# Dealing with missing data through mixture models 

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## Overview

1 Missing data problem

## Data (1/2)

Many variables collected :

- Heterogeneous data (of various natures)
- Missing data
- Incertain data (by interval)

Heterogeneous, missing, incertain

| Units $\mathbf{x}^{O} \in \mathcal{X}$ |  |  |  |
| :---: | :---: | :---: | :---: |
| $?$ | 0.5 | $?$ | 5 |
| 0.3 | 0.1 | green | 3 |
| 0.3 | 0.6 | \{red, green \} | 3 |
| 0.9 | $[0.250 .45]$ | red | $?$ |
| $\downarrow$ | $\downarrow$ | $\downarrow$ | $\downarrow$ |
| continuous | continuous | categorical | integer |

## Data (2/2)

And also :

- Rank data
- Directional data
- Ordinal data
- Functional data
- Network data
-...



## Imputation of missing data

## Motivation for imputing missing values

Most of standard statistical methods cannot cope with missing data $\Rightarrow$ need to complete the dataset

## Single imputation

- $E\left[x^{M}\right]$ : average
$-\arg \max p\left(\mathbf{x}^{M}\right):$ mode
- $E\left[\mathbf{x}^{M} \mid \mathrm{x}^{\mathrm{O}}\right]$ : conditional expectation (regression, NPALS, ...)

■ Underestimation of the variability related to missing values

## Multiple imputation

- Replace missing value by many possibles values ideally coming from $p\left(x^{M} \mid x^{O}\right)$
- Variability inherent to missing data taken into account
- Necessity to consider many version of the dataset when performing the learning


## The fully conditional specification approach (Van Buuren \& al. (2006)

## Presentation

- Specify a conditional model $p\left(x_{j} \mid \mathbf{x}_{-j}, \theta_{j}\right)$ for each $j$ (linear regression, logistic regression, ...)
- At each iteration

1 Draw for each variable $j$ the missing value given the observed values, the simulated missing values and the current parameter
2 Update the parameters of the conditional models

## Advantage

- Missing data variability taken into account
- Simulated missing values expected to come from $p\left(\mathbf{x}^{M} \mid \mathbf{x}^{O}\right)$

■ Good performance in practice : implemented in the R package mice.

## Supervised classification (1/3)

- Data: learning data $\mathcal{D}=\left(\mathbf{x}^{O}, \mathbf{z}\right)$
- $n$ units : $\mathbf{x}=\left(\mathbf{x}_{1}, \ldots, \mathbf{x}_{n}\right)=\left(\mathbf{x}^{0}, \mathbf{x}^{M}\right)$ belonging to the space $\mathcal{X}$
- Observed variables $x^{\circ}$
- Missing variables $x^{M}$
- Partition in $K$ clusters $G_{1}, \ldots, G_{K}: \mathbf{z}=\left(\mathbf{z}_{1}, \ldots, \mathbf{z}_{n}\right), \mathbf{z}_{i}=\left(z_{i 1}, \ldots, z_{i K}\right)^{\prime}$

$$
\mathbf{x}_{i} \in G_{k} \quad \Leftrightarrow \quad z_{i k}=1 \text { et } \forall h \neq k, z_{i h}=0
$$

■ Goal : learn a classification rule $r \mathcal{D}$

$$
\begin{array}{rlll}
r: & \longrightarrow & \{1, \ldots, K\} \\
\mathbf{x}_{n+1}^{O} & \longmapsto & r\left(\mathbf{x}_{n+1}^{O}\right) .
\end{array}
$$

## Supervised classification (2/3)

Heterogeneous, missing, uncertain

| Units $\mathbf{x}^{O}$ |  |  |  |  | Partition $\mathbf{z}$ | $\Leftrightarrow$ | Class |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $?$ | 0.5 | red | 5 | 0 | 1 | 0 | $\Leftrightarrow$ |
| 0.3 | 0.1 | vert | 3 | 1 | 0 | 0 | $\Leftrightarrow$ |
| 0.3 | 0.6 | \{red, green | $G_{2}$ |  |  |  |  |
| 0.9 | $[0.250 .45]$ | red | 3 | 1 | 0 | 0 | $\Leftrightarrow$ |
| $\downarrow$ | $\downarrow$ | $\downarrow$ | $\downarrow$ | 0 | 0 | 1 | $\Leftrightarrow$ |
| continuous | continuous | categorical | $\downarrow$ | $G_{1}$ |  |  |  |
| integer |  |  |  |  |  |  |  |

## Supervised classification (3/3)



## Semi-supervised classification (1/3)

- Data : learning data $\mathcal{D}=\left(\mathbf{x}^{0}, \mathbf{z}^{\mathrm{O}}\right)$
- $n$ units : $\mathbf{x}=\left(\mathbf{x}_{1}, \ldots, \mathbf{x}_{n}\right)=\left(\mathbf{x}^{0}, \mathbf{x}^{M}\right)$ belonging to the space $\mathcal{X}$
- Observed varibles $x^{O}$
- Missing variables $x^{M}$
- Partition: $\mathbf{z}=\left(\mathbf{z}_{1}, \ldots, \mathbf{z}_{n}\right)=\left(\mathbf{z}^{0}, \mathbf{z}^{M}\right)$
- Observed class $z^{\circ}$
- Missing class $z^{M}$
- Goal : estimate the classification rule $r$ from $\mathcal{D}$

$$
\begin{array}{rlll}
r: & \longrightarrow & \{1, \ldots, K \\
& & \\
\mathbf{x}_{n+1}^{O} & \longmapsto & r\left(\mathbf{x}_{n+1}^{O}\right) .
\end{array}
$$

- Idea : $\mathbf{x}$ is cheaper than $\mathbf{z}$ thus $n \gg n_{\ell}, n_{\ell}$ number of labeled units.


## Semi-supervised classification (2/3)

heterogeneous, missing, uncertain

| Units $\mathrm{x}^{O}$ |  |  |  | Partition $\mathrm{z}^{\mathrm{O}}$ |  |  | $\Leftrightarrow$ | Class |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ? | 0.5 | red | 5 | 0 | ? | ? | $\Leftrightarrow$ | $G_{2}$ ou $G_{3}$ |
| 0.3 | 0.1 | vert | 3 | 1 | 0 | 0 | $\Leftrightarrow$ | $G_{1}$ |
| 0.3 | 0.6 | \{red,green\} | 3 | ? | ? | ? | $\Leftrightarrow$ | ? ? ? |
| 0.9 | [0.25 0.45] | red | ? | 0 | 0 | 1 | $\Leftrightarrow$ | G3 |
| continue | continuous | categorical | integer |  |  |  |  |  |

## Semi-supervised classification (3/3)



## Unsupervised classification (1/3)

- Data : learning data $\mathcal{D}=\mathbf{x}^{O}$, with $\mathbf{z}^{O}=\emptyset$
- Goal : estimate the partition $\mathbf{z}$ and the number of clusters $K$
- Usually usually known as: clustering


## Unsupervised classification (2/3)

heterogneous, missing, uncertain

| Units $\mathrm{x}^{\circ}$ |  |  |  | Partition z ${ }^{\circ}$ |  |  | $\Leftrightarrow$ | Cluster |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ? | 0.5 | red | 5 | ? | ? | ? | $\Leftrightarrow$ | ??? |
| 0.3 | 0.1 | green | 3 | ? | ? | ? | $\Leftrightarrow$ | ??? |
| 0.3 | 0.6 | \{red, green\} | 3 | ? | ? | ? | $\Leftrightarrow$ | ??? |
| 0.9 | [0.25 0.45] | red | ? | ? | ? | ? | $\Leftrightarrow$ | ??? |
| $\begin{gathered} \downarrow \\ \text { continuous } \end{gathered}$ | $\begin{gathered} \downarrow \\ \text { continuous } \end{gathered}$ | categorical | interger |  |  |  |  |  |

## Unsupervised classification (3/3)



## Usuals solutions (1/2)

Two types of models
■ Generatives models

- Modeling of $\mathrm{p}(\boldsymbol{x}, \boldsymbol{z})$
- Which implies a direct modeling of $\mathrm{p}(\boldsymbol{x})=\sum_{\boldsymbol{z}} \mathrm{p}(\boldsymbol{x}, \boldsymbol{z})$
- Missing data easily taken into account on $\boldsymbol{z}$ and $\boldsymbol{x}$
- Predictive models
- Modeling of $\mathrm{p}(\mathbf{z} \mid \boldsymbol{x})$ eventually only $\mathbf{1}_{\{\mathrm{p}(\mathbf{z} \mid \mathrm{x})>1 / 2\}}$, or only the rank on $\mathrm{p}(\mathbf{z} \mid \boldsymbol{x})$
- Avoids assumptions on $\mathrm{p}(\boldsymbol{x})$, and thus limits the modeling errors
- Difficulty to take into account missing data on $\boldsymbol{z}$ and/or $\boldsymbol{x}$


## Solutions usuelles (2/2)

- Missing / uncertain data : multiple inputation
- Mixed data : empirical recoding

How to deal with heterogenous, missing, uncertain data in an integrated way?

## Solutions usuelles (2/2)

- Missing / uncertain data : multiple inputation
- Mixed data : empirical recoding

How to deal with heterogenous, missing, uncertain data in an integrated way? By using the mixture models.

## Mixture models (1/2)

- Rigorous definition of a cluster :

$$
\mathbf{x}_{1} \in G_{k} \quad \Leftrightarrow \quad \mathbf{x}_{1} \text { is a realization of } \mathbf{x}_{1} \sim \mathrm{p}_{k}\left(\mathbf{x}_{1}\right)
$$

- Mixture formulation :

$$
\begin{aligned}
\mathbf{z}_{1} & \sim \operatorname{Mult}_{K}\left(1, \pi_{1}, \ldots, \pi_{K}\right) \\
\mathbf{x}_{1 \mid Z_{1 k}=1} & \sim \mathrm{p}_{k}\left(\mathbf{x}_{1}\right)
\end{aligned}
$$

- Joint and marginal distribution (mixture) :

$$
\begin{aligned}
\left(\mathbf{x}_{1}, \mathbf{Z}_{1}\right) & \sim \prod_{k=1}^{K}\left[\pi_{k} \mathrm{p}_{k}\left(\mathbf{x}_{1}\right)\right]^{z_{1 k}} \\
\mathbf{x}_{1} & \sim \mathrm{p}\left(\mathrm{x}_{1}\right)=\sum_{k=1}^{K} \pi_{k} \mathrm{p}_{k}\left(\mathbf{x}_{1}\right)
\end{aligned}
$$

## Mixture models (2/2)

$$
\mathrm{p}\left(\mathrm{x}_{1}\right)=\sum_{k=1}^{K} \pi_{k} \mathrm{p}_{k}\left(\mathrm{x}_{1}\right)
$$

Mixture models (2/2)

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$$
\mathrm{p}\left(\mathbf{x}_{1}\right)=\sum_{k=1}^{K} \pi_{k} \mathrm{p}_{k}\left(\mathbf{x}_{1}\right)
$$



## Prostate cancer data (1/5)

- Units : patients with prostate cancer classified in grade 3 or 4 of cancer based on advanced study.
- Variables : $d=12$ preliminary measures on each patient :
- 8 continuous variables : age, weight, systolic blood pressure, diastolic blood pressure, serum hemoglobin, size of primary tumor, index of tumor stage and histologic grade, serum prostatic acid phosphatase
- 4 categorical variables : performance rating, cardiovascular disease history, electrocardiogram code, bone metastases
- Missing data
- Goal : predict the grade of the cancer based on preliminary analysis.

| Conrriate | Ablurexicion | Number of Lerets (if categorical) |
| :---: | :---: | :---: |
| Age | Age |  |
| Weight | Wt |  |
| Performance rating | PF | 4 |
| Cardiorascular disease history | HX | 2 |
| Systolic Blood pressure | SBP |  |
| Diastolic blood pressure | DBP |  |
| Electrocardiogram oode | EKG | 7 |
| Serum heemoglobin | HG |  |
| Size of primary tumour | S2 |  |
| Index of tumour stage and histolic crade | SG |  |
| Serum prostatic acid phosphatase | ${ }_{\text {AP }}$ |  |
| Bone metatases | B.I | 2 |

