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An exponential timestepping algorithm for diffusion with discontinuous coefficients

Antoine Lejay^{*}, Lionel Lenôtre[†] and Géraldine Pichot[‡]

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Abstract

We present a new Monte Carlo algorithm to simulate diffusion processes in presence of discontinuous convective and diffusive terms. The algorithm is based on the knowledge of close form analytic expressions of the resolvents of the diffusion processes which are usually easier to obtain than close form analytic expressions of the density. In the particular case of diffusion processes with piecewise constant coefficients, known as Skew Diffusions, such close form expressions for the resolvent are available. Then we apply our algorithm to this particular case and we show that the approximate densities of the particles given by the algorithm replicate well the particularities of the true densities (discontinuities, bimodality, ...) Besides, numerical experiments show a quick convergence.

Keywords: Monte Carlo, Skew diffusions, resolvent kernel, diffusion processes with discontinuous coefficients.

Highlights:

- We present a new algorithm that simulates diffusion processes with discontinuous diffusive and convective terms.
- Applied to Skew diffusions, we show that the algorithm ensures a correct repartition of the mass.
- The convergence is very fast.

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1 Introduction

Simulating diffusion processes in media presenting discontinuous characteristics is ubiquitous for practical applications. Among them, let us cite (with only a few references) geophysics for inert fluids [11, 18, 25, 37, 41], air [40] and ocean [39]; astrophysics [44]; molecular dynamics [7]; population ecology [8, 27]; finance [10, 17, 43], ...

In practice, a diffusion process can be thought as the collection of the possible trajectories of particles moving randomly in a medium. This is the path of the Monte Carlo method (also called Lagrangian techniques or particles tracking). For example, the particles may represent a plume of pollutant in a porous medium with initial concentration C_0 . Then the concentration around any point y at time t is given by $C(t, y) = \int C_0(x)p(t, x, y) dx$ where $p(t, x, \cdot)$ is the density of the particles at time t whose initial position is x . This density is known in physics for being solution to the Fokker-Planck (or Kolmogorov Forward) equation

$$\begin{cases} \partial_t p(t, x, y) = \frac{1}{2} \nabla(a(y) \nabla p(t, x, y)) - \nabla(b(y)p(t, x, y)), \\ p(t, x, y) \xrightarrow[t \rightarrow 0]{} \delta_x \end{cases} \quad (1.1)$$

As a result, when one simulates N particles starting from x whose displacement respects the dynamics of the operator $\mathcal{L} = \frac{1}{2} \nabla(a \nabla \cdot) + b \nabla \cdot$ which is the adjoint of $\frac{1}{2} \nabla(a \nabla \cdot) + \nabla(b \cdot)$ appearing in equation (1.1), the empirical density $p_{(N)}(t, x, \cdot)$ of the N particles gives an approximation of $p(t, x, y)$. The concentration of the pollutant can thus be approximated by these Lagrangian simulation [25, 26]. Likewise, many other physical quantities may be computed this way, for example macrodispersion coefficients, breakthrough curves, [4, 33].

Monte Carlo simulations have several advantages. Among them,

- they are really simple to set-up and implement,
- they are completely grid-free,
- they do not suffer from the curse of dimensionality,
- they do not introduce artificial numerical diffusion [45].

The challenge is to move the particles in the medium by following as accurately as possible their true dynamics.

The simplest case is when the underlying operator is $\frac{1}{2}a \Delta \cdot + b \nabla \cdot$ with continuous coefficients. In that case, the associated process $\{X_t\}_{t \geq 0}$ is solution to a Stochastic Differential Equation (SDE) $dX_t = \sqrt{a(X_t)} dW_t + b(X_t) dt$ for a Brownian motion W . The distribution of $X_{t+\Delta t}$ given X_t is then close to the Gaussian distribution of mean $b \Delta t$ and variance $a \Delta t$. The addition of the Markov property to that last observation directly leads to approximate the successive positions at times $\{k \Delta t\}_{k=0, \dots, n}$ of the stochastic process by using Gaussian distributions. This method is the so-called Euler-Maruyama scheme [24], which generalizes to SDE the Euler scheme for ODE.

However, in many situations, the Gaussian approximation is no longer valid or leads to bad behaviors [25, 39]. This is the case when one faces discontinuities in the diffusivity or considers a process generated by a divergence form operator (Fick's law, for example).

To overcome these problems, several schemes have been proposed so far in the literature (see *e.g.*, [5, 18, 25, 30, 38, 41] among many others). However, some convergent schemes do not always lead to accurate simulations as important physical properties may be lost

as shown by some benchmark tests [31]. In addition, only a few schemes actually deal with a convective term b (for example, Random Walk Methods [14, 15, 29]). In some cases, exact simulation techniques, based on rejection-acceptance principle, were developed and allowed to deal with a drift [12, 16]. But, they are particularly heavy to implement and computationally excessively costly. They also suffer from a lack of flexibility. The basic functionals vary with the coefficients.

This article presents two contributions.

First, we propose a **GE**neralized **A**lgorithm based on **RE**solvent for **D**iffusion (**GEARED**), which uses a functional called the resolvent kernel instead of an approximation of the density $p(t, x, y)$ as in the Euler-Maruyama scheme. More precisely, the algorithm uses the resolvent kernel in conjunction with recentered exponential timesteps. This approach is relevant once the resolvent kernel has simple analytic and tractable expressions unlike the density. An important feature of the resolvent kernel is that it keeps the symmetry. We refer to [31] for a list of features with their characterizations. In the case of the Brownian motion, this approach has been studied by K. Jansons and G. Lythe who showed its efficiency to deal with boundary conditions [21–23] (see also [1, 2, 35]). Here we extend this approach to deal with discontinuities or locally non constant coefficients.

Second, we apply the **GEARED** algorithm to deal with the simulation in a one-dimensional medium of diffusion processes X which are generated by

$$\mathcal{L} = \frac{\rho}{2} \frac{d}{dx} \left(a \frac{d}{dx} \right) + b \frac{d}{dx}$$

where a and b are piecewise constant. We show that the **GEARED** completely overcomes the restrictions of some of the schemes mentioned above which are based on the particular form of the density or explicit knowledge of the distribution of the marginal distribution of the process. Indeed, in presence of a two-valued drift, explicit closed form expressions for the density could be cumbersome and then hard to use for numerical purposes while the resolvent kernel has an explicit expression [28]. Numerical experiments show that the **GEARED** algorithm leads to accurate approximations, even in situations where the target density is far from being Gaussian.

The outline of the paper is the following. In Section 2, we present the **GEARED** algorithm based on an exponential timestepping scheme. In Section 3, we present the implementation of the algorithm for piecewise discontinuous coefficients. Numerical results are given in Section 4. We conclude in Section 5.

2 Context and presentation of the **GEARED** algorithm

In this section, let us introduce first the assumptions on the coefficients and recall the exponential formula for the resolvent kernel. Then we present the **GEARED** algorithm.

2.1 Assumptions on the coefficients

Notation 2.1. We denote by $\mathcal{C}_0(\mathbb{R})$ the space of continuous functions vanishing at infinity, by $L^2(\mathbb{R})$ the space of square integrable functions on \mathbb{R} and by $H^1(\mathbb{R})$ the space of functions in $L^2(\mathbb{R})$ whose weak derivatives belong also to $L^2(\mathbb{R})$.

Assumption 2.1. a, ρ, b are measurable functions from \mathbb{R} to \mathbb{R} such that

$$0 < \lambda \leq a(x), \rho(x) \leq \Lambda, |b(x)| \leq \Lambda$$

for some positive constants λ, Λ .

Let us define

$$h(x) := 2 \int_0^x \frac{b(y)}{a(y)\rho(y)} dy. \quad (2.1)$$

We set $(\mathcal{L}, \text{Dom}(\mathcal{L}))$ the infinitesimal generator given by

$$\mathcal{L} := \frac{1}{2}\rho(x)\frac{d}{dx}\left(a(x)\frac{d}{dx}\cdot\right) + b(x)\frac{d}{dx} = \frac{1}{2}e^{-h(x)}\rho(x)\frac{d}{dx}\left(a(x)e^{h(x)}\frac{d}{dx}\cdot\right) \quad (2.2)$$

and the domain

$$\text{Dom}(\mathcal{L}) = \{f \in \mathcal{C}_0(\mathbb{R}, \mathbb{R}) \mid \mathcal{L}f \in \mathcal{C}_0(\mathbb{R}, \mathbb{R})\}.$$

The two different expressions of the operator above corresponds. The right-hand side of (2.2) is actually the so-called factorized form we are going to introduce later.

The assumptions on a, ρ and b ensure the existence of a unique, Feller process X whose infinitesimal generator is $(\mathcal{L}, \text{Dom}(\mathcal{L}))$. More precisely, X is the process whose density transition function $p(t, x, y)$ derives from the semi-group $\{P_t\}_{t>0}$ associated to $(\mathcal{L}, \text{Dom}(\mathcal{L}))$. This is the result of the equality

$$P_t f(x) = \mathbf{E}_x[f(X_t)] = \int_{\mathbb{R}} p(t, x, y) f(y) dy,$$

for any measurable function f which is either bounded or in $L^2(\mathbb{R})$.

Consequently, X is the continuous stochastic process whose density transition function $p(t, x, y)$ is the solution to Fokker-Planck equation and is thus the process of interest for the simulation of a diffusion problem. As an illustration,

- When $a = 1$, then X is the solution to the SDE

$$X_t = x + \int_0^t \sqrt{\rho(X_s)} dW_s + \int_0^t b(X_s) ds.$$

- When a has some isolated discontinuities with left and right-limits, the process X is solution to some SDE with local time (See *e.g.* [29]).

2.2 Definition of resolvent kernel and reminder of the exponential formula

Definition 2.1. *The resolvent $\{R_\lambda\}_{\lambda>0}$ of the infinitesimal generator $(\mathcal{L}, \text{Dom}(\mathcal{L}))$ is the family of operator $R_\lambda = (\lambda - \mathcal{L})^{-1}$ acting on $\mathcal{C}_0(\mathbb{R})$ whose range is $\text{Dom}(\mathcal{L})$.*

In practice, the resolvent $\{R_\lambda\}_{\lambda>0}$ of an infinitesimal generator $(\mathcal{L}, \text{Dom}(\mathcal{L}))$ is given by the Laplace transform of the semi-group $\{P_t\}_{t\geq 0}$ (see [34, theorem 3.1]). As an equation, it rewrites

$$R_\lambda f(x) = \int_0^{+\infty} e^{-\lambda t} P_t f(x) dt, \quad f \in \mathcal{C}_0(\mathbb{R}).$$

When the semi-group $\{P_t\}_{t\geq 0}$ has a density transition function, then according to [28, 32]

$$R_\lambda f(x) = \int_{\mathbb{R}} r(\lambda; x, y) f(y) dy, \quad \text{for } f \in \mathcal{C}_0(\mathbb{R})$$

where

$$r(\lambda; x, y) = \int_0^{+\infty} e^{-\lambda t} p(t, x, y) dt.$$

The functional $r(\lambda; x, y)$ is the so-called *resolvent kernel* or *Green kernel*.

For small values of t , $t^{-1}R_{1/t}$ is close to P_t . The semi-group can be reconstructed from the resolvent through the *exponential formula* by iterating the application of the resolvent.

Proposition 2.1 (Exponential formula [9, 34]). *For any $t > 0$ and any $f \in \mathcal{C}_0(\mathbb{R})$,*

$$P_t f = \lim_{n \rightarrow \infty} \left(\frac{n}{t} R_{n/t} \right)^n f. \quad (2.3)$$

2.3 Presentation of the GEARED algorithm

2.3.1 Motivations and notations

Many simulation methods for X fix the time step Δt and draw a realization of a Markov chain $(\xi_k)_{k\geq 0}$ such that

$$\xi_{k+1} \sim \bar{p}_{\xi_k}(\Delta t, \xi_k, y) dy,$$

where $\bar{p}_x(\Delta t, x, \cdot)$ is a parametric family of approximations of $p(\Delta t, x, \cdot)$ when Δt is small, the parameter being the starting point x (this is why it appears twice). With such a scheme, $\{(k\Delta t, \xi_k)\}_{k=0, \dots, n}$ is an approximation of $\{(k\Delta t, X_{k\Delta t})\}_{k=0, \dots, n}$.

When the coefficients are regular enough, the simplest yet efficient scheme is the Euler-Maruyama scheme [24]. In this case, $\bar{p}_x(\Delta t, x, y)$ is obtained by freezing the values of the coefficients at the point x .

When the coefficients are discontinuous, the density $p(t, x, \cdot)$ is no longer well approximated by a Gaussian one. Specific schemes should then be designed. They must ensure the correct repartition of the mass (See [30] and references within). For that purpose, one should find a proper approximation $\bar{p}_x(\Delta t, x, y)$ of $p(\Delta t, x, y)$.

Notation 2.2. We denote by $\mathcal{E}(\lambda)$ the exponential distribution of parameter $\lambda > 0$.

2.3.2 The GEARED algorithm

The following result is the cornerstone for the construction the GEARED algorithm and is based on a exponential timestepping scheme. It shows how one can use the resolvent to sample the position of X at exponential timesteps.

Proposition 2.2. Let $\zeta \sim \mathcal{E}(\lambda)$ be independent of X . The density of X_ζ , starting at X_0 , is $\lambda r(\lambda; X_0, \cdot)$.

Proof. Let us consider that $X_0 = x$. The density of the random variable X_ζ is, by conditioning with respect to ζ , for any $f \in \mathcal{C}_0(\mathbb{R}; \mathbb{R})$,

$$\begin{aligned} \mathbf{E}[f(X_\zeta)] &= \int_0^{+\infty} \lambda e^{-\lambda t} \mathbf{E}[f(X_t)] dt = \int_0^{+\infty} \lambda e^{-\lambda t} \int_{\mathbb{R}} p(t, x, y) f(y) dy dt \\ &= \int_{\mathbb{R}} \lambda r(\lambda; x, y) f(y) m(y) dy. \end{aligned}$$

Thus, $X_\zeta \sim \lambda r(\lambda; x, \cdot)$ when $X_0 = x$. □

To build the exponential the timestepping scheme is now rather simple. Using the Proposition 2.2, for any function $f \in \mathcal{C}_0(\mathbb{R})$,

$$\begin{aligned} \mathbf{E}_{x_0}[f(\overline{X}_T^{(n)})] &= \frac{1}{\Delta t} \int_{\mathbb{R}} \cdots \int_{\mathbb{R}} r(\Delta t^{-1}; x_0, x_1) r(\Delta t^{-1}; x_1, x_2) \cdots r(\Delta t^{-1}; x_{n-1}, x_n) f(x_n) dx_1 \cdots dx_n \\ &= \left(\frac{n}{T} R_{T/n} \right)^n f(x_0). \end{aligned} \quad (2.4)$$

An application of Exponential formula (2.3) then yields to

$$\mathbf{E}_{x_0}[f(\overline{X}_T^{(n)})] \xrightarrow{n \rightarrow \infty} \mathbf{E}_{x_0}[f(X_T)] = P_T f(x_0).$$

As a result, for a timestep $\Delta t = T/n$,

$$\overline{X}_0^{(n)} = X_0, \quad \overline{X}_{(k+1)\Delta t}^{(n)} \sim \Delta t^{-1} r(\Delta t^{-1}; \overline{X}_{k\Delta t}^{(n)}, \cdot),$$

where λ has been replaced by $\frac{1}{\Delta t}$, provides a reliable approximation of a sample path of X . This idea is summarized in Algorithm 1.

Data: An initial position x at time 0, a time horizon $T > 0$ and an integer n such that $\Delta t = T/n$ is the timestep.

Result: An approximated path $(\overline{X}_0^{(n)}, \overline{X}_{\Delta t}^{(n)}, \dots, \overline{X}_T^{(n)})$ of $(X_0, X_{T/n}, \dots, X_T)$ with $X_0 = x$.

Set $\overline{X}_0^{(n)} = x$.

for $i = 1, \dots, n$ **do**

 | Sample $\overline{X}_{i\Delta t}^{(n)}$ using the density $\Delta t^{-1} r(\Delta t^{-1}; \overline{X}_{(i-1)\Delta t}^{(n)}, \cdot)$.

end

return $(\overline{X}_0^{(n)}, \overline{X}_{\Delta t}^{(n)}, \dots, \overline{X}_T^{(n)})$.

Algorithm 1: The GEARED algorithm.

2.3.3 Convergence of the GEARED algorithm

When λ is large, $\zeta \sim \mathcal{E}(\lambda)$ concentrates around its mean value $\lambda^{-1} = \Delta t$. We formalize this point in the next proposition.

Proposition 2.3. *Let T be a time horizon. With $\lambda = n/T$ and $\Delta t = T/n = \lambda^{-1}$, define*

$$\sigma_0 = 0 \text{ and } \sigma_{k+1} = \sigma_k + \zeta_k, \quad \zeta_k \sim \mathcal{E}(\lambda), \quad \{\zeta_k\}_{k \geq 0} \text{ independent.}$$

For any $\epsilon > 0$ and any $\beta > 0$, there exists n' large enough such that

$$\mathbb{P} \left[\sup_{k=0, \dots, n} |X_{\sigma_k} - X_{k\Delta t}| \geq \beta \right] \leq \epsilon, \quad \forall n \geq n'. \quad (2.5)$$

In the above proposition, $(X_{\sigma_0}, \dots, X_{\sigma_n})$ has the same distribution as $(\bar{X}_0^{(n)}, \dots, \bar{X}_T^{(n)})$. This proves that the vector of successive positions is close to the one of the true positions. With some standard additional work, not done here, it is possible to prove that the family of linear interpolation of $(\bar{X}_0^{(n)}, \dots, \bar{X}_T^{(n)})$ is tight and thus converges to $(X_t)_{t \in [0, T]}$.

Remark 2.1. Although our algorithm draw a realization of X_ζ , the exponential time ζ itself is not drawn and not known. Trying to recover the exact time wipes out all the numerical interest of the method as it requires to know the density $p(t, x, \cdot)$, which we want to avoid.

Proof. For the above family $\{\zeta_k\}_{k \geq 0}$ of exponential random variables, a martingale inequality yields

$$\mathbb{P}[\zeta_n \geq \alpha] \leq \frac{K}{\alpha n} \text{ with } \epsilon_n = \sup_{k=0, \dots, n} \left| \sigma_k - \frac{kT}{n} \right|. \quad (2.6)$$

Thus, σ_k is an approximation of kT/n , the k -th position of the process. In addition, from [20, Theorem 5.1], for any $\tau \geq 0$,

$$\mathbb{P}[\sigma_n \geq T + \tau] \leq \exp\left(-\frac{\tau}{T}\right). \quad (2.7)$$

We fix $\tau > 0$. Let $\text{osc}_T(f, \delta) = \sup_{t \in [0, T], |s| \leq \delta} |f(t+s) - f(t)|$ be the modulus of continuity of continuous functions $f : [0, T] \rightarrow \mathbb{R}$. Since the paths of X are continuous, for any $\beta, \epsilon > 0$, there exists $\alpha > 0$ such that $\mathbb{P}[\text{osc}_T(X, \alpha) \geq \beta] \leq \epsilon$. This follows *e.g.* from Theorem 8.2 and Theorem 1.4 in [6] on tightness.

Then for any $\epsilon > 0$ and $\beta > 0$, when τ is such that $\exp(-\tau/T) \leq \epsilon$, α such that $\mathbb{P}[\text{osc}_{T+\tau}(X, \alpha) \geq \beta] \leq \epsilon$ and n such that $K/\alpha n \leq \epsilon$, using (2.6) and (2.7),

$$\begin{aligned} \mathbb{P} \left[\sup_{k=0, \dots, n} |X_{\sigma_k} - X_{kT/n}| \geq \beta \right] &\leq \mathbb{P}[\sigma_n \geq T + \tau] + \mathbb{P}[|X_{\sigma_k} - X_{kT/n}| \geq \beta; \sigma_n \leq T + \tau] \\ &\leq \mathbb{P}[\sigma_n \geq T + \tau] + \mathbb{P}[\text{osc}_{T+\tau}(X, \epsilon_n); \sigma_n \leq T + \tau] \\ &\leq \exp\left(\frac{-\tau}{T}\right) + \mathbb{P}[\text{osc}_{T+\tau}(X, \alpha) \geq \beta] + \mathbb{P}[\epsilon_n \geq \alpha] \leq 3\epsilon. \end{aligned}$$

This proves (2.5). □

3 Application to the case of piecewise constant coefficients

For the sake of simplicity of the presentation, let us consider coefficients with a discontinuity at 0.

3.1 Definition of knotted operators

Notation 3.1 (Knotted). For two functions $f_-, f_+ : \mathbb{R} \rightarrow \mathbb{R}^d$, we define their *knotted* by

$$(f_- \bowtie f_+)(x) := \begin{cases} f_-(x) & \text{if } x < 0, \\ f_+(x) & \text{if } x \geq 0. \end{cases} \quad (3.1)$$

For $i = -, +$, let (a_\pm, ρ_\pm, b_\pm) be continuous coefficients over \mathbb{R} satisfying Assumption 2.1. We knot them into

$$(a, \rho, b) := (a_-, \rho_-, b_-) \bowtie (a_+, \rho_+, b_+).$$

Notice that a, ρ and b are continuous on $(-\infty, 0)$ and $(0, +\infty)$ with left and right limits at 0.

For $i = -, +, \cdot$, we denote by \mathcal{L}_\pm the operator (2.2) with the coefficients (a_\pm, ρ_\pm, b_\pm) .

3.2 Reduction to a Drifted Skew Brownian Motion (DSBM)

Let us consider the simulation of the process X generated by \mathcal{L}^\bowtie of the form (2.2) with the piecewise constant coefficients (a, ρ, b) given by

$$a(x) := (a_- \bowtie a_+)(x), \quad \rho(x) = (\rho_- \bowtie \rho_+)(x) \quad \text{and} \quad b(x) = (b_- \bowtie b_+)(x), \quad (3.2)$$

where $a^i, \rho^i > 0$ and $b^i \in \mathbb{R}$, for $i = 1, 2$.

The process X is the unique strong solution to the SDE

$$X_t = x + \int_0^t \sqrt{a(X_s)\rho(X_s)} dW_s + \int_0^t b(X_s) ds + \frac{a_+ - a_-}{a_+ + a_-} L_t^0(X)$$

where W is a Brownian motion and $L_t^0(X)$ is the symmetric local time of X at 0 [29]. It is equivalent through the change of variables

$$\Phi(x) = \frac{x}{\sqrt{a(x)\rho(x)}}$$

(often called the Lamperti's transform) to the *the Drifted Skew Brownian motion* (DSBM) $Y = \Phi(X)$ (see [28]) which is the solution to

$$Y_t = x + W_t + \int_0^t \frac{b(X_s)}{\sqrt{a(X_s)\rho(X_s)}} ds + (2\beta - 1)L_t^0(Y)$$

$$\text{where } \beta := \frac{\sqrt{\frac{a_+}{\rho_+}}}{\sqrt{\frac{a_+}{\rho_+}} + \sqrt{\frac{a_-}{\rho_-}}} \in (0, 1) \quad \text{and} \quad \theta = 2\beta - 1 \in (-1, 1).$$

The DSBM Y is associated to the coefficients

$$\widehat{\mathbf{a}}\left(\beta, \frac{b_+}{\sqrt{a_+\rho_+}}, \frac{b_-}{\sqrt{a_-\rho_-}}\right) := \left((1-\beta) \bowtie \beta, (1-\beta)^{-1} \bowtie \beta^{-1}, \frac{b_-}{\sqrt{a_-\rho_-}} \bowtie \frac{b_+}{\sqrt{a_+\rho_+}}\right).$$

Remark 3.1. The transformation Φ is remarkable as reduce the number of parameters to deal with. In fact, in order to consider the simulation of the class of processes X , we only have to consider the simulation of the process Z whose coefficients are

$$\widehat{\mathbf{a}}(\beta, \gamma_+, \gamma_-) = ((1-\beta) \bowtie \beta, (1-\beta)^{-1} \bowtie \beta^{-1}, \gamma_- \bowtie \gamma_+).$$

The process Z is described by only 3 parameters $\beta \in (0, 1)$, $\gamma_-, \gamma_+ \in \mathbb{R}$, while X is described by 6 parameters.

3.3 Simulation algorithm in the case of piecewise constant coefficients

Consequently, we can simulate $X_{t+\Delta t}$ given X_t by simulating $Y_{t+\Delta t}$ given $Y_t = \Phi(X_t)$ and then compute $\Phi^{-1}(Y_{t+\Delta t})$. Algorithm 2 shows how to simulate the position of the process X after one step assuming that one knows how to simulate the DSBM Y .

Data: A position $x = X_t$ and a (random or deterministic) timestep Δt .

Result: A position of $X_{t+\Delta t}$ given X_t .

Draw $y = Y_{\Delta t}$ given $Y_0 = \Phi(x)$ where Y is a DSBM of parameter

$$\widehat{\mathbf{a}}\left(\beta, \frac{b_+}{\sqrt{a_+\rho_+}}, \frac{b_-}{\sqrt{a_-\rho_-}}\right);$$

return $\Phi^{-1}(y)$.

Algorithm 2: Sampling X with piecewise constant coefficients given by (3.2) using the DSBM Y .

Now let us use the GEARED algorithm to simulate the DSBM Y . To do so, we need an expression of the resolvent kernel of Y .

3.4 Close form expression of the DSBM's resolvent kernel

Let us provide the resolvent kernel of a process Z whose coefficients are

$$\widehat{\mathbf{a}}(\beta, \gamma_+, \gamma_-) = ((1-\beta) \bowtie \beta, (1-\beta)^{-1} \bowtie \beta^{-1}, \gamma_- \bowtie \gamma_+) \quad (3.3)$$

for $\beta \in (0, 1)$, $\gamma_+, \gamma_- \in \mathbb{R}$. We need the main following result of [28] which provides a computational method of the resolvent kernel for knotted operators. It is also valid for the more general case of operators with piecewise continuous coefficients. Also, from the way this result is constructed, multiple interfaces as well as boundary conditions may be considered by a similar approach.

Notation 3.2. For a continuous increasing function G , we define $D^G f(x) := \lim_{\epsilon \rightarrow 0} (f(x + \epsilon) - f(x))(G(x + \epsilon) - G(x))$.

Theorem 3.1 (Construction of the resolvent [28]). *With h given by (2.1), h_{\pm} defined similarly by replacing (a, ρ, b) by $(a_{\pm}, \rho_{\pm}, b_{\pm})$, we set*

$$S_{\pm}(x) := \frac{e^{-h_{\pm}(x)}}{a_{\pm}(x)}, \quad S := S_- \bowtie S_+ \quad \text{and} \quad m(x) := \frac{\exp(h(y))}{\rho(y)}.$$

For two continuous functions f and g such that $D^{S_{\pm}}g$ and $D^{S_{\pm}}f$ exists, we define the Wronskian $\text{Wr}[f, g]$ and the knotted Wronskian $\text{Wr}^{\bowtie}[f, g]$ by

$$\begin{aligned} \text{Wr}[f, g] &:= f(x)D^S g(x) - g(x)D^S f(x), \quad x \in \mathbb{R}, \\ \text{Wr}^{\bowtie}[f, g] &:= f(x)D^{S_{\pm}} g(x) - g(x)D^{S_{\pm}} f(x), \quad x \in \mathbb{R}. \end{aligned}$$

For each $\lambda > 0$, let us assumed that we have found the unique positive, continuous solutions ϕ_{\pm} and ψ_{\pm} to

$$\mathcal{L}_{\pm}\phi_{\pm} = \lambda\phi_{\pm} \quad \text{and} \quad \mathcal{L}_{\pm}\psi_{\pm} = \lambda\psi_{\pm} \quad \text{with} \quad \phi_{\pm}(0) = \psi_{\pm}(0) = 1$$

such that ϕ_{\pm} decreases from $+\infty$ to 0 while ψ_{\pm} increases from 0 to $+\infty$.

The resolvent kernel of \mathcal{L} is for $y \geq 0$,

$$\begin{aligned} r(\lambda; x, y) &= c_1^+ \phi_+(y)m(y)\psi_-(x)\mathbb{1}_{x \leq 0} + (c_2^+ \phi_+(y)\phi_+(x) + c_3^+ \phi_+(y)\psi_+(x))m(y)\mathbb{1}_{x \in (0, y)} \\ &\quad + (c_2^+ \phi_+(y)\phi_+(x) + c_3^+ \psi_+(y)\phi_+(x))m(y)\mathbb{1}_{x \geq y} \end{aligned}$$

with

$$\begin{aligned} c_1^+ &= \frac{2}{\Theta^+} \text{Wr}[\phi_+, \psi_+](0), & c_2^+ &= \frac{-2}{\Theta^+} \text{Wr}^{\bowtie}[\psi_+, \psi_-](0), \\ c_3^+ &= \frac{2}{\Theta^+} \text{Wr}^{\bowtie}[\phi_+, \psi_-](0), & \Theta^+ &= \text{Wr}[\phi_+, \psi_+](y) \text{Wr}^{\bowtie}[\phi_+, \psi_-](0). \end{aligned}$$

For $y < 0$,

$$\begin{aligned} r(\lambda; x, y) &= c_1^- \psi_-(y)m(y)\phi_+(x)\mathbb{1}_{x \geq 0} + (c_2^- \psi_-(y)\psi_-(x) + c_3^- \psi_-(y)\phi_-(x))m(y)\mathbb{1}_{x \in (y, 0)} \\ &\quad + (c_3^- \phi_-(y)\psi_-(x) + c_2^- \psi_-(y)\psi_-(x))m(y)\mathbb{1}_{x \leq y} \end{aligned}$$

with

$$\begin{aligned} c_1^- &= \frac{2}{\Theta^-} \text{Wr}[\phi_-, \psi_-](0), & c_2^- &= \frac{-2}{\Theta^-} \text{Wr}^{\bowtie}[\phi_+, \phi_-](0), \\ c_3^- &= \frac{2}{\Theta^-} \text{Wr}^{\bowtie}[\phi_+, \psi_-](0), & \Theta^- &= \text{Wr}[\phi_-, \psi_-](y) \text{Wr}^{\bowtie}[\phi_+, \psi_-](0). \end{aligned}$$

Remark 3.2. The functions S_{\pm} and S are the *scale function* of the processes associated to $(\mathcal{L}^{\pm}, \text{Dom}(\mathcal{L}^{\pm}))$ and $(\mathcal{L}, \text{Dom}(\mathcal{L}))$. The function m is the *speed measure* of $(\mathcal{L}, \text{Dom}(\mathcal{L}))$.

Remark 3.3. The functions ϕ_{\pm} and ψ_{\pm} are then critical for the knowledge of the processes generated by \mathcal{L}_{\pm} . Various quantities such as hitting times, occupation times are have their Laplace transforms which are directly obtained from these two functions [19, 36].

In the case of piecewise constant coefficients, the minimal functions $\phi_{\pm}(\lambda; \cdot)$ and $\psi_{\pm}(\lambda; \cdot)$ are [28]:

$$\begin{aligned} \psi_{\pm}(\lambda; x) &= \exp\left(\left(-\gamma_{\pm} + \sqrt{\gamma_{\pm}^2 + 2\lambda}\right)x\right) \quad \text{for } x \in \mathbb{R} \\ \text{and } \phi_{\pm}(\lambda; x) &= \exp\left(\left(-\gamma_{\pm} - \sqrt{\gamma_{\pm}^2 + 2\lambda}\right)x\right) \quad \text{for } x \in \mathbb{R}. \end{aligned}$$

Notation 3.3. For $\lambda > 0$,

$$\begin{aligned}\lambda_- &= \sqrt{\gamma_-^2 + 2\lambda}, & \lambda_+ &= \sqrt{\gamma_+^2 + 2\lambda}, \\ \alpha_{-\ominus} &= -\gamma_- - \sqrt{\gamma_-^2 + 2\lambda} \leq 0, & \alpha_{-\oplus} &= -\gamma_- + \sqrt{\gamma_-^2 + 2\lambda} \geq 0, \\ \alpha_{+\ominus} &= -\gamma_+ - \sqrt{\gamma_+^2 + 2\lambda} \leq 0, & \alpha_{+\oplus} &= -\gamma_+ + \sqrt{\gamma_+^2 + 2\lambda} \geq 0.\end{aligned}$$

and

$$\begin{aligned}\Theta &= \alpha_{-\oplus} - \beta(\alpha_{+\oplus} + \alpha_{-\oplus}) = -\beta\alpha_{+\oplus} + (1 - \beta)\alpha_{-\oplus} > 0, \\ C_+ &= \frac{-\alpha_{-\oplus} + \beta(\alpha_{+\oplus} + \alpha_{-\oplus})}{\Theta} \geq -1 \text{ and } C_- = \frac{-\alpha_{-\ominus} + \beta(\alpha_{+\ominus} + \alpha_{-\ominus})}{\Theta} \geq -1.\end{aligned}$$

Remark 3.4. In $\alpha_{\pm, \cdot}$, the first sign stands for γ_- or γ_+ while the second (circled sign) is the one in front of $\sqrt{\gamma_{\pm}^2 + 2\lambda}$.

Applying theorem 3.1, we obtain the following formula for the Green kernel.

Proposition 3.1. *The resolvent kernel with respect to the Lebesgue measure of the diffusion process Z whose coefficients are given by (3.3) is for $y \geq 0$ and $\lambda \in \mathbb{C} \setminus (-\infty, 0)$,*

$$r(\lambda; x, y) = \begin{cases} 2\beta\Theta^{-1} \exp(-\alpha_{+\oplus}y + \alpha_{-\oplus}x) & \text{if } x < 0 \leq y, \\ \lambda_+^{-1} \times (\exp(\alpha_{+\oplus}x) + C_+ \exp(\alpha_{+\ominus}x)) \exp(-\alpha_{+\oplus}y) & \text{if } 0 \leq x \leq y, \\ \lambda_+^{-1} \times (\exp(-\alpha_{+\oplus}y) + C_+ \exp(-\alpha_{+\ominus}y)) \exp(\alpha_{+\oplus}x) & \text{if } 0 \leq y \leq x, \\ 2(1 - \beta)\Theta^{-1} \exp(-\alpha_{-\ominus}y + \alpha_{-\oplus}x) & \text{if } y < 0 \leq x, \\ \lambda_-^{-1} \times (\exp(\alpha_{-\ominus}x) + C_- \exp(\alpha_{-\oplus}x)) \exp(-\alpha_{-\ominus}y) & \text{if } y \leq x < 0, \\ \lambda_-^{-1} \times (\exp(-\alpha_{-\oplus}y) + C_- \exp(-\alpha_{-\ominus}y)) \exp(\alpha_{-\oplus}x) & \text{if } x \leq y < 0. \end{cases} \quad (3.4)$$

3.5 The GEARED algorithm to simulate the DSBM

Recall that, as shown above (see Algorithm 2), simulating X with coefficients $(a_{\pm}, \rho_{\pm}, b_{\pm})$ resolves itself to the simulation of $Y = \phi(X)$ where $\phi(x) = x/\sqrt{a(x)\rho(x)}$ and Y is the DSBM associated to the coefficients $\hat{\mathbf{a}}(\beta, \frac{b_+}{\sqrt{a_+\rho_+}}, \frac{b_-}{\sqrt{a_-\rho_-}})$.

So let us present the GEARED algorithm to simulate a process Z whose coefficients are

$$\hat{\mathbf{a}}(\beta, \gamma_+, \gamma_-) = ((1 - \beta) \boxtimes \beta, (1 - \beta)^{-1} \boxtimes \beta^{-1}, \gamma_- \boxtimes \gamma_+)$$

for $\beta \in (0, 1)$, $\gamma_+, \gamma_- \in \mathbb{R}$.

3.5.1 Expression of the resolvent kernel of the DSBM starting from x

First let us define the truncated exponential law.

Definition 3.1 (Truncated exponential law). *A random variable is said to follow a truncated exponential law on $[a, b]$, where $a \geq 0$ and $b \leq +\infty$, if it has the probability distribution function*

$$e_{a,b}(\lambda; y) dy = \mathbb{P}[\zeta \in dy \mid \zeta \in [a, b]] = \frac{\lambda e^{-\lambda y}}{e^{-\lambda a} - e^{-\lambda b}}, \quad \zeta \sim \mathcal{E}(\lambda).$$

Notation 3.4. We denote by $\mathcal{E}(\lambda)$ the exponential distribution of parameter λ .

We now detail how to simulate Z_ζ when $\zeta \sim \mathcal{E}(\lambda)$ and Z is a DSBM starting from x .

According to the formula (3.4), there are two expressions resolvent kernel of the DSBM Z_ζ , one regarding $x < 0$, the other $x > 0$.

If $x < 0$, the density $q = \lambda r(\lambda; x, \cdot) \mathbb{1}_{x < 0}$ of Z_ζ given $X_0 = x$, is:

$$q(y) = c_1^-(x) e_{0,+\infty}(\alpha_{+\oplus}; y) \mathbb{1}_{y \geq 0} + c_2^-(x) e_{-x,+\infty}(-\alpha_{-\ominus}; -y) \mathbb{1}_{y \leq x} \\ + (c_3^-(x) f_{0,-x}(\alpha_{-\oplus}; -y) + c_4^-(x) e_{0,-x}(-\alpha_{-\ominus}; -y)) \mathbb{1}_{x \leq y \leq 0} \quad (3.5)$$

where

$$c_1^-(x) = \frac{2\lambda\beta}{\Theta\alpha_{+\oplus}} e^{\alpha_{+\oplus}x}, \quad c_2^-(x) = \frac{-\lambda}{\alpha_{-\ominus}\lambda_-} (1 + C_- e^{2\lambda_-x}), \\ c_3^-(x) = \frac{\lambda}{\lambda_-} \frac{1 - e^{\alpha_{+\oplus}x}}{\alpha_{-\oplus}}, \quad c_4^-(x) = \frac{-\lambda}{\lambda_-} C_- \frac{e^{\alpha_{+\oplus}x} - e^{2\lambda_-x}}{\alpha_{-\ominus}}.$$

Similarly, when $x \geq 0$, the density q of Z_ζ given $Z_0 = x$ is

$$q(y) = c_1^+(x) e_{0,+\infty}(-\alpha_{-\ominus}; -y) \mathbb{1}_{y \leq 0} + c_2^+(x) e_{x,+\infty}(\alpha_{+\oplus}; y) \mathbb{1}_{y \geq x} \\ + (c_3^+(x) f_{0,x}(-\alpha_{+\oplus}; y) + c_4^+(x) e_{0,x}(\alpha_{+\oplus}; y)) \mathbb{1}_{0 < y < x} \quad (3.6)$$

where

$$c_1^+(x) = \frac{2\lambda(\beta - 1)}{\Theta\alpha_{-\ominus}} e^{\alpha_{+\oplus}x}, \quad c_2^+(x) = \frac{\lambda}{\alpha_{+\oplus}\lambda_+} (1 + C_+ e^{-2\lambda_+x}), \\ c_3^+(x) = \frac{\lambda}{\lambda_+} \frac{e^{\alpha_{+\oplus}x} - 1}{\alpha_{+\oplus}}, \quad c_4^+(x) = \frac{\lambda}{\lambda_+} C_+ \frac{e^{\alpha_{+\oplus}x} - e^{-2\lambda_+x}}{\alpha_{+\oplus}}.$$

Now we need algorithms for the simulation of random variables with density q .

3.5.2 Algorithms for the simulation of random variables

Let us first recall three elementary results on the simulation of random variables.

Lemma 3.1 ([13, Sect. II.4.1, p. 66]). *Let V be a random variable with density q . For some $m \geq 1$, let $c_1, \dots, c_m > 0$ and q_1, \dots, q_m be the densities of random variables $V_{[1]}, \dots, V_{[m]}$. We assume that*

$$q(y) = c_1 q_1(y) + \dots + c_m q_m(y). \quad (3.7)$$

Let $I \in \{1, \dots, m\}$ be a discrete random variable with $\mathbb{P}[I = i] = c_i$ (from (3.7), the c_i 's sum to 1), the random variable $V_{[I]}$ has the same law as V .

Lemma 3.2 (Acceptance-rejection, see e.g., [13, p. 42]). *Let V be a random variable whose density q satisfies*

$$q(y) = \frac{1}{1 - C} (q_1(y) - C q_2(y)) \text{ with } 0 < C < 1. \quad (3.8)$$

Then Algorithm 3 gives a realization of V .

Data: The densities q decomposed as (3.8).

Result: A random variate V with density q .

repeat

 Draw V according to q_1 ;

 Draw $U \in \mathcal{U}(0, 1)$;

until $Cq_2(V) \leq Uq_1(V)$;

return V .

Algorithm 3: Sampling V using a acceptance-rejection scheme.

Lemma 3.3. *If V has its support on $[a, b]$ with a density $q(y)$, then the density of $-V$ is $q(-y)$.*

To simulate the DSBM Z , we proceed in two steps.

If $x < 0$, following the expression of the density (3.5), when $C_- \geq 0$, a careful analysis of the signs of $c_i^-(x)$ shows that Lemma 3.1 could be applied using the densities

$$\begin{aligned} q_1^-(y) &= e_{0,+\infty}(\alpha_{+\oplus}; y)\mathbb{1}_{y \leq 0}, \quad q_2^-(y) = e_{-x,+\infty}(-\alpha_{-\ominus}; -y)\mathbb{1}_{y \geq x}, \\ q_3^-(y) &= f_{0,-x}(\alpha_{-\oplus}; -y)\mathbb{1}_{x \leq y \leq 0} \text{ and } q_4^-(y) = e_{0,-x}(-\alpha_{-\ominus}; -y)\mathbb{1}_{x \leq y \leq 0}. \end{aligned}$$

with the weights $c_1^-(x)$, $c_2^-(x)$, $c_3^-(x)$ and $c_4^-(x)$. While, when $C_- < 0$, Lemma 3.1 has to be applied using the densities

$$\begin{aligned} q_1^-(y) &= e_{0,+\infty}(\alpha_{+\oplus}; y)\mathbb{1}_{y \leq 0}, \quad q_2^-(y) = e_{-x,+\infty}(-\alpha_{-\ominus}; -y)\mathbb{1}_{y \geq x}, \\ q_{3,4}^-(y) &= f_{0,-x}(\alpha_{-\oplus}; -y) + \frac{c_4^-(x)}{c_3^-(x)}e_{0,-x}(-\alpha_{-\ominus}; -y)\mathbb{1}_{x \leq y \leq 0} \end{aligned}$$

and the weights $c_1^-(x)$, $c_2^-(x)$ and $c_3^-(x)(1 + c_4^-(x)/c_3^-(x))$. In this last case, we need Lemma 3.2 to deal with the simulation of random variables distributed according to the density $q_{3,4}^-$.

We have a similar situation to the case $x < 0$ for simulating the random variable with density $q(y)$ (3.6) as the sign of C_+ may be positive or negative. In particular, when $C_+ < 0$, Lemma 3.1 is applied to the densities

$$\begin{aligned} q_1^+(y) &= e_{0,+\infty}(-\alpha_{-\ominus}; -y)\mathbb{1}_{y \leq 0}, \quad q_2^+(y) = e_{x,+\infty}(\alpha_{+\oplus}; y)\mathbb{1}_{y \geq x}, \\ q_{3,4}^+(y) &= f_{0,x}(-\alpha_{+\oplus}; y) + \frac{c_4^+(x)}{c_3^+(x)}e_{0,x}(\alpha_{+\oplus}; y)\mathbb{1}_{x \leq y \leq 0}. \end{aligned}$$

and the weights $c_1^+(x)$, $c_2^+(x)$ and $c_3^+(x)(1 + c_4^+(x)/c_3^+(x))$.

A random variable V following the truncated exponential law on $[a, b]$ can be sampled by inverting its distribution function, that is

$$V = \frac{-1}{\lambda} \log(Ue^{-\lambda b} + (1-U)e^{-\lambda a}) \text{ with } U \sim \mathcal{U}(0, 1).$$

Hence, the variable V with density

$$f_{0,a}(\lambda; y) = \frac{\lambda e^{\lambda y}}{e^{\lambda a} - 1} \mathbb{1}_{y \in [0, a]}, \quad \lambda, a > 0$$

can be sampled using

$$V = \frac{1}{\lambda} \log(U(e^{\lambda a} - 1) + 1) \text{ with } U \sim \mathcal{U}(0, 1).$$

3.5.3 Full GEARED algorithm for the simulation of the DSBM

The densities q_i^\pm are easily simulated, *e.g.* by inverting their distribution functions. The densities $q_{3,4}^\pm$ are easily simulated through Algorithm 3. The whole simulation scheme is summed up in Algorithm 4.

Data: An initial position x at time 0 and a timestep $\Delta t > 0$.

Result: A position $y = Z_\zeta$ where $\zeta \sim \mathcal{E}(\Delta t^{-1})$. The position y is an approximation of $Z_{\Delta t}$.

Draw $U \sim \mathcal{U}(0, 1)$;

if $x < 0$ **then**

if $U < c_1^-(x)$ **then** Draw $y \sim e_{0,+\infty}(\alpha_{+\oplus}; \cdot)$;

else if $U < c_1^-(x) + c_2^-(x)$ **then**

Draw $y \sim e_{x,+\infty}(-\alpha_{-\ominus}; \cdot)$;

Set $y \leftarrow -y$;

else if $c_4^-(x) \geq 0$ **then**

if $U < c_1^-(x) + c_2^-(x) + c_3^-(x)$ **then**

Draw $y \sim f_{0,-x}(\alpha_{-\oplus}; \cdot)$;

else

Draw $y \sim e_{0,-x}(-\alpha_{-\ominus}; \cdot)$;

end

Set $y \leftarrow -y$;

else if $c_4^-(x) < 0$ **then**

Draw $y \sim q_{3,4}^-(y)$ according to Algorithm 3;

Set $y \leftarrow -y$;

end

else

if $U < c_1^+(x)$ **then** Draw $y \sim e_{0,+\infty}(-\alpha_{-\ominus}; \cdot)$;

Set $y \leftarrow -y$;

else if $U < c_1^+(x) + c_2^+(x)$ **then**

Draw $y \sim e_{x,+\infty}(\alpha_{+\oplus}; \cdot)$

else if $c_4^+(x) \geq 0$ **then**

if $U < c_1^+(x) + c_2^+(x) + c_3^+(x)$ **then**

Draw $y \sim f_{0,x}(-\alpha_{+\ominus}; \cdot)$;

else

Draw $y \sim e_{0,-x}(\alpha_{+\oplus}; \cdot)$;

end

else if $c_4^+(x) < 0$ **then**

Draw $y \sim q_{3,4}^+(y)$ according to Algorithm 3;

end

end

Algorithm 4: One-step of the GEARED algorithm for simulating the DSBM.

4 Numerical Experiments

In this section, we present the results of some numerical simulations. In Subsection 4.1, we provide some histograms of the density. In Subsection 4.2, we take profit from the knowledge of the distribution function of the position of the Skew Brownian motion to perform finer tests that show a good accuracy.

4.1 Numerical approximations of the densities

4.1.1 Histograms for Skew Brownian Motion SBM (case $\gamma_+ = \gamma_- = 0$)

First let us consider some experiments with the Skew Brownian Motion (SBM) which is a DSBM with zero drift (case $\gamma_+ = \gamma_- = 0$). In Figures 1 and 2, we compare the histogram obtained with the GEARED algorithm to the true density whose formula can be found *e.g.* in [30, 42].

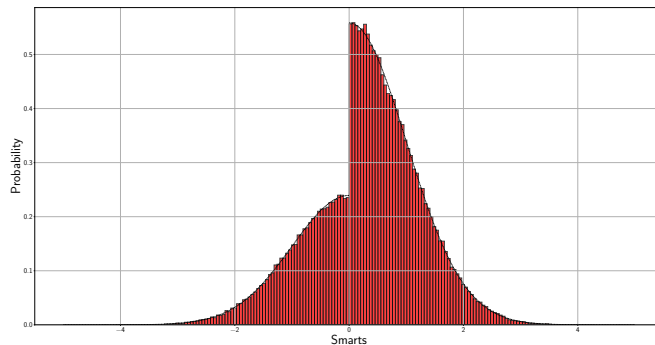


Figure 1: Histogram obtained with the GEARED algorithm using 250 000 samples of a SBM with parameters $\theta = 2\beta - 1 = 0.4$ ($\beta = 0.7$), $x = 0$, $T = 1.0$, $\Delta t = T/n$ and $n = 500$. Comparison with the true density (solid line).

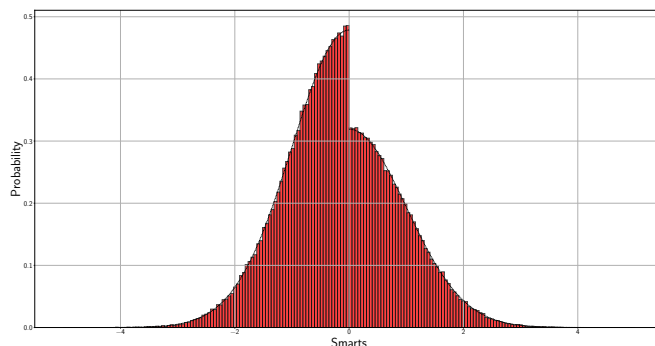


Figure 2: Histogram obtained with the GEARED algorithm using 250 000 samples of a SBM with parameters $\theta = 2\beta - 1 = -0.4$ ($\beta = 0.3$), $x = 0$, $T = 1.0$, $\Delta t = T/n$ and $n = 500$. Comparison with the true density (solid line).

4.1.2 Histograms for DSBM

In Figures 3 and 4, the density of the DSBM for several values of $\gamma_- = \gamma_+$ is given. Various situations could be obtained that show that the Gaussian approximation is not suitable. The density could even be bimodal in some situations. Explicit formula for the density could be found in [3, 16, 28].

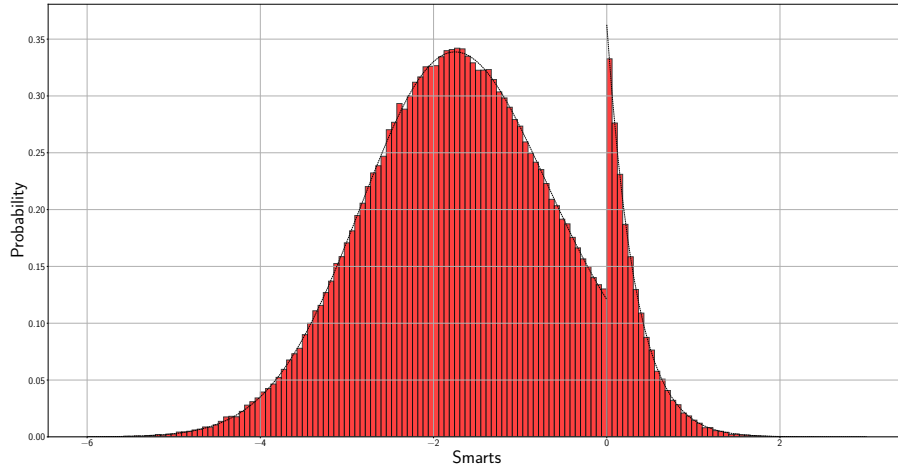


Figure 3: Histogram obtained with the GEARED algorithm using 250 000 samples of a DSBM with parameters $\theta = 2\beta - 1 = 0.5$ ($\beta = 0.75$), $\gamma_- = \gamma_+ = -2.0$, $x = 0$, $T = 1.0$, $\Delta t = T/n$ and $n = 500$. Comparison with the true density (solid line).

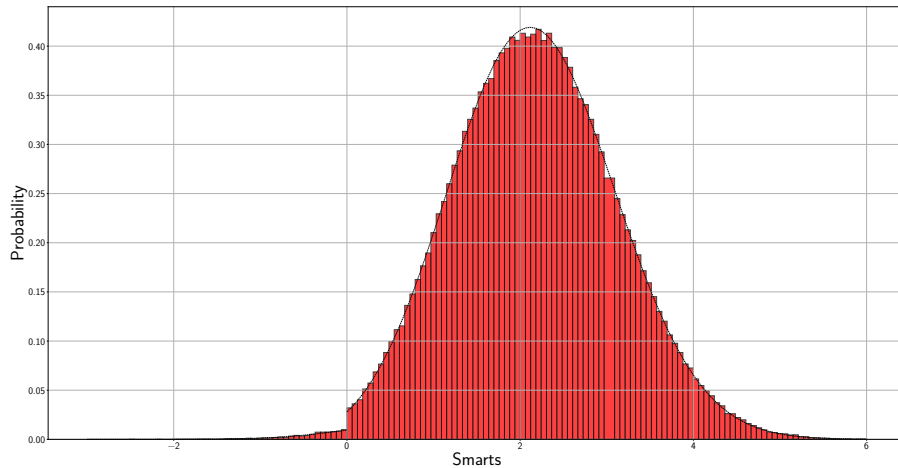


Figure 4: Histogram obtained with the GEARED algorithm using 250 000 samples of a DSBM with the parameters $\theta = 2\beta - 1 = 0.5$ ($\beta = 0.75$), $\gamma_- = \gamma_+ = 2.0$, $x = 0$, $T = 1.0$, $\Delta t = T/n$ and $n = 500$. Comparison with the true density (solid line).

4.1.3 Densities of some very irregular DSBM

In Figures 5 and 6, the density of the DSBM for several values of γ_- and γ_+ is represented. No explicit formula is known for the density although an explicit expression is known for the resolvent [28]. The non-Gaussian character is obvious.

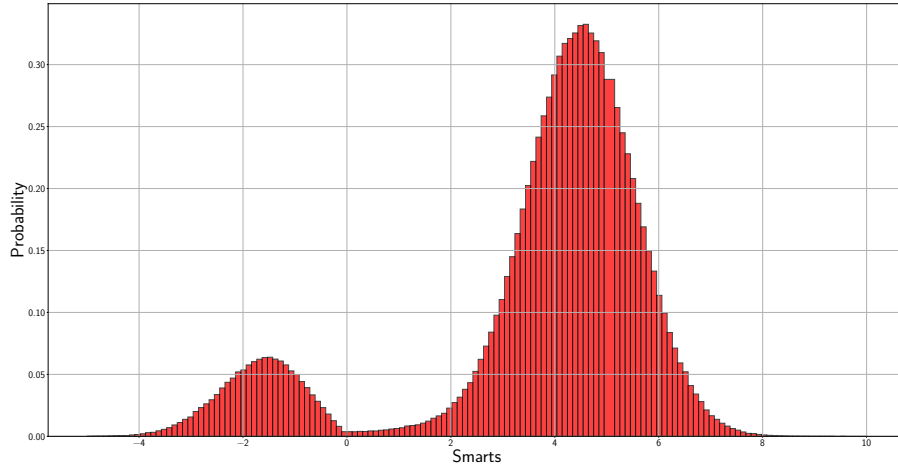


Figure 5: Histogram obtained with the GEARED algorithm using 1 000 000 samples of a DSBM with the parameters $\theta = 2\beta - 1 = 0.25$ ($\beta = 0.625$), $\gamma_- = -1.0$, $\gamma_+ = 4.5$, $x = 0$, $T = 1.0$, $\Delta t = T/n$ and $n = 500$.

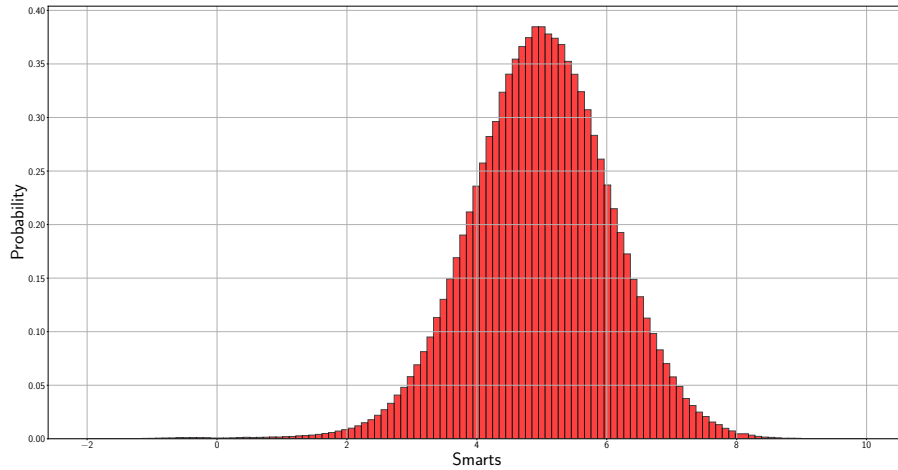


Figure 6: Histogram obtained with the GEARED algorithm using 1 000 000 samples of a DSBM with the parameters $\theta = 2\beta - 1 = 0.35$ ($\beta = 0.675$), $\gamma_- = 2.0$, $\gamma_+ = 5.0$, $x = 0$, $T = 1.0$, $\Delta t = T/n$ and $n = 500$.

4.2 Convergence and reliability

We present in this subsection some further numerical results to assess the quality of the GEARED algorithm.

4.2.1 Kolmogorov-Smirnov test

The Kolmogorov-Smirnov test allows one to test if an empirical distribution function follows a theoretical one. We use it to test whether or not the empirical density given by the scheme is close enough to the real one.

Unlike some particular cases discussed in [28], we have no tractable analytic expression of the density or the distribution of the marginal distribution of the DSBM in general when γ_+ or γ_- do not vanish. As a result, we consider only the case of a SBM X with a parameter $\theta = 2\beta - 1$ whose distribution function can easily be computed from the explicit expression of the density of the SBM (that is when $\gamma_+ = \gamma_- = 0$) [30, 42]

$$F_T(x) = \mathbb{P}[X_T \leq x] = \begin{cases} P(x - x_0, t) - \theta P(x - |x_0|, t) & \text{if } x < 0, \\ P(x - x_0, t) + \theta(P(x + |x_0|, t) - P(-|x_0|, t)) & \text{if } x \geq 0 \end{cases}$$

with $P(x, t) = \frac{1}{\sqrt{2\pi t}} \int_{-\infty}^x \exp\left(-\frac{y^2}{2t}\right) dy.$

Let us denote by $\overline{X}_T^{(n,i)}$ the position of the i -th particle at time T with N independent samples after n steps when the starting point is x_0 . Thanks to Proposition 2.3, the distribution of $\overline{X}_T^{(n,i)}$ is close to the one of X_T . This implies that the empirical distribution function of $\{\overline{X}_T^{(n,i)}\}_{i=1,\dots,N}$

$$F_T^{(n,1:N)}(x) = \frac{1}{N} \sum_{i=1}^N \mathbb{1}_{\overline{X}_T^{(n,i)} \leq x}, \quad x \in \mathbb{R},$$

is close to the distribution function $F_T(x) = \mathbb{P}[X_T \leq x]$ of X_T with $X_0 = x$.

In Figure 7, we plot the difference between $F_T^{(n,1:N)}$ and F_T on the left. Let $\{X_T^{(i)}\}_{i=1,\dots,N}$ be N independent samples of X_T .

Owing to the properties of the distribution functions, $\{F_T(X_T^{(i)})\}_{i=1,\dots,N}$ is distributed like $\{U^i\}_{i=1,\dots,N}$ for N independent samples of the uniform distribution over $[0, 1]$. If we denote by $G_T^{(N)}$ the empirical distribution function of $\{U^i\}_{i=1,\dots,N}$, then $x \mapsto \sqrt{N}(G_T^{(N)}(x) - x)$ converges as N tends to infinity to a Brownian bridge. Therefore, for each $x \in [0, 1]$, $\sqrt{N}(G_T^{(N)}(x) - x)$ looks like a Gaussian random variable with mean 0 and variance $x(1-x)$. A confidence band can thus be constructed this way.

The empirical distribution function of $\{F_T(\overline{X}_T^{(n,i)})\}_{i=1,\dots,N}$ is $F_T^{(n,1:N)} \circ F_T^{-1}$.

In Figure 7, we represent the scaled difference $D_{n,1:N} : x \in [0, 1] \mapsto \sqrt{N}((F_T^{(n,1:N)}) \circ F_T^{-1}(x) - x)$. The more this difference looks like a Brownian bridge B^{br} , the more accurate is the scheme. We see that after 100 steps, the scaled difference given by the sample cannot be distinguished from a Brownian bridge.

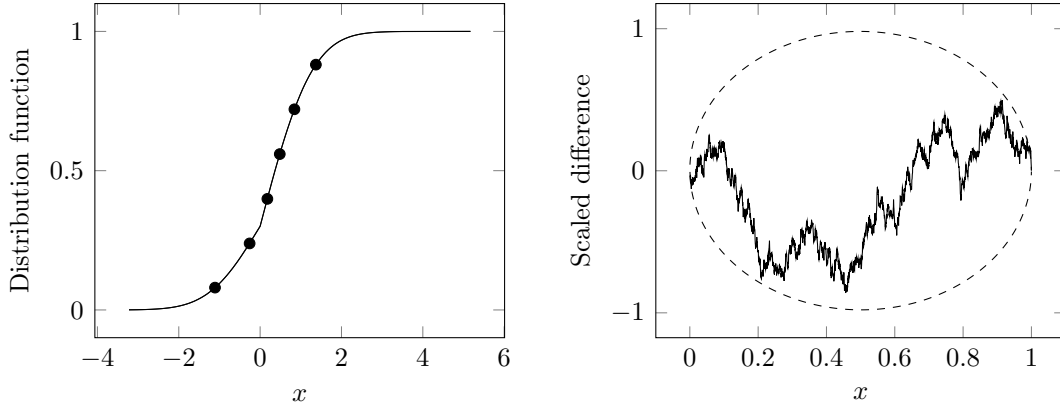


Figure 7: *Left:* The empirical distribution function $F_T^{(n,1:N)}$ of the positions $\{\bar{X}_T^{(n,i)}\}_{i=1,\dots,n}$ of the scheme after n steps (solid line) against the true distribution function (dots) using N samples. *Right:* Scaled difference $D_{n,1:N} : x \in [0, 1] \mapsto \sqrt{N}((F_T^{(n,1:N)}) \circ F(x) - x)$ and 95 %-confidence bands given by $x \mapsto \pm 1.95\sqrt{x(1-x)}$. *Parameters:* $\theta = 2\beta - 1 = 0.4$, $\gamma_+ = \gamma_- = 0$, $T = 1$, $X_0 = 0$, $N = 250\,000$ (number of particles) and $n = 100$ (number of steps).

The Kolmogorov-Smirnov statistics is the maximum of the absolute value of the scaled difference $|D_{n,1:N}(x)|$ for $x \in [0, 1]$. This statistics is compared with the maximum of the Brownian bridge. In Table 1, we give the value of $d = \max_{x \in [0,1]} |D_{n,1:N}(x)|$ in function of the number of steps n , as well as the p -value $\mathbb{P}[\max |B^{\text{br}}| > d]$ for a Brownian bridge B^{br} . This shows the good agreement of the distribution functions, even for only 100 steps.

4.3 Repartition of mass

As shown in [31], it seems to be crucial for the accuracy of the GEARED algorithm that the proportion of particles in a given zone (distribution of mass) is as accurate as possible, especially for application towards physics.

From its very construction, the mass on each side of the interface is preserved. We now consider the mass in a narrower zone J , which is nothing more than $m_J^n = \mathbb{P}[\bar{X}_T^{(n,1)} \in J]$. The latter quantity is approximated by $m_J^{n,1:N} = \frac{1}{N} \sum_{i=1}^N \mathbb{1}_{\bar{X}_T^{(n,i)} \in J}$. In Figure 8, we plot the estimation of the mass as well as confidence intervals constructed from Binomial distributions. Again, we find very good agreements even for only 100 steps.

4.4 Comparison between the Monte Carlo approximation and an approximated one

At last, for the DSBM, we compare the exact density computed through a numerical inversion of the Laplace transform with the one of the scheme given by composing the resolvent kernel n times as in (2.4). The latter quantity is computed by discretizing the integrals. Even for a small number of steps ($n = 30$), we see in Figure 9 that the density of the scheme converges quickly to the true density, even when the latter is discontinuous at 0.

n	distance d	p -value	distance d	p -value
	$\theta = 0.4$		$\theta = -0.2$	
100	0.0017	0.44	0.0023	0.13
150	0.0017	0.48	0.0028	0.04
200	0.0017	0.49	0.0016	0.58
250	0.0013	0.82	0.0018	0.42
300	0.0024	0.10	0.0015	0.64
350	0.0015	0.59	0.0013	0.76
400	0.0019	0.34	0.0020	0.26
450	0.0012	0.86	0.0028	0.05
500	0.0018	0.40	0.0018	0.40

Table 1: Kolmogorov-Smirnov statistics in function of the number n of steps. *Parameters:* $\theta = 2\beta - 1 \in \{0.4, -0.2\}$, $\gamma_+ = \gamma_- = 0$, $T = 1$, $X_0 = 0$, $N = 250\,000$ (number of particles) $X_0 = 0$ and n is the number of steps.

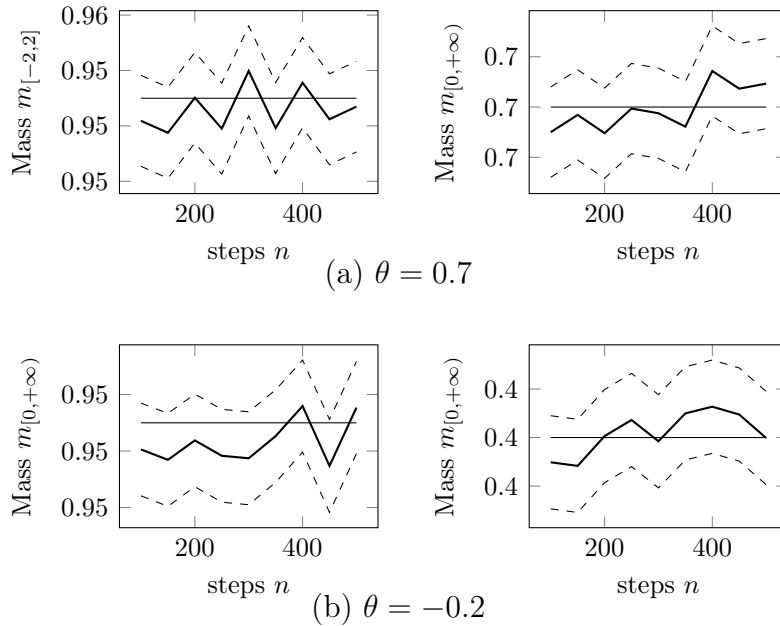


Figure 8: Estimation of the empirical probabilities $m_J^{n,1:N}$ for $J = [-2, 2]$ and $J = [0, +\infty)$ as a function of the number of steps n (solid), with a 95%-confidence interval, and comparison with the true value (horizontal line). *Parameters:* $\theta = 2\beta - 1 \in \{0.7, -0.2\}$, $\gamma_+ = \gamma_- = 0$, $T = 1$, $X_0 = 0$, $N = 250\,000$ (number of particles) and $n \in 100, 150, \dots, 500$ (number of steps).

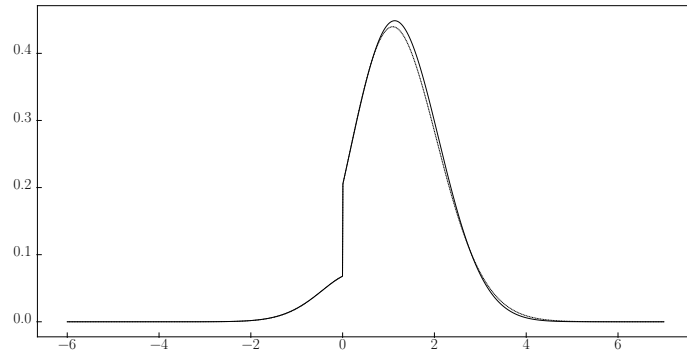


Figure 9: Exact density obtained by numerical Laplace inversion of the resolvent (solid) and density of the scheme obtained by composition the resolvent kernel n times (dashed). *Parameters:* $\theta = 2\beta - 1 = 0.5$, $\gamma_+ = \gamma_- = 1$, $T = 1$, $X_0 = 0$, and $n = 30$ (number of steps).

5 Conclusion

Often close form analytic expressions of the resolvent kernel of diffusion processes are easier to obtain than close form analytic expressions of the density. In that cases, the **GEARED** algorithm offers a very interesting alternative to simulate diffusion processes in media with discontinuous coefficients. We applied this algorithm to the case of piecewise constant coefficients since, in that case, the resolvent kernel has a simple and tractable expression. Numerical simulations showed a good fit of the simulated densities, a correct repartition of mass and a fast convergence to the true density. We are currently investigating the use of this algorithm in dimensions greater than 1 and in the case of diffusion of other nature.

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