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Finding a subdivision of a prescribed digraph of order 4

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Abstract

The problem of when a given digraph contains a subdivision of a fixed digraph F is considered. Bang-Jensen et al. [2] laid out foundations for approaching this problem from the algorithmic point of view. In this paper we give further support to several open conjectures and speculations about algorithmic complexity of finding F-subdivisions. In particular, up to 5 exceptions, we completely classify for which 4-vertex digraphs F, the F-subdivision problem is polynomial-time solvable and for which it is NP-complete. While all NP-hardness proofs are made by reduction from some version of the 2-linkage problem in digraphs, some of the polynomial-time solvable cases involve relatively complicated algorithms.

1 Introduction

In this paper, all digraphs are meant to be *strict*, that is without loops and without multiple arcs. In one occasion, however, multiple arcs will be allowed. In that case, we will use the term *multidigraph*. We follow standard terminology as used in [1, 4].

A subdivision of a digraph F, also called an F-subdivision, is a digraph obtained from F by replacing each arc ab of F by a directed (a,b)-path. In this paper, we consider the following problem for a fixed digraph F.

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F-SUBDIVISION

Input: A digraph D.

Question: Does D contain a subdivision of F as a subdigraph?

Bang-Jensen et al. [2] conjectured that there is a dichotomy between NP-complete and polynomial-time solvable instances.

Conjecture 1. For every digraph F, the F-SUBDIVISION problem is polynomial-time solvable or NP-complete.

According to this conjecture, there are only two kinds of digraphs F: intractable digraphs F, for which F-SUBDIVISION is NP-complete, and tractable digraphs, for which F-SUBDIVISION is solvable in polynomial-time.

Bang-Jensen et al. [2] proved that many digraphs are intractable; see Theorem 9 in Section 3. In particular, every digraph in which every vertex v is big (that is such that either $d^+(v) \geq 3$, or $d^-(v) \geq 3$, or $d^-(v) = d^+(v) = 2$) is intractable. They also give many examples of tractable digraphs. See Subsection 4. However, there is no clear evidence, of which graph should be tractable and which one should be intractable, despite some results and conjectures give some outline.

Establishing a conjecture of of Johnson et al. [10], Kawabarayashi and Kreutzer [11] proved the Directed Grid Theorem.

Theorem 2 (Kawabarayashi and Kreutzer [11]). For any positive integer k, there exists an integer f(k) such that every digraph with directed treewidth greater than f(k) contains a cylindrical grid of order k as a butterfly minor.

Here, a *cylindrical grid* of order k consists of k concentric directed cycles and 2k directed paths connecting the cycles in alternating directions. See Figure 1 for an illustration. A *butterfly minor* of a digraph D is a digraph obtained from a subgraph of D by contracting arcs which are either the only outgoing arc of their tail or the only incoming arc of their head.

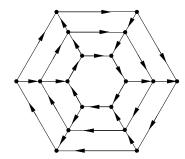


Figure 1: The cylindrical grid of order 3.

Moreover, their proof is algorithmic.

Theorem 3 (Kawabarayashi and Kreutzer [11]). For any positive integer k, there exists an integer f(k) such that given any digraph, in polynomial time, we can obtain either

- a cylindrical grid of order k as a butterfly minor, or
- a directed tree decomposition of width at most f(k).

Because the k-LINKAGE problem (See Section 3 for definitions and details on k-LINKAGE) is polynomial-time solvable on digraph with bounded directed treewidth, for any fixed F, the F-SUBDIVISION is also polynomial-time solvable on digraphs of bounded directed tree-width (see [2]

for more details.). Moreover, by induction on the number of vertices, one can show that for any planar digraph with no big vertices F, there is an integer k_F such that the cylindrical grid of order k_F contains an F-subdivision. Furthermore, if F has no big vertices, then if a minor of D has an F-subdivision, then so does D. (One can uncontract the arcs without any problem because the vertices of F are not big). All these directly imply the following:

Corollary 4. F-Subdivision is polynomial-time solvable when F is a planar digraph with no big vertices.

Proof. On can solve F-Subdivision as follows. Given a digraph D, one runs the algorithm given by Theorem 3. If it returns a cylindrical grid of order k_F , then we return 'Yes' as it contains an F-subdivision. If it returns a directed tree decomposition of width at most $f(k_F)$, then one runs the polynomial-time algorithm to solve F-subdivision for digraphs with directed tree width at most $f(k_F)$.

On the other hand, Bang-Jensen et al. [2] proposed the following sort of counterpart.

Conjecture 5 (Bang-Jensen et al. [2]). F-SUBDIVISION is NP-complete for every non-planar digraph F.

Bang-Jensen et al. [2] were able to classify all digraphs of order at most 3: they are all tractable except the complete symmetric digraph on three vertices, which is intractable. In this paper, we consider digraphs of order 4. We classify all digraphs of order 4 except for five of them (up to directional duality). These are the digraphs O_i for $1 \le i \le 5$ depicted Figure 2.

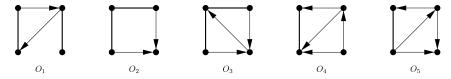


Figure 2: Digraphs on 4-vertices that are not known to be tractable or intractable. Bold undirected edges represent directed 2-cycles.

Theorem 6. Let F be a digraph of order 4 that is not isomorphic to any of O_j for $1 \le j \le 5$. If F contains a directed 2-cycle whose vertices are big or F is one of the graphs N_i depicted in Figure 3 for $1 \le i \le 9$, then F-Subdivision NP-complete. Otherwise F-Subdivision is polynomial-time solvable.

Theorem 6 implies that all oriented graphs of order 4 are tractable. In particular, the wheel W_3 is tractable. The wheel W_k is the graph obtained from the directed cycle on k vertices \vec{C}_k by adding a vertex, called the *centre*, dominating every vertex of \vec{C}_k . In [2], Bang-Jensen et al. proved that W_2 is tractable and that W_k -Subdivision is NP-complete for all $k \geq 4$. The case of W_3 was left as an open problem.

Theorem 6 also completes the classification of tournaments. Bang-Jensen et al. [2] proved that every tournament of order at most 3 is tractable, and that every tournament of order at least 5 is intractable (see Theorem 9). They also show that the transitive tournament of order 4 is tractable. The other tournaments of order four are W_3 , its converse, and ST_4 , the strong tournament of order 4, no vertex of which is big.

In Section 3 we prove some digraphs F to be intractable. To do so, we use a reduction from the NP-complete problem RESTRICTED 2-LINKAGE; given a digraph D without big vertices in which x_1 and x_2 are sources and y_1 and y_2 are sinks, this problem consists in deciding whether there exists

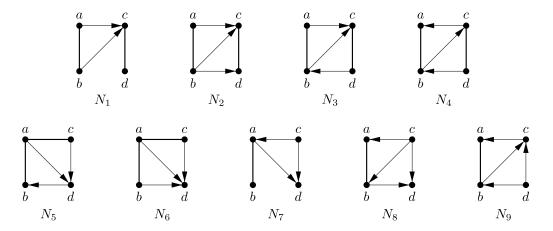


Figure 3: Some intractable digraphs on 4-vertices. Bold undirected edges represent directed 2-cycles.



Figure 4: The 3-wheel W_3 .

two vertex-disjoint directed paths P_1 from x_1 to y_1 and P_2 from x_2 to y_2 . The proofs all use the same technique. Given an instance D, x_1, x_2, y_1, y_2 of RESTRICTED 2-LINKAGE, we construct a digraph D' by putting D on two arcs $e_1 = u_1v_1$ and $e_2 = u_2v_2$ of F, that is by taking the disjoint union of D and F, removing the arcs e_1 and e_2 and adding the arcs u_1x_1, y_1v_1, u_2x_2 and y_2v_2 and show that D' an F-subdivision if and only if there is a 2-linkage from (x_1, x_2) to (y_1, y_2) in D. This implies that F-SUBDIVISION is NP-complete Unfortunately, this technique does not work for O_j , $1 \le j \le 5$. For any pair of arcs e_1 and e_2 of O_j , the existence of an F-subdivision in the digraph D' obtained by putting D on those arcs does not imply the existence of a 2-linkage from (x_1, x_2) to (y_1, y_2) in D.

We then turn out to prove some digraphs of order 4 to be tractable. Since every digraph of order 4 is planar, Corollary 4 implies that digraphs of order 4 with no big vertices are tractable. Before the Directed Grid Theorem was proved, we found elementary proofs to show that result. These proofs can be easily implemented and the derived algorithms are certainly of lower complexity than the ones derived from the Directed Grid Theorem. They can be found in [9]. Consequently, we only consider digraphs with at least one big vertex.

We present in Section 4 some known results and tools, including Menger's Theorem, which we profusely use. Then we scan the digraphs F of vertices with respect to the number of edges in their 2-cycle digraph G_F , which is the graph with vertex set V(F), in which two vertices are linked by an edge if they are in a directed 2-cycle in F. Corollary 10 proved in Section 3, implies that if G_F has three edges, then F is intractable. So we only need to examine digraphs F for which G_F has at most two edges. We first consider the oriented graphs, (for which G_F has no edge). We prove in in Section 5 that all oriented graphs of order 4 are tractable. The main result here is a polynomial-time algorithm solving W_3 -Subdivision (Theorem 21). Next we consider digraphs F for which G_F has one or two edges). We prove that the digraphs E_i , $1 \le i \le 9$, depicted in Figure 5 are tractable. The polynomial-time algorithm to solve E_i -Subdivision is relatively easy for $1 \le i \le 8$, but the one to solve E_9 is more involved. Finally, in Section 7, we summarize all results to prove Theorem 6.

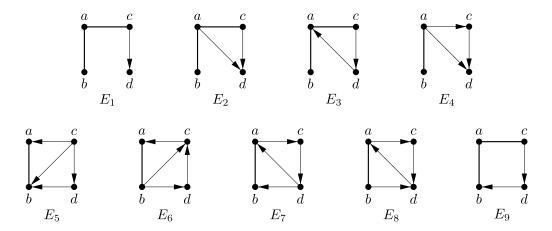


Figure 5: Some tractable digraphs on 4-vertices. Bold undirected edges represent directed 2-cycles.

1.1 Finding an F-subdivision

The letters n and m will always denote the number of vertices and arcs of the input digraph D of the problem in question. By *linear time*, we mean O(n+m) time.

Lemma 7. If F-SUBDIVISION can be solved in f(n,m) time, where f is non-decreasing in m, then there is an algorithm that finds an F-subdivision (if one exists) in a digraph in $((m+1) \cdot f(n,m) + m)$ time.

Proof. Suppose that there exists an algorithm F-decide(D) that decides in f(n,m) whether D contains an F-subdivision. We now construct an algorithm F-find(D) that finds an F-subdivision in D if there is one, and returns 'no' otherwise. It proceeds as follows.

Let a_1, \ldots, a_m be the arcs of D. If F-decide(D) returns 'no', then we also return 'no'. If not, then D contains an F-subdivision, we find it as follows: We initialize $D_0 := D$. For i = 1 to m, $D_i := D_{i-1} \setminus a_i$ if F-decide $(D_{i-1} \setminus a_i)$ returns 'yes', and $D_i := D_{i-1}$ otherwise.

F-find is valid because at step i, we delete the arc a_i if and only if there is an F-subdivision not containing i. Hence at each step i, we are sure that D_i contains an F-subdivision, and that any F-subdivision must contain all the arcs of $A(D_i) \cap \{a_1, \ldots, a_i\}$.

F-find runs (m+1) times the algorithm F-decide and removes at most m times an arc. Therefore, it runs in time $(m+1) \cdot f(n,m) + m$.

Lemma 7 implies that deciding if there is an F-subdivision in a digraph is polynomial-time solvable, if and only if, finding an F-subdivision in a digraph is polynomial-time solvable. Therefore, since we are primarily interested in determining if the problems are polynomial-time solvable or NP-complete, and for sake of clarity, we only present algorithms for solving F-SUBDIVISION as a decision problem. However, the proofs of validity of all given algorithms always rely on constructive claims. Hence each algorithm can be easily transformed into a polynomial-time algorithm for finding an F-subdivision in a given digraph. Moreover, the reader can check that the additional work does not increase the time complexity. Hence, our algorithms for finding F-subdivisions have the same complexity as their decision versions.

2 Definitions and notations

We rely on [1, 4] for standard notation and concepts. Let D be a digraph. The *converse* of D is the digraph \overline{D} obtained from D by reversing the orientation of all arcs. We denote by UG(D) the

underlying (multi)graph of D, that is, the (multi)graph we obtain by replacing each arc by an edge. To every graph G, we can *associate* a symmetric digraph by replacing every edge uv by the two arcs uv and vu.

A source in D is a vertex of indegree zero and a sink is a vertex of outdegree zero.

An oriented graph is an orientation of an undirected graph. In other words, it is a digraph with no directed cycles of length 2. An oriented path is an orientation of an undirected path. Hence an oriented path P is a sequence $(x_1, a_1, x_2, a_2, \ldots, a_{n-1}, x_n)$, where the x_i are distinct vertices and for all $1 \le j \le n-1$, a_j is either the arc $x_j x_{j+1}$ or the arc $x_{j+1} x_j$. For sake of clarity, we often refer to such an oriented path P by the underlying undirected path $x_1 x_2 \ldots x_n$. This is a slight abuse, because the oriented path P is not completely determined by this sequence as there are two possible orientations for each edge. However, when we use this notation, either the orientation does not matter or it is clear from the context.

Let $P=x_1x_2\cdots x_n$ be an oriented path. We say that P is an (x_1,x_n) -path. The vertex x_1 is the *initial vertex* of P and x_n its *terminal vertex*. We denote the initial vertex of P by s(P) and the terminal vertex of P by t(P). The subpath $x_2\cdots x_{n-1}$ is denoted by P° . If x_1x_2 is an arc, then P is an *outpath*, otherwise P is an *inpath*. The path P is *directed* if no vertex is the tail of two arcs in P nor the head of two arcs. In other words, all arcs are oriented in the same direction. There are two kinds of directed paths, namely directed outpaths and directed inpaths. For convenience, a directed outpath is called a *dipath*. The *blocks* of an oriented path P are the maximal directed subpaths of P. We often enumerate them from the initial vertex to the terminal vertex of the path. The number of blocks of P is denoted by P is denoted by P, the opposite path of P, denoted P, is the path P is the path P is the oriented subpath P is P in the oriented subpath P is P in the oriented subpath P in the oriented subpath P is P in the oriented subpath P in the oriented subpath P is the path P in the oriented subpath P in the oriented subpat

The above definitions and notation can also be used for oriented cycles. If $C = x_1x_2...x_nx_1$ is an oriented cycle, we shall assume that either C is a *directed cycle*, that is x_ix_{i+1} is an arc for all $1 \le i \le n$, where $x_{n+1} = x_1$, or both edges of C incident with x_1 are directed outwards, i.e. x_1x_2 and x_1x_n are arcs of C.

For a set X of vertices, the *outsection* of X in D, denoted by $S_D^+(X)$, is the set of vertices that are reachable from X by a dipath. The outsection of a set in a digraph can be found in linear time using the Breadth-First Search. The directional dual notion, the *insection* of X in D is denoted by $S_D^-(X)$.

The digraph D is connected (resp. k-connected) if UG(D) is a connected (resp. k-connected) graph. It is strongly connected, or strong, if for any two vertices u, v, there is a (u, v)-dipath in D. If D is strong, we use the notation D[u, v] to denote any (u, v)-dipath in D. The disjoint union of two digraphs D_1 and D_2 is denoted $D_1 + D_2$.

By contracting a vertex-set $X\subseteq V(D)$ we refer to the operation of first taking the digraph D-X and then adding new vertex v_X and adding the arc v_Xw for each $w\in V(D-X)$ with an inneighbour in X and the arc uv_X for each $u\in V(D-X)$ with an outneighbour in X. The contraction of a non-strong digraph D is the digraph obtained by contracting all strong components of D.

3 Intractable digraphs

Let $x_1, x_2, \ldots, x_k, y_1, y_2, \ldots, y_k$ be distinct vertices of a digraph D. A k-linkage from (x_1, x_2, \ldots, x_k) to (y_1, y_2, \ldots, y_k) in D is a system of disjoint dipaths P_1, P_2, \ldots, P_k such that P_i is an (x_i, y_i) -path in D. Fortune, Hopcroft and Wyllie [7] showed that for any $k \geq 2$, k-LINKAGE is NP-complete. The problem is also NP-complete when restricted to some classes of digraphs. Recall that a vertex v is big if either $d^+(v) \geq 3$, or $d^-(v) \geq 3$, or $d^-(v) = d^+(v) = 2$.

RESTRICTED 2-LINKAGE

Input: A digraph D without big vertices in which x_1 and x_2 are sources and y_1 and y_2 are sinks. Question: Is there a 2-linkage from (x_1, x_2) to (y_1, y_2) in D?

Theorem 8 (Bang-Jensen et al. [2]). The RESTRICTED 2-LINKAGE problem is NP-complete.

Using this theorem, Bang-Jensen et al. [2] deduced a sufficient condition for F-SUBDIVISION to be NP-complete.

For a digraph D, we denote by B(D) the set of its big vertices. A big path in a digraph is a directed path whose endvertices are big and whose internal vertices all have both indegree and outdegree equal to 1 in D (in particular an arc between two big vertices is a big path). Note also that two big paths with the same endvertices are necessarily internally disjoint.

The big paths digraph of D, denoted BP(D), is the multidigraph with vertex set B(D) in which there are as many arcs between two vertices u and v as there are big (u, v)-paths in D.

Theorem 9 (Bang-Jensen et al. [2]). Let F be a digraph. If F contains two arcs ab and cd whose endvertices are big vertices and such that $(BP(F)\setminus\{ab,cd\})\cup\{ad,cb\}$ is not isomorphic to BP(F), then F-Subdivision is NP-complete.

Corollary 10. Let F be a digraph. If F contains a directed cycle of length 2 whose vertices are big, then F-Subdivision is NP-complete.

So far, all known intractable digraphs were proved intractable by a reduction from RESTRICTED 2-LINKAGE. This paper is no exception: we now show that some digraphs are NP-hard with such reductions.

Proposition 11. For each digraph N_i , $1 \le i \le 9$, depicted in Figure 3, N_i -Subdivision is NP-complete.

Proof. In each case, the problem is proved to be NP-complete by reduction from RESTRICTED 2-LINKAGE. Let D, x_1 , x_2 , y_1 and y_2 be an instance of this problem. We construct a digraph D_i by putting D on two arcs $e_1 = u_1v_1$ and $e_2 = u_2v_2$ of N_i (that will be specified later), that is by taking the disjoint union of D and N_i , removing the arcs e_1 and e_2 and adding the arcs u_1x_1 , y_1v_1 , u_2x_2 and y_2v_2 . We then show that D_i contains an N_i -subdivision if and only if there is a 2-linkage from (x_1, x_2) to (y_1, y_2) in D. This implies that N_i -SUBDIVISION is NP-complete.

Clearly, by construction of D_i , if there is a 2-linkage from (x_1, x_2) to (y_1, y_2) in D, then D_i contains an N_i -subdivision. We now prove the converse for each i. In each case we shall assume that D_i contains an N_i -subdivision S, and we shall denote by a', b', c', d' the vertices in S corresponding to a, b, c, d, respectively.

- i=1: We choose $e_1=ab$ and $e_2=cd$. Since D contains no big vertices, we have c'=c. Because $d_{D_1}^-(c)=3$, the arcs ac, bc and dc are in S. Moreover, the arc ba is in S, because every vertex has indegree at least 1 in S. Thus $d_S^+(b)\geq 2$, and so either b=b' or b=a'. By symmetry between a and b in N_1 , we may assume that b=b'. Then, necessarily, a=a'. Therefore, in S, there are disjoint (a,b)- and (c,d)-dipaths. These two paths induce a 2-linkage from (x_1,x_2) to (y_1,y_2) in D.
- $i \in \{2,3,4\}$: We choose $e_1 = ab$ and $e_2 = cd$. Since D contains no big vertices, we have $\{b,c\} = \{b',c'\}$. Therefore, the arc bc is contained in S, and this shows that b' = b and c' = c. Now for degree reasons, all arcs incident to b and c must be in S. It follows that a' = a and d' = d. (This is clear for N_3 and N_4 . For N_2 , we first conclude that $\{a',d'\} = \{a,d\}$ and then consider degrees of a and d to obtain the same conclusion.) Therefore, in S, there are disjoint (a,b)- and (c,d)-dipaths. These two paths induce a 2-linkage from (x_1,x_2) to (y_1,y_2) in D.
- i = 5: We choose $e_1 = ba$ and $e_2 = cd$. Since D contains no big vertices, we have a' = a. Hence all the arcs incident to a (ac, ca, ad, ab, y_1a) are in A(S). Therefore, since aca is a 2-cycle and it is in

S, c is either b' or c'. But $d^-(c)=1$, so c cannot be b' since b' must have indegree at least 2, and thus c=c'. All vertices have outdegree at least 1 in S, so $db \in A(S)$ since we know that the arc ad and therefore d is in S. Now there are two internally disjoint (a',b)-dipaths in S-c', then necessarily b=b', since there should be two disjoint paths from a' to b' in S-c' and they should use the arcs ad and ab that we have already conclude they must belong to S. Moreover, d' must be in one of those dipaths, so d=d'. Therefore, in S, there are internally disjoint (b,a)- and (c,d)-dipaths. These two paths induce a 2-linkage from (x_1,x_2) to (y_1,y_2) in D.

- i=6: We choose $e_1=ab$ and $e_2=cd$. Since D contains no big vertices, we have a'=a and d'=d. Hence all arcs incident to those two vertices are in S. Therefore $\{b',c'\}=\{b,c\}$. By symmetry of N_6 , we may assume that b'=b and c'=c. Therefore, in S, there are disjoint (a,b)-and (c,d)-dipaths. These two paths induce a 2-linkage from (x_1,x_2) to (y_1,y_2) in D.
- i=7: We choose $e_1=ab$ and $e_2=cd$. Since D contains no big vertices, we have a'=a. Hence all arcs incident to a are in S. So c and d are in V(S). Since $d_{D_7}^+(d)=0$, we have d=d'; since $d_{D_7}^-(c)=0$, we have c=c'. Therefore, in S, there are disjoint (a,b)- and (c,d)-dipaths. These two paths induce a 2-linkage from (x_1,x_2) to (y_1,y_2) in D.
- i=8: We choose $e_1=ab$ and $e_2=cd$. Since D contains no big vertices, we have b'=b and c'=c. Hence all arcs incident to those two vertices are in S. So $d\in V(S)$. Since $d_{D_8}^+(d)=0$, it follows that d=d'. The arcs ba and ca show that $d_S^-(a)\geq 2$. Thus a=a'. Therefore, in S, there are disjoint (a,b)- and (c,d)-dipaths. These two paths induce a 2-linkage from (x_1,x_2) to (y_1,y_2) in D.
- i=9: We choose $e_1=ab$ and $e_2=dc$. Since D contains no big vertices, we have b'=b. Hence all arcs incident to b are in S. In particular $c,d\in V(S)$. Since $d_{D_9}^-(d)=0$, we have d'=d. Since $d_S^+(c)\geq 1$, the arc ca is in A(S), so $d_S^-(a)=2$, and thus $a\in\{a',c'\}$. Since a' and c' are both in the outsection of d in N_9-b , S contains a (d,a)-dipath disjoint from b. This dipath must pass through c and therefore the arc y_2c lies in S. This implies that $d_S^-(c)\geq 2$, so c=c' and then we have a=a'. Consequently, in S, there are disjoint (a,b)- and (d,c)-dipaths. These two paths induce a 2-linkage from (x_1,x_2) to (y_1,y_2) in D.

4 Known results and tools for *F***-**SUBDIVISION

4.1 Menger's Theorem

Let X and Y be two sets of vertices in a digraph D. An (X,Y)-dipath is a dipath with initial vertex in X, terminal vertex in Y and all internal vertices in $V(D) \setminus (X \cup Y)$. For notational clarity, for a vertex x (resp. a subdigraph S of D), we abbreviate $\{x\}$ to x (resp. V(S) to S) in the notation. For example, an (x,S)-dipath is an $(\{x\},V(S))$ -dipath.

Let D be a digraph, and let x and y be distinct vertices of D. Two (x,y)-paths P and Q are internally disjoint if they have no internal vertices in common, that is, if $V(P) \cap V(Q) = \{x,y\}$. A k-separation of (x,y) in D is a partition (W,S,Z) of its vertex set such that $x \in W$, $y \in Z$, $|S| \le k$, each vertex in W can be reached from x by a dipath in D[W], and there is no arc from W to Z.

One version of the celebrated Menger's Theorem is the following.

Theorem 12 (Menger). Let k be a positive integer, let D be a digraph, and let x and y be distinct vertices in D such that $xy \notin A(D)$. Then, in D, either there are k+1 pairwise internally disjoint (x,y)-dipaths, or there is a k-separation of (x,y).

For any fixed k, there exist algorithms running in linear time that, given a digraph D and two distinct vertices x and y such that $xy \notin A(D)$, returns either k+1 internally disjoint (x,y)-dipaths in D, or a k-separation (W,S,Z) of (x,y). Indeed, in such a particular case, any flow algorithm like

Ford–Fulkerson algorithm for example, performs at most k+1 incrementing-path searches, because it increments the flow by 1 each time, and we stop when the flow has value k+1, or if we find a cut of size less than k+1, which corresponds to a k-separation. Moreover each incrementing-path search consists in a search (usually Breadth-First Search) in an auxiliary digraph of the same size, and so is done in linear time. For more details, we refer the reader to the book of Ford and Fulkerson [6] or Chapter 7 of [4]. We call such an algorithm a *Menger algorithm*.

Observe that using Menger algorithms, one can decide if there are k internally disjoint (x, y)-dipaths in a digraph D. If $xy \notin A(D)$, then we apply a Menger algorithm directly; if $xy \in A(D)$, then we check whether there are k-1 internally disjoint (x, y)-dipaths in $D \setminus xy$.

Let D be a digraph. Let X and Y be non-empty sets of vertices in D. Two (X,Y)-dipaths P and Q are *disjoint* if they have no vertices in common, that is if $V(P) \cap V(Q) = \emptyset$. A k-separation of (X,Y) in D is a partition (W,S,Z) of its vertex set such that $X \subseteq W \cup S$, $Y \subseteq Z \cup S$, $|S| \le k$, all vertices of W can be reached from $X \setminus S$ by dipaths in D[W], and there is no arc from W to Z.

Let x be a vertex of D and Y be a non-empty subset of $V(D) \setminus \{x\}$. Two (x,Y)-dipaths P and Q are *independent* if $V(P) \cap V(Q) = \{x\}$. A k-separation of (x,Y) in D is a partition (W,S,Z) of its vertex set such that $x \in W$, $Y \subseteq Z \cup S$, $|S| \le k$, all vertices of W can be reached from x by dipaths in D[W], and there is no arc from W to Z.

Let y be a vertex of D and X be a non-empty subset of $V(D) \setminus \{y\}$. Two (X,y)-paths are independent if $V(P) \cap V(Q) = \{y\}$. A k-separation of (X,y) in D is a partition (W,S,Z) of its vertex set such that W and Z are non-empty, $X \subseteq W \cup S$, $y \in Z$, $|S| \le k$, all vertices of W can be reached from $X \setminus S$ by dipaths in D[W], and there are no arcs from W to Z.

Let $W \subset V(D)$. The digraph D_W is the one obtained from D by adding a vertex s_W and the arcs $s_W w$ for all $w \in W$ and the digraph D^W is the one obtained from D by adding a vertex t_W and the arcs wt_W for all $w \in W$.

Applying Theorem 12 to D_X^Y and (s_X, t_Y) (resp. D^Y and (x, t_Y) , D_X and (s_X, y)), we obtain the following version of Menger's Theorem.

Theorem 13 (Menger). Let k be a positive integer, and let D be a digraph. Then the following hold.

- (i) If X and Y are two non-empty subsets of V(D), then, in D, either there are k+1 pairwise disjoint (X,Y)-dipaths, or there is a k-separation of (X,Y).
- (ii) If x is a vertex of D and Y is a non-empty subset of V(D), then, in D, either there are k+1 pairwise independent (x,Y)-dipaths in D, or there is a k-separation of (x,Y).
- (iii) If X is a non-empty subset of V(D) and y is a vertex of D and , then, in D, either there are k+1 pairwise independent (X,y)-dipaths in D, or there is a k-separation of (X,y).

Moreover, a Menger Algorithm applied to D_X^Y and (s_X, t_Y) (resp. D^Y and (x, t_Y) , D_X and (s_X, Y)) finds in linear time the k+1 dipaths or the separation as described in Theorem 13 (i) (resp. (ii), (iii)).

Let x and y be two vertices. An (x,y)-handle is an (x,y)-dipath if $x \neq y$, and a directed cycle containing x if x = y. Let y_1, \ldots, y_p be p distinct vertices, k_1, \ldots, k_p be positive integers and set $k = k_1 + \cdots + \cdots + k_p$. One can decide if there are k internally disjoint handles P_1, \ldots, P_k such that k_i of them are (x,y_i) -handles, $1 \leq i \leq p$, by applying a Menger algorithm between in an auxiliary digraph D'. This digraph is obtained from $D - (\{y_1, \ldots, y_p\} \setminus \{x\})$ as follows. Add a new vertex y. For each i, create a set B_i of k_i new vertices and all arcs from $N_D^-(y_i)$ to B_i and from B_i to y.

Similarly, suppose that X is a set of vertices, y_1, \ldots, y_p be p distinct vertices not in X, and $k = k_1 + \cdots + \cdots + k_p$. One can decide if there are k internally disjoint paths P_1, \ldots, P_k , all with distinct initial vertices in X, and such that k_i of them are terminating in $y_i, 1 \le i \le p$.

4.2 Subdivision with prescribed original vertices

Let F be a digraph and u a vertex in F. In an F-subdivision S, the vertex corresponding to u is called the u-vertex of S. A vertex corresponding to some vertex $u \in F$ is called an original vertex.

Bang-Jensen et al. [2] proved that, given a digraph D and a vertex z in D, one can decide in polynomial time if D contains a W_2 -subdivision with centre z. Therefore W_2 -SUBDIVISION is polynomial-time solvable. We now prove that we can also decide in polynomial time if there is a W_2 -subdivision with two prescribed original vertices.

Lemma 14. Let W_2 be the 2-wheel with centre c and rim aba. Given a digraph D and two vertices b' and c', one can decide in $O(n^2(n+m))$ time if there is a W_2 -subdivision in D with b-vertex b' and c-vertex c'.

Proof. Let us call a W_2 -subdivision with b-vertex b' and c-vertex c' a (b', c')-forced W_2 -subdivision. Let S be the strong component of b' in D - c'. The key element is the following claim.

Claim 14.1. D contains a (b',c')-forced W_2 -subdivision if and only if there exist distinct vertices x_1 and x_2 in V(S) such that there are two independent $(c',\{x_1,x_2\})$ -dipaths P_1 and P_2 in $D-(S\setminus\{x_1,x_2\})$ and there are two independent $(\{x_1,x_2\},b')$ -dipaths Q_1 and Q_2 in S.

Subproof. Clearly, existence of two vertices x_1, x_2 and four dipaths P_1, P_2, Q_1, Q_2 as in the statement is a necessary condition for the existence of a (b',c')-forced W_2 -subdivision. Let us now prove that it is also sufficient. Assume that such vertices x_1, x_2 and dipaths P_1, P_2, Q_1, Q_2 exist. Since S is strong, it contains a dipath R from b' to $(V(Q_1) \cup V(Q_2)) \setminus \{b'\}$. (This set is not empty since it contains $\{x_1, x_2\} \setminus \{b'\}$.) Then $P_1 \cup P_2 \cup Q_1 \cup Q_2 \cup R$ is a (b', c')-forced W_2 -subdivision.

Our algorithm is the following. We first compute S, which can be done in linear time. Then for every pair $\{x_1, x_2\}$ of vertices of S, we check by running twice a Menger algorithm if the dipaths P_1 and P_2 , and Q_1 and Q_2 as described in Claim 14.1 exist. If yes, we return 'yes', otherwise we return 'no'. The validity of this algorithm is given by Claim 14.1. Since there are $O(n^2)$ pairs of vertices $\{x_1, x_2\}$, the algorithm runs in $O(n^2(n+m))$ time.

A *spider* is a tree obtained from disjoint directed paths by identifying one end of each path into a single vertex. This vertex is called the *body* of the spider. Observe that if T is a spider, then every T-subdivision contains T as a subdigraph. Hence a digraph contains a T-subdivision if and only if it contains T as a subdigraph. This implies that T-SUBDIVISION can be solved in $O(n^{|T|})$ time. It also easily implies the following.

Lemma 15. Let F be a digraph and T a spider. If F is tractable, then F + T is also tractable.

Gluing a spider T with body b to F at a vertex $u \in V(F)$ consists in taking the disjoint union of F and T and identifying u and b.

Lemma 16. Let F be a digraph and u a vertex of F. If given a digraph D and a vertex v of D, one can decide in polynomial time if there is an F-subdivision in D such that v is the u-vertex, then any digraph obtained from F by gluing a spider at u is tractable.

Proof. Let T be a spider with body b and let F' be the digraph obtained by gluing T to F at u. Clearly, every F'-subdivision contains an F'-subdivision in which the arcs of T are not subdivided. Such an F'-subdivision is said to be *canonical*.

Consider the following algorithm. For every vertex v we repeat the following. For every set W of |V(T)|-1 vertices, we check whether $D[W\cup\{v\}]$ contains a copy of T with body v. This can be done in constant time. Then we check if D-W contains an F-subdivision with u-vertex v. This can be done in polynomial time by our assumption.

This algorithm clearly decides in polynomial time whether a given digraph D contains a canonical F'-subdivision.

A (k_1, \ldots, k_p) -spindle is the union of p pairwise internally disjoint (a, b)-dipaths P_1, \ldots, P_p of respective lengths k_1, \ldots, k_p . The vertex a is said to be the *tail* of the spindle and b its *head*. Bang-Jensen et al. [2] proved that spindles are tractable. Their proof uses the following result.

Theorem 17 (Bang-Jensen et al. [2]). Let F be a spindle with tail a and head b. Given a digraph D and two vertices a' and b', we can decide in polynomial time if D contains an F-subdivision with a-vertex a' and b-vertex b'.

The $(k_1,\ldots,k_p;l_1,\ldots,l_q)$ -bispindle, denoted $B(k_1,\ldots,k_p;l_1,\ldots,l_q)$, is the digraph obtained from the disjoint union of a (k_1,\ldots,k_p) -spindle with tail a_1 and head b_1 and an (l_1,\ldots,l_q) -spindle with tail a_2 and head b_2 by identifying a_1 with b_2 into a vertex a, and a_2 with b_1 into a vertex b. The vertices a and b are called, respectively, the *left node* and the *right node* of the bispindle. The directed (a,b)-paths are called the *forward paths*, while the directed (b,a)-paths are called the *backward paths*. Bang-Jensen et al. [2] proved that a bispindle is intractable if and only if $p \geq 1$, $q \geq 1$ and $p + q \geq 4$. To prove that a bispindle with two forward paths and one backward path is tractable, they provided the following theorem.

Theorem 18 (Bang-Jensen et al. [2]). Let F be a bispindle with two forward paths and one backward path, and let x be one of its nodes. Given a digraph D and a vertex a', we can decide in polynomial time if D contains an F-subdivision with a-vertex a'.

Lemma 19. Let F be a digraph and let u_1, \ldots, u_p be distinct vertices of F. Suppose that for every outneighbour v of u_1 , replacing the arc u_1v by a dipath u_1wv of length 2, where $w \notin V(F)$, always results in the same digraph F'. Suppose that for every given digraph D of order n and p vertices x_1, \ldots, x_p in D, one can decide in f(n) time whether there is an F-subdivision in D such that x_i is the u_i -vertex for every i. Then given a digraph D and p vertices x_1, \ldots, x_p , one can decide in $O\left(\binom{d^+(x_1)-1}{d^+(u_1)-1}\sum_{y\in N^+(x_1)}d^+(y)\cdot f(n-1)\right)$ time whether there is an F'-subdivision in D such that x_i is the u_i -vertex for every i.

Proof. Set $q=d^+(u_1)$. For every set of q neighbours y_1,\ldots,y_q of x_1 and every outneighbour z of y_1 , where $z\notin\{y_2,\ldots,y_q\}$, we shall give a procedure that verifies if D contains an F'-subdivision S' such that x_i is the u_i -vertex for all $1\leq i\leq p$, and $\{x_1y_1,\ldots,x_1y_q,y_1z\}\subseteq A(S')$. Such an F'-subdivision is called *forced*.

Let D' be the digraph obtained from $D-y_1$ by deleting all arcs leaving x_1 except x_1y_2, \ldots, x_1y_q , and adding the arc x_1z .

Claim 19.1. D has a forced F'-subdivision if and only if D' has an F-subdivision such that x_i is the u_i -vertex for every i.

Subproof. Suppose that S is an F-subdivision in D' such that x_i is the u_i -vertex for all i. Since x_1 has outdegree q in D', we have $\{x_1y_2, \ldots, x_1y_q, x_1z\} \subseteq A(S)$. Let S' be the digraph obtained from S by replacing the arc x_1z by the dipath x_1y_1z . Because replacing the arc u_1v by a dipath of length S' results in S' for any outneighbour S' of S' is an S'-subdivision in S'. Thus S' is a forced S'-subdivision in S'.

Conversely, assume that S' is a forced F'-subdivision in D. Then the digraph S obtained from S' by replacing the dipath x_1y_1z by the arc x_1z is an F-subdivision in D' such that x_i is the u_i -vertex for every i.

This claim implies that deciding whether D contains a forced F'-subdivision can be done by checking whether D' has an F-subdivision such that x_i is the u_i -vertex for all i. This can be done

in f(n-1) time by assumption. By repeating this for every possible set $\{y_1,\ldots,y_q,z\}$ where the y_i 's are distinct outneighbours of x_1 and $z \notin \{y_2,\ldots,y_q\}$ is an outneighbour of y_1 , we obtain an algorithm to decide whether there is an F'-subdivision in D such that x_i is the u_i -vertex for all i. Since there are at most $\binom{d^+(x_1)-1}{d^+(u_1)-1}\sum_{y\in N^+(x_1)}d^+(y)$ such sets, the running time of this algorithm is as claimed.

5 Oriented graphs of order 4

The aim of this section is to prove that every oriented graph of order 4 is tractable.

Theorem 20. *If F is an oriented graph of order* 4*, then F*-SUBDIVISION *is polynomial-time solvable.*

Proof. If F has no big vertices, then by Theorem 2, F-SUBDIVISION is polynomial-time solvable. Henceforth, we assume that F has at least one big vertex. Free to consider its converse, we may assume that F has a vertex with out-degree 3. Necessarily, we must be in one the following three cases:

(i) |A(F)| = 6. Then F is either the transitive tournament TT_4 , or the wheel W_3 . Bang-Jensen et al. [2] (Theorem 64) proved that TT_4 -SUBDIVISION is polynomial-time solvable. We show in Subsection 5.1 that W_3 is tractable.

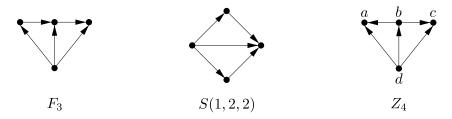


Figure 6: Oriented graphs with 4 vertices, 5 arcs, and a vertex of out-degree 3

- (ii) |A(F)| = 5. Then F must be one of the oriented graphs depicted Figure 6. S(1,2,2) is a spindle and F_3 is the 3-fan. These digraphs have been shown to be tractable in [2] (Proposition 20 and Theorem 61). We prove in Subsection 5.2 that Z_4 is tractable.
- (iii) $|A(F)| \le 4$. Then F is either a star or a star plus an arc. Those digraphs have been proved to be tractable in [2].

5.1 Subdivision of the 3-wheel

Theorem 21. W_3 -Subdivision can be solved in $O(n^6(n+m))$ time.

The proof of this theorem relies on the following notion. Let X be a set of three vertices. An X-tripod is a digraph which is the union of a directed cycle C and three disjoint dipaths P_1, P_2, P_3 with initial vertices in X and terminal vertices in C. If the P_i are (X, C)-dipaths, we say that the tripod is unfolded. Note that the dipaths P_i may be of length 0. We shall denote the tripod described above as the 4-tuple (C, P_1, P_2, P_3) .

Proposition 22. Let $X = \{x_1, x_2, x_3\}$ be a set of three distinct vertices. Any X-tripod contains an unfolded X-tripod.

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We shall consider the following decision problem.

TRIPOD

Input: A strong digraph D and a set X of three distinct vertices of D.

Question: Does D contain an X-tripod?

Lemma 23. TRIPOD can be solved in $O(n^2(n+m))$ time.

Proof. Let us describe a procedure tripod(D, X), solving TRIPOD.

We first look for a directed cycle of length at least 3 in D. This can be done in linear time. If there is no such cycle, then we return 'no'.

Otherwise we have a directed cycle C of length at least 3. We choose a set Y of three vertices in C and run a Menger algorithm between X and Y. If such an algorithm finds three disjoint (X,Y)-dipaths P_1, P_2, P_3 , then we return the tripod (C, P_1, P_2, P_3) . Otherwise, the Menger algorithm finds a 2-separation (W, S, Z) of (X, Y). Note that $|S| \ge 1$ because D is strong.

Assume first that |S|=1, say $S=\{s\}$. Let D_1 be the digraph obtained from $D[W\cup S]$ by adding the arc sw for every vertex w in W having an inneighbour $z\in Z$. We then make a recursive call to tripod (D_1,X) . This is valid by virtue of the following claim.

Claim 23.1. There is an X-tripod in D if and only if there is an X-tripod in D_1 .

Subproof. Suppose first that there is an X-tripod in D_1 . Then D_1 contains an unfolded X-tripod T_1 by Proposition 22. If T_1 is contained in D, then we are done. So we may assume that it is not. Then T_1 contains an arc $sw \in A(D_1) \setminus A(D)$. It can contain only one such arc since every vertex has outdegree at most one in T_1 and all such arcs leave s. Furthermore, the head w of this arc is in W and w has an inneighbour z in Z. Now, since D is strong, there is an (s, z)-dipath Q in D. Because there is no arc from W to Z, all internal vertices of Q are in Z. Hence the digraph T obtained from T_1 by replacing the arc sw by the dipath Qzw is an X-tripod in D.

Suppose now that D contains an X-tripod. Then it contains an unfolded X-tripod $T=(C_1,P_1,P_2,P_3)$ by Proposition 22. Since all (X,Z)-dipaths in D go through s, the terminal vertices of the P_i are in $W \cup S$, and $D[Z] \cap T$ is a dipath Q which is a subpath of one of the P_i or C_1 . If Q is a (t,z)-dipath, then T contains arcs st and st for some st for some st for some st then st dipath st obtained from st by replacing st by the arc st is an st-tripod in st .

Assume now that |S|=2, say $S=\{s_1,s_2\}$. If there is no arc from Z to W, let D_2 be the digraph obtained from $D[W\cup S]$ by adding the arc s_1s_2 (resp. s_2s_1) (if the arc is not already present in D) if there is an (s_1,s_2) -dipath (resp. (s_2,s_1) -dipath) in $D[Z\cup S]$. We then make a recursive call to tripod (D_2,X) . This is valid by virtue of the following claim.

Claim 23.2. There is an X-tripod in D if and only if there is an X-tripod in D_2 .

Subproof. Suppose first that there exists an X-tripod in D_2 . Then there is an unfolded X-tripod T_2 in D_2 , by Proposition 22. Then either it is an X-tripod in D, or T_2 contains exactly one of the arcs s_1s_2, s_2s_1 and this arc is not in A(D). Without loss of generality, we may assume that this arc is s_1s_2 . Since $s_1s_2 \in A(D_2) \setminus A(D)$, there is an (s_1, s_2) -dipath Q in $D[Z \cup S]$. Hence the digraph T obtained from T_2 by replacing the arc s_1s_2 by the dipath Q is an X-tripod in D.

Suppose now that D contains an X-tripod. Then it contains an unfolded X-tripod $T=(C_2,P_1,P_2,P_3)$ by Proposition 22. For i=1,2,3, let y_i be the terminal vertex of P_i . Without loss of generality, we may assume that y_1,y_2,y_3 appear in this order along C_2 . Since all $(X,Z\cup S)$ -dipaths intersect S, one of the y_i , say y_3 , must be in W. The three oriented paths P_2 , $P_1C_2[y_1,y_2]$, and $\overline{C_2}[y_3y_2]$ are independent (W,y_2) -paths. But the graph underlying D has no edges between W and Z, by the assumption made in the current subcase. So y_2 is in $W\cup S$. Similarly, y_1 is in $W\cup S$. It follows that $T\cap D[Z]$ is a dipath Q which is a subpath of one of the P_i or C_2 . Moreover, the

inneighbour in T of the initial vertex of Q is some vertex $s \in S$ (because there is no arc from W to Z) and the outneighbour in T of the terminal vertex of Q is some vertex $s' \in S$ because there is no arc from Z to W). Furthermore $s \neq s'$ for otherwise $sQs' = C_2$ which is impossible as since $y_3 \in W \cap C_2$. Moreover, because sQs' is an (s,s')-dipath in $D[Z \cup S]$, ss' is an arc in D_2 . Thus the digraph T_2 obtained from T by replacing sQs' by the arc ss' is an X-tripod in D_2 .

Now we may assume that there is an arc z_1w_1 with $z_1 \in Z$ and $w_1 \in W$. Since D is strong, there is a cycle C' containing the arc z_1w_1 . Necessarily, the cycle C' must go through S and it contains at least three vertices.

<u>Case 1</u>: $S \subset V(C')$. Set $Y' = \{w_1, s_1, s_2\}$. We run a Menger algorithm between X and Y'. If such an algorithm finds three disjoint (X, Y')-dipaths P'_1, P'_2, P'_3 , then we return the X-tripod (C', P'_1, P'_2, P'_3) .

If not, we obtain a 2-separation (W',S',Z') of (X,Y'). We claim that |W'|<|W|. Indeed, no vertex $z\in Z$ is in W' because every (X,z)-dipath must go through S and thus through S'. Hence $W'\subseteq W\setminus\{w_1\}$. Now, we replace C by C', Y by Y' and (W,S,Z) by (W',S',Z'), and then redo the procedure.

<u>Case 2</u>: $|S \cap V(C')| = 1$. Without loss of generality, we may assume $S \cap V(C') = \{s_1\}$. Set $Y' = \{w_1, s_1, z_1\}$. As in Case 1, we run a Menger algorithm between X and Y'. If such an algorithm finds three disjoint (X, Y')-dipaths P'_1, P'_2, P'_3 , then we return the X-tripod (C', P'_1, P'_2, P'_3) .

If not, the Menger algorithm returns a 2-separation (W',S',Z') for (X,Y'). Observe that there is a vertex $s_1' \in S' \cap W$ because w_1 is reachable from X in D[W]. If S' contains a vertex s_2' in Z, then one can see that there are no (X,Y')-dipaths in $D-\{s_1',s_2\}$. Thus, there is a 2-separation (W'',S'',Z'') of (X,Y') where $S''\subseteq\{s_1',s_2\}$ and $s_1\in Z''$. Hence, after possibly replacing the 2-separation (W',S',Z') by (W'',S'',Z''), we may assume that $S'\subset W\cup S$.

If |W'| < |W|, then we set C := C', Y := Y', (W, S, Z) := (W', S', Z'), and redo the procedure.

If not, then the set $R = Z \cap W'$ is not empty. Set $L = Z \setminus R = Z \cap Z'$. There is no arc from R to L, because (W', S', Z') is a 2-separation. Moreover, all (X, R)-dipaths must go through s_2 . In particular, $s_2 \in W'$. Let D_3 be the digraph obtained from D - L by adding an arc s_1w for every $w \in W$ having an inneighbour in L. We then make a recursive call to $\texttt{tripod}(D_3, X)$. This is valid by virtue of the following claim.

Claim 23.3. There is an X-tripod in D if and only if there is an X-tripod in D_3 .

Subproof. Suppose first that D_3 contains an X-tripod. Then it contains an unfolded X-tripod T_3 by Proposition 22. If T_3 is contained in D, then we are done. So we may assume that T_3 is not contained in D. Then T_3 contains an arc in $s_1w \in A(D_3) \setminus A(D)$. It contains only one such arc since every vertex has outdegree at most one in T_3 and all arcs of $A(D_3) \setminus A(D)$ leave s_1 . Furthermore the head w of this arc is in W and has an inneighbour $z \in L$. Since D is strong, there is an (s_1, z) -dipath Q in D. Moreover since $s_2 \in W'$ all the (s_2, z) -dipaths must go through S'. But $S' \subseteq W \cup \{s_1\}$, so all (s_2, z) -dipaths must go through s_1 . Thus Q does not go through s_2 . It follows that all internal vertices of Q are in Z, because (W, S, Z) is a 2-separation, and so in L because there is no arc from R to L. Consequently, the digraph T obtained from T_3 by replacing the arc s_1w by the dipath Qzw is an X-tripod in D.

Suppose now that D contains an X-tripod. Then it contains an unfolded X-tripod $T=(C_3,P_1,P_2,P_3)$ by Proposition 22. For i=1,2,3, let y_i be the terminal vertex of P_i . Without loss of generality, we may assume that y_1,y_2,y_3 appear in this order along C_3 . If T is contained in D-L, then it is an X-tripod in D_3 . Hence we may assume that T contains some vertices of L. Observe that the arcs entering L all leave s_1 . Hence, y_i cannot be in L, since there are two (X,y_i) -dipaths in T,

which are disjoint except for the common vertex y_i . Consequently, the intersection of T with D[L] is a dipath Q which is a subpath of one of the P_i or C_3 . Moreover, the inneighbour in T of the initial vertex of Q is s_1 and the outneighbour in T of the terminal vertex of Q is some vertex $w \in W \cup \{s_1\}$, because there is no arc from L to $R \cup \{s_2\}$. But $w \neq s_1$ for otherwise s_1Qs_1 would be C_3 and would contain at most one of the y_i , a contradiction. Thus the digraph T_3 obtained from T by replacing s_1Qw by the arc s_1w is an X-tripod in D_3 .

Claims 23.1, 23.2 and 23.3 ensure that our algorithm is correct. Each time we do a recursive call, the number of vertices decreases. So we do at most n of them. Between two recursive calls, we first find a cycle of length at least 3 in linear time, and next run a sequence of Menger algorithms to produce a new 2-separation. At each step the size of the set W decreases. Therefore, we run at most n times the Menger algorithm between two recursive calls. Since a Menger algorithm runs in linear time, the time between two calls is at most O(n(n+m)) and so tripod runs in $O(n^2(n+m))$ time.

We now deduce Theorem 21 from Lemma 23.

Proof of Theorem 21. For every vertex v, we examine whether there is a W_3 -subdivision with centre v in D. Observe that such a subdivision S is the union of a directed cycle C, and three internally disjoint (v,C)-dipaths P_1 , P_2 , P_3 with distinct terminal vertices y_1,y_2,y_3 . The cycle C is contained in some strong component Γ of D-v. For i=1,2,3, let x_i be the first vertex of P_i that belongs to Γ . Set $X=\{x_1,x_2,x_3\}$. Then the paths $P_i[x_i,y_i]$, i=1,2,3, and C form an X-tripod in Γ , and the $P_i[v,x_i]$, i=1,2,3, are internally disjoint (v,X)-dipaths in $D-(\Gamma\setminus X)$.

Hence for finding a W_3 -subdivision with centre v, we use the following procedure to check whether there is a set X as above. First, we compute the strong components of D-v. Next, for every subset X of three vertices in the same strong component Γ , we run a Menger algorithm to check whether there are three independent (v,X)-dipaths in $D-(\Gamma\setminus X)$. If yes, we check whether there is an X-tripod in Γ . If yes again, then we clearly have a W_3 -subdivision with centre v, and we return 'yes'. If not, there is no such subdivision, and we proceed to the next triple.

For each vertex v, there are at most n^3 possible triples. And for each triple we run a Menger algorithm in time O(n+m) and possibly tripod in time $O(n^2(n+m))$. Hence the time spent on each vertex v is $O(n^5(n+m))$. As we examine at most n vertices, the algorithm runs in $O(n^6(n+m))$ time.

5.2 Z_4 -subdivision

In this subsection, we show that Z_4 is tractable. The proof relies on the following lemma.

Lemma 24. Let D be a digraph. There is a Z_4 -subdivision in D if and only if there exists four distinct vertices a', b', c' and d' in D such that the following hold.

- (i) There are three independent $(d', \{a', b', c'\})$ -dipaths.
- (ii) There are two independent $(b', \{a', c'\})$ -dipaths.

Proof. If D contains a Z_4 -subdivision S, then the vertices a', b', c', d' corresponding to a, b, c, d (as indicated on Figure 6) clearly satisfy conditions (i) and (ii).

Conversely, suppose that D contains four vertices a', b', c', d' satisfying conditions (i) and (ii). Let P_1, P_2, P_3 be three independent $(d', \{a', b', c'\})$ -dipaths with $t(P_1) = a', t(P_2) = b'$ and $t(P_3) = c'$; let Q_1, Q_2 be two independent $(b', \{a', c'\})$ -dipaths with $t(Q_1) = a'$ and $t(Q_2) = c'$.

We consider such vertices a', b', c', d' and dipaths such that the sum of the lengths of P_1, P_2, P_3, Q_1 and Q_2 is minimized.

Claim 24.1.
$$V(Q_1) \cap V(P_1) = \{a'\} \text{ and } V(Q_2) \cap V(P_3) = \{c'\}.$$

Subproof. Suppose $V(Q_1) \cap V(P_1) \neq \{a'\}$. Then there is a vertex a'' distinct from a' in $V(Q_1) \cap V(P_1)$. The vertices a'', b', c', d' satisfy condition (i) with $P_1[d', a'']$, P_2 , P_3 and condition (ii) with $Q_1[b', a'']$, Q_2 . This contradicts our choice of a', b', c', d' and the corresponding paths, and so $V(Q_1) \cap V(P_1) = \{a'\}$.

The conclusion that $V(Q_2) \cap V(P_3) = \{c'\}$ is proved in the same way; the details are omitted. \Diamond

Claim 24.2.
$$(V(Q_1) \cup V(Q_2)) \cap V(P_2) = \{b'\}.$$

Subproof. Suppose not. Then let b'' be the last vertex distinct from b' along P_2 which is in $V(Q_1) \cup V(Q_2)$. By symmetry, we may assume that $b'' \in V(Q_1)$. But the four vertices a', b'', c', d' satisfy condition (i) with P_1 , $P_2[d', b'']$, P_3 and condition (ii) with $Q_1[b'', a']$, $P_2[b'', b']Q_2$. This contradicts our choice of a', b', c', d' and proves our claim.

Claim 24.3.
$$V(Q_1) \cap V(P_3) = \emptyset$$
 and $V(Q_2) \cap V(P_1) = \emptyset$.

Subproof. Suppose not. Then $V(Q_1) \cap V(P_3)$ or $V(Q_2) \cap V(P_1)$ is not empty.

Assume first that these two sets are both non-empty. Let a'' be a vertex in $V(Q_2) \cap V(P_1)$ and c'' be a vertex in $V(Q_1) \cap V(P_3)$. Then the four vertices a'', b', c'', d' satisfy condition (i) with $P_1[d', a'']$, $P_3[d', c'']$, P_2 and condition (ii) with $Q_2[b', a'']$, $Q_1[b', c'']$. This contradicts our choice of a', b', c', d'. Hence, exactly one of the two sets is empty. By symmetry, we may assume that $V(Q_1) \cap V(P_3) \neq 0$

Hence, exactly one of the two sets is empty. By symmetry, we may assume that $V(Q_1) \cap V(P_3) \neq \emptyset$, Let b'' be a vertex in $V(Q_1) \cap V(P_3)$. Now the four vertices a', b'', c', d' satisfy condition (i) with P_1 , $P_3[d', b'']$, P_2Q_2 and condition (ii) with $Q_1[b'', a']$, $P_3[b'', c']$. This contradicts our choice of a', b', c', d' and proves our claim.

Claims 24.1, 24.2 and 24.3 imply that
$$P_1 \cup P_2 \cup P_3 \cup Q_1 \cup Q_2$$
 is a Z_4 -subdivision.

Theorem 25. \mathbb{Z}_4 -SUBDIVISION can be solved in $O(n^4(n+m))$ time.

Proof. By Lemma 24, Z_4 -Subdivision is equivalent to deciding whether there are four vertices satisfying the condition (i) and (ii) of the lemma. But given four vertices a', b', c', d', one can check in linear time if conditions (i) and (ii) hold by running two Menger algorithms. Since there are $O(n^4)$ sets of four vertices in D, Z_4 -Subdivision can be solved in $O(n^4(n+m))$ time.

6 Some tractable digraphs

6.1 Easier cases

A symmetric star is a symmetric digraph associated to a star. The centre of a symmetric star is the centre of the star to which it is associated. A superstar is a digraph obtained from a symmetric star by adding an arc joining two non-central vertices. The centre of a superstar is the centre of the star from which it is derived. The symmetric star of order k+1 is denoted by SS_k and the superstar of order k+1 is denoted by SS_k^* . An SS_k -subdivision with centre a is the union of k internally disjoint (a,a)-handles. Therefore, on can decide if there is an SS_k -subdivision with centre a in linear time using a Menger algorithm. Bang-Jensen et al. [2] showed that SS_3^* -SUBDIVISION is polynomial-time solvable. Their result can be extended to all superstars.

Theorem 26. Let k be a positive integer. Given digraph D and a vertex v of D, on can decide in $O(n^{2k}(n+m))$ -time whether D contains an SS_k^* -subdivision with centre v.

Proof. We describe a procedure that given v, a set $X = \{x_1, \ldots, x_k\}$ of k distinct outneighbours of v and a set $Y = \{y_1, \ldots, y_k\}$ of k distinct inneighbours of v checks if there is an SS_k^* -subdivision S with centre v such that $\{vx_1, \ldots, vx_k\} \cup \{y_1v, \ldots, y_kv\} \in A(S)$. (Note that it is allowed that $X \cap Y \neq \emptyset$.) Such a subdivision will be called (v, X, Y)-forced.

Applying a Menger algorithm, check whether in D-v there are k disjoint dipaths P_1,\ldots,P_k from X to Y. If not, then D certainly does not contain any (v,X,Y)-forced SS_k^* -subdivision. If yes, then check whether there is a dipath Q from some P_i to a different P_j whose internal vertices are not in $\{v\} \cup \bigcup_{i=1}^k P_i$. This can be done in linear time by running a search on the digraph obtained from D-v by contracting each path P_i into a single vertex. If such a dipath Q exists, then P_1,\ldots,P_k and Q together with v and the arcs from v to X and from Y to v form a (v,X,Y)-forced SS_k^* -subdivision. If not, then no (v,X,Y)-forced SS_k^* -subdivision using the chosen arcs exists, because there is no vertex $x \in X$ with two vertices of Y in its outsection in D-v.

Applying this linear-time procedure for every possible pair (X,Y), we can decide in $O(n^{2k}(n+m))$ -time whether D contains an SS_k^* -subdivision with centre v.

Corollary 27. For every positive integer k, SS_k^* -Subdivision can be solved in $O(n^{2k+1}(n+m))$ -time.

Proposition 28. For $1 \le i \le 8$, the digraph E_i depicted in Figure 5 is tractable.

Proof. i=1: Let us describe a procedure that, given two distinct vertices a' and d' in D and two outneighbours s_1 , s_2 of a' distinct from d', decides whether there is an E_1 -subdivision with a-vertex a' and d-vertex d' such that $a's_1$ and $a's_2$ are arcs of S. Such a subdivision is said to be $(a's_1, a's_2, d)$ -forced.

We check whether there is a dipath Q from $\{s_1, s_2\}$ to d' in D-a', and with a Menger algorithm we check whether there are two independent $(\{s_1, s_2\}, a')$ -dipaths P_1 and P_2 in D-d'. If these three dipaths do not exist, then D contains no $(a's_1, a's_2, d)$ -forced E_1 -subdivision, and we return 'no'. If the three paths Q, P_1, P_2 exist, then we return 'yes'. Indeed, denoting by c' the last vertex along Q in $P_1 \cup P_2$, the digraph $a's_1 \cup P_1 \cup a's_2 \cup P_2 \cup Q[c', d']$ is an $(a's_1, a's_2, d)$ -forced E_1 -subdivision.

Applying the above procedure for all possible triples $(a's_1, a's_2, d')$, one solves E_1 -SUBDIVISION in $O(n^4(n+m))$ time.

i=2: Let us describe a procedure that given two distinct vertices a' and d' in D, a set $U=\{u_1,u_2,u_3\}$ of three outneighbours of a', returns 'yes' if it finds an E_2 -subdivision and returns 'no' only if there is no E_2 -subdivision with a-vertex a' and d-vertex d' such that $\{a'u_1,a'u_2,a'u_3\}\subseteq A(S)$. Such a subdivision is said to be (a',d',U)-forced.

We check with a Menger algorithm whether $|S_{D-a'}^-(d')\cap U|\geq 2$ and whether there are three internally disjoint dipaths P_1,P_2,P_3 with distinct initial vertices in U and with $t(P_1)=t(P_2)=a'$ and $t(P_3)=d'$. If these two conditions are not both fulfilled, then D contains no (a',d',U)-forced E_2 -subdivision, and we return 'no'. If these conditions are fulfilled, then we return 'yes'. Indeed consider three dipaths P_1,P_2,P_3 as above. Without loss of generality, $s(P_i)=u_i$ for $1\leq i\leq 3$. Since $|S_{D-a'}^-(d')\cap U|\geq 2$, there exists a $(P_1\cup P_2,P_3)$ -dipath in D-a'. Let us denote its terminal vertex by d''. Then the union of the directed cycles $a'u_1P_1, a'u_2P_2$, and the dipaths $a'u_3P_3[u_3,d'']$, and Q is an E_2 -subdivision.

Applying the above procedure for all possible triples (a', d', U), one solves E_2 -SUBDIVISION in $O(n^5(n+m))$ time.

i=3: Let us describe a procedure that given two distinct vertices a' and d' in D and two outneighbours s_1 , s_2 of a' distinct from d', returns 'yes' when it finds an E_3 -subdivision and returns 'no' only if there is no E_3 -subdivision with a-vertex a' and d-vertex d' such that $\{a's_1, a's_2\} \subseteq S$. Such a subdivision is said to be $(a's_1, a's_2, d')$ -forced.

We check whether there is an $(\{s_1, s_2\}, d')$ dipath Q in D-a' and whether there are three independent $(\{s_1, s_2, d'\}, a')$ -dipaths P_1, P_2, P_3 in D. If these two conditions are not both fulfilled, then D contains no $(a's_1, a's_2, d')$ -forced E_3 -subdivision, and we return 'no'. If these conditions are fulfilled then we return 'yes'.

Indeed, suppose there are four such dipaths Q, P_1, P_2, P_3 . We may assume without loss of generality that $s(P_3) = d'$. Denote by c' the last vertex along Q in $P_1 \cup P_2$, and by d'' the first vertex in Q[c',d'] which is on P_3 . Then the union of the two directed cycles $a's_1P_1a', a's_2P_2a'$ and the dipaths Q[c',d''] and $P_3[d'',a']$ is an E_3 -subdivision.

Applying the above procedure for all possible triples $(a's_1, a's_2, d')$, one solves E_3 -SUBDIVISION in $O(n^4(n+m))$ time.

i=4: Let us describe a procedure that, given an arc sa' and a vertex $d' \notin \{s, a'\}$, checks whether there is an E_4 -subdivision S with a-vertex a', d-vertex d', and such that $sa' \in A(S)$. Such a subdivision is said to be (sa', d')-forced.

We check with a Menger algorithm whether there are three independent $(a', \{s, d'\})$ -dipaths, where two of the paths end up at d' and one at s. If three such dipaths do not exist, then there is clearly no (sa', d')-forced E_4 -subdivision, and we return 'no'. If three such dipaths exist, then their union together with the arcs sa' form an (sa', d')-forced E_4 -subdivision.

Applying the above procedure for all possible pairs (sa', d'), one solves E_4 -SUBDIVISION in O(mn(n+m)) time.

i=5: Let us describe a procedure that, given two distinct vertices b',c' and a set $S=\{s_1,s_2,s_3\}$ of three distinct inneighbours of b' checks whether there is an E_5 -subdivision S' with b-vertex b', c-vertex c', and such that $\{s_1b',s_2b',s_3b'\} \subset A(S')$. Such a subdivision is said to be (b',c',S)-forced.

We check with a Menger algorithm, if there are three independent (c', S)-dipaths P_1, P_2, P_3 , and we check whether there is a $(b', S \setminus \{c'\})$ -dipath Q in D - c'. If four such dipaths do not exist, then we return 'no' because there is no (b', c', S)-forced E_5 -subdivision. If such dipaths P_1, P_2, P_3 and Q exist, then let x be the first vertex of Q in $P_1 \cup P_2 \cup P_3$. Then the union of $P_1, P_2, P_3, Q[b', x]$ and the three arcs s_1b', s_2b', s_3b' form a (b', c', S)-forced E_5 -subdivision.

Applying the above procedure for all possible triples (a', b', S), one solves E_5 -SUBDIVISION in $O(n^5(n+m))$ time.

i=6: Observe that every E_6 -subdivision may be seen as an E_6 -subdivision in which the arc dc is not subdivided. Henceforth, by an E_6 -subdivision, we mean such a subdivision.

Let us describe a procedure that, given two disjoint arcs, sb' and d'c', returns 'yes' if it finds an E_6 -subdivision and returns 'no' only if there is no E_6 -subdivision S with b-vertex b', c-vertex c', d-vertex d' and such that $\{sb', d'c'\} \subseteq A(S)$. Such a subdivision is called (sb', d'c')-forced.

Applying a Menger algorithm, we check whether in D there are three independent $(b', \{s, c', d'\})$ -dipaths P_1, P_2, P_3 with $t(P_1) = s$ and applying a search we check whether there is a (c', s)-dipath Q in $D - \{b', d'\}$. Clearly, if four such dipaths do not exist, then D contains no (sb', d'c')-forced E_6 -subdivision, so we return 'no'. Conversely, if these dipaths exist, then Q contains a (c', P_1) -subdipath R. Let c'' be the last vertex along R in $V(P_2 \cup P_3)$. Now in $P_2 \cup P_3 \cup R[c', c''] \cup d'c'$, there are two internally disjoint (b', c'')-dipaths P'_2, P'_3 . Thus $P_1 \cup sb' \cup P'_2 \cup P'_3 \cup R[c'', t(R)]$ is an E_6 -subdivision, and we return 'yes'.

Doing this for every possible pair (sb', d'c'), one decides in $O(m^2(n+m))$ time whether D contains an E_6 -subdivision.

i=7: We proceed in two stages. We first check whether there is an E_7 -subdivision in which the arc ab is not subdivided. Next we check whether there is an E_7 -subdivision in which the arc ab is subdivided.

In the first stage we decide whether there is an E_7 -subdivision with a-vertex a' and b-vertex b' for some arc a'b'. To do so, for every dipath a'uv in D-b', we check whether there is an E_7 -subdivision with a-vertex a' and b-vertex b', and which contains the arcs of $\{a'u, uv, a'b'\}$. Such a subdivision is said to be (a'uv, a'b')-forced.

We proceed as follows. Applying a Menger algorithm, we check whether in D-u there are independent $(\{v,b'\},a')$ -dipaths P_1 and P_2 with $s(P_1)=v$, and applying a search we check whether there is a (v,b')-dipath Q in D-a'-u. Clearly, if three such dipaths do not exist, then D contains no (a'uv,a'b')-forced E_7 -subdivision, so we return 'no'. Conversely, if these dipaths exists, then Q contains a (P_1,P_2) -subdipath R. Then the union of P_1 , P_2 , R, a'uv, and a'b' is an E_7 -subdivision, and we return 'yes'. Doing this for every possible pair (a'uv,a'b'), one decides in $O(m^2(n+m))$ time that either D contains an E_7 -subdivision, or that D contains no E_7 -subdivision in which the arc ab is not subdivided.

Let G_7 be the digraph obtained from E_7 by subdividing the arc ab into a dipath awb of length 2. The second stage consists in deciding whether D contains an G_7 -subdivision. We use a procedure similar to the one for detecting superstar subdivision. Given a pair $\{a'w_1x_1, a'w_2x_2\}$ of dipaths that are disjoint except for their initial vertex a', and two distinct inneighbours y_1, y_2 of a' that are not in $\{w_1, w_2\}$ (allowing the possibility that $\{x_1, x_2\} \cap \{y_1, y_2\} \neq \emptyset$), the procedure returns 'yes' if it finds an G_7 -subdivision and returns 'no' only if there is no G_7 -subdivision with a-vertex a' containing all arcs in $A' = \{a'w_1, w_1x_1, a'w_2, w_2x_2, y_1a', y_2a'\}$. Such a subdivision is called A'-forced.

The procedure proceeds as follows. With a Menger algorithm, we first check whether in $D-\{a',w_1,w_2\}$ there are two disjoint dipaths P_1,P_2 from $\{x_1,x_2\}$ to $\{y_1,y_2\}$. If not, then D certainly does not contain any A'-forced G_7 -subdivision. If yes, then check whether there is a (P_1,P_2) -dipath Q in $D-\{a',w_1,w_2\}$. If such a dipath exists, then the union of the paths $P_1,P_2,Q,a'w_1x_1,a'w_2x_2$ and the arcs y_1a' and y_2a' is an G_7 -subdivision and we return 'yes'. Next, we check if there is a (P_2,P_1) -dipath Q in $D-\{a',w_1,w_2\}$. If Q exists, we return 'yes'. If not, then no A'-forced G_7 -subdivision exists, because there is no vertex $x \in \{x_1,x_2\}$ with two vertices of $\{y_1,y_2\}$ in its outsection in $D-\{a',w_1,w_2\}$. So we return 'no'.

This procedure runs in linear time. Thus, running it for every possible set A', one decides in $O(m^2n^3(n+m))$ time whether D contains an G_7 -subdivision, which is nothing but an E_7 -subdivision in which the arc ab is subdivided.

Doing the two stages one after another, we obtain an $O(m^2n^3(n+m))$ -time algorithm for solving E_7 -SUBDIVISION.

i=8: Similarly to the case i=7, we proceed in two stages. We first check whether there is an E_8 -subdivision in which the arc ab is not subdivided. Next we check whether there is an E_8 -subdivision in which the arc ab is subdivided.

The first stage is the following. For every vertex a', every two distinct outneighbours b', u, and every inneighbour t' of a' distinct from b' and u, we run a procedure that returns 'yes' if it finds an E_8 -subdivision, and return 'no' if there is no E_8 -subdivision with a-vertex a' and b-vertex b' and whose arc set includes $\{t'a', a'b', a'u\}$. Such a subdivision is called (t'a', a'b', a'u)-forced. The procedure is the following. With a Menger algorithm, we check whether in D-u there are two independent $(b', \{a', t'\})$ -dipaths P_1, P_2 and whether there is a (u, t')-dipath Q in $D - \{a', b'\}$. If three such paths do not exist, then D certainly contains no (t'a', a'b', a'u)-forced E_8 -subdivision and we return 'no'. If these three paths exist, we then we return 'yes'. Indeed let d' be the first vertex along Q in $P_1 \cup P_2$. Now the union of $P_1, P_2, Q[u, d'], a'b', t'a'$ and a'u is an E_8 -subdivision with a-vertex a' and b-vertex b'.

Doing this for every possible triple (t'a', a'b', a'u), one can decide in time $O(n^2m(n+m))$ whether there is an E_8 -subdivision with in which the arc ab is not subdivided.

Observe that an E_8 -subdivision in which ab is subdivided is an G_7 -subdivision. Hence the second

phase is exactly the same as the one for E_7 .

Doing the two stages one after another, we obtain an $O(m^2n^3(n+m))$ -time algorithm for solving E_8 -SUBDIVISION.

6.2 E_9 is tractable

Theorem 29. E_9 -SUBDIVISION can be solved in $O(n^7(n+m))$ time.

The proof relies on the following notion. A *shunt* is a digraph composed of three dipaths P, Q and R such that R has length at least 2, $s(R) \in P$, $t(R) \in Q$ and P, Q, R^0 are disjoint. We frequently refer to a shunt by the triple (P, Q, R). An (S, T)-shunt is a shunt (P, Q, R) such that $\{s(P), s(Q)\} = S$ and $\{t(P), t(Q)\} = T$.

We consider the following decision problem.

SHUNT

Input: A digraph D and four distinct vertices s_1, s_2, t_1, t_2 .

Question: Does D contain an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt?

Assume that there are two disjoint dipaths P, Q from $\{s_1, s_2\}$ to $\{t_1, t_2\}$ in D. We now give some necessary and sufficient conditions considering P and Q for D to have an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt.

For any vertex x in V(P), an x-bypass is a dipath B internally disjoint from P and Q with initial vertex in P[s(P), x[and terminal vertex in P[x, t(P)]. Similarly, for any vertex x in V(Q), an x-bypass is a dipath B internally disjoint from P and Q with initial vertex in Q[s(Q), x[and terminal vertex in Q[x, t(Q)]. If x is the end-vertex of an arc between P and Q, then every x-bypass is said to be an arc bypass (figure 7(a)). A crossing (with respect to P and Q) is a pair of arcs $\{uv, u'v'\}$ such that u is before v' along P and u' is before v along Q. If uv' is an arc of P and u'v is an arc of Q, then the crossing is tight. Otherwise it is loose.

Let $C = \{uv, u'v'\}$ be a tight crossing. A C-forward path is a dipath internally disjoint from P and Q either with initial vertex u and terminal vertex v', or with initial vertex u' and terminal vertex v (figure 7(b)). A C-backward path is a dipath internally disjoint from P and Q either with initial vertex in P[v', t(P)] and terminal vertex in P[s(P), u], or with initial vertex in Q[v, t(Q)] and terminal vertex in Q[s(Q), u']. A C-backward arc is an arc that forms a C-backward arc path of length 1. A C-bypass is an x-bypass B, where x is an endvertex of a C-backward arc and if $x \in P[s(P), u]$ (resp. Q[s(Q), u']), t(B) is also in P[s(P), u] (resp. Q[s(Q), u']), or if $x \in P[v', t(P)]$ (resp. Q[v, t(Q)]), s(B) is also in P[v', t(P)] (resp. Q[v, t(Q)]) (figure 7(c)).

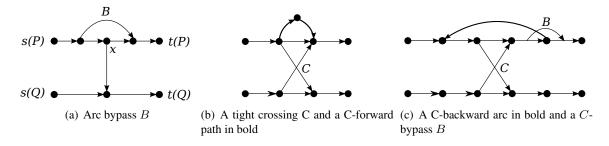


Figure 7: Conditions considering P and Q for D to have an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt.

Lemma 30. Let D be a digraph, and let P and Q be two disjoint dipaths from $\{s_1, s_2\}$ to $\{t_1, t_2\}$. D has an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt if and only if one of the following holds:

- (a) there is a (P,Q)-dipath or a (Q,P)-dipath R of length ≥ 2 ;
- (b) there is an arc bypass for some arc uv between P and Q;
- (c) there is a loose crossing;
- (d) there is a tight crossing C with a C-forward path, a C-backward path of length at least 2 or a crossing bypass.

Proof. Let us first price that if one of (a)–(d) holds, then D has an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt.

- (a) If such a dipath R exists, then (P, Q, R) or (Q, P, R) is an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt.
- (b) If B is a u-bypass and $u \in V(P)$, then $(P[s(P), s(B)] \cup B \cup P[t(B), t(P)], Q, P[s(B), u] \cup uv)$ is an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt. There is a shunt constructed analogously if $u \in V(Q)$ and also when B is a v-bypass.
- (c) Let $\{uv, u'v'\}$ be a loose crossing. By symmetry, we may assume that uv' is not an arc. Then $(P[s(P), u] \cup uv \cup Q[v, t(Q)], Q[s(Q), u'] \cup u'v' \cup P[v', t(P)], P[u, v'])$ is an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt.
- (d) Let $C = \{uv, u'v'\}$ be a tight crossing.

If there is a C-forward path, then replacing the arc uv' on P or the arc u'v on Q by this C-forward path, we obtain two dipaths with a loose crossing, so we are done by (c).

If there is a C-backward path R of length at least 2, then $P[s(P),u] \cup uv \cup Q[v,t(Q)]$, $Q[s(Q),u'] \cup u'v' \cup P[v',t(P)]$) and R form an $(\{s_1,s_2\},\{t_1,t_2\})$ -shunt.

Suppose now that B is a C-bypass. By symmetry and directional duality, we may assume that B is an x-bypass with $t(B) \in P[s(P), u]$. Let a = xw be the corresponding C-backward arc a, where $w \in P[v', t(P)]$. Then $(Q[s(Q), u'] \cup u'v' \cup P[v', t(P)]), P[s(P), s(B)] \cup B \cup P[t(B), u] \cup uv \cup Q[v, t(Q)], wx \cup P[x, t(B)])$ is an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt.

Let us now prove the reciprocal by the contrapositive. Suppose for a contradiction none of (a)–(d) holds, but D contains an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt (P', Q', R'). Without loss of generality, we may assume that this shunt maximizes $|(A(P) \cup A(Q)) \cap (A(P') \cup A(Q'))|$. Free to swap the names of P and Q, we may assume that s(P) = s(P').

Let u be the farthest vertex along P' such that P'[s(P'), u] does not intersect Q. Necessarily $u \in V(P)$ for otherwise there would be a dipath of length at least 2 from P to Q. In addition, for the same reason, if $u \neq t(P)$, then the outneighbour v of u in P' must be in Q. Hence all vertices of $P'[s(P'), u] \cap P$ are in P[s(P), u], for otherwise there would be a u-bypass in P, which would be an arc bypass for uv. Note also that, for every vertex x in P[s(P), u] - P', there is a subdipath of P' which is an x-bypass. So $Q' \cap P[s(P), u] = \emptyset$, for otherwise in Q' there would be a dipath from Q to P[s(P), u] which is either has length at least 2 or is an arc with an arc bypass in P'. Let R'' be the shortest subdipath of P' with initial vertex in V(P) and terminal vertex s(R') if $s(R') \in P'[s(P'), u]$, and let R'' be the path of length 0 (s(R')) otherwise. Now, ($P'', Q'', R) = (P[s(P), u] \cup P'[u, t(P')], Q', R'' \cup R'$) is an ($\{s_1, s_2\}, \{t_1, t_2\}$)-shunt. Moreover if $P'[s(P'), u] \neq P[s(P), u]$, then P'' and Q'' have more arcs in common with P and Q than P' and Q', which contradicts our choice of (P', Q', R'). Therefore P'[s(P'), u] = P[s(P), u].

Let u' be the farthest vertex along Q' such that Q'[s(Q'), u'] does not intersect P. As above, one shows that Q'[s(Q'), u'] = Q[s(Q), u'].

If u = t(P), then P' = P and necessarily Q = Q'. Thus R' is a dipath of length at least 2 from P to Q as (P', Q', R') is a shunt, which is a contradiction. Therefore, we may assume that

 $u \neq t(P)$ and similarly $u' \neq t(Q)$. Furthermore the out-neighbour v of u in P' is in V(Q) and the out-neighbour v' of u' is in V(P). Since P' and Q' are disjoint, P'[s(P'), u] = P[s(P), u] and Q'[s(Q'), u'] = Q[s(Q), u'], it follows that $C = \{uv, u'v'\}$ is a crossing with respect to P and Q, and thus a tight crossing.

Consider the dipath R'.

- Assume first that $s(R') \in P'[s(P'), u]$. Let S be the shortest subdipath of $R' \cup Q'[t(R'), t(Q')]$ such that s(S) = s(R') and $t(S) \in V(P) \cup V(Q)$. Vertex t(S) cannot be in Q[s(Q), u'] for otherwise S = R' and it would be a dipath of length at least 2 between P and Q. Furthermore, if $t(S) \in V(Q)$, $\{s(R')t(S), u'v'\}$ is a loose crossing, since the distance between u' and t(S) in Q is at least 2 (u is between s(R') and v, and v is between u' and t(S). Therefore $t(S) \in V(P)$ and so t(S) is on P[v', t(P)]. But then S is a forward path or an arc bypass in P, a contradiction.
- Assume now that $s(R') \in P'[v,t(P')]$. Set $P^* = Q[s(Q),u'] \cup u'v \cup P'[v,t(P')]$ and $Q^* = P[s(P),u] \cup uv' \cup Q'[v',t(Q')]$. If $t(R') \in Q'[v',t(Q')]$, then (P^*,Q^*,R') is an $(\{s_1,s_2\},\{t_1,t_2\})$ -shunt. But P^* and Q^* have more arcs in common with P and Q than P' and Q', which contradicts our choice of (P',Q',R'). Therefore $t(R') \in Q'[s(Q'),u']$.

Let S be the shortest subdipath of $P'[v, s(R')] \cup R'$ such that t(S) = t(R') and $s(S) \in V(P) \cup V(Q)$.

Assume first that $s(S) \in V(Q)$. Then S is a C-backward path. Hence it must have length 1. Therefore $s(S) \notin V(P') \cup V(Q')$ because R' has length at least 2. Let u_1 be the farthest vertex on P'[v,t(P')] that is in V(Q) and such that $P'[v,u_1]$ does not intersect P. Observe that u_1 appears before s(S) in Q, for otherwise there would be a C-bypass in P', as $s(S) \notin P'$. In particular, u_1 is not the terminal vertex of P'. Let v_1 be the first vertex after u_1 along P' which is on $P \cup Q$. It must be in V(P) by the choice of u_1 . Therefore u_1v_1 is an arc because there is no dipath of length at least 2 between Q and P. Let u_2 be the farthest vertex on $Q'[v',t(Q')] \cap P$ such that $Q'[v',u_2]$ does not intersect Q. Then v_1 is after u_2 along P, for otherwise there would be an arc bypass in P for u_1v_1 . Thus u_2 is not the terminal vertex of Q'. Let v_2 be the first vertex after u_2 along Q' which is on $P \cup Q$. It must be in V(Q) by the choice of u_2 . Hence u_2v_2 is an arc because there is no dipath of length at least 2 between P and Q. Moreover, observe that for every vertex x in $Q[v,u_1]-P'$ there is a subdipath of P' which is an x-bypass. Therefore v_2 must be in $Q[u_1,t(Q)]$ for otherwise it would be an arc bypass. Hence $\{u_2v_2,u_1v_1\}$ is a crossing for $P \cup Q$, and so it must be tight. This implies in particular that $s(S) \in Q[v_2,t(Q)]$.

Set $P^+ = P'[s(P'), u] \cup uv' \cup Q'[v', u_2] \cup u_2v_1 \cup P'[v_1, t(P')])$ and $Q^+ = Q'[s(Q), u'] \cup u'v \cup P'[v, u_1] \cup u_1v_2 \cup Q'[v_2, t(Q')])$. If $s(R') \in P'[v_1, t(P')])$, then (P^+, Q^+, R') is an $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt. But P^+ and Q^+ have more arcs in common with P and Q than P' and Q', which contradicts our choice of (P', Q', R'). Therefore $s(R') \in P'[(v, u_1)]$. Now $P'[v, s(R')] \cup R'$ contains a subdipath T that is internally disjoint from P and Q and has initial vertex in $Q[v, u_1]$ and terminal vertex in $P \cup Q[v_2, t(Q)]$, by the locations of s(R') and s(S), s(S) being in R', and since we know that $u_1 \in P'$, $v_2 \in Q'$ and therefore neither of them is in R'. Necessarily, $t(T) \in V(P)$ for otherwise T is an arc bypass. Hence T is an arc. Furthermore, t(T) could not be in $P[v', u_2]$ for otherwise Q' would contain a t(T)-bypass, which would be an arc bypass. Hence $t(T) \in P[v_1, t(Q)]$ and $\{u_2v_2, T\}$ is a loose crossing, a contradiction.

Assume now that $s(S) \in V(P)$. Then it must be in P[v', t(P)]. Since there is no dipath of

length at least 2 from P to Q, S has length 1. Moreover, since R' has length at least 2, s(S) is an internal vertex of R', so it is not in $V(P' \cup Q')$. Let u_2 be the farthest vertex on Q'[v', t(Q')] that is in V(P) and such that $Q'[v', u_2]$ does not intersect Q. Then u_2 appears before s(S) on P, for otherwise there would be an arc bypass for s(S)t(S) in P and so u_2 is not the terminal vertex of Q'. Let v_2 be the first vertex after u_2 along Q' which is on $P \cup Q$. It must be in V(Q) by the choice of u_2 , and so on Q[v,t(Q)]. u_2v_2 is an arc for otherwise for otherwise there would be a dipath of length 2 from P to Q. Let u_1 be the farthest vertex on P'[v,t(P')] that is also in V(Q) such that $P'[v,u_1]$ does not intersect P. Vertex u_1 appears before v_2 in Q, for otherwise there would be an arc bypass for u_2v_2 in Q, and so u_1 is not the terminal vertex of P'. Let v_1 be the first vertex after u_1 along P' which is on $P \cup Q$. It must be in V(Q) by the choice of u_1 . Hence u_1v_1 is an arc because there is no dipath of length at least 2 between Q and P. Moreover, observe that for every vertex x in $P[v',u_2]-Q'$ there is a subdipath of P' which is an x-bypass. Therefore v_1 must be in $P[u_2,t(P)]$ for otherwise it would be an arc bypass. Hence $\{u_2v_2,u_1v_1\}$ is crossing for $P \cup Q$, and so it must be tight. This implies in particular that $s(S) \in P[v_1,t(P)]$.

We then find a contradiction as in the previous case by considering P^+ and Q^+ .

This finishes the proof of the Lemma.

Theorem 31. SHUNT can be solved in $O(n^2(n+m))$ time.

Proof. We describe a procedure shunt (D, s_1, s_2, t_1, t_2) , solving SHUNT and estimate its time complexity. The procedure then check, by a Menger algorithm, if there are two disjoint dipaths P, Q from $\{s_1, s_2\}$ to $\{t_1, t_2\}$, which runs in O(n+m) time. Observe that the arcs s_1s_2 and s_2s_1 are useless, so we remove them from D if they exist. Then we should check if there are paths of length at least 2, arc bypasses, loose crossings, C-forward paths, backward paths of length at least 2 or crossing bypasses with respect to P and Q, according to Lemma 30. For every vertex $u \in P$ (and any vertex in Q, similarly), we do the following: if u has a neighbour in Q, we test if there is a path from P[s(P), u]to P[u, t(P)], which would be an arc bypass. Let v' be the last vertex of Q such that uv' is an arc (and such that v'u is an arc, similarly). Then, for a vertex v in P[u, t(P)], we check if there is a vertex u' in Q[s(Q), v'] such that u'v (vu') is an arc. Then if u, v and u'v' have distance at least 2 in P and Q respectively, it would be a loose crossing. Otherwise, if such edges exists there is a tight crossing $C = \{uv', u'v\}$ containing u. We then run a Menger algorithm one more time, to test if there is a dipath from u to v in the digraph induced by (V(D) - V(P) - V(Q)), which would be a forward path. So far, the running time of the algorithm is bounded by $O(n^2(n+m))$: the complexity of calculating the P and Q initially plus the complexity of, for each vertex in in $P \cup Q$, look for an arc bypass, plus the running time of analysing if each pair of vertices in P or Q are part of a loose crossing and finally plus the time of looking for a forward path. Then, still considering the same tight crossing C, for every vertex x in P[v, t(P)], we check if there is a dipath to some y in P[v, t(P)]. If it is the case and xy is an arc, we then look for dipaths from P[s(P), y] to P[y, u] and from P[v, x]to P[x, t(P)]. This can be done in $O(n^2(n+m))$: for every pair of vertices u and x, we uses Menger algorithm possibly three times to compute the dipaths above. So, shunt (D, s_1, s_2, t_1, t_2) runs in $O(n^2(n+m))$ time in total.

With Theorem 31 at hands, we now deduce Theorem 29. We believe that it could also be used to prove the tractability of other digraphs F.

Proof of Theorem 29. For every vertex v of D and for every set of two outneighbours s_1, s_2 and two inneighbours t_1, t_2 of v, we check if there is a $(\{s_1, s_2\}, \{t_1, t_2\})$ -shunt in D. Observe that there is an E_9 -SUBDIVISION in D in which v is the a-vertex if and only if there is a shunt for a pair of

outneighbours and a pair of inneighbours of v. So, since there are n^5 possible choices for vertex v and its neighbours, and for each of them we apply the procedure shunt that runs in $O(n^2(n+m))$ time, our algorithm decides whether there is an E_9 -SUBDIVISION in D in $O(n^7(n+m))$ time.

7 Proof of Theorem 6

To prove Theorem 6, we review all digraphs D of order 4, and determine if they are tractable or intractable or if their status is unknown.

For a digraph D, its 2-cycle graph G_D is the graph with the same vertex set in which two vertices are linked by an edge if they are in a directed 2-cycle in D. Thus, the 2-cycle graph of an oriented graph is an empty graph. We denote by A'(D) be the set of arcs of D which are not in directed 2-cycles.

Let F be a digraph of order 4. By Corollary 10, if F contains a directed 2-cycle whose vertices are big, then F is intractable. So we may assume that F contains no such 2-cycles. In particular, it implies that G_F has at most one vertex of degree at least two. So G_F has at most three edges.

<u>Case 0</u>: G_F has no edges. Then F is tractable by Theorem 20.

<u>Case 1</u>: G_F has three edges. Then necessarily, G_F is the star of order 3. Hence F is either the symmetric star or the superstar of order 4. In both cases, F is tractable, see Subsection 6.1.

Case 2: G_F has exactly two edges which are non-adjacent.

If $|A'(F)| \leq 1$, then F has no big vertex, so by Corollary 4 F is tractable.

If $|A'(F)| \ge 2$, then F is either one of N_1 , N_2 , N_3 , N_4 , O_1 and their converses, or F has no big vertex. In the later case, F is tractable by Corollary 4. If $F = N_i$ for $i \in \{1, 2, 3, 4\}$, then F is intractable by Proposition 11. We do not know the complexity of O_1 -subdivision.

Case 3: G_F has exactly two edges which are adjacent.

If A'(F) is empty, then $F = SS_2 + K_1$, where K_1 is the digraph on one vertex. As discussed in Subsection 6, SS_2 is tractable. Thus, by Lemma 15, F is tractable.

If |A'(F)| = 1, then F either is $SS_2^* + K_1$, or E_1 or the converse of E_1 , or is obtained from SS_2^* by gluing an arc on its centre. Now $SS_2^* + K_1$ is tractable by Corollary 27 and Lemma 15; E_1 (and thus its converse) is tractable by Proposition 28; if F is obtained from SS_2^* by gluing an arc on its centre, then it is tractable by Theorem 26 and by Lemma 16.

If |A'(F)| = 2, then F is either E_2 , E_3 , E_9 , O_2 or one of their converses. If $F \in \{E_2, E_3, E_9\}$, then it is tractable by Proposition 28. If $F = O_2$, then we do not know.

If |A'(F)| = 3, then F is either N_5 , N_6 , O_3 or one of their converses. If $F \in \{N_5, N_6\}$, then it is intractable by Proposition 11. The complexity of O_3 -SUBDIVISION is still unknown.

Case 4: G_F has exactly one edge.

If F has no big vertices, then, by Corollary 4, F is tractable. Henceforth, we may assume that F has a big vertex, i.e. a vertex with in-degree or out-degree at least 3 or both in-degree and out-degree equal to 2. Observe that it implies that F is connected and $|A'(F)| \ge 2$.

|A'(F)| = 2, F obtained from \vec{C}_2 by gluing a spider on one its vertices. Then F is tractable by Lemma 16.

If |A'(F)| = 3, then we distinguish several subcases according to the position of the arcs of A'(F) relatively to the directed 2-cycle C of F.

• A'(F) induces an orientation of a star. Then F is obtained from W_2 or its converse by gluing an arc on its centre. Thus F is tractable by Lemma 16.

- A'(F) induces an oriented path whose first vertex is a vertex of C and whose third vertex is the other vertex of C. Then F is obtained either from the bispindle B(2,1;1) by gluing an arc on one of its nodes, or from W_2 or its converse by gluing an arc on one of its vertices. In both cases, F is tractable by Lemma 16 and Theorem 18 and Lemma 14.
- A'(F) induces an oriented 3-cycle. If this cycle is directed, then F is a windmill, that is a subdivision of a symmetric star. Bang-Jensen et al. [2] proved that windmills are tractable, so F is tractable. If this cycle is not directed, then F is either E_4 or its converse, or N_7 . If F is E_4 or its converse, then it is tractable by Proposition 28. If $F = N_7$, then it is intractable by Proposition 11.

If |A'(F)| = 4, then it is either N_8 , N_9 , E_5 , E_6 , E_7 , E_8 , O_4 , O_5 , or one of their converses. If F is N_8 or N_9 , then it is intractable by Proposition 11. If F is E_5 , E_6 , E_7 , or E_8 , then it is tractable by Proposition 28. The complexity of O_4 -SUBDIVISION and O_5 -SUBDIVISION is still open.

This concludes the proof of Theorem 6.

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