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## **To cite this version:**

Chao Tan, Luyu Li, Chentao Wu, Jie Li. DASM: A Dynamic Adaptive Forward Assembly Area Method to Accelerate Restore Speed for Deduplication-Based Backup Systems. 13th IFIP International Conference on Network and Parallel Computing (NPC), Oct 2016, Xi'an, China. pp.58-70,  $10.1007/978-3-319-47099-3\_5$ . hal-01647993

## **HAL Id: hal-01647993 <https://inria.hal.science/hal-01647993>**

Submitted on 24 Nov 2017

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### **DASM: A Dynamic Adaptive Forward Assembly Area Method to Accelerate Restore Speed for Deduplication-based Backup Systems**

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**Abstract.** Data deduplication yields an important role in modern backup systems for its demonstrated ability to improve storage efficiency. However, in deduplication-based backup systems, the consequent exhausting fragmentation problem has drawn ever-increasing attention over in terms of backup frequencies, which leads to the degradation of restoration speed. Various Methods are proposed to address this problem. However, most of them purchase restore speed at the expense of deduplication ratio reduction, which is not efficient.

In this paper, we present a Dynamic Adaptive Forward Assembly Area Method, called DASM, to accelerate restore speed for deduplicationbased backup systems. DASM exploits the fragmentation information within the restored backup streams and dynamically trades off between chunk-level cache and container-level cache. DASM is a pure data restoration module which pursues optimal read performance without sacrificing deduplication ratio. Meanwhile, DASM is a resource independent and cache efficient scheme, which works well under different memory footprint restrictions. To demonstrate the effectiveness of DASM, we conduct several experiments under various backup workloads. The results show that, DASM is sensitive to fragmentation granularity and can accurately adapt to the changes of fragmentation size. Besides, experiments also show that DASM improves the restore speed of traditional LRU and ASM methods by up to 58.9% and 57.1%, respectively.

**Keywords:** Data Deduplication; Restore Speed; Reliability; Cache Policy; Performance Evaluation

## **1 Introduction**

Data deduplication is an effective technique used to improve storage efficiency in modern backup systems. [13] [2]. A typical deduplication-based backup system partitions backup streams into variable-size or fixed-size chunks. Each data chunk is identified by fingerprints calculated using cryptographic methods, such as SHA-1 [11]. Two chunks are considered to be duplicates if they have identical fingerprints. For each chunk, deduplication system employs Key-Value Store, also referred to fingerprint index, to identify possible duplicates. Only new fresh chunks are physically stored in containers while duplicates are eliminated.

However, in backup systems, the deviation between physical locality and logical locality increases when backup frequencies are improved, which leads to the physical dispersion of subsequent backup streams. The consequent exhausting fragmentation problem has drawn ever-increasing attention, which results in the degradation of restoration speed and expensive garbage collection operations [8] [10].

In the past decade, various methods are proposed to address this problem [7] [9]. Most of them purchase restore speed by sacrificing the deduplication ratio, which is costly [12] [6]. Traditional restoration method employs LRU algorithm to cache chunk containers. In many scenarios, LRU buffers a large amount of unuseful chunks within containers. Besides, unlike some other applications, we have perfect pre-knowledge of future access informations during restoration, which cannot be well utilized by LRU. A few advanced approaches like ASM [6] employs a forward assembly area to prefetch data chunks within a same container. Nevertheless, ASM is a chunk-level restoration method which limits its read performance due to the one-container cache regulation.

In this paper, we present a Dynamic Adaptive Forward Assembly Area Method, called DASM, to accelerate restore speed for deduplication-based backup systems. DASM exploits the fragmentation information within the restored backup streams and dynamically trades off between chunk-level cache and container-level cache. DASM is a pure data restoration module which pursues optimal read performance without sacrificing deduplication ratio. Meanwhile, DASM works well under different memory footprint restrictions.

The main contributions of this paper are summarized as follows,

- *•* We propose a novel Dynamic Adaptive Forward Assembly Area method (DASM) for deduplication-based backup systems, which outperforms prior approaches in terms of restoration speed. DASM performs well in different scenarios, such as various memory restrictions and backup workloads.
- *•* We conduct several experiments to demonstrate the effectiveness of DASM. The results show that DASM sharply improves the restore speed in various workloads.

The remainder of the paper is organized as follows. Section 2 reviews the background and the motivation of DASM. Section 3 illustrates the details of our DASM. Section 4 evaluates the performance of our scheme compared with other popular restoration cache algorithms. Finally we conclude our work in Section 5.

## **2 Background and Motivation**

In this section, firstly, we introduce data deduplication briefly. Then we explore the fragmentation problem and how it impacts restoration speed. After that, an elaborate investigation of existing solutions and the motivation of our approach are exhibited.

#### **2.1 Data Deduplication**



**Fig. 1.** Data Deduplication System Architecture.

In backup systems, data deduplication can significantly improve storage efficiency [13] [2]. Figure 1 illustrates a typical data deduplication system architecture [4].

Two chunks are considered to be duplicates if they have identical fingerprints. A typical deduplication system employs Key-Value Store, referred to fingerprint index as well, to identify possible duplicates. The key-value store maps each fingerprint to the corresponding physical location of data chunks. The recipe store is used to record logical fingerprint sequences according to the order of the original data stream, in case of future data restoration. And container store is a log-structured storage warehouse. After deduplication, data chunks are aggregated into fixed-sized containers(usually 4MB) and stored in a container store.

As shown in Figure 1, original backup streams are partitioned into several variable or fixed-size chunks. The hash engine calculates a fingerprint for each data chunk using cryptographic methods, such as SHA-1 [11].

Once a fingerprint is produced, the system takes following steps to eliminate duplicates:  $(1)$  Look up in the fingerprint cache.  $(2)$  If it is a cache hit, it means that a duplicate data chunk has already existed. In this situation, we can only record the fingerprint into recipe store and terminate the deduplication process. (3) If cache misses, it looks up in the key-value store for further identification. (4) If there is a match, jump to step 5. Otherwise, the data chunk is considered to be a new fresh and stored into containers in the container store. (5) Record the fingerprint in the recipe store. (6) Update fingerprint cache to explore data localities.

#### **2.2 Fragmentation Problem and Restoration Speed**

Fragmentation is one of the exhausting problems caused by typical deduplication scheme. As we can see in Figure 1, physical chunks are stored sequentially in order of their appearance. In the essence, the physical locality is similar to the logical locality for the first backup stream. However, this deviation increases as time goes because duplicate chunks are eliminated, which leads to the physical dispersion of subsequent backup streams.

Fragmentation problems is troublesome in many aspects. First, it degrades the restoration speed [8]. In deduplication systems, read and write operations are executes with basic granularity of container. Thus data restoration should be faster with consecutive physical distribution. Besides, chunks could become invalid because of data deletion operations. Physical dispersion results in holes within the containers, which leads to the emergence of inefficient garbage collection [10].

Various methods are proposed to address these problems. On one hand, several methods accelerate the restore speed via decreasing deduplication ratio. [3]. iDedup [6] selectively deduplicates only sequences of disk blocks and replaces the expensive, on-disk, deduplication metadata with a smaller, in-memory cache. These techniques enable it to tradeoff deduplication ratio for performance. The context-based rewriting (CBR) minimizes drop in restore performance for latest backups by shifting fragmentation to older backups, which are rarely used for restore [5].

Traditional restoration method employs LRU algorithm to cache chunk containers. However, LRU is a container-level cache policy which buffers a large amount of unused chunks within containers. Besides, unlike other data access pattern, we have perfect pre-knowledge of future access information during restoration, which is not utilized by LRU. ASM [6] employs a forward assembly area to prefetch data chunks within a same container. Nevertheless, ASM is a chunk-level restoration method which limits its read performance since the one-container cache regulation.

#### **2.3 Forward Assembly Area**

Forward Assembly Area (ASM) is a chunk-level restoration method which caches chunks rather than containers for better cache performance. Figure 2 depicts the basic functions of ASM.



**Fig. 2.** Forward Assembly Area(ASM) Method.

ASM employs a large forward assembly area to assemble M bytes of the restored backup. Meanwhile, it utilizes two dedicated buffers, a recipe buffer to cache recipe streams and a chunk-container-sized buffer to cache proper containers that is being used.

In a simple case shown in Figure 2, firstly, ASM reads the recipes from their related recipe store preserved in disk into the recipe buffer. Then, ASM obtains the top *n* recipes which hold at most *M* bytes of the restored data. After that, ASM finds the earliest unrestored chunk and loads the corresponding container into its I/O buffer. For *chunk*1 with fingerprint *f p*1, the corresponding container *container*13 is loaded into the container buffer. Then, all the chunks belongs to *container*13 in the top *n* recipe items will be restored ,which are *chunk*1, *chunk*5,*chunk*7 in this case. ASM repeats this procedure until the *M* bytes are completely filled. Finally, ASM flushes these *M* bytes of restored data into disk.

ASM restores *M* bytes every time and only one container is loaded into memory during each recovery, which improves the cache performance. However, the one-container regulation may degrade the read performance since each container have to wait until the last one finishes restoration of all chunks.

#### **2.4 Our Motivation**

Many previous literatures attempt to figure out the fragmentation problem through deduplication procedures, such as rewriting. These methods purchase restore speed at the expense of deduplication ratio reduction, which is unworthy. From the restoration's perspective purely, traditional LRU cache policy ignores the perfect pre-knowledge of future access information during restoration and holds plenty of useless chunks in memory, which is a big resource waste. ASM is a chunk-level restoration method which limits its read performance since the one-container cache regulation.

To address this problem, we propose a novel Dynamic Adaptive Forward Assembly Area method (DASM) for deduplication-based backup systems, which arms ASM with a multiple-container-sized cache. DASM adaptively adjusts the size of the forward assembly area and the container cache according to the fragmentation level of the restored backup streams to pursue optimal restoration performance. DASM is resource independent and cache efficient, which outperforms prior approaches under different memory footprint restrictions and various backup workloads.

## **3 Design of DASM**

To overcome the shortages of the forward assembly area method, we present a Dynamic Adaptive Forward Assembly Area method (DASM) which arms ASM with a multiple-container-sized cache. Figure 3 exhibits the overall architecture of DASM.

Different from ASM, DASM carries a multiple-container-sized cache called Container Cache, which buffers multiple containers. To reduce the resource de-



**Fig. 3.** Overview of Dynamic Adaptive Forward Assembly Area Method(DASM).

pendencies and increase cache efficiencies, we impose restrictions on memory footprint by bounding the overall size of the ASM area and the container cache.

Besides the original ASM area and the new joint container cache, DASM involves other two main components as below,

### *•* **Dynamic Orthotics**

Dynamic Orthotics is a calculation model which exploits future access information to pursue optimal restoration performance within the restriction of finite memory footprint. It regards the fragmentation rate as a major criterion and dynamically adjusts the proportion of the ASM area to the container cache. Details are discussed in Section 3.1.

## *•* **Cache Policy**

Cache Policy module depicts the cache replacement policies carried out in the container cache. It works as a centralized scheduler which dispatches containers legitimately to reduce cache miss and minimize the bandwidth requirement.

DASM abides by the following steps,

1) Tradeoff the ASM area and the container cache according to the fragmentation rate, which are typically done by Dynamic Orthotics module. After Dynamic Orthotics completes the tradeoff, the top *n* chunks within *C* containers are restored at this time.

2) Load the required *C* containers into the container cache. If there is a cache miss, DASM selects appropriate cache policies for container replacement.

3) Execute the ASM restoration schemes policies repeatedly: find the earliest unrestored chunk and copy all the chunks pertains to its corresponding container to the forward assembly area.

4) Flush all the restored data to disks and restart from step 1.

#### **3.1 Dynamic Orthotics**

Restoration speed is strongly depended on the fragmentation granularity of the restored data stream. We consider two extreme situations,

(1) Lowest fragmentation granularity for the first backup: as for the first backup. in this scenario, we can shrink container caches to a single container size since almost all consecutive chunks belong to a same container.

(2) Highest fragmentation granularity that almost all unique chunks are placed in different containers with each other: Under this circumstance, we have to shrink ASM area to acquire as large container cache area as possible.

Based on these observations, we propose a mathematical model called Dynamic Orthotics, which exploits future access information to pursue optimal restoration performance within the restriction of finite memory footprint. It regards fragmentation rate as the major criterion and dynamically adjusts the proportion of the ASM area to container cache.

For clarity, we define a few symbols as shown in Table 1.





Suppose there are *n* chunks waiting to be restored in the forward assembly area and they belong to *C<sup>n</sup>* containers. To obtain optimal restoration performance, ASM area should hold exactly  $\sum_{i=1}^{n}$  *chunksize<sub>i</sub>* bytes while container cache has the ability to load accurately *C<sup>n</sup>* containers. The relationships between these notations can be formulated by the following equations:

$$
|ASM| = \sum_{i=1}^{n} chunksize_i \tag{1}
$$

$$
|CC| \stackrel{i=1}{=} C_n * CS \tag{2}
$$

$$
|ASM| + |CC| \le |MFP| \tag{3}
$$

We define fragmentation rate by the following equation,

$$
fragmentation\ rate = \frac{|CC|}{|MFP|} \tag{4}
$$

As shown in Algorithm 1, Dynamic Orthotics reads chunk information sequentially from the recipe buffer. For each chunk, dynamic orthotics calculates whether it can be pushed into ASM. If Equation 1 2 3 still holds, then add the chunk into ASM. Otherwise, terminate and adjust *|*ASM*|* and *|*CC*|* according to the returned value.

**Algorithm 1:** Dynamic Orthotics

**Aim:** Dynamically adjust the proportion of the ASM area to container cache according to the fragmentation rate. **while** *(chunk ← RecipeBuffer.head)̸*= *null* **do**  $C'_n$  = chunk.CID in CC?  $C_n$  :  $C_n + 1$ **if**  $(ASM.size + chunk.size) + C'_n * CS \le MFP.size$  **then** ASM.size+=chunk.sie  $C_n = C'_n$ **else**  $\Box$  **return** *ASM.size,*  $C_n$ 

#### **3.2 Near-optimal Cache Policy**

To reduce container cache miss penalty as much as possible, we implement a variant of Belady's optimal replacement cache policy [1].

Belady's policy evicts the cached container that will be accessed in the farthest future. With foreseeable container access information, it is oversimplified to achieve optimality. However, with fragmentation rate high enough, we may have to traverse along the recipe list for a long time to find a victim, which is expensive. Therefore we establish several cache policies which could achieve near-optimal performance under framework of DASM.

- If a container has already existed in the container cache and it will be reused during the next round, keep it in the cache.
- If there exists no such containers, evict all containers in the container cache.

DASM dynamically adapts the size of container cache and reserve exactly *C<sup>n</sup>* containers' size for the containers required. Since containers which are not reused during the next round will be evicted no matter how, we just evict them without considering replacement order.

## **4 Performance Evaluation**

To demonstrate the effectiveness of DASM, we conduct several experiments using various backup datasets to evaluate the performance of DASM and compare it with traditional restore methods such as LRU and ASM.

#### **4.1 Evaluation Methodology**

**1) Evaluation Platform** We utilize an open-source deduplication platform called Deduplication Framework (DeFrame) [4], for comprehensive data deduplication evaluation. DeFrame implements the entire parameter space discussed in a modular and extensible fashion; this enables apple-to-apple comparisons among both existing and potential solutions [4].

We implement and evaluate a DASM prototype on DeFrame under the Ubuntu 14.10 operating system, with linux kernel version 3.13.0, running on a quad-core Intel i5-4430 processor at 3.00 GHz, with a 12GB RAM, a 1TB 7200RPM hard disk drive.

**2) Traditional restoration methods for comparison** This evaluation employs LRU, ASM as the contrasts. As illustrates in Section 2, traditional restoration method employs LRU algorithm to cache chunk containers. ASM employs a forward assembly area to prefetch data chunks within a same container.

**3) Evaluation Metrics** In this paper, we exploit restoration speed as our major evaluation metric. Restore speeds are measured in term of encoding time in seconds.Besides, we explores fragmentation rate to show that DASM is sensitive to fragmentation degree and can adapt to fragmentation change accurately. The fragmentation rate is defined in Section 3.1 as:

$$
fragmentation\ rate = \frac{|CC|}{|MFP|} \tag{5}
$$

**4) Evaluation Datasets** We choose three real-world files as our datasets: ubuntu-14.04.3, ubuntu-14.10 and ubuntu-15.04. These datasets are firstly stored as the 1st, 2nd and 3rd backup streams in the deduplication systems, respectively. After that, we evaluates performance of LRU, ASM and our DASM methods by restoring each original backup streams. Table 2 lists some detailed information about these datasets.

Backup data	<b>Bytes</b>	Chunks	Average Chunk Size	Containers
ubuntu-14.04.3	1054867456	228791	4610	'255
ubuntu $-14.10$	1186529280	1257945	4599	378
ubuntu $-15.04$	1150844928	250609	4592	480

Table 2. DETAILED INFORMATION ABOUT DATASETS

#### **4.2 Experimental Results**

In this section, we give the experimental results of DASM and compare it with LRU and ASM under three backup streams to illustrate its benefits.

**1) Restore Speed Under Different Cache Size** Table 3 and Figure 4 describe the comparison between restore speed among LRU, ASM and DASM under different cache size. Experiments show that DASM improves the restore speed of traditional LRU and ASM methods by up to 58.9% and 57.1%, respectively.

	128M		256M				1G			
	1st	2 <sub>nd</sub>	3rd	1st	2nd	3rd	1st	2 <sub>nd</sub>	3rd	
<b>DASM</b>	4.733	6.047	5.982	4.552	5.689	5.329	4.34	5.937	4.947	
LRU	11.507		12.233 12.311	8.173	8.245	7.874	9.081	9.461	10.114	
Improvement	58.9%	50.6%	51.4%				44.3% 31.0% 32.3% 52.2%	57.2%	$51.1\%$	
<b>ASM</b>	8.341	9.491	9.623	8.453	8.127	6.693			9.572 10.692 11.544	
Improvement $43.3\%$		36.3%	$ 37.8\% 46.1\% 30.0\% 20.3\% 54.7\% 44.5\% 57.1\%$							
14 14 14 12.311 12.233 11.507 11.544 12 12 12 $\mathbb{Z}_{2.623}$ 10.692 10.114 .491 $9.46$ <sub>I</sub> m 10 10 10 8.341 8.178.453 8.245.127 7.874 7.0817.572 8 8 8 <b>78.693</b> 5.982 6.047 16.937 \$.689 4.947 6 6 4.733 6 4.552 4.34 4 4 4 $\overline{2}$ $\overline{\mathbf{c}}$ $\overline{2}$ O ŋ O MFP=128M MFP=256M $MFP=1G$ MFP=128M MFP=256M $MFP=1G$ MFP=128M MFP=256M $MFP=1G$ <b>ZLRU DASM DDASM</b> <b>DASM &amp;DASM</b> <b>ZLRU</b> <b>ZLRU DASM DDASM</b> (b) Restore speed for the 2 <sup>nd</sup> backup (a) Restore speed for the $1st$ backup (c) Restore speed for the $3rd$ backup										

**Table 3.** Comparison among LRU, ASM and DASM under different cache size in terms of restore speed.

**Fig. 4.** Comparison among LRU, ASM and DASM under different cache size in terms of restore speed.



**Fig. 5.** Comparison among LRU, ASM and DASM under different backup streams in terms of restore speed.

**2)Restore Speed Under Different backup streams** Figure 5 illustrates the comparison between restore speed among LRU, ASM and DASM under different backup streams. Since the first backup is stored sequentially among the containers, which means that it carries the lowest fragmentation problem, it is restored fastest under arbitrary circumstances. As shown in the Figure, DASM outperforms LRU and ASM under any backup streams.

**3) Fragmentation Rate** Figure 6 depicts the fragmentation rate changing curves under different backup streams. As we can see in the figure, regardless of the size of memory footprint, as backup time increases, the average fragmentation rate rises with amplitude aggrandizament  $(3rd > 2nd > 1st)$ . This phenomenon implies that our DASM can effectively and accurately detect fragmentation changes and adjust accordingly.

#### **4.3 Analysis**

Traditional LRU cache policy ignores the perfect pre-knowledge of future access information during restoration and holds plenty of useless chunks in memory,



**Fig. 6.** Fragmentation rate curves under different backup streams

which is a big resource waste. ASM is a chunk-level restoration method which limits its read performance since the one-container cache regulation.

From the results in the previous subsecitons, it is clear that DASM approach has many advantages on restore speed in backup systems compared to the previous restore methods: LRU and ASM. There are several reasons to achieve these gains. First, DASM integrates container cache which can effectively enhance the hit ratio of chunks and reduce read latency. Second, DASM can accurately capture current fragmentation granularit and dynamiclly adjust ASM area size and container cache size to achieve the best performance. Therefore, DASM outperforms LRU and ASM enormously.

## **5 Conclusions**

In this paper, we present a Dynamic Adaptive Forward Assembly Area Method, called DASM, to accelerate restore speed for deduplication-based backup systems. Different from previous approaches, DASM is a pure data restoration module which pursue optimal read performance without sacrificing deduplication ratio. DASM exploits the fragmentation information within the restored backup streams and dynamically trades off between chunk-level cache and container-level cache which leverages both advantages of LRU and ASM. Experiments results show that DASM is sensitive to fragmentation degree and can adapt to fragmentation change accurately. Besides, experiments also show that DASM improves the restore speed of traditional LRU and ASM methods by up to 58.9% and 57.1%, respectively.

#### **6 Acknowledgement**

We thank anonymous reviewers for their insightful comments. This work is partially sponsored by the National 863 Program of China (No. 2015AA015302), the National 973 Program of China No.2015CB352403), the National Natural Science Foundation of China (NSFC) (No. 61332001, No. 61303012, and No. 61572323), the Scientific Research Foundation for the Returned Overseas Chinese Scholars, and the CCF-Tencent Open Fund.

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