

The non-linear sewing lemma I: weak formulation

Antoine Brault, Antoine Lejay

▶ To cite this version:

Antoine Brault, Antoine Lejay. The non-linear sewing lemma I: weak formulation. 2018. hal- 01716945v1

HAL Id: hal-01716945 https://inria.hal.science/hal-01716945v1

Preprint submitted on 25 Feb 2018 (v1), last revised 15 May 2019 (v5)

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

The non-linear sewing lemma I: weak formulation

Antoine Brault* Antoine Lejay[†]

February 25, 2018

We introduce a new framework to deal with rough differential equations based on flows and their approximations. Our main result is to prove that measurable flows exist under weak conditions, even solutions to the corresponding rough differential equations are not unique. We show that under additional conditions of the approximation, there exists a unique Lipschitz flow. Then, a perturbation formula is given. Finally, we link our approach to the additive, multiplicative sewing lemmas and the rough Euler scheme.

Keywords: rough paths; rough differential equations; non uniqueness of solutions; flow approximations; measurable flows; Lipschitz flows; sewing lemma.

1 Introduction

1.1 Motivations

The theory of rough paths allows one to define the solution to a differential equation of type

$$y_t = a + \int_0^t f(y_s) \, \mathrm{d}x_s,\tag{1}$$

^{*}Institut de Mathématiques de Toulouse, UMR 5219; Université de Toulouse, UPS IMT, F-31062 Toulouse Cedex 9, France; antoine.brault@math.univ-toulouse.fr

[†]Université de Lorraine, CNRS, Inria, IECL, F-54000 Nancy, France, antoine.lejay@univ-lorraine.fr

for a path x which is irregular, say α -Hölder continuous. Such an equation is then called a Rough Differential Equation (RDE) [19, 20, 24]. The key point of this theory is to show that such a solution can be defined provided that x is extended to a path \mathbf{x} , called a rough path, living in a larger space that depends on the integer part of $1/\alpha$. When $\alpha > 1/2$, no such extension is needed. This case is referred as the Young case, as the integrals are constructed in the sense given by L.C. Young [23, 27]. Provided that one considers a rough path, integrals and differential equations are natural extensions of ordinary ones.

The first proof of existence of a solution to (1) from T. Lyons relied on a fixed point [24, 25, 26]. It was quickly shown that RDE shares the same properties as ordinary differential equations, including the flow property. In [15], A.M. Davie gives an alternative proof that used an Euler type approximation and gave counter-example to uniqueness. More recently, I. Bailleul gave a direct construction through the flow property [3, 4, 6].

A flow in a metric space V is a family $\{\psi_{t,s}\}_{0 \leq s \leq t \leq T}$ of maps from V to V such that $\psi_{t,s} \circ \psi_{s,r} = \psi_{t,r}$ for any $0 \leq r \leq s \leq t \leq T$. When $y_t(s,a)$ is a family of solutions to differential equations with $y_s(s,a) = a$, the element $\psi_{t,s}(a)$ can be seen as a map which carries a to $y_t(s,a)$. A flow requires some compatibilities on the family of solutions so that solutions may exist although no flow may hold. Flow are related to dynamical systems. There are a slightly different objects than solutions. One of their interest lies in their characterization as lipeomorphims (Lipschitz functions with a Lipschitz inverse), diffeomorphisms...

In this article, we develop a generic framework to construct flows from approximations. We do not focus on a particular form of the solutions, so that our construction is a *non-linear sewing lemma*, modelled after the additive and multiplicative sewing lemmas [18].

In this first part, we study flows under weak conditions and prove existence of a measurable flow even when the solutions of RDE are not necessarily unique. Such a result is new in the literature where existence of flows were only proved under stronger regularity conditions (the many approaches are summarized in [14]). Besides, our approach also contains the additive and multiplicative sewing lemmas [12, 18]. The rough equivalent of the Duhamel formula for solving linear RDE [13] with a perturbative terms follows directly from our construction.

In a second part [9], we provide conditions for uniqueness and continuity. Besides, we show that our construction encompass many of the previous approaches or results: A.M. Davie [15], I. Bailleul [2, 3, 5], P. Friz & N. Victoir [20].

Our starting point in the world of classical analysis is the *product formula* which relates how the iterated product of an approximation of a flow converge to the flow [1, 11]. It is important both from the theoretical and numerical point of view.

On a Banach space V, let us consider a family $(\epsilon, a) \in \mathbb{R}_+ \times V \mapsto \Phi(\epsilon, a)$, called an algorithm of class \mathscr{C}^1 in (ϵ, a) such that $\Phi(0, a) = a$. The parameter ϵ is related to the quality of the approximation.

For a vector field f, let also ψ be a flow on V, by which we mean that map which associate to each a in V the solution $\psi_t(a) := y_t$ solution to the ODE $\dot{y}_t = f(y_t)$ for $t \ge 0$ with $y_0 = a$.

The algorithm Φ is *consistent* with the vector field when

$$f(a) = \frac{\partial \Phi}{\partial \epsilon}(0, a), \ \forall a \in V.$$
 (2)

Then

$$\underbrace{\Phi(t/n, \Phi(t/n, \dots \Phi(t/n, a)))}_{n \text{ times}} \text{ converges to } \phi_t(a) \text{ as } n \to \infty.$$
 (3)

The Euler scheme for solving ODE is the prototypical example of such behavior. Set $\Phi(\epsilon, a) = a + f(a)\epsilon$ so that (2) holds. In this case, (3) expresses nothing more than the convergence of the Euler scheme.

For example, one recovers easily the proof of Lie's theorem on matrices. For this, if A is a matrix, then $\exp(tA)$ is the solution to $\dot{Y}_t = AY_t$ with $Y_0 = \text{Id}$. The exponential $\exp(tA)$ is easily recovered as

$$\exp(tA) = \lim_{n \to \infty} \left(\operatorname{Id} + \frac{t}{n} A \right)^n.$$

For two matrices A and B, $\exp(t(A+B))$ is given by

$$\exp(t(A+B)) = \lim_{n\to\infty} \left(\exp\left(\frac{tA}{n}\right)\exp\left(\frac{tB}{n}\right)\right)^n.$$

For this, we have only to consider $\Phi(\epsilon, a) = \exp(\epsilon A) \exp(\epsilon B)a$ and to verify that $\partial_{\epsilon}\Phi(0, a) = (A + B)a$ for any matrix a.

For unbounded operators, it is also related to Chernoff and Trotter's results on the approximation of semi-groups [17, 28]. The product formula also justifies the construction of some splitting schemes [8].

In this article, we consider as an algorithm a family $\{\phi_{t,s}\}_{0 \leq s \leq t \leq T}$ of functions from V to V which is close to the identity map in short time and such that $\phi_{t,s} \circ \phi_{s,r}$ is close to $\phi_{t,r}$ for any time $s \leq r \leq t$. For a path x of finite p-variation, $1 \leq p < 2$ with values in \mathbb{R}^d and a smooth enough function $f: \mathbb{R}^m \to L(\mathbb{R}^d, \mathbb{R}^m)$, such an example is given by $\phi_{t,s}(a) = a + f(a)x_{s,t}$.

We then study the behavior of the composition ϕ^{π} of the ϕ_{t_{i+1},t_i} along a partition $\pi = \{t_i\}_{i=0,\dots,n}$. Clearly, as the mesh of the partition π goes to 0, the limit, when it exists is a candidate to be a flow. In the example given above, it will be the flow associated to the family of Young differential equations $y_t(a) = a + \int_0^t f(y_s(a)) dx_s$.

After having introduced some necessary notations (Section 1.2) including the central notion of galaxies (Section 1.2.3) which partition the space of families $\{\phi_{t,s}\}_{0 \leq s \leq t \leq T}$ of functions from a Banach space V to itself according to their proximity, we present the main results of our articles in 1.3

1.2 Notations, definitions and concepts

The following notations and hypotheses will be constantly used throughout all this article.

1.2.1 Hölder and Lipschitz continuous functions

Let V and W be two metric spaces.

The space of continuous functions from V to W is denoted by $\mathscr{C}(V, W)$.

Let d (resp. d') be a distance on V (resp. W). For $\gamma \in (0, 1]$, we say that a function $f: V \to W$ is γ -Hölder if

$$||f||_{\gamma} := \sup_{\substack{a,b \in \mathcal{V}, \\ a \neq b}} \frac{d'(f(a), f(b))}{d(a, b)^{\gamma}},$$

whenever this quantity is finite. If $\gamma = 1$ we say that f is Lipschitz. We then set $||f||_{\text{Lip}} := ||f||_1$.

For any integer $r \ge 0$ and $\gamma \in (0,1]$, we denote by $\mathscr{C}^{r+\gamma}(V,W)$ the subspace of functions from V to W whose derivatives $d^k f$ of order $k \le r$ are continuous and such that $d^r f$ is γ -Hölder.

We denote by $\mathscr{C}_{b}^{r+\gamma}(V,W)$ the subset of $\mathscr{C}^{r+\gamma}(V,W)$ of bounded functions with bounded derivatives up to order r.

1.2.2 Controls and remainders

From now, V is a topological, complete metric space with a distance d. A distinguished point of V is denoted by 0.

We fix $\gamma \in (0, 1]$. Let $N_{\gamma} : V \to [1, +\infty)$ be a γ -Hölder continuous function with constant $||N||_{\gamma}$. The indice γ in N_{γ} is refers to its regularity. If N_{γ} is Lipschitz continuous $(\gamma = 1)$, then we simply write N.

Let us fix a time horizon T. We write $\mathbb{T} := [0, T]$ as well as

$$\mathbb{T}_2^+ := \{ (s, t) \in \mathbb{T}^2 \mid s \leqslant t \} \text{ and } \mathbb{T}_3^+ := \{ (r, s, t) \in \mathbb{T}^3 \mid r \leqslant s \leqslant t \}.$$
 (4)

A control $\omega: \mathbb{T}_2^+ \to \mathbb{R}_+$ is a super-additive family, i.e.,

$$\omega_{r,s} + \omega_{s,t} \leq \omega_{r,t}, \ \forall (r,s,t) \in \mathbb{T}^3$$

which is continuous close to its diagonal with $\omega_{s,s} = 0$ for all $s \in \mathbb{T}$. A typical example of a control is $\omega_{s,t} = C|t-s|$ where C is a non-negative constant.

For $p \ge 1$, we say that a path $x \in \mathcal{C}(\mathbb{T}, \mathbb{V})$ is a path of finite p-variation controlled by ω if

$$||x||_p := \sup_{\substack{(s,t) \in \mathbb{T}_2^+, \\ s \neq t}} \frac{d(x_s, x_t)}{\omega_{s,t}^{1/p}} < +\infty.$$

A remainder is a function $\varpi : \mathbb{R}_+ \to \mathbb{R}_+$ be a continuous, increasing function such that for some $0 < \varkappa < 1$,

$$2\varpi\left(\frac{\delta}{2}\right) \leqslant \varkappa\varpi(\delta), \ \forall \delta > 0. \tag{5}$$

A typical example for a remainder is $\varpi(\delta) = \delta^{\theta}$ for any $\theta > 1$.

We consider that $\delta: \mathbb{R}_+ \to \mathbb{R}_+$ is a non-decreasing function with $\lim_{T\to 0} \delta_T = 0$.

Finally, let $\eta: \mathbb{R}_+ \to \mathbb{R}_+$ be a continuous, increasing function such that for all $(s,t) \in \mathbb{T}_2^+$,

$$\eta(\omega_{s,t})\varpi(\omega_{s,t})^{\gamma} \leqslant \delta_T \varpi(\omega_{s,t}).$$
(6)

Partitions of \mathbb{T} are customary denoted by $\pi = \{t_i\}_{i=0,\dots,n}$. The mesh $|\pi|$ of a partition π is $|\pi| := \max_{i=0,\dots,n} (t_{i+1} - t_i)$. The discrete simplices π_2^+ and π_3^+ are defined similarly to \mathbb{T}_2^+ and \mathbb{T}_3^+ in (4).

1.2.3 Galaxies

Notation 1. We denote by $\mathcal{F}(V)$ the set of functions $\{\phi_{t,s}\}_{(s,t)\in\mathbb{T}_2^+}$ from V to V which are continuous in (s,t), i.e. for any $a\in V$, the map $(s,t)\in\mathbb{T}_2^+\mapsto\phi_{t,s}(a)$ is continuous.

Notation 2 (Iterated products). For any $\phi \in \mathcal{F}(V)$, any partition π of \mathbb{T} and any $(s,t) \in \mathbb{T}_2^+$, we write

$$\phi_{t,s}^{\pi} := \phi_{t,t_i} \circ \phi_{t_i,t_{i-1}} \circ \cdots \circ \phi_{t_{i+1},t_i} \circ \phi_{t_i,s}, \tag{7}$$

where $[t_i, t_j]$ is the biggest interval of such kind contained in $[s, t] \subset \mathbb{T}$. If no such interval exists, then $\phi_{t,s}^{\pi} = \phi_{t,s}$.

Clearly, for any partition, $\phi^{\pi} \in \mathcal{F}(V)$. A trivial but important remark is that from the very construction,

$$\phi_{t,r}^{\pi} = \phi_{t,s}^{\pi} \circ \phi_{s,r}^{\pi} \text{ for any } s \in \pi, \ r \leqslant s \leqslant t.$$
 (8)

In particular, $\{\phi_{t,s}^{\pi}\}_{(s,t)\in\pi_{+}^{2}}$ enjoys a (semi-)flow property when the times are restricted to the elements of π .

The article is mainly devoted to study the possible limits of ϕ^{π} as the mesh of π decreases to 0.

Notation 3. From a distance d on V, we define the distance $\Delta_{N_{\gamma}}$ on the space of functions from V to V by

$$\Delta_{N_{\gamma}}(f,g) := \sup_{a \in V} \frac{d(f(a), g(a))}{N_{\gamma}(a)},$$

where N_{γ} is defined in Section 1.2.

This distance is extended on $\mathcal{F}(V)$ by

$$\Delta_{N_{\gamma},\varpi}(\phi,\psi) := \sup_{\substack{(s,t) \in \mathbb{T}_2^+ \\ s \neq t}} \frac{\Delta_{N_{\gamma}}(\phi_{t,s}, \psi_{t,s})}{\varpi(\omega_{s,t})},$$

where ω , ϖ are defined in Section 1.2. The distance $\Delta_{N_{\gamma},\varpi}$ may take infinite values.

If d is a distance for which (V, d) is complete, then $(\mathscr{C}(V, V), \Delta_N)$ and $(\mathscr{F}(V), \Delta_{N,\varpi})$ are complete.

Definition 1 (Galaxy). We define the equivalence relation \sim on $\mathcal{F}(V)$ by $\phi \sim \psi$ if and only if there exists a constant C such that

$$d(\phi_{t,s}(a), \psi_{t,s}(a)) \leq CN_{\gamma}(a)\varpi(\omega_{s,t}), \ \forall a \in V, \ \forall (s,t) \in \mathbb{T}_2^+.$$

In other words, $\phi \sim \psi$ if and only if $\Delta_{N_{\gamma},\varpi}(\phi,\psi) < +\infty$. Each quotient class of $\mathcal{F}(V)/\sim$ is called a *galaxy*, which contains elements of $\mathcal{F}(V)$ which are at finite distance from each others.

1.3 Summary of the main results

The galaxies partition the space $\mathcal{F}(V)$. Each galaxy may contain two classes of elements on which we focus on this article:

1. The flows, that is the families ψ which satisfy

$$\psi_{t,r} = \psi_{t,s} \circ \psi_{s,r} \tag{9}$$

for any $(r, s, t) \in \mathbb{T}_3^+$, or equivalently, $\psi^{\pi} = \psi$ (See (7)) for any partition π .

2. The almost flows which we see as time-inhomogeneous algorithms. Besides some conditions on the continuity and the growth given in Definition 2 below, an almost flow ϕ is close to a flow with the difference that

$$d(\phi_{t,s} \circ \phi_{s,r}(a), \phi_{t,r}(a)) \leqslant N_{\gamma}(a)\varpi(\omega_{r,t}), \ \forall (r,s,t) \in \mathbb{T}_3^+, \ a \in V,$$

for a suitable function $N_{\gamma}: V \to [1, +\infty)$.

Along with an almost flow ϕ comes the notion of manifold of solutions, that is a family $\{y_t(a)\}_{t\geq 0,\ a\in V}$ of paths such that

$$d(y_t(a), \phi_{t,s}(y_s(a))) \leq C\varpi(\omega_{s,t}), \ \forall (s,t) \in \mathbb{T}_2^+.$$

Each path y(a) is a solution which we called *solution in the sense of Davie* as our definition expands naturally the one introduced by A.M. Davie in [15].

Clearly, a manifold of solutions associated to an almost flow ϕ is also associated to any almost flow in the same galaxy as ϕ . Besides, if a flow ψ exists in the same galaxy as ϕ , then $z_t(a) = \psi_{t,0}(a)$ defines a manifold of solutions. Flows are more constrained object than solutions as (9) implies some compatibility conditions, while it is possible to create new paths of solutions from two different ones. As it will be shown in [9], uniqueness of manifold of solutions is strongly related to existence of a flow.

Given an almost flow ϕ , it is natural to study the limit of the net $\{\phi^{\pi}\}_{\pi}$ as the mesh of π decreases to 0. Any limit will be a good candidate to be a flow.

Our first main result (Theorem 1) asserts that if ϕ is an almost flow in a galaxy G, then any iterated map ϕ^{π} belongs to G whatever the partition π although the map ϕ^{π} is not necessarily an almost flow. More precisely, a control is given on $\Delta_{N_{\gamma},\varpi}(\phi^{\pi},\phi)$ which is uniform in the partition π .

An immediate corollary is that any possible limit of $\{\phi^{\pi}\}_{\pi}$ also belongs to G as the mesh of the partition decreases to 0.

Our second main result (Theorem 2) is that when the underlying Banach space V is finite-dimensional for compactness reasons, there exists a least one measurable

flow in a galaxy containing an almost flow, even when several manifold of solutions may exists.

Our third results is to give conditions ensuring the existence of at most one flow in a galaxy. If the sufficient for this that a galaxy G contains a Lipschitz flow ψ . In this case, $\{\phi^{\pi}\}_{\pi}$ converges to ψ whatever the almost flow ϕ in G. The rate of convergence is also quantified.

Finally, we apply our results to the additive, multiplicative sewing lemmas [18] as well as to the algorithms proposed by A.M. Davie in [15] to show existence of measurable flows even without uniqueness. In the sequel [9], we study in details the properties of Lipschitz flows and give some conditions on almost Lipschitz flows to generate them. In addition, we also apply our results to other approximations of RDE, namely the one proposed by P. Friz & N. Victoir [20] and the one proposed by I. Bailleul [3] by using perturbation arguments.

1.4 Outline

We show in Section 2 that a uniform control of the iterated product of approximation of flows with respect to the subdivision. In Section 3, we prove our main result: the existence of a measurable flow under weak conditions of regularity. Then, in Section 4 we show the existence and uniqueness of a Lipschitz flow under stronger assumptions. Moreover, we give a rate of the convergence of the iterated product to the flow. In Section 5, we show that the convergence of the iterated product of an approximation of flow is preserved under the action of a additive perturbation. Finally, we recover in Section 6 the additive [25], multiplicative [13, 18] and Davie's sewing lemmas [15].

2 A uniform control over almost flows

In this section, we define almost flows which serves as approximations. The properties of an almost flow ϕ are weaker than the minimal condition to obtain the convergence of the iterated products ϕ^{π} as the mesh of the partitions π decreases to 0. However, we prove in Theorem 1 that we can control ϕ^{π} uniformly over the partitions π . This justifies our definition.

2.1 Definition of almost flows

Definition 2 (Almost flow). An element $\phi \in \mathcal{F}(V)$ is an *almost flow* if for any $(r, s, t) \in \mathbb{T}_3^+$, $a \in V$,

$$\phi_{t,t}(a) = a,\tag{10}$$

$$d(\phi_{t,s}(a), a) \leqslant \delta_T N_{\gamma}(a), \tag{11}$$

$$d(\phi_{t,s}(a), \phi_{t,s}(b)) \leqslant (1 + \delta_T)d(a,b) + \eta(\omega_{s,t})d(a,b)^{\gamma}, \tag{12}$$

$$d(\phi_{t,s} \circ \phi_{s,r}(a), \phi_{t,r}(a)) \leq N_{\gamma}(a) \varpi(\omega_{r,t}). \tag{13}$$

Remark 1. A family $\phi \in \mathcal{F}(V)$ satisfying condition (12) with $\gamma = 1$ is said to be quasi-contractive. This notion plays an important role in the fixed point theory [7].

Definition 3 (Iterated almost flow). For a partition π and an almost flow ϕ , we call ϕ^{π} an *iterated almost flows*, where ϕ^{π} is the iterated product defined in (7).

Definition 4 (A flow). A flow ψ is a family of functions $\{\psi_{t,s}\}_{(s,t)\in\mathbb{T}_2^+}$ from V to V (not necessarily continuous in (s,t)) such that $\phi_{t,t}(a)=a$ and $\psi_{t,s}\circ\psi_{s,r}(a)=\psi_{t,r}(a)$ for any $a\in V$ and $(r,s,t)\in\mathbb{T}_3^+$.

2.2 A uniform control on iterated almost flows

Before proving our main result in Section 3, we prove an important uniform control over ϕ^{π} .

Theorem 1. Let ϕ be an almost flow. Then there exists a time horizon T small enough and a constant $L_T \geqslant 1$ as well as a constant $K_T \geqslant 1$ that decreases to 1 as T decreases to 0 such that

$$d(\phi_{t,s}^{\pi}(a), \phi_{t,s}(a)) \leqslant L_T N_{\gamma}(a) \varpi(\omega_{s,t}), \tag{14}$$

$$N_{\gamma}(\phi_{ts}^{\pi}(a)) \leqslant K_T N_{\gamma}(a), \tag{15}$$

for any $(s,t) \in \mathbb{T}^2_+$, $a \in V$ and any partition π of \mathbb{T} .

Remark 2. The distance d may be replaced by a pseudo-distance in the statement of Theorem 1.

The proof of Theorem 1 is inspired by the one of the Claim in the proof of Lemma 2.4 in [15]. With respect to the one of A.M. Davie, we consider obtaining a uniform control over a family of elements indiced by $(s,t) \in \mathbb{T}_2^+$ which are also parametrized by points in V.

Definition 5 (Successive points / distance between two points). Let π be a partition of [0,T]. Two points s and t of π are said to be at distance k if there are exactly k-1 points between them in π . We write $d_{\pi}(t,s)=k$. Points at distance 1 are called successive points in π .

Proof. For $a \in V$, $(r,t) \in \mathbb{T}_2^+$ and a partition π , we set

$$U_{r,t}(a) := d(\phi_{t,r}^{\pi}(a), \phi_{t,r}(a)).$$

We now restrict ourselves to the case $(r,t) \in \pi_2^+$. To control $U_{r,t}(a)$ in a way that does not depend on π , we use an induction in the distance between r and t.

Our induction hypothesis is that there exist constants $L_T \ge 0$ and $K_T \ge 1$ independent from the partition π such that for any $(r,t) \in \pi_2^+$ at distance at most $m \ge 1$,

$$U_{r,t}(a) \leqslant L_T N_{\gamma}(a) \varpi(\omega_{r,t}),$$
 (16)

$$N_{\gamma}(\phi_{t,s}^{\pi}(a)) \leqslant K_T N_{\gamma}(a), \tag{17}$$

with K_T decreases to 1 at T goes to 0.

If r and t are successive points, $\phi_{t,r}^{\pi} = \phi_{t,r}$ so that $U_{r,t}(a) = 0$. Thus, (16) is true for m = 1. With (11) and since $N_{\gamma}(a)^{\gamma} \leq N_{\gamma}(a)$ as $N_{\gamma}(a) \geq 1$ by hypothesis,

$$N_{\gamma}(\phi_{t,s}(a)) \leqslant N_{\gamma}(\phi_{t,s}(a)) - N_{\gamma}(a) + N_{\gamma}(a) \leqslant \|N_{\gamma}\|_{\gamma} d(\phi_{t,s}(a), a)^{\gamma} + N_{\gamma}(a)$$
$$\leqslant \|N_{\gamma}\|_{\gamma} \delta_{T}^{\gamma} N_{\gamma}(a)^{\gamma} + N_{\gamma}(a) \leqslant (\|N_{\gamma}\|_{\gamma} \delta_{T}^{\gamma} + 1) N_{\gamma}(a).$$

For m=2, it is also true with $L_T=1$ as $U_{r,t}(a)=d(\phi_{t,s}\circ\phi_{s,r}(a),\phi_{t,r}(a))$ where s is the point in the middle of r and t. This proves (16).

In addition, using (16),

$$N_{\gamma}(\phi_{t,s}^{\pi}(a)) \leq ||N||_{\gamma} d(\phi_{t,s}^{\pi}(a), \phi_{t,s}(a))^{\gamma} + N_{\gamma}(\phi_{t,s}(a)) - N_{\gamma}(a) + N_{\gamma}(a)$$

$$\leq K_{T} N_{\gamma}(a) \text{ with } K_{T} := ||N||_{\gamma} \varpi(\omega_{0,T})^{\gamma} + ||N_{\gamma}||_{\gamma} \delta_{T}^{\gamma} + 1. \quad (18)$$

Clearly, K_T decreases to 1 at T decreases to 0. This proves (17) whenever (16), in particular for m = 1.

Assume that that (16)-(17) when the distance between r and t is smaller than m for some $m \ge 2$.

For $s \in \pi$, $r \leqslant s \leqslant t$, with (8),

$$U_{r,t}(a) \leq d(\phi_{t,s}^{\pi} \circ \phi_{s,r}^{\pi}(a), \phi_{t,s} \circ \phi_{s,r}^{\pi}(a)) + d(\phi_{t,s} \circ \phi_{s,r}^{\pi}(a), \phi_{t,s} \circ \phi_{s,r}(a)) + d(\phi_{t,s} \circ \phi_{s,r}(a), \phi_{t,r}(a)).$$

With (12) and (13),

$$U_{r,t}(a) \leq U_{s,t}(\phi_{s,r}^{\pi}(a)) + (1 + \delta_T)U_{r,s}(a) + \eta(\omega_{s,t})U_{r,s}(a)^{\gamma} + N_{\gamma}(a)\varpi(\omega_{r,t}).$$
 (19)

Using (19) on $U_{s,t}(\phi_{s,r}^{\pi}(a))$ by replacing (r, s, t) by (s, s', t), where s and s' are two successive points of π leads to

$$U_{s,t}(\phi_{s,r}^{\pi}(a)) \leqslant U_{s',t}(\phi_{s',r}^{\pi}(a)) + N_{\gamma}(\phi_{s,r}^{\pi}(a)) \overline{\omega}(\omega_{s,t})$$

since $\phi_{s',s} \circ \phi_{s,r}^{\pi}(a) = \phi_{s',r}^{\pi}(a)$ and $U_{s,s'}(a) = 0$.

With (16)-(17) and our hypothesis on η , again since $N_{\gamma} \ge 1$ and s, s' are at distance less than m provided that s is at distance at most 2 from t,

$$U_{r,t}(a) \leqslant N_{\gamma}(a) \left(K_T L_T \varpi(\omega_{s',t}) + (L_T + \delta_T (1 + L_T^{\gamma})) \varpi(\omega_{r,s}) + (1 + K_T) \varpi(\omega_{r,t}) \right).$$

$$(20)$$

Since ω is super-additive, one may choose two successive points s and s' in π with r < s < s' < t such that

$$\omega_{r,s} \leqslant \frac{\omega_{r,t}}{2} \text{ and } \omega_{s',t} \leqslant \frac{\omega_{r,t}}{2}.$$
 (21)

With such a choice, (20) becomes with (5) and since $L_T \ge 1$,

$$U_{r,t}(a) \leqslant \left(L_T \frac{K_T + 1 + 2\delta_T}{2} \varkappa + 1 + K_T\right) N_{\gamma}(a) \varpi(\omega_{r,t}).$$

If T is small enough so that

$$\alpha := \frac{1 + K_T + 2\delta_T}{2} \varkappa < 1 \text{ and } L_T \alpha + 1 + K_T \leqslant L_T,$$

then one may choose L_T so that $L_T\alpha + 1 + K_T \leq L_T$, that is $L_T \geq \max\{1, (1 + K_T)/(1-\alpha)\}$. This choice ensures that $U_{r,t}(a) \leq L_T N_{\gamma}(a) \varpi(\omega_{r,t})$ when r and t are at distance m. Condition (17) follows from (18) and (16).

The choice of T, K_T and L_T does not depend on π . In particular, $d(\phi_{t,s}^{\pi}(a), \phi_{t,s}(a)) \leq L_T N_{\gamma}(a) \varpi(\omega_{s,t})$ becomes true for any $(s,t) \in \mathbb{T}_2^+$, is it is sufficient to add the points s and t to π .

Corollary 1. Let ϕ be an almost flow and π be a partition of \mathbb{T} . Then $\phi^{\pi} \sim \phi$ (we have not proved that ϕ^{π} is itself an almost flow).

Notation 4. For an almost flow ϕ , let us denote by $S_{\phi}(s, a)$ the set of all the possible limits of the net $\{\phi_{\cdot,s}^{\pi}(a)\}_{\pi}$ in $(\mathscr{C}([s,T],V),\|\cdot\|_{\infty})$ for nested partitions.

When V is a finite dimensional space with the norm $|\cdot|$, $S_{\phi}(s, a) \neq \emptyset$. We start with a lemma which will be useful to prove some equi-continuity. We denote $\bar{B}(0, R)$ the closed ball center in 0 of radius R > 0.

Lemma 1. We assume that V is a finite dimensional vector space and ϕ is an almost flow. Then, for all $\epsilon > 0$ there exists $\delta > 0$ such that for all $(s,t), (s',t') \in \mathbb{T}_2^+$ with $|t-t'|, |s-s'| < \delta$ and $a \in \bar{B}(0,R)$,

$$|\phi_{t,s}(a) - \phi_{t',s'}(a)| \leq \epsilon.$$

Proof. In all the proof $(s,t), (s',t') \in \mathbb{T}_2^+$. For any $a \in \bar{B}(0,R), (s,t) \in \mathbb{T}_2^+ \mapsto \phi_{t,s}(a)$ is continuous, so uniformly continuous on the compact \mathbb{T}_2^+ . Let $\epsilon > 0$, there is δ_a such that for all $|t-t'|, |s-s'| < \delta_a$,

$$|\phi_{t,s}(a) - \phi_{t',s'}(a)| \leqslant \frac{\epsilon}{3}.$$
 (22)

For a $\rho > 0$ with (12), for all $b \in B(a, \rho)$,

$$|\phi_{t,s}(a) - \phi_{t,s}(b)| \leq (1 + \delta_T)\rho + \eta(\omega_{0,T})\rho^{\gamma},$$

where $B(a, \rho)$ denotes the open ball centred in a of radius ρ . We choose $\rho(\epsilon) > 0$ such that $(1 + \delta_T)\rho(\epsilon) + \eta(\omega_{0,T})\rho(\epsilon)^{\gamma} \leq \epsilon/3$ to obtain for all $b \in B(a, \rho(\epsilon))$,

$$|\phi_{t,s}(a) - \phi_{t,s}(b)| \leqslant \frac{\epsilon}{3}.$$
 (23)

We note that $\bigcup_{a\in \bar{B}(0,R)} B(a,\rho(\epsilon))$ is a covering of $\bar{B}(0,R)$ which is a compact of V. There exist an integer N and a finite family of balls $B(a_i,\rho(\epsilon))$ for $i\in\{1,\ldots,N\}$ such that $\bar{B}(0,R)\subset\bigcup_{i\in\{1,\ldots,N\}} B(a_i,\rho(\epsilon))$.

It follows that for all $b \in \overline{B}(0, R)$ there exists $i \in \{1, ..., N\}$ such that $b \in B(a_i, \rho(\epsilon))$. From (22)-(23) there exists $\delta_{a_i} > 0$ such that for all $|t - t'|, |s - s'| < \delta_{a_i}$,

$$|\phi_{t,s}(b) - \phi_{t',s'}(b)| \leq \epsilon.$$

Taking $\delta := \min_{i \in \{1,\dots,N\}} \delta_{a_i}$, we obtain that for all $|t-t'|, |s-s'| < \delta$ and $b \in \bar{B}(0,R)$,

$$|\phi_{t,s}(b) - \phi_{t',s'}(b)| \leqslant \epsilon,$$

which achieves the proof.

Proposition 1. Assume that V is finite-dimensional and that ϕ is an almost flow. Then $S_{\phi}(r, a)$ is not empty for any $(r, a) \in \mathbb{T} \times V$.

Proof. Let us show for an almost flow ϕ , $\{\phi_{\cdot,r}^{\pi}(a)\}_{\pi}$ is equi-continuous and bounded. The result is then a direct consequence of the Ascoli-Arzelà theorem.

Let $(\pi_n)_{n\in\mathbb{N}}$ be an increasing sequence of partition of \mathbb{T} such that $|\pi_n| \to 0$ when $n \to +\infty$ and $\bigcup_{n\in\mathbb{N}} \pi_n$ dense in \mathbb{T} . Let R > 0 and $R' := N_{\gamma}(R)(L_T\varpi(\omega_{0,T}) + \delta_T) + R$. From Theorem 1, for any $a \in \bar{B}(0,R)$ and $(s,t) \in \mathbb{T}_2^+$,

$$|\phi_{t,s}^{\pi_n}(a)| \leq |\phi_{t,s}^{\pi_n}(a) - \phi_{t,s}(a)| + |\phi_{t,s}(a) - a| + |a|$$

$$\leq N_{\gamma}(a)(L_T\varpi(\omega_{0,T}) + \delta_T) + |a| \leq R'.$$

Let $(r, s, t) \in \mathbb{T}_3^+$ and $s, t \in \bigcap_{n \in \mathbb{N}} \pi_n$, let $\epsilon > 0$ and $\delta > 0$ given by Lemma 1 for $\epsilon/2$. For $|t - s| < \delta$, let m an integer such that $s, t \in \pi_m$.

We differentiate two cases. If $m \leq n$, then $\pi_m \subset \pi_n$, which implies that $\phi_{t,r}^{\pi_n} = \phi_{t,s}^{\pi_n} \circ \phi_{s,r}^{\pi_n}$. From Theorem 1 and Lemma 1, for all $a \in \bar{B}(0,R)$, for all $|t-s| < \delta$

$$|\phi_{t,r}^{\pi_n}(a) - \phi_{s,r}^{\pi_n}(a)| \leq |\phi_{t,s}^{\pi_n} \circ \phi_{s,r}^{\pi_n}(a) - \phi_{s,r}^{\pi_n}(a)| \leq \frac{\epsilon}{2} + L_T N_{\gamma}(\phi_{s,r}^{\pi_n}(a)) \varpi(\omega_{s,t}).$$

Since, $\omega_{s,s} = 0$ and ω is continuous close to diagonal, there exists $\delta' > 0$ such that for all $|t - s| < \delta'$, $L_T N_{\gamma}(\phi_{s,r}^{\pi_n}(a)) \varpi(\omega_{s,t}) < \epsilon/2$. Thus for all $|t - s| < \min(\delta, \delta')$, $|\phi_{t,r}^{\pi_n}(a) - \phi_{s,r}^{\pi_n}(a)| \leq \epsilon$.

In the case m > n, let s_-, s_+ be successive points in π_n such that $[s, t] \in \subset [s_-, s_+]$. Then, $\phi_{t,r}^{\pi_n}(a) = \phi_{t,s_-} \circ \phi_{s_-,r}^{\pi_n}(a)$ and $\phi_{s,r}^{\pi_n}(a) = \phi_{s,s_-} \circ \phi_{s_-,r}^{\pi_n}(a)$. According to Lemma 1, for $|t-s| < \delta$ with $s, t \in \pi_m$, and all $a \in \bar{B}(0, R)$,

$$|\phi_{t,r}^{\pi_n}(a) - \phi_{s,r}^{\pi_n}(a)| = |\phi_{t,s_-} \circ \phi_{s_-,r}^{\pi_n}(a) - \phi_{s,s_-} \circ \phi_{s_-,r}^{\pi_n}(a)| \leqslant \epsilon.$$
 (24)

By continuity of $t \mapsto \phi_{t,r}^{\pi_n}(a)$, and density of $\bigcap_{m \in \mathbb{N}} \pi_m$ in \mathbb{T} , we obtain (24) for all $(s,t) \in \mathbb{T}_2^+$ with $r \leq s$ and $|t-s| < \delta$. This proves that $\{t \mapsto \phi_{t,r}^{\pi_n}(a)\}_n$ is uniformly equicontinuous for all $a \in V$. We conclude the proof with the Ascoli-Arzelà theorem.

3 The non-linear sewing lemma

After showing a uniform control of ϕ^{π} with respect to π when ϕ is an almost flow in the previous section, we prove our main result in Theorem 2. We show that in the finite dimensional case, we can built a flow from ϕ^{π} using a selection principle due to [10].

We restate the notion of solution in the sense introduced by A.M. Davie [15] in the context of a metric space and a general almost flow.

Definition 6 (Solution in the sense of Davie). For an almost flow ϕ , a solution in the sense of Davie associated to ϕ is a path $y \in \mathscr{C}(\mathbb{S}, \mathbb{V})$ with $\mathbb{S} = [r, r + T] \subset \mathbb{T}$ if there is a constant $K \geq 0$ such that

$$d(y_t, \phi_{t,s}(y_s)) \leqslant KN_{\gamma}(y_r)\varpi(\omega_{s,t}), \ \forall (s,t) \in \mathbb{S}^2_+.$$
 (25)

Remark 3. Our definition of solution is a natural extension of that of Davie in [15] for a metric space V and a general almost flow ϕ .

Remark 4. If ϕ is only an almost flow, it is not guarantee that there exists a solution and even less that the uniqueness of the solution holds. When $S_{\phi}(r,a) \neq \emptyset$, we prove below in Lemma 3 that a solution in the sense of Davie exists. Even when $S_{\phi}(r,a) \neq \emptyset$ for any $r \in \mathbb{T}$ and any $a \in V$ does not prove that there exists a choice of families of solutions $\{\psi_{\cdot,r}(a)\}_{r\in\mathbb{T},a\in V}$ which satisfies the flow property.

Notation 5. We denote $\Omega(r, a)$ the set of continuous path such that $y \in \mathcal{C}(\mathbb{S}, V)$ verifying $y_r = a$. We denote by $G_{\phi}^K(r, a)$ the set of paths in $\Omega(r, a)$ verifying (25) for the constant K.

Definition 7 (Splicing of paths). For $r \leq s$, let us consider $y(r, a) \in \mathcal{C}_a([r, T], V)$ and $z \in \mathcal{C}_b([s, T], V)$ with $b = y_s(r, a)$. Their splicing is

$$(y \bowtie_s z)_t(r, a) = \begin{cases} y_t(r, a) & \text{if } t \leqslant s, \\ z_t(s, y_s(r, a)) & \text{if } t \geqslant s. \end{cases}$$

We restate here, the definition of a family of abstract integral local funnels (Definition 2 in [10]), which leads to the existence of a measurable flow.

Definition 8. A family $F(r, a) \subset \mathcal{C}(\mathbb{T}, V)$ with $r \in [0, +\infty)$, $a \in V$, will be called a family of abstract local integral funnels with terminal times T(r, a) if F(r, a) satisfies

- **H0** The map $(r, a) \in [0, +\infty) \times V \mapsto T(r, a)$ is a lower semi-continuous in the sense that if $(r_n, a_n) \to (r, a)$, then $T(r, a) \leq \liminf_n T(r_n, a_n)$.
- **H1** Every set F(r, a) is a non-empty compact in $\mathscr{C}(\mathbb{T}, V)$ and every path $y(r, a) \in F(r, a)$ is a continuous map from $\mathbb{T} = [T_0, T_0 + T(r, a)]$ to V, and $y_r(r, a) = a$.
- **H2** For all $r \ge 0$, the map $a \in V \mapsto S(r, a)$ is measurable in the sense that for any closed subset $\mathcal{K} \subset \mathcal{C}([0, 1], V)$, $\{a \in V \mid \tilde{F}(r, a) \cap \mathcal{K} \ne \emptyset\}$ is Borel, where $\tilde{F}(r, a)$ is the set of re-parametrizations of paths of F(r, a) on [0, 1].
- **H3** If $y(r, a) \in F(r, a)$ and $\tau < T(r, a)$, then $T(t_0 + \tau, y_{r+\tau}(r, a)) \ge T(r, a) \tau$ and $t \in [r + \tau, r + \tau + T(t_0 + \tau, y_{r+\tau}(r, a))] \mapsto y_t(r, a) \in F(r + \tau, y_{r+\tau}(r, a)).$

H4 If $y(r, a) \in F(r, a)$ and $\tau < T(r, a)$, and $z \in F(r + \tau, y_{t+\tau}(r, a))$ then the spliced path (Definition 7) $x := y \bowtie_{r+\tau} z \in F(r, a)$.

Definition 9 (Lipschitz almost flow). A Lipschitz almost flow is an almost flow for which (12) is satisfied with $\eta = 0$, and $N_{\gamma} = N_1 = N$ is Lipschitz continuous.

A flow is constructed by assigning to each point of the space of particular choice of a solution in the sense of Davie in a sense which is compatible.

Hypothesis 1. Let V be a finite dimensional vector space. Let ϕ be a Lipschitz almost flow (Definition 9) with N bounded. We fix a time horizon T > 0 such that $\varkappa(1 + \delta_T) < 1$.

Remark 5. In the case N bounded, we can choose $K_T = 1$ and $L_T = 2/(1 - \varkappa(1 + \delta_T))$ where K_T and L_T are the constants of Theorem 1.

The main theorem of this paper is the following one.

Theorem 2 (Non-linear sewing lemma, weak formulation). Under Hypothesis 1, there exists a family $\psi \in \mathcal{F}(V)$ in the same galaxy as ϕ such that $\psi_{t,s}$ is Borel measurable for any $(s,t) \in \mathbb{T}^2_+$ and ψ satisfies the flow property.

Remark 6. Proving such a result with a general Banach space V is false as even existence of solutions to ordinary differential equations may fail [16, 22].

Remark 7. To prove Theorem 2, we show that $(G^{L_T}(r,a))_{r\in[0,+\infty),a\in V}$ is a family of abstract local integral funnels in the sense of Definition 8. Then, we use Theorem 2 of [10].

Lemmas 2-7 prove that $G^{L_T}(r, a)$ is a family of local abstract funnels in the sense of the Definition 2 in [10]. Then we apply Theorem 2 in [10] to obtain the following theorem.

Lemma 2. Under the Hypothesis 1, the terminal times T(r,a) is independent of the starting time r and the starting point a. We denote T = T(r,a). In particular, H0 holds for $F = G_{\phi}^{L_T}$.

Proof. Indeed, \varkappa and δ_T does not depend neither of $a \in V$ and T_0 .

We recall that $S_{\phi}(r, a)$ is defined in Notation 4 Our first result is that when $S_{\phi}(r, a) \neq \emptyset$, then there exists at least one solution in the sense of Davie in $G_{\phi}^{L_T}(r, a)$.

Lemma 3. Assume that $K \ge K_T L_T$ in Definition 6, where K_T and L_T are constants in Theorem 1. For any $(r, a) \in \mathbb{T} \times V$, $S_{\phi}(r, a) \subset G_{\phi}^K(r, a)$ for an almost flow ϕ (note that $S_{\phi}(r, a)$ may be empty).

Proof. If $y \in S_{\phi}(r, a)$ when $S_{\phi}(r, a) \neq \emptyset$, then there exists a sequence $\{\pi_k\}_{k \in \mathbb{N}}$ of partitions such that $y_t = \lim \phi_{t,r}^{\pi_k}(a)$ uniformly in $t \in [r, T]$. We note that $y_r = a$. For $k \in \mathbb{N}$ and $s_k \in \pi_k$, with (8) and Theorem 1,

$$d(\phi_{t,r}^{\pi_k}(a), \phi_{t,s_k} \circ \phi_{s_k,r}^{\pi_k}(a)) = d(\phi_{t,s_k}^{\pi_k} \circ \phi_{s_k,r}^{\pi_k}(a), \phi_{t,s_k} \circ \phi_{s_k,r}^{\pi_k}(a))$$

$$\leq L_T N_{\gamma}(\phi_{s_k,r}^{\pi_k}(a)) \varpi(\omega_{s_k,t})$$

$$\leq L_T K_T N_{\gamma}(a) \varpi(\omega_{s_k,t}). \tag{26}$$

And moreover,

$$d(\phi_{t,s_{k}} \circ \phi_{s_{k},r}^{\pi_{k}}(a), \phi_{t,s}(y_{s}(a))) \leq d(\phi_{t,s_{k}} \circ \phi_{s_{k},r}^{\pi_{k}}(a), \phi_{t,s_{k}} \circ y_{s}(a)) + d(\phi_{t,s_{k}} \circ y_{s}(a), \phi_{t,s} \circ y_{s}(a))$$

$$\leq (1 + \delta_{T})d(\phi_{s_{k},r}^{\pi_{k}}(a), y_{s}(a)) + \eta(\omega_{0,T})d(\phi_{s_{k},r}^{\pi_{k}}(a), y_{s}(a))^{\gamma}$$

$$+ d(\phi_{t,s_{k}} \circ y_{s}(a), \phi_{t,s} \circ y_{s}(a)). \tag{27}$$

Choosing $\{s_k\}_{k\in\mathbb{N}}$ so that s_k decreases to s and passing to the limit, we obtain with (27) that $\phi_{t,s_k} \circ \phi_{s_k,r}^{\pi_k}(a)$ converges uniformly to $\phi_{t,s} \circ y_s(a)$. Thus, when $k \to +\infty$, (26) shows that y is a solution in the sense of Davie.

Lemma 4. Under Hyposthesis 1, $G_{\phi}^{L_T}(r,a)$ is non-empty compact subset of the path $y \in \mathcal{C}(\mathbb{S}, \mathbb{V})$ such that $y_r = a$ for any $r \in \mathbb{T}$ and $a \in \mathbb{V}$. It shows that H1 holds for $F := G_{\phi}^{L_T}$.

Proof. It follows directly from Proposition 1 and Lemma 3 (with $K_T = 1$ and $K = L_T$) that $G_{\phi}^K(r, a)$ is not empty. Now, if $\{y^k\}_k$ is a sequence in $G_{\phi}^K(r, a)$ then $\{y^k\}_k$ is equi-continuous with the same argument as in proof of Proposition 1. And the subsequence of $\{y^k\}_k$ converges in $G_{\phi}^K(r, a)$ because of the continuity of $a \in V \mapsto \phi_{t,s}(a)$ for any $(s,t) \in \mathbb{T}_2^+$.

Let us denote $\tilde{G}_{\phi}^{L_T}(r, a)$, the set of paths in $y \in G_{\phi}^{L_T}(r, a)$ reparametrised on [0, 1] as $t \in [0, 1] \mapsto \tilde{y}_t := y_{r+t(T-r)}$.

Lemma 5. Let us assume Hypothesis 1. Let $r \ge 0$, for any closed subset $\mathcal{K} \subset \mathcal{C}([0,1], V)$, the set $S'(r) := \{a \in V \mid \tilde{G}_{\phi}^{L_T}(r, a) \cap \mathcal{K} \ne \emptyset\}$ is closed in V, in particular it is a Borel set in V. It shows that H2 holds for $F = G_{\phi}^{L_T}$.

Proof. Let $\{a_k\}_{k\in\mathbb{N}}$ be a convergent sequence of S'(r). For each $k\in\mathbb{N}$, we choose a path $\tilde{y}^k\in \tilde{G}_{\phi}^{L_T}(r,a_k)\cap\mathcal{K}$ (which is not empty by definition). Then, for every $s,t\in[0,1],\ s\leqslant t$,

$$d(\tilde{y}_t^k, \tilde{y}_s^k) \leqslant d(\tilde{y}_t^k, \phi_{\tilde{t}, \tilde{s}}(\tilde{y}_s^k)) + d(\phi_{\tilde{t}, \tilde{s}}(\tilde{y}_s^k), \tilde{y}_s^k) \leqslant [L_T \varpi(\omega_{\tilde{s}, \tilde{t}}) + \delta_{\tilde{t} - \tilde{s}}] ||N||_{\infty},$$
 (28)

where $\tilde{t} := r + t(T - r)$ and $\tilde{s} := r + s(T - r)$. Since $\tilde{t} - \tilde{s}$ goes to zero when $t - s \to 0$, it follows that $\{t \in [0, 1] \mapsto \tilde{y}_t^k\}_{k \in \mathbb{N}}$ is equi-continuous.

The sequence $\{a_k\}_{k\in\mathbb{N}}$ converges, so it is bounded by a constant $A \geq 0$. Applying (28) between s = 0 and t, we get $|\tilde{y}_t^k| \leq [L_T \varpi(\omega_{0,1}) + \delta_T] ||N||_{\infty} + A$, which proves that $t \in [0,1] \mapsto y^k$ is uniformly bounded.

By Ascoli-Arzelà theorem, there is a convergent subsequence $\{\tilde{y}^{k_i}\}_{i\in\mathbb{N}}$ in $(\mathcal{C}([0,1], \mathbf{V}), \|\cdot\|_{\infty})$ to a path y. This path belongs to \mathcal{K} since \mathcal{K} is closed. Because $\phi_{t,s}$ is continuous, $\tilde{y} \in \tilde{G}_{\phi}^{L_T}(r, a)$. Hence S'(r) is closed and then Borel.

The proof of the next lemma is an immediate consequence of the definition of a solution in the sense of Davie.

Lemma 6. If $t \in [r, r+T] \mapsto y(r, a)$ belongs to $G_{\phi}^{L_T}(r, a)$, then for any $r' \ge 0$, its restriction $t \in [r+r', r+r'+T] \mapsto y_t(r, a)$ belongs to $G_{\phi}^{L_T}(r+r', y_{r+r'}(r, a))$. It shows that H3 holds for $F = G_{\phi}^{L_T}$.

Lemma 7. We assume that Hypothesis 1 hold. For $r' \ge 0$, if $y \in G_{\phi}^{L_T}(r,a)$ and $z \in G_{\phi}^{L_T}(r+r',y_{r+r'}(r,a))$, then $y \bowtie_{r+r'} z \in G_{\phi}^{L_T}(r,a)$. It shows that H4 holds for $F := G_{\phi}^{L_T}$

Proof. Let us write $x := y \bowtie_s z$ where s := r + r' and $U_{\tau,t} := d(x_t, \phi_{t,\tau}(x_\tau))$ for $\tau \leqslant t$. On the one hand, for any $r \leqslant \tau \leqslant s \leqslant t$ with (25), (12) and (13),

$$U_{\tau,t} \leqslant d(x_t, \phi_{t,s}(x_s)) + d(\phi_{t,s}(x_s), \phi_{t,s} \circ \phi_{s,\tau}(x_\tau)) + d(\phi_{t,s} \circ \phi_{s,\tau}(x_\tau), \phi_{t,\tau}(x_\tau))$$

$$\leqslant ||N||_{\infty} (2 + \delta_T) L_T \varpi(\omega_{\tau,t}). \tag{29}$$

On another hand, for $s \leqslant \tau \leqslant t$ or $\tau \leqslant t \leqslant s$ with (25)

$$U_{\tau,t} \leqslant ||N||_{\infty} L_T \varpi(\omega_{\tau,t}). \tag{30}$$

Thus, combining (29) and (30), for any $r \leq \tau \leq t \leq T$,

$$U_{\tau,t} \leq ||N||_{\infty} (2 + \delta_T) L_T \varpi(\omega_{\tau,t}).$$

Besides, for any $r \leq \tau \leq u \leq t \leq T$ with (12) and (13).

$$U_{\tau t} \leq U_{u,t} + (1 + \delta_T)U_{\tau u} + ||N||_{\infty} \varpi(\omega_{\tau t}). \tag{31}$$

Let $\lambda \in (0,1)$ such that ϖ^{λ} satisfies (5) with $\varkappa_{\lambda} := 2^{1-\lambda} \varkappa^{\lambda} < 1$. Let $T(\lambda) > 0$ a real such that $\varkappa_{\lambda}(1 + \delta_{T(\lambda)}) < 1$. For any, two successive points τ, t of a subdivision π ,

$$U_{\tau,t} \leqslant D_{L_T}(\pi,\lambda)\varpi^{\lambda}(\omega_{\tau,t}),$$
 (32)

where $D_{L_T}(\pi, \lambda) := ||N||_{\infty} (2 + \delta_T) L_T \sup_{\tau, t \text{ successive points of } \pi} \varpi^{1-\lambda}(\omega_{\tau, t}).$

Let us show by induction over the distance m between points τ and t in $\pi \cap [0, T(\lambda)]^2$ that

$$U_{\tau,t} \leqslant A_{L_T}(\pi,\lambda)\varpi^{\lambda}(\omega_{\tau,t}),$$
 (33)

where $A_{L_T}(\pi, \lambda) := \frac{D_{L_T}(\pi, \lambda)(1 + \delta_{T(\lambda)}) + 2\|N\|_{\infty} \varpi^{\lambda}(\omega_{0,T(\lambda)})}{1 - \varkappa_{\lambda}(1 + \delta_{T(\lambda)})}$. For m = 1, τ and t are successive points then (33) holds with (32). Now, we assume that (33) holds for any two points at distance m. Let τ and t be two points at distance m + 1 in $\pi \cap [0, T(\lambda)]^2$. Since ω is super-additive, one may choose two successive points s and s' in π with $\tau < s < s' < t$ such that $\omega_{\tau,s} \le \omega_{\tau,t}/2$ and $\omega_{s',t} \le \omega_{\tau,t}/2$. Then, by applying (31) between (τ, s, s') and (s, s', t) we obtain,

$$U_{\tau,t} \leq U_{s,t} + (1 + \delta_{T(\lambda)}) U_{\tau,s} + ||N||_{\infty} \varpi^{1-\lambda} (\omega_{0,T(\lambda)}) \varpi^{\lambda} (\omega_{\tau,t})$$

$$\leq U_{s',t} + (1 + \delta_{T(\lambda)}) U_{s,s'} + (1 + \delta_{T(\lambda)}) U_{\tau,s} + 2||N||_{\infty} \varpi^{1-\lambda} (\omega_{0,T(\lambda)}) \varpi^{\lambda} (\omega_{\tau,t})$$

$$\leq [A_{L_T}(\pi,\lambda) \varkappa_{\lambda} (1 + \delta_{T(\lambda)}) + (1 + \delta_{T(\lambda)}) D_{L_T}(\pi,\lambda) + 2||N||_{\infty} \varpi^{1-\lambda} (\omega_{0,T(\lambda)})] \varpi^{\lambda}_{\tau,t}$$

$$\leq A_{L_T}(\pi,\lambda) \varpi^{\lambda}_{\tau,t},$$

with our choice of $A_{L_T}(\pi, \lambda)$. This concludes the induction, so (33) holds for any $\tau, t \in \pi \cap [0, T(\lambda)]^2$.

Clearly, $D_{L_T}(\pi, \lambda) \to 0$ when the mesh of π goes to zero. Then, $A_{L_T}(\pi, \lambda) \to A(\lambda) := 2\|N\|_{\infty} \varpi_{0,T(\lambda)}^{\lambda}/(1 - \varkappa_{\lambda}(1 + \delta_{T(\lambda)}))$ when the mesh of π goes to zero.

By continuity of $(\tau, t) \mapsto U_{\tau,t}$, considering a finer and finer partitions leads to $U_{\tau,t} \leq A(\lambda) \varpi^{\lambda}(\omega_{\tau,t})$ for any $r \leq \tau \leq t \leq T(\lambda)$.

Finally, choosing $T(\lambda)$ so that $T(\lambda)$ increases to T defined in Hypothesis 1 when λ goes to 1, we conclude that for any $r \leq \tau \leq t \leq T$,

$$U_{\tau,t} \leqslant ||N||_{\infty} L_T \varpi(\omega_{\tau,t}),$$

where L_T is defined in Hypothesis 1. This proves that $z \in G_{\phi}^{L_T}(r,a)$.

Proof of Theorem 2. Lemma 2-7 prove that conditions H0-H4 of Definition 8 hold for $F = G_{\phi}^{L_T}$. This means that $G^{L_T}(r,a)$ is a family of abstract local integral funnels. We apply Theorem 1 in [10]. For any $(r,a) \in \mathbb{T} \times V$, there exists a measurable map $a \mapsto (t \mapsto \psi_{t,r}(a))$ respect to the Borel subsets of $\mathscr{C}^0(\mathbb{T}, V)$ with the property that $\psi_{r,r}(a) = a$ and $\psi_{t,s} \circ \psi_{s,r}(a) = \psi_{t,r}(a)$, $t \ge r$.

4 Lipschitz flows

A Lipschitz almost flow which has the flow property is said to be a Lipschitz flow. We recast the definition.

Definition 10 (Lipschitz flow). A flow $\psi \in \mathcal{F}(V)$ is said to be a *Lipschitz flow* is for any $(s,t) \in \mathbb{T}_2^+$, $\psi_{t,s}$ is Lipschitz in space with $\|\psi_{t,s}\|_{\text{Lip}} \leq 1 + \delta_T$.

In this section, we consider galaxies that contain a Lipschitz flow.

We prove that such a Lipschitz flow ψ is the only possible flow in the galaxy (Theorem 5), and that the iterated almost flow ϕ^{π} of any almost flow ϕ converges to ψ (Theorem 3). We also characterize the rate of convergence (Theorem 4).

Let us choose $\lambda \in (0,1)$ such that ϖ^{λ} satisfies the same properties as ϖ up to changing \varkappa to $\varkappa_{\lambda} := 2^{1-\lambda} \varkappa^{\lambda}$, provided $\varkappa_{\lambda} < 1$. This is possible as soon as $\lambda > 1/(1 - \log_2(\varkappa))$ with (5).

Clearly, if for $\psi, \chi \in \mathcal{F}(V)$, $\Delta_{N,\varpi}(\psi, \chi) < +\infty$, then

$$\Delta_{N,\varpi^{\lambda}}(\psi,\chi) \leqslant \Delta_{N,\varpi}(\psi,\chi)\varpi^{1-\lambda}(\omega_{0,T}) < +\infty, \tag{34}$$

where ϖ is defined by (5). Hence, the galaxies remain the same when ϖ is changed to ϖ^{λ} . We define

$$\Theta(\pi) := \sup_{d_{\pi}(s,s')=1} \varpi^{1-\lambda}(\omega_{s,s'}). \tag{35}$$

Theorem 3. Let ϕ be an almost flow such that $\|\phi^{\pi}\|_{\text{Lip}} \leq 1 + \delta_{T}$ whatever the partition π , we say that ϕ satisfies the uniform Lipschitz (UL) condition. Then there exists a Lipschitz flow $\zeta \in \mathcal{F}(V)$ with $\|\zeta_{s,t}\|_{\text{Lip}} \leq 1 + \delta_{T}$ such that $\{\phi^{\pi}\}$ converges to ζ as $|\pi| \to 0$.

Theorem 4. Let ϕ be an almost flow and ψ be a Lipschitz flow with $\psi \sim \phi$. Then there exists a constant K that depends only on λ , $\Delta_{N,\varpi}(\phi,\psi)$, \varkappa and T (assumed to be small enough) so that

$$\Delta_{N,\varpi^{\lambda}}(\psi,\phi^{\pi}) \leqslant K\Theta(\pi).$$

In particular, $\{\phi^{\pi}\}_{\pi}$ converges to ψ as $|\pi| \to 0$.

Theorem 5 (Uniqueness of Lipschitz flows). If ψ is a Lipschitz flow and χ is a flow (not necessarily Lipschitz a priori) in the same galaxy as ψ , that is $\chi \sim \psi$, then $\chi = \psi$.

Hypothesis 2. Let us fix a partition π . We consider ψ and χ in $\mathcal{F}(V)$ such that $\psi \sim \chi$ and for any $(r, s, t) \in \pi^3_+$,

$$\|\psi_{t,s}\|_{\text{Lip}} \leqslant 1 + \delta_T,\tag{36}$$

$$N(\chi_{t,s}(a)) \le (1 + \delta_T)N(a), \ \forall a \in V, \tag{37}$$

$$\Delta_N(\psi_{t,s} \circ \psi_{s,r}, \psi_{t,r}) \leqslant \beta_{\psi} \varpi(\omega_{r,t}) \text{ and } \Delta_N(\chi_{t,s} \circ \chi_{s,r}, \chi_{t,r}) \leqslant \beta_{\chi} \varpi(\omega_{r,t})$$
 (38)

for some constant $\beta_{\chi}, \beta_{\phi} \geq 0$.

Remark 8. In Hypothesis 2, the role of ψ and χ are not exchangeable: ψ is assumed to be Lipschitz, there is no such requirement on χ . The reason of this dissymmetry lies in (41).

Remark 9. If ψ is a Lipschitz almost flow and χ is an almost flow, then (ψ, χ) satisfies Hypothesis 2 for any partition π . The condition (37) is a particular case of (15).

We choose λ and T so that

$$\frac{1}{1 - \log_2(\varkappa)} < \lambda < 1 \text{ and } 3\delta_T + \delta_T^3 < 2\frac{1 - \varkappa_\lambda}{\varkappa_\lambda}.$$

We define (recall that $\Theta(\pi)$ is given by (35)),

$$\rho_T := \varpi(\omega_{0,T})^{1-\lambda},$$

$$\gamma(\pi) := \sup_{d_{\pi}(s,s')=1} \frac{\Delta_N(\psi,\chi)}{\varpi^{\lambda}(\omega_{s,s'})} \leqslant \Delta_{N,\varpi^{\lambda}}(\psi,\chi)\Theta(\pi),$$

$$\beta(\pi) := (2 + 3\delta_T + \delta_T^2)(\beta_{\psi} + \beta_{\chi})\rho_T + (1 + \delta_T)^2\gamma(\pi) \geqslant \gamma(\pi),$$
and
$$L(\pi) := \frac{2\beta(\pi)}{2 - \varkappa_{\lambda}(2 + 3\delta_T + \delta_T^2)} \geqslant \gamma(\pi).$$

Here, $\Theta(\pi)$ and thus $\gamma(\pi)$ converge to zero when the mesh of π tends to zero.

Lemma 8. Let $\phi, \chi \in \mathcal{F}(V)$ and π be satisfying Hypothesis 2. With the above choice of λ and T, it holds that

$$d(\phi_{t,r}(a), \chi_{t,r}(a)) \leqslant L(\pi \cup \{t,r\}) N(a) \varpi^{\lambda}(\omega_{r,t}), \ \forall (r,t) \in \mathbb{T}_{+}^{2}.$$
(39)

Proof. We set $F_{r,t} := \Delta_N(\psi_{t,r}, \chi_{t,r})$, where Δ_N is defined in Notation 3. From Definition 1, $F_{r,t} \leq \Delta_{N,\varpi}(\psi, \chi)\varpi(\omega_{r,t}) < +\infty$ since $\psi \sim \chi$.

In particular, for $(r, s, t) \in \pi^3_+$, with (37) in Hypothesis 2,

$$d(\psi_{t,s} \circ \chi_{s,r}(a), \chi_{t,s} \circ \chi_{s,r}(a)) \leqslant F_{s,t} N(\chi_{s,r}(a)) \leqslant (1 + \delta_T) N(a) F_{s,t}. \tag{40}$$

For any $(r, s, t) \in \pi_3^+$, the fact that ϕ , χ are almost flow combined with (36)-(38) and (40) imply that for any $a \in V$,

$$d(\psi_{t,r}(a), \chi_{t,r}(a))$$

$$\leq d(\psi_{t,s} \circ \psi_{s,r}(a), \psi_{t,s} \circ \chi_{s,r}(a)) + d(\psi_{t,s} \circ \chi_{s,r}(a), \chi_{t,s} \circ \chi_{s,r}(a)) + (\beta_{\phi} + \beta_{\chi}) N(a) \varpi(\omega_{r,t})$$

$$\leq (1 + \delta_T) N(a) F_{r,s} + (1 + \delta_T) N(a) F_{s,t} + (\beta_{\chi} + \beta_{\phi}) N(a) \varpi(\omega_{r,t}). \tag{41}$$

Thus, dividing by N(a),

$$F_{r,t} \leq (1 + \delta_T)(F_{r,s} + F_{s,t}) + (\beta_\chi + \beta_\psi)\rho_T \varpi^\lambda(\omega_{r,t}). \tag{42}$$

We proceed by induction. Our hypothesis is that

$$F_{r,t} \leq L(\pi)\varpi^{\lambda}(\omega_{r,t}), \forall (r,t) \in \pi_2^+, \text{ at distance at most } m.$$
 (43)

When m=1, r and t are successive points. From the very definition of $\gamma(\pi)$,

$$F_{r,t} \leqslant \gamma(\pi)\varpi^{\lambda}(\omega_{r,t}).$$
 (44)

The induction hypothesis (16) is true for m = 1 since $L(\pi) \ge \gamma(\pi)$.

Assume that the induction hypothesis is true at some level $m \ge 1$. Let $(r, s, t) \in \pi_3^+$ with r < s < t and $d_{\pi}(r, t) = m + 1$. Let s' be such that s and s' are successive points in π (possibly, s' = t). Clearly, $d_{\pi}(r, s) \le m$ and $d_{\pi}(s', t) \le m$. Using (42) to decompose $F_{s,t}$ using s' and using (44),

$$F_{r,t} \leq (1 + \delta_T) F_{r,s} + (1 + \delta_T)^2 F_{s',t} + (1 + \delta_T)^2 \gamma(\pi) \varpi^{\lambda}(\omega_{s,s'})$$

$$+ (2 + 3\delta_T + \delta_T^2) (\beta_{\psi} + \beta_{\chi}) \rho_T \varpi^{\lambda}(\omega_{r,t})$$

$$\leq (1 + \delta_T) F_{r,s} + (1 + \delta_T)^2 F_{s',t} + \beta(\pi) \varpi^{\lambda}(\omega_{r,t})$$

With the induction hypothesis, since r and s (resp. s' and t) are at distance at most m,

$$F_{r,t} \leq L(\pi)(1+\delta_T)\varpi^{\lambda}(\omega_{r,s}) + L(\pi)(1+\delta_T)^2\varpi^{\lambda}(\omega_{s',t}) + \beta(\pi)\varpi^{\lambda}(\omega_{r,t}).$$

Choosing s and s' to satisfy (21), our choice of $L(\pi)$ and (5) imply that

$$F_{r,t} \leqslant \left(L(\pi)\frac{2+3\delta_T+\delta_T^2}{2}\varkappa_\lambda + \beta(\pi)\right)\varpi^\lambda(\omega_{r,t}) \leqslant L(\pi)\varpi^\lambda(\omega_{r,t}).$$

The induction hypothesis (43) is then true at level m + 1, and then whatever the distance between the points of the partition.

Finally, (39) is obtained by replacing
$$\pi$$
 by $\pi \cup \{r, t\}$.

Proof Theorem 3. Let σ and π be two partitions with $\pi \subset \sigma$. We set $\psi := \phi^{\sigma}$ and $\chi := \phi^{\pi}$.

With Theorem 1,

$$\Delta_{N,\varpi}(\phi^{\sigma},\phi^{\pi}) \leq \Delta_{N,\varpi}(\phi^{\sigma},\phi) + \Delta_{N,\varpi}(\phi^{\pi},\phi) \leq 2L_T.$$

With (34), $\Delta_{N,\varpi^{\lambda}}(\psi,\chi) \leq 2L_T \rho_T$, so that $\{\Delta_{N,\varpi^{\lambda}}(\psi,\chi)\}_{\pi,\sigma}$ is bounded.

Again with Theorem 1, (ψ, χ) satisfies Hypothesis 2 for the subdivision π (up to changing δ_T) with $\beta_{\psi} = \beta_{\chi} = 0$.

Hence, $L(\pi) = C\gamma(\pi)$ where

$$C := \frac{2(1 + \delta_T)^2}{(2 - \varkappa_\lambda (2 + 3\delta_T + \delta_T^2)}.$$

We may then rewrite (39) as

$$d(\phi_{t,r}^{\sigma}(a), \phi_{t,r}^{\pi}(a)) \leqslant C\gamma(\pi \cup \{r, t\}) N(a) \varpi^{\lambda}(\omega_{r,t}). \tag{45}$$

Since $\gamma(\pi)$ decreases to 0 as $|\pi|$ decreases to 0 and $|\pi \cup \{r,t\}| \leq |\pi|$, it is easily shown that $\{\phi_{t,s}^{\pi}\}_{\pi}$ forms a Cauchy net with respect to the nested partitions. Then, it does converges to a limit $\zeta_{s,t}(a)$. By Theorem 8 and the continuity of N, $N(\zeta_{s,r}) \leq K_T N(a)$. From the UL condition, $a \mapsto \zeta_{t,s}(a)$ is Lipschitz continuous with $\|\zeta_{t,s}\|_{\text{Lip}} \leq 1 + \delta_T$.

Moreover ζ does not depend on the subdivision π . Indeed, if $\tilde{\pi}$ is another subdivision, we obtain with (45), that $\{\phi^{\tilde{\pi}}\}_{\tilde{\pi}}$ converges to ζ when $|\tilde{\pi}| \to 0$.

Finally, if if $\{\pi_k\}_{k\geq 0}$ is a family of nested partitions, and $(r,s,t)\in \mathbb{T}_3^+$,

$$\phi_{t,r}^{\pi_k \cup \{s\}} = \phi_{t,s}^{\pi_k} \circ \phi_{s,r}^{\pi_k}.$$

Because $|\pi_k \cup \{s\}| \leq |\pi_k|$ and (45), $\phi^{\pi_k \cup \{s\}}$ converges to ζ when $k \to +\infty$. Moreover, for any $a \in V$,

$$d(\zeta_{t,s} \circ \zeta_{s,r}(a), \phi_{t,s}^{\pi_k} \circ \phi_{s,r}^{\pi_k}(a)) \leq d(\zeta_{t,s} \circ \zeta_{s,r}(a), \phi_{t,s}^{\pi_k} \circ \zeta_{s,r}(a)) + d(\phi_{t,s}^{\pi_k} \circ \zeta_{s,r}(a), \phi_{t,s}^{\pi_k} \circ \phi_{s,r}^{\pi_k}(a))$$

$$\leq C\gamma(\pi_k \cup \{r,t\}) N(\zeta_{s,r}(a)) \varpi^{\lambda}(\omega_{r,t}) + (1 + \delta_T) d(\zeta_{s,r}(a), \phi_{s,r}^{\pi_k}(a))$$

$$\leq C\gamma(\pi_k \cup \{r,t\}) (1 + K_T) N(a) \varpi(\omega_{r,t}),$$

because $N(\zeta_{s,r}(a)) \leq K_T N(a)$. So, $\{\phi_{t,s}^{\pi_k} \circ \phi_{s,r}^{\pi_k}\}_{\pi_k}$ converge uniformly to $\zeta_{t,s} \circ \zeta_{s,r}$ when $m \to +\infty$. Then, the flow property $\zeta_{t,s} \circ \zeta_{s,r} = \zeta_{t,r}$ holds.

Proof Theorem 4. For a partition π , the pair (ψ, ϕ^{π}) satisfies Hypothesis 2 for the subdivision π with $\beta_{\psi} = \beta_{\chi} = 0$. As in the proof of Theorem 3 (we have assumed for convenience that $\Delta_{N,\varpi}(\phi,\psi) \leq L_T$),

$$\Delta_{N,\varpi^{\lambda}}(\psi,\phi^{\pi}) \leqslant C\gamma(\pi) \leqslant 2CL_{T}\rho_{T}\Theta(\pi)$$

for C given by (4). This proves the result.

Proof Theorem 5. For any partition π , ψ and χ satisfy Hypothesis 2 with $\beta_{\psi} = \beta_{\chi} = 0$. Thus,

$$\Delta_{N,\varpi^{\lambda}}(\psi,\chi) \leqslant C\gamma(\pi)$$

with C given by (4). As $\gamma(\pi)$ decreases to 0 when $|\pi|$ decreases to 0, we obtain that $\psi = \chi$.

Corollary 2. Let ψ and χ be two almost flows with $\psi \sim \chi$. Then for T small enough (in function of some $\lambda < 1$, \varkappa and δ)

$$\Delta_{N,\varpi}(\psi,\chi) \leqslant \frac{2(2+3\delta_T+\delta_T^2)(\beta_\psi+\beta_\chi)}{2-\varkappa_\lambda(2+3\delta_T+\delta_T^2)}.$$

Proof. With Remark 9, (ψ, χ) satisfies Hypothesis 2. Letting the mesh of the partition decreasing to 0 as the in proof of Theorem 5, and then letting λ increasing to 1 leads to the result.

5 Perturbations

In this section, we consider the construction of almost flow by perturbations of existing ones. We assume that V is a Banach space.

Let $\phi \in \mathcal{F}(V)$ be an almost rough path with respect to a function N_{γ} such that $N_{\gamma}(a) \geq N_{\gamma}(0) \geq 1$.

Notation 6. For $\phi \in \mathcal{F}(V)$ when V is a Banach space, we write

$$\phi_{t,s,r}(a) = \phi_{t,s}(\phi_{s,r}(a)) - \phi_{t,r}(a).$$

Definition 11. Let $\epsilon \in \mathcal{F}(V)$ such that for any $(s,t) \in \mathbb{T}_2^+$, $a,b \in V$,

$$\epsilon_{t,t} \equiv 0,\tag{46}$$

$$|\epsilon_{t,s}(a)| \leq \lambda N_{\gamma}(a)\varpi(\omega_{s,t}),$$
 (47)

$$|\epsilon_{t,s}(b) - \epsilon_{t,s}(a)| \leq \eta(\omega_{s,t})|b - a|^{\gamma} \tag{48}$$

for some $\lambda \geq 0$. We say that ϵ is a perturbation.

Proposition 2. If $\phi \in \mathcal{F}(V)$ is an almost flow and $\epsilon \in \mathcal{F}(V)$ is a perturbation, then $\psi := \phi + \epsilon$ is an almost flow. Besides, $\psi \sim \chi$.

Proof. Let $(r, s, t) \in \mathbb{T}_3^+$ and $a, b \in V$. From (46), (10) is satisfied. With $\delta_T' := \delta_T + \lambda \varpi(\omega_{0,T})$, (11) is also true. In addition, with (48),

$$|\psi_{t,s}(b) - \psi_{t,s}(a)| \leq (1 + \delta_T)|b - a| + 2\eta(\omega_{s,t})|b - a|^{\gamma}.$$

Thus, ψ satisfies (12).

To show (13), we write

$$\phi_{t,s,r}(a) = \phi_{t,s} \circ \psi_{s,r}(a) + \epsilon_{t,s} \circ \psi_{s,r}(a) - \phi_{t,r}(a) - \epsilon_{t,s}(a)$$

$$= \underbrace{\phi_{t,s,r}(a)}_{I_{r,s,t}} + \underbrace{\phi_{t,s} \circ (\phi_{s,r} + \epsilon_{s,r})(a) - \phi_{t,s} \circ \phi_{s,r}(a)}_{II_{r,s,t}}$$

$$+ \underbrace{\epsilon_{t,s} \circ (\phi_{s,r}(a) + \epsilon_{s,r}(a)) - \epsilon_{t,s} \circ \phi_{s,r}(a)}_{III_{r,s,t}} + \underbrace{\epsilon_{t,s} \circ \phi_{s,r}(a) - \epsilon_{t,s}(a)}_{IV_{r,s,t}}.$$

$$(49)$$

We control the first term with (13), $|I_{r,s,t}| \leq N_{\gamma}(a)\varpi(\omega_{r,t})$. For the second one, we use (6), (12) and (47),

$$|\Pi_{r,s,t}| \leq (1+\delta_T)|\epsilon_{s,r}(a)| + \eta(\omega_{s,r})|\epsilon_{s,r}|^{\gamma}$$

$$\leq (1+\delta_T)\lambda N_{\gamma}(a)\varpi(\omega_{r,s}) + \eta(\omega_{s,t})\lambda^{\gamma}N_{\gamma}^{\gamma}(a)\varpi(\omega_{r,s})^{\gamma}$$

$$\leq [1+(1+\lambda^{\gamma})\delta_T]N_{\gamma}(a)\varpi(\omega_{r,t}),$$

because $N_{\gamma}(a) \ge 1$ implies that $N_{\gamma}^{\gamma}(a) \le N_{\gamma}(a)$ for $\gamma \in (0,1)$.

With (47) and (46), we obtain for the third term,

$$|\mathrm{III}_{r,s,t}| \leqslant \eta(\omega_{s,t}) |\epsilon_{s,r}(a)|^{\gamma} \leqslant \lambda^{\gamma} N_{\gamma}(a)^{\gamma} \eta(\omega_{s,t}) \varpi(\omega_{r,s})^{\gamma} \leqslant \lambda^{\gamma} N_{\gamma}(a) \delta_{T} \varpi(\omega_{s,t}),$$

where the last line comes from (6). And for the last term, we use (15) and (47),

$$|IV_{r,s,t}| \leq |\epsilon_{t,s} \circ \phi_{s,r}(a)| + |\epsilon_{t,s}(a)| \leq (N_{\gamma}(\phi_{s,r}) + N_{\gamma}(a))\lambda \varpi(\omega_{s,t})$$

$$\leq (K_T + 1)N_{\gamma}(a)\lambda \varpi(\omega_{s,t}).$$

Thus, combining estimations for each four terms of (49), we obtain (13) which proves that ψ is an almost flow.

Besides,

$$|\psi_{t,s}(a) - \phi_{t,s}(a)| = |\epsilon_{t,s}(a)| \le \lambda N_{\gamma}(a)\varpi(\omega_{s,t}),$$

which proves that $\psi \sim \phi$ and concludes the proof.

6 Applications

On this section, we show that our framework cover former different sewing lemmas.

6.1 The additive sewing lemma

The additive sewing lemma is the key to construct integrals the young integral [27] and the rough integral [25], [21].

We consider that V is a Banach space with a norm $|\cdot|$. The distance d is d(a,b) = |b-a|.

Definition 12 (Almost additive functional). A family $\{\alpha_{s,t}\}_{(s,t)\in\mathbb{T}_2^+}$ is an almost additive functional if

$$\alpha_{r,s,t} := \alpha_{r,s} + \alpha_{s,t} - \alpha_{r,t} \text{ satisfies } |\alpha_{r,s,t}| \leq \varpi(\omega_{r,t}), \ \forall (r,s,t) \in \mathbb{T}_3^+.$$

It is an additive functional if $\alpha_{r,s,t} = 0$ for any $(r,s,t) \in \mathbb{T}_3^+$.

Proposition 3 (The additive sewing lemma [18, 24]). If $\{\alpha_{s,t}\}_{(s,t)\in\mathbb{T}_2^+}$ is an almost additive functional with $|\alpha_{s,t}| \leq \delta_T$, there exists an additive additive functional $\{\gamma_{s,t}\}_{(s,t)\in\mathbb{T}_2^+}$ which is unique in the sense that for any constant $C \geq 0$ and any additive functional $\{\beta_{s,t}\}_{(s,t)\in\mathbb{T}_2^+}$, $|\beta_{s,t} - \alpha_{s,t}| \leq C\varpi(\omega_{s,t})$ implies that $\beta = \gamma$.

Proof. Clearly, $\phi_{t,s}(a) = a + \alpha_{s,t}$ is an almost flow which satisfies the UL condition. Hence the result.

6.2 The multiplicative sewing lemma

Here we recover the results of [18] and [13]. We consider now that the metric space V has a monoid structure. Hence, for any two elements $a, b \in V$, there exists a product which we write ab which belongs in V. We also assume that there exists a Lipschitz function $N: V \to [1, +\infty)$ such that

$$d(ac,bc) \leq N(c)d(a,b)$$
 and $d(ca,cb) \leq N(c)d(a,b)$ for all $a,b,c \in V$.

Definition 13. A family $\{\alpha_{s,t}\}_{(s,t)\in\mathbb{T}_2^+}$ is said to be an almost multiplicative functional if

$$d(\alpha_{r,s}\alpha_{s,t},\alpha_{r,t}) \leq \varpi(\omega_{r,t}), \ \forall (r,s,t) \in \mathbb{T}^3_+.$$

It is a multiplicative functional if $\alpha_{r,s}\alpha_{s,t} = \alpha_{r,t}$.

Proposition 4 (The multiplicative sewing lemma [18]). If $\{\alpha_{s,t}\}_{(s,t)\in\mathbb{T}^2_+}$ is an almost multiplicative functional then there exists a unique multiplicative functional $\{\gamma_{s,t}\}_{(s,t)\in\mathbb{T}^2_+}$ such that any other multiplicative functional $\{\gamma_{s,t}\}_{(s,t)\in\mathbb{T}^2_+}$ such that $d(\beta_{s,t},\alpha_{s,t}) \leq C\varpi(\omega_{s,t})$ for any $(s,t)\in\mathbb{T}^2_+$ satisfies $\beta=\gamma$.

Proof. For this, it is sufficient to consider $\phi_{t,s}(a) = a\alpha_{s,t}$ which is an almost flow which satisfies the UL condition.

Remark 10. Actually, as for the additive sewing lemma (which is itself a subcase of the multiplicative sewing lemma), we have a stronger statement: No (non-linear) flow satisfies $d(\psi_{t,s}(a), a\alpha_{s,t}) \leq C\varpi(\omega_{s,t})$ except $\{a \mapsto a\beta_{s,t}\}_{(s,t)\in\mathbb{T}_+^2}$ which is constructed as the limit of the products of the $\alpha_{s,t}$ over smaller and smaller intervals.

6.3 The multiplicative sewing lemma in a Banach algebra

Consider now that V has a Banach algebra structure with a norm $|\cdot|$ such that $|ab| \leq |a| \times |b|$ and a unit element 1 (the product of two elements is still denoted by ab).

A typical example is the Banach algebra of bounded operators over a Banach space X.

This situation fits in the multiplicative sewing lemma with d(a,b) = |a-b| and N(a) = |a|, $a, b \in V$. As seen in [13], we have many more properties: continuity, existence of an inverse, Dyson formula, Duhamel principle, ...

In particular, this framework is well suited for considering linear differential equations of type

$$y_{t,s} = a + \int_{s}^{t} y_{r,s} d\alpha_r, a \in V, \ t \geqslant s \geqslant 0$$

for an operator valued path $\alpha : \mathbb{T}_2^+ \to V$. If α is γ -Hölder with $\gamma > 1/2$, then $\phi_{t,s}(a) = a(1 + \alpha_{s,t})$ defines an almost flow which satisfies the condition UL (at the price of imposing some conditions on α , this could be extended to $\gamma < 1/2$).

Defining an "affine flow" $\phi_{t,s}(a) = a(1 + \alpha_{s,t}) + \beta_{s,t}$ where both α and β are γ -Hölder with $\gamma > 1/2$, the associated flow ψ is such that $\psi_{t,s}(a)$ is solution to the perturbed equation

$$\psi_{t,s}(a) = a + \int_s^t \psi_{r,s}(a) \, \mathrm{d}\alpha_r + \beta_{s,t}.$$

This gives an alternative construction to the one of [13] where a backward integral between β and α was defined in the style of the Duhamel formula. All these results are extended to the rough case $1/3 < \gamma \le 1/2$.

Example 1 (Lyons extension theorem). With the tensor product \otimes as product and a suitable norm, for any integer k, the tensor algebra

$$T_k(X) := \mathbb{R} \oplus X \oplus X^{\otimes 2} \oplus \cdots \oplus X^{\otimes k}$$

is a Banach algebra. Chen series of iterated integrals (and then rough paths) take their values in some space $T_k(X)$. The Lyons extension theorem states that any rough path \mathbf{x} of finite p-variation with values in $T_k(X)$ for some $k \ge \lfloor p \rfloor$ is uniquely extended to a rough path with values in $T_\ell(X)$ for any $\ell \ge k$, which leads to the concept of signature [24, 25]. This follows $a \mapsto a \otimes \mathbf{x}_{s,t}$ as an almost flow which satisfies the UL condition (see also [18] and also [13]).

6.4 Rough differential equation

Now, we show that our construction is related to the one of A.M. Davie [15]. The main idea is to define an almost flow as the truncated Taylor expansion of the solution of (1). The number of term in the Taylor expansion depends directly on the regularity of x. In the Young case one term is needed whereas in the rough case two terms are required.

Here U and V are two Banach spaces, where we use the same notation $|\cdot|$ to denote their norms which can differ. We denote by $\mathcal{L}(U, V)$ the continuous linear maps from U to V. Let f be a map from V to $\mathcal{L}(U, V)$. If f is regular, we denote its Fréchet derivative in $a \in V$, $df(a) \in \mathcal{L}(V, \mathcal{L}(U, V))$.

Moreover, for any $a \in W$ and $(r, s, t) \in \mathbb{T}_3^+$, we set $\phi_{t,s,r}(a) := \phi_{t,s} \circ \phi_{s,r}(a) - \phi_{t,r}(a)$.

6.4.1 Almost flow in the Young case

Let $x : \mathbb{T} \to U$ be a path of finite p-variation controlled by ω with $1 \leq p < 2$. We define a family $(\phi_{t,s})_{(s,t)\in\mathbb{T}_2^+}$ in $\mathcal{F}(V)$ such that for all $a \in V$ and $(s,t) \in \mathbb{T}_2^+$,

$$\phi_{t,s}(a) := a + f(a)x_{s,t},\tag{50}$$

where $x_{s,t} := x_t - x_s$.

Proposition 5. Assume that $f \in \mathcal{C}^{\gamma}(V, \mathcal{L}(U, V))$, with $1 + \gamma > p$. Then ϕ is an almost flow.

Proof. We check that assumptions of Definition 2 hold. Let (r, s, t) be in \mathbb{T}_3^+ and let a, b be in V. First, $\phi_{t,t}(a) = a$ because $x_{t,t} = 0$. Second,

$$|\phi_{t,s}(a) - a| \leq |f(a)| \cdot |x_{s,t}| \leq |f(a)| \cdot ||x||_p \omega_{s,t}^{1/p},$$

which proves (11). Third,

$$|\phi_{t,s}(a) - \phi_{t,s}(b)| \le |a - b| + |f(a) - f(b)||x_{s,t}| \le |a - b| + ||f||_{\gamma} ||x||_{p} \omega_{s,t}^{1/p} |a - b|^{\gamma},$$

which proves (12). It remains to prove (13). We compute,

$$\phi_{t,s,r}(a) = f(\phi_{s,r}(a))x_{s,t} - f(a)x_{s,t},$$

and we obtain the following estimation

$$|\phi_{t,s,r}(a)| \leq ||f||_{\gamma} ||x||_{p} \omega_{s,t}^{1/p} |\phi_{s,r}(a) - a|^{\gamma} \leq ||f||_{\gamma} ||f(a)|^{\gamma} ||x||_{p}^{2} \omega_{r,t}^{(1+\gamma)/p}$$

$$\leq ||f||_{\gamma} (1 + |f(a)|) ||x||_{p}^{2} \omega_{r,t}^{(1+\gamma)/p}.$$

Setting
$$\varpi(\omega_{r,t}) := \omega_{r,t}^{(1+\gamma)/p}$$
, $\eta(\omega_{s,t}) := \|f\|_{\gamma} \|x\|_{p} \omega_{s,t}^{1/p}$ and
$$N_{\gamma}(a) := (1 + |f(a)|) (\|x\|_{p} + \|f\|_{\gamma} \|x\|_{p}^{2}),$$

it proves that ϕ is an almost flow.

This concludes the proof.

Let ψ be a flow in the same galaxy as the almost flow ϕ . For any $a \in V$ and any $(r,t) \in \mathbb{T}^2_+$, we set

$$y_t(r, a) := \psi_{t,r}(a)$$
 so that $y_r(r, a) = a$.

Clearly, $(r, a) \mapsto (t \in [r, T] \mapsto y_t(r, a))$ is a family of continuous paths which satisfies

$$|y_t(r,a) - \phi_{t,r}(y_s(r,a))| \le CN_{\gamma}(y_s(r,a))\omega_{s,t}^{2/p}, \ \forall (s,t) \in \mathbb{T}_+^2, \ \forall a \in V$$

since $y_t(r, a) = \psi_{t,s}(y_s(r, a))$. Besides, $s \in [r, T] \mapsto N_{\gamma}(y_s(r, a))$ is bounded. Therefore, with our choice of the almost flow ϕ , $\phi_{,r}(a) = y(r, a)$ is a solution in the sense defined by A.M. Davie [15] for the Young differential equation $z_t = a + \int_r^t f(z_s) dx_s$. Even if several solutions may exists for a given (r, a), the flow corresponds to a particular choice of a family of solutions which is constructed thanks to a selection principle. This family of solution is stable under splicing (see Definition 7).

Corollary 3. We assume that V is a finite-dimensional vector space and $f \in \mathcal{C}^1_b(V, \mathcal{L}(U, V))$. Then there exists a flow $\psi \in \mathcal{F}(V)$ in the same galaxy as ϕ such that $\psi_{t,s}$ is Borel measurable for any $(s,t) \in \mathbb{T}^2_+$.

Remark 11. Under our condition on f, A.M. Davie shown that several solutions to the Young differential equation $y = a + \int_0^{\cdot} f(y_s(a)) dx_s$ may exist (Example 1 in [15]). Uniqueness requires f to be $(1 + \gamma)$ -Hölder continuous with $1 + \gamma > p$.

Proof. According to Proposition 6, ϕ is an almost flow. Here $\gamma = 1$, so ϕ is Lipschitz. Then, we conclude the proof in applying Theorem 2 to ϕ .

6.4.2 Almost flow in the rough case

When the regularity of x is weaker than in the Young case, we need more terms in the Taylor expansion to obtain an almost flow.

Let $T_2(U) := \mathbb{R} \oplus U \oplus (U \otimes U)$ be the truncated tensor algebra (with addition + and tensor product \otimes). A distance is defined on the subset of elements of $T_2(U)$ on the form $a = 1 + a^1 + a^2$ with $a^i \in U^{\otimes i}$ by $d(a, b) = |a^{-1} \otimes b|$ where $|\cdot|$ is a norm on $T_2(U)$ such that $|a \otimes b| \leq |a| \cdot |b|$ for any $a, b \in U$.

Let $\mathbf{x} = (1, \mathbf{x}^1, \mathbf{x}^2)$ be a rough path with values in $T_2(\mathbf{U})$ of finite p-variation, $2 \le p < 3$, controlled by ω (See e.g., [19, 24] for a complete definition).

We define a family $(\phi_{t,s})_{(s,t)\in\mathbb{T}_2^+}$ in $\mathcal{F}(\mathbf{V})$ such that for all $a\in\mathbf{V}$ and $(s,t)\in\mathbb{T}_2^+$,

$$\phi_{t,s}(a) := a + f(a)\mathbf{x}_{s,t}^{1} + df(a) \cdot f(a)\mathbf{x}_{s,t}^{2}.$$
(51)

Proposition 6. Assume that $f \in \mathscr{C}_b^{1+\gamma}(V, \mathscr{L}(U, V))$, with $2 + \gamma > p$. Then ϕ is an almost flow.

Proof. We check that the assumptions of Definition 2 hold. The proofs of (10), (11) and (12) are very similar to the ones in the proof of Proposition 5. The computation to show (13) is a bit more involved.

Indeed, for any $a \in V$, $(r, s, t) \in \mathbb{T}_3^+$,

$$\phi_{t,s,r}(a) = -f(a)\mathbf{x}_{s,t}^{1} + f(\phi_{s,r}(a))\mathbf{x}_{s,t}^{1} - df(a) \cdot f(a)(\mathbf{x}_{s,t}^{2} + \mathbf{x}_{r,s}^{1} \otimes \mathbf{x}_{s,t}^{1})$$

$$+ df(\phi_{s,r}) \cdot f(\phi_{s,r}(a))\mathbf{x}_{s,t}^{2}$$

$$= [f(\phi_{s,t}(a)) - f(a) - df(a) \cdot f(a)\mathbf{x}_{r,s}^{1}] \otimes \mathbf{x}_{s,t}^{1}$$

$$+ [df(\phi_{s,r}(a)) \cdot f(\phi_{s,r}(a)) - df(a) \cdot f(a)]\mathbf{x}_{s,t}^{2}$$

$$= \underbrace{f(\phi_{s,t}(a)) - f(a) - df(a) \cdot (\phi_{s,r}(a) - a)}_{I_{r,s,t}} + \underbrace{df(a) \cdot f(a)\mathbf{x}_{r,s}^{2} \otimes \mathbf{x}_{s,t}^{1}}_{II_{r,s,t}}$$

$$+ \underbrace{[df(\phi_{s,t}(a)) \cdot f(\phi_{s,r}(a)) - df(a) \cdot f(a)]\mathbf{x}_{s,t}^{2}}_{III_{r,s,t}}.$$

For the first term,

$$\begin{aligned} |\mathbf{I}_{r,s,t}| &\leq \|\mathbf{d}f\|_{\gamma} \|\mathbf{x}^{1}\|_{p} \omega_{s,t}^{1/p} |\phi_{s,r}(a) - a|^{1+\gamma} \\ &\leq \|\mathbf{d}f\|_{\gamma} \|\mathbf{x}^{1}\|_{p} \omega_{s,t}^{1/p} [\|f\|_{\infty} \|\mathbf{x}^{1}\|_{p} + \|\mathbf{d}f \cdot f\|_{\infty} \|\mathbf{x}^{2}\|_{\frac{p}{2}} \omega_{0,T}^{1/p}]^{1+\gamma} \omega_{r,s}^{(1+\gamma)/p}. \end{aligned}$$

For the two last terms,

$$|\Pi_{r,s,t}| \leq \| df \cdot f \|_{\infty} \| \mathbf{x}^1 \|_p \| \mathbf{x}^2 \|_{\frac{p}{2}} \omega_{r,t}^{3/p} \leq \| df \cdot f \|_{\infty} \| \mathbf{x}^1 \|_p \| \mathbf{x}^2 \|_{\frac{p}{2}} \omega_{0,T}^{(1-\gamma)/p} \omega_{r,t}^{(2+\gamma)/p}$$

and

$$|\mathrm{III}_{r,s,t}| \leqslant \|\mathbf{x}^2\|_{\frac{p}{2}} \omega_{r,t}^{2/p} \left[\|\mathrm{d}f\|_{\gamma} \|f\|_{\infty} |\phi_{s,r}(a) - a|^{\gamma} + \|\mathrm{d}f\|_{\infty} \|f\|_{\mathrm{Lip}} |\phi_{s,r}(a) - a| \right] \leqslant C \omega_{r,t}^{3/p},$$

where C is a constant which depends on f, df, ω , γ , \mathbf{x} . It proves that ϕ is a Lipschitz almost flow.

This concludes the proof.

As for the Young case, any flow ψ in the same galaxy as the almost flow ϕ given by (51) gives rise to a family of solutions in the sense of A.M. Davie [15] to the Rough Differential Equation $z_t = a + \int_0^t f(z_s) d\mathbf{x}_s$.

Corollary 4. We assume that V is a finite-dimensional vector space and $f \in \mathcal{C}^2_b(V, \mathcal{L}(U, V))$. Then there exists a flow $\psi \in \mathcal{F}(V)$ in the same galaxy as ϕ such that $\psi_{t,s}$ is Borel measurable for any $(s,t) \in \mathbb{T}^2_+$.

Remark 12. Under our condition on f, A.M. Davie shown that several solutions to the rough differential equation $y = a + \int_0^r f(y_s(a)) d\mathbf{x}_s$ may exist (Example 2 in [15]). Uniqueness requires f to be $(2 + \gamma)$ -Hölder continuous with $2 + \gamma > p$.

Proof. According to Proposition 6, ϕ is an almost flow. Here $\gamma = 1$, so ϕ is Lipschitz. Then, we conclude the proof in applying Theorem 2 to ϕ .

Acknowledgments

The authors are very grateful to Laure Coutin for her numerous valuable remarks and corrections. We are also grateful to the CIRM (Marseille, France) for its kind hospitality with the Research-in-Pair program.

References

- [1] R. Abraham, J. E. Marsden, and T. Ratiu. *Manifolds, tensor analysis, and applications*. Second. Vol. 75. Applied Mathematical Sciences. Springer-Verlag, New York, 1988. DOI: 10.1007/978-1-4612-1029-0.
- [2] I. Bailleul. A flow-based approach to rough differential equations. Lecture note of a Master 2 course, Université Rennes 1, France, arxiv:1404.0890. 2014.
- [3] I. Bailleul. "Flows driven by rough paths". In: *Rev. Mat. Iberoamericana* 31.3 (2015), pp. 901–934. DOI: 10.4171/RMI/858.

- [4] I. Bailleul and J. Diehl. Rough flows. arxiv:1505.01692. 2015.
- [5] I. Bailleul. "Flows driven by Banach space-valued rough paths". In: Séminaire de Probabilités XLVI. Vol. 2123. Lecture Notes in Math. Springer, Cham, 2014, pp. 195–205. DOI: 10.1007/978-3-319-11970-0_7.
- [6] I. Bailleul. "Regularity of the Itô-Lyons map". In: Confluentes Math. 7.1 (2015), pp. 3–11. DOI: 10.5802/cml.15.
- [7] V Berinde. "On the convergence of the Ishikawa iteration in the class of quasi contractive operators". In: *Acta Math. Univ. Comenianae* 73.1 (2004), pp. 119–126.
- [8] S. Blanes, F. Casas, J. A. Oteo, and J. Ros. "The Magnus expansion and some of its applications". In: *Phys. Rep.* 470.5-6 (2009), pp. 151–238. DOI: 10.1016/j.physrep.2008.11.001.
- [9] A. Brault and A. Lejay. The non-linear sewing lemma II: Lipschitz continuous form. 2018.
- [10] J. Cardona and L. Kapitanski. Measurable process selection theorem and non-autonomous inclusions. Preprint. 2017.
- [11] A. J. Chorin, M. F. McCracken, T. J. R. Hughes, and J. E. Marsden. "Product formulas and numerical algorithms". In: *Comm. Pure Appl. Math.* 31.2 (1978), pp. 205–256.
- [12] L. Coutin. "Rough paths via sewing Lemma". In: ESAIM: PS 16 (2012). Spring School Mons Random differential equations and Gaussian fields, pp. 479–526. DOI: 10.1051/ps/2011108.
- [13] L. Coutin and A. Lejay. "Perturbed linear rough differential equations". In: Ann. Math. Blaise Pascal 21.1 (2014), pp. 103-150. URL: http://ambp.cedram.org/item?id=AMBP_2014_21_1_103_0.
- [14] L. Coutin and A. Lejay. "Sensitivity of rough differential equations: An approach through the Omega lemma". In: *J. Differential Equations* 264.6 (2018), pp. 3899–3917. DOI: 10.1016/j.jde.2017.11.031.
- [15] A. M. Davie. "Differential equations driven by rough paths: an approach via discrete approximation". In: *Appl. Math. Res. Express. AMRX* 2 (2007), Art. ID abm009, 40.
- [16] J. Dieudonné. "Deux exemples singuliers d'équations différentielles". In: Acta Sci. Math. Szeged 12.Leopoldo Fejér et Frederico Riesz LXX annos natis dedicatus, Pars B (1950), pp. 38–40.

- [17] K.-J. Engel and R. Nagel. One-parameter semigroups for linear evolution equations. Vol. 194. Graduate Texts in Mathematics. With contributions by S. Brendle, M. Campiti, T. Hahn, G. Metafune, G. Nickel, D. Pallara, C. Perazzoli, A. Rhandi, S. Romanelli and R. Schnaubelt. Springer-Verlag, New York, 2000.
- [18] D. Feyel, A. de La Pradelle, and G. Mokobodzki. "A non-commutative sewing lemma". In: *Electron. Commun. Probab.* 13 (2008), pp. 24–34. DOI: 10.1214/ECP.v13-1345.
- [19] P. K. Friz and M. Hairer. A course on rough paths. Universitext. With an introduction to regularity structures. Springer, Cham, 2014. DOI: 10.1007/ 978-3-319-08332-2.
- [20] P. K. Friz and N. B. Victoir. Multidimensional stochastic processes as rough paths. Vol. 120. Cambridge Studies in Advanced Mathematics. Theory and applications. Cambridge University Press, Cambridge, 2010. DOI: 10.1017/ CB09780511845079.
- [21] M. Gubinelli. "Controlling rough paths". In: Journal of Functional Analysis 216.1 (2004), pp. 86–140.
- [22] P. Hájek and M. Johanis. "On Peano's theorem in Banach spaces". In: *J. Differential Equations* 249.12 (2010), pp. 3342–3351. DOI: 10.1016/j.jde. 2010.09.013.
- [23] T. Lyons. "Differential equations driven by rough signals. I. An extension of an inequality of L. C. Young". In: *Math. Res. Lett.* 1.4 (1994), pp. 451–464. DOI: 10.4310/MRL.1994.v1.n4.a5.
- [24] T. Lyons and Z. Qian. System control and rough paths. Oxford Mathematical Monographs. Oxford: Oxford University Press, 2002. DOI: 10.1093/acprof: oso/9780198506485.001.0001.
- [25] T. J. Lyons. "Differential equations driven by rough signals". In: Rev. Mat. Iberoamericana 14.2 (1998), pp. 215–310. DOI: 10.4171/RMI/240.
- [26] T. J. Lyons, M. Caruana, and T. Lévy. Differential equations driven by rough paths (Lectures from the 34th Summer School on Probability Theory held in Saint-Flour, July 6–24, 2004). Vol. 1908. Lecture Notes in Mathematics. Berlin: Springer, 2007.
- [27] L. C. Young. "An inequality of the Hölder type, connected with Stieltjes integration". In: Acta Math. 67.1 (1936), pp. 251–282. DOI: 10.1007/BF02401743.
- [28] B. Zheng, L. Zhang, M. Cho, and J. Wu. "A survey of the matrix exponential formulae with some applications". In: *J. Math. Study* 49.4 (2016), pp. 393–428. DOI: 10.4208/jms.v49n4.16.04.