

Model-based variable clustering

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Model-based variable clustering

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Outline

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- Variable selection in clustering
- Multiple Gaussian Mixture
- Proposed Multiple Mixture Model
- Properties of the model

² Parameters estimation and model selection

- **Maximum likelihood inference**
- Penalized observed-data likelihood
- Integrated complete-data likelihood

3 Numerical experiments on real data

- Mixed data framework
- **e** Results on real data

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Variable selection in clustering Multiple Gaussian Mixture Proposed Multiple Mixture Model Properties of the model

Data

 $\mathbf{x} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$ composed of *n* independent observations $\mathbf{x}_i = (x_{i1}, \dots, x_{id})$ defined on \mathbb{R}^d .

Goal

Cluster the data in G clusters.

What variables use in clustering?

- Well-posed problem in the supervised classification setting with objective criteria: error rate, AUC, . . .
- Ill-posed problem in clustering since the class variable is not known by advance. Thus what are the most relevant variables with respect to this unknown variable?
- Pragmatic solution 1: Prior choice of the practitioner among available variables (according to some focus)
- Pragmatic soltuion 2: Posterior analysis of the correlation between the predicted cluster (based on all the variables) and each variable

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Variable selection in clustering Multiple Gaussian Mixture Proposed Multiple Mixture Model Properties of the model

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The model based clustering solution

- Mixture models allow to perform clustering by modelling the distribution of the data as a mixture of G components each one corresponding to a cluster.
- Thus possibility to suppose that some variables do not depend (directly) on the cluster in the probabilistic model.

Some references

- Raftery & Dean (2006): some classifying, and some redundant variables. Redundant variables independent of the cluster given the classifying variables.
- Maugis & al. (2009): refinement of Raftery & Dean (2006) by specifying the role of each variable.

Advantages of these approaches

- Improve the accuracy of the clustering by decreasing the variance of the estimators
- Allow some specific interpretation of the classifying variables

Variable selection in clustering Multiple Gaussian Mixture Proposed Multiple Mixture Model Properties of the model

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 $\epsilon = 1$

Limitations of these approaches

- Combinatorial problem to select the best model with these refined approaches
- Search too hard to perform when the number of variables is large

Solution: use simpler models for a better search (Marbac & Serdki 2016,2017)

- Assumption of conditional independence of the classifying variables given the cluster
- Non-classifying variables are independent
- Optimisation of the integrated classification likelihood (ICL)
- Better results than previous approaches on large number of variables with moderated sample size
- The independence assumption allows to easily consider the heterogeneous data setting

Variable selection in clustering Multiple Gaussian Mixture Proposed Multiple Mixture Model Properties of the model

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Several clustering variables

- The variables in the data can convey several clustering view points with respect to different groups of variables
- Allow to find some clustering which could be hidden by other variables

Some references

- Galimberti & al. (2007): First proposition of a multiple Gaussian mixture model
- **•** Galimberti & al. (2017): Refinement of the previous model with ideas similar to to Raftery & Dean (2006) et Maugis & al. (2009)

Remarks

- Smart modelling of the role of each variable
- Search hard to perform when the number of variables is large
- Specific to the Gaussian setting

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- \bullet B independent blocks.
- \bullet block b follows a Gaussian mixture with G_b components (for $b = 1, \ldots, B$, with the assumption of class conditional independence of the variables
- $\bullet \ \omega = (\omega_j; j = 1, \ldots, d)$ the repartition of the variables in blocks; $\omega_j = b$ if variable *i* belongs to block *b*.
- The probability distribution function (pdf) of x_i is

$$
p(\mathbf{x}_i|\mathbf{m},\boldsymbol{\theta}) = \prod_{b=1}^B \sum_{g=1}^{G_b} \pi_{bg} \prod_{j \in \Omega_b} \phi(x_{ij}|\mu_{gj}, \sigma_{gj}^2),
$$

 \bullet $m = (G_1, \ldots, G_B, \omega)$ defines the model • $\Omega_b = \{j : \omega_j = b\}$ the subset of variables belonging to block b $\theta = (\pi, \mu, \sigma)$ model parameters $\bullet \ \pi = (\pi_{bg}; b = 1, \ldots, B; g = 1, \ldots, G_b)$ the proportions with $0 < \pi_{bg}$ and $\sum_{g=1}^{G_{b}}\pi_{bg}=1$ $\boldsymbol{\mu} = (\mu_{\scriptstyle{\text{g}j}}; \boldsymbol{\mathit{g}}=1,\dots, \boldsymbol{G}_{\scriptstyle{\omega_{\scriptstyle{j}}}}; j=1,\dots,d)$ the means $\boldsymbol{\sigma} = (\sigma_{\textit{gj}}; \boldsymbol{g}=1,\dots, \boldsymbol{G}_{\omega_{\vec{j}}}; j=1,\dots,d)$ the standard deviations $\phi(.|\mu_{\textit{gj}}, \sigma^2_{\textit{gj}})$ the pdf of the Gaussian distribution with mean $\mu_{\textit{gj}}$ and variance σ_{gj}^2 .

Variable selection in clustering Multiple Gaussian Mixture Proposed Multiple Mixture Model Properties of the model

Illustration :

- $n = 100$ from a MGMM with $B = 2$ blocks of two variables.
- Variable 1 and 2 belong to block 1 and variables 3 and 4 in block 2
- **•** Each block follows a bi-component Gaussian mixture (*i.e.,* $G_b = 2$) with equal proportions (i.e., $\pi_{bg} = 1/2$) and $\mu_{1j} = 4$, $\mu_{2j} = -4$ and $\sigma_{gj} = 1$.

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Variable selection in clustering Multiple Gaussian Mixture Proposed Multiple Mixture Model Properties of the model

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Remarks

- Different partitions explained by subsets of variables.
- Generalizes approaches used for variable selection in model-based clustering (if $B = 2$ and $G_1 = 1$ then variables belonging to block 1 are not relevant for the clustering, while variables belonging to block 2 are relevant)
- MGMM permits variable selection and multiple partitions explained by subsets of variables (variables classification).
- Sparse model: number of parameters $\nu_{\bm m} = \sum_{b=1}^B (\mathsf{G}_b 1) + 2 \mathsf{G}_b$ card (Ω_b)
- Better model search expected than in the model of Galimberti & al. (2017)
- Natural extension to the heterogeneous data setting

Identifiability

Model identifiability is directly obtained from the identifiability of Gaussian mixture with local independence (Teicher, 1963, 1967).

Maximum likelihood inference Penalized observed-data likelihood Integrated complete-data likelihood

Observed-data likelihood for sample x and model m

$$
\ell(\boldsymbol{\theta}|\boldsymbol{m},\mathbf{x}) = \sum_{b=1}^{B} \sum_{i=1}^{n} \ln \left(\sum_{g=1}^{G_b} \pi_{bg} \prod_{j \in \Omega_b} \phi(x_{ij}|\mu_{gj}, \sigma_{gj}^2) \right).
$$

Observed-data likelihood for sample x and model m

- \bullet B independent mixtures
- \bullet $\mathbf{z} = (\mathbf{z}_{ib}; i = 1, \ldots, n; b = 1, \ldots, B)$ vectors of the component memberships
- $\bm{z}_{ib} = (z_{ib1}, \dots, z_{ibG_b})$ where $z_{ibg} = 1$ if observation i arose from component g for block b, and $z_{ibg} = 0$ otherwise

Completed-data likelihood for sample x and model m

$$
\ell(\boldsymbol{\theta}|\boldsymbol{m},\mathbf{x},\mathbf{z})=\sum_{b=1}^B f_{\boldsymbol{\pi}_b}+\sum_{j=1}^d f_j(\omega_j),
$$

$$
f_{\boldsymbol{\pi}_b} = \sum_{i=1}^n \sum_{g=1}^{G_b} z_{ibg} \ln \pi_{bg} \text{ and } f_j(\omega_j) = \sum_{i=1}^n \sum_{g=1}^{G_{\omega_j}} z_{i\omega_j g} \ln \phi(x_{ij}|\mu_{\omega_j j}, \sigma^2_{\omega_j j}).
$$

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EM algorithm

Starting from the initial value $\theta^{[0]}$, iteration $[r]$ is composed of two steps: **E-step** Computation of the fuzzy partitions $t_{ibg}^{[r]} := \mathbb{E}[Z_{ibg} | \mathbf{x}_i, \mathbf{m}, \boldsymbol{\theta}^{[r-1]}],$ hence

$$
t_{ibg}^{[r]} = \frac{\pi_{bg}^{[r-1]} \prod_{j \in \Omega_b} \phi(x_{ij}|\mu_{gj}, \sigma_{gj}^2)}{\sum_{k=1}^{G_b} \pi_{bk}^{[r-1]} \prod_{j \in \Omega_b} \phi(x_{ij}|\mu_{kj}, \sigma_{kj}^2)},
$$

M-step Maximization of the expected value of the complete-data log-likelihood over the parameters,

$$
\pi_{bg}^{[r]} = \frac{n_{bg}^{[r]}}{n}, \mu_{gj}^{[r]} = \frac{1}{n_{\omega_{j}g}^{[r]}} \sum_{i=1}^{n} t_{i\omega_{j}g}^{[r]} x_{ij} \text{ and } \sigma_{gj}^{[r]} = \frac{1}{n_{\omega_{j}g}^{[r]}} \sum_{i=1}^{n} t_{i\omega_{j}g}^{[r]} (x_{ij} - \mu_{\omega_{j}j}^{[r]})^{2}.
$$

Remarks

- \bullet Independence between the B blocks of variables permits to maximize the observed-data log-likelihood on each block separately.
- Possible modification to perform the block estimation and the parameter inference simultaneously.

Maximum likelihood inference Penalized observed-data likelihood Integrated complete-data likelihood

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Model collection M

$$
\mathcal{M} = \{ \boldsymbol{m} : \omega_j \leq B_{\text{max}} \text{ and } G_b \leq G_{\text{max}}; j = 1, \ldots, d; b = 1, \ldots, B_{\text{max}} \},
$$

where B_{max} is the maximum number of blocks and G_{max} is the maximum number of components within block.

Model selection

Model selection often achieved by searching the model m^* maximizing the BIC criterion which is defined by

$$
\text{BIC}(m) = \max_{\theta_m} \ell_{\text{pen}}(\theta_m|m, \mathbf{x})
$$

where

$$
\ell_{\text{pen}}(\boldsymbol{\theta_m|m}, \mathbf{x}) = \ell(\boldsymbol{\theta_m|m}, \mathbf{x}) - \frac{\nu_m}{2} \ln n.
$$

Remark

$$
(\boldsymbol{m}^\star, \hat{\boldsymbol{\theta}}_{\boldsymbol{m}^\star}) = \argmax_{(\boldsymbol{m}, \boldsymbol{\theta}_{\boldsymbol{m}})} \ell_{\text{pen}}(\boldsymbol{\theta}_{\boldsymbol{m}}|\boldsymbol{m}, \mathbf{x})
$$

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Combinatorial model selection through a modified the EM algorithm for B and (G_1, \ldots, G_B) fixed : choice of $m \Leftrightarrow$ choice of ω

The EM algorithm to achieve $\argmax_{(\bm\omega,\bm\theta)}\ell_{pen}(\bm\theta_{\bm m}|\bm m,\mathsf{x}),$ starting from $(\bm\omega^{[0]},\bm\theta^{[0]})$ is at iteration $[r]$:

E-step Computation of the fuzzy partitions $t_{ibg}^{[r]} := \mathbb{E}[Z_{ibg} | \mathbf{x}_i, \mathbf{m}, \theta^{[r-1]}]$, hence

$$
t_{ibg}^{[r]} := \frac{\pi_{bg}^{[r-1]} \prod_{j \in \Omega_b} \phi(x_{ij} | \mu_{gj}, \sigma_{gj}^2)}{\sum_{k=1}^{G_b} \pi_{bk}^{[r-1]} \prod_{j \in \Omega_b} \phi(x_{ij} | \mu_{kj}, \sigma_{kj}^2)},
$$

M-step Maximization of the expected value of the complete-data log-likelihood over the parameters,

$$
\pi_{bg}^{[r]} = \frac{n_{bg}^{[r]}}{n}, \omega_j^{[r]} = \underset{b'=1,...,B}{\arg \max} \Delta_{jb'}^{[r]}, \mu_{gj}^{[r]} = \frac{1}{n_{\omega_j^{[r]}}}\sum_{i=1}^n t_{i\omega_j^{[r]}}^{[r]} \sum_{j=1}^{x_{ij}} x_{ij}
$$
\n
$$
\sigma_{gj}^{[r]} = \frac{1}{n_{\omega_j^{[r]}}}\sum_{i=1}^n t_{i\omega_j^{[r]}}^{[r]} \sum_{i\omega_j^{[r]}} (x_{ij} - \mu_{\omega_j^{[r]}}^{[r]})^2,
$$
\nwith $\Delta_{jb}^{[r]} = \max_{(\mu_{gj}, \sigma_{gj} : g=1,...,G_b)} \sum_{i=1}^n \sum_{g=1}^{G_b} z_{ibg} \ln \phi(x_{ij} | \mu_{gj}, \sigma_{gj}^2) - G_b \ln n.$

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Integrated complete-data likelihood

$$
p(\mathbf{x}, \mathbf{z}|\mathbf{m}) = \int p(\mathbf{x}, \mathbf{z}|\mathbf{m}, \theta) p(\theta|\mathbf{m}) d\theta.
$$

Assumptions

- Independence between the prior distributions
- **•** Standard conjugate priors
- Closed form of the complete-data integrated likelihood

MICL (maximum integrated complete-data likelihood) criterion

$$
\mathsf{MICL}(m) = \ln p(\mathsf{x}, \mathsf{z}_m^* | m) \text{ with } \mathsf{z}_m^* = \arg\max_{\mathsf{z}_m} \ln p(\mathsf{x}, \mathsf{z} | m).
$$

Thus

$$
(m^{\star}, z_{m^{\star}}^{\star}) = \underset{(m,z_m)}{\arg \max} \ln p(\mathbf{x}, \mathbf{z}|m).
$$

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Maximum likelihood inference Penalized observed-data likelihood Integrated complete-data likelihood

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 $\mathcal{A}(\overline{\mathbb{Q}}) \rightarrow \mathcal{A}(\overline{\mathbb{R}}) \rightarrow \mathcal{A}(\overline{\mathbb{R}}) \rightarrow$

Motivations

- Criteria based on the integrated complete-data likelihood are popular for model-based clustering
- Take into account the clustering purpose : model the data distribution and provide well-separated components

Optimisation of MICL over (z, ω) for B and G_1, \ldots, G_B fixed

Starting at the initial value $\omega^{[0]}$, each ω_j is uniformly sampled among $\{1, \ldots, B\}$, the algorithm at iteration [r] is Partition step: find $z^{[r]}$ such that for $b = 1, \ldots, B$

$$
\rho({\bf x}_{\{j|\omega^{[r]}_j=b\}}, {\bf z}^{[r]}_b|\bm{m}^{[r]})\geq \rho({\bf x}_{\{j|\omega^{[r]}_j=b\}}, {\bf z}^{[r-1]}_b|\bm{m}^{[r]}).
$$

Model step: find $\omega^{[r+1]}$ such that for $j = 1, \ldots, d$

$$
\omega_j^{[r+1]} = \argmax_{b \in \{1, ..., B\}} p(\mathbf{x}_j, \mathbf{z}_b^{[r]} | \omega_j = b)
$$

Mixed dataset

- \bullet $\mathbf{x}_i = (x_{i1}, \ldots, x_{id})$ is a vector of mixed variables (continuous, binary, count or categorical
- local independence within block \Rightarrow extension to the mixed data analysis

Subset of the 1987 National Indonesia Contraceptive Prevalence Survey

1473 Indian women described by

- One continuous variable (AGE: age)
- One integer variable (Chi: number of children)
- Seven categorical variables (EL: education level, ELH: education level of the husband, Rel: religion, Oc: occupation, OcH: occupation of the husband, SLI: standard-of-living index and ME: media exposure).

Mixed data framework Results on real data

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Results obtained by the BIC criterion

Analysis with :

- maximum of three blocks : $B_{\text{max}} = 3$
- maximum of six components : $G_{\text{max}} = 6$

Table: Best three models according to the BIC: block repartition, number of components per block and BIC values.

Adjusted Rand Index computed on the partitions obtained by blocks 1 and 2 equal to 0.01.

Mixed data framework Results on real data

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Results obtained by the MICL criterion

Table: Best three models according to the MICL: block repartition, number of components per block and MICL values.

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Mixed data framework Results on real data

Conclusion

- Proposition of model-based clustering with several class variables, each one explaining the heterogeneity of a block of variables:
	- Find groups of variables producing the same clustering of the individuals
	- Interpret the clustering produced for each group of variables
- Model search performed simultaneously with parameters estimation
- Proposed model can be used in the heterogeneous data settings

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