.

2.4 Randomized incremental construction and random subsamples

For the algorithmic complexity aspects, we state a version of a standard theorem for the RIC procedure, stated in [13]). We first need a necessary condition for the theorem. When a new point p is added to an existing triangulation, a *conflict* is defined to be a previously existing simplex whose circumball contains p.

▶ Condition 6. At each step of the RIC, the set of newly introduced conflicts can be computed in time proportional to the number of conflicts.

In the Euclidean case, Condition 6 is verified to hold by observing that the set of simplices in conflict with the new point is a connected set, and therefore walking on the adjacency graph of the simplices is enough to yield the set of introduced conflicts (see e.g. [11]). We now come to the general theorem on the algorithmic complexity of RIC.

- ▶ **Theorem 7** (Devillers [13] Theorem 5(1,2)). Let F(s) denote the expected number of simplices that appear in the d-skeleton of the Delaunay complex of a uniform random sample of size s, from a given point set P. Then, if Condition 6 holds and F(s) = O(s), we have (i) The expected space complexity is O(n).
- 189 (ii) The expected time complexity is $\sum_{s=1}^{n} \frac{n-s}{s} = O(n \log n)$.

Thus bounding the complexity of incremental algorithms reduces to bounding the expected complexity of the Delaunay triangulation of random subsets of ε -nets of a given size.

A subset \mathcal{Y} of set \mathcal{X} is a uniform random sample of \mathcal{X} of size s if \mathcal{Y} is any possible subset of \mathcal{X} of size s with equal probability. In case the multiplicity of a point in \mathcal{X} is greater than 1, the sample counts only one copy of the point; all other copies are present in \mathcal{Y} if and only if the original point is present.

In order to work with uniform random samples, we shall prove a lemma on the uniformly random sampling distribution or *sampling without replacement*, which is stated below, and shall be a key probabilistic component of our proofs. The lemma provides a bound on the probability of a non-monotone compound event, that is, if the event holds true for a fixed set of k points, there could exist supersets as well as subsets of the chosen set for which the event does not hold. This may well be of general interest, as most natural contiguity results with Bernoulli (i.e. independent) sampling, are for monotone events.

Lemma 8. Given $a,b,c\in\mathbb{Z}^+$, with $b\leq\min(\frac{a}{2},c-1)$, the probability that the random sample A having cardinality a of a set C of cardinality c, contains the included subset B having cardinality b, and is disjoint from the excluded subset T, which is disjoint from B and has cardinality at least t, is at most $\left(\frac{a}{c}\right)^b\left(1-\frac{t}{c-b}\right)^{a-b}\leq \left(\frac{a}{c}\right)^b\cdot\exp\left(-\frac{at}{2c}\right)$,

As a consequence of Lemma 8, it can be shown that for finite sampling spaces, the j-th moment is essentially the j-th power of the first moment, for sufficiently small j.

Lemma 9 (j-th moment). Given $a, b, c \in \mathbb{Z}^+$, and a set C of size c, a fixed subset $B \subseteq C$ of size $b \le c$ and a uniformly random sample A of size a, then for $j \le c/2$, the j-th moment of the random variable $X := \sharp (A \cap B)$ i.e. $\mathbb{E}[X^j]$, satisfies $\mathbb{E}[X^j] \le (\mathbb{E}[X])^j$.

3 Results

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 ε -nets in \mathbb{T}^d : The following theorem gives a constant bound on the expected size of star(p) and $star^2(p)$, for the Euclidean metric on the flat torus \mathbb{T}^d .

- Theorem 10 (Euclidean metric). Given an ε -net \mathcal{X} in \mathbb{T}^d in general position, where $\varepsilon \in (0, \frac{1}{4}]$, the following holds.
- The expected number of simplices incident to a point $p \in \mathcal{X}$, $\mathbb{E}\left[\sharp\left(star(p)\right)\right]$ in the Delaunay triangulation of a uniform random sample $S \subset \mathcal{X}$ of size $s \geq 4(2\sqrt{d})^d d^3 + 1$ containing p, is less than $2 \cdot 6^{d^2 + d}$.
- 220 (ii) The expected number of simplices incident to the simplices in star(p), $\mathbb{E}\left[\sharp\left(star^{2}(p)\right)\right]$, is also a constant.

Polyhedral Surfaces in \mathbb{E}^3 : A *polyhedral surface* S in \mathbb{E}^3 is a collection of a finite number of polygons $F \subset S$, called *facets*, which are pairwise disjoint or meet along an edge. In this paper, S will denote an arbitrary but fixed polyhedral surface, with C facets, and having total length of the boundaries of its faces L and total area of its faces A.

We next show that the expected complexity of the Delaunay triangulation of a uniformly random subsample of an ε -net on a polyhedral surface, is linear in the size of the subsample.

▶ **Theorem 11.** Given $\varepsilon \in [0,1]$, and \mathcal{X} an ε -net on \mathcal{S} , having n points, let $\mathcal{Y} \subset \mathcal{X}$ be a random sub-sample of \mathcal{X} having size s. Then the Delaunay triangulation $Del(\mathcal{Y})$ of \mathcal{Y} on \mathcal{S} has O(s) simplices. Further, for a random point $p \in \mathcal{Y}$, $\mathbb{E}\left[\sharp\left(star^2(p)\right)\right] = O(1)$.

Algorithmic Bounds: We next use the above combinatorial bounds to get the space and time complexity of the randomized incremental construction of the Delaunay triangulation of an ε -net, on the flat d-torus or on a polyhedral surface in \mathbb{E}^3 .

Theorem 12 (Randomized incremental construction). Given $\varepsilon \in [0, 1/4]$, and an ε -net \mathcal{X} in general position over (i) a flat torus \mathbb{T}^d , or (ii) a fixed polyhedral surface $\mathcal{S} \subset \mathbb{E}^3$, then the randomized incremental construction of the Delaunay triangulation takes $O(n \log n)$ expected time and O(n) expected space, where $n = \sharp(\mathcal{X})$ and the constant in the big O is

independent of n. Further, at each step of the randomized incremental construction, the Delaunay triangulation of the set $\mathcal Y$ of already added points of $\mathcal X$ embeds in $\mathbb T^d$.

Extensions: Finally, our extensions are stated and proved in Section 7.

4 Euclidean Metric on \mathbb{T}^d

In this section, we prove that a subsample \mathcal{Y} of a given size s, drawn randomly from an ε -net $\mathcal{X} \subset \mathbb{T}^d$, has a Delaunay triangulation in which the star of any given vertex has a constant expected complexity. Hence, the expected complexity of the triangulation is linear in the size of the subsample. The constant of proportionality is bounded by 2^{cd^2} , where c is a constant independent of ε and d.

We begin by setting up the proof framework. We recall that $n := \sharp(\mathcal{X})$. Define $q := \frac{s-1}{n-1}$. Define $\delta := \varepsilon \cdot \left(\frac{2d}{q}\right)^{1/d}$. Let $I_0 := [0, \delta)$, $I_k := [2^{k-1}\delta, 2^k\delta)$ for k > 0. To bound the expected complexity, we shall consider the probability of existence of potential d-simplices in \mathcal{X} , incident to p and having radius in the intervals I_k , as k ranges over \mathbb{Z}^+ .

Throughout this section, we shall use σ to mean a d-simplex incident to p, with circumcentre c_{σ} and circumradius r_{σ} , and τ to mean the set of vertices of $\sigma \setminus \{p\}$. To count the number of simplices in star(p) with circumradius in I_k , let $S_p(k)$ denote the set of possible (d-1)-simplices with vertices in \mathcal{X} , such that for every $\tau \in S_p(k)$, the d-simplex $\sigma := \tau \cup \{p\}$ has circumradius $r_{\sigma} \in I_k$. Set $s_p(k) := \sharp (S_p(k))$. Let n_k denote the minimum number of points of \mathcal{X} in the interior of the circumball of σ , over all $\tau \in S_p(k)$: $n_k := \min_{\tau \in S_p(k)} \{\sharp (B(c_{\sigma}, r_{\sigma}) \cap \mathcal{X}) : \sigma = \tau \cup \{p\}\}$. For $\tau \in S_p(k)$, let $P_p(k)$ denote an upper bound on the probability that $\sigma = \tau \cup \{p\}$ appears in $Del(\mathcal{Y})$, that is,

$$P_p(k) := \max_{\tau \in S_p(k)} \{ \mathbb{P} \left[\sigma \in Del(\mathcal{Y}) \right] \}.$$

Finally, let $Z_p(k)$ denote the subset of simplices $\tau \in S_p(k)$ such that $\sigma \in Del(\mathcal{Y})$.

The main lemma in the proof is a bound on the expected complexity of the star of p, in terms of $s_p(k)$ and $P_p(k)$.

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▶ Lemma 13. \mathbb{E}\left[\sharp\left(star(p)\right)\right] \leq \sum_{k>0} \mathbb{E}\left[Z_p(k)\right] \leq \sum_{k>0} s_p(k) \cdot P_p(k).
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It only remains, therefore, to establish bounds on $s_p(k)$ and $P_p(k)$ as functions of k, and finally to bound the sum $\sum_{k\geq 0} s_p(k) \cdot P_p(k)$. In order to ensure we always have a triangulation embedded in \mathbb{T}^d , we shall use Theorem 4. Accordingly, we get two different regimes of the simplices in the triangulation. When the circumradius of a potential simplex $\sigma \in star(p)$ is at most 1/4, then the simplex lies in a ball of radius at most 1/2 with center p. By Theorem 47, in this regime the triangulation embeds in the one-sheeted covering of \mathbb{T}^d . Therefore, for a fixed set of vertices, there is a unique circumball. When the circumradius is greater than 1/4, the simplex is contained in a ball of radius > 1/2 around p, and therefore embeds in the 3^d -sheeted covering of \mathbb{T}^d , i.e. \mathbb{T}^d_3 . In this case, each vertex has 3^d copies, and so for a given choice of d vertices of a simplex, one can have $(3^d)^d$ circumballs. We shall therefore split the sum $\sum_{k\geq 0} \mathbb{E}\left[Z_p(k)\right]$ into the two regimes, $0\leq k\leq k_{\max}$, and $k>k_{\max}$, where k_{\max} denotes $\log_2 \frac{1}{4\delta}$. We first discuss the case when $0\leq k\leq k_{\max}$.

Simplices with small circumradii: $k \in [0, k_{\text{max}}]$. We begin by establishing a bound on $P_p(k)$. Applying Lemma 8,

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▶ Lemma 14. P_p(k) \le q^d \cdot \exp(-qn_k/2).
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Lemma 15. Let σ be a d-simplex incident to p, with circumcentre c_{σ} and circumradius r_{σ} . Then $\sigma \subset B[p, 2r_{\sigma}]$ and $B(c_{\sigma}, r_{\sigma}) \subset B(p, 2r_{\sigma})$.

Now we can bound $s_p(k)$ using the above observation together with Lemma 1.

▶ Lemma 16. For
$$k \ge 0$$
, $s_p(k) \le \frac{(6 \cdot 2^k \delta/\varepsilon)^{d^2}}{d!}$.

Finally, we bound n_k from below using Lemma 2.

Lemma 17. Let σ be a simplex incident to p, having circumvadius $r_{\sigma} \in I_k$, $k \geq 0$.

$$n_k \ge \begin{cases} 0 & k = 0. \\ \left(\frac{2^{k-1}\delta}{\varepsilon}\right)^d & 0 < k \le k_{\max}. \end{cases}$$

Proof. When $k \leq k_{\text{max}}$, the radius of the circumball of a simplex $\sigma = \tau \cup \{p\}$, $\tau \in S_p(k)$, is at most $2^{k_{\text{max}}} \delta \leq 1/4 < 1/2$. Applying Theorem 4, we work in the one-sheeted covering of \mathbb{T}^d . Using the fact that \mathcal{X} is an ε -covering, we apply Lemma 2 to get that $n_k \geq (2^{k-1}\delta/\varepsilon)^d$.

Next, using the above bounds on $s_p(k)$ and n_k , we shall bound the sum $\sum_{k=0}^{k_{\text{max}}} \mathbb{E}[Z_p(k)]$ in the following couple of lemmas.

▶ **Lemma 18.**
$$\mathbb{E}[Z_p(0)] \leq 6^{d^2+d}$$
.

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Proof. Substituting the bounds on $s_p(0)$ and $P_p(0)$ proved in Lemmas 16, 14 and 17 respectively, we have

$$\mathbb{E}\left[Z_{p}(0)\right] = s_{p}(0) \cdot P_{p}(0)$$

$$= \frac{\left(6(\delta/\varepsilon)\right)^{d^{2}}}{d!} \cdot q^{d} \leq \frac{6^{d^{2}} \cdot (2d)^{d}}{d!} \leq 6^{d^{2}} \cdot (2e)^{d},$$

where in the second step we used the definition of δ to get $q(\delta/\varepsilon)^d = 2d$, and in the last step we used Stirling's approximation $d^d/d! \le e^d$. Since 2e < 6, this proves the lemma.

Lemma 19.
$$\sum_{k=0}^{k_{\max}} \mathbb{E}\left[Z_p(k)\right] \leq (1-(2/e)^6)^{-1} \cdot 6^{d^2+d}$$

Lastly, we need to bound the expected number of simplices with exceptionally large circumradii, i.e. $\sum_{k>k_{\max}} \mathbb{E}[Z_p(k)]$.

Simplices with large circumradii: $k > k_{\rm max}$.

$$\blacktriangleright$$
 Lemma 20. $\sum_{k>k_{\max}} \mathbb{E}\left[Z_p(k)\right] \leq 5$.

Thus, by Lemmas 13, 19, and 20, the expected complexity of the star of p is at most $(1-(2/e)^6)^{-1} \cdot 6^{d^2+d} + 5 \le 2 \cdot 6^{d^2+d}$ for $d \ge 2$, which completes the proof of Theorem 10 (i).

Theorem 10(ii) (Proof Sketch). The proof will build on the previous part. The idea is to consider potential pairs of simplices (σ, τ) , with $\sigma \in star(p)$ and $\tau \in star^2(p)$, such that $\sigma \setminus \{p\} \cap \tau \neq \emptyset$, and bound from above the probability that a pair (σ, τ) can exist in the Delaunay complex. As in the proof of part (i) of the Theorem, we shall sum over all possible ranges of pairs of circumradii of the simplex-pairs. We need to (a) upper bound the number of potential simplex-pairs, in a given range of pairs of circumradii, which we do using a product bound over the individual ranges, and (b) lower bound the number of points excluded from being selected in the subsample, if a given simplex-pair is to be realised in the Delaunay complex. The key idea is to use the larger circumradius of the given simplex-pair for the lower bound in (b).

5 Polyhedral Surfaces in \mathbb{E}^3

In this section, we introduce a partition of the sub-sample \mathcal{Y} into boundary and interior points, to do a case analysis of the expected number of edges in the Delaunay triangulation $Del(\mathcal{Y})$, depending on whether the end-points of a potential Delaunay edge, are boundary or interior points, and whether they lie on the same facet or on different facets.

Main ideas: Our overall strategy will be to mesh the proofs of Attali-Boissonnat [4] and Theorem 10. Briefly, Attali and Boissonnat reduce the problem to counting the Delaunay edges of the point sample, which they do by distinguishing between boundary and interior points of a facet. For boundary points, they allow all possible edges. For interior points, the case of edges with endpoints on the same facet is easy to handle, while geometric constructions are required to handle the case of endpoints on different facets, or that of edges with one endpoint in the interior and another on the boundary. However, we shall need to introduce some new ideas to adapt our previous methods to this setting.

Firstly, an edge can have multiple balls passing through its endpoints and, as soon as one of these balls is empty, the edge is in the triangulation. This is handled using a geometric construction (see Lemma 29). Basically, the idea is to build a constant-sized packing of a sphere centered on a given point, using large balls, such that any sphere of a sufficiently large radius which passes through the point, must contain a ball from the packing.

Secondly, since we have randomly spaced points at the boundaries, boundary effects could penetrate deep into the interior. To handle this, we introduce the notion of *levels* of a surface, instead of the fixed strip around the boundary used in [4], and use a probabilistic, rather than deterministic, classification of boundary and interior points. The new classification is based on the level of a point and the radius of the largest empty disk passing through it.

For a curve Γ , $l(\Gamma)$ denotes its length. For a subset of a surface $R \subset \mathcal{S}$, a(R) denotes the area of R. We next present some general lemmas, which will be needed in the proofs of the main lemmas. For sets $A, B \subset \mathbb{E}^3$, $A \oplus B$ denotes the Minkowski sum of A and B, i.e. the set $\{x+y: x \in A, y \in B\}$. Throughout this section, we shall use κ to denote the maximum number of points of an ε -net in a disk of radius 2ε , which is at most $3^d = 9$, and define $q := \frac{s}{n}$, and $\delta := \varepsilon/\sqrt{q}$.

Given facet $F \in \mathcal{S}$ and $k \geq 0$, define the level set $L_{\leq k} := F \cap (\partial F \oplus 2^k \delta)$. $L_{=k} := L_{\leq k} \setminus L_{\leq k-1}$. For $x \in \mathcal{X}$, the level of x, denoted Lev(x), is k such that $x \in L_{=k}$. Let $L_{\leq k}(\mathcal{X}), L_{=k}(\mathcal{X})$ denote $L_{\leq k} \cap \mathcal{X}$, $L_{=k} \cap \mathcal{X}$ respectively. Note that for $x \in L_{=k}$, $k \geq 1$, the distance $d(x, \partial F) \in (2^{k-1}\delta, 2^k \delta]$. Hence, if Lev(x) = k, $D(x, 2^{k-1}\delta) \subset F$. For k = 0, $d(x, \partial F) \in [0, \delta]$.

We now introduce a bi-partition of the point set, which will be crucial to the analysis of the main proof. Given $x \in F$ having Lev(x) = k, then $x \in Bd_F(\mathcal{Y})$, or x is a boundary point, if k = 0 or if there exists an empty disk (w.r.t. \mathcal{Y}) of radius greater than $2^{k-1}\delta$ passing through x. $x \in Int_F(\mathcal{Y})$, or an interior point if and only if $x \in \mathcal{Y} \setminus Bd_F(\mathcal{Y})$. In general, $x \in Bd_S(\mathcal{Y})$ if $x \in Bd_F(\mathcal{Y})$ for some $F \in \mathcal{S}$, and $x \in Int_S(\mathcal{Y})$ is defined similarly.

Let E_1 denote the set of edges in $Del(\mathcal{Y})$ of the type $\{x_1, x_2\}$: $x_1, x_2 \in Bd_{\mathcal{S}}(\mathcal{Y})$. Let E_2 denote the set of edges in $Del(\mathcal{Y})$ of the type $\{x, y\}$: $x, y \in Int_F(\mathcal{Y})$, for some $F \in \mathcal{S}$. Let E_3 denote the set of edges in $Del(\mathcal{Y})$ of the type $\{x, y\}$: $x, y \in Int_{\mathcal{S}}(\mathcal{Y})$, such that $x \in F$, $y \in F' \neq F$. Let E_4 denote the set of edges $\{x, y\}$ in $Del(\mathcal{Y})$ of the type $x \in Bd_{\mathcal{S}}(\mathcal{Y})$, $y \in Int(F)$, where F is a facet in \mathcal{S} with supporting plane P.

We have the following lemmas.

- **Lemma 21.** $\mathbb{E}[\sharp(E_1)] \leq O(1) \cdot (\kappa^2 L^2/A) \cdot s$.
- **▶ Lemma 22.** $\mathbb{E}[\sharp(E_2)] \leq c_4 \cdot \kappa s$, where $c_4 \leq 2 \cdot 10^5$.
- ▶ **Lemma 23.** $\mathbb{E}[\sharp(E_3)] \leq c_4 \cdot (C-1) \cdot \kappa s$.
- ▶ **Lemma 24.** $\mathbb{E}[\sharp(E_4)] \leq O(1) \cdot \frac{\kappa^2 L^2}{A} s.$
- Given the above lemmas, the proof of Theorem 11 follows easily.

Proof of Theorem 11. As in [4] (Section 4), by Euler's formula, the number of tetrahedra $t(Del(\mathcal{Y}))$ in the Delaunay triangulation of \mathcal{S} , is at most $e(Del(\mathcal{Y})) - \sharp(\mathcal{Y}) = e(Del(\mathcal{Y})) - s$, where $e(Del(\mathcal{Y}))$ is the number of edges in the Delaunay triangulation. Therefore, it suffices to only count the edges of $Del(\mathcal{Y})$. Next, observe that any point $x \in \mathcal{Y}$ is either a boundary or an interior point, that is $Bd_{\mathcal{S}}(\mathcal{Y}) \sqcup Int_{\mathcal{S}}(\mathcal{Y}) = \mathcal{Y}$. An edge in $Del(\mathcal{Y})$, therefore, can be either between two points in $Bd_{\mathcal{S}}(\mathcal{Y})$, or two points in $Int_{\mathcal{S}}(\mathcal{Y})$, or between a point in $Bd_{\mathcal{S}}(\mathcal{Y})$ and another in $Int_{\mathcal{S}}(\mathcal{Y})$. The case of a pair of points in $Int_{\mathcal{S}}(\mathcal{Y})$ is further split based on whether the points belong to the same facet of \mathcal{S} or different facets. Thus using the above exhaustive case analysis, the proof follows simply by summing the bounds. The proof of part (ii) is by similar extensions, as sketched in the proof of Theorem 10 (ii).

It only remains to prove Lemmas 21- 24. We first present a few technical lemmas, which will be required for the analysis of all the cases.

5.1 Some Technical Lemmas

Proposition 25 ([4]). Let F be a facet of S. For any Borel set $R \subset F$, we have

$$\left(\frac{a(R)}{4\pi\varepsilon^2}\right) \leq \sharp (R \cap \mathcal{X}) \leq \left(\frac{\kappa \cdot a(R \oplus \varepsilon)}{\pi\varepsilon^2}\right), \text{ and therefore,}$$
 (1)

$$\left(\frac{A}{4\pi\varepsilon^2}\right) \leq \sharp \left(\mathcal{S} \cap \mathcal{X}\right) = n \leq \left(\frac{A}{\pi\varepsilon^2}\right), \tag{2}$$

where the last inequality in (2) holds for all $A \geq \pi \varepsilon^2$.

Proposition 26 ([4]). Let F be a facet of S, let $\Gamma \subset F$ be a curve contained in F, and $k \in \mathbb{N}$. Then

$$\sharp \left((\Gamma \oplus k\varepsilon) \cap \mathcal{X} \right) \leq \left(\frac{(2k+1)^2}{k} \right) \kappa \frac{l(\Gamma)}{\varepsilon} \tag{3}$$

$$\leq \left(9k\kappa \frac{l(\Gamma)}{\varepsilon}\right), \text{ when } k \geq 1. \tag{4}$$

▶ **Lemma 27.** Given a circle $\Sigma_1 \subset \mathbb{E}^2$ of unit radius centered at the origin, seven disks having centers in Σ_1 and radius 1/2, are necessary and sufficient to cover Σ_1 .

▶ **Lemma 28** (Level Size).
$$\sharp (L_{=k} \cap \mathcal{X}) \leq \sharp (L_{\leq k} \cap \mathcal{X}) \leq 9\kappa L\left(\frac{2^k \delta}{\varepsilon^2}\right)$$
.

- ▶ Lemma 29. Given a point $x \in S$ in the facet F with supporting plane P with Lev(x) > 0,

 and $k \in \mathbb{N}$ such that $0 \le k < Lev(x)$, with $r_0 = 2^k \delta$, there exists a collection \mathcal{D}_x of at most $c_B = 7$ disks in F, such that
- 398 (i) Each $D \in \mathcal{D}_x$ is contained in F.
- 399 (ii) Each $D \in \mathcal{D}_x$ has radius $r_0/4$,

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 $A_{00}(iii)$ Any disk $D \subset P$ of radius at least r_0 , such that $x \in \partial D$, contains at least one disk in \mathcal{D}_x .

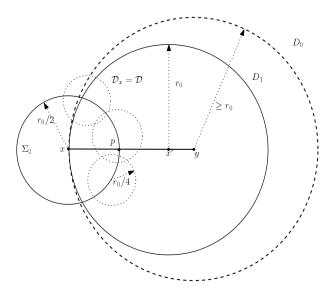


Figure 1 Lemma 29

▶ Lemma 30 (Decay lemma). Given $x_1, \ldots, x_t \in \mathcal{X}$, such that $Lev(x_i) > 0$, $1 \le i \le t$, then for all $0 \le k_i < Lev(x_i)$, with $r_i^* := 2^{k_i} \delta$, the probability of the event 402

$$E := \{ \forall i \in [t] : \exists D_i = D(y_i, r_i) : r_i \ge r_i^*, \ x_i \in \mathcal{Y}, \ x_i \in \partial D_i \ and \ int(D_i) \cap \mathcal{Y} = \emptyset \},$$

is given by 404

$$\mathbb{P}\left[E\right] \leq \left\{ \begin{array}{ll} q^t & k_{\max} = 0, \\ c_1 \cdot q^t \cdot \exp\left(-c_2 \cdot 2^{2k_{\max}}\right) & k_{\max} > 0, \end{array} \right.$$

where $c_1 = c_B^t$, $c_2 \ge 2^{-7}$, and $k_{\max} := \max_i \{k_i\}$. Thus

$$\mathbb{P}[E] \le c_1 \cdot q^t \cdot \exp\left(-c_2 \cdot 2^{2k_{\max}}\right), \quad k_{\max} \ge 0.$$

▶ **Lemma 31** (Growth Lemma). Given any point $x \in S$ in a facet F, and $0 \le k < Lev(x)$, 408

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$$(i) \ 2^{2k-2}/q \le \sharp \left(D(x, 2^k \delta) \cap \mathcal{X}\right) \le 4 \cdot (2^{2k}/q).$$

$$_{411}(ii) \quad 2^{2k-2} \le \sharp (D(x, 2^k \delta) \cap \mathcal{Y}) \le 4 \cdot (2^{2k}).$$

Proofs of Lemmas 21-24 5.2

We now briefly describe a construction of [4], which will be central to our analysis.

▶ Construction 32 (Attali-Boissonnat [4]). Let P be a plane and Z be a finite set of points.

To each point $x \in Z$, assign the region $V(x) = V_x(Z) \subset P$ of points $y \in P$ such that the sphere

tangent to P at y and passing through x encloses no point of Z. Let $\mathcal{V} := \{V(x) : x \in Z\}$. 416

We next summarize some conclusions of Attali-Boissonnat regarding the construction. 417 The proofs of these propositions can be found in [4].

▶ Proposition 33.(i) V is a partition of P.

For each $x \in Z$, V(x) is an intersection of regions that are either disks or complements 420 (ii) of disks. 421

 $^{422}(iii)$ The total length of the boundary curves in V is equal to the total length of the convex boundaries.

For the rest of this subsection, we shall apply Construction 32 on the plane P, and the points in $Bd_{\mathcal{S}}(\mathcal{Y})$ as Z. Let $\mathcal{T} := Int_{F}(\mathcal{Y})$ for some facet $F \in \mathcal{S}$. Given $x \in Z$, $y \in P \setminus V(x)$, let $k_{y} = k_{y}(x)$ denote the least $k \geq 0$ such that $y \in \partial V(x) \oplus 2^{k}\delta$.

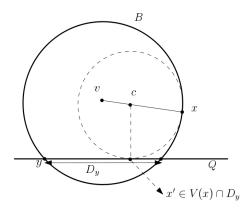


Figure 2 $x \in Z = Bd_{\mathcal{S}}(\mathcal{Y}), y \in \mathcal{T} = Int_F(\mathcal{Y}), z \in V(x) \cap D_y$.

Proposition 34 (Attali-Boissonnat [4]). Suppose there exists a ball $B \subset \mathbb{E}^3$ and $y \in P$, such that $y, x \in \partial B$, and $B \cap \mathcal{T} = \emptyset$. Then the disk $D_y = P \cap B$ satisfies $D_y \cap \mathcal{T} = \emptyset$, $y \in \partial D_y$ and $D_y \cap V_x \neq \emptyset$.

Lemma 35. If $\{x,y\} \in E_4$ with $x \in Bd_{\mathcal{S}}(\mathcal{Y}), y \in Int(F), then <math>k_y \leq Lev(y)$.

Now we partition the pairs of vertices $\{x,y\} \in E_4$ with $x \in Bd_{\mathcal{S}}(\mathcal{Y})$, depending on whether $y \in V_F(x)$ or $y \in \partial V_F(x) \oplus 2^{k_y} \delta$. That is, given a facet $F \in \mathcal{S}$, let $E_4(Int(F))$ denote the set of edges $\{x,y\} \in E_4$ with $y \in int(V_F(x))$, and $E_4(Bd(F))$ denote the set of edges in E_4 with $y \in \partial (V_F(x)) \oplus 2^k \delta$, for $k \in [0, k_y]$. Define $E_4(Int) := \bigcup_{F \in \mathcal{S}} E_4(Int(F))$ and $E_4(Bd) := \bigcup_{F \in \mathcal{S}} E_4(Bd(F))$ respectively.

Lemma 24. The proof follows from Lemmas 36 and 37, which bound the expected number of edges in $E_4(Int)$ and $E_4(Bd)$ respectively.

Lemma 36. Given a facet $F \in \mathcal{S}$, $\mathbb{E}[E_4(Int(F))] \leq q \cdot \sharp (\mathcal{X} \cap F)$. As a consequence, $\mathbb{E}[E_4(Int)] \leq s$.

▶ Lemma 37. Given a facet $F \in \mathcal{S}$, $\mathbb{E}\left[E_4(Bd(F))\right] \leq \left(O(1) \cdot \frac{\kappa^2 L \cdot l(\partial F)s}{A}\right)$. As a consequence, $\mathbb{E}\left[E_4(Bd(\mathcal{S}))\right] \leq \left(O(1) \cdot \frac{\kappa^2 L^2 s}{A}\right)$.

6 Randomized Incremental Construction (Proof of Theorem 12)

In this section, we show how the results in Sections 4 and 5 imply bounds on the computational complexity of constructing Delaunay triangulations of ε -nets. Our main tool shall be Theorem 7. However, we need to show first that Condition 6 holds, which we do in the following lemma. In the setting of Theorem 10 and Theorem 11, given a subset $\mathcal{Y} \subset \mathcal{X}$, and a point $q \in \mathcal{Y}$, let $V_{\mathcal{Y}}$ denote the Voronoi diagram of \mathcal{Y} , and $V_{\mathcal{Y}}(q)$ denote the cell of q in $V_{\mathcal{Y}}$.

Lemma 38. If $\mathcal{Y} \subset \mathcal{X}$ is a uniformly random subset of size s, and $p \in \mathcal{X} \setminus \mathcal{Y}$ is a uniformly random point from $\mathcal{X} \setminus \mathcal{Y}$, then the set of conflicts introduced by adding p to the Voronoi diagram of \mathcal{Y} , can be computed in constant expected time.

Proof. To find the conflicts introduced by adding the point p to \mathcal{Y} , it suffices to examine only the faces of the Voronoi cells neighboring the point q such that $p \in V_{\mathcal{Y}}(q)$ (i.e. the parent of p), since each conflict gives rise to at most one face of $V_{\mathcal{Y} \cup \{p\}}(p)$. The number of faces of $V_{\mathcal{Y}}(q)$ is at most the faces of the neighbouring cells of $V_{\mathcal{Y} \cup \{p\}}(p)$, which is equal to $star^2(p)$. If $s \leq 4(2\sqrt{d})^d \cdot d^3 + 1$, $star^2(p)$ is at most $s^d = O(1)$, otherwise by Theorem $star^2(p)$ is at most $star^2(p)$. A similar argument also works for the polyhedral setting, using Theorem $star^2(p)$.

Theorem 12 now follows directly by applying Theorems 10(i) and 11(i) to the result of Theorem 7.

7 Euclidean Orbifolds and Bounded-Distortion Metrics

In this section, we shall give some extensions of Theorem 10 and 12. Given a space \mathcal{S} , $\varepsilon \in [0,1]$ and $\kappa \in \mathbb{Z}^+$, an (ε,κ) -sample is a set of points for which any ball of radius ε in \mathcal{S} , contains at least one point and at most κ points.

- **Theorem 39.** Theorems 10 and 11 hold when the point set is an (ε, κ) sample.
- ▶ **Theorem 40.** Theorems 10 and 11 also work for the case when the random sample is an i.i.d. sample with probability parameter q = s/n.

Proof Sketch. The proof is on the lines of Theorems 10 and 11. It is only when computing $P_p(k)$ that we make use of the fact that points are selected independently. Here, we get directly that $P_p(k) \le q^d (1-q)^{n_k} \le q^d \cdot \exp(-qn_k)$. The rest of the proof follows as before.

Coming to our results for Delaunay triangulations of Euclidean d-manifolds and embedded metrics in \mathbb{T}^d , we need a few definitions first.

473 Euclidean *d*-orbifolds

A d-dimensional Bieberbach group \mathcal{G} is a discrete group of isometries acting on \mathbb{E}^d . A d-orbifold \mathbb{E}^d/\mathcal{G} is the compact quotient space (i.e. collection of orbits) of \mathbb{E}^d acted on by a d-dimensional Bieberbach group \mathcal{G} . When the group action is free (i.e. has no fixed points), the d-orbifold is a closed Euclidean d-manifold. Every Euclidean d-manifold is the quotient space of some d-Bieberbach group acting on \mathbb{E}^d [7], [30]. For Euclidean d-orbifolds, we have:

Theorem 41. Given a closed Euclidean d-orbifold $\mathbb{M} = \mathbb{E}^d/\mathcal{G}$, equipped with the Euclidean metric, where \mathcal{G} is a d-Bieberbach group, there exists a covering space $\mathcal{C}_{\mathbb{M}}$ with multiplicity $m = m^*(\mathcal{G}, d) < \infty$, such that the Delaunay triangulation of \mathcal{M} embeds in $\mathcal{C}_{\mathbb{M}}$, and the statements of Theorems 10 and 12 apply for ε -nets, for any $\varepsilon \in [0, 1/4]$.

Embedded metrics with bounded distortion

For a metric \mathfrak{d} on some domain \mathcal{S} embedded in \mathbb{E}^d , define its distortion $\kappa_{\mathfrak{d}}$ (with respect to \mathbb{E}^d) to be the minimum $\lambda \geq 1$ such that $\forall x,y \in \mathcal{S}: \frac{1}{\lambda} ||x-y|| \leq \mathfrak{d}(x,y) \leq \lambda ||x-y||$. A $d \times d$ matrix $M \in \mathbb{E}^d$ is positive definite if, for all $x \neq 0 \in \mathbb{E}^d$, $x^\top M x > 0$. For a positive definite matrix M, define its condition number c_M to be the ratio of its maximum to its minimum eigenvalue. For embedded metrics with bounded distortion, we have:

Theorem 42. Given a metric \mathfrak{d} over \mathbb{T}^d with distortion $\kappa_{\mathfrak{d}} < \infty$, there exists an integer $m = m_{\mathfrak{d}} < (2\kappa_{\mathfrak{d}}\sqrt{d})^d$, such that the Delaunay triangulation over $(\mathbb{T}^d, \mathfrak{d})$ embeds in \mathbb{T}^d_m with the Euclidean metric. In particular, if \mathfrak{d} is of the form $\mathfrak{d}(x,y) = \sqrt{(x-y)^\top M(x-y)}$, $x,y \in \mathbb{T}^d$, where $M \in \mathbb{E}^{d \times d}$ is a positive definite matrix having condition number at most c_M , then $m \leq (2c_M\sqrt{d})^d$. Hence, given any $\varepsilon \in [0,1/4]$, the statements of Theorems 10 and 12 apply for ε -nets over the metric space $(\mathbb{T}^d,\mathfrak{d})$.

The proofs of Theorems 41 and 42 follow by finding covering spaces of bounded multiplicity where the Delaunay triangulation can be embedded, and generalizing Lemmas 16–20 to such spaces. In the case of Theorem 41, the existence of the covering space follows from the algorithmic version of Bieberbach's theorem [6] by Caroli-Teillaud [10] (Section 4). For Theorem 42, we use a geometric condition of Caroli-Teillaud [10] (Criterion 3.11) to explicitly bound the multiplicity of the covering space. The proofs are sketched in the Appendix.

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A Appendix

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Proofs from Section 1

- **Lemma 43.** Given $\varepsilon \in (0,1]$, an ε -net \mathcal{X} over \mathbb{T}^d , of n points, a uniformly random sample $S \subset \mathcal{X}$ of k points and $\varepsilon' = \varepsilon \sqrt[d]{n/k}$, then
- 588 (i) With high probability, there exists a ball of radius ε' with $\Omega(\log k/\log \log k)$ points in S.
- With probability at least a constant, there exists a ball of radius $\Omega(\varepsilon' \log k)$ with no points in S.

Sketch of Proof. The following balls-and-bins and coupon-collector arguments which can be shown to prove this:

- for adius ε' with $\Omega(\frac{\log k}{\log \log k})$ points.
- Similarly, there are $\Omega(\varepsilon'/\log k) = \Omega(k/\log k)$ balls of radius $\varepsilon' \sqrt[d]{\log k}$ that cover the ε -net, (ii) 598 and choosing k points from this covering, can be thought of as an instance of the coupon 599 collector problem: we are allowed k draws (i.e. we choose k points), each draw is one of the "coupons" (i.e. the balls in the covering) with equal probability, and we want the 601 probability that at least one coupon has not been collected, i.e. at least one ball from the covering has no point chosen from it. Now the well-known lower tail of the number of 603 draws taken to collect all coupons in the the coupon collector problem, gives that with 604 high probability, for $k' = \Omega(k/\log k)$ coupons, and at most $O(k'\log k') = k$ draws, all 605 coupons will not be collected, that is, some ball of radius $\Omega(\varepsilon' \sqrt[d]{\log k})$ will be empty. 606

Proofs from Section 2

Proof of Lemma 1. Consider a maximal set of disjoint balls of radius $\frac{\rho}{2}$ with center inside the ball B(r) of radius r. Then the balls with the same centers and radius ρ cover the ball B(r) (otherwise it contradicts the maximality). By a volume argument we get that the number of balls is bounded from above by $\frac{V_d \times \left(r + \frac{\rho}{2}\right)^d}{V_d \times \left(\frac{\rho}{2}\right)^d} \le \left(\frac{3r}{\rho}\right)^d$ for $\rho < 1$.

Proof of Lemma 2. The volume argument gives a lower bound of $\frac{V_d \times r^d}{V_d \times \rho^d} = \left(\frac{r}{\rho}\right)^d$.

Proof of Lemma 3. Observe that, by the minimum distance property of the points in \mathcal{X} , the balls of radius $\varepsilon/2$ centered around each point in \mathcal{X} , are disjoint, and by a volume argument there can be at most $\frac{1}{V_d \times (\varepsilon/2)^d} \leq 2^{-d} d^{d/2} (\varepsilon/2)^{-d} = d^{d/2} \varepsilon^{-d}$ such balls in \mathbb{T}^d . The balls of radius ε centered around each point in \mathcal{X} cover the space thus their number is at least $\frac{1}{V_d \times \varepsilon^d} \geq d^{d/2} 2^{-3d} \cdot \varepsilon^{-d}$. This completes the proof of the lemma.

Lemma 5. Observe that the circumradius of any simplex in $Del(\mathcal{X})$ cannot be greater than ε , since this would imply the existence of a ball in \mathbb{T}^d of radius at least ε , containing no points from \mathcal{X} . Therefore given a point $p \in \mathcal{X}$, any point which lies in a Delaunay simplex incident to p, must be at most distance 2ε from p. Again by a volume argument, the number of such points is at most $\frac{V_d \times (2\varepsilon + \varepsilon/2)^d}{V_d \times ((\varepsilon/2)^d)} = 5^d$. Thus, the number of Delaunay simplices of dimension at most d that contain p, is at most the complexity of the d-skeleton of the Delaunay complex

in \mathbb{T}^d on 5^d vertices. This is at most $(5^d)^{\lceil d/2 \rceil}$. Thus we can conclude that the number of simplices in $Del(\mathcal{X})$ is at most the cardinality of \mathcal{X} , times the maximum number of simplices incident to any given point $p \in \mathcal{X}$, or $(5^d)^{\lceil d/2 \rceil} \cdot \sharp (\mathcal{X}) \leq (5^d)^{\frac{d+1}{2}} d^{d/2} \varepsilon^{-d} \leq 4^{d^2} \varepsilon^{-d}$.

Proof of Lemma 9. The j-th moment $\mathbb{E}\left[X^{j}\right]$ is the sum over all ordered j-tuples l=0 $(l_{1},l_{2},\ldots,l_{j})\in B^{j}$ of the probability that a j-tuple gets chosen in the random sample A^{j} . Fix $l\in B^{j}$. If any element of B gets repeated in the tuple, then $\mathbb{P}\left[l\right]$ is selected l0. Assuming therefore that for all l1 l2 l3, and applying Lemma 8 with the included subset l4, and the excluded subset as the empty set, this probability can be upper bound as l3 l4 l5. Summing over all l5 tuples in l5, gives us that l5 l6 l7 l8. Summing over all l8 tuples in l9, gives us that l8 l8 l9 l9.

Proof of Lemma 8. The total number of ways of choosing the random sample A is $\binom{c}{a}$. The number of ways of choosing A such that $B \subset A$ and $T \cap A = \emptyset$, is $\binom{c-b-t}{a-b}$. Therefore the required probability is

$$\begin{array}{lll} ^{637} & \mathbb{P}\left[B\subset A,\ T\cap A=\emptyset\right] & = & \frac{\binom{c-b-t}{a-b}}{\binom{c}{a}} \\ & = & \frac{\prod_{i=0}^{b-1}(a-i)\prod_{i=b}^{a-1}(a-i)}{\prod_{i=0}^{b-1}(c-i)\prod_{i=b}^{a-b-1}(c-b-t-i)} \cdot \frac{\prod_{i=0}^{a-b-1}(c-b-t-i)}{\prod_{i=0}^{a-b-1}(a-b-i)} \\ ^{639} & = & \frac{\prod_{i=0}^{b-1}(a-i)\prod_{i=0}^{a-b-1}(c-b-t-i)}{\prod_{i=0}^{b-1}(c-i)} \\ & = & (a/c)^b\frac{\prod_{i=0}^{b-1}(1-i/a)}{\prod_{i=0}^{b-1}(1-i/c)}\left(1-\frac{t}{c-b}\right)^{a-b}\left(\frac{\prod_{i=0}^{a-b-1}(1-\frac{i}{c-b-t})}{\prod_{i=0}^{a-b-1}(1-\frac{i}{c-b})}\right) \\ & \leq & (a/c)^b\left(1-\frac{t}{c-b}\right)^{a-b}, \end{array}$$

where in the last step, observe that for the product $\prod_{i=0}^{b-1}(1-i/a)$ for each i, the term (1-i/a) in the numerator is smaller than the corresponding term (1-i/c) in the denominator, since $a \le c$. A similar observation holds for the product $\left(\prod_{i=0}^{a-b-1}(1-\frac{i}{c-b-i})\right).$ Now, observe that $\left(1-\frac{t}{c-b}\right)^{a-b} \le \exp\left(-\left(\frac{t(a-b)}{c-b}\right)\right) \le \exp\left(-\left(\frac{at}{2c}\right)\right)$, if $b \le a/2$ and b < c.

Proofs from Section 4

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Proof of Lemma 13. For a simplex $\sigma = \tau \cup \{p\}$, with the vertex set of τ in $S_p(k)$, let $\mathbf{1}_{[\tau]}$ be the indicator random variable which is 1 if $\sigma \in star(p)$, and zero otherwise. Then $Z_p(k) := \sum_{\tau \in S_p(k)} \mathbf{1}_{[\tau]}$, and $\sharp (star(p)) = \sum_{k \geq 0}^{k_{\max}} Z_p(k)$.

Taking expectations over the random sample \mathcal{Y} , we get

$$\mathbb{E}\left[\sharp\left(star(p)\right)\right] = \sum_{k\geq 0}^{k_{\max}} \mathbb{E}\left[Z_p(k)\right]$$

$$= \sum_{k\geq 0}^{k_{\max}} \sum_{\tau \in S_p(k)} \mathbb{E}\left[\mathbf{1}_{[\tau]}\right] \leq \sum_{k\geq 0}^{k_{\max}} \sum_{\tau \in S_p(k)} P_d(k) = \sum_{k\geq 0}^{k_{\max}} s_p(k) \cdot P_d(k).$$

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Proof of Lemma 14. The simplex σ can be a Delaunay simplex only if (i) the set of its vertices is included in the subsample \mathcal{Y} , and (ii) all points in $B(c_{\sigma}, r_{\sigma}) \cap \mathcal{X}$ are excluded from \mathcal{Y} . The idea is therefore, to use Lemma 17 to bound the number of points in $B(c_{\sigma}, r_{\sigma}) \cap \mathcal{X}$ from below by n_k , and then upper-bound the probability that all these points are excluded from \mathcal{Y} .

This suggests applying Lemma 8, with the universe having c=n-1 elements, sample size a=s-1, included set having b=d elements, and excluded set having $t=n_k$ elements. We verify first that the conditions of the lemma are satisfied, i.e. (i) $b \leq \min\{\frac{a}{2}, c-1\}$, since $s \geq 4d+1$. Now applying the lemma, we get

$$\mathbb{P}\left[\sigma \in Del(\mathcal{Y})\right] \leq \left(\frac{s-1}{n-1}\right)^d \exp\left(-n_k \cdot \left(\frac{s-1}{2(n-1)}\right)\right)$$
$$= q^d \cdot \exp\left(-qn_k/2\right) \leq q^d \cdot \exp\left(-qn_k/2\right),$$

where the equality was by the substitution $q = \frac{s-1}{n-1}$, and the last inequality followed from the fact that $d = b \le c - 1 = n - 2$.

Proof of Lemma 15. This follows simply from the triangle inequality. For the first statement, we have that for any $p' \in \sigma$, $||p,p'|| \le ||p,c_{\sigma}|| + ||c_{\sigma},p'|| = 2r_{\sigma}$. The second statement follows by replacing the above inequalities with strict inequalities for the points in the open ball $B(c_{\sigma}, r_{\sigma})$.

Proof of Lemma 16. Let τ be an element of $S_p(k)$. Using Lemma 15 and the definition of $S_p(k)$, we have that $\sigma = \tau \cup \{p\} \subset B[p, 2^{k+1}\delta]$. If $k \leq k_{\max}$, then $2^{k+1}\delta \leq 1/2$. Therefore applying Theorem 4, we can work in the one-sheeted covering of \mathbb{T}^d . Now applying Lemma 1, the number of points in $B(p, 2^{k+1}\delta) \cap \mathcal{X}$ is at most $(3 \cdot 2^{k+1}\delta/\varepsilon)^d = (6 \cdot 2^k\delta/\varepsilon)^d$. Therefore, the set of possible simplices incident to p and having vertices in $B[p, 2^{k+1}\delta] \cap \mathcal{X}$ is at most the set of all d-tuples of points in $B[p, 2^{k+1}\delta] \cap \mathcal{X}$, i.e. at most $(6 \cdot 2^k\delta/\varepsilon)^{d^2}/d!$.

Proof of Lemma 19. For $k \ge 1$, consider the ratio of successive terms $\frac{\mathbb{E}[Z_p(k+1)]}{\mathbb{E}[Z_p(k)]} = \frac{s_p(k+1) \cdot P_p(k+1)}{s_p(k) \cdot P_p(k)}$ in Lemma 13. From Lemmas 16 and 17, we have

$$\frac{s_p(k+1) \cdot P_p(k+1)}{s_p(k) \cdot P_p(k)} = \frac{(6 \cdot 2^{k+1} \delta/\varepsilon)^{d^2}/d!}{(6 \cdot 2^k \delta/\varepsilon)^{d^2}/d!} \times \frac{q^d \cdot \exp\left(-q(2^k \delta/\varepsilon)^d/2\right)}{q^d \cdot \exp\left(-q(2^{k-1} \delta/\varepsilon)^d/2\right)}$$

$$= 2^{d^2} \cdot \exp\left(-\frac{q}{2} \cdot \left((2^{k-1} \delta/\varepsilon)^d\right)(2^d - 1)\right)$$

$$= 2^{d^2} \cdot \exp\left(-\frac{1}{2} \cdot \left(2^{(k-1)d} 2d\right)(2^d - 1)\right),$$

where in the last step we used the definition of $\delta = \varepsilon (2d/q)^{1/d}$, so that $q(\delta/\varepsilon)^d = 2d$. The last expression is minimized when k = 1, d = 2, to get $2^{d^2} \cdot \exp\left(d(2^d - 1)\right) = 2^4 \cdot e^{-6} \le (2/e)^6$. For k = 0, the ratio $\frac{\mathbb{E}[Z_p(1)]}{\mathbb{E}[Z_p(0)]} \le 2^{d^2} \cdot \exp\left(-d \cdot 2^d\right)$, which is at most $(2/e)^6$ for $d \ge 2$.

Therefore for all $0 \le k \le k_{\text{max}} - 1$, we have that $\frac{\mathbb{E}[Z_p(k+1)]}{\mathbb{E}[Z_p(k)]} \le (2/e)^6$. Thus, the sum $\sum_{k=0}^{k_{\text{max}}} \mathbb{E}[Z_p(k)]$ is upper bounded by the sum of a geometric progression with leading term $\mathbb{E}[Z_p(0)] \le 6^{d^2+d}$ and common ratio $(2/e)^6$, which is at most $(1-(2/e)^6)^{-1} \cdot 6^{d^2+d}$.

Proof of Lemma 20. From Lemma 3, we have that $n = \sharp(\mathcal{X}) \leq 2^{-d}d^{d/2}\varepsilon^{-d}$. Therefore, by Lemma 2, any ball B of radius at least $2^{k_{\max}}\delta \geq 1/4$, has at least $(2^{k_{\max}}\delta/\varepsilon)^d = (1/4\varepsilon)^d \geq 1/4$. Lemma 2, any ball B of radius at least $(2^{k_{\max}}\delta)^d = (1/4\varepsilon)^d \geq 1/4$.

$$\sharp \left(\mathrm{int} B \cap \mathcal{X} \right) \ \geq \ \left(rac{n}{(2\sqrt{d})^d}
ight).$$

Here, since $2^{k+1}\delta > 1/2$, we shall use Theorem 4 and work in the 3^d -sheeted covering of \mathbb{T}^d . The maximum number of d-tuples which can possibly form a Delaunay d-simplex with p, is at most $\binom{n-1}{d} \leq (n-1)^d/d!$. Since the multiplicity of the covering map is 3^d , each vertex of a simplex $\tau \in S_p(k)$ can be chosen from one of at most 3^d copies in the covering space. Thus, each simplex in $S_p(k)$ yields less than 3^{d^2} possible Delaunay spheres in \mathbb{T}^d . Therefore, the expected number of simplices having radius at least $2^{k_{\max}}\delta$, is at most

$$\sum_{k>k_{\text{max}}} \mathbb{E}\left[Z_{p}(k)\right] = 3^{d^{2}} \frac{(n-1)^{d}}{d!} \cdot P_{p}(k)$$

$$= 3^{d^{2}} \frac{(n-1)^{d}}{d!} \cdot q^{d} \cdot \exp\left(-\frac{q}{2} \cdot \frac{n-1}{(2\sqrt{d})^{d}}\right)$$

$$\leq 3^{d^{2}} \frac{(s-1)^{d}}{d!} \cdot \exp\left(-\frac{s-1}{2(2\sqrt{d})^{d}}\right). \tag{5}$$

For $s > s_0 = 4(2\sqrt{d})^d \cdot d^3 + 1$, this function is decreasing in term of s and it is easy to check that the value in s_0 is smaller than 5. Thus we have $\sum_{k>k_{\max}} \mathbb{E}\left[Z_p(k)\right] \leq 5$.

4 Proofs from Section 5

Lemma 44. Given $a>0,\ b\in(0,1),\ the\ sum\ \sum_{n\in\mathbb{Z}_+}2^{an}\cdot\exp\left(-b\cdot 2^{an}\right)$ is at most $\frac{2\log_2(1/b)}{eab}$.

Proof of Lemma 44. The proof follows from elementary calculus. The maximum term is when $2^{an} = 1/b$, i.e. $n = \frac{\log_2(1/b)}{a}$, and evaluates to $2^{an} \exp(-b \cdot 2^{an}) = \frac{1}{eb}$, and terms decrease exponentially afterwards. The sum is therefore upper bounded by twice the maximum term, times the number of terms before the maximum, which is the claimed bound.

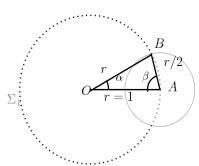
Proof of Lemma 28. The first inequality is obvious, as $L_{=k} \subseteq L_{\leq k}$. The proof of the second inequality follows by applying Proposition 26 over the boundaries of the facets. For a fixed facet $F \in \mathcal{S}$, we get

$$\sharp \left(\left(\partial F \oplus \left(\frac{2^k \delta}{\varepsilon} \right) \varepsilon \right) \cap \mathcal{X} \right) \ \leq \ \left(\frac{9 \kappa 2^k \delta}{\varepsilon} \right) \cdot \left(\frac{l(\partial F)}{\varepsilon} \right).$$

Summing over all $F \in \mathcal{S}$, we get

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$$\sharp \left(L_{\leq k} \cap \mathcal{X}\right) = \sum_{F \in \mathcal{S}} \sharp \left(\left(\partial F \oplus 2^k \delta\right) \cap \mathcal{X}\right) \leq \left(\frac{9\kappa 2^k \delta}{\varepsilon^2}\right) \sum_{F \in \mathcal{S}} l(\partial F) = \left(\frac{9\kappa 2^k \delta}{\varepsilon^2}\right) \cdot L.$$



Proof of Lemma 27.

Figure 3 Angle covered by disk of radius 1/2 is $= 2\alpha$

Let D_2 denote a disk of radius 1/2, having its center lying on the circle Σ_1 . Let 2α denote the angle subtended by $\Sigma_1 \cap D_2$ on the center of Σ_1 . By symmetry, the angle $\angle OAB$ in figure 3 is α . Applying the sine law to the triangle OAB, we get

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$$\frac{1}{\sin \beta} = \frac{1/2}{\sin \alpha}, \text{ or,}$$
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$$\frac{1}{\sin(\pi/2 - \alpha/2)} = \frac{1/2}{\sin \alpha}, \text{ or,}$$
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$$\frac{1}{\cos(\alpha/2)} = \frac{1/2}{\sin \alpha}, \text{ or,}$$
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$$4\sin(\alpha/2) = 1.$$

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Therefore, $\alpha = 2\arcsin(1/4)$, or $2\alpha = 4\arcsin(1/4)$.

Thus, one disk covers an angle of $4\arcsin(1/4)$, and so the number of required disks having radius 1/2, is at least $\frac{2\pi}{4\arcsin(1/4)} \approx 6.21 < 7$.

It is now easy to see that we can place the disks on the boundary in a greedy manner, such that they cover the maximum possible angle, except of course the last disk which may have some overlap with the first disk. Thus seven disks would suffice as well.

Proof of Lemma 31. By the definition of Lev(x), we have that $D(x, 2^{Lev(x)-1}\delta) \subset F$. Now the statement follows by the application of Proposition 25, as below

$$\frac{\pi(2^{k}\delta)^{2}}{4\pi\varepsilon^{2}} \leq \sharp \left(D(x, 2^{k}\delta) \cap \mathcal{X}\right) \leq \frac{\pi(2^{k}\delta + \varepsilon)^{2}}{\pi\varepsilon^{2}}, \text{ or,}$$

$$\frac{2^{2k-2}n}{s} \leq \sharp \left(D(x, 2^{k}\delta) \cap \mathcal{X}\right) \leq \frac{2 \cdot 2^{2k}n}{s},$$

where we used that $\delta := \left(\sqrt{\frac{n}{s}}\right) \varepsilon$. This gives the first statement of the lemma, using q = s/n. The second statement follows simply by taking expectation.

Proof of Lemma 29. Let $D_0 = D(y, r)$ for some $y \in P$, $r \ge r_0$, be a disk such that $x \in \partial D_0$. Let $D_1 = D(x', r_0)$ be the unique disk with centre x' on the line xy, radius r_0 , and having $x \in \partial D_1$. Note that

(a) $D_1 \subseteq D_0$ by construction, and,

743 (b) $x' \in F$, since $r_0 = 2^k \delta \le 2^{Lev(x)-1} \delta$, so that $x' \in D(x, r_0) \subset F$.

Consider $\Sigma_2 = \Sigma(x, r_0/2)$, and let $p = xx' \cap \Sigma_2$, that is, the point p lies on the line xx', at distance $r_0/2$ from x (and therefore from x' as well). We shall build a minimal covering \mathcal{D} of the circle Σ_2 , by disks centered in Σ_2 , having radius $r_0/4$. From Lemma 27, we get $\sharp(\mathcal{D}) = 7$. Let $D' \in \mathcal{D}$ be a disk in the covering. Then by the triangle inequality, $D' \subset D(x, r_0/2 + r_0/4) \subset D(x, r_0)$. As before, by the definitions of Lev(x) and r_0 , this implies $D' \subset F$. Thus \mathcal{D} satisfies conditions (i) and (ii) of the lemma. Further, since \mathcal{D} is a covering of Σ_2 , there exists $D_p \in \mathcal{D}$ such that $p \in D_p$. Therefore, the disk $D_p \subset D_1 \subset D_0$, and $D_p \subset F$. Thus $D_p \in \mathcal{D}$ satisfies condition (iii). Now taking $\mathcal{D}_x = \mathcal{D}$ completes the proof of the lemma.

Proof of Lemma 30. Firstly, consider the case where $k_{\text{max}} = 0$, i.e. all the k_i 's are zero. In this case we simply upper bound the probability of the event E, by the probability of including all the points x_1, \ldots, x_t in \mathcal{Y} . By Lemma 8, this is at most q^t .

We next come to the case when $k_{\text{max}} > 0$. Since for all $i \in [t]$, $k_i < Lev(x_i)$, we can apply Lemma 29 for each i, with $k = k_i$, to conclude that for each i, there exists a collection \mathcal{D}_i of at most c_B disks of radius $r_i^*/4$, such that any disk having radius greater than r_i^* and

passing through x_i , must contain some disk $D_i^* \in \mathcal{D}_i$. Let T denote the set $\prod_{i=1}^t \mathcal{D}_i$. By the union bound over the set T, we get

$$\mathbb{P}[E] \leq \mathbb{P}[\exists B \in T : \forall i \in [t], B_i \cap \mathcal{Y} = \emptyset]
 \leq \sharp (T) \cdot \mathbb{P}[\forall i \in [t], B_i \cap \mathcal{Y} = \emptyset],$$

where $B \in T$ is some fixed element of T.

Let $j:=\arg\max_{i\in[t]}k_i$, so that $k_{\max}=k_j$. Now, the event E requires the set $x_1,\ldots x_t$ to be in the sample $\mathcal Y$, and the interiors of the disks D_i^* to be free from points in $\mathcal Y$. In particular, the disk D_j^* should not contain any points in $\mathcal Y$. Therefore applying Lemma 8 on the universe $C=\mathcal X$, the random sample $A=\mathcal Y$, the included subset $B=\{x_1,\ldots,x_t\}$, and the excluded subset $Z=D_j^*\cap\mathcal X$ of size at least $z=\frac{\pi(r_j^*/4)^2}{4\pi\varepsilon^2}$, we get

$$\mathbb{P}[E] \leq \sharp (T) \cdot \mathbb{P} \left[\forall B_i \in u, \ B_i \cap \mathcal{Y} = \emptyset \right]$$

$$\leq (c_B)^t \cdot q^t \cdot \exp\left(-\frac{1}{2} q \cdot \left(\frac{\pi (r_j^*/4)^2}{4\pi \varepsilon^2} \right) \right)$$

$$\leq c_1 q^t \cdot \exp\left(-2^{2k_{\max}-7} \right).$$

where in the last step we used that $q=s/n,\ \delta=\sqrt{n/s}\cdot\varepsilon,$ and $r_j^*=2^{k_{\max}}\delta,$ and set $c_1=c_B^t.$

Proof of Lemma 21. Let $x_1, x_2 \in Bd_{\mathcal{S}}(\mathcal{Y})$. To bound the expected number of edges in E_1 , we simply bound the number of pairs $(x_1, x_2) \in Bd_{\mathcal{S}}(\mathcal{Y}) \times Bd_{\mathcal{S}}(\mathcal{Y})$. Let $l_1 := Lev(x)$ and $l_2 := Lev(y)$, and let $l := \max_i (l_i)_{i=1}^2$. By definition, if l = 0, then $x_1, x_2 \in Bd_{\mathcal{S}}(\mathcal{Y})$. For $l \geq 1$, we get that $x_1 \in Bd_{\mathcal{S}}(\mathcal{Y})$ and $x_2 \in Bd_{\mathcal{S}}(\mathcal{Y})$ only if there exists a disk of radius at least $2^{l-1}\delta$ passing through x_1 or x_2 , and containing no points of \mathcal{Y} . Therefore to bound the probability that $(x_1, x_2) \in (Bd_{\mathcal{S}}(\mathcal{Y}))^2$, we can apply the Decay Lemma 30, with t = 2, for $i \in \{1, 2\}$. We get

$$\mathbb{P}[(x_1, x_2) \in E_1] \leq \mathbb{P}[(x_1, x_2) \in (Bd_{\mathcal{S}}(\mathcal{Y}))^2]
\leq c_1 q^2 \cdot \exp(-c_2 \cdot 2^{2l-2}) \leq c_1 q^2 \cdot \exp(-c_2' \cdot 2^{2l}),$$
(6)

where $c_2' = c_2/4 = 2^{-9}$. Summing over all choices of levels of x_1 and x_2 , we have

$$\mathbb{E}\left[\sharp\left(E_{1}\right)\right] \leq \sum_{l_{1}\geq0}\sharp\left(L_{=l_{1}}\cap\mathcal{X}\right)\sum_{l_{2}\geq0}\sharp\left(L_{=l_{2}}\cap\mathcal{X}\right)\mathbb{P}\left[\left(x_{1},x_{2}\right)\in\left(Bd_{\mathcal{S}}(\mathcal{Y})\right)^{2}\right].$$

By symmetry, it is enough to assume without loss of generality that $l_1 \geq l_2$, i.e. $l = l_1$. Thus,

$$\mathbb{E}\left[\sharp\left(E_{1}\right)\right] \leq 2\sum_{l_{1}>0}\sharp\left(L_{=l_{1}}\cap\mathcal{X}\right)\sum_{l_{2}=0}^{l_{1}}\sharp\left(L_{=l_{2}}\cap\mathcal{X}\right)\mathbb{P}\left[\left(x_{1},x_{2}\right)\in\left(Bd_{\mathcal{S}}(\mathcal{Y})\right)^{2}\right].$$

Applying equation (6) and the Level Size Lemma 28, we get

$$\mathbb{E}\left[\sharp\left(E_{1}\right)\right] \leq 2\sum_{l_{1}\geq0}\sharp\left(L_{\leq l_{1}}\cap\mathcal{X}\right)\sum_{l_{2}=0}^{l_{1}}\sharp\left(L_{\leq l_{2}}\cap\mathcal{X}\right)\cdot c_{1}q^{2}\cdot\exp\left(-c_{2}'\cdot2^{2l_{1}}\right)$$

$$\leq 2c_{1}q^{2}\sum_{l_{1}\geq0}(9\kappa L\cdot(2^{l_{1}}\delta/\varepsilon^{2}))\sum_{l_{2}=0}^{l_{1}}(9\kappa L\cdot(2^{l_{2}}\delta/\varepsilon^{2}))\cdot\exp\left(-c_{2}'\cdot2^{2l_{1}}\right)$$

$$\leq 2c_{1}q^{2}(9\kappa L\left(\frac{\delta}{\varepsilon^{2}}\right))^{2}\sum_{l_{1}\geq0}2^{l_{1}}\cdot\exp\left(-c_{2}'\cdot2^{2l_{1}}\right)\sum_{l_{2}=0}^{l_{1}}2^{l_{2}}.$$

Using the definitions of q and δ , together with Proposition 25, and writing the terms outside the summation as N_1 , we get $N_1:=2\cdot c_1q^2\left(9\kappa L\left(\frac{\delta}{\varepsilon^2}\right)\right)^2=2c_1\cdot(9\kappa L)^2\left(\frac{s}{n\varepsilon^2}\right)\leq 4c_1\cdot\left(\frac{4\pi(9\kappa L)^2}{A}\right)\cdot s$, we continue

$$\mathbb{E}\left[\sharp\left(E_{1}\right)\right] \leq N_{1} \sum_{l_{1}>0} 2^{l_{1}} \cdot \exp\left(-c_{2}^{\prime} \cdot 2^{2l_{1}}\right) \cdot 2 \cdot 2^{l_{1}} \leq 2N_{1} \sum_{l_{1}>0} 2^{2l_{1}} \cdot \exp\left(-c_{2}^{\prime} \cdot 2^{2l_{1}}\right).$$

The summation can be bounded using Lemma 44, to get

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$$\mathbb{E}\left[\sharp\left(E_{1}\right)\right] \leq 2N_{1} \cdot \left(2 \cdot \frac{\log 1/c_{2}'}{2ec_{2}'}\right) = 2N_{1} \cdot \frac{\log 1/c_{2}'}{e \cdot c_{2}'}.$$

Now substituting
$$c_2' = 2^{-9}$$
 gives $\mathbb{E}\left[\sharp\left(E_1\right)\right] \leq 2 \cdot 10^4 \cdot c_1 \cdot \left(\frac{4\pi(9\kappa L)^2}{A}\right) \cdot s$.

Proof of Lemma 22. Let l denote $\min\{Lev(x), Lev(y)\}$. Observe that if l=0, then either x or y is a boundary point, and hence we can assume $l\geq 1$. Let $x'=\arg\min_{z\in\partial F}d(z,x)$, and $y'=\arg\min_{z\in\partial F}d(z,y)$, i.e. x' is the closest point to x in ∂F , and similarly for y'. By the definition of $Bd_{\mathcal{S}}(\mathcal{Y})$, observe that $d(x,y)\leq d(x,x')+d(x',y)\leq d(x,x')+d(y,y')\leq 2\cdot 2^{l-1}\delta$. Hence we have that $d(x,y)\leq 2^{l}\delta$.

By the Growth Lemma 31, the expected number of Delaunay neighbours y of a point x such that $d(x,y) \leq \delta$ is at most $\mathbb{E}\left[D(x,\delta) \cap \mathcal{Y}\right] \leq q \cdot \frac{4}{q} = 4$. Thus the expected number of edges in E_2 from pairs (x,y) with $x,y \in Int_F(\mathcal{Y})$ for some $F \in \mathcal{S}$, and $d(x,y) \leq \delta$, is at most $4 \cdot \sharp (\mathcal{Y})$. For longer-distance edges, let $k \geq 1$ be such that $2^{k-1}\delta \leq d(x,y) \leq 2^k\delta$. Taking $t=2, x_1=x, x_2=y, k_1=k-1$, and $k_2 \leq k_1$, and applying the Decay Lemma 30, we get that

$$\mathbb{P}\left[\{x,y\} \in E_2\right] \le c_1 q^2 \cdot \exp\left(-c_2 2^{2k-2}\right) \le c_1 q^2 \cdot \exp\left(-c_2' 2^{2k}\right),$$

where $c_2' = c_2/4$. Summing over all possible choices of $l \geq 1$, and $k \leq l$, we get

$$\mathbb{E}\left[\sharp\left(E_{2}\right)\right] \leq \sum_{l\geq1} \sharp\left(L_{=l}\cap\mathcal{X}\right) \sum_{k=1}^{l} \sharp\left(D(x,2^{k}\delta)\cap\mathcal{X}\right) \cdot c_{1}q^{2} \cdot \exp\left(-c_{2}^{\prime}2^{2^{k}}\right)$$

$$\leq c_{1}q^{2} \left(\sum_{l\geq1} \sharp\left(L_{=l}\cap\mathcal{X}\right) \sum_{k=1}^{l} \kappa 2^{2k} (\delta/\varepsilon)^{2} \cdot \exp\left(-c_{2}^{\prime}2^{2^{k}}\right)\right)$$

$$\leq c_{1}\kappa q \left(\frac{q\delta^{2}}{\varepsilon^{2}}\right) \cdot \left(\sum_{l\geq1} \sharp\left(L_{=l}\cap\mathcal{X}\right)\right) \frac{2 \cdot (1/2) \cdot \log 1/c_{2}^{\prime}}{ec_{2}^{\prime}}$$

$$\leq c_{1}\kappa q \cdot c_{3} \left(\sum_{l\geq1} \sharp\left(L_{=l}\cap\mathcal{X}\right)\right)$$

$$\leq c_{1}\kappa q \cdot c_{3} \cdot n = c_{4} \cdot \kappa s.$$

where in the second step we applied the Growth Lemma 31, and in the third step we bounded the sum $\sum_{k\geq 0} 2^{2k} \exp\left(-c_2 2^{2k}\right)$ using Lemma 44, and used that $q=s/n=\varepsilon^2/\delta^2$. Note that $c_3\leq 4\cdot 10^3$, and $c_4:=c_1\cdot c_3\leq 2\cdot 10^5$.

Proof of Lemma 23. Let $x, y \in Int_{\mathcal{S}}(\mathcal{Y})$, where $x \in F$ and $y \in F'$, for some $F, F' \in \mathcal{S}$. Let F' be fixed. To analyse this case, we shall first give a geometric construction of [4], and state an observation from their proof.

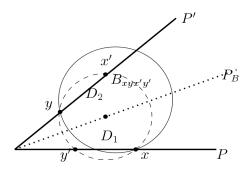


Figure 4 $x, y \in Int_{\mathcal{S}}(\mathcal{Y})$, on different facets $F \subset P, F' \subset P'$

**Construction 45 (Attali-Boissonnat [4]). Let P and P' denote the supporting planes of the facets F and F' respectively. Let P_B be the bisector plane of P and P'. We denote by $x' \in P'$, the reflection of $x \in P$ with respect to P_B , and similarly by $y' \in P$, the reflection of $y \in P'$. Let $B = B_{xyx'y'}$ be the smallest ball in \mathbb{E}^3 passing through x, y, x', y', having intersections $D_1 = B \cap P$ and $D_2 = B \cap P'$ with P and P' respectively.

Attali and Boissonnat observed that

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Proposition 46 (Attali-Boissonnat [4]). Any ball in \mathbb{E}^3 having x and y on its boundary, must contain either D_1 or D_2 .

Therefore, if there exists a ball $B \in \mathbb{E}^3$ such that $x, y \in \partial B$, and $int(B) \cap \mathcal{Y} = \emptyset$, then either $D_1 \cap \mathcal{Y} = \emptyset$, or $D_2 \cap \mathcal{Y} = \emptyset$. We get

$$\mathbb{P}\left[\left\{x,y\right\} \in E_{3}\right] \leq \mathbb{P}\left[\bigcup_{i=1}^{2}\left\{D_{i} \cap \mathcal{Y} = \emptyset\right\}\right] \leq 2 \cdot \mathbb{P}\left[D_{1} \cap \mathcal{Y} = \emptyset\right].$$

Observe that, as in Case II, we have $x' \in D(y, 2^{Lev(y)}\delta)$, since otherwise $y \in Bd_{\mathcal{S}}(\mathcal{Y})$. (Note that our definition of boundary points allows us to ignore the fact that x' is not necessarily a point in \mathcal{X} .) Further, the set $\{x' \in D(y, 2^k\delta)\}$, 0 < k < Lev(y), is bounded in size by $\{D(y', 2^k\delta) \cap F \cap \mathcal{Y}\}$. The rest of the analysis for the fixed facet F', therefore follows as in Case II. Summing over all $F' \in \mathcal{S} \setminus \{F\}$, we get $\mathbb{E}[\#(E_3)] \leq c_4 \cdot (\mathcal{C} - 1)\kappa s$.

Proof of Proposition 34. The first part of the proposition, $D_y \cap \mathcal{T} = \emptyset$, follows from the condition on B. For the next part, note that $y \in \partial D_y$. Let v denote the center of the ball B, and let z be a variable point on the line segment vx. Let B(z) denote the ball with center z, having $x \in \partial B(z)$. For z = v, B(z) = B intersects P. For z = x, $B(z) = \{x\}$ does not intersect P. Therefore there exists some value of z = c such that B(c) is tangential to P (see figure 2). Let x' denote the point where B(c) touches P. Then $x' \in D_y$, since by Construction 32 $B(z) \subset B$ for all z in the segment vx, and hence $B(c) \cap P \subset B \cap P$. Also, $x' \in V(x)$, by the definition of V(x). Therefore we get $x' \in D_y \cap V(x)$.

Proof of Lemma 35. Suppose $\{x,y\} \in E_4$. Then there exists a ball $B \in \mathbb{E}^3$ with $x,y \in \partial B$, and $int(B) \cap \mathcal{Y} = \emptyset$. Therefore $D_y := B \cap P$ also satisfies $int(D_y) \cap \mathcal{Y} = \emptyset$. By Proposition 34 we have that $D_y \cap V(x) \neq \emptyset$. Therefore, $y \in V(x) \oplus 2r_y$, where r_y is the radius of D_y . But since $y \in Int(F)$, we have that any disk having y on its boundary and containing no point of \mathcal{Y} in its interior can have radius at most $2^{Lev(y)-1}\delta$. Therefore $r_y \leq 2^{Lev(y)-1}\delta$. Now taking k_y such that $2^{k_y}\delta = 2r_y$, we get that $k_y \leq Lev(y)$.

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Proof of Proposition 33(iii) Consider a point $x \in Z$, and let V(x) be the region corresponding to x in \mathcal{V} . By Proposition 33 (ii), $V(x) = (\bigcap_{D \in D_x} D) \bigcap (\bigcap_{\bar{D} \in C_x} \bar{D})$, where D_x is a set of disks and C_x is a set of complements of disks in the plane P. Let $y \in \partial V(x)$.

Then if $y \in \bigcap_{D \in D_x} D$, then there exists $D_1 \in D_x$, such that $y \in \partial D_1$, and so y is part of a convex segment in $\partial V(x)$. Otherwise, there exists $\bar{D}_2 \in C_x$, such that $y \in \partial \bar{D}_2$. In this case, let V(z), $z \in Z$, denote the region such that $y \in \partial V(z)$. Then $D_2 \supset V(z)$, and therefore y belongs to a convex segment in $\partial V(z)$.

Thus, every point $y \in \partial V(x)$ is convex either for V(x) or for a neighbouring region of V(x), and so the total length of the convex boundary curves in \mathcal{V} gives the total length of all the boundary curves.

Proof of Lemma 36. Let $x \in \mathcal{X}$ and $y \in \mathcal{X} \cap F$. Let $\mathcal{E}_{x,y}$ denote the event $\{x,y\} \in \mathcal{E}_4(Int(F))$. Then $\mathcal{E}_{x,y}$ can occur only if (i) $x \in Bd_{\mathcal{S}}(\mathcal{Y})$ and, (ii) $y \in Int_{\mathcal{S}}(Y) \cap V_F(x)$. Fix a choice of \mathcal{Y} , say $Y \in \binom{\mathcal{X}}{s}$. Conditioning on this choice of \mathcal{Y} , $Bd_{\mathcal{S}}(\mathcal{Y})$ is a fixed set of points. The number of pairs contributing to $E_4(Int(F))$ is at most $\mathcal{Y} = \mathcal{Y} \cap \mathcal{Y}$. The main observation is now that since $\mathcal{Y} \cap \mathcal{Y} \cap \mathcal{Y}$ restricted to F is a sub-division of F, for each $Y \in \mathcal{X} \cap F$, there is a unique $X = X_Y \in \mathcal{Y} \cap \mathcal{Y}$ such that $Y \in V_F(x)$. Therefore we get

$$E_4(Int(F)) \leq \sum_{V_F(x)\in\mathcal{V}: x\in Bd_{\mathcal{S}}(Y)} \sharp (V_F(x)\cap Y) \leq \sharp (Y\cap F).$$

Since the last bound holds for any choice of Y, taking expectation over all choices we get

$$\mathbb{E}\left[E_4(Int(F))\right] \leq \mathbb{E}\left[\sharp \left(\mathcal{Y} \cap F\right)\right] = q \cdot \sharp \left(\mathcal{X} \cap F\right).$$

Now summing over all faces gives $[E_4(Int)] \leq \mathbb{E}\left[\sharp\left(\mathcal{Y}\right)\right] = s.$

Proof of Lemma 37. To compute the expected value of $E_4(Bd(S))$, fix a face $F \in S$.

Consider a pair of points $x, y \in \mathcal{X}$, such that $y \in F$. Let $\mathcal{E}_{x,y}$ denote the event $\{x, y\} \in \mathcal{E}_{4}(Bd(F))$.

The value of $E_4(Bd)$ is the number of $x, y \in \mathcal{X}$, such that $\mathcal{E}_{x,y}$ occurs. Taking expectations,

$$\mathbb{E}\left[E_4(Bd(F))\right] \leq \sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{X} \cap F} \mathbb{P}\left[\mathcal{E}_{x,y}\right]. \tag{7}$$

Observe that $\mathcal{E}_{x,y}$ occurs only if (i) $x \in Bd_{\mathcal{S}}(\mathcal{Y})$ and (ii) $k_y(x) \leq Lev(y)$, by applying Construction 32, on the plane $P, Z = Bd_{\mathcal{S}}(\mathcal{Y})$, and $\mathcal{T} = \mathcal{Y} \cap P$, and using Proposition 34. By Lemma 35, $k_y(x) \in [0, Lev(y)]$.

Let P_{k_1,k_2} denote the probability that $\{x,y\} \in E_4(Bd(F))$, with $Lev(x) = k_1$, and k_2 as

$$\mathbb{E}\left[E_4(Bd(F))\right] \leq \sum_{k_1 \geq 0} \sharp \left(L_{=k_1} \cap \mathcal{X}\right) \sum_{k_2 \geq 0} \sum_{V_F \in \mathcal{V}} \sharp \left(\left(\partial V_F \oplus 2^{k_2} \delta\right) \cap \mathcal{X}\right) \cdot P_{k_1, k_2}.$$

Applying the Decay Lemma 30 with t=2, $x_1=x$, $x_2=y$, $k_1=\max\{0,k_1-1\}$ (since $x\in Bd_{\mathcal{S}}(\mathcal{Y})$), and $k_2=\max\{0,k_2-1\}$, we get

$$P_{k_1,k_2} \le c_1 q^2 \cdot \exp\left(-f(k^*)\right),$$

where $k^* := \max\{0, k_1 - 1, k_2 - 1\}$, and $f(k^*) = 0$ if $k^* = 0$, and $c'_2 \cdot 2^{2k^*}$ otherwise, with $c'_2 = c_2/4$.

As in the proof of Lemma 21, we shall use symmetry to handle the case where $k_1 \ge k_2$ and $k_2 > k_1$ together. We get

$$\mathbb{E}\left[E_4(Bd(F))\right] \leq 2\sum_{k_1 \geq 0} \sharp \left(L_{=k_1} \cap \mathcal{X}\right) \sum_{k_2 \leq k_1} \sum_{V(x) \in \mathcal{V}} \sharp \left(\left(\partial V(x) \oplus 2^{k_2} \delta\right) \cap \mathcal{X}\right) \cdot c_1 q^2 \cdot \exp\left(-c_2' 2^{2k_1}\right).$$

By the Level Size Lemma 28, we get that $\sharp (L_{=k_1} \cap \mathcal{X}) \leq \frac{9\kappa L 2^{k_1} \delta}{\varepsilon^2}$. Using Proposition 26, we get that $\sharp \left(\{\partial V(x) \oplus 2^{k_2} \delta\} \cap \mathcal{Y} \right) \leq \frac{9\kappa \cdot l(\partial V(x)) 2^{k_2} \delta}{\varepsilon^2}$. By Proposition 33 (iii), each boundary in the partition \mathcal{V} is convex for some $x \in Bd_{\mathcal{S}}(\mathcal{Y})$. Therefore we need to sum $l(\partial V(x))$ only over the convex curves in $\partial V(x)$, $x \in Bd_{\mathcal{S}}(\mathcal{Y})$. The length of these curves is at most $l(\partial F)$. Thus we get

$$\mathbb{E}\left[E_4(Bd(F))\right] \leq 2L \cdot l(\partial F) \cdot \left(\frac{9\kappa\delta q}{\varepsilon^2}\right)^2 \sum_{k_1 > 0} 2^{k_1} \sum_{k_2 < k_1} 2^{k_2} c_1 \cdot \exp\left(-c_2' \cdot 2^{2k_1}\right).$$

Using Lemma 44, the above summation is bounded by a constant. This comes to c_1 · $O(1)\left(\frac{(9\kappa))^2L\cdot l(\partial F)\delta^2q^2}{\varepsilon^4}\right)=O\left(\frac{\kappa^2L\cdot l(\partial F)s}{A}\right)$, where the last step followed from the lower bound on n in Proposition 25 (2), and the identities $q=s/n=\delta^2/\varepsilon^2$. Summing y over all facets F in \mathcal{S} , we get $\mathbb{E}\left[E_4(Bd(\mathcal{S}))\right]=\left(O(1)\cdot\frac{\kappa^2L^2s}{A}\right)$.

905 Proofs from Section 7

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Proof of Theorem 41. From Bieberbach's theorem [6], and Caroli-Teillaud's construction [10]
 (Section 4), it follows that

▶ Theorem 47 (Bieberbach [6], Caroli-Teillaud [10](Section 4)). Every Euclidean d-orbifold \mathbb{M} has a covering space using a finite number $m_{\mathbb{M}}$ of sheets of a d-hyperparallelepiped $\tilde{\mathbb{T}}^d_{\mathbb{M}}$, such that the Delaunay triangulation of any point set on \mathbb{M} is the projection of the Delaunay triangulation of the cover of the point set in the covering space.

The proof of Theorem 41 is on similar lines as that of Theorem 10, except (i) we work with the hyperparallelepiped $\tilde{\mathbb{T}}^d_{\mathbb{M}}$, and (ii) we need to take the effect of the multiplicity (i.e. the number $m_{\mathbb{M}}$ of sheets of $\tilde{\mathbb{T}}^d_{\mathbb{M}}$ required for Theorem 47 to hold) into account for all simplices. To handle (i), we observe that the volume of balls will change as the hyperparallelepiped is no longer a hypercube. Thus, a factor of the volume of the unit hyperparallelepiped $\tilde{\mathbb{T}}^d_{\mathbb{M}}$, will come into the estimates in Lemma 5. To handle the effect of multiplicity, we introduce an extra multiplicative factor of $m^d_{\mathbb{M}}$ in the bound of the number of possible d-simplices with any fixed set of points (compared to Lemma 20). Additionally, we take into account that the number of distinct points inside a potential simplex is at least a $1/m_{\mathbb{M}}$ -fraction of the number guaranteed by Lemma 17. This gives a worse bound for the expected complexity of the star than in Theorem 10, but still a constant.

Proof of Theorem 42. The action of \mathbb{Z}^d on \mathbb{E}^d is defined by translation, i.e. for $x \in \mathbb{E}^d$, $g \in \mathbb{Z}^d$, $gx := g \cdot x = g + x$. For a finite point set $P \in \mathbb{E}^d$, let $\Delta(\mathbb{Z}^d P)$ denote the largest ball in \mathbb{E}^d containing no points from $\mathbb{Z}^d P$. Let $\delta((k\mathbb{Z})^d)$ denote the minimum distance by which a point in \mathbb{E}^d is translated by $(k\mathbb{Z})^d$. Finally, let $\pi(.)$ denote the projection map of the covering space \mathbb{T}^d_k on to \mathbb{T}^d . We shall use the following geometric condition of Caroli and Teillaud [10].

Lemma 48. If $\Delta(\mathbb{Z}^d P) < \delta((k\mathbb{Z})^d)/2$, then for any finite $Y \supset P$, the projection $\pi(Del(\mathbb{Z}^d Y))$ is a triangulation of \mathbb{T}^d .

Now, observe that in the Euclidean metric, the diameter $\Delta_{\parallel,\parallel}(\mathbb{Z}^d P)$ of the largest ball not 931 containing any point from the set $\mathbb{Z}^d P$ is at most \sqrt{d} , with equality holding when $\sharp (P) = 1$, 932 and that $\Delta(S') \leq \Delta(S)$ for any $S' \supseteq S$, since adding points can only decrease the diameter 933 of the largest empty ball. Therefore, in the metric \mathfrak{d} , we have that

$$\Delta_{\mathfrak{d}}(\mathbb{Z}^d P) \leq \Delta_{\|.\|}(\mathbb{Z}^d P) \cdot \left(\max_{x,y \in \mathcal{S}} \frac{\mathfrak{d}(x,y)}{\|x-y\|}\right).$$

By the previously observed bound on $\Delta_{\|.\|}(\mathbb{Z}^d P)$, we have

$$\Delta_{\mathfrak{d}}(\mathbb{Z}^d P) \leq \left(\max_{x,y \in \mathcal{S}} \frac{\mathfrak{d}(x,y)}{\|x-y\|} \right) \cdot \sqrt{d}.$$

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Also, letting $((k\mathbb{Z})^d)^*$ denote the non-identity elements of $(k\mathbb{Z})^d$, 938

$$\delta_{\mathfrak{d}}((k\mathbb{Z})^d) = \min_{x \in \mathcal{G}, \ g \in ((k\mathbb{Z})^d)^*} \mathfrak{d}(x, gx) = \min_{x \in \mathcal{G}, \ g \in ((k\mathbb{Z})^d)^*} \frac{\mathfrak{d}(x, gx)}{\|x - gx\|} \cdot \|x - gx\|.$$

For the flat torus \mathbb{T}_k^d , $\min_{x,g} \|x - gx\| = k$. Therefore, in the metric \mathfrak{d} , the condition of Lemma 48 is satisfied if

$$\max_{x,y \in \mathbb{Z}^d P} \frac{\mathfrak{d}(x,y)}{\|x-y\|} \cdot \sqrt{d} < \frac{1}{2} \left(\min_{x \in P, \ g \in ((k\mathbb{Z})^d)^*} \frac{\mathfrak{d}(x,gx)}{\|x-gx\|} \cdot \|x-gx\| \right), \text{ or,}$$

$$\begin{array}{lll}
 & 2\sqrt{d} \cdot \max_{x,y \in \mathbb{Z}^{d}P} \frac{\mathfrak{d}(x,y)}{\|x-y\|} \cdot \max_{x' \in P, \ g \in ((k\mathbb{Z})^{d})^{*}} \frac{\|x'-gx'\|}{\mathfrak{d}(x',gx')} & < k, \text{ which is true if} \\
 & 2\sqrt{d} \cdot \max_{x,y \in \mathbb{Z}^{d}P} \frac{\mathfrak{d}(x,y)}{\|x-y\|} \cdot \min_{x',y' \in \mathbb{Z}^{d}P} \frac{\mathfrak{d}(x',y')}{\|x'-y'\|} & < k, \text{ or,} \\
\end{array}$$

$$2\sqrt{d} \cdot \max_{x,y \in \mathbb{Z}^{d}P} \frac{\mathfrak{d}(x,y)}{\|x-y\|} \cdot \min_{x',y' \in \mathbb{Z}^{d}P} \frac{\mathfrak{d}(x',y')}{\|x'-y'\|} < k, \text{ or,}$$

$$2\sqrt{d\cdot\kappa_{\mathfrak{d}}} < k$$

since by definition, the distortion $\kappa_{\mathfrak{d}}$ satisfies for all $x, y \in \mathbb{Z}^d P$, $\mathfrak{d}(x, y) \leq \kappa_{\mathfrak{d}} \|x - y\|$, i.e. $\kappa_{\mathfrak{d}} \geq \max_{x,y \in \mathbb{Z}^d P} \frac{\mathfrak{d}(x,y)}{\|x-y\|}$, as well as $\|x - y\| \leq \kappa_{\mathfrak{d}} \mathfrak{d}(x,y)$, i.e. $\kappa_{\mathfrak{d}} \geq \min_{x,y \in \mathbb{Z}^d P} \frac{\mathfrak{d}(x,y)}{\|x-y\|}$. 947

Since the fundamental domain of \mathbb{T}_k^d contains k^d copies of the fundamental domain of \mathbb{T}^d , we have $m \leq k^d$, and so the first part of the theorem follows with $m \leq (2\sqrt{d}\kappa_0)^d$. The second part easily follows from the well-known linear algebraic facts that (a) $\max_{\|x\|=1} \{x^{\top} M x\} = 0$ $\max_{\|x\|=1} \{\|Ax\|\} = \sigma_{\max}(A)$, and that (b) $\min_{\|x\|=1} \{x^{\top} M x\} = \sigma_{\max}(A^{-1}) = \sigma_{\min}(A)$ where A is such that $M = A^{\top}A$ and $\sigma_{\max}(A)$, $\sigma_{\min}(A)$ are respectively the largest and the smallest singular values of A.